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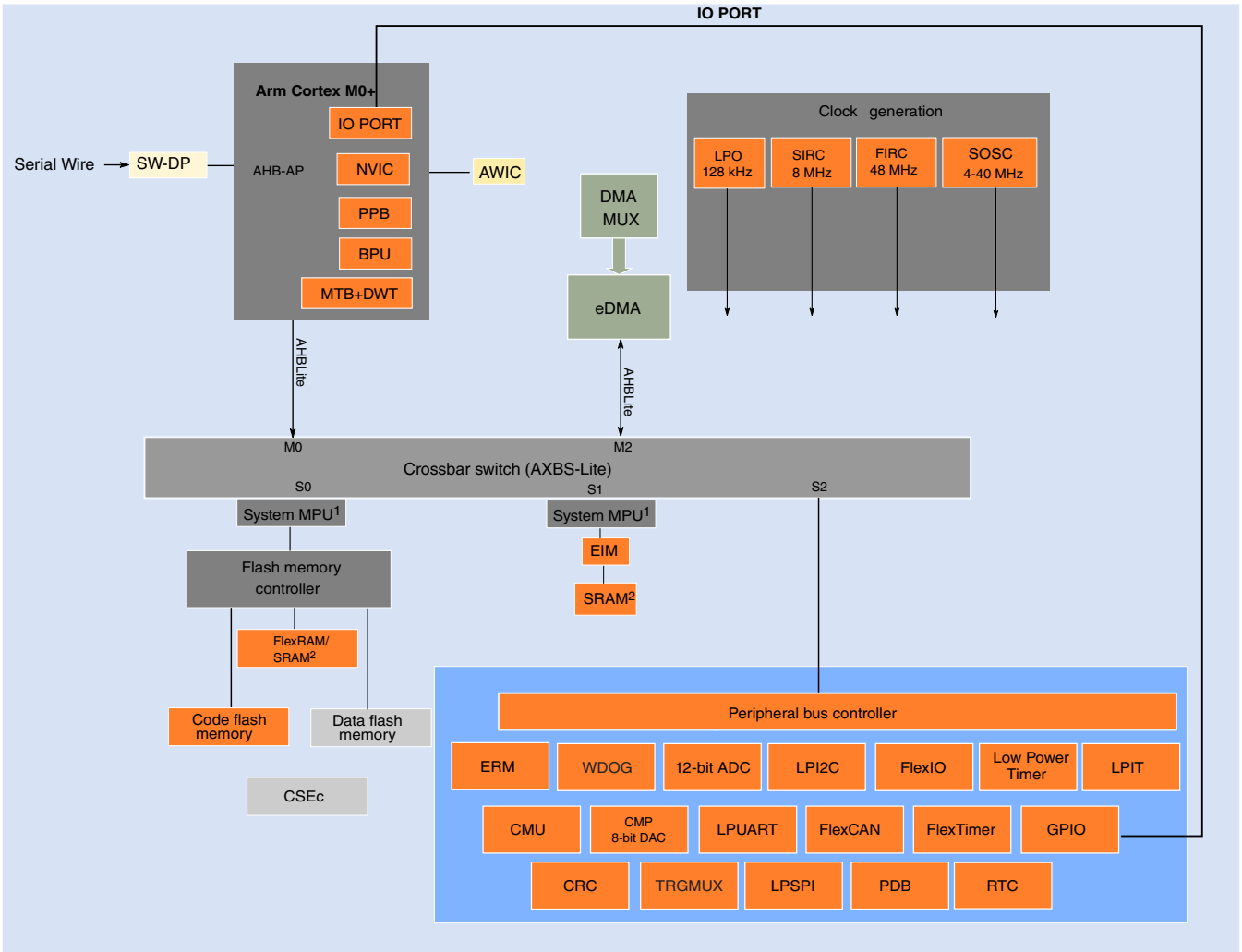
What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M4F
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	CANbus, FlexIO, I²C, LINbus, SPI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	89
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x12b SAR; D/A1x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/fs32k144hrt0mllt



1: On this device, NXP's system MPU implements the safety mechanisms to prevent masters from accessing restricted memory regions. This system MPU provides memory protection at the level of the Crossbar Switch. Crossbar master (Core, DMA) can be assigned different access rights to each protected memory region. The Arm M0+ core version in this family does not integrate the Arm Core MPU, which would concurrently monitor only core-initiated memory accesses. In this document, the term MPU refers to NXP's system MPU.

2: For the device-specific sizes, see the "On-chip SRAM sizes" table in the "Memories and Memory Interfaces" chapter of the S32K1xx Series Reference Manual.

