Microchip Technology - A54SX16A-2TQ144 Datasheet

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Obsolete
Number of LABs/CLBs	1452
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	113
Number of Gates	24000
Voltage - Supply	2.25V ~ 5.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	144-LQFP
Supplier Device Package	144-TQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/a54sx16a-2tq144

Email: info@E-XFL.COM Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Temperature Grade Offering

Package	**A54SX08A**	**A54SX16A**	**A54SX32A**	**A54SX72A**
PQ208	C,I,A,M	C,I,A,M	C,I,A,M	C,I,A,M
TQ100	C,I,A,M	C,I,A,M	C,I,A,M	
TQ144	C,I,A,M	C,I,A,M	C,I,A,M	
TQ176			C,I,M	
BG329			C,I,M	
FG144	C,I,A,M	C,I,A,M	C,I,A,M	
FG256		C,I,A,M	C,I,A,M	C,I,A,M
FG484			C,I,M	C,I,A,M
CQ208			C,M,B	C,M,B
CQ256			C,M,B	C,M,B

Notes:

1. *C = Commercial*
2. *I = Industrial*
3. *A = Automotive*
4. *M = Military*
5. *B = MIL-STD-883 Class B*
6. *For more information regarding automotive products, refer to the* SX-A Automotive Family FPGAs *datasheet.*
7. *For more information regarding Mil-Temp and ceramic packages, refer to the* HiRel SX-A Family FPGAs *datasheet.*

Speed Grade and Temperature Grade Matrix

	F	**Std**	**–1**	**–2**	**–3**
Commercial	✓	✓	✓	✓	Discontinued
Industrial		✓	✓	✓	Discontinued
Automotive		✓			
Military		✓	✓		
MIL-STD-883B		✓	✓		

Notes:

1. *For more information regarding automotive products, refer to the* SX-A Automotive Family FPGAs *datasheet.*
2. *For more information regarding Mil-Temp and ceramic packages, refer to the* HiRel SX-A Family FPGAs *datasheet.*

Contact your Actel Sales representative for more information on availability.

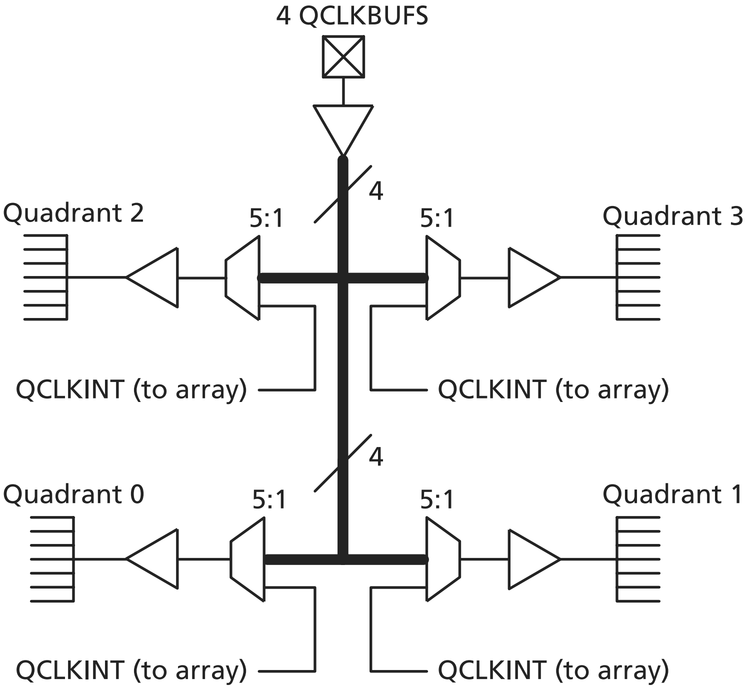


Figure 1-9 • **SX-A QCLK Architecture**

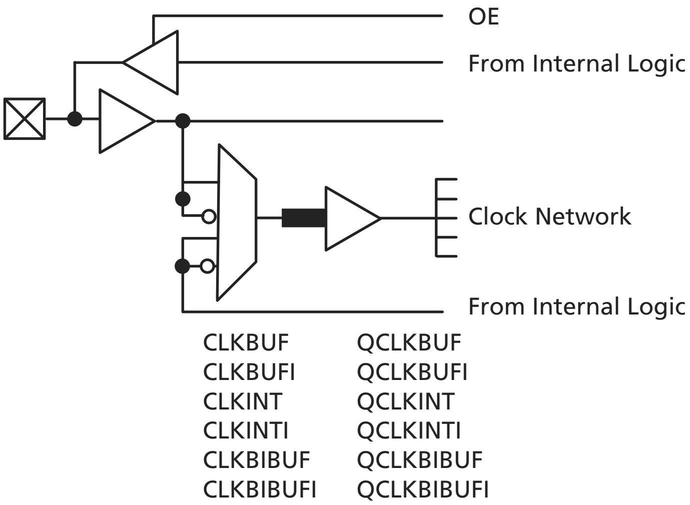


Figure 1-10 • **A54SX72A Routed Clock and QCLK Buffer**

Boundary-Scan Testing (BST)

All SX-A devices are IEEE 1149.1 compliant and offer superior diagnostic and testing capabilities by providing Boundary Scan Testing (BST) and probing capabilities. The BST function is controlled through the special JTAG pins (TMS, TDI, TCK, TDO, and TRST). The functionality of the JTAG pins is defined by two available modes: Dedicated and Flexible. TMS cannot be employed as a user I/O in either mode.

Dedicated Mode

In Dedicated mode, all JTAG pins are reserved for BST; designers cannot use them as regular I/Os. An internal pull-up resistor is automatically enabled on both TMS and TDI pins, and the TMS pin will function as defined in the IEEE 1149.1 (JTAG) specification.

To select Dedicated mode, the user must reserve the JTAG pins in Actel's Designer software. Reserve the JTAG pins by checking the **Reserve JTAG** box in the Device Selection Wizard (Figure 1-12).

The default for the software is Flexible mode; all boxes are unchecked. Table 1-5 lists the definitions of the options in the Device Selection Wizard.

Figure 1-12 • **Device Selection Wizard**

Table 1-5 • **Reserve Pin Definitions**

Pin	Function
Reserve JTAG	Keeps pins from being used and changes the behavior of JTAG pins (no pull-up on TMS)
Reserve JTAG Test Reset	Regular I/O or JTAG reset with an internal pull-up
Reserve Probe	Keeps pins from being used or regular I/O

Flexible Mode

In Flexible mode, TDI, TCK, and TDO may be employed as either user I/Os or as JTAG input pins. The internal resistors on the TMS and TDI pins are not present in flexible JTAG mode.

