



Welcome to [E-XFL.COM](#)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

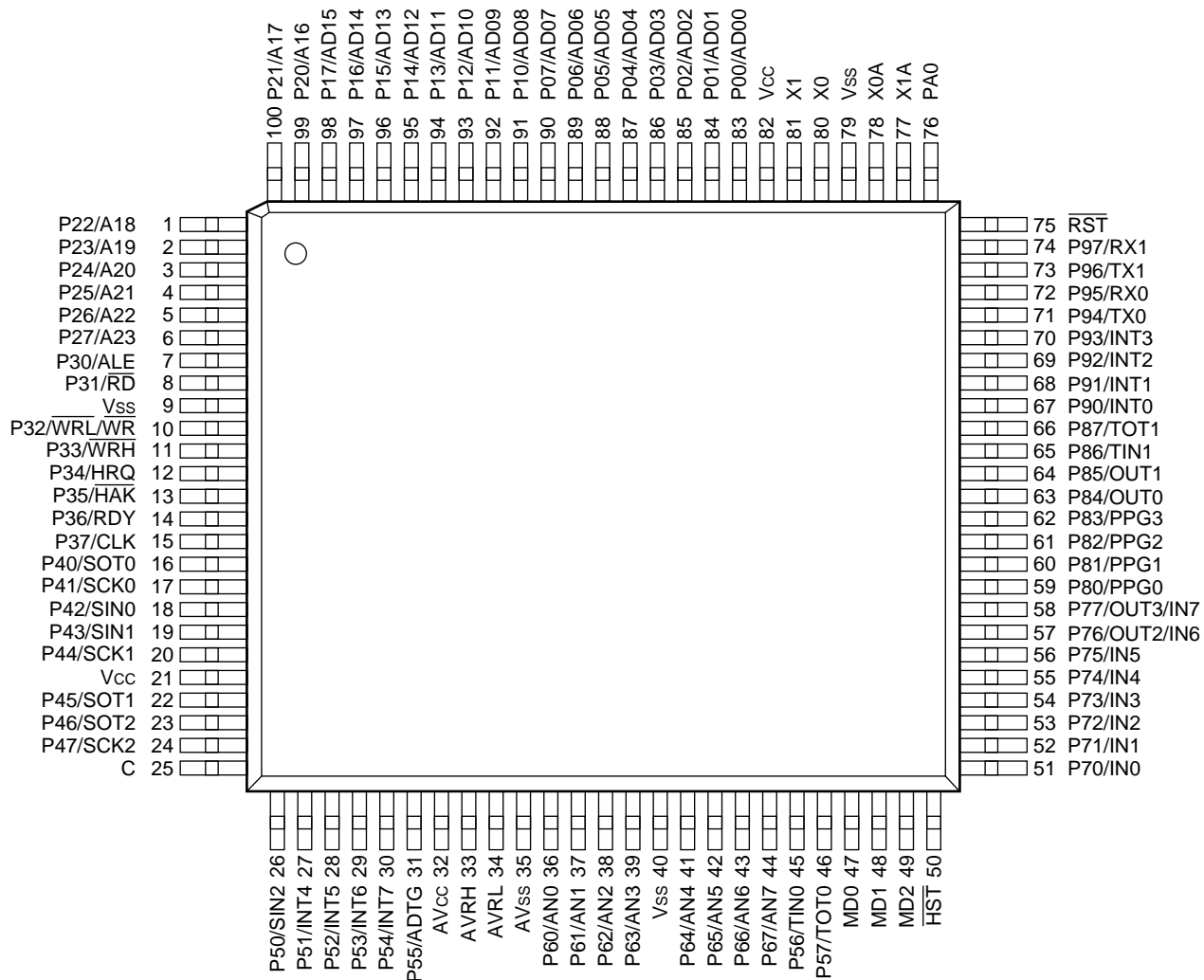
Product Status	Obsolete
Core Processor	F <sup>2</sup> MC-16LX
Core Size	16-Bit
Speed	16MHz
Connectivity	CANbus, EBI/EMI, SCI, Serial I/O, UART/USART
Peripherals	POR, WDT
Number of I/O	81
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/mb90f543gspmc-ge1">https://www.e-xfl.com/product-detail/infineon-technologies/mb90f543gspmc-ge1</a>

\*2 : It is setting of DIP switch S2 when Emulation pod (MB2145-507) is used. Please refer to the MB2145-507 hardware manual (2.7 Emulator-specific Power Pin) about details.

\*3 : Operating Voltage Range

Products	Operation guarantee range
MB90F543G(S)/F546G(S)/F548G(S)/ MB90549G(S)/F549G(S)/V540/V540G	4.5 V to 5.5 V
MB90F548GL(S)/543G(S)/547G(S)/548G(S)	3.5 V to 5.5 V

(TOP VIEW)



(FPT-100P-M20)

### 3. Pin Description

Pin No.		Pin name	Circuit type	Function
LQFP <sup>2</sup>	QFP <sup>1</sup>			
80 81	82 83	X0 X1	A (Oscillation)	High speed crystal oscillator input pins
78	80	X0A	A (Oscillation)	Low speed crystal oscillator input pins. For the one clock system parts, perform external pull-down processing.
77	79	X1A		Low speed crystal oscillator input pins. For the one clock system parts, leave it open.
75	77	$\overline{\text{RST}}$	B	External reset request input pin
50	52	$\overline{\text{HST}}$	C	Hardware standby input pin
83 to 90	85 to 92	P00 to P07	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		AD00 to AD07		I/O pins for 8 lower bits of the external address/data bus. This function is enabled when the external bus is enabled.
91 to 98	93 to 100	P10 to P17	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		AD08 to AD15		I/O pins for 8 higher bits of the external address/data bus. This function is enabled when the external bus is enabled.
99 to 6	1 to 8	P20 to P27	I	General I/O port with programmable pullup. In external bus mode, this function is valid when the corresponding bits in the external address output control resister (HACR) are set to "1".
		A16 to A23		8-bit I/O pins for A16 to A23 at the external address/data bus. In external bus mode, this function is valid when the corresponding bits in the external address output control resister (HACR) are set to "0".
7	9	P30	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		ALE		Address latch enable output pin. This function is enabled when the external bus is enabled.
8	10	P31	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode.
		$\overline{\text{RD}}$		Read strobe output pin for the data bus. This function is enabled when the external bus is enabled.
10	12	P32	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the $\overline{\text{WR}}/\overline{\text{WRL}}$ pin output is disabled.
		$\overline{\text{WRL}}$		Write strobe output pin for the data bus. This function is enabled when both the external bus and the $\overline{\text{WR}}/\overline{\text{WRL}}$ pin output are enabled. $\overline{\text{WRL}}$ is write-strobe output pin for the lower 8 bits of the data bus in 16-bit access.
		$\overline{\text{WR}}$		$\overline{\text{WR}}$ is write-strobe output pin for the 8 bits of the data bus in 8-bit access.

