



#### Welcome to E-XFL.COM

#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Obsolete
Core Processor	AVR
Core Size	8-Bit
Speed	8MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	32
Program Memory Size	8KB (4K x 16)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	40-DIP (0.600", 15.24mm)
Supplier Device Package	40-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atmega8535I-8pc

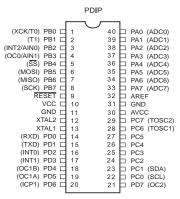
Email: info@E-XFL.COM

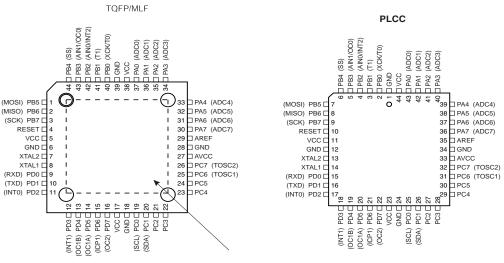
Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



# **Pin Configurations**

Figure 1. Pinout ATmega8535





NOTE: MLF Bottom pad should be soldered to ground.

Disclaimer

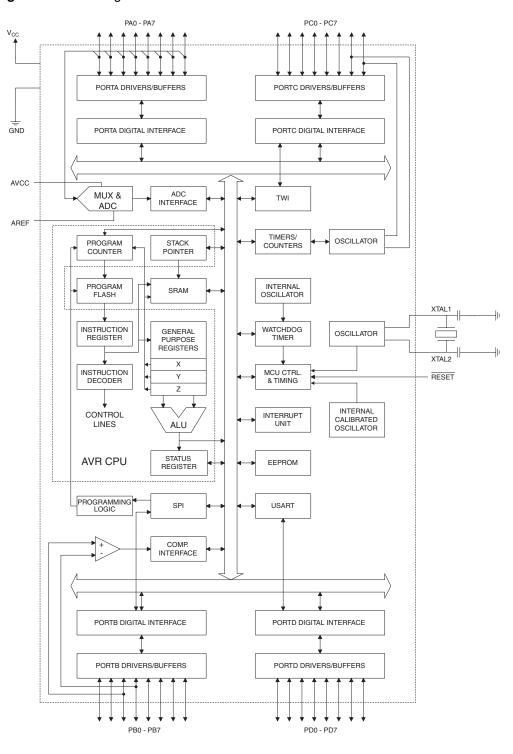
Typical values contained in this data sheet are based on simulations and characterization of other AVR microcontrollers manufactured on the same process technology. Min and Max values will be available after the device is characterized.

# **Overview**

The ATmega8535 is a low-power CMOS 8-bit microcontroller based on the AVR enhanced RISC architecture. By executing instructions in a single clock cycle, the ATmega8535 achieves throughputs approaching 1 MIPS per MHz allowing the system designer to optimize power consumption versus processing speed.

**Block Diagram** 

## Figure 2. Block Diagram







The AVR core combines a rich instruction set with 32 general purpose working registers. All 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The ATmega8535 provides the following features: 8K bytes of In-System Programmable Flash with Read-While-Write capabilities, 512 bytes EEPROM, 512 bytes SRAM, 32 general purpose I/O lines, 32 general purpose working registers, three flexible Timer/Counters with compare modes, internal and external interrupts, a serial programmable USART, a byte oriented Two-wire Serial Interface, an 8-channel, 10-bit ADC with optional differential input stage with programmable gain in TQFP package, a programmable Watchdog Timer with Internal Oscillator, an SPI serial port, and six software selectable power saving modes. The Idle mode stops the CPU while allowing the SRAM, Timer/Counters, SPI port, and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next interrupt or Hardware Reset. In Power-save mode, the asynchronous timer continues to run, allowing the user to maintain a timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except asynchronous timer and ADC, to minimize switching noise during ADC conversions. In Standby mode, the crystal/resonator Oscillator is running while the rest of the device is sleeping. This allows very fast start-up combined with low-power consumption. In Extended Standby mode, both the main Oscillator and the asynchronous timer continue to run.

The device is manufactured using Atmel's high density nonvolatile memory technology. The On-chip ISP Flash allows the program memory to be reprogrammed In-System through an SPI serial interface, by a conventional nonvolatile memory programmer, or by an On-chip Boot program running on the AVR core. The boot program can use any interface to download the application program in the Application Flash memory. Software in the Boot Flash section will continue to run while the Application Flash section is updated, providing true Read-While-Write operation. By combining an 8-bit RISC CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel ATmega8535 is a powerful microcontroller that provides a highly flexible and cost effective solution to many embedded control applications.

The ATmega8535 AVR is supported with a full suite of program and system development tools including: C compilers, macro assemblers, program debugger/simulators, In-Circuit Emulators, and evaluation kits.

# AT90S8535 Compatibility

ty The ATmega8535 provides all the features of the AT90S8535. In addition, several new features are added. The ATmega8535 is backward compatible with AT90S8535 in most cases. However, some incompatibilities between the two microcontrollers exist. To solve this problem, an AT90S8535 compatibility mode can be selected by programming the S8535C fuse. ATmega8535 is pin compatible with AT90S8535, and can replace the AT90S8535 on current Printed Circuit Boards. However, the location of fuse bits and the electrical characteristics differs between the two devices.

#### AT90S8535 Compatibility Mode

Programming the S8535C fuse will change the following functionality:

- The timed sequence for changing the Watchdog Time-out period is disabled. See "Timed Sequences for Changing the Configuration of the Watchdog Timer" on page 45 for details.
  - The double buffering of the USART Receive Register is disabled. See "AVR USART vs. AVR UART Compatibility" on page 146 for details.

