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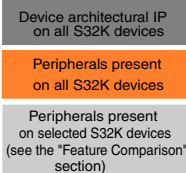
What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4F
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	CANbus, FlexIO, I ² C, LINbus, SPI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	58
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x12b SAR; D/A1x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/fs32k142hat0vlht



Description Input Multiplexing sheet(s) attached with Reference Manual.

	Parameter	S32K11x		S32K14x			
		K116	K118	K142	K144	K146	K148
System	Core	Arm® Cortex™-M0+		Arm® Cortex™-M4F			
	Frequency	48 MHz		80 MHz (RUN mode) or 112 MHz (HSRUN mode) ¹			
	IEEE-754 FPU	○		●			
	Cryptographic Services Engine (CSEc) ¹	●		●			
	CRC module	1x		1x			
	ISO 26262	capable up to ASIL-B		capable up to ASIL-B			
	Peripheral speed	up to 48 MHz		up to 112 MHz (HSRUN)			
	Crossbar	●		●			
	DMA	●		●			
	External Watchdog Monitor (EWM)	○		●			
	Memory Protection Unit (MPU)	●		●			
	FIRC CMU	●		○			
	Watchdog	1x		1x			
	Low power modes	●		●			
	HSRUN mode ¹	○		●			
	Number of I/Os	up to 43	up to 58	up to 89	up to 128	up to 156	
	Single supply voltage	2.7 - 5.5 V		2.7 - 5.5 V			
	Ambient Operation Temperature (T _A)	-40°C to +105°C / +125°C		-40°C to +105°C / +125°C			
Memory	Flash	128 KB	256 KB	256 KB	512 KB	1 MB	2 MB ²
	Error Correcting Code (ECC)	●		●			
	System RAM (including FlexRAM and MTB)	17 KB	25 KB	32 KB	64 KB	128 KB	256 KB
	FlexRAM (also available as system RAM)	2 KB		4 KB			
	Cache	○		4 KB			
	EEPROM emulated by FlexRAM ¹	2 KB (up to 32 KB D-Flash)		4 KB (up to 64 KB D-Flash)			See footnote 3
	External memory interface	○		○			QuadSPI incl. HyperBus™
Timer	Low Power Interrupt Timer (LPIT)	1x		1x			
	FlexTimer (16-bit counter) 8 channels	2x (16)		4x (32)		6x (48)	8x (64)
	Low Power Timer (LPTMR)	1x		1x			
	Real Time Counter (RTC)	1x		1x			
	Programmable Delay Block (PDB)	1x		2x			
Analog	Trigger mux (TRGMUX)	1x (43)	1x (45)	1x (64)		1x (73)	1x (81)
	12-bit SAR ADC (1 Msps each)	1x (13)	1x (16)	2x (16)		2x (24)	2x (32)
	Comparator with 8-bit DAC	1x		1x			
Communication	10/100 Mbps IEEE-1588 Ethernet MAC	○		○			1x
	Serial Audio Interface (AC97, TDM, I2S)	○		○			2x
	Low Power UART/LIN (LPUART) (Supports LIN protocol versions 1.3, 2.0, 2.1, 2.2A, and SAE J2602)	2x		2x	3x		
	Low Power SPI (LPSPPI)	1x	2x	2x	3x		
	Low Power I2C (LPI2C)	1x		1x			2x
	FlexCAN (CAN-FD ISO/CD 11898-1)	1x (1x with FD)		2x (1x with FD)	3x (1x with FD)	3x (2x with FD)	3x (3x with FD)
	FlexIO (8 pins configurable as UART, SPI, I2C, I2S)	1x		1x			
IDEs	Debug & trace	SWD, MTB (1 KB), JTAG ⁴		SWD, JTAG (ITM, SWV, SWO)			SWD, JTAG (ITM, SWV, SWO), ETM
	Ecosystem (IDE, compiler, debugger)	NXP S32 Design Studio (GCC) + SDK, IAR, GHS, Arm®, Lauterbach, iSystems		NXP S32 Design Studio (GCC) + SDK, IAR, GHS, Arm®, Lauterbach, iSystems			
Other	Packages ⁵	32-pin QFN 48-pin LQFP	48-pin LQFP 64-pin LQFP	64-pin LQFP 100-pin LQFP	64-pin LQFP 100-pin LQFP 100-pin MAPBGA	64-pin LQFP 100-pin MAPBGA 100-pin LQFP 144-pin LQFP	100-pin MAPBGA 144-pin LQFP 176-pin LQFP

LEGEND:

○ Not implemented

● Available on the device

1 No write or erase access to Flash module, including Security (CSEc) and EEPROM commands, are allowed when device is running at HSRUN mode (112MHz) or VLPR mode.