(Continued)

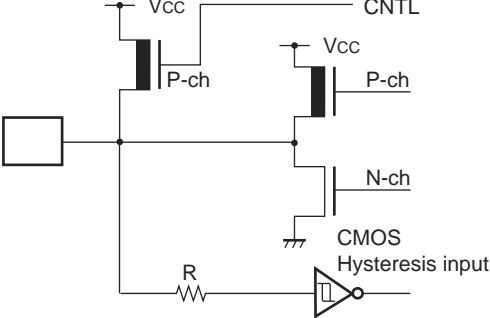
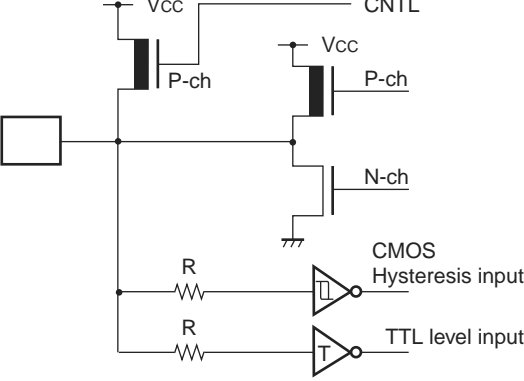
(Continued)

Pin No.		Pin name	Circuit type	Function
LQFP <sup>*2</sup>	QFP <sup>*1</sup>			
72	74	P95	D	General I/O port. This function is always enabled.
		RX0		RX input pin for CAN0 Interface. When the CAN function is used, output from the other functions must be stopped.
73	75	P96	D	General I/O port. This function is enabled when CAN1 disables the output.
		TX1		TX output pin for CAN1. This function is enabled when CAN1 enables the output (only MB90540G series) .
74	76	P97	D	General I/O port. This function is always enabled.
		RX1		RX input pin for CAN1 Interface. When the CAN function is used, output from the other functions must be stopped (only MB90540G series) .
76	78	PA0	D	General I/O port. This function is always enabled.
32	34	AV <sub>CC</sub>	Power supply	Power supply pin for the A/D Converter. This power supply must be turned on or off while a voltage higher than or equal to AV <sub>CC</sub> is applied to V <sub>CC</sub> .
35	37	AV <sub>SS</sub>	Power supply	Power supply pin for the A/D Converter.
33	35	AVRH	Power supply	External reference voltage input pin for the A/D Converter. This power supply must be turned on or off while a voltage higher than or equal to AVRH is applied to AV <sub>CC</sub> .
34	36	AVRL	Power supply	External reference voltage input pin for the A/D Converter.
47, 48	49, 50	MD0, MD1	C	Input pins for specifying the operating mode. The pins must be directly connected to V <sub>CC</sub> or V <sub>SS</sub> .
49	51	MD2	F	Input pin for specifying the operating mode. The pin must be directly connected to V <sub>CC</sub> or V <sub>SS</sub> .
25	27	C	—	Power supply stabilization capacitor pin. It should be connected externally to an 0.1 $\mu$ F ceramic capacitor.
21, 82	23, 84	V <sub>CC</sub>	Power supply	Input pin for power supply (5.0 V) .
9, 40, 79	11, 42, 81	V <sub>SS</sub>	Power supply	Input pin for power supply (0.0 V) .

\*1 : FPT-100P-M06

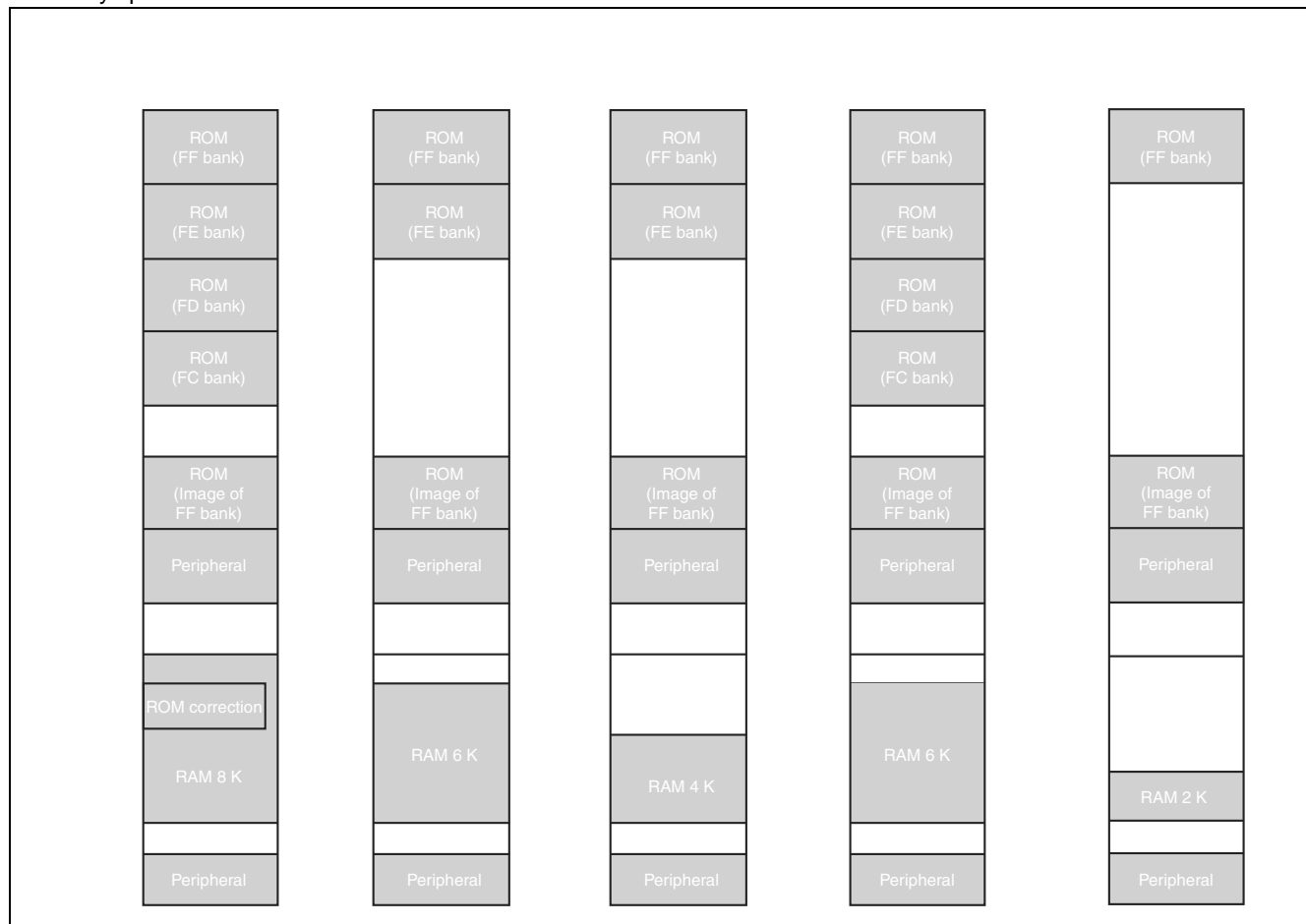
\*2 : FPT-100P-M20

(Continued)

Circuit type	Diagram	Remarks
H		<ul style="list-style-type: none"> <li>■ CMOS level output</li> <li>■ CMOS Hysteresis input</li> <li>■ Programmable pull-up resistor : 50 kΩ approx.</li> </ul>
I		<ul style="list-style-type: none"> <li>■ CMOS level output</li> <li>■ CMOS Hysteresis input</li> <li>■ TTL level input (Flash devices in Flash writer mode only)</li> <li>■ Programmable pullup resistor : 50 kΩ approx.</li> </ul>

## 7. Memory Map

The memory space of the MB90540G/545G Series is shown below.



