

Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex® -M0+
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, I ² S, LCD, POR, PWM, WDT
Number of I/O	84
Program Memory Size	192KB (192K x 8)
Program Memory Type	FLASH
EEPROM Size	3K x 8
RAM Size	20K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 16x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-UFBGA
Supplier Device Package	100-UFBGA (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32l083vzi6

Contents

1	Introduction	9
2	Description	10
2.1	Device overview	11
2.2	Ultra-low-power device continuum	13
3	Functional overview	14
3.1	Low-power modes	14
3.2	Interconnect matrix	19
3.3	ARM® Cortex®-M0+ core with MPU	20
3.4	Reset and supply management	21
3.4.1	Power supply schemes	21
3.4.2	Power supply supervisor	21
3.4.3	Voltage regulator	22
3.5	Clock management	22
3.6	Low-power real-time clock and backup registers	25
3.7	General-purpose inputs/outputs (GPIOs)	25
3.8	Memories	26
3.9	Boot modes	26
3.10	Direct memory access (DMA)	27
3.11	Liquid crystal display (LCD)	27
3.12	Analog-to-digital converter (ADC)	27
3.13	Temperature sensor	28
3.13.1	Internal voltage reference (V_{REFINT})	28
3.13.2	V_{LCD} voltage monitoring	29
3.14	Digital-to-analog converter (DAC)	29
3.15	Ultra-low-power comparators and reference voltage	29
3.16	Touch sensing controller (TSC)	30
3.17	AES	31
3.18	Timers and watchdogs	31
3.18.1	General-purpose timers (TIM2, TIM3, TIM21 and TIM22)	31
3.18.2	Low-power Timer (LPTIM)	32

3.18.3	Basic timer (TIM6, TIM7)	32
3.18.4	SysTick timer	32
3.18.5	Independent watchdog (IWDG)	32
3.18.6	Window watchdog (WWDG)	33
3.19	Communication interfaces	33
3.19.1	I2C bus	33
3.19.2	Universal synchronous/asynchronous receiver transmitter (USART) . .	34
3.19.3	Low-power universal asynchronous receiver transmitter (LPUART) . .	35
3.19.4	Serial peripheral interface (SPI)/Inter-integrated sound (I2S)	35
3.19.5	Universal serial bus (USB)	36
3.20	Clock recovery system (CRS)	36
3.21	Cyclic redundancy check (CRC) calculation unit	36
3.22	Serial wire debug port (SW-DP)	36
4	Pin descriptions	37
5	Memory mapping	56
6	Electrical characteristics	57
6.1	Parameter conditions	57
6.1.1	Minimum and maximum values	57
6.1.2	Typical values	57
6.1.3	Typical curves	57
6.1.4	Loading capacitor	57
6.1.5	Pin input voltage	57
6.1.6	Power supply scheme	58
6.1.7	Optional LCD power supply scheme	59
6.1.8	Current consumption measurement	59
6.2	Absolute maximum ratings	60
6.3	Operating conditions	62
6.3.1	General operating conditions	62
6.3.2	Embedded reset and power control block characteristics	64
6.3.3	Embedded internal reference voltage	65
6.3.4	Supply current characteristics	66
6.3.5	Wakeup time from low-power mode	78
6.3.6	External clock source characteristics	80
6.3.7	Internal clock source characteristics	84

6.3.8	PLL characteristics	87
6.3.9	Memory characteristics	88
6.3.10	EMC characteristics	89
6.3.11	Electrical sensitivity characteristics	91
6.3.12	I/O current injection characteristics	92
6.3.13	I/O port characteristics	93
6.3.14	NRST pin characteristics	97
6.3.15	12-bit ADC characteristics	98
6.3.16	DAC electrical specifications	104
6.3.17	Temperature sensor characteristics	106
6.3.18	Comparators	107
6.3.19	Timer characteristics	108
6.3.20	Communications interfaces	108
6.3.21	LCD controller	117
7	Package information	119
7.1	LQFP100 package information	119
7.2	UFBGA100 package information	122
7.3	LQFP64 package information	125
7.4	TFBGA64 package information	128
7.5	LQFP48 package information	131
7.6	Thermal characteristics	134
7.6.1	Reference document	135
8	Part numbering	136
9	Revision history	137

List of figures

Figure 1.	STM32L083xx block diagram	12
Figure 2.	Clock tree	24
Figure 3.	STM32L083xx LQFP100 pinout - 14 x 14 mm	37
Figure 4.	STM32L083xx UFBGA100 ballout - 7x 7 mm.	38
Figure 5.	STM32L083xx LQFP64 pinout - 10 x 10 mm	39
Figure 6.	STM32L083xx TFBGA64 ballout - 5x 5 mm.	40
Figure 7.	STM32L083xx LQFP48 pinout - 7 x 7 mm	41
Figure 8.	Memory map	56
Figure 9.	Pin loading conditions.	57
Figure 10.	Pin input voltage	57
Figure 11.	Power supply scheme	58
Figure 12.	Optional LCD power supply scheme	59
Figure 13.	Current consumption measurement scheme	59
Figure 14.	IDD vs VDD, at TA= 25/55/85/105 °C, Run mode, code running from Flash memory, Range 2, HSE, 1WS	68
Figure 15.	IDD vs VDD, at TA= 25/55/85/105 °C, Run mode, code running from Flash memory, Range 2, HSI16, 1WS	68
Figure 16.	IDD vs VDD, at TA= 25 °C, Low-power run mode, code running from RAM, Range 3, MSI (Range 0) at 64 KHz, 0 WS	72
Figure 17.	IDD vs VDD, at TA= 25/55/ 85/105/125 °C, Stop mode with RTC enabled and running on LSE Low drive	73
Figure 18.	IDD vs VDD, at TA= 25/55/85/105/125 °C, Stop mode with RTC disabled, all clocks off	74
Figure 19.	High-speed external clock source AC timing diagram	80
Figure 20.	Low-speed external clock source AC timing diagram	81
Figure 21.	HSE oscillator circuit diagram	82
Figure 22.	Typical application with a 32.768 kHz crystal	83
Figure 23.	HSI16 minimum and maximum value versus temperature	84
Figure 24.	VIH/VIL versus VDD (CMOS I/Os)	94
Figure 25.	VIH/VIL versus VDD (TTL I/Os)	94
Figure 26.	I/O AC characteristics definition	97
Figure 27.	Recommended NRST pin protection	98
Figure 28.	ADC accuracy characteristics.	101
Figure 29.	Typical connection diagram using the ADC	102
Figure 30.	Power supply and reference decoupling (V_{REF+} not connected to V_{DDA}).	102
Figure 31.	Power supply and reference decoupling (V_{REF+} connected to V_{DDA}).	103
Figure 32.	12-bit buffered/non-buffered DAC.	106
Figure 33.	SPI timing diagram - slave mode and CPHA = 0	112
Figure 34.	SPI timing diagram - slave mode and CPHA = 1 ⁽¹⁾	113
Figure 35.	SPI timing diagram - master mode ⁽¹⁾	113
Figure 36.	I ² S slave timing diagram (Philips protocol) ⁽¹⁾	115
Figure 37.	I ² S master timing diagram (Philips protocol) ⁽¹⁾	115
Figure 38.	USB timings: definition of data signal rise and fall time	117
Figure 39.	LQFP100 - 100-pin, 14 x 14 mm low-profile quad flat package outline	119
Figure 40.	LQFP100 - 100-pin, 14 x 14 mm low-profile quad flat recommended footprint.	121
Figure 41.	LQFP100 marking example (package top view)	121
Figure 42.	UFBGA100 - 100-pin, 7 x 7 mm, 0.50 mm pitch, ultra fine pitch ball	