2 Available when EEPROM, CSEc and Data Flash are not used. Else only up to 1,984 KB is available for Program Flash.

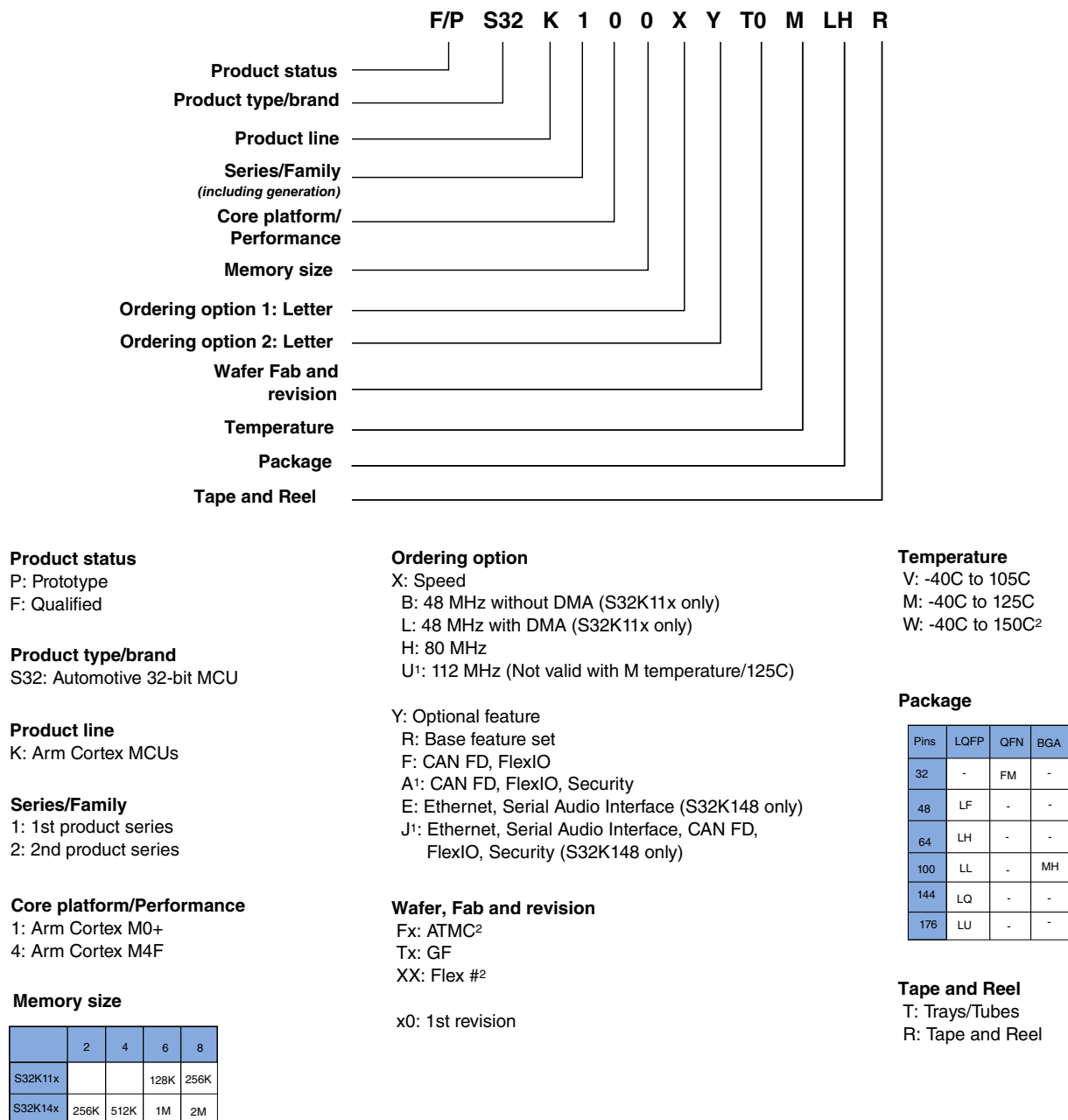
3 4 KB (up to 512 KB D-Flash as a part of 2 MB Flash). Up to 64 KB of flash is used as EEPROM backup and the remaining 448 KB of the last 512 KB block can be used as Data flash or Program flash. See chapter FTFC for details.

4 Only for Boundary Scan Register

5 See Dimensions section for package drawings

Figure 3. S32K1xx product series comparison

3.2 Ordering information



- CSEc (Security) or EEPROM writes/erase will trigger error flags in HSRUN mode (112 MHz) because this use case is not allowed to execute simultaneously. The device will need to switch to RUN mode (80 MHz) to execute CSEc (Security) or EEPROM writes/erase.
- Not supported yet
- Part numbers no longer offered as standard include:
Ordering Option X (M:64MHz); Ordering Option Y (N: limited RAM. 16KB for K142, 48KB for K144, 96KB for K146, 192KB for K148
S: Security); Temperature (C: -40C to 85C)

NOTE

Not all part number combinations are available. See S32K1xx_Orderable_Part_Number_List.xlsx attached with the Datasheet for list of standard orderable parts.

Figure 4. Ordering information

4 General

4.1 Absolute maximum ratings

NOTE

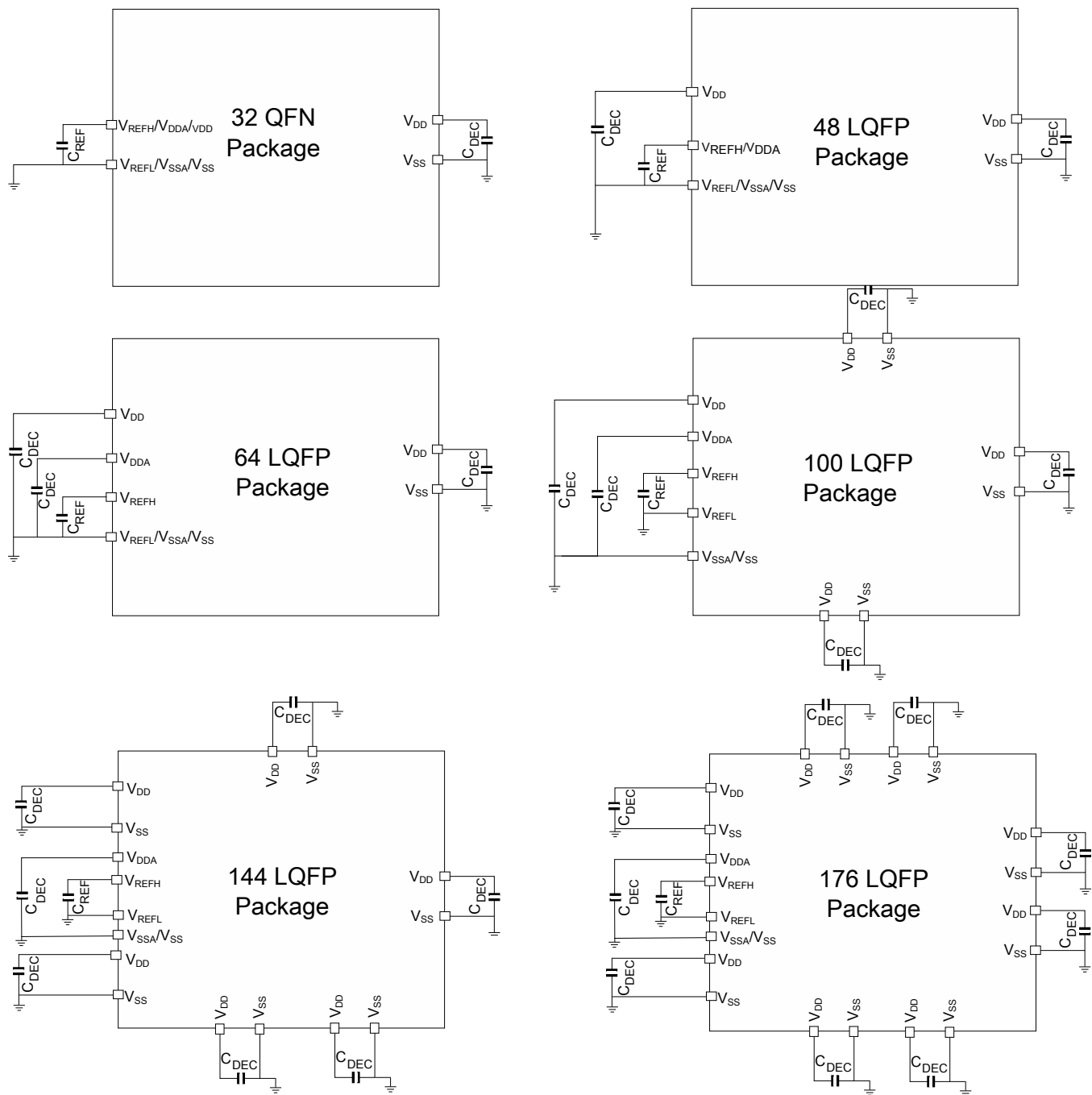
- Functional operating conditions appear in the DC electrical characteristics. Absolute maximum ratings are stress ratings only, and functional operation at the maximum values is not guaranteed. See footnotes in the following table for specific conditions.
- Stress beyond the listed maximum values may affect device reliability or cause permanent damage to the device.
- All the limits defined in the datasheet specification must be honored together and any violation to any one or more will not guarantee desired operation.
- Unless otherwise specified, all maximum and minimum values in the datasheet are across process, voltage, and temperature.