Note : The high-order portion of bank 00 gives the image of the FF bank ROM to make the small model of the C compiler effective. Since the low-order 16 bits address are the same, the table in ROM can be referenced without using the “far” specification in the pointer declaration.

For example, an attempt to access 00C000<sub>H</sub> accesses the value at FFC000<sub>H</sub> in ROM. The ROM area in bank FF exceeds 48 Kbytes, and its entire image cannot be shown in bank 00. The image between FF4000<sub>H</sub> and FFFFFFF<sub>H</sub> is visible in bank 00, while the image between FF0000<sub>H</sub> and FF3FFF<sub>H</sub> is visible only in bank FF.

Address	Register	Abbreviation	Access	Resource name	Initial value
A2 <sub>H</sub> to A4 <sub>H</sub>	Prohibited				
A5 <sub>H</sub>	Automatic ready function select register	ARSR	W	External Memory Access	0 0 1 1 _ _ 0 0 <sub>B</sub>
A6 <sub>H</sub>	External address output control register	HACR	W		0 0 0 0 0 0 0 0 <sub>B</sub>
A7 <sub>H</sub>	Bus control signal selection register	ECSR	W		0 0 0 0 0 0 0 _ <sub>B</sub>
A8 <sub>H</sub>	Watchdog Timer control register	WDTC	R/W	Watchdog Timer	XXXXX 1 1 1 <sub>B</sub>
A9 <sub>H</sub>	Time Base Timer Control register	TBTC	R/W	Time Base Timer	1 - - 0 0 1 0 0 <sub>B</sub>
AA <sub>H</sub>	Watch timer control register	WTC	R/W	Watch Timer	1 X 0 0 0 0 0 0 <sub>B</sub>
AB <sub>H</sub> to AD <sub>H</sub>	Prohibited				
AE <sub>H</sub>	Flash memory control status register (Flash only, otherwise reserved)	FMCS	R/W	Flash Memory	0 0 0 X 0 0 0 0 <sub>B</sub>
AF <sub>H</sub>	Prohibited				
B0 <sub>H</sub>	Interrupt control register 00	ICR00	R/W	Interrupt controller	0 0 0 0 0 1 1 1 <sub>B</sub>
B1 <sub>H</sub>	Interrupt control register 01	ICR01	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
B2 <sub>H</sub>	Interrupt control register 02	ICR02	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
B3 <sub>H</sub>	Interrupt control register 03	ICR03	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
B4 <sub>H</sub>	Interrupt control register 04	ICR04	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
B5 <sub>H</sub>	Interrupt control register 05	ICR05	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
B6 <sub>H</sub>	Interrupt control register 06	ICR06	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
B7 <sub>H</sub>	Interrupt control register 07	ICR07	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
B8 <sub>H</sub>	Interrupt control register 08	ICR08	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
B9 <sub>H</sub>	Interrupt control register 09	ICR09	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
BA <sub>H</sub>	Interrupt control register 10	ICR10	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
BB <sub>H</sub>	Interrupt control register 11	ICR11	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
BC <sub>H</sub>	Interrupt control register 12	ICR12	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
BD <sub>H</sub>	Interrupt control register 13	ICR13	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
BE <sub>H</sub>	Interrupt control register 14	ICR14	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
BF <sub>H</sub>	Interrupt control register 15	ICR15	R/W		0 0 0 0 0 1 1 1 <sub>B</sub>
C0 <sub>H</sub> to FF <sub>H</sub>	External				

Address	Register	Abbreviation	Access	Resource name	Initial value
1FF0 <sub>H</sub>	Program address detection register 0	PADR0	R/W	Address Match Detection Function	XXXXXXXX <sub>B</sub>
1FF1 <sub>H</sub>	Program address detection register 0	PADR0	R/W		XXXXXXXX <sub>B</sub>
1FF2 <sub>H</sub>	Program address detection register 0	PADR0	R/W		XXXXXXXX <sub>B</sub>
1FF3 <sub>H</sub>	Program address detection register 1	PADR1	R/W		XXXXXXXX <sub>B</sub>
1FF4 <sub>H</sub>	Program address detection register 1	PADR1	R/W		XXXXXXXX <sub>B</sub>
1FF5 <sub>H</sub>	Program address detection register 1	PADR1	R/W		XXXXXXXX <sub>B</sub>

(Continued)



*(Continued)*

Address	Register	Abbreviation	Access	Resource name	Initial value
3928 <sub>H</sub>	Output Compare Register 0	OCCP0	R/W	Output Compare 0/1	XXXXXXXX <sub>B</sub>
3929 <sub>H</sub>	Output Compare Register 0	OCCP0	R/W		XXXXXXXX <sub>B</sub>
392A <sub>H</sub>	Output Compare Register 1	OCCP1	R/W		XXXXXXXX <sub>B</sub>
392B <sub>H</sub>	Output Compare Register 1	OCCP1	R/W		XXXXXXXX <sub>B</sub>
392C <sub>H</sub>	Output Compare Register 2	OCCP2	R/W	Output Compare 2/3	XXXXXXXX <sub>B</sub>
392D <sub>H</sub>	Output Compare Register 2	OCCP2	R/W		XXXXXXXX <sub>B</sub>
392E <sub>H</sub>	Output Compare Register 3	OCCP3	R/W		XXXXXXXX <sub>B</sub>
392F <sub>H</sub>	Output Compare Register 3	OCCP3	R/W		XXXXXXXX <sub>B</sub>
3930 <sub>H</sub> to 39FF <sub>H</sub>	Reserved				
3A00 <sub>H</sub> to 3AFF <sub>H</sub>	Reserved for CAN 0 Interface.				
3B00 <sub>H</sub> to 3BFF <sub>H</sub>	Reserved for CAN 0 Interface.				
3C00 <sub>H</sub> to 3CFF <sub>H</sub>	Reserved for CAN 1 Interface.				
3D00 <sub>H</sub> to 3DFF <sub>H</sub>	Reserved for CAN 1 Interface.				
3E00 <sub>H</sub> to 3FFF <sub>H</sub>	Reserved				

■ Read/write notation

R/W : Reading and writing permitted  
R : Read-only  
W : Write-only

■ Initial value notation

0 : Initial value is "0".  
1 : Initial value is "1".  
X : Initial value is undefined.  
\_ : Initial value is unused.

**Note:** Any write access to reserved addresses in I/O map should not be performed. A read access to reserved addresses results in reading "X".

## 9. CAN Controller

The MB90540G series contains two CAN controllers (CAN0 and CAN1) , the MB90545G series contains only one (CAN0) . The Evaluation Chip MB90V540G also has two CAN controllers.

