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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

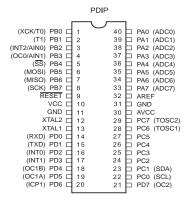
Applications of "<u>Embedded - Microcontrollers</u>"

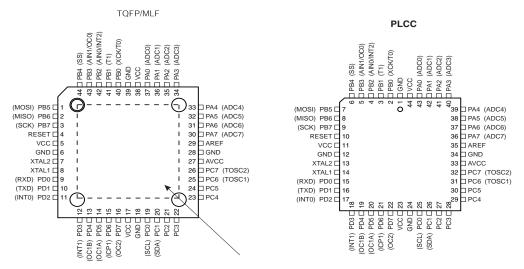
Details	
Product Status	Obsolete
Core Processor	AVR
Core Size	8-Bit
Speed	16MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	32
Program Memory Size	8KB (4K x 16)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VFQFN Exposed Pad
Supplier Device Package	44-VQFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atmega8535-16mc



### **Pin Configurations**

Figure 1. Pinout ATmega8535





NOTE: MLF Bottom pad should be soldered to ground.

### **Disclaimer**

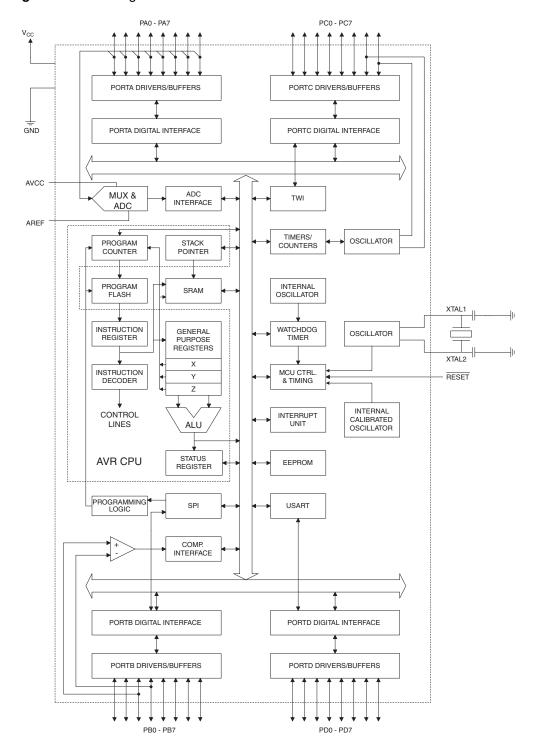
Typical values contained in this data sheet are based on simulations and characterization of other AVR microcontrollers manufactured on the same process technology. Min and Max values will be available after the device is characterized.

### **Overview**

The ATmega8535 is a low-power CMOS 8-bit microcontroller based on the AVR enhanced RISC architecture. By executing instructions in a single clock cycle, the ATmega8535 achieves throughputs approaching 1 MIPS per MHz allowing the system designer to optimize power consumption versus processing speed.

### **Block Diagram**

Figure 2. Block Diagram







The AVR core combines a rich instruction set with 32 general purpose working registers. All 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The ATmega8535 provides the following features: 8K bytes of In-System Programmable Flash with Read-While-Write capabilities, 512 bytes EEPROM, 512 bytes SRAM, 32 general purpose I/O lines, 32 general purpose working registers, three flexible Timer/Counters with compare modes, internal and external interrupts, a serial programmable USART, a byte oriented Two-wire Serial Interface, an 8-channel, 10-bit ADC with optional differential input stage with programmable gain in TQFP package, a programmable Watchdog Timer with Internal Oscillator, an SPI serial port, and six software selectable power saving modes. The Idle mode stops the CPU while allowing the SRAM, Timer/Counters, SPI port, and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next interrupt or Hardware Reset. In Power-save mode, the asynchronous timer continues to run, allowing the user to maintain a timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except asynchronous timer and ADC, to minimize switching noise during ADC conversions. In Standby mode, the crystal/resonator Oscillator is running while the rest of the device is sleeping. This allows very fast start-up combined with low-power consumption. In Extended Standby mode, both the main Oscillator and the asynchronous timer continue to run.

The device is manufactured using Atmel's high density nonvolatile memory technology. The On-chip ISP Flash allows the program memory to be reprogrammed In-System through an SPI serial interface, by a conventional nonvolatile memory programmer, or by an On-chip Boot program running on the AVR core. The boot program can use any interface to download the application program in the Application Flash memory. Software in the Boot Flash section will continue to run while the Application Flash section is updated, providing true Read-While-Write operation. By combining an 8-bit RISC CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel ATmega8535 is a powerful microcontroller that provides a highly flexible and cost effective solution to many embedded control applications.

The ATmega8535 AVR is supported with a full suite of program and system development tools including: C compilers, macro assemblers, program debugger/simulators, In-Circuit Emulators, and evaluation kits.

### AT90S8535 Compatibility

The ATmega8535 provides all the features of the AT90S8535. In addition, several new features are added. The ATmega8535 is backward compatible with AT90S8535 in most cases. However, some incompatibilities between the two microcontrollers exist. To solve this problem, an AT90S8535 compatibility mode can be selected by programming the S8535C fuse. ATmega8535 is pin compatible with AT90S8535, and can replace the AT90S8535 on current Printed Circuit Boards. However, the location of fuse bits and the electrical characteristics differs between the two devices.

