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## What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

## Applications of "[Embedded - Microcontrollers](#)"

### Details

Product Status	Active
Core Processor	F <sup>2</sup> MC-16LX
Core Size	16-Bit
Speed	16MHz
Connectivity	CANbus, EBI/EMI, SCI, Serial I/O, UART/USART
Peripherals	POR, WDT
Number of I/O	81
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-BQFP
Supplier Device Package	100-QFP (14x20)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/mb90f543gspf-gs-9021">https://www.e-xfl.com/product-detail/infineon-technologies/mb90f543gspf-gs-9021</a>

Starting by an external trigger input.  
Conversion time : 26.3  $\mu$ s

- FULL-CAN interfaces  
MB90540G series : 2 channels  
MB90545G series : 1 channel  
Conforming to Version 2.0 Part A and Part B

Flexible message buffering (mailbox and FIFO buffering can be mixed)

- External bus interface : Maximum address space 16 Mbytes
- Package: QFP-100, LQFP-100

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Pin No.		Pin name	Circuit type	Function
LQFP <sup>2</sup>	QFP <sup>1</sup>			
11	13	P33	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode, external bus 8-bit mode or when WRH pin output is disabled.
		$\overline{\text{WRH}}$		Write strobe output pin for the 8 higher bits of the data bus. This function is enabled when the external bus is enabled, when the external bus 16-bit mode is selected, and when the WRH output pin is enabled.
12	14	P34	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold functions are enabled.
13	15	P35	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold functions are enabled.
14	16	P36	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the external ready function is disabled.
		RDY		Ready input pin. This function is enabled when both the external bus and the external ready functions are enabled.
15	17	P37	H	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the CLK output is disabled.
		CLK		CLK output pin. This function is enabled when both the external bus and CLK outputs are enabled.
16	18	P40	G	General I/O port. This function is enabled when UART0 disables the serial data output.
		SOT0		Serial data output pin for UART0. This function is enabled when UART0 enables the serial data output.
17	19	P41	G	General I/O port. This function is enabled when UART0 disables serial clock output.
		SCK0		Serial clock I/O pin for UART0. This function is enabled when UART0 enables the serial clock output.
18	20	P42	G	General I/O port. This function is always enabled.
		SIN0		Serial data input pin for UART0. Set the corresponding Port Direction Register to input if this function is used.
19	21	P43	G	General I/O port. This function is always enabled.
		SIN1		Serial data input pin for UART1. Set the corresponding Port Direction Register to input if this function is used.

(Continued)

Pin No.		Pin name	Circuit type	Function
LQFP <sup>2</sup>	QFP <sup>1</sup>			
20	22	P44	G	General I/O port. This function is enabled when UART1 disables the clock output.
		SCK1		Serial clock pulse I/O pin for UART1. This function is enabled when UART1 enables the serial clock output.
22	24	P45	G	General I/O port. This function is enabled when UART1 disables the serial data output.
		SOT1		Serial data output pin for UART1. This function is enabled when UART1 enables the serial data output.
23	25	P46	G	General I/O port. This function is enabled when the Extended I/O serial interface disables the serial data output.
		SOT2		Serial data output pin for the Extended I/O serial interface. This function is enabled when the Extended I/O serial interface enables the serial data output.
24	26	P47	G	General I/O port. This function is enabled when the Extended I/O serial interface disables the clock output.
		SCK2		Serial clock pulse I/O pin for the Extended I/O serial interface. This function is enabled when the Extended I/O serial interface enables the Serial clock output.
26	28	P50	D	General I/O port. This function is always enabled.
		SIN2		Serial data input pin for the Extended I/O serial interface. Set the corresponding Port Direction Register to input if this function is used.
27 to 30	29 to 32	P51 to P54	D	General I/O port. This function is always enabled.
		INT4 to INT7		External interrupt request input pins for INT4 to INT7. Set the corresponding Port Direction Register to input if this function is used.
31	33	P55	D	General I/O port. This function is always enabled.
		ADTG		Trigger input pin for the A/D converter. Set the corresponding Port Direction Register to input if this function is used.
36 to 39	38 to 41	P60 to P63	E	General I/O port. This function is enabled when the analog input enable register specifies a port.
		AN0 to AN3		Analog input pins for the 8/10-bit A/D converter. This function is enabled when the analog input enable register specifies A/D.
41 to 44	43 to 46	P64 to P67	E	General I/O port. The function is enabled when the analog input enable register specifies a port.
		AN4 to AN7		Analog input pins for the 8/10-bit A/D converter. This function is enabled when the analog input enable register specifies A/D.
45	47	P56	D	General I/O port. This function is always enabled.
		TIN0		Event input pin for the 16-bit reload timers 0. Set the corresponding Port Direction Register to input if this function is used.