The CAN controller has the following features :

- Conforms to CAN Specification Version 2.0 Part A and B
  - Supports transmission/reception in standard frame and extended frame formats
- Supports transmission of data frames by receiving remote frames
- 16 transmitting/receiving message buffers
  - 29-bit ID and 8-byte data
  - Multi-level message buffer configuration
- Provides full-bit comparison, full-bit mask, acceptance register 0/acceptance register 1 for each message buffer as ID acceptance mask
  - Two acceptance mask registers in either standard frame format or extended frame formats
- Bit rate programmable from 10 Kbps to 1 Mbps (when input clock is at 16 MHz)

### List of Control Registers

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
000070 <sub>H</sub>	000080 <sub>H</sub>	Message buffer valid register	BVALR	R/W	00000000 00000000 <sub>B</sub>
000071 <sub>H</sub>	000081 <sub>H</sub>				
000072 <sub>H</sub>	000082 <sub>H</sub>	Transmit request register	TREQR	R/W	00000000 00000000 <sub>B</sub>
000073 <sub>H</sub>	000083 <sub>H</sub>				
000074 <sub>H</sub>	000084 <sub>H</sub>	Transmit cancel register	TCANR	W	00000000 00000000 <sub>B</sub>
000075 <sub>H</sub>	000085 <sub>H</sub>				
000076 <sub>H</sub>	000086 <sub>H</sub>	Transmit complete register	TCR	R/W	00000000 00000000 <sub>B</sub>
000077 <sub>H</sub>	000087 <sub>H</sub>				
000078 <sub>H</sub>	000088 <sub>H</sub>	Receive complete register	RCR	R/W	00000000 00000000 <sub>B</sub>
000079 <sub>H</sub>	000089 <sub>H</sub>				
00007A <sub>H</sub>	00008A <sub>H</sub>	Remote request receiving register	RRTRR	R/W	00000000 00000000 <sub>B</sub>
00007B <sub>H</sub>	00008B <sub>H</sub>				
00007C <sub>H</sub>	00008C <sub>H</sub>	Receive overrun register	ROVRR	R/W	00000000 00000000 <sub>B</sub>
00007D <sub>H</sub>	00008D <sub>H</sub>				
00007E <sub>H</sub>	00008E <sub>H</sub>	Receive interrupt enable register	RIER	R/W	00000000 00000000 <sub>B</sub>
00007F <sub>H</sub>	00008F <sub>H</sub>				

(Continued)

## 10. Interrupt Map

Interrupt cause	EI <sup>2</sup> OS clear	Interrupt vector		Interrupt control register	
		Number	Address	Number	Address
Reset	N/A	#08	FFFFDC <sub>H</sub>	—	—
INT9 instruction	N/A	#09	FFFFD8 <sub>H</sub>	—	—
Exception	N/A	#10	FFFFD4 <sub>H</sub>	—	—
CAN 0 RX	N/A	#11	FFFFD0 <sub>H</sub>	ICR00	0000B0 <sub>H</sub>
CAN 0 TX/NS	N/A	#12	FFFFCC <sub>H</sub>		
CAN 1 RX	N/A	#13	FFFFC8 <sub>H</sub>	ICR01	0000B1 <sub>H</sub>
CAN 1 TX/NS	N/A	#14	FFFFC4 <sub>H</sub>		
External Interrupt INT0/INT1	*1	#15	FFFFC0 <sub>H</sub>	ICR02	0000B2 <sub>H</sub>
Time Base Timer	N/A	#16	FFFFBC <sub>H</sub>		
16-bit Reload Timer 0	*1	#17	FFFFB8 <sub>H</sub>	ICR03	0000B3 <sub>H</sub>
8/10-bit A/D Converter	*1	#18	FFFFB4 <sub>H</sub>		
16-bit Free-run Timer	N/A	#19	FFFFB0 <sub>H</sub>	ICR04	0000B4 <sub>H</sub>
External Interrupt INT2/INT3	*1	#20	FFFFAC <sub>H</sub>		
Serial I/O	*1	#21	FFFFA8 <sub>H</sub>	ICR05	0000B5 <sub>H</sub>
8/16-bit PPG 0/1	N/A	#22	FFFFA4 <sub>H</sub>		
Input Capture 0	*1	#23	FFFFA0 <sub>H</sub>	ICR06	0000B6 <sub>H</sub>
External Interrupt INT4/INT5	*1	#24	FFFF9C <sub>H</sub>		
Input Capture 1	*1	#25	FFFF98 <sub>H</sub>	ICR07	0000B7 <sub>H</sub>
8/16-bit PPG 2/3	N/A	#26	FFFF94 <sub>H</sub>		
External Interrupt INT6/INT7	*1	#27	FFFF90 <sub>H</sub>	ICR08	0000B8 <sub>H</sub>
Watch Timer	N/A	#28	FFFF8C <sub>H</sub>		
8/16-bit PPG 4/5	N/A	#29	FFFF88 <sub>H</sub>	ICR09	0000B9 <sub>H</sub>
Input Capture 2/3	*1	#30	FFFF84 <sub>H</sub>		
8/16-bit PPG 6/7	N/A	#31	FFFF80 <sub>H</sub>	ICR10	0000BA <sub>H</sub>
Output Compare 0	*1	#32	FFFF7C <sub>H</sub>		
Output Compare 1	*1	#33	FFFF78 <sub>H</sub>	ICR11	0000BB <sub>H</sub>
Input Capture 4/5	*1	#34	FFFF74 <sub>H</sub>		
Output Compare 2/3 - Input Capture 6/7	*1	#35	FFFF70 <sub>H</sub>	ICR12	0000BC <sub>H</sub>
16-bit Reload Timer 1	*1	#36	FFFF6C <sub>H</sub>		
UART 0 RX	*2	#37	FFFF68 <sub>H</sub>	ICR13	0000BD <sub>H</sub>
UART 0 TX	*1	#38	FFFF64 <sub>H</sub>		
UART 1 RX	*2	#39	FFFF60 <sub>H</sub>	ICR14	0000BE <sub>H</sub>
UART 1 TX	*1	#40	FFFF5C <sub>H</sub>		
Flash Memory	N/A	#41	FFFF58 <sub>H</sub>	ICR15	0000BF <sub>H</sub>
Delayed interrupt	N/A	#42	FFFF54 <sub>H</sub>		

(Continued)

## 11.2 Recommended Conditions

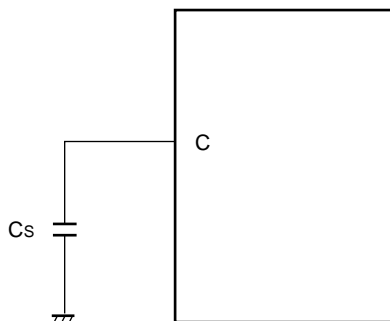
( $V_{SS} = AV_{SS} = 0.0\text{ V}$ )

Parameter	Symbol	Value			Units	Remarks
		Min	Typ	Max		
Power supply voltage	$V_{CC}, AV_{CC}$	4.5	5.0	5.5	V	Under normal operation : Other than MB90F548GL(S)/543G(S)/547G(S)/548G(S)
						Under normal operation when A/D converter is used : MB90F548GL(S)/543G(S)/547G(S)/548G(S)
		3.5	5.0	5.5	V	Under normal operation when A/D converter is not used : MB90F548GL(S)/543G(S)/547G(S)/548G(S)
		3.0	—	5.5	V	Maintain RAM data in stop mode
Smooth capacitor	$C_S$	0.022	0.1	1.0	$\mu\text{F}$	*
Operating temperature	$T_A$	−40	—	+105	°C	