2.2 Ultra-low-power device continuum

The ultra-low-power family offers a large choice of core and features, from 8-bit proprietary core up to ARM® Cortex®-M4, including ARM® Cortex®-M3 and ARM® Cortex®-M0+. The STM32Lx series are the best choice to answer your needs in terms of ultra-low-power features. The STM32 ultra-low-power series are the best solution for applications such as gaz/water meter, keyboard/mouse or fitness and healthcare application. Several built-in features like LCD drivers, dual-bank memory, low-power run mode, operational amplifiers, 128-bit AES, DAC, crystal-less USB and many other definitely help you building a highly cost optimized application by reducing BOM cost. STMicroelectronics, as a reliable and long-term manufacturer, ensures as much as possible pin-to-pin compatibility between all STM8Lx and STM32Lx on one hand, and between all STM32Lx and STM32Fx on the other hand. Thanks to this unprecedented scalability, your legacy application can be upgraded to respond to the latest market feature and efficiency requirements.

Table 3. Functionalities depending on the operating power supply range

Operating power supply range	Functionalities depending on the operating power supply range			
	DAC and ADC operation	Dynamic voltage scaling range	I/O operation	USB
$V_{DD} = 1.65$ to 1.71 V	ADC only, conversion time up to 570 ksp/s	Range 2 or range 3	Degraded speed performance	Not functional
$V_{DD} = 1.71$ to 1.8 V ⁽¹⁾	ADC only, conversion time up to 1.14 Msp/s	Range 1, range 2 or range 3	Degraded speed performance	Functional ⁽²⁾
$V_{DD} = 1.8$ to 2.0 V ⁽¹⁾	Conversion time up to 1.14 Msp/s	Range 1, range 2 or range 3	Degraded speed performance	Functional ⁽²⁾
$V_{DD} = 2.0$ to 2.4 V	Conversion time up to 1.14 Msp/s	Range 1, range 2 or range 3	Full speed operation	Functional ⁽²⁾
$V_{DD} = 2.4$ to 3.6 V	Conversion time up to 1.14 Msp/s	Range 1, range 2 or range 3	Full speed operation	Functional ⁽²⁾

1. CPU frequency changes from initial to final must respect "fcpu initial < 4*fcpu final". It must also respect 5 μ s delay between two changes. For example to switch from 4.2 MHz to 32 MHz, you can switch from 4.2 MHz to 16 MHz, wait 5 μ s, then switch from 16 MHz to 32 MHz.

2. To be USB compliant from the I/O voltage standpoint, the minimum V_{DD_USB} is 3.0 V.

Table 4. CPU frequency range depending on dynamic voltage scaling

CPU frequency range	Dynamic voltage scaling range
16 MHz to 32 MHz (1ws) 32 kHz to 16 MHz (0ws)	Range 1
8 MHz to 16 MHz (1ws) 32 kHz to 8 MHz (0ws)	Range 2
32 kHz to 4.2 MHz (0ws)	Range 3

3.3 ARM® Cortex®-M0+ core with MPU

The Cortex-M0+ processor is an entry-level 32-bit ARM Cortex processor designed for a broad range of embedded applications. It offers significant benefits to developers, including:

- a simple architecture that is easy to learn and program
- ultra-low power, energy-efficient operation
- excellent code density
- deterministic, high-performance interrupt handling
- upward compatibility with Cortex-M processor family
- platform security robustness, with integrated Memory Protection Unit (MPU).

The Cortex-M0+ processor is built on a highly area and power optimized 32-bit processor core, with a 2-stage pipeline Von Neumann architecture. The processor delivers exceptional energy efficiency through a small but powerful instruction set and extensively optimized design, providing high-end processing hardware including a single-cycle multiplier.

The Cortex-M0+ processor provides the exceptional performance expected of a modern 32-bit architecture, with a higher code density than other 8-bit and 16-bit microcontrollers.

Owing to its embedded ARM core, the STM32L083xx are compatible with all ARM tools and software.

Nested vectored interrupt controller (NVIC)

The ultra-low-power STM32L083xx embed a nested vectored interrupt controller able to handle up to 32 maskable interrupt channels and 4 priority levels.

