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# **Understanding Embedded - PLDs (Programmable Logic Devices)**

Embedded - PLDs, or Programmable Logic Devices, are a type of digital electronic component used to build reconfigurable digital circuits. Unlike fixed-function logic devices, PLDs can be programmed to perform specific functions by the user. This flexibility allows designers to customize the logic to meet the exact needs of their applications, making PLDs a crucial component in modern embedded systems.

# Applications of Embedded - PLDs (Programmable Logic Devices)

The versatility of PLDs makes them suitable for a wide range of applications. In consumer electronics, PLDs are used to enhance the functionality and performance of

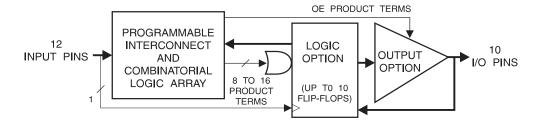
Details	
Product Status	Obsolete
Programmable Type	EE PLD
Number of Macrocells	10
Voltage - Input	5V
Speed	10 ns
Mounting Type	Surface Mount
Package / Case	28-LCC (J-Lead)
Supplier Device Package	28-PLCC (11.51x11.51)
Purchase URL	https://www.e-xfl.com/product-detail/atmel/atf22v10c-10jc

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



Figure 1-1. Logic Diagram



## 2. Pin Configurations

**Table 2-1.** Pin Configurations (All Pinouts Top View)

Pin Name	Function
CLK	Clock
IN	Logic Inputs
I/O	Bi-directional Buffers
GND	Ground
VCC	+5V Supply
PD	Power-down

Figure 2-1. TSSOP

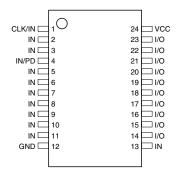


Figure 2-2. DIP/SOIC

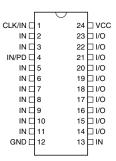
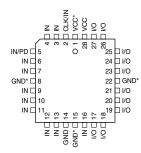


Figure 2-3. PLCC/LCC



Note: For all PLCCs (except "-5"), pins 1, 8, 15 and 22 can be left unconnected. However, if they are connected, superior performance will be achieved

### 3. Absolute Maximum Ratings\*

Temperature under Bias55°C to +125°C
Storage Temperature65°C to +150°C
Voltage on Any Pin with Respect to Ground2.0V to +7.0V <sup>(1)</sup>
Voltage on Input Pins with Respect to Ground during Programming2.0V to +14.0V <sup>(1)</sup>
Programming Voltage with Respect to Ground2.0V to +14.0V <sup>(1)</sup>

\*NOTICE:

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note:

1. Minimum voltage is -0.6V DC, which may undershoot to -2.0V for pulses of less than 20ns.

Maximum output pin voltage is  $V_{CC}$  + 0.75V DC, which may overshoot to 7.0V for pulses of less than 20ns.

### 4. DC and AC Operating Conditions

	Commercial	Industrial	Military
Operating Temperature (Ambient)	0°C - 70°C	-40°C - 85°C	-55°C - 125°C (case)
V <sub>CC</sub> Power Supply	5V ± 5%	5V ± 10%	5V ± 10%