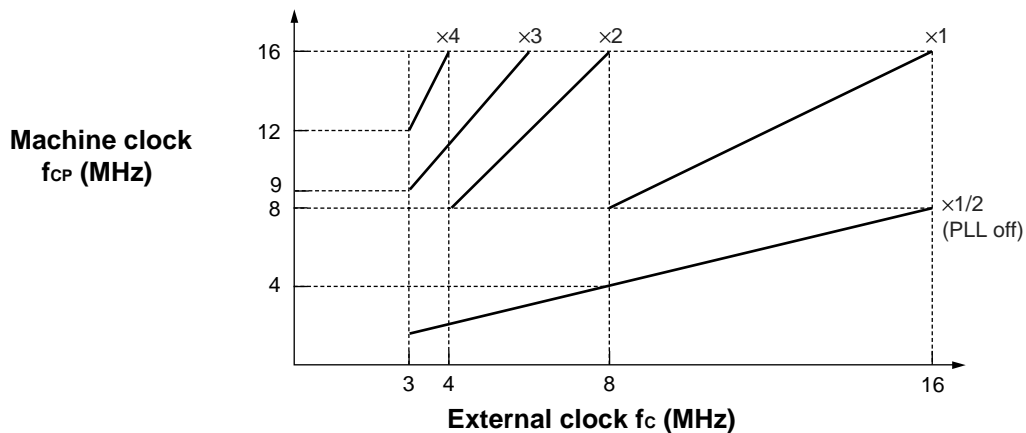
\*: Use a ceramic capacitor or a capacitor of better 4. AC characteristics. The bypass capacitor should be greater than this capacitor.

**WARNING:** The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges. Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure. No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

### ■ C Pin Connection Diagram



■ External clock frequency and Machine clock frequency



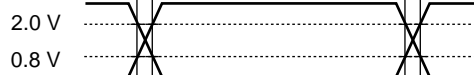
AC characteristics are set to the measured reference voltage values below.

