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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	F <sup>2</sup> MC-16LX
Core Size	16-Bit
Speed	16MHz
Connectivity	CANbus, EBI/EMI, SCI, Serial I/O, UART/USART
Peripherals	POR, WDT
Number of I/O	81
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-BQFP
Supplier Device Package	100-QFP (14x20)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/mb90f543gspf-g">https://www.e-xfl.com/product-detail/infineon-technologies/mb90f543gspf-g</a>

Starting by an external trigger input.  
Conversion time : 26.3  $\mu$ s

- FULL-CAN interfaces  
MB90540G series : 2 channels  
MB90545G series : 1 channel  
Conforming to Version 2.0 Part A and Part B

Flexible message buffering (mailbox and FIFO buffering can be mixed)

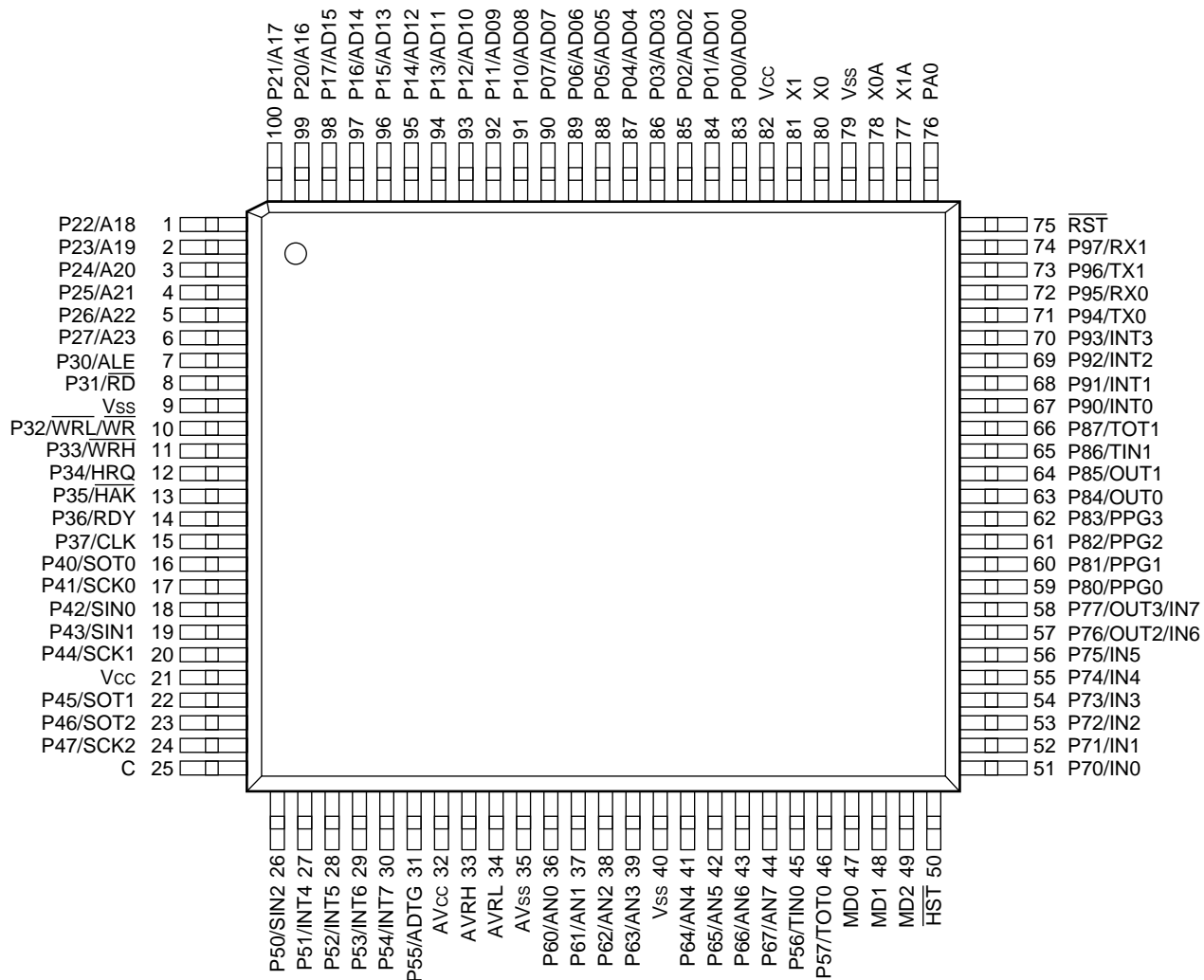
- External bus interface : Maximum address space 16 Mbytes
- Package: QFP-100, LQFP-100

\*2 : It is setting of DIP switch S2 when Emulation pod (MB2145-507) is used. Please refer to the MB2145-507 hardware manual (2.7 Emulator-specific Power Pin) about details.

\*3 : Operating Voltage Range

Products	Operation guarantee range
MB90F543G(S)/F546G(S)/F548G(S)/ MB90549G(S)/F549G(S)/V540/V540G	4.5 V to 5.5 V
MB90F548GL(S)/543G(S)/547G(S)/548G(S)	3.5 V to 5.5 V

(TOP VIEW)



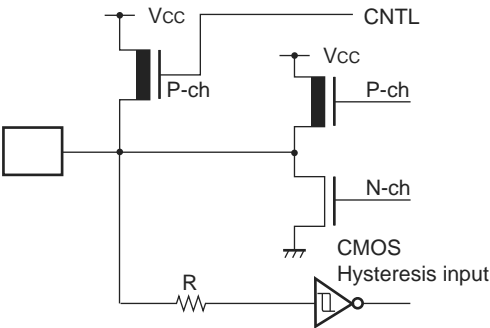
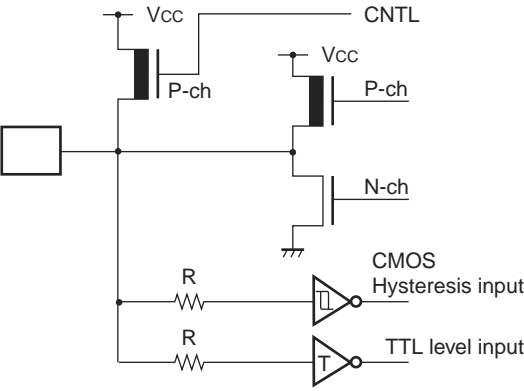
(FPT-100P-M20)

