



Welcome to [E-XFL.COM](https://www.e-xfl.com)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I ² C, IrDA, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, I ² S, LVD, POR, PS2, PWM, WDT
Number of I/O	45
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2.5V ~ 5.5V
Data Converters	A/D 7x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/nuvoton-technology-corporation-america/nuc220sd2an

	5.20.1 Overview	79
	5.20.2 Features	79
6	ELECTRICAL CHARACTERISTICS	80
6.1	Absolute Maximum Ratings	80
6.2	DC Electrical Characteristics	81
6.3	AC Electrical Characteristics	87
	6.3.1 External 4~24 MHz High Speed Oscillator	87
	6.3.2 External 4~24 MHz High Speed Crystal	87
	6.3.3 External 32.768 kHz Low Speed Crystal Oscillator	88
	6.3.4 Internal 22.1184 MHz High Speed Oscillator	88
	6.3.5 Internal 10 kHz Low Speed Oscillator	88
6.4	Analog Characteristics	89
	6.4.1 12-bit SARADC Specification	89
	6.4.2 LDO and Power Management Specification	89
	6.4.3 Low Voltage Reset Specification	90
	6.4.4 Brown-out Detector Specification	90
	6.4.5 Power-on Reset Specification	90
	6.4.6 Temperature Sensor Specification	91
	6.4.7 Comparator Specification	91
	6.4.8 USB PHY Specification	92
6.5	Flash DC Electrical Characteristics	94
7	PACKAGE DIMENSIONS	95
7.1	100-pin LQFP (14x14x1.4 mm footprint 2.0 mm)	95
7.2	64-pin LQFP (7x7x1.4 mm footprint 2.0 mm)	96
7.3	48-pin LQFP (7x7x1.4 mm footprint 2.0 mm)	97
8	REVISION HISTORY	98



List of Tables

Table 1-1 Connectivity Support Table..... 7

Table 5-1 Address Space Assignments for On-Chip Controllers..... 46

Table 5-2 Exception Model 49

Table 5-3 System Interrupt Map..... 50

Table 5-4 Vector Table Format 51

Table 5-9 UART Baud Rate Equation..... 70

Table 5-10 UART Baud Rate Setting Table..... 71

2 FEATURES

The equipped features are dependent on the product line and their sub products.

2.1 NuMicro™ NUC200 Features – Advanced Line

- ARM® Cortex™-M0 core
 - Runs up to 50 MHz
 - One 24-bit system timer
 - Supports low power sleep mode
 - Single-cycle 32-bit hardware multiplier
 - NVIC for the 32 interrupt inputs, each with 4-levels of priority
 - Serial Wire Debug supports with 2 watchpoints/4 breakpoints
- Built-in LDO for wide operating voltage ranged from 2.5 V to 5.5 V
- Flash Memory
 - 32K/64K/128K bytes Flash for program code
 - 4 KB flash for ISP loader
 - Supports In-System-Program (ISP) and In-Application-Program (IAP) application code update
 - 512 byte page erase for flash
 - Configurable data flash address and size for 128 KB system, fixed 4 KB data flash for the 32 KB and 64 KB system
 - Supports 2-wired ICP update through SWD/ICE interface
 - Supports fast parallel programming mode by external programmer
- SRAM Memory
 - 8K/16K bytes embedded SRAM
 - Supports PDMA mode
- PDMA (Peripheral DMA)
 - Supports 9 channels PDMA for automatic data transfer between SRAM and peripherals
 - Supports CRC calculation with four common polynomials, CRC-CCITT, CRC-8, CRC-16 and CRC-32
- Clock Control
 - Flexible selection for different applications
 - Built-in 22.1184 MHz high speed oscillator for system operation
 - ◆ Trimmed to $\pm 1\%$ at $+25\text{ }^{\circ}\text{C}$ and $V_{DD} = 5\text{ V}$
 - ◆ Trimmed to $\pm 3\%$ at $-40\text{ }^{\circ}\text{C} \sim +85\text{ }^{\circ}\text{C}$ and $V_{DD} = 2.5\text{ V} \sim 5.5\text{ V}$
 - Built-in 10 kHz low speed oscillator for Watchdog Timer and Wake-up operation
 - Supports one PLL, up to 50 MHz, for high performance system operation
 - External 4~24 MHz high speed crystal input for precise timing operation
 - External 32.768 kHz low speed crystal input for RTC function and low power system operation
- GPIO
 - Four I/O modes:
 - ◆ Quasi-bidirectional
 - ◆ Push-pull output
 - ◆ Open-drain output
 - ◆ Input only with high impedance
 - TTL/Schmitt trigger input selectable
 - I/O pin configured as interrupt source with edge/level setting

- Timer
 - Supports 4 sets of 32-bit timers with 24-bit up-timer and one 8-bit prescale counter
 - Independent clock source for each timer
 - Provides one-shot, periodic, toggle and continuous counting operation modes
 - Supports event counting function
 - Supports input capture function
- Watchdog Timer
 - Multiple clock sources
 - 8 selectable time-out period from 1.6 ms ~ 26.0 sec (depending on clock source)
 - Wake-up from Power-down or Idle mode
 - Interrupt or reset selectable on watchdog time-out
- Window Watchdog Timer
 - 6-bit down counter with 11-bit prescale for wide range window selected
- RTC
 - Supports software compensation by setting frequency compensate register (FCR)
 - Supports RTC counter (second, minute, hour) and calendar counter (day, month, year)
 - Supports Alarm registers (second, minute, hour, day, month, year)
 - Selectable 12-hour or 24-hour mode
 - Automatic leap year recognition
 - Supports periodic time tick interrupt with 8 period options 1/128, 1/64, 1/32, 1/16, 1/8, 1/4, 1/2 and 1 second
 - Supports battery power pin (V_{BAT})
 - Supports wake-up function
- PWM/Capture
 - Up to four built-in 16-bit PWM generators providing eight PWM outputs or four complementary paired PWM outputs
 - Each PWM generator equipped with one clock source selector, one clock divider, one 8-bit prescaler and one Dead-Zone generator for complementary paired PWM
 - Up to eight 16-bit digital capture timers (shared with PWM timers) providing eight rising/falling capture inputs
 - Supports Capture interrupt
- UART
 - Up to three UART controllers
 - UART ports with flow control (TXD, RXD, nCTS and nRTS)
 - UART0 with 64-byte FIFO is for high speed
 - UART1/2(optional) with 16-byte FIFO for standard device
 - Supports IrDA (SIR) and LIN function
 - Supports RS-485 9-bit mode and direction control
 - Programmable baud-rate generator up to 1/16 system clock
 - Supports PDMA mode
- SPI
 - Up to four sets of SPI controllers
 - The maximum SPI clock rate of Master can up to 36 MHz (chip working at 5V)
 - The maximum SPI clock rate of Slave can up to 18 MHz (chip working at 5V)
 - Supports SPI Master/Slave mode
 - Full duplex synchronous serial data transfer
 - Variable length of transfer data from 8 to 32 bits
 - MSB or LSB first data transfer
 - Rx and Tx on both rising or falling edge of serial clock independently



