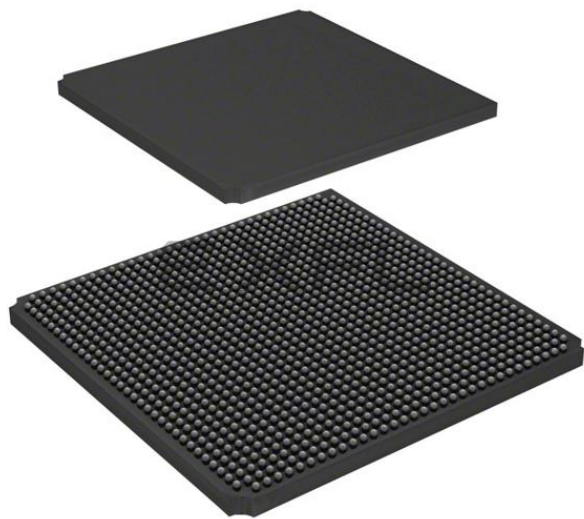




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[Embedded - System On Chip \(SoC\): The Heart of Modern Embedded Systems](#)

[Embedded - System On Chip \(SoC\)](#) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are [Embedded - System On Chip \(SoC\)](#)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Obsolete
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	512KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I ² C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 100K Logic Modules
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1152-BBGA, FCBGA
Supplier Device Package	1152-FCBGA (35x35)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/m2s100-1fc1152

Table 15 • Inrush Currents at Power up, $-40\text{ }^{\circ}\text{C} \leq T_J \leq 100\text{ }^{\circ}\text{C}$ – Typical Process

Power Supplies	Voltage (V)	005	010	025	050	060	090	150	Unit
V_{DD}	1.26	25	32	38	48	45	77	109	mA
V_{PP}	3.46	33	49	36	180	13	36	51	mA
V_{DDI}	2.62	134	141	161	187	93	272	388	mA
Number of banks		7	8	8	10	10	9	19	

2.3.3 Average Fabric Temperature and Voltage Derating Factors

The following table lists the average temperature and voltage derating factors for fabric timing delays normalized to $T_J = 85\text{ }^{\circ}\text{C}$, in worst-case $V_{DD} = 1.14\text{ V}$.

Table 16 • Average Junction Temperature and Voltage Derating Factors for Fabric Timing Delays

Array Voltage V_{DD} (V)	$-40\text{ }^{\circ}\text{C}$	$0\text{ }^{\circ}\text{C}$	$25\text{ }^{\circ}\text{C}$	$70\text{ }^{\circ}\text{C}$	$85\text{ }^{\circ}\text{C}$	$100\text{ }^{\circ}\text{C}$
1.14	0.83	0.89	0.92	0.98	1.00	1.02
1.2	0.75	0.80	0.83	0.89	0.91	0.93
1.26	0.69	0.73	0.76	0.81	0.83	0.85

Table 19 • Maximum Data Rate Summary Table for Voltage-Referenced I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
LPDDR			400	Mbps
HSTL1.5 V			400	Mbps
SSTL 2.5 V	510	700	400	Mbps
SSTL 1.8 V			667	Mbps
SSTL 1.5 V			667	Mbps

Table 20 • Maximum Data Rate Summary Table for Differential I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	Unit
LVPECL (input only)	900		Mbps
LVDS 3.3 V	535		Mbps
LVDS 2.5 V	535	700	Mbps
RSDS	520	700	Mbps
BLVDS	500		Mbps
MLVDS	500		Mbps
Mini-LVDS	520	700	Mbps

Table 21 • Maximum Frequency Summary Table for Single-Ended I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
PCI 3.3 V	315			MHz
LVTTL 3.3 V	300			MHz
LVC MOS 3.3 V	300			MHz
LVC MOS 2.5 V	205	210	200	MHz
LVC MOS 1.8 V	147.5	200	200	MHz
LVC MOS 1.5 V	80	110	118	MHz
LVC MOS 1.2 V	60	80	100	MHz
LPDDR– LVC MOS 1.8 V mode			200	MHz

