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#### What is "[Embedded - Microcontrollers](#)"?

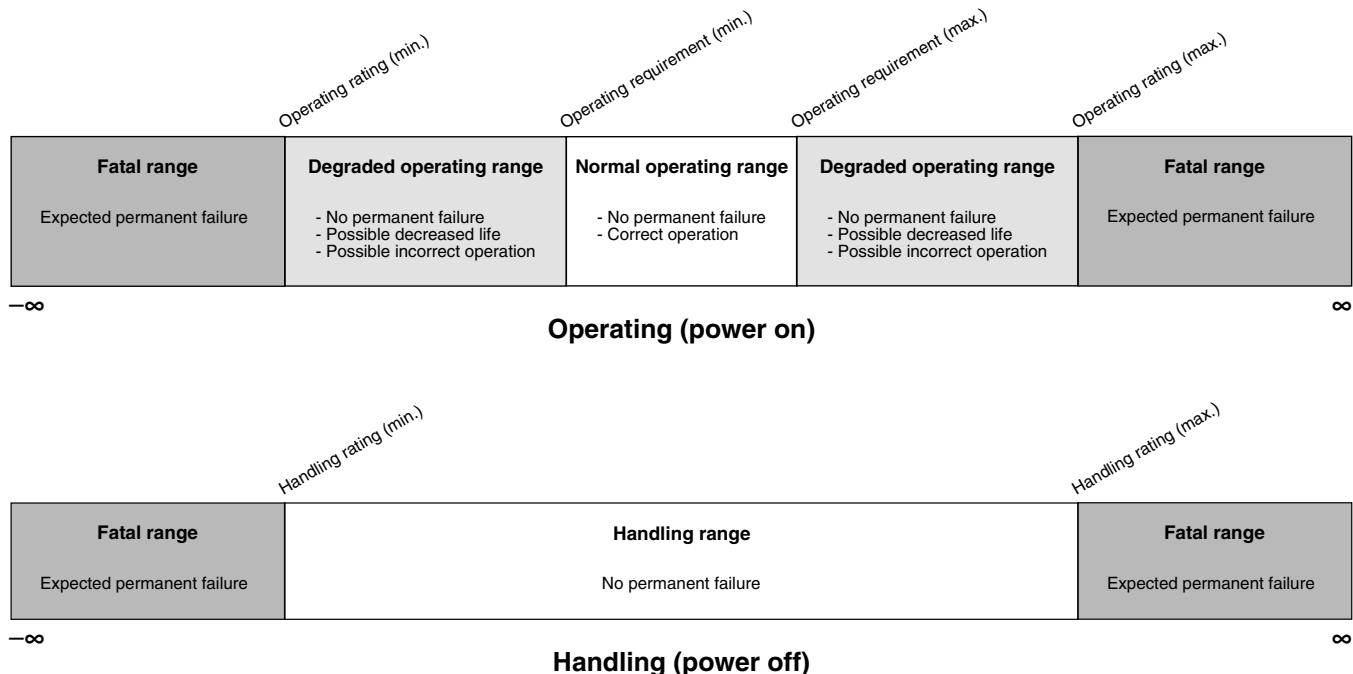
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Not For New Designs
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	100MHz
Connectivity	CANbus, EBI/EMI, I²C, IrDA, SD, SPI, UART/USART
Peripherals	DMA, I²S, LVD, POR, PWM, WDT
Number of I/O	104
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 46x16b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LQFP
Supplier Device Package	144-LQFP (20x20)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/mk10dx256zvlq10r">https://www.e-xfl.com/product-detail/nxp-semiconductors/mk10dx256zvlq10r</a>

## 3.6 Relationship between ratings and operating requirements



## 3.7 Guidelines for ratings and operating requirements

Follow these guidelines for ratings and operating requirements:

- Never exceed any of the chip's ratings.
- During normal operation, don't exceed any of the chip's operating requirements.
- If you must exceed an operating requirement at times other than during normal operation (for example, during power sequencing), limit the duration as much as possible.

## 3.8 Definition: Typical value

A *typical value* is a specified value for a technical characteristic that:

- Lies within the range of values specified by the operating behavior
- Given the typical manufacturing process, is representative of that characteristic during operation when you meet the typical-value conditions or other specified conditions

Typical values are provided as design guidelines and are neither tested nor guaranteed.

**Table 6. Power consumption operating behaviors (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I <sub>DD_VLPR</sub>	Very-low-power run mode current at 3.0 V — all peripheral clocks enabled	—	N/A	—	mA	7
I <sub>DD_VLPW</sub>	Very-low-power wait mode current at 3.0 V — all peripheral clocks disabled	—	N/A	—	mA	8
I <sub>DD_STOP</sub>	Stop mode current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 105°C	— — —	0.59 2.26 5.94	1.4 7.9 19.2	mA	
I <sub>DD_VLPS</sub>	Very-low-power stop mode current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 105°C	— — —	93 520 1350	435 2000 4000	μA	
I <sub>DD_LLS</sub>	Low leakage stop mode current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 105°C	— — —	4.8 28 126	20 68 270	μA	9
I <sub>DD_VLLS3</sub>	Very low-leakage stop mode 3 current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 105°C	— — —	3.1 17 82	8.9 35 148	μA	9
I <sub>DD_VLLS2</sub>	Very low-leakage stop mode 2 current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 105°C	— — —	2.2 7.1 41	5.4 12.5 125	μA	
I <sub>DD_VLLS1</sub>	Very low-leakage stop mode 1 current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 105°C	— — —	2.1 6.2 30	7.6 13.5 46	μA	
I <sub>DD_VBAT</sub>	Average current with RTC and 32kHz disabled at 3.0 V • @ -40 to 25°C • @ 70°C • @ 105°C	— — —	0.33 0.60 1.97	0.39 0.78 2.9	μA	

Table continues on the next page...

2.  $V_{DD} = 3.3$  V,  $T_A = 25$  °C,  $f_{OSC} = 12$  MHz (crystal),  $f_{SYS} = 96$  MHz,  $f_{BUS} = 48$  MHz
3. Specified according to Annex D of IEC Standard 61967-2, *Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*

## 5.2.7 Designing with radiated emissions in mind

To find application notes that provide guidance on designing your system to minimize interference from radiated emissions:

1. Go to [www.freescale.com](http://www.freescale.com).
2. Perform a keyword search for “EMC design.”

## 5.2.8 Capacitance attributes

**Table 8. Capacitance attributes**

Symbol	Description	Min.	Max.	Unit
$C_{IN\_A}$	Input capacitance: analog pins	—	7	pF
$C_{IN\_D}$	Input capacitance: digital pins	—	7	pF

## 5.3 Switching specifications

### 5.3.1 Device clock specifications

**Table 9. Device clock specifications**

Symbol	Description	Min.	Max.	Unit	Notes
Normal run mode					
$f_{SYS}$	System and core clock	—	100	MHz	
$f_{BUS}$	Bus clock	—	50	MHz	
$FB\_CLK$	FlexBus clock	—	50	MHz	
$f_{FLASH}$	Flash clock	—	25	MHz	
$f_{LPTMR}$	LPTMR clock	—	25	MHz	

### 5.3.2 General switching specifications

These general purpose specifications apply to all signals configured for GPIO, UART, CAN, CMT, and I<sup>2</sup>C signals.

