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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

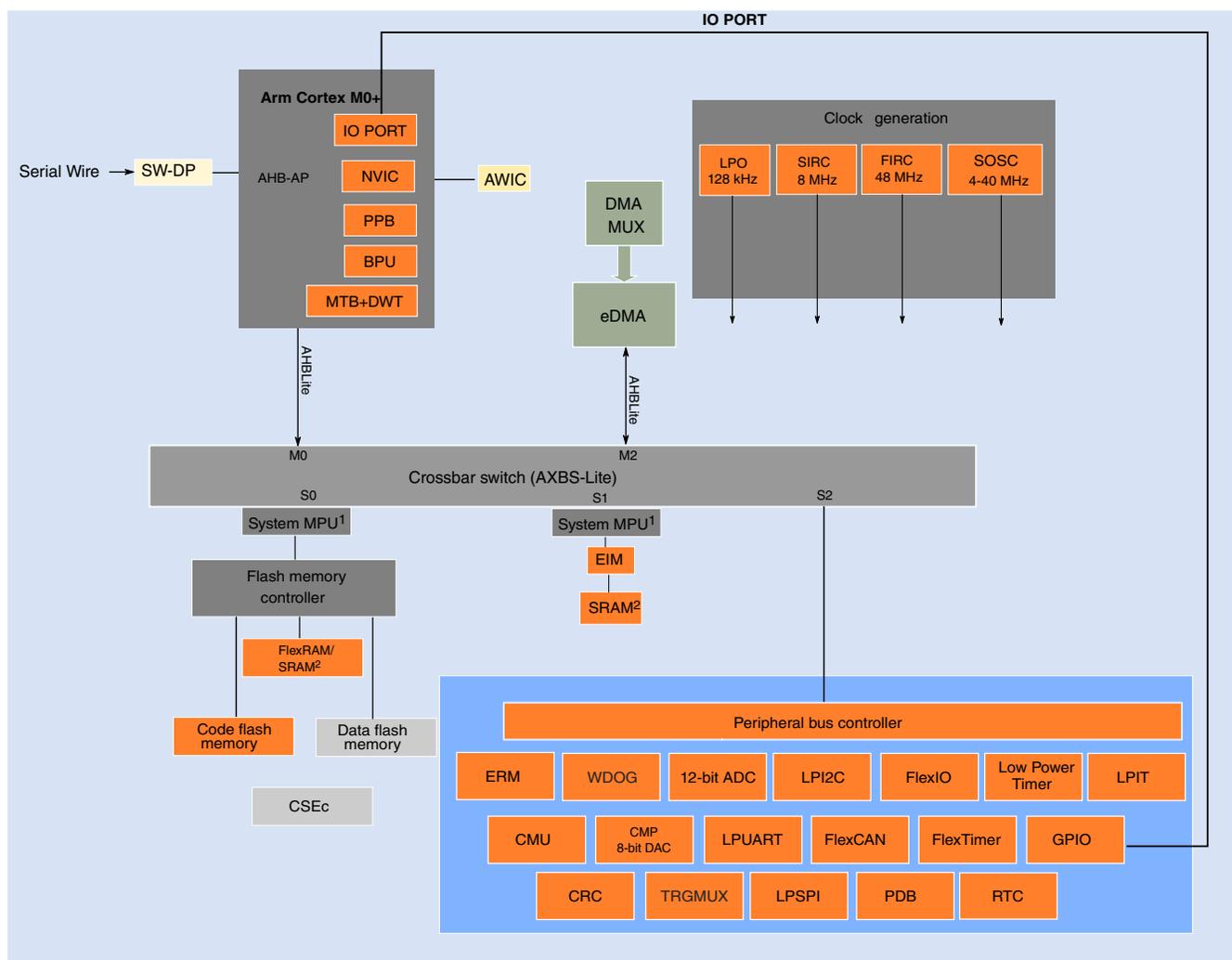
### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4F
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	CANbus, FlexIO, I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	58
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x12b SAR; D/A1x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/fs32k142hat0mlht">https://www.e-xfl.com/product-detail/nxp-semiconductors/fs32k142hat0mlht</a>

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1: On this device, NXP's system MPU implements the safety mechanisms to prevent masters from accessing restricted memory regions. This system MPU provides memory protection at the level of the Crossbar Switch. Crossbar master (Core, DMA) can be assigned different access rights to each protected memory region. The Arm M0+ core version in this family does not integrate the Arm Core MPU, which would concurrently monitor only core-initiated memory accesses. In this document, the term MPU refers to NXP's system MPU.

2: For the device-specific sizes, see the "On-chip SRAM sizes" table in the "Memories and Memory Interfaces" chapter of the S32K1xx Series Reference Manual.

Device architectural IP on all S32K devices
Peripherals present on all S32K devices
Peripherals present on selected S32K devices (see the "Feature Comparison" section)

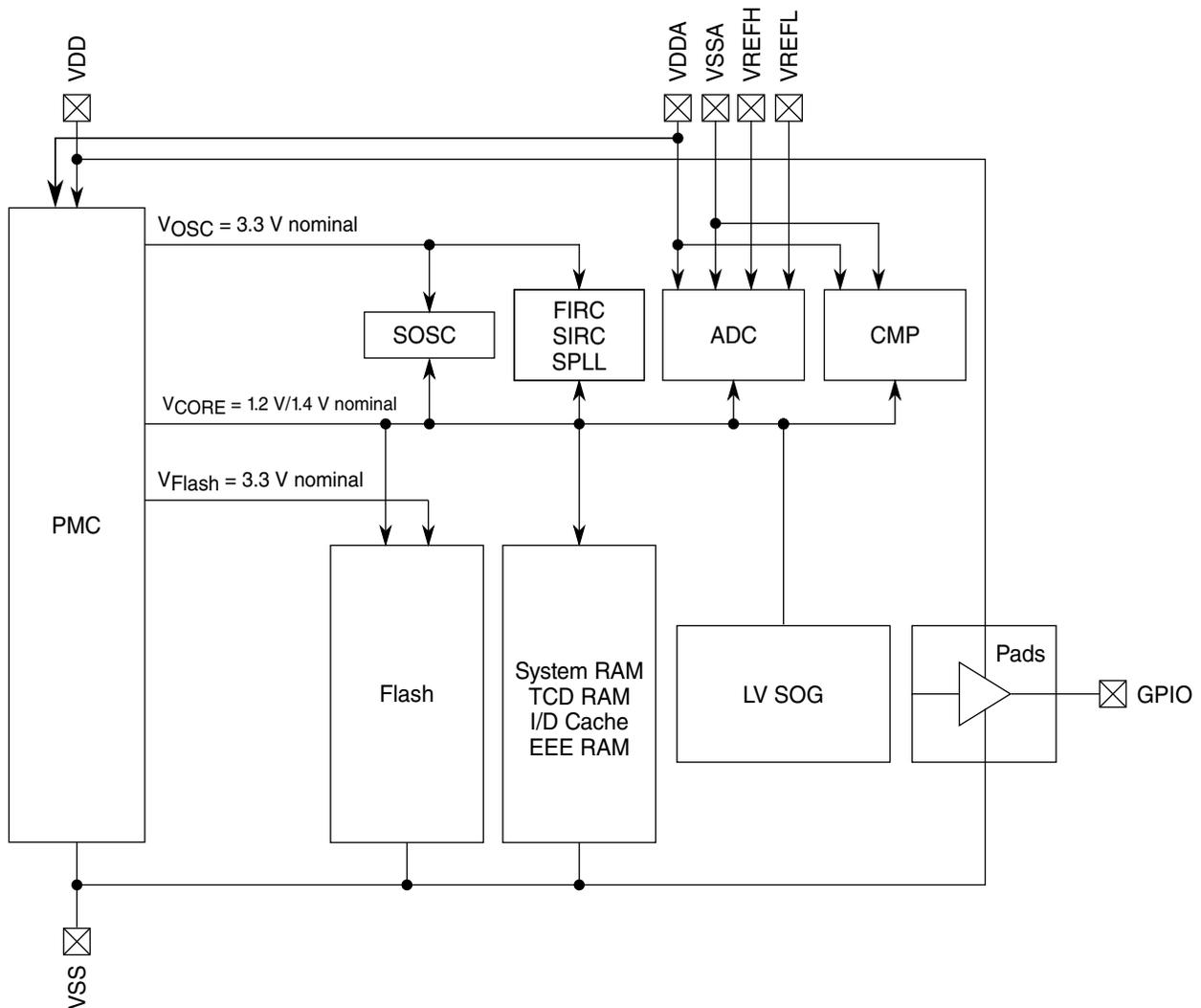
Figure 2. High-level architecture diagram for the S32K11x family

