Infineon Technologies - MB90F543GSPF-GS-9016 Datasheet

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	F²MC-16LX
Core Size	16-Bit
Speed	16MHz
Connectivity	CANbus, EBI/EMI, SCI, Serial I/O, UART/USART
Peripherals	POR, WDT
Number of I/O	81
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-BQFP
Supplier Device Package	100-QFP (14x20)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90f543gspf-gs-9016

Features	MB90F543G (S) /F548G (S) MB90F549G (S) /F546G (S) MB90F548GL(S)	MB90543G (S) MB90547G (S) MB90548G (S) MB90549G (S)	MB90V540G
16-bit Reload Timer (2 channels)	Operation clock frequency : fsys/2^1, fsys/2^3, fsys/2^5 (fsys = System clock frequency) Supports External Event Count function Signals an interrupt when overflow		
16-bit Free-run Timer	Supports Timer Clear when a match with Output Compare (Channel 0) Operation clock freq. : fsys/2^2, fsys/2^4, fsys/2^6, fsys/2^8 (fsys = System clock freq.)		
16-bit Output Compare (4 channels)	Signals an interrupt when a match with 16-bit Free-run Timer Four 16-bit compare registers A pair of compare registers can be used to generate an output signal		
16-bit Input Capture (8 channels)	Rising edge, falling edge or rising & falling edge sensitive Four 16-bit Capture registers Signals an interrupt upon external event		
8/16-bit Programmable Pulse Generator (4 channels)	Supports 8-bit and 16-bit operation modes Eight 8-bit reload counters Eight 8-bit reload registers for L pulse width Eight 8-bit reload registers for H pulse width A pair of 8-bit reload counters can be configured as one 16-bit reload counter or as 8-bit prescaler plus 8-bit reload counter 4 output pins Operation clock freq. : fsys, fsys/2^1, fsys/2^2, fsys/2^3, fsys/2^4 or 128 µs@fosc = 4 MHz (fsys = System clock frequency, fosc = Oscillation clock frequency)		
CAN Interface MB90540G series : 2 channels MB90545G series : 1 channel	Conforms to CAN Specification Version 2.0 Part A and B Automatic re-transmission in case of error Automatic transmission responding to Remote Frame Prioritized 16 massage buffers for data and ID's supports multipe massages Flexible configuration of acceptance filtering : Full bit compare/Full bit mask/Two partial bit masks Supports up to 1 Mbps		
32 kHz Sub-clock	Sub-clock for low power operation		
External Interrupt (8 channels)	Can be programmed edge sensitive or level sensitive		
External bus interface	External access using the selectable 8-bit or 16-bit bus is enabled (external bus mode.)		
I/O Ports	Virtually all external pins can be used as general purpose I/O All push-pull outputs and schmitt trigger inputs Bit-wise programmable as input/output or peripheral signal Sub-clock for 32 kHz Sub clock low power operation		
Flash Memory	Supports automatic programming, Embeded Algorithm Write/Erase/Erase-Suspend/Erase-Resume commands A flag indicating completion of the algorithm Number of erase cycles : 10,000 times Data retention time : 10 years Boot block configuration Erase can be performed on each block Block protection by externally programmed voltage		

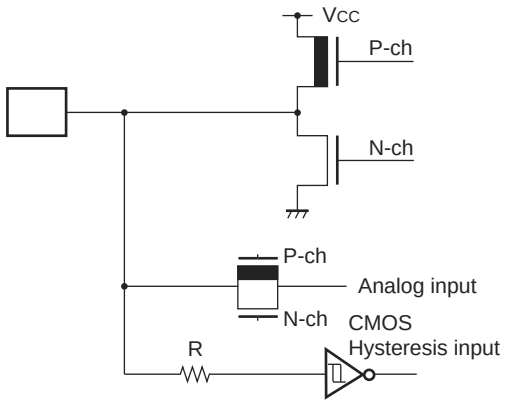
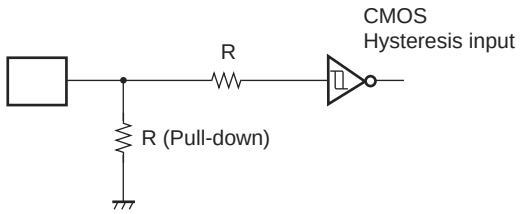
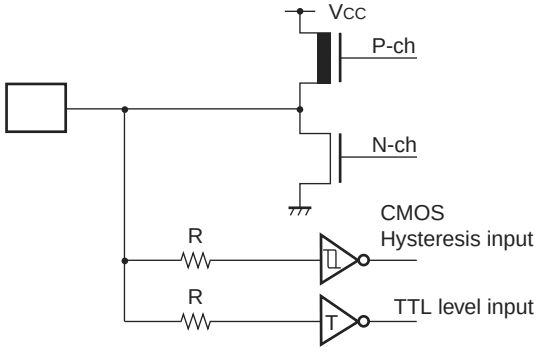
*1 : If the one clock system is used, equip X0A and X1A with clocks from the tool side.

(Continued)

Pin No.		Pin name	Circuit type	Function
LQFP*2	QFP*1			
72	74	P95	D	General I/O port. This function is always enabled.
		RX0		RX input pin for CAN0 Interface. When the CAN function is used, output from the other functions must be stopped.
73	75	P96	D	General I/O port. This function is enabled when CAN1 disables the output.
		TX1		TX output pin for CAN1. This function is enabled when CAN1 enables the output (only MB90540G series) .
74	76	P97	D	General I/O port. This function is always enabled.
		RX1		RX input pin for CAN1 Interface. When the CAN function is used, output from the other functions must be stopped (only MB90540G series) .
76	78	PA0	D	General I/O port. This function is always enabled.
32	34	AV_{CC}	Power supply	Power supply pin for the A/D Converter. This power supply must be turned on or off while a voltage higher than or equal to AV_{CC} is applied to V_{CC}.
35	37	AV_{SS}	Power supply	Power supply pin for the A/D Converter.
33	35	AVRH	Power supply	External reference voltage input pin for the A/D Converter. This power supply must be turned on or off while a voltage higher than or equal to AVRH is applied to AV_{CC}.
34	36	AVRL	Power supply	External reference voltage input pin for the A/D Converter.
47, 48	49, 50	MD0, MD1	C	Input pins for specifying the operating mode. The pins must be directly connected to V_{CC} or V_{SS}.
49	51	MD2	F	Input pin for specifying the operating mode. The pin must be directly connected to V_{CC} or V_{SS}.
25	27	C	—	Power supply stabilization capacitor pin. It should be connected externally to an 0.1 µF ceramic capacitor.
21, 82	23, 84	V_{CC}	Power supply	Input pin for power supply (5.0 V) .
9, 40, 79	11, 42, 81	V_{SS}	Power supply	Input pin for power supply (0.0 V) .

*1 : FPT-100P-M06

*2 : FPT-100P-M20

Circuit type	Diagram	Remarks
E		■ CMOS level output ■ CMOS Hysteresis input ■ Analog input
F		■ CMOS Hysteresis input ■ Pull-down Resistor : 50 kΩ approx. (except Flash devices)
G		■ CMOS level output ■ CMOS Hysteresis input ■ TTL level input (Flash devices in Flash writer mode only)

