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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

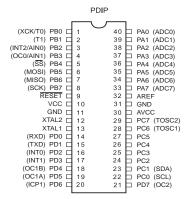
Applications of "<u>Embedded - Microcontrollers</u>"

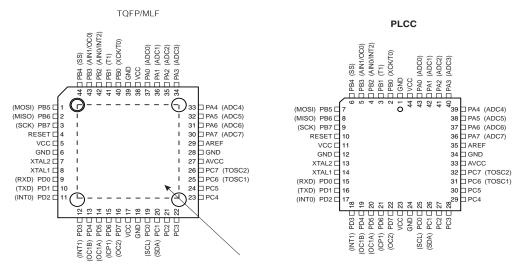
Details	
Product Status	Obsolete
Core Processor	AVR
Core Size	8-Bit
Speed	16MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	32
Program Memory Size	8KB (4K x 16)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atmega8535-16ac



### **Pin Configurations**

Figure 1. Pinout ATmega8535





NOTE: MLF Bottom pad should be soldered to ground.

### **Disclaimer**

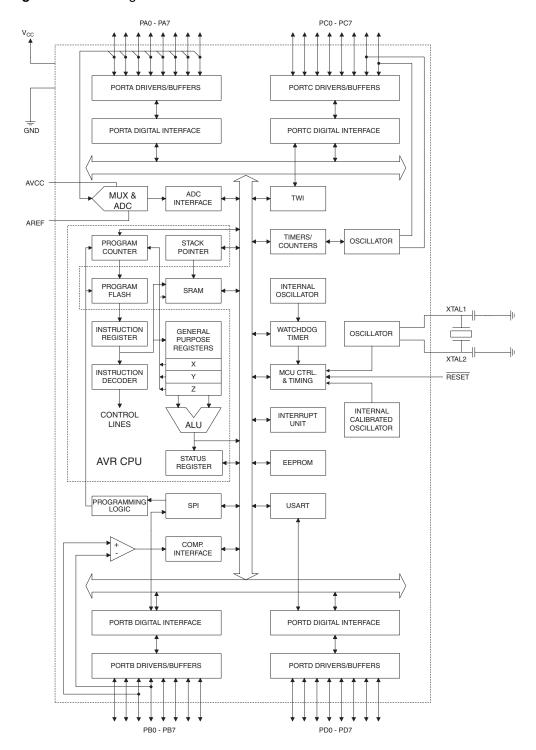
Typical values contained in this data sheet are based on simulations and characterization of other AVR microcontrollers manufactured on the same process technology. Min and Max values will be available after the device is characterized.

### **Overview**

The ATmega8535 is a low-power CMOS 8-bit microcontroller based on the AVR enhanced RISC architecture. By executing instructions in a single clock cycle, the ATmega8535 achieves throughputs approaching 1 MIPS per MHz allowing the system designer to optimize power consumption versus processing speed.

### **Block Diagram**

Figure 2. Block Diagram







The AVR core combines a rich instruction set with 32 general purpose working registers. All 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The ATmega8535 provides the following features: 8K bytes of In-System Programmable Flash with Read-While-Write capabilities, 512 bytes EEPROM, 512 bytes SRAM, 32 general purpose I/O lines, 32 general purpose working registers, three flexible Timer/Counters with compare modes, internal and external interrupts, a serial programmable USART, a byte oriented Two-wire Serial Interface, an 8-channel, 10-bit ADC with optional differential input stage with programmable gain in TQFP package, a programmable Watchdog Timer with Internal Oscillator, an SPI serial port, and six software selectable power saving modes. The Idle mode stops the CPU while allowing the SRAM, Timer/Counters, SPI port, and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next interrupt or Hardware Reset. In Power-save mode, the asynchronous timer continues to run, allowing the user to maintain a timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except asynchronous timer and ADC, to minimize switching noise during ADC conversions. In Standby mode, the crystal/resonator Oscillator is running while the rest of the device is sleeping. This allows very fast start-up combined with low-power consumption. In Extended Standby mode, both the main Oscillator and the asynchronous timer continue to run.

The device is manufactured using Atmel's high density nonvolatile memory technology. The On-chip ISP Flash allows the program memory to be reprogrammed In-System through an SPI serial interface, by a conventional nonvolatile memory programmer, or by an On-chip Boot program running on the AVR core. The boot program can use any interface to download the application program in the Application Flash memory. Software in the Boot Flash section will continue to run while the Application Flash section is updated, providing true Read-While-Write operation. By combining an 8-bit RISC CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel ATmega8535 is a powerful microcontroller that provides a highly flexible and cost effective solution to many embedded control applications.