## 2 Feature comparison

The following figure summarizes the memory, peripherals and packaging options for the S32K1xx devices. All devices which share a common package are pin-to-pin compatible.

### NOTE

Availability of peripherals depends on the pin availability in a particular package. For more information see *IO Signal*



\*Note: VSSA and VSS are shorted at package level

Figure 6. Power diagram

## 4.5 LVR, LVD and POR operating requirements

Table 5. V<sub>DD</sub> supply LVR, LVD and POR operating requirements

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V <sub>POR</sub>	Rising and falling V <sub>DD</sub> POR detect voltage	1.1	1.6	2.0	V	
V <sub>LVR</sub>	LVR falling threshold (RUN, HSRUN, and STOP modes)	2.50	2.58	2.7	V	
V <sub>LVR_HYST</sub>	LVR hysteresis	—	45	—	mV	1
V <sub>LVR_LP</sub>	LVR falling threshold (VLPS/VLPR modes)	1.97	2.22	2.44	V	
V <sub>LVD</sub>	Falling low-voltage detect threshold	2.8	2.875	3	V	
V <sub>LVD_HYST</sub>	LVD hysteresis	—	50	—	mV	1

Table continues on the next page...

Table 7. Power consumption (Typicals unless stated otherwise) 1

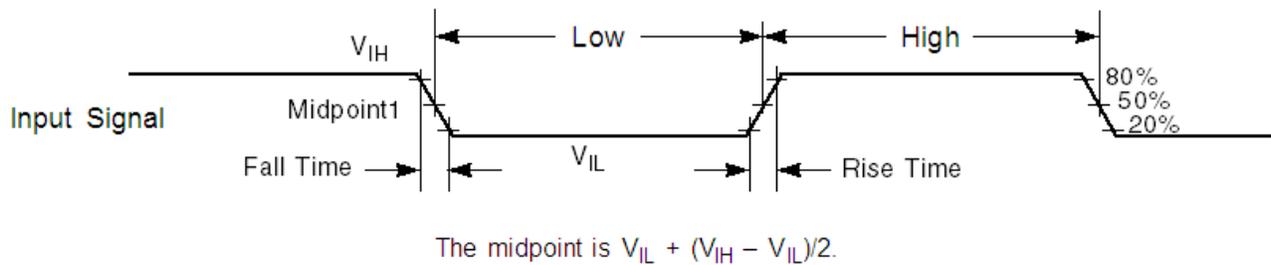
Chip/Device	Ambient Temperature (°C)		VLPS ( $\mu$ A) <sup>2</sup>		VLPR (mA)			STOP1 (mA)	STOP2 (mA)	RUN@48 MHz (mA)		RUN@64 MHz (mA)		RUN@80 MHz (mA)		HSRUN@112 MHz (mA) <sup>3</sup>		IDD/MHz ( $\mu$ A/MHz) <sup>4</sup>	
			Peripherals disabled <sup>5</sup>	Peripherals enabled	Peripherals disabled <sup>6</sup>	Peripherals enabled use case 1 <sup>6</sup>	Peripherals enabled use case 2 <sup>7</sup>			Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled		
S32K116	25	Typ	26	40	1.05	1.07	TBD	6.3	7.2	11.8	20.3	NA						245	
	85	Typ	76	93	1.1	1.11	TBD	6.6	7.5	12	20.6	NA						251	
		Max	287	300	1.39	1.4	NA	8	8.9	13.4	22.1	NA						279	
	105	Typ	139	164	1.15	1.16	TBD	6.8	7.7	12.3	20.8	NA						255	
		Max	590	603	1.68	1.69	NA	9.2	10.1	14.5	23.1	NA						302	
	125	Typ	NA	NA	NA	NA	TBD	NA	NA	NA	NA	NA						NA	
Max		891	904	2.02	2.04	NA	10.4	11.3	15.6	24.1	NA						325		
S32K118	25	Typ	26	38	1.9	2.5	TBD	7	12	TBD	TBD	NA						TBD	
	105	Typ	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	NA						TBD
		Max	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	NA						TBD
	125	Max	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	42	NA						TBD	
S32K142	25	Typ	29	40	1.17	1.21	2.19	6.4	7.4	17.3	24.6	24.5	31.3	28.8	37.5	40.5	52.2	360	
	85	Typ	128	137	1.48	1.51	2.31	7	8	17.6	24.9	25	31.6	29.1	37.7	41.1	52.5	364	
		Max	335	360	1.87	1.89	NA	8.6	9.4	22	28.2	26.9	33.5	32	40	44	55.6	400	
	105	Typ	240	257	1.58	1.61	2.44	7.6	8.3	18.3	25.7	25.5	31.9	29.8	38	41.5	53.1	373	
		Max	740	791	2.32	2.34	NA	9.9	10.9	23.1	30.2	27.8	35.3	33.8	40.7	44.9	57.4	423	
125	Typ	NA	NA	NA	NA	2.84	NA	NA	NA	NA	NA	NA	NA	NA	NA	NA	NA		

Table continues on the next page...

## 5 I/O parameters

### 5.1 AC electrical characteristics

Unless otherwise specified, propagation delays are measured from the 50% to the 50% point, and rise and fall times are measured at the 20% and 80% points, as shown in the following figure.



**Figure 7. Input signal measurement reference**

### 5.2 General AC specifications

These general purpose specifications apply to all signals configured for GPIO, UART, and timers.

**Table 10. General switching specifications**

Symbol	Description	Min.	Max.	Unit	Notes
	GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path	1.5	—	Bus clock cycles	1, 2
	GPIO pin interrupt pulse width (digital glitch filter disabled, passive filter disabled) — Asynchronous path	50	—	ns	3
WFRST	$\overline{\text{RESET}}$ input filtered pulse	—	10	ns	4
WNFRST	$\overline{\text{RESET}}$ input not filtered pulse	Maximum of (100 ns, bus clock period)	—	ns	5

1. This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In Stop and VLPS modes, the synchronizer is bypassed so shorter pulses can be recognized in that case.
2. The greater of synchronous and asynchronous timing must be met.
3. These pins do not have a passive filter on the inputs. This is the shortest pulse width that is guaranteed to be recognized.
4. Maximum length of  $\overline{\text{RESET}}$  pulse which will be filtered by internal filter.
5. Minimum length of  $\overline{\text{RESET}}$  pulse, guaranteed not to be filtered by the internal filter. This number depends on bus clock period also. For example, in VLPR mode bus clock is 4 MHz, which make clock period of 250 ns. In this case, minimum pulse width which will cause reset is 250 ns. For faster bus clock frequencies which have clock period less than 100 ns, the minimum pulse width not filtered will be 100 ns.