## AT90S8535 Compatibility Mode

Programming the S8535C fuse will change the following functionality:

- The timed sequence for changing the Watchdog Time-out period is disabled. See "Timed Sequences for Changing the Configuration of the Watchdog Timer" on page 45 for details.
- The double buffering of the USART Receive Register is disabled. See "AVR USART vs. AVR UART Compatibility" on page 146 for details.

### **Pin Descriptions**

**V**<sub>CC</sub> Digital supply voltage.

GND Ground.

Port A (PA7..PA0) Port A serves as the analog inputs to the A/D Converter.

Port A also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. When pins PA0 to PA7 are used as inputs and are externally pulled low, they will source current if the internal pull-up resistors are activated. The Port A pins are tri-stated when

a reset condition becomes active, even if the clock is not running.

Port B (PB7..PB0)

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port B also serves the functions of various special features of the ATmega8535 as listed

on page 60.

Port C (PC7..PC0)

Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset

condition becomes active, even if the clock is not running.

Port D (PD7..PD0) Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each

bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset

condition becomes active, even if the clock is not running.

Port D also serves the functions of various special features of the ATmega8535 as listed

on page 64.

RESET Reset input. A low level on this pin for longer than the minimum pulse length will gener-

ate a reset, even if the clock is not running. The minimum pulse length is given in Table

15 on page 37. Shorter pulses are not guaranteed to generate a reset.

**XTAL1** Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.

**XTAL2** Output from the inverting Oscillator amplifier.

AVCC is the supply voltage pin for Port A and the A/D Converter. It should be externally

connected to  $V_{CC}$ , even if the ADC is not used. If the ADC is used, it should be con-

nected to V<sub>CC</sub> through a low-pass filter.

AREF is the analog reference pin for the A/D Converter.



## **About Code Examples**

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C Compiler documentation for more details.