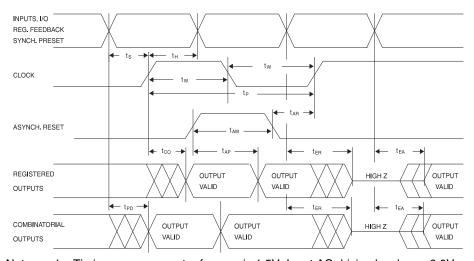


### 4.1 DC Characteristics

Symbol	Parameter	Condition				Тур	Max	Units
I <sub>IL</sub>	Input or I/O Low Leakage Current	$0 \le V_{IN} \le V_{IL}$ (Max)			-10.0	μΑ		
I <sub>IH</sub>	Input or I/O High Leakage Current	$3.5 \le V_{IN} \le V_{CC}$	$3.5 \le V_{IN} \le V_{CC}$				10.0	μА
		C-5, 7, 10	Com.		85.0	130.0	mA	
	Power Supply Current,	$V_{CC} = Max,$	C-10	Ind.		90.0	140.0	mA
I <sub>CC</sub>	Standby	V <sub>IN</sub> = Max, Outputs Open	C-15	Ind.		65.0	115.0	mA
			CQ-15	Ind.		35.0	70.0	mA
			C-5, 7, 10	Com.			150.0	mA
	Clocked Power Supply Current		C-10	Ind., Mil.			160.0	mA
I <sub>CC2</sub>			C-15	Ind.		70.0	125	mA
			C-15	Mil.			160.0	mA
			CQ-15	Ind.		40.0	80.0	mA
	Power Supply Current,	V <sub>CC</sub> = Max		Com.		10.0	500.0	μΑ
I <sub>PD</sub>	PD Mode	V <sub>IN</sub> = 0, Max		Ind.		10.0	650.0	μΑ
I <sub>OS</sub> <sup>(1)</sup>	Output Short Circuit Current	V <sub>OUT</sub> = 0.5V					-130.0	mA
V <sub>IL</sub>	Input Low Voltage				-0.5		0.8	٧
V <sub>IH</sub>	Input High Voltage				2.0		V <sub>CC</sub> +0.75	٧
.,	Outrot Lave Valle	$V_{IN} = V_{IH}$ or $V_{IL}$ ,	I <sub>OL</sub> = 16mA	Com., Ind.			0.5	V
V <sub>OL</sub>	Output Low Voltage	V <sub>CC</sub> = Min	I <sub>OL</sub> = 12mA	Mil.			0.5	V
V <sub>OH</sub>	Output High Voltage	$V_{IN} = V_{IH} \text{ or } V_{IL},$ $V_{CC} = \text{Min}$	I <sub>OH</sub> = -4.0mA		2.4			V

Note: 1. Not more than one output at a time should be shorted. Duration of short circuit test should not exceed 30 sec

### 4.2 AC Waveforms (1)



Note: 1. Timing measurement reference is 1.5V. Input AC driving levels are 0.0V and 3.0V, unless otherwise specified

# 4 Atmel ATF22V10C(Q)

### 4.3 AC Characteristics<sup>(1)</sup>

		-	5	-7		-10		-15		
Symbol	Parameter	Min	Max	Min	Max	Min	Max	Min	Max	Units
t <sub>PD</sub>	Input or Feedback to Combinatorial Output	1.0	5.0	3.0	7.5	3.0	10.0	3.0	15.0	ns
t <sub>CO</sub>	Clock to Output	1.0	4.0	2.0	4.5 <sup>(2)</sup>	2.0	6.5	2.0	8.0	ns
t <sub>CF</sub>	Clock to Feedback		2.5		2.5		2.5		2.5	ns
t <sub>S</sub>	Input or Feedback Setup Time	3.0		3.5		4.5		10.0		ns
t <sub>H</sub>	Hold Time	0		0		0		0		ns
	External Feedback 1/(t <sub>S</sub> + t <sub>CO</sub> )	142.0		125.0 <sup>(3)</sup>		90.0		55.5		MHz
f <sub>MAX</sub>	Internal Feedback 1/(t <sub>S</sub> + t <sub>CF</sub> )	166.0		142.0		117.0		80.0		MHz
	No Feedback 1/(t <sub>WH</sub> + t <sub>WL</sub> )	166.0		166.0		125.0		83.3		MHz
t <sub>W</sub>	Clock Width (t <sub>WL</sub> and t <sub>WH</sub> )	3.0		3.0		3.0		6.0		ns
t <sub>EA</sub>	Input or I/O to Output Enable	2.0	6.0	3.0	7.5	3.0	10.0	3.0	15.0	ns
t <sub>ER</sub>	Input or I/O to Output Disable	2.0	5.0	3.0	7.5	3.0	9.0	3.0	15.0	ns
t <sub>AP</sub>	Input or I/O to Asynchronous Reset of Register	3.0	7.0	3.0	10.0	3.0	12.0	3.0	20.0	ns
t <sub>AW</sub>	Asynchronous Reset Width	5.5		7.0		8.0			15.0	ns
t <sub>AR</sub>	Asynchronous Reset Recovery Time	4.0		5.0		6.0			10.0	ns
t <sub>SP</sub>	Setup Time, Synchronous Preset	4.0		4.5		6.0			10.0	ns
t <sub>SPR</sub>	Synchronous Preset to Clock Recovery Time	4.0		5.0		8.0			10.0	ns

Notes: 1. See ordering information for valid part numbers

2. 5.5ns for DIP package devices

3. 111MHz for DIP package devices





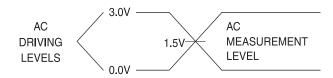
#### Power-down AC Characteristics<sup>(1)(2)(3)</sup> 4.4