### 3. Pin Description

Pin No.		Pin name	Circuit type	Function
LQFP <sup>2</sup>	QFP <sup>1</sup>			
80 81	82 83	X0 X1	A (Oscillation)	High speed crystal oscillator input pins
78	80	X0A	A (Oscillation)	Low speed crystal oscillator input pins. For the one clock system parts, perform external pull-down processing.
77	79	X1A		Low speed crystal oscillator input pins. For the one clock system parts, leave it open.
75	77	$\overline{\text{RST}}$	B	External reset request input pin
50	52	$\overline{\text{HST}}$	C	Hardware standby input pin
83 to 90	85 to 92	P00 to P07	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		AD00 to AD07		I/O pins for 8 lower bits of the external address/data bus. This function is enabled when the external bus is enabled.
91 to 98	93 to 100	P10 to P17	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		AD08 to AD15		I/O pins for 8 higher bits of the external address/data bus. This function is enabled when the external bus is enabled.
99 to 6	1 to 8	P20 to P27	I	General I/O port with programmable pullup. In external bus mode, this function is valid when the corresponding bits in the external address output control resister (HACR) are set to "1".
		A16 to A23		8-bit I/O pins for A16 to A23 at the external address/data bus. In external bus mode, this function is valid when the corresponding bits in the external address output control resister (HACR) are set to "0".
7	9	P30	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		ALE		Address latch enable output pin. This function is enabled when the external bus is enabled.
8	10	P31	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		$\overline{\text{RD}}$		Read strobe output pin for the data bus. This function is enabled when the external bus is enabled.
10	12	P32	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the $\overline{\text{WR}}$ / $\overline{\text{WRL}}$ pin output is disabled.
		$\overline{\text{WRL}}$		Write strobe output pin for the data bus. This function is enabled when both the external bus and the $\overline{\text{WR}}$ / $\overline{\text{WRL}}$ pin output are enabled. $\overline{\text{WRL}}$ is write-strobe output pin for the lower 8 bits of the data bus in 16-bit access.
		$\overline{\text{WR}}$		$\overline{\text{WR}}$ is write-strobe output pin for the 8 bits of the data bus in 8-bit access.

(Continued)

(Continued)

Circuit type	Diagram	Remarks
H		<ul style="list-style-type: none"> <li>■ CMOS level output</li> <li>■ CMOS Hysteresis input</li> <li>■ Programmable pull-up resistor : 50 kΩ approx.</li> </ul>
I		<ul style="list-style-type: none"> <li>■ CMOS level output</li> <li>■ CMOS Hysteresis input</li> <li>■ TTL level input (Flash devices in Flash writer mode only)</li> <li>■ Programmable pullup resistor : 50 kΩ approx.</li> </ul>

**(6) Pull-up/down resistors**

The MB90540G/545G Series does not support internal pull-up/down resistors (except Port0 – Port3 : pull-up resistors) . Use external components where needed.

**(7) Crystal Oscillator Circuit**

Noises around X0 or X1 pins may be possible causes of abnormal operations. Make sure to provide bypass capacitors via the shortest distances from X0, X1 pins, crystal oscillator (or ceramic resonator) and ground lines, and make sure, to the utmost effort, that lines of oscillation circuits do not cross the lines of other circuits.

It is highly recommended to provide a printed circuit board artwork surrounding X0 and X1 pins with a ground area for stabilizing the operation.

**(8) Turning-on Sequence of Power Supply to A/D Converter and Analog Inputs**

Make sure to turn on the A/D converter power supply ( $AV_{CC}$ ,  $AV_{RH}$ ,  $AV_{RL}$ ) and analog inputs (AN0 to AN7) after turning-on the digital power supply ( $V_{CC}$ ) .

Turn-off the digital power after turning off the A/D converter supply and analog inputs. In this case, make sure that the voltage does not exceed  $AV_{RH}$  or  $AV_{CC}$  (turning on/off the analog and digital power supplies simultaneously is acceptable) .

**(9) Connection of Unused Pins of A/D Converter**

Connect unused pins of A/D converter to  $AV_{CC} = V_{CC}$ ,  $AV_{SS} = AV_{RH} = V_{SS}$ .

**(10) N.C. Pin**

The N.C. (internally connected) pin must be opened for use.

**(11) Notes on Energization**

To prevent the internal regulator circuit from malfunctioning, set the voltage rise time during energization at 50  $\mu$ s or more (0.2 V to 2.7 V) .

*(Continued)*

Address	Register	Abbreviation	Access	Resource name	Initial value
3928 <sub>H</sub>	Output Compare Register 0	OCCP0	R/W	Output Compare 0/1	XXXXXXXX <sub>B</sub>
3929 <sub>H</sub>	Output Compare Register 0	OCCP0	R/W		XXXXXXXX <sub>B</sub>
392A <sub>H</sub>	Output Compare Register 1	OCCP1	R/W		XXXXXXXX <sub>B</sub>
392B <sub>H</sub>	Output Compare Register 1	OCCP1	R/W		XXXXXXXX <sub>B</sub>
392C <sub>H</sub>	Output Compare Register 2	OCCP2	R/W	Output Compare 2/3	XXXXXXXX <sub>B</sub>
392D <sub>H</sub>	Output Compare Register 2	OCCP2	R/W		XXXXXXXX <sub>B</sub>
392E <sub>H</sub>	Output Compare Register 3	OCCP3	R/W		XXXXXXXX <sub>B</sub>
392F <sub>H</sub>	Output Compare Register 3	OCCP3	R/W		XXXXXXXX <sub>B</sub>
3930 <sub>H</sub> to 39FF <sub>H</sub>	Reserved				
3A00 <sub>H</sub> to 3AFF <sub>H</sub>	Reserved for CAN 0 Interface.				
3B00 <sub>H</sub> to 3BFF <sub>H</sub>	Reserved for CAN 0 Interface.				
3C00 <sub>H</sub> to 3CFF <sub>H</sub>	Reserved for CAN 1 Interface.				
3D00 <sub>H</sub> to 3DFF <sub>H</sub>	Reserved for CAN 1 Interface.				
3E00 <sub>H</sub> to 3FFF <sub>H</sub>	Reserved				

■ Read/write notation

R/W : Reading and writing permitted  
R : Read-only  
W : Write-only

■ Initial value notation

0 : Initial value is "0".  
1 : Initial value is "1".  
X : Initial value is undefined.  
\_ : Initial value is unused.

**Note:** Any write access to reserved addresses in I/O map should not be performed. A read access to reserved addresses results in reading "X".



## 9. CAN Controller

The MB90540G series contains two CAN controllers (CAN0 and CAN1) , the MB90545G series contains only one (CAN0) . The Evaluation Chip MB90V540G also has two CAN controllers.