The Cortex-M0+ processor closely integrates a configurable Nested Vectored Interrupt Controller (NVIC), to deliver industry-leading interrupt performance. The NVIC:

- includes a Non-Maskable Interrupt (NMI)
- provides zero jitter interrupt option
- provides four interrupt priority levels

The tight integration of the processor core and NVIC provides fast execution of Interrupt Service Routines (ISRs), dramatically reducing the interrupt latency. This is achieved through the hardware stacking of registers, and the ability to abandon and restart load-multiple and store-multiple operations. Interrupt handlers do not require any assembler wrapper code, removing any code overhead from the ISRs. Tail-chaining optimization also significantly reduces the overhead when switching from one ISR to another.

To optimize low-power designs, the NVIC integrates with the sleep modes, that include a deep sleep function that enables the entire device to enter rapidly stop or standby mode.

This hardware block provides flexible interrupt management features with minimal interrupt latency.

3.4 Reset and supply management

3.4.1 Power supply schemes

- $V_{DD} = 1.65$ to 3.6 V: external power supply for I/Os and the internal regulator. Provided externally through V_{DD} pins.
- V_{SSA} , $V_{DDA} = 1.65$ to 3.6 V: external analog power supplies for ADC reset blocks, RCs and PLL. V_{DDA} and V_{SSA} must be connected to V_{DD} and V_{SS} , respectively.
- $V_{DD_USB} = 1.65$ to 3.6 V: external power supply for USB transceiver, USB_DM (PA11) and USB_DP (PA12). To guarantee a correct voltage level for USB communication V_{DD_USB} must be above 3.0 V. If USB is not used this pin must be tied to V_{DD} .

3.4.2 Power supply supervisor

The devices have an integrated ZEROPOWER power-on reset (POR)/power-down reset (PDR) that can be coupled with a brownout reset (BOR) circuitry.

Two versions are available:

- The version with BOR activated at power-on operates between 1.8 V and 3.6 V.
- The other version without BOR operates between 1.65 V and 3.6 V.

After the V_{DD} threshold is reached (1.65 V or 1.8 V depending on the BOR which is active or not at power-on), the option byte loading process starts, either to confirm or modify default thresholds, or to disable the BOR permanently: in this case, the VDD min value becomes 1.65 V (whatever the version, BOR active or not, at power-on).

When BOR is active at power-on, it ensures proper operation starting from 1.8 V whatever the power ramp-up phase before it reaches 1.8 V. When BOR is not active at power-up, the power ramp-up should guarantee that 1.65 V is reached on V_{DD} at least 1 ms after it exits the POR area.

Five BOR thresholds are available through option bytes, starting from 1.8 V to 3 V. To reduce the power consumption in Stop mode, it is possible to automatically switch off the internal reference voltage (V_{REFINT}) in Stop mode. The device remains in reset mode when V_{DD} is below a specified threshold, $V_{POR/PDR}$ or V_{BOR} , without the need for any external reset circuit.

Note: *The start-up time at power-on is typically 3.3 ms when BOR is active at power-up, the start-up time at power-on can be decreased down to 1 ms typically for devices with BOR inactive at power-up.*

The devices feature an embedded programmable voltage detector (PVD) that monitors the $V_{DD/VDDA}$ power supply and compares it to the V_{PVD} threshold. This PVD offers 7 different levels between 1.85 V and 3.05 V, chosen by software, with a step around 200 mV. An interrupt can be generated when $V_{DD/VDDA}$ drops below the V_{PVD} threshold and/or when $V_{DD/VDDA}$ is higher than the V_{PVD} threshold. The interrupt service routine can then generate a warning message and/or put the MCU into a safe state. The PVD is enabled by software.

3.19.3 Low-power universal asynchronous receiver transmitter (LPUART)

The devices embed one Low-power UART. The LPUART supports asynchronous serial communication with minimum power consumption. It supports half duplex single wire communication and modem operations (CTS/RTS). It allows multiprocessor communication.

The LPUART has a clock domain independent from the CPU clock. It can wake up the system from Stop mode using baudrates up to 46 Kbaud. The Wakeup events from Stop mode are programmable and can be:

- Start bit detection
- Or any received data frame
- Or a specific programmed data frame

Only a 32.768 kHz clock (LSE) is needed to allow LPUART communication up to 9600 baud. Therefore, even in Stop mode, the LPUART can wait for an incoming frame while having an extremely low energy consumption. Higher speed clock can be used to reach higher baudrates.

LPUART interface can be served by the DMA controller.

3.19.4 Serial peripheral interface (SPI)/Inter-integrated sound (I2S)

Up to two SPIs are able to communicate at up to 16 Mbits/s in slave and master modes in full-duplex and half-duplex communication modes. The 3-bit prescaler gives 8 master mode frequencies and the frame is configurable to 8 bits or 16 bits. The hardware CRC generation/verification supports basic SD Card/MMC modes.

The USARTs with synchronous capability can also be used as SPI master.

One standard I2S interfaces (multiplexed with SPI2) is available. It can operate in master or slave mode, and can be configured to operate with a 16-/32-bit resolution as input or output channels. Audio sampling frequencies from 8 kHz up to 192 kHz are supported. When the I2S interfaces is configured in master mode, the master clock can be output to the external DAC/CODEC at 256 times the sampling frequency.

The SPIs can be served by the DMA controller.

Refer to [Table 14](#) for the differences between SPI1 and SPI2.