The ATmega8535 AVR is supported with a full suite of program and system development tools including: C compilers, macro assemblers, program debugger/simulators, In-Circuit Emulators, and evaluation kits.

### AT90S8535 Compatibility

The ATmega8535 provides all the features of the AT90S8535. In addition, several new features are added. The ATmega8535 is backward compatible with AT90S8535 in most cases. However, some incompatibilities between the two microcontrollers exist. To solve this problem, an AT90S8535 compatibility mode can be selected by programming the S8535C fuse. ATmega8535 is pin compatible with AT90S8535, and can replace the AT90S8535 on current Printed Circuit Boards. However, the location of fuse bits and the electrical characteristics differs between the two devices.

## AT90S8535 Compatibility Mode

Programming the S8535C fuse will change the following functionality:

- The timed sequence for changing the Watchdog Time-out period is disabled. See "Timed Sequences for Changing the Configuration of the Watchdog Timer" on page 45 for details.
- The double buffering of the USART Receive Register is disabled. See "AVR USART vs. AVR UART Compatibility" on page 146 for details.

### **Pin Descriptions**

**V**<sub>CC</sub> Digital supply voltage.

GND Ground.

Port A (PA7..PA0) Port A serves as the analog inputs to the A/D Converter.

Port A also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. When pins PA0 to PA7 are used as inputs and are externally pulled low, they will source current if the internal pull-up resistors are activated. The Port A pins are tri-stated when

a reset condition becomes active, even if the clock is not running.

Port B (PB7..PB0)

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port B also serves the functions of various special features of the ATmega8535 as listed

on page 60.

Port C (PC7..PC0)

Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset

condition becomes active, even if the clock is not running.

Port D (PD7..PD0) Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each

bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset

condition becomes active, even if the clock is not running.

Port D also serves the functions of various special features of the ATmega8535 as listed

on page 64.

RESET Reset input. A low level on this pin for longer than the minimum pulse length will gener-

ate a reset, even if the clock is not running. The minimum pulse length is given in Table

15 on page 37. Shorter pulses are not guaranteed to generate a reset.

**XTAL1** Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.

**XTAL2** Output from the inverting Oscillator amplifier.

AVCC is the supply voltage pin for Port A and the A/D Converter. It should be externally

connected to  $V_{CC}$ , even if the ADC is not used. If the ADC is used, it should be con-

nected to V<sub>CC</sub> through a low-pass filter.

AREF is the analog reference pin for the A/D Converter.





### **Resources**

A comprehensive set of development tools, application notes and datasheets are available for download on http://www.atmel.com/avr.

## **About Code Examples**

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C Compiler documentation for more details.





