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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M4F
Core Size	32-Bit Single-Core
Speed	64MHz
Connectivity	CANbus, FlexIO, I²C, LINbus, SPI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	58
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x12b SAR; D/A1x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/fs32k144mst0mlht

- Communications interfaces
  - Up to three Low Power Universal Asynchronous Receiver/Transmitter (LPUART/LIN) modules with DMA support and low power availability
  - Up to three Low Power Serial Peripheral Interface (LPSPI) modules with DMA support and low power availability
  - Up to two Low Power Inter-Integrated Circuit (LPI2C) modules with DMA support and low power availability
  - Up to three FlexCAN modules (with optional CAN-FD support)
  - FlexIO module for emulation of communication protocols and peripherals (UART, I2C, SPI, I2S, LIN, PWM, etc).
  - Up to one 10/100Mbps Ethernet with IEEE1588 support and two Synchronous Audio Interface (SAI) modules.
- Safety and Security
  - Cryptographic Services Engine (CSEc) implements a comprehensive set of cryptographic functions as described in the SHE (Secure Hardware Extension) Functional Specification. Note: CSEc (Security) or EEPROM writes/erase will trigger error flags in HSRUN mode (112 MHz) because this use case is not allowed to execute simultaneously. The device will need to switch to RUN mode (80 MHz) to execute CSEc (Security) or EEPROM writes/erase.
  - 128-bit Unique Identification (ID) number
  - Error-Correcting Code (ECC) on flash and SRAM memories
  - System Memory Protection Unit (System MPU)
  - Cyclic Redundancy Check (CRC) module
  - Internal watchdog (WDOG)
  - External Watchdog monitor (EWM) module
- Timing and control
  - Up to eight independent 16-bit FlexTimers (FTM) modules, offering up to 64 standard channels (IC/OC/PWM)
  - One 16-bit Low Power Timer (LPTMR) with flexible wake up control
  - Two Programmable Delay Blocks (PDB) with flexible trigger system
  - One 32-bit Low Power Interrupt Timer (LPIT) with 4 channels
  - 32-bit Real Time Counter (RTC)
- Package
  - 32-pin QFN, 48-pin LQFP, 64-pin LQFP, 100-pin LQFP, 100-pin MAPBGA, 144-pin LQFP, 176-pin LQFP package options
- 16 channel DMA with up to 63 request sources using DMAMUX

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Description Input Multiplexing sheet(s) attached with Reference Manual.