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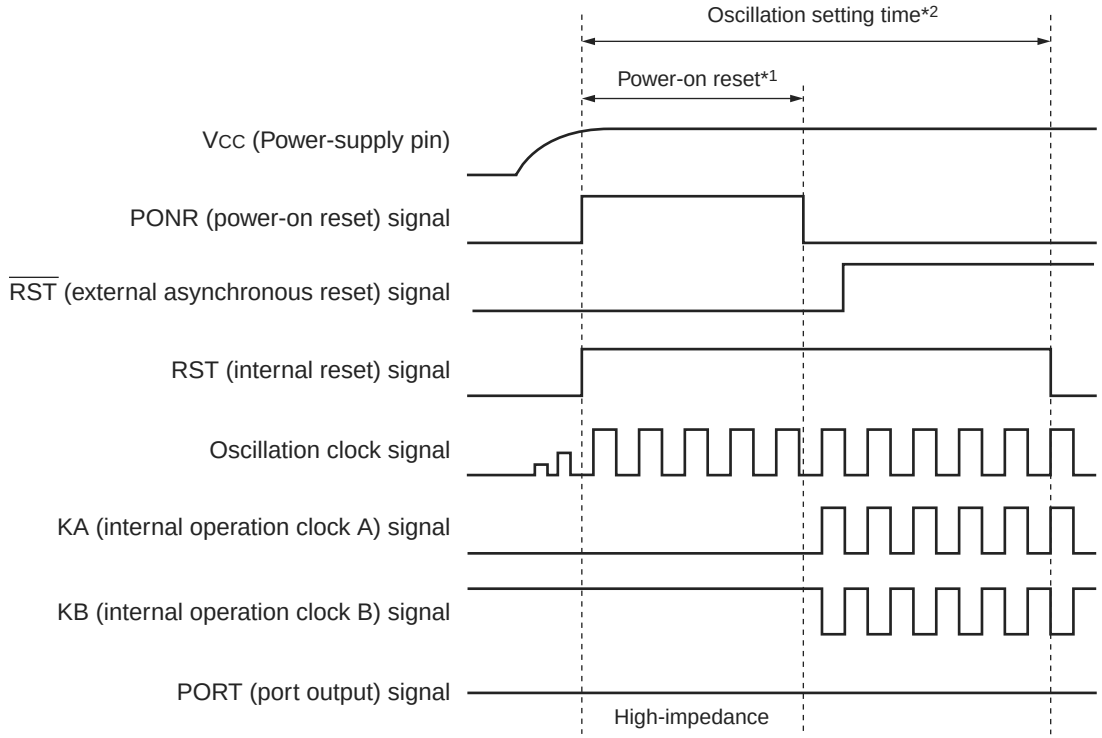
■ $\overline{\text{RST}}$ pin is “L”



*1 : Power-on reset time : “Period of clock frequency” × 2^{17} (Clock frequency of 16 MHz : 8.19 ms)

*2 : Oscillation setting time : “Period of clock frequency” × 2^{18} (Clock frequency of 16 MHz : 16.38 ms)

(13) Initialization

In the device, there are internal registers which are initialized only by a power-on reset. To initialize these registers, please turn on the power again.

(14) Directions of “DIV A, Ri” and “DIVW A, RWi” instructions

In the Signed multiplication and division instructions (“DIV A, Ri” and “DIVW A, RWi”) , the value of the corresponding bank register (DTB, ADB, USB, SSB) is set in “00_H”.

If the values of the corresponding bank registers (DTB, ADB, USB, SSB) are set to other than “00_H”, the remainder by the execution result of the instruction is not stored in the register of the instruction operand.

(15) Using REALOS

The use of EI²OS is not possible with the REALOS real time operating system.

(16) Caution on Operations during PLL Clock Mode

If the PLL clock mode is selected, the microcontroller attempt to be working with the self-oscillating circuit even when there is no external oscillator or external clock input is stopped. Performance of this operation, however, cannot be guaranteed.

Address	Register	Abbreviation	Access	Resource name	Initial value
$A2_H$ to $A4_H$	Prohibited				
$A5_H$	Automatic ready function select register	ARSR	W	External Memory Access	0 0 1 1 _ _ 0 0_B
$A6_H$	External address output control register	HACR	W		0 0 0 0 0 0 0 0_B
$A7_H$	Bus control signal selection register	ECSR	W		0 0 0 0 0 0 0 $_B$
$A8_H$	Watchdog Timer control register	WDTC	R/W	Watchdog Timer	XXXXX 1 1 1_B
$A9_H$	Time Base Timer Control register	TBTC	R/W	Time Base Timer	1 - - 0 0 1 0 0_B
AA_H	Watch timer control register	WTC	R/W	Watch Timer	1 X 0 0 0 0 0 0_B
AB_H to AD_H	Prohibited				
AE_H	Flash memory control status register (Flash only, otherwise reserved)	FMCS	R/W	Flash Memory	0 0 0 X 0 0 0 0_B
AF_H	Prohibited				
$B0_H$	Interrupt control register 00	ICR00	R/W	Interrupt controller	0 0 0 0 0 1 1 1_B
$B1_H$	Interrupt control register 01	ICR01	R/W		0 0 0 0 0 1 1 1_B
$B2_H$	Interrupt control register 02	ICR02	R/W		0 0 0 0 0 1 1 1_B
$B3_H$	Interrupt control register 03	ICR03	R/W		0 0 0 0 0 1 1 1_B
$B4_H$	Interrupt control register 04	ICR04	R/W		0 0 0 0 0 1 1 1_B
$B5_H$	Interrupt control register 05	ICR05	R/W		0 0 0 0 0 1 1 1_B
$B6_H$	Interrupt control register 06	ICR06	R/W		0 0 0 0 0 1 1 1_B
$B7_H$	Interrupt control register 07	ICR07	R/W		0 0 0 0 0 1 1 1_B
$B8_H$	Interrupt control register 08	ICR08	R/W		0 0 0 0 0 1 1 1_B
$B9_H$	Interrupt control register 09	ICR09	R/W		0 0 0 0 0 1 1 1_B
BA_H	Interrupt control register 10	ICR10	R/W		0 0 0 0 0 1 1 1_B
BB_H	Interrupt control register 11	ICR11	R/W		0 0 0 0 0 1 1 1_B
BC_H	Interrupt control register 12	ICR12	R/W		0 0 0 0 0 1 1 1_B
BD_H	Interrupt control register 13	ICR13	R/W		0 0 0 0 0 1 1 1_B
BE_H	Interrupt control register 14	ICR14	R/W		0 0 0 0 0 1 1 1_B
BF_H	Interrupt control register 15	ICR15	R/W		0 0 0 0 0 1 1 1_B
$C0_H$ to FF_H	External				

Address	Register	Abbreviation	Access	Resource name	Initial value
$1FF0_H$	Program address detection register 0	PADR0	R/W	Address Match Detection Function	$XXXXXXXX_B$
$1FF1_H$	Program address detection register 0	PADR0	R/W		$XXXXXXXX_B$
$1FF2_H$	Program address detection register 0	PADR0	R/W		$XXXXXXXX_B$
$1FF3_H$	Program address detection register 1	PADR1	R/W		$XXXXXXXX_B$
$1FF4_H$	Program address detection register 1	PADR1	R/W		$XXXXXXXX_B$
$1FF5_H$	Program address detection register 1	PADR1	R/W		$XXXXXXXX_B$

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9. CAN Controller

The MB90540G series contains two CAN controllers (CAN0 and CAN1) , the MB90545G series contains only one (CAN0) . The Evaluation Chip MB90V540G also has two CAN controllers.

The CAN controller has the following features :

- Conforms to CAN Specification Version 2.0 Part A and B
  - Supports transmission/reception in standard frame and extended frame formats
- Supports transmission of data frames by receiving remote frames
- 16 transmitting/receiving message buffers
  - 29-bit ID and 8-byte data
  - Multi-level message buffer configuration
- Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
  - Two acceptance mask registers in either standard frame format or extended frame formats
- Bit rate programmable from 10 Kbps to 1 Mbps (when input clock is at 16 MHz)

List of Control Registers

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
000070_H	000080_H	Message buffer valid register	BVALR	R/W	$00000000\ 00000000_B$
000071_H	000081_H				
000072_H	000082_H	Transmit request register	TREQR	R/W	$00000000\ 00000000_B$
000073_H	000083_H				
000074_H	000084_H	Transmit cancel register	TCANR	W	$00000000\ 00000000_B$
000075_H	000085_H				
000076_H	000086_H	Transmit complete register	TCR	R/W	$00000000\ 00000000_B$
000077_H	000087_H				
000078_H	000088_H	Receive complete register	RCR	R/W	$00000000\ 00000000_B$
000079_H	000089_H				
$00007A_H$	$00008A_H$	Remote request receiving register	RRTRR	R/W	$00000000\ 00000000_B$
$00007B_H$	$00008B_H$				
$00007C_H$	$00008C_H$	Receive overrun register	ROVRR	R/W	$00000000\ 00000000_B$
$00007D_H$	$00008D_H$				
$00007E_H$	$00008E_H$	Receive interrupt enable register	RIER	R/W	$00000000\ 00000000_B$
$00007F_H$	$00008F_H$				