To select the Flexible mode, uncheck the **Reserve JTAG** box in the Device Selection Wizard dialog in the Actel Designer software. In Flexible mode, TDI, TCK, and TDO pins may function as user I/Os or BST pins. The functionality is controlled by the BST Test Access Port (TAP) controller. The TAP controller receives two control inputs, TMS and TCK. Upon power-up, the TAP controller enters the Test-Logic-Reset state. In this state, TDI, TCK, and TDO function as user I/Os. The TDI, TCK, and TDO are transformed from user I/Os into BST pins when a rising edge on TCK is detected while TMS is at logic low. To return to Test-Logic Reset state, TMS must be high for at least five TCK cycles. **An external 10 k pull-up resistor to V_{CCI} should be placed on the TMS pin to pull it High by default.**

Table 1-6 describes the different configuration requirements of BST pins and their functionality in different modes.

Table 1-6 • **Boundary-Scan Pin Configurations and Functions**

Mode	Designer "Reserve JTAG" Selection	TAP Controller State
Dedicated (JTAG)	Checked	Any
Flexible (User I/O)	Unchecked	Test-Logic-Reset
Flexible (JTAG)	Unchecked	Any EXCEPT Test-Logic-Reset

TRST Pin

The TRST pin functions as a dedicated Boundary-Scan Reset pin when the **Reserve JTAG Test Reset** option is selected as shown in Figure 1-12. An internal pull-up resistor is permanently enabled on the TRST pin in this mode. Actel recommends connecting this pin to ground in normal operation to keep the JTAG state controller in the Test-Logic-Reset state. When JTAG is being used, it can be left floating or can be driven high.

When the **Reserve JTAG Test Reset** option is not selected, this pin will function as a regular I/O. If unused as an I/O in the design, it will be configured as a tristated output.

SX-A Probe Circuit Control Pins

SX-A devices contain internal probing circuitry that provides built-in access to every node in a design, enabling 100% real-time observation and analysis of a device's internal logic nodes without design iteration. The probe circuitry is accessed by Silicon Explorer II, an easy to use, integrated verification and logic analysis tool that can sample data at 100 MHz (asynchronous) or 66 MHz (synchronous). Silicon Explorer II attaches to a PC’s standard COM port, turning the PC into a fully functional 18-channel logic analyzer. Silicon Explorer II allows designers to complete the design verification process at their desks and reduces verification time from several hours per cycle to a few seconds.

The Silicon Explorer II tool uses the boundary-scan ports (TDI, TCK, TMS, and TDO) to select the desired nets for verification. The selected internal nets are assigned to the PRA/PRB pins for observation. Figure 1-13 illustrates the interconnection between Silicon Explorer II and the FPGA to perform in-circuit verification.

Design Considerations

In order to preserve device probing capabilities, users should avoid using the TDI, TCK, TDO, PRA, and PRB pins as input or bidirectional ports. Since these pins are active during probing, critical input signals through these pins are not available. In addition, the security fuse must not be programmed to preserve probing capabilities. Actel recommends that you use a 70 Ω series termination resistor on every probe connector (TDI, TCK, TMS, TDO, PRA, PRB). The 70 Ω series termination is used to prevent data transmission corruption during probing and reading back the checksum.

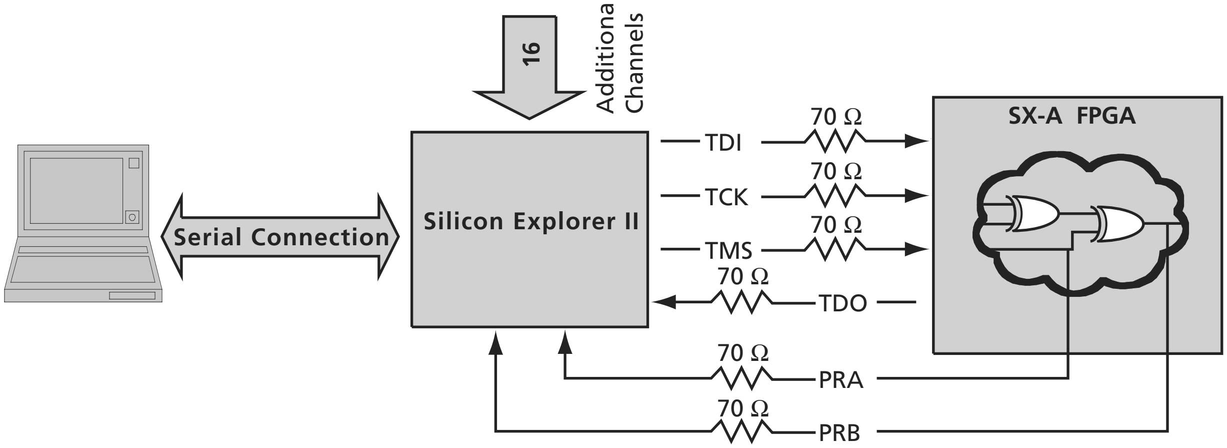


Figure 1-13 • **Probe Setup**

Related Documents

Application Notes

Global Clock Networks in Actel's Antifuse Devices
http://www.actel.com/documents/GlobalClk_AN.pdf
Using A54SX72A and RT54SX72S Quadrant Clocks
http://www.actel.com/documents/QCLK_AN.pdf
Implementation of Security in Actel Antifuse FPGAs
http://www.actel.com/documents/Antifuse_Security_AN.pdf
Actel eX, SX-A, and RTSX-S I/Os
http://www.actel.com/documents/AntifuseIO_AN.pdf
Actel SX-A and RT54SX-S Devices in Hot-Swap and Cold-Sparing Applications
http://www.actel.com/documents/HotSwapColdSparing_AN.pdf
Programming Antifuse Devices
http://www.actel.com/documents/AntifuseProgram_AN.pdf

Datasheets

HiRel SX-A Family FPGAs
http://www.actel.com/documents/HRSXA_DS.pdf
SX-A Automotive Family FPGAs
http://www.actel.com/documents/SXA_Auto_DS.pdf

User's Guides

Silicon Sculptor User's Guide
http://www.actel.com/documents/SiliSculptII_Sculpt3_ug.pdf

