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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

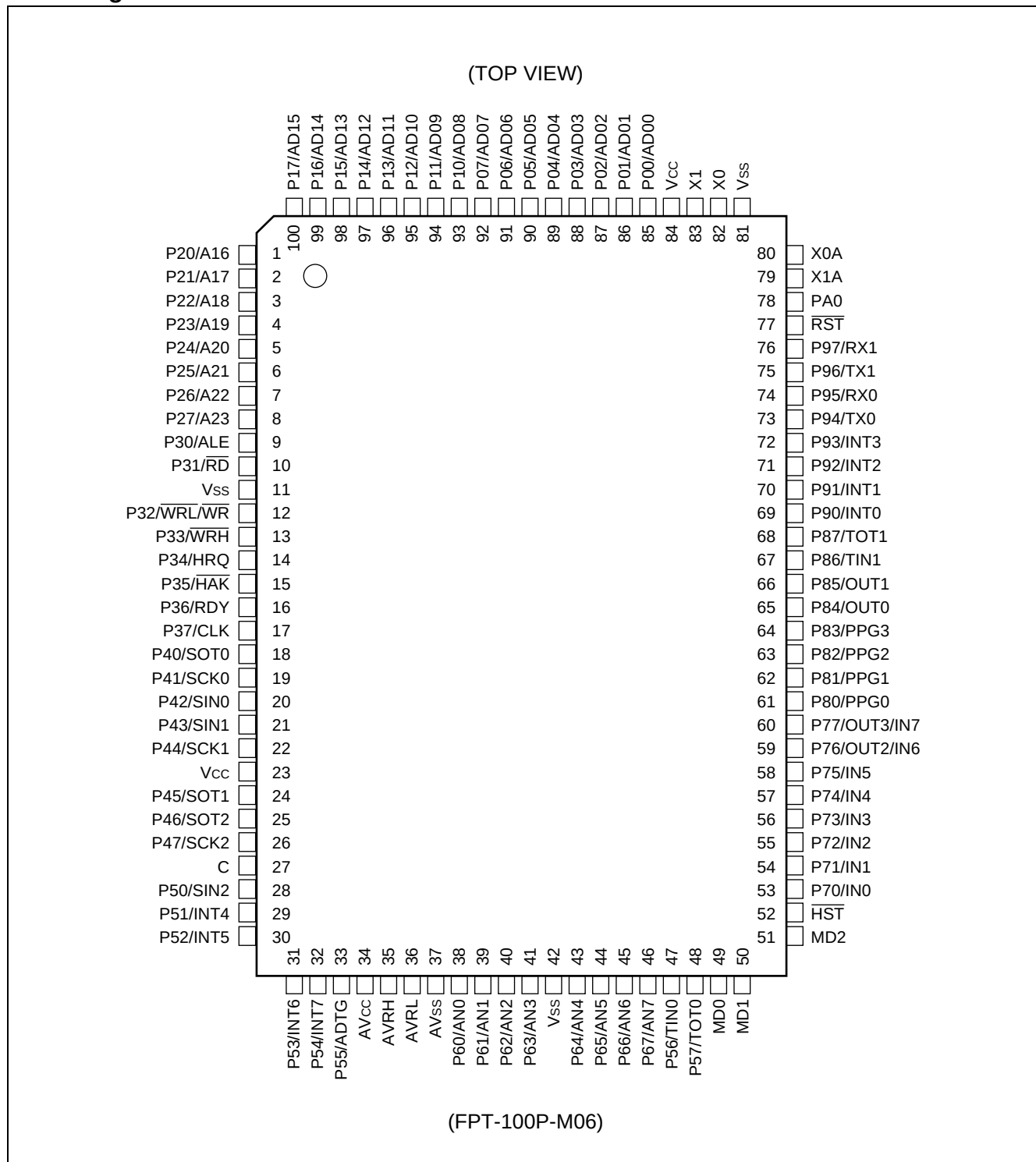
Product Status	Obsolete
Core Processor	F ² MC-16LX
Core Size	16-Bit
Speed	16MHz
Connectivity	CANbus, EBI/EMI, SCI, Serial I/O, UART/USART
Peripherals	POR, WDT
Number of I/O	81
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb90f549gspmc-ge1