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
24 <sub>H</sub>	Serial mode register 1	SMR1	R/W	UART1	0 0 0 0 0 0 0 0 <sub>B</sub>
25 <sub>H</sub>	Serial control register 1	SCR1	R/W		0 0 0 0 0 1 0 0 <sub>B</sub>
26 <sub>H</sub>	Serial input data register 1/ Serial output data register 1	SIDR1/SODR1	R/W		XXXXXXXX <sub>B</sub>
27 <sub>H</sub>	Serial status register 1	SSR1	R/W		0 0 0 0 1 _ 0 0 <sub>B</sub>
28 <sub>H</sub>	UART1 prescaler control register	CDCR	R/W		0 _ _ _ 1 1 1 1 <sub>B</sub>
29 <sub>H</sub>	Serial Edge select register	SES1	R/W		_ _ _ _ _ _ 0 <sub>B</sub>
2A <sub>H</sub>	Prohibited				
2B <sub>H</sub>	Serial I/O prescaler	SCDCR	R/W	Extended I/O Serial Interface	0 _ _ _ 1 1 1 1 <sub>B</sub>
2C <sub>H</sub>	Serial mode control register	SMCS	R/W		_ _ _ _ 0 0 0 0 <sub>B</sub>
2D <sub>H</sub>	Serial mode control register	SMCS	R/W		0 0 0 0 0 0 1 0 <sub>B</sub>
2E <sub>H</sub>	Serial data register	SDR	R/W		XXXXXXXX <sub>B</sub>
2F <sub>H</sub>	Serial Edge select register	SES2	R/W		_ _ _ _ _ _ 0 <sub>B</sub>
30 <sub>H</sub>	External interrupt enable register	ENIR	R/W	External Interrupt	0 0 0 0 0 0 0 0 <sub>B</sub>
31 <sub>H</sub>	External interrupt request register	EIRR	R/W		XXXXXXXX <sub>B</sub>
32 <sub>H</sub>	External interrupt level register	ELVR	R/W		0 0 0 0 0 0 0 0 <sub>B</sub>
33 <sub>H</sub>	External interrupt level register	ELVR	R/W		0 0 0 0 0 0 0 0 <sub>B</sub>
34 <sub>H</sub>	A/D control status register 0	ADCS0	R/W	A/D Converter	0 0 0 0 0 0 0 0 <sub>B</sub>
35 <sub>H</sub>	A/D control status register 1	ADCS1	R/W		0 0 0 0 0 0 0 0 <sub>B</sub>
36 <sub>H</sub>	A/D data register 0	ADCR0	R		XXXXXXXX <sub>B</sub>
37 <sub>H</sub>	A/D data register 1	ADCR1	R/W		0 0 0 0 1 _ XX <sub>B</sub>
38 <sub>H</sub>	PPG0 operation mode control register	PPGC0	R/W	16-bit Programmable Pulse Generator 0/1	0 _ 0 0 0 _ _ 1 <sub>B</sub>
39 <sub>H</sub>	PPG1 operation mode control register	PPGC1	R/W		0 _ 0 0 0 0 0 1 <sub>B</sub>
3A <sub>H</sub>	PPG0/1 clock selection register	PPG01	R/W		0 0 0 0 0 0 _ _ <sub>B</sub>
3B <sub>H</sub>	Prohibited				
3C <sub>H</sub>	PPG2 operation mode control register	PPGC2	R/W	16-bit Programmable Pulse Generator 2/3	0 _ 0 0 0 _ _ 1 <sub>B</sub>
3D <sub>H</sub>	PPG3 operation mode control register	PPGC3	R/W		0 _ 0 0 0 0 0 1 <sub>B</sub>
3E <sub>H</sub>	PPG2/3 Clock Selection Register	PPG23	R/W		0 0 0 0 0 0 _ _ <sub>B</sub>
3F <sub>H</sub>	Prohibited				
40 <sub>H</sub>	PPG4 operation mode control register	PPGC4	R/W	16-bit Programmable Pulse Generator 4/5	0 _ 0 0 0 _ _ 1 <sub>B</sub>
41 <sub>H</sub>	PPG5 operation mode control register	PPGC5	R/W		0 _ 0 0 0 0 0 1 <sub>B</sub>
42 <sub>H</sub>	PPG4/5 clock selection register	PPG45	R/W		0 0 0 0 0 0 _ _ <sub>B</sub>
43 <sub>H</sub>	Prohibited				
44 <sub>H</sub>	PPG6 operation mode control register	PPGC6	R/W	16-bit Programmable Pulse Generator 6/7	0 _ 0 0 0 _ _ 1 <sub>B</sub>
45 <sub>H</sub>	PPG7 operation mode control register	PPGC7	R/W		0 _ 0 0 0 0 0 1 <sub>B</sub>
46 <sub>H</sub>	PPG6/7 clock selection register	PPG67	R/W		0 0 0 0 0 0 _ _ <sub>B</sub>

(Continued)

## 9. CAN Controller

The MB90540G series contains two CAN controllers (CAN0 and CAN1) , the MB90545G series contains only one (CAN0) . The Evaluation Chip MB90V540G also has two CAN controllers.

The CAN controller has the following features :

- Conforms to CAN Specification Version 2.0 Part A and B
  - Supports transmission/reception in standard frame and extended frame formats
- Supports transmission of data frames by receiving remote frames
- 16 transmitting/receiving message buffers
  - 29-bit ID and 8-byte data
  - Multi-level message buffer configuration
- Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
  - Two acceptance mask registers in either standard frame format or extended frame formats
- Bit rate programmable from 10 Kbps to 1 Mbps (when input clock is at 16 MHz)

### List of Control Registers

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
000070 <sub>H</sub>	000080 <sub>H</sub>	Message buffer valid register	BVALR	R/W	00000000 00000000 <sub>B</sub>
000071 <sub>H</sub>	000081 <sub>H</sub>				
000072 <sub>H</sub>	000082 <sub>H</sub>	Transmit request register	TREQR	R/W	00000000 00000000 <sub>B</sub>
000073 <sub>H</sub>	000083 <sub>H</sub>				
000074 <sub>H</sub>	000084 <sub>H</sub>	Transmit cancel register	TCANR	W	00000000 00000000 <sub>B</sub>
000075 <sub>H</sub>	000085 <sub>H</sub>				
000076 <sub>H</sub>	000086 <sub>H</sub>	Transmit complete register	TCR	R/W	00000000 00000000 <sub>B</sub>
000077 <sub>H</sub>	000087 <sub>H</sub>				
000078 <sub>H</sub>	000088 <sub>H</sub>	Receive complete register	RCR	R/W	00000000 00000000 <sub>B</sub>
000079 <sub>H</sub>	000089 <sub>H</sub>				
00007A <sub>H</sub>	00008A <sub>H</sub>	Remote request receiving register	RRTRR	R/W	00000000 00000000 <sub>B</sub>
00007B <sub>H</sub>	00008B <sub>H</sub>				
00007C <sub>H</sub>	00008C <sub>H</sub>	Receive overrun register	ROVRR	R/W	00000000 00000000 <sub>B</sub>
00007D <sub>H</sub>	00008D <sub>H</sub>				
00007E <sub>H</sub>	00008E <sub>H</sub>	Receive interrupt enable register	RIER	R/W	00000000 00000000 <sub>B</sub>
00007F <sub>H</sub>	00008F <sub>H</sub>				

(Continued)