■ Input signal waveform

Hysteresis Input Pin



TTL Input Pin



■ Output signal waveform

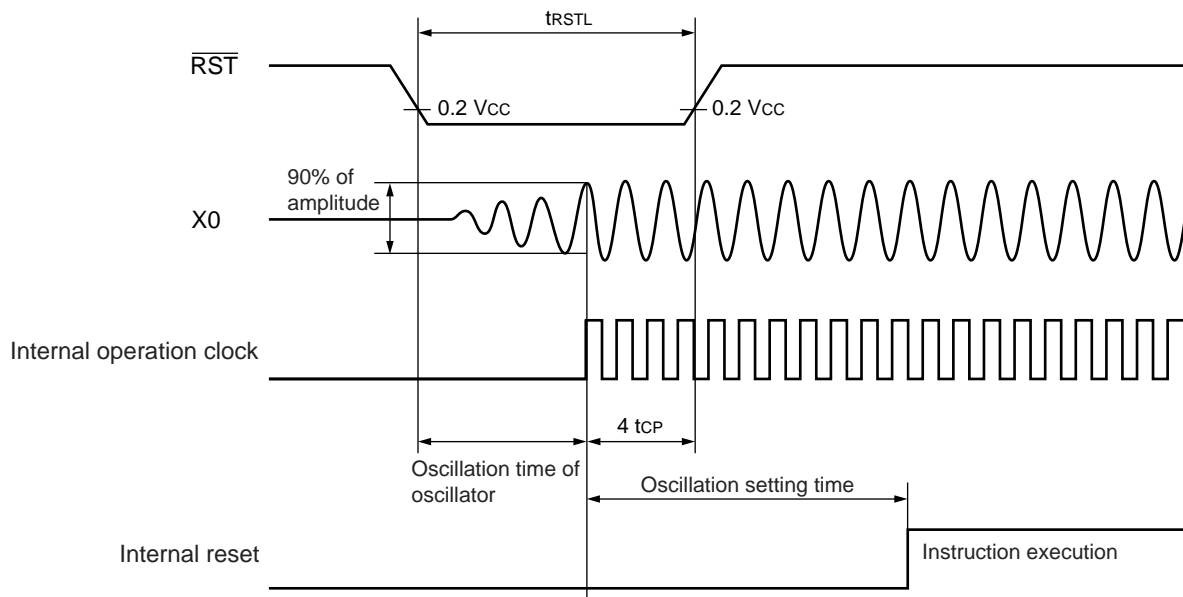
Output Pin

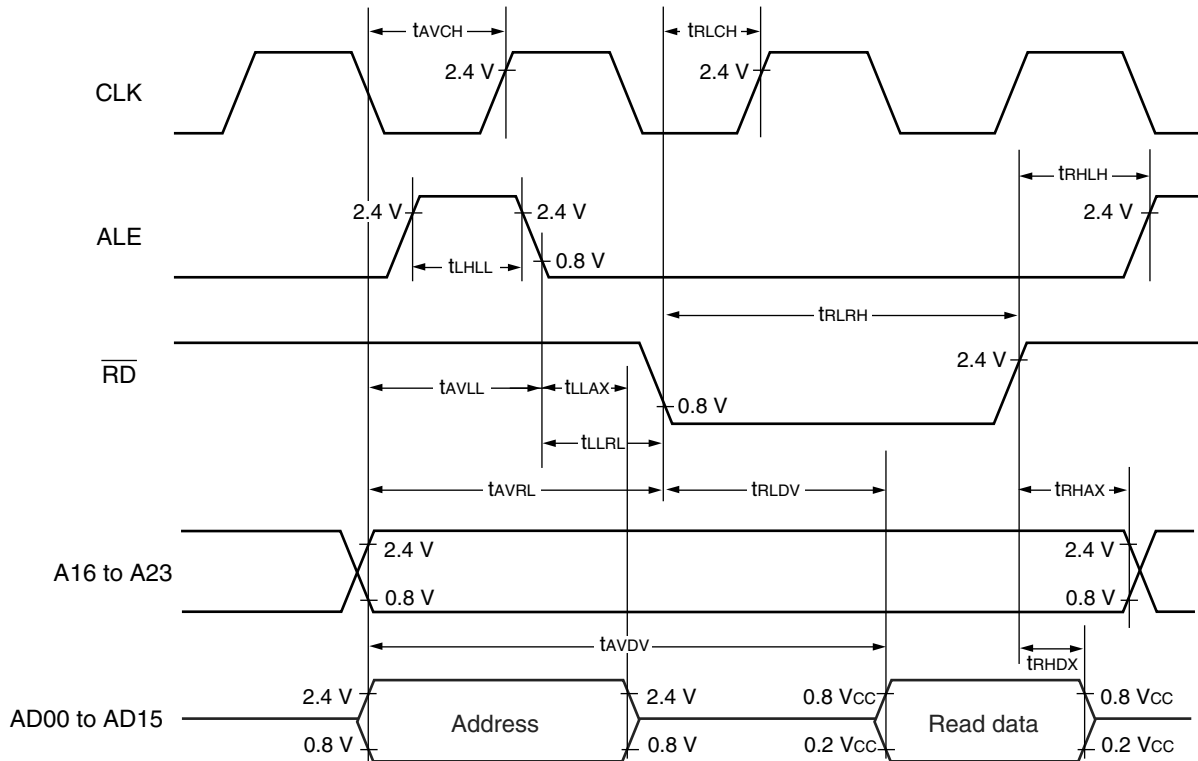


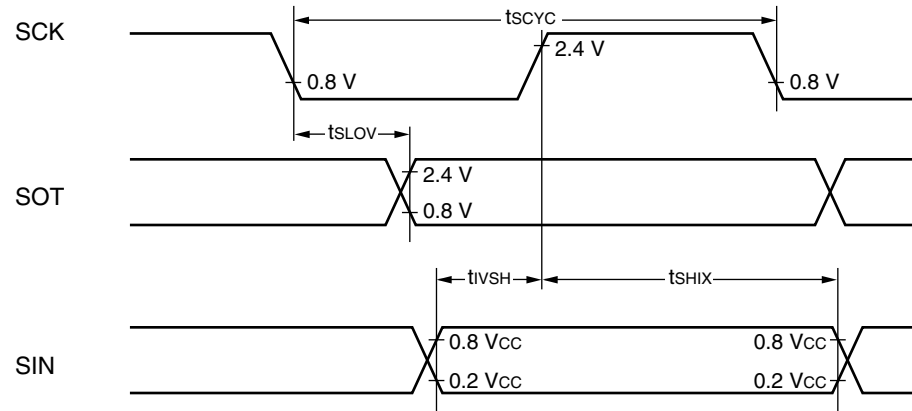
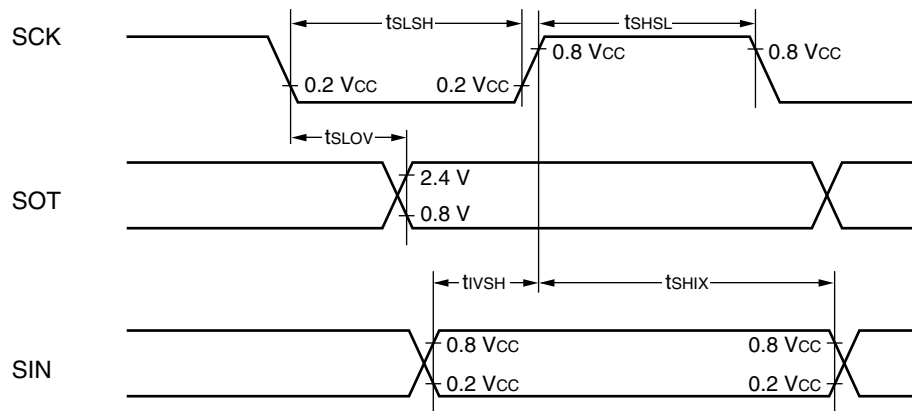
- In under normal operation, pseudo timer mode, sub-clock mode, sub-sleep mode, timer mode



- In stop mode



**■ Bus Timing (Read)**


**Internal Shift Clock Mode**

**External Shift Clock Mode**




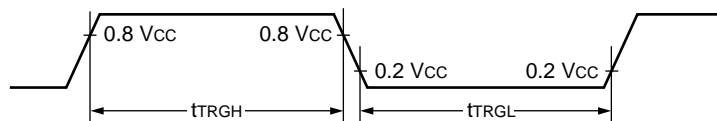
#### 11.4.12 Trigger Input Timing

(MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 3.5\text{ V to }5.5\text{ V}$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

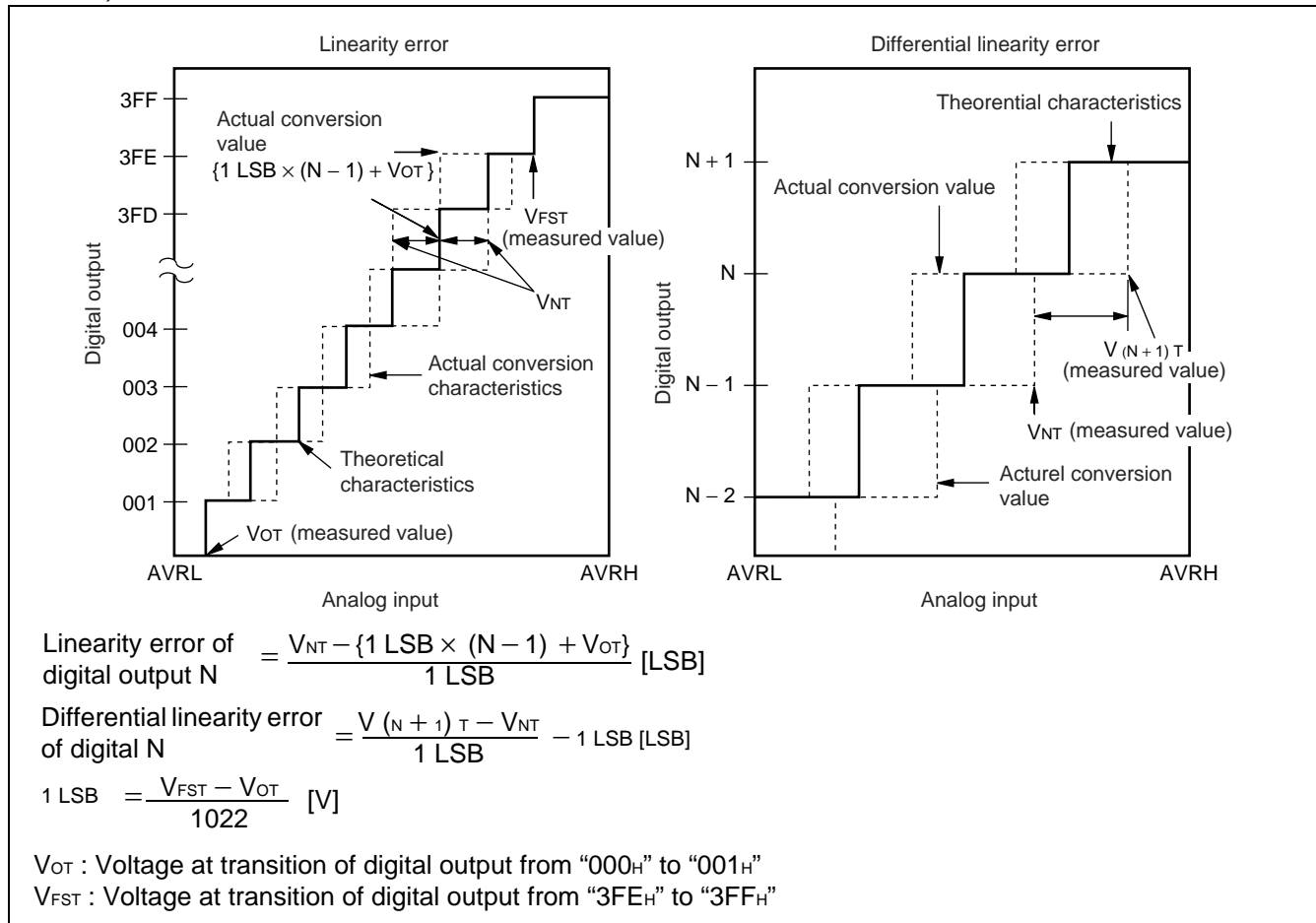
(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S):  $V_{CC} = 5.0\text{ V} \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0.0\text{ V}$ ,  $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$ )

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
Input pulse width	$t_{TRGH}$	INT0 to INT7, ADTG	—	5 $t_{CP}$	—	ns	Under normal operation
	$t_{TRGL}$			1	—	$\mu\text{s}$	In stop mode

#### ■ Trigger Input Timing



(Continued)



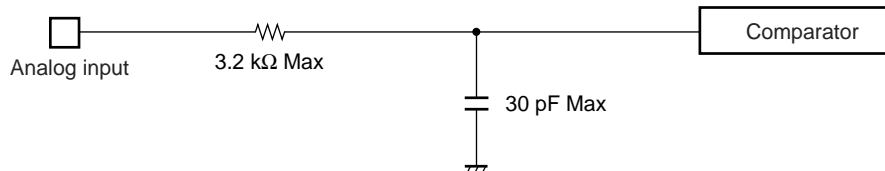
### 11.5.3 Notes on Using A/D Converter

Select the output impedance value for the external circuit of analog input according to the following conditions, :

- Output impedance values of the external circuit of 15 kΩ or lower are recommended.
- When capacitors are connected to external pins, the capacitance of several thousand times the internal capacitor value is recommended to minimized the effect of voltage distribution between the external capacitor and internal capacitor.