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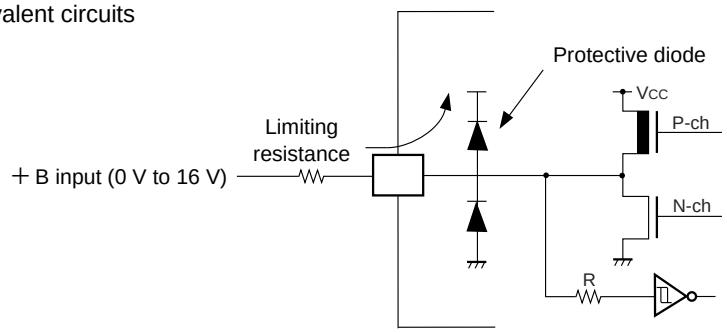
Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003B00H	003D00H	Control status register	CSR	R/W, R	00---000 0----0-1B
003B01H	003D01H				
003B02H	003D02H	Last event indicator register	LEIR	R/W	-------- 000-0000B
003B03H	003D03H				
003B04H	003D04H	Receive/transmit error counter register	RTEC	R	00000000 00000000B
003B05H	003D05H				
003B06H	003D06H	Bit timing register	BTR	R/W	-1111111 11111111B
003B07H	003D07H				
003B08H	003D08H	IDE register	IDER	R/W	XXXXXXXX XXXXXXXXB
003B09H	003D09H				
003B0AH	003D0AH	Transmit RTR register	TRTRR	R/W	00000000 00000000B
003B0BH	003D0BH				
003B0CH	003D0CH	Remote frame receive waiting register	RFWTR	R/W	XXXXXXXX XXXXXXXXB
003B0DH	003D0DH				
003B0EH	003D0EH	Transmit request enable register	TIER	R/W	00000000 00000000B
003B0FH	003D0FH				
003B10H	003D10H	Acceptance mask select register	AMSR	R/W	XXXXXXXX XXXXXXXXB
003B11H	003D11H				
003B12H	003D12H				XXXXXXXX XXXXXXXXB
003B13H	003D13H				
003B14H	003D14H	Acceptance mask register 0	AMR0	R/W	XXXXXXXX XXXXXXXXB
003B15H	003D15H				
003B16H	003D16H				XXXXX--- XXXXXXXXB
003B17H	003D17H				
003B18H	003D18H	Acceptance mask register 1	AMR1	R/W	XXXXXXXX XXXXXXXXB
003B19H	003D19H				
003B1AH	003D1AH				XXXXX--- XXXXXXXXB
003B1BH	003D1BH				

List of Message Buffers (ID Registers)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003A00H to 003A1FH	003C00H to 003C1FH	General-purpose RAM	—	R/W	XXXXXXXXB to XXXXXXXXB
003A20H	003C20H	ID register 0	IDR0	R/W	XXXXXXXX XXXXXXXXB
003A21H	003C21H				
003A22H	003C22H				XXXXX--- XXXXXXXXB
003A23H	003C23H				

- Note that analog system input/output pins other than the A/D input pins (LCD drive pins, comparator input pins, etc.) cannot accept + B signal input.
- Sample recommended circuits :

■ Input/Output Equivalent circuits



WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

11.2 Recommended Conditions

(V_{SS} = AV_{SS} = 0.0 V)

Parameter	Symbol	Value			Units	Remarks
		Min	Typ	Max		
Power supply voltage	V_{CC}, AV_{CC}	4.5	5.0	5.5	V	Under normal operation : Other than MB90F548GL(S)/543G(S)/547G(S)/548G(S)
						Under normal operation when A/D conveter is used : MB90F548GL(S)/543G(S)/547G(S)/548G(S)
		3.5	5.0	5.5	V	Under normal operation when A/D conveter is not used : MB90F548GL(S)/543G(S)/547G(S)/548G(S)
		3.0	−	5.5	V	Maintain RAM data in stop mode
Smooth capacitor	C_S	0.022	0.1	1.0	µF	*
Operating temperature	T_A	−40	−	+105	°C	

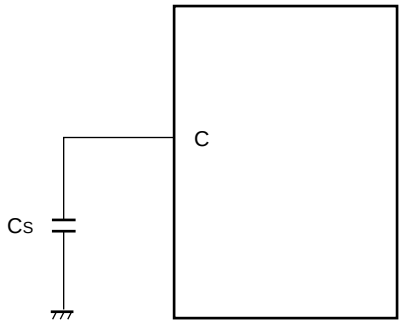
*: Use a ceramic capacitor or a capacitor of better 4. AC characteristics. The bypass capacitor should be greater than this capacitor.

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

■ **C Pin Connection Diagram**



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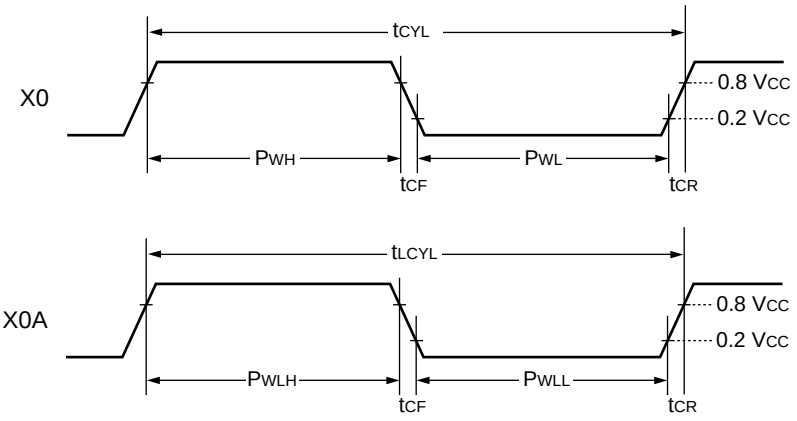
(MB90543G(S)/547G(S)/548G(S)/F548GL(S): V_{CC} = 3.5 V to 5.5 V, V_{SS} = AV_{SS} = 0.0 V, T_A = −40 °C to +105 °C)

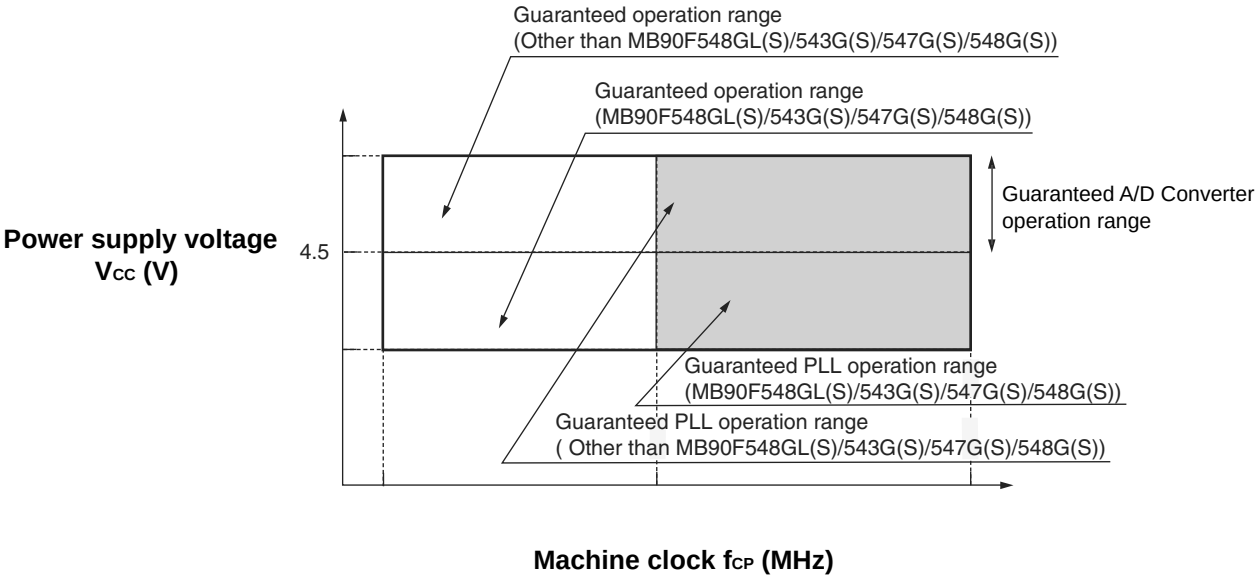
(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): V_{CC} = 5.0 V ± 10%, V_{SS} = AV_{SS} = 0.0 V, T_A = −40 °C to +105 °C)