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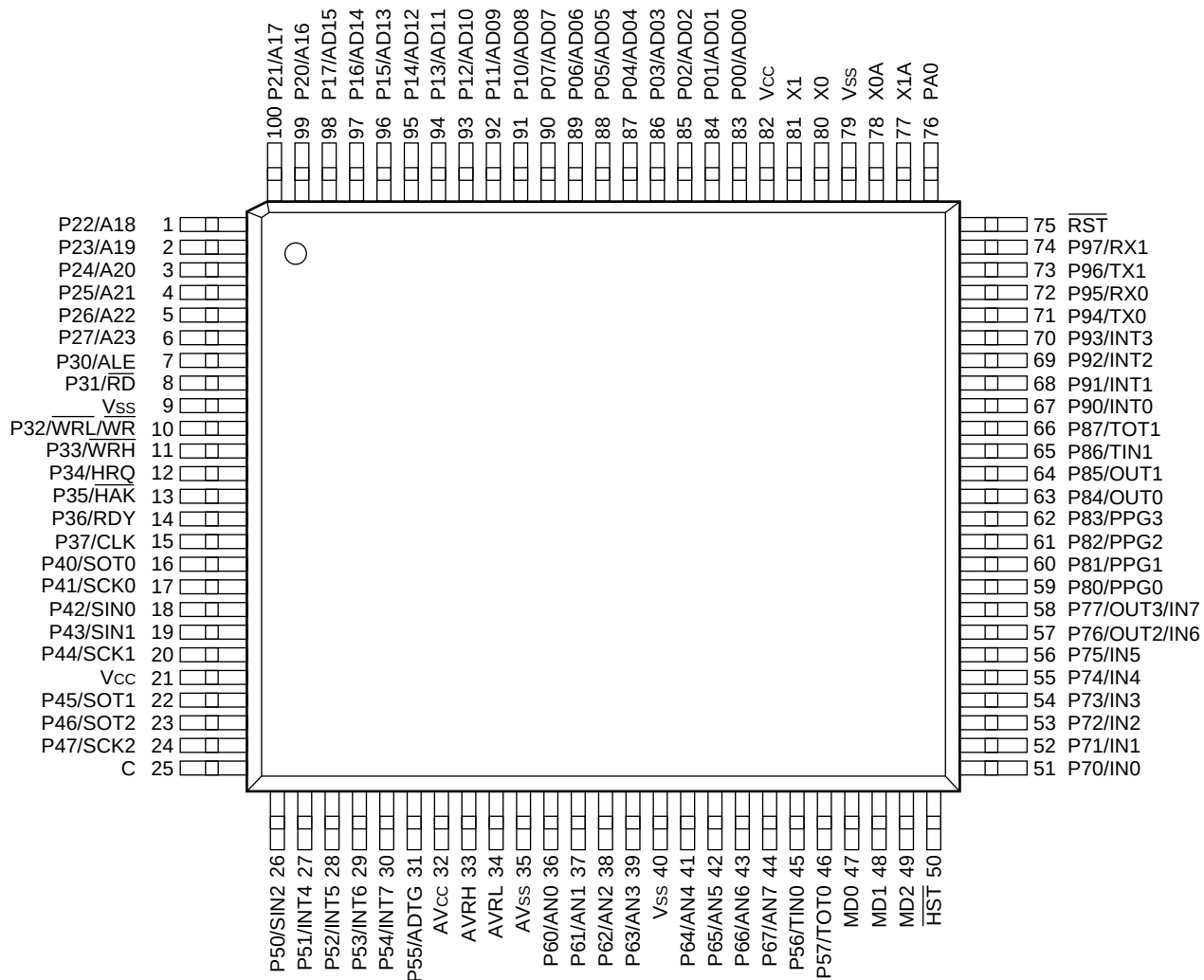
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2. Pin Assignment



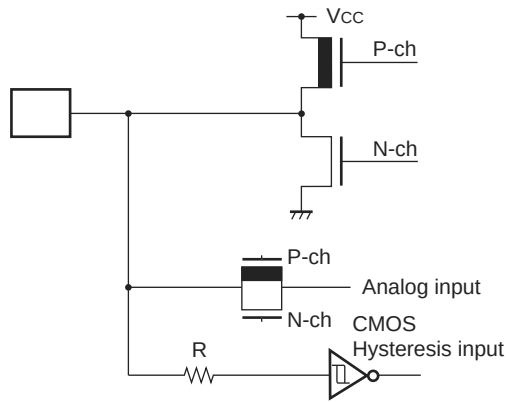
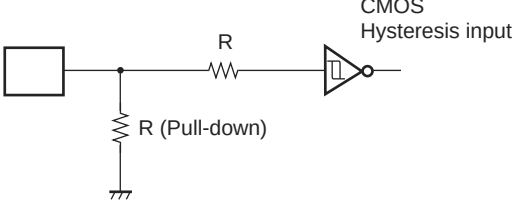
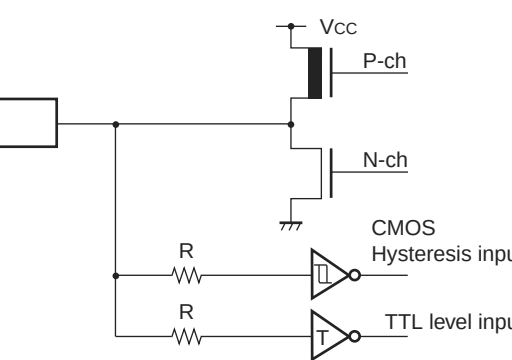
(TOP VIEW)



(FPT-100P-M20)

Pin No.		Pin name	Circuit type	Function
LQFP ²	QFP ¹			
11	13	P33	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode, external bus 8-bit mode or when WRH pin output is disabled.
		$\overline{\text{WRH}}$		Write strobe output pin for the 8 higher bits of the data bus. This function is enabled when the external bus is enabled, when the external bus 16-bit mode is selected, and when the WRH output pin is enabled.
12	14	P34	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the hold function is disabled.
		HRQ		Hold request input pin. This function is enabled when both the external bus and the hold functions are enabled.
13	15	P35	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the hold function is disabled.
		$\overline{\text{HAK}}$		Hold acknowledge output pin. This function is enabled when both the external bus and the hold functions are enabled.
14	16	P36	I	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the external ready function is disabled.
		RDY		Ready input pin. This function is enabled when both the external bus and the external ready functions are enabled.
15	17	P37	H	General I/O port with programmable pullup. This function is enabled in the single-chip mode or when the CLK output is disabled.
		CLK		CLK output pin. This function is enabled when both the external bus and CLK outputs are enabled.
16	18	P40	G	General I/O port. This function is enabled when UART0 disables the serial data output.
		SOT0		Serial data output pin for UART0. This function is enabled when UART0 enables the serial data output.
17	19	P41	G	General I/O port. This function is enabled when UART0 disables serial clock output.
		SCK0		Serial clock I/O pin for UART0. This function is enabled when UART0 enables the serial clock output.
18	20	P42	G	General I/O port. This function is always enabled.
		SIN0		Serial data input pin for UART0. Set the corresponding Port Direction Register to input if this function is used.
19	21	P43	G	General I/O port. This function is always enabled.
		SIN1		Serial data input pin for UART1. Set the corresponding Port Direction Register to input if this function is used.