**Table 10. General switching specifications**

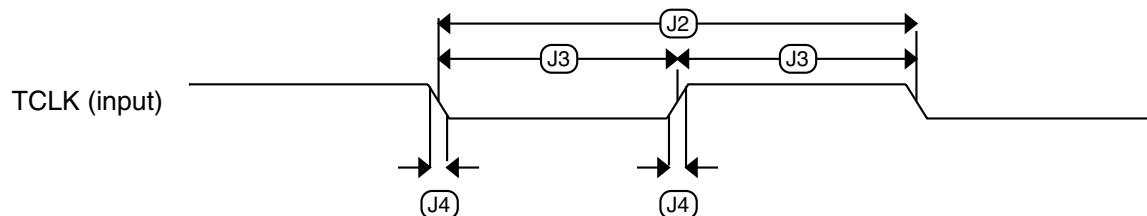
Symbol	Description	Min.	Max.	Unit	Notes
	GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path	1.5	—	Bus clock cycles	<a href="#">1, 2</a>
	GPIO pin interrupt pulse width (digital glitch filter disabled, analog filter enabled) — Asynchronous path	100	—	ns	<a href="#">3</a>
	GPIO pin interrupt pulse width (digital glitch filter disabled, analog filter disabled) — Asynchronous path	16	—	ns	<a href="#">3</a>
	External reset pulse width (digital glitch filter disabled)	100	—	ns	<a href="#">3</a>
	Mode select (EZP_CS) hold time after reset deassertion	2	—	Bus clock cycles	
	Port rise and fall time (high drive strength) <ul style="list-style-type: none"> <li>• Slew disabled               <ul style="list-style-type: none"> <li>• <math>1.71 \leq V_{DD} \leq 2.7V</math></li> <li>• <math>2.7 \leq V_{DD} \leq 3.6V</math></li> </ul> </li> <li>• Slew enabled               <ul style="list-style-type: none"> <li>• <math>1.71 \leq V_{DD} \leq 2.7V</math></li> <li>• <math>2.7 \leq V_{DD} \leq 3.6V</math></li> </ul> </li> </ul>	—	12	ns	<a href="#">4</a>
	Port rise and fall time (high drive strength) <ul style="list-style-type: none"> <li>• Slew disabled               <ul style="list-style-type: none"> <li>• <math>1.71 \leq V_{DD} \leq 2.7V</math></li> <li>• <math>2.7 \leq V_{DD} \leq 3.6V</math></li> </ul> </li> <li>• Slew enabled               <ul style="list-style-type: none"> <li>• <math>1.71 \leq V_{DD} \leq 2.7V</math></li> <li>• <math>2.7 \leq V_{DD} \leq 3.6V</math></li> </ul> </li> </ul>	—	6	ns	
	Port rise and fall time (low drive strength) <ul style="list-style-type: none"> <li>• Slew disabled               <ul style="list-style-type: none"> <li>• <math>1.71 \leq V_{DD} \leq 2.7V</math></li> <li>• <math>2.7 \leq V_{DD} \leq 3.6V</math></li> </ul> </li> <li>• Slew enabled               <ul style="list-style-type: none"> <li>• <math>1.71 \leq V_{DD} \leq 2.7V</math></li> <li>• <math>2.7 \leq V_{DD} \leq 3.6V</math></li> </ul> </li> </ul>	—	36	ns	
	Port rise and fall time (low drive strength) <ul style="list-style-type: none"> <li>• Slew disabled               <ul style="list-style-type: none"> <li>• <math>1.71 \leq V_{DD} \leq 2.7V</math></li> <li>• <math>2.7 \leq V_{DD} \leq 3.6V</math></li> </ul> </li> <li>• Slew enabled               <ul style="list-style-type: none"> <li>• <math>1.71 \leq V_{DD} \leq 2.7V</math></li> <li>• <math>2.7 \leq V_{DD} \leq 3.6V</math></li> </ul> </li> </ul>	—	24	ns	

1. This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In Stop, VLPS, LLS, and VLLSx modes, the synchronizer is bypassed so shorter pulses can be recognized in that case.
2. The greater synchronous and asynchronous timing must be met.
3. This is the minimum pulse width that is guaranteed to be recognized as a pin interrupt request in Stop, VLPS, LLS, and VLLSx modes.
4. 75 pF load
5. 15 pF load

## 5.4 Thermal specifications

**Table 14. JTAG full voltage range electricals (continued)**

Symbol	Description	Min.	Max.	Unit
J3	TCLK clock pulse width			
	• Boundary Scan	50	—	ns
	• JTAG and CJTAG	25	—	ns
	• Serial Wire Debug	12.5	—	ns
J4	TCLK rise and fall times	—	3	ns
J5	Boundary scan input data setup time to TCLK rise	20	—	ns
J6	Boundary scan input data hold time after TCLK rise	0	—	ns
J7	TCLK low to boundary scan output data valid	—	25	ns
J8	TCLK low to boundary scan output high-Z	—	25	ns
J9	TMS, TDI input data setup time to TCLK rise	8	—	ns
J10	TMS, TDI input data hold time after TCLK rise	1.4	—	ns
J11	TCLK low to TDO data valid	—	22.1	ns
J12	TCLK low to TDO high-Z	—	22.1	ns
J13	TRST assert time	100	—	ns
J14	TRST setup time (negation) to TCLK high	8	—	ns

**Figure 5. Test clock input timing**

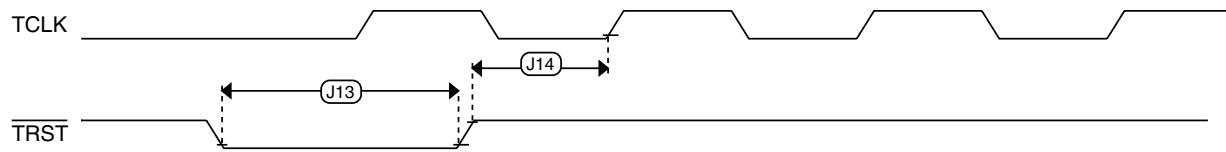


Figure 8. TRST timing

## 6.2 System modules

There are no specifications necessary for the device's system modules.