**List of Message Buffers (DLC Registers and Data Registers)**

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003A60 <sub>H</sub>	003C60 <sub>H</sub>	DLC register 0	DLCR0	R/W	----XXXX <sub>B</sub>
003A61 <sub>H</sub>	003C61 <sub>H</sub>				
003A62 <sub>H</sub>	003C62 <sub>H</sub>	DLC register 1	DLCR1	R/W	----XXXX <sub>B</sub>
003A63 <sub>H</sub>	003C63 <sub>H</sub>				
003A64 <sub>H</sub>	003C64 <sub>H</sub>	DLC register 2	DLCR2	R/W	----XXXX <sub>B</sub>
003A65 <sub>H</sub>	003C65 <sub>H</sub>				
003A66 <sub>H</sub>	003C66 <sub>H</sub>	DLC register 3	DLCR3	R/W	----XXXX <sub>B</sub>
003A67 <sub>H</sub>	003C67 <sub>H</sub>				
003A68 <sub>H</sub>	003C68 <sub>H</sub>	DLC register 4	DLCR4	R/W	----XXXX <sub>B</sub>
003A69 <sub>H</sub>	003C69 <sub>H</sub>				
003A6A <sub>H</sub>	003C6A <sub>H</sub>	DLC register 5	DLCR5	R/W	----XXXX <sub>B</sub>
003A6B <sub>H</sub>	003C6B <sub>H</sub>				
003A6C <sub>H</sub>	003C6C <sub>H</sub>	DLC register 6	DLCR6	R/W	----XXXX <sub>B</sub>
003A6D <sub>H</sub>	003C6D <sub>H</sub>				
003A6E <sub>H</sub>	003C6E <sub>H</sub>	DLC register 7	DLCR7	R/W	----XXXX <sub>B</sub>
003A6F <sub>H</sub>	003C6F <sub>H</sub>				
003A70 <sub>H</sub>	003C70 <sub>H</sub>	DLC register 8	DLCR8	R/W	----XXXX
003A71 <sub>H</sub>	003C71 <sub>H</sub>				
003A72 <sub>H</sub>	003C72 <sub>H</sub>	DLC register 9	DLCR9	R/W	----XXXX <sub>B</sub>
003A73 <sub>H</sub>	003C73 <sub>H</sub>				
003A74 <sub>H</sub>	003C74 <sub>H</sub>	DLC register 10	DLCR10	R/W	----XXXX <sub>B</sub>
003A75 <sub>H</sub>	003C75 <sub>H</sub>				
003A76 <sub>H</sub>	003C76 <sub>H</sub>	DLC register 11	DLCR11	R/W	----XXXX <sub>B</sub>
003A77 <sub>H</sub>	003C77 <sub>H</sub>				
003A78 <sub>H</sub>	003C78 <sub>H</sub>	DLC register 12	DLCR12	R/W	----XXXX <sub>B</sub>
003A79 <sub>H</sub>	003C79 <sub>H</sub>				
003A7A <sub>H</sub>	003C7A <sub>H</sub>	DLC register 13	DLCR13	R/W	----XXXX <sub>B</sub>
003A7B <sub>H</sub>	003C7B <sub>H</sub>				
003A7C <sub>H</sub>	003C7C <sub>H</sub>	DLC register 14	DLCR14	R/W	----XXXX <sub>B</sub>
003A7D <sub>H</sub>	003C7D <sub>H</sub>				
003A7E <sub>H</sub>	003C7E <sub>H</sub>	DLC register 15	DLCR15	R/W	----XXXX <sub>B</sub>
003A7F <sub>H</sub>	003C7F <sub>H</sub>				
003A80 <sub>H</sub> to 003A87 <sub>H</sub>	003C80 <sub>H</sub> to 003C87 <sub>H</sub>	Data register 0 (8 bytes)	DTR0	R/W	XXXXXXXX <sub>B</sub> to XXXXXXXX <sub>B</sub>

*(Continued)*



*(Continued)*

\*1 : The interrupt request flag is cleared by the EI<sup>2</sup>OS interrupt clear signal.

\*2 : The interrupt request flag is cleared by the EI<sup>2</sup>OS interrupt clear signal. A stop request is available.

Notes :

- N/A : The interrupt request flag is not cleared by the EI<sup>2</sup>OS interrupt clear signal.
- For a peripheral module with two interrupt causes for a single interrupt number, both interrupt request flags are cleared by the EI<sup>2</sup>OS interrupt clear signal.
- At the end of EI<sup>2</sup>OS, the EI<sup>2</sup>OS clear signal will be asserted for all the interrupt flags assigned to the same interrupt number. If one interrupt flag starts the EI<sup>2</sup>OS and in the meantime another interrupt flag is set by a hardware event, the later event is lost because the flag is cleared by the EI<sup>2</sup>OS clear signal caused by the first event. So it is recommended not to use the EI<sup>2</sup>OS for this interrupt number.
- If EI<sup>2</sup>OS is enabled, EI<sup>2</sup>OS is initiated when one of the two interrupt signals in the same interrupt control register (ICR) is asserted. This means that different interrupt sources share the same EI<sup>2</sup>OS Descriptor which should be unique for each interrupt source. For this reason, when one interrupt source uses the EI<sup>2</sup>OS, the other interrupt should be disabled.

## 11. Electrical Characteristics

### 11.1 Absolute Maximum Ratings

( $V_{SS} = AV_{SS} = 0.0\text{ V}$ )

Parameter	Symbol	Value		Units	Remarks
		Min	Max		
Power supply voltage	$V_{CC}$	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	
	$AV_{CC}$	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$V_{CC} = AV_{CC}$ *1
	$AVRH, AVRL$	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$AV_{CC} \geq AVRH/AVRL, AVRH \geq AVRL$ *1
Input voltage	$V_I$	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*2
Output voltage	$V_O$	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*2
Maximum clamp current	$I_{CLAMP}$	-2.0	+2.0	mA	*6
Total maximum clamp current	$\Sigma  I_{CLAMP} $	—	20	mA	*6
"L" level max output current	$I_{OL}$	—	15	mA	*3
"L" level avg. output current	$I_{OLAV}$	—	4	mA	*4
"L" level max overall output current	$\Sigma I_{OL}$	—	100	mA	
"L" level avg. overall output current	$\Sigma I_{OLAV}$	—	50	mA	*5
"H" level max output current	$I_{OH}$	—	-15	mA	*3
"H" level avg. output current	$I_{OHAV}$	—	-4	mA	*4
"H" level max overall output current	$\Sigma I_{OH}$	—	-100	mA	
"H" level avg. overall output current	$\Sigma I_{OHAV}$	—	-50	mA	*5
Power consumption	$P_D$	—	500	mW	Flash device
		—	400	mW	MASK ROM
Operating temperature	$T_A$	-40	+105	°C	
Storage temperature	$T_{STG}$	-55	+150	°C	

\*1 :  $AV_{CC}$ ,  $AVRH$ ,  $AVRL$  should not exceed  $V_{CC}$ . Also,  $AVRH$ ,  $AVRL$  should not exceed  $AV_{CC}$ , and  $AVRL$  does not exceed  $AVRH$ .

\*2 :  $V_I$  and  $V_O$  should not exceed  $V_{CC} + 0.3\text{ V}$ . However if the maximum current to/from an input is limited by some means with external components, the  $I_{CLAMP}$  rating supercedes the  $V_I$  rating.

\*3 : The maximum output current is a peak value for a corresponding pin.

\*4 : Average output current is an average current value observed for a 100 ms period for a corresponding pin.

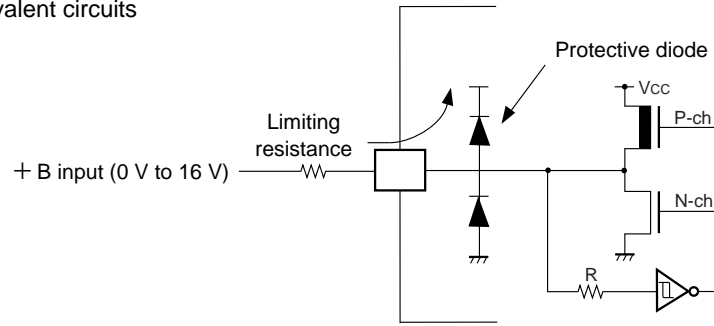
\*5 : Total average current is an average current value observed for a 100 ms period for all corresponding pins.