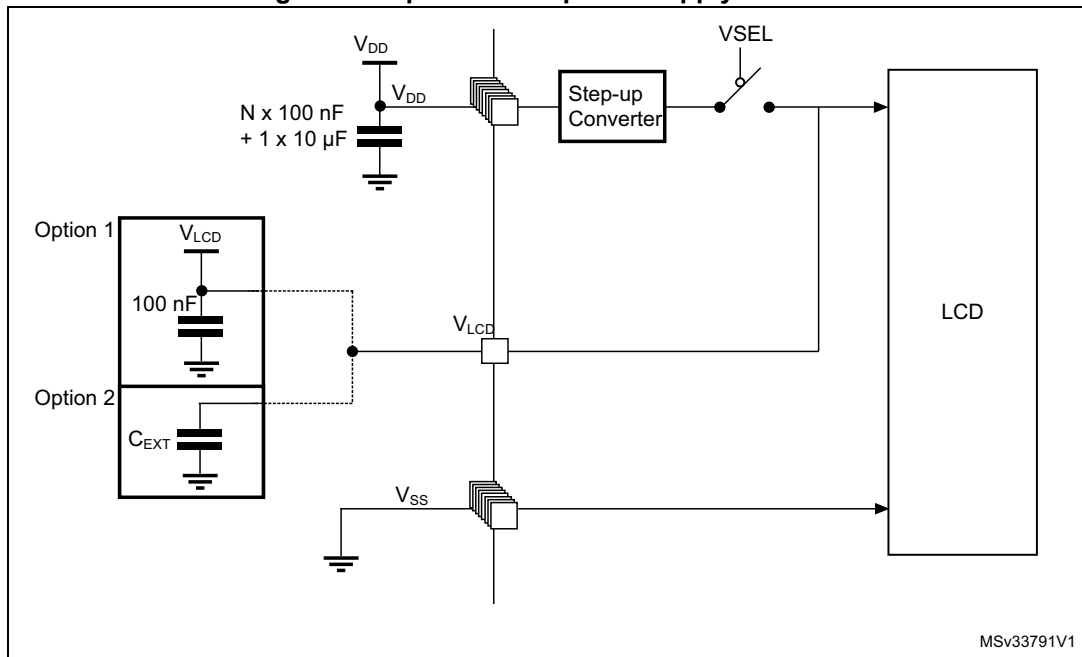
Table 14. SPI/I2S implementation

SPI features ⁽¹⁾	SPI1	SPI2
Hardware CRC calculation	X	X
I2S mode	-	X
TI mode	X	X

1. X = supported.

6.1.7 Optional LCD power supply scheme

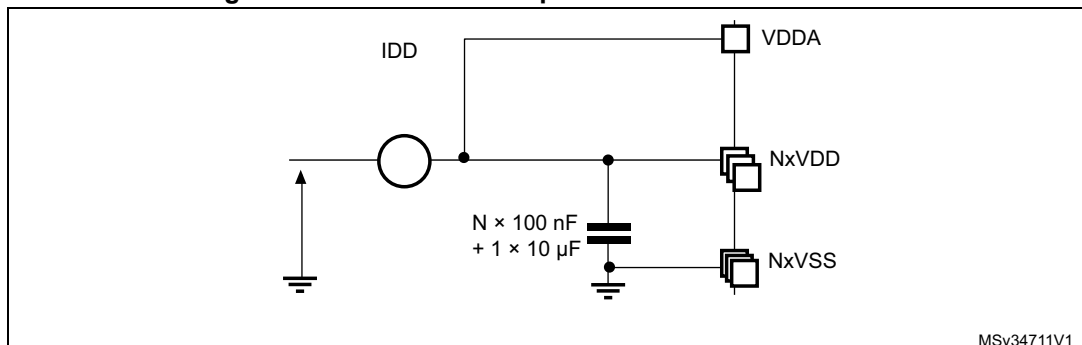
Figure 12. Optional LCD power supply scheme



1. Option 1: LCD power supply is provided by a dedicated V_{LCD} supply source, $VSEL$ switch is open.
2. Option 2: LCD power supply is provided by the internal step-up converter, $VSEL$ switch is closed, an external capacitance is needed for correct behavior of this converter.

6.1.8 Current consumption measurement

Figure 13. Current consumption measurement scheme



6.3 Operating conditions

6.3.1 General operating conditions

Table 26. General operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
f_{HCLK}	Internal AHB clock frequency	-	0	32	MHz
f_{PCLK1}	Internal APB1 clock frequency	-	0	32	
f_{PCLK2}	Internal APB2 clock frequency	-	0	32	
V_{DD}	Standard operating voltage	BOR detector disabled	1.65	3.6	V
		BOR detector enabled, at power on	1.8	3.6	
		BOR detector disabled, after power on	1.65	3.6	
V_{DDA}	Analog operating voltage (DAC not used)	Must be the same voltage as $V_{DD}^{(1)}$	1.65	3.6	V
V_{DDA}	Analog operating voltage (all features)	Must be the same voltage as $V_{DD}^{(1)}$	1.8	3.6	V
V_{DD_USB}	Standard operating voltage, USB domain ⁽²⁾	USB peripheral used	3.0	3.6	V
		USB peripheral not used	1.65	3.6	
V_{IN}	Input voltage on FT, FTf and RST pins ⁽³⁾	$2.0\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-0.3	5.5	V
		$1.65\text{ V} \leq V_{DD} \leq 2.0\text{ V}$	-0.3	5.2	
	Input voltage on BOOT0 pin	-	0	5.5	
	Input voltage on TC pin	-	-0.3	$V_{DD}+0.3$	
P_D	Power dissipation at $T_A = 85\text{ °C}$ (range 6) or $T_A = 105\text{ °C}$ (range 7) ⁽⁴⁾	UFBGA100 package	-	351	mW
		LQFP100 package	-	488	
		TFBGA64 package	-	313	
		LQFP64 package	-	435	
		LQFP48 package	-	370	
	Power dissipation at $T_A = 125\text{ °C}$ (range 3) ⁽⁴⁾	UFBGA100 package	-	88	
		LQFP100 package	-	122	
		TFBGA64 package	-	78	
		LQFP64 package	-	109	
		LQFP48 package	-	93	

6.3.2 Embedded reset and power control block characteristics

The parameters given in the following table are derived from the tests performed under the ambient temperature condition summarized in [Table 26](#).