## 5.3 DC electrical specifications at 3.3 V Range

### NOTE

For details on the pad types defined in [Table 11](#) and [Table 12](#), see Reference Manual section *IO Signal Table* and IO Signal Description Input Multiplexing sheet(s) attached with Reference Manual.

**Table 11. DC electrical specifications at 3.3 V Range**

Symbol	Parameter	Value			Unit	Notes
		Min.	Typ.	Max.		
$V_{DD}$	I/O Supply Voltage	2.7	3.3	4	V	1
$V_{ih}$	Input Buffer High Voltage	$0.7 \times V_{DD}$	—	$V_{DD} + 0.3$	V	2
$V_{il}$	Input Buffer Low Voltage	$V_{SS} - 0.3$	—	$0.3 \times V_{DD}$	V	3
$V_{hys}$	Input Buffer Hysteresis	$0.06 \times V_{DD}$	—	—	V	
$I_{oh_{GPIO}}$ $I_{oh_{GPIO-HD\_DSE\_0}}$	I/O current source capability measured when pad $V_{oh} = (V_{DD} - 0.8 V)$	3.5	—	—	mA	
$I_{ol_{GPIO}}$ $I_{ol_{GPIO-HD\_DSE\_0}}$	I/O current sink capability measured when pad $V_{ol} = 0.8 V$	3	—	—	mA	
$I_{oh_{GPIO-HD\_DSE\_1}}$	I/O current source capability measured when pad $V_{oh} = (V_{DD} - 0.8 V)$	14	—	—	mA	4
$I_{ol_{GPIO-HD\_DSE\_1}}$	I/O current sink capability measured when pad $V_{ol} = 0.8 V$	12	—	—	mA	4
$I_{oh_{GPIO-FAST\_DSE\_0}}$	I/O current sink capability measured when pad $V_{oh} = V_{DD} - 0.8 V$	9.5	—	—	mA	5
$I_{ol_{GPIO-FAST\_DSE\_0}}$	I/O current sink capability measured when pad $V_{ol} = 0.8 V$	10	—	—	mA	5
$I_{oh_{GPIO-FAST\_DSE\_1}}$	I/O current sink capability measured when pad $V_{oh} = V_{DD} - 0.8 V$	16	—	—	mA	5
$I_{ol_{GPIO-FAST\_DSE\_1}}$	I/O current sink capability measured when pad $V_{ol} = 0.8 V$	15.5	—	—	mA	5
IOHT	Output high current total for all ports	—	—	100	mA	
IIN	Input leakage current (per pin) for full temperature range at $V_{DD} = 3.3 V$					6
	All pins other than high drive port pins		0.005	0.5	$\mu A$	
	High drive port pins <sup>7</sup>		0.010	0.5	$\mu A$	
$R_{PU}$	Internal pullup resistors	20		60	k $\Omega$	8
$R_{PD}$	Internal pulldown resistors	20		60	k $\Omega$	9

1. S32K148 will operate from 2.7 V when executing from internal FIRC. When the PLL is engaged S32K148 is guaranteed to operate from 2.97 V. All other S32K family devices operate from 2.7 V in all modes.
2. For reset pads, same  $V_{ih}$  levels are applicable
3. For reset pads, same  $V_{il}$  levels are applicable
4. The value given is measured at high drive strength mode. For value at low drive strength mode see the  $I_{oh\_Standard}$  value given above.
5. For reference only. Run simulations with the IBIS model and custom board for accurate results.

5. Several I/O have both high drive and normal drive capability selected by the associated Portx\_PCRn[DSE] control bit. All other GPIOs are normal drive only. For details refer to *SK3K144\_IO\_Signal\_Description\_Input\_Multiplexing.xlsx* attached with the *Reference Manual*.
6. Measured at input  $V = V_{SS}$
7. Measured at input  $V = V_{DD}$

## 5.5 AC electrical specifications at 3.3 V range

**Table 13. AC electrical specifications at 3.3 V Range**

Symbol	DSE	Rise time (nS) <sup>1</sup>		Fall time (nS) <sup>1</sup>		Capacitance (pF) <sup>2</sup>
		Min.	Max.	Min.	Max.	
tRF <sub>GPIO</sub>	NA	3.2	14.5	3.4	15.7	25
		5.7	23.7	6.0	26.2	50
		20.0	80.0	20.8	88.4	200
tRF <sub>GPIO-HD</sub>	0	3.2	14.5	3.4	15.7	25
		5.7	23.7	6.0	26.2	50
		20.0	80.0	20.8	88.4	200
	1	1.5	5.8	1.7	6.1	25
		2.4	8.0	2.6	8.3	50
		6.3	22.0	6.0	23.8	200
tRF <sub>GPIO-FAST</sub>	0	0.6	2.8	0.5	2.8	25
		3.0	7.1	2.6	7.5	50
		12.0	27.0	10.3	26.8	200
	1	0.4	1.3	0.38	1.3	25
		1.5	3.8	1.4	3.9	50
		7.4	14.9	7.0	15.3	200

1. For reference only. Run simulations with the IBIS model and your custom board for accurate results.
2. Maximum capacitances supported on Standard IOs. However interface or protocol specific specifications might be different, for example for ENET, QSPI etc. . For protocol specific AC specifications, see respective sections.

## 5.6 AC electrical specifications at 5 V range

**Table 14. AC electrical specifications at 5 V Range**

Symbol	DSE	Rise time (nS) <sup>1</sup>		Fall time (nS) <sup>1</sup>		Capacitance (pF) <sup>2</sup>
		Min.	Max .	Min.	Max.	
tRF <sub>GPIO</sub>	NA	2.8	9.4	2.9	10.7	25
		5.0	15.7	5.1	17.4	50
		17.3	54.8	17.6	59.7	200
tRF <sub>GPIO-HD</sub>	0	2.8	9.4	2.9	10.7	25
		5.0	15.7	5.1	17.4	50

*Table continues on the next page...*

**Table 18. External System Oscillator frequency specifications**

Symbol	Description	Min.		Typ.		Max.		Unit	Notes
		S32K14x	S32K11x	S32K14x	S32K11x	S32K14x	S32K11x		
$f_{osc\_hi}$	Oscillator crystal or resonator frequency	4		—		40		MHz	
$f_{ec\_extal}$	Input clock frequency (external clock mode)	—		—		50	48	MHz	1
$t_{dc\_extal}$	Input clock duty cycle (external clock mode)	48		50		52		%	1
$t_{cst}$	Crystal Start-up Time							ms	2
	8 MHz low-gain mode (HGO=0)	—		1.5		—			
	8 MHz high-gain mode (HGO=1)	—		2.5		—			
	40 MHz low-gain mode (HGO=0)	—		2		—			
	40 MHz high-gain mode (HGO=1)	—		2		—			

1. Frequencies below 40 MHz can be used for degraded duty cycle upto 40-60%
2. Proper PC board layout procedures must be followed to achieve specifications.

