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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	16MHz
Connectivity	CANbus, EBI/EMI, SCI, Serial I/O, UART/USART
Peripherals	POR, WDT
Number of I/O	81
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90f543gpmc-g-fle1

Starting by an external trigger input.
Conversion time : 26.3 μ s

- FULL-CAN interfaces
MB90540G series : 2 channels
MB90545G series : 1 channel
Conforming to Version 2.0 Part A and Part B

Flexible message buffering (mailbox and FIFO buffering can be mixed)

- External bus interface : Maximum address space 16 Mbytes
- Package: QFP-100, LQFP-100

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*2 : It is setting of DIP switch S2 when Emulation pod (MB2145-507) is used. Please refer to the MB2145-507 hardware manual (2.7 Emulator-specific Power Pin) about details.

*3 : Operating Voltage Range

Products	Operation guarantee range
MB90F543G(S)/F546G(S)/F548G(S)/ MB90549G(S)/F549G(S)/V540/V540G	4.5 V to 5.5 V
MB90F548GL(S)/543G(S)/547G(S)/548G(S)	3.5 V to 5.5 V

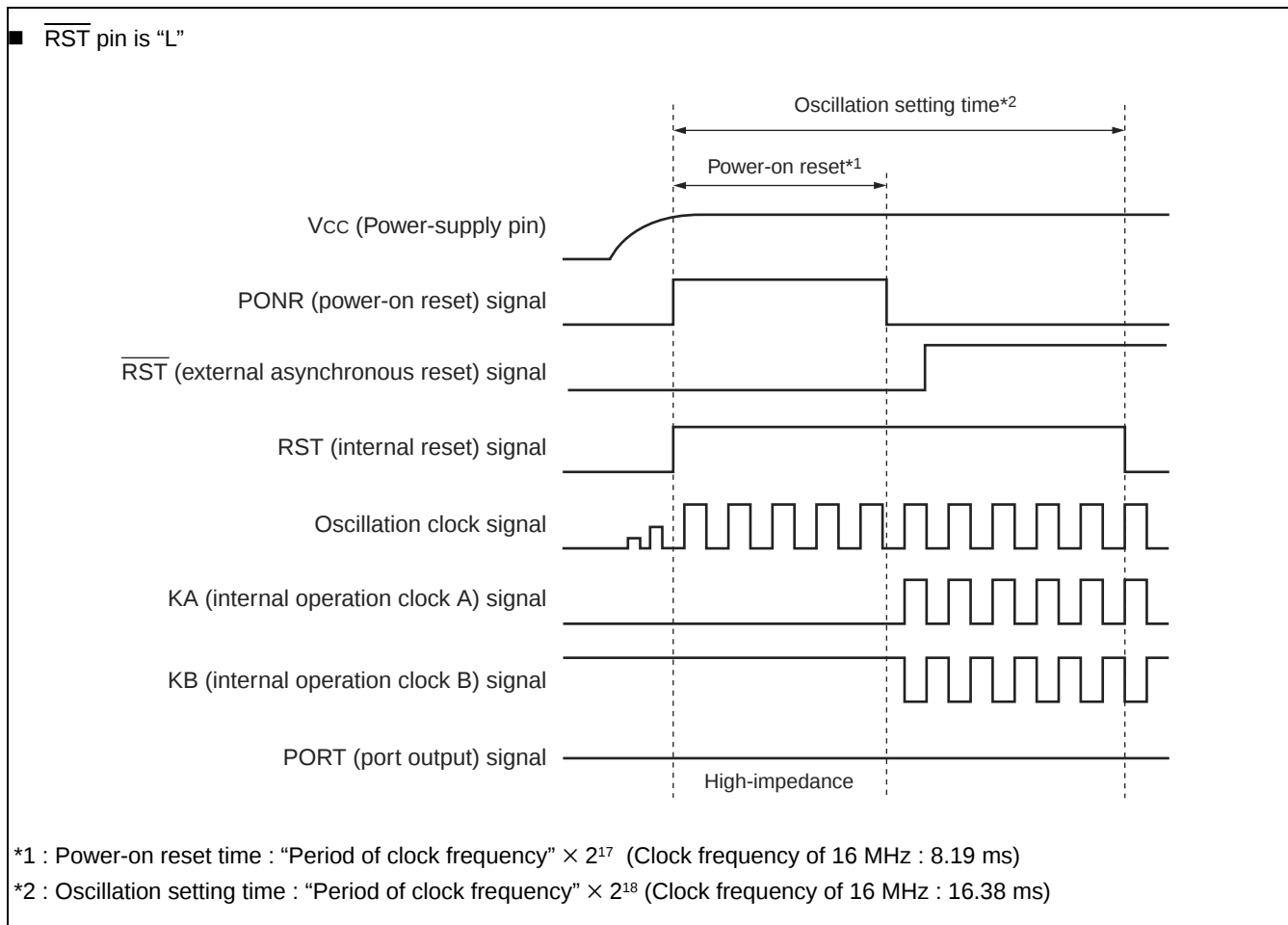
3. Pin Description

Pin No.		Pin name	Circuit type	Function
LQFP ²	QFP ¹			
80 81	82 83	X0 X1	A (Oscillation)	High speed crystal oscillator input pins
78	80	X0A	A (Oscillation)	Low speed crystal oscillator input pins. For the one clock system parts, perform external pull-down processing.
77	79	X1A		Low speed crystal oscillator input pins. For the one clock system parts, leave it open.
75	77	$\overline{\text{RST}}$	B	External reset request input pin
50	52	$\overline{\text{HST}}$	C	Hardware standby input pin
83 to 90	85 to 92	P00 to P07	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		AD00 to AD07		I/O pins for 8 lower bits of the external address/data bus. This function is enabled when the external bus is enabled.
91 to 98	93 to 100	P10 to P17	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		AD08 to AD15		I/O pins for 8 higher bits of the external address/data bus. This function is enabled when the external bus is enabled.
99 to 6	1 to 8	P20 to P27	I	General I/O port with programmable pullup. In external bus mode, this function is valid when the corresponding bits in the external address output control resister (HACR) are set to "1".
		A16 to A23		8-bit I/O pins for A16 to A23 at the external address/data bus. In external bus mode, this function is valid when the corresponding bits in the external address output control resister (HACR) are set to "0".
7	9	P30	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		ALE		Address latch enable output pin. This function is enabled when the external bus is enabled.
8	10	P31	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		$\overline{\text{RD}}$		Read strobe output pin for the data bus. This function is enabled when the external bus is enabled.
10	12	P32	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the $\overline{\text{WR}}/\overline{\text{WRL}}$ pin output is disabled.
		$\overline{\text{WRL}}$		Write strobe output pin for the data bus. This function is enabled when both the external bus and the $\overline{\text{WR}}/\overline{\text{WRL}}$ pin output are enabled. $\overline{\text{WRL}}$ is write-strobe output pin for the lower 8 bits of the data bus in 16-bit access.
		$\overline{\text{WR}}$		$\overline{\text{WR}}$ is write-strobe output pin for the 8 bits of the data bus in 8-bit access.