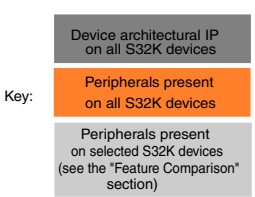


Figure 2. High-level architecture diagram for the S32K11x family

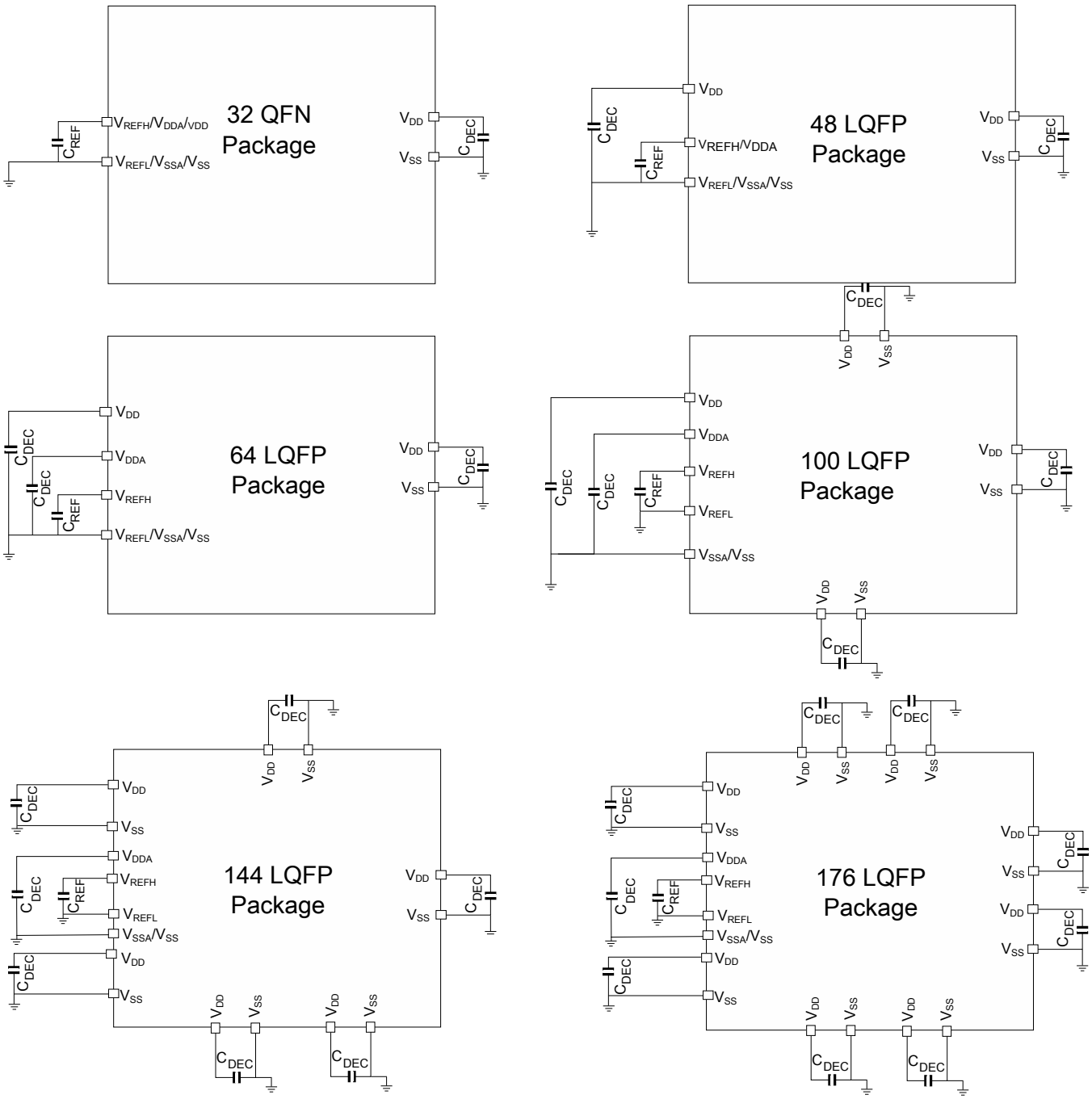
2 Feature comparison

The following figure summarizes the memory, peripherals and packaging options for the S32K1xx devices. All devices which share a common package are pin-to-pin compatible.

NOTE

Availability of peripherals depends on the pin availability in a particular package. For more information see *IO Signal*

4.4 Power and ground pins



NOTE: V_{DD} and V_{DDA} must be shorted to a common source on PCB

Figure 5. Pinout decoupling

Table 8. VLPS additional use-case power consumption at typical conditions

Use-case	Description	Temp.	Device						Unit
			S32K116	S32K118	S32K142	S32K144	S32K146	S32K148	
VLPS and RTC	• Clock source: LPO or RTC_CLKIN	25	TBD	TBD	30	30	30	40	µA
		85	TBD	TBD	110	170	180	240	µA
		105	TBD	TBD	230	330	350	490	µA
		125	TBD	TBD	570	680	810	1250	µA
VLPS and LPUART TX/RX	• Clock source: SIRC • Transmiting or receiving continuously using DMA • Baudrate: 19.2 kbps	25	TBD	TBD	230	230	250	250	µA
		85	TBD	TBD	320	400	410	490	µA
		105	TBD	TBD	490	550	600	850	µA
		125	TBD	TBD	890	1070	1250	1960	µA
VLPS and LPUART wake-up	• Clock source: SIRC • Wake-up address feature enabled • Baudrate: 19.2 kbps	25	TBD	TBD	100	100	110	110	µA
		85	TBD	TBD	170	240	280	350	µA
		105	TBD	TBD	260	400	480	600	µA
		125	TBD	TBD	530	580	1000	1280	µA
VLPS and LPI2C master	• Clock Source: SIRC • Transmit/receive using DMA • Baudrate: 100 kHz	25	TBD	TBD	670	690	820	900	µA
		85	TBD	TBD	880	960	1220	1370	µA
		105	TBD	TBD	1080	1250	1660	2060	µA
		125	TBD	TBD	1970	1980	2860	3690	µA
VLPS and LPI2C slave wake-up	• Clock source: SIRC • Wake-up address feature enabled • Baudrate: 100 kHz	25	TBD	TBD	250	250	270	280	µA
		85	TBD	TBD	340	340	410	510	µA
		105	TBD	TBD	430	430	610	810	µA
		125	TBD	TBD	740	760	1170	1540	µA
VLPS and LPSPI master	• Clock source: SIRC • Transmit/receive using DMA • Baudrate: 500 kHz	25	TBD	TBD	2.99	3.19	3.75	4.11	mA
		85	TBD	TBD	3.26	3.7	4.35	4.93	mA
		105	TBD	TBD	3.5	4.2	4.93	5.74	mA
		125	TBD	TBD	3.93	4.63	5.97	7.38	mA
VLPS and LPIT	• Clock source: SIRC • 1 channel enable • Mode: 32-bit periodic counter	25	TBD	TBD	100	100	120	130	µA
		85	TBD	TBD	190	250	260	320	µA
		105	TBD	TBD	310	410	440	570	µA
		125	TBD	TBD	640	750	910	1280	µA

The following table shows the power consumption targets for S32K148 in various mode of operations measure at 3.3 V.