Parameter	Symbol	Pin name	Value			Units	Remarks
			Min	Typ	Max		
Clock cycle time	t_{CYL}	X0, X1	62.5	—	333	ns	No multiplier When using an oscillator circuit V_{CC} = 5.0 V ± 10%
			62.5	—	125	ns	PLL multiplied by 1 When using an oscillator circuit V_{CC} = 5.0 V ± 10%
			125	—	250	ns	PLL multiplied by 2 When using an oscillator circuit V_{CC} = 5.0 V ± 10%
			187.5	—	333	ns	PLL multiplied by 3 When using an oscillator circuit V_{CC} = 5.0 V ± 10%
			250	—	333	ns	PLL multiplied by 4 When using an oscillator circuit V_{CC} = 5.0 V ± 10%
			200	—	333	ns	When using an oscillator circuit V_{CC} < 4.5 V(MB90F548GL(S)/543G(S)/547G(S)/548G(S))
			62.5	—	333	ns	No multiplier When using an external clock
			62.5	—	125	ns	PLL multiplied by 1 When using an external clock
			125	—	250	ns	PLL multiplied by 2 When using an external clock
			187.5	—	333	ns	PLL multiplied by 3 When using an external clock
			250	—	333	ns	PLL multiplied by 4 When using an external clock
	t_{LCYL}	X0A, X1A	—	30.5	—	µs	
Input clock pulse width	P_{WH}, P_{WL}	X0	10	—	—	ns	Duty ratio is about 30% to 70%.
	P_{WLH}, P_{WLL}	X0A	—	15.2	—	µs	
Input clock rise and fall time	t_{CR}, t_{CF}	X0	—	—	5	ns	When using an external clock
Machine clock frequency	f_{CP}	—	1.5	—	16	MHz	When using main clock
	f_{LCP}	—	—	8.192	—	kHz	When using sub-clock
Machine clock cycle time	t_{CP}	—	62.5	—	666	ns	When using main clock
	t_{LCP}	—	—	122.1	—	µs	When using sub-clock

■ **Clock Timing**



■ **Guaranteed PLL operation range**



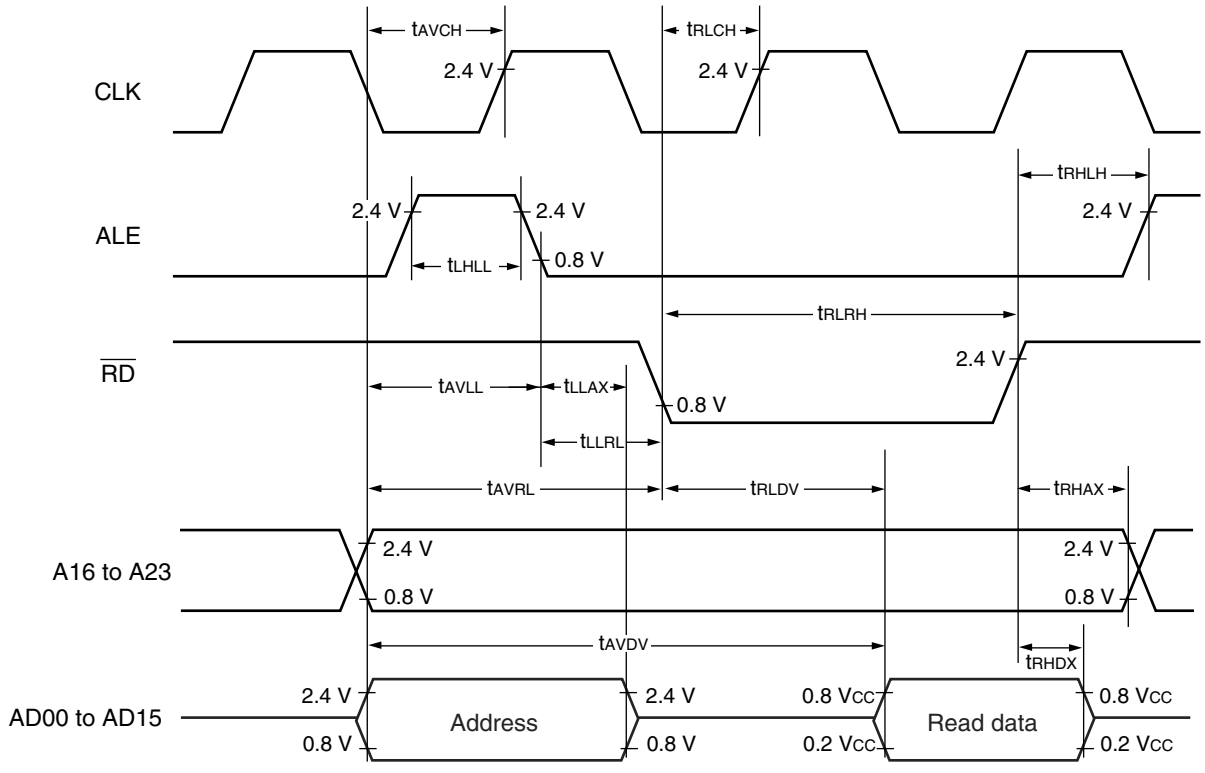
11.4.5 Bus Timing (Read)

(MB90543G(S)/547G(S)/548G(S)/F548GL(S): V_{CC} = 3.5 V to 5.5 V, V_{SS} = AV_{SS} = 0.0 V, T_A = − 40 °C to + 105 °C)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): V_{CC} = 5.0 V ± 10%, V_{SS} = AV_{SS} = 0.0 V, T_A = − 40 °C to + 105 °C)

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
ALE pulse width	t_{LHLL}	ALE		$t_{CP}/2 - 20$	−	ns	
Valid address → ALE↓ time	t_{AVLL}	ALE, A16 to A23, AD00 to AD15		$t_{CP}/2 - 20$	−	ns	
ALE↓ → Address valid time	t_{LLAX}	ALE, AD00 to AD15		$t_{CP}/2 - 15$	−	ns	
Valid address → $\overline{RD}$↓ time	t_{AVRL}	A16 toA23, AD00 to AD15, $\overline{RD}$		$t_{CP} - 15$	−	ns	
Valid address → Valid data input	t_{AVDV}	A16 to A23, AD00 to AD15		−	$5\ t_{CP}/2 - 60$	ns	
$\overline{RD}$ pulse width	t_{RLRH}	RD	−	$3\ t_{CP}/2 - 20$	−	ns	
$\overline{RD}$↓ → Valid data input	t_{RLDV}	$\overline{RD}$, AD00 to AD15		−	$3\ t_{CP}/2 - 60$	ns	
$\overline{RD}$↑ → Data hold time	t_{RHDX}	$\overline{RD}$, AD00 to AD15		0	−	ns	
$\overline{RD}$↑ → ALE↑ time	t_{RHLH}	$\overline{RD}$, ALE		$t_{CP}/2 - 15$	−	ns	
$\overline{RD}$↑ → Address valid time	t_{RHAX}	$\overline{RD}$, A16 to A23		$t_{CP}/2 - 10$	−	ns	
Valid address → CLK↑ time	t_{AVCH}	A16 to A23, AD00 to AD15, CLK		$t_{CP}/2 - 20$	−	ns	
$\overline{RD}$↓ → CLK↑ time	t_{RLCH}	$\overline{RD}$, CLK		$t_{CP}/2 - 20$	−	ns	
ALE↓ → $\overline{RD}$↓ time	t_{LLRL}	ALE, $\overline{RD}$		$t_{CP}/2 - 15$	−	ns	

