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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	XCore
Core Size	32-Bit 16-Core
Speed	1000MIPS
Connectivity	Configurable
Peripherals	-
Number of I/O	90
Program Memory Size	128KB (32K x 32)
Program Memory Type	SRAM
EEPROM Size	-
RAM Size	-
Voltage - Supply (Vcc/Vdd)	0.90V ~ 5.5V
Data Converters	A/D 8x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	217-LFBGA
Supplier Device Package	217-FBGA (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/xmos/xs1-a16a-128-fb217-i10

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It is our intention to provide you with accurate and comprehensive documentation for the hardware and software components used in this product. To subscribe to receive updates, visit <http://www.xmos.com/>.

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9 Boot Procedure

The device is kept in reset by driving RST_N low. When in reset, all GPIO pins are high impedance. When the device is taken out of reset by releasing RST_N the processor starts its internal reset process. After approximately 750,000 input clocks, all GPIO pins have their internal pull-resistor enabled, and the processor boots at a clock speed that depends on MODE0 and MODE1.

The processor boot procedure is illustrated in Figure 9. In normal usage, MODE[4:2] controls the boot source according to the table in Figure 10. If bit 5 of the security register (see §10.1) is set, the device boots from OTP.

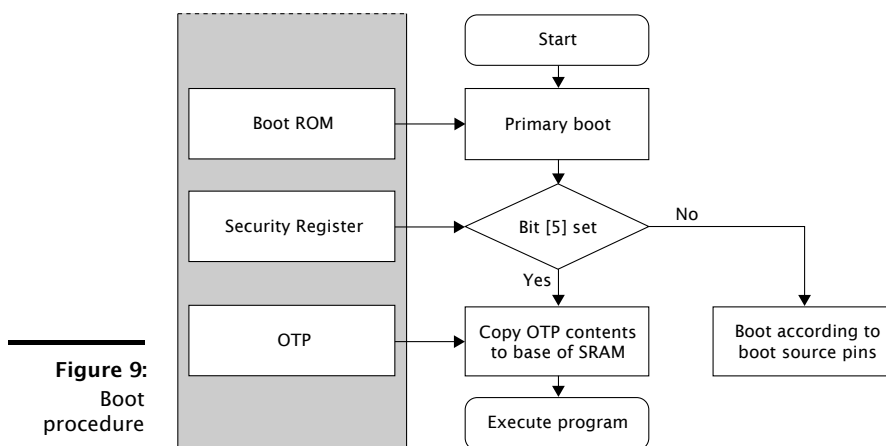


Figure 10:
Boot source pins

MODE [4]	MODE [3]	MODE [2]	Boot Source
X	0	0	None: Device waits to be booted via JTAG
X	0	1	Reserved
0	1	0	Tile0 boots from link B, Tile1 from channel end 0 via Tile0
0	1	1	Tile0 boots from SPI, Tile1 from channel end 0 via Tile0
1	1	0	Tile0 and Tile1 independently enable link B and internal links (E, F, G, H), and boot from channel end 0
1	1	1	Tile0 and Tile 1 boot from SPI independently

The boot image has the following format:

- ▶ A 32-bit program size s in words.
- ▶ Program consisting of $s \times 4$ bytes.
- ▶ A 32-bit CRC, or the value 0x0D15AB1E to indicate that no CRC check should be performed.

The program size and CRC are stored least significant byte first. The program is loaded into the lowest memory address of RAM, and the program is started from that address. The CRC is calculated over the byte stream represented by the program size and the program itself. The polynomial used is 0xEDB88320 (IEEE 802.3); the CRC register is initialized with 0xFFFFFFFF and the residue is inverted to produce the CRC.

9.1 Boot from SPI master

If set to boot from SPI master, the processor enables the four pins specified in Figure 11, and drives the SPI clock at 2.5 MHz (assuming a 400 MHz core clock). A READ command is issued with a 24-bit address 0x000000. The clock polarity and phase are 0 / 0.

Figure 11:
SPI master
pins

Pin	Signal	Description
X0D00	MISO	Master In Slave Out (Data)
X0D01	SS	Slave Select
X0D10	SCLK	Clock
X0D11	MOSI	Master Out Slave In (Data)

The xCORE Tile expects each byte to be transferred with the *least-significant bit first*. Programmers who write bytes into an SPI interface using the most significant bit first may have to reverse the bits in each byte of the image stored in the SPI device.