Table 85 • LVCMOS 1.2 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.883	4.568	4.868	5.726	5.329	6.269	7.994	9.404	7.527	8.855	ns
4 mA	Slow	3.774	4.44	4.188	4.926	4.613	5.426	8.972	10.555	8.315	9.782	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.11 3.3 V PCI/PCIX

Peripheral Component Interface (PCI) for 3.3 V standards specify support for 33 MHz and 66 MHz PCI bus applications.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to MSIO Bank Only)

Table 86 • PCI/PCI-X DC Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	3.15	3.3	3.45	V

Table 87 • PCI/PCI-X DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	3.45	V
Input current high ¹	$I_{IH}(DC)$			
Input current low ¹	$I_{IL}(DC)$			

1. See Table 24, page 22.

Table 88 • PCI/PCI-X DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V_{OH}		Per PCI specification		V
DC output logic low	V_{OL}		Per PCI specification		V

Table 89 • PCI/PCI-X Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (MSIO I/O bank)	D_{MAX}	630	Mbps	AC Loading: per JEDEC specifications

Table 90 • PCI/PCI-X AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path (falling edge)	V_{TRIP}	$0.615 \times V_{DDI}$	V
Measuring/trip point for data path (rising edge)	V_{TRIP}	$0.285 \times V_{DDI}$	V
Resistance for data test path	R_{TT_TEST}	25	Ω
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	10	pF

Table 185 • M-LVDS DC Voltage Specification Output Voltage Specification (for MSIO I/O Bank Only)

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V_{OH}	1.25	1.425	1.6	V
DC output logic low	V_{OL}	0.9	1.075	1.25	V

Table 186 • M-LVDS Differential Voltage Specification

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing (for MSIO I/O bank only)	V_{OD}	300	650	mV
Output common mode voltage (for MSIO I/O bank only)	V_{OCM}	0.3	2.1	V
Input common mode voltage	V_{ICM}	0.3	1.2	V
Input differential voltage	V_{ID}	50	2400	mV

Table 187 • M-LVDS Minimum and Maximum AC Switching Speed for MSIO I/O Bank

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	500	Mbps	AC loading: 2 pF / 100 Ω differential load

Table 188 • M-LVDS AC Impedance Specifications

Parameter	Symbol	Typ	Unit
Termination resistance	R_T	50	Ω

Table 189 • M-LVDS AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	Cross point	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$

Table 190 • M-LVDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.738	3.221	ns
100	2.735	3.218	ns

Table 191 • M-LVDS AC Switching Characteristics for Receiver (for MSIOD I/O Bank - Input Buffers)

On-Die Termination (ODT)	T _{py}		Unit
	-1	-Std	
None	2.495	2.934	ns
100	2.495	2.935	ns

Table 192 • M-LVDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)

T _{DP}		T _{ZL}		T _{ZH}		T _{HZ}		T _{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.258	2.656	2.348	2.762	2.334	2.746	2.123	2.497	2.125	2.5	ns

2.3.7.4 Mini-LVDS

Mini-LVDS is an unidirectional interface from the timing controller to the column drivers and is designed to the Texas Instruments Standard SLDA007A.

Mini-LVDS Minimum and Maximum Input and Output Levels**Table 193 • Mini-LVDS Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	2.375	2.5	2.625	V

Table 194 • Mini-LVDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC Input voltage	V _I	0	2.925	V

Table 195 • Mini-LVDS DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V _{OH}	1.25	1.425	1.6	V
DC output logic low	V _{OL}	0.9	1.075	1.25	V

Table 196 • Mini-LVDS DC Differential Voltage Specification

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing	V _{OD}	300	600	mV
Output common mode voltage	V _{OCM}	1	1.4	V
Input common mode voltage	V _{ICM}	0.3	1.2	V
Input differential voltage	V _{ID}	100	600	mV

Table 197 • Mini-LVDS Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	D _{MAX}	520	Mbps	AC loading: 2 pF / 100 Ω differential load
Maximum data rate (for MSIOD I/O bank)	D _{MAX}	700	Mbps	AC loading: 2 pF / 100 Ω differential load

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 210 • RSDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.855	3.359	ns
100	2.85	3.353	ns

Table 211 • RSDS AC Switching Characteristics for Receiver (for MSIOD I/O Bank - Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.602	3.061	ns
100	2.597	3.055	ns

