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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	eZ8
Core Size	8-Bit
Speed	20MHz
Connectivity	I²C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	19
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	A/D 5x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f0822sj020eg

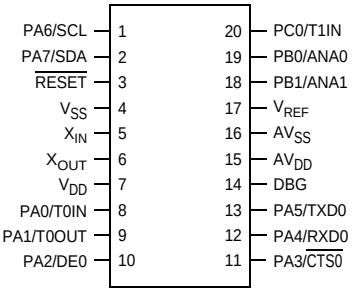

Figure 2. The Z8F0821 and Z8F0421 MCUs in 20-Pin SSOP and PDIP Packages

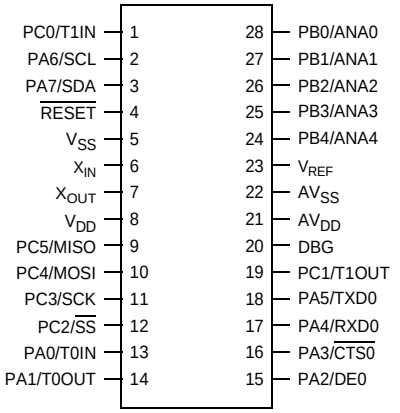

Figure 3. The Z8F0822 and Z8F0422 MCUs in 28-Pin SOIC and PDIP Packages

Pin Characteristics

Table 4 provides detailed information about the characteristics for each pin available on Z8 Encore! XP® F0822 Series products. The data in Table 4 is sorted alphabetically by pin symbol mnemonic.

Table 4. Pin Characteristics

Symbol Mnemonic	Direction	Reset Direction	Active Low or Active High	Tri-State Output	Internal Pull-Up or Pull-Down	Schmitt-Trigger Input	Open Drain Output
AV_{DD}	N/A	N/A	N/A	N/A	No	No	N/A
AV_{SS}	N/A	N/A	N/A	N/A	No	No	N/A
DBG	I/O	I	N/A	Yes	No	Yes	Yes
PA[7:0]	I/O	I	N/A	Yes	Programmable pull-up	Yes	Yes, programmable
PB[4:0]	I/O	I	N/A	Yes	Programmable pull-up	Yes	Yes, programmable
PC[5:0]	I/O	I	N/A	Yes	Programmable pull-up	Yes	Yes, programmable
RESET	I	I	Low	N/A	Pull-up	Yes	N/A
V_{DD}	N/A	N/A	N/A	N/A	No	No	N/A
V_{REF}	Analog	N/A	N/A	N/A	No	No	N/A
V_{SS}	N/A	N/A	N/A	N/A	No	No	N/A
X_{IN}	I	I	N/A	N/A	No	No	N/A
X_{OUT}	O	O	N/A	No	No	No	No

the POR status bit in the Watchdog Timer Control Register (WDTCTL) is set to 1. Figure 7 displays the VBO operation. See the Electrical Characteristics chapter on page 176 for the VBO and POR threshold voltages (V_{VBO} and V_{POR}).

The VBO circuit can be either enabled or disabled during STOP Mode. Operation during STOP Mode is set by the VBO_AO option bit. For information about configuring VBO_AO, see the Option Bits chapter on page 155.