# **Pin Descriptions**

V <sub>cc</sub>	Digital supply voltage.
GND	Ground.
Port A (PA7PA0)	Port A serves as the analog inputs to the A/D Converter. Port A also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. When pins PA0 to PA7 are used as inputs and are externally pulled low, they will source current if the internal pull-up resistors are activated. The Port A pins are tri-stated when
Port B (PB7PB0)	a reset condition becomes active, even if the clock is not running. Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.
	Port B also serves the functions of various special features of the ATmega8535 as listed on page 60.
Port C (PC7PC0)	Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset condition becomes active, even if the clock is not running.
Port D (PD7PD0)	Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.
	Port D also serves the functions of various special features of the ATmega8535 as listed on page 64.
RESET	Reset input. A low level on this pin for longer than the minimum pulse length will gener- ate a reset, even if the clock is not running. The minimum pulse length is given in Table 15 on page 37. Shorter pulses are not guaranteed to generate a reset.
XTAL1	Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.
XTAL2	Output from the inverting Oscillator amplifier.
AVCC	AVCC is the supply voltage pin for Port A and the A/D Converter. It should be externally connected to $V_{CC}$ , even if the ADC is not used. If the ADC is used, it should be connected to $V_{CC}$ through a low-pass filter.
AREF	AREF is the analog reference pin for the A/D Converter.





# Resources

A comprehensive set of development tools, application notes and datasheets are available for download on http://www.atmel.com/avr.

# About Code Examples

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C Compiler documentation for more details.



Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
0x3F (0x5F)	SREG	I	Т	Н	S	V	N	Z	С	10
0x3E (0x5E)	SPH	-	-	-	-	-	-	SP9	SP8	12
0x3D (0x5D)	SPL	SP7	SP6	SP5	SP4	SP3	SP2	SP1	SP0	12
0x3C (0x5C)	OCR0				ner/Counter0 Out	tput Compare Re	-			85
0x3B (0x5B)	GICR	INT1	INT0	INT2	-	-	-	IVSEL	IVCE	49, 69
0x3A (0x5A)	GIFR	INTF1	INTF0	INTF2	-	-	-	-	-	70
0x39 (0x59)	TIMSK	OCIE2	TOIE2	TICIE1	OCIE1A	OCIE1B	TOIE1	OCIE0	TOIE0	85, 115, 133
0x38 (0x58)	TIFR	OCF2	TOV2	ICF1	OCF1A	OCF1B	TOV1	OCF0	TOV0	86, 116, 134
0x37 (0x57) 0x36 (0x56)	SPMCR TWCR	SPMIE TWINT	RWWSB TWEA	– TWSTA	RWWSRE TWSTO	BLBSET TWWC	PGWRT TWEN	PGERS -	SPMEN TWIE	228 181
0x36 (0x56) 0x35 (0x55)	MCUCR	SM2	SE	SM1	SM0	ISC11	ISC10	ISC01	ISC00	32, 68
0x34 (0x54)	MCUCSR	-	ISC2	_	_	WDRF	BORF	EXTRF	PORF	40, 69
0x33 (0x53)	TCCR0	FOC0	WGM00	COM01	COM00	WGM01	CS02	CS01	CS00	83
0x32 (0x52)	TCNT0					nter0 (8 Bits)				85
0x31 (0x51)	OSCCAL				Oscillator Cal	ibration Register				30
0x30 (0x50)	SFIOR	ADTS2	ADTS1	ADTS0	_	ACME	PUD	PSR2	PSR10	59,88,135,203,223
0x2F (0x4F)	TCCR1A	COM1A1	COM1A0	COM1B1	COM1B0	FOC1A	FOC1B	WGM11	WGM10	110
0x2E (0x4E)	TCCR1B	ICNC1	ICES1	-	WGM13	WGM12	CS12	CS11	CS10	113
0x2D (0x4D)	TCNT1H			Time	er/Counter1 – Co	unter Register Hig	gh Byte			114
0x2C (0x4C)	TCNT1L					unter Register Lo	,			114
0x2B (0x4B)	OCR1AH					compare Register				114
0x2A (0x4A)	OCR1AL					Compare Register				114
0x29 (0x49)	OCR1BH				· ·	Compare Register				114
0x28 (0x48)	OCR1BL					Compare Register	-			114
0x27 (0x47)	ICR1H					Capture Register	0,			114
0x26 (0x46)	ICR1L	50.00				Capture Register		0001	0000	114
0x25 (0x45)	TCCR2	FOC2	WGM20	COM21	COM20	WGM21	CS22	CS21	CS20	128
0x24 (0x44) 0x23 (0x43)	TCNT2 OCR2			Tir		nter2 (8 Bits) tput Compare Re	nistor			130 131
0x22 (0x42)	ASSR	-	_	-		AS2	TCN2UB	OCR2UB	TCR2UB	131
0x21 (0x41)	WDTCR		_	_	WDCE	WDE	WDP2	WDP1	WDP0	42
	UBRRH	URSEL	_	_	-			R[11:8]		169
0x20 <sup>(1)</sup> (0x40) <sup>(1)</sup>	UCSRC	URSEL	UMSEL	UPM1	UPM0	USBS	UCSZ1	UCSZ0	UCPOL	167
0x1F (0x3F)	EEARH	-	-	_	_	-	_	-	EEAR8	19
0x1E (0x3E)	EEARL			I	EEPROM Addres	s Register Low B	yte			19
0x1D (0x3D)	EEDR		_	-	EEPROM	Data Register		-	-	19
0x1C (0x3C)	EECR	-	-	-	-	EERIE	EEMWE	EEWE	EERE	19
0x1B (0x3B)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	66
0x1A (0x3A)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	66
0x19 (0x39)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	66
0x18 (0x38)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	66
0x17 (0x37)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	66
0x16 (0x36)	PINB	PINB7 PORTC7	PINB6	PINB5	PINB4	PINB3 PORTC3	PINB2	PINB1	PINB0 PORTC0	67 67
0x15 (0x35) 0x14 (0x34)	PORTC DDRC	DDC7	PORTC6 DDC6	PORTC5 DDC5	PORTC4 DDC4	DDC3	PORTC2 DDC2	PORTC1 DDC1	DDC0	67
0x14 (0x34) 0x13 (0x33)	PINC	PINC7	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	67
0x12 (0x32)	PORTD	PORTD7	PORTD6	PORTD5	PORTD4	PORTD3	PORTD2	PORTD1	PORTDO	67
0x11 (0x31)	DDRD	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	67
0x10 (0x30)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	67
0x0F (0x2F)	SPDR				SPI Da	ta Register				143
0x0E (0x2E)	SPSR	SPIF	WCOL	_	_	-	_	_	SPI2X	143
0x0D (0x2D)	SPCR	SPIE	SPE	DORD	MSTR	CPOL	CPHA	SPR1	SPR0	141
0x0C (0x2C)	UDR				USART I/O	Data Register				164
0x0B (0x2B)	UCSRA	RXC	TXC	UDRE	FE	DOR	PE	U2X	MPCM	165
0x0A (0x2A)	UCSRB	RXCIE	TXCIE	UDRIE	RXEN	TXEN	UCSZ2	RXB8	TXB8	166
0x09 (0x29)	UBRRL					te Register Low E				169
0x08 (0x28)	ACSR	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	203
0x07 (0x27)	ADMUX	REFS1	REFS0	ADLAR	MUX4	MUX3	MUX2	MUX1	MUX0	219
0x06 (0x26)	ADCSRA	ADEN	ADSC	ADATE	ADIF	ADIE	ADPS2	ADPS1	ADPS0	221
0x05 (0x25)	ADCH					gister High Byte				222
0x04 (0x24) 0x03 (0x23)	ADCL TWDR			Ŧ		egister Low Byte terface Data Regi	etor			222 183
0x03 (0x23) 0x02 (0x22)	TWDR	TWA6	TWA5	TWA4	TWA3	TWA2	TWA1	TWA0	TWGCE	183
0x02 (0x22) 0x01 (0x21)	TWAR	TWA6	TWA5 TWS6	TWA4 TWS5	TWA3 TWS4	TWA2 TWS3		TWA0	TWPS0	183
0/01 (0/21)	111011	11101					_			100