■ **Bus Timing (Read)**



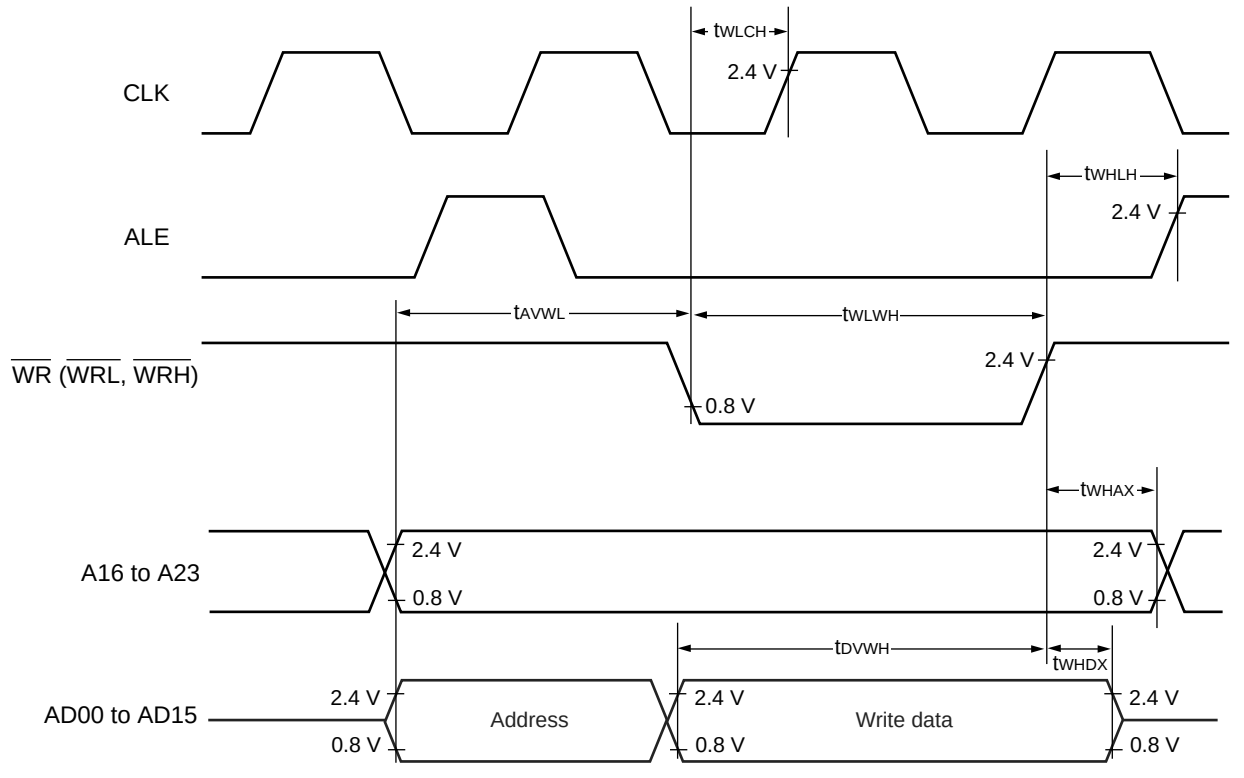
11.4.6 Bus Timing (Write)

(MB90543G(S)/547G(S)/548G(S)/F548GL(S): V_{CC} = 3.5 V to 5.5 V, V_{SS} = AV_{SS} = 0.0 V, T_A = − 40 °C to + 105 °C)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): V_{CC} = 5.0 V ± 10%, V_{SS} = AV_{SS} = 0.0 V, T_A = − 40 °C to + 105 °C)

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
Valid address → $\overline{WR}$↓ time	t_{AVWL}	A16 to A23 AD00 to AD15, $\overline{WR}$	—	t_{CP} − 15	—	ns	
$\overline{WR}$ pulse width	t_{WLWH}	WR		3 t_{CP}/2 − 20	—	ns	
Valid data output → $\overline{WR}$↑ time	t_{DVWH}	AD00 to AD15, $\overline{WR}$		3 t_{CP}/2 − 20	—	ns	
$\overline{WR}$↑ → Data hold time	t_{WHDX}	AD00 to AD15, $\overline{WR}$		20	—	ns	
$\overline{WR}$↑ → Address valid time	t_{WHAX}	A16 to A23, $\overline{WR}$		t_{CP}/2 − 10	—	ns	
$\overline{WR}$↑ → ALE↑ time	t_{WHLH}	$\overline{WR}$, ALE		t_{CP}/2 − 15	—	ns	
$\overline{WR}$↑ → CLK↑ time	t_{WLCH}	$\overline{WR}$, CLK		t_{CP}/2 − 20	—	ns	

■ **Bus Timing** (**Write**)



11.4.7 Ready Input Timing

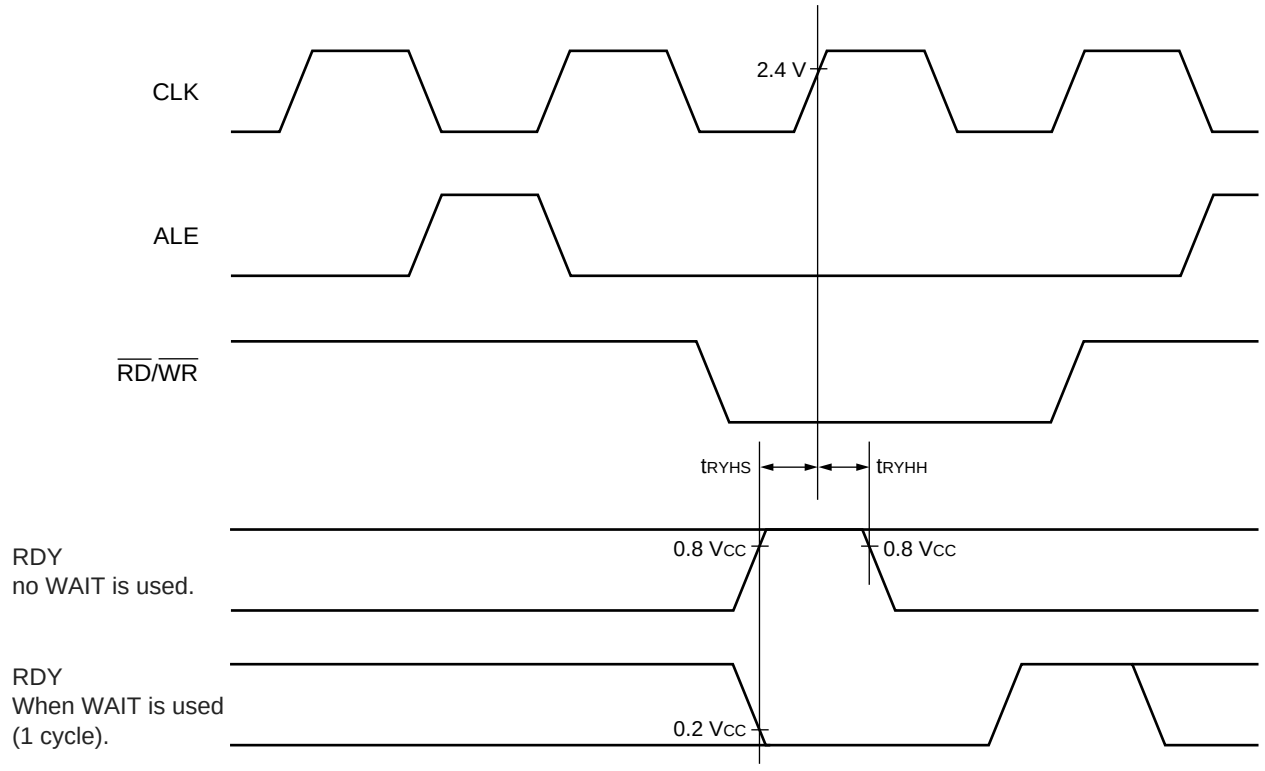
(MB90543G(S)/547G(S)/548G(S)/F548GL(S): V_{CC} = 3.5 V to 5.5 V, V_{SS} = AV_{SS} = 0.0 V, T_A = − 40 °C to + 105 °C)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): V_{CC} = 5.0 V ± 10%, V_{SS} = AV_{SS} = 0.0 V, T_A = − 40 °C to + 105 °C)

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
RDY setup time	t_{RYHS}	RDY	—	45	—	ns	
RDY hold time	t_{RYHH}	RDY		0	—	ns	

Note : If the RDY setup time is insufficient, use the auto-ready function.