		-5 -7		-10		-15				
Symbol	Parameter	Min	Max	Min	Max	Min	Max	Min	Max	Units
t <sub>IVDH</sub>	Valid Input before PD High	5.0		7.5		10.0		15.0		ns
t <sub>GVDH</sub>	Valid OE before PD High	0		0		0		0		ns
t <sub>CVDH</sub>	Valid Clock before PD High	0		0		0				ns
t <sub>DHIX</sub>	Input Don't Care after PD High		5.0		7.0		10.0		15.0	ns
t <sub>DHGX</sub>	OE Don't Care after PD High		5.0		7.0		10.0		15.0	ns
t <sub>DHCX</sub>	Clock Don't Care after PD High		5.0		7.0		10.0		15.0	ns
t <sub>DLIV</sub>	PD Low to Valid Input		5.0		7.5		10.0		15.0	ns
t <sub>DLGV</sub>	PD Low to Valid $\overline{\text{OE}}$		15.0		20.0		25.0		30.0	ns
t <sub>DLCV</sub>	PD Low to Valid Clock		15.0		20.0		25.0		30.0	ns
t <sub>DLOV</sub>	PD Low to Valid Output		20.0		25.0		30.0		35.0	ns

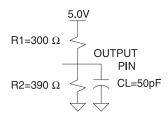
- Notes: 1. Output data is latched and held
  - 2. High-Z outputs remain high-Z
  - 3. Clock and input transitions are ignored

#### 4.5 **Input Test Waveforms**

#### 4.5.1 **Input Test Waveforms and Measurement Levels**



#### 4.5.2 **Commercial Output Test Loads**



#### 4.6 **Pin Capacitance**

**Table 4-1.** Pin Capacitance (f = 1MHz, T =  $25^{\circ}C^{(1)}$ )

	Тур	Max	Units	Conditions
C <sub>IN</sub>	5	8	pF	$V_{IN} = 0V$
C <sub>OUT</sub>	6	8	pF	V <sub>OUT</sub> = 0V

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not 100% tested

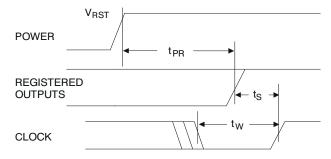
### 4.7 Power-up Reset

The registers in the Atmel<sup>®</sup> ATF22V10Cs are designed to reset during power-up. At a point delayed slightly from  $V_{CC}$  crossing  $V_{RST}$ , all registers will be reset to the low state. The output state will depend on the polarity of the output buffer.

This feature is critical for state machine initialization. However, due to the asynchronous nature of reset and the uncertainty of how  $V_{CC}$  actually rises in the system, the following conditions are required:

- 1. The V<sub>CC</sub> rise must be monotonic, and starts below 0.7V
- 2. After reset occurs, all input and feedback setup times must be met before driving the clock pin high
- The clock must remain stable during t<sub>PR</sub>

Figure 4-1. Power-up Reset Timing



### 4.8 Preload of Registered Outputs

The ATF22V10C registers are provided with circuitry to allow loading of each register with either a high or a low. This feature will simplify testing since any state can be forced into the registers to control test sequencing. A JEDEC file with preload is generated when a source file with vectors is compiled. Once downloaded, the JEDEC file preload sequence will be done automatically by most of the approved programmers after the programming.

## 5. Electronic Signature Word

There are 64-bits of programmable memory that are always available to the user, even if the device is secured. These bits can be used for user-specific data.

## 6. Security Fuse Usage

A single fuse is provided to prevent unauthorized copying of the ATF22V10C fuse patterns. Once programmed, fuse verify and preload are inhibited. However, the 64-bit User Signature remains accessible.

The security fuse should be programmed last, as its effect is immediate.

### 7. Programming/Erasing

Programming/erasing is performed using standard PLD programmers. See "CMOS PLD Programming Hardware and Software Support" for information on software/programming.

**Table 7-1.** Programming/Erasing

Parameter	Description	Тур	Max	Units
t <sub>PR</sub>	Power-up Reset Time	600	1,000	ns
V <sub>RST</sub>	Power-up Reset Voltage	3.8	4.5	٧





### 8. Input and I/O Pin-keeper Circuits

The Atmel® ATF22V10C contains internal input and I/O pin-keeper circuits. These circuits allow each ATF22V10C pin to hold its previous value even when it is not being driven by an external source or by the device's output buffer. This helps to ensure that all logic array inputs are at known valid logic levels. This reduces system power by preventing pins from floating to indeterminate levels. By using pin-keeper circuits rather than pull-up resistors, there is no DC current required to hold the pins in either logic state (high or low).

These pin-keeper circuits are implemented as weak feedback inverters, as shown in the Input Diagram below. These keeper circuits can easily be overdriven by standard TTL- or CMOS-compatible drivers. The typical overdrive current required is 40µA.