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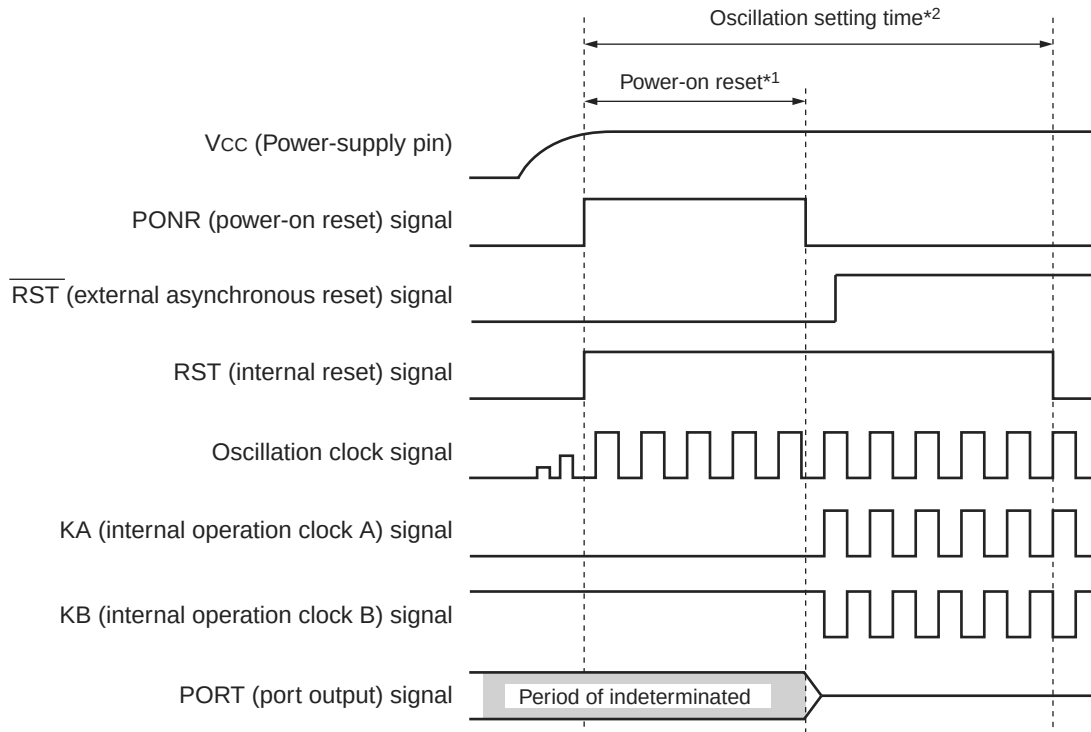
Circuit type	Diagram	Remarks
E		■ CMOS level output ■ CMOS Hysteresis input ■ Analog input
F		■ CMOS Hysteresis input ■ Pull-down Resistor : 50 kΩ approx. (except Flash devices)
G		■ CMOS level output ■ CMOS Hysteresis input ■ TTL level input (Flash devices in Flash writer mode only)

(Continued)

(12) Indeterminate outputs from ports 0 and 1 (MB90V540G only)

During oscillation setting time of step-down circuit (during a power-on reset) after the power is turned on, the outputs from ports 0 and 1 become following state.

- If $\overline{\text{RST}}$ pin is "H", the outputs become indeterminate.
 - If $\overline{\text{RST}}$ pin is "L", the outputs become high-impedance.
- Pay attention to the port output timing shown as follow.

■ $\overline{\text{RST}}$ pin is "H"


*1 : Power-on reset time : "Period of clock frequency" $\times 2^{17}$ (Clock frequency of 16 MHz : 8.19 ms)

*2 : Oscillation setting time : "Period of clock frequency" $\times 2^{18}$ (Clock frequency of 16 MHz : 16.38 ms)

Address	Register	Abbreviation	Access	Resource name	Initial value
24 _H	Serial mode register 1	SMR1	R/W	UART1	0 0 0 0 0 0 0 0 _B
25 _H	Serial control register 1	SCR1	R/W		0 0 0 0 0 1 0 0 _B
26 _H	Serial input data register 1/ Serial output data register 1	SIDR1/SODR1	R/W		XXXXXXXX _B
27 _H	Serial status register 1	SSR1	R/W		0 0 0 0 1 _ 0 0 _B
28 _H	UART1 prescaler control register	CDCR	R/W		0 _ _ 1 1 1 1 _B
29 _H	Serial Edge select register	SES1	R/W		_ _ _ _ _ 0 _B
2A _H	Prohibited				
2B _H	Serial I/O prescaler	SCDCR	R/W	Extended I/O Serial Interface	0 _ _ 1 1 1 1 _B
2C _H	Serial mode control register	SMCS	R/W		_ _ _ 0 0 0 0 _B
2D _H	Serial mode control register	SMCS	R/W		0 0 0 0 0 1 0 _B
2E _H	Serial data register	SDR	R/W		XXXXXXXX _B
2F _H	Serial Edge select register	SES2	R/W		_ _ _ _ _ 0 _B
30 _H	External interrupt enable register	ENIR	R/W	External Interrupt	0 0 0 0 0 0 0 0 _B
31 _H	External interrupt request register	EIRR	R/W		XXXXXXXX _B
32 _H	External interrupt level register	ELVR	R/W		0 0 0 0 0 0 0 0 _B
33 _H	External interrupt level register	ELVR	R/W		0 0 0 0 0 0 0 0 _B
34 _H	A/D control status register 0	ADCS0	R/W	A/D Converter	0 0 0 0 0 0 0 0 _B
35 _H	A/D control status register 1	ADCS1	R/W		0 0 0 0 0 0 0 0 _B
36 _H	A/D data register 0	ADCR0	R		XXXXXXXX _B
37 _H	A/D data register 1	ADCR1	R/W		0 0 0 0 1 _ XX _B
38 _H	PPG0 operation mode control register	PPGC0	R/W	16-bit Programmable Pulse Generator 0/1	0 _ 0 0 _ _ 1 _B
39 _H	PPG1 operation mode control register	PPGC1	R/W		0 _ 0 0 0 0 1 _B
3A _H	PPG0/1 clock selection register	PPG01	R/W		0 0 0 0 0 _ _ _B
3B _H	Prohibited				
3C _H	PPG2 operation mode control register	PPGC2	R/W	16-bit Programmable Pulse Generator 2/3	0 _ 0 0 _ _ 1 _B
3D _H	PPG3 operation mode control register	PPGC3	R/W		0 _ 0 0 0 0 1 _B
3E _H	PPG2/3 Clock Selection Register	PPG23	R/W		0 0 0 0 0 _ _ _B
3F _H	Prohibited				
40 _H	PPG4 operation mode control register	PPGC4	R/W	16-bit Programmable Pulse Generator 4/5	0 _ 0 0 _ _ 1 _B
41 _H	PPG5 operation mode control register	PPGC5	R/W		0 _ 0 0 0 0 1 _B
42 _H	PPG4/5 clock selection register	PPG45	R/W		0 0 0 0 0 _ _ _B
43 _H	Prohibited				
44 _H	PPG6 operation mode control register	PPGC6	R/W	16-bit Programmable Pulse Generator 6/7	0 _ 0 0 _ _ 1 _B
45 _H	PPG7 operation mode control register	PPGC7	R/W		0 _ 0 0 0 0 1 _B
46 _H	PPG6/7 clock selection register	PPG67	R/W		0 0 0 0 0 _ _ _B