Table 212 • RSDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.097	2.467	2.303	2.709	2.291	2.695	1.961	2.307	1.947	2.29	ns

Table 213 • RSDS AC Switching Characteristics for Transmitter (for MSIOD I/O Bank - Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
No pre-emphasis	1.614	1.899	1.559	1.834	1.55	1.823	1.59	1.87	1.575	1.852	ns
Min pre-emphasis	1.604	1.887	1.742	2.05	1.728	2.032	1.889	2.222	1.858	2.185	ns
Med pre-emphasis	1.521	1.79	1.753	2.062	1.737	2.043	1.9	2.235	1.868	2.197	ns
Max pre-emphasis	1.492	1.754	1.762	2.073	1.745	2.052	1.91	2.247	1.876	2.206	ns

2.3.7.6 LVPECL

Low-Voltage Positive Emitter-Coupled Logic (LVPECL) is another differential I/O standard. It requires that one data bit be carried through two signal lines. Similar to LVDS, two pins are needed. It also requires external resistor termination. IGLOO2 and SmartFusion2 SoC FPGAs support only LVPECL receivers and do not support LVPECL transmitters.

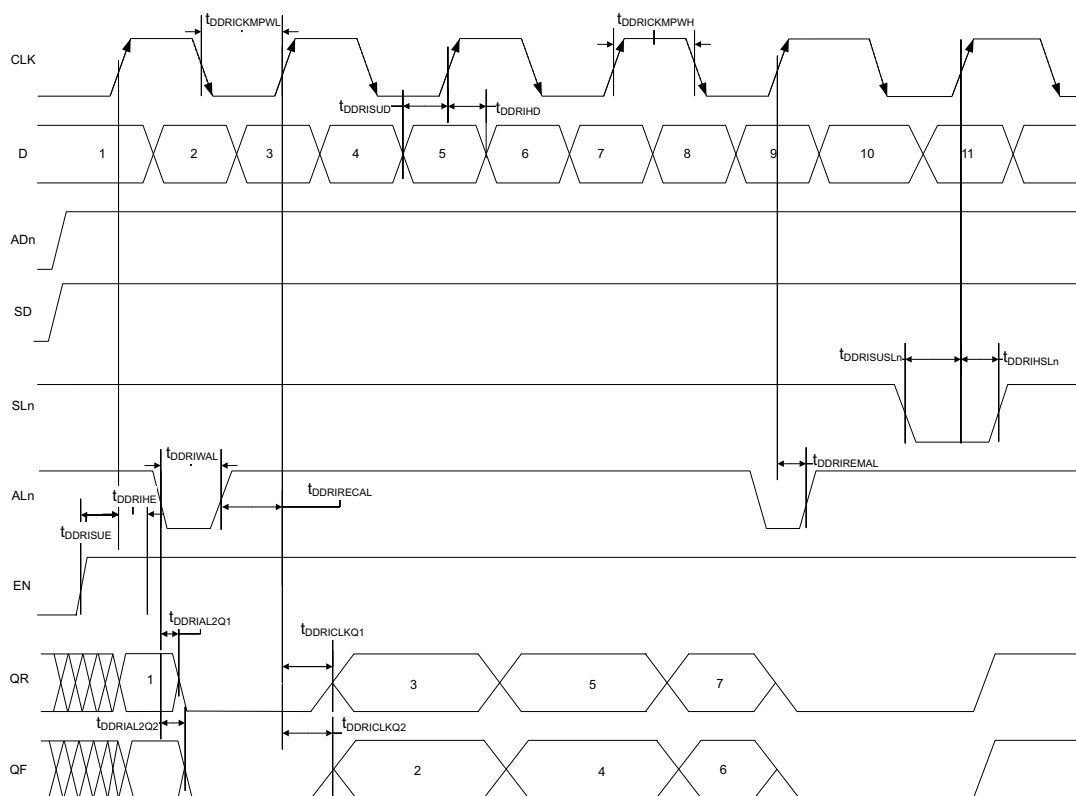
Minimum and Maximum Input and Output Levels (Applicable to MSIO I/O Bank Only)

Table 214 • LVPECL Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	3.15	3.3	3.45	V