# **Register Summary**



# Instruction Set Summary

Mnemonics	Operands	Description	Operation	Flags	#Clocks
ARITHMETIC AND	LOGIC INSTRUCTION	S			
ADD	Rd, Rr	Add two Registers	$Rd \leftarrow Rd + Rr$	Z,C,N,V,H	1
ADC	Rd, Rr	Add with Carry two Registers	$Rd \leftarrow Rd + Rr + C$	Z,C,N,V,H	1
ADIW	Rdl,K	Add Immediate to Word	$Rdh:Rdl \leftarrow Rdh:Rdl + K$	Z,C,N,V,S	2
SUB	Rd, Rr	Subtract two Registers	Rd ← Rd - Rr	Z,C,N,V,H	1
SUBI	Rd, K	Subtract Constant from Register	Rd ← Rd - K	Z,C,N,V,H	1
SBC	Rd, Rr	Subtract with Carry two Registers	$Rd \leftarrow Rd - Rr - C$	Z,C,N,V,H	1
SBCI	Rd, K	Subtract with Carry Constant from Reg.	$Rd \leftarrow Rd - K - C$	Z,C,N,V,H	1
SBIW	Rdl,K	Subtract Immediate from Word	Rdh:Rdl ← Rdh:Rdl - K	Z,C,N,V,S	2
AND	Rd, Rr	Logical AND Registers	$Rd \leftarrow Rd \bullet Rr$	Z,N,V	1
ANDI	Rd, K	Logical AND Register and Constant	$Rd \leftarrow Rd ullet K$	Z,N,V	1
OR	Rd, Rr	Logical OR Registers	Rd ← Rd v Rr	Z,N,V	1
ORI	Rd, K	Logical OR Register and Constant	$Rd \leftarrow Rd \lor K$	Z,N,V	1
EOR	Rd, Rr	Exclusive OR Registers	$Rd \leftarrow Rd \oplus Rr$	Z,N,V	1
COM	Rd	One's Complement	$Rd \leftarrow 0xFF - Rd$	Z,C,N,V	1
NEG	Rd	Two's Complement	Rd ← 0x00 – Rd	Z,C,N,V,H	1
SBR	Rd,K	Set Bit(s) in Register	$Rd \leftarrow Rd \lor K$	Z,N,V	1
CBR	Rd,K	Clear Bit(s) in Register	$Rd \leftarrow Rd \bullet (0xFF - K)$	Z,N,V	1
INC	Rd	Increment	Rd ← Rd + 1	Z,N,V	1
DEC	Rd	Decrement	Rd ← Rd – 1	Z,N,V	1
TST	Rd	Test for Zero or Minus	$Rd \leftarrow Rd \bullet Rd$	Z,N,V	1
CLR	Rd	Clear Register	$Rd \leftarrow Rd \oplus Rd$	Z,N,V	1
SER	Rd	Set Register	Rd ← 0xFF	None	1
MUL	Rd, Rr	Multiply Unsigned	$R1:R0 \leftarrow Rd x Rr$	Z,C	2
MULS	Rd, Rr	Multiply Signed	$R1:R0 \leftarrow Rd \times Rr$	Z,C	2
MULSU	Rd, Rr	Multiply Signed with Unsigned	$R1:R0 \leftarrow Rd \times Rr$	Z,C	2
FMUL	Rd, Rr	Fractional Multiply Unsigned	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z,C	2
FMULS	Rd, Rr	Fractional Multiply Signed	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z,C	2
FMULSU	Rd, Rr	Fractional Multiply Signed with Unsigned	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z,C	2
BRANCH INSTRUC					
RJMP	k	Relative Jump	$PC \leftarrow PC + k + 1$	None	2
IJMP		Indirect Jump to (Z)	$PC \leftarrow Z$	None	2
RCALL	k	Relative Subroutine Call	PC ← PC + k + 1	None	3
ICALL		Indirect Call to (Z)		None	3
RET		Subroutine Return		None	4
RETI	Dd Dr	Interrupt Return		Nene	4
CPSE	Rd,Rr	Compare, Skip if Equal	if (Rd = Rr) PC ← PC + 2 or 3 Rd – Rr	None	1/2/3
CP CPC	Rd,Rr Rd,Rr	Compare	Rd – Rr – C	Z, N,V,C,H Z, N,V,C,H	1
CPI	Rd,K	Compare with Carry Compare Register with Immediate	Rd – K		1
SBRC		Skip if Bit in Register Cleared	if (Rr(b)=0) PC $\leftarrow$ PC + 2 or 3	Z, N,V,C,H	1/2/3
SBRS	Rr, b Rr, b	Skip if Bit in Register is Set	if $(Rr(b)=0) PC \leftarrow PC + 2 or 3$ if $(Rr(b)=1) PC \leftarrow PC + 2 or 3$	None None	1/2/3
SBIC	P, b	Skip if Bit in I/O Register Cleared	if $(P(b)=0) PC \leftarrow PC + 2 \text{ or } 3$	None	1/2/3
SBIS	P, b	Skip if Bit in I/O Register is Set	if $(P(b)=1) PC \leftarrow PC + 2 \text{ or } 3$	None	1/2/3
BRBS	s, k	Branch if Status Flag Set	if (SREG(s) = 1) then $PC \leftarrow PC+k + 1$	None	1/2
BRBC	s, k	Branch if Status Flag Cleared	if (SREG(s) = 1) then $PC \leftarrow PC+k+1$ if (SREG(s) = 0) then $PC \leftarrow PC+k+1$	None	1/2
BREQ	k	Branch if Equal	if $(Z = 1)$ then PC $\leftarrow$ PC + k + 1	None	1/2
BRNE	k	Branch if Not Equal	if (Z = 0) then PC $\leftarrow$ PC + k + 1	None	1/2
BRCS	k	Branch if Carry Set	if (C = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRCC	k	Branch if Carry Cleared	if (C = 0) then PC $\leftarrow$ PC + k + 1	None	1/2
BRSH	k	Branch if Same or Higher	if (C = 0) then PC $\leftarrow$ PC + k + 1	None	1/2
BRLO	k	Branch if Lower	if (C = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRMI	k	Branch if Minus	if (N = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRPL	k	Branch if Plus	if (N = 0) then PC $\leftarrow$ PC + k + 1	None	1/2
BRGE	k	Branch if Greater or Equal, Signed	if $(N \oplus V = 0)$ then PC $\leftarrow$ PC + k + 1	None	1/2
BRLT	k	Branch if Less Than Zero, Signed	if $(N \oplus V = 0)$ then PC $\leftarrow$ PC + k + 1	None	1/2
BRHS	k	Branch if Half Carry Flag Set	if (H = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRHC	k	Branch if Half Carry Flag Cleared	if (H = 0) then PC $\leftarrow$ PC + k + 1	None	1/2
BRTS	k	Branch if T Flag Set	if (T = 1) then PC $\leftarrow$ PC + k + 1	None	1/2
BRTC	k	Branch if T Flag Cleared	if $(T = 0)$ then PC $\leftarrow$ PC + k + 1	None	1/2
BRVS	k	Branch if Overflow Flag is Set	if $(V = 1)$ then PC $\leftarrow$ PC + k + 1	None	1/2
	k	Branch if Overflow Flag is Cleared	if $(V = 0)$ then PC $\leftarrow$ PC + k + 1	None	1/2
BBVC				110110	1/2
BRVC BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC $\leftarrow$ PC + k + 1	None	1/2