Table 1. Absolute maximum ratings

Symbol	Parameter	Conditions ¹	Min	Max	Unit
V_{DD} ²	2.7 V - 5.5V input supply voltage	—	-0.3	5.8 ³	V
V_{REFH}	3.3 V / 5.0 V ADC high reference voltage	—	-0.3	5.8 ³	V
$I_{INJPAD_DC_ABS}$ ⁴	Continuous DC input current (positive / negative) that can be injected into an I/O pin	—	-3	+3	mA
V_{IN_DC}	Continuous DC Voltage on any I/O pin with respect to V_{SS}	—	-0.8	5.8 ⁵	V
$I_{INJSUM_DC_ABS}$	Sum of absolute value of injected currents on all the pins (Continuous DC limit)	—	—	30	mA
T_{ramp} ⁶	ECU supply ramp rate	—	0.5 V/min	500 V/ms	—
T_{ramp_MCU} ⁷	MCU supply ramp rate	—	0.5 V/min	100 V/ms	—
T_A ⁸	Ambient temperature	—	-40	125	°C
T_{STG}	Storage temperature	—	-55	165	°C
$V_{IN_TRANSIENT}$	Transient overshoot voltage allowed on I/O pin beyond V_{IN_DC} limit	—	—	6.8 ⁹	V

1. All voltages are referred to V_{SS} unless otherwise specified.
2. As V_{DD} varies between the minimum value and the absolute maximum value the analog characteristics of the I/O and the ADC will both change. See section [I/O parameters](#) and [ADC electrical specifications](#) respectively for details.
3. 60 s lifetime – No restrictions i.e. The part can switch.
10 hours lifetime – Device in reset i.e. The part cannot switch.

4.4 Power and ground pins



NOTE: V_{DD} and V_{DDA} must be shorted to a common source on PCB

Figure 5. Pinout decoupling

Table 8. VLPS additional use-case power consumption at typical conditions

Use-case	Description	Temp.	Device						Unit
			S32K116	S32K118	S32K142	S32K144	S32K146	S32K148	
VLPS and RTC	Clock source: LPO or RTC_CLKIN	25	TBD	TBD	30	30	30	40	μA
		85	TBD	TBD	110	170	180	240	μA
		105	TBD	TBD	230	330	350	490	μA
		125	TBD	TBD	570	680	810	1250	μA
VLPS and LPUART TX/RX	- Clock source: SIRC - Transmitting or receiving continuously using DMA - Baudrate: 19.2 kbps	25	TBD	TBD	230	230	250	250	μA
		85	TBD	TBD	320	400	410	490	μA
		105	TBD	TBD	490	550	600	850	μA
		125	TBD	TBD	890	1070	1250	1960	μA
VLPS and LPUART wake-up	- Clock source: SIRC - Wake-up address feature enabled - Baudrate: 19.2 kbps	25	TBD	TBD	100	100	110	110	μA
		85	TBD	TBD	170	240	280	350	μA
		105	TBD	TBD	260	400	480	600	μA
		125	TBD	TBD	530	580	1000	1280	μA
VLPS and LPI2C master	- Clock Source: SIRC - Transmit/receive using DMA - Baudrate: 100 kHz	25	TBD	TBD	670	690	820	900	μA
		85	TBD	TBD	880	960	1220	1370	μA
		105	TBD	TBD	1080	1250	1660	2060	μA
		125	TBD	TBD	1970	1980	2860	3690	μA
VLPS and LPI2C slave wake-up	- Clock source: SIRC - Wake-up address feature enabled - Baudrate: 100 kHz	25	TBD	TBD	250	250	270	280	μA
		85	TBD	TBD	340	340	410	510	μA
		105	TBD	TBD	430	430	610	810	μA
		125	TBD	TBD	740	760	1170	1540	μA
VLPS and LPSPi master	- Clock source: SIRC - Transmit/receive using DMA - Baudrate: 500 kHz	25	TBD	TBD	2.99	3.19	3.75	4.11	mA
		85	TBD	TBD	3.26	3.7	4.35	4.93	mA
		105	TBD	TBD	3.5	4.2	4.93	5.74	mA
		125	TBD	TBD	3.93	4.63	5.97	7.38	mA
VLPS and LPIT	- Clock source: SIRC 1 channel enable - Mode: 32-bit periodic counter	25	TBD	TBD	100	100	120	130	μA
		85	TBD	TBD	190	250	260	320	μA
		105	TBD	TBD	310	410	440	570	μA
		125	TBD	TBD	640	750	910	1280	μA

**Table 17. External System Oscillator electrical specifications
(continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
	High-gain mode (HGO=1)	—	1	—	MΩ	
R _S	Series resistor					
	Low-gain mode (HGO=0)	—	0	—	kΩ	
	High-gain mode (HGO=1)	—	0	—	kΩ	
V _{pp}	Peak-to-peak amplitude of oscillation (oscillator mode)					3
	Low-gain mode (HGO=0)	—	1.0	—	V	
	High-gain mode (HGO=1)	—	3.3	—	V	

1. Crystal oscillator circuit provides stable oscillations when $g_{mXOSC} > 5 * gm_crit$. The gm_crit is defined as:

$$gm_crit = 4 * ESR * (2\pi F)^2 * (C_0 + C_L)^2$$

where:

- g_{mXOSC} is the transconductance of the internal oscillator circuit
- ESR is the equivalent series resistance of the external crystal
- F is the external crystal oscillation frequency
- C_0 is the shunt capacitance of the external crystal
- C_L is the external crystal total load capacitance. $C_L = C_s + [C_1 * C_2 / (C_1 + C_2)]$
- C_s is stray or parasitic capacitance on the pin due to any PCB traces
- C_1, C_2 external load capacitances on EXTAL and XTAL pins

See manufacture datasheet for external crystal component values

- When low-gain is selected, internal R_F will be selected and external R_F should not be attached.
 - When high-gain is selected, external R_F (1 M Ohm) needs to be connected for proper operation of the crystal. For external resistor, up to 5% tolerance is allowed.
- The EXTAL and XTAL pins should only be connected to required oscillator components and must not be connected to any other devices.