2.3.9.2 Input DDR Timing Diagram

Figure 11 • Input DDR Timing Diagram



2.3.9.3 Timing Characteristics

The following table lists the input DDR propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 221 • Input DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	–1	–Std	Unit
T _{DDRICKQ1}	Clock-to-Out Out_QR for input DDR	B, C	0.16	0.188	ns
T _{DDRICKQ2}	Clock-to-Out Out_QF for input DDR	B, D	0.166	0.195	ns
T _{DDRISUD}	Data setup for input DDR	A, B	0.357	0.421	ns
T _{DDRIHD}	Data hold for input DDR	A, B	0	0	ns
T _{DDRISUE}	Enable setup for input DDR	E, B	0.46	0.542	ns
T _{DDRIHE}	Enable hold for input DDR	E, B	0	0	ns
T _{DDRISUSLN}	Synchronous load setup for input DDR	G, B	0.46	0.542	ns
T _{DDRIHSLN}	Synchronous load hold for input DDR	G, B	0	0	ns
T _{DDRIAL2Q1}	Asynchronous load-to-out QR for input DDR	F, C	0.587	0.69	ns
T _{DDRIAL2Q2}	Asynchronous load-to-out QF for input DDR	F, D	0.541	0.636	ns
T _{DDRIREMAL}	Asynchronous load removal time for input DDR	F, B	0	0	ns
T _{DDRIRECAL}	Asynchronous load recovery time for input DDR	F, B	0.074	0.087	ns

2.3.10.2 Timing Characteristics

The following table lists the combinatorial cell propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

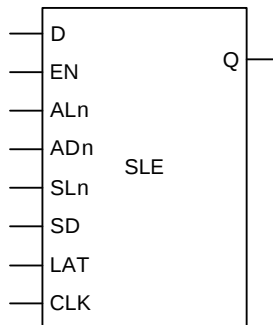
Table 223 • Combinatorial Cell Propagation Delays

Combinatorial Cell	Equation	Symbol	–1	–Std	Unit
INV	$Y = !A$	T_{PD}	0.1	0.118	ns
AND2	$Y = A \cdot B$	T_{PD}	0.164	0.193	ns
NAND2	$Y = !(A \cdot B)$	T_{PD}	0.147	0.173	ns
OR2	$Y = A + B$	T_{PD}	0.164	0.193	ns
NOR2	$Y = !(A + B)$	T_{PD}	0.147	0.173	ns
XOR2	$Y = A \oplus B$	T_{PD}	0.164	0.193	ns
XOR3	$Y = A \oplus B \oplus C$	T_{PD}	0.225	0.265	ns
AND3	$Y = A \cdot B \cdot C$	T_{PD}	0.209	0.246	ns
AND4	$Y = A \cdot B \cdot C \cdot D$	T_{PD}	0.287	0.338	ns

2.3.10.3 Sequential Module

IGLOO2 and SmartFusion2 SoC FPGAs offer a separate flip-flop which can be used independently from the LUT. The flip-flop can be configured as a register or a latch and has a data input and optional enable, synchronous load (clear or preset), and asynchronous load (clear or preset).

Figure 15 • Sequential Module



The following table lists the 010 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 229 • 010 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.626	0.669	0.627	0.668	ns
Input high delay for global clock	T_{RCKH}	1.112	1.182	1.308	1.393	ns
Maximum skew for global clock	T_{RCKSW}		0.07		0.085	ns

The following table lists the 005 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 230 • 005 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.625	0.66	0.628	0.66	ns
Input high delay for global clock	T_{RCKH}	1.126	1.187	1.325	1.397	ns
Maximum skew for global clock	T_{RCKSW}		0.061		0.072	ns

2.3.12 FPGA Fabric SRAM

See *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide* for more information.