(Continued)

Address	Register	Abbreviation	Access	Resource name	Initial value
3900 _H	Reload L	PRL0	R/W	16-bit Programmable Pulse Generator 0/1	XXXXXXXX _B
3901 _H	Reload H	PRLH0	R/W		XXXXXXXX _B
3902 _H	Reload L	PRL1	R/W		XXXXXXXX _B
3903 _H	Reload H	PRLH1	R/W		XXXXXXXX _B
3904 _H	Reload L	PRL2	R/W	16-bit Programmable Pulse Generator 2/3	XXXXXXXX _B
3905 _H	Reload H	PRLH2	R/W		XXXXXXXX _B
3906 _H	Reload L	PRL3	R/W		XXXXXXXX _B
3907 _H	Reload H	PRLH3	R/W		XXXXXXXX _B
3908 _H	Reload L	PRL4	R/W	16-bit Programmable Pulse Generator 4/5	XXXXXXXX _B
3909 _H	Reload H	PRLH4	R/W		XXXXXXXX _B
390A _H	Reload L	PRL5	R/W		XXXXXXXX _B
390B _H	Reload H	PRLH5	R/W		XXXXXXXX _B
390C _H	Reload L	PRL6	R/W	16-bit Programmable Pulse Generator 6/7	XXXXXXXX _B
390D _H	Reload H	PRLH6	R/W		XXXXXXXX _B
390E _H	Reload L	PRL7	R/W		XXXXXXXX _B
390F _H	Reload H	PRLH7	R/W		XXXXXXXX _B
3910 _H to 3917 _H	Reserved				
3918 _H	Input Capture Register 0	IPCP0	R	Input Capture 0/1	XXXXXXXX _B
3919 _H	Input Capture Register 0	IPCP0	R		XXXXXXXX _B
391A _H	Input Capture Register 1	IPCP1	R		XXXXXXXX _B
391B _H	Input Capture Register 1	IPCP1	R		XXXXXXXX _B
391C _H	Input Capture Register 2	IPCP2	R	Input Capture 2/3	XXXXXXXX _B
391D _H	Input Capture Register 2	IPCP2	R		XXXXXXXX _B
391E _H	Input Capture Register 3	IPCP3	R		XXXXXXXX _B
391F _H	Input Capture Register 3	IPCP3	R		XXXXXXXX _B
3920 _H	Input Capture Register 4	IPCP4	R	Input Capture 4/5	XXXXXXXX _B
3921 _H	Input Capture Register 4	IPCP4	R		XXXXXXXX _B
3922 _H	Input Capture Register 5	IPCP5	R		XXXXXXXX _B
3923 _H	Input Capture Register 5	IPCP5	R		XXXXXXXX _B
3924 _H	Input Capture Register 6	IPCP6	R	Input Capture 6/7	XXXXXXXX _B
3925 _H	Input Capture Register 6	IPCP6	R		XXXXXXXX _B
3926 _H	Input Capture Register 7	IPCP7	R		XXXXXXXX _B
3927 _H	Input Capture Register 7	IPCP7	R		XXXXXXXX _B

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Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003B00 _H	003D00 _H	Control status register	CSR	R/W, R	00---000 0---0-1 _B
003B01 _H	003D01 _H				
003B02 _H	003D02 _H	Last event indicator register	LEIR	R/W	----- 000-0000 _B
003B03 _H	003D03 _H				
003B04 _H	003D04 _H	Receive/transmit error counter register	RTEC	R	00000000 00000000 _B
003B05 _H	003D05 _H				
003B06 _H	003D06 _H	Bit timing register	BTR	R/W	-1111111 11111111 _B
003B07 _H	003D07 _H				
003B08 _H	003D08 _H	IDE register	IDER	R/W	XXXXXXXX XXXXXXXX _B
003B09 _H	003D09 _H				
003B0A _H	003D0A _H	Transmit RTR register	TRTRR	R/W	00000000 00000000 _B
003B0B _H	003D0B _H				
003B0C _H	003D0C _H	Remote frame receive waiting register	RFWTR	R/W	XXXXXXXX XXXXXXXX _B
003B0D _H	003D0D _H				
003B0E _H	003D0E _H	Transmit request enable register	TIER	R/W	00000000 00000000 _B
003B0F _H	003D0F _H				
003B10 _H	003D10 _H	Acceptance mask select register	AMSR	R/W	XXXXXXXX XXXXXXXX _B
003B11 _H	003D11 _H				XXXXXXXX XXXXXXXX _B
003B12 _H	003D12 _H				
003B13 _H	003D13 _H				
003B14 _H	003D14 _H	Acceptance mask register 0	AMR0	R/W	XXXXXXXX XXXXXXXX _B
003B15 _H	003D15 _H				XXXXXX--- XXXXXXXX _B
003B16 _H	003D16 _H				
003B17 _H	003D17 _H				
003B18 _H	003D18 _H	Acceptance mask register 1	AMR1	R/W	XXXXXXXX XXXXXXXX _B
003B19 _H	003D19 _H				XXXXXX--- XXXXXXXX _B
003B1A _H	003D1A _H				
003B1B _H	003D1B _H				