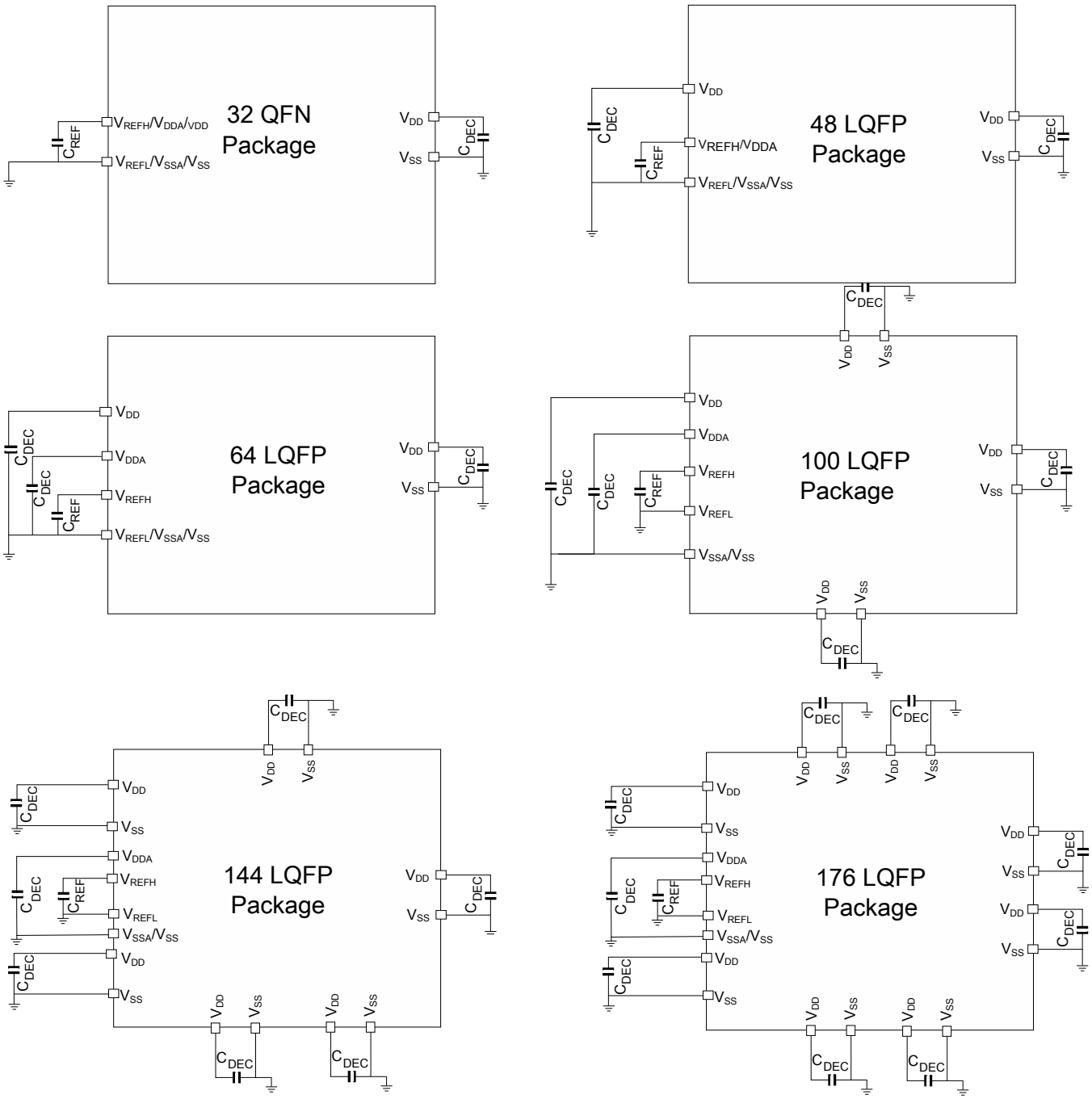
		S32K11x		S32K14x			
	Parameter	K116	K118	K142	K144	K146	K148
	Core	Arm® Cortex™-M0+		Arm® Cortex™-M4F			
	Frequency	48 MHz		80 MHz (RUN mode) or 112 MHz (HSRUN mode)[1]			
System	IEEE-754 FPU	○		●			
System	Cryptographic Services Engine (CSEc)[1]	●		●			
System	CRC module	1x		1x			
System	ISO 26262	capable up to ASIL-B		capable up to ASIL-B			
System	Peripheral speed	up to 48 MHz		up to 112 MHz (HSRUN)			
System	Crossbar	●		●			
System	DMA	●		●			
System	External Watchdog Monitor (EWM)	○		●			
System	Memory Protection Unit (MPU)	●		●			
System	FIRC CMU	●		○			
System	Watchdog	1x		1x			
System	Low power modes	●		●			
System	HSRUN mode[1]	○		●			
System	Number of I/Os	up to 43	up to 58	up to 89		up to 128	up to 156
System	Single supply voltage	2.7 - 5.5 V		2.7 - 5.5 V			
System	Ambient Operation Temperature (T_A)	-40ºC to +105ºC / +125ºC		-40ºC to +105ºC / +125ºC			
Memory	Flash	128 KB	256 KB	256 KB	512 KB	1 MB	2 MB[2]
Memory	Error Correcting Code (ECC)	●		●			
Memory	System RAM (including FlexRAM and MTB)	17 KB	25 KB	32 KB	64 KB	128 KB	256 KB
Memory	FlexRAM (also available as system RAM)	2 KB		4 KB			
Memory	Cache	○		4 KB			
Memory	EEPROM emulated by FlexRAM[1]	2 KB (up to 32 KB D-Flash)		4 KB (up to 64 KB D-Flash)			See footnote 3
Memory	External memory interface	○		○			QuadSPI incl. HyperBus™
Timer	Low Power Interrupt Timer (LPIT)	1x		1x			
Timer	FlexTimer (16-bit counter) 8 channels	2x (16)		4x (32)		6x (48)	8x (64)
Timer	Low Power Timer (LPTMR)	1x		1x			
Timer	Real Time Counter (RTC)	1x		1x			
Timer	Programmable Delay Block (PDB)	1x		2x			
Analog	Trigger mux (TRGMUX)	1x (43)	1x (45)	1x (64)		1x (73)	1x (81)
Analog	12-bit SAR ADC (1 Msps each)	1x (13)	1x (16)	2x (16)		2x (24)	2x (32)
Analog	Comparator with 8-bit DAC	1x		1x			
Communication	10/100 Mbps IEEE-1588 Ethernet MAC	○		○			1x
Communication	Serial Audio Interface (AC97, TDM, I2S)	○		○			2x
Communication	Low Power UART/LIN (LPUART) (Supports LIN protocol versions 1.3, 2.0, 2.1, 2.2A, and SAE J2602)	2x		2x	3x		
Communication	Low Power SPI (LPSPI)	1x	2x	2x	3x		
Communication	Low Power I2C (LPI2C)	1x		1x			2x
Communication	FlexCAN (CAN-FD ISO/CD 11898-1)	1x (1x with FD)		2x (1x with FD)	3x (1x with FD)	3x (2x with FD)	3x (3x with FD)
Communication	FlexIO (8 pins configurable as UART, SPI, I2C, I2S)	1x		1x			
IDEs	Debug & trace	SWD, MTB (1 KB), JTAG[4]		SWD, JTAG (ITM, SWV, SWO)			SWD, JTAG (ITM, SWV, SWO), ETM
IDEs	Ecosystem (IDE, compiler, debugger)	NXP S32 Design Studio (GCC) + SDK, IAR, GHS, Arm®, Lauterbach, iSystems		NXP S32 Design Studio (GCC) + SDK, IAR, GHS, Arm®, Lauterbach, iSystems			
Other	Packages[5]	32-pin QFN 48-pin LQFP	48-pin LQFP 64-pin LQFP	64-pin LQFP 100-pin LQFP	64-pin LQFP 100-pin LQFP 100-pin MAPBGA	64-pin LQFP 100-pin MAPBGA 100-pin LQFP 144-pin LQFP	100-pin MAPBGA 144-pin LQFP 176-pin LQFP

LEGEND:
- ○ Not implemented
- ● Available on the device

1 No write or erase access to Flash module, including Security (CSEc) and EEPROM commands, are allowed when device is running at HSRUN mode (112MHz) or VLPR mode.
2 Available when EEEPROM, CSEc and Data Flash are not used. Else only up to 1,984 KB is available for Program Flash.
3 4 KB (up to 512 KB D-Flash as a part of 2 MB Flash). Up to 64 KB of flash is used as EEPROM backup and the remaining 448 KB of the last 512 KB block can be used as Data flash or Program flash. See chapter FTFC for details.
4 Only for Boundary Scan Register
5 See Dimensions section for package drawings

Figure 3. S32K1xx product series comparison

4.4 Power and ground pins



NOTE: V_{DD} and V_{DDA} must be shorted to a common source on PCB

Figure 5. Pinout decoupling

Table 4. Supplies decoupling capacitors 1, 2

Symbol	Description	Min. 3	Typ.	Max.	Unit
C_{REF}, 4, 5	ADC reference high decoupling capacitance	70	100	—	nF
C_{DEC} 5, 6, 7	Recommended decoupling capacitance	70	100	—	nF

1. V_{DD} and V_{DDA} must be shorted to a common source on PCB. The differential voltage between V_{DD} and V_{DDA} is for RF-AC only. Appropriate decoupling capacitors to be used to filter noise on the supplies. See application note AN5032 for reference supply design for SAR ADC. All V_{SS} pins should be connected to common ground at the PCB level.
2. All decoupling capacitors must be low ESR ceramic capacitors (for example X7R type).
3. Minimum recommendation is after considering component aging and tolerance.
4. For improved performance, it is recommended to use 10 µF, 0.1 µF and 1 nF capacitors in parallel.
5. All decoupling capacitors should be placed as close as possible to the corresponding supply and ground pins.
6. Contact your local Field Applications Engineer for details on best analog routing practices.
7. The filtering used for decoupling the device supplies must comply with the following best practices rules:
   - The protection/decoupling capacitors must be on the path of the trace connected to that component.
   - No trace exceeding 1 mm from the protection to the trace or to the ground.
   - The protection/decoupling capacitors must be as close as possible to the input pin of the device (maximum 2 mm).
   - The ground of the protection is connected as short as possible to the ground plane under the integrated circuit.