Mnemonics	Operands	Description	Operation	Flags	#Clocks
MOV	Rd, Rr	Move Between Registers	$Rd \leftarrow Rr$	None	1
MOVW	Rd, Rr	Copy Register Word	$Rd+1:Rd \leftarrow Rr+1:Rr$	None	1
LDI	Rd, K	Load Immediate	$Rd \leftarrow K$	None	1
LD	Rd, X	Load Indirect	$Rd \leftarrow (X)$	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	$Rd \leftarrow (X),  X \leftarrow X + 1$	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	$X \leftarrow X - 1$ , Rd $\leftarrow (X)$	None	2
LD	Rd, Y	Load Indirect	$Rd \leftarrow (Y)$	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	$Rd \leftarrow (Y),  Y \leftarrow Y + 1$	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	$Y \leftarrow Y - 1, Rd \leftarrow (Y)$	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	$Rd \leftarrow (Y + q)$	None	2
LD	Rd, Z	Load Indirect	$Rd \leftarrow (Z)$	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	$Z \leftarrow Z - 1, Rd \leftarrow (Z)$	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	$Rd \leftarrow (Z + q)$	None	2
LDS	Rd, k	Load Direct from SRAM	$Rd \leftarrow (k)$	None	2
ST	X, Rr	Store Indirect	(X) ← Rr	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	$(X) \leftarrow \operatorname{Rr}, X \leftarrow X + 1$	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	$X \leftarrow X - 1, (X) \leftarrow Rr$	None	2
ST	Y, Rr	Store Indirect	$(Y) \leftarrow Rr$	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	$(Y) \leftarrow Rr, Y \leftarrow Y + 1$	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	$Y \leftarrow Y - 1$ , $(Y) \leftarrow Rr$	None	2
STD	Y+q,Rr	Store Indirect with Displacement	$(Y + q) \leftarrow Rr$	None	2
ST	Z, Rr	Store Indirect	$(Z) \leftarrow Rr$	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	$(Z) \leftarrow Rr, Z \leftarrow Z + 1$	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	$Z \leftarrow Z - 1, (Z) \leftarrow Rr$	None	2
STD	Z+q,Rr	Store Indirect with Displacement	$(Z + q) \leftarrow Rr$	None	2
STS	k, Rr	Store Direct to SRAM	(k) ← Rr	None	2
LPM		Load Program Memory	$R0 \leftarrow (Z)$	None	3
LPM	Rd, Z	Load Program Memory	Rd ← (Z)	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	$Rd \leftarrow (Z), Z \leftarrow Z + 1$	None	3
SPM	D-L D	Store Program Memory	(Z) ← R1:R0	None	-
IN	Rd, P	In Port	Rd ← P	None	1
OUT	P, Rr	Out Port	$P \leftarrow Rr$	None	1
PUSH	Rr Rd	Push Register on Stack		None	2
BIT AND BIT-TEST		Pop Register from Stack	$Rd \leftarrow STACK$	None	2
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	$VO(P,b) \leftarrow 1$ $VO(P,b) \leftarrow 0$	None	2
LSL	Rd	Logical Shift Left	$Rd(n+1) \leftarrow Rd(n), Rd(0) \leftarrow 0$	Z,C,N,V	1
LSR	Rd	Logical Shift Right	$Rd(n) \leftarrow Rd(n+1), Rd(7) \leftarrow 0$	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	$Rd(0) \leftarrow C, Rd(n+1) \leftarrow Rd(n), C \leftarrow Rd(7)$	Z,C,N,V	1
ROR	Rd	Rotate Right Through Carry	$Rd(7) \leftarrow C, Rd(n) \leftarrow Rd(n+1), C \leftarrow Rd(0)$	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	$Rd(n) \leftarrow Rd(n+1), n=06$	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(30)←Rd(74),Rd(74)←Rd(30)	None	1
BSET	s	Flag Set	SREG(s) $\leftarrow 1$	SREG(s)	1
BCLR	s	Flag Clear	SREG(s) $\leftarrow 0$	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	$T \leftarrow Rr(b)$	T	1
BLD	Rd, b	Bit load from T to Register	$Rd(b) \leftarrow T$	None	1
SEC		Set Carry	$C \leftarrow 1$	C	1
CLC		Clear Carry	C ← 0	c	1
SEN	1	Set Negative Flag	$N \leftarrow 1$	N	1
CLN		Clear Negative Flag	$N \leftarrow 0$	N	1
SEZ		Set Zero Flag	$Z \leftarrow 1$	Z	1
CLZ		Clear Zero Flag	$Z \leftarrow 0$	Z	1
SEI		Global Interrupt Enable	← 1	1	1
CLI		Global Interrupt Disable	1 ← 0	1	1
SES		Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV		Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	$V \leftarrow 0$	V	1
SET		Set T in SREG	T ← 1	Т	1
CLT		Clear T in SREG	$T \leftarrow 0$	Т	1
	1		H ← 1	Н	1
SEH		Set Hall Cally Flay III SheG			
SEH CLH		Set Half Carry Flag in SREG Clear Half Carry Flag in SREG		н	1
	STRUCTIONS		$H \leftarrow 0$		





Mnemonics	Operands	Description	Operation	Flags	#Clocks
SLEEP		Sleep	(see specific descr. for Sleep function)	None	1
WDR		Watchdog Reset	(see specific descr. for WDR/Timer)	None	1
BREAK		Break	For On-chip Debug Only	None	N/A

Speed (MHz)	Power Supply	Ordering Code	Package <sup>(1)</sup>	Operation Range
		ATmega8535L-8AC	44A	
		ATmega8535L-8PC	40P6	Commercial
		ATmega8535L-8JC	44J	(0°C to 70°C)
		ATmega8535L-8MC	44M1	
		ATmega8535L-8AI	44A	
8	2.7 - 5.5V	ATmega8535L-8PI	40P6	
0	2.7 - 5.5 V	ATmega8535L-8JI	44J	
		ATmega8535L-8MI	44M1	Industrial
		ATmega8535L-8AU <sup>(2)</sup>	44A	(-40°C to 85°C)
		ATmega8535L-8PU <sup>(2)</sup>	40P6	
		ATmega8535L-8JU <sup>(2)</sup>	44J	
		ATmega8535L-8MU <sup>(2)</sup>	44M1	
		ATmega8535-16AC	44A	
		ATmega8535-16PC	40P6	Commercial
		ATmega8535-16JC	44J	(0°C to 70°C)
		ATmega8535-16MC	44M1	
		ATmega8535-16AI	44A	
16	4.5 - 5.5V	ATmega8535-16PI	40P6	
10	4.5 - 5.5V	ATmega8535-16JI	44J	
		ATmega8535-16MI	44M1	Industrial
		ATmega8535-16AU <sup>(2)</sup>	44A	(-40°C to 85°C)
		ATmega8535-16PU <sup>(2)</sup>	40P6	
		ATmega8535-16JU <sup>(2)</sup>	44J	
		ATmega8535-16MU <sup>(2)</sup>	44M1	