2.3.12.1 FPGA Fabric Large SRAM (LSRAM)

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 1K × 18 in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.334		0.393	ns
Read access time without pipeline register	T_{CLK2Q}		2.273		2.674	ns
Access time with feed-through write timing			1.529		1.799	ns
Address setup time	T_{ADDRSU}	0.441		0.519		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.341		0.401		ns
Data hold time	T_{DHD}	0.107		0.126		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns

Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Block select hold time	T _{BLKH} D	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T _{BLK2} Q		1.529		1.799	ns
Block select minimum pulse width	T _{BLKMPW}	0.186		0.219		ns
Read enable setup time	T _{RDESU}	0.449		0.528		ns
Read enable hold time	T _{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLESU}	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLEHD}	0.102		0.12		ns
Asynchronous reset to output propagation delay	T _{R2Q}	–	1.506	–	1.772	ns
Asynchronous reset removal time	T _{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T _{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T _{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	T _{PLRSTREM}	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	T _{PLRSTREC}	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	T _{PLRSTMPW}	0.282		0.332		ns
Synchronous reset setup time	T _{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T _{SRSTHD}	0.036		0.043		ns
Write enable setup time	T _{WESU}	0.39		0.458		ns
Write enable hold time	T _{WEHD}	0.242		0.285		ns
Maximum frequency	F _{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 2K × 9 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T _{CY}	2.5		2.941		ns
Clock minimum pulse width high	T _{CLKMPWH}	1.125		1.323		ns
Clock minimum pulse width low	T _{CLKMPWL}	1.125		1.323		ns
Pipelined clock period	T _{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	T _{PLCLKMPWH}	1.125		1.323		ns
Pipelined clock minimum pulse width low	T _{PLCLKMPWL}	1.125		1.323		ns
Read access time with pipeline register			0.334		0.393	ns
Read access time without pipeline register	T _{CLK2Q}		2.273		2.674	ns
Access time with feed-through write timing			1.529		1.799	ns

Table 237 • μ SRAM (RAM64x18) in 64 × 18 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 64 × 16 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 238 • μ SRAM (RAM64x16) in 64 × 16 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.983	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns

Table 240 • μ SRAM (RAM128x8) in 128 × 8 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.982	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

Table 243 • μ SRAM (RAM1024x1) in 1024 × 1 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.003		0.004		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.247		0.29		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.03		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

2.3.13 Programming Times

The following tables list the programming times in typical conditions when $T_J = 25\text{ }^{\circ}\text{C}$, $V_{DD} = 1.2\text{ V}$. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 244 • JTAG Programming (Fabric Only)

M2S/M2GL				
Device	Image size Bytes	Program	Verify	Unit
005	302672	22	10	Sec
010	568784	28	18	Sec
025	1223504	51	26	Sec
050	2424832	66	54	Sec
060	2418896	77	54	Sec
090	3645968	113	126	Sec
150	6139184	155	193	Sec

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only) (continued)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
150	161	161	161	Sec

Table 255 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 ¹	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec
150	161	161	161	Sec
005	87	67	66	Sec
010	161	113	113	Sec
025	229	120	121	Sec
050	112	Not Supported	Not Supported	Sec
060	368	161	158	Sec
090	582	261	260	Sec
150	867	309	310	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 276 • Cryptographic Block Characteristics (continued)

Service	Conditions	Timing	Unit
SHA256	512 bits	540	kbps
	1024 bits	780	kbps
	2048 bits	950	kbps
	24 kbits	1140	kbps
HMAC	512 bytes	820	kbps
	1024 bytes	890	kbps
	2048 bytes	930	kbps
	24 kbytes	980	kbps
KeyTree		1.8	ms
Challenge-response	PUF = OFF	25	ms
	PUF = ON	7	ms
ECC point multiplication		590	ms
ECC point addition		8	ms

1. Using cypher block chaining (CBC) mode.

2.3.19 Crystal Oscillator

The following table describes the electrical characteristics of the crystal oscillator in the IGLOO2 FPGA and SmartFusion2 SoC FPGAs.