**Table 23. Flash command timing specifications for S32K14x (continued)**

Symbol	Description <sup>1</sup>		S32K142		S32K144		S32K146		S32K148		Unit	Notes
			Typ	Max	Typ	Max	Typ	Max	Typ	Max		
	setting (32-bit write complete, ready for next 32-bit write)	Last (Nth) 32-bit write (time for write only, not cleanup)	200	550	200	550	200	550	200	550		
$t_{\text{quickwrClnup}}$	Quick Write Cleanup execution time	—	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	ms	7

1. All command times assumes 25 MHz or greater flash clock frequency (for synchronization time between internal/external clocks).
2. Maximum times for erase parameters based on expectations at cycling end-of-life.
3. For all EEPROM Emulation terms, the specified timing shown assumes previous record cleanup has occurred. This may be verified by executing FCCOB Command 0x77, and checking FCCOB number 5 contents show 0x00 - No EEPROM issues detected.
4. 1st time EERAM writes after a Reset or SETRAM may incur additional overhead for EEE cleanup, resulting in up to 2x the times shown.
5. Only after the Nth write completes will any data be valid. Emulated EEPROM record scheme cleanup overhead may occur after this point even after a brownout or reset. If power on reset occurs before the Nth write completes, the last valid record set will still be valid and the new records will be discarded.
6. Quick Write times may take up to 550  $\mu\text{s}$ , as additional cleanup may occur when crossing sector boundaries.
7. Time for emulated EEPROM record scheme overhead cleanup. Automatically done after last (Nth) write completes, assuming still powered. Or via SETRAM cleanup execution command is requested at a later point.

**Table 24. Flash command timing specifications for S32K11x**

Symbol	Description <sup>1</sup>		S32K116		S32K118		Unit	Notes
			Typ	Max	Typ	Max		
$t_{\text{rd1blk}}$	Read 1 Block execution time	32 KB flash	—	0.36	—	0.36	ms	
		64 KB flash	—	—	—	—		
		128 KB flash	—	1.2	—	—		
		256 KB flash	—	—	—	2		
		512 KB flash	—	—	—	—		
$t_{\text{rd1sec}}$	Read 1 Section execution time	2 KB flash	—	75	—	75	$\mu\text{s}$	
		4 KB flash	—	100	—	100		
$t_{\text{pgmchk}}$	Program Check execution time	—	—	100	—	100	$\mu\text{s}$	
$t_{\text{pgm8}}$	Program Phrase execution time	—	90	225	90	225	$\mu\text{s}$	
$t_{\text{ersblk}}$	Erase Flash Block execution time	32 KB flash	15	300	15	300	ms	2
		64 KB flash	—	—	—	—		
		128 KB flash	120	1100	—	—		
		256 KB flash	—	—	250	2125		
		512 KB flash	—	—	—	—		

Table continues on the next page...

**Table 24. Flash command timing specifications for S32K11x (continued)**

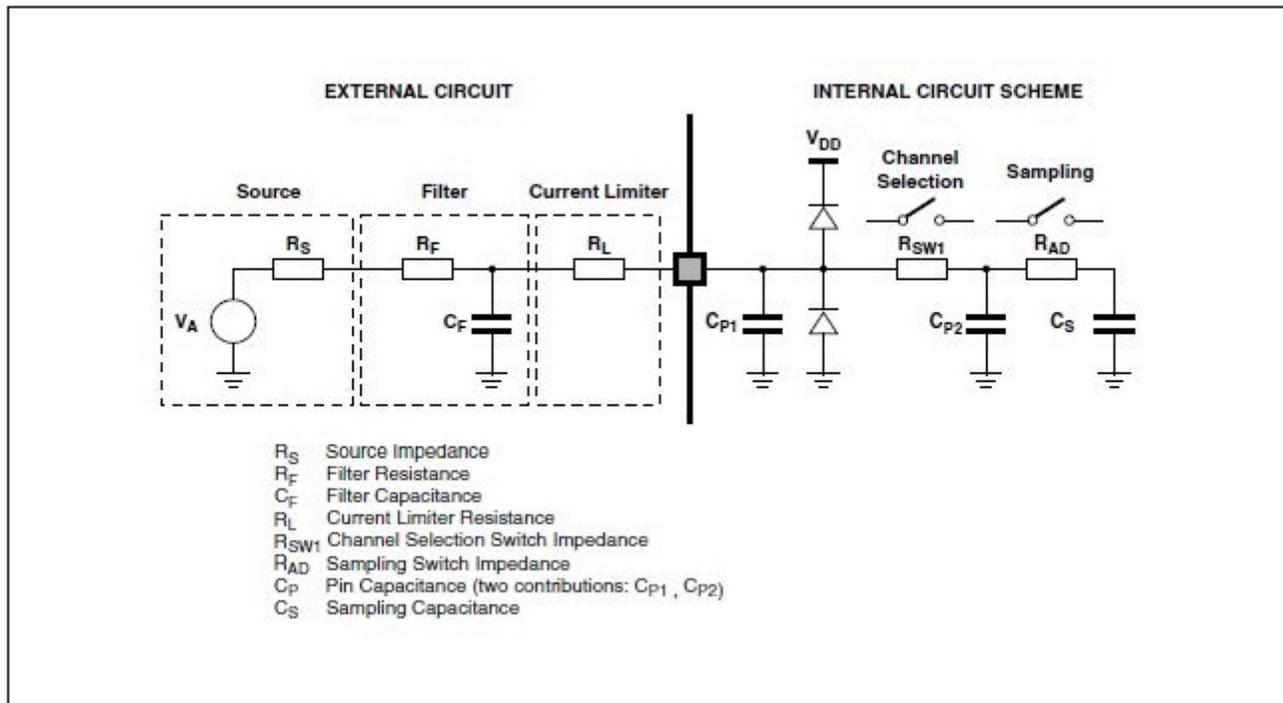
Symbol	Description <sup>1</sup>		S32K116		S32K118		Unit	Notes
			Typ	Max	Typ	Max		
t <sub>ersscr</sub>	Erase Flash Sector execution time	—	12	130	12	130	ms	2
t <sub>pgmsec1k</sub>	Program Section execution time (1 KB flash)	—	5	—	5	—	ms	
t <sub>rd1all</sub>	Read 1s All Block execution time	—	—	1.7	—	2.8	ms	
t <sub>rdonce</sub>	Read Once execution time	—	—	30	—	30	μs	
t <sub>pgmonce</sub>	Program Once execution time	—	90	—	90	—	μs	
t <sub>ersall</sub>	Erase All Blocks execution time	—	150	1500	230	2500	ms	2
t <sub>vfykey</sub>	Verify Backdoor Access Key execution time	—	—	35	—	35	μs	
t <sub>ersallu</sub>	Erase All Blocks Unsecure execution time	—	150	1500	230	2500	ms	2
t <sub>pgmpart</sub>	Program Partition for EEPROM execution time	32 KB EEPROM backup	71	—	71	—	ms	3
		64 KB EEPROM backup	—	—	—	—		
t <sub>setram</sub>	Set FlexRAM Function execution time	Control Code 0xFF	0.08	—	0.08	—	ms	3
		32 KB EEPROM backup	0.8	1.2	0.8	1.2		
		48 KB EEPROM backup	—	—	—	—		
		64 KB EEPROM backup	—	—	—	—		
t <sub>eewr8b</sub>	Byte write to FlexRAM execution time	32 KB EEPROM backup	385	1700	385	1700	μs	3-4
		48 KB EEPROM backup	—	—	—	—		
		64 KB EEPROM backup	—	—	—	—		
t <sub>eewr16b</sub>	16-bit write to FlexRAM execution time	32 KB EEPROM backup	385	1700	385	1700	μs	3-4
		48 KB EEPROM backup	—	—	—	—		
		64 KB EEPROM backup	—	—	—	—		
t <sub>eewr32bers</sub>	32-bit write to erased FlexRAM location execution time	—	360	2000	360	2000	μs	

Table continues on the next page...