If a large boot image is to be read in, it is faster to first load a small boot-loader that reads the large image using a faster SPI clock, for example 50 MHz or as fast as the flash device supports.

The pins used for SPI boot are hardcoded in the boot ROM and cannot be changed. If required, an SPI boot program can be burned into OTP that uses different pins.

9.2 Boot from xConnect Link

If set to boot from an xConnect Link, the processor enables Link B around 200 ns after the boot process starts. Enabling the Link switches off the pull-down on resistors X0D16..X0D19, drives X0D16 and X0D17 low (the initial state for the Link), and monitors pins X0D18 and X0D19 for boot-traffic. X0D18 and X0D19 must be low at this stage. If the internal pull-down is too weak to drain any residual charge, external pull-downs of 10K may be required on those pins.

The boot-rom on the core will then:

1. Allocate channel-end 0.
2. Input a word on channel-end 0. It will use this word as a channel to acknowledge the boot. Provide the null-channel-end 0x0000FF02 if no acknowledgment is required.
3. Input the boot image specified above, including the CRC.

13.3 Deep Sleep Modes and Real-Time Counter

The normal mode in which the XS1-A16A-128-FB217 operates is the AWAKE mode. In this mode, all cores, memory, and peripherals operate as normal. To save power, the XS1-A16A-128-FB217 can be put into a deep sleep mode, called ASLEEP, where the digital node is powered down, and most peripherals are powered down. The XS1-A16A-128-FB217 will stay in the ASLEEP mode until one of two conditions:

1. An external pin is asserted or deasserted (set by the program);
2. The 64-bit real-time counter reaches a value set by the program; or

When the chip is awake, the real-time counter counts the number of clock ticks on the oscillator. As such, the real-time counter will run at a fixed ratio, but synchronously with the 100 MHz timers on the xCORE Tile. When asleep, the real-time counter can be automatically switched to the 31,250 Hz silicon oscillator to save power (see Appendix H). To ensure that the real-time counter increases linearly over time, a programmable value is added to the counter on every 31,250 Hz clock-tick. This means that the clock will run at a granularity of 31,250 Hz but still maintain real-time in terms of the frequency of the main oscillator. If an accurate clock is required, even whilst asleep, then an external crystal or oscillator shall be provided that is used in both AWAKE and ASLEEP state.

The designer has to make a trade-off between accuracy of clocks when asleep and awake, costs, and deep-sleep power consumption. Four example designs are shown in Figure 15.

Figure 15:
Example
trade-offs in
oscillator
selection

Clocks used		Power Asleep	BOM costs	Accuracy	
Awake	Asleep			Awake	Asleep
20 Mhz SiOsc	31,250 SiOsc	lowest	lowest	lowest	lowest
24 MHz Crystal	31,250 SiOsc	lowest	medium	highest	lowest
5 MHz ext osc	5 MHz ext osc	medium	highest	highest	highest
24 MHz Crystal	24 MHz crystal	highest	medium	highest	highest

During deep-sleep, the program can store some state in 128 bytes of Deep Sleep Memory.

13.4 Requirements during sleep mode

Whilst in sleep mode, the device must still be powered as normal over 3V3 or 5V0 on VSUP, and 3V3 on VDDIO; however it will draw less power on both VSUP and VDDIO.

For best results (lowest power):

- The XTAL bias and XTAL oscillators should be switched off.
- The sleep register should be configured to

The power supplies must be brought up monotonically and input voltages must not exceed specification at any time.

The VDDIO supply to the XS1-A16A-128-FB217 requires a 100nF X5R or X7R ceramic decoupling capacitor placed as close as possible to the supply pins. VDDIO_OUT is the switched IO supply; it is only supplied when the chip is AWAKE. This pin can be used to provide extra decoupling, or it can be used to switch other devices off during sleep mode, for example a SPI flash. No more than 240 mA should be drawn on VDDIO at any time: this includes any supply sourced statically (e.g., driving a LED from a GPIO pin), any dynamic power consumption (e.g., toggling a GPIO pin at a high frequency) and any devices powered through VDDIO_OUT.