3.2.1.3 NuMicro™ NUC200LxxAN LQFP 48-pin

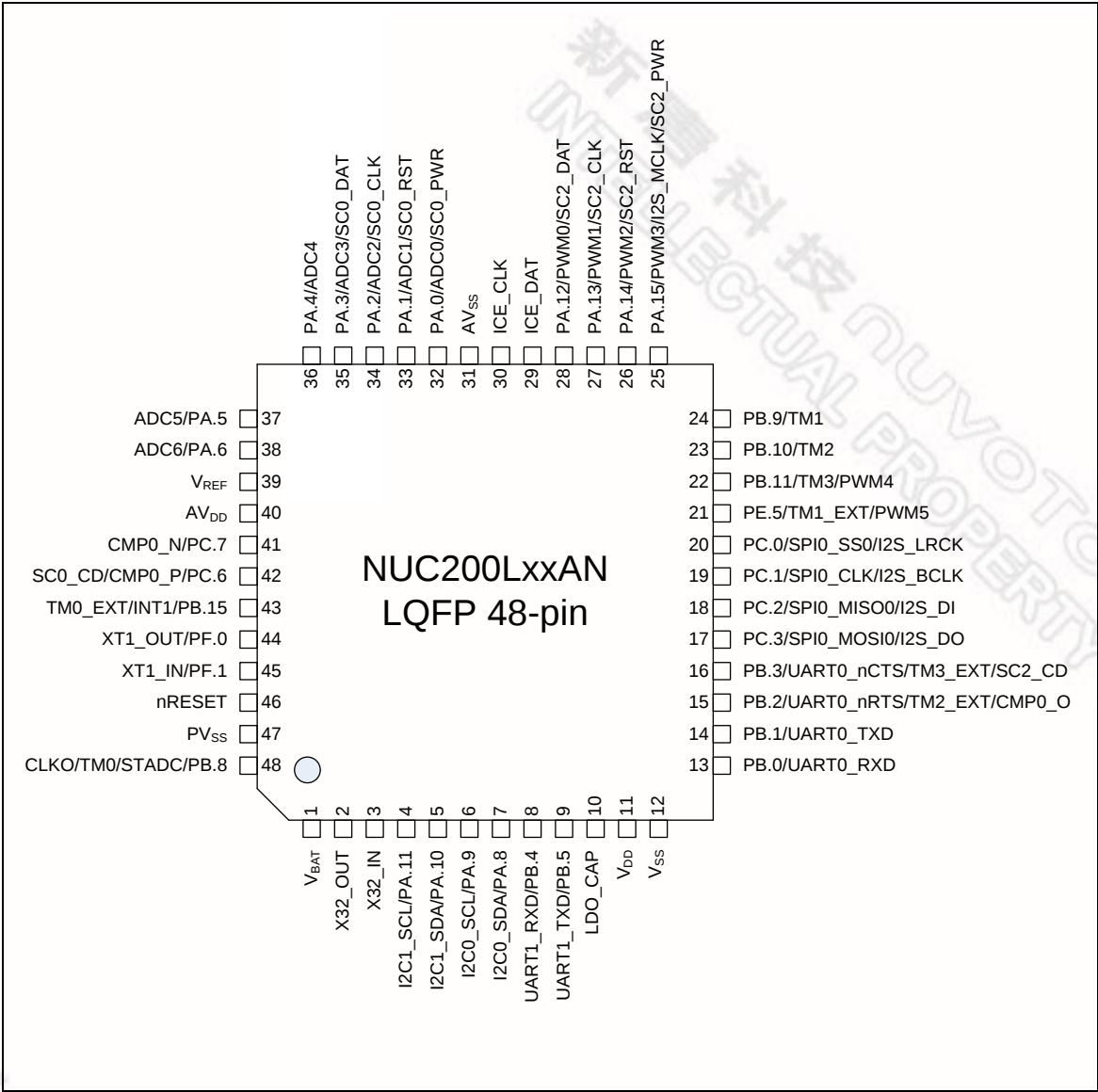


Figure 3-4 NuMicro™ NUC200LxxAN LQFP 48-pin Diagram



3.2.2.3 NuMicro™ NUC220LxxAN LQFP 48-pin

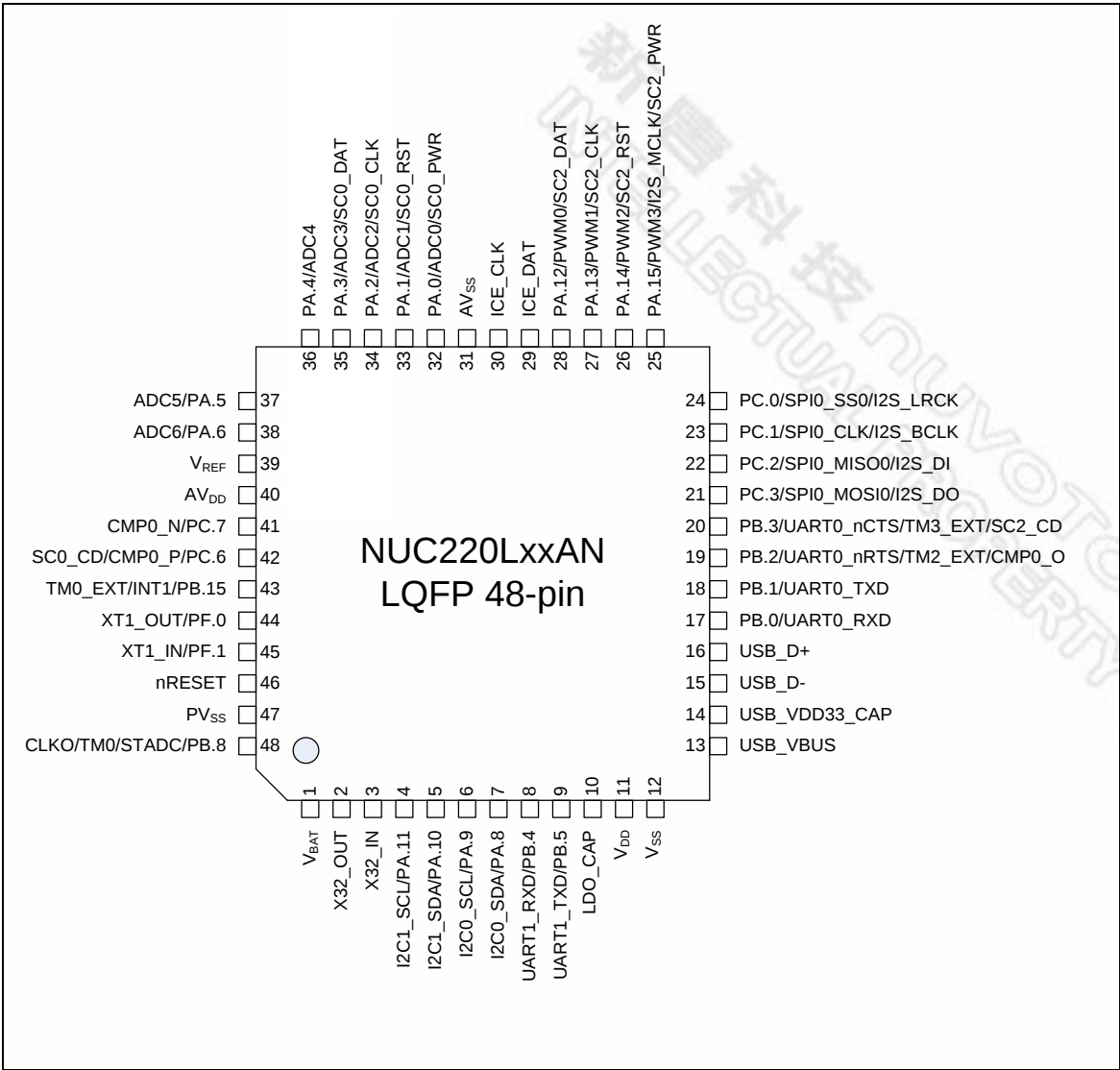


Figure 3-7 NuMicro™ NUC220LxxAN LQFP 48-pin Diagram



Pin No.			Pin Name	Pin Type	Description
LQFP 100-pin	LQFP 64-pin	LQFP 48-pin			
35	20	16	PB.3	I/O	General purpose digital I/O pin.
			UART0_nCTS	I	Clear to Send input pin for UART0.
			TM3_EXT	I	Timer3 external capture input pin.
			SC2_CD	I	SmartCard2 card detect pin.
36	21		PD.6	I/O	General purpose digital I/O pin.
37	22		PD.7	I/O	General purpose digital I/O pin.
38	23		PD.14	I/O	General purpose digital I/O pin.
			UART2_RXD	I	Data receiver input pin for UART2.
39	24		PD.15	I/O	General purpose digital I/O pin.
			UART2_TXD	O	Data transmitter output pin for UART2.
40			PC.5	I/O	General purpose digital I/O pin.
			SPI0_MOSI1	I/O	2 nd SPI0 MOSI (Master Out, Slave In) pin.
41			PC.4	I/O	General purpose digital I/O pin.
			SPI0_MISO1	I/O	2 nd SPI0 MISO (Master In, Slave Out) pin.
42	25	17	PC.3	I/O	General purpose digital I/O pin.
			SPI0_MOSI0	I/O	1 st SPI0 MOSI (Master Out, Slave In) pin.
			I2S_DO	O	I ² S data output.
43	26	18	PC.2	I/O	General purpose digital I/O pin.
			SPI0_MISO0	I/O	1 st SPI0 MISO (Master In, Slave Out) pin.
			I2S_DI	I	I ² S data input.
44	27	19	PC.1	I/O	General purpose digital I/O pin.
			SPI0_CLK	I/O	SPI0 serial clock pin.
			I2S_BCLK	I/O	I ² S bit clock pin.
45	28	20	PC.0	I/O	General purpose digital I/O pin.
			SPI0_SS0	I/O	1 st SPI0 slave select pin.
			I2S_LRCK	I/O	I ² S left right channel clock.
46			PE.6	I/O	General purpose digital I/O pin.