Figure 8-1. Input Diagram

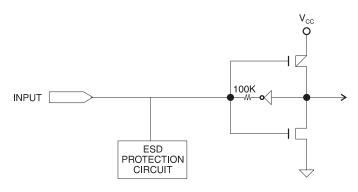
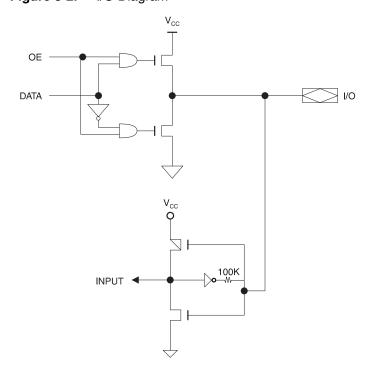


Figure 8-2. I/O Diagram



### 9. Power-down Mode

The Atmel<sup>®</sup> ATF22V10C includes an optional pin-controlled power-down feature. When this mode is enabled, the PD pin acts as the power-down pin (Pin 4 on the DIP/SOIC packages and Pin 5 on the PLCC package). When the PD pin is high, the device supply current is reduced to less than 100mA. During power-down, all output data and internal logic states are latched and held. Therefore, all registered and combinatorial output data remain valid. Any outputs that were in an undetermined state at the onset of power-down will remain at the same state. During power-down, all input signals except the power-down pin are blocked. Input and I/O hold latches remain active to ensure that pins do not float to indeterminate levels, further reducing system power. The power-down pin feature is enabled in the logic design file. Designs using the power-down pin may not use the PD pin logic array input. However, all other PD pin macrocell resources may still be used, including the buried feedback and foldback product term array inputs.

PD pin configuration is controlled by the design file, and appears as a separate fuse bit in the JEDEC file. When the power-down feature is not specified in the design file, the IN/PD pin will be configured as a regular logic input.

Note: Some programmers list the 22V10 JEDEC compatible 22V10C (no PD used) separately from the non-22V10 JEDEC compatible 22V10CEX (with PD used)

### 10. Compiler Mode Selection

Table 10-1. Compiler Mode Selection

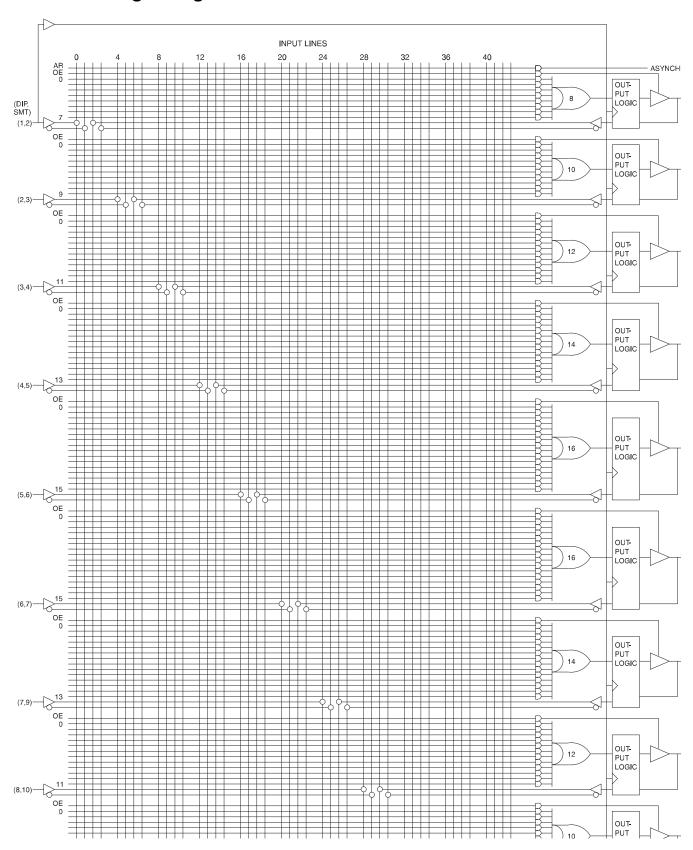
	PAL Mode	GAL Mode	Power-down Mode <sup>(1)</sup>
	(5828 Fuses)	(5892 Fuses)	(5893 Fuses)
Synario	ATF22V10C (DIP)	ATTF22V10C DIP (UES)	ATF22V10C DIP (PWD)
	ATF22V10C (PLCC)	ATF22C10C PLCC (UES)	ATF22V10C PLCC (PWD)
WINCUPL	P22V10	G22V10	G22V10CP
	P22V10LCC	G22V10LCC	G22V10CPLCC