Table 2-8 • **AC Specifications (5 V PCI Operation)**

Symbol	Parameter	Condition	Min.	Max.	Units
$I_{OH(AC)}$	Switching Current High	$0 < V_{OUT} \le 1.4$ [1]	–44	–	mA
		$1.4 \le V_{OUT} < 2.4$ [1, 2]	$(-44 + (V_{OUT} - 1.4)/0.024)$	–	mA
		$3.1 < V_{OUT} < V_{CCI}$ [1, 3]	–	EQ 2-1 on page 2-5	–
	(Test Point)	$V_{OUT} = 3.1$ [3]	–	–142	mA
$I_{OL(AC)}$	Switching Current Low	$V_{OUT} \ge 2.2$ [1]	95	–	mA
		$2.2 > V_{OUT} > 0.55$ [1]	$(V_{OUT}/0.023)$	–	mA
		$0.71 > V_{OUT} > 0$ [1, 3]	–	EQ 2-2 on page 2-5	–
	(Test Point)	$V_{OUT} = 0.71$ [3]	–	206	mA
I_{CL}	Low Clamp Current	$-5 < V_{IN} \le -1$	$-25 + (V_{IN} + 1)/0.015$	–	mA
$slew_R$	Output Rise Slew Rate	0.4 V to 2.4 V load [4]	1	5	V/ns
$slew_F$	Output Fall Slew Rate	2.4 V to 0.4 V load [4]	1	5	V/ns

Notes:

1. *Refer to the V/I curves in Figure 2-1 on page 2-5. Switching current characteristics for REQ# and GNT# are permitted to be one half of that specified here; i.e., half size output drivers may be used on these signals. This specification does not apply to CLK and RST#, which are system outputs. "Switching Current High" specifications are not relevant to SERR#, INTA#, INTB#, INTC#, and INTD#, which are open drain outputs.*
2. *Note that this segment of the minimum current curve is drawn from the AC drive point directly to the DC drive point rather than toward the voltage rail (as is done in the pull-down curve). This difference is intended to allow for an optional N-channel pull-up.*
3. *Maximum current requirements must be met as drivers pull beyond the last step voltage. Equations defining these maximums (A and B) are provided with the respective diagrams in Figure 2-1 on page 2-5. The equation defined maximum should be met by design. In order to facilitate component testing, a maximum current test point is defined for each side of the output driver.*
4. *This parameter is to be interpreted as the cumulative edge rate across the specified range, rather than the instantaneous rate at any point within the transition range. The specified load (diagram below) is optional; i.e., the designer may elect to meet this parameter with an unloaded output per revision 2.0 of the PCI Local Bus Specification. However, adherence to both maximum and minimum parameters is now required (the maximum is no longer simply a guideline). Since adherence to the maximum slew rate was not required prior to revision 2.1 of the specification, there may be components in the market for some time that have faster edge rates; therefore, motherboard designers must bear in mind that rise and fall times faster than this specification could occur and should ensure that signal integrity modeling accounts for this. Rise slew rate does not apply to open drain outputs.*

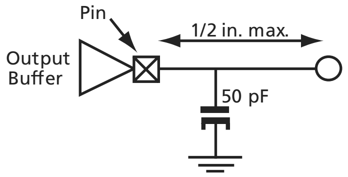
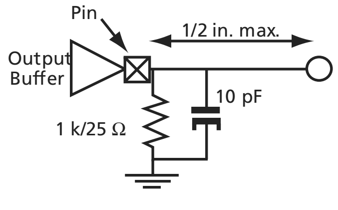


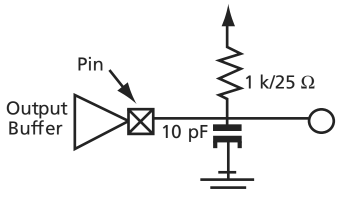
Table 2-10 • **AC Specifications (3.3 V PCI Operation)**

Symbol	**Parameter**	**Condition**	**Min.**	**Max.**	**Units**
$I_{OH(AC)}$	Switching Current High	$0 < V_{OUT} \leq 0.3V_{CCI}$ [1]	$-12V_{CCI}$	–	mA
		$0.3V_{CCI} \leq V_{OUT} < 0.9V_{CCI}$ [1]	$(-17.1(V_{CCI} - V_{OUT}))$	–	mA
		$0.7V_{CCI} < V_{OUT} < V_{CCI}$ [1, 2]	–	EQ 2-3 on page 2-7	–
	(Test Point)	$V_{OUT} = 0.7V_{CC}$ [2]	–	$-32V_{CCI}$	mA
$I_{OL(AC)}$	Switching Current Low	$V_{CCI} > V_{OUT} \geq 0.6V_{CCI}$ [1]	$16V_{CCI}$	–	mA
		$0.6V_{CCI} > V_{OUT} > 0.1V_{CCI}$ [1]	$(26.7V_{OUT})$	–	mA
		$0.18V_{CCI} > V_{OUT} > 0$ [1, 2]	–	EQ 2-4 on page 2-7	–
	(Test Point)	$V_{OUT} = 0.18V_{CC}$ [2]	–	$38V_{CCI}$	mA
I_{CL}	Low Clamp Current	$-3 < V_{IN} \leq -1$	$-25 + (V_{IN} + 1)/0.015$	–	mA
I_{CH}	High Clamp Current	$V_{CCI} + 4 > V_{IN} \geq V_{CCI} + 1$	$25 + (V_{IN} - V_{CCI} - 1)/0.015$	–	mA
$slew_R$	Output Rise Slew Rate	$0.2V_{CCI}$ - $0.6V_{CCI}$ load [3]	1	4	V/ns
$slew_F$	Output Fall Slew Rate	$0.6V_{CCI}$ - $0.2V_{CCI}$ load [3]	1	4	V/ns

Notes:

1. *Refer to the V/I curves in Figure 2-2 on page 2-7. Switching current characteristics for REQ# and GNT# are permitted to be one half of that specified here; i.e., half size output drivers may be used on these signals. This specification does not apply to CLK and RST#, which are system outputs. "Switching Current High" specifications are not relevant to SERR#, INTA#, INTB#, INTC#, and INTD#, which are open drain outputs.*
2. *Maximum current requirements must be met as drivers pull beyond the last step voltage. Equations defining these maximums (C and D) are provided with the respective diagrams in Figure 2-2 on page 2-7. The equation defined maximum should be met by design. In order to facilitate component testing, a maximum current test point is defined for each side of the output driver.*
3. *This parameter is to be interpreted as the cumulative edge rate across the specified range, rather than the instantaneous rate at any point within the transition range. The specified load (diagram below) is optional; i.e., the designer may elect to meet this parameter with an unloaded output per the latest revision of the PCI Local Bus Specification. However, adherence to both maximum and minimum parameters is required (the maximum is no longer simply a guideline). Rise slew rate does not apply to open drain outputs.*