47	29	21	PE.5	I/O	General purpose digital I/O pin.
			PWM5	I/O	PWM5 output/Capture input.
			TM1_EXT	I	Timer1 external capture input pin.



Pin No.			Pin Name	Pin Type	Description
LQFP 100-pin	LQFP 64-pin	LQFP 48-pin			
48	30	22	PB.11	I/O	General purpose digital I/O pin.
			TM3	I/O	Timer3 event counter input / toggle output.
			PWM4	I/O	PWM4 output/Capture input.
49	31	23	PB.10	I/O	General purpose digital I/O pin.
			TM2	I/O	Timer2 event counter input / toggle output.
			SPI0_SS1	I/O	2 nd SPI0 slave select pin.
50	32	24	PB.9	I/O	General purpose digital I/O pin.
			TM1	I/O	Timer1 event counter input / toggle output.
			SPI1_SS1	I/O	2 nd SPI1 slave select pin.
51			PE.4	I/O	General purpose digital I/O pin.
52			PE.3	I/O	General purpose digital I/O pin.
53			PE.2	I/O	General purpose digital I/O pin.
54			PE.1	I/O	General purpose digital I/O pin.
			PWM7	I/O	PWM7 output/Capture input.
55			PE.0	I/O	General purpose digital I/O pin.
			PWM6	I/O	PWM6 output/Capture input.
56			PC.13	I/O	General purpose digital I/O pin.
			SPI1_MOSI1	I/O	2 nd SPI1 MOSI (Master Out, Slave In) pin.
57			PC.12	I/O	General purpose digital I/O pin.
			SPI1_MISO1	I/O	2 nd SPI1 MISO (Master In, Slave Out) pin.
58	33		PC.11	I/O	General purpose digital I/O pin.
			SPI1_MOSI0	I/O	1 st SPI1 MOSI (Master Out, Slave In) pin.
59	34		PC.10	I/O	General purpose digital I/O pin.
			SPI1_MISO0	I/O	1 st SPI1 MISO (Master In, Slave Out) pin.
60	35		PC.9	I/O	General purpose digital I/O pin.
			SPI1_CLK	I/O	SPI1 serial clock pin.
61	36		PC.8	I/O	General purpose digital I/O pin.
			SPI1_SS0	I/O	1 st SPI1 slave select pin.
62	37	25	PA.15	I/O	General purpose digital I/O pin.
			PWM3	I/O	PWM output/Capture input.