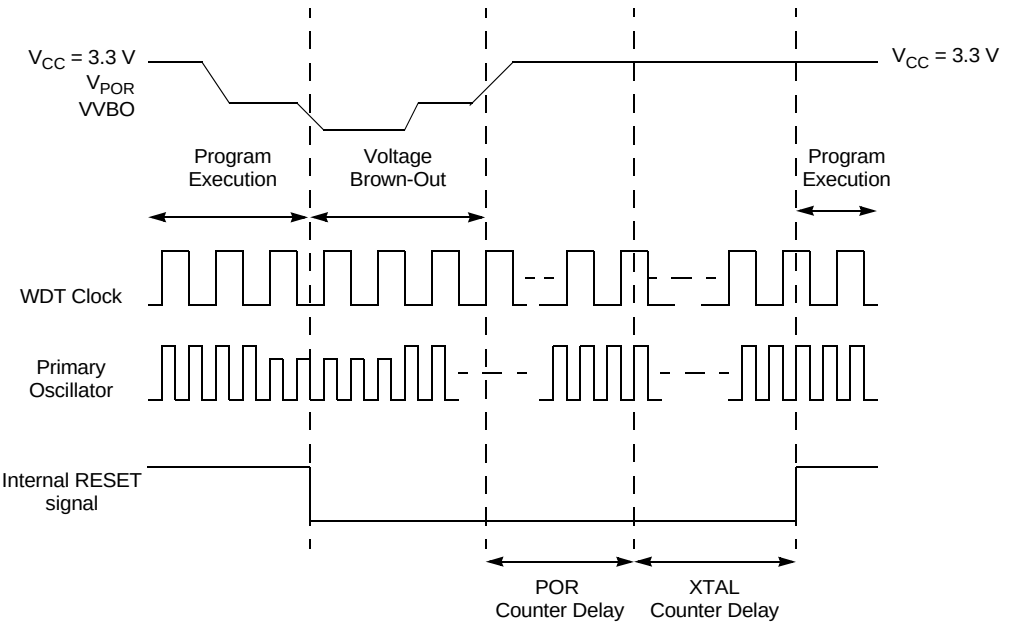

Figure 7. Voltage Brown-Out Reset Operation

Watchdog Timer Reset

If the device is in NORMAL or HALT Mode, WDT initiates a System Reset at time-out, if the WDT_RES option bit is set to 1. This setting is the default (unprogrammed) setting of the WDT_RES option bit. The WDT status bit in the WDT Control Register is set to signify that the reset was initiated by the WDT.

External Pin Reset

The $\overline{\text{RESET}}$ pin contains a Schmitt-triggered input, an internal pull-up, an analog filter, and a digital filter to reject noise. After the $\overline{\text{RESET}}$ pin is asserted for at least 4 system

Architecture

Figure 9 displays a block diagram of the interrupt controller.

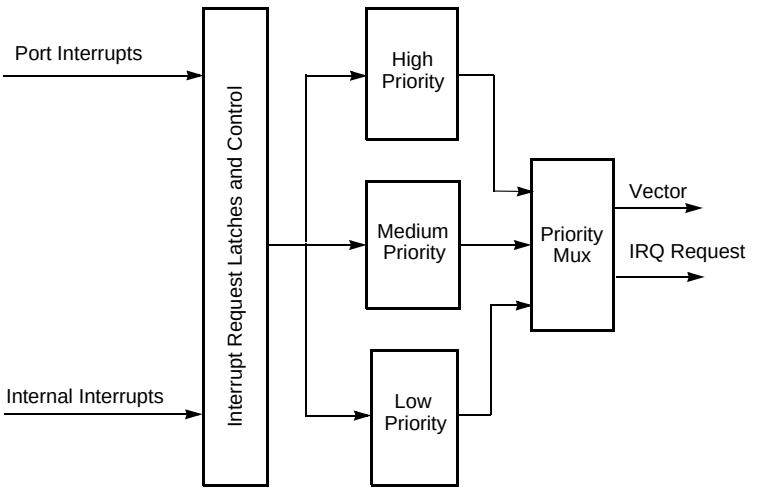

Figure 9. Interrupt Controller Block Diagram

Operation

This section describes the operational aspects of the following functions.

Master Interrupt Enable: see page 42

Interrupt Vectors and Priority: see page 43

Interrupt Assertion: see page 43

Software Interrupt Assertion: see page 44

Master Interrupt Enable

The master interrupt enable bit (IRQE) in the Interrupt Control Register globally enables and disables interrupts.

Interrupts are globally enabled by any of the following actions:

- Execution of an Enable Interrupt (EI) instruction
- Execution of an Return from Interrupt (IRET) instruction

Reading the Timer Count Values

The current count value in the timers can be read while counting (enabled). This capability has no effect on timer operation. When the timer is enabled and the Timer High Byte Register is read, the contents of the Timer Low Byte Register are placed in a holding register. A subsequent read from the Timer Low Byte Register returns the value in the holding register. This operation allows accurate reads of the full 16-bit timer count value while enabled. When the timers are not enabled, a read from the Timer Low Byte Register returns the actual value in the counter.

Timer Output Signal Operation

Timer Output is a GPIO port pin alternate function. Generally, the Timer Output is toggled every time the counter is reloaded.