(Continued)

Pin No.		Pin name	Circuit type	Function
LQFP ²	QFP ¹			
46	48	P57	D	General I/O port. This function is enabled when the 16-bit reload timers 0 disables the output.
		TOT0		Output pin for the 16-bit reload timers 0. This function is enabled when the 16-bit reload timers 0 enables the output.
51 to 56	53 to 58	P70 to P75	D	General I/O ports. This function is always enabled.
		IN0 to IN5		Trigger input pins for input captures ICU0 to ICU5. Set the corresponding Port Direction Register to input if this function is used.
57 , 58	59 , 60	P76 , P77	D	General I/O ports. This function is enabled when the OCU disables the waveform output.
		OUT2 , OUT3		Event output pins for output compares OCU2 and OCU3. This function is enabled when the OCU enables the waveform output.
		IN6 , IN7		Trigger input pins for input captures ICU6 and ICU7. Set the corresponding Port Direction Register to input and disable the OCU waveform output if this function is used.
59 to 62	61 to 64	P80 to P83	D	General I/O ports. This function is enabled when 8/16-bit PPG disables the waveform output.
		PPG0 to PPG3		Output pins for 8/16-bit PPGs. This function is enabled when 8/16-bit PPG enables the waveform output.
63 , 64	65 , 66	P84 , P85	D	General I/O ports. This function is enabled when the OCU disables the waveform output.
		OUT0 , OUT1		Waveform output pins for output compares OCU0 and OCU1. This function is enabled when the OCU enables the waveform output.
65	67	P86	D	General I/O port. This function is always enabled.
		TIN1		Input pin for the 16-bit reload timers 1. Set the corresponding Port Direction Register to input if this function is used.
66	68	P87	D	General I/O port. This function is enabled when the 16-bit reload timers 1 disables the output.
		TOT1		Output pin for the 16-bit reload timers 1. This function is enabled when the 16-bit reload timers 1 enables the output.
67 to 70	69 to 72	P90 to P93	D	General I/O port. This function is always enabled.
		INT0 to INT3		External interrupt request input pins for INT0 to INT3. Set the corresponding Port Direction Register to input if this function is used.
71	73	P94	D	General I/O port. This function is enabled when CAN0 disables the output.
		TX0		TX output pin for CAN0. This function is enabled when CAN0 enables the output.

(Continued)



(13) Initialization

In the device, there are internal registers which are initialized only by a power-on reset. To initialize these registers, please turn on the power again.

(14) Directions of "DIV A, Ri" and "DIVW A, RWi" instructions

In the Signed multiplication and division instructions ("DIV A, Ri" and "DIVW A, RWi"), the value of the corresponding bank register (DTB, ADB, USB, SSB) is set in "00H".

If the values of the corresponding bank registers (DTB, ADB, USB, SSB) are set to other than "00H", the remainder by the execution result of the instruction is not stored in the register of the instruction operand.

(15) Using REALOS

The use of EI²OS is not possible with the REALOS real time operating system.

(16) Caution on Operations during PLL Clock Mode

If the PLL clock mode is selected, the microcontroller attempt to be working with the self-oscillating circuit even when there is no external oscillator or external clock input is stopped. Performance of this operation, however, cannot be guaranteed.

Address	Register	Abbreviation	Access	Resource name	Initial value
47 _H to 4B _H	Prohibited				
4C _H	Input capture control status register 0/1	ICS01	R/W	Input Capture 0/1	0 0 0 0 0 0 0 0 _B
4D _H	Input capture control status register 2/3	ICS23	R/W	Input Capture 2/3	0 0 0 0 0 0 0 0 _B
4E _H	Input capture control status register 4/5	ICS45	R/W	Input Capture 4/5	0 0 0 0 0 0 0 0 _B
4F _H	Input capture control status register 6/7	ICS67	R/W	Input Capture 6/7	0 0 0 0 0 0 0 0 _B
50 _H	Timer control status register 0	TMCSR0	R/W	16-bit Reload Timer 0	0 0 0 0 0 0 0 0 _B
51 _H	Timer control status register 0	TMCSR0	R/W		____ 0 0 0 0 _B
52 _H	Timer register 0/reload register 0	TMR0/TMRLR0	R/W		XXXXXXXX _B
53 _H	Timer register 0/reload register 0	TMR0/TMRLR0	R/W		XXXXXXXX _B
54 _H	Timer control status register 1	TMCSR1	R/W	16-bit Reload Timer 1	0 0 0 0 0 0 0 0 _B
55 _H	Timer control status register 1	TMCSR1	R/W		____ 0 0 0 0 _B
56 _H	Timer register 1/reload register 1	TMR1/TMRLR1	R/W		XXXXXXXX _B
57 _H	Timer register 1/reload register 1	TMR1/TMRLR1	R/W		XXXXXXXX _B
58 _H	Output compare control status register 0	OCS0	R/W	Output Compare 0/1	0 0 0 0 __ 0 0 _B
59 _H	Output compare control status register 1	OCS1	R/W		__ __ 0 0 0 0 0 _B
5A _H	Output compare control status register 2	OCS2	R/W	Output Compare 2/3	0 0 0 0 __ 0 0 _B
5B _H	Output compare control status register 3	OCS3	R/W		__ __ 0 0 0 0 0 _B
5C _H to 6B _H	Prohibited				
6C _H	Timer Data register	TCDT	R/W	I/O Timer	0 0 0 0 0 0 0 0 _B
6D _H	Timer Data register	TCDT	R/W		0 0 0 0 0 0 0 0 _B
6E _H	Timer Control register	TCCS	R/W		0 0 0 0 0 0 0 0 _B
6F _H	ROM mirror function selection register	ROMM	R/W	ROM Mirror	__ __ __ __ __ 1 _B
70 _H to 7F _H	Reserved for CAN 0 Interface.				
80 _H to 8F _H	Reserved for CAN 1 Interface.				
90 _H to 9D _H	Prohibited				
9E _H	Program address detection control status register	PACSR	R/W	Address Match Detection Function	0 0 0 0 0 0 0 0 _B
9F _H	Delayed interrupt/release register	DIRR	R/W	Delayed Interrupt	__ __ __ __ __ 0 _B
A0 _H	Low-power mode control register	LPMCR	R/W	Low Power Controller	0 0 0 1 1 0 0 0 _B
A1 _H	Clock selection register	CKSCR	R/W	Low Power Controller	1 1 1 1 1 1 0 0 _B