## **Register Summary**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
0x3F (0x5F)	SREG	I	Т	Н	S	V	N	Z	С	10
0x3E (0x5E)	SPH	-	-	-	-	-	-	SP9	SP8	12
0x3D (0x5D)	SPL	SP7	SP6	SP5	SP4	SP3	SP2	SP1	SP0	12
0x3C (0x5C)	OCR0		•	Ti	mer/Counter0 Ou	tput Compare Re	gister	T	1	85
0x3B (0x5B)	GICR	INT1	INT0	INT2	-	-	-	IVSEL	IVCE	49, 69
0x3A (0x5A)	GIFR	INTF1	INTF0	INTF2	-	-	-	-	-	70
0x39 (0x59)	TIMSK	OCIE2	TOIE2	TICIE1	OCIE1A	OCIE1B	TOIE1	OCIE0	TOIE0	85, 115, 133
0x38 (0x58)	TIFR	OCF2	TOV2	ICF1	OCF1A	OCF1B	TOV1	OCF0	TOV0	86, 116, 134
0x37 (0x57)	SPMCR	SPMIE	RWWSB		RWWSRE	BLBSET	PGWRT	PGERS	SPMEN	228
0x36 (0x56)	TWCR	TWINT	TWEA	TWSTA	TWSTO	TWWC	TWEN	-	TWIE	181
0x35 (0x55) 0x34 (0x54)	MCUCR MCUCSR	SM2	SE ISC2	SM1	SM0	ISC11 WDRF	ISC10 BORF	ISC01	ISC00 PORF	32, 68 40, 69
0x34 (0x54) 0x33 (0x53)	TCCR0	FOC0	WGM00	COM01	COM00	WGM01	CS02	EXTRF CS01	CS00	40, 69 83
0x32 (0x52)	TCNT0	1000	Walvioo	COMOT		inter0 (8 Bits)	0302	0301	0300	85
0x31 (0x51)	OSCCAL					ibration Register				30
0x30 (0x50)	SFIOR	ADTS2	ADTS1	ADTS0	-	ACME	PUD	PSR2	PSR10	59,88,135,203,223
0x2F (0x4F)	TCCR1A	COM1A1	COM1A0	COM1B1	COM1B0	FOC1A	FOC1B	WGM11	WGM10	110
0x2E (0x4E)	TCCR1B	ICNC1	ICES1	_	WGM13	WGM12	CS12	CS11	CS10	113
0x2D (0x4D)	TCNT1H			Tim	er/Counter1 – Co		gh Byte		•	114
0x2C (0x4C)	TCNT1L				er/Counter1 – Co					114
0x2B (0x4B)	OCR1AH			Timer/Co	unter1 – Output C	Compare Register	A High Byte			114
0x2A (0x4A)	OCR1AL			Timer/Co	unter1 – Output 0	Compare Register	A Low Byte			114
0x29 (0x49)	OCR1BH			Timer/Co	unter1 – Output C	Compare Register	B High Byte			114
0x28 (0x48)	OCR1BL			Timer/Co	unter1 – Output 0	Compare Register	B Low Byte			114
0x27 (0x47)	ICR1H			Timer/	Counter1 - Input	Capture Register	High Byte			114
0x26 (0x46)	ICR1L			Timer/	Counter1 - Input	Capture Register	Low Byte			114
0x25 (0x45)	TCCR2	FOC2	WGM20	COM21	COM20	WGM21	CS22	CS21	CS20	128
0x24 (0x44)	TCNT2					inter2 (8 Bits)				130
0x23 (0x43)	OCR2			Ti	mer/Counter2 Ou		1	1	1	131
0x22 (0x42)	ASSR	-	-	-		AS2	TCN2UB	OCR2UB	TCR2UB	131
0x21 (0x41)	WDTCR	-	-	_	WDCE	WDE	WDP2	WDP1	WDP0	42
0x20 <sup>(1)</sup> (0x40) <sup>(1)</sup>	UBRRH	URSEL	-	UPM1	UPM0	LIODO		R[11:8]	LIOPOL	169 167
0x1F (0x3F)	EEARH	URSEL -	UMSEL -	— — — — — — — — — — — — — — — — — — —	UPIVIU	USBS	UCSZ1	UCSZ0	UCPOL EEAR8	19
0x1E (0x3E)	EEARL	_			EEPROM Addres	s Register Low B		_	LLANO	19
0x1D (0x3D)	EEDR					Data Register	yte			19
0x1C (0x3C)	EECR	_	_	_	-	EERIE	EEMWE	EEWE	EERE	19
0x1B (0x3B)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	66
0x1A (0x3A)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	66
0x19 (0x39)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	66
0x18 (0x38)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	66
0x17 (0x37)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	66
0x16 (0x36)	PINB	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	67
0x15 (0x35)	PORTC	PORTC7	PORTC6	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	67
0x14 (0x34)	DDRC	DDC7	DDC6	DDC5	DDC4	DDC3	DDC2	DDC1	DDC0	67
0x13 (0x33)	PINC	PINC7	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	67
0x12 (0x32)	PORTD	PORTD7	PORTD6	PORTD5	PORTD4	PORTD3	PORTD2	PORTD1	PORTD0	67
0x11 (0x31)	DDRD	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	67
0x10 (0x30)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	67
0x0F (0x2F)	SPDR		T .			ta Register			1	143
0x0E (0x2E)	SPSR	SPIF	WCOL	_		-	-	_	SPI2X	143
0x0D (0x2D)	SPCR	SPIE	SPE	DORD	MSTR	CPOL Parietan	CPHA	SPR1	SPR0	141
0x0C (0x2C)	UDR	DVC	T)/0	LIBBE		Data Register	l 5=	1101	MEGH	164
0x0B (0x2B)	UCSRA	RXC	TXC	UDRE	FE	DOR	PE LICEZO	U2X	MPCM	165
0x0A (0x2A) 0x09 (0x29)	UCSRB	RXCIE	TXCIE	UDRIE	RXEN	TXEN te Register Low E	UCSZ2	RXB8	TXB8	166
0x09 (0x29) 0x08 (0x28)	UBRRL ACSR	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	169 203
` '	ADMUX	REFS1	REFS0	ADLAR	MUX4	MUX3	MUX2	MUX1	MUX0	203
	ADIVIUA									219
0x07 (0x27)		ADEN ADSC ADATE ADIF ADIE ADPS2 ADPS1 ADPS0								
0x06 (0x26)	ADCSRA	ADEN			ADC Data Register High Byte					
0x06 (0x26) 0x05 (0x25)	ADCSRA ADCH	ADEN								222
0x06 (0x26) 0x05 (0x25) 0x04 (0x24)	ADCSRA ADCH ADCL	ADEN		1	ADC Data Re	egister Low Byte	ister			222
0x06 (0x26) 0x05 (0x25)	ADCSRA ADCH	TWA6	TWA5	TWA4		egister Low Byte	ister TWA1	TWA0	TWGCE	

### **Register Summary (Continued)**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
0x00 (0x20)	TWBR	Two-wire Serial Interface Bit Rate Register					181			

Notes:

- 1. Refer to the USART description for details on how to access UBRRH and UCSRC.
- 2. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.
- 3. Some of the status flags are cleared by writing a logical one to them. Note that the CBI and SBI instructions will operate on all bits in the I/O Register, writing a one back into any flag read as set, thus clearing the flag. The CBI and SBI instructions work with registers 0x00 to 0x1F only.