Pin No.			Pin Name	Pin Type	Description
LQFP 100-pin	LQFP 64-pin	LQFP 48-pin			
			I2S_MCLK	O	I ² S master clock output pin.
			SC2_PWR	O	SmartCard2 power pin.
63	38	26	PA.14	I/O	General purpose digital I/O pin.
			PWM2	I/O	PWM2 output/Capture input.
			SC2_RST	O	SmartCard2 reset pin.
64	39	27	PA.13	I/O	General purpose digital I/O pin.
			PWM1	I/O	PWM1 output/Capture input.
			SC2_CLK	O	SmartCard2 clock pin.
65	40	28	PA.12	I/O	General purpose digital I/O pin.
			PWM0	I/O	PWM0 output/Capture input.
			SC2_DAT	O	SmartCard2 data pin.
66	41	29	ICE_DAT	I/O	Serial wire debugger data pin.
67	42	30	ICE_CLK	I	Serial wire debugger clock pin.
68			V _{DD}	P	Power supply for I/O ports and LDO source for internal PLL and digital circuit.
69			V _{SS}	P	Ground pin for digital circuit.
70	43	31	AV _{SS}	AP	Ground pin for analog circuit.
71	44	32	PA.0	I/O	General purpose digital I/O pin.
			ADC0	AI	ADC0 analog input.
			SC0_PWR	O	SmartCard0 power pin.
72	45	33	PA.1	I/O	General purpose digital I/O pin.
			ADC1	AI	ADC1 analog input.
			SC0_RST	O	SmartCard0 reset pin.
73	46	34	PA.2	I/O	General purpose digital I/O pin.
			ADC2	AI	ADC2 analog input.
			SC0_CLK	O	SmartCard0 clock pin.
74	47	35	PA.3	I/O	General purpose digital I/O pin.
			ADC3	AI	ADC3 analog input.
			SC0_DAT	O	SmartCard0 data pin.
75	48	36	PA.4	I/O	General purpose digital I/O pin.
			ADC4	AI	ADC4 analog input.

Pin No.			Pin Name	Pin Type	Description
LQFP 100-pin	LQFP 64-pin	LQFP 48-pin			
			TM3_EXT	I	Timer3 external capture input pin.
			SC2_CD	I	SmartCard2 card detect pin.
36			PD.6	I/O	General purpose digital I/O pin.
37			PD.7	I/O	General purpose digital I/O pin.
38			PD.14	I/O	General purpose digital I/O pin.
			UART2_RXD	I	Data receiver input pin for UART2.
39			PD.15	I/O	General purpose digital I/O pin.
			UART2_TXD	O	Data transmitter output pin for UART2.
40			PC.5	I/O	General purpose digital I/O pin.
			SPI0_MOSI1	I/O	2 nd SPI0 MOSI (Master Out, Slave In) pin.
41			PC.4	I/O	General purpose digital I/O pin.
			SPI0_MISO1	I/O	2 nd SPI0 MISO (Master In, Slave Out) pin.
42	25	21	PC.3	I/O	General purpose digital I/O pin.
			SPI0_MOSI0	I/O	1 st SPI0 MOSI (Master Out, Slave In) pin.
			I2S_DO	O	I ² S data output.
43	26	22	PC.2	I/O	General purpose digital I/O pin.
			SPI0_MISO0	I/O	1 st SPI0 MISO (Master In, Slave Out) pin.
			I2S_DI	I	I ² S data input.
44	27	23	PC.1	I/O	General purpose digital I/O pin.
			SPI0_CLK	I/O	SPI0 serial clock pin.
			I2S_BCLK	I/O	I ² S bit clock pin.
45	28	24	PC.0	I/O	General purpose digital I/O pin.
			SPI0_SS0	I/O	1 st SPI0 slave select pin.
			I2S_LRCK	I/O	I ² S left right channel clock.
46			PE.6	I/O	General purpose digital I/O pin.
47	29		PE.5	I/O	General purpose digital I/O pin.
			PWM5	I/O	PWM5 output/Capture input.
			TM1_EXT	I	Timer1 external capture input pin.
48	30		PB.11	I/O	General purpose digital I/O pin.



Pin No.			Pin Name	Pin Type	Description
LQFP 100-pin	LQFP 64-pin	LQFP 48-pin			
			SC2_PWR	O	SmartCard2 power pin.
63	38	26	PA.14	I/O	General purpose digital I/O pin.
			PWM2	I/O	PWM2 output/Capture input.
			SC2_RST	O	SmartCard2 reset pin.
64	39	27	PA.13	I/O	General purpose digital I/O pin.
			PWM1	I/O	PWM1 output/Capture input.
			SC2_CLK	O	SmartCard2 clock pin.
65	40	28	PA.12	I/O	General purpose digital I/O pin.
			PWM0	I/O	PWM0 output/Capture input.
			SC2_DAT	O	SmartCard2 data pin.
66	41	29	ICE_DAT	I/O	Serial wire debugger data pin.
67	42	30	ICE_CLK	I	Serial wire debugger clock pin.
68			V _{DD}	P	Power supply for I/O ports and LDO source for internal PLL and digital circuit.
69			V _{SS}	P	Ground pin for digital circuit.
70	43	31	AV _{SS}	AP	Ground pin for analog circuit.
71	44	32	PA.0	I/O	General purpose digital I/O pin.
			ADC0	AI	ADC0 analog input.
			SC0_PWR	O	SmartCard0 power pin.
72	45	33	PA.1	I/O	General purpose digital I/O pin.
			ADC1	AI	ADC1 analog input.
			SC0_RST	O	SmartCard0 reset pin.
73	46	34	PA.2	I/O	General purpose digital I/O pin.
			ADC2	AI	ADC2 analog input.
			SC0_CLK	O	SmartCard0 clock pin.
74	47	35	PA.3	I/O	General purpose digital I/O pin.
			ADC3	AI	ADC3 analog input.
			SC0_DAT	O	SmartCard0 data pin.
75	48	36	PA.4	I/O	General purpose digital I/O pin.
			ADC4	AI	ADC4 analog input.
			SC1_PWR	O	SmartCard1 power pin.