## **Register Summary**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page	
0x3F (0x5F)	SREG	I	Т	Н	S	V	N	Z	С	10	
0x3E (0x5E)	SPH	-	-	-	-	-	-	SP9	SP8	12	
0x3D (0x5D)	SPL	SP7	SP6	SP5	SP4	SP3	SP2	SP1	SP0	12	
0x3C (0x5C)	OCR0		•	Tir	mer/Counter0 Ou	tput Compare Re	gister	T	1	85	
0x3B (0x5B)	GICR	INT1	INT0	INT2	-	-	-	IVSEL	IVCE	49, 69	
0x3A (0x5A)	GIFR	INTF1	INTF0	INTF2	-	-	-	-	-	70	
0x39 (0x59)	TIMSK	OCIE2	TOIE2	TICIE1	OCIE1A	OCIE1B	TOIE1	OCIE0	TOIE0	85, 115, 133	
0x38 (0x58)	TIFR	OCF2	TOV2	ICF1	OCF1A	OCF1B	TOV1	OCF0	TOV0	86, 116, 134	
0x37 (0x57)	SPMCR	SPMIE	RWWSB	-	RWWSRE	BLBSET	PGWRT	PGERS	SPMEN	228	
0x36 (0x56)	TWCR	TWINT	TWEA	TWSTA	TWSTO	TWWC	TWEN	-	TWIE	181	
0x35 (0x55) 0x34 (0x54)	MCUCR	SM2	SE ISC2	SM1	SM0	ISC11	ISC10	ISC01	ISC00	32, 68	
0x34 (0x54) 0x33 (0x53)	MCUCSR TCCR0	FOC0	WGM00	COM01	COM00	WDRF WGM01	BORF CS02	EXTRF CS01	PORF CS00	40, 69 83	
0x32 (0x52)	TCNT0	1000	Walvioo	COMOT		inter0 (8 Bits)	0302	0301	0300	85	
0x31 (0x51)	OSCCAL					ibration Register				30	
0x30 (0x50)	SFIOR	ADTS2	ADTS1	ADTS0	-	ACME	PUD	PSR2	PSR10	59,88,135,203,223	
0x2F (0x4F)	TCCR1A	COM1A1	COM1A0	COM1B1	COM1B0	FOC1A	FOC1B	WGM11	WGM10	110	
0x2E (0x4E)	TCCR1B	ICNC1	ICES1	_	WGM13	WGM12	CS12	CS11	CS10	113	
0x2D (0x4D)	TCNT1H		•	Time	er/Counter1 – Co		gh Byte		•	114	
0x2C (0x4C)	TCNT1L			Tim	er/Counter1 – Co	unter Register Lo	w Byte			114	
0x2B (0x4B)	OCR1AH				unter1 – Output C		•			114	
0x2A (0x4A)	OCR1AL			Timer/Co	unter1 – Output 0	Compare Register	A Low Byte			114	
0x29 (0x49)	OCR1BH			Timer/Co	unter1 – Output C	Compare Register	B High Byte			114	
0x28 (0x48)	OCR1BL			Timer/Co	unter1 – Output 0	Compare Register	r B Low Byte			114	
0x27 (0x47)	ICR1H			Timer/0	Counter1 - Input	Capture Register	High Byte			114	
0x26 (0x46)	ICR1L			Timer/	Counter1 - Input	Capture Register	Low Byte			114	
0x25 (0x45)	TCCR2	FOC2	WGM20	COM21	COM20	WGM21	CS22	CS21	CS20	128	
0x24 (0x44)	TCNT2		Timer/Counter2 (8 Bits)				130				
0x23 (0x43)	OCR2			Tiı	mer/Counter2 Ou		ĭ	1	1	131	
0x22 (0x42)	ASSR	-	-	-		AS2	TCN2UB	OCR2UB	TCR2UB	131	
0x21 (0x41)	WDTCR	-	-	_	WDCE	WDE	WDP2	WDP1	WDP0	42	
0x20 <sup>(1)</sup> (0x40) <sup>(1)</sup>	UBRRH	URSEL	-	UPM1	UPM0	LIODO		R[11:8]	LIOPOL	169 167	
0x1F (0x3F)	EEARH	URSEL -	UMSEL -	— — — — — — — — — — — — — — — — — — —	UPIVIU	USBS	UCSZ1	UCSZ0	UCPOL EEAR8	19	
0x1E (0x3E)	EEARL	_			EEPROM Addres	s Register Low B	•	_	LLANO	19	
0x1D (0x3D)	EEDR					Data Register	yte			19	
0x1C (0x3C)	EECR	_	_	_	-	EERIE	EEMWE	EEWE	EERE	19	
0x1B (0x3B)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	66	
0x1A (0x3A)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	66	
0x19 (0x39)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	66	
0x18 (0x38)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	66	
0x17 (0x37)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	66	
0x16 (0x36)	PINB	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	67	
0x15 (0x35)	PORTC	PORTC7	PORTC6	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	67	
0x14 (0x34)	DDRC	DDC7	DDC6	DDC5	DDC4	DDC3	DDC2	DDC1	DDC0	67	
0x13 (0x33)	PINC	PINC7	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	67	
0x12 (0x32)	PORTD	PORTD7	PORTD6	PORTD5	PORTD4	PORTD3	PORTD2	PORTD1	PORTD0	67	
0x11 (0x31)	DDRD	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	67	
0x10 (0x30)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	67	
0x0F (0x2F)	SPDR	OPIE	WCC.			ta Register			OPIOV	143	
0x0E (0x2E)	SPSR	SPIF	WCOL	-	- MCTD	-	- CPUA	-	SPI2X	143	
0x0D (0x2D) 0x0C (0x2C)	SPCR	SPIE	SPE	DORD	MSTR USART I/O	CPOL Data Register	CPHA	SPR1	SPR0	141	
0x0C (0x2C) 0x0B (0x2B)	UDR UCSRA	RXC	TXC	UDRE	FE USART I/O	Data Register DOR	PE	U2X	MPCM	164 165	
0x0B (0x2B) 0x0A (0x2A)	UCSRB	RXCIE	TXCIE	UDRIE	RXEN	TXEN	UCSZ2	RXB8	TXB8	166	
0x0A (0x2A) 0x09 (0x29)	UBRRL	INVIE	IAUE	li .		te Register Low E		HAD0	1700	169	
0x08 (0x28)	ACSR	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	203	
	ADMUX	REFS1	REFS0	ADLAR	MUX4	MUX3	MUX2	MUX1	MUX0	219	
()x()7 (0x27)			ADSC	ADATE	ADIF	ADIE	ADPS2	ADPS1	ADPS0	221	
0x07 (0x27) 0x06 (0x26)		ADEN									
0x06 (0x26)	ADCSRA	ADEN	•		ADC Data Re	ADC Data Register High Byte  ADC Data Register Low Byte					
` '		ADEN								222 222	
0x06 (0x26) 0x05 (0x25)	ADCSRA ADCH	ADEN		T		egister Low Byte	ister				
0x06 (0x26) 0x05 (0x25) 0x04 (0x24)	ADCSRA ADCH ADCL	TWA6	TWA5	TWA4	ADC Data Re	egister Low Byte	ister TWA1	TWA0	TWGCE	222	