## 6.3 Clock modules

### 6.3.1 MCG specifications

Table 15. MCG specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$f_{ints\_ft}$	Internal reference frequency (slow clock) — factory trimmed at nominal VDD and 25 °C	—	32.768	—	kHz	
$f_{ints\_t}$	Internal reference frequency (slow clock) — user trimmed — over fixed voltage and temperature range of 0–70°C	31.25	—	38.2	kHz	
$\Delta f_{dco\_res\_t}$	Resolution of trimmed average DCO output frequency at fixed voltage and temperature — using SCTRIM and SCFTRIM	—	± 0.3	± 0.6	% $f_{dco}$	1
$\Delta f_{dco\_t}$	Total deviation of trimmed average DCO output frequency over fixed voltage and temperature range of 0–70°C	—	± 1.5	± 4.5	% $f_{dco}$	1
$f_{intf\_ft}$	Internal reference frequency (fast clock) — factory trimmed at nominal VDD and 25°C	—	4	—	MHz	
$f_{intf\_t}$	Internal reference frequency (fast clock) — user trimmed at nominal VDD and 25 °C	3	—	5	MHz	
$f_{loc\_low}$	Loss of external clock minimum frequency — RANGE = 00	(3/5) x $f_{ints\_t}$	—	—	kHz	
$f_{loc\_high}$	Loss of external clock minimum frequency — RANGE = 01, 10, or 11	(16/5) x $f_{ints\_t}$	—	—	kHz	
FLL						
$f_{fll\_ref}$	FLL reference frequency range	31.25	—	39.0625	kHz	

Table continues on the next page...

### 6.3.3.2 32 kHz oscillator frequency specifications

Table 19. 32 kHz oscillator frequency specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$f_{osc\_lo}$	Oscillator crystal	—	32.768	—	kHz	
$t_{start}$	Crystal start-up time	—	1000	—	ms	1
$f_{ec\_extal32}$	Externally provided input clock frequency	—	32.768	—	kHz	2
$V_{ec\_extal32}$	Externally provided input clock amplitude	700	—	$V_{BAT}$	mV	2, 3

- Proper PC board layout procedures must be followed to achieve specifications.
- This specification is for an externally supplied clock driven to EXTAL32 and does not apply to any other clock input. The oscillator remains enabled and XTAL32 must be left unconnected.
- The parameter specified is a peak-to-peak value and  $V_{IH}$  and  $V_{IL}$  specifications do not apply. The voltage of the applied clock must be within the range of  $V_{SS}$  to  $V_{BAT}$ .

## 6.4 Memories and memory interfaces

### 6.4.1 Flash electrical specifications

This section describes the electrical characteristics of the flash memory module.

#### 6.4.1.1 Flash timing specifications — program and erase

The following specifications represent the amount of time the internal charge pumps are active and do not include command overhead.

Table 20. NVM program/erase timing specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{hvpgm4}$	Longword Program high-voltage time	—	7.5	18	μs	
$t_{hversscr}$	Sector Erase high-voltage time	—	13	113	ms	1
$t_{hversblk256k}$	Erase Block high-voltage time for 256 KB	—	416	3616	ms	1

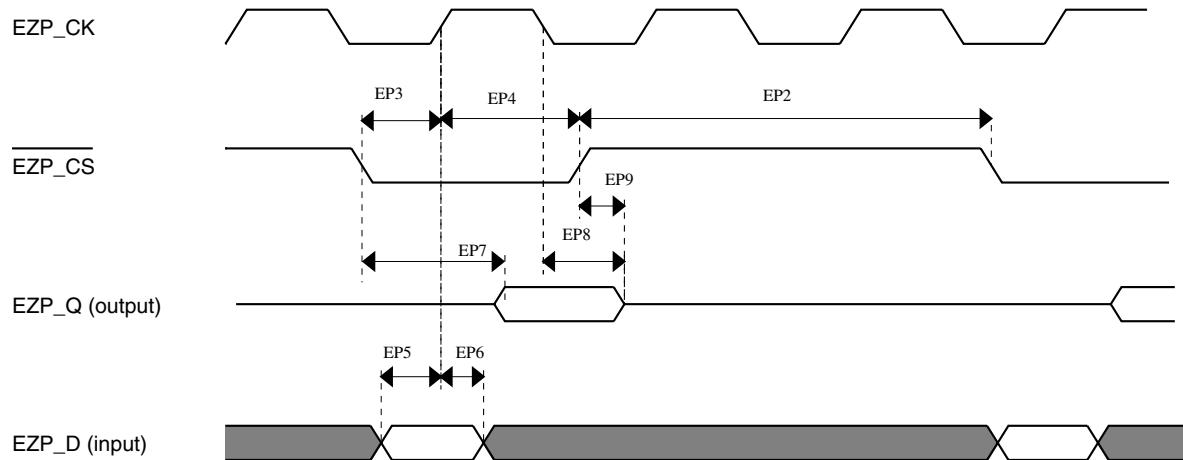
- Maximum time based on expectations at cycling end-of-life.

#### 6.4.1.2 Flash timing specifications — commands

Table 21. Flash command timing specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{rd1blk256k}$	Read 1s Block execution time • 256 KB program/data flash	—	—	1.7	ms	
$t_{rd1sec2k}$	Read 1s Section execution time (flash sector)	—	—	60	μs	1

Table continues on the next page...

**Figure 9. EzPort Timing Diagram**

### 6.4.3 Flexbus Switching Specifications

All processor bus timings are synchronous; input setup/hold and output delay are given in respect to the rising edge of a reference clock, FB\_CLK. The FB\_CLK frequency may be the same as the internal system bus frequency or an integer divider of that frequency.

The following timing numbers indicate when data is latched or driven onto the external bus, relative to the Flexbus output clock (FB\_CLK). All other timing relationships can be derived from these values.

**Table 25. Flexbus limited voltage range switching specifications**

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	2.7	3.6	V	
	Frequency of operation	—	FB_CLK	MHz	
FB1	Clock period	20	—	ns	
FB2	Address, data, and control output valid	—	11.5	ns	<a href="#">1</a>
FB3	Address, data, and control output hold	0.5	—	ns	<a href="#">1</a>
FB4	Data and FB_TA input setup	8.5	—	ns	<a href="#">2</a>
FB5	Data and FB_TA input hold	0.5	—	ns	<a href="#">2</a>

1. Specification is valid for all FB\_AD[31:0], FB\_BE/BWEn, FB\_CSn, FB\_OE, FB\_R/W, FB\_TBST, FB\_TSIZ[1:0], FB\_ALE, and FB\_TS.