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		20		MHz	
Accuracy	ACCXTAL			0.0047	%	005, 010, 025, 050, 060, and 090 devices
				0.0058	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		200	300	ps	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		200	300	ps	010, 025, 050, and 060 devices
			250	410	ps	150 devices
			250	550	ps	005 and 090 devices
Operating current	IDYNXTAL		1.5		mA	010, 050, and 060 devices
			1.65		mA	005, 025, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

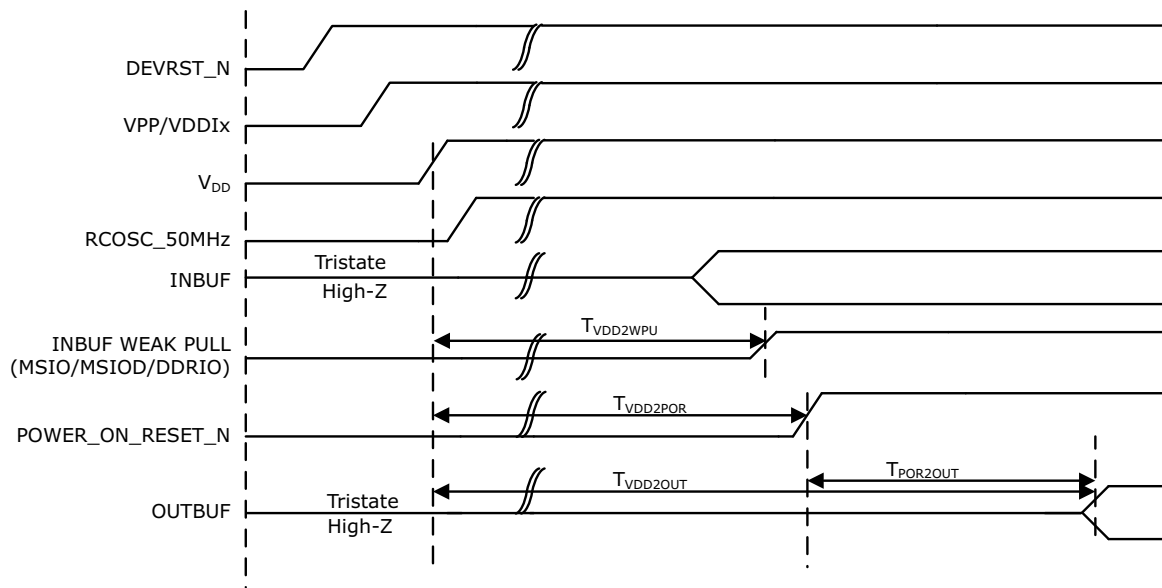
Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

Figure 18 • Power-up to Functional Timing Diagram for IGLOO2

2.3.25 DEVRST_N Characteristics

Table 290 • DEVRST_N Characteristics for All Devices

Parameter	Symbol	Max	Unit
DEVRST_N ramp rate	$T_{RAMPDEVRSTN}$	1	us
DEVRST_N cycling rate	$F_{MAXPDEVRSTN}$	100	kHz

2.3.26 DEVRST_N to Functional Times

The following table lists the SmartFusion2 DEVRST_N to functional times in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 291 • DEVRST_N to Functional Times for SmartFusion2

Symbol	From	To	Description	Maximum Power-up to Functional Time for SmartFusion2 (uS)						
				005	010	025	050	060	090	150
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	518	501	527	521	422	419	694
$T_{POR2MSSRST}$	POWER_ON_RESET_N	MSS_RESET_N_M2F	Fabric to MSS	515	497	524	518	417	414	689
$T_{MSSRST2OUT}$	MSS_RESET_N_M2F	Output available at I/O	MSS to output	3.5	3.5	3.5	3.3	4.8	4.8	4.8
$T_{DEVRST2OUT}$	DEVRST_N	Output available at I/O	V_{DD} at its minimum threshold level to output	706	768	715	691	641	635	871

2.3.31.2 SmartFusion2 Inter-Integrated Circuit (I²C) Characteristics

This section describes the DC and switching of the I²C interface. Unless otherwise noted, all output characteristics given are for a 100 pF load on the pins. For timing parameter definitions, see Figure 21, page 125.