\*6 :

- Applicable to pins : P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, PA0
- Use within recommended operating conditions.
- Use at DC voltage (current) .
- The + B signal should always be applied with a limiting resistance placed between the + B signal and the microcontroller.
- The value of the limiting resistance should be set so that when the + B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
- Note that when the microcontroller drive current is low, such as in the power saving modes, the + B input potential may pass through the protective diode and increase the potential at the  $V_{CC}$  pin, and this may affect other devices.
- Note that if a + B signal is input when the microcontroller current is off (not fixed at 0 V) , the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the + B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the power-on result.
- Care must be taken not to leave the + B input pin open.

- Note that analog system input/output pins other than the A/D input pins (LCD drive pins, comparator input pins, etc.) cannot accept + B signal input.
- Sample recommended circuits :

■ Input/Output Equivalent circuits



**WARNING:** Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

(Continued)

(MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 3.5\text{ V to }5.5\text{ V}$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ °C to }+105\text{ °C}$ )

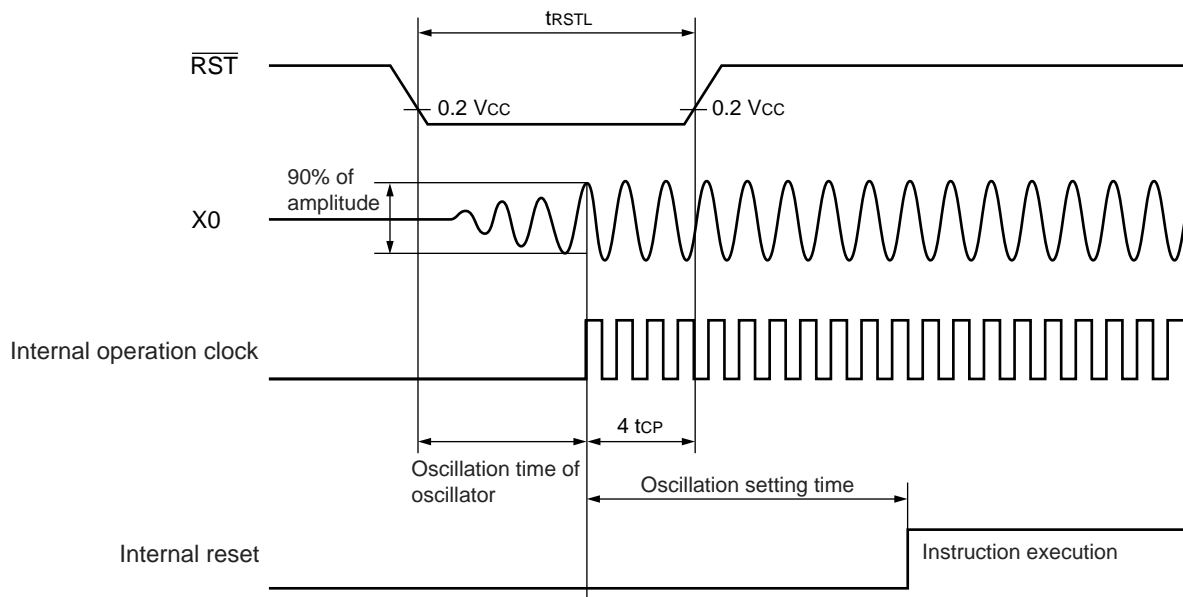
(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 5.0\text{ V} \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ °C to }+105\text{ °C}$ )

Parameter	Symbol	Pin name	Value			Units	Remarks
			Min	Typ	Max		
Clock cycle time	tcyl	X0, X1	62.5	—	333	ns	No multiplier When using an oscillator circuit $V_{CC} = 5.0\text{ V} \pm 10\%$
			62.5	—	125	ns	PLL multiplied by 1 When using an oscillator circuit $V_{CC} = 5.0\text{ V} \pm 10\%$
			125	—	250	ns	PLL multiplied by 2 When using an oscillator circuit $V_{CC} = 5.0\text{ V} \pm 10\%$
			187.5	—	333	ns	PLL multiplied by 3 When using an oscillator circuit $V_{CC} = 5.0\text{ V} \pm 10\%$
			250	—	333	ns	PLL multiplied by 4 When using an oscillator circuit $V_{CC} = 5.0\text{ V} \pm 10\%$
			200	—	333	ns	When using an oscillator circuit $V_{CC} < 4.5\text{ V}$ (MB90F548GL(S)/543G(S)/ 547G(S)/548G(S))
			62.5	—	333	ns	No multiplier When using an external clock
			62.5	—	125	ns	PLL multiplied by 1 When using an external clock
			125	—	250	ns	PLL multiplied by 2 When using an external clock
			187.5	—	333	ns	PLL multiplied by 3 When using an external clock
			250	—	333	ns	PLL multiplied by 4 When using an external clock
	tLCYL	X0A, X1A	—	30.5	—	μs	
Input clock pulse width	P <sub>WH</sub> , P <sub>WL</sub>	X0	10	—	—	ns	Duty ratio is about 30% to 70%.
	P <sub>WLH</sub> , P <sub>WLL</sub>	X0A	—	15.2	—	μs	
Input clock rise and fall time	t <sub>CR</sub> , t <sub>CF</sub>	X0	—	—	5	ns	When using an external clock
Machine clock frequency	f <sub>CP</sub>	—	1.5	—	16	MHz	When using main clock
	f <sub>LCP</sub>	—	—	8.192	—	kHz	When using sub-clock
Machine clock cycle time	t <sub>CP</sub>	—	62.5	—	666	ns	When using main clock
	t <sub>LCP</sub>	—	—	122.1	—	μs	When using sub-clock

- In under normal operation, pseudo timer mode, sub-clock mode, sub-sleep mode, timer mode