2. Specification is valid for all FB\_AD[31:0] and FB\_TA.

**Table 26. Flexbus full voltage range switching specifications**

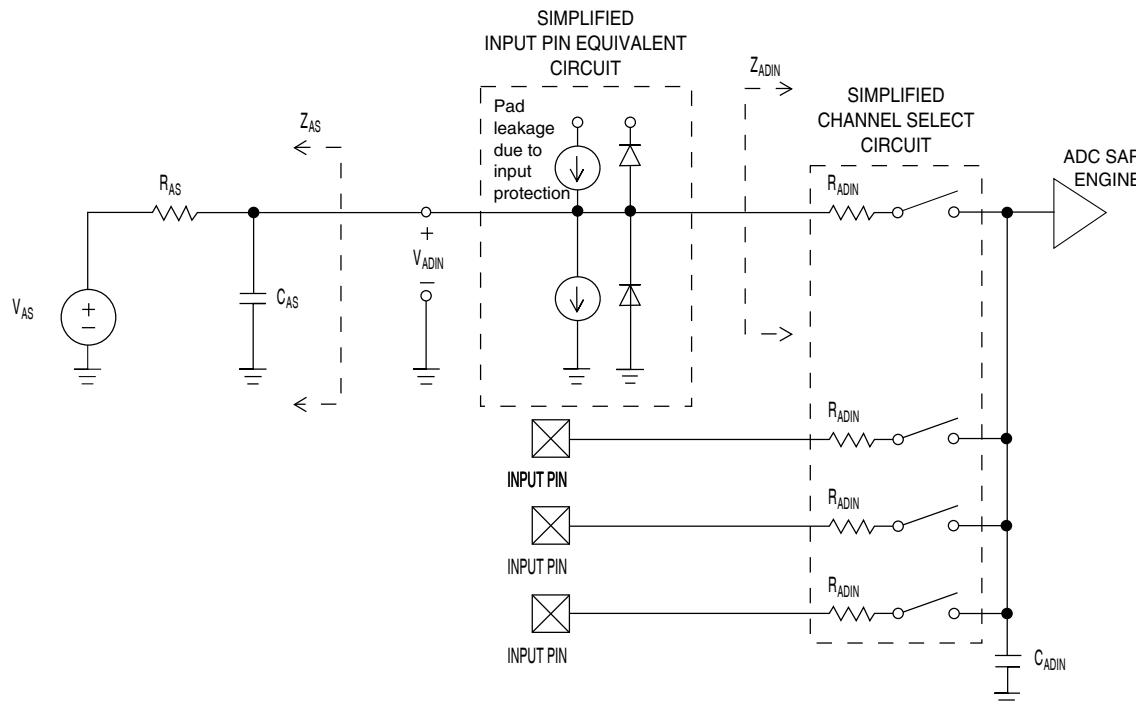
Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	1.71	3.6	V	
	Frequency of operation	—	FB_CLK	MHz	
FB1	Clock period	1/FB_CLK	—	ns	
FB2	Address, data, and control output valid	—	13.5	ns	<a href="#">1</a>
FB3	Address, data, and control output hold	0	—	ns	<a href="#">1</a>
FB4	Data and FB_TA input setup	13.7	—	ns	<a href="#">2</a>
FB5	Data and FB_TA input hold	0.5	—	ns	<a href="#">2</a>

1. Specification is valid for all FB\_AD[31:0], FB\_BE/BWE<sub>n</sub>, FB\_CS<sub>n</sub>, FB\_OE, FB\_R/W, FB\_TBST, FB\_TSIZ[1:0], FB\_ALE, and FB\_TS.
2. Specification is valid for all FB\_AD[31:0] and FB\_TA.

**Table 27. 16-bit ADC operating conditions (continued)**

Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
$C_{rate}$	ADC conversion rate	16-bit mode No ADC hardware averaging Continuous conversions enabled, subsequent conversion time	37.037	—	461.467	Ksps	5

1. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25 °C,  $f_{ADCK} = 1.0$  MHz, unless otherwise stated. Typical values are for reference only, and are not tested in production.
2. DC potential difference.
3. This resistance is external to MCU. To achieve the best results, the analog source resistance must be kept as low as possible. The results in this data sheet were derived from a system that had  $< 8 \Omega$  analog source resistance. The  $R_{AS}/C_{AS}$  time constant should be kept to  $< 1$  ns.
4. To use the maximum ADC conversion clock frequency, the ADHSC bit must be set and the ADLPC bit must be clear.
5. For guidelines and examples of conversion rate calculation, download the [ADC calculator tool](#).

**Figure 12. ADC input impedance equivalency diagram**

### 6.6.1.2 16-bit ADC electrical characteristics

**Table 28. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ )**

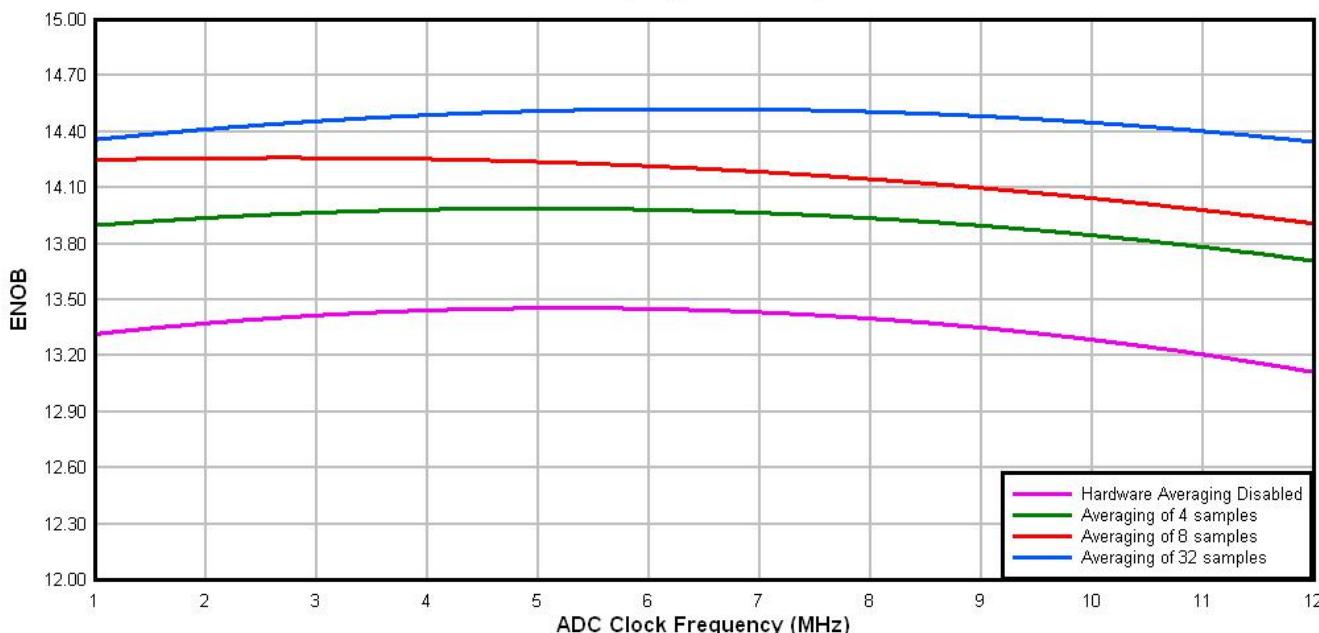
Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
$I_{DDA\_ADC}$	Supply current		0.215	—	1.7	mA	3