Table 9. Power consumption at 3.3 V

Chip/Device	Ambient Temperature (°C)		RUN@80 MHz (mA)		HSRUN@112 MHz (mA)[1]	
			Peripherals enabled + QSPI	Peripherals enabled + ENET + SAI	Peripherals enabled + QSPI	Peripherals enabled + ENET + SAI
S32K148	25	Typ	67.3	79.1	89.8	105.5
	85	Typ	67.4	79.2	95.6	105.9
		Max	82.5	88.2	109.7	117.4
	105	Typ	68.0	79.8	96.6	106.7
		Max	80.3	89.1	109.0	119.0
	125	Max	83.5	94.7	NA	

1. HSRUN mode must not be used at 125°C. Max ambient temperature for HSRUN mode is 105°C.

4.8 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
V_{HBM}	Electrostatic discharge voltage, human body model	– 4000	4000	V	1
V_{CDM}	Electrostatic discharge voltage, charged-device model				2
	All pins except the corner pins	– 500	500	V	
	Corner pins only	– 750	750	V	
I_{LAT}	Latch-up current at ambient temperature of 125 °C	– 100	100	mA	3

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.
3. Determined according to JEDEC Standard JESD78, *IC Latch-Up Test*.

4.9 EMC radiated emissions operating behaviors

EMC measurements to IC-level IEC standards are available from NXP on request.

Table 17. External System Oscillator electrical specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
	High-gain mode (HGO=1)	—	1	—	MΩ	
R_S	Series resistor					
	Low-gain mode (HGO=0)	—	0	—	kΩ	
	High-gain mode (HGO=1)	—	0	—	kΩ	
V_{pp}	Peak-to-peak amplitude of oscillation (oscillator mode)					3
	Low-gain mode (HGO=0)	—	1.0	—	V	
	High-gain mode (HGO=1)	—	3.3	—	V	

1. Crystal oscillator circuit provides stable oscillations when g_{mXOSC} > 5 * gm_crit. The gm_crit is defined as:

   gm_crit = 4 * ESR * $(2\pi F)^2$ * $(C_0 + C_L)^2$

   where:

   - g_{mXOSC} is the transconductance of the internal oscillator circuit
   - ESR is the equivalent series resistance of the external crystal
   - F is the external crystal oscillation frequency
   - C_0 is the shunt capacitance of the external crystal
   - C_L is the external crystal total load capacitance. $C_L = C_s + [C_1 * C_2/(C_1+C_2)]$
   - C_s is stray or parasitic capacitance on the pin due to any PCB traces
   - C_1, C_2 external load capacitances on EXTAL and XTAL pins

   See manufacture datasheet for external crystal component values
2. - When low-gain is selected, internal R_F will be selected and external R_F should not be attached.
   - When high-gain is selected, external R_F (1 M Ohm) needs to be connected for proper operation of the crystal. For external resistor, up to 5% tolerance is allowed.
3. The EXTAL and XTAL pins should only be connected to required oscillator components and must not be connected to any other devices.

6.2.2 External System Oscillator frequency specifications

6.3.1.1 Flash timing specifications — commands

Table 23. Flash command timing specifications for S32K14x

Symbol	Description[1]		S32K142		S32K144		S32K146		S32K148			
			Typ	Max	Typ	Max	Typ	Max	Typ	Max	Unit	Notes
t_{rd1blk}	Read 1 Block execution time	32 KB flash	—	—	—	—	—	—	—	—	ms	
		64 KB flash	—	0.5	—	0.5	—	0.5	—	—		
		128 KB flash	—	—	—	—	—	—	—	—		
		256 KB flash	—	2	—	—	—	—	—	—		
		512 KB flash	—	—	—	1.8	—	2	—	2		
t_{rd1sec}	Read 1 Section execution time	2 KB flash	—	75	—	75	—	75	—	75	µs	
		4 KB flash	—	100	—	100	—	100	—	100		
t_{pgmchk}	Program Check execution time	—	—	95	—	95	—	95	—	100	µs	
t_{pgm8}	Program Phrase execution time	—	90	225	90	225	90	225	90	225	µs	
t_{ersblk}	Erase Flash Block execution time	32 KB flash	—	—	—	—	—	—	—	—	ms	2
		64 KB flash	30	550	30	550	30	550	—	—		
		128 KB flash	—	—	—	—	—	—	—	—		
		256 KB flash	250	2125	—	—	—	—	—	—		
		512 KB flash	—	—	250	4250	250	4250	250	4250		
t_{ersscr}	Erase Flash Sector execution time	—	12	130	12	130	12	130	12	130	ms	2
$t_{pgmsec1k}$	Program Section execution time (1KB flash)	—	5	—	5	—	5	—	5	—	ms	
t_{rd1all}	Read 1s All Block execution time	—	—	2.8	—	2.3	—	5.2	—	8.2	ms	
t_{rdonce}	Read Once execution time	—	—	30	—	30	—	30	—	30	µs	
$t_{pgmonce}$	Program Once execution time	—	90	—	90	—	90	—	90	—	µs	
t_{ersall}	Erase All Blocks execution time	—	250	2800	400	4900	700	10000	1400	17000	ms	2
t_{vfykey}	Verify Backdoor Access Key execution time	—	—	35	—	35	—	35	—	35	µs	
$t_{ersallu}$	Erase All Blocks Unsecure execution time	—	250	2800	400	4900	700	10000	1400	17000	ms	2
$t_{pgmpart}$	Program Partition for EEPROM execution time	32 KB EEPROM backup	70	—	70	—	70	—	—	—	ms	3
		64 KB EEPROM backup	71	—	71	—	71	—	150	—		

Table continues on the next page...

Table 23. Flash command timing specifications for S32K14x (continued)

Symbol	Description[1]		S32K142		S32K144		S32K146		S32K148			
			Typ	Max	Typ	Max	Typ	Max	Typ	Max	Unit	Notes
	setting (32-bit write complete, ready for next 32-bit write)	Last (Nth) 32-bit write (time for write only, not cleanup)	200	550	200	550	200	550	200	550		
$t_{quickwrClnup}$	Quick Write Cleanup execution time	—	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	ms	7

1. All command times assumes 25 MHz or greater flash clock frequency (for synchronization time between internal/external clocks).
2. Maximum times for erase parameters based on expectations at cycling end-of-life.
3. For all EEPROM Emulation terms, the specified timing shown assumes previous record cleanup has occurred. This may be verified by executing FCCOB Command 0x77, and checking FCCOB number 5 contents show 0x00 - No EEPROM issues detected.
4. 1st time EERAM writes after a Reset or SETRAM may incur additional overhead for EEE cleanup, resulting in up to 2× the times shown.
5. Only after the Nth write completes will any data be valid. Emulated EEPROM record scheme cleanup overhead may occur after this point even after a brownout or reset. If power on reset occurs before the Nth write completes, the last valid record set will still be valid and the new records will be discarded.
6. Quick Write times may take up to 550 µs, as additional cleanup may occur when crossing sector boundaries.
7. Time for emulated EEPROM record scheme overhead cleanup. Automatically done after last (Nth) write completes, assuming still powered. Or via SETRAM cleanup execution command is requested at a later point.