- In stop mode



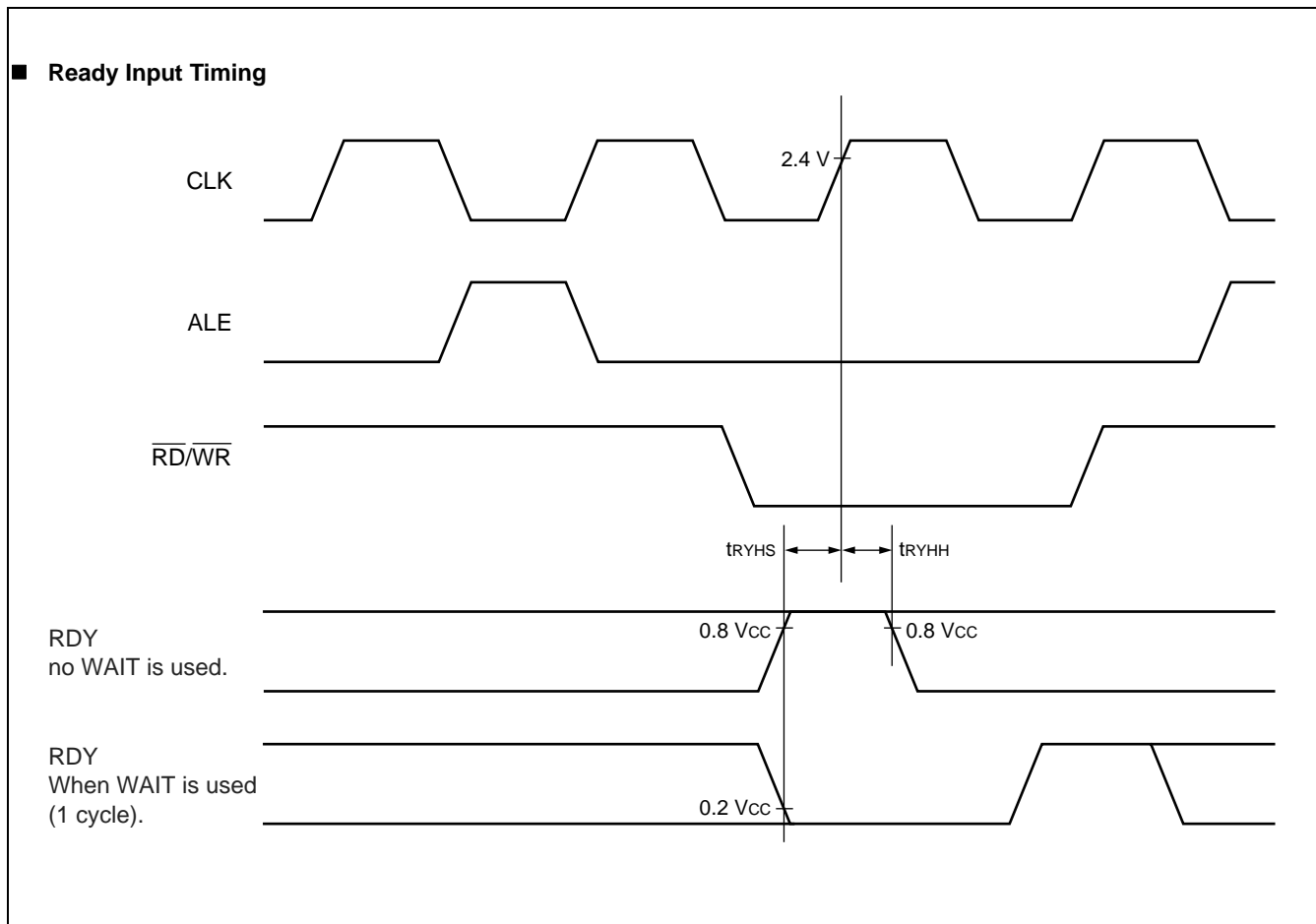
### 11.4.7 Ready Input Timing

(MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 3.5 \text{ V to } 5.5 \text{ V}$ ,  $V_{SS} = AV_{SS} = 0.0 \text{ V}$ ,  $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ )

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 5.0 \text{ V} \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0.0 \text{ V}$ ,  $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ )

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
RDY setup time	$t_{RYHS}$	RDY	—	45	—	ns	
RDY hold time	$t_{RYHH}$	RDY	—	0	—	ns	

Note : If the RDY setup time is insufficient, use the auto-ready function.



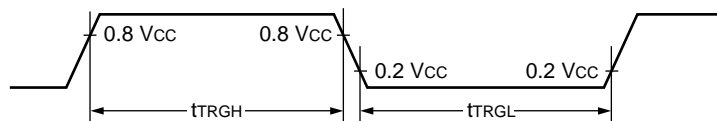
#### 11.4.12 Trigger Input Timing

(MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 3.5\text{ V to }5.5\text{ V}$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 5.0\text{ V} \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
Input pulse width	$t_{TRGH}$	INT0 to INT7, ADTG	—	5 $t_{CP}$	—	ns	Under normal operation
	$t_{TRGL}$			1	—	$\mu\text{s}$	In stop mode

#### ■ Trigger Input Timing



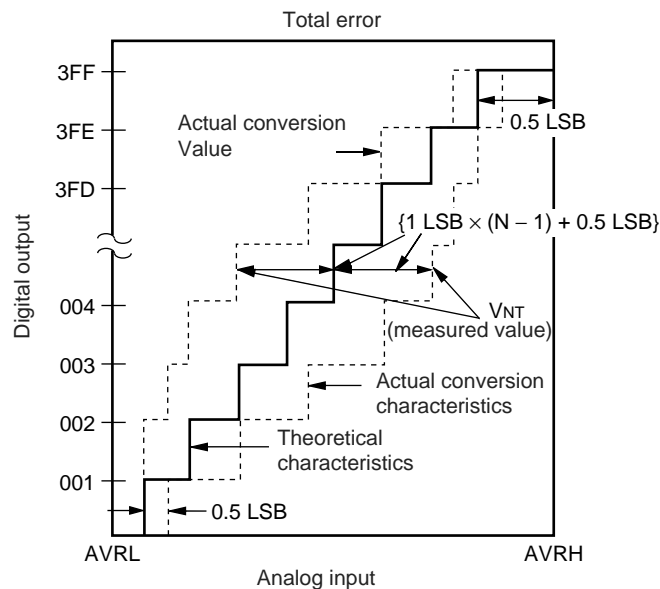
### 11.5.2 A/D Converter Glossary

**Resolution :** Analog changes that are identifiable with the A/D converter

**Linearity error :** The deviation of the straight line connecting the zero transition point ("00 0000 0000" ↔ "00 0000 0001") with the full-scale transition point ("11 1111 1110" ↔ "11 1111 1111") from actual conversion characteristics

**Differential linearity error :** The deviation of input voltage needed to change the output code by 1 LSB from the theoretical value

**Total error :** The total error is defined as a difference between the actual value and the theoretical value, which includes zero-transition error/full-scale transition error and linearity error.



$$1 \text{ LSB} = (\text{Theoretical value}) \frac{AVRH - AVRL}{1024} [\text{V}]$$

$$V_{OT} (\text{Theoretical value}) = AVRL + 0.5 \text{ LSB} [\text{V}]$$

$$V_{FST} (\text{Theoretical value}) = AVRH - 1.5 \text{ LSB} [\text{V}]$$

$$\text{Total error for digital output } N = \frac{V_{NT} - \{1 \text{ LSB} \times (N - 1) + 0.5 \text{ LSB}\}}{1 \text{ LSB}} [\text{LSB}]$$