The following table lists the I²C characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 303 • I²C Characteristics

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Input low voltage	V_{IL}	-0.3		0.8	V	See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Input high voltage	V_{IH}	2		3.45	V	See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Hysteresis of schmitt triggered inputs for $V_{DDI} > 2\text{ V}$	V_{HYS}	$0.05 \times V_{DDI}$			V	See Table 28, page 23 for more information.
Input current high	I_{IL}			10	μA	See Single-Ended I/O Standards, page 24 for more information.
Input current low	I_{IH}			10	μA	See Single-Ended I/O Standards, page 24 for more information.
Input rise time	T_{ir}			1000	ns	Standard mode
				300	ns	Fast mode
Input fall time	T_{if}			300	ns	Standard mode
				300	ns	Fast mode
Maximum output voltage low (open drain) at 3 mA sink current for $V_{DDI} > 2\text{ V}$	V_{OL}			0.4	V	See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Pin capacitance	C_{in}			10	pF	$V_{IN} = 0$, $f = 1.0\text{ MHz}$
Output fall time from V_{IHMin} to V_{ILMax}^1	t_{OF}^1		21.04		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 400\text{ pF}$
			5.556		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 100\text{ pF}$
Output rise time from V_{ILMax} to V_{IHMin}^1	t_{OR}^1		19.887		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 400\text{ pF}$
			5.218		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 100\text{ pF}$
Output buffer maximum pull-down resistance ^{2, 3}	$R_{pull-up}^{2,3}$			50	Ω	
Output buffer maximum pull-up resistance ^{2, 4}	$R_{pull-down}^{2,4}$			131.25	Ω	

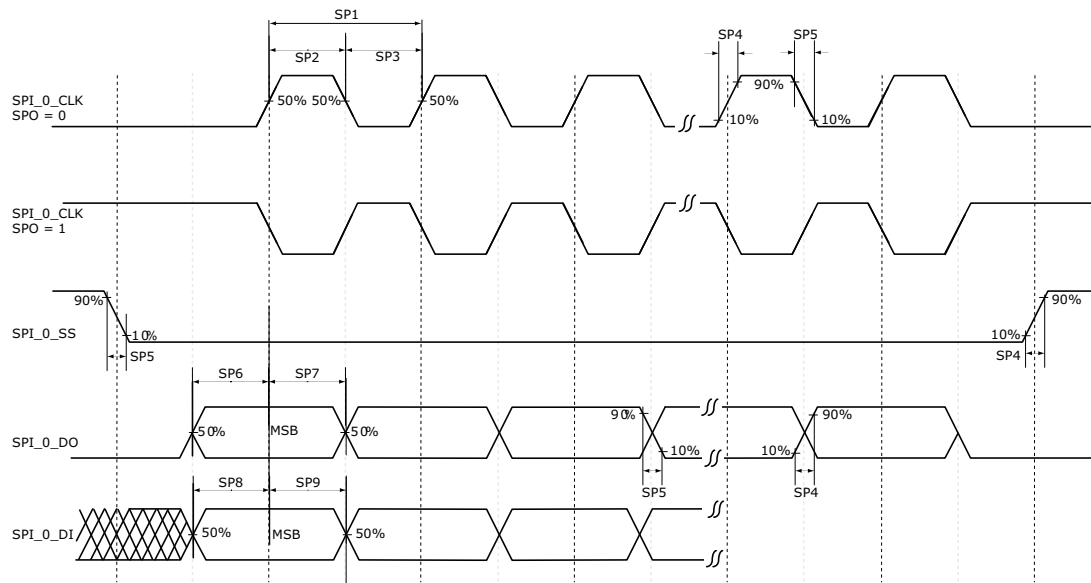
2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see Figure 22, page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

Figure 22 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)

2.3.32 CAN Controller Characteristics

The following table lists the CAN controller characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 306 • CAN Controller Characteristics

Parameter	Description	–1	–Std	Unit
FCANREFCLK ¹	Internally sourced CAN reference clock frequency	160	136	MHz
BAUDCANMAX	Maximum CAN performance baud rate	1	1	Mbps
BAUDCANMIN	Minimum CAN performance baud rate	0.05	0.05	Mbps

1. PCLK to CAN controller must be a multiple of 8 MHz.

2.3.33 USB Characteristics

The following table lists the USB characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 307 • USB Characteristics

Parameter	Description	–1	–Std	Unit
FUSBREFCLK	Internally sourced USB reference clock frequency	166	142	MHz
TUSBCLK	USB clock period	16.66	16.66	ns
TUSBPD	Clock to USB data propagation delay	9.0	9.0	ns
TUSBSU	Setup time for USB data	6.0	6.0	ns
TUSBHD	Hold time for USB data	0	0	ns