The CAN controller has the following features :

- Conforms to CAN Specification Version 2.0 Part A and B
  - Supports transmission/reception in standard frame and extended frame formats
- Supports transmission of data frames by receiving remote frames
- 16 transmitting/receiving message buffers
  - 29-bit ID and 8-byte data
  - Multi-level message buffer configuration
- Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
  - Two acceptance mask registers in either standard frame format or extended frame formats
- Bit rate programmable from 10 Kbps to 1 Mbps (when input clock is at 16 MHz)

### List of Control Registers

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
000070 <sub>H</sub>	000080 <sub>H</sub>	Message buffer valid register	BVALR	R/W	00000000 00000000 <sub>B</sub>
000071 <sub>H</sub>	000081 <sub>H</sub>				
000072 <sub>H</sub>	000082 <sub>H</sub>	Transmit request register	TREQR	R/W	00000000 00000000 <sub>B</sub>
000073 <sub>H</sub>	000083 <sub>H</sub>				
000074 <sub>H</sub>	000084 <sub>H</sub>	Transmit cancel register	TCANR	W	00000000 00000000 <sub>B</sub>
000075 <sub>H</sub>	000085 <sub>H</sub>				
000076 <sub>H</sub>	000086 <sub>H</sub>	Transmit complete register	TCR	R/W	00000000 00000000 <sub>B</sub>
000077 <sub>H</sub>	000087 <sub>H</sub>				
000078 <sub>H</sub>	000088 <sub>H</sub>	Receive complete register	RCR	R/W	00000000 00000000 <sub>B</sub>
000079 <sub>H</sub>	000089 <sub>H</sub>				
00007A <sub>H</sub>	00008A <sub>H</sub>	Remote request receiving register	RRTRR	R/W	00000000 00000000 <sub>B</sub>
00007B <sub>H</sub>	00008B <sub>H</sub>				
00007C <sub>H</sub>	00008C <sub>H</sub>	Receive overrun register	ROVRR	R/W	00000000 00000000 <sub>B</sub>
00007D <sub>H</sub>	00008D <sub>H</sub>				
00007E <sub>H</sub>	00008E <sub>H</sub>	Receive interrupt enable register	RIER	R/W	00000000 00000000 <sub>B</sub>
00007F <sub>H</sub>	00008F <sub>H</sub>				

(Continued)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003A24 <sub>H</sub>	003C24 <sub>H</sub>	ID register 1	IDR1	R/W	XXXXXXXX XXXXXXXX <sub>B</sub>
003A25 <sub>H</sub>	003C25 <sub>H</sub>				
003A26 <sub>H</sub>	003C26 <sub>H</sub>				XXXXXX--- XXXXXXXX <sub>B</sub>
003A27 <sub>H</sub>	003C27 <sub>H</sub>				
003A28 <sub>H</sub>	003C28 <sub>H</sub>	ID register 2	IDR2	R/W	XXXXXXXX XXXXXXXX <sub>B</sub>
003A29 <sub>H</sub>	003C29 <sub>H</sub>				
003A2A <sub>H</sub>	003C2A <sub>H</sub>				XXXXXX--- XXXXXXXX <sub>B</sub>
003A2B <sub>H</sub>	003C2B <sub>H</sub>				
003A2C <sub>H</sub>	003C2C <sub>H</sub>	ID register 3	IDR3	R/W	XXXXXXXX XXXXXXXX <sub>B</sub>
003A2D <sub>H</sub>	003C2D <sub>H</sub>				
003A2E <sub>H</sub>	003C2E <sub>H</sub>				XXXXXX--- XXXXXXXX <sub>B</sub>
003A2F <sub>H</sub>	003C2F <sub>H</sub>				
003A30 <sub>H</sub>	003C30 <sub>H</sub>	ID register 4	IDR4	R/W	XXXXXXXX XXXXXXXX <sub>B</sub>
003A31 <sub>H</sub>	003C31 <sub>H</sub>				
003A32 <sub>H</sub>	003C32 <sub>H</sub>				XXXXXX--- XXXXXXXX <sub>B</sub>
003A33 <sub>H</sub>	003C33 <sub>H</sub>				
003A34 <sub>H</sub>	003C34 <sub>H</sub>	ID register 5	IDR5	R/W	XXXXXXXX XXXXXXXX <sub>B</sub>
003A35 <sub>H</sub>	003C35 <sub>H</sub>				
003A36 <sub>H</sub>	003C36 <sub>H</sub>				XXXXXX--- XXXXXXXX <sub>B</sub>
003A37 <sub>H</sub>	003C37 <sub>H</sub>				
003A38 <sub>H</sub>	003C38 <sub>H</sub>	ID register 6	IDR6	R/W	XXXXXXXX XXXXXXXX <sub>B</sub>
003A39 <sub>H</sub>	003C39 <sub>H</sub>				
003A3A <sub>H</sub>	003C3A <sub>H</sub>				XXXXXX--- XXXXXXXX <sub>B</sub>
003A3B <sub>H</sub>	003C3B <sub>H</sub>				

(Continued)