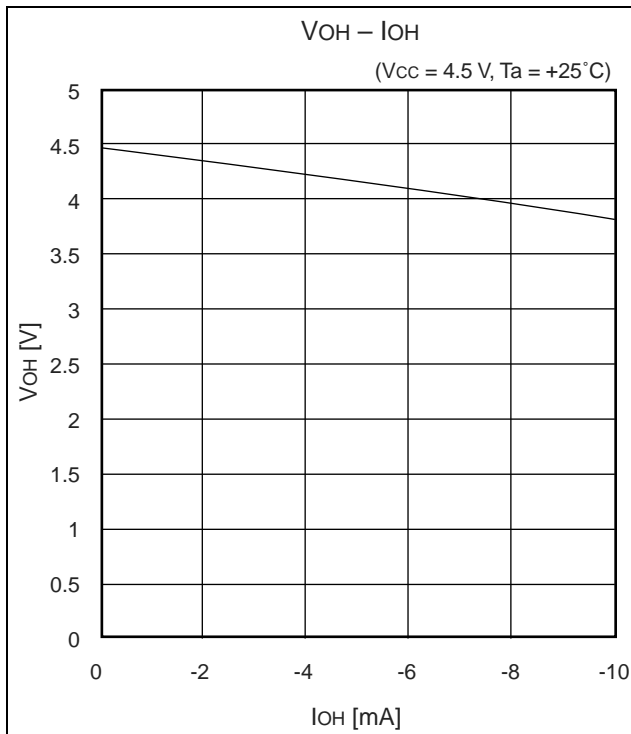
$V_{NT}$  : Voltage at a transition of digital output from (N - 1) to N

(Continued)