Table 27. Embedded reset and power control block characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{VDD}^{(1)}$	V_{DD} rise time rate	BOR detector enabled	0	-	∞	$\mu s/V$
		BOR detector disabled	0	-	1000	
	V_{DD} fall time rate	BOR detector enabled	20	-	∞	
		BOR detector disabled	0	-	1000	
$T_{RSTTEMPO}^{(1)}$	Reset temporization	V_{DD} rising, BOR enabled	-	2	3.3	ms
		V_{DD} rising, BOR disabled ⁽²⁾	0.4	0.7	1.6	
$V_{POR/PDR}$	Power on/power down reset threshold	Falling edge	1	1.5	1.65	V
		Rising edge	1.3	1.5	1.65	
V_{BOR0}	Brown-out reset threshold 0	Falling edge	1.67	1.7	1.74	
		Rising edge	1.69	1.76	1.8	
V_{BOR1}	Brown-out reset threshold 1	Falling edge	1.87	1.93	1.97	
		Rising edge	1.96	2.03	2.07	
V_{BOR2}	Brown-out reset threshold 2	Falling edge	2.22	2.30	2.35	
		Rising edge	2.31	2.41	2.44	
V_{BOR3}	Brown-out reset threshold 3	Falling edge	2.45	2.55	2.6	
		Rising edge	2.54	2.66	2.7	
V_{BOR4}	Brown-out reset threshold 4	Falling edge	2.68	2.8	2.85	
		Rising edge	2.78	2.9	2.95	
V_{PVD0}	Programmable voltage detector threshold 0	Falling edge	1.8	1.85	1.88	
		Rising edge	1.88	1.94	1.99	
V_{PVD1}	PVD threshold 1	Falling edge	1.98	2.04	2.09	
		Rising edge	2.08	2.14	2.18	
V_{PVD2}	PVD threshold 2	Falling edge	2.20	2.24	2.28	
		Rising edge	2.28	2.34	2.38	
V_{PVD3}	PVD threshold 3	Falling edge	2.39	2.44	2.48	
		Rising edge	2.47	2.54	2.58	
V_{PVD4}	PVD threshold 4	Falling edge	2.57	2.64	2.69	
		Rising edge	2.68	2.74	2.79	
V_{PVD5}	PVD threshold 5	Falling edge	2.77	2.83	2.88	
		Rising edge	2.87	2.94	2.99	

Table 29. Embedded internal reference voltage⁽¹⁾ (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{LPBUF}^{(4)}$	Consumption of reference voltage buffer for VREF_OUT and COMP	-	-	730	1200	nA
$V_{REFINT_DIV1}^{(4)}$	1/4 reference voltage	-	24	25	26	% V_{REFINT}
$V_{REFINT_DIV2}^{(4)}$	1/2 reference voltage	-	49	50	51	
$V_{REFINT_DIV3}^{(4)}$	3/4 reference voltage	-	74	75	76	

1. Refer to [Table 41: Peripheral current consumption in Stop and Standby mode](#) for the value of the internal reference current consumption (I_{REFINT}).
2. Guaranteed by test in production.
3. The internal V_{REF} value is individually measured in production and stored in dedicated EEPROM bytes.
4. Guaranteed by design.
5. Shortest sampling time can be determined in the application by multiple iterations.
6. To guarantee less than 1% VREF_OUT deviation.

6.3.4 Supply current characteristics

The current consumption is a function of several parameters and factors such as the operating voltage, temperature, I/O pin loading, device software configuration, operating frequencies, I/O pin switching rate, program location in memory and executed binary code. The current consumption is measured as described in [Figure 13: Current consumption measurement scheme](#).

All Run-mode current consumption measurements given in this section are performed with a reduced code that gives a consumption equivalent to Dhrystone 2.1 code if not specified otherwise.

The current consumption values are derived from the tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 26: General operating conditions](#) unless otherwise specified.

The MCU is placed under the following conditions:

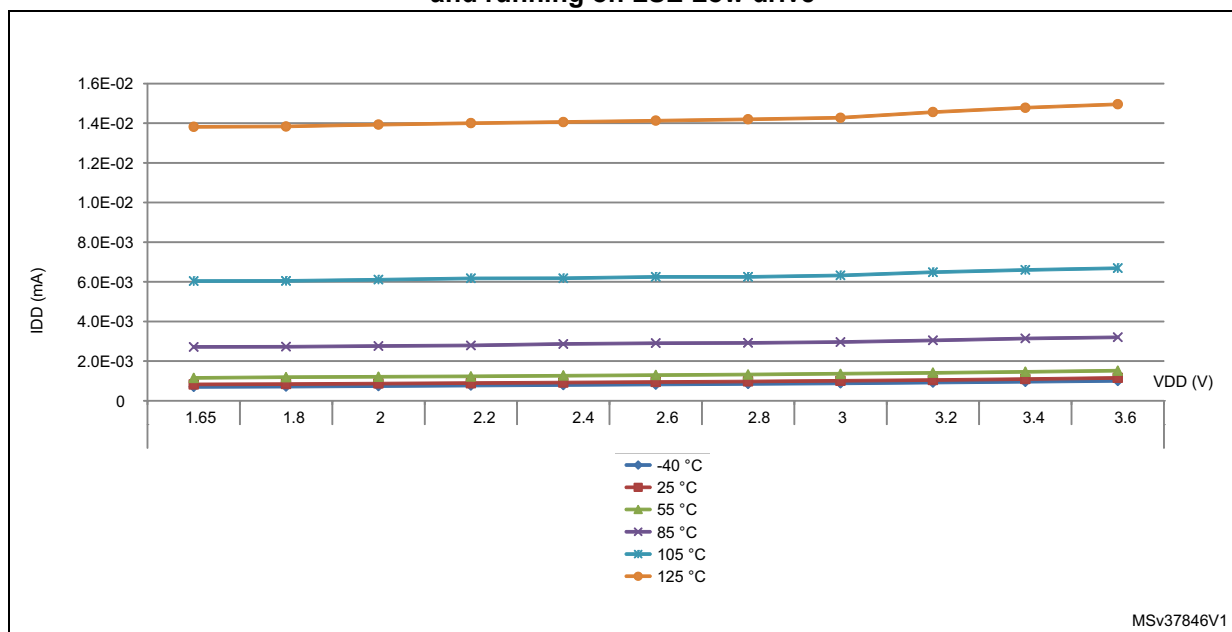
- All I/O pins are configured in analog input mode
- All peripherals are disabled except when explicitly mentioned
- The Flash memory access time and prefetch is adjusted depending on fHCLK frequency and voltage range to provide the best CPU performance unless otherwise specified.
- When the peripherals are enabled $f_{APB1} = f_{APB2} = f_{APB}$
- When PLL is on, the PLL inputs are equal to HSI = 16 MHz (if internal clock is used) or HSE = 16 MHz (if HSE bypass mode is used)
- The HSE user clock applied to OSCI_IN input follows the characteristic specified in [Table 43: High-speed external user clock characteristics](#)
- For maximum current consumption $V_{DD} = V_{DDA} = 3.6$ V is applied to all supply pins
- For typical current consumption $V_{DD} = V_{DDA} = 3.0$ V is applied to all supply pins if not specified otherwise

The parameters given in [Table 51](#), [Table 26](#) and [Table 27](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 26](#).