*Table continues on the next page...*

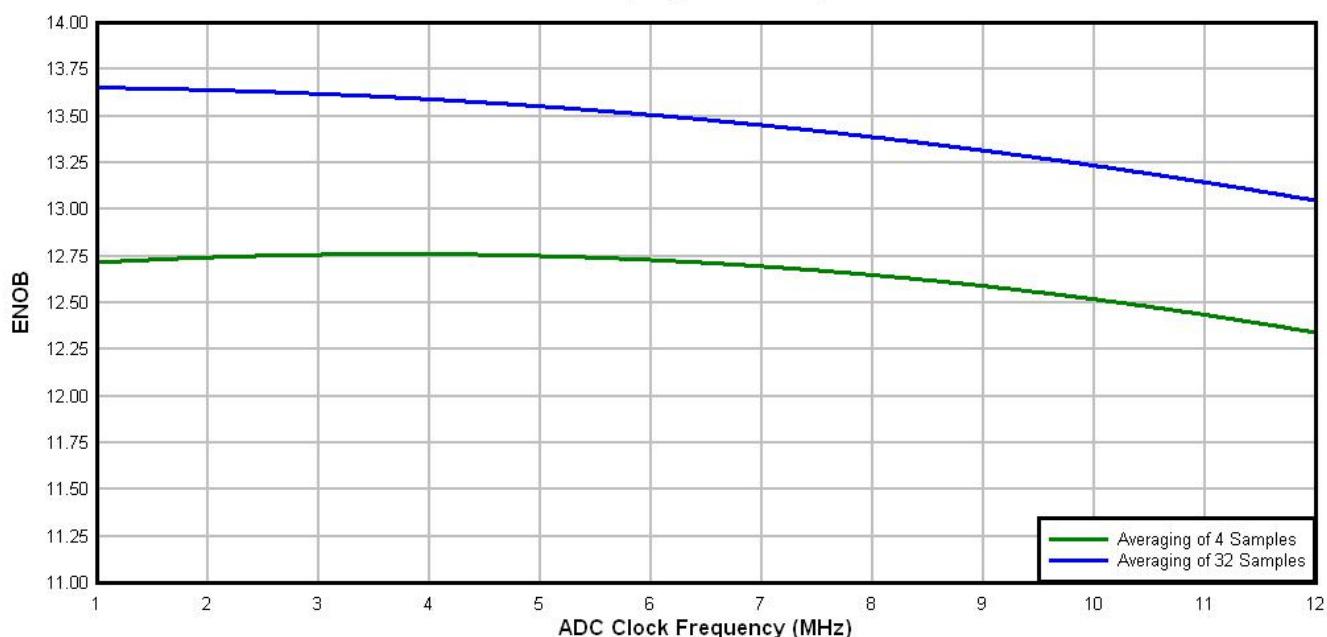
**Table 28. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
$E_{IL}$	Input leakage error			$I_{in} \times R_{AS}$		mV	$I_{in}$ = leakage current (refer to the MCU's voltage and current operating ratings)
	Temp sensor slope	Across the full temperature range of the device	1.55	1.62	1.69	mV/°C	
$V_{TEMP25}$	Temp sensor voltage	25 °C	706	716	726	mV	

1. All accuracy numbers assume the ADC is calibrated with  $V_{REFH} = V_{DDA}$
2. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25°C,  $f_{ADCK} = 2.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
3. The ADC supply current depends on the ADC conversion clock speed, conversion rate and the ADLPC bit (low power). For lowest power operation the ADLPC bit must be set, the HSC bit must be clear with 1 MHz ADC conversion clock speed.
4. 1 LSB =  $(V_{REFH} - V_{REFL})/2^N$
5. ADC conversion clock < 16 MHz, Max hardware averaging (AVGE = %1, AVGS = %11)
6. Input data is 100 Hz sine wave. ADC conversion clock < 12 MHz.
7. Input data is 1 kHz sine wave. ADC conversion clock < 12 MHz.

**Typical ADC 16-bit Differential ENOB vs ADC Clock  
100Hz, 90% FS Sine Input****Figure 13. Typical ENOB vs. ADC\_CLK for 16-bit differential mode**

**Typical ADC 16-bit Single-Ended ENOB vs ADC Clock  
100Hz, 90% FS Sine Input**



**Figure 14. Typical ENOB vs. ADC\_CLK for 16-bit single-ended mode**

### 6.6.1.3 16-bit ADC with PGA operating conditions

**Table 29. 16-bit ADC with PGA operating conditions**

Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
V <sub>DDA</sub>	Supply voltage	Absolute	1.71	—	3.6	V	
V <sub>REFPGA</sub>	PGA ref voltage		V <sub>REF_OU</sub> T	V <sub>REF_OU</sub> T	V <sub>REF_OU</sub> T	V	<a href="#">2, 3</a>
V <sub>ADIN</sub>	Input voltage		V <sub>SSA</sub>	—	V <sub>DDA</sub>	V	
V <sub>CM</sub>	Input Common Mode range		V <sub>SSA</sub>	—	V <sub>DDA</sub>	V	
R <sub>PGAD</sub>	Differential input impedance	Gain = 1, 2, 4, 8 Gain = 16, 32 Gain = 64	— — —	128 64 32	— — —	kΩ	<a href="#">IN+ to IN-<sup>4</sup></a>
R <sub>AS</sub>	Analog source resistance		—	100	—	Ω	<a href="#">5</a>
T <sub>S</sub>	ADC sampling time		1.25	—	—	μs	<a href="#">6</a>