Table 6. Power mode transition operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit
	VLPS → RUN	8	—	17	µs
	STOP1 → RUN	0.07	0.075	0.08	µs
	STOP2 → RUN	0.07	0.075	0.08	µs
	VLPR → RUN	19	—	26	µs
	VLPR → VLPS	5.1	5.7	6.5	µs
	VLPS → VLPR	18.8	23	27.75	µs
	RUN → Compute operation	0.72	0.75	0.77	µs
	HSRUN → Compute operation	0.3	0.31	0.35	µs
	RUN → STOP1	0.35	0.38	0.4	µs
	RUN → STOP2	0.2	0.23	0.25	µs
	RUN → VLPS	0.3	0.35	0.4	µs
	RUN → VLPR	3.5	3.8	5	µs
	VLPS → Asynchronous DMA Wakeup	105	110	125	µs
	STOP1 → Asynchronous DMA Wakeup	1	1.1	1.3	µs
	STOP2 → Asynchronous DMA Wakeup	1	1.1	1.3	µs
	Pin reset → Code execution	—	214	—	µs

NOTE

HSRUN should only be used when frequencies in excess of 80 MHz are required. When using 80 MHz and below, RUN mode is the recommended operating mode.

4.7 Power consumption

The following table shows the power consumption targets for the device in various mode of operations. Attached *S32K1xx_Power_Modes _Configuration.xlsx* details the modes used in gathering the power consumption data stated in the following table Table 7. For full functionality refer to table: Module operation in available power modes of the *Reference Manual*.

5.3 DC electrical specifications at 3.3 V Range

NOTE

For details on the pad types defined in Table 11 and Table 12, see Reference Manual section *IO Signal Table* and IO Signal Description Input Multiplexing sheet(s) attached with Reference Manual.

Table 11. DC electrical specifications at 3.3 V Range

Symbol	Parameter	Value			Unit	Notes
		Min.	Typ.	Max.		
V_{DD}	I/O Supply Voltage	2.7	3.3	4	V	1
V_{ih}	Input Buffer High Voltage	0.7 × V_{DD}	—	V_{DD} + 0.3	V	2
V_{il}	Input Buffer Low Voltage	V_{SS} – 0.3	—	0.3 × V_{DD}	V	3
V_{hys}	Input Buffer Hysteresis	0.06 × V_{DD}	—	—	V	
Ioh_{GPIO} $Ioh_{GPIO\text{-}HD\_DSE\_0}$	I/O current source capability measured when pad V_{oh} = (V_{DD} – 0.8 V)	3.5	—	—	mA	
Iol_{GPIO} $Iol_{GPIO\text{-}HD\_DSE\_0}$	I/O current sink capability measured when pad V_{ol} = 0.8 V	3	—	—	mA	
$Ioh_{GPIO\text{-}HD\_DSE\_1}$	I/O current source capability measured when pad V_{oh} = (V_{DD} – 0.8 V)	14	—	—	mA	4
$Iol_{GPIO\text{-}HD\_DSE\_1}$	I/O current sink capability measured when pad V_{ol} = 0.8 V	12	—	—	mA	4
$Ioh_{GPIO\text{-}FAST\_DSE\_0}$	I/O current sink capability measured when pad V_{oh}=V_{DD}-0.8 V	9.5	—	—	mA	5
$Iol_{GPIO\text{-}FAST\_DSE\_0}$	I/O current sink capability measured when pad V_{ol} = 0.8 V	10	—	—	mA	5
$Ioh_{GPIO\text{-}FAST\_DSE\_1}$	I/O current sink capability measured when pad V_{oh}=V_{DD}-0.8 V	16	—	—	mA	5
$Iol_{GPIO\text{-}FAST\_DSE\_1}$	I/O current sink capability measured when pad V_{ol} = 0.8 V	15.5	—	—	mA	5
IOHT	Output high current total for all ports	—	—	100	mA	
IIN	Input leakage current (per pin) for full temperature range at V_{DD} = 3.3 V					6
	All pins other than high drive port pins		0.005	0.5	µA	
	High drive port pins [7]		0.010	0.5	µA	
R_{PU}	Internal pullup resistors	20		60	kΩ	8
R_{PD}	Internal pulldown resistors	20		60	kΩ	9

1. S32K148 will operate from 2.7 V when executing from internal FIRC. When the PLL is engaged S32K148 is guaranteed to operate from 2.97 V. All other S32K family devices operate from 2.7 V in all modes.
2. For reset pads, same V_{ih} levels are applicable
3. For reset pads, same V_{il} levels are applicable
4. The value given is measured at high drive strength mode. For value at low drive strength mode see the Ioh_Standard value given above.
5. For refernce only. Run simulations with the IBIS model and custom board for accurate results.

Table 14. AC electrical specifications at 5 V Range (continued)

Symbol	DSE	Rise time (nS)[1]		Fall time (nS) [1]		Capacitance (pF) [2]
		Min.	Max .	Min.	Max.	
		17.3	54.8	17.6	59.7	200
	1	1.1	4.6	1.1	5.0	25
		2.0	5.7	2.0	5.8	50
		5.4	16.0	5.0	16.0	200
$tRF_{GPIO-FAST}$	0	0.42	2.2	0.37	2.2	25
		2.0	5.0	1.9	5.2	50
		9.3	18.8	8.5	19.3	200
	1	0.37	0.9	0.35	0.9	25
		1.2	2.7	1.2	2.9	50
		6.0	11.8	6.0	12.3	200

1. For reference only. Run simulations with the IBIS model and your custom board for accurate results.
2. Maximum capacitances supported on Standard IOs. However interface or protocol specific specifications might be different, for example for ENET, QSPI etc. . For protocol specific AC specifications, see respective sections.