## **Instruction Set Summary**

Mnemonics	Operands	Description	Operation	Flags	#Clocks
ARITHMETIC AND	LOGIC INSTRUCTIO	NS	•	<u> </u>	· ·
ADD	Rd, Rr	Add two Registers	Rd ← Rd + Rr	Z,C,N,V,H	1
ADC	Rd, Rr	Add with Carry two Registers	$Rd \leftarrow Rd + Rr + C$	Z,C,N,V,H	1
ADIW	Rdl,K	Add Immediate to Word	Rdh:Rdl ← Rdh:Rdl + K	Z,C,N,V,S	2
SUB	Rd, Rr	Subtract two Registers	Rd ← Rd - Rr	Z,C,N,V,H	1
SUBI	Rd, K	Subtract Constant from Register	Rd ← Rd - K	Z,C,N,V,H	1
SBC	Rd, Rr	Subtract with Carry two Registers	Rd ← Rd - Rr - C	Z,C,N,V,H	1
SBCI	Rd, K	Subtract with Carry Constant from Reg.	Rd ← Rd - K - C	Z,C,N,V,H	1
SBIW	Rdl,K	Subtract Immediate from Word	Rdh:Rdl ← Rdh:Rdl - K	Z,C,N,V,S	2
AND	Rd, Rr	Logical AND Registers	Rd ← Rd • Rr	Z,N,V	1
ANDI	Rd, K	Logical AND Register and Constant	Rd ← Rd • K	Z,N,V	1
OR	Rd, Rr	Logical OR Registers	Rd ← Rd v Rr	Z,N,V	1
ORI	Rd, K	Logical OR Register and Constant	Rd ← Rd v K	Z,N,V	1
EOR	Rd, Rr	Exclusive OR Registers	$Rd \leftarrow Rd \oplus Rr$	Z,N,V	1
COM	Rd	One's Complement	$Rd \leftarrow 0xFF - Rd$	Z,C,N,V	1
NEG	Rd	Two's Complement	Rd ← 0x00 − Rd	Z,C,N,V,H	1
SBR	Rd,K	Set Bit(s) in Register	Rd ← Rd v K	Z,N,V	1
CBR	Rd,K	Clear Bit(s) in Register	Rd ← Rd • (0xFF - K)	Z,N,V	1
INC	Rd	Increment	Rd ← Rd + 1	Z,N,V	1
DEC	Rd	Decrement	Rd ← Rd – 1	Z,N,V	1
TST	Rd	Test for Zero or Minus	Rd ← Rd • Rd	Z,N,V	1
CLR	Rd	Clear Register	Rd ← Rd ⊕ Rd	Z,N,V	1
SER	Rd	Set Register	Rd ← 0xFF	None	1
MUL	Rd, Rr	Multiply Unsigned	R1:R0 ← Rd x Rr	Z,C	2
MULS	Rd, Rr	Multiply Signed	R1:R0 ← Rd x Rr	Z,C	2
MULSU	Rd, Rr	Multiply Signed with Unsigned	R1:R0 ← Rd x Rr	Z,C	2
FMUL	Rd, Rr	Fractional Multiply Unsigned	R1:R0 ← (Rd x Rr) << 1	Z,C	2
FMULS	Rd, Rr	Fractional Multiply Signed	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z,C	2
FMULSU	Rd, Rr	Fractional Multiply Signed with Unsigned	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z,C	2
BRANCH INSTRUC			· · · · · · · · · · · · · · · · · · ·		•
RJMP	k	Relative Jump	PC ← PC + k + 1	None	2
IJMP		Indirect Jump to (Z)	PC ← Z	None	2
RCALL	k	Relative Subroutine Call	PC ← PC + k + 1	None	3
ICALL		Indirect Call to (Z)	PC ← Z	None	3
RET		Subroutine Return	PC ← STACK	None	4
RETI		Interrupt Return	PC ← STACK	1	4
CPSE	Rd,Rr	Compare, Skip if Equal	if (Rd = Rr) PC ← PC + 2 or 3	None	1/2/3
СР	Rd,Rr	Compare	Rd – Rr	Z, N,V,C,H	1
CPC	Rd,Rr	Compare with Carry	Rd – Rr – C	Z, N,V,C,H	1
CPI	Rd,K	Compare Register with Immediate	Rd – K	Z, N,V,C,H	1
SBRC	Rr, b	Skip if Bit in Register Cleared	if (Rr(b)=0) PC ← PC + 2 or 3	None	1/2/3
SBRS	Rr, b	Skip if Bit in Register is Set	if (Rr(b)=1) PC ← PC + 2 or 3	None	1/2/3
SBIC	P, b	Skip if Bit in I/O Register Cleared	if $(P(b)=0)$ PC $\leftarrow$ PC + 2 or 3	None	1/2/3
SBIS	P, b	Skip if Bit in I/O Register is Set	if (P(b)=1) PC $\leftarrow$ PC + 2 or 3	None	1/2/3
BRBS	s, k	Branch if Status Flag Set	if (SREG(s) = 1) then PC←PC+k + 1	None	1/2
BRBC	s, k	Branch if Status Flag Cleared	if (SREG(s) = 0) then PC←PC+k + 1	None	1/2
BREQ	k	Branch if Equal	if $(Z = 1)$ then $PC \leftarrow PC + k + 1$	None	1/2
BRNE	k	Branch if Not Equal	if (Z = 0) then PC ← PC + k + 1	None	1/2
BRCS	k	Branch if Carry Set	if (C = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRCC	k	Branch if Carry Cleared	if (C = 0) then PC ← PC + k + 1	None	1/2
BRSH	k	Branch if Same or Higher	if (C = 0) then PC ← PC + k + 1	None	1/2
BRLO	k	Branch if Lower	if (C = 1) then PC ← PC + k + 1	None	1/2
BRMI	k	Branch if Minus	if (N = 1) then PC ← PC + k + 1	None	1/2
BRPL	k	Branch if Plus	if (N = 0) then PC ← PC + k + 1	None	1/2
BRGE	k	Branch if Greater or Equal, Signed	if $(N \oplus V = 0)$ then $PC \leftarrow PC + k + 1$	None	1/2
BRLT	k	Branch if Less Than Zero, Signed	if $(N \oplus V = 0)$ then $PC \leftarrow PC + k + 1$	None	1/2
BRHS	k	Branch if Half Carry Flag Set	if (H = 1) then PC ← PC + k + 1	None	1/2
BRHC	k	Branch if Half Carry Flag Cleared	if (H = 0) then PC ← PC + k + 1	None	1/2
BRTS	k	Branch if T Flag Set	if (T = 1) then PC ← PC + k + 1	None	1/2
BRTC	k	Branch if T Flag Cleared	if (T = 0) then PC ← PC + k + 1	None	1/2
BRVS	k	Branch if Overflow Flag is Set	if (V = 1) then PC ← PC + k + 1	None	1/2
BRVC	k	Branch if Overflow Flag is Cleared	if (V = 0) then PC ← PC + k + 1	None	1/2
	k	Branch if Interrupt Enabled	if ( I = 1) then PC ← PC + k + 1	None	1/2
	I IN	Dianollii liitellupt Eliabieu	11 ( 1 − 1) 01011 FU ← FU + K + 1	LINOUE	1/4
BRIE BRID	k	Branch if Interrupt Disabled	if ( I = 0) then PC ← PC + k + 1	None	1/2