Timer Control Register Definitions

This section defines the features of the following Timer Control registers.

Timer 0–1 High and Low Byte Registers: see page 64

Timer Reload High and Low Byte Registers: see page 65

Timer 0–1 PWM High and Low Byte Registers: see page 66

Timer 0–3 Control 0 Registers: see page 67

Timer 0–1 Control 1 Registers: see page 68

Timer 0–1 High and Low Byte Registers

The Timer 0–1 High and Low Byte (TxH and TxL) registers, shown in Tables 39 and 40, contain the current 16-bit timer count value. When the timer is enabled, a read from TxH causes the value in TxL to be stored in a temporary holding register. A read from TMRL always returns this temporary register when the timers are enabled. When the timer is disabled, reads from the TMRL reads the register directly.

Zilog does not recommend writing to the Timer High and Low Byte registers while the timer is enabled. There are no temporary holding registers available for write operations, so simultaneous 16-bit writes are not possible. If either the Timer High or Low Byte registers are written during counting, the 8-bit written value is placed in the counter (High or Low Byte) at the next clock edge. The counter continues counting from the new value.

Table 48. Watchdog Timer Control Register (WDTCTL)

Bit	7	6	5	4	3	2	1	0
Field	POR	STOP	WDT	EXT	Reserved			
RESET	See Table 49.				0			
R/W	R							
Address	FF0H							

Bit	Description
[7] POR	**Power-On Reset Indicator** If this bit is set to 1, a POR event occurred. This bit is reset to 0, if a WDT time-out or Stop Mode Recovery occurs. This bit is also reset to 0, when the register is read.
[6] STOP	**Stop Mode Recovery Indicator** If this bit is set to 1, a Stop Mode Recovery occurred. If the STOP and WDT bits are both set to 1, the Stop Mode Recovery occurred due to a WDT time-out. If the stop bit is 1 and the WDT bit is 0, the Stop Mode Recovery was not caused by a WDT time-out. This bit is reset by a POR or a WDT time-out that occurred while not in STOP Mode. Reading this register also resets this bit.
[5] WDT	**Watchdog Timer Time-Out Indicator** If this bit is set to 1, a WDT time-out occurred. A POR resets this pin. A Stop Mode Recovery due a change in an input pin also resets this bit. Reading this register resets this bit.
[4] EXT	**External Reset Indicator** If this bit is set to 1, a Reset initiated by the external $\overline{\text{RESET}}$ pin occurred. A POR or a Stop Mode Recovery from a change in an input pin resets this bit. Reading this register resets this bit.
[3:0]	**Reserved** These bits are reserved and must be programmed to 0000.

Table 49. Watchdog Timer Events

Reset or Stop Mode Recovery Event	POR	STOP	WDT	EXT
Power-On Reset	1	0	0	0
Reset through $\overline{\text{RESET}}$ pin assertion	0	0	0	1
Reset through WDT time-out	0	0	1	0
Reset through the OCD (OCTCTL[1] set to 1)	1	0	0	0
Reset from STOP Mode through the DBG Pin driven Low	1	0	0	0
Stop Mode Recovery through GPIO pin transition	0	1	0	0
Stop Mode Recovery through WDT time-out	0	1	1	0

- Set or clear the CTSE bit to enable or disable control from the remote receiver through the $\overline{\text{CTS}}$ pin.

7. Execute an EI instruction to enable interrupts.

The UART is now configured for interrupt-driven data transmission. Because the UART Transmit Data Register is empty, an interrupt is generated immediately. When the UART transmit interrupt is detected, the associated ISR performs the following:

1. Write the UART Control 1 Register to select the outgoing address bit:
   - Set the Multiprocessor Bit Transmitter (MPBT) if sending an address byte; clear it if sending a data byte.
2. Write the data byte to the UART Transmit Data Register. The transmitter automatically transfers data to the Transmit Shift Register and then transmits the data.
3. Clear the UART transmit interrupt bit in the applicable Interrupt Request Register.
4. Execute the IRET instruction to return from the ISR and waits for the Transmit Data Register to again become empty.