6.2.2 External System Oscillator frequency specifications

Table 23. Flash command timing specifications for S32K14x (continued)

Symbol	Description ¹		S32K142		S32K144		S32K146		S32K148		Unit Notes	
			Typ	Max	Typ	Max	Typ	Max	Typ	Max		
	setting (32-bit write complete, ready for next 32-bit write)	Last (Nth) 32-bit write (time for write only, not cleanup)	200	550	200	550	200	550	200	550		
$t_{\text{quickwrClnup}}$	Quick Write Cleanup execution time	—	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	ms	7

1. All command times assumes 25 MHz or greater flash clock frequency (for synchronization time between internal/external clocks).
2. Maximum times for erase parameters based on expectations at cycling end-of-life.
3. For all EEPROM Emulation terms, the specified timing shown assumes previous record cleanup has occurred. This may be verified by executing FCCOB Command 0x77, and checking FCCOB number 5 contents show 0x00 - No EEPROM issues detected.
4. 1st time EERAM writes after a Reset or SETRAM may incur additional overhead for EEE cleanup, resulting in up to 2x the times shown.
5. Only after the Nth write completes will any data be valid. Emulated EEPROM record scheme cleanup overhead may occur after this point even after a brownout or reset. If power on reset occurs before the Nth write completes, the last valid record set will still be valid and the new records will be discarded.
6. Quick Write times may take up to 550 μ s, as additional cleanup may occur when crossing sector boundaries.
7. Time for emulated EEPROM record scheme overhead cleanup. Automatically done after last (Nth) write completes, assuming still powered. Or via SETRAM cleanup execution command is requested at a later point.

Table 24. Flash command timing specifications for S32K11x

Symbol	Description ¹		S32K116		S32K118		Unit Notes	
			Typ	Max	Typ	Max		
t_{rd1blk}	Read 1 Block execution time	32 KB flash	—	0.36	—	0.36	ms	
		64 KB flash	—	—	—	—		
		128 KB flash	—	1.2	—	—		
		256 KB flash	—	—	—	2		
		512 KB flash	—	—	—	—		
t_{rd1sec}	Read 1 Section execution time	2 KB flash	—	75	—	75	μ s	
		4 KB flash	—	100	—	100		
t_{pgmchk}	Program Check execution time	—	—	100	—	100	μ s	
t_{pgm8}	Program Phrase execution time	—	90	225	90	225	μ s	
t_{ersblk}	Erase Flash Block execution time	32 KB flash	15	300	15	300	ms	2
		64 KB flash	—	—	—	—		
		128 KB flash	120	1100	—	—		
		256 KB flash	—	—	250	2125		
		512 KB flash	—	—	—	—		

Table continues on the next page...

Table 26. QuadSPI electrical specifications

FLASH PORT	Sym	Unit	FLASH A												FLASH B			
			RUN ¹						HSRUN ¹						RUN/HSRUN ²			
QuadSPI Mode			SDR						SDR						SDR		DDR ³	
			Internal Sampling		Internal DQS				Internal Sampling		Internal DQS				Internal Sampling		External DQS	
			N1		PAD Loopback		Internal Loopback		N1		PAD Loopback		Internal Loopback		N1		External DQS	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max
Register Settings																		
MCR[DDR_EN]		-	0		0		0		0		0		0		0		1	
MCR[DQS_EN]		-	0		1		1		0		1		1		0		1	
MCR[SCLKCFG[0]]		-	-		1		0		-		1		0		-		-	
MCR[SCLKCFG[1]]		-	-		1		0		-		1		0		-		-	
MCR[SCLKCFG[2]]		-	-		-		-		-		-		-		-		0	
MCR[SCLKCFG[3]]		-	-		-		-		-		-		-		-		0	
MCR[SCLKCFG[5]]		-	0		0		0		0		0		0		0		1	
SMPR[FSPHS]		-	0		1		0		0		1		0		0		0	
SMPR[FSDLY]		-	0		0		0		0		0		0		0		0	
SOCCR [SOCCFG[7:0]]			-		0		23		-		0		30		-		-	
SOCCR[SOCCFG[15:8]]		-	-		-		-		-		-		-		-		30	
FLSHCR[TDH]		-	0x00		0x00		0x00		0x00		0x00		0x00		0x00		0x01	
Timing Parameters																		
SCK Clock Frequency	f _{SCK}	MHz	-	38	-	64	-	48	-	40	-	80	-	50	-	20	-	20 ⁴
SCK Clock Period	t _{SCK}	ns	1/f _{SCK}	-	1/f _{SCK}	-	1/f _{SCK}	-	1/f _{SCK}	-	1/f _{SCK}	-	1/f _{SCK}	-	50.0	-	50.0 ⁴	-

Table continues on the next page...