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Address	Register	Abbreviation	Access	Resource name	Initial value
3928 _H	Output Compare Register 0	OCCP0	R/W	Output Compare 0/1	XXXXXXXX _B
3929 _H	Output Compare Register 0	OCCP0	R/W		XXXXXXXX _B
392A _H	Output Compare Register 1	OCCP1	R/W		XXXXXXXX _B
392B _H	Output Compare Register 1	OCCP1	R/W		XXXXXXXX _B
392C _H	Output Compare Register 2	OCCP2	R/W	Output Compare 2/3	XXXXXXXX _B
392D _H	Output Compare Register 2	OCCP2	R/W		XXXXXXXX _B
392E _H	Output Compare Register 3	OCCP3	R/W		XXXXXXXX _B
392F _H	Output Compare Register 3	OCCP3	R/W		XXXXXXXX _B
3930 _H to 39FF _H	Reserved				
3A00 _H to 3AFF _H	Reserved for CAN 0 Interface.				
3B00 _H to 3BFF _H	Reserved for CAN 0 Interface.				
3C00 _H to 3CFF _H	Reserved for CAN 1 Interface.				
3D00 _H to 3DFF _H	Reserved for CAN 1 Interface.				
3E00 _H to 3FFF _H	Reserved				

■ Read/write notation

R/W : Reading and writing permitted
R : Read-only
W : Write-only

■ Initial value notation

0 : Initial value is "0".
1 : Initial value is "1".
X : Initial value is undefined.
— : Initial value is unused.

Note: Any write access to reserved addresses in I/O map should not be performed. A read access to reserved addresses results in reading "X".

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003A24 _H	003C24 _H	ID register 1	IDR1	R/W	XXXXXXXX XXXXXXXX _B
003A25 _H	003C25 _H				XXXXXX--- XXXXXXXX _B
003A26 _H	003C26 _H				
003A27 _H	003C27 _H				
003A28 _H	003C28 _H	ID register 2	IDR2	R/W	XXXXXXXX XXXXXXXX _B
003A29 _H	003C29 _H				XXXXXX--- XXXXXXXX _B
003A2A _H	003C2A _H				
003A2B _H	003C2B _H				
003A2C _H	003C2C _H	ID register 3	IDR3	R/W	XXXXXXXX XXXXXXXX _B
003A2D _H	003C2D _H				XXXXXX--- XXXXXXXX _B
003A2E _H	003C2E _H				
003A2F _H	003C2F _H				
003A30 _H	003C30 _H	ID register 4	IDR4	R/W	XXXXXXXX XXXXXXXX _B
003A31 _H	003C31 _H				XXXXXX--- XXXXXXXX _B
003A32 _H	003C32 _H				
003A33 _H	003C33 _H				
003A34 _H	003C34 _H	ID register 5	IDR5	R/W	XXXXXXXX XXXXXXXX _B
003A35 _H	003C35 _H				XXXXXX--- XXXXXXXX _B
003A36 _H	003C36 _H				
003A37 _H	003C37 _H				
003A38 _H	003C38 _H	ID register 6	IDR6	R/W	XXXXXXXX XXXXXXXX _B
003A39 _H	003C39 _H				XXXXXX--- XXXXXXXX _B
003A3A _H	003C3A _H				
003A3B _H	003C3B _H				

(Continued)

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Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003A88 _H to 003A8F _H	003C88 _H to 003C8F _H	Data register 1 (8 bytes)	DTR1	R/W	XXXXXXXX _B to XXXXXXXX _B
003A90 _H to 003A97 _H	003C90 _H to 003C97 _H	Data register 2 (8 bytes)	DTR2	R/W	XXXXXXXX _B to XXXXXXXX _B
003A98 _H to 003A9F _H	003C98 _H to 003C9F _H	Data register 3 (8 bytes)	DTR3	R/W	XXXXXXXX _B to XXXXXXXX _B
003AA0 _H to 003AA7 _H	003CA0 _H to 003CA7 _H	Data register 4 (8 bytes)	DTR4	R/W	XXXXXXXX _B to XXXXXXXX _B
003AA8 _H to 003AAF _H	003CA8 _H to 003CAF _H	Data register 5 (8 bytes)	DTR5	R/W	XXXXXXXX _B to XXXXXXXX _B
003AB0 _H to 003AB7 _H	003CB0 _H to 003CB7 _H	Data register 6 (8 bytes)	DTR6	R/W	XXXXXXXX _B to XXXXXXXX _B
003AB8 _H to 003ABF _H	003CB8 _H to 003CBF _H	Data register 7 (8 bytes)	DTR7	R/W	XXXXXXXX _B to XXXXXXXX _B
003AC0 _H to 003AC7 _H	003CC0 _H to 003CC7 _H	Data register 8 (8 bytes)	DTR8	R/W	XXXXXXXX _B to XXXXXXXX _B
003AC8 _H to 003ACF _H	003CC8 _H to 003CCF _H	Data register 9 (8 bytes)	DTR9	R/W	XXXXXXXX _B to XXXXXXXX _B
003AD0 _H to 003AD7 _H	003CD0 _H to 003CD7 _H	Data register 10 (8 bytes)	DTR10	R/W	XXXXXXXX _B to XXXXXXXX _B
003AD8 _H to 003ADF _H	003CD8 _H to 003CDF _H	Data register 11 (8 bytes)	DTR11	R/W	XXXXXXXX _B to XXXXXXXX _B
003AE0 _H to 003AE7 _H	003CE0 _H to 003CE7 _H	Data register 12 (8 bytes)	DTR12	R/W	XXXXXXXX _B to XXXXXXXX _B
003AE8 _H to 003AEF _H	003CE8 _H to 003CEF _H	Data register 13 (8 bytes)	DTR13	R/W	XXXXXXXX _B to XXXXXXXX _B
003AF0 _H to 003AF7 _H	003CF0 _H to 003CF7 _H	Data register 14 (8 bytes)	DTR14	R/W	XXXXXXXX _B to XXXXXXXX _B
003AF8 _H to 003AFF _H	003CF8 _H to 003CFF _H	Data register 15 (8 bytes)	DTR15	R/W	XXXXXXXX _B to XXXXXXXX _B