*Table continues on the next page...*

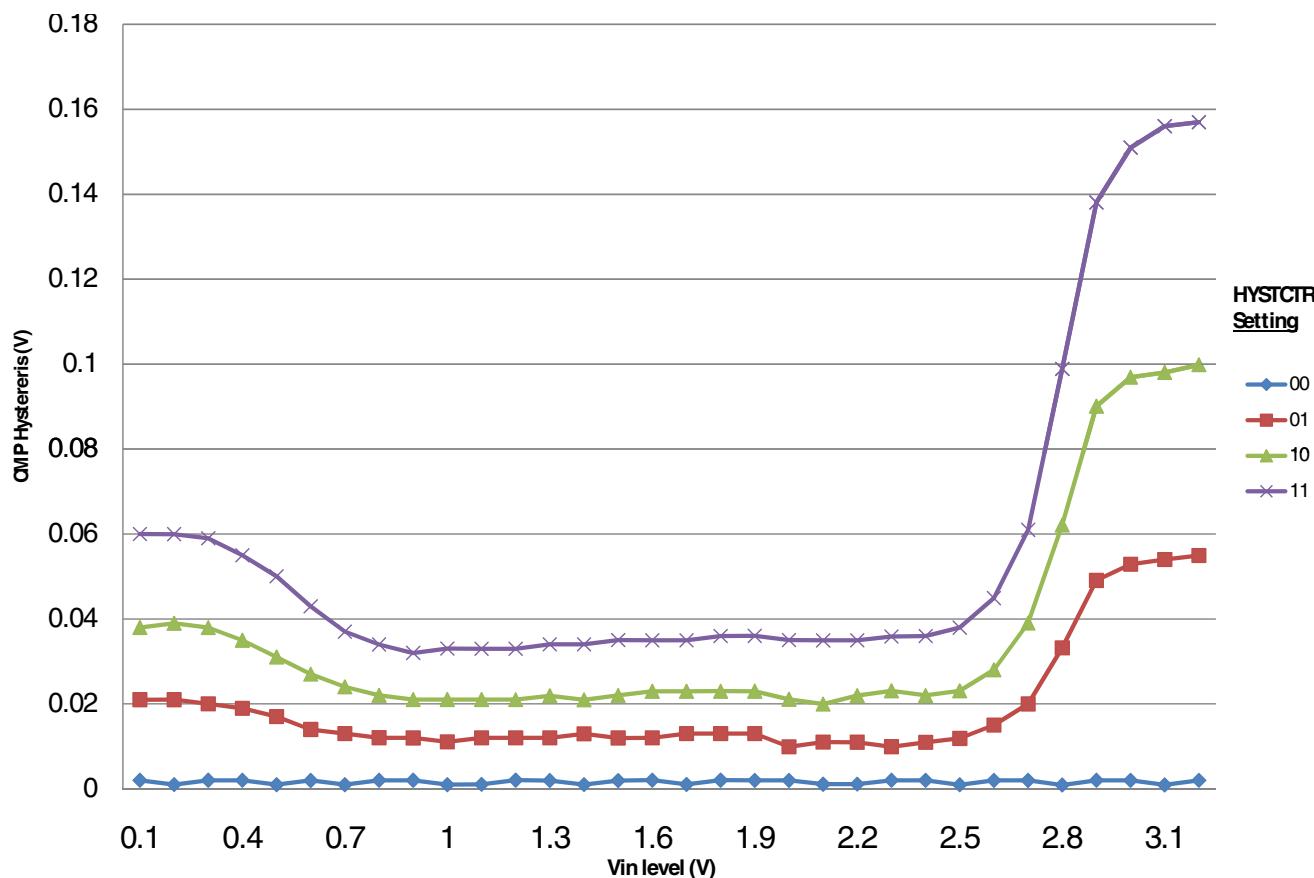


Figure 16. Typical hysteresis vs. Vin level (VDD=3.3V, PMODE=1)

### 6.6.3 12-bit DAC electrical characteristics

#### 6.6.3.1 12-bit DAC operating requirements

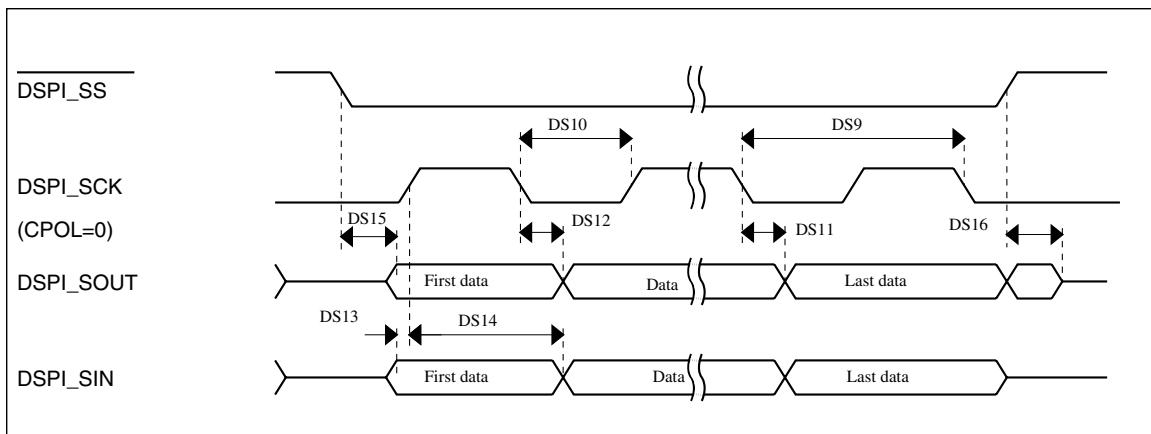
Table 32. 12-bit DAC operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
$V_{DDA}$	Supply voltage	1.71	3.6	V	
$V_{DACP}$	Reference voltage	1.13	3.6	V	1
$T_A$	Temperature	Operating temperature range of the device		°C	
$C_L$	Output load capacitance	—	100	pF	2
$I_L$	Output load current	—	1	mA	

1. The DAC reference can be selected to be  $V_{DDA}$  or the voltage output of the VREF module (VREF\_OUT)
2. A small load capacitance (47 pF) can improve the bandwidth performance of the DAC

**Table 39. Slave mode DSPI timing (limited voltage range)**

Num	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
	Frequency of operation		12.5	MHz
DS9	DSPI_SCK input cycle time	$4 \times t_{BUS}$	—	ns
DS10	DSPI_SCK input high/low time	$(t_{SCK}/2) - 2$	$(t_{SCK}/2) + 2$	ns
DS11	DSPI_SCK to DSPI_SOUT valid	—	10	ns
DS12	DSPI_SCK to DSPI_SOUT invalid	0	—	ns
DS13	DSPI_SIN to DSPI_SCK input setup	2	—	ns
DS14	DSPI_SCK to DSPI_SIN input hold	7	—	ns
DS15	DSPI_SS active to DSPI_SOUT driven	—	14	ns
DS16	DSPI_SS inactive to DSPI_SOUT not driven	—	14	ns

**Figure 20. DSPI classic SPI timing — slave mode**

### 6.8.3 DSPI switching specifications (full voltage range)

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provides DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