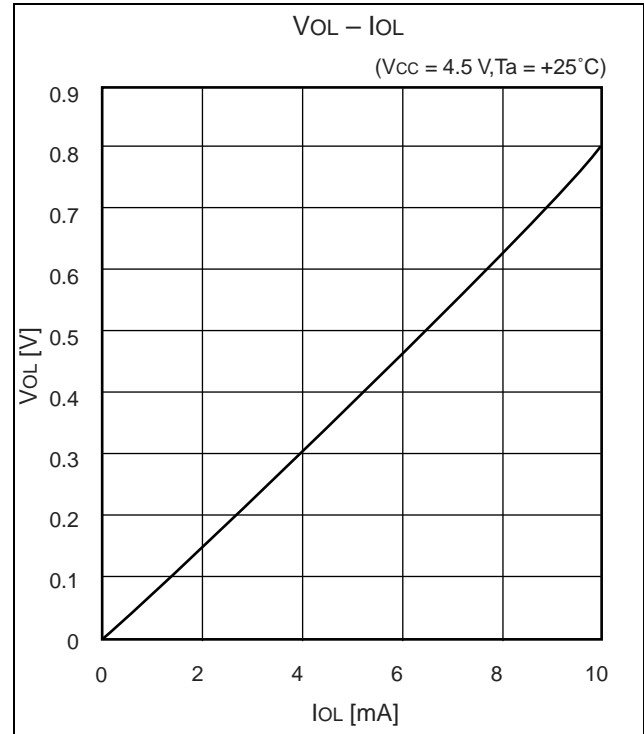


## 12. Example Characteristics

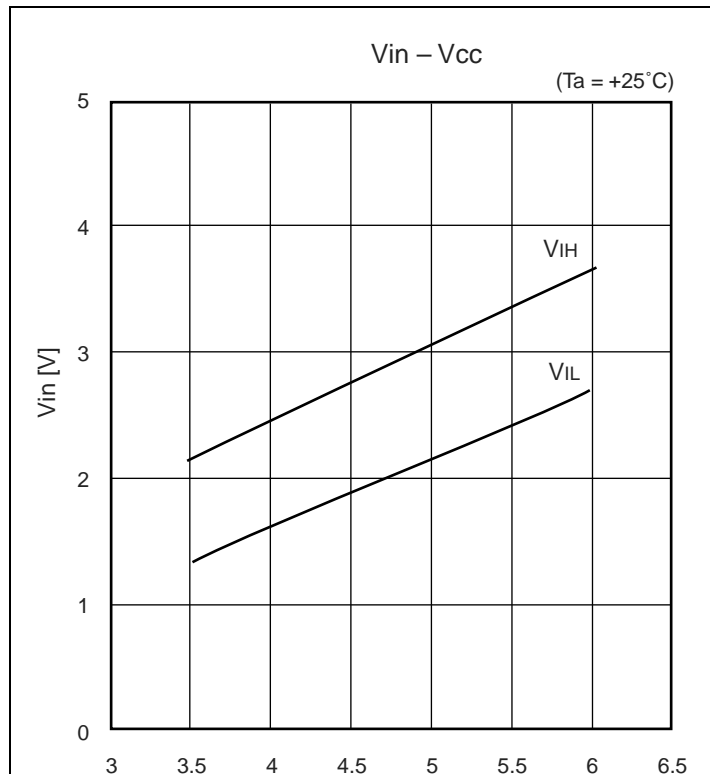
■ “H” level output voltage



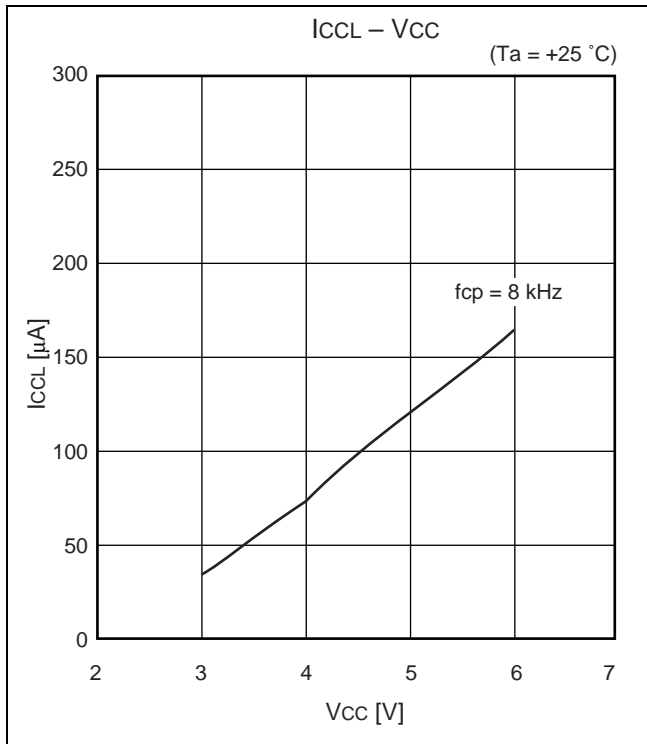
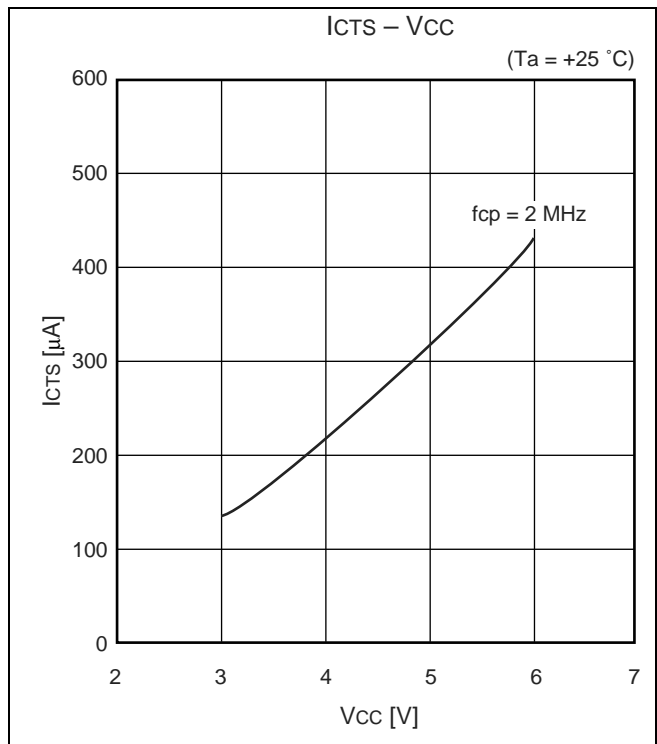
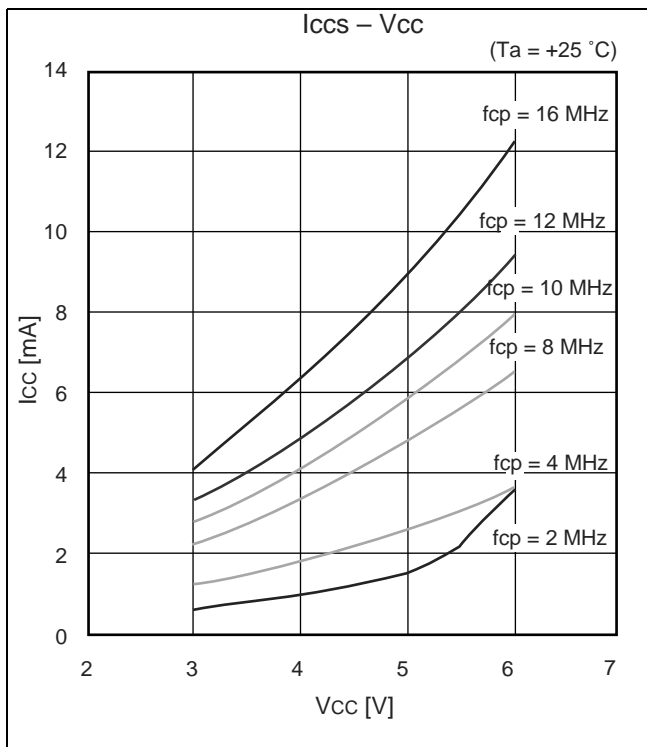
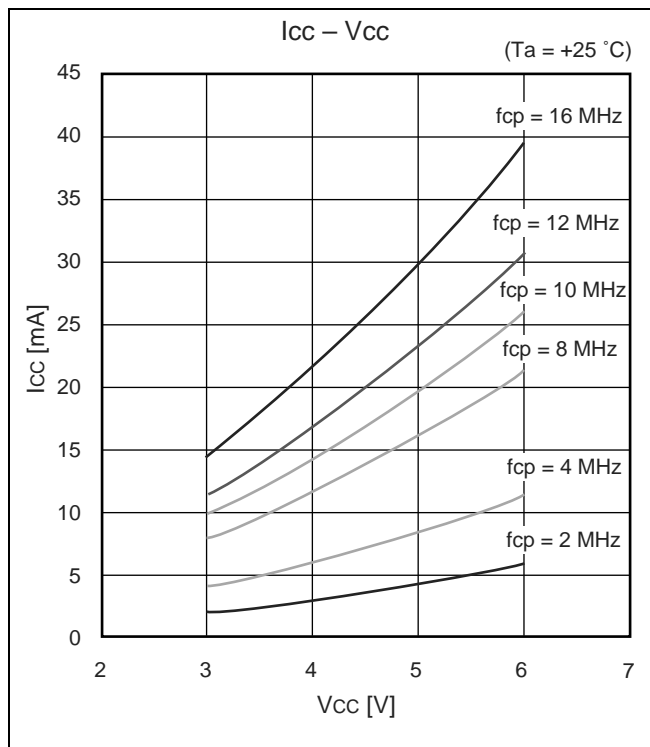
■ “L” level output voltage