List of Message Buffers (ID Registers)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003A00 _H to 003A1F _H	003C00 _H to 003C1F _H	General-purpose RAM	—	R/W	XXXXXXXX _B to XXXXXXXX _B
003A20 _H	003C20 _H	ID register 0	IDR0	R/W	XXXXXXXX XXXXXXXX _B
003A21 _H	003C21 _H				XXXXXX--- XXXXXXXX _B
003A22 _H	003C22 _H				
003A23 _H	003C23 _H				

(Continued)

Address		Register	Abbreviation	Access	Initial Value
CAN0	CAN1				
003A3C _H	003C3C _H	ID register 7	IDR7	R/W	XXXXXXXX XXXXXXXX _B
003A3D _H	003C3D _H				
003A3E _H	003C3E _H				XXXXX--- XXXXXXXX _B
003A3F _H	003C3F _H				
003A40 _H	003C40 _H	ID register 8	IDR8	R/W	XXXXXXXX XXXXXXXX _B
003A41 _H	003C41 _H				
003A42 _H	003C42 _H				XXXXX--- XXXXXXXX _B
003A43 _H	003C43 _H				
003A44 _H	003C44 _H	ID register 9	IDR9	R/W	XXXXXXXX XXXXXXXX _B
003A45 _H	003C45 _H				
003A46 _H	003C46 _H				XXXXX--- XXXXXXXX _B
003A47 _H	003C47 _H				
003A48 _H	003C48 _H	ID register 10	IDR10	R/W	XXXXXXXX XXXXXXXX _B
003A49 _H	003C49 _H				
003A4A _H	003C4A _H				XXXXX--- XXXXXXXX _B
003A4B _H	003C4B _H				
003A4C _H	003C4C _H	ID register 11	IDR11	R/W	XXXXXXXX XXXXXXXX _B
003A4D _H	003C4D _H				
003A4E _H	003C4E _H				XXXXX--- XXXXXXXX _B
003A4F _H	003C4F _H				
003A50 _H	003C50 _H	ID register 12	IDR12	R/W	XXXXXXXX XXXXXXXX _B
003A51 _H	003C51 _H				
003A52 _H	003C52 _H				XXXXX--- XXXXXXXX _B
003A53 _H	003C53 _H				
003A54 _H	003C54 _H	ID register 13	IDR13	R/W	XXXXXXXX XXXXXXXX _B
003A55 _H	003C55 _H				
003A56 _H	003C56 _H				XXXXX--- XXXXXXXX _B
003A57 _H	003C57 _H				
003A58 _H	003C58 _H	ID register 14	IDR14	R/W	XXXXXXXX XXXXXXXX _B
003A59 _H	003C59 _H				
003A5A _H	003C5A _H				XXXXX--- XXXXXXXX _B
003A5B _H	003C5B _H				
003A5C _H	003C5C _H	ID register 15	IDR15	R/W	XXXXXXXX XXXXXXXX _B
003A5D _H	003C5D _H				
003A5E _H	003C5E _H				XXXXX--- XXXXXXXX _B
003A5F _H	003C5F _H				

10. Interrupt Map

Interrupt cause	EI ² OS clear	Interrupt vector		Interrupt control register	
		Number	Address	Number	Address
Reset	N/A	#08	FFFFDC _H	—	—
INT9 instruction	N/A	#09	FFFFD8 _H	—	—
Exception	N/A	#10	FFFFD4 _H	—	—
CAN 0 RX	N/A	#11	FFFFD0 _H	ICR00	0000B0 _H
CAN 0 TX/NS	N/A	#12	FFFFCC _H		
CAN 1 RX	N/A	#13	FFFFC8 _H	ICR01	0000B1 _H
CAN 1 TX/NS	N/A	#14	FFFFC4 _H		
External Interrupt INT0/INT1	*1	#15	FFFFC0 _H	ICR02	0000B2 _H
Time Base Timer	N/A	#16	FFFFBC _H		
16-bit Reload Timer 0	*1	#17	FFFFB8 _H	ICR03	0000B3 _H
8/10-bit A/D Converter	*1	#18	FFFFB4 _H		
16-bit Free-run Timer	N/A	#19	FFFFB0 _H	ICR04	0000B4 _H
External Interrupt INT2/INT3	*1	#20	FFFFAC _H		
Serial I/O	*1	#21	FFFFA8 _H	ICR05	0000B5 _H
8/16-bit PPG 0/1	N/A	#22	FFFFA4 _H		
Input Capture 0	*1	#23	FFFFA0 _H	ICR06	0000B6 _H
External Interrupt INT4/INT5	*1	#24	FFFF9C _H		
Input Capture 1	*1	#25	FFFF98 _H	ICR07	0000B7 _H
8/16-bit PPG 2/3	N/A	#26	FFFF94 _H		
External Interrupt INT6/INT7	*1	#27	FFFF90 _H	ICR08	0000B8 _H
Watch Timer	N/A	#28	FFFF8C _H		
8/16-bit PPG 4/5	N/A	#29	FFFF88 _H	ICR09	0000B9 _H
Input Capture 2/3	*1	#30	FFFF84 _H		
8/16-bit PPG 6/7	N/A	#31	FFFF80 _H	ICR10	0000BA _H
Output Compare 0	*1	#32	FFFF7C _H		
Output Compare 1	*1	#33	FFFF78 _H	ICR11	0000BB _H
Input Capture 4/5	*1	#34	FFFF74 _H		
Output Compare 2/3 - Input Capture 6/7	*1	#35	FFFF70 _H	ICR12	0000BC _H
16-bit Reload Timer 1	*1	#36	FFFF6C _H		
UART 0 RX	*2	#37	FFFF68 _H	ICR13	0000BD _H
UART 0 TX	*1	#38	FFFF64 _H		
UART 1 RX	*2	#39	FFFF60 _H	ICR14	0000BE _H
UART 1 TX	*1	#40	FFFF5C _H		
Flash Memory	N/A	#41	FFFF58 _H	ICR15	0000BF _H
Delayed interrupt	N/A	#42	FFFF54 _H		

(Continued)

(Continued)

*1 : The interrupt request flag is cleared by the EI²OS interrupt clear signal.