**List of Message Buffers (DLC Registers and Data Registers)**

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003A60 <sub>H</sub>	003C60 <sub>H</sub>	DLC register 0	DLCR0	R/W	----XXXX <sub>B</sub>
003A61 <sub>H</sub>	003C61 <sub>H</sub>				
003A62 <sub>H</sub>	003C62 <sub>H</sub>	DLC register 1	DLCR1	R/W	----XXXX <sub>B</sub>
003A63 <sub>H</sub>	003C63 <sub>H</sub>				
003A64 <sub>H</sub>	003C64 <sub>H</sub>	DLC register 2	DLCR2	R/W	----XXXX <sub>B</sub>
003A65 <sub>H</sub>	003C65 <sub>H</sub>				
003A66 <sub>H</sub>	003C66 <sub>H</sub>	DLC register 3	DLCR3	R/W	----XXXX <sub>B</sub>
003A67 <sub>H</sub>	003C67 <sub>H</sub>				
003A68 <sub>H</sub>	003C68 <sub>H</sub>	DLC register 4	DLCR4	R/W	----XXXX <sub>B</sub>
003A69 <sub>H</sub>	003C69 <sub>H</sub>				
003A6A <sub>H</sub>	003C6A <sub>H</sub>	DLC register 5	DLCR5	R/W	----XXXX <sub>B</sub>
003A6B <sub>H</sub>	003C6B <sub>H</sub>				
003A6C <sub>H</sub>	003C6C <sub>H</sub>	DLC register 6	DLCR6	R/W	----XXXX <sub>B</sub>
003A6D <sub>H</sub>	003C6D <sub>H</sub>				
003A6E <sub>H</sub>	003C6E <sub>H</sub>	DLC register 7	DLCR7	R/W	----XXXX <sub>B</sub>
003A6F <sub>H</sub>	003C6F <sub>H</sub>				
003A70 <sub>H</sub>	003C70 <sub>H</sub>	DLC register 8	DLCR8	R/W	----XXXX
003A71 <sub>H</sub>	003C71 <sub>H</sub>				
003A72 <sub>H</sub>	003C72 <sub>H</sub>	DLC register 9	DLCR9	R/W	----XXXX <sub>B</sub>
003A73 <sub>H</sub>	003C73 <sub>H</sub>				
003A74 <sub>H</sub>	003C74 <sub>H</sub>	DLC register 10	DLCR10	R/W	----XXXX <sub>B</sub>
003A75 <sub>H</sub>	003C75 <sub>H</sub>				
003A76 <sub>H</sub>	003C76 <sub>H</sub>	DLC register 11	DLCR11	R/W	----XXXX <sub>B</sub>
003A77 <sub>H</sub>	003C77 <sub>H</sub>				
003A78 <sub>H</sub>	003C78 <sub>H</sub>	DLC register 12	DLCR12	R/W	----XXXX <sub>B</sub>
003A79 <sub>H</sub>	003C79 <sub>H</sub>				
003A7A <sub>H</sub>	003C7A <sub>H</sub>	DLC register 13	DLCR13	R/W	----XXXX <sub>B</sub>
003A7B <sub>H</sub>	003C7B <sub>H</sub>				
003A7C <sub>H</sub>	003C7C <sub>H</sub>	DLC register 14	DLCR14	R/W	----XXXX <sub>B</sub>
003A7D <sub>H</sub>	003C7D <sub>H</sub>				
003A7E <sub>H</sub>	003C7E <sub>H</sub>	DLC register 15	DLCR15	R/W	----XXXX <sub>B</sub>
003A7F <sub>H</sub>	003C7F <sub>H</sub>				
003A80 <sub>H</sub> to 003A87 <sub>H</sub>	003C80 <sub>H</sub> to 003C87 <sub>H</sub>	Data register 0 (8 bytes)	DTR0	R/W	XXXXXXXX <sub>B</sub> to XXXXXXXX <sub>B</sub>

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## 11.4 AC Characteristics

### 11.4.1 Clock Timing

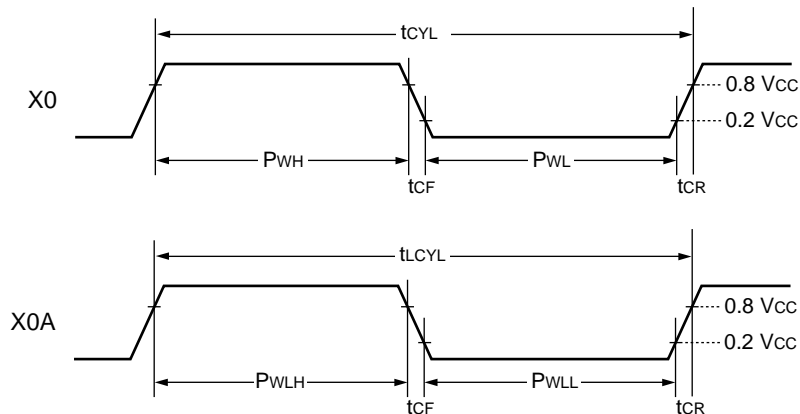
(MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 3.5 \text{ V to } 5.5 \text{ V}$ ,  $V_{SS} = AV_{SS} = 0.0 \text{ V}$ ,  $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ )

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 5.0 \text{ V} \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0.0 \text{ V}$ ,  $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ )

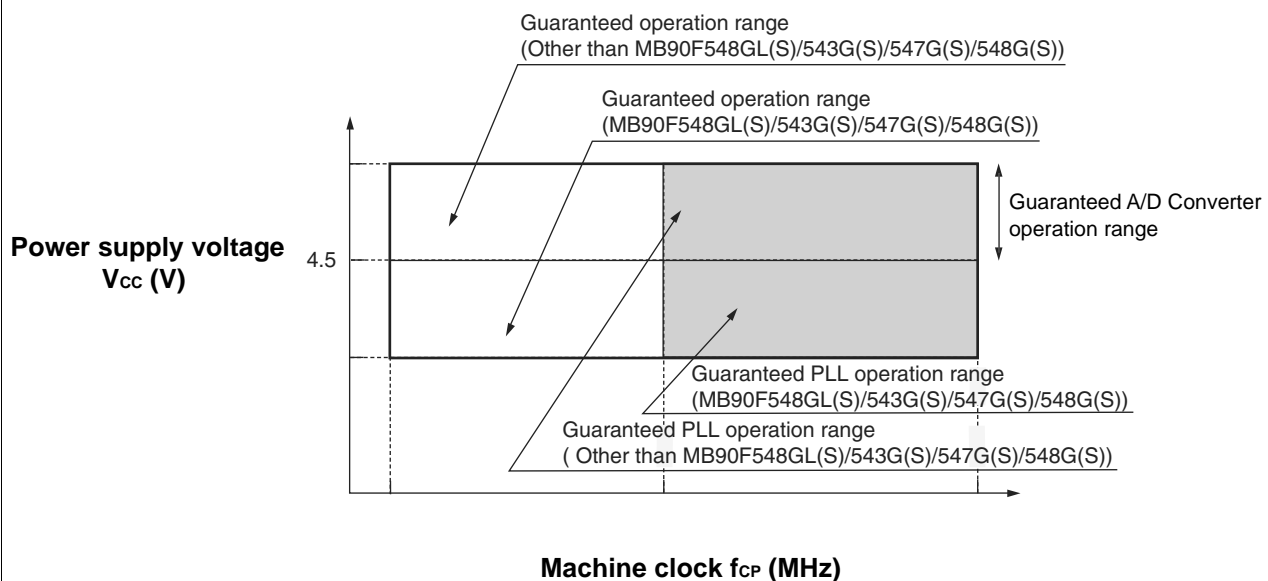
Parameter	Symbol	Pin name	Value			Units	Remarks
			Min	Typ	Max		
Oscillation frequency	$f_c$	X0, X1	3	—	16	MHz	No multiplier When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			8	—	16	MHz	PLL multiplied by 1 When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			4	—	8	MHz	PLL multiplied by 2 When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			3	—	5.33	MHz	PLL multiplied by 3 When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			3	—	4	MHz	PLL multiplied by 4 When using an oscillator circuit $V_{CC} = 5.0 \text{ V} \pm 10\%$
			3	—	5	MHz	When using an oscillator circuit $V_{CC} < 4.5 \text{ V}$ (MB90F548GL(S)/543G(S)/ 547G(S)/548G(S))
			3	—	16	MHz	No multiplier When using an external clock
			8	—	16	MHz	PLL multiplied by 1 When using an external clock
			4	—	8	MHz	PLL multiplied by 2 When using an external clock
			3	—	5.33	MHz	PLL multiplied by 3 When using an external clock
			3	—	4	MHz	PLL multiplied by 4 When using an external clock
	$f_{CL}$	X0A, X1A	—	32.768	—	kHz	