Thermal Characteristics

Introduction

The temperature variable in Actel Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption will cause the chip's junction to be higher than the ambient, case, or board temperatures. EQ 2-9 and EQ 2-10 give the relationship between thermal resistance, temperature gradient and power.

$$\theta_{JA} = \frac{T_J - T_A}{P}$$

EQ 2-9

$$\theta_{JA} = \frac{T_C - T_A}{P}$$

EQ 2-10

Where:

θ_{JA} = Junction-to-air thermal resistance
θ_{JC} = Junction-to-case thermal resistance
T_J = Junction temperature
T_A = Ambient temperature
T_C = Ambient temperature
P = total power dissipated by the device

Table 2-12 • **Package Thermal Characteristics**

Package Type	**Pin Count**	θ_{JC}	θ_{JA} Still Air	θ_{JA} 1.0 m/s 200 ft./min.	θ_{JA} 2.5 m/s 500 ft./min.	**Units**
Thin Quad Flat Pack (TQFP)	100	14	33.5	27.4	25	°C/W
Thin Quad Flat Pack (TQFP)	144	11	33.5	28	25.7	°C/W
Thin Quad Flat Pack (TQFP)	176	11	24.7	19.9	18	°C/W
Plastic Quad Flat Pack (PQFP)[1]	208	8	26.1	22.5	20.8	°C/W
Plastic Quad Flat Pack (PQFP) with Heat Spreader[2]	208	3.8	16.2	13.3	11.9	°C/W
Plastic Ball Grid Array (PBGA)	329	3	17.1	13.8	12.8	°C/W
Fine Pitch Ball Grid Array (FBGA)	144	3.8	26.9	22.9	21.5	°C/W
Fine Pitch Ball Grid Array (FBGA)	256	3.8	26.6	22.8	21.5	°C/W
Fine Pitch Ball Grid Array (FBGA)	484	3.2	18	14.7	13.6	°C/W

Notes:

1. *The A54SX08A PQ208 has no heat spreader.*
2. *The SX-A PQ208 package has a heat spreader for A54SX16A, A54SX32A, and A54SX72A.*

Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JESD-51 series but has little relevance in actual performance of the product in real application. It should be employed with caution but is useful for comparing the thermal performance of one package to another.

A sample calculation to estimate the absolute maximum power dissipation allowed (worst case) for a 329-pin PBGA package at still air is as follows. i.e.:

θ_{JA} = 17.1°C/W is taken from Table 2-12 on page 2-11

T_A = 125°C is the maximum limit of ambient (from the datasheet)

$$\text{Max. Allowed Power} = \frac{\text{Max Junction Temp} - \text{Max. Ambient Temp}}{\theta_{JA}} = \frac{150°\text{C} - 125°\text{C}}{17.1°\text{C/W}} = 1.46\text{ W}$$

EQ 2-11

The device's power consumption must be lower than the calculated maximum power dissipation by the package.

The power consumption of a device can be calculated using the Actel power calculator. If the power consumption is higher than the device's maximum allowable power dissipation, then a heat sink can be attached on top of the case or the airflow inside the system must be increased.

Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable for packages used with external heat sinks and only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration. If the power consumption is higher than the calculated maximum power dissipation of the package, then a heat sink is required.

Calculation for Heat Sink

For example, in a design implemented in a FG484 package, the power consumption value using the power calculator is 3.00 W. The user-dependent data T_J and T_A are given as follows:

T_J = 110°C

T_A = 70°C

From the datasheet:

θ_{JA} = 18.0°C/W

θ_{JC} = 3.2 °C/W

$$P = \frac{\text{Max Junction Temp} - \text{Max. Ambient Temp}}{\theta_{JA}} = \frac{110°\text{C} - 70°\text{C}}{18.0°\text{C/W}} = 2.22\text{ W}$$

EQ 2-12

The 2.22 W power is less than then required 3.00 W; therefore, the design requires a heat sink or the airflow where the device is mounted should be increased. The design's junction-to-air thermal resistance requirement can be estimated by:

$$\theta_{JA} = \frac{\text{Max Junction Temp} - \text{Max. Ambient Temp}}{P} = \frac{110°\text{C} - 70°\text{C}}{3.00\text{ W}} = 13.33°\text{C/W}$$

EQ 2-13

Timing Characteristics

Timing characteristics for SX-A devices fall into three categories: family-dependent, device-dependent, and design-dependent. The input and output buffer characteristics are common to all SX-A family members. Internal routing delays are device-dependent. Design dependency means actual delays are not determined until after placement and routing of the user's design are complete. The timing characteristics listed in this datasheet represent sample timing numbers of the SX-A devices. Design-specific delay values may be determined by using Timer or performing simulation after successful place-and-route with the Designer software.

Critical Nets and Typical Nets

Propagation delays are expressed only for typical nets, which are used for initial design performance evaluation. Critical net delays can then be applied to the most timing-critical paths. Critical nets are determined by net property assignment prior to placement and routing. Up to 6 percent of the nets in a design may be designated as critical, while 90 percent of the nets in a design are typical.

Long Tracks

Some nets in the design use long tracks. Long tracks are special routing resources that span multiple rows, columns, or modules. Long tracks employ three to five antifuse connections. This increases capacitance and resistance, resulting in longer net delays for macros connected to long tracks. Typically, up to 6 percent of nets in a fully utilized device require long tracks. Long tracks contribute approximately 4 ns to 8.4 ns delay. This additional delay is represented statistically in higher fanout routing delays.

Timing Derating

SX-A devices are manufactured with a CMOS process. Therefore, device performance varies according to temperature, voltage, and process changes. Minimum timing parameters reflect maximum operating voltage, minimum operating temperature, and best-case processing. Maximum timing parameters reflect minimum operating voltage, maximum operating temperature, and worst-case processing.