*2 : The interrupt request flag is cleared by the EI²OS interrupt clear signal. A stop request is available.

Notes :

- N/A : The interrupt request flag is not cleared by the EI²OS interrupt clear signal.
- For a peripheral module with two interrupt causes for a single interrupt number, both interrupt request flags are cleared by the EI²OS interrupt clear signal.
- At the end of EI²OS, the EI²OS clear signal will be asserted for all the interrupt flags assigned to the same interrupt number. If one interrupt flag starts the EI²OS and in the meantime another interrupt flag is set by a hardware event, the later event is lost because the flag is cleared by the EI²OS clear signal caused by the first event. So it is recommended not to use the EI²OS for this interrupt number.
- If EI²OS is enabled, EI²OS is initiated when one of the two interrupt signals in the same interrupt control register (ICR) is asserted. This means that different interrupt sources share the same EI²OS Descriptor which should be unique for each interrupt source. For this reason, when one interrupt source uses the EI²OS, the other interrupt should be disabled.

11. Electrical Characteristics

11.1 Absolute Maximum Ratings

($V_{SS} = AV_{SS} = 0.0\text{ V}$)

Parameter	Symbol	Value		Units	Remarks
		Min	Max		
Power supply voltage	V_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	
	AV_{CC}	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$V_{CC} = AV_{CC}$ *1
	$AVRH, AVRL$	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	$AV_{CC} \geq AVRH/AVRL, AVRH \geq AVRL$ *1
Input voltage	V_I	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*2
Output voltage	V_O	$V_{SS} - 0.3$	$V_{SS} + 6.0$	V	*2
Maximum clamp current	I_{CLAMP}	- 2.0	+ 2.0	mA	*6
Total maximum clamp current	$\Sigma I_{CLAMP} $	—	20	mA	*6
"L" level max output current	I_{OL}	—	15	mA	*3
"L" level avg. output current	I_{OLAV}	—	4	mA	*4
"L" level max overall output current	ΣI_{OL}	—	100	mA	
"L" level avg. overall output current	ΣI_{OLAV}	—	50	mA	*5
"H" level max output current	I_{OH}	—	-15	mA	*3
"H" level avg. output current	I_{OHAV}	—	-4	mA	*4
"H" level max overall output current	ΣI_{OH}	—	-100	mA	
"H" level avg. overall output current	ΣI_{OHAV}	—	-50	mA	*5
Power consumption	P_D	—	500	mW	Flash device
		—	400	mW	MASK ROM
Operating temperature	T_A	-40	+105	°C	
Storage temperature	T_{STG}	-55	+150	°C	

*1 : AV_{CC} , $AVRH$, $AVRL$ should not exceed V_{CC} . Also, $AVRH$, $AVRL$ should not exceed AV_{CC} , and $AVRL$ does not exceed $AVRH$.

*2 : V_I and V_O should not exceed $V_{CC} + 0.3\text{ V}$. However if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supercedes the V_I rating.

*3 : The maximum output current is a peak value for a corresponding pin.

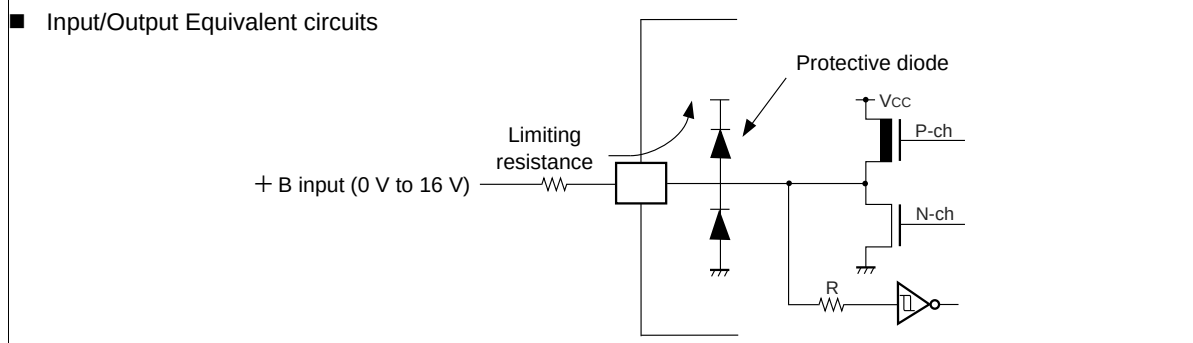
*4 : Average output current is an average current value observed for a 100 ms period for a corresponding pin.

*5 : Total average current is an average current value observed for a 100 ms period for all corresponding pins.

*6 :

- Applicable to pins : P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, PA0
- Use within recommended operating conditions.
- Use at DC voltage (current) .
- The + B signal should always be applied with a limiting resistance placed between the + B signal and the microcontroller.
- The value of the limiting resistance should be set so that when the + B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
- Note that when the microcontroller drive current is low, such as in the power saving modes, the + B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.
- Note that if a + B signal is input when the microcontroller current is off (not fixed at 0 V) , the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the + B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the power-on result.
- Care must be taken not to leave the + B input pin open.