# **Ordering Information**

Note: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging alternative, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

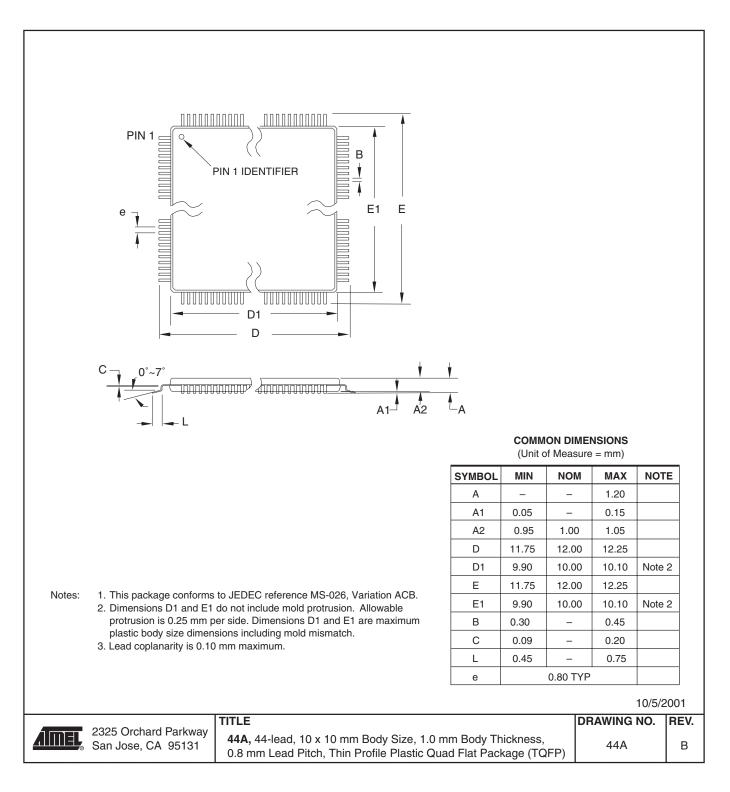
	Package Type			
44 <b>A</b>	44-lead, Thin (1.0 mm) Plastic Gull Wing Quad Flat Package (TQFP)			
40P6	40-pin, 0.600" Wide, Plastic Dual Inline Package (PDIP)			
44J	44-lead, Plastic J-leaded Chip Carrier (PLCC)			
44M1-A	44-pad, 7 x 7 x 1.0 mm body, lead pitch 0.50 mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)			