**Table 27. 12-bit ADC operating conditions (continued)**

Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
f <sub>ADCK</sub>	ADC conversion clock frequency	Normal usage	2	40	50	MHz	3, 4
f <sub>CONV</sub>	ADC conversion frequency	No ADC hardware averaging. <sup>5</sup> Continuous conversions enabled, subsequent conversion time	46.4	928	1160	Ksps	6, 7
		ADC hardware averaging set to 32. <sup>5</sup> Continuous conversions enabled, subsequent conversion time	1.45	29	36.25	Ksps	6, 7

1. Typical values assume V<sub>DDA</sub> = 5 V, Temp = 25 °C, f<sub>ADCK</sub> = 40 MHz, R<sub>AS</sub>=20 Ω, and C<sub>AS</sub>=10 nF unless otherwise stated. Typical values are for reference only, and are not tested in production.
2. For packages without dedicated V<sub>REFH</sub> and V<sub>REFL</sub> pins, V<sub>REFH</sub> is internally tied to V<sub>DDA</sub>, and V<sub>REFL</sub> is internally tied to V<sub>SS</sub>. To get maximum performance, reference supply quality should be better than SAR ADC. See application note AN5032 for details.
3. Clock and compare cycle need to be set according to the guidelines mentioned in the *Reference Manual*.
4. ADC conversion will become less reliable above maximum frequency.
5. When using ADC hardware averaging, see the *Reference Manual* to determine the most appropriate setting for AVGS.
6. Numbers based on the minimum sampling time of 275 ns.
7. For guidelines and examples of conversion rate calculation, see the *Reference Manual* section 'Calibration function'



**Figure 13. ADC input impedance equivalency diagram**

### 6.4.1.2 12-bit ADC electrical characteristics

#### NOTE

- ADC performance specifications are documented using a single ADC. For parallel/simultaneous operation of both ADCs, either for sampling the same channel by both ADCs or for sampling different channels by each ADC, some amount of decrease in performance can be expected. Care must be taken to stagger the two ADC conversions, in particular the sample phase, to minimize the impact of simultaneous conversions.
- On reduced pin packages where ADC reference pins are shared with supply pins, ADC analog performance characteristics may be impacted. The amount of variation will be directly impacted by the external PCB layout and hence care must be taken with PCB routing. See [AN5426](#) for details

**Table 28. 12-bit ADC characteristics (2.7 V to 3 V) ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SS}$ )**

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
$V_{DDA}$	Supply voltage		2.7	—	3	V	
$I_{DDA\_ADC}$	Supply current per ADC		—	0.6	—	mA	3
SMPLTS	Sample Time		275	—	Refer to the <i>Reference Manual</i>	ns	
TUE <sup>4</sup>	Total unadjusted error		—	±4	±8	LSB <sup>5</sup>	6, 7, 8, 9
DNL	Differential non-linearity		—	±1.0	—	LSB <sup>5</sup>	6, 7, 8, 9
INL	Integral non-linearity		—	±2.0	—	LSB <sup>5</sup>	6, 7, 8, 9

1. All accuracy numbers assume the ADC is calibrated with  $V_{REFH}=V_{DDA}=V_{DD}$ , with the calibration frequency set to less than or equal to half of the maximum specified ADC clock frequency.
2. Typical values assume  $V_{DDA} = 3\text{ V}$ ,  $\text{Temp} = 25\text{ }^\circ\text{C}$ ,  $f_{ADCK} = 40\text{ MHz}$ ,  $R_{AS}=20\text{ }\Omega$ , and  $C_{AS}=10\text{ nF}$ .
3. The ADC supply current depends on the ADC conversion rate.
4. Represents total static error, which includes offset and full scale error.
5.  $1\text{ LSB} = (V_{REFH} - V_{REFL})/2^N$
6. The specifications are with averaging and in standalone mode only. Performance may degrade depending upon device use case scenario. When using ADC averaging, refer to the *Reference Manual* to determine the most appropriate settings for AVGS.
7. For ADC signals adjacent to  $V_{DD}/V_{SS}$  or XTAL/EXTAL or high frequency switching pins, some degradation in the ADC performance may be observed.
8. All values guarantee the performance of the ADC for multiple ADC input channel pins. When using ADC to monitor the internal analog parameters, assume minor degradation.
9. All the parameters in the table are given assuming system clock as the clocking source for ADC.

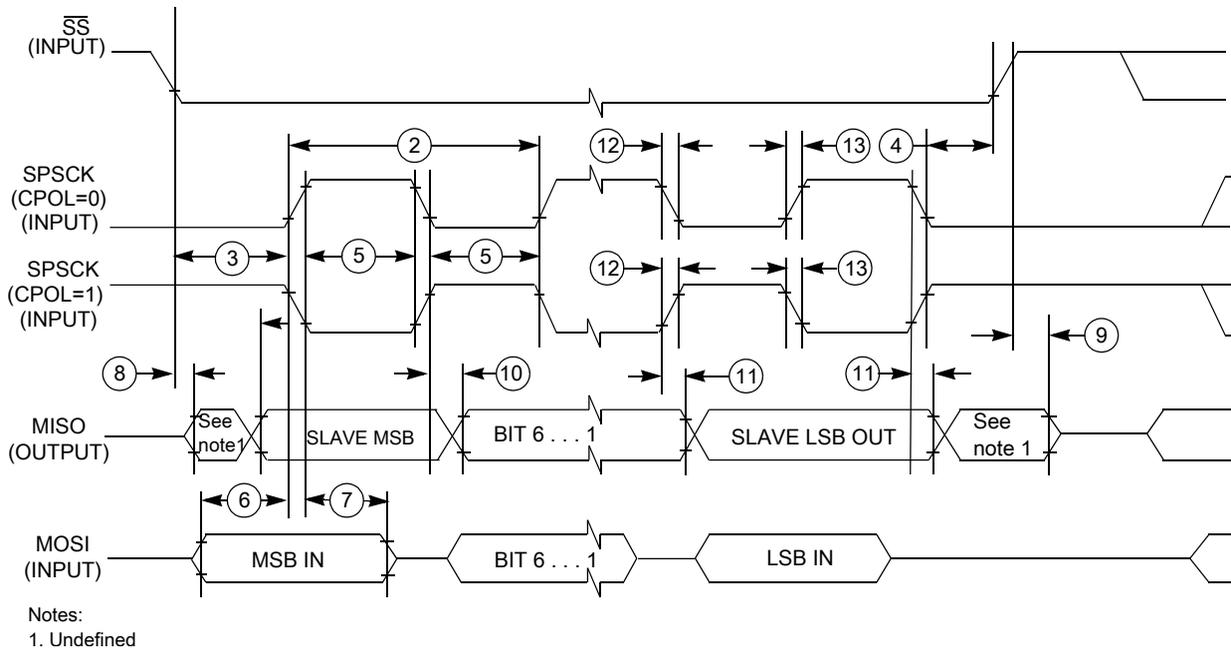


Figure 20. LPSPI slave mode timing (CPHA = 0)