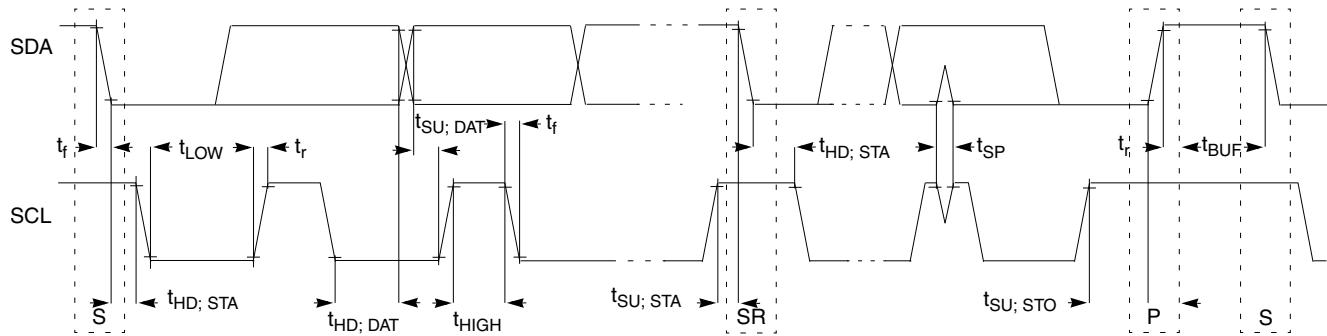
**Table 40. Master mode DSPI timing (full voltage range)**

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	1.71	3.6	V	<a href="#">1</a>
	Frequency of operation	—	12.5	MHz	
DS1	DSPI_SCK output cycle time	$4 \times t_{BUS}$	—	ns	

Table continues on the next page...

## Peripheral operating requirements and behaviors

6.  $C_b$  = total capacitance of the one bus line in pF.



**Figure 23. Timing definition for fast and standard mode devices on the I<sup>2</sup>C bus**

### 6.8.5 UART switching specifications

See [General switching specifications](#).

### 6.8.6 SDHC specifications

The following timing specs are defined at the chip I/O pin and must be translated appropriately to arrive at timing specs/constraints for the physical interface.

**Table 43. SDHC switching specifications**

Num	Symbol	Description	Min.	Max.	Unit
<b>Card input clock</b>					
SD1	fpp	Clock frequency (low speed)	0	400	kHz
	fpp	Clock frequency (SD/SDIO full speed\high speed)	0	25\50	MHz
	fpp	Clock frequency (MMC full speed\high speed)	0	20\50	MHz
	f <sub>OD</sub>	Clock frequency (identification mode)	0	400	kHz
SD2	t <sub>WL</sub>	Clock low time	7	—	ns
SD3	t <sub>WH</sub>	Clock high time	7	—	ns
SD4	t <sub>TLH</sub>	Clock rise time	—	3	ns
SD5	t <sub>THL</sub>	Clock fall time	—	3	ns
<b>SDHC output / card inputs SDHC_CMD, SDHC_DAT (reference to SDHC_CLK)</b>					
SD6	t <sub>OD</sub>	SDHC output delay (output valid)	-5	8.3	ns
<b>SDHC input / card inputs SDHC_CMD, SDHC_DAT (reference to SDHC_CLK)</b>					
SD7	t <sub>ISU</sub>	SDHC input setup time	5	—	ns
SD8	t <sub>IH</sub>	SDHC input hold time	0	—	ns

**Pinout**

144 LQFP	144 MAP BGA	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
7	E3	PTE4/ LLWU_P2	DISABLED		PTE4/ LLWU_P2	SPI1_PCS0	UART3_TX	SDHC0_D3				
8	E2	PTE5	DISABLED		PTE5	SPI1_PCS2	UART3_RX	SDHC0_D2				
9	E1	PTE6	DISABLED		PTE6	SPI1_PCS3	UART3_CTS_b	I2S0_MCLK		I2S0_CLKIN		
10	F4	PTE7	DISABLED		PTE7		UART3_RTS_b	I2S0_RXD				
11	F3	PTE8	DISABLED		PTE8		UART5_TX	I2S0_RX_FS				
12	F2	PTE9	DISABLED		PTE9		UART5_RX	I2S0_RX_BCLK				
13	F1	PTE10	DISABLED		PTE10		UART5_CTS_b	I2S0_TXD				
14	G4	PTE11	DISABLED		PTE11		UART5_RTS_b	I2S0_TX_FS				
15	G3	PTE12	DISABLED		PTE12			I2S0_TX_BCLK				
16	E6	VDD	VDD	VDD								
17	F7	VSS	VSS	VSS								
18	H1	PTE16	ADC0_SE4a	ADC0_SE4a	PTE16	SPI0_PCS0	UART2_TX	FTM0_CLKIN0		FTM0_FLT3		
19	H2	PTE17	ADC0_SE5a	ADC0_SE5a	PTE17	SPI0_SCK	UART2_RX	FTM0_CLKIN1		LPT0_ALT3		
20	G1	PTE18	ADC0_SE6a	ADC0_SE6a	PTE18	SPI0_SOUT	UART2_CTS_b	I2C0_SDA				
21	G2	PTE19	ADC0_SE7a	ADC0_SE7a	PTE19	SPI0_SIN	UART2_RTS_b	I2C0_SCL				
22	H3	VSS	VSS	VSS								
23	J1	ADC0_DP1	ADC0_DP1	ADC0_DP1								
24	J2	ADC0_DM1	ADC0_DM1	ADC0_DM1								
25	K1	ADC1_DP1	ADC1_DP1	ADC1_DP1								
26	K2	ADC1_DM1	ADC1_DM1	ADC1_DM1								
27	L1	PGA0_DP/ ADC0_DP0/ ADC1_DP3	PGA0_DP/ ADC0_DP0/ ADC1_DP3	PGA0_DP/ ADC0_DP0/ ADC1_DP3								
28	L2	PGA0_DM/ ADC0_DM0/ ADC1_DM3	PGA0_DM/ ADC0_DM0/ ADC1_DM3	PGA0_DM/ ADC0_DM0/ ADC1_DM3								
29	M1	PGA1_DP/ ADC1_DP0/ ADC0_DP3	PGA1_DP/ ADC1_DP0/ ADC0_DP3	PGA1_DP/ ADC1_DP0/ ADC0_DP3								
30	M2	PGA1_DM/ ADC1_DM0/ ADC0_DM3	PGA1_DM/ ADC1_DM0/ ADC0_DM3	PGA1_DM/ ADC1_DM0/ ADC0_DM3								
31	H5	VDDA	VDDA	VDDA								
32	G5	VREFH	VREFH	VREFH								
33	G6	VREFL	VREFL	VREFL								
34	H6	VSSA	VSSA	VSSA								