11. Electrical Characteristics

11.1 Absolute Maximum Ratings

($V_{SS} = AV_{SS} = 0.0\text{ V}$)

Parameter	Symbol	Value		Units	Remarks
		Min	Max		
Power supply voltage	V_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	
	AV_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$V_{CC} = AV_{CC}$ *1
	$AVRH, AVRL$	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$AV_{CC} \geq AVRH/AVRL, AVRH \geq AVRL$ *1
Input voltage	V_I	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*2
Output voltage	V_O	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*2
Maximum clamp current	I_{CLAMP}	- 2.0	+ 2.0	mA	*6
Total maximum clamp current	$\Sigma I_{CLAMP} $	—	20	mA	*6
"L" level max output current	I_{OL}	—	15	mA	*3
"L" level avg. output current	I_{OLAV}	—	4	mA	*4
"L" level max overall output current	ΣI_{OL}	—	100	mA	
"L" level avg. overall output current	ΣI_{OLAV}	—	50	mA	*5
"H" level max output current	I_{OH}	—	-15	mA	*3
"H" level avg. output current	I_{OHAV}	—	-4	mA	*4
"H" level max overall output current	ΣI_{OH}	—	-100	mA	
"H" level avg. overall output current	ΣI_{OHAV}	—	-50	mA	*5
Power consumption	P_D	—	500	mW	Flash device
		—	400	mW	MASK ROM
Operating temperature	T_A	-40	+105	°C	
Storage temperature	T_{STG}	-55	+150	°C	

*1 : AV_{CC} , $AVRH$, $AVRL$ should not exceed V_{CC} . Also, $AVRH$, $AVRL$ should not exceed AV_{CC} , and $AVRL$ does not exceed $AVRH$.

*2 : V_I and V_O should not exceed $V_{CC} + 0.3\text{ V}$. However if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supercedes the V_I rating.

*3 : The maximum output current is a peak value for a corresponding pin.

*4 : Average output current is an average current value observed for a 100 ms period for a corresponding pin.

*5 : Total average current is an average current value observed for a 100 ms period for all corresponding pins.

*6 :

- Applicable to pins : P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, PA0
- Use within recommended operating conditions.
- Use at DC voltage (current) .
- The + B signal should always be applied with a limiting resistance placed between the + B signal and the microcontroller.
- The value of the limiting resistance should be set so that when the + B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
- Note that when the microcontroller drive current is low, such as in the power saving modes, the + B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.
- Note that if a + B signal is input when the microcontroller current is off (not fixed at 0 V) , the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the + B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the power-on result.
- Care must be taken not to leave the + B input pin open.

11.4 AC Characteristics

11.4.1 Clock Timing

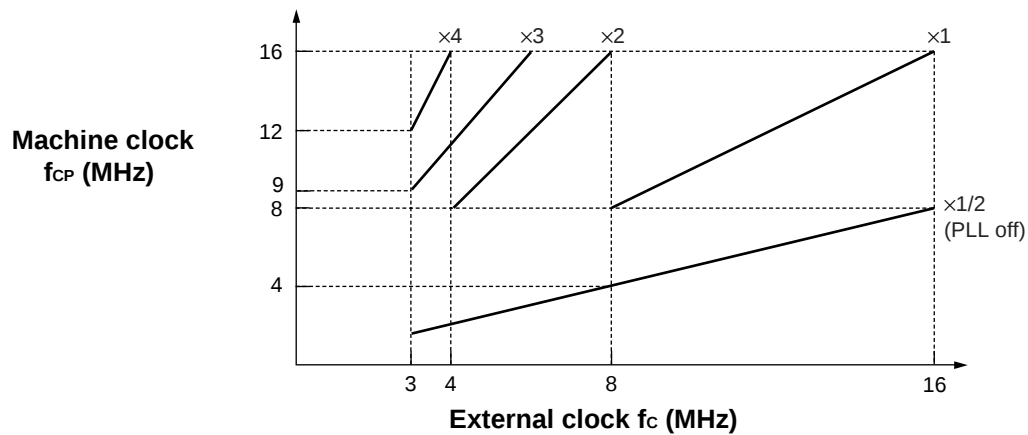
(MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 3.5 \text{ V to } 5.5 \text{ V}$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Value			Units	Remarks
			Min	Typ	Max		
Oscillation frequency	f_c	X0, X1	3	—	16	MHz	No multiplier When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			8	—	16	MHz	PLL multiplied by 1 When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			4	—	8	MHz	PLL multiplied by 2 When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			3	—	5.33	MHz	PLL multiplied by 3 When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			3	—	4	MHz	PLL multiplied by 4 When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			3	—	5	MHz	When using an oscillator circuit $V_{CC} < 4.5 \text{ V}$ (MB90F548GL(S)/543G(S)/ 547G(S)/548G(S))
			3	—	16	MHz	No multiplier When using an external clock
			8	—	16	MHz	PLL multiplied by 1 When using an external clock
			4	—	8	MHz	PLL multiplied by 2 When using an external clock
			3	—	5.33	MHz	PLL multiplied by 3 When using an external clock
			3	—	4	MHz	PLL multiplied by 4 When using an external clock
	f_{CL}	X0A, X1A	—	32.768	—	kHz	

(Continued)

■ External clock frequency and Machine clock frequency



AC characteristics are set to the measured reference voltage values below.