Receiving Data using the Polled Method

Observe the following procedure to configure the UART for polled data reception:

1. Write to the UART Baud Rate High and Low Byte registers to set the required baud rate.
2. Enable the UART pin functions by configuring the associated GPIO port pins for alternate function operation.
3. Write to the UART Control 1 Register to enable Multiprocessor mode functions, if appropriate.
4. Write to the UART Control 0 Register to:
   - Set the receive enable bit (REN) to enable the UART for data reception
   - Enable parity, if required, and if MULTIPROCESSOR Mode is not enabled, and select either even or odd parity.
5. Check the RDA bit in the UART Status 0 Register to determine if the Receive Data Register contains a valid data byte (indicated by 1). If RDA is set to 1 to indicate available data, continue to Step 6. If the Receive Data Register is empty (indicated by a 0), continue to monitor the RDA bit awaiting reception of the valid data.

Table 63. SPI Clock Phase (PHASE) and Clock Polarity (CLKPOL) Operation

PHASE	CLKPOL	SCK Transmit Edge	SCK Receive Edge	SCK Idle State
0	0	Falling	Rising	Low
0	1	Rising	Falling	High
1	0	Rising	Falling	Low
1	1	Falling	Rising	High

Transfer Format PHASE is 0

Figure 23 displays the timing diagram for an SPI transfer in which PHASE is cleared to 0. The two SCK waveforms show polarity with CLKPOL reset to 0 and with CLKPOL set to one. The diagram can be interpreted as either a Master or Slave timing diagram, because the SCK Master-In/Slave-Out (MISO) and Master-Out/Slave-In (MOSI) pins are directly connected between the Master and the Slave.

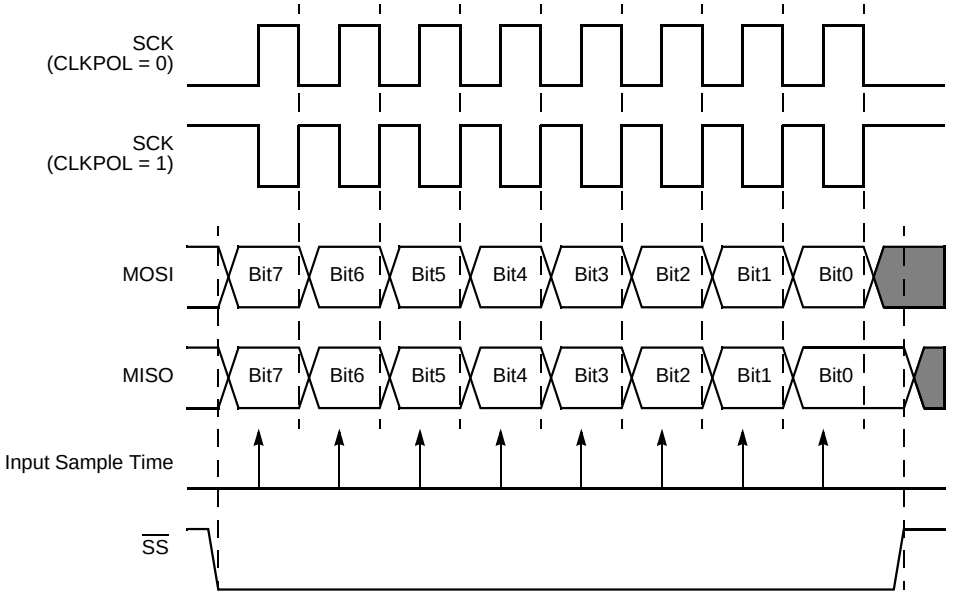

Figure 23. SPI Timing When PHASE is 0

Page Select Register

The Page Select (FPS) Register, shown in Table 86, selects the Flash memory page to be erased or programmed. Each Flash page contains 512 bytes of Flash memory. During a Page Erase operation, all Flash memory locations with the 7 most significant bits of the address provided by the PAGE field are erased to FFH.

The Page Select Register shares its Register File address with the Flash Sector Protect Register. The Page Select Register cannot be accessed when the Flash Sector Protect Register is enabled.

Table 86. Page Select Register (FPS)

Bit	7	6	5	4	3	2	1	0
Field	INFO_EN	PAGE						
RESET	0							
R/W	R/W							
Address	FF9H							

Bit	Description
[7] INFO_EN	**Information Area Enable** 0 = Information Area is not selected. 1 = Information Area is selected. The Information area is mapped into the Flash memory address space at addresses FE00H through FFFFH.
[6:0] PAGE	**Page Select** This 7-bit field selects the Flash memory page for Programming and Page Erase operations. Flash memory address[15:9] = PAGE[6:0].