If the ADC is used, it requires a 100nF X5R or X7R ceramic decoupling capacitor placed as close as possible to the AVDD pin. Care should be taken to minimize noise on these inputs, and if necessary an extra 10uF decoupling capacitor and ferrite bead can be used to remove noise from this supply.

The crystal oscillator requires careful routing of the XI / XO nodes as these are high impedance and very noise sensitive. Hence, the traces should be as wide and short as possible, and routed over a continuous ground plane. They should not be routed near noisy supply lines or clocks. The device has a load capacitance of 18pF for the crystal. Care must be taken, so that the inductance and resistance of the ground returns from the capacitors to the ground of the device is minimized.

15.1 Land patterns and solder stencils

The land pattern recommendations in this document are based on a RoHS compliant process and derived, where possible, from the nominal *Generic Requirements for Surface Mount Design and Land Pattern Standards* [IPC-7351B](#) specifications. This standard aims to achieve desired targets of heel, toe and side fillets for solder-joints.

Solder paste and ground via recommendations are based on our engineering and development kit board production. They have been found to work and optimized as appropriate to achieve a high yield. These factors should be taken into account during design and manufacturing of the PCB.

The following land patterns and solder paste contains recommendations. Final land pattern and solder paste decisions are the responsibility of the customer. These should be tuned during manufacture to suit the manufacturing process.

The package is a 217 pin Fine Ball Grid Array package on a 0.8mm pitch with 0.4mm balls.

An example land pattern is shown in Figure [20](#).

Pad widths and spacings are such that solder mask can still be applied between the pads using standard design rules. This is highly recommended to reduce solder shorts.

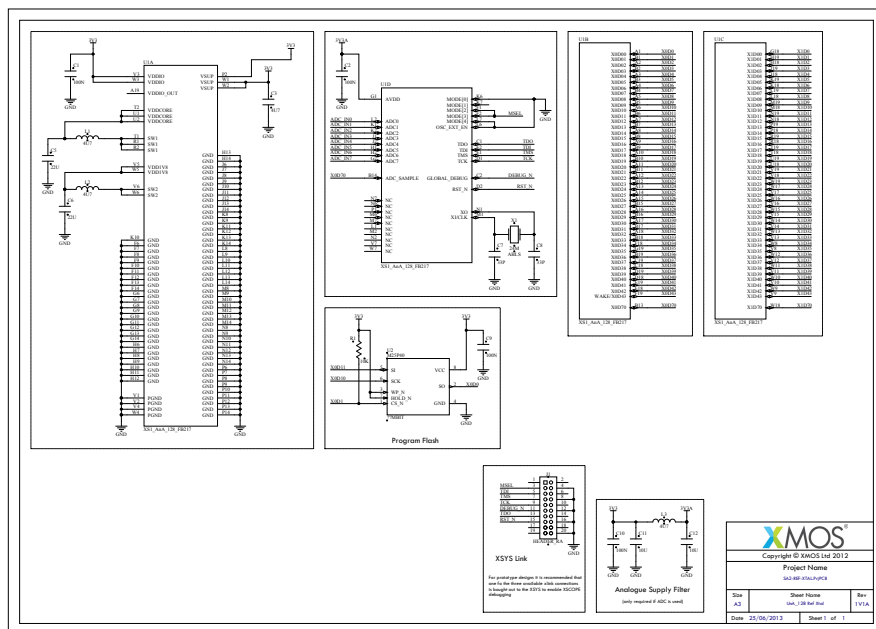
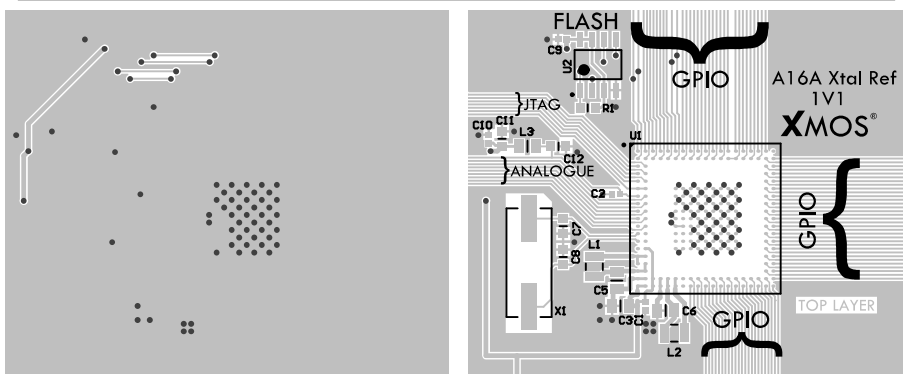