Note: 1. These device types will create a JEDEC file which when programmed in Atmel ATF22V10C devices will enable the power-down mode feature. All other device types have the feature disabled



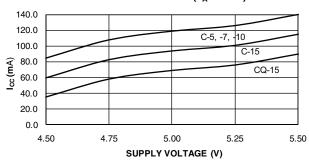


# 11. Functional Logic Diagram

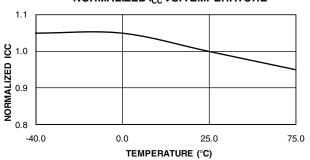


# Atmel ATF22V10C(Q)

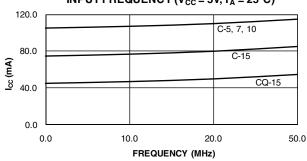
# ATMEL ATF22V10C/CQ SUPPLY CURRENT VS. SUPPLY VOLTAGE ( $T_A = 25^{\circ}$ C)



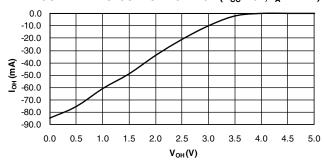
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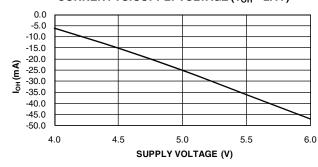
# ATMEL ATF22V10C/CQ SUPPLY CURRENT VS. INPUT FREQUENCY ( $V_{CC} = 5V, T_A = 25^{\circ}C$ )



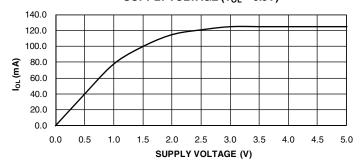
# ATMEL ATF22V10C/CQ OUTPUT SOURCE CURRENT VS. OUTPUT VOLTAGE ( $V_{CC}$ = 5V, $T_A$ = 25°C)



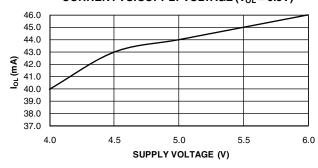
# ATMEL ATF22V10C/CQ OUTPUT SOURCE CURRENT VS. SUPPLY VOLTAGE ( $V_{OH}$ = 2.4V)



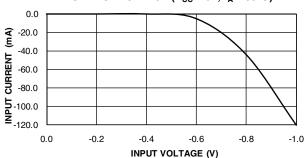
ATMEL ATF22V10C/CQ OUTPUT SINK CURRENT VS. SUPPLY VOLTAGE ( $V_{OL} = 0.5V$ )



# ATMEL ATF22V10C/CQ OUTPUT SINK CURRENT VS. SUPPLY VOLTAGE ( $V_{OL} = 0.5V$ )

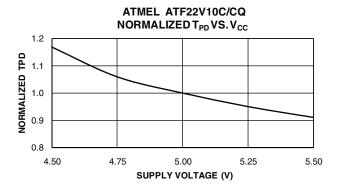


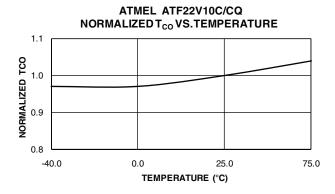
# ATMEL ATF22V10C/CQ INPUT CLAMP CURRENT VS. INPUT VOLTAGE ( $V_{CC} = 5V, T_A = 35^{\circ}C$ )