## Pinout

144 LQFP	144 MAP BGA	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
60	K8	PTA8	ADC0_SE11	ADC0_SE11	PTA8		FTM1_CH0			FTM1_QD_PHB	TRACE_D2	
61	L8	PTA9	DISABLED		PTA9		FTM1_CH1			FTM1_QD_PHB	TRACE_D1	
62	M9	PTA10	DISABLED		PTA10		FTM2_CH0			FTM2_QD_PHB	TRACE_D0	
63	L9	PTA11	DISABLED		PTA11		FTM2_CH1			FTM2_QD_PHB		
64	K9	PTA12	CMP2_IN0	CMP2_IN0	PTA12	CAN0_TX	FTM1_CH0			I2S0_RXD	FTM1_QD_PHB	
65	J9	PTA13/ LLWU_P4	CMP2_IN1	CMP2_IN1	PTA13/ LLWU_P4	CAN0_RX	FTM1_CH1			I2S0_TX_FS	FTM1_QD_PHB	
66	L10	PTA14	DISABLED		PTA14	SPI0_PCS0	UART0_TX			I2S0_TX_BCLK		
67	L11	PTA15	DISABLED		PTA15	SPI0_SCK	UART0_RX			I2S0_RXD		
68	K10	PTA16	DISABLED		PTA16	SPI0_SOUT	UART0_CTS_b			I2S0_RX_FS		
69	K11	PTA17	ADC1_SE17	ADC1_SE17	PTA17	SPI0_SIN	UART0_RTS_b			I2S0_MCLK	I2S0_CLKIN	
70	E8	VDD	VDD	VDD								
71	G8	VSS	VSS	VSS								
72	M12	PTA18	EXTAL	EXTAL	PTA18		FTM0_FLT2	FTM_CLKIN0				
73	M11	PTA19	XTAL	XTAL	PTA19		FTM1_FLT0	FTM_CLKIN1		LPT0_ALT1		
74	L12	RESET_b	RESET_b	RESET_b								
75	K12	PTA24	DISABLED		PTA24					FB_A29		
76	J12	PTA25	DISABLED		PTA25					FB_A28		
77	J11	PTA26	DISABLED		PTA26					FB_A27		
78	J10	PTA27	DISABLED		PTA27					FB_A26		
79	H12	PTA28	DISABLED		PTA28					FB_A25		
80	H11	PTA29	DISABLED		PTA29					FB_A24		
81	H10	PTB0/ LLWU_P5	ADC0_SE8/ ADC1_SE8/ TSI0_CH0	ADC0_SE8/ ADC1_SE8/ TSI0_CH0	PTB0/ LLWU_P5	I2C0_SCL	FTM1_CH0			FTM1_QD_PHB		
82	H9	PTB1	ADC0_SE9/ ADC1_SE9/ TSI0_CH6	ADC0_SE9/ ADC1_SE9/ TSI0_CH6	PTB1	I2C0_SDA	FTM1_CH1			FTM1_QD_PHB		
83	G12	PTB2	ADC0_SE12/ TSI0_CH7	ADC0_SE12/ TSI0_CH7	PTB2	I2C0_SCL	UART0_RTS_b			FTM0_FLT3		
84	G11	PTB3	ADC0_SE13/ TSI0_CH8	ADC0_SE13/ TSI0_CH8	PTB3	I2C0_SDA	UART0_CTS_b			FTM0_FLT0		
85	G10	PTB4	ADC1_SE10	ADC1_SE10	PTB4					FTM1_FLT0		
86	G9	PTB5	ADC1_SE11	ADC1_SE11	PTB5					FTM2_FLT0		
87	F12	PTB6	ADC1_SE12	ADC1_SE12	PTB6					FB_AD23		
88	F11	PTB7	ADC1_SE13	ADC1_SE13	PTB7					FB_AD22		

## Pinout

144 LQFP	144 MAP BGA	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
117	A7	PTC12			PTC12		UART4_RTS_b		FB_AD27			
118	D6	PTC13			PTC13		UART4_CTS_b		FB_AD26			
119	C6	PTC14			PTC14		UART4_RX		FB_AD25			
120	B6	PTC15			PTC15		UART4_TX		FB_AD24			
121	—	VSS	VSS	VSS								
122	—	VDD	VDD	VDD								
123	A6	PTC16			PTC16	CAN1_RX	UART3_RX		FB_CS5_b/ FB_TSIZ1/ FB_BE23_16_b			
124	D5	PTC17			PTC17	CAN1_TX	UART3_TX		FB_CS4_b/ FB_TSIZ0/ FB_BE31_24_b			
125	C5	PTC18			PTC18		UART3_RTS_b		FB_TBST_b/ FB_CS2_b/ FB_BE15_8_b			
126	B5	PTC19			PTC19		UART3_CTS_b		FB_CS3_b/ FB_BE7_0_b	FB_TA_b		
127	A5	PTD0/ LLWU_P12			PTD0/ LLWU_P12	SPI0_PCS0	UART2_RTS_b		FB_ALE/ FB_CS1_b/ FB_TS_b			
128	D4	PTD1	ADC0_SE5b	ADC0_SE5b	PTD1	SPI0_SCK	UART2_CTS_b		FB_CS0_b			
129	C4	PTD2/ LLWU_P13			PTD2/ LLWU_P13	SPI0_SOUT	UART2_RX		FB_AD4			
130	B4	PTD3			PTD3	SPI0_SIN	UART2_TX		FB_AD3			
131	A4	PTD4/ LLWU_P14			PTD4/ LLWU_P14	SPI0_PCS1	UART0_RTS_b	FTM0_CH4	FB_AD2	EWM_IN		
132	A3	PTD5	ADC0_SE6b	ADC0_SE6b	PTD5	SPI0_PCS2	UART0_CTS_b	FTM0_CH5	FB_AD1	EWM_OUT_b		
133	A2	PTD6/ LLWU_P15	ADC0_SE7b	ADC0_SE7b	PTD6/ LLWU_P15	SPI0_PCS3	UART0_RX	FTM0_CH6	FB_AD0	FTM0_FLT0		
134	M10	VSS	VSS	VSS								
135	F8	VDD	VDD	VDD								
136	A1	PTD7			PTD7	CMT_IRO	UART0_TX	FTM0_CH7		FTM0_FLT1		
137	C9	PTD8	DISABLED		PTD8	I2C0_SCL	UART5_RX			FB_A16		
138	B9	PTD9	DISABLED		PTD9	I2C0_SDA	UART5_TX			FB_A17		
139	B3	PTD10	DISABLED		PTD10		UART5_RTS_b			FB_A18		
140	B2	PTD11	DISABLED		PTD11	SPI2_PCS0	UART5_CTS_b	SDHC0_CLKIN		FB_A19		
141	B1	PTD12	DISABLED		PTD12	SPI2_SCK		SDHC0_D4		FB_A20		
142	C3	PTD13	DISABLED		PTD13	SPI2_SOUT		SDHC0_D5		FB_A21		

144 LQFP	144 MAP BGA	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
143	C2	PTD14	DISABLED		PTD14	SPI2_SIN		SDHC0_D6		FB_A22		
144	C1	PTD15	DISABLED		PTD15	SPI2_PCS1		SDHC0_D7		FB_A23		

## 8.2 K10 Pinouts

The below figure shows the pinout diagram for the devices supported by this document. Many signals may be multiplexed onto a single pin. To determine what signals can be used on which pin, see the previous section.

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