Table 37. Typical and maximum current consumptions in Stop mode

Symbol	Parameter	Conditions	Typ	Max ⁽¹⁾	Unit
I_{DD} (Stop)	Supply current in Stop mode	$T_A = -40$ to 25°C	0,43	1,00	μA
		$T_A = 55^\circ\text{C}$	0,735	2,50	
		$T_A = 85^\circ\text{C}$	2,25	4,90	
		$T_A = 105^\circ\text{C}$	5,3	13,00	
		$T_A = 125^\circ\text{C}$	12,5	28,00	

1. Guaranteed by characterization results at 125°C , unless otherwise specified.

Figure 17. I_{DD} vs V_{DD} , at $T_A = 25/55/ 85/105/125^\circ\text{C}$, Stop mode with RTC enabled and running on LSE Low drive

6.3.6 External clock source characteristics

High-speed external user clock generated from an external source

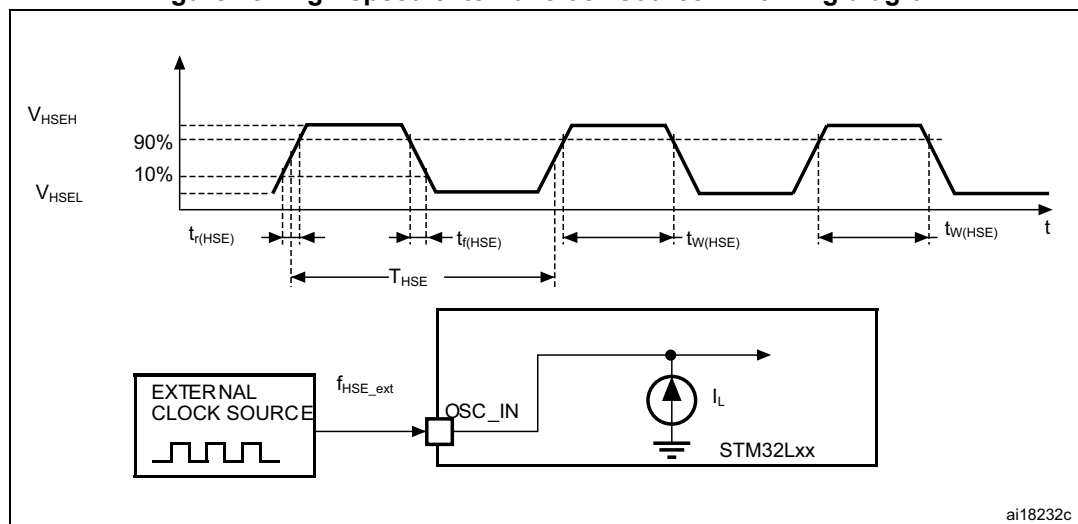
In bypass mode the HSE oscillator is switched off and the input pin is a standard GPIO. The external clock signal has to respect the I/O characteristics in [Section 6.3.12](#). However, the recommended clock input waveform is shown in [Figure 19](#).

Table 43. High-speed external user clock characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSE_ext}	User external clock source frequency	CSS is on or PLL is used	1	8	32	MHz
		CSS is off, PLL not used	0	8	32	MHz
V_{HSEH}	OSC_IN input pin high level voltage	-	$0.7V_{DD}$	-	V_{DD}	V
V_{HSEL}	OSC_IN input pin low level voltage		V_{SS}	-	$0.3V_{DD}$	
$t_{w(HSE)}$ $t_{w(HSE)}$	OSC_IN high or low time		12	-	-	ns
$t_{r(HSE)}$ $t_{f(HSE)}$	OSC_IN rise or fall time		-	-	20	
$C_{in(HSE)}$	OSC_IN input capacitance		-	2.6	-	pF
$DuCy_{(HSE)}$	Duty cycle		45	-	55	%
I_L	OSC_IN Input leakage current	$V_{SS} \leq V_{IN} \leq V_{DD}$	-	-	± 1	μA

1. Guaranteed by design.

Figure 19. High-speed external clock source AC timing diagram



High-speed external clock generated from a crystal/ceramic resonator

The high-speed external (HSE) clock can be supplied with a 1 to 25 MHz crystal/ceramic resonator oscillator. All the information given in this paragraph are based on characterization results obtained with typical external components specified in [Table 45](#). In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

Table 45. HSE oscillator characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{OSC_IN}	Oscillator frequency	-	1		25	MHz
R_F	Feedback resistor	-	-	200	-	k Ω
G_m	Maximum critical crystal transconductance	Startup	-	-	700	$\mu A/V$
$t_{SU(HSE)}^{(2)}$	Startup time	V_{DD} is stabilized	-	2	-	ms

1. Guaranteed by design.
2. Guaranteed by characterization results. $t_{SU(HSE)}$ is the startup time measured from the moment it is enabled (by software) to a stabilized 8 MHz oscillation is reached. This value is measured for a standard crystal resonator and it can vary significantly with the crystal manufacturer.

For C_{L1} and C_{L2} , it is recommended to use high-quality external ceramic capacitors in the 5 pF to 25 pF range (typ.), designed for high-frequency applications, and selected to match the requirements of the crystal or resonator (see [Figure 21](#)). C_{L1} and C_{L2} are usually the same size. The crystal manufacturer typically specifies a load capacitance which is the series combination of C_{L1} and C_{L2} . PCB and MCU pin capacitance must be included (10 pF can be used as a rough estimate of the combined pin and board capacitance) when sizing C_{L1} and C_{L2} . Refer to the application note AN2867 "Oscillator design guide for ST microcontrollers" available from the ST website www.st.com.