Figure 21:
Example
XTAL
schematic,
with top and
bottom
layout of a
2-layer PCB



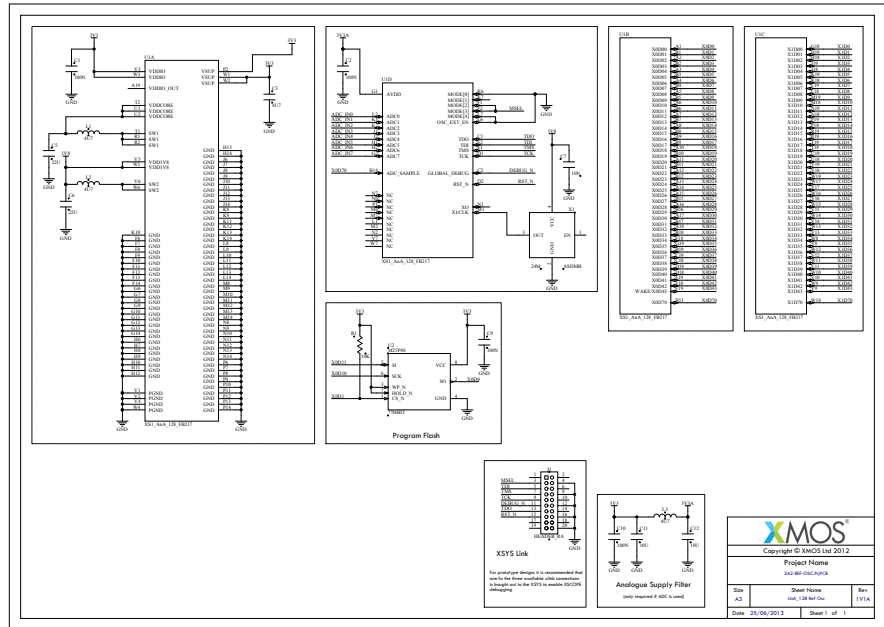
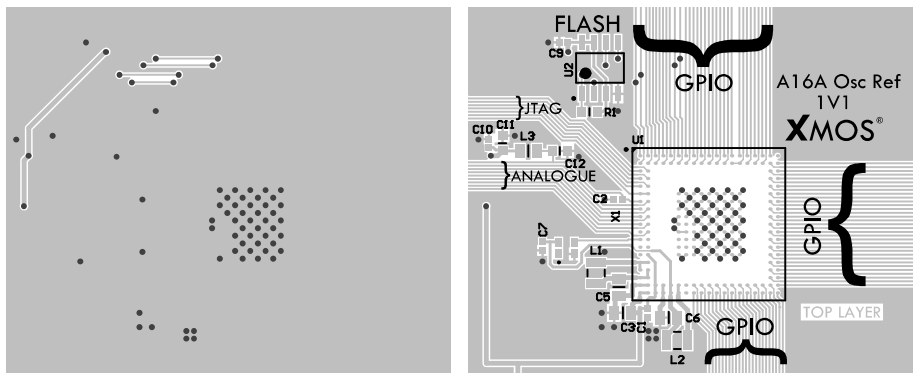


Figure 22:
Example
Oscillator
schematic,
with top and
bottom
layout of a
2-layer PCB



17.5 Digital I/O Characteristics

Figure 28:
Digital I/O
characteris-
tics

Symbol	Parameter	MIN	TYP	MAX	UNITS	Notes
V(IH)	Input high voltage	2.00		3.60	V	A
V(IL)	Input low voltage	-0.30		0.70	V	A
V(OH)	Output high voltage	2.00			V	B, C
V(OL)	Output low voltage			0.60	V	B, C
R(PU)	Pull-up resistance		35K		Ω	D
R(PD)	Pull-down resistance		35K		Ω	D

A All pins except power supply pins.