5 FUNCTIONAL DESCRIPTION

5.1 ARM® Cortex™-M0 Core

The Cortex™-M0 processor is a configurable, multistage, 32-bit RISC processor, which has an AMBA AHB-Lite interface and includes an NVIC component. It also has optional hardware debug functionality. The processor can execute Thumb code and is compatible with other Cortex™-M profile processor. The profile supports two modes -Thread mode and Handler mode. Handler mode is entered as a result of an exception. An exception return can only be issued in Handler mode. Thread mode is entered on Reset, and can be entered as a result of an exception return. Figure 5-1 shows the functional controller of processor.

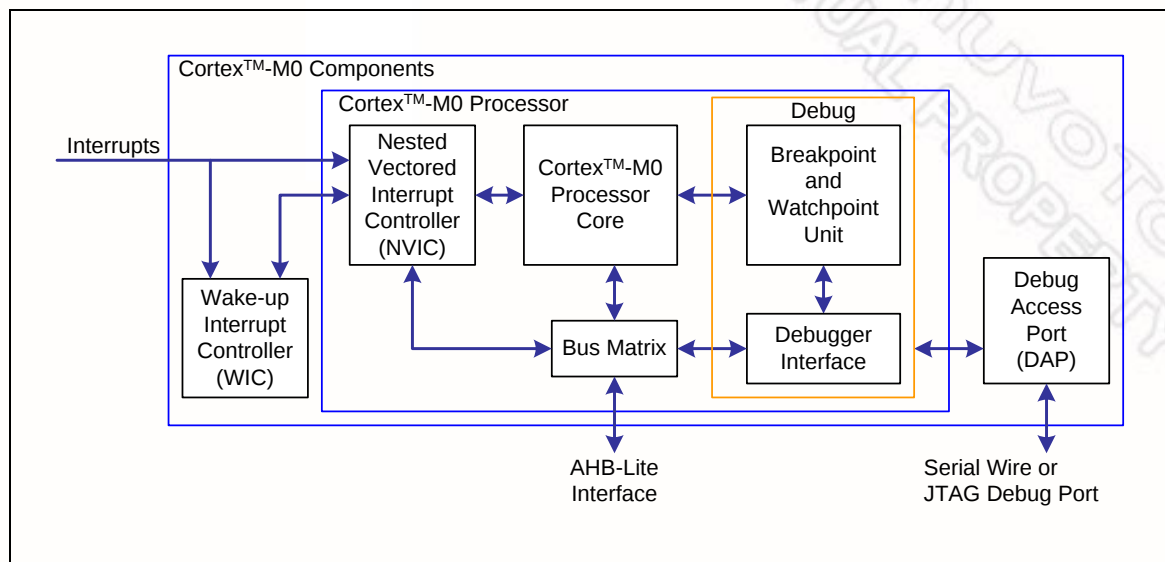


Figure 5-1 Functional Controller Diagram

The implemented device provides the following components and features:

- A low gate count processor:
 - ◆ ARMv6-M Thumb® instruction set
 - ◆ Thumb-2 technology
 - ◆ ARMv6-M compliant 24-bit SysTick timer
 - ◆ A 32-bit hardware multiplier
 - ◆ System interface supported with little-endian data accesses
 - ◆ Ability to have deterministic, fixed-latency, interrupt handling
 - ◆ Load/store-multiples and multicycle-multiplies that can be abandoned and restarted to facilitate rapid interrupt handling
 - ◆ C Application Binary Interface compliant exception model. This is the ARMv6-M, C Application Binary Interface (C-ABI) compliant exception model that enables the use of pure C functions as interrupt handlers
 - ◆ Low Power Sleep mode entry using Wait For Interrupt (WFI), Wait For Event (WFE) instructions, or the return from interrupt sleep-on-exit feature

5.2.3 System Power Distribution

In this chip, the power distribution is divided into four segments.

- Analog power from AV_{DD} and AV_{SS} provides the power for analog components operation.
- Digital power from V_{DD} and V_{SS} supplies the power to the internal regulator which provides a fixed 1.8 V power for digital operation and I/O pins.
- USB transceiver power from USB_VBUS offers the power for operating the USB transceiver.
- Battery power from V_{BAT} supplies the RTC and external 32.768 kHz crystal.

The outputs of internal voltage regulators, LDO_CAP and USB_VDD33_CAP , require an external capacitor which should be located close to the corresponding pin. Analog power (AV_{DD}) should be the same voltage level of the digital power (V_{DD}). Figure 5-2 shows the power distribution of NuMicro™ NUC200; Figure 5-3 shows the power distribution of NuMicro™ NUC220.