## **Register Summary (Continued)**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
0x00 (0x20)	0x00 (0x20) TWBR Two-wire Serial Interface Bit Rate Register					181				

Notes:

- 1. Refer to the USART description for details on how to access UBRRH and UCSRC.
- 2. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.
- 3. Some of the status flags are cleared by writing a logical one to them. Note that the CBI and SBI instructions will operate on all bits in the I/O Register, writing a one back into any flag read as set, thus clearing the flag. The CBI and SBI instructions work with registers 0x00 to 0x1F only.



Mnemonics	Operands	Description	Operation	Flags	#Clocks
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	Rd+1:Rd ← Rr+1:Rr	None	1
LDI	Rd, K	Load Immediate	Rd ← K	None	1
LD	Rd, X	Load Indirect	$Rd \leftarrow (X)$	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	$Rd \leftarrow (X), X \leftarrow X + 1$	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	$X \leftarrow X - 1$ , Rd $\leftarrow (X)$	None	2
LD	Rd, Y	Load Indirect	$Rd \leftarrow (Y)$	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	$Rd \leftarrow (Y), Y \leftarrow Y + 1$	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	$Y \leftarrow Y - 1$ , $Rd \leftarrow (Y)$	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	$Rd \leftarrow (Y + q)$	None	2
LD	Rd, Z	Load Indirect	$Rd \leftarrow (Z)$	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	$Z \leftarrow Z - 1$ , $Rd \leftarrow (Z)$	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	$Rd \leftarrow (Z + q)$	None	2
LDS	Rd, k	Load Direct from SRAM	Rd ← (k)	None	2
ST	X, Rr	Store Indirect	(X) ← Rr	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	$(X) \leftarrow Rr, X \leftarrow X + 1$	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	$X \leftarrow X - 1, (X) \leftarrow Rr$	None	2
ST	Y, Rr	Store Indirect	(Y) ← Rr	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	$(Y) \leftarrow Rr, Y \leftarrow Y + 1$	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	$Y \leftarrow Y - 1, (Y) \leftarrow Rr$	None	2
STD	Y+q,Rr	Store Indirect with Displacement	(Y + q) ← Rr	None	2
	Z, Rr	Store Indirect	(Z) ← Rr	None	<b>†</b>
ST ST	Z+, Rr -Z, Rr	Store Indirect and Post-Inc. Store Indirect and Pre-Dec.	$(Z) \leftarrow Rr, Z \leftarrow Z + 1$	None	2
STD	Z+q,Rr	Store Indirect with Displacement	$Z \leftarrow Z - 1$ , $(Z) \leftarrow Rr$ $(Z + q) \leftarrow Rr$	None None	2
STS	k, Rr	Store Direct to SRAM	$(k) \leftarrow Rr$	None	2
LPM	K, NI	Load Program Memory	$R0 \leftarrow (Z)$	None	3
LPM	Rd, Z	Load Program Memory	$Rd \leftarrow (Z)$	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	3
SPM	riu, Z+	Store Program Memory	(Z) ← R1:R0	None	-
IN	Rd, P	In Port	Rd ← P	None	1
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	Rd ← STACK	None	2
BIT AND BIT-TEST	INSTRUCTIONS				
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	I/O(P,b) ← 0	None	2
LSL	Rd	Logical Shift Left	$Rd(n+1) \leftarrow Rd(n), Rd(0) \leftarrow 0$	Z,C,N,V	1
LSR	Rd	Logical Shift Right	$Rd(n) \leftarrow Rd(n+1), Rd(7) \leftarrow 0$	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	$Rd(0)\leftarrow C,Rd(n+1)\leftarrow Rd(n),C\leftarrow Rd(7)$	Z,C,N,V	1
ROR	Rd	Rotate Right Through Carry	$Rd(7)\leftarrow C,Rd(n)\leftarrow Rd(n+1),C\leftarrow Rd(0)$	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	$Rd(n) \leftarrow Rd(n+1), n=06$	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(30)←Rd(74),Rd(74)←Rd(30)	None	1
BSET	s	Flag Set	SREG(s) ← 1	SREG(s)	1
BCLR	S	Flag Clear	SREG(s) ← 0	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	$T \leftarrow Rr(b)$	Т	1
BLD	Rd, b	Bit load from T to Register	$Rd(b) \leftarrow T$	None	1
SEC	-	Set Carry	C ← 1	С	1
CLC	-	Clear Carry	C ← 0	С	1
SEN	1	Set Negative Flag	N ← 1	N	1
CLN	1	Clear Negative Flag	N ← 0	N	1
SEZ	ļ	Set Zero Flag	Z ← 1	Z	1
CLZ	1	Clear Zero Flag	Z ← 0	Z	1
SEI	1	Global Interrupt Enable	1←1	1	1
CLI	1	Global Interrupt Disable	1←0	ı	1
SES	1	Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV	1	Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET	1	Set T in SREG	T ← 1	T	1
CLT	1	Clear T in SREG	T ← 0	T	1
SEH	1	Set Half Carry Flag in SREG	H ← 1	H	1
CLH	TDUOTIONO	Clear Half Carry Flag in SREG	H ← 0	Н	1
MCU CONTROL INS	INUCTIONS	Lu o ii	T	T	
NOP		No Operation		None	1