Temperature and Voltage Derating Factors

Table 2-13 • **Temperature and Voltage Derating Factors (Normalized to Worst-Case Commercial, T_J = 70°C, V_{CCA} = 2.25 V)**

V_{CCA}	Junction Temperature (T_J)						
	–55°C	–40°C	0°C	25°C	70°C	85°C	125°C
2.250 V	0.79	0.80	0.87	0.89	1.00	1.04	1.14
2.500 V	0.74	0.75	0.82	0.83	0.94	0.97	1.07
2.750 V	0.68	0.69	0.75	0.77	0.87	0.90	0.99

Table 2-28 • **A54SX32A Timing Characteristics (Continued)**
(Worst-Case Commercial Conditions, V_{CCA} = 2.25 V, V_{CCI} = 3.0 V, T_J = 70°C)

Parameter	Description	–3 Speed[1] Min.	–3 Speed[1] Max.	–2 Speed Min.	–2 Speed Max.	–1 Speed Min.	–1 Speed Max.	Std. Speed Min.	Std. Speed Max.	–F Speed Min.	–F Speed Max.	Units
t_{INYH}	Input Data Pad to Y High 5 V PCI		0.7		0.8		0.9		1.0		1.4	ns
t_{INYL}	Input Data Pad to Y Low 5 V PCI		0.9		1.1		1.2		1.4		1.9	ns
t_{INYH}	Input Data Pad to Y High 5 V TTL		0.9		1.1		1.2		1.4		1.9	ns
t_{INYL}	Input Data Pad to Y Low 5 V TTL		1.4		1.6		1.8		2.1		2.9	ns
Input Module Predicted Routing Delays[3]												
t_{IRD1}	FO = 1 Routing Delay		0.3		0.3		0.3		0.4		0.6	ns
t_{IRD2}	FO = 2 Routing Delay		0.4		0.5		0.5		0.6		0.8	ns
t_{IRD3}	FO = 3 Routing Delay		0.5		0.6		0.7		0.8		1.1	ns
t_{IRD4}	FO = 4 Routing Delay		0.7		0.8		0.9		1		1.4	ns
t_{IRD8}	FO = 8 Routing Delay		1.2		1.4		1.5		1.8		2.5	ns
t_{IRD12}	FO = 12 Routing Delay		1.7		2		2.2		2.6		3.6	ns

Notes:

1. *All –3 speed grades have been discontinued.*
2. *For dual-module macros, use* $t_{PD} + t_{RD1} + t_{PDn}$ *,* $t_{RCO} + t_{RD1} + t_{PDn}$ *, or* $t_{PD1} + t_{RD1} + t_{SUD}$ *, whichever is appropriate.*
3. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.*

Table 2-35 • **A54SX72A Timing Characteristics (Worst-Case Commercial Conditions, V_{CCA} = 2.25 V, V_{CCI} = 3.0 V, T_J = 70°C)**

Parameter	**Description**	**–3 Speed[1]**		**–2 Speed**		**–1 Speed**		**Std. Speed**		**–F Speed**		**Units**
		Min.	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	
C-Cell Propagation Delays[2]												
t_{PD}	Internal Array Module		1.0		1.1		1.3		1.5		2.0	ns
Predicted Routing Delays[3]												
t_{DC}	FO = 1 Routing Delay, Direct Connect		0.1		0.1		0.1		0.1		0.1	ns
t_{FC}	FO = 1 Routing Delay, Fast Connect		0.3		0.3		0.3		0.4		0.6	ns
t_{RD1}	FO = 1 Routing Delay		0.3		0.3		0.4		0.5		0.7	ns
t_{RD2}	FO = 2 Routing Delay		0.4		0.5		0.6		0.7		1	ns
t_{RD3}	FO = 3 Routing Delay		0.5		0.7		0.8		0.9		1.3	ns
t_{RD4}	FO = 4 Routing Delay		0.7		0.9		1		1.1		1.5	ns
t_{RD8}	FO = 8 Routing Delay		1.2		1.5		1.7		2.1		2.9	ns
t_{RD12}	FO = 12 Routing Delay		1.7		2.2		2.5		3		4.2	ns
R-Cell Timing												
t_{RCO}	Sequential Clock-to-Q		0.7		0.8		0.9		1.1		1.5	ns
t_{CLR}	Asynchronous Clear-to-Q		0.6		0.7		0.7		0.9		1.2	ns
t_{PRESET}	Asynchronous Preset-to-Q		0.7		0.8		0.8		1.0		1.4	ns
t_{SUD}	Flip-Flop Data Input Set-Up	0.7		0.8		0.9		1.0		1.4		ns
t_{HD}	Flip-Flop Data Input Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{WASYN}	Asynchronous Pulse Width	1.3		1.5		1.7		2.0		2.8		ns
$t_{RECASYN}$	Asynchronous Recovery Time	0.3		0.4		0.4		0.5		0.7		ns
t_{HASYN}	Asynchronous Hold Time	0.3		0.3		0.3		0.4		0.6		ns
t_{MPW}	Clock Minimum Pulse Width	1.5		1.7		2.0		2.3		3.2		ns
Input Module Propagation Delays												
t_{INYH}	Input Data Pad to Y High 2.5 V LVCMOS		0.6		0.7		0.8		0.9		1.3	ns
t_{INYL}	Input Data Pad to Y Low 2.5 V LVCMOS		0.8		1.0		1.1		1.3		1.7	ns
t_{INYH}	Input Data Pad to Y High 3.3 V PCI		0.6		0.7		0.7		0.9		1.2	ns
t_{INYL}	Input Data Pad to Y Low 3.3 V PCI		0.7		0.8		0.9		1.0		1.4	ns
t_{INYH}	Input Data Pad to Y High 3.3 V LVTTL		0.7		0.7		0.8		1.0		1.4	ns
t_{INYL}	Input Data Pad to Y Low 3.3 V LVTTL		1.0		1.2		1.3		1.5		2.1	ns

Notes:

1. *All –3 speed grades have been discontinued.*
2. *For dual-module macros, use* $t_{PD} + t_{RD1} + t_{PDn}$ *,* $t_{RCO} + t_{RD1} + t_{PDn}$ *, or* $t_{PD1} + t_{RD1} + t_{SUD}$ *, whichever is appropriate.*
3. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual performance.*

Table 2-36 • **A54SX72A Timing Characteristics**
(Worst-Case Commercial Conditions V_{CCA} = 2.25 V, V_{CCI} = 2.25 V, T_J = 70°C)