B Ports 1A, 1D, 1E, 1H, 1I, 1J, 1K and 1L are nominal 8 mA drivers, the remainder of the general-purpose I/Os are 4 mA.

C Measured with 4 mA drivers sourcing 4 mA, 8 mA drivers sourcing 8 mA.

D Used to guarantee logic state for an I/O when high impedance. The internal pull-ups/pull-downs should not be used to pull external circuitry.

17.6 ESD Stress Voltage

Figure 29:
ESD stress
voltage

Symbol	Parameter	MIN	TYP	MAX	UNITS	Notes
HBM	Human body model			2.00	kV	
CDM	Charged Device Model			500	V	

17.7 Device Timing Characteristics

Figure 30:
Device timing
characteris-
tics

Symbol	Parameter	MIN	TYP	MAX	UNITS	Notes
T(RST)	Reset pulse width	5			μ s	
T(INIT)	Initialisation (On Silicon Oscillator)			TBC	ms	A
	Initialisation (Crystal Oscillator)			TBC	ms	
T(WAKE)	Wake up time (Sleep to Active)			TBC	ms	
T(SLEEP)	Sleep Time (Active to Sleep)			TBC	ms	

A Shows the time taken to start booting after RST_N has gone high.

17.8 Crystal Oscillator Characteristics

Figure 31:
Crystal
oscillator
characteris-
tics

Symbol	Parameter	MIN	TYP	MAX	UNITS	Notes
F(FO)	Input Frequency	5		30	MHz	

A channel-end should be allocated to communicate with the configuration registers. The destination of the channel-end should be set to `0xnnnnpp02` where `nnnn` is the node-identifier and `pp` is the peripheral identifier.

A write message comprises the following:

control-token 36	24-bit response channel-end identifier	8-bit register number	8-bit size	data	control-token 1
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The response to a write message comprises either control tokens 3 and 1 (for success), or control tokens 4 and 1 (for failure).

A read message comprises the following:

control-token 37	24-bit response channel-end identifier	8-bit register number	8-bit size	control-token 1
---------------------	---	--------------------------	---------------	--------------------

The response to the read message comprises either control token 3, data, and control-token 1 (for success), or control tokens 4 and 1 (for failure).

B.1 RAM base address: 0x00

This register contains the base address of the RAM. It is initialized to 0x00010000.

0x00: RAM base address	Bits	Perm	Init	Description
	31:2	RW		Most significant 16 bits of all addresses.
	1:0	RO	-	Reserved

B.2 Vector base address: 0x01

Base address of event vectors in each resource. On an interrupt or event, the 16 most significant bits of the destination address are provided by this register; the least significant 16 bits come from the event vector.

0x01: Vector base address	Bits	Perm	Init	Description
	31:16	RW		The most significant bits for all event and interrupt vectors.
	15:0	RO	-	Reserved

B.3 xCORE Tile control: 0x02

Register to control features in the xCORE tile

0x02: xCORE Tile control	Bits	Perm	Init	Description
	31:6	RO	-	Reserved
	5	RW	0	Set to 1 to select the dynamic mode for the clock divider when the clock divider is enabled. In dynamic mode the clock divider is only activated when all active logical cores are paused. In static mode the clock divider is always enabled.
	4	RW	0	Set to 1 to enable the clock divider. This slows down the xCORE tile clock in order to use less power.
	3:0	RO	-	Reserved

B.4 xCORE Tile boot status: 0x03

This read-only register describes the boot status of the xCORE tile.

0x11: Debug SPC	Bits	Perm	Init	Description
	31:0	DRW		Value.

B.13 Debug SSP: 0x12

This register contains the value of the SSP register when the debugger was called.

0x12: Debug SSP	Bits	Perm	Init	Description
	31:0	DRW		Value.

B.14 DGETREG operand 1: 0x13

The resource ID of the logical core whose state is to be read.