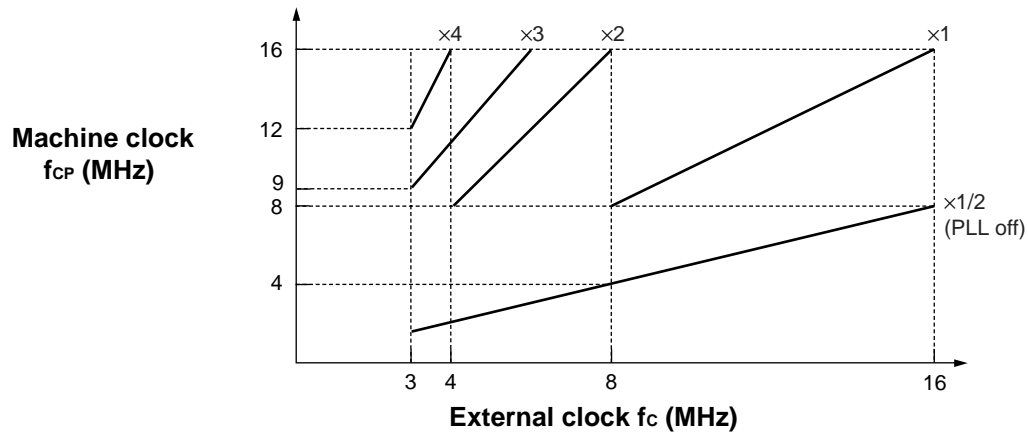
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### ■ Clock Timing



### ■ Guaranteed PLL operation range



**■ External clock frequency and Machine clock frequency**


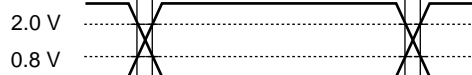
AC characteristics are set to the measured reference voltage values below.

**■ Input signal waveform**

Hysteresis Input Pin



TTL Input Pin


**■ Output signal waveform**

Output Pin



**11.4.5 Bus Timing (Read)**

(MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 3.5\text{ V to }5.5\text{ V}$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 5.0\text{ V} \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

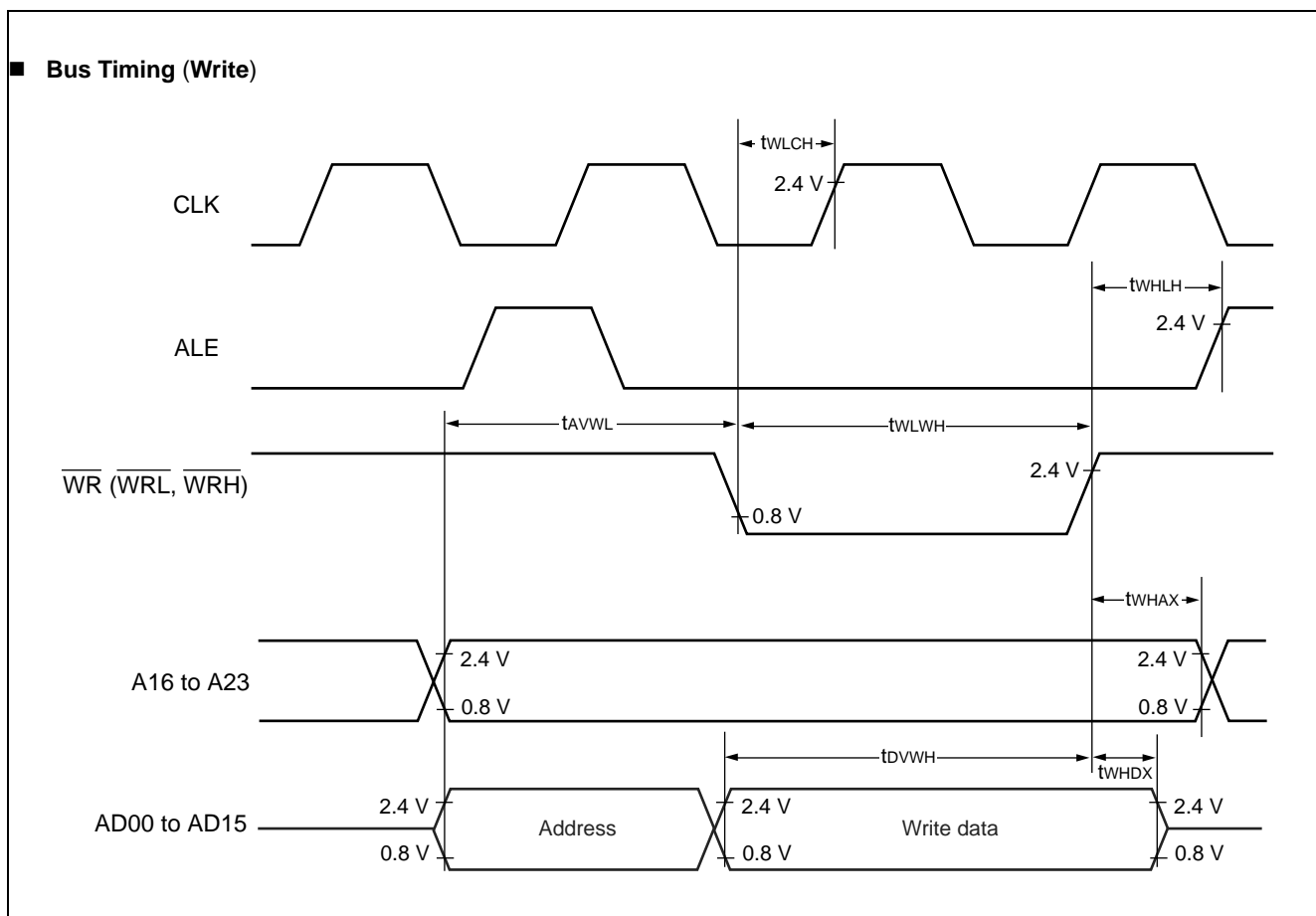
Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
ALE pulse width	$t_{LHLL}$	ALE	—	$t_{CP}/2 - 20$	—	ns	
Valid address → ALE↓ time	$t_{AVLL}$	ALE, A16 to A23, AD00 to AD15		$t_{CP}/2 - 20$	—	ns	
ALE↓ → Address valid time	$t_{LLAX}$	ALE, AD00 to AD15		$t_{CP}/2 - 15$	—	ns	
Valid address → $\overline{RD}$ ↓ time	$t_{AVRL}$	A16 to A23, AD00 to AD15, RD		$t_{CP} - 15$	—	ns	
Valid address → Valid data input	$t_{AVDV}$	A16 to A23, AD00 to AD15		—	$5 t_{CP}/2 - 60$	ns	
$\overline{RD}$ pulse width	$t_{RLRH}$	RD		$3 t_{CP}/2 - 20$	—	ns	
$\overline{RD}$ ↓ → Valid data input	$t_{RLDV}$	$\overline{RD}$ , AD00 to AD15		—	$3 t_{CP}/2 - 60$	ns	
$\overline{RD}$ ↑ → Data hold time	$t_{RHDX}$	$\overline{RD}$ , AD00 to AD15		0	—	ns	
$\overline{RD}$ ↑ → ALE↑ time	$t_{RHLH}$	$\overline{RD}$ , ALE		$t_{CP}/2 - 15$	—	ns	
$\overline{RD}$ ↑ → Address valid time	$t_{RHAX}$	$\overline{RD}$ , A16 to A23		$t_{CP}/2 - 10$	—	ns	
Valid address → CLK↑ time	$t_{AVCH}$	A16 to A23, AD00 to AD15, CLK		$t_{CP}/2 - 20$	—	ns	
$\overline{RD}$ ↓ → CLK↑ time	$t_{RLCH}$	$\overline{RD}$ , CLK		$t_{CP}/2 - 20$	—	ns	
ALE↓ → $\overline{RD}$ ↓ time	$t_{LLRL}$	ALE, $\overline{RD}$		$t_{CP}/2 - 15$	—	ns	