Flash Sector Protect Register

The Flash Sector Protect Register, shown in Table 87, protects Flash memory sectors from being programmed or erased from user code. The Flash Sector Protect Register shares its Register File address with the Page Select Register. The Flash Sector Protect Register can be accessed only after writing the Flash Control Register with 5EH.

User code can only write bits in this register to 1 (bits cannot be cleared to 0 by user code). To determine the appropriate Flash memory sector address range and sector number for your F0822 Series product, please refer to Table 82 on page 143.

If breakpoints are enabled, the OCD can be configured to automatically enter DEBUG Mode, or to loop on the break instruction. If the OCD is configured to loop on the BRK instruction, then the CPU is still enabled to service DMA and interrupt requests.

The loop on a BRK instruction can be used to service interrupts in the background. For interrupts to be serviced in the background, there cannot be any breakpoints in the ISR. Otherwise, the CPU stops on the breakpoint in the interrupt routine. For interrupts to be serviced in the background, interrupts must also be enabled. Debugging software should not automatically enable interrupts when using this feature, because interrupts are typically disabled during critical sections of code where interrupts should not occur (such as adjusting the stack pointer or modifying shared data).

Software can poll the IDLE bit of the OCDSTAT Register to determine if the OCD is looping on a BRK instruction. When software wants to stop the CPU on the BRK instruction it is looping on, software should not set the DBGMODE bit of the OCDCTL Register. The CPU can have vectored to and be in the middle of an ISR when this bit gets set. Instead, software must clear the BRKLP bit. This allows the CPU to finish the ISR it is in and return the BRK instruction. When the CPU returns to the BRK instruction it was previously looping on, it automatically sets the DBGMODE bit and enter DEBUG Mode.

Software should also note that the majority of the OCD commands are still disabled when the eZ8 CPU is looping on a BRK instruction. The eZ8 CPU must be stopped and the part must be in DEBUG Mode before these commands can be issued.

Breakpoints in Flash Memory

The BRK instruction is Op Code 00H, which corresponds to the fully programmed state of a byte in Flash memory. To implement a Breakpoint, write 00H to the appropriate address, overwriting the current instruction. To remove a Breakpoint, the corresponding page of Flash memory must be erased and reprogrammed with the original data.

OCDCNTR Register

The OCD contains a multipurpose 16-bit counter register. It can be used for the following:

- Count system clock cycles between breakpoints
- Generate a BRK when it counts down to zero
- Generate a BRK when its value matches the Program Counter

When configured as a counter, the OCDCNTR Register starts counting when the OCD leaves DEBUG Mode and stops counting when it enters DEBUG Mode again or when it reaches the maximum count of FFFFH. The OCDCNTR Register automatically resets itself to 0000H when the OCD exits DEBUG Mode if it is configured to count clock cycles between breakpoints.

Table 93. On-Chip Debugger Commands (Continued)

Debug Command	Command Byte	Enabled When Not in DEBUG Mode?	Disabled by Read Protect Option Bit
Read Register	09H	–	Only reads of the peripheral control registers at address F00H–FFH are allowed.
Write Program Memory	0AH	–	Disabled
Read Program Memory	0BH	–	Disabled
Write Data Memory	0CH	–	Disabled
Read Data Memory	0DH	–	Disabled
Read Program Memory CRC	0EH	–	–
Reserved	0FH	–	–
Step Instruction	10H	–	Disabled
Stuff Instruction	11H	–	Disabled
Execute Instruction	12H	–	Disabled
Reserved	13H–FFH	–	–

In the following bulleted list of OCD Commands, data and commands sent from the host to the OCD are identified by DBG ← Command/Data. Data sent from the OCD back to the host is identified by DBG → Data.