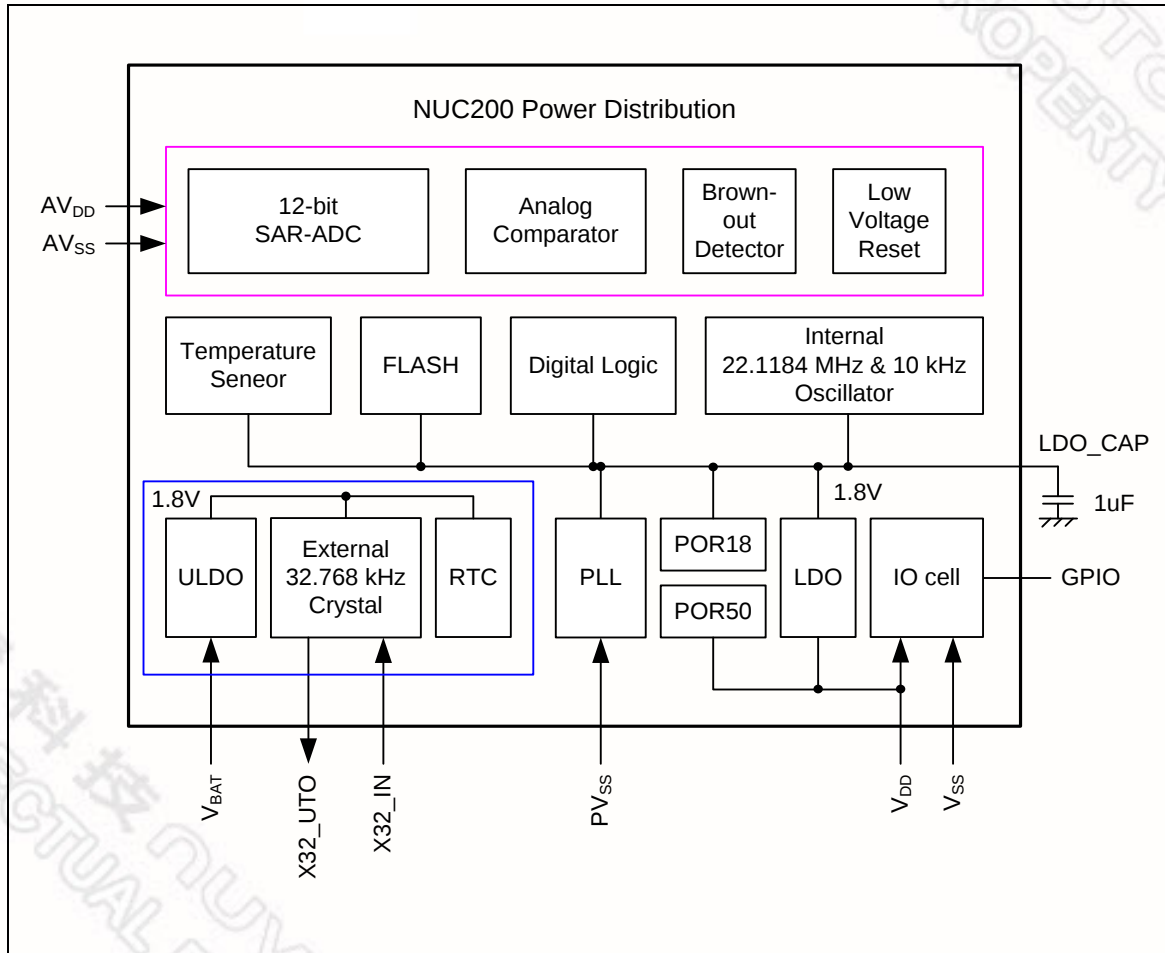


Figure 5-2 NuMicro™ NUC200 Power Distribution Diagram

5.2.6.4 Interrupt Source Register Map

Besides the interrupt control registers associated with the NVIC, the NuMicro™ NUC200 Series also implements some specific control registers to facilitate the interrupt functions, including “interrupt source identification”, “NMI source selection” and “interrupt test mode”, which are described below.

R: read only, W: write only, R/W: both read and write

Register	Offset	R/W	Description	Reset Value
INT Base Address: INT_BA = 0x5000_0300				
IRQ0_SRC	INT_BA+0x00	R	IRQ0 (BOD) interrupt source identity	0xFFFF_XXXX
IRQ1_SRC	INT_BA+0x04	R	IRQ1 (WDT) interrupt source identity	0xFFFF_XXXX
IRQ2_SRC	INT_BA+0x08	R	IRQ2 (EINT0) interrupt source identity	0xFFFF_XXXX
IRQ3_SRC	INT_BA+0x0C	R	IRQ3 (EINT1) interrupt source identity	0xFFFF_XXXX
IRQ4_SRC	INT_BA+0x10	R	IRQ4 (GPA/GPB) interrupt source identity	0xFFFF_XXXX
IRQ5_SRC	INT_BA+0x14	R	IRQ5 (GPC/GPD/GPE/GPF) interrupt source identity	0xFFFF_XXXX
IRQ6_SRC	INT_BA+0x18	R	IRQ6 (PWMA) interrupt source identity	0xFFFF_XXXX
IRQ7_SRC	INT_BA+0x1C	R	IRQ7 (PWMB) interrupt source identity	0xFFFF_XXXX
IRQ8_SRC	INT_BA+0x20	R	IRQ8 (TMR0) interrupt source identity	0xFFFF_XXXX
IRQ9_SRC	INT_BA+0x24	R	IRQ9 (TMR1) interrupt source identity	0xFFFF_XXXX
IRQ10_SRC	INT_BA+0x28	R	IRQ10 (TMR2) interrupt source identity	0xFFFF_XXXX
IRQ11_SRC	INT_BA+0x2C	R	IRQ11 (TMR3) interrupt source identity	0xFFFF_XXXX
IRQ12_SRC	INT_BA+0x30	R	IRQ12 (UART0/UART2) interrupt source identity	0xFFFF_XXXX
IRQ13_SRC	INT_BA+0x34	R	IRQ13 (UART1) interrupt source identity	0xFFFF_XXXX
IRQ14_SRC	INT_BA+0x38	R	IRQ14 (SPI0) interrupt source identity	0xFFFF_XXXX
IRQ15_SRC	INT_BA+0x3C	R	IRQ15 (SPI1) interrupt source identity	0xFFFF_XXXX
IRQ16_SRC	INT_BA+0x40	R	IRQ16 (SPI2) interrupt source identity	0xFFFF_XXXX
IRQ17_SRC	INT_BA+0x44	R	IRQ17 (SPI3) interrupt source identity	0xFFFF_XXXX
IRQ18_SRC	INT_BA+0x48	R	IRQ18 (I ² C0) interrupt source identity	0xFFFF_XXXX
IRQ19_SRC	INT_BA+0x4C	R	IRQ19 (I ² C1) interrupt source identity	0xFFFF_XXXX
IRQ20_SRC	INT_BA+0x50	R	Reserved	0xFFFF_XXXX
IRQ21_SRC	INT_BA+0x54	R	Reserved	0xFFFF_XXXX
IRQ22_SRC	INT_BA+0x58	R	IRQ22 (SC0/SC1/SC2) interrupt source identity	0xFFFF_XXXX