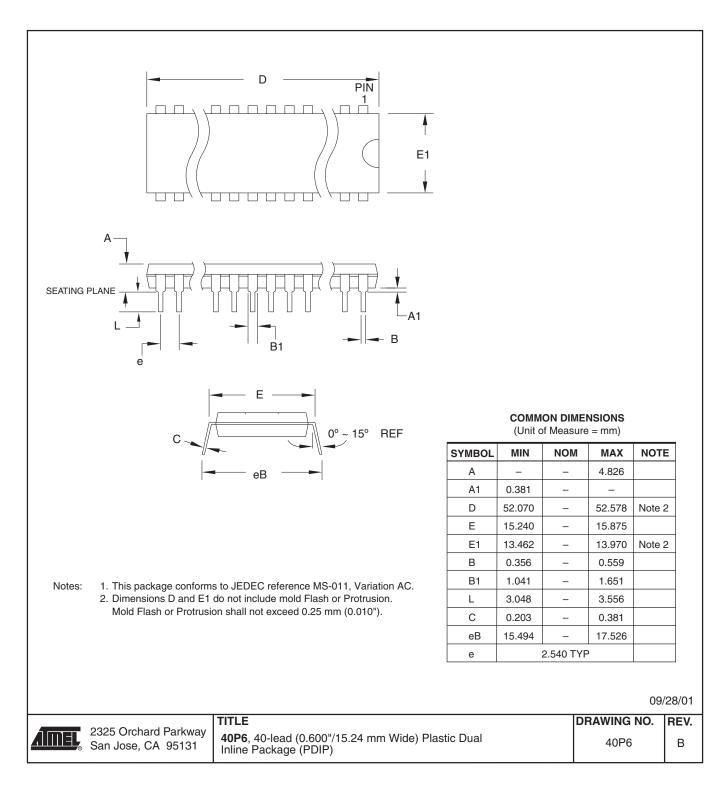


# **Packaging Information**

44A



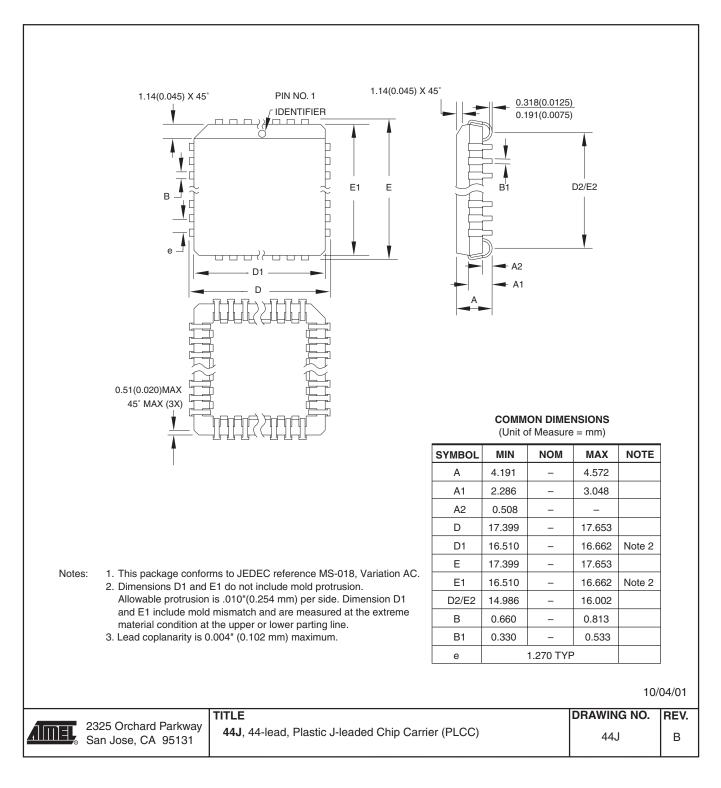
## 40P6



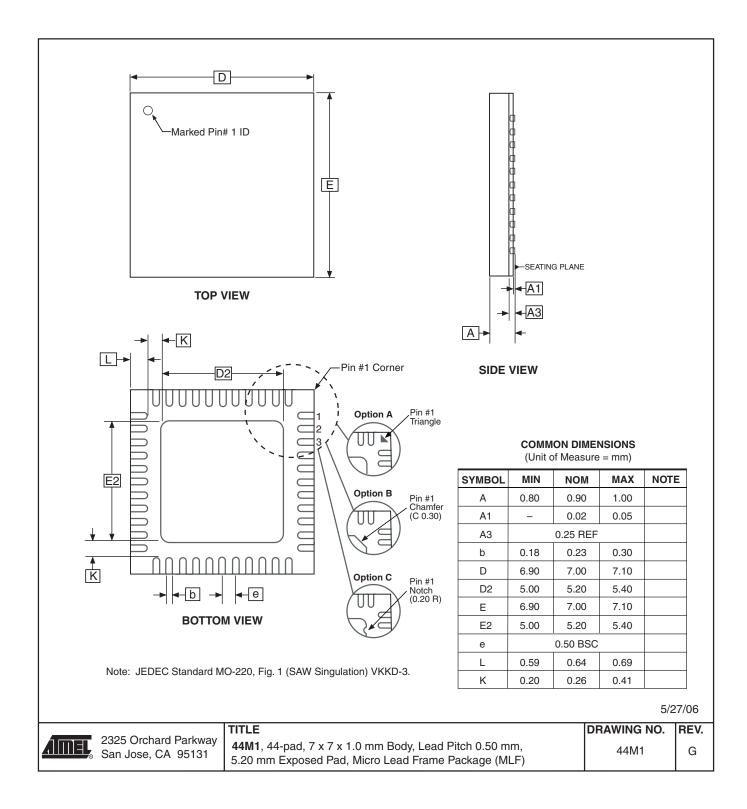








44M1-A





# Errata

ATmega8535 Rev. A and B

- The revision letter refer to the device revision.
- First Analog Comparator conversion may be delayed
- Asynchronous Oscillator does not stop in Power-down

### 1. First Analog Comparator conversion may be delayed

If the device is powered by a slow rising  $V_{\rm CC},$  the first Analog Comparator conversion will take longer than expected on some devices.

## **Problem Fix/Workaround**

When the device has been powered or reset, disable then enable the Analog Comparator before the first conversion.

## 2. Asynchronous Oscillator does not stop in Power-down

The asynchronous oscillator does not stop when entering Power-down mode. This leads to higher power consumption than expected.

### **Problem Fix/Workaround**

Manually disable the asynchronous timer before entering Power-down.

# Datasheet Revision History

Changes from Rev. 2502J- 08/06 to Rev. 2502K- 10/06

Changes from Rev. 2502I- 06/06 to Rev. 2502J- 08/06

Changes from Rev. 2502H- 04/06 to Rev. 2502I- 06/06

Changes from Rev. 2502G- 04/05 to Rev. 2502H- 04/06

Changes from Rev. 2502F- 06/04 to Rev. 2502G- 04/05