Mnemonics	Operands	Description	Operation	Flags	#Clocks
SLEEP		Sleep	(see specific descr. for Sleep function)	None	1
WDR		Watchdog Reset	(see specific descr. for WDR/Timer)	None	1
BREAK		Break	For On-chip Debug Only	None	N/A

## **Ordering Information**

Speed (MHz)	Power Supply	Ordering Code	Package <sup>(1)</sup>	Operation Range
		ATmega8535L-8AC	44A	
		ATmega8535L-8PC	40P6	Commercial
		ATmega8535L-8JC	44J	(0°C to 70°C)
		ATmega8535L-8MC	44M1	
		ATmega8535L-8AI	44A	
Q.	2.7 - 5.5V	ATmega8535L-8PI	40P6	
8	Z.7 - 3.5 V	ATmega8535L-8JI	44J	
		ATmega8535L-8MI	44M1	Industrial
		ATmega8535L-8AU <sup>(2)</sup>	44A	(-40°C to 85°C)
		ATmega8535L-8PU <sup>(2)</sup>	40P6	
		ATmega8535L-8JU <sup>(2)</sup>	44J	
		ATmega8535L-8MU <sup>(2)</sup>	44M1	
		ATmega8535-16AC	44A	
		ATmega8535-16PC	40P6	Commercial
		ATmega8535-16JC	44J	(0°C to 70°C)
		ATmega8535-16MC	44M1	
		ATmega8535-16AI	44A	
16	4.5 - 5.5V	ATmega8535-16PI	40P6	
16	4.5 - 5.5 v	ATmega8535-16JI	44J	
		ATmega8535-16MI	44M1	Industrial
		ATmega8535-16AU <sup>(2)</sup>	44A	(-40°C to 85°C)
		ATmega8535-16PU <sup>(2)</sup>	40P6	
		ATmega8535-16JU <sup>(2)</sup>	44J	
		ATmega8535-16MU <sup>(2)</sup>	44M1	

Note:

- 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities..
- 2. Pb-free packaging alternative, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

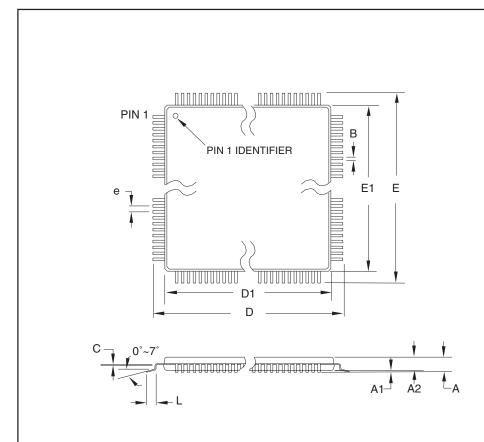
	Package Type					
44 <b>A</b>	44-lead, Thin (1.0 mm) Plastic Gull Wing Quad Flat Package (TQFP)					
40P6	40-pin, 0.600" Wide, Plastic Dual Inline Package (PDIP)					
44J	44-lead, Plastic J-leaded Chip Carrier (PLCC)					
44M1-A	44-pad, 7 x 7 x 1.0 mm body, lead pitch 0.50 mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)					





## **Packaging Information**

### 44A



## **COMMON DIMENSIONS**

(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
Α	_	_	1.20	
A1	0.05	_	0.15	
A2	0.95	1.00	1.05	
D	11.75	12.00	12.25	
D1	9.90	10.00	10.10	Note 2
Е	11.75	12.00	12.25	
E1	9.90	10.00	10.10	Note 2
В	0.30	_	0.45	
С	0.09	_	0.20	
L	0.45	_	0.75	
е		0.80 TYP		

Notes:

- 1. This package conforms to JEDEC reference MS-026, Variation ACB.
- 2. Dimensions D1 and E1 do not include mold protrusion. Allowable protrusion is 0.25 mm per side. Dimensions D1 and E1 are maximum plastic body size dimensions including mold mismatch.