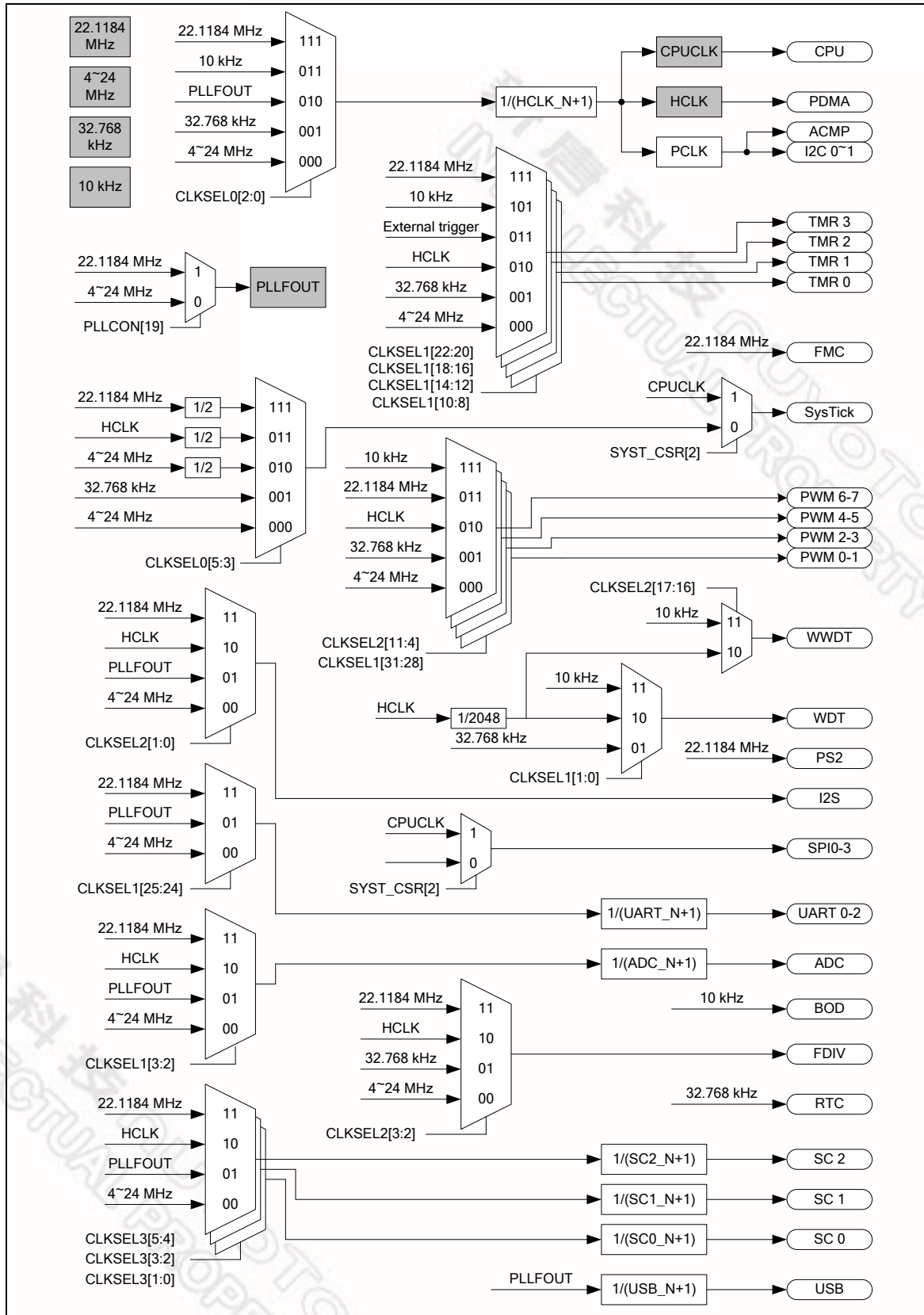


Figure 5-4 Clock Generator Global View Diagram

5.3.6 Frequency Divider Output

This device is equipped with a power-of-2 frequency divider which is composed by 16 chained divide-by-2 shift registers. One of the 16 shift register outputs selected by a sixteen to one multiplexer is reflected to CLKO function pin. Therefore there are 16 options of power-of-2 divided clocks with the frequency from $F_{in}/2^1$ to $F_{in}/2^{16}$ where F_{in} is input clock frequency to the clock divider.

The output formula is $F_{out} = F_{in}/2^{(N+1)}$, where F_{in} is the input clock frequency, F_{out} is the clock divider output frequency and N is the 4-bit value in FSEL (FRQDIV[3:0]).

When writing 1 to DIVIDER_EN (FRQDIV[4]), the chained counter starts to count. When writing 0 to DIVIDER_EN (FRQDIV[4]), the chained counter continuously runs till divided clock reaches low state and stay in low state.

If DIVIDER1 (FRQDIV[5]) is set to 1, the frequency divider clock (FRQDIV_CLK) will bypass power-of-2 frequency divider. The frequency divider clock will be output to CLKO pin directly.