Mnemonics	Operands	Description	Operation	Flags	#Clocks
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	Rd+1:Rd ← Rr+1:Rr	None	1
LDI	Rd, K	Load Immediate	Rd ← K	None	1
LD	Rd, X	Load Indirect	$Rd \leftarrow (X)$	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	$Rd \leftarrow (X), X \leftarrow X + 1$	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	$X \leftarrow X - 1$ , Rd $\leftarrow (X)$	None	2
LD	Rd, Y	Load Indirect	$Rd \leftarrow (Y)$	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	$Rd \leftarrow (Y), Y \leftarrow Y + 1$	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	$Y \leftarrow Y - 1$ , $Rd \leftarrow (Y)$	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	$Rd \leftarrow (Y + q)$	None	2
LD	Rd, Z	Load Indirect	$Rd \leftarrow (Z)$	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	$Z \leftarrow Z - 1$ , $Rd \leftarrow (Z)$	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	$Rd \leftarrow (Z + q)$	None	2
LDS	Rd, k	Load Direct from SRAM	Rd ← (k)	None	2
ST	X, Rr	Store Indirect	(X) ← Rr	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	$(X) \leftarrow Rr, X \leftarrow X + 1$	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	$X \leftarrow X - 1, (X) \leftarrow Rr$	None	2
ST	Y, Rr	Store Indirect	(Y) ← Rr	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	$(Y) \leftarrow Rr, Y \leftarrow Y + 1$	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	$Y \leftarrow Y - 1, (Y) \leftarrow Rr$	None	2
STD	Y+q,Rr	Store Indirect with Displacement	(Y + q) ← Rr	None	2
	Z, Rr	Store Indirect	(Z) ← Rr	None	<b>†</b>
ST ST	Z+, Rr -Z, Rr	Store Indirect and Post-Inc. Store Indirect and Pre-Dec.	$(Z) \leftarrow Rr, Z \leftarrow Z + 1$	None	2
STD	Z+q,Rr	Store Indirect with Displacement	$Z \leftarrow Z - 1$ , $(Z) \leftarrow Rr$ $(Z + q) \leftarrow Rr$	None None	2
STS	k, Rr	Store Direct to SRAM	$(k) \leftarrow Rr$	None	2
LPM	K, NI	Load Program Memory	$R0 \leftarrow (Z)$	None	3
LPM	Rd, Z	Load Program Memory	$Rd \leftarrow (Z)$	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	3
SPM	riu, Z+	Store Program Memory	(Z) ← R1:R0	None	-
IN	Rd, P	In Port	Rd ← P	None	1
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	Rd ← STACK	None	2
BIT AND BIT-TEST	INSTRUCTIONS				
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	I/O(P,b) ← 0	None	2
LSL	Rd	Logical Shift Left	$Rd(n+1) \leftarrow Rd(n), Rd(0) \leftarrow 0$	Z,C,N,V	1
LSR	Rd	Logical Shift Right	$Rd(n) \leftarrow Rd(n+1), Rd(7) \leftarrow 0$	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	$Rd(0)\leftarrow C,Rd(n+1)\leftarrow Rd(n),C\leftarrow Rd(7)$	Z,C,N,V	1
ROR	Rd	Rotate Right Through Carry	$Rd(7)\leftarrow C,Rd(n)\leftarrow Rd(n+1),C\leftarrow Rd(0)$	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	$Rd(n) \leftarrow Rd(n+1), n=06$	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(30)←Rd(74),Rd(74)←Rd(30)	None	1
BSET	s	Flag Set	SREG(s) ← 1	SREG(s)	1
BCLR	S	Flag Clear	SREG(s) ← 0	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	$T \leftarrow Rr(b)$	Т	1
BLD	Rd, b	Bit load from T to Register	$Rd(b) \leftarrow T$	None	1
SEC		Set Carry	C ← 1	С	1
CLC		Clear Carry	C ← 0	С	1
SEN	1	Set Negative Flag	N ← 1	N	1
CLN	1	Clear Negative Flag	N ← 0	N	1
SEZ	ļ	Set Zero Flag	Z ← 1	Z	1
CLZ	1	Clear Zero Flag	Z ← 0	Z	1
SEI	1	Global Interrupt Enable	1←1	1	1
CLI	1	Global Interrupt Disable	1←0	ı	1
SES	1	Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV	1	Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET	1	Set T in SREG	T ← 1	T	1
CLT	1	Clear T in SREG	T ← 0	T	1
SEH	1	Set Half Carry Flag in SREG	H ← 1	H	1
CLH	TDUOTIONO	Clear Half Carry Flag in SREG	H ← 0	Н	1
MCU CONTROL INS	INUCTIONS	Lu o ii	T	T	
NOP		No Operation		None	1