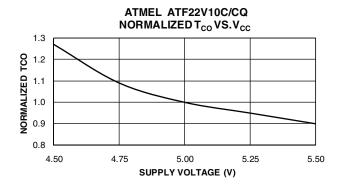


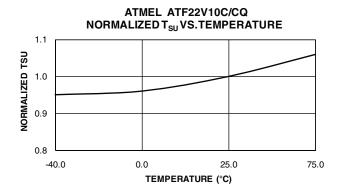


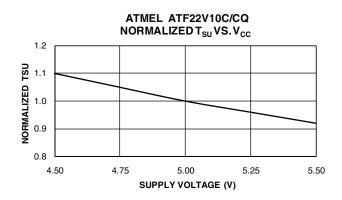


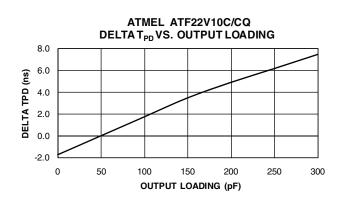


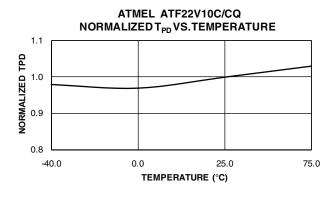


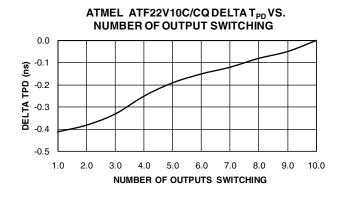




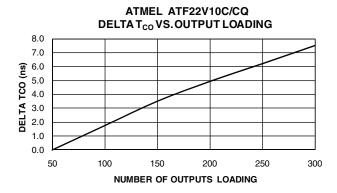


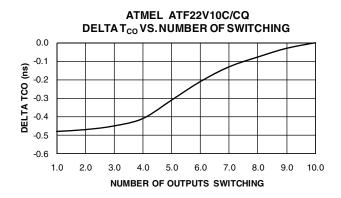






# Atmel ATF22V10C(Q)









## 12. Ordering Information

### 12.1 Atmel ATF22V10C(Q) Green Package Options (Pb/Halide-free/RoHS Compliant)

t <sub>PD</sub> (ns)	t <sub>S</sub> (ns)	t <sub>co</sub> (ns)	Ordering Code	Package	Operation Range
5	3	4	ATF22V10C-5JX	28J	Commercial (0°C to 70°C)
7.5	3.5	4.5	ATF22V10C-7PX ATF22V10C-7SX	24P3 24S	Commercial (0°C to 70°C)
7.5	3.5	4.5	ATF22V10C-7JU	28J	Industrial (-40°C to 85°C)
10	4.5	6.5	ATF22V10C-10JU ATF22V10C-10PU ATF22V10C-10SU ATF22V10C-10XU	28J 24P3 24S 24X	Industrial (-40°C to 85°C)
45	10		ATF22V10C-15JU ATF22V10C-15PU	28J 24P3	Industrial (-40°C to 85°C)
15	15   10	8	ATF22V10CQ-15JU	28J	Industrial (-40°C to 85°C)

### 12.2 Using "C" Product for Industrial

To use commercial product for industrial temperature ranges, down-grade one speed grade from the industrial-grade to the commercial-grade device (e.g. 7ns PX = 10ns PU) and de-rate power by 30%.

## 12.3 Military Package Options (Lead-based)(1)

t <sub>PD</sub> (ns)	t <sub>S</sub> (ns)	t <sub>co</sub> (ns)	Ordering Code	Package	Operation Range
			ATF22V10C-10GM/883 ATF22V10C-10NM/883	24D3 28L	Military
10	4.5	6.5	5962-8984116LA	24D3	(-55°C to 125°C) Class B, Fully Compliant
			5962-89841163A	28L	Class B, Fully Compilant
			ATF22V10C-15GM/883 ATF22V10C-15NM/883	24D3 28L	Military
15	10	8	5962-8984115LA 5962-89841153A	24D3 28L	(-55°C to 125°C) Class B, Fully Compliant

Notes: 1. Military/DSCC parts meet the DSCC drawing specifications

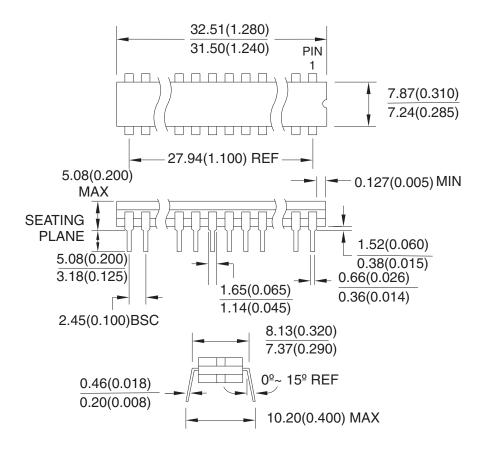
	Package Type		
24D3	24-lead, 0.300" Wide, Non-windowed Ceramic Dual Inline Package (CERDIP)		
24P3	24-pin, 0.300" Wide, Plastic Dual Inline Package (PDIP)		
24S	24-lead, 0.300" Wide, Plastic Gull Wing Small Outline (SOIC)		
24X	24-lead, 4.4mm Wide, Plastic Thin Shrink Small Outline (TSSOP)		
28J	28-lead, Plastic J-leaded Chip Carrier (PLCC)		
28L	28-lead, Ceramic Leadless Chip Carrier (LCC)		

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## 13. Packaging Information