Note : When the output impedance of the external circuit is too high, the sampling period for analog voltages may not be sufficient (sampling period = 4.00 μs @machine clock of 16 MHz) .

#### ■ Equipment of analog input circuit model

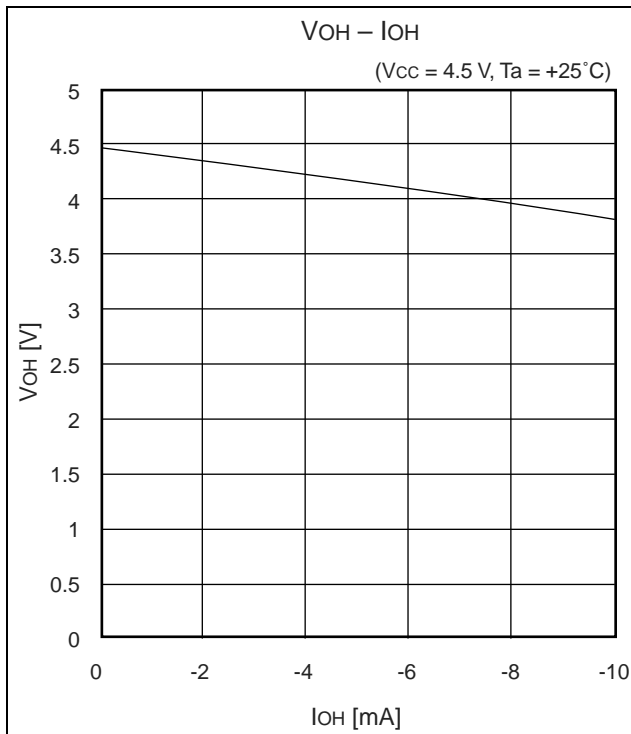


### 11.5.4 Error

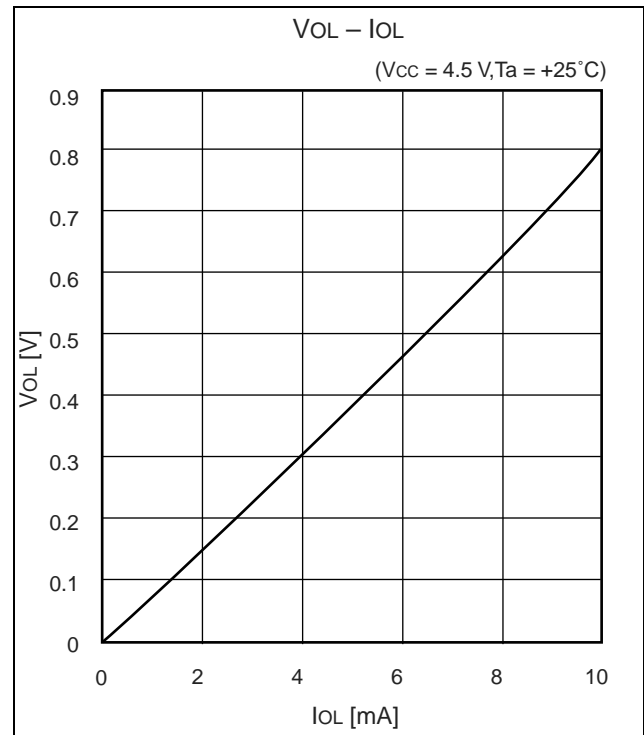
The smaller the |AVRH – AVRL|, the greater the error would become relatively.