■ Input signal waveform

Hysteresis Input Pin



TTL Input Pin



■ Output signal waveform

Output Pin

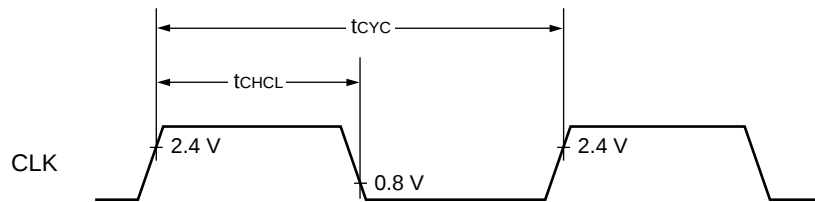


11.4.2 Clock Output Timing

(MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 3.5\text{ V to }5.5\text{ V}$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
Cycle time	t_{CYC}	CLK	$V_{CC} = 5\text{ V} \pm 10\%$	62.5	—	ns	
CLK $\uparrow$ → CLK $\downarrow$	t_{CHCL}			20	—	ns	



11.4.3 Reset and Hardware Standby Input Timing

(MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 3.5\text{ V to }5.5\text{ V}$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Value		Units	Remarks
			Min	Max		
Reset input time	t_{RSTL}	$\overline{RST}$	4 t_{CP}	—	ns	Under normal operation
			Oscillation time of oscillator + 4 t_{CP}	—	ms	In stop mode
			100	—	μs	In pseudo timer mode (MB90543G (S) /547G (S) /548G (S))
			4 t_{CP}	—	ns	In pseudo timer mode (Other than MB90543G (S) /547G (S) /548G (S))
			2 t_{LCP}	—	μs	In sub-clock mode, sub-sleep mode, timer mode
Hardware standby input time	t_{HSTL}	HST	4 t_{CP}	—	ns	Under normal operation

Note : “ t_{cp} ” represents one cycle time of the machine clock.

Oscillation time of oscillator is time that amplitude reached the 90%. In the crystal oscillator, the oscillation time is between several ms to tens of ms. In ceramic oscillator, the oscillation time is between hundreds of μs to several ms. In the external clock, the oscillation time is 0 ns.

Any reset can not fully initialize the Flash Memory if it is performing the automatic algorithm.

11.4.5 Bus Timing (Read)

(MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 3.5\text{ V to }5.5\text{ V}$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
ALE pulse width	t_{LHLL}	ALE	—	$t_{CP}/2 - 20$	—	ns	
Valid address → ALE↓ time	t_{AVLL}	ALE, A16 to A23, AD00 to AD15		$t_{CP}/2 - 20$	—	ns	
ALE↓ → Address valid time	t_{LLAX}	ALE, AD00 to AD15		$t_{CP}/2 - 15$	—	ns	
Valid address → $\overline{RD}$ ↓ time	t_{AVRL}	A16 to A23, AD00 to AD15, RD		$t_{CP} - 15$	—	ns	
Valid address → Valid data input	t_{AVDV}	A16 to A23, AD00 to AD15		—	$5 t_{CP}/2 - 60$	ns	
$\overline{RD}$ pulse width	t_{RLRH}	RD		$3 t_{CP}/2 - 20$	—	ns	
$\overline{RD}$ ↓ → Valid data input	t_{RLDV}	$\overline{RD}$, AD00 to AD15		—	$3 t_{CP}/2 - 60$	ns	
$\overline{RD}$ ↑ → Data hold time	t_{RHDX}	$\overline{RD}$, AD00 to AD15		0	—	ns	
$\overline{RD}$ ↑ → ALE↑ time	t_{RHLH}	$\overline{RD}$, ALE		$t_{CP}/2 - 15$	—	ns	
$\overline{RD}$ ↑ → Address valid time	t_{RHAX}	$\overline{RD}$, A16 to A23		$t_{CP}/2 - 10$	—	ns	
Valid address → CLK↑ time	t_{AVCH}	A16 to A23, AD00 to AD15, CLK		$t_{CP}/2 - 20$	—	ns	
$\overline{RD}$ ↓ → CLK↑ time	t_{RLCH}	$\overline{RD}$, CLK		$t_{CP}/2 - 20$	—	ns	
ALE↓ → $\overline{RD}$ ↓ time	t_{LLRL}	ALE, $\overline{RD}$		$t_{CP}/2 - 15$	—	ns	