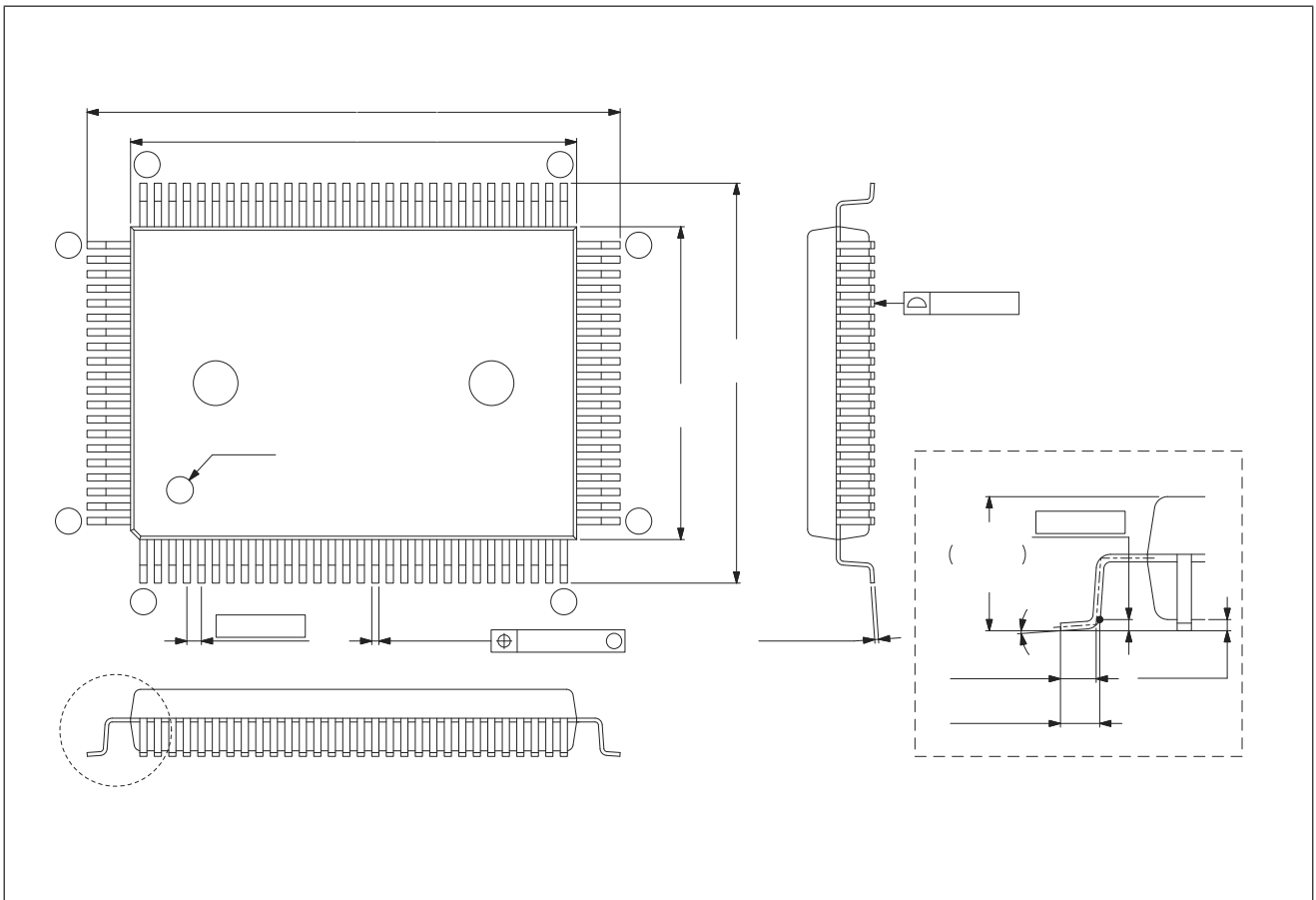
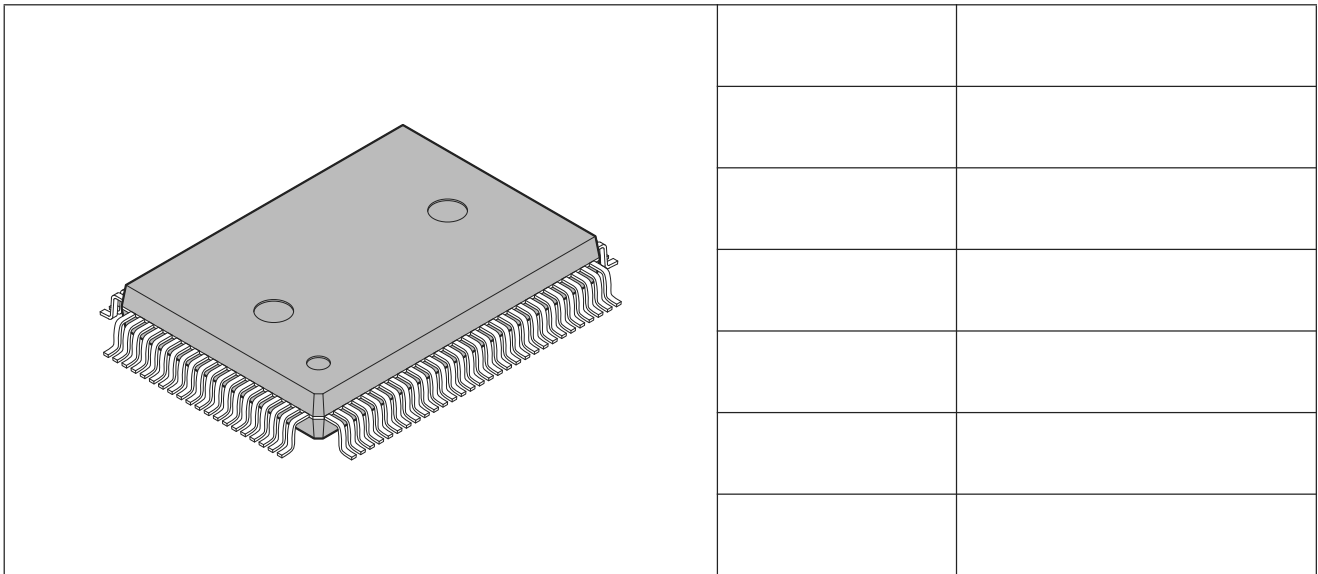
■ “H” level input voltage/ “L” level input voltage  
(Hysteresis input)



■ Power supply current (MB90F549G)



## 14. Package Dimensions



(Continued)

## 15. Major Changes

Spanson Publication Number: DS07-13703-7E

Section	Change Results
■ PRODUCT LINEUP	Changed the name in peripheral resource. 16-bit I/O Timer → 16-bit Free-run Timer
■ I/O CIRCUIT TYPE	Changed the name of input typ. Hysteresis → CMOS Hysteresis HYS → CMOS Hysteresis
■ BLOCK DIAGRAM	Changed the arrow direction of SOT1 signal at UART1(SCI). “← →” (input/output) → “←” (output)
■ I/O MAP	Changed the text of “Note”.
■ INTERRUPT MAP	Changed the name of peripheral resource of the pin number: #19. I/O Timer → 16-bit Free-run Timer
■ ELECTRICAL CHARACTERISTICS	Changed the remarks of “parameter: Power supply voltage”.
2. Recommended Conditions	
3. DC Characteristics	Changed the maximum value of symbol : VILM of parameter: Input voltage. $V_{CC} + 0.3 \rightarrow V_{SS} + 0.3$ Added the following remarks for parameter : Pull-down resistance. Except Flash device
4. AC Characteristics	Added the value when using an external clock in Oscillation frequency and Clock cycle time on (1) Clock Timing for parameter.
(1) Clock Timing	Added the item of A/D converter operation range in figure of “■ Guaranteed PLL operation range”
(3) Reset and Hardware Standby Input Timing	Changed the following item. (3) Reset and Hardware Standby Input Timing Remarks: In sub-clock mode, sub-sleep mode, timer mode $2t_{CP} \rightarrow 2t_{LCP}$
(4) Power On Reset	Changed as follows; Due to repetitive operation → Waiting time until power-on
5. A/D Converter	Changed the unit of Zero transition voltage and Full scale transition voltage. mV → V
■ ORDERING INFORMATION	Added the MB90F548GLPMC in Part Numbers.

**NOTE:** Please see “Document History” about later revised information.

## Document History

Document Title: MB90F543G(S)/546G(S)/548G(S)/549G(S)/549G(S)/V540G/MB90543G(S)/547G(S)/548G(S)/F548GL(S) CMOS F2MC-16LX MB90540G/545G Series 16-bit Proprietary Microcontroller Document Number: 002-07696				
Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	—	AKIH	11/13/2008	Migrated to Cypress and assigned document number 002-07696. No change to document contents or format.
*A	5537115	AKIH	11/30/2016	Updated to Cypress template

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