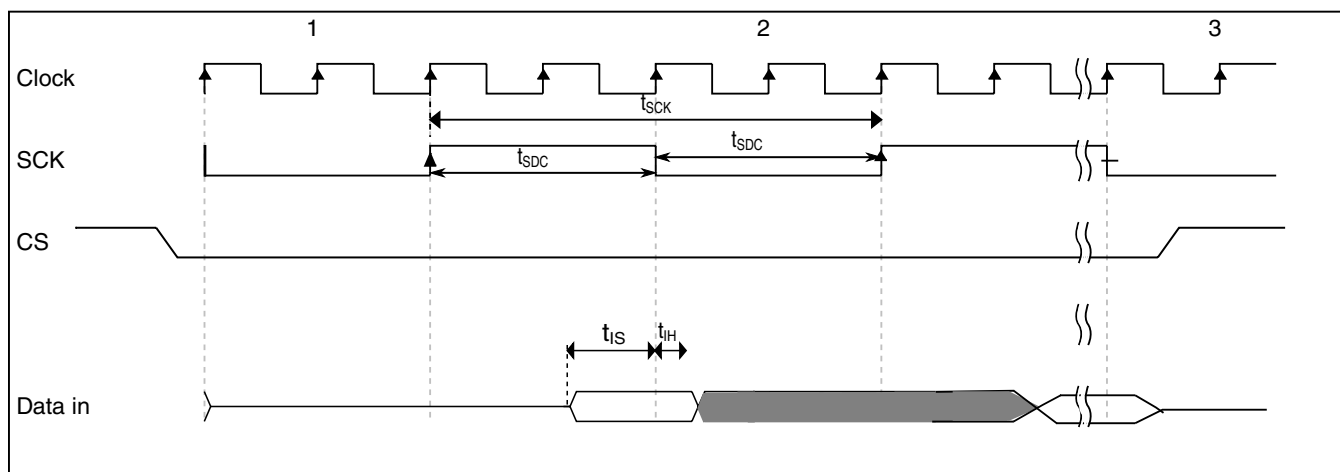


Figure 9. QuadSPI input timing (SDR mode) diagram

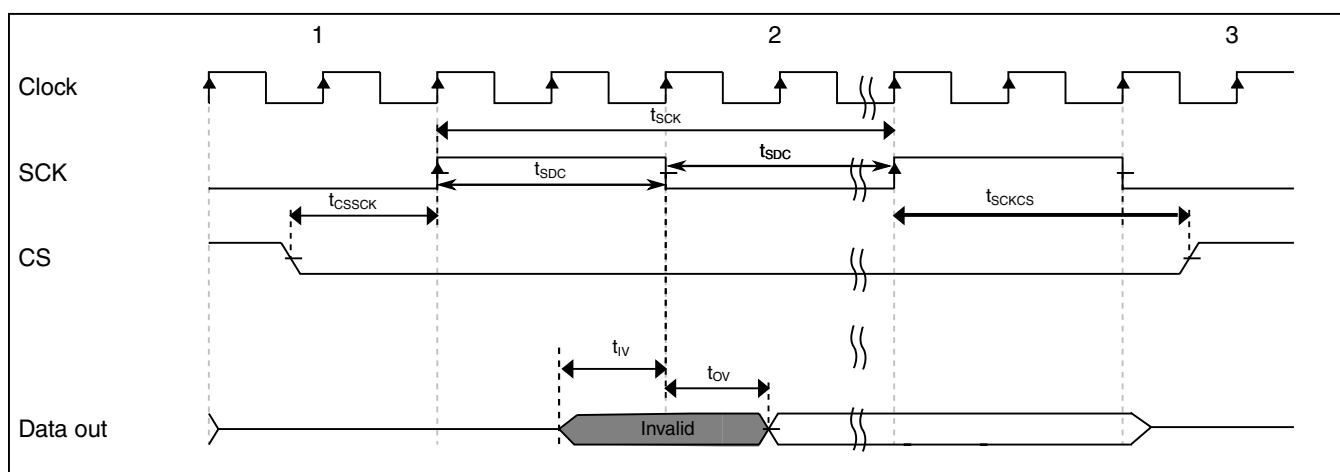
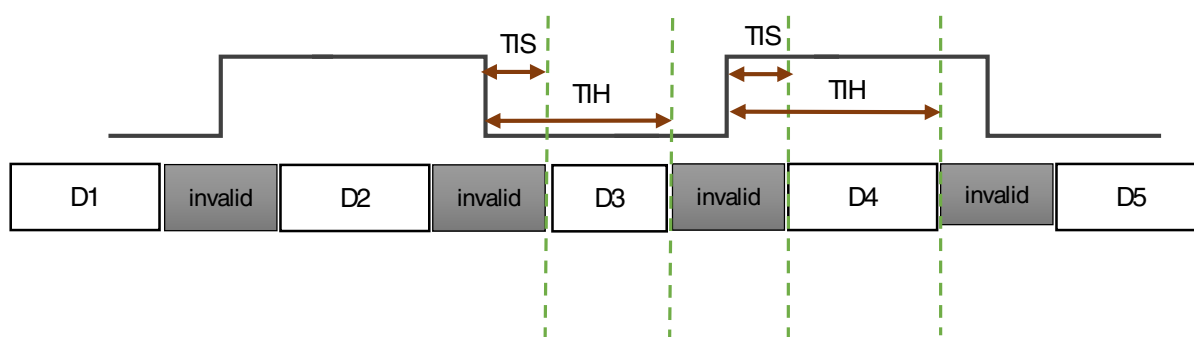


Figure 10. QuadSPI output timing (SDR mode) diagram



TIS – Setup Time

TIH – Hold Time

Figure 11. QuadSPI input timing (HyperRAM mode) diagram

Table 29. 12-bit ADC characteristics (3 V to 5.5 V)($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SS}$)

Symbol	Description	Conditions ¹	Min.	Typ. ²	Max.	Unit	Notes
V_{DDA}	Supply voltage		3	—	5.5	V	
I_{DDA_ADC}	Supply current per ADC		—	1	—	mA	3
SMPLTS	Sample Time		275	—	Refer to the <i>Reference Manual</i>	ns	
TUE ⁴	Total unadjusted error		—	±4	±8	LSB ⁵	6, 7, 8, 9
DNL	Differential non-linearity		—	±0.7	—	LSB ⁵	6, 7, 8, 9
INL	Integral non-linearity		—	±1.0	—	LSB ⁵	6, 7, 8, 9

1. All accuracy numbers assume the ADC is calibrated with $V_{REFH}=V_{DDA}=V_{DD}$, with the calibration frequency set to less than or equal to half of the maximum specified ADC clock frequency.
2. Typical values assume $V_{DDA} = 5.0$ V, Temp = 25 °C, $f_{ADCK} = 40$ MHz, $R_{AS}=20$ Ω, and $C_{AS}=10$ nF unless otherwise stated.
3. The ADC supply current depends on the ADC conversion rate.
4. Represents total static error, which includes offset and full scale error.
5. $1 \text{ LSB} = (V_{REFH} - V_{REFL})/2^N$
6. The specifications are with averaging and in standalone mode only. Performance may degrade depending upon device use case scenario. When using ADC averaging, refer to the *Reference Manual* to determine the most appropriate settings for AVGS.
7. For ADC signals adjacent to V_{DD}/V_{SS} or XTAL/EXTAL or high frequency switching pins, some degradation in the ADC performance may be observed.
8. All values guarantee the performance of the ADC for multiple ADC input channel pins. When using ADC to monitor the internal analog parameters, assume minor degradation.
9. All the parameters in the table are given assuming system clock as the clocking source for ADC.

NOTE

- Due to triple bonding in lower pin packages like 32-QFN, 48-LQFP, and 64-LQFP degradation might be seen in ADC parameters.
- When using high speed interfaces such as the QuadSPI, SAI0, SAI1 or ENET there may be some ADC degradation on the adjacent analog input paths. See following table for details.