Table 24. Flash command timing specifications for S32K11x

Symbol	Description[1]		S32K116		S32K118			
			Typ	Max	Typ	Max	Unit	Notes
t_{rd1blk}	Read 1 Block execution time	32 KB flash	—	0.36	—	0.36	ms	
		64 KB flash	—	—	—	—		
		128 KB flash	—	1.2	—	—		
		256 KB flash	—	—	—	2		
		512 KB flash	—	—	—	—		
t_{rd1sec}	Read 1 Section execution time	2 KB flash	—	75	—	75	µs	
		4 KB flash	—	100	—	100		
t_{pgmchk}	Program Check execution time	—	—	100	—	100	µs	
t_{pgm8}	Program Phrase execution time	—	90	225	90	225	µs	
t_{ersblk}	Erase Flash Block execution time	32 KB flash	15	300	15	300	ms	2
		64 KB flash	—	—	—	—		
		128 KB flash	120	1100	—	—		
		256 KB flash	—	—	250	2125		
		512 KB flash	—	—	—	—		

Table continues on the next page...

Table 24. Flash command timing specifications for S32K11x (continued)

Symbol	Description[1]		S32K116		S32K118			
			Typ	Max	Typ	Max	Unit	Notes
t_{ersscr}	Erase Flash Sector execution time	—	12	130	12	130	ms	2
$t_{pgmsec1k}$	Program Section execution time (1 KB flash)	—	5	—	5	—	ms	
t_{rd1all}	Read 1s All Block execution time	—	—	1.7	—	2.8	ms	
t_{rdonce}	Read Once execution time	—	—	30	—	30	µs	
$t_{pgmonce}$	Program Once execution time	—	90	—	90	—	µs	
t_{ersall}	Erase All Blocks execution time	—	150	1500	230	2500	ms	2
t_{vfykey}	Verify Backdoor Access Key execution time	—	—	35	—	35	µs	
$t_{ersallu}$	Erase All Blocks Unsecure execution time	—	150	1500	230	2500	ms	2
$t_{pgmpart}$	Program Partition for EEPROM execution time	32 KB EEPROM backup	71	—	71	—	ms	3
		64 KB EEPROM backup	—	—	—	—		
t_{setram}	Set FlexRAM Function execution time	Control Code 0xFF	0.08	—	0.08	—	ms	3
		32 KB EEPROM backup	0.8	1.2	0.8	1.2		
		48 KB EEPROM backup	—	—	—	—		
		64 KB EEPROM backup	—	—	—	—		
t_{eewr8b}	Byte write to FlexRAM execution time	32 KB EEPROM backup	385	1700	385	1700	µs	3,4
		48 KB EEPROM backup	—	—	—	—		
		64 KB EEPROM backup	—	—	—	—		
$t_{eewr16b}$	16-bit write to FlexRAM execution time	32 KB EEPROM backup	385	1700	385	1700	µs	3,4
		48 KB EEPROM backup	—	—	—	—		
		64 KB EEPROM backup	—	—	—	—		
$t_{eewr32bers}$	32-bit write to erased FlexRAM location execution time	—	360	2000	360	2000	µs	

Table continues on the next page...

Table 26. QuadSPI electrical specifications

FLASH PORT	Sym	Unit	FLASH A												FLASH B			
			RUN[1]						HSRUN[1]						RUN/HSRUN[2]			
QuadSPI Mode			SDR						SDR						SDR		DDR[3]	
			Internal Sampling		Internal DQS				Internal Sampling		Internal DQS				Internal Sampling		External DQS	
			N1		PAD Loopback		Internal Loopback		N1		PAD Loopback		Internal Loopback		N1		External DQS	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max
Register Settings																		
MCR[DDR_EN]		-	0		0		0		0		0		0		0		1	
MCR[DQS_EN]		-	0		1		1		0		1		1		0		1	
MCR[SCLKCFG[0]]		-	-		1		0		-		1		0		-		-	
MCR[SCLKCFG[1]]		-	-		1		0		-		1		0		-		-	
MCR[SCLKCFG[2]]		-	-		-		-		-		-		-		-		0	
MCR[SCLKCFG[3]]		-	-		-		-		-		-		-		-		0	
MCR[SCLKCFG[5]]		-	0		0		0		0		0		0		0		1	
SMPR[FSPHS]		-	0		1		0		0		1		0		0		0	
SMPR[FSDLY]		-	0		0		0		0		0		0		0		0	
SOCCR [SOCCFG[7:0]]			-		0		23		-		0		30		-		-	
SOCCR[SOCCFG[15:8]]		-	-		-		-		-		-		-		-		30	
FLSHCR[TDH]		-	0x00		0x00		0x00		0x00		0x00		0x00		0x00		0x01	
Timing Parameters																		
SCK Clock Frequency	f_{SCK}	MHz	-	38	-	64	-	48	-	40	-	80	-	50	-	20	-	20[4]
SCK Clock Period	t_{SCK}	ns	1/fSCK	-	1/fSCK	-	1/fSCK	-	1/fSCK	-	1/fSCK	-	1/fSCK	-	50.0	-	50.0[4]	-

Table continues on the next page...