Figure 21. HSE oscillator circuit diagram

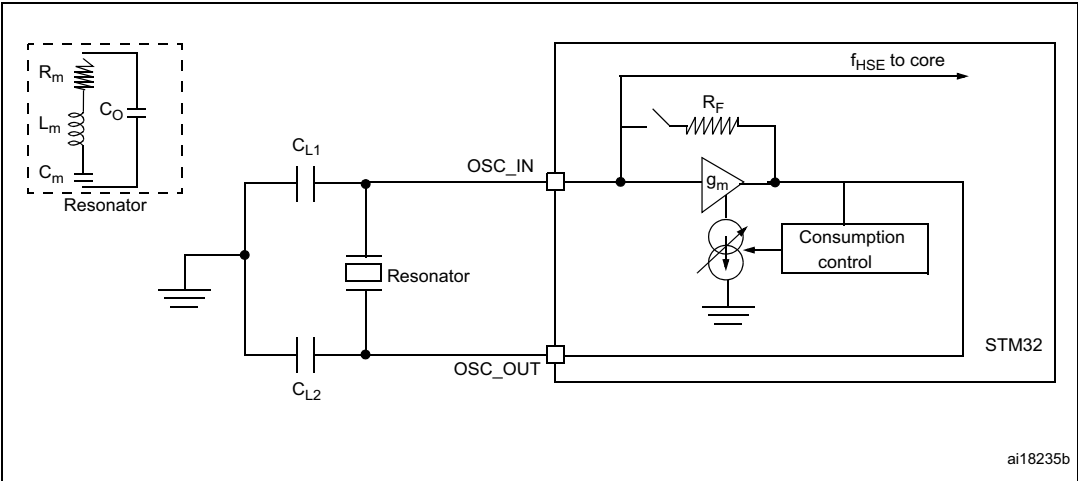


Table 54. Flash memory and data EEPROM endurance and retention (continued)

Symbol	Parameter	Conditions	Value	Unit
			Min ⁽¹⁾	
t _{RET} ⁽²⁾	Data retention (program memory) after 10 kcycles at T _A = 85 °C	T _{RET} = +85 °C	30	years
	Data retention (EEPROM data memory) after 100 kcycles at T _A = 85 °C		30	
	Data retention (program memory) after 10 kcycles at T _A = 105 °C	T _{RET} = +105 °C	10	
	Data retention (EEPROM data memory) after 100 kcycles at T _A = 105 °C			
	Data retention (program memory) after 200 cycles at T _A = 125 °C	T _{RET} = +125 °C		
	Data retention (EEPROM data memory) after 2 kcycles at T _A = 125 °C			

1. Guaranteed by characterization results.

2. Characterization is done according to JEDEC JESD22-A117.

6.3.10 EMC characteristics

Susceptibility tests are performed on a sample basis during device characterization.

Functional EMS (electromagnetic susceptibility)

While a simple application is executed on the device (toggling 2 LEDs through I/O ports), the device is stressed by two electromagnetic events until a failure occurs. The failure is indicated by the LEDs:

- **Electrostatic discharge (ESD)** (positive and negative) is applied to all device pins until a functional disturbance occurs. This test is compliant with the IEC 61000-4-2 standard.
- **FTB**: A Burst of Fast Transient voltage (positive and negative) is applied to V_{DD} and V_{SS} through a 100 pF capacitor, until a functional disturbance occurs. This test is compliant with the IEC 61000-4-4 standard.

A device reset allows normal operations to be resumed.

The test results are given in [Table 55](#). They are based on the EMS levels and classes defined in application note AN1709.

Table 55. EMS characteristics

Symbol	Parameter	Conditions	Level/Class
V_{FESD}	Voltage limits to be applied on any I/O pin to induce a functional disturbance	$V_{\text{DD}} = 3.3\text{ V}$, LQFP100, $T_A = +25\text{ °C}$, $f_{\text{HCLK}} = 32\text{ MHz}$ conforms to IEC 61000-4-2	3B
V_{EFTB}	Fast transient voltage burst limits to be applied through 100 pF on V_{DD} and V_{SS} pins to induce a functional disturbance	$V_{\text{DD}} = 3.3\text{ V}$, LQFP100, $T_A = +25\text{ °C}$, $f_{\text{HCLK}} = 32\text{ MHz}$ conforms to IEC 61000-4-4	4A

Input/output AC characteristics

The definition and values of input/output AC characteristics are given in [Figure 26](#) and [Table 62](#), respectively.

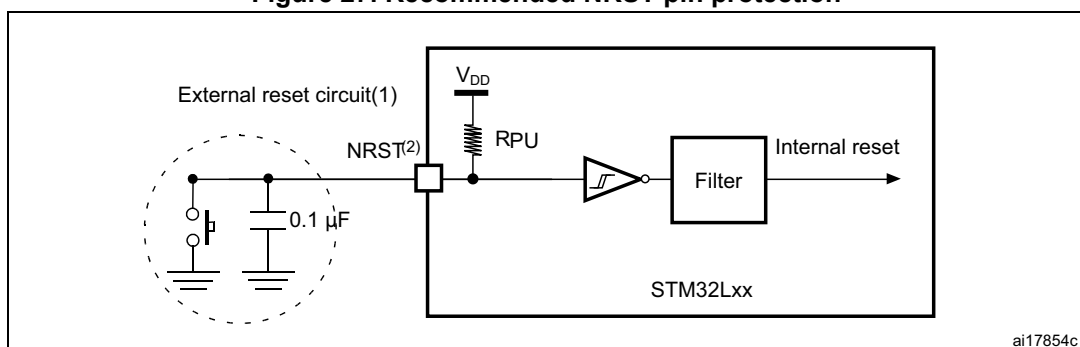
Unless otherwise specified, the parameters given in [Table 62](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 26](#).