Pin name	TGATE purpose
PTE8	CMP0_IN3
PTC3	ADC0_SE11/CMP0_IN4
PTC2	ADC0_SE10/CMP0_IN5
PTD7	CMP0_IN6
PTD6	CMP0_IN7
PTD28	ADC1_SE22
PTD27	ADC1_SE21

6.4.2 CMP with 8-bit DAC electrical specifications

Table 31. Comparator with 8-bit DAC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit
I _{DDHS}	Supply current, High-speed mode ¹				μA
	-40 - 125 °C	—	230	300	
I _{DDL}	Supply current, Low-speed mode ¹				μA
	-40 - 105 °C	—	6	11	
	-40 - 125 °C		6	13	
V _{AIN}	Analog input voltage	0	0 - V _{DDA}	V _{DDA}	V
V _{AIO}	Analog input offset voltage, High-speed mode				mV
	-40 - 125 °C	-25	±1	25	
V _{AIO}	Analog input offset voltage, Low-speed mode				mV
	-40 - 125 °C	-40	±4	40	
t _{DHSB}	Propagation delay, High-speed mode ²				ns
	-40 - 105 °C	—	35	200	
	-40 - 125 °C		35	300	
t _{DL}	Propagation delay, Low-speed mode ²				μs
	-40 - 105 °C	—	0.5	2	
	-40 - 125 °C	—	0.5	3	
t _{DH}	Propagation delay, High-speed mode ³				ns
	-40 - 105 °C	—	70	400	
	-40 - 125 °C	—	70	500	
t _{DL}	Propagation delay, Low-speed mode ³				μs
	-40 - 105 °C	—	1	5	
	-40 - 125 °C	—	1	5	
t _{IDH}	Initialization delay, High-speed mode ⁴				μs
	-40 - 125 °C	—	1.5	3	
t _{IDL}	Initialization delay, Low-speed mode ⁴				μs
	-40 - 125 °C	—	10	30	
V _{HYST0}	Analog comparator hysteresis, Hyst0				mV
	-40 - 125 °C	—	0	—	
V _{HYST1}	Analog comparator hysteresis, Hyst1, High-speed mode				mV
	-40 - 125 °C	—	19	66	
	Analog comparator hysteresis, Hyst1, Low-speed mode				
	-40 - 125 °C	—	15	40	
V _{HYST2}	Analog comparator hysteresis, Hyst2, High-speed mode				mV
	-40 - 125 °C	—	34	133	

Table continues on the next page...

Table 31. Comparator with 8-bit DAC electrical specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit
	Analog comparator hysteresis, Hyst2, Low-speed mode				
	-40 - 125 °C	—	23	80	
V _{HYST3}	Analog comparator hysteresis, Hyst3, High-speed mode				mV
	-40 - 125 °C	—	46	200	
	Analog comparator hysteresis, Hyst3, Low-speed mode				
	-40 - 125 °C	—	32	120	
I _{DAC8b}	8-bit DAC current adder (enabled)				
	3.3V Reference Voltage	—	6	9	μA
	5V Reference Voltage	—	10	16	μA
INL ⁵	8-bit DAC integral non-linearity	−0.75	—	0.75	LSB ⁶
DNL	8-bit DAC differential non-linearity	−0.5	—	0.5	LSB ⁶
t _{DDAC}	Initialization and switching settling time	—	—	30	μs

1. Difference at input > 200mV
2. Applied $\pm (100 \text{ mV} + V_{\text{HYST0}/1/2/3+ \text{ max. of } V_{\text{AIO}})$ around switch point.
3. Applied $\pm (30 \text{ mV} + 2 \times V_{\text{HYST0}/1/2/3+ \text{ max. of } V_{\text{AIO}})$ around switch point.
4. Applied $\pm (100 \text{ mV} + V_{\text{HYST0}/1/2/3})$.
5. Calculation method used: Linear Regression Least Square Method
6. $1 \text{ LSB} = V_{\text{reference}}/256$

NOTE

For comparator IN signals adjacent to V_{DD}/V_{SS} or XTAL/EXTAL or switching pins cross coupling may happen and hence hysteresis settings can be used to obtain the desired comparator performance. Additionally, an external capacitor (1nF) should be used to filter noise on input signal. Also, source drive should not be weak (Signal with < 50 K pull up/down is recommended).

6.5 Communication modules

6.5.1 LPUART electrical specifications

Refer to [General AC specifications](#) for LPUART specifications.

6.5.1.1 Supported baud rate

Baud rate = Baud clock / ((OSR+1) * SBR).

For details, see section: 'Baud rate generation' of the *Reference Manual*.

6.5.2 LPSPI electrical specifications

The Low Power Serial Peripheral Interface (LPSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The following tables provide timing characteristics for classic LPSPI timing modes.

- All timing is shown with respect to 20% V_{DD} and 80% V_{DD} thresholds.
- All measurements are with maximum output load of 50 pF, input transition of 1 ns and pad configured with fastest slew setting (DSE = 1).

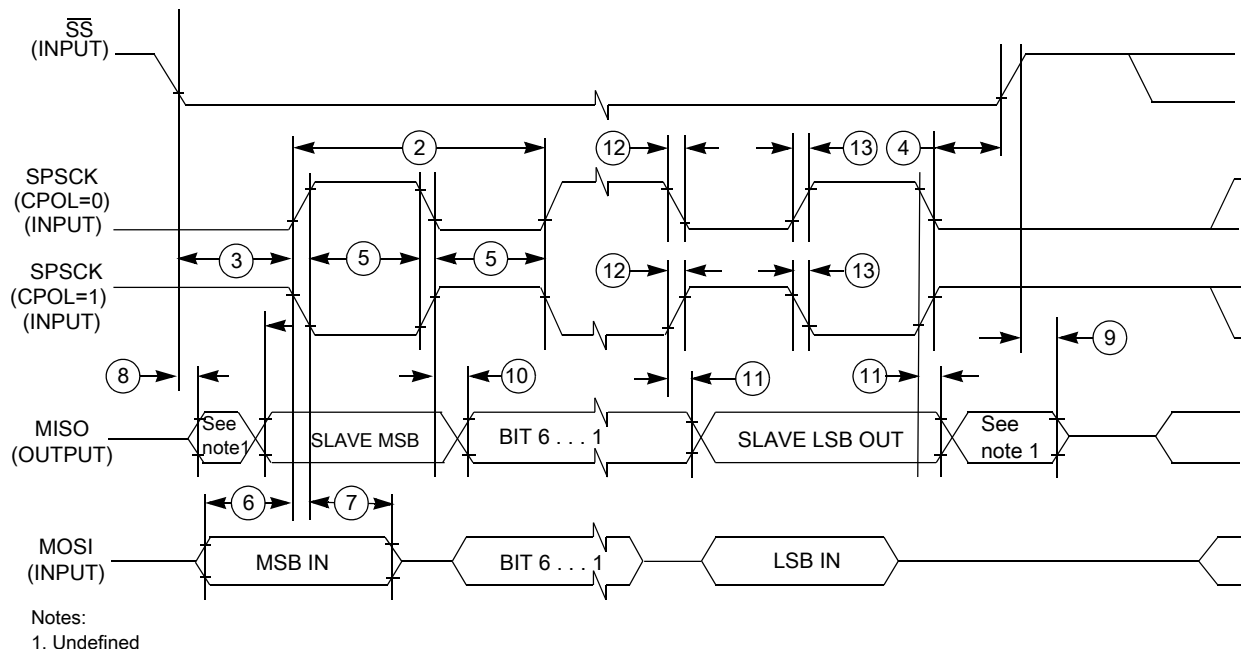


Figure 20. LPSPI slave mode timing (CPHA = 0)