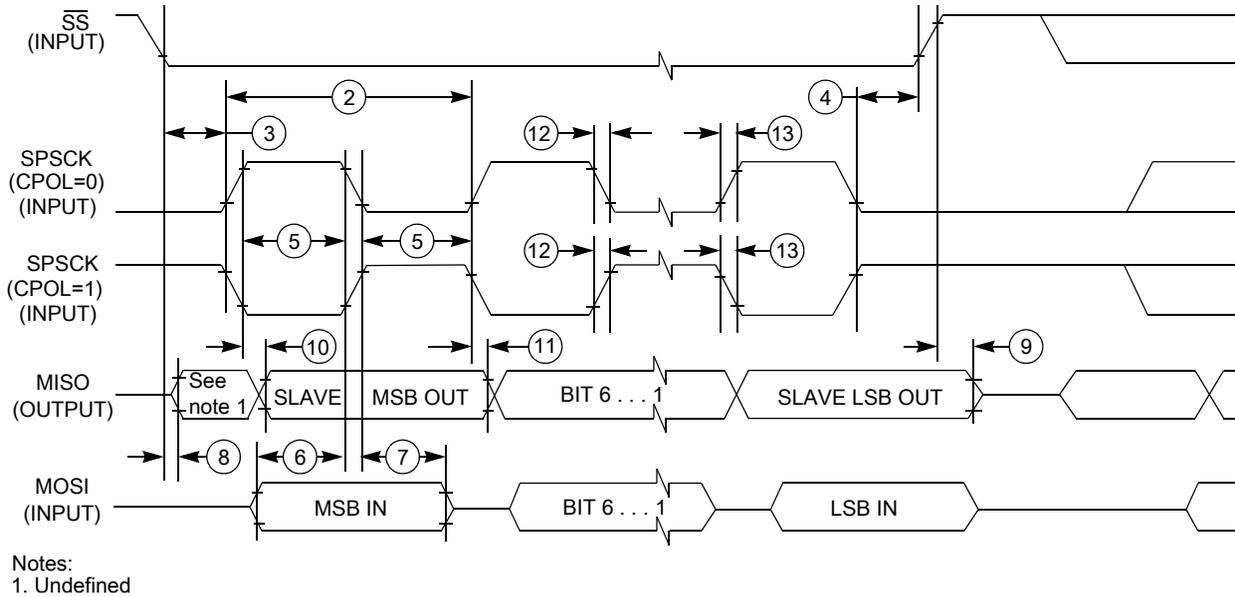


Figure 21. LPSPI slave mode timing (CPHA = 1)

### 6.5.3 LPI2C electrical specifications

See [General AC specifications](#) for LPI2C specifications.

For supported baud rate see section 'Chip-specific LPI2C information' of the *Reference Manual*.

## 6.5.4 FlexCAN electrical specifications

For supported baud rate, see section 'Protocol timing' of the *Reference Manual*.

## 6.5.5 SAI electrical specifications

The following table describes the SAI electrical characteristics.

- Measurements are with maximum output load of 50 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN ), the interface should be OFF.

**Table 33. Master mode timing specifications**

Symbol	Description	Min.	Max.	Unit
—	Operating voltage	2.97	3.6	V
S1	SAI_MCLK cycle time	40	—	ns
S2	SAI_MCLK pulse width high/low	45%	55%	MCLK period
S3	SAI_BCLK cycle time	80	—	ns
S4	SAI_BCLK pulse width high/low	45%	55%	BCLK period
S5	SAI_RXD input setup before SAI_BCLK	28	—	ns
S6	SAI_RXD input hold after SAI_BCLK	0	—	ns
S7	SAI_BCLK to SAI_TXD output valid	—	8	ns
S8	SAI_BCLK to SAI_TXD output invalid	-2	—	ns
S9	SAI_FS input setup before SAI_BCLK	28	—	ns
S10	SAI_FS input hold after SAI_BCLK	0	—	ns
S11	SAI_BCLK to SAI_FS output valid	—	8	ns
S12	SAI_BCLK to SAI_FS output invalid	-2	—	ns

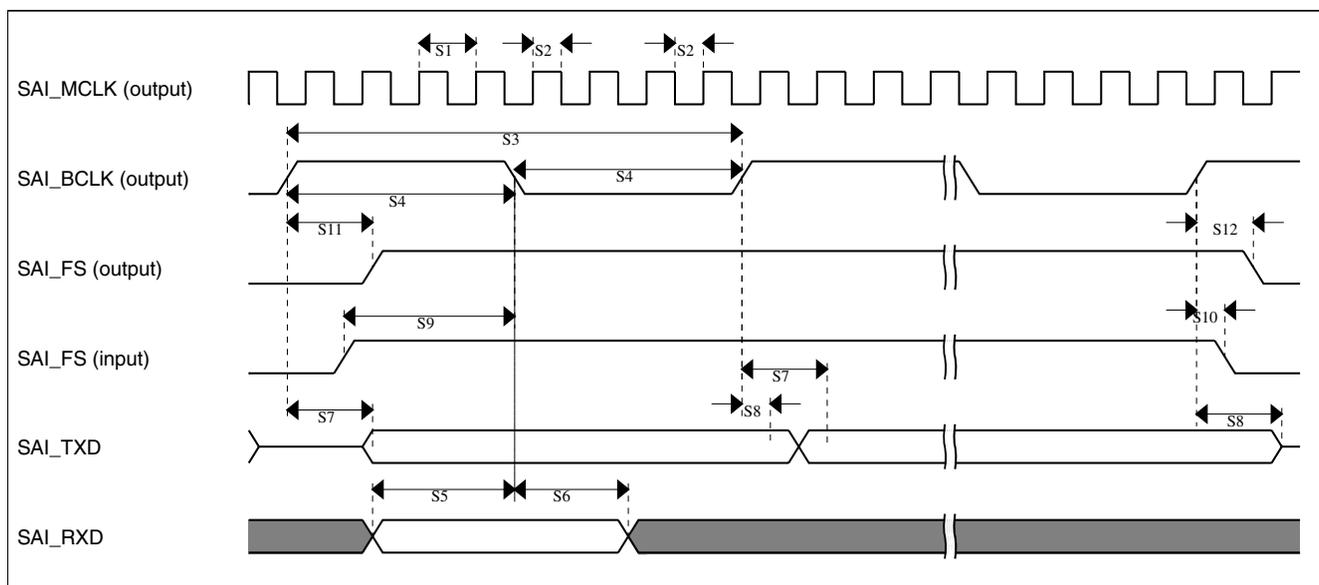


Figure 22. SAI Timing — Master modes

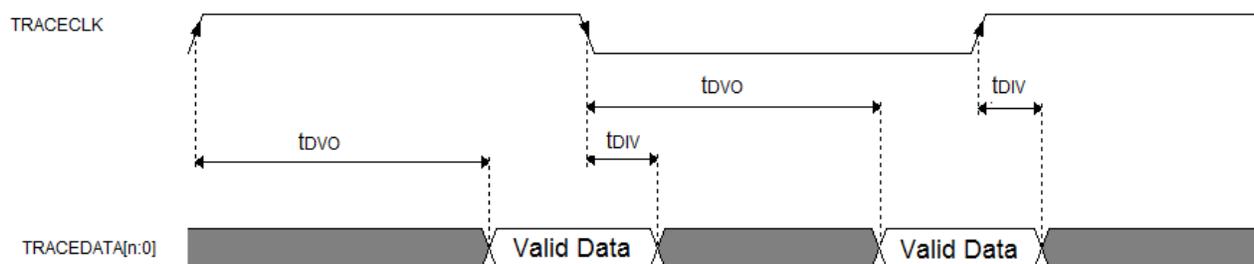
Table 34. Slave mode timing specifications