■ **Ready Input Timing**



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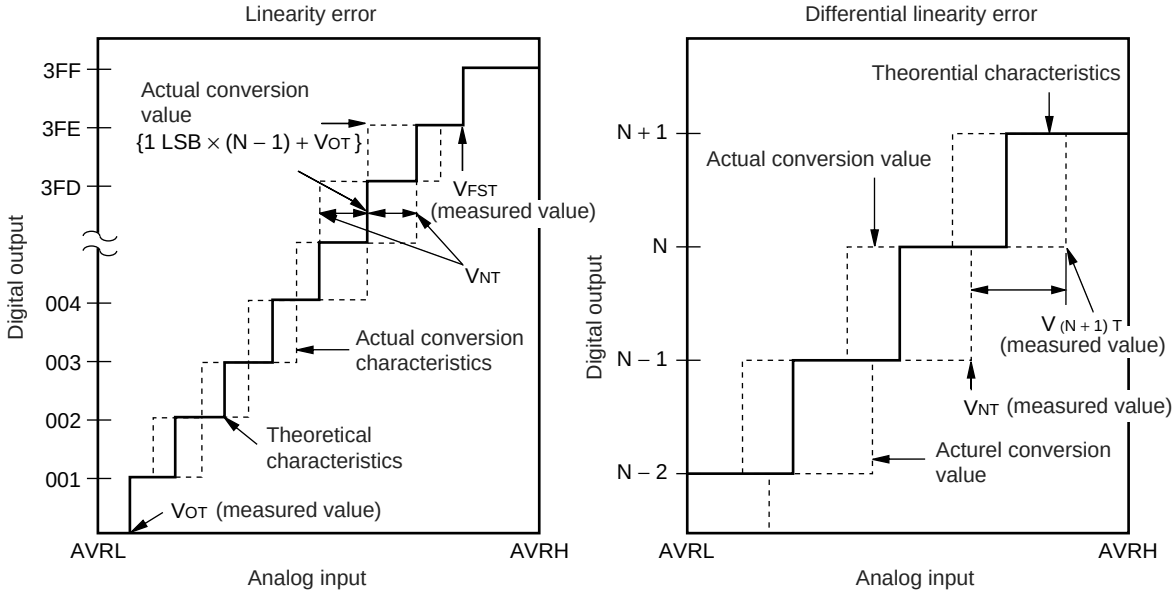


$$\text{Linearity error of digital output N} = \frac{V_{NT} - \{1\ \text{LSB} \times (N-1) + V_{OT}\}}{1\ \text{LSB}}\ [\text{LSB}]$$

$$\text{Differential linearity error of digital N} = \frac{V_{(N+1)T} - V_{NT}}{1\ \text{LSB}} - 1\ \text{LSB}\ [\text{LSB}]$$

$$1\ \text{LSB} = \frac{V_{FST} - V_{OT}}{1022}\ [\text{V}]$$

V_{OT} : Voltage at transition of digital output from "000_H" to "001_H"
V_{FST} : Voltage at transition of digital output from "$3FE_H$" to "$3FF_H$"

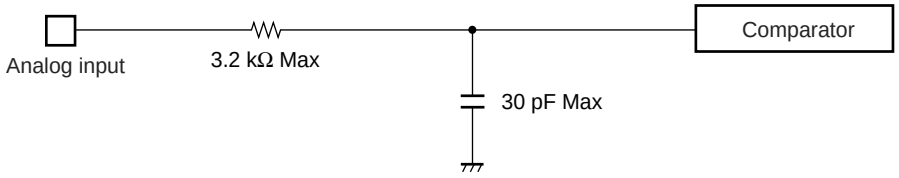
11.5.3 Notes on Using A/D Converter

Select the output impedance value for the external circuit of analog input according to the following conditions, :

- Output impedance values of the external circuit of 15 kΩ or lower are recommended.
- When capacitors are connected to external pins, the capacitance of several thousand times the internal capacitor value is recommended to minimized the effect of voltage distribution between the external capacitor and internal capacitor.

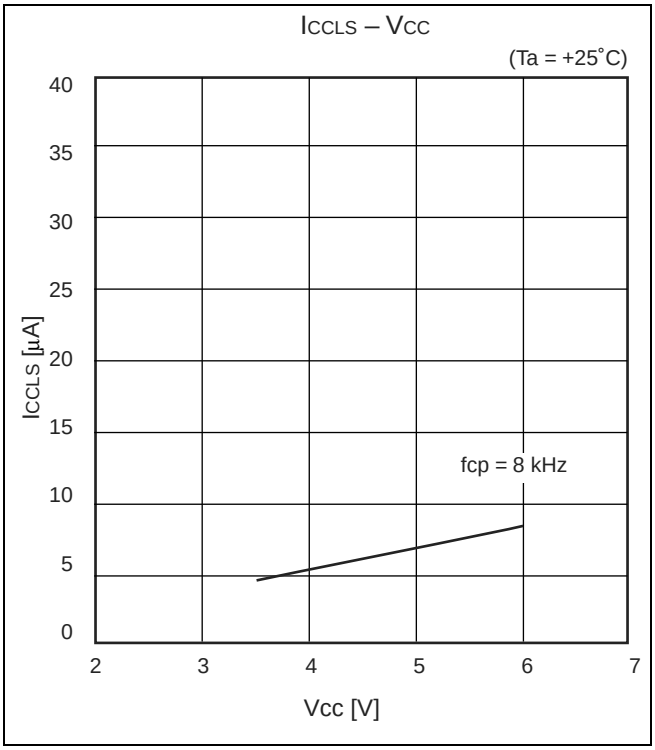
Note : When the output impedance of the external circuit is too high, the sampling period for analog voltages may not be sufficient (sampling period = 4.00 μs @machine clock of 16 MHz) .

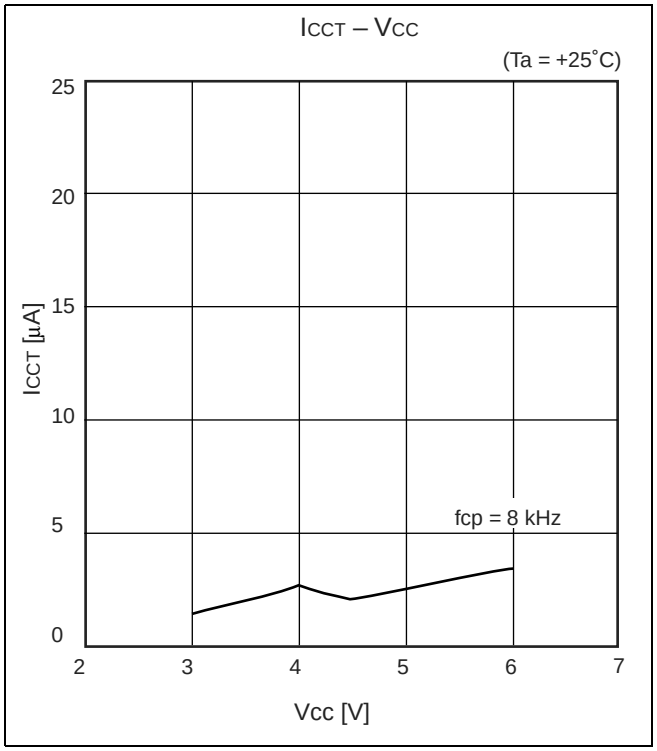
■ **Equipment of analog input circuit model**