- Note that analog system input/output pins other than the A/D input pins (LCD drive pins, comparator input pins, etc.) cannot accept + B signal input.
- Sample recommended circuits :



WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

11.3 DC Characteristics

(MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 3.5 \text{ V to } 5.5 \text{ V}$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Condition	Value			Units	Remarks
				Min	Typ	Max		
Input H voltage	V_{IHS}	CMOS hysteresis input pin	—	$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	
	V_{IH}	TTL input pin	—	2.0	—	—	V	
	V_{IHM}	MD input pin	—	$V_{CC} - 0.3$	—	$V_{CC} + 0.3$	V	
Input L voltage	V_{ILS}	CMOS hysteresis input pin	—	$V_{CC} - 0.3$	—	$0.2 V_{CC}$	V	
	V_{IL}	TTL input pin	—	—	—	0.8	V	
	V_{ILM}	MD input pin	—	$V_{SS} - 0.3$	—	$V_{SS} + 0.3$	V	
Output H voltage	V_{OH}	All output pins	$V_{CC} = 4.5 \text{ V}$, $I_{OH} = -4.0 \text{ mA}$	$V_{CC} - 0.5$	—	—	V	
Output L voltage	V_{OL}	All output pins	$V_{CC} = 4.5 \text{ V}$, $I_{OL} = 4.0 \text{ mA}$	—	—	0.4	V	
Input leak current	I_{IL}	—	$V_{CC} = 5.5 \text{ V}$, $V_{SS} < V_I < V_{CC}$	—5	—	5	μA	
Pull-up resistance	R_{UP}	P00 to P07, P10 to P17, P20 to P27, P30 to P37, RST	—	25	50	100	$\text{k}\Omega$	
Pull-down resistance	R_{DOWN}	MD2	—	25	50	100	$\text{k}\Omega$	Except Flash devices

(Continued)

11.4.4 Power On Reset

(MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 3.5 \text{ V to } 5.5 \text{ V}$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$)

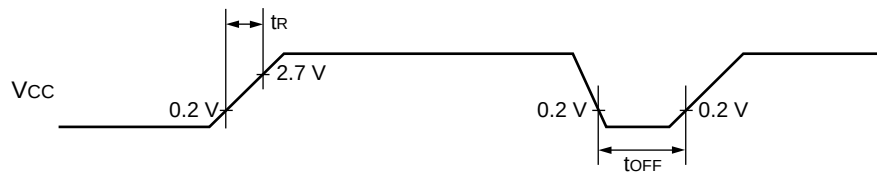
(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0 \text{ V}$, $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
Power on rise time	t_R	V_{CC}	—	0.05	30	ms	*
Power off time	t_{OFF}	V_{CC}	—	50	—	ms	Waiting time until power-on

* : V_{CC} must be kept lower than 0.2 V before power-on.

Notes : ■ The above values are used for creating a power-on reset.

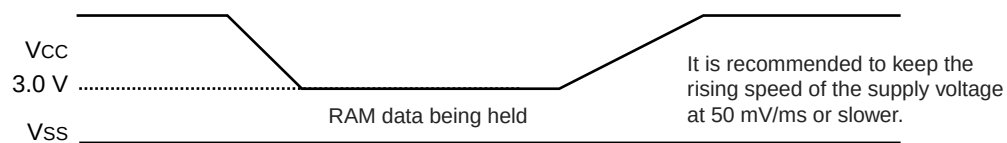
■ Some registers in the device are initialized only upon a power-on reset. To initialize these register, turn on the power supply using the above values.



Sudden changes in the power supply voltage may cause a power-on reset.

To change the power supply voltage while the device is in operation, it is recommended to raise the voltage smoothly to suppress fluctuations as shown below.

In this case, change the supply voltage with the PLL clock not used. If the voltage drop is 1 V or fewer per second, however, you can use the PLL clock.



11.4.8 Hold Timing

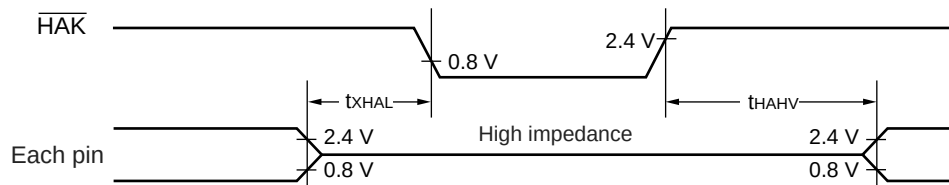
(MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 3.5\text{ V to }5.5\text{ V}$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
Pin floating $\rightarrow \overline{\text{HAK}}\downarrow$ time	t_{XHAL}	$\overline{\text{HAK}}$	—	30	t_{CP}	ns	
$\overline{\text{HAK}}\uparrow$ time $\rightarrow$ Pin valid time	t_{HAHV}	$\overline{\text{HAK}}$	—	t_{CP}	$2 t_{CP}$	ns	

Note : There is more than 1 cycle from the time HRQ is read to the time the $\overline{\text{HAK}}$ is changed.

■ Hold Timing



11.4.9 UART0/1, Serial I/O Timing

(MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 3.5\text{ V to }5.5\text{ V}$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

(Other than MB90543G(S)/547G(S)/548G(S)/F548GL(S): $V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0.0\text{ V}$, $T_A = -40\text{ }^{\circ}\text{C to }+105\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Condition	Value		Units	Remarks
				Min	Max		
Serial clock cycle time	t_{SCYC}	SCK0 to SCK2	Internal clock operation output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$8 t_{CP}$	—	ns	
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOV}	SCK0 to SCK2, SOT0 to SOT2		— 80	80	ns	
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{VSH}	SCK0 to SCK2, SIN0 to SIN2		100	—	ns	
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIX}	SCK0 to SCK2, SIN0 to SIN2		60	—	ns	
Serial clock "H" pulse width	t_{SHSL}	SCK0 to SCK2	External clock operation output pins are $C_L = 80\text{ pF} + 1\text{ TTL}$.	$4 t_{CP}$	—	ns	
Serial clock "L" pulse width	t_{SLSH}	SCK0 to SCK2		$4 t_{CP}$	—	ns	
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOV}	SCK0 to SCK2, SOT0 to SOT2		—	150	ns	
Valid SIN $\rightarrow$ SCK $\uparrow$	t_{VSH}	SCK0 to SCK2, SIN0 to SIN2		60	—	ns	
SCK $\uparrow \rightarrow$ Valid SIN hold time	t_{SHIX}	SCK0 to SCK2, SIN0 to SIN2		60	—	ns	

Notes :

- AC characteristic in CLK synchronized mode.
- C_L is load capacity value of pins when testing.
- For t_{CP} (Machine clock cycle time) , refer to “ (1) Clock Timing”.