Read OCD Revision (00H). The Read OCD Revision command determines the version of the OCD. If OCD commands are added, removed, or changed, this revision number changes.

```
DBG ← 00H
DBG → OCDREV[15:8] (Major revision number)
DBG → OCDREV[7:0] (Minor revision number)
```

Write OCD Counter Register (01H). The Write OCD Counter Register command writes the data that follows to the OCDCNTR Register. If the device is not in DEBUG Mode, the data is discarded.

```
DBG ← 01H
DBG ← OCDCNTR[15:8]
DBG ← OCDCNTR[7:0]
```

Read OCD Status Register (02H). The Read OCD Status Register command reads the OCDSTAT Register.

```
DBG ← 02H
DBG → OCDSTAT[7:0]
```

Read OCD Counter Register (03H). The OCD Counter Register can be used to count system clock cycles in between breakpoints, generate a BRK when it counts down to zero,

```
DBG ← 12H
DBG ← 1-5 byte opcode
```

On-Chip Debugger Control Register Definitions

This section describes the features of the On-Chip Debugger Control and Status registers.

OCD Control Register

The OCD Control Register, shown in Table 94, controls the state of the OCD. This register enters or exits DEBUG Mode and enables the BRK instruction. It can also reset the Z8 Encore! XP® F0822 Series device.

A *reset and stop* function can be achieved by writing 81H to this register. A *reset and go* function can be achieved by writing 41H to this register. If the device is in DEBUG Mode, a *run* function can be implemented by writing 40H to this register.

Table 94. OCD Control Register (OCDCTL)

Bit	7	6	5	4	3	2	1	0
Field	DBGMODE	BRKEN	DBGACK	BRKLOOP	BRKPC	BRKZRO	Reserved	RST
RESET	0							
R/W	R/W			R				R/W

Bit	Description
[7] DBGMODE	**Debug Mode** Setting this bit to 1 causes the device to enter DEBUG Mode. When in DEBUG Mode, the eZ8 CPU stops fetching new instructions. Clearing this bit causes the eZ8 CPU to start running again. This bit is automatically set when a BRK instruction is decoded and breakpoints are enabled. If the Read Protect option bit is enabled, this bit can only be cleared by resetting the device, it cannot be written to 0. 0 = The Z8 Encore! XP® F0822 Series device is operating in NORMAL Mode. 1 = The Z8 Encore! XP® F0822 Series device is in DEBUG Mode.
[6] BRKEN	**Breakpoint Enable** This bit controls the behavior of the BRK instruction (Op Code 00H). By default, breakpoints are disabled and the BRK instruction behaves like an NOP instruction. If this bit is set to 1 and a BRK instruction is decoded, the OCD takes action dependent upon the BRKLOOP bit. 0 = BRK instruction is disabled. 1 = BRK instruction is enabled.
[5] DBGACK	**Debug Acknowledge** This bit enables the debug acknowledge feature. If this bit is set to 1, then the OCD sends an Debug Acknowledge character (FFH) to the host when a Breakpoint occurs. 0 = Debug Acknowledge is disabled. 1 = Debug Acknowledge is enabled.

Electrical Characteristics

The data in this chapter represents all known data prior to qualification and characterization of the Z8 Encore! XP® F0822 Series of products, and is therefore subject to change. Additional electrical characteristics may be found in the individual chapters of this document.

Absolute Maximum Ratings

These ratings are stress ratings only. Operation of the device at any condition outside those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect device reliability. For improved reliability, unused inputs must be tied to one of the supply voltages (V_{DD} or V_{SS}).

! **Caution:** Stresses greater than those listed in Table 97 can cause permanent damage to the device.

Table 97. Absolute Maximum Ratings

Parameter	Minimum	Maximum	Units	Notes
Ambient temperature under bias	–40	+105	°C	1
Storage temperature	–65	+150	°C	
Voltage on any pin with respect to V_{SS}	–0.3	+5.5	V	2
Voltage on AV_{SS} pin with respect to V_{SS}	–0.3	+0.3	V	2
Voltage on V_{DD} pin with respect to V_{SS}	–0.3	+3.6	V	
Voltage on AV_{DD} pin with respect to V_{DD}	–0.3	+0.3	V	
Maximum current on input and/or inactive output pin	–5	+5	µA	
Maximum output current from active output pin	–25	+25	mA	
20-pin SSOP Package Maximum Ratings at –40°C to 70°C				
Total power dissipation		430	mW	
Maximum current into V_{DD} or out of V_{SS}		120	mA	

Note: This voltage applies to all pins except the following: V_{DD}, AV_{DD}, V_{REF}, pins that support analog input (Port B), and where otherwise noted.