Table 62. I/O AC characteristics⁽¹⁾

OSPEEDRx[1:0] bit value ⁽¹⁾	Symbol	Parameter	Conditions	Min	Max ⁽²⁾	Unit
00	$f_{\max(\text{IO})\text{out}}$	Maximum frequency ⁽³⁾	$C_L = 50 \text{ pF}$, $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$	-	400	kHz
			$C_L = 50 \text{ pF}$, $V_{DD} = 1.65 \text{ V to } 2.7 \text{ V}$	-	100	
	$t_{f(\text{IO})\text{out}}$ $t_{r(\text{IO})\text{out}}$	Output rise and fall time	$C_L = 50 \text{ pF}$, $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$	-	125	ns
			$C_L = 50 \text{ pF}$, $V_{DD} = 1.65 \text{ V to } 2.7 \text{ V}$	-	320	
01	$f_{\max(\text{IO})\text{out}}$	Maximum frequency ⁽³⁾	$C_L = 50 \text{ pF}$, $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$	-	2	MHz
			$C_L = 50 \text{ pF}$, $V_{DD} = 1.65 \text{ V to } 2.7 \text{ V}$	-	0.6	
	$t_{f(\text{IO})\text{out}}$ $t_{r(\text{IO})\text{out}}$	Output rise and fall time	$C_L = 50 \text{ pF}$, $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$	-	30	ns
			$C_L = 50 \text{ pF}$, $V_{DD} = 1.65 \text{ V to } 2.7 \text{ V}$	-	65	
10	$F_{\max(\text{IO})\text{out}}$	Maximum frequency ⁽³⁾	$C_L = 50 \text{ pF}$, $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$	-	10	MHz
			$C_L = 50 \text{ pF}$, $V_{DD} = 1.65 \text{ V to } 2.7 \text{ V}$	-	2	
	$t_{f(\text{IO})\text{out}}$ $t_{r(\text{IO})\text{out}}$	Output rise and fall time	$C_L = 50 \text{ pF}$, $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$	-	13	ns
			$C_L = 50 \text{ pF}$, $V_{DD} = 1.65 \text{ V to } 2.7 \text{ V}$	-	28	
11	$F_{\max(\text{IO})\text{out}}$	Maximum frequency ⁽³⁾	$C_L = 30 \text{ pF}$, $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$	-	35	MHz
			$C_L = 50 \text{ pF}$, $V_{DD} = 1.65 \text{ V to } 2.7 \text{ V}$	-	10	
	$t_{f(\text{IO})\text{out}}$ $t_{r(\text{IO})\text{out}}$	Output rise and fall time	$C_L = 30 \text{ pF}$, $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$	-	6	ns
			$C_L = 50 \text{ pF}$, $V_{DD} = 1.65 \text{ V to } 2.7 \text{ V}$	-	17	
Fm+ configuration ⁽⁴⁾	$f_{\max(\text{IO})\text{out}}$	Maximum frequency ⁽³⁾	$C_L = 50 \text{ pF}$, $V_{DD} = 2.5 \text{ V to } 3.6 \text{ V}$	-	1	MHz
	$t_{f(\text{IO})\text{out}}$	Output fall time		-	10	ns
	$t_{r(\text{IO})\text{out}}$	Output rise time		-	30	
	$f_{\max(\text{IO})\text{out}}$	Maximum frequency ⁽³⁾	$C_L = 50 \text{ pF}$, $V_{DD} = 1.65 \text{ V to } 3.6 \text{ V}$	-	350	KHz
	$t_{f(\text{IO})\text{out}}$	Output fall time		-	15	ns
	$t_{r(\text{IO})\text{out}}$	Output rise time		-	60	
-	$t_{\text{EXTI}pw}$	Pulse width of external signals detected by the EXTI controller	-	8	-	ns

1. The I/O speed is configured using the OSPEEDRx[1:0] bits. Refer to the line reference manual for a description of GPIO Port configuration register.
2. Guaranteed by design.
3. The maximum frequency is defined in [Figure 26](#).
4. When Fm+ configuration is set, the I/O speed control is bypassed. Refer to the line reference manual for a detailed description of Fm+ I/O configuration.

Figure 27. Recommended NRST pin protection



1. The reset network protects the device against parasitic resets.
2. The user must ensure that the level on the NRST pin can go below the $V_{IL(NRST)}$ max level specified in [Table 63](#). Otherwise the reset will not be taken into account by the device.

6.3.15 12-bit ADC characteristics

Unless otherwise specified, the parameters given in [Table 64](#) are derived from tests performed under ambient temperature, f_{PCLK} frequency and V_{DDA} supply voltage conditions summarized in [Table 26: General operating conditions](#).

Note: It is recommended to perform a calibration after each power-up.

Table 64. ADC characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage for ADC on	Fast channel	1.65	-	3.6	V
		Standard channel	1.75 ⁽¹⁾	-	3.6	
V_{REF+}	Positive reference voltage	-	1.65		V_{DDA}	V
V_{REF-}	Negative reference voltage	-	-	0	-	
$I_{DDA(ADC)}$	Current consumption of the ADC on V_{DDA} and V_{REF+}	1.14 Msps	-	200	-	µA
		10 ksps	-	40	-	
	Current consumption of the ADC on V_{DD} ⁽²⁾	1.14 Msps	-	70	-	
		10 ksps	-	1	-	
f_{ADC}	ADC clock frequency	Voltage scaling Range 1	0.14	-	16	MHz
		Voltage scaling Range 2	0.14	-	8	
		Voltage scaling Range 3	0.14	-	4	
$f_S^{(3)}$	Sampling rate	12-bit resolution	0.01	-	1.14	MHz
$f_{TRIG}^{(3)}$	External trigger frequency	$f_{ADC} = 16$ MHz, 12-bit resolution	-	-	941	kHz
		-	-	-	17	1/ f_{ADC}
V_{AIN}	Conversion voltage range	-	0	-	V_{REF+}	V
$R_{AIN}^{(3)}$	External input impedance	See Equation 1 and Table 65 for details	-	-	50	kΩ
$R_{ADC}^{(3)(4)}$	Sampling switch resistance	-	-	-	1	kΩ

Figure 31. Power supply and reference decoupling (V_{REF+} connected to V_{DDA})