Mnemonics	Operands	Description	Operation	Flags	#Clocks
SLEEP		Sleep	(see specific descr. for Sleep function)	None	1
WDR		Watchdog Reset	(see specific descr. for WDR/Timer)	None	1
BREAK		Break	For On-chip Debug Only	None	N/A

## **Ordering Information**

Speed (MHz)	Power Supply	Ordering Code	Package <sup>(1)</sup>	Operation Range
		ATmega8535L-8AC	44A	
		ATmega8535L-8PC	40P6	Commercial
		ATmega8535L-8JC	44J	(0°C to 70°C)
		ATmega8535L-8MC	44M1	
		ATmega8535L-8AI	44A	
8	2.7 - 5.5V	ATmega8535L-8PI	40P6	
O	2.7 - 3.5V	ATmega8535L-8JI	44J	
		ATmega8535L-8MI	44M1	Industrial
		ATmega8535L-8AU <sup>(2)</sup>	44A	(-40°C to 85°C)
		ATmega8535L-8PU <sup>(2)</sup>	40P6	
		ATmega8535L-8JU <sup>(2)</sup>	44J	
		ATmega8535L-8MU <sup>(2)</sup>	44M1	
		ATmega8535-16AC	44A	
		ATmega8535-16PC	40P6	Commercial
		ATmega8535-16JC	44J	(0°C to 70°C)
		ATmega8535-16MC	44M1	
		ATmega8535-16AI	44A	
16	4.5 - 5.5V	ATmega8535-16PI	40P6	
	4.5 - 5.5 v	ATmega8535-16JI	44J	
		ATmega8535-16MI	44M1	Industrial
		ATmega8535-16AU <sup>(2)</sup>	44A	(-40°C to 85°C)
		ATmega8535-16PU <sup>(2)</sup>	40P6	
		ATmega8535-16JU <sup>(2)</sup>	44J	
		ATmega8535-16MU <sup>(2)</sup>	44M1	

Note:

- 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities..
- 2. Pb-free packaging alternative, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

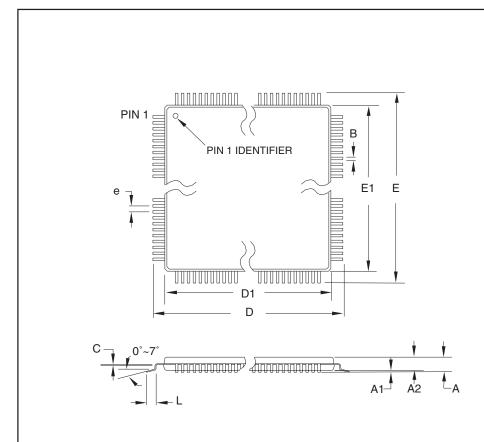
	Package Type				
44 <b>A</b>	44-lead, Thin (1.0 mm) Plastic Gull Wing Quad Flat Package (TQFP)				
40P6	40-pin, 0.600" Wide, Plastic Dual Inline Package (PDIP)				
44J	44-lead, Plastic J-leaded Chip Carrier (PLCC)				
44M1-A	44-pad, 7 x 7 x 1.0 mm body, lead pitch 0.50 mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)				





## **Packaging Information**

### 44A



### **COMMON DIMENSIONS**

(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
Α	_	_	1.20	
A1	0.05	_	0.15	
A2	0.95	1.00	1.05	
D	11.75	12.00	12.25	
D1	9.90	10.00	10.10	Note 2
Е	11.75	12.00	12.25	
E1	9.90	10.00	10.10	Note 2
В	0.30	_	0.45	
С	0.09	_	0.20	
L	0.45	_	0.75	
е		0.80 TYP		

Notes:

- 1. This package conforms to JEDEC reference MS-026, Variation ACB.
- 2. Dimensions D1 and E1 do not include mold protrusion. Allowable protrusion is 0.25 mm per side. Dimensions D1 and E1 are maximum plastic body size dimensions including mold mismatch.