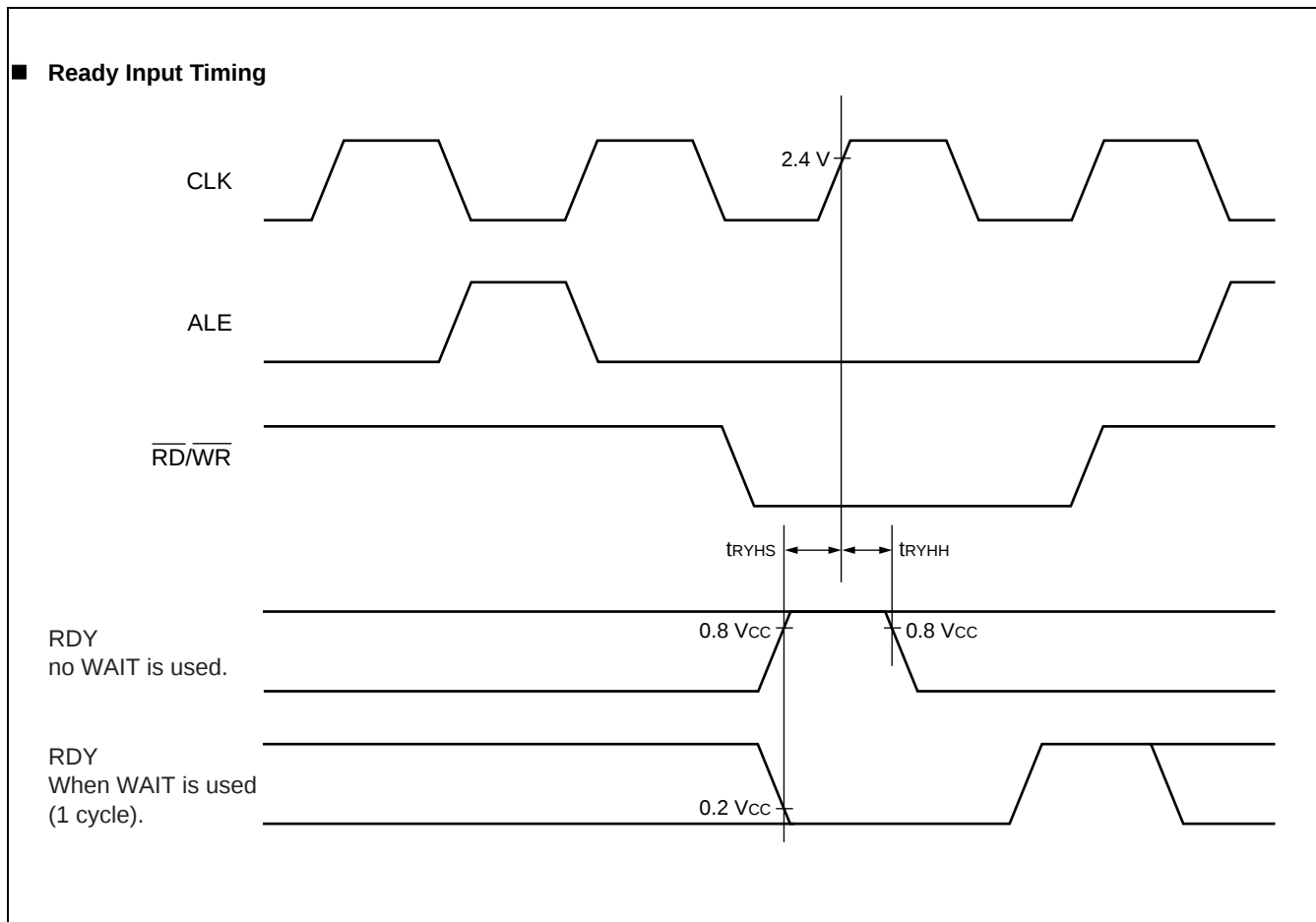
11.4.7 Ready Input Timing

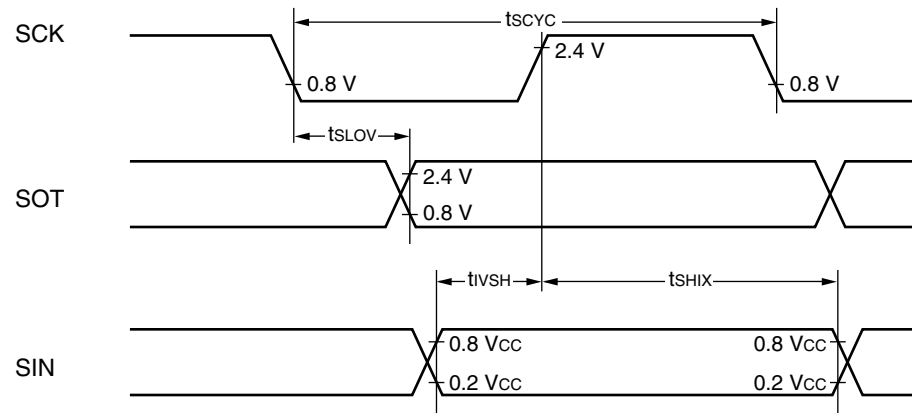
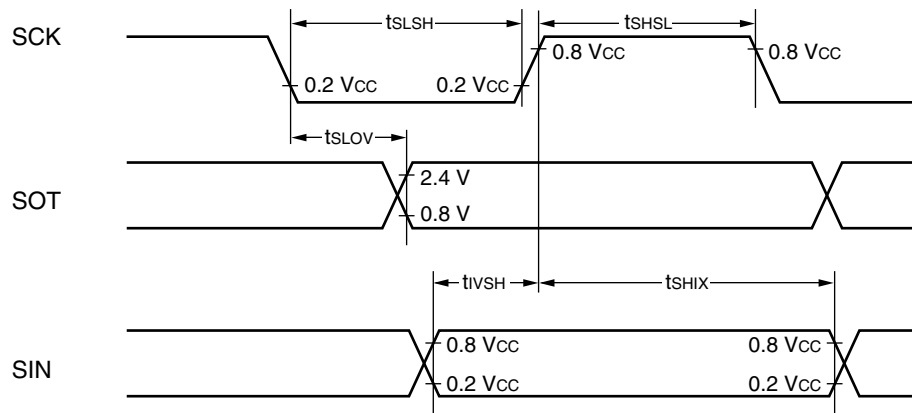
(MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 3.5 \text{ V to } 5.5 \text{ V}$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$)