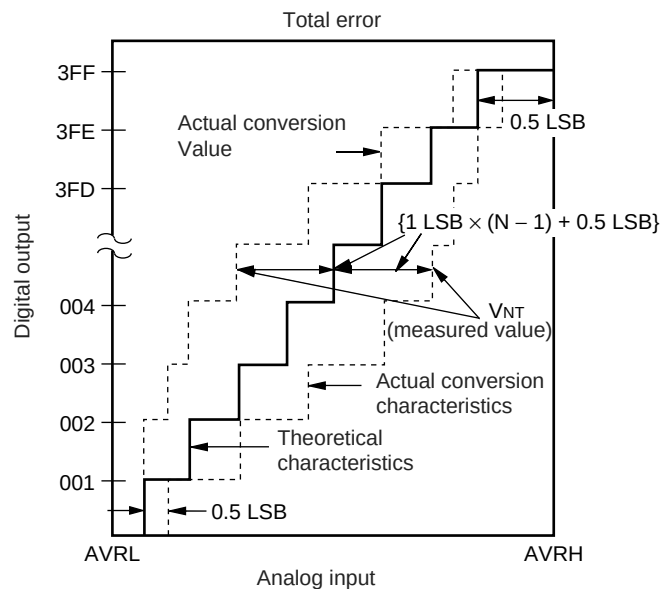
11.5.2 A/D Converter Glossary

Resolution : Analog changes that are identifiable with the A/D converter

Linearity error : The deviation of the straight line connecting the zero transition point ("00 0000 0000" ↔ "00 0000 0001") with the full-scale transition point ("11 1111 1110" ↔ "11 1111 1111") from actual conversion characteristics

Differential linearity error : The deviation of input voltage needed to change the output code by 1 LSB from the theoretical value

Total error : The total error is defined as a difference between the actual value and the theoretical value, which includes zero-transition error/full-scale transition error and linearity error.



$$1 \text{ LSB} = (\text{Theoretical value}) \frac{\text{AVRH} - \text{AVRL}}{1024} [\text{V}]$$

$$V_{OT} (\text{Theoretical value}) = \text{AVRL} + 0.5 \text{ LSB} [\text{V}]$$

$$V_{FST} (\text{Theoretical value}) = \text{AVRH} - 1.5 \text{ LSB} [\text{V}]$$

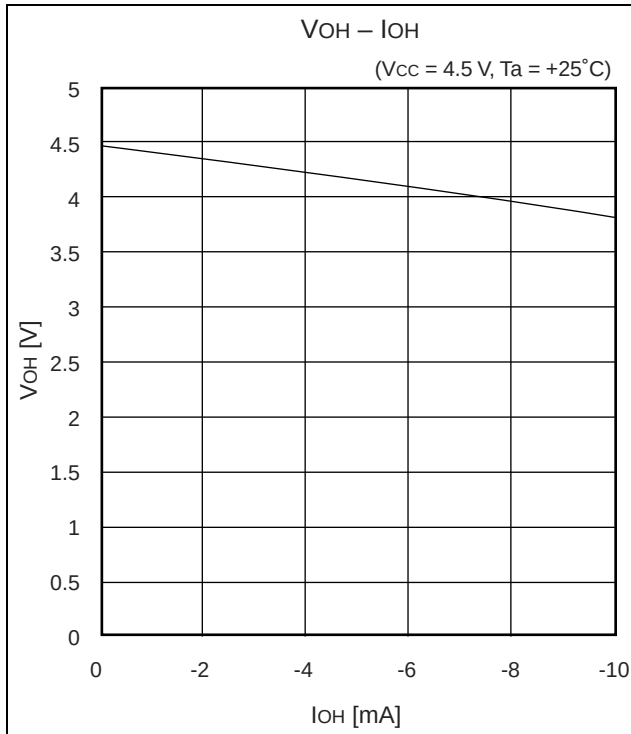
$$\text{Total error for digital output } N = \frac{V_{NT} - \{1 \text{ LSB} \times (N - 1) + 0.5 \text{ LSB}\}}{1 \text{ LSB}} [\text{LSB}]$$

V_{NT} : Voltage at a transition of digital output from $(N - 1)$ to N

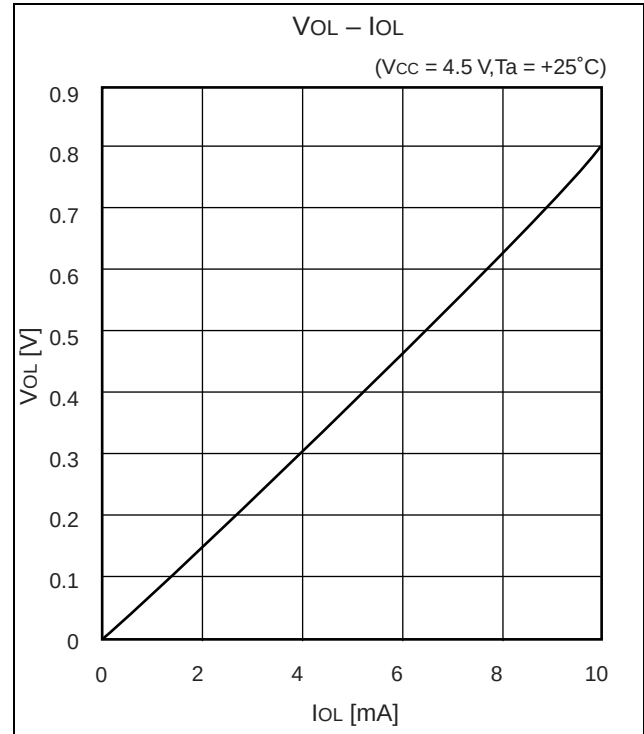
(Continued)

12. Example Characteristics

■ “H” level output voltage



■ “L” level output voltage



■ “H” level input voltage/ “L” level input voltage
(Hysteresis input)