TITLE

3. Lead coplanarity is 0.10 mm maximum.

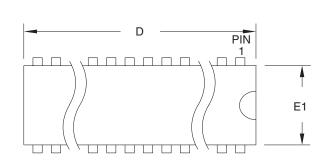
10/5/2001

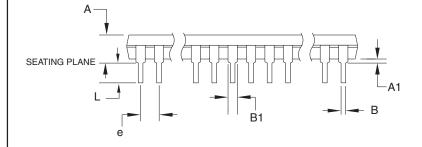
4mei	2325 Orchard	Parkway
	2325 Orchard San Jose, CA	95131

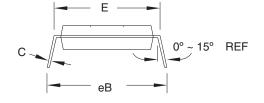
44A, 44-lead, 10 x 10 mm Body Size, 1.0 mm Body Thickness,
0.8 mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)

DRAWING NO.	REV.
44A	В

### 40P6







Notes:

- 1. This package conforms to JEDEC reference MS-011, Variation AC.
- Dimensions D and E1 do not include mold Flash or Protrusion. Mold Flash or Protrusion shall not exceed 0.25 mm (0.010").

### **COMMON DIMENSIONS**

(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
Α	_	_	4.826	
A1	0.381	_	_	
D	52.070	_	52.578	Note 2
Е	15.240	_	15.875	
E1	13.462	_	13.970	Note 2
В	0.356	_	0.559	
B1	1.041	_	1.651	
L	3.048	_	3.556	
С	0.203	_	0.381	
eB	15.494	_	17.526	
е	2.540 TYP			

09/28/01

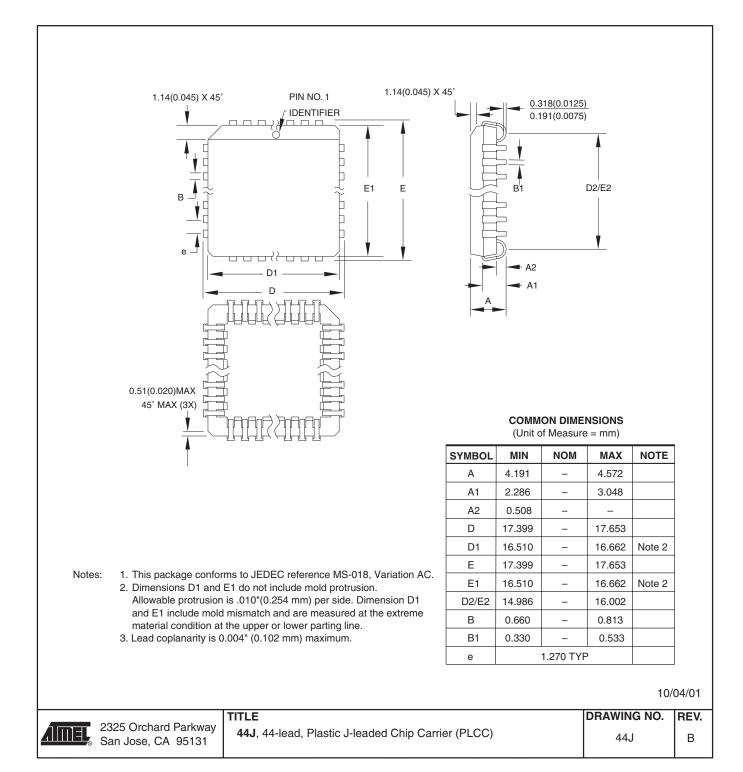
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2325 Orchard Parkway San Jose, CA 95131 TITLE
40P6, 40-lead (0.600"/15.24 mm Wide) Plastic Dual Inline Package (PDIP)

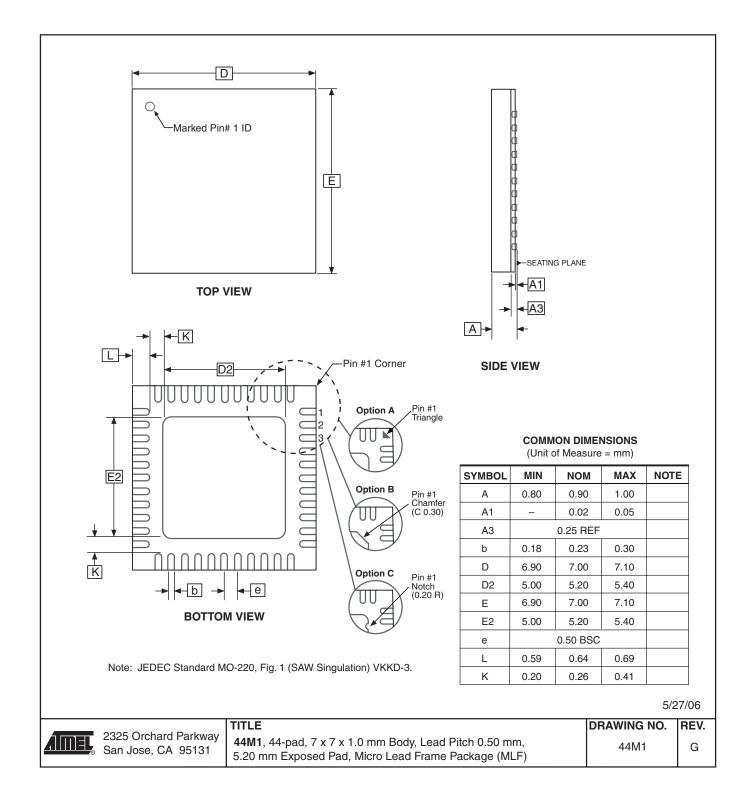
DRAWING NO. REV. 40P6 B



### 44J



### 44M1-A







### **Errata**

The revision letter refer to the device revision.