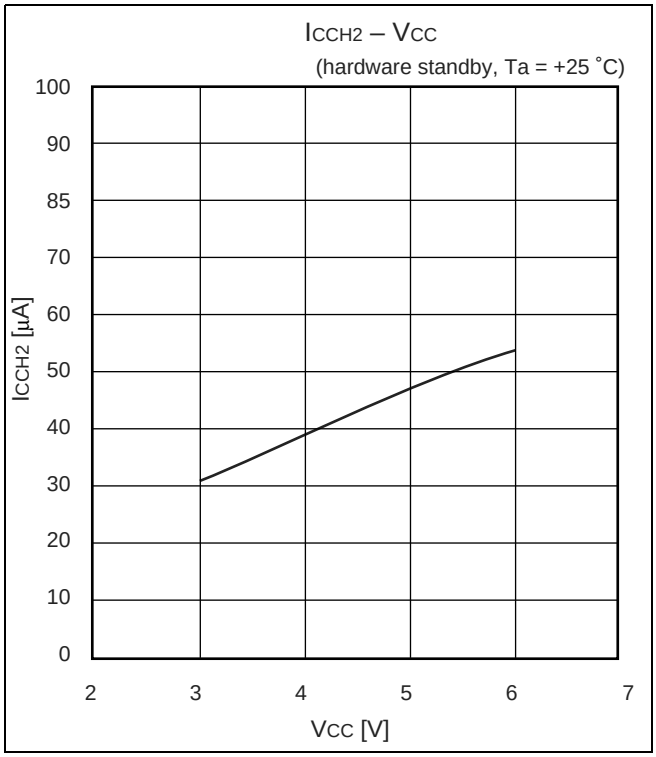


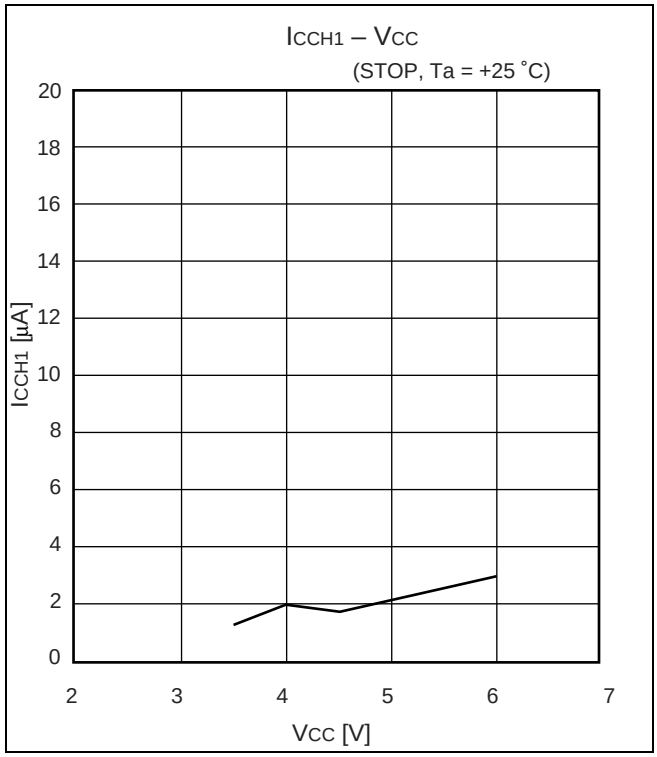
11.5.4 Error

The smaller the | AVRH − AVRL |, the greater the error would become relatively.

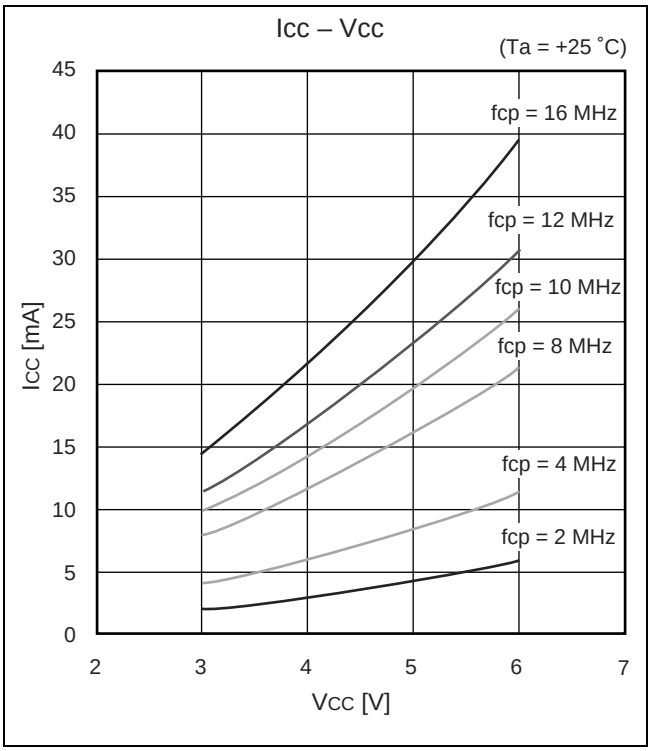

ICCLS – VCC
(Ta = +25˚C)
ICCLS [µA]
40
35
30
25
20
15
10
5
0
fcp = 8 kHz
2
3
4
5
6
7
Vcc [V]

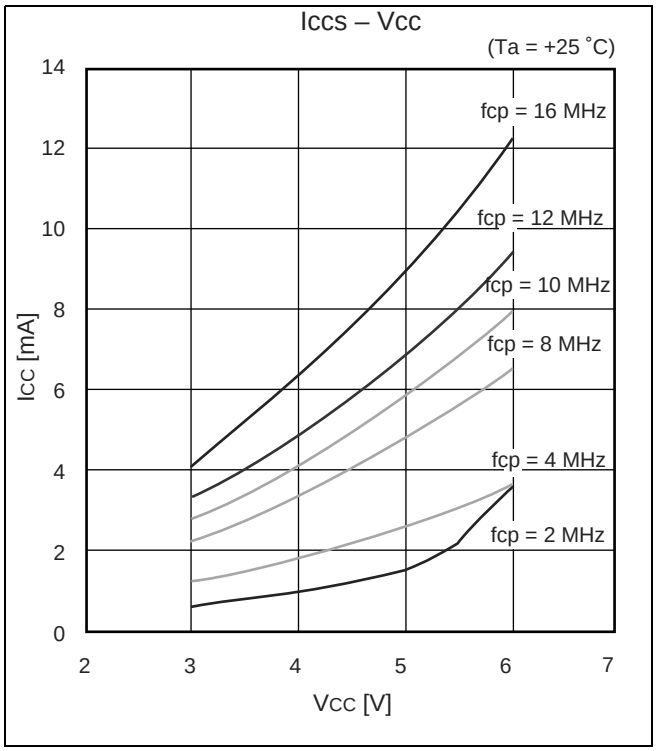

ICCT – VCC
(Ta = +25˚C)
ICCT [µA]
25
20
15
10
5
0
fcp = 8 kHz
2
3
4
5
6
7
Vcc [V]

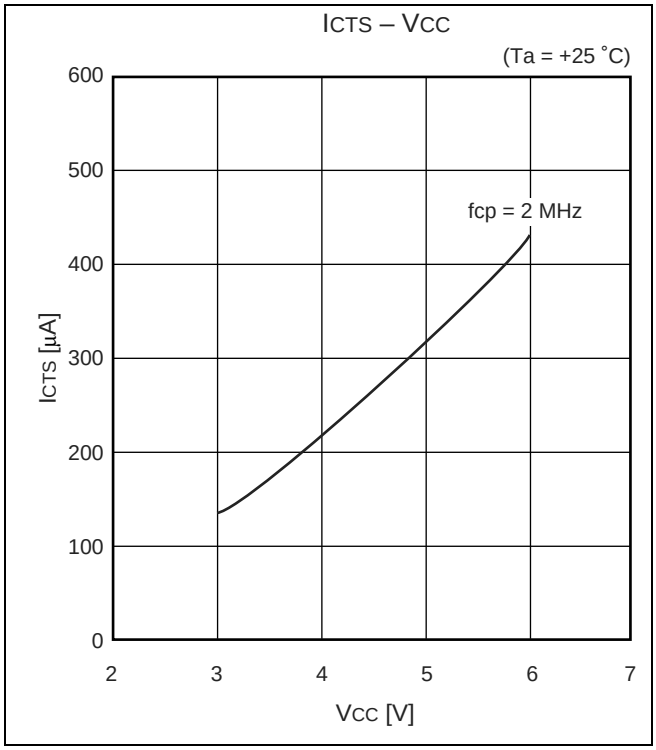

ICCH2 – VCC
(hardware standby, Ta = +25 ˚C)
ICCH2 [µA]
100
90
85
70
60
50
40
30
20
10
0
2
3
4
5
6
7
VCC [V]