Symbol	Description	Min.	Max.	Unit
—	Operating voltage	2.97	3.6	V
S13	SAI_BCLK cycle time (input)	80	—	ns
S14 <sup>1</sup>	SAI_BCLK pulse width high/low (input)	45%	55%	BCLK period
S15	SAI_RXD input setup before SAI_BCLK	8	—	ns
S16	SAI_RXD input hold after SAI_BCLK	2	—	ns
S17	SAI_BCLK to SAI_TXD output valid	—	28	ns
S18	SAI_BCLK to SAI_TXD output invalid	0	—	ns
S19	SAI_FS input setup before SAI_BCLK	8	—	ns
S20	SAI_FS input hold after SAI_BCLK	2	—	ns
S21	SAI_BCLK to SAI_FS output valid	—	28	ns
S22	SAI_BCLK to SAI_FS output invalid	0	—	ns

1. The slave mode parameters (S15 - S22) assume 50% duty cycle on SAI\_BCLK input. Any change in SAI\_BCLK duty cycle input must be taken care during the board design or by the master timing.

**Table 39. Trace specifications (continued)**

	Symbol	Description	RUN Mode			HSRUN Mode		VLPR Mode	Unit
Trace on fast pads	$f_{TRACE}$	Max Trace frequency	80	48	40	74.667	80	4	MHz
	$t_{DVO}$	Data Output Valid	4	4	4	4	4	20	ns
	$t_{DIV}$	Data Output Invalid	-2	-2	-2	-2	-2	-10	ns
Trace on slow pads	$f_{TRACE}$	Max Trace frequency	22.86	24	20	22.4	22.86	4	MHz
	$t_{DVO}$	Data Output Valid	8	8	8	8	8	20	ns
	$t_{DIV}$	Data Output Invalid	-4	-4	-4	-4	-4	-10	ns



**Figure 31. TRACE CLKOUT specifications**

### 6.6.3 JTAG electrical specifications

**Table 42. Thermal characteristics for the 100 MAPBGA package**

Rating	Conditions	Symbol	Values			Unit
			S32K146	S32K144	S32K148	
Thermal resistance, Junction to Ambient (Natural Convection) <sup>1, 2</sup>	Single layer board (1s)	$R_{\theta JA}$	57.2	61.0	52.5	°C/W
Thermal resistance, Junction to Ambient (Natural Convection) <sup>1, 2, 3</sup>	Four layer board (2s2p)	$R_{\theta JA}$	32.1	35.6	27.5	°C/W
Thermal resistance, Junction to Ambient (@200 ft/min) <sup>1, 2, 3</sup>	Single layer board (1s)	$R_{\theta JMA}$	44.1	46.6	39.0	°C/W
Thermal resistance, Junction to Ambient (@200 ft/min) <sup>1, 3</sup>	Two layer board (2s2p)	$R_{\theta JMA}$	27.2	30.9	22.8	°C/W
Thermal resistance, Junction to Board <sup>4</sup>	—	$R_{\theta JB}$	15.3	18.9	11.2	°C/W
Thermal resistance, Junction to Case <sup>5</sup>	—	$R_{\theta JC}$	10.2	14.2	7.5	°C/W
Thermal resistance, Junction to Package Top outside center <sup>6</sup>	—	$\Psi_{JT}$	0.2	0.4	0.2	°C/W
Thermal resistance, Junction to Package Bottom outside center <sup>7</sup>	—	$\Psi_{JB}$	12.2	15.9	18.3	°C/W

1. Junction temperature is a function of die size, on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
2. Per SEMI G38-87 and JEDEC JESD51-2 with the single layer board horizontal.
3. Per JEDEC JESD51-6 with the board horizontal.
4. Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
5. Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1).
6. Thermal characterization parameter indicating the temperature difference between package top and the junction temperature per JEDEC JESD51-2. When Greek letters are not available, the thermal characterization parameter is written as Psi-JT.
7. Thermal characterization parameter indicating the temperature difference between package bottom center and the junction temperature per JEDEC JESD51-12. When Greek letters are not available, the thermal characterization parameter is written as Psi-JB.

## Dimensions

To determine the junction temperature of the device in the application when heat sinks are not used, the Thermal Characterization Parameter ( $\Psi_{JT}$ ) can be used to determine the junction temperature with a measurement of the temperature at the top center of the package case using this equation:

$$T_J = T_T + (\Psi_{JT} \times P_D)$$

where:

- $T_T$  = thermocouple temperature on top of the package ( $^{\circ}\text{C}$ )
- $\Psi_{JT}$  = thermal characterization parameter ( $^{\circ}\text{C}/\text{W}$ )
- $P_D$  = power dissipation in the package (W)

The thermal characterization parameter is measured per JESD51-2 specification using a 40 gauge type T thermocouple epoxied to the top center of the package case. The thermocouple should be positioned so that the thermocouple junction rests on the package. A small amount of epoxy is placed over the thermocouple junction and over about 1 mm of wire extending from the junction. The thermocouple wire is placed flat against the package case to avoid measurement errors caused by cooling effects of the thermocouple wire.

## 8 Dimensions

### 8.1 Obtaining package dimensions

Package dimensions are provided in the package drawings.

To find a package drawing, go to <http://www.nxp.com> and perform a keyword search for the drawing's document number:

Package option	Document Number
32-pin QFN	SOT617-3 <sup>1</sup>
48-pin LQFP	98ASH00962A
64-pin LQFP	98ASS23234W
100-pin LQFP	98ASS23308W
100-pin MAPBGA	98ASA00802D
144-pin LQFP	98ASS23177W
176-pin LQFP	98ASS23479W

1. 5x5 mm package

Table 43. Revision History (continued)