Table 26. QuadSPI electrical specifications (continued)

FLASH PORT	Sym	Unit	FLASH A												FLASH B			
			RUN[1]						HSRUN[1]						RUN/HSRUN[2]			
QuadSPI Mode			SDR						SDR						SDR		DDR[3]	
			Internal Sampling		Internal DQS				Internal Sampling		Internal DQS				Internal Sampling		External DQS	
			N1		PAD Loopback		Internal Loopback		N1		PAD Loopback		Internal Loopback		N1		External DQS	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max
SCK Duty Cycle	t_{SDC}	ns	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 0.750	tSCK/2 - 0.750	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 2.5	tSCK/2 + 2.5	tSCK/2 - 2.5	tSCK/2 + 2.5
Data Input Setup Time	t_{IS}	ns	15	-	2.5	-	10	-	14	-	1.6	-	9	-	25	-	2	-
Data Input Hold Time	t_{IH}	ns	0	-	1	-	1	-	0	-	1	-	1	-	0	-	20	-
Data Output Valid Time	t_{OV}	ns	-	4.5	-	4.5	-	4.5	-	4	-	4	-	4	-	10	-	10
Data Output In-Valid Time	t_{IV}	ns	-	5	-	5	-	5	-	5	-	3[5]	-	5	-	5	5	-
CS to SCK Time [6]	t_{CSSCK}	ns	5	-	5	-	5	-	5	-	5	-	5	-	10	-	10	-
SCK to CS Time [7]	t_{SCKCS}	ns	5	-	5	-	5	-	5	-	5	-	5	-	5	-	5	-
Output Load		pf	25		25		25		25		25		25		25		25	

1. See Reference Manual for details on mode settings
2. See Reference Manual for details on mode settings
3. Valid for HyperRAM only
4. RWDS(External DQS CLK) frequency
5. For operating frequency ≤ 64 Mhz,Output invalid time is 5 ns.
6. Program register value QuadSPI_FLSHCR[TCSS] = 4`h2
7. Program register value QuadSPI_FLSHCR[TCSH] = 4`h1

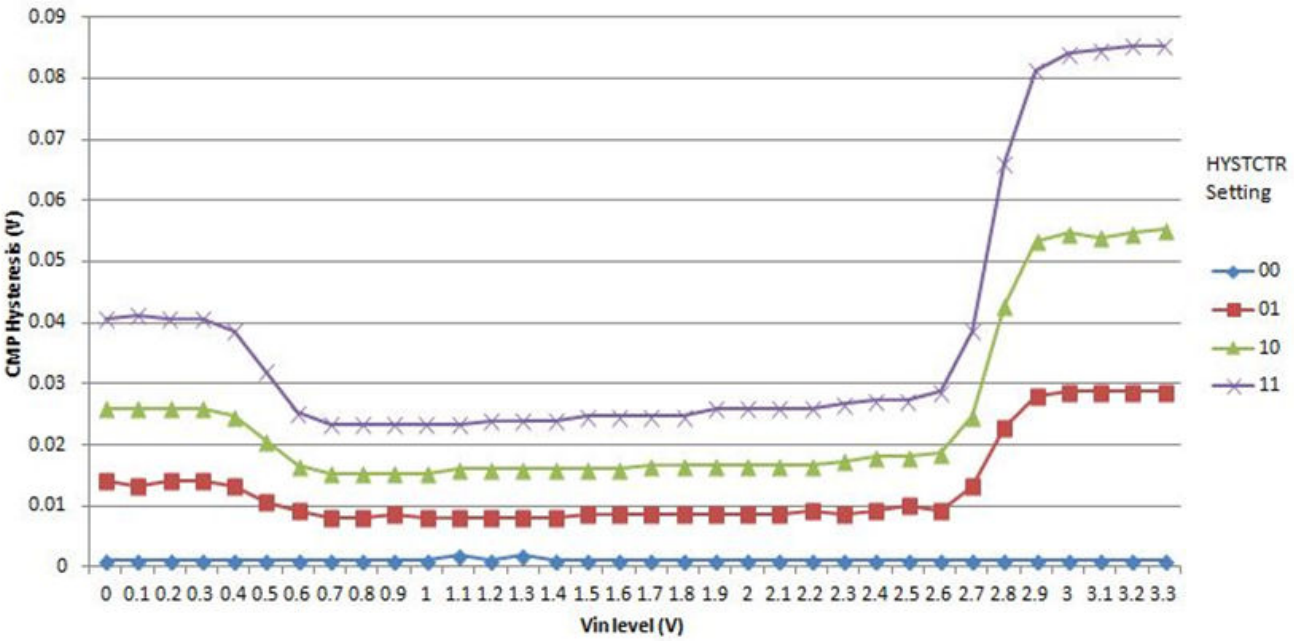


Figure 14. Typical hysteresis vs. Vin level (VDDA = 3.3 V, PMODE = 0)