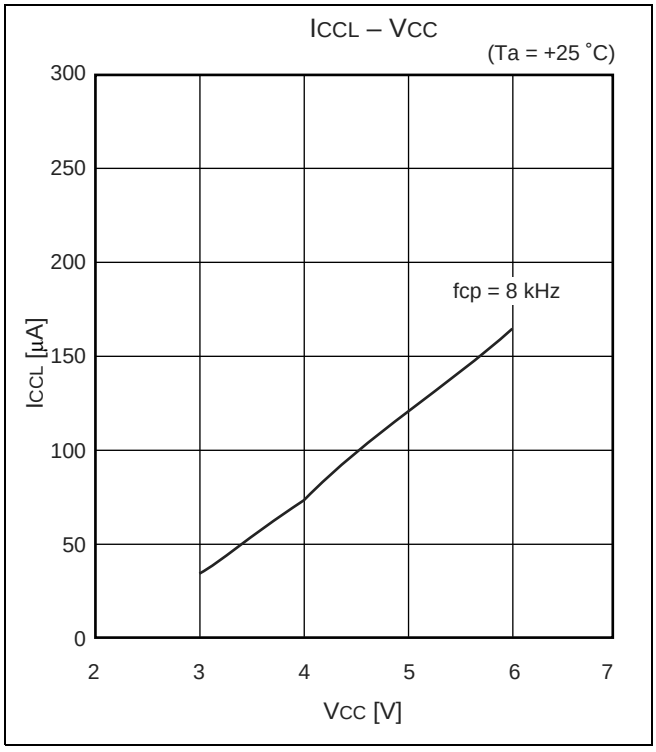

ICCH1 – VCC
(STOP, Ta = +25 ˚C)
ICCH1 [µA]
20
18
16
14
12
10
8
6
4
2
0
2
3
4
5
6
7
VCC [V]

■ Power supply current (MB90F549G)





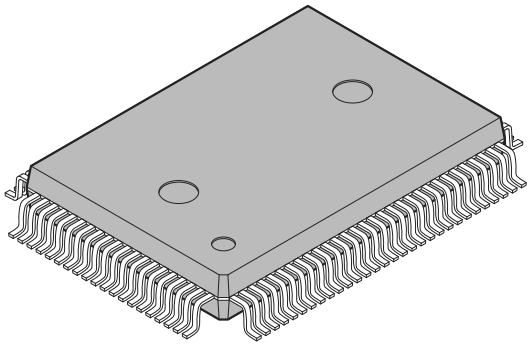


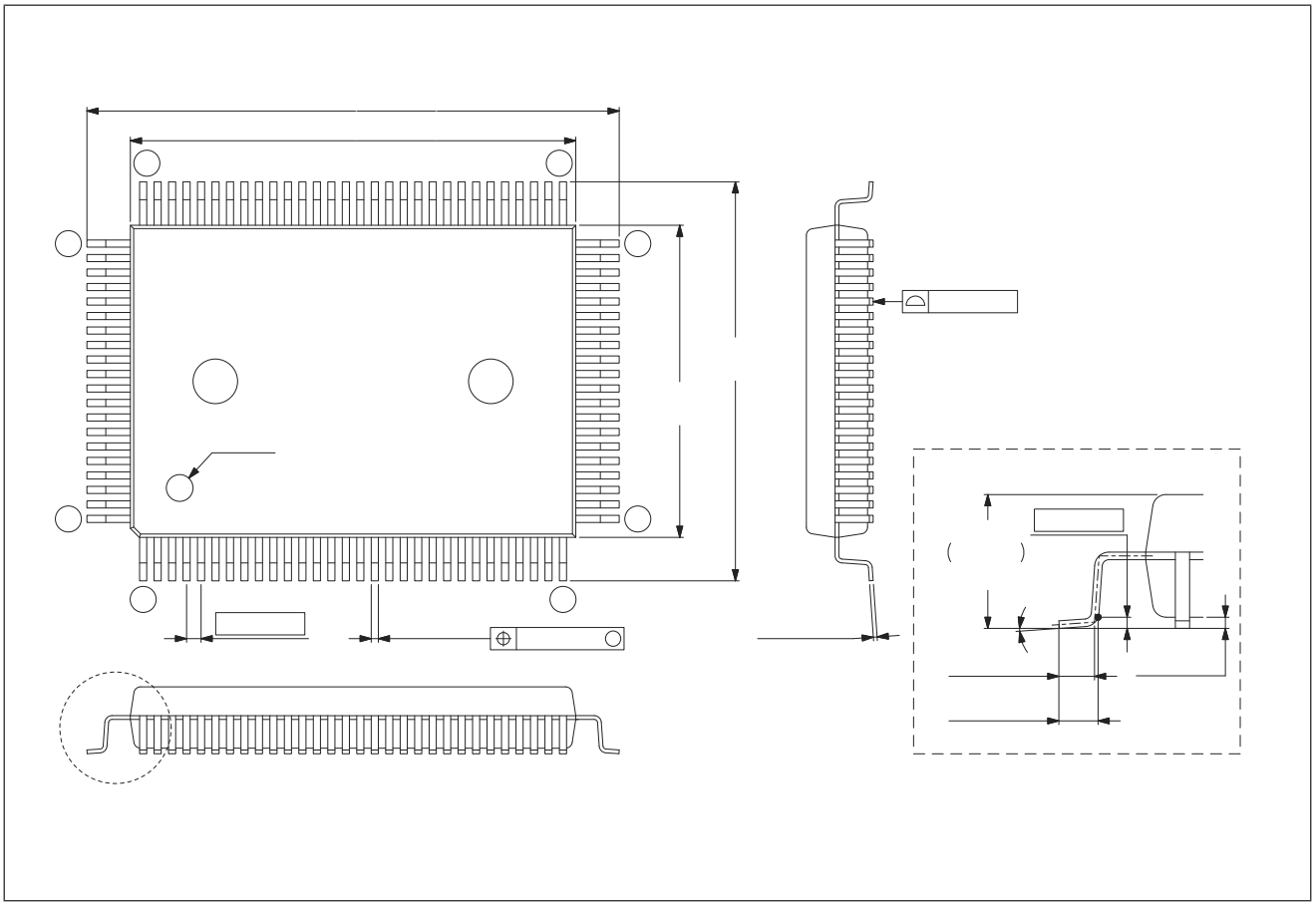


13. Ordering Information

Part number	Package	Remarks
MB90F543GPF MB90F543GSPF MB90F546GPF MB90F546GSPF MB90F548GPF MB90F548GSPF MB90F548GLPF MB90F548GLSPF MB90F549GPF MB90F549GSPF MB90543GPF MB90543GSPF MB90547GPF MB90547GSPF MB90548GPF MB90548GSPF MB90549GPF MB90549GSPF	100-pin Plastic QFP (FPT-100P-M06)	
MB90F543GPMC MB90F543GSPMC MB90F546GPMC MB90F546GSPMC MB90F548GPMC MB90F548GSPMC MB90F548GLPMC MB90F548GLSPMC MB90F549GPMC MB90F549GSPMC MB90543GPMC MB90543GSPMC MB90547GPMC MB90547GSPMC MB90548GPMC MB90548GSPMC MB90549GPMC MB90549GSPMC	100-pin Plastic LQFP (FPT-100P-M20)	

14. Package Dimensions



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