### ATmega8535 Rev. A and B

- First Analog Comparator conversion may be delayed
- Asynchronous Oscillator does not stop in Power-down

### 1. First Analog Comparator conversion may be delayed

If the device is powered by a slow rising  $V_{\text{CC}}$ , the first Analog Comparator conversion will take longer than expected on some devices.

### **Problem Fix/Workaround**

When the device has been powered or reset, disable then enable the Analog Comparator before the first conversion.

### 2. Asynchronous Oscillator does not stop in Power-down

The asynchronous oscillator does not stop when entering Power-down mode. This leads to higher power consumption than expected.

### Problem Fix/Workaround

Manually disable the asynchronous timer before entering Power-down.

## **Datasheet Revision History**

Please note that the referring page numbers in this section are referring to this document. The referring revision in this section are referring to the document revision.

## Changes from Rev. 2502J- 08/06 to Rev. 2502K- 10/06

- 1. Updated TOP/BOTTOM description for all Timer/Counters Fast PWM mode.
- 2. Updated "Errata" on page 18.

## Changes from Rev. 2502I- 06/06 to Rev. 2502J- 08/06

1. Updated "Ordering Information" on page 13.

# Changes from Rev. 2502H- 04/06 to Rev. 2502I- 06/06

1. Updated code example "USART Initialization" on page 150.

# Changes from Rev. 2502G- 04/05 to Rev. 2502H- 04/06

- 1. Added "Resources" on page 6.
- 2. Updated Table 7 on page 29, Table 17 on page 42 and Table 111 on page 258.
- 3. Updated "Serial Peripheral Interface SPI" on page 136.
- 4. Updated note in "Bit Rate Generator Unit" on page 180.

# Changes from Rev. 2502F- 06/04 to Rev. 2502G- 04/05

- 1. Removed "Preliminary" and TBD's.
- 2. Updated Table 37 on page 69 and Table 113 on page 261.
- 3. Updated "Electrical Characteristics" on page 255.
- 4. Updated "Ordering Information" on page 13.

# Changes from Rev. 2502E-12/03 to Rev. 2502G-06/04

1. MLF-package alternative changed to "Quad Flat No-Lead/Micro Lead Frame Package QFN/MLF".

# Changes from Rev. 2502E-12/03 to Rev. 2502F-06/04

- 1. Updated "Reset Characteristics" on page 37.
- 2. Updated SPH in "Stack Pointer" on page 12.
- 3. Updated C code in "USART Initialization" on page 150.
- 4. Updated "Errata" on page 18.

# Changes from Rev. 2502D-09/03 to Rev. 2502E-12/03

- 1. Updated "Calibrated Internal RC Oscillator" on page 29.
- 2. Added section "Errata" on page 18.





# Changes from Rev. 2502C-04/03 to Rev. 2502D-09/03

- 1. Removed "Advance Information" and some TBD's from the datasheet.
- 2. Added note to "Pinout ATmega8535" on page 2.
- 3. Updated "Reset Characteristics" on page 37.
- 4. Updated "Absolute Maximum Ratings" and "DC Characteristics" in "Electrical Characteristics" on page 255.
- 5. Updated Table 111 on page 258.
- 6. Updated "ADC Characteristics" on page 263.
- 7. Updated "ATmega8535 Typical Characteristics" on page 266.
- 8. Removed CALL and JMP instructions from code examples and "Instruction Set Summary" on page 10.

## Changes from Rev. 2502B-09/02 to Rev. 2502C-04/03

- 1. Updated "Packaging Information" on page 14.
- 2. Updated Figure 1 on page 2, Figure 84 on page 179, Figure 85 on page 185, Figure 87 on page 191, Figure 98 on page 207.
- 3. Added the section "EEPROM Write During Power-down Sleep Mode" on page 22.
- 4. Removed the references to the application notes "Multi-purpose Oscillator" and "32 kHz Crystal Oscillator", which do not exist.
- 5. Updated code examples on page 44.
- 6. Removed ADHSM bit.
- 7. Renamed Port D pin ICP to ICP1. See "Alternate Functions of Port D" on page 64.
- 8. Added information about PWM symmetry for Timer 0 on page 79 and Timer 2 on page 126.
- 9. Updated Table 68 on page 169, Table 75 on page 190, Table 76 on page 193, Table 77 on page 196, Table 108 on page 253, Table 113 on page 261.
- 10. Updated description on "Bit 5 TWSTA: TWI START Condition Bit" on page 182.
- 11. Updated the description in "Filling the Temporary Buffer (Page Loading)" and "Performing a Page Write" on page 231.
- 12. Removed the section description in "SPI Serial Programming Characteristics" on page 254.
- 13. Updated "Electrical Characteristics" on page 255.

- 14. Updated "ADC Characteristics" on page 263.
- 14. Updated "Register Summary" on page 8.
- 15. Various Timer 1 corrections.
- 16. Added WD\_FUSE period in Table 108 on page 253.

Changes from Rev. 2502A-06/02 to Rev. 2502B-09/02

1. Canged the Endurance on the Flash to 10,000 Write/Erase Cycles.





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