5.7 Standard input pin capacitance

Table 15. Standard input pin capacitance

Symbol	Description	Min.	Max.	Unit
C_{IN_D}	Input capacitance: digital pins	—	7	pF

NOTE

Please refer to External System Oscillator electrical specifications for EXTAL/XTAL pins.

5.8 Device clock specifications

Table 16. Device clock specifications [1]

Symbol	Description	Min.	Max.	Unit
High Speed run mode[2]				
f_{SYS}	System and core clock	—	112	MHz
f_{BUS}	Bus clock	—	56	MHz
f_{FLASH}	Flash clock	—	28	MHz
Normal run mode (S32K11x series)				
f_{SYS}	System and core clock	—	48	MHz
f_{BUS}	Bus clock	—	48	MHz

Table continues on the next page...

Table 16. Device clock specifications [1] (continued)

Symbol	Description	Min.	Max.	Unit
f_{FLASH}	Flash clock	—	24	MHz
Normal run mode (S32K14x series) [3]				
f_{SYS}	System and core clock	—	80	MHz
f_{BUS}	Bus clock	—	40[4]	MHz
f_{FLASH}	Flash clock	—	26.67	MHz
VLPR mode[5]				
f_{SYS}	System and core clock	—	4	MHz
f_{BUS}	Bus clock	—	4	MHz
f_{FLASH}	Flash clock	—	1	MHz
f_{ERCLK}	External reference clock	—	16	MHz

1. Refer to the section Feature comparison for the availability of modes and other specifications.
2. Only available on some devices. See section Feature comparison.
3. With SPLL as system clock source.
4. 48 MHz when f_{SYS} is 48 MHz
5. The frequency limitations in VLPR mode here override any frequency specification listed in the timing specification for any other module.

6 Peripheral operating requirements and behaviors

6.1 System modules

There are no electrical specifications necessary for the device's system modules.

6.2 Clock interface modules

6.2.1 External System Oscillator electrical specifications

6.2.3 System Clock Generation (SCG) specifications

6.2.3.1 Fast internal RC Oscillator (FIRC) electrical specifications

Table 19. Fast internal RC Oscillator electrical specifications

Symbol	Parameter[1]	Value			Unit
		Min.	Typ.	Max.	
F_{FIRC}	FIRC target frequency	—	48	—	MHz
ΔF	Frequency deviation across process, voltage, and temperature < 105°C	—	±0.5	±1	$\%F_{FIRC}$
ΔF125	Frequency deviation across process, voltage, and temperature < 125°C	—	±0.5	±1.1	$\%F_{FIRC}$
$T_{Startup}$	Startup time		3.4	5	µs[2]
T_{JIT}, [3]	Cycle-to-Cycle jitter	—	300	500	ps
T_{JIT}[3]	Long term jitter over 1000 cycles	—	0.04	0.1	$\%F_{FIRC}$

1. With FIRC regulator enable
2. Startup time is defined as the time between clock enablement and clock availability for system use.
3. FIRC as system clock

NOTE

Fast internal RC Oscillator is compliant with CAN and LIN standards.

6.2.3.2 Slow internal RC oscillator (SIRC) electrical specifications

Table 20. Slow internal RC oscillator (SIRC) electrical specifications

Symbol	Parameter	Value			Unit
		Min.	Typ.	Max.	
F_{SIRC}	SIRC target frequency	—	8	—	MHz
ΔF	Frequency deviation across process, voltage, and temperature < 105°C	—	—	±3	$\%F_{SIRC}$
ΔF125	Frequency deviation across process, voltage, and temperature < 125°C	—	—	±3.3	$\%F_{SIRC}$
$T_{Startup}$	Startup time	—	9	12.5	µs[1]

1. Startup time is defined as the time between clock enablement and clock availability for system use.

Table 24. Flash command timing specifications for S32K11x (continued)

Symbol	Description[1]		S32K116		S32K118			
			Typ	Max	Typ	Max	Unit	Notes
$t_{eewr32b}$	32-bit write to FlexRAM execution time	32 KB EEPROM backup	630	2000	630	2000	µs	3,4
		48 KB EEPROM backup	—	—	—	—		
		64 KB EEPROM backup	—	—	—	—		
$t_{quickwr}$	32-bit Quick Write execution time: Time from CCIF clearing (start the write) until CCIF setting (32-bit write complete, ready for next 32-bit write)	1st 32-bit write	200	550	200	550	µs	4,5,6
		2nd through Next to Last (Nth-1) 32-bit write	150	550	150	550		
		Last (Nth) 32-bit write (time for write only, not cleanup)	200	550	200	550		
$t_{quickwrClnup}$	Quick Write Cleanup execution time	—	—	(# of Quick Writes) * 2.0	—	(# of Quick Writes) * 2.0	ms	7

1. All command times assume 25 MHz or greater flash clock frequency (for synchronization time between internal/external clocks).
2. Maximum times for erase parameters based on expectations at cycling end-of-life.
3. For all EEPROM Emulation terms, the specified timing shown assumes previous record cleanup has occurred. This may be verified by executing FCCOB Command 0x77, and checking FCCOB number 5 contents show 0x00 - No EEPROM issues detected.
4. 1st time EERAM writes after a Reset or SETRAM may incur additional overhead for EEE cleanup, resulting in up to 2x the times shown.
5. Only after the Nth write completes will any data be valid. Emulated EEPROM record scheme cleanup overhead may occur after this point even after a brownout or reset. If power on reset occurs before the Nth write completes, the last valid record set will still be valid and the new records will be discarded.
6. Quick Write times may take up to 550 µs, as additional cleanup may occur when crossing sector boundaries.
7. Time for emulated EEPROM record scheme overhead cleanup. Automatically done after last (Nth) write completes, assuming still powered. Or via SETRAM cleanup execution command is requested at a later point.

NOTE

Under certain circumstances FlexMEM maximum times may be exceeded. In this case the user or application may wait, or assert reset to the FTFC macro to stop the operation.

6.3.1.2 Reliability specifications

Table 25. NVM reliability specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
When using as Program and Data Flash						
$t_{nvmretp1k}$	Data retention after up to 1 K cycles	20	—	—	years	1
$n_{nvmcycp}$	Cycling endurance	1 K	—	—	cycles	2, 3

Table continues on the next page...