TITLE

3. Lead coplanarity is 0.10 mm maximum.

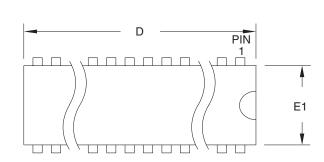
10/5/2001

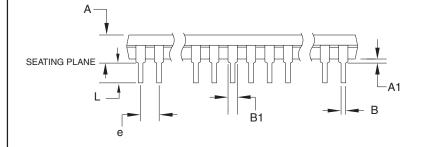
4mei	2325 Orchard	Parkway
	2325 Orchard San Jose, CA	95131

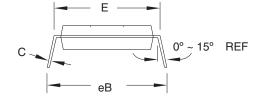
44A, 44-lead, 10 x 10 mm Body Size, 1.0 mm Body Thickness,
0.8 mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)

DRAWING NO.	REV.
44A	В

### 40P6







Notes:

- 1. This package conforms to JEDEC reference MS-011, Variation AC.
- Dimensions D and E1 do not include mold Flash or Protrusion. Mold Flash or Protrusion shall not exceed 0.25 mm (0.010").

### **COMMON DIMENSIONS**

(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
А	_	_	4.826	
A1	0.381	_	_	
D	52.070	_	52.578	Note 2
Е	15.240	_	15.875	
E1	13.462	_	13.970	Note 2
В	0.356	_	0.559	
B1	1.041	_	1.651	
L	3.048	_	3.556	
С	0.203	_	0.381	
eB	15.494	_	17.526	
е		2.540 TYP	)	

09/28/01

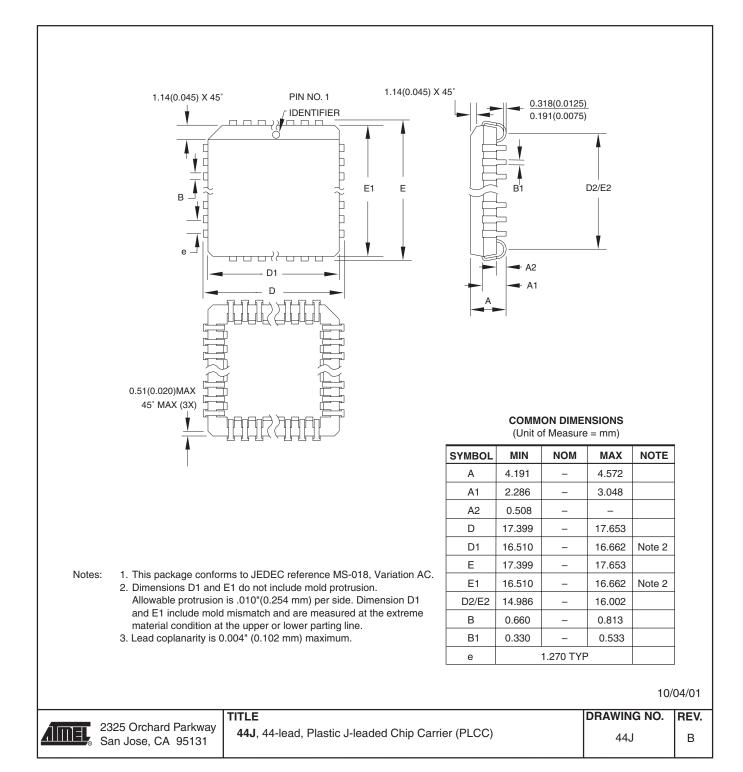
1	_			
1	A			
1.4		ш		
IÆ	oxdot	ш		
			(6	•