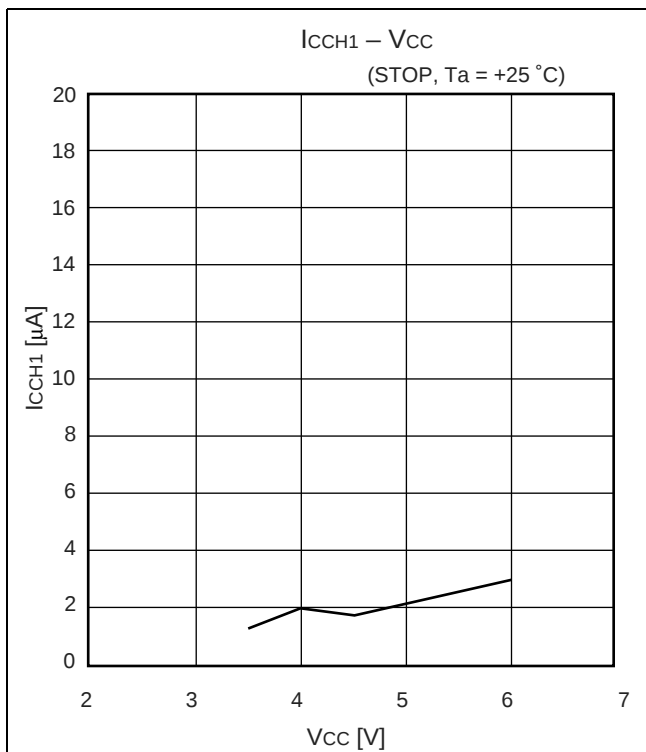
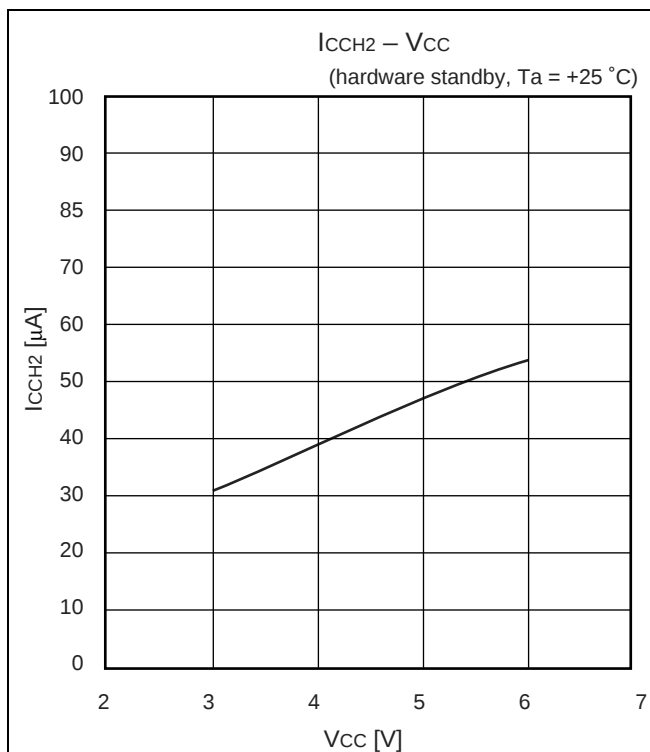
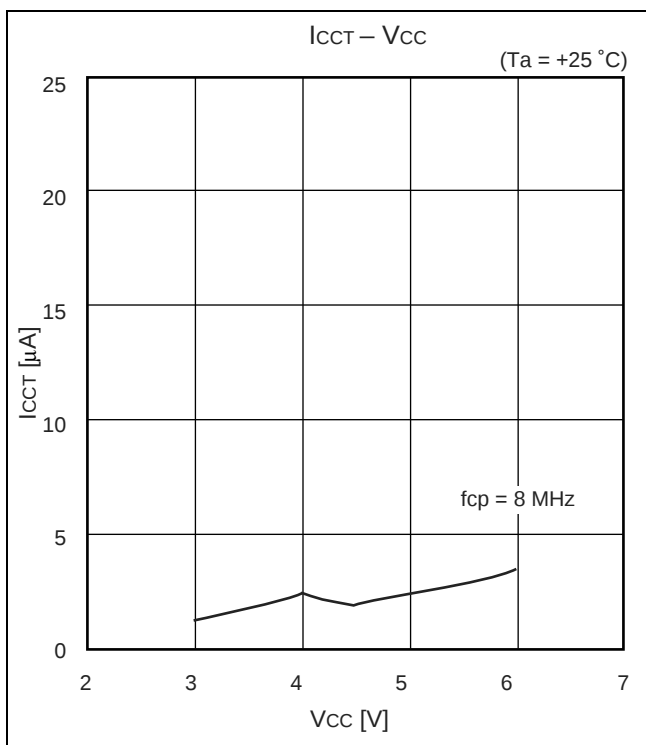
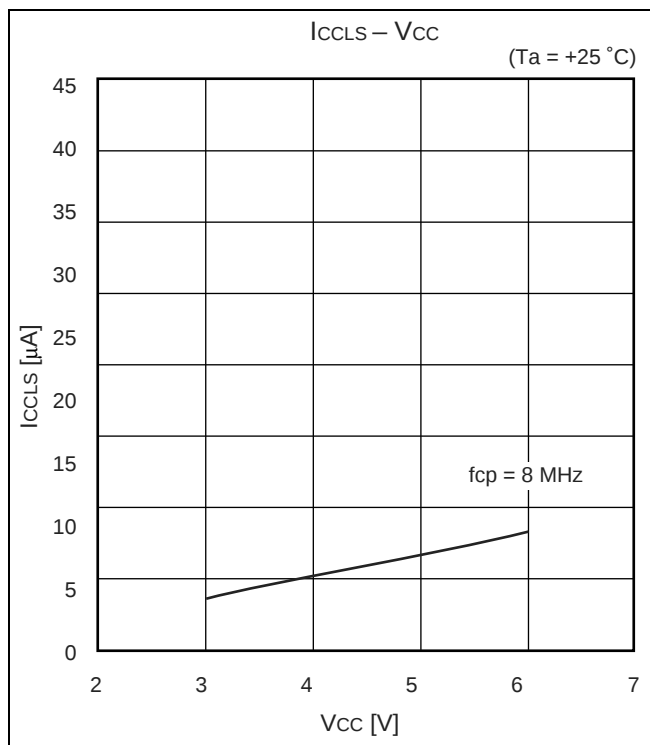
(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
RDY setup time	t_{RYHS}	RDY	—	45	—	ns	
RDY hold time	t_{RYHH}	RDY	—	0	—	ns	