Table 26. QuadSPI electrical specifications (continued)

FLASH PORT	Sym	Unit	FLASH A												FLASH B			
			RUN[1]						HSRUN[1]						RUN/HSRUN[2]			
QuadSPI Mode			SDR						SDR						SDR		DDR[3]	
			Internal Sampling		Internal DQS				Internal Sampling		Internal DQS				Internal Sampling		External DQS	
			N1		PAD Loopback		Internal Loopback		N1		PAD Loopback		Internal Loopback		N1		External DQS	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max
SCK Duty Cycle	t_{SDC}	ns	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 0.750	tSCK/2 - 0.750	tSCK/2 - 1.5	tSCK/2 + 1.5	tSCK/2 - 2.5	tSCK/2 + 2.5	tSCK/2 - 2.5	tSCK/2 + 2.5
Data Input Setup Time	t_{IS}	ns	15	-	2.5	-	10	-	14	-	1.6	-	9	-	25	-	2	-
Data Input Hold Time	t_{IH}	ns	0	-	1	-	1	-	0	-	1	-	1	-	0	-	20	-
Data Output Valid Time	t_{OV}	ns	-	4.5	-	4.5	-	4.5	-	4	-	4	-	4	-	10	-	10
Data Output In-Valid Time	t_{IV}	ns	-	5	-	5	-	5	-	5	-	3[5]	-	5	-	5	5	-
CS to SCK Time [6]	t_{CSSCK}	ns	5	-	5	-	5	-	5	-	5	-	5	-	10	-	10	-
SCK to CS Time [7]	t_{SCKCS}	ns	5	-	5	-	5	-	5	-	5	-	5	-	5	-	5	-
Output Load		pf	25		25		25		25		25		25		25		25	

1. See Reference Manual for details on mode settings
2. See Reference Manual for details on mode settings
3. Valid for HyperRAM only
4. RWDS(External DQS CLK) frequency
5. For operating frequency ≤ 64 Mhz,Output invalid time is 5 ns.
6. Program register value QuadSPI_FLSHCR[TCSS] = 4`h2
7. Program register value QuadSPI_FLSHCR[TCSH] = 4`h1

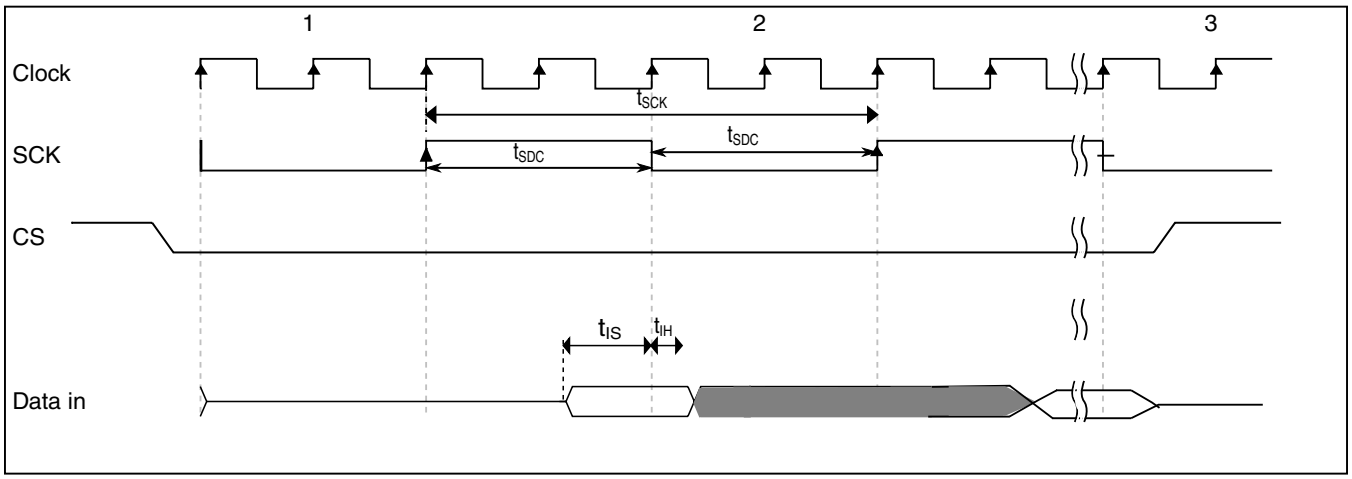


Figure 9. QuadSPI input timing (SDR mode) diagram

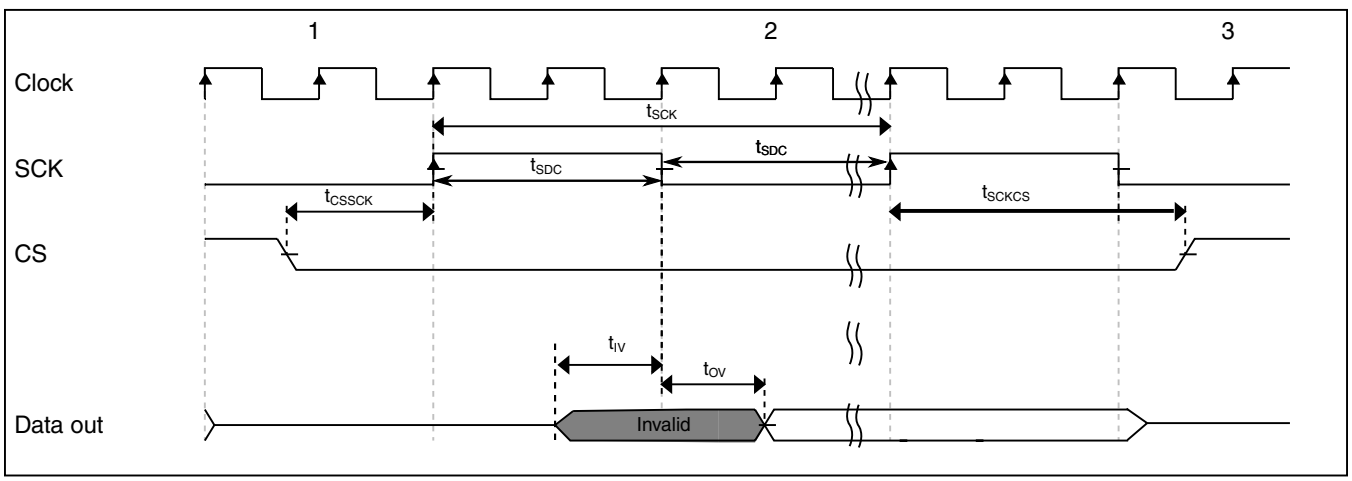
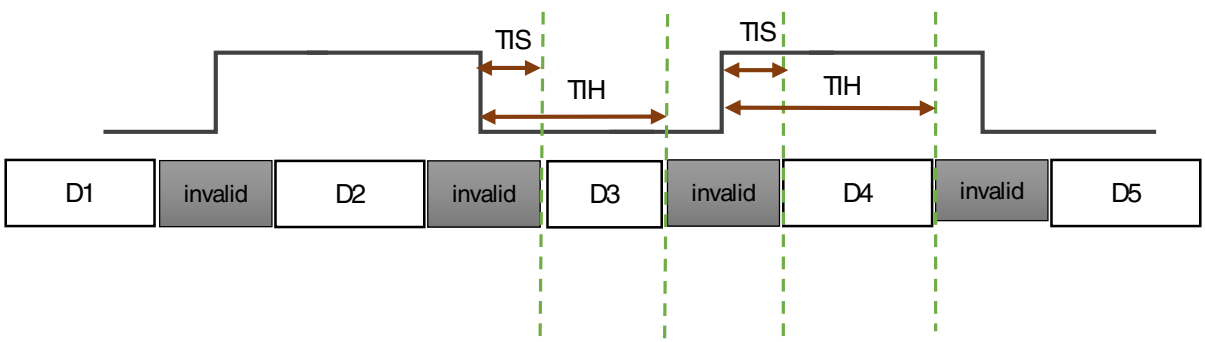