0x13: DGETREG operand 1	Bits	Perm	Init	Description
	31:8	RO	-	Reserved
	7:0	DRW		Thread number to be read

B.15 DGETREG operand 2: 0x14

Register number to be read by DGETREG

0x14: DGETREG operand 2	Bits	Perm	Init	Description
	31:5	RO	-	Reserved
	4:0	DRW		Register number to be read

B.16 Debug interrupt type: 0x15

Register that specifies what activated the debug interrupt.

B.19 Debug scratch: 0x20 .. 0x27

A set of registers used by the debug ROM to communicate with an external debugger, for example over JTAG. This is the same set of registers as the [Debug Scratch registers in the xCORE tile configuration](#).

0x20 .. 0x27:
Debug
scratch

Bits	Perm	Init	Description
31:0	DRW		Value.

B.20 Instruction breakpoint address: 0x30 .. 0x33

This register contains the address of the instruction breakpoint. If the PC matches this address, then a debug interrupt will be taken. There are four instruction breakpoints that are controlled individually.

0x30 .. 0x33:
Instruction
breakpoint
address

Bits	Perm	Init	Description
31:0	DRW		Value.

B.21 Instruction breakpoint control: 0x40 .. 0x43

This register controls which logical cores may take an instruction breakpoint, and under which condition.

0x40 .. 0x43:
Instruction
breakpoint
control

Bits	Perm	Init	Description
31:24	RO	-	Reserved
23:16	DRW	0	A bit for each logical core in the tile allowing the breakpoint to be enabled individually for each logical core.
15:2	RO	-	Reserved
1	DRW	0	Set to 1 to cause an instruction breakpoint if the PC is not equal to the breakpoint address. By default, the breakpoint is triggered when the PC is equal to the breakpoint address.
0	DRW	0	When 1 the instruction breakpoint is enabled.

B.22 Data watchpoint address 1: 0x50 .. 0x53

This set of registers contains the first address for the four data watchpoints.

C xCORE Tile Configuration

The xCORE Tile control registers can be accessed using configuration reads and writes (use `write_tile_config_reg(tileref, ...)` and `read_tile_config_reg(tileref, ...)` for reads and writes).

Number	Perm	Description
0x00	RO	Device identification
0x01	RO	xCORE Tile description 1
0x02	RO	xCORE Tile description 2
0x04	CRW	Control PSwitch permissions to debug registers
0x05	CRW	Cause debug interrupts
0x06	RW	xCORE Tile clock divider
0x07	RO	Security configuration
0x10 .. 0x13	RO	PLink status
0x20 .. 0x27	CRW	Debug scratch
0x40	RO	PC of logical core 0
0x41	RO	PC of logical core 1
0x42	RO	PC of logical core 2
0x43	RO	PC of logical core 3
0x44	RO	PC of logical core 4
0x45	RO	PC of logical core 5
0x46	RO	PC of logical core 6
0x47	RO	PC of logical core 7
0x60	RO	SR of logical core 0
0x61	RO	SR of logical core 1
0x62	RO	SR of logical core 2
0x63	RO	SR of logical core 3
0x64	RO	SR of logical core 4
0x65	RO	SR of logical core 5
0x66	RO	SR of logical core 6
0x67	RO	SR of logical core 7
0x80 .. 0x9F	RO	Chanend status

Figure 42:
Summary

C.1 Device identification: 0x00

0x00: Device identification	Bits	Perm	Init	Description
	31:24	RO		Processor ID of this xCORE tile.
	23:16	RO		Number of the node in which this xCORE tile is located.
	15:8	RO		xCORE tile revision.
	7:0	RO		xCORE tile version.

C.2 xCORE Tile description 1: 0x01

This register describes the number of logical cores, synchronisers, locks and channel ends available on this xCORE tile.

0x01: xCORE Tile description 1	Bits	Perm	Init	Description
	31:24	RO		Number of channel ends.
	23:16	RO		Number of locks.
	15:8	RO		Number of synchronisers.
	7:0	RO	-	Reserved

C.3 xCORE Tile description 2: 0x02

This register describes the number of timers and clock blocks available on this xCORE tile.

0x02: xCORE Tile description 2	Bits	Perm	Init	Description
	31:16	RO	-	Reserved
	15:8	RO		Number of clock blocks.
	7:0	RO		Number of timers.