Parameter	Description	–3 Speed* Min.	–3 Speed* Max.	–2 Speed Min.	–2 Speed Max.	–1 Speed Min.	–1 Speed Max.	Std. Speed Min.	Std. Speed Max.	–F Speed Min.	–F Speed Max.	Units
Dedicated (Hardwired) Array Clock Networks												
t_{HCKH}	Input Low to High (Pad to R-cell Input)		1.6		1.9		2.1		2.5		3.8	ns
t_{HCKL}	Input High to Low (Pad to R-cell Input)		1.6		1.9		2.1		2.5		3.8	ns
t_{HPWH}	Minimum Pulse Width High	1.5		1.7		2.0		2.3		3.2		ns
t_{HPWL}	Minimum Pulse Width Low	1.5		1.7		2.0		2.3		3.2		ns
t_{HCKSW}	Maximum Skew		1.4		1.6		1.8		2.1		3.3	ns
t_{HP}	Minimum Period	3.0		3.4		4.0		4.6		6.4		ns
f_{HMAX}	Maximum Frequency		333		294		250		217		156	MHz
Routed Array Clock Networks												
t_{RCKH}	Input Low to High (Light Load) (Pad to R-cell Input)		2.3		2.6		2.9		3.4		4.8	ns
t_{RCKL}	Input High to Low (Light Load) (Pad to R-cell Input)		2.8		3.2		3.7		4.3		6.0	ns
t_{RCKH}	Input Low to High (50% Load) (Pad to R-cell Input)		2.4		2.8		3.2		3.7		5.2	ns
t_{RCKL}	Input High to Low (50% Load) (Pad to R-cell Input)		2.9		3.3		3.8		4.5		6.2	ns
t_{RCKH}	Input Low to High (100% Load) (Pad to R-cell Input)		2.6		3.0		3.4		4.0		5.6	ns
t_{RCKL}	Input High to Low (100% Load) (Pad to R-cell Input)		3.1		3.6		4.0		4.7		6.6	ns
t_{RPWH}	Minimum Pulse Width High	1.5		1.7		2.0		2.3		3.2		ns
t_{RPWL}	Minimum Pulse Width Low	1.5		1.7		2.0		2.3		3.2		ns
t_{RCKSW}	Maximum Skew (Light Load)		1.9		2.2		2.5		3.0		4.1	ns
t_{RCKSW}	Maximum Skew (50% Load)		1.8		2.1		2.4		2.8		3.9	ns
t_{RCKSW}	Maximum Skew (100% Load)		1.8		2.1		2.4		2.8		3.9	ns
Quadrant Array Clock Networks												
t_{QCKH}	Input Low to High (Light Load) (Pad to R-cell Input)		2.6		3.0		3.4		4.0		5.6	ns
t_{QCHKL}	Input High to Low (Light Load) (Pad to R-cell Input)		2.6		3.0		3.3		3.9		5.5	ns
t_{QCKH}	Input Low to High (50% Load) (Pad to R-cell Input)		2.8		3.2		3.6		4.3		6.0	ns
t_{QCHKL}	Input High to Low (50% Load) (Pad to R-cell Input)		2.8		3.2		3.6		4.2		5.9	ns

Note: **All –3 speed grades have been discontinued.*

Table 2-37 • **A54SX72A Timing Characteristics (Continued)**
(Worst-Case Commercial Conditions V_{CCA} = 2.25 V, V_{CCI} = 3.0 V, T_J = 70°C)

		–3 Speed*		**–2 Speed**		**–1 Speed**		**Std. Speed**		**–F Speed**		
Parameter	**Description**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
t_{QCKH}	Input Low to High (100% Load) (Pad to R-cell Input)		1.7		1.9		2.2		2.5		3.5	ns
t_{QCHKL}	Input High to Low (100% Load) (Pad to R-cell Input)		1.7		2		2.2		2.6		3.6	ns
t_{QPWH}	Minimum Pulse Width High	1.5		1.7		2.0		2.3		3.2		ns
t_{QPWL}	Minimum Pulse Width Low	1.5		1.7		2.0		2.3		3.2		ns
t_{QCKSW}	Maximum Skew (Light Load)		0.2		0.3		0.3		0.3		0.5	ns
t_{QCKSW}	Maximum Skew (50% Load)		0.4		0.5		0.5		0.6		0.9	ns
t_{QCKSW}	Maximum Skew (100% Load)		0.4		0.5		0.5		0.6		0.9	ns

Note: **All –3 speed grades have been discontinued.*

Table 2-38 • **A54SX72A Timing Characteristics (Worst-Case Commercial Conditions V_{CCA} = 2.25 V, V_{CCI} = 4.75 V, T_J = 70°C)**

Parameter	Description	–3 Speed* Min.	–3 Speed* Max.	–2 Speed Min.	–2 Speed Max.	–1 Speed Min.	–1 Speed Max.	Std. Speed Min.	Std. Speed Max.	–F Speed Min.	–F Speed Max.	Units
Dedicated (Hardwired) Array Clock Networks												
t_{HCKH}	Input Low to High (Pad to R-cell Input)		1.6		1.8		2.1		2.4		3.8	ns
t_{HCKL}	Input High to Low (Pad to R-cell Input)		1.6		1.9		2.1		2.5		3.8	ns
t_{HPWH}	Minimum Pulse Width High	1.5		1.7		2.0		2.3		3.2		ns
t_{HPWL}	Minimum Pulse Width Low	1.5		1.7		2.0		2.3		3.2		ns
t_{HCKSW}	Maximum Skew		1.4		1.6		1.8		2.1		3.3	ns
t_{HP}	Minimum Period	3.0		3.4		4.0		4.6		6.4		ns
f_{HMAX}	Maximum Frequency		333		294		250		217		156	MHz
Routed Array Clock Networks												
t_{RCKH}	Input Low to High (Light Load) (Pad to R-cell Input)		2.3		2.6		3.0		3.5		4.9	ns
t_{RCKL}	Input High to Low (Light Load) (Pad to R-cell Input)		2.8		3.2		3.6		4.3		6.0	ns
t_{RCKH}	Input Low to High (50% Load) (Pad to R-cell Input)		2.5		2.9		3.2		3.8		5.3	ns
t_{RCKL}	Input High to Low (50% Load) (Pad to R-cell Input)		3.0		3.4		3.9		4.6		6.4	ns
t_{RCKH}	Input Low to High (100% Load) (Pad to R-cell Input)		2.6		3.0		3.4		3.9		5.5	ns
t_{RCKL}	Input High to Low (100% Load) (Pad to R-cell Input)		3.2		3.6		4.1		4.8		6.8	ns
t_{RPWH}	Minimum Pulse Width High	1.5		1.7		2.0		2.3		3.2		ns
t_{RPWL}	Minimum Pulse Width Low	1.5		1.7		2.0		2.3		3.2		ns
t_{RCKSW}	Maximum Skew (Light Load)		1.9		2.2		2.5		3.0		4.1	ns
t_{RCKSW}	Maximum Skew (50% Load)		1.9		2.2		2.5		3.0		4.1	ns
t_{RCKSW}	Maximum Skew (100% Load)		1.9		2.2		2.5		3.0		4.1	ns
Quadrant Array Clock Networks												
t_{QCKH}	Input Low to High (Light Load) (Pad to R-cell Input)		1.2		1.4		1.6		1.8		2.6	ns
t_{QCHKL}	Input High to Low (Light Load) (Pad to R-cell Input)		1.3		1.4		1.6		1.9		2.7	ns
t_{QCKH}	Input Low to High (50% Load) (Pad to R-cell Input)		1.4		1.6		1.8		2.1		3.0	ns
t_{QCHKL}	Input High to Low (50% Load) (Pad to R-cell Input)		1.4		1.7		1.9		2.2		3.1	ns