Figure 10. QuadSPI output timing (SDR mode) diagram



TIS – Setup Time
TIH – Hold Time

Figure 11. QuadSPI input timing (HyperRAM mode) diagram

Table 27. 12-bit ADC operating conditions (continued)

Symbol	Description	Conditions	Min.	Typ.[1]	Max.	Unit	Notes
f_{ADCK}	ADC conversion clock frequency	Normal usage	2	40	50	MHz	3, 4
f_{CONV}	ADC conversion frequency	No ADC hardware averaging.[5] Continuous conversions enabled, subsequent conversion time	46.4	928	1160	Ksps	6, 7
		ADC hardware averaging set to 32. [5] Continuous conversions enabled, subsequent conversion time	1.45	29	36.25	Ksps	6, 7

1. Typical values assume V_{DDA} = 5 V, Temp = 25 °C, f_{ADCK} = 40 MHz, R_{AS}=20 Ω, and C_{AS}=10 nF unless otherwise stated. Typical values are for reference only, and are not tested in production.
2. For packages without dedicated V_{REFH} and V_{REFL} pins, V_{REFH} is internally tied to V_{DDA}, and V_{REFL} is internally tied to V_{SS}. To get maximum performance, reference supply quality should be better than SAR ADC. See application note AN5032 for details.
3. Clock and compare cycle need to be set according to the guidelines mentioned in the *Reference Manual* .
4. ADC conversion will become less reliable above maximum frequency.
5. When using ADC hardware averaging, see the *Reference Manual* to determine the most appropriate setting for AVGS.
6. Numbers based on the minimum sampling time of 275 ns.
7. For guidelines and examples of conversion rate calculation, see the *Reference Manual* section 'Calibration function'

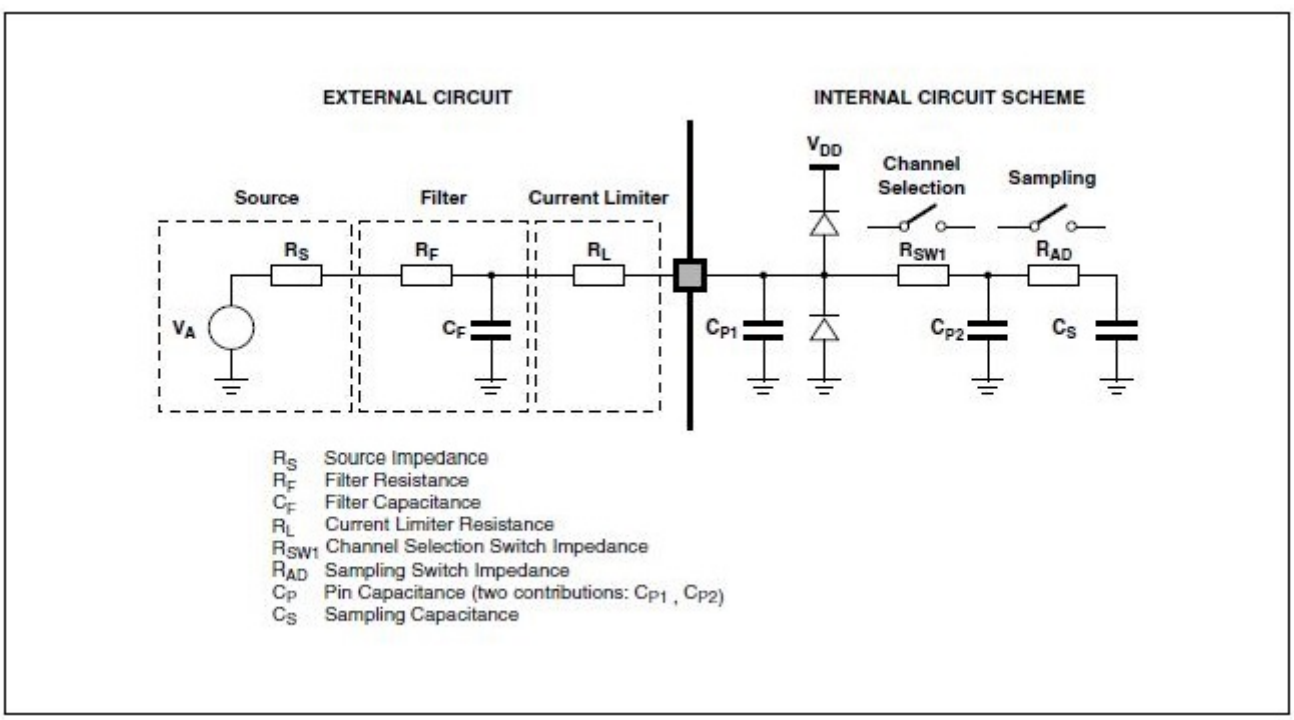


Figure 13. ADC input impedance equivalency diagram

6.5.4 FlexCAN electical specifications

For supported baud rate, see section 'Protocol timing' of the *Reference Manual*.