## 12. Example Characteristics

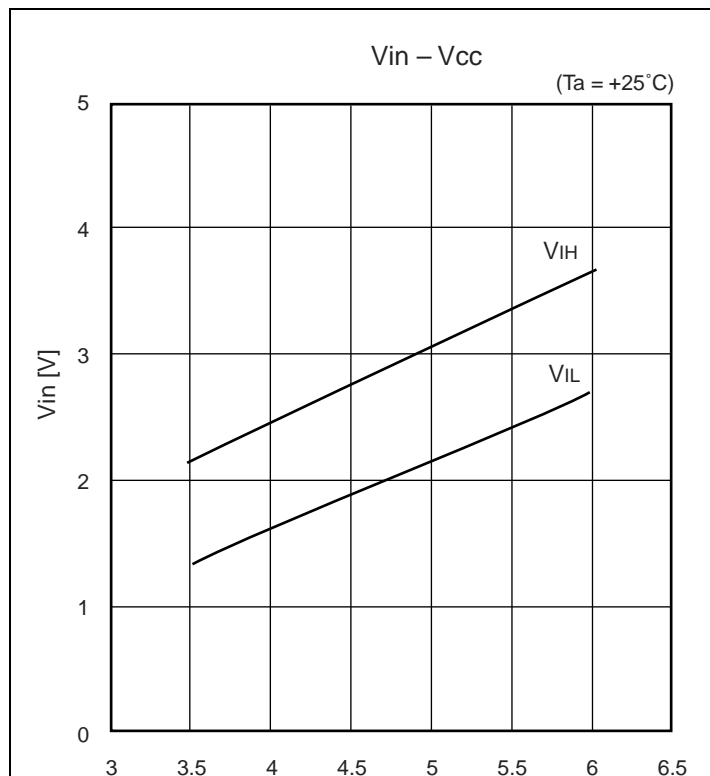
■ “H” level output voltage

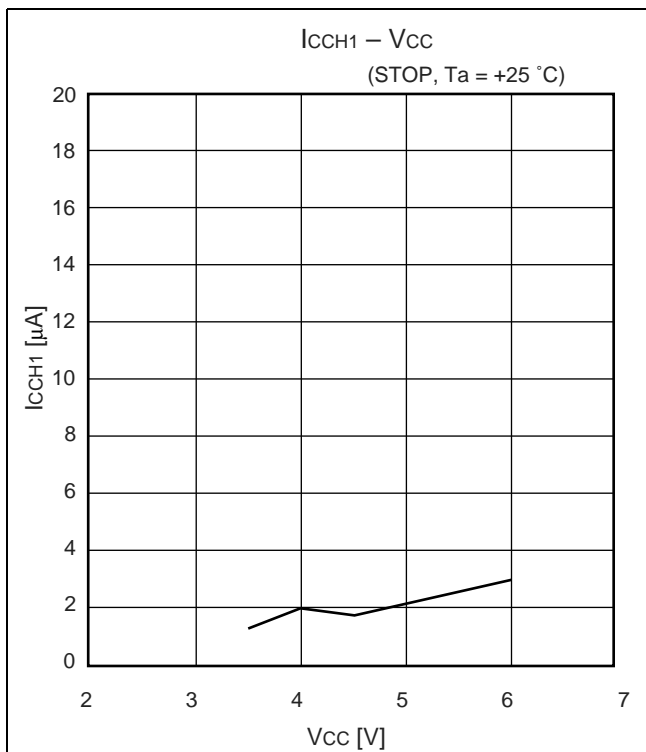
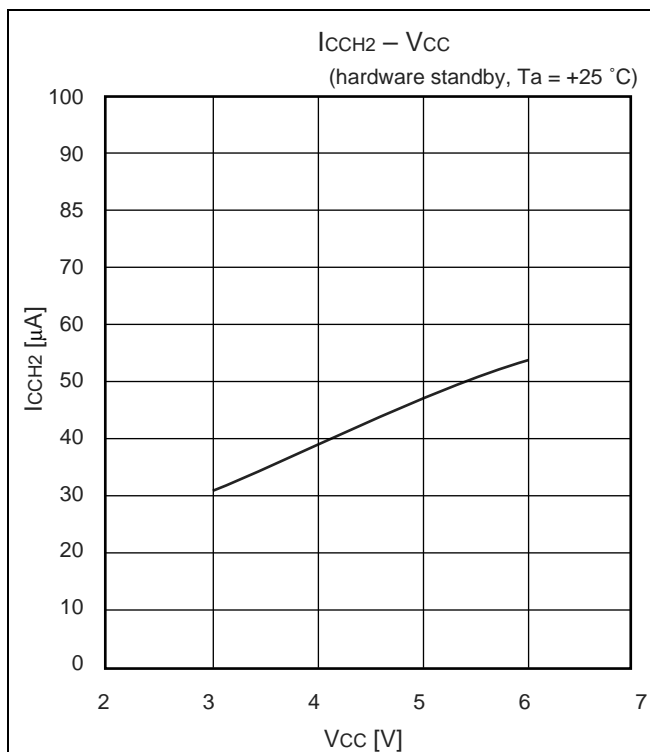
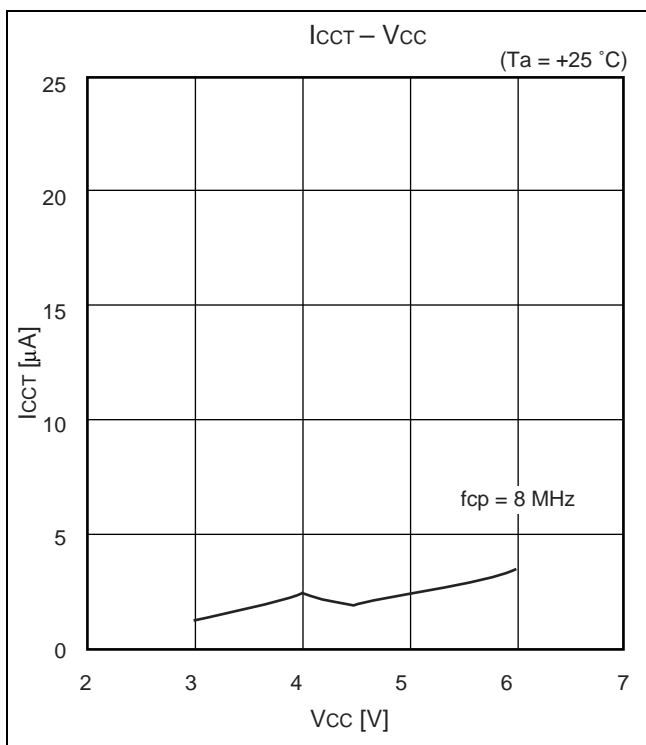
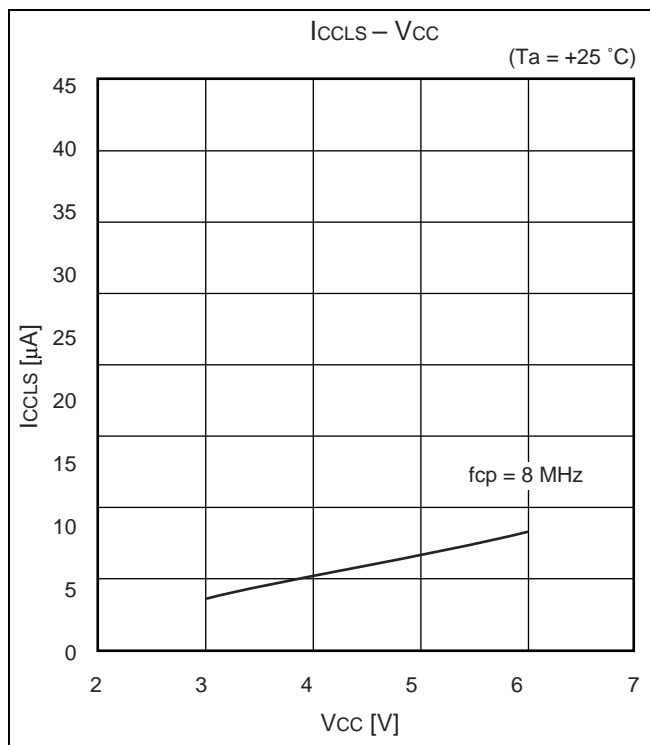


■ “L” level output voltage



■ “H” level input voltage/ “L” level input voltage  
(Hysteresis input)





## Sales, Solutions, and Legal Information

### Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at [Cypress Locations](#).

### Products

ARM® Cortex® Microcontrollers	<a href="http://cypress.com/arm">cypress.com/arm</a>
Automotive	<a href="http://cypress.com/automotive">cypress.com/automotive</a>
Clocks & Buffers	<a href="http://cypress.com/clocks">cypress.com/clocks</a>
Interface	<a href="http://cypress.com/interface">cypress.com/interface</a>
Internet of Things	<a href="http://cypress.com/iot">cypress.com/iot</a>
Lighting & Power Control	<a href="http://cypress.com/powerpsoc">cypress.com/powerpsoc</a>
Memory	<a href="http://cypress.com/memory">cypress.com/memory</a>
PSoC	<a href="http://cypress.com/psoc">cypress.com/psoc</a>
Touch Sensing	<a href="http://cypress.com/touch">cypress.com/touch</a>
USB Controllers	<a href="http://cypress.com/usb">cypress.com/usb</a>
Wireless/RF	<a href="http://cypress.com/wireless">cypress.com/wireless</a>

### PSoC® Solutions

[PSoC 1](#) | [PSoC 3](#) | [PSoC 4](#) | [PSoC 5LP](#)

### Cypress Developer Community

[Forums](#) | [Projects](#) | [Video](#) | [Blogs](#) | [Training](#) | [Components](#)

### Technical Support

[cypress.com/support](http://cypress.com/support)

© Cypress Semiconductor Corporation, 2002-2016. This document is the property of Cypress Semiconductor Corporation and its subsidiaries, including Spansion LLC ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Cypress products are not designed, intended, or authorized for use as critical components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or system could cause personal injury, death, or property damage ("Unintended Uses"). A critical component is any component of a device or system whose failure to perform can be reasonably expected to cause the failure of the device or system, or to affect its safety or effectiveness. Cypress is not liable, in whole or in part, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from or related to all Unintended Uses of Cypress products. You shall indemnify and hold Cypress harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of Cypress products.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit [cypress.com](http://cypress.com). Other names and brands may be claimed as property of their respective owners.