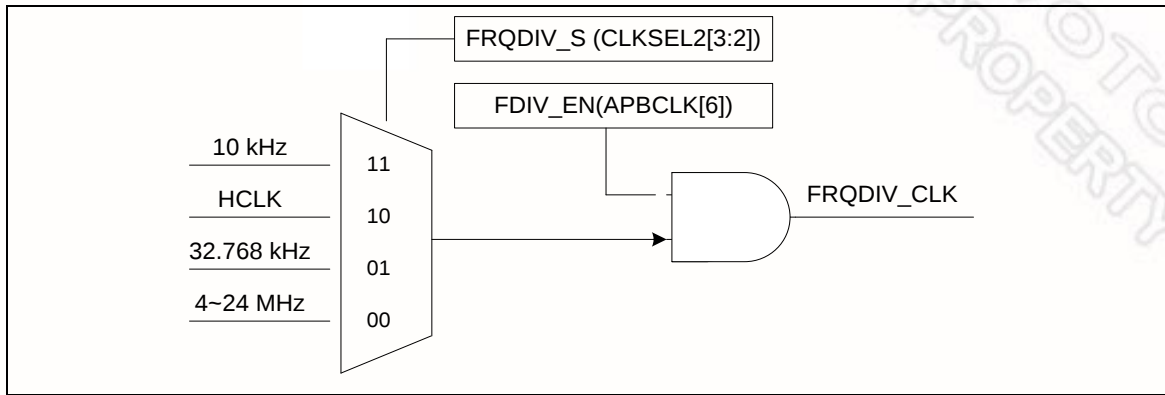


Figure 5-8 Clock Source of Frequency Divider

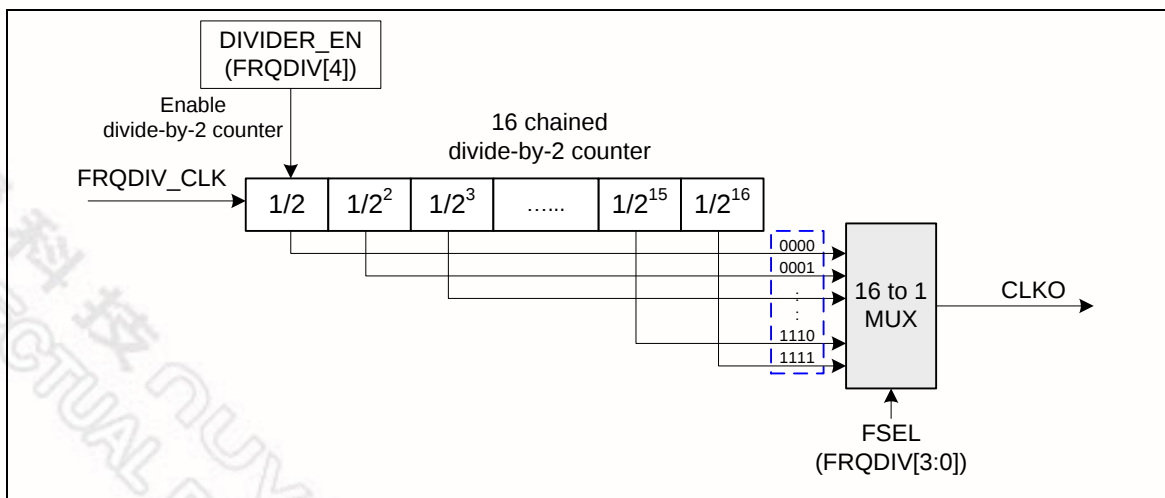


Figure 5-9 Frequency Divider Block Diagram

example:

HCLK = 50 MHz, PWM_CLK = 25 MHz, Interrupt latency is 900 ns

So the maximum capture frequency will be $1/900\text{ns} \approx 1000\text{ kHz}$

5.7.2 Features

5.7.2.1 PWM function:

- Up to 2 PWM groups (PWMA/PWMB) to support 8 PWM channels or 4 complementary PWM paired channels
- Each PWM group has two PWM generators with each PWM generator supporting one 8-bit prescaler, two clock divider, two PWM-timers, one Dead-zone generator and two PWM outputs.
- Up to 16-bit resolution
- PWM Interrupt request synchronized with PWM period
- One-shot or Auto-reload mode PWM
- Edge-aligned type or Center-aligned type option

5.7.2.2 Capture Function:

- Timing control logic shared with PWM generators
- Supports 8 Capture input channels shared with 8 PWM output channels
- Each channel supports one rising latch register (CRLR), one falling latch register (CFLR) and Capture interrupt flag (CAPIFx)

5.16 Analog-to-Digital Converter (ADC)

5.16.1 Overview

The NuMicro™ NUC200 Series contains one 12-bit successive approximation analog-to-digital converters (SAR A/D converter) with 8 input channels. The A/D converter supports three operation modes: single, single-cycle scan and continuous scan mode. The A/D converter can be started by software, PWM Center-aligned trigger and external STADC pin.

5.16.2 Features

- Analog input voltage range: 0~V_{REF}
- 12-bit resolution and 10-bit accuracy is guaranteed
- Up to 8 single-end analog input channels or 4 differential analog input channels
- Up to 760 kSPS conversion rate as ADC clock frequency is 16 MHz (chip working at 5V)
- Three operating modes
 - Single mode: A/D conversion is performed one time on a specified channel
 - Single-cycle scan mode: A/D conversion is performed one cycle on all specified channels with the sequence from the smallest numbered channel to the largest numbered channel
 - Continuous scan mode: A/D converter continuously performs Single-cycle scan mode until software stops A/D conversion
- An A/D conversion can be started by:
 - Writing 1 to ADST bit through software
 - PWM Center-aligned trigger
 - External pin STADC
- Conversion results are held in data registers for each channel with valid and overrun indicators
- Conversion result can be compared with specify value and user can select whether to generate an interrupt when conversion result matches the compare register setting
- Channel 7 supports 3 input sources: external analog voltage, internal Band-gap voltage, and internal temperature sensor output



PARAMETER	SYM.	SPECIFICATION				TEST CONDITIONS
		MIN.	TYP.	MAX.	UNIT	
	I _{IDLE10}		1.7		mA	V _{DD} = 5.5V All IP and PLL disabled, XTAL = 4 MHz
	I _{IDLE11}		2.4		mA	V _{DD} = 3.3V, All IP enabled and PLL disabled, XTAL = 4 MHz
	I _{IDLE12}		0.8		mA	V _{DD} = 3.3V, All IP and PLL disabled, XTAL = 4 MHz
Operating Current Idle Mode at 32.768 kHz	I _{IDLE13}		133		μA	V _{DD} = 5.5V, All IP enabled and PLL disabled, XTAL = 32.768 kHz
	I _{IDLE14}		120		μA	V _{DD} = 5.5V, All IP and PLL disabled, XTAL = 32.768 kHz
	I _{IDLE15}		133		μA	V _{DD} = 3.3V, All IP enabled and PLL disabled, XTAL = 32.768 kHz
	I _{IDLE16}		120		μA	V _{DD} = 3.3V, All IP and PLL disabled, XTAL = 32.768 kHz
Operating Current Idle Mode at 10 kHz	I _{IDLE13}		122		μA	V _{DD} = 5.5V, All IP enabled and PLL disabled, LIRC10 kHz enabled
	I _{IDLE14}		118		μA	V _{DD} = 5.5V, All IP and PLL disabled, LIRC10 kHz enabled
	I _{IDLE15}		122		μA	V _{DD} = 3.3V, All IP enabled and PLL disabled, LIRC10 kHz enabled
	I _{IDLE16}		118		μA	V _{DD} = 3.3V All IP and PLL disabled, LIRC10 kHz enabled
Standby Current	I _{PWD1}		15		μA	V _{DD} = 5.5V, RTC disabled, When BOD function disabled

8 REVISION HISTORY

Revision	Date	Description
V1.00	June 07, 2012	Initial release

Important Notice

Nuvoton Products are neither intended nor warranted for usage in systems or equipment, any malfunction or failure of which may cause loss of human life, bodily injury or severe property damage. Such applications are deemed, "Insecure Usage".

Insecure usage includes, but is not limited to: equipment for surgical implementation, atomic energy control instruments, airplane or spaceship instruments, the control or operation of dynamic, brake or safety systems designed for vehicular use, traffic signal instruments, all types of safety devices, and other applications intended to support or sustain life.

All Insecure Usage shall be made at customer's risk, and in the event that third parties lay claims to Nuvoton as a result of customer's Insecure Usage, customer shall indemnify the damages and liabilities thus incurred by Nuvoton.

Please note that all data and specifications are subject to change without notice.
All the trademarks of products and companies mentioned in this datasheet belong to their respective owners.