Changes from Rev. 2502E-12/03 to Rev. 2502G-06/04

Changes from Rev. 2502E-12/03 to Rev. 2502F-06/04

Changes from Rev. 2502D-09/03 to Rev. 2502E-12/03 Please note that the referring page numbers in this section are referring to this document. The referring revision in this section are referring to the document revision.

- 1. Updated TOP/BOTTOM description for all Timer/Counters Fast PWM mode.
- 2. Updated "Errata" on page 18.
- 1. Updated "Ordering Information" on page 13.
- 1. Updated code example "USART Initialization" on page 150.
- 1. Added "Resources" on page 6.
- 2. Updated Table 7 on page 29, Table 17 on page 42 and Table 111 on page 258.
- 3. Updated "Serial Peripheral Interface SPI" on page 136.
- 4. Updated note in "Bit Rate Generator Unit" on page 180.
- 1. Removed "Preliminary" and TBD's.
- 2. Updated Table 37 on page 69 and Table 113 on page 261.
- 3. Updated "Electrical Characteristics" on page 255.
- 4. Updated "Ordering Information" on page 13.
- 1. MLF-package alternative changed to "Quad Flat No-Lead/Micro Lead Frame Package QFN/MLF".
- 1. Updated "Reset Characteristics" on page 37.
- 2. Updated SPH in "Stack Pointer" on page 12.
- 3. Updated C code in "USART Initialization" on page 150.
- 4. Updated "Errata" on page 18.
- 1. Updated "Calibrated Internal RC Oscillator" on page 29.
- 2. Added section "Errata" on page 18.