C.4 Control PSwitch permissions to debug registers: 0x04

This register can be used to control whether the debug registers (marked with permission CRW) are accessible through the tile configuration registers. When this bit is set, write -access to those registers is disabled, preventing debugging of the xCORE tile over the interconnect.

D.11 Debug source: 0x1F

Contains the source of the most recent debug event.

0x1F:
Debug source

Bits	Perm	Init	Description
31:5	RO	-	Reserved
4	RW		If set, the external DEBUG_N pin is the source of the most recent debug interrupt.
3:1	RO	-	Reserved
0	RW		If set, the xCORE Tile is the source of the most recent debug interrupt.

D.12 Link status, direction, and network: 0x20 .. 0x27

These registers contain status information for low level debugging (read-only), the network number that each link belongs to, and the direction that each link is part of. The registers control links C, D, A, B, G, H, E, and F in that order.

0x20 .. 0x27:
Link status,
direction, and
network

Bits	Perm	Init	Description
31:26	RO	-	Reserved
25:24	RO		If this link is currently routing data into the switch, this field specifies the type of link that the data is routed to: 0: plink 1: external link 2: internal control link
23:16	RO	0	If the link is routing data into the switch, this field specifies the destination link number to which all tokens are sent.
15:12	RO	-	Reserved
11:8	RW	0	The direction that this this link is associated with; set for routing.
7:6	RO	-	Reserved
5:4	RW	0	Determines the network to which this link belongs, set for quality of service.
3	RO	-	Reserved
2	RO	0	Set to 1 if the current packet is junk and being thrown away. A packet is considered junk if, for example, it is not routable.
1	RO	0	Set to 1 if the switch is routing data into the link, and if a route exists from another link.
0	RO	0	Set to 1 if the link is routing data into the switch, and if a route is created to another link on the switch.

0x04: Node configuration register	Bits	Perm	Init	Description
	31	RW	0	Set to 1 to disable further updates to the node configuration and link control and status registers.
	30:1	RO	-	Reserved
	0	RW	0	Header mode. 0: 3-byte headers; 1: 1-byte headers.

E.3 Node identifier: 0x05

0x05: Node identifier	Bits	Perm	Init	Description
	31:16	RO	-	Reserved
	15:0	RW	0	16-bit node identifier. This does not need to be set, and is present for compatibility with XS1-switches.

E.4 Reset and Mode Control: 0x50

The XS1-S has two main reset signals: a system-reset and an xCORE Tile-reset. System-reset resets the whole system including external devices, whilst xCORE Tile-reset resets the xCORE Tile(s) only. The resets are induced either by software (by a write to the register below) or by one of the following:

- * External reset on RST_N (System reset)
- * Brown out on one of the power supplies (System reset)
- * Watchdog timer (System reset)
- * Sleep sequence (xCORE Tile reset)
- * Clock source change (xCORE Tile reset)

The minimum system reset duration is achieved when the fastest permissible clock is used. The reset durations will be proportionately longer when a slower clock is used. Note that the minimum system reset duration allows for all power rails except the VOUT2 to turn off, and decay.

The length of the system reset comes from an internal counter, counting 524,288 oscillator clock cycles which gives the maximum time allowable for the supply rails to discharge. The system reset duration is a balance between leaving a long time for the supply rails to discharge, and a short time for the system to boot. Example reset times are 44 ms with a 12 MHz oscillator or 5.5 ms with a 96 MHz oscillator.

H.1 General oscillator control: 0x00

0x00:
General
oscillator
control

Bits	Perm	Init	Description
7:2	RO	-	Reserved
1	RW	0	Set to 1 to reset the xCORE Tile when the value of the oscillator select control register (bit 0) is changed.
0	RW	pin	Selects the oscillator to use: 0: Crystal oscillator 1: On-silicon oscillator

H.2 On-silicon-oscillator control: 0x01

This register controls the on-chip logic that implements an on-chip oscillator. The on-chip oscillator does not require an external crystal, but does not provide an accurate timing source. The nominal frequency of the on-silicon-oscillator is given below, but the actual frequency are temperature, voltage, and chip dependent.