### 13.1 24D3 - CERDIP

Dimensions in Millimeters and (Inches). Controlling dimension: Inches. MIL-STD 1835 D-9 Config A (Glass Sealed)



10/21/03



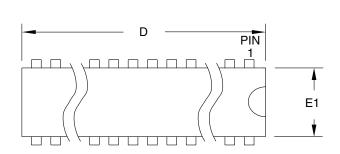
TITLE
24D3, 24-lead, 0.300" Wide. Non-windowed, Ceramic
Dual Inline Package (Cerdip)

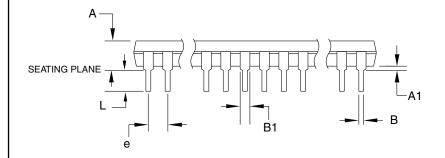
DRAWING NO. REV. 24D3 B

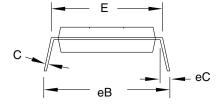




### 13.2 24P3 - PDIP







Notes:

- This package conforms to JEDEC reference MS-001, Variation AF
- Dimensions D and E1 do not include mold Flash or Protrusion Mold Flash or Protrusion shall not exceed 0.25mm (0.010")

### **COMMON DIMENSIONS**

(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
Α	_	_	5.334	
A1	0.381	-	_	
D	31.623	_	32.131	Note 2
E	7.620	_	8.255	
E1	6.096	-	7.112	Note 2
В	0.356	-	0.559	
B1	1.270	-	1.651	
L	2.921	_	3.810	
С	0.203	-	0.356	
еВ	ı	_	10.922	
eC	0.000	_	1.524	
е	2.540 TYP			

6/1/04

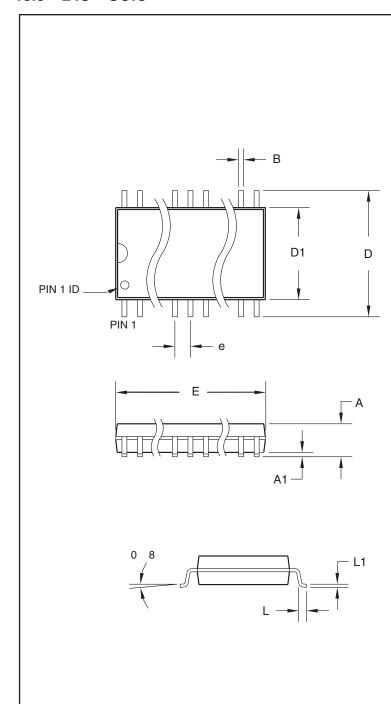
D

Almei	Package Drawing Contact:
	Package Drawing Contact: packagedrawings@atmel.com

TITLE	D
<b>24P3</b> , 24-lead (0.300"/7.62mm Wide) Plastic Dual Inline Package (PDIP)	

24P3

#### 13.3 24S - SOIC



### **COMMON DIMENSIONS**

(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
Α	_	_	2.65	
A1	0.10	_	0.30	
D	10.00	_	10.65	
D1	7.40	_	7.60	
E	15.20	_	15.60	
В	0.33	_	0.51	
L	0.40	-	1.27	
L1	0.23	_	0.32	
е		1.27 BSC		

06/17/2002

Package Drawing Contact: packagedrawings@atmel.com

TITLE 24S, 24-lead (0.300" body) Plastic Gull Wing Small Outline (SOIC)