Note: **All –3 speed grades have been discontinued.*

Table 2-38 • **A54SX72A Timing Characteristics (Continued)**
(Worst-Case Commercial Conditions V_{CCA} = 2.25 V, V_{CCI} = 4.75 V, T_J = 70°C)

		–3 Speed*		**–2 Speed**		**–1 Speed**		**Std. Speed**		**–F Speed**		
Parameter	**Description**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Units**
t_{QCKH}	Input Low to High (100% Load) (Pad to R-cell Input)		1.6		1.8		2.1		2.4		3.4	ns
t_{QCHKL}	Input High to Low (100% Load) (Pad to R-cell Input)		1.6		1.9		2.1		2.5		3.5	ns
t_{QPWH}	Minimum Pulse Width High	1.5		1.7		2.0		2.3		3.2		ns
t_{QPWL}	Minimum Pulse Width Low	1.5		1.7		2.0		2.3		3.2		ns
t_{QCKSW}	Maximum Skew (Light Load)		0.2		0.3		0.3		0.3		0.5	ns
t_{QCKSW}	Maximum Skew (50% Load)		0.4		0.5		0.5		0.6		0.9	ns
t_{QCKSW}	Maximum Skew (100% Load)		0.4		0.5		0.5		0.6		0.9	ns

Note: **All –3 speed grades have been discontinued.*

Table 2-39 • **A54SX72A Timing Characteristics**
(Worst-Case Commercial Conditions $V_{CCA} = 2.25$ V, $V_{CCI} = 2.3$ V, $T_J = 70°C$)

Parameter	Description	–3 Speed[1]		–2 Speed		–1 Speed		Std. Speed		–F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
2.5 V LVCMOS Output Module Timing[2, 3]												
t_{DLH}	Data-to-Pad Low to High		3.9		4.5		5.1		6.0		8.4	ns
t_{DHL}	Data-to-Pad High to Low		3.1		3.6		4.1		4.8		6.7	ns
t_{DHLS}	Data-to-Pad High to Low—low slew		12.7		14.6		16.5		19.4		27.2	ns
t_{ENZL}	Enable-to-Pad, Z to L		2.4		2.8		3.2		3.7		5.2	ns
t_{ENZLS}	Data-to-Pad, Z to L—low slew		11.8		13.7		15.5		18.2		25.5	ns
t_{ENZH}	Enable-to-Pad, Z to H		3.9		4.5		5.1		6.0		8.4	ns
t_{ENLZ}	Enable-to-Pad, L to Z		2.1		2.5		2.8		3.3		4.7	ns
t_{ENHZ}	Enable-to-Pad, H to Z		3.1		3.6		4.1		4.8		6.7	ns
d_{TLH}[4]	Delta Low to High		0.031		0.037		0.043		0.051		0.071	ns/pF
d_{THL}[4]	Delta High to Low		0.017		0.017		0.023		0.023		0.037	ns/pF
d_{THLS}[4]	Delta High to Low—low slew		0.057		0.06		0.071		0.086		0.117	ns/pF

Note:

1. *All –3 speed grades have been discontinued.*
2. *Delays based on 35 pF loading.*
3. *The equivalent IO Attribute settings for 2.5 V LVCMOS is 2.5 V LVTTL in the software.*
4. *To obtain the slew rate, substitute the appropriate Delta value, load capacitance, and the V_{CCI} value into the following equation:*
   Slew Rate [V/ns] = $(0.1*V_{CCI} – 0.9*V_{CCI})/ (C_{load} * d_{T[LH|HL|HLS]})$
   where C_{load} *is the load capacitance driven by the I/O in pF*
   $d_{T[LH|HL|HLS]}$ *is the worst case delta value from the datasheet in ns/pF.*

Table 2-40 • **A54SX72A Timing Characteristics (Worst-Case Commercial Conditions V_{CCA} = 2.25 V, V_{CCI} = 3.0 V, T_J = 70°C)**

Parameter	Description	–3 Speed[1]		–2 Speed		–1 Speed		Std. Speed		–F Speed		Units
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
3.3 V PCI Output Module Timing[2]												
t_{DLH}	Data-to-Pad Low to High		2.3		2.7		3.0		3.6		5.0	ns
t_{DHL}	Data-to-Pad High to Low		2.5		2.9		3.2		3.8		5.3	ns
t_{ENZL}	Enable-to-Pad, Z to L		1.4		1.7		1.9		2.2		3.1	ns
t_{ENZH}	Enable-to-Pad, Z to H		2.3		2.7		3.0		3.6		5.0	ns
t_{ENLZ}	Enable-to-Pad, L to Z		2.5		2.8		3.2		3.8		5.3	ns
t_{ENHZ}	Enable-to-Pad, H to Z		2.5		2.9		3.2		3.8		5.3	ns
d_{TLH}[3]	Delta Low to High		0.025		0.03		0.03		0.04		0.045	ns/pF
d_{THL}[3]	Delta High to Low		0.015		0.015		0.015		0.015		0.025	ns/pF
3.3 V LVTTL Output Module Timing[4]												
t_{DLH}	Data-to-Pad Low to High		3.2		3.7		4.2		5.0		6.9	ns
t_{DHL}	Data-to-Pad High to Low		3.2		3.7		4.2		4.9		6.9	ns
t_{DHLS}	Data-to-Pad High to Low—low slew		10.3		11.9		13.5		15.8		22.2	ns
t_{ENZL}	Enable-to-Pad, Z to L		2.2		2.6		2.9		3.4		4.8	ns
t_{ENZLS}	Enable-to-Pad, Z to L—low slew		15.8		18.9		21.3		25.4		34.9	ns
t_{ENZH}	Enable-to-Pad, Z to H		3.2		3.7		4.2		5.0		6.9	ns
t_{ENLZ}	Enable-to-Pad, L to Z		2.9		3.3		3.7		4.4		6.2	ns
t_{ENHZ}	Enable-to-Pad, H to Z		3.2		3.7		4.2		4.9		6.9	ns
d_{TLH}[3]	Delta Low to High		0.025		0.03		0.03		0.04		0.045	ns/pF
d_{THL}[3]	Delta High to Low		0.015		0.015		0.015		0.015		0.025	ns/pF
d_{THLS}[3]	Delta High to Low—low slew		0.053		0.053		0.067		0.073		0.107	ns/pF