#### 11.4.6 Bus Timing (Write)

(MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 3.5\text{ V to }5.5\text{ V}$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 5.0\text{ V} \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
Valid address $\rightarrow \overline{WR}\downarrow$ time	$t_{AVWL}$	A16 to A23 AD00 to AD15, $\overline{WR}$	—	$t_{CP} - 15$	—	ns	
$\overline{WR}$ pulse width	$t_{WLWH}$	$\overline{WR}$		$3 t_{CP}/2 - 20$	—	ns	
Valid data output $\rightarrow \overline{WR}\uparrow$ time	$t_{DVWH}$	AD00 to AD15, $\overline{WR}$		$3 t_{CP}/2 - 20$	—	ns	
$\overline{WR}\uparrow \rightarrow$ Data hold time	$t_{WHDX}$	AD00 to AD15, $\overline{WR}$		20	—	ns	
$\overline{WR}\uparrow \rightarrow$ Address valid time	$t_{WHAX}$	A16 to A23, $\overline{WR}$		$t_{CP}/2 - 10$	—	ns	
$\overline{WR}\uparrow \rightarrow$ ALE $\uparrow$ time	$t_{WHLH}$	$\overline{WR}$ , ALE		$t_{CP}/2 - 15$	—	ns	
$\overline{WR}\uparrow \rightarrow$ CLK $\uparrow$ time	$t_{WLCH}$	$\overline{WR}$ , CLK		$t_{CP}/2 - 20$	—	ns	



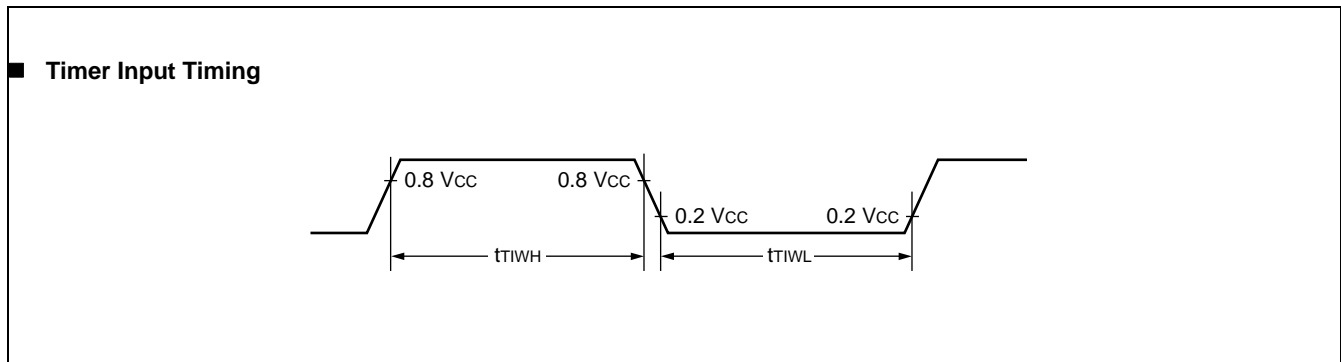


#### 11.4.10 Timer Input Timing

(MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 3.5\text{ V to }5.5\text{ V}$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 5.0\text{ V} \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
Input pulse width	$t_{TIWH}$	TIN0, TIN1	—	$4\ t_{CP}$	—	ns	
	$t_{TIWL}$	IN0 to IN7					