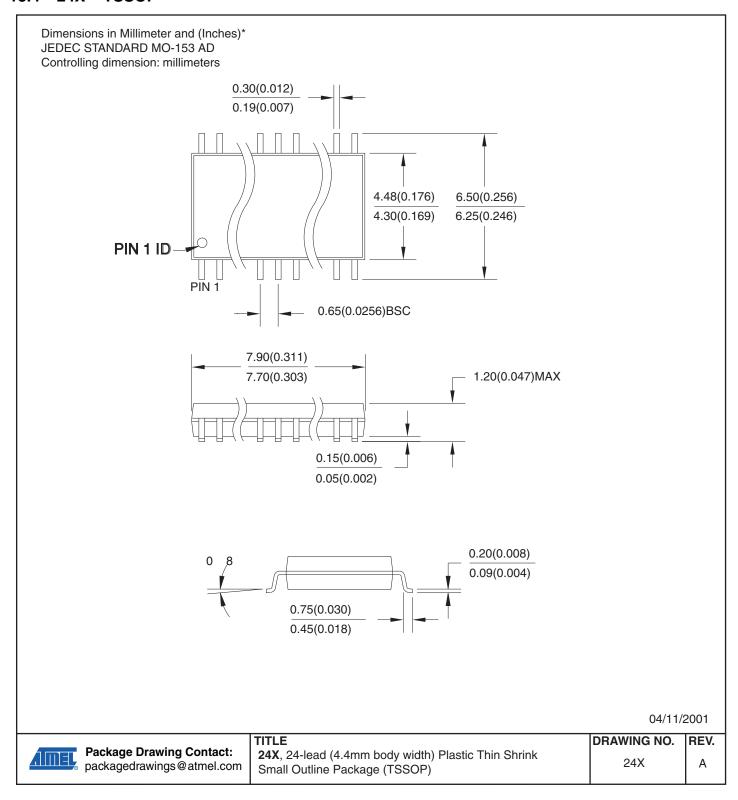
DRAWING NO. REV. 24S

В



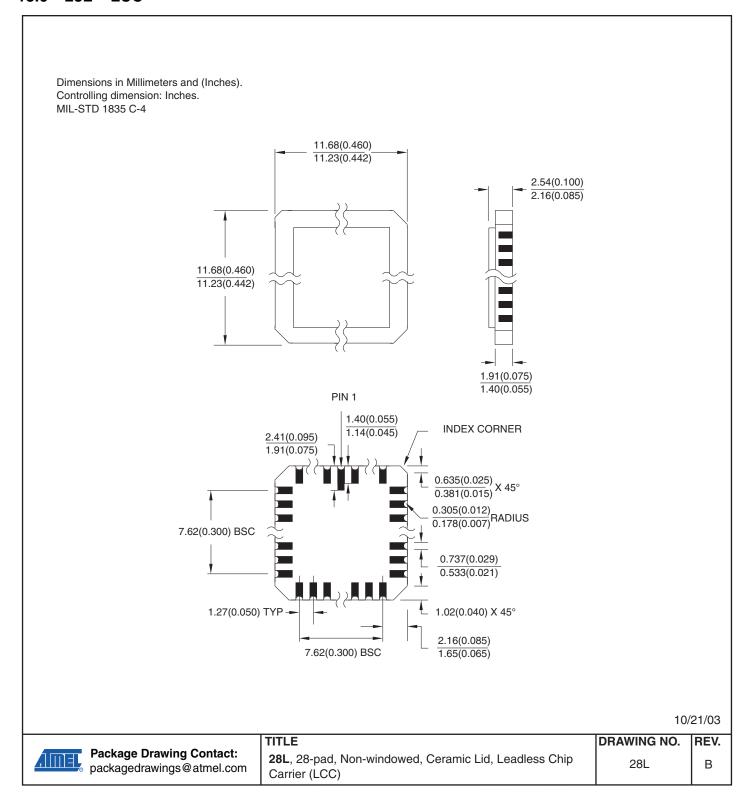


### 13.4 24X - TSSOP





### 13.6 28L - LCC



# 14. Revision History

Doc. Rev.	Date	Comments		
0735U	Updated C-15 military device I <sub>CC</sub> limit  Revised the maximum power supply current in PD mode for commercial- and industrial devices from 100μA to 500μA and 100μA to 650μA maximum, respectively  C-15 and CQ-15 Commercial part removed from Table 4-1.  Removed Mil from I <sub>CC</sub> , C-15 (Ind.) parts  I <sub>CC2</sub> at 15mhz Max changed from 90mA to 125mA			
0735T	05/2009	Added military-grade packages and removed leaded parts		
0735S	08/2008	Added new green part		
0735R	06/2008	Updated Green package options		





#### Headquarters

**Atmel Corporation** 

2325 Orchard Parkway San Jose, CA 95131 USA

Tel: (+1) (408) 441-0311 Fax: (+1) (408) 487-2600

www.atmel.com

#### International

**Atmel Asia Limited** 

Unit 01-5 & 16, 19F BEA Tower, Millennium City 5 418 Kwun Tong Road Kwun Tong, Kowloon HONG KONG

Tel: (+852) 2245-6100 Fax: (+852) 2722-1369 **Atmel Munich GmbH** 

Business Campus Parkring 4 D-85748 Garching b. Munich GERMANY

Tel: (+49) 89-31970-0 Fax: (+49) 89-3194621 Atmel Japan

9F, Tonetsu Shinkawa Bldg. 1-24-8 Shinkawa Chuo-ku, Tokyo 104-0033 JAPAN

Tel: (+81) (3) 3523-3551 Fax: (+81) (3) 3523-7581

#### **Product Contacts**

**Technical Support** 

PLD@atmel.com

Sales Contact

www.atmel.com/contacts

Literature Requests

www.atmel.com/literature

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