2325 Orchard Parkway San Jose, CA 95131 TITLE
40P6, 40-lead (0.600"/15.24 mm Wide) Plastic Dual Inline Package (PDIP)

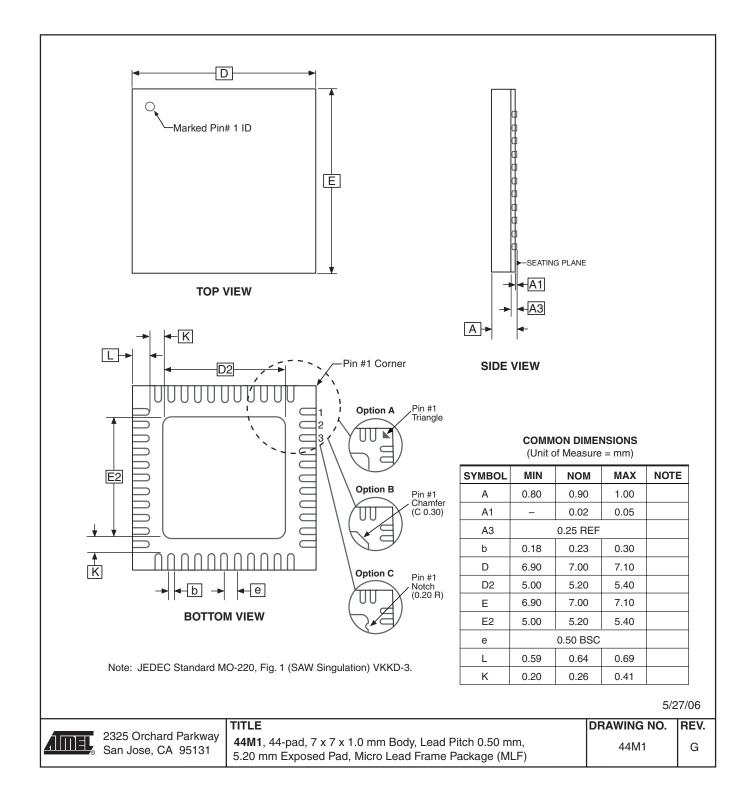
DRAWING NO. REV. 40P6 B



### 44J



### 44M1-A







### **Errata**

The revision letter refer to the device revision.

### ATmega8535 Rev. A and B

- First Analog Comparator conversion may be delayed
- Asynchronous Oscillator does not stop in Power-down

### 1. First Analog Comparator conversion may be delayed

If the device is powered by a slow rising  $V_{\text{CC}}$ , the first Analog Comparator conversion will take longer than expected on some devices.

### **Problem Fix/Workaround**

When the device has been powered or reset, disable then enable the Analog Comparator before the first conversion.

### 2. Asynchronous Oscillator does not stop in Power-down

The asynchronous oscillator does not stop when entering Power-down mode. This leads to higher power consumption than expected.

### Problem Fix/Workaround

Manually disable the asynchronous timer before entering Power-down.

## **Datasheet Revision History**

Please note that the referring page numbers in this section are referring to this document. The referring revision in this section are referring to the document revision.

# Changes from Rev. 2502J- 08/06 to Rev. 2502K- 10/06

- 1. Updated TOP/BOTTOM description for all Timer/Counters Fast PWM mode.
- 2. Updated "Errata" on page 18.

# Changes from Rev. 2502I- 06/06 to Rev. 2502J- 08/06

1. Updated "Ordering Information" on page 13.

# Changes from Rev. 2502H- 04/06 to Rev. 2502I- 06/06

1. Updated code example "USART Initialization" on page 150.

# Changes from Rev. 2502G- 04/05 to Rev. 2502H- 04/06

- 1. Added "Resources" on page 6.
- 2. Updated Table 7 on page 29, Table 17 on page 42 and Table 111 on page 258.
- 3. Updated "Serial Peripheral Interface SPI" on page 136.
- 4. Updated note in "Bit Rate Generator Unit" on page 180.

# Changes from Rev. 2502F- 06/04 to Rev. 2502G- 04/05

- 1. Removed "Preliminary" and TBD's.
- 2. Updated Table 37 on page 69 and Table 113 on page 261.
- 3. Updated "Electrical Characteristics" on page 255.
- 4. Updated "Ordering Information" on page 13.

# Changes from Rev. 2502E-12/03 to Rev. 2502G-06/04

1. MLF-package alternative changed to "Quad Flat No-Lead/Micro Lead Frame Package QFN/MLF".

# Changes from Rev. 2502E-12/03 to Rev. 2502F-06/04

- 1. Updated "Reset Characteristics" on page 37.
- 2. Updated SPH in "Stack Pointer" on page 12.
- 3. Updated C code in "USART Initialization" on page 150.
- 4. Updated "Errata" on page 18.

# Changes from Rev. 2502D-09/03 to Rev. 2502E-12/03

- 1. Updated "Calibrated Internal RC Oscillator" on page 29.
- 2. Added section "Errata" on page 18.