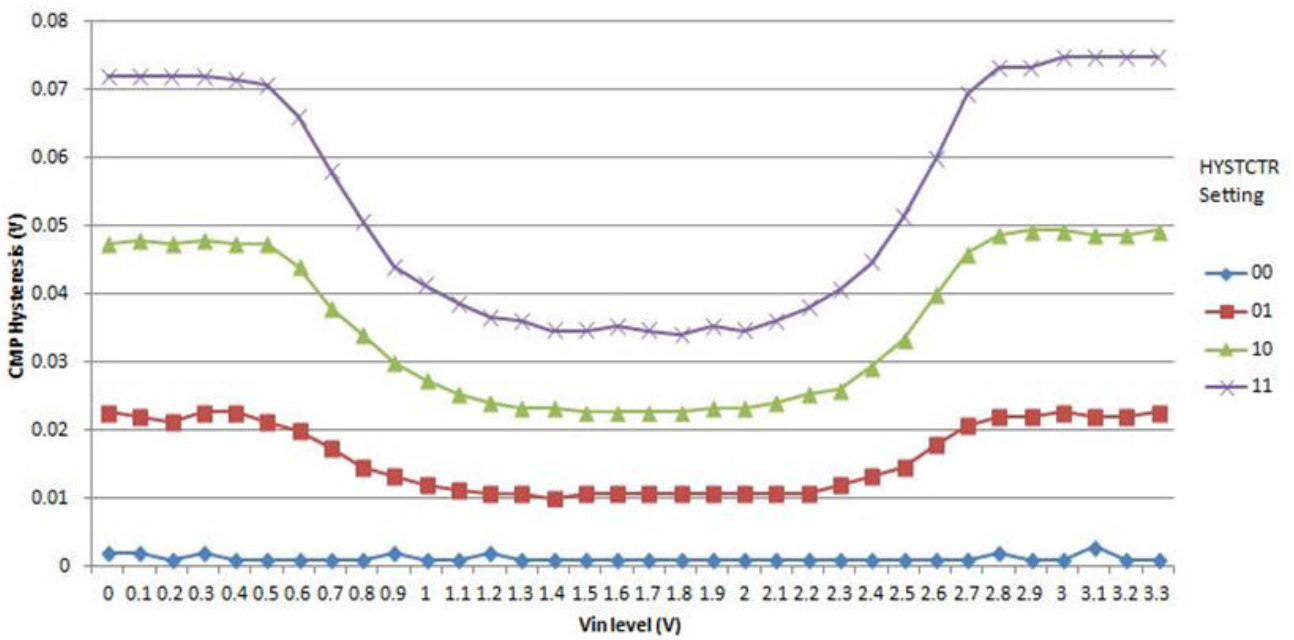


Figure 15. Typical hysteresis vs. Vin level (VDDA = 3.3 V, PMODE = 1)

Table 32. LPSPI electrical specifications[1] (continued)

Num	Symbol	Description	Conditions	Run Mode[2]				HSRUN Mode[2]				VLPR Mode				Unit
				5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		
				Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
8	t_a	Slave access time	Slave	-	50	-	50	-	50	-	50	-	100	-	100	ns
9	t_{dis}	Slave MISO (SOUT) disable time	Slave	-	50	-	50	-	50	-	50	-	100	-	100	ns
10	t_v	Data valid (after SPSCK edge)	Slave	-	30	-	39	-	26	-	36 [11] 31 [12]	-	92	-	96	ns
			Master	-	12	-	16	-	11	-	15	-	47	-	48	
			Master Loopback[5]	-	12	-	16	-	11	-	15	-	47	-	48	
			Master Loopback(slow)[6]	-	8	-	10	-	7	-	9	-	44	-	44	
11	t_{HO}	Data hold time(outputs)	Slave	4	-	4	-	4	-	4	-	4	-	4	-	ns
			Master	-15	-	-22	-	-15	-	-23	-	-22	-	-29	-	
			Master Loopback[5]	-10	-	-14	-	-10	-	-14	-	-14	-	-19	-	
			Master Loopback(slow)[6]	-15	-	-22	-	-15	-	-22	-	-21	-	-27	-	
12	$t_{RI/FI}$	Rise/Fall time input	Slave	-	1	-	1	-	1	-	1	-	1	-	1	ns
			Master	-		-		-		-		-		-		
			Master Loopback[5]	-		-		-		-		-		-		
			Master Loopback(slow)[6]	-		-		-		-		-		-		
13	$t_{RO/FO}$	Rise/Fall time output	Slave	-	25	-	25	-	25	-	25	-	25	-	25	ns
			Master	-		-		-		-		-		-		
			Master Loopback [5]	-		-		-		-		-		-		

Table continues on the next page...

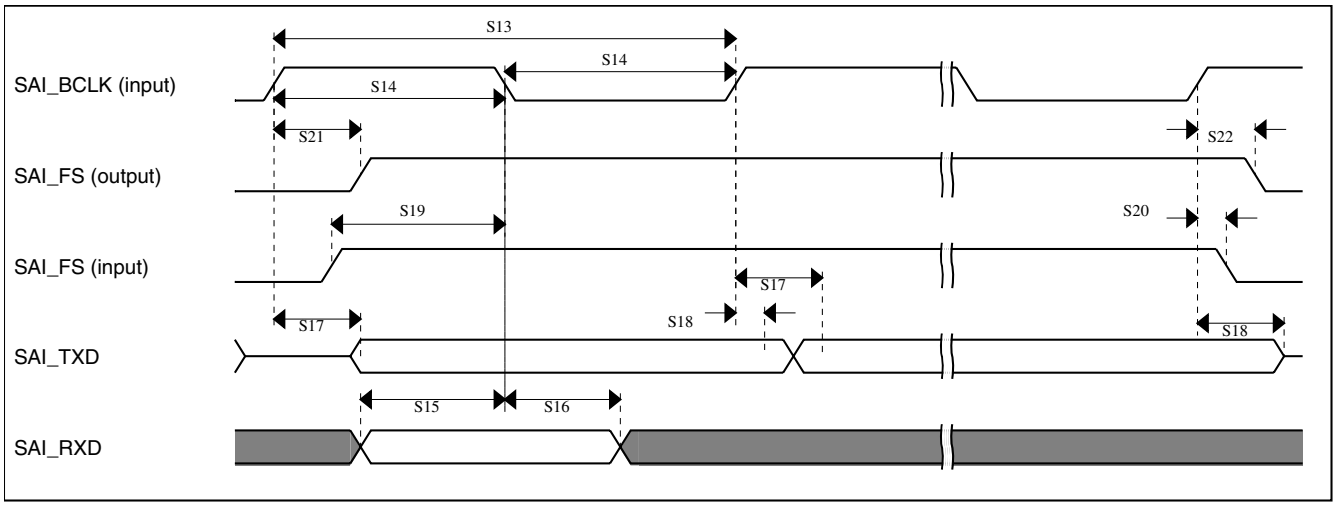


Figure 23. SAI Timing — Slave modes

6.5.6 Ethernet AC specifications

The following timing specs are defined at the chip I/O pin and must be translated appropriately to arrive at timing specs/constraints for the physical interface.

The following table describes the MII electrical characteristics.

- Measurements are with maximum output load of 25 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.