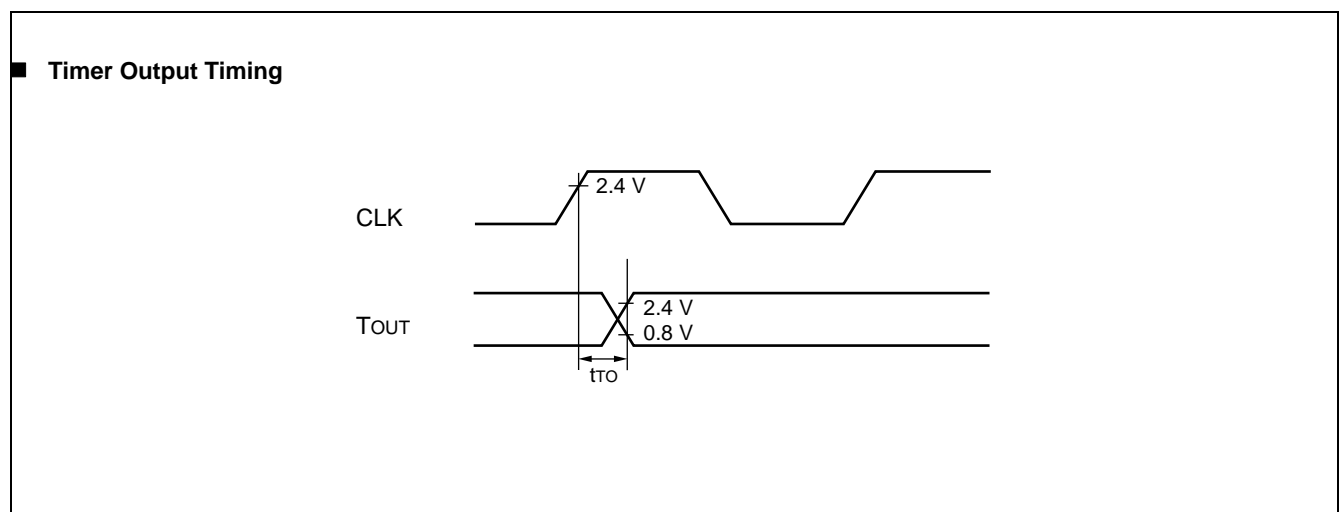


#### 11.4.11 Timer Output Timing

(MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 3.5\text{ V to }5.5\text{ V}$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 5.0\text{ V} \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
CLK $\uparrow$ $\rightarrow$ TOUT change time	$t_{TO}$	TOT0, TOT1, PPG0 to PPG3	—	30	—	ns	



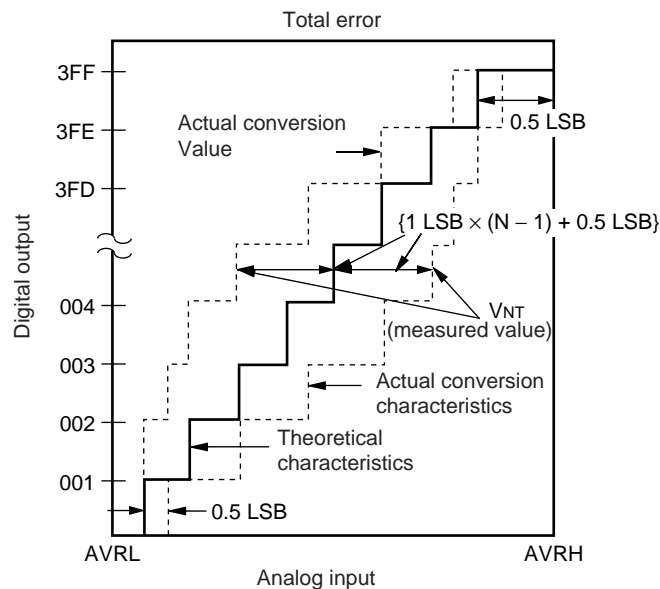
### 11.5.2 A/D Converter Glossary

**Resolution :** Analog changes that are identifiable with the A/D converter

**Linearity error :** The deviation of the straight line connecting the zero transition point ("00 0000 0000" ↔ "00 0000 0001") with the full-scale transition point ("11 1111 1110" ↔ "11 1111 1111") from actual conversion characteristics

**Differential linearity error :** The deviation of input voltage needed to change the output code by 1 LSB from the theoretical value

**Total error :** The total error is defined as a difference between the actual value and the theoretical value, which includes zero-transition error/full-scale transition error and linearity error.



$$1 \text{ LSB} = (\text{Theoretical value}) \frac{AVRH - AVRL}{1024} [\text{V}]$$