Rev. No.	Date	Substantial Changes
		<ul style="list-style-type: none"> <li>• Updated note 'All the limits defined ...'</li> <li>• Updated parameter 'I<sub>INJPAD_DC_ABS</sub>', 'V<sub>IN_DC</sub>', I<sub>INJSUM_DC_ABS</sub>.</li> <li>• In <a href="#">Table 2</a>, <ul style="list-style-type: none"> <li>• Updated parameter I<sub>INJPAD_DC_OP</sub> and I<sub>INJSUM_DC_OP</sub>.</li> </ul> </li> <li>• In <a href="#">Table 5</a>, updated TBDs for V<sub>LVR_HYST</sub>, V<sub>LVD_HYST</sub>, and V<sub>LVW_HYST</sub></li> <li>• In <a href="#">Power mode transition operating behaviors</a>, <ul style="list-style-type: none"> <li>• Added VLPR → VLPS</li> <li>• Added VLPS → VLPR</li> <li>• Updated TBDs for VLPS → Asynchronous DMA Wakeup, STOP1 → Asynchronous DMA Wakeup, and STOP2 → Asynchronous DMA Wakeup</li> </ul> </li> <li>• In <a href="#">Table 7</a>, updated the specifications for S32K144.</li> <li>• Updated the attachment <i>S32K1xx_Power_Modes_Configuration.xlsx</i>.</li> <li>• In <a href="#">Table 15</a>, removed C<sub>IN_A</sub>.</li> <li>• In <a href="#">Table 17</a>, <ul style="list-style-type: none"> <li>• Updated specificatins for g<sub>mXOSC</sub>.</li> <li>• Removed I<sub>DDOSC</sub></li> </ul> </li> <li>• In <a href="#">Table 19</a>, <ul style="list-style-type: none"> <li>• Added parameter ΔF125.</li> <li>• Removed I<sub>DDFIRC</sub></li> </ul> </li> <li>• In <a href="#">Table 20</a>, <ul style="list-style-type: none"> <li>• Added parameter ΔF125.</li> <li>• Removed I<sub>DDSIRC</sub></li> </ul> </li> <li>• In <a href="#">Table 21</a>, removed I<sub>LPO</sub></li> <li>• Updated section: <a href="#">Flash memory module (FTFC) electrical specifications</a></li> <li>• In section: <a href="#">12-bit ADC operating conditions</a>, <ul style="list-style-type: none"> <li>• Updated TBDs for I<sub>DDA_ADC</sub> and TUE in <a href="#">Table 28</a></li> <li>• Updated TBDs for I<sub>DDA_ADC</sub> and TUE in <a href="#">Table 29</a></li> </ul> </li> <li>• In section: <a href="#">QuadSPI AC specifications</a>, updated figure 'QuadSPI output timing (HyperRAM mode) diagram'.</li> <li>• In section: <a href="#">12-bit ADC operating conditions</a>, updated <a href="#">Table 27</a>.</li> <li>• In section: <a href="#">CMP with 8-bit DAC electrical specifications</a>, added note 'For comparator IN signals adjacent ...'</li> <li>• In table: <a href="#">Table 32</a>, minor update in footnote 6.</li> <li>• In table: <a href="#">Table 41</a>, updated specifications for S32K146.</li> </ul>
5	06 Dec 2017	<ul style="list-style-type: none"> <li>• Removed S32K148 from 'Caution'</li> <li>• Updated figure: <a href="#">S32K1xx product series comparison</a> for <ul style="list-style-type: none"> <li>• 'EEPROM emulated by FlexRAM' of S32K148 (Added content to footnote)</li> <li>• Added support for LIN protocol version 2.2 A</li> </ul> </li> <li>• In <a href="#">Absolute maximum ratings</a> : <ul style="list-style-type: none"> <li>• Added note 'Unless otherwise ...'</li> <li>• Added parameter 'Added note 'T<sub>ramp_MCU</sub>'</li> <li>• Updated footnote for 'T<sub>ramp</sub>'</li> </ul> </li> <li>• In <a href="#">Voltage and current operating requirements</a> : <ul style="list-style-type: none"> <li>• Added footnote 'V<sub>DD</sub> and V<sub>DDA</sub> must be shorted ...' against parameter 'V<sub>DD</sub>-V<sub>DDA</sub>'</li> <li>• Updated footnote 'V<sub>DD</sub> and V<sub>DDA</sub> must be shorted ...'</li> </ul> </li> <li>• In <a href="#">Power and ground pins</a> <ul style="list-style-type: none"> <li>• Added diagrams for 32-QFN and 48-LQFP and footnote below the diagrams.</li> <li>• Updated footnote 'V<sub>DD</sub> and V<sub>DDA</sub> must be shorted ...'</li> </ul> </li> <li>• In <a href="#">Power mode transition operating behaviors</a> :</li> </ul>

Table continues on the next page...

Table 43. Revision History (continued)

Rev. No.	Date	Substantial Changes
		<ul style="list-style-type: none"> <li>Updated 3.3 V numbers and added footnote against <math>f_{op}</math>, <math>t_{SU}</math>, and <math>t_V</math> in HSRUN Mode</li> <li>Added footnote to '<math>t_{WSPCK}</math>'</li> <li>Updated <a href="#">Thermal characteristics</a> for S32K11x</li> </ul>
6	31 Jan 2018	<ul style="list-style-type: none"> <li>Changed the representation of ARM trademark throughout.</li> <li>Removed S32K142 from 'Caution'</li> <li>In 'Key features', added the following note under 'Power management', 'Memory and memory interfaces', and 'Reliability, safety and security': <ul style="list-style-type: none"> <li>No write or erase access to ...</li> </ul> </li> <li>In <a href="#">High-level architecture diagram for the S32K14x family</a>, added the following footnote: <ul style="list-style-type: none"> <li>No write or erase access to ...</li> </ul> </li> <li>In <a href="#">High-level architecture diagram for the S32K11x family</a> : <ul style="list-style-type: none"> <li>Minor editorial update: Fixed the placement of SRAM, under 'Flash memory controller' block</li> </ul> </li> <li>Updated figure: <a href="#">S32K1xx product series comparison</a> : <ul style="list-style-type: none"> <li>Updated footnote 1, and added against 'HSRUN' in addition to 'HW security module (CSEc)' and 'EEPROM emulated by FlexRAM'.</li> <li>Updated 'System RAM (including FlexRAM and MTB)' row for S32K144, S32K146, and S32K148.</li> <li>Updated channel count for S32K116 in row '12-bit SAR ADC (1 MSPS each)'.</li> </ul> </li> <li>Updated <a href="#">Ordering information</a></li> <li>Updated <a href="#">Flash timing specifications — commands</a> for S32K148, S32K142, S32K146, S32K116, and S32K118.</li> </ul>
7	19 April 2018	<ul style="list-style-type: none"> <li>Changed Caution to Notes <ul style="list-style-type: none"> <li>Updated the wordings of Notes and removed S32K146</li> <li>Added 'Following two are the available ...'</li> </ul> </li> <li>In 'Key features' : <ul style="list-style-type: none"> <li>Editorial updates</li> <li>Updated the note under Power management, Memory and memory interfaces, and Safety and security.</li> <li>Updated FlexIO under Communications interfaces</li> <li>Added ENET and SAI under Communications interfaces</li> <li>Updated Cryptographic Services Engine (CSEc) under 'Safety and security'</li> </ul> </li> <li>In <a href="#">High-level architecture diagram for the S32K14x family</a> : <ul style="list-style-type: none"> <li>Minor editorial updates</li> <li>Updated note 3</li> </ul> </li> <li>In <a href="#">High-level architecture diagram for the S32K11x family</a> : <ul style="list-style-type: none"> <li>Minor editorial updates</li> </ul> </li> <li>In figure: <a href="#">S32K1xx product series comparison</a> : <ul style="list-style-type: none"> <li>Editorial updates</li> <li>Updated Frequency for S32K14x</li> <li>Updated footnote 4</li> <li>Added footnote 5</li> </ul> </li> <li>In <a href="#">Ordering information</a> : <ul style="list-style-type: none"> <li>Renamed section, updated the starting paragraph</li> <li>Updated the figure</li> </ul> </li> <li>In <a href="#">Voltage and current operating requirements</a>, updated the note</li> <li>In <a href="#">Power consumption</a> : <ul style="list-style-type: none"> <li>Updated specs for S32K146</li> <li>Removed section 'Modes configuration', and moved its content under the first paragraph.</li> </ul> </li> <li>In <a href="#">12-bit ADC operating conditions</a> :</li> </ul>

Table continues on the next page...