Notes:

1. *All –3 speed grades have been discontinued.*
2. *Delays based on 10 pF loading and 25 Ω resistance.*
3. *To obtain the slew rate, substitute the appropriate Delta value, load capacitance, and the V_{CCI} value into the following equation:*
   Slew Rate [V/ns] = $(0.1*V_{CCI} – 0.9*V_{CCI})/ (C_{load} * d_{T[LH|HL|HLS]})$
   where C_{load} is the load capacitance driven by the I/O in pF
   $d_{T[LH|HL|HLS]}$ is the worst case delta value from the datasheet in ns/pF.
4. *Delays based on 35 pF loading.*

176-Pin TQFP	
Pin Number	A54SX32A Function
1	GND
2	TDI, I/O
3	I/O
4	I/O
5	I/O
6	I/O
7	I/O
8	I/O
9	I/O
10	TMS
11	V_{CCI}
12	I/O
13	I/O
14	I/O
15	I/O
16	I/O
17	I/O
18	I/O
19	I/O
20	I/O
21	GND
22	V_{CCA}
23	GND
24	I/O
25	TRST, I/O
26	I/O
27	I/O
28	I/O
29	I/O
30	I/O
31	I/O
32	V_{CCI}
33	V_{CCA}
34	I/O
35	I/O
36	I/O
37	I/O
38	I/O
39	I/O
40	I/O
41	I/O
42	I/O
43	I/O
44	GND
45	I/O
46	I/O
47	I/O
48	I/O
49	I/O
50	I/O
51	I/O
52	V_{CCI}
53	I/O
54	I/O
55	I/O
56	I/O
57	I/O
58	I/O
59	I/O
60	I/O
61	I/O
62	I/O
63	I/O
64	PRB, I/O
65	GND
66	V_{CCA}
67	NC
68	I/O
69	HCLK
70	I/O
71	I/O
72	I/O
73	I/O
74	I/O
75	I/O
76	I/O
77	I/O
78	I/O
79	I/O
80	I/O
81	I/O
82	V_{CCI}
83	I/O
84	I/O
85	I/O
86	I/O
87	TDO, I/O
88	I/O
89	GND
90	I/O
91	I/O
92	I/O
93	I/O
94	I/O
95	I/O
96	I/O
97	I/O
98	V_{CCA}
99	V_{CCI}
100	I/O
101	I/O
102	I/O
103	I/O
104	I/O
105	I/O
106	I/O
107	I/O
108	GND
109	V_{CCA}
110	GND
111	I/O
112	I/O
113	I/O
114	I/O
115	I/O
116	I/O
117	I/O
118	I/O
119	I/O
120	I/O
121	I/O
122	V_{CCA}
123	GND
124	V_{CCI}
125	I/O
126	I/O
127	I/O
128	I/O
129	I/O
130	I/O
131	I/O
132	I/O
133	GND
134	I/O
135	I/O
136	I/O
137	I/O
138	I/O
139	I/O
140	V_{CCI}
141	I/O
142	I/O
143	I/O
144	I/O

144-Pin FBGA			
Pin Number	A54SX08A Function	A54SX16A Function	A54SX32A Function
G1	I/O	I/O	I/O
G2	GND	GND	GND
G3	I/O	I/O	I/O
G4	I/O	I/O	I/O
G5	GND	GND	GND
G6	GND	GND	GND
G7	GND	GND	GND
G8	V_{CCI}	V_{CCI}	V_{CCI}
G9	I/O	I/O	I/O
G10	I/O	I/O	I/O
G11	I/O	I/O	I/O
G12	I/O	I/O	I/O
H1	TRST, I/O	TRST, I/O	TRST, I/O
H2	I/O	I/O	I/O
H3	I/O	I/O	I/O
H4	I/O	I/O	I/O
H5	V_{CCA}	V_{CCA}	V_{CCA}
H6	V_{CCA}	V_{CCA}	V_{CCA}
H7	V_{CCI}	V_{CCI}	V_{CCI}
H8	V_{CCI}	V_{CCI}	V_{CCI}
H9	V_{CCA}	V_{CCA}	V_{CCA}
H10	I/O	I/O	I/O
H11	I/O	I/O	I/O
H12	NC	NC	NC
J1	I/O	I/O	I/O
J2	I/O	I/O	I/O
J3	I/O	I/O	I/O
J4	I/O	I/O	I/O
J5	I/O	I/O	I/O
J6	PRB, I/O	PRB, I/O	PRB, I/O
J7	I/O	I/O	I/O
J8	I/O	I/O	I/O
J9	I/O	I/O	I/O
J10	I/O	I/O	I/O
J11	I/O	I/O	I/O
J12	V_{CCA}	V_{CCA}	V_{CCA}

144-Pin FBGA			
Pin Number	A54SX08A Function	A54SX16A Function	A54SX32A Function
K1	I/O	I/O	I/O
K2	I/O	I/O	I/O
K3	I/O	I/O	I/O
K4	I/O	I/O	I/O
K5	I/O	I/O	I/O
K6	I/O	I/O	I/O
K7	GND	GND	GND
K8	I/O	I/O	I/O
K9	I/O	I/O	I/O
K10	GND	GND	GND
K11	I/O	I/O	I/O
K12	I/O	I/O	I/O
L1	GND	GND	GND
L2	I/O	I/O	I/O
L3	I/O	I/O	I/O
L4	I/O	I/O	I/O
L5	I/O	I/O	I/O
L6	I/O	I/O	I/O
L7	HCLK	HCLK	HCLK
L8	I/O	I/O	I/O
L9	I/O	I/O	I/O
L10	I/O	I/O	I/O
L11	I/O	I/O	I/O
L12	I/O	I/O	I/O
M1	I/O	I/O	I/O
M2	I/O	I/O	I/O
M3	I/O	I/O	I/O
M4	I/O	I/O	I/O
M5	I/O	I/O	I/O
M6	I/O	I/O	I/O
M7	V_{CCA}	V_{CCA}	V_{CCA}
M8	I/O	I/O	I/O
M9	I/O	I/O	I/O
M10	I/O	I/O	I/O
M11	TDO, I/O	TDO, I/O	TDO, I/O
M12	I/O	I/O	I/O