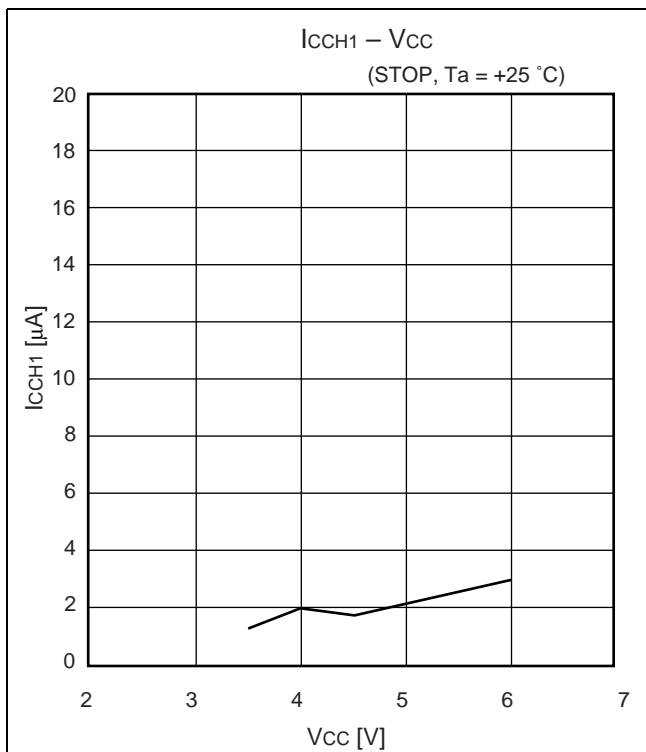
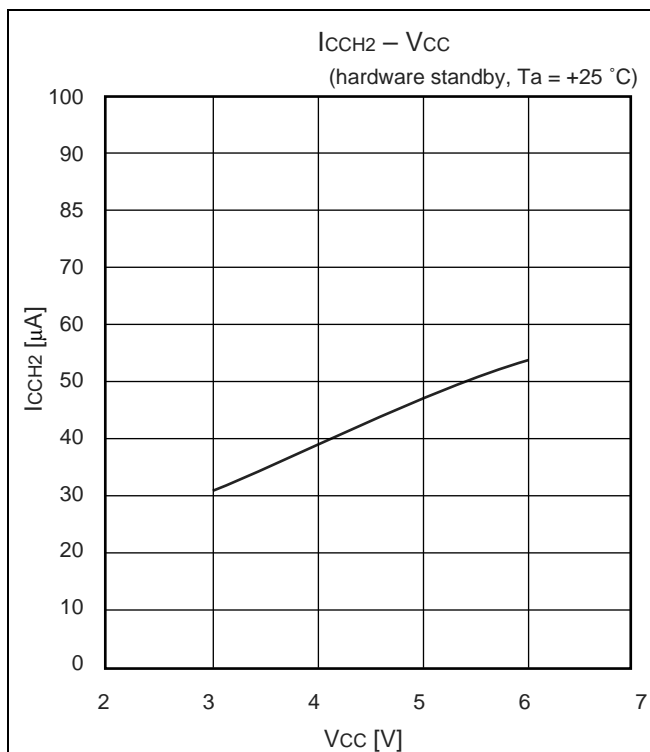
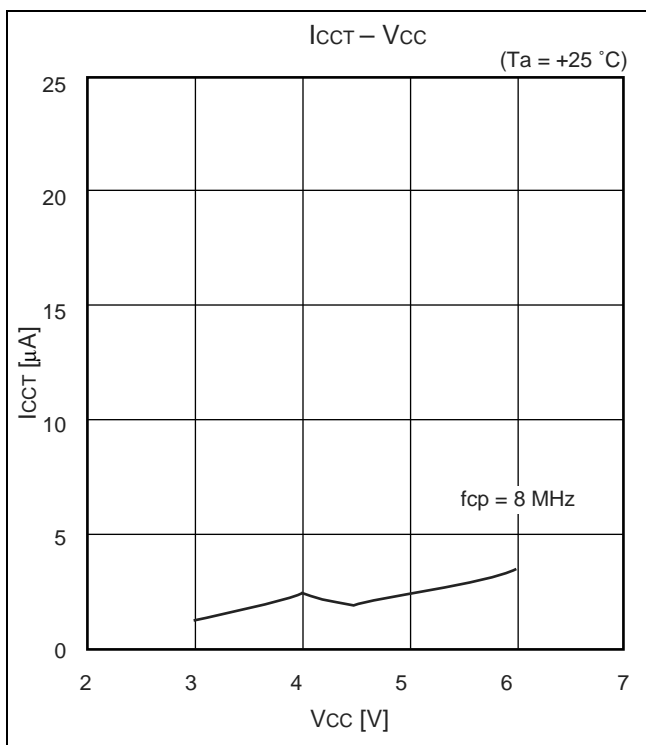
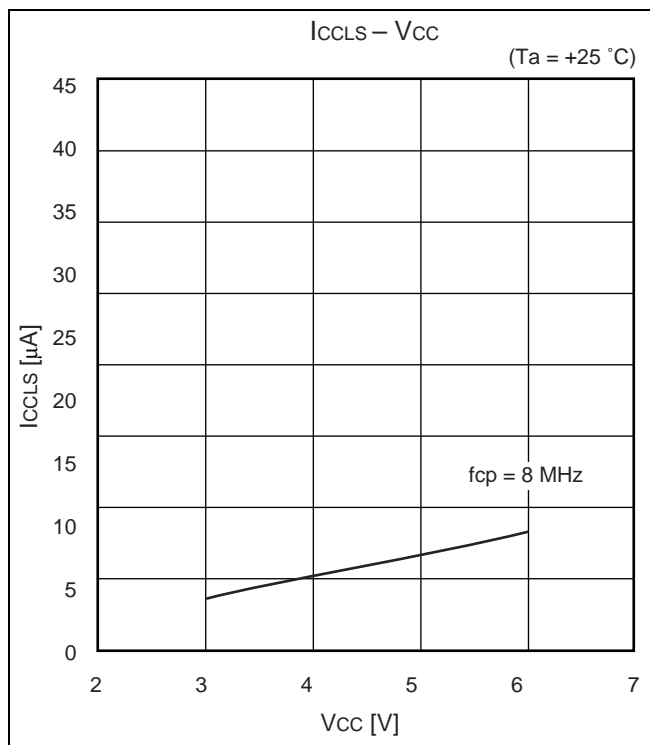
$$V_{OT} (\text{Theoretical value}) = AVRL + 0.5 \text{ LSB} [\text{V}]$$

$$V_{FST} (\text{Theoretical value}) = AVRH - 1.5 \text{ LSB} [\text{V}]$$

$$\text{Total error for digital output } N = \frac{V_{NT} - \{1 \text{ LSB} \times (N - 1) + 0.5 \text{ LSB}\}}{1 \text{ LSB}} [\text{LSB}]$$

$V_{NT}$  : Voltage at a transition of digital output from (N - 1) to N

(Continued)



## 15. Major Changes

Spanson Publication Number: DS07-13703-7E

Section	Change Results
■ PRODUCT LINEUP	Changed the name in peripheral resource. 16-bit I/O Timer → 16-bit Free-run Timer
■ I/O CIRCUIT TYPE	Changed the name of input typ. Hysteresis → CMOS Hysteresis HYS → CMOS Hysteresis
■ BLOCK DIAGRAM	Changed the arrow direction of SOT1 signal at UART1(SCI). “← →” (input/output) → “←” (output)
■ I/O MAP	Changed the text of “Note”.
■ INTERRUPT MAP	Changed the name of peripheral resource of the pin number: #19. I/O Timer → 16-bit Free-run Timer
■ ELECTRICAL CHARACTERISTICS	Changed the remarks of “parameter: Power supply voltage”.
2. Recommended Conditions	
3. DC Characteristics	Changed the maximum value of symbol : VILM of parameter: Input voltage. $V_{CC} + 0.3 \rightarrow V_{SS} + 0.3$ Added the following remarks for parameter : Pull-down resistance. Except Flash device
4. AC Characteristics	Added the value when using an external clock in Oscillation frequency and Clock cycle time on (1) Clock Timing for parameter.
(1) Clock Timing	Added the item of A/D converter operation range in figure of “■ Guaranteed PLL operation range”
(3) Reset and Hardware Standby Input Timing	Changed the following item. (3) Reset and Hardware Standby Input Timing Remarks: In sub-clock mode, sub-sleep mode, timer mode $2t_{CP} \rightarrow 2t_{LCP}$
(4) Power On Reset	Changed as follows; Due to repetitive operation → Waiting time until power-on
5. A/D Converter	Changed the unit of Zero transition voltage and Full scale transition voltage. mV → V
■ ORDERING INFORMATION	Added the MB90F548GLPMC in Part Numbers.

**NOTE:** Please see “Document History” about later revised information.

## Document History

Document Title: MB90F543G(S)/546G(S)/548G(S)/549G(S)/549G(S)/V540G/MB90543G(S)/547G(S)/548G(S)/F548GL(S) CMOS F2MC-16LX MB90540G/545G Series 16-bit Proprietary Microcontroller Document Number: 002-07696				
Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	—	AKIH	11/13/2008	Migrated to Cypress and assigned document number 002-07696. No change to document contents or format.
*A	5537115	AKIH	11/30/2016	Updated to Cypress template

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