0x01:
On-silicon-
oscillator
control

Bits	Perm	Init	Description
7:2	RO	-	Reserved
1	RW	0	Selects the clock speed of the on-chip oscillator: 0: approximately 20 Mhz (fast clock) 1: approximately 31,250 Hz (slow clock)
0	RW	1	Set to 0 to disable the on-chip oscillator. Do not do this unless the xCORE Tile is running off the crystal oscillator.

H.3 Crystal-oscillator control: 0x02

This register controls the on-chip logic that implements the crystal oscillator; the crystal-oscillator requires an external crystal.

0x02:
Crystal-
oscillator
control

Bits	Perm	Init	Description
7:2	RO	-	Reserved
1	RW	1	Set to 0 to disable the crystal bias circuit. Only switch the bias off if an external oscillator rather than a crystal is connected.
0	RW	1	Set to 0 to disable the crystal oscillator. Do not do this unless the xCORE Tile is running off the on-silicon oscillator.

Number	Perm	Description
0x00	RW	General control
0x04	RW	Time to wake-up, least significant 32 bits
0x08	RW	Time to wake-up, most significant 32 bits
0x0C	RW	Power supply states whilst ASLEEP
0x10	RW	Power supply states whilst WAKING1
0x14	RW	Power supply states whilst WAKING2
0x18	RW	Power supply states whilst AWAKE
0x1C	RW	Power supply states whilst SLEEPING1
0x20	RW	Power supply states whilst SLEEPING2
0x24	RW	Power sequence status
0x2C	RW	DCDC control
0x30	RW	Power supply status
0x34	RW	VDDCORE level control
0x40	RW	LDO5 level control

Figure 49:
Summary

J.1 General control: 0x00

This register controls the basic settings for power modes.

Bits	Perm	Init	Description
31:21	RO	-	Reserved
20:16	RW	16	Log2 number of cycles to stay in this state: 0: 1 clock cycles 1: 2 clock cycles 2: 4 clock cycles ... 31: 2147483648 clock cycles
15	RO	-	Reserved
14	RW	0	Set to 1 to disable clock to the xCORE Tile.
13:10	RO	-	Reserved
9	RW	0	Sets modulation used by DCDC2: 0: PWM modulation (max 475 mA) 1: PFM modulation (max 50 mA)
8	RW	0	Sets modulation used by DCDC1: 0: PWM modulation (max 700 mA) 1: PFM modulation (max 50 mA)
7:6	RO	-	Reserved
5	RW	1	Set to 1 to enable VOUT6 (IO supply).
4	RW	0	Set to 1 to enable LDO5 (core PLL supply).
3:2	RO	-	Reserved
1	RO	1	Set to 1 to enable DCDC2 (analogue supply).
0	RW	0	Set to 1 to enable DCDC1 (core supply).

0x1C:
Power supply
states whilst
SLEEPING1

J.9 Power supply states whilst SLEEPING2: 0x20

This register controls what state the power control block should be in when in the SLEEPING2 state. It also defines the time that the system shall stay in this state.

0x30:
Power supply
status

Bits	Perm	Init	Description
31:25	RO	-	Reserved
24	RO		1 if on-silicon oscillator is stable.
23:20	RO	-	Reserved
19	RO		1 if VDDPLL is good.
18:17	RO	-	Reserved
16	RO		1 if VDDCORE is good.
15:10	RO	-	Reserved
9	RO		1 if DCDC2 is in current limiting mode.
8	RO		1 if DCDC1 is in current limiting mode.
7:2	RO	-	Reserved
1	RO		1 if DCDC2 is in soft-start mode.
0	RO		1 if DCDC1 is in soft-start mode.

J.13 VDDCORE level control: 0x34

This register can be used to set the desired voltage on VDDCORE. If the level is to be raised or lowered, it should be raised in steps of no more than 10 mV per microsecond in order to prevent overshoot and undershoot. The default value depends on the MODE pins.

0x34:
VDDCORE
level control

Bits	Perm	Init	Description
31:7	RO	-	Reserved
6:0	RW	pin	The required voltage in 10 mV steps: 0: 0.60V 1: 0.61V 2: 0.62V ... 69: 1.29V 70: 1.30V

J.14 LDO5 level control: 0x40

This register can be used to set the desired voltage on LDO5. If the level is to be raised, it should be raised in steps of 1 (100 mV). The default value depends on the MODE pins.