6.5.5 SAI electrical specifications

The following table describes the SAI electrical characteristics.

- Measurements are with maximum output load of 50 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.

Table 33. Master mode timing specifications

Symbol	Description	Min.	Max.	Unit
—	Operating voltage	2.97	3.6	V
S1	SAI_MCLK cycle time	40	—	ns
S2	SAI_MCLK pulse width high/low	45%	55%	MCLK period
S3	SAI_BCLK cycle time	80	—	ns
S4	SAI_BCLK pulse width high/low	45%	55%	BCLK period
S5	SAI_RXD input setup before SAI_BCLK	28	—	ns
S6	SAI_RXD input hold after SAI_BCLK	0	—	ns
S7	SAI_BCLK to SAI_TXD output valid	—	8	ns
S8	SAI_BCLK to SAI_TXD output invalid	-2	—	ns
S9	SAI_FS input setup before SAI_BCLK	28	—	ns
S10	SAI_FS input hold after SAI_BCLK	0	—	ns
S11	SAI_BCLK to SAI_FS output valid	—	8	ns
S12	SAI_BCLK to SAI_FS output invalid	-2	—	ns

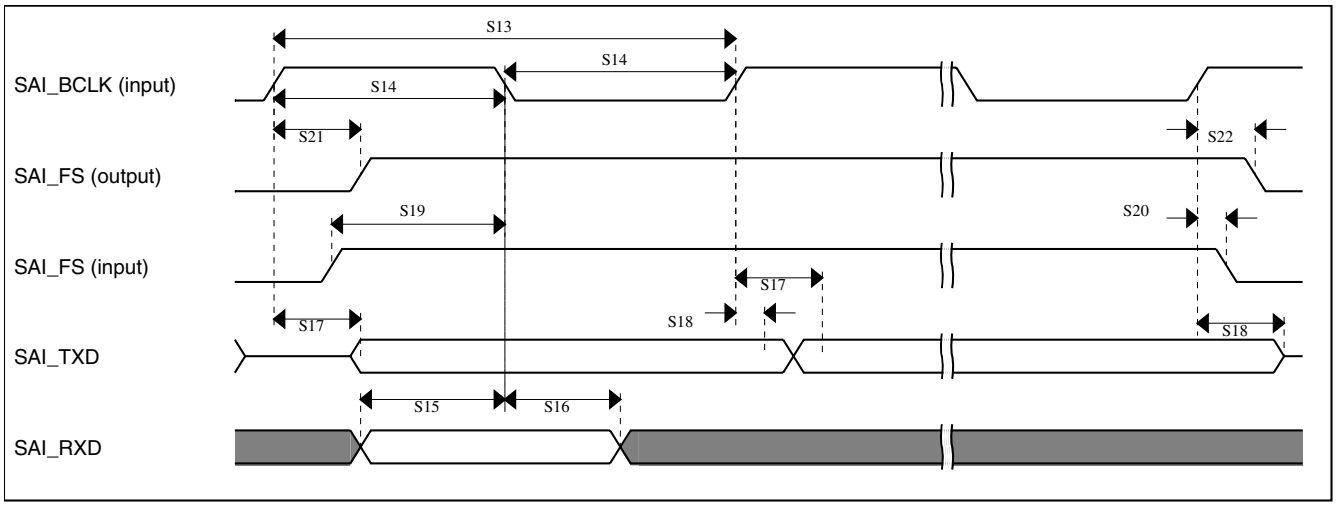


Figure 23. SAI Timing — Slave modes

6.5.6 Ethernet AC specifications

The following timing specs are defined at the chip I/O pin and must be translated appropriately to arrive at timing specs/constraints for the physical interface.

The following table describes the MII electrical characteristics.

- Measurements are with maximum output load of 25 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.

Table 35. MII signal switching specifications

Symbol	Description	Min.	Max.	Unit
—	RXCLK frequency	—	25	MHz
MII1	RXCLK pulse width high	35%	65%	RXCLK period
MII2	RXCLK pulse width low	35%	65%	RXCLK period
MII3	RXD[3:0], RXDV, RXER to RXCLK setup	5	—	ns
MII4	RXCLK to RXD[3:0], RXDV, RXER hold	5	—	ns
—	TXCLK frequency	—	25	MHz
MII5	TXCLK pulse width high	35%	65%	TXCLK period
MII6	TXCLK pulse width low	35%	65%	TXCLK period
MII7	TXCLK to TXD[3:0], TXEN, TXER invalid	2	—	ns
MII8	TXCLK to TXD[3:0], TXEN, TXER valid	—	25	ns

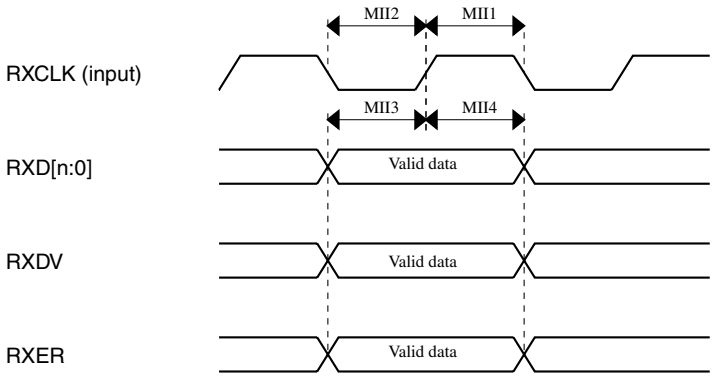


Figure 24. MII receive diagram

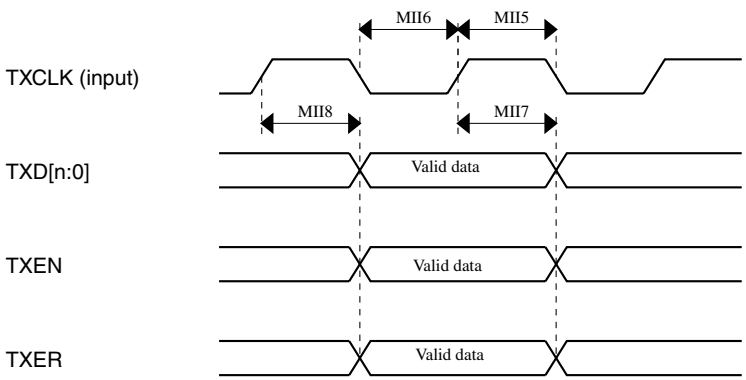


Figure 25. MII transmit signal diagram

The following table describes the RMII electrical characteristics.