UART Timing

Figure 54 and Table 112 provide timing information for UART pins for the case where the Clear To Send input pin ($\overline{CTS}$) is used for flow control. In this example, it is assumed that the Driver Enable polarity has been configured to be Active Low and is represented here by $\overline{DE}$. The $\overline{CTS}$ to $\overline{DE}$ assertion delay (T1) assumes the UART Transmit Data Register has been loaded with data prior to $\overline{CTS}$ assertion.

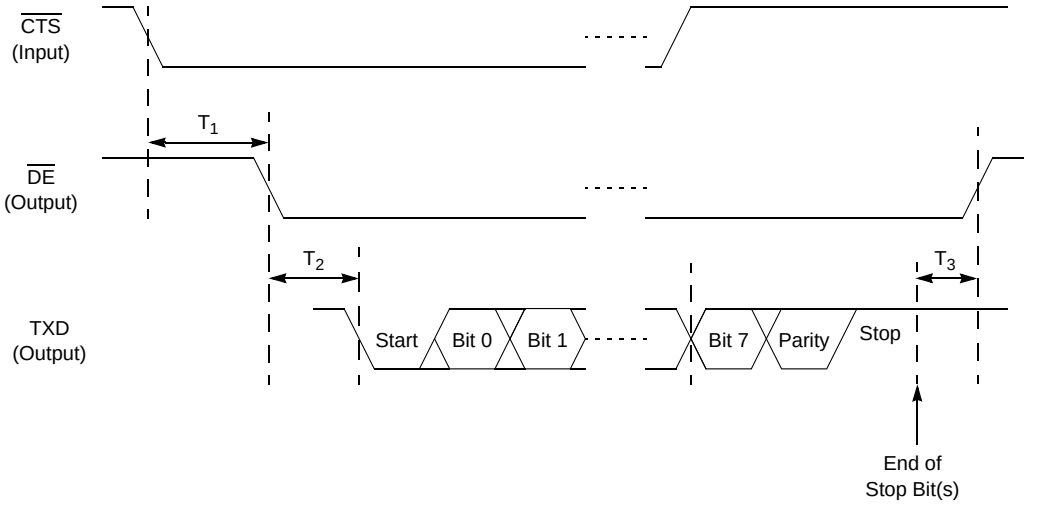

Figure 54. UART Timing with $\overline{CTS}$

Table 112. UART Timing with $\overline{CTS}$

		Delay (ns)	
Parameter	**Abbreviation**	**Minimum**	**Maximum**
T_1	$\overline{CTS}$ Fall to $\overline{DE}$ Assertion Delay	2 * X_{IN} period	2 * X_{IN} period + 1 Bit period
T_2	$\overline{DE}$ Assertion to TXD Falling Edge (Start) Delay	1 Bit period	1 Bit period + 1 * X_{IN} period
T_3	End of Stop Bit(s) to $\overline{DE}$ Deassertion Delay	1 * X_{IN} period	2 * X_{IN} period

Figure 55 and Table 113 provide timing information for UART pins for the case where the Clear To Send input signal ($\overline{CTS}$) is not used for flow control. In this example, it is assumed that the Driver Enable polarity has been configured to be Active Low and is rep-

Table 127. eZ8 CPU Instruction Summary (Continued)

Assembly Mnemonic	Symbolic Operation	Address Mode dst	Address Mode src	Op Code(s) (Hex)	Flags C	Z	S	V	D	H	Fetch Cycles	Instr. Cycles
LD dst, rc	dst ← src	r	IM	0C-FC	-	-	-	-	-	-	2	2
		r	X(r)	C7							3	3
		X(r)	r	D7							3	4
		r	Ir	E3							2	3
		R	R	E4							3	2
		R	IR	E5							3	4
		R	IM	E6							3	2
		IR	IM	E7							3	3
		Ir	r	F3							2	3
		IR	R	F5							3	3
LDC dst, src	dst ← src	r	Irr	C2	-	-	-	-	-	-	2	5
		Ir	Irr	C5							2	9
		Irr	r	D2							2	5
LDCI dst, src	dst ← src r ← r + 1 rr ← rr + 1	Ir	Irr	C3	-	-	-	-	-	-	2	9
		Irr	Ir	D3							2	9
LDE dst, src	dst ← src	r	Irr	82	-	-	-	-	-	-	2	5
		Irr	r	92							2	5
LDEI dst, src	dst ← src r ← r + 1 rr ← rr + 1	Ir	Irr	83	-	-	-	-	-	-	2	9
		Irr	Ir	93							2	9
LDWX dst, src	dst ← src	ER	ER	1F E8	-	-	-	-	-	-	5	4

Note: Flags Notation:
* = Value is a function of the result of the operation.
– = Unaffected.
X = Undefined.
0 = Reset to 0.
1 = Set to 1.