# Changes from Rev. 2502C-04/03 to Rev. 2502D-09/03

- 1. Removed "Advance Information" and some TBD's from the datasheet.
- 2. Added note to "Pinout ATmega8535" on page 2.
- 3. Updated "Reset Characteristics" on page 37.
- 4. Updated "Absolute Maximum Ratings" and "DC Characteristics" in "Electrical Characteristics" on page 255.
- 5. Updated Table 111 on page 258.
- 6. Updated "ADC Characteristics" on page 263.
- 7. Updated "ATmega8535 Typical Characteristics" on page 266.
- 8. Removed CALL and JMP instructions from code examples and "Instruction Set Summary" on page 10.

## Changes from Rev. 2502B-09/02 to Rev. 2502C-04/03

- 1. Updated "Packaging Information" on page 14.
- 2. Updated Figure 1 on page 2, Figure 84 on page 179, Figure 85 on page 185, Figure 87 on page 191, Figure 98 on page 207.
- 3. Added the section "EEPROM Write During Power-down Sleep Mode" on page 22.
- 4. Removed the references to the application notes "Multi-purpose Oscillator" and "32 kHz Crystal Oscillator", which do not exist.
- 5. Updated code examples on page 44.
- 6. Removed ADHSM bit.
- 7. Renamed Port D pin ICP to ICP1. See "Alternate Functions of Port D" on page 64.
- 8. Added information about PWM symmetry for Timer 0 on page 79 and Timer 2 on page 126.
- 9. Updated Table 68 on page 169, Table 75 on page 190, Table 76 on page 193, Table 77 on page 196, Table 108 on page 253, Table 113 on page 261.
- 10. Updated description on "Bit 5 TWSTA: TWI START Condition Bit" on page 182.
- 11. Updated the description in "Filling the Temporary Buffer (Page Loading)" and "Performing a Page Write" on page 231.
- 12. Removed the section description in "SPI Serial Programming Characteristics" on page 254.
- 13. Updated "Electrical Characteristics" on page 255.

- 14. Updated "ADC Characteristics" on page 263.
- 14. Updated "Register Summary" on page 8.
- 15. Various Timer 1 corrections.
- 16. Added WD\_FUSE period in Table 108 on page 253.

Changes from Rev. 2502A-06/02 to Rev. 2502B-09/02

1. Canged the Endurance on the Flash to 10,000 Write/Erase Cycles.





### **Atmel Corporation**

2325 Orchard Parkway San Jose, CA 95131, USA Tel: 1(408) 441-0311

Fax: 1(408) 487-2600

### **Regional Headquarters**

### Europe

Atmel Sarl Route des Arsenaux 41 Case Postale 80 CH-1705 Fribourg Switzerland

Tel: (41) 26-426-5555 Fax: (41) 26-426-5500

### Asia

Room 1219 Chinachem Golden Plaza 77 Mody Road Tsimshatsui East Kowloon Hong Kong

Tel: (852) 2721-9778 Fax: (852) 2722-1369

### Japan

9F, Tonetsu Shinkawa Bldg. 1-24-8 Shinkawa Chuo-ku, Tokyo 104-0033 Japan

Tel: (81) 3-3523-3551 Fax: (81) 3-3523-7581

### **Atmel Operations**

### Memory

2325 Orchard Parkway San Jose, CA 95131, USA Tel: 1(408) 441-0311 Fax: 1(408) 436-4314

### Microcontrollers

2325 Orchard Parkway San Jose, CA 95131, USA Tel: 1(408) 441-0311 Fax: 1(408) 436-4314

La Chantrerie BP 70602 44306 Nantes Cedex 3, France

Tel: (33) 2-40-18-18-18 Fax: (33) 2-40-18-19-60

### ASIC/ASSP/Smart Cards

Zone Industrielle 13106 Rousset Cedex, France Tel: (33) 4-42-53-60-00

Fax: (33) 4-42-53-60-01

1150 East Cheyenne Mtn. Blvd. Colorado Springs, CO 80906, USA

Tel: 1(719) 576-3300 Fax: 1(719) 540-1759

Scottish Enterprise Technology Park Maxwell Building East Kilbride G75 0QR, Scotland

Tel: (44) 1355-803-000 Fax: (44) 1355-242-743

#### RF/Automotive

Theresienstrasse 2 Postfach 3535 74025 Heilbronn, Germany Tel: (49) 71-31-67-0

Fax: (49) 71-31-67-2340

1150 East Cheyenne Mtn. Blvd. Colorado Springs, CO 80906, USA

Tel: 1(719) 576-3300 Fax: 1(719) 540-1759

### Biometrics/Imaging/Hi-Rel MPU/ High Speed Converters/RF Datacom

Avenue de Rochepleine

BP 123

38521 Saint-Egreve Cedex, France

Tel: (33) 4-76-58-30-00 Fax: (33) 4-76-58-34-80

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