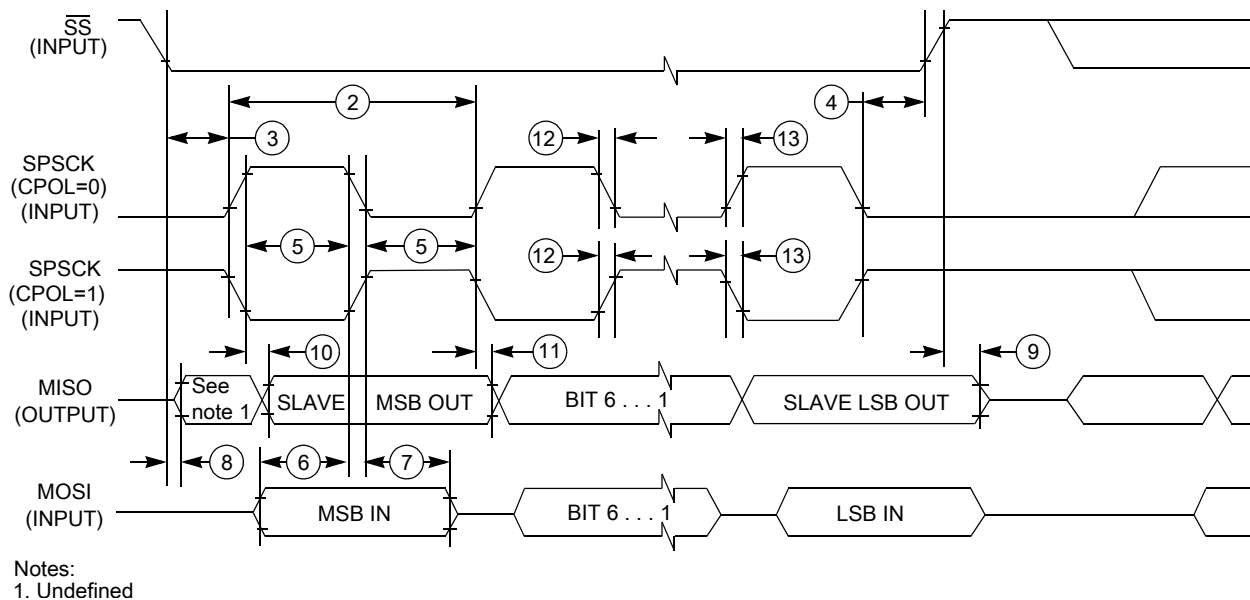


Figure 21. LPSPI slave mode timing (CPHA = 1)

6.5.3 LPI2C electrical specifications

See [General AC specifications](#) for LPI2C specifications.

For supported baud rate see section 'Chip-specific LPI2C information' of the *Reference Manual*.

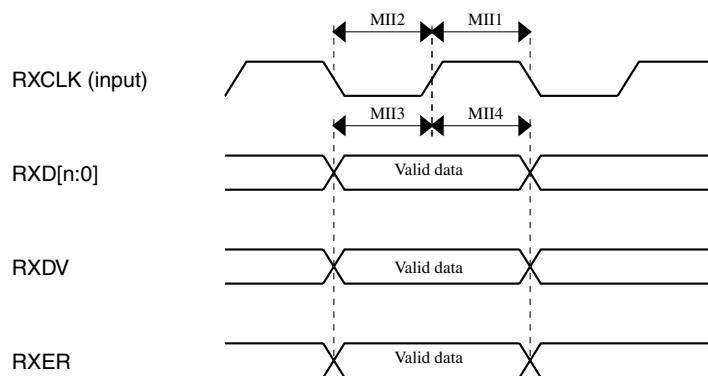


Figure 24. MII receive diagram

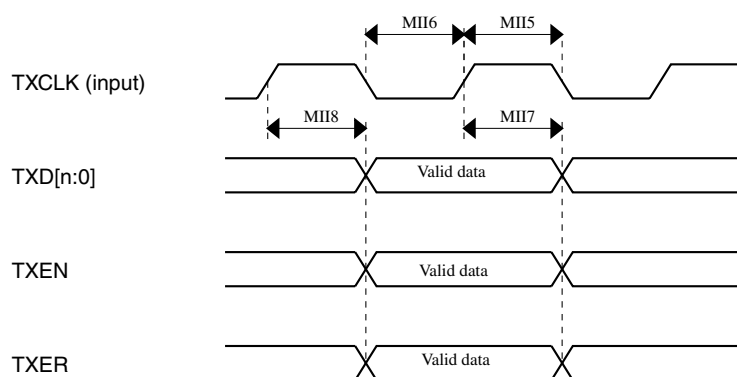


Figure 25. MII transmit signal diagram

The following table describes the RMII electrical characteristics.

- Measurements are with maximum output load of 25 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.

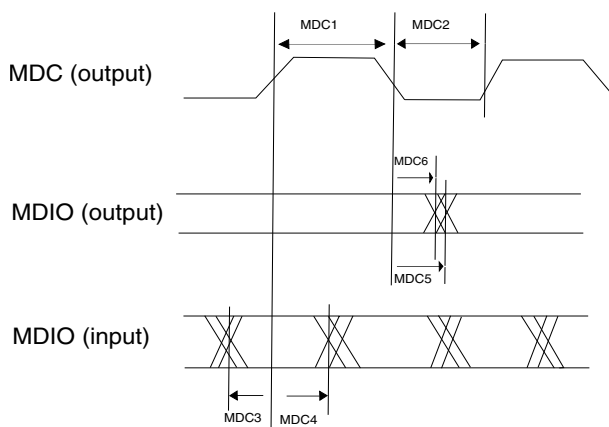
Table 36. RMII signal switching specifications

Symbol	Description	Min.	Max.	Unit
—	RMII input clock RMII_CLK Frequency	—	50	MHz
RMII1, RMII5	RMII_CLK pulse width high	35%	65%	RMII_CLK period
RMII2, RMII6	RMII_CLK pulse width low	35%	65%	RMII_CLK period
RMII3	RXD[1:0], CRS_DV, RXER to RMII_CLK setup	4	—	ns
RMII4	RMII_CLK to RXD[1:0], CRS_DV, RXER hold	2	—	ns

Table continues on the next page...