Hex Address: F01

Table 131. Timer 0–1 Low Byte Register (TxL)

Bit	7	6	5	4	3	2	1	0
Field	TL							
RESET	0							1
R/W	R/W							
Address	F01H, F09H							

Hex Address: F02

Table 132. Timer 0–1 Reload High Byte Register (TxRH)

Bit	7	6	5	4	3	2	1	0
Field	TRH							
RESET	1							
R/W	R/W							
Address	F02H, F0AH							

Hex Address: F03

Table 133. Timer 0–1 Reload Low Byte Register (TxRL)

Bit	7	6	5	4	3	2	1	0
Field	TRL							
RESET	1							
R/W	R/W							
Address	F03H, F0BH							

Hex Address: F07

Table 137. Timer 0–1 Control Registers (TxCTL)

Bit	7	6	5	4	3	2	1	0
Field	TEN	TPOL	PRES			TMODE		
RESET	0							
R/W	R/W							
Address	F07H, F0FH							

Hex Address: F08

Table 138. Timer 0–1 High Byte Register (TxH)

Bit	7	6	5	4	3	2	1	0
Field	TH							
RESET	0							
R/W	R/W							
Address	F00H, F08H							

Hex Address: F09

Table 139. Timer 0–1 Low Byte Register (TxL)

Bit	7	6	5	4	3	2	1	0
Field	TL							
RESET	0							1
R/W	R/W							
Address	F01H, F09H							

Hex Address: F0A

Table 140. Timer 0–1 Reload High Byte Register (TxRH)

Bit	7	6	5	4	3	2	1	0
Field	TRH							
RESET	1							
R/W	R/W							
Address	F02H, F0AH							

Hex Address: F63

Table 165. SPI Mode Register (SPIMODE)

Bit	7	6	5	4	3	2	1	0
Field	Reserved		DIAG	NUMBITS[2:0]			SSIO	SSV
RESET	0							
R/W	R		R/W					
Address	F63H							

Hex Address: F64

Table 166. SPI Diagnostic State Register (SPIDST)

Bit	7	6	5	4	3	2	1	0
Field	SCKEN	TCKEN	SPISTATE					
RESET	0							
R/W	R							
Address	F64H							

Hex Address: F65

This address is reserved.

Hex Address: F66

Table 167. SPI Baud Rate High Byte Register (SPIBRH)

Bit	7	6	5	4	3	2	1	0
Field	BRH							
RESET	1							
R/W	R/W							
Address	F66H							

Hex Address: FD6

Table 188. Port A–C Input Data Registers (PxIN)

Bit	7	6	5	4	3	2	1	0
Field	PIN7	PIN6	PIN5	PIN4	PIN3	PIN2	PIN1	PIN0
RESET	X							
R/W	R							
Address	FD2H, FD6H, FDAH							

Hex Address: FD7

Table 189. Port A–C Output Data Register (PxOUT)

Bit	7	6	5	4	3	2	1	0
Field	POUT7	POUT6	POUT5	POUT4	POUT3	POUT2	POUT1	POUT0
RESET	0							
R/W	R/W							
Address	FD3H, FD7H, FDBH							

Hex Address: FD8

Table 190. Port A–C GPIO Address Registers (PxADDR)

Bit	7	6	5	4	3	2	1	0
Field	PADDR[7:0]							
RESET	00H							
R/W	R/W							
Address	FD0H, FD4H, FD8H							

Hex Address: FD9

Table 191. Port A–C Control Registers (PxCTL)

Bit	7	6	5	4	3	2	1	0
Field	PCTL							
RESET	00H							
R/W	R/W							
Address	FD1H, FD5H, FD9H							