- Measurements are with maximum output load of 25 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.

Table 36. RMII signal switching specifications

Symbol	Description	Min.	Max.	Unit
—	RMII input clock RMII_CLK Frequency	—	50	MHz
RMII1, RMII5	RMII_CLK pulse width high	35%	65%	RMII_CLK period
RMII2, RMII6	RMII_CLK pulse width low	35%	65%	RMII_CLK period
RMII3	RXD[1:0], CRS_DV, RXER to RMII_CLK setup	4	—	ns
RMII4	RMII_CLK to RXD[1:0], CRS_DV, RXER hold	2	—	ns

Table continues on the next page...

Table 41. Thermal characteristics for 32-pin QFN and 48/64/100/144/176-pin LQFP package (continued)

Rating	Conditions	Symbol	Package	Values						Unit
				S32K116	S32K118	S32K142	S32K144	S32K146	S32K148	
Thermal resistance, Junction to Package Top[7]	Natural Convection	Ψ_{JT}	32	1	NA	NA	NA	NA	NA	
			48	4	2	NA	NA	NA	NA	
			64	NA	2	2	2	2	NA	
			100	NA	NA	2	2	2	NA	
			144	NA	NA	NA	NA	2	1	
			176	NA	NA	NA	NA	NA	1	

1. Junction temperature is a function of die size, on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
2. Per JEDEC JESD51-2 with natural convection for horizontally oriented board. Board meets JESD51-9 specification for 1s or 2s2p board, respectively.
3. Per JEDEC JESD51-6 with forced convection for horizontally oriented board. Board meets JESD51-9 specification for 1s or 2s2p board, respectively.
4. Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
5. Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1).
6. Thermal resistance between the die and the solder pad on the bottom of the package. Interface resistance is ignored.
7. Thermal characterization parameter indicating the temperature difference between package top and the junction temperature per JEDEC JESD51-2. When Greek letters are not available, the thermal characterization parameter is written as Psi-JT.

9 Pinouts

9.1 Package pinouts and signal descriptions

For package pinouts and signal descriptions, refer to the Reference Manual.

10 Revision History

The following table provides a revision history for this document.

Table 43. Revision History

Rev. No.	Date	Substantial Changes
1	12 Aug 2016	Initial release

2	03 March 2017	• Updated descpition of QSPI and Clock interfaces in Key Features section
		• Updated figure: High-level architecture diagram for the S32K1xx family
		• Updated figure: S32K1xx product series comparison
		• Added note in section Selecting orderable part number
		• Updated figure: Ordering information
		• In table: Absolute maximum ratings :
		  • Added footnote to I_{INJPAD_DC}
		  • Updated min and max value of I_{INJPAD_DC}
		  • Updated description, max and min values for I_{INJSUM}
		  • Updated $V_{IN\_TRANSIENT}$
		• In table: Voltage and current operating requirements :
		  • Renamed V_{SUP_OFF}
		  • Updated max value of V_{DD_OFF}
		  • Removed V_{INA} and V_{IN}
		  • Added V_{REFH} and V_{REFL}
		  • Updated footnote "Typical conditions assumes V_{DD} = V_{DDA} = V_{REFH} = 5 V ...
		  • Removed I_{NJSUM_AF}
		• Updated footnotes in table Table 4
		• Updated section Power mode transition operating behaviors
		• In table: Power consumption
		  • Added footnote "With PMC_REGSC[CLKBIASDIS] ... "
		  • Updated conditions for VLPR
		  • Removed Idd/MHz for S32K144
		  • Updated numbers for S32K142 and S32K148
		  • Removed use case footnotes
		• In section Modes configuration :
		  • Replaced table "Modes configuration" with spreadsheet attachment: 'S32K1xx_Power_Modes _Master_configuration_sheet'
		• In table: DC electrical specifications at 3.3 V Range :
		  • Added footnotes to V_{ih} Input Buffer High Voltage and V_{ih} Input Buffer Low Voltage
		  • Added footnote to High drive port pins
		• In table: DC electrical specifications at 5.0 V Range :

Table continues on the next page...

Table 43. Revision History (continued)

Rev. No.	Date	Substantial Changes
		• Updated values for V_{REFH} and V_{REFL} to add refernce to the section "voltage and current operating requirments" for Min and Max valaues • Updated footnote to Typ. • Removed footnote from RAS Analog source resistance • Updated figure: ADC input impedance equivalency diagram • In table: 12-bit ADC characteristics (2.7 V to 3 V) (V_{REFH} = V_{DDA}, V_{REFL} = V_{SS}) • Removed rows for V_{TEMP_S} and V_{TEMP25} • Updated footnote to Typ. • In table: 12-bit ADC characteristics (3 V to 5.5 V)(V_{REFH} = V_{DDA}, V_{REFL} = V_{SS}) • Removed rows for V_{TEMP_S} and V_{TEMP25} • Removed number for TUE • Updated footnote to Typ. • In table: Comparator with 8-bit DAC electrical specifications • Updated Typ. of I_{DDLS} Supply current, Low-speed mode • Updated Typ. of t_{DLSB} Propagation delay, Low-speed mode • Updated Typ. of t_{DHSS} Propagation delay, High-speed mode • Updated t_{DLSS} Propagation delay • Added row for t_{DDAC} Initialization and switching settling time • Updated footnote • Updated section LPSPI electrical specifications • Added section: SAI electrical specifications • Updated section: Ethernet AC specifications • Added section: Clockout frequency • Added section