Changes from Rev. 2502C-04/03 to Rev. 2502D-09/03

- 1. Removed "Advance Information" and some TBD's from the datasheet.
- 2. Added note to "Pinout ATmega8535" on page 2.
- 3. Updated "Reset Characteristics" on page 37.
- 4. Updated "Absolute Maximum Ratings" and "DC Characteristics" in "Electrical Characteristics" on page 255.
- 5. Updated Table 111 on page 258.
- 6. Updated "ADC Characteristics" on page 263.
- 7. Updated "ATmega8535 Typical Characteristics" on page 266.
- 8. Removed CALL and JMP instructions from code examples and "Instruction Set Summary" on page 10.

Changes from Rev. 2502B-09/02 to Rev. 2502C-04/03

- 1. Updated "Packaging Information" on page 14.
- 2. Updated Figure 1 on page 2, Figure 84 on page 179, Figure 85 on page 185, Figure 87 on page 191, Figure 98 on page 207.
- 3. Added the section "EEPROM Write During Power-down Sleep Mode" on page 22.
- 4. Removed the references to the application notes "Multi-purpose Oscillator" and "32 kHz Crystal Oscillator", which do not exist.
- 5. Updated code examples on page 44.
- 6. Removed ADHSM bit.
- 7. Renamed Port D pin ICP to ICP1. See "Alternate Functions of Port D" on page 64.
- 8. Added information about PWM symmetry for Timer 0 on page 79 and Timer 2 on page 126.
- 9. Updated Table 68 on page 169, Table 75 on page 190, Table 76 on page 193, Table 77 on page 196, Table 108 on page 253, Table 113 on page 261.
- 10. Updated description on "Bit 5 TWSTA: TWI START Condition Bit" on page 182.
- 11. Updated the description in "Filling the Temporary Buffer (Page Loading)" and "Performing a Page Write" on page 231.
- 12. Removed the section description in "SPI Serial Programming Characteristics" on page 254.
- 13. Updated "Electrical Characteristics" on page 255.

- 14. Updated "ADC Characteristics" on page 263.
- 14. Updated "Register Summary" on page 8.
- 15. Various Timer 1 corrections.
- 16. Added WD\_FUSE period in Table 108 on page 253.
- 1. Canged the Endurance on the Flash to 10,000 Write/Erase Cycles.

Changes from Rev. 2502A-06/02 to Rev. 2502B-09/02





## **Atmel Corporation**

2325 Orchard Parkway San Jose, CA 95131, USA Tel: 1(408) 441-0311 Fax: 1(408) 487-2600

## **Regional Headquarters**

#### Europe

Atmel Sarl Route des Arsenaux 41 Case Postale 80 CH-1705 Fribourg Switzerland Tel: (41) 26-426-5555 Fax: (41) 26-426-5500

### Asia

Room 1219 Chinachem Golden Plaza 77 Mody Road Tsimshatsui East Kowloon Hong Kong Tel: (852) 2721-9778 Fax: (852) 2722-1369

### Japan

9F, Tonetsu Shinkawa Bldg. 1-24-8 Shinkawa Chuo-ku, Tokyo 104-0033 Japan Tel: (81) 3-3523-3551 Fax: (81) 3-3523-7581

## **Atmel Operations**

*Memory* 2325 Orchard Parkway San Jose, CA 95131, USA Tel: 1(408) 441-0311 Fax: 1(408) 436-4314

### Microcontrollers

2325 Orchard Parkway San Jose, CA 95131, USA Tel: 1(408) 441-0311 Fax: 1(408) 436-4314

La Chantrerie BP 70602 44306 Nantes Cedex 3, France Tel: (33) 2-40-18-18-18 Fax: (33) 2-40-18-19-60

### ASIC/ASSP/Smart Cards

Zone Industrielle 13106 Rousset Cedex, France Tel: (33) 4-42-53-60-00 Fax: (33) 4-42-53-60-01

1150 East Cheyenne Mtn. Blvd. Colorado Springs, CO 80906, USA Tel: 1(719) 576-3300 Fax: 1(719) 540-1759

Scottish Enterprise Technology Park Maxwell Building East Kilbride G75 0QR, Scotland Tel: (44) 1355-803-000 Fax: (44) 1355-242-743

### **RF**/Automotive

Theresienstrasse 2 Postfach 3535 74025 Heilbronn, Germany Tel: (49) 71-31-67-0 Fax: (49) 71-31-67-2340

1150 East Cheyenne Mtn. Blvd. Colorado Springs, CO 80906, USA Tel: 1(719) 576-3300 Fax: 1(719) 540-1759

## Biometrics/Imaging/Hi-Rel MPU/

High Speed Converters/RF Datacom Avenue de Rochepleine BP 123 38521 Saint-Egreve Cedex, France Tel: (33) 4-76-58-30-00 Fax: (33) 4-76-58-34-80

*Literature Requests* www.atmel.com/literature

Disclaimer: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. EXCEPT AS SET FORTH IN ATMEL'S TERMS AND CONDI-TIONS OF SALE LOCATED ON ATMEL'S WEB SITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITVE, SPECIAL OR INCIDEN-TAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS OF PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and product descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Atmel's products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.

© 2006 Atmel Corporation. All rights reserved. Atmel<sup>®</sup>, logo and combinations thereof, Everywhere You Are<sup>®</sup>, AVR<sup>®</sup>, and others are the trademarks or registered trademarks of Atmel Corporation or its subsidiaries. Other terms and product names may be trademarks of others.