Table 35. MII signal switching specifications

Symbol	Description	Min.	Max.	Unit
—	RXCLK frequency	—	25	MHz
MII1	RXCLK pulse width high	35%	65%	RXCLK period
MII2	RXCLK pulse width low	35%	65%	RXCLK period
MII3	RXD[3:0], RXDV, RXER to RXCLK setup	5	—	ns
MII4	RXCLK to RXD[3:0], RXDV, RXER hold	5	—	ns
—	TXCLK frequency	—	25	MHz
MII5	TXCLK pulse width high	35%	65%	TXCLK period
MII6	TXCLK pulse width low	35%	65%	TXCLK period
MII7	TXCLK to TXD[3:0], TXEN, TXER invalid	2	—	ns
MII8	TXCLK to TXD[3:0], TXEN, TXER valid	—	25	ns

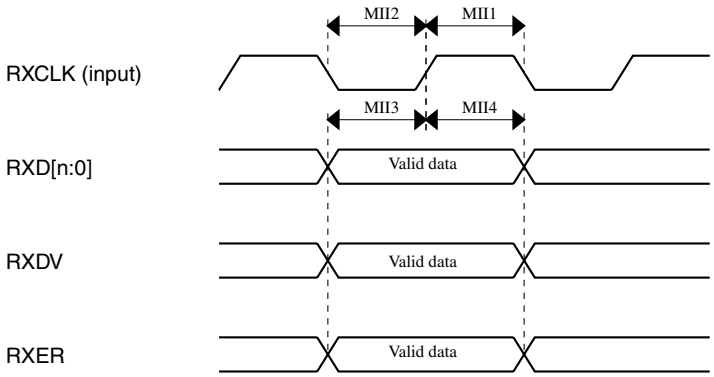


Figure 24. MII receive diagram

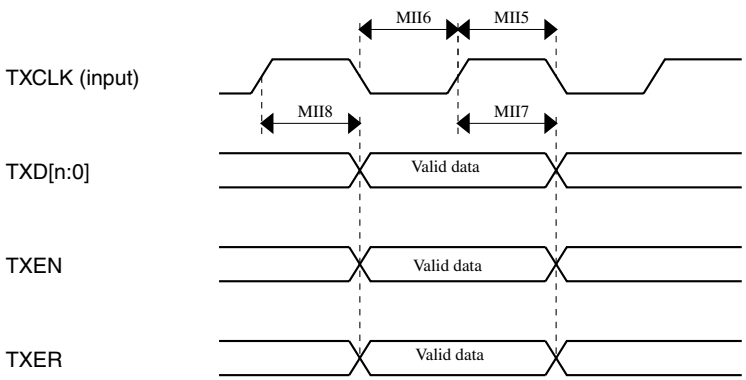


Figure 25. MII transmit signal diagram

The following table describes the RMII electrical characteristics.

- Measurements are with maximum output load of 25 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.

Table 36. RMII signal switching specifications

Symbol	Description	Min.	Max.	Unit
—	RMII input clock RMII_CLK Frequency	—	50	MHz
RMII1, RMII5	RMII_CLK pulse width high	35%	65%	RMII_CLK period
RMII2, RMII6	RMII_CLK pulse width low	35%	65%	RMII_CLK period
RMII3	RXD[1:0], CRS_DV, RXER to RMII_CLK setup	4	—	ns
RMII4	RMII_CLK to RXD[1:0], CRS_DV, RXER hold	2	—	ns

Table continues on the next page...

Table 36. RMII signal switching specifications (continued)

Symbol	Description	Min.	Max.	Unit
RMII7	RMII_CLK to TXD[1:0], TXEN invalid	2	—	ns
RMII8	RMII_CLK to TXD[1:0], TXEN valid	—	15	ns

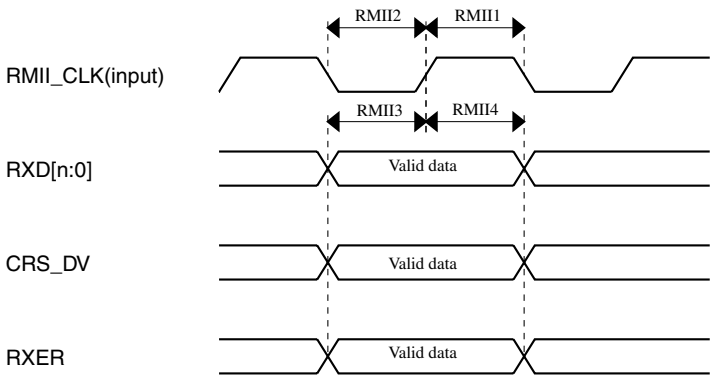


Figure 26. RMII receive diagram

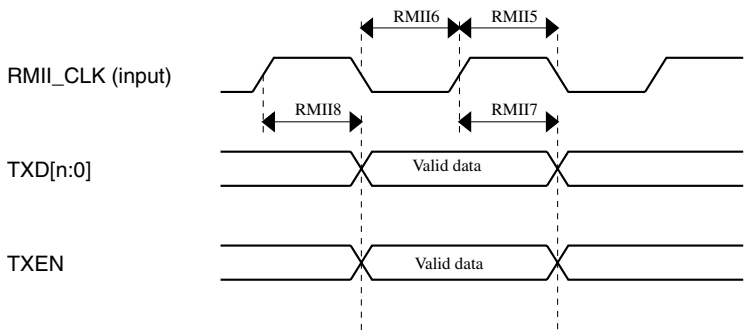


Figure 27. RMII transmit diagram

The following table describes the MDIO electrical characteristics.

- Measurements are with maximum output load of 25 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.
- MDIO pin must have external Pull-up.

Table 37. MDIO timing specifications

Symbol	Description	Min.	Max.	Unit
—	MDC Clock Frequency	—	2.5	MHz

Table continues on the next page...