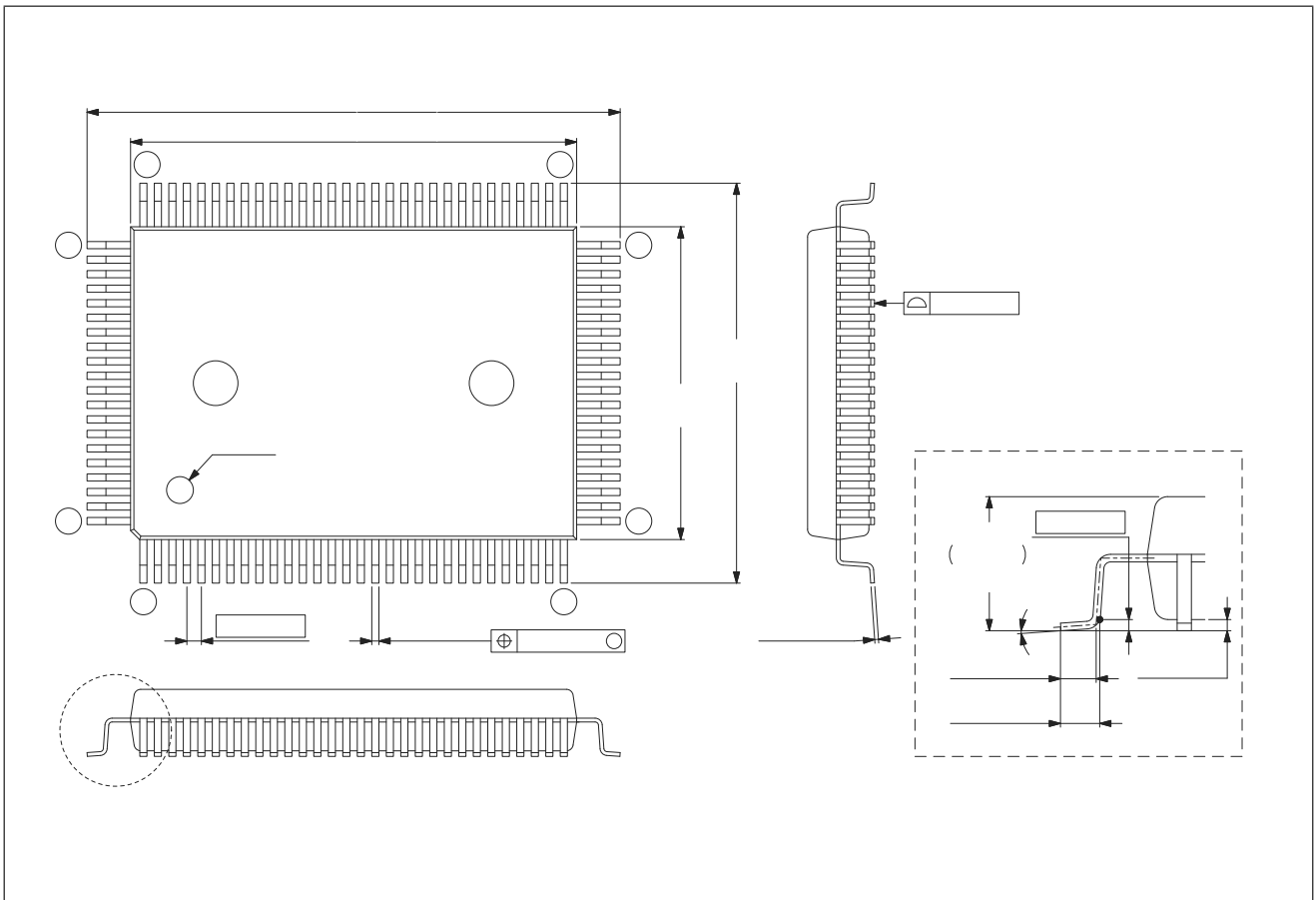
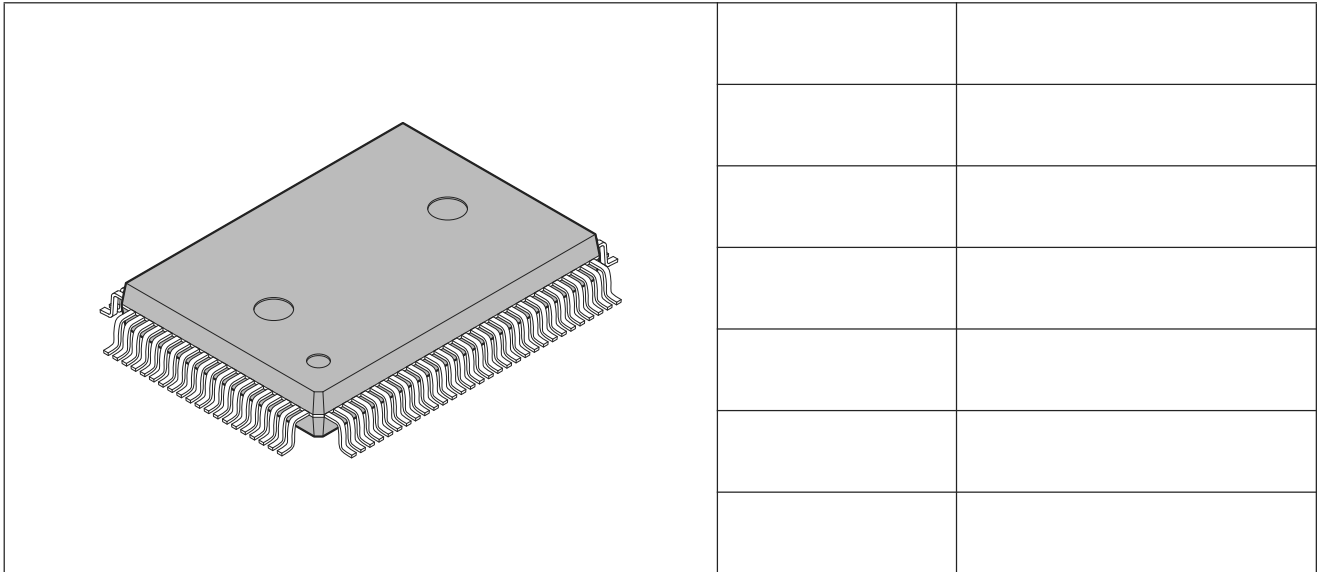
Note : If the RDY setup time is insufficient, use the auto-ready function.



Internal Shift Clock Mode

External Shift Clock Mode




14. Package Dimensions



(Continued)

(Continued)