Table 37. MDIO timing specifications (continued)

Symbol	Description	Min.	Max.	Unit
MDC1	MDC pulse width high	40%	60%	MDC period
MDC2	MDC pulse width low	40%	60%	MDC period
MDC3	MDIO (input) to MDC rising edge setup	25	—	ns
MDC4	MDIO (input) to MDC rising edge hold	0	—	ns
MDC5	MDC falling edge to MDIO output valid (maximum propagation delay)	—	25	ns
MDC6	MDC falling edge to MDIO output invalid (minimum propagation delay)	-10	—	ns

**Figure 28. MII/RMII serial management channel timing diagram**

6.5.7 Clockout frequency

Maximum supported clock out frequency for this device is 20 MHz

6.6 Debug modules

6.6.1 SWD electrical specifications

Table 41. Thermal characteristics for 32-pin QFN and 48/64/100/144/176-pin LQFP package (continued)

Rating	Conditions	Symbol	Package	Values						Unit	
				S32K116	S32K118	S32K142	S32K144	S32K146	S32K148		
			144	NA	NA	NA	NA	37	31		
			176	NA	NA	NA	NA	NA	30		
Thermal resistance, Junction to Ambient (@200 ft/min) ^{1, 3}	Four layer board (2s2p)	R _{θJMA}	32	26	NA	NA	NA	NA	NA		
			48	48	41	NA	NA	NA	NA		
			64	NA	37	36	36	35	NA		
			100	NA	NA	34	34	33	NA		
			144	NA	NA	NA	NA	36	30		
			176	NA	NA	NA	NA	NA	29		
			Thermal resistance, Junction to Board ⁴	—	R _{θJB}	32	11	NA	NA		NA
48	33	24	NA	NA		NA	NA	NA			
64	NA	26	25	25		23	NA				
100	NA	NA	25	25		24	NA				
144	NA	NA	NA	NA		30	24				
176	NA	NA	NA	NA		NA	24				
Thermal resistance, Junction to Case ⁵	—	R _{θJC}	32	NA	NA	NA	NA	NA	NA		
			48	23	19	NA	NA	NA	NA		
			64	NA	14	13	12	11	NA		
			100	NA	NA	13	12	11	NA		
			144	NA	NA	NA	NA	12	9		
			176	NA	NA	NA	NA	NA	9		
Thermal resistance, Junction to Case (Bottom) ⁶	—	R _{θJCBottom}	32	1	NA						
			48	NA							
			64								
			100								
			144								
			176								

Table continues on the next page...

Table 43. Revision History

Rev. No.	Date	Substantial Changes
		- Added footnotes V_{ih} Input Buffer High Voltage and V_{il} Input Buffer Low Voltage - Updated table: AC electrical specifications at 3.3 V range - Updated table: AC electrical specifications at 5 V range - In table: Standard input pin capacitance - Added footnote to Normal run mode (S32K14x series) - Removed note from 1M ohms Feedback Resistor in figure Oscillator connections scheme - In table: External System Oscillator electrical specifications - Updated typical of I_{DDOSC} Supply current — low-gain mode (low-power mode) (HGO=0) 1 for 4 and 8 MHz - Removed rows for I_{lk_ext} EXTAL/XTAL impedance High-frequency, low-gain mode (low-power mode) and high-frequency, high-gain mode and V_{EXTAL} - Updated Typ. of R_S low-gain mode - Updated description of R_F, R_S, and V_{PP} - Removed footnote from R_F Feedback resistor - Updated footnote for C_1 C_2 and R_F - In table: Table 18 - Removed mention of high-frequency - Added HGO 0, 1 information - In table: Fast internal RC Oscillator electrical specifications - Updated F_{FIRC} - Updated description of ΔF - Updated typ and max values of T_{JIT} cycle-to-cycle jitter and T_{JIT} Long term jitter over 1000 cycles - Added footnotes to T_{JIT} cycle-to-cycle jitter and T_{JIT} Long term jitter over 1000 cycles - Updated naming convention of I_{DDFIRC} Supply current - Added footnote to I_{DDFIRC} Supply current - Added footnote to column Parameter - In table: Slow internal RC oscillator (SIRC) electrical specifications - Removed V_{DD} Supply current in 2 MHz Mode - Removed footnote and updated description of ΔF - Updated footnote to F_{SIRC} and I_{DDSIRC} - In table: SPLL electrical specifications - Added row for F_{SPLL_REF} PLL Reference - Updated naming convention throughout the table - Updated the max value of T_{SPLL_LOCK} Lock detector detection time - In table: Flash timing specifications — commands - Added footnotes: - All command times assumes ... - For all EEPROM Emulation terms ... 'First time' EERAM writes after a POR ... - Removed footnote 'Assumes 25 MHz or ...' - Updated Max of $t_{ewr32bers}$ - Added parameters $t_{quickwr}$ and $t_{quickwrCinup}$ - In table: Reliability specifications - Removed Typ. values for all parameters - Removed footnote 'Typical values represent ...' - Added footnote 'Any other EEE driver usage ...' - Updated QuadSPI AC specifications - Removed topic: Reliability, Safety and Security modules - In table: 12-bit ADC operating conditions - Updated V_{DDA}

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Table 43. Revision History (continued)

Rev. No.	Date	Substantial Changes
		- Updated 3.3 V numbers and added footnote against f_{op}, t_{SU}, and t_V in HSRUN Mode - Added footnote to 't_{WSPCK}' - Updated Thermal characteristics for S32K11x
6	31 Jan 2018	- Changed the representation of ARM trademark throughout. - Removed S32K142 from 'Caution' - In 'Key features', added the following note under 'Power management', 'Memory and memory interfaces', and 'Reliability, safety and security': - No write or erase access to ... - In High-level architecture diagram for the S32K14x family, added the following footnote: - No write or erase access to ... - In High-level architecture diagram for the S32K11x family : - Minor editorial update: Fixed the placement of SRAM, under 'Flash memory controller' block - Updated figure: S32K1xx product series comparison : - Updated footnote 1, and added against 'HSRUN' in addition to 'HW security module (CSEc)' and 'EEPROM emulated by FlexRAM'. - Updated 'System RAM (including FlexRAM and MTB)' row for S32K144, S32K146, and S32K148. - Updated channel count for S32K116 in row '12-bit SAR ADC (1 MSPS each)'. - Updated Ordering information - Updated Flash timing specifications — commands for S32K148, S32K142, S32K146, S32K116, and S32K118.
7	19 April 2018	- Changed Caution to Notes - Updated the wordings of Notes and removed S32K146 - Added 'Following two are the available ...' - In 'Key features' : - Editorial updates - Updated the note under Power management, Memory and memory interfaces, and Safety and security. - Updated FlexIO under Communications interfaces - Added ENET and SAI under Communications interfaces - Updated Cryptographic Services Engine (CSEc) under 'Safety and security' - In High-level architecture diagram for the S32K14x family : - Minor editorial updates - Updated note 3 - In High-level architecture diagram for the S32K11x family : - Minor editorial updates - In figure: S32K1xx product series comparison : - Editorial updates - Updated Frequency for S32K14x - Updated footnote 4 - Added footnote 5 - In Ordering information : - Renamed section, updated the starting paragraph - Updated the figure - In Voltage and current operating requirements, updated the note - In Power consumption : - Updated specs for S32K146 - Removed section 'Modes configuration', and moved its content under the first paragraph. - In 12-bit ADC operating conditions :

Table continues on the next page...