Table 38. SWD electrical specifications

Symbol	Description	Run Mode				HSRUN Mode				VLPR Mode				Unit
		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
S1	SWD_CLK frequency of operation	-	25	-	25	-	25	-	25	-	10	-	10	MHz
S2	SWD_CLK cycle period	1/S1	-	1/S1	-	1/S1	-	1/S1	-	1/S1	-	1/S1	-	ns
S3	SWD_CLK clock pulse width	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	ns
S4	SWD_CLK rise and fall times	-	1	-	1	-	1	-	1	-	1	-	1	ns
S9	SWD_DIO input data setup time to SWD_CLK rise	4	-	4	-	4	-	4	-	16	-	16	-	ns
S10	SWD_DIO input data hold time after SWD_CLK rise	3	-	3	-	3	-	3	-	10	-	10	-	ns
S11	SWD_CLK high to SWD_DIO data valid	-	28	-	38	-	28	-	38	-	70	-	77	ns
S12	SWD_CLK high to SWD_DIO high-Z	-	28	-	38	-	28	-	38	-	70	-	77	ns
S13	SWD_CLK high to SWD_DIO data invalid	0	-	0	-	0	-	0	-	0	-	0	-	ns

Table 39. Trace specifications (continued)

	Symbol	Description	RUN Mode			HSRUN Mode		VLPR Mode	Unit
Trace on fast pads	f_{TRACE}	Max Trace frequency	80	48	40	74.667	80	4	MHz
	t_{DVO}	Data Output Valid	4	4	4	4	4	20	ns
	t_{DIV}	Data Output Invalid	-2	-2	-2	-2	-2	-10	ns
Trace on slow pads	f_{TRACE}	Max Trace frequency	22.86	24	20	22.4	22.86	4	MHz
	t_{DVO}	Data Output Valid	8	8	8	8	8	20	ns
	t_{DIV}	Data Output Invalid	-4	-4	-4	-4	-4	-10	ns

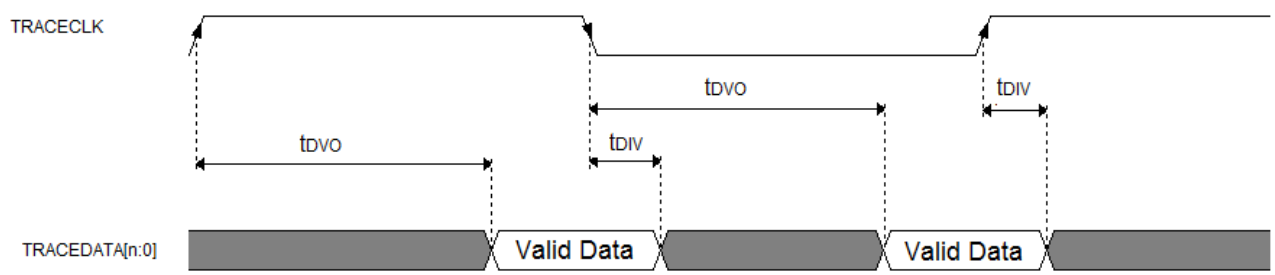


Figure 31. TRACE CLKOUT specifications

6.6.3 JTAG electrical specifications

Table 43. Revision History (continued)

Rev. No.	Date	Substantial Changes
		• Updated values for V_{REFH} and V_{REFL} to add refernce to the section "voltage and current operating requirments" for Min and Max valaues • Updated footnote to Typ. • Removed footnote from RAS Analog source resistance • Updated figure: ADC input impedance equivalency diagram • In table: 12-bit ADC characteristics (2.7 V to 3 V) (V_{REFH} = V_{DDA}, V_{REFL} = V_{SS}) • Removed rows for V_{TEMP_S} and V_{TEMP25} • Updated footnote to Typ. • In table: 12-bit ADC characteristics (3 V to 5.5 V)(V_{REFH} = V_{DDA}, V_{REFL} = V_{SS}) • Removed rows for V_{TEMP_S} and V_{TEMP25} • Removed number for TUE • Updated footnote to Typ. • In table: Comparator with 8-bit DAC electrical specifications • Updated Typ. of I_{DDLS} Supply current, Low-speed mode • Updated Typ. of t_{DLSB} Propagation delay, Low-speed mode • Updated Typ. of t_{DHSS} Propagation delay, High-speed mode • Updated t_{DLSS} Propagation delay • Added row for t_{DDAC} Initialization and switching settling time • Updated footnote • Updated section LPSPI electrical specifications • Added section: SAI electrical specifications • Updated section: Ethernet AC specifications • Added section: Clockout frequency • Added section: Trace electrical specifications • Updated table: Table 41 : Updated numbers for S32K142 and S32K148 • Updated table: Table 42 : Updated numbers for S32K148 • Updated Document number for 32-pin QFN in topic Obtaining package dimensions
3	14 March 2017	• In Table 2 • Updated min. value of V_{DD_OFF} • Added parameter I_{INJSUM_AF} • Updated Power mode transition operating behaviors • Updated Power consumption • Updated footnote to T_{SPLL_LOCK} in SPLL electrical specifications • In 12-bit ADC electrical characteristics • Updated table: 12-bit ADC characteristics (2.7 V to 3 V) (VREFH = VDDA, VREFL = VSS) • Added typ. value to I_{DDA_ADC}, TUE, DNL, and INL • Added min. value to SMPLTS • Removed footnote 'All the parameters in this table ... ' • Updated table: 12-bit ADC characteristics (3 V to 5.5 V) (VREFH = VDDA, VREFL = VSS) • Added typ. value to I_{DDA_ADC} • Removed footnote 'All the parameters in this table ... ' • In Flash timing specifications — commands updated Max. value of t_{vfykey} to 33 µs
4	02 June 2017	• In section: Block diagram, added block diagram for S32K11x series. • Updated figure: S32K1xx product series comparison. • In section: Selecting orderable part number , added reference to attachement *S32K_Part_Numbers.xlsx*. • In section: Ordering information • Updated figure: Ordering information. • In Table 1,

Table continues on the next page...

Table 43. Revision History

Rev. No.	Date	Substantial Changes
		• Updated specs for T_{JIT} Cycle-to-Cycle jitter to 300 ps • In QuadSPI AC specifications : • Updated specs for T_{iv} Data Output In-Valid Time • In figure 'QuadSPI output timing (SDR mode) diagram', marked Invalid area • In CMP with 8-bit DAC electrical specifications : • Removed '(VAIO)' from decription of V_{HYST0} • In LPSPI electrical specifications : • Added note 'Undefined' in figures 'LPSPI slave mode timing (CPHA = 0)' and 'LPSPI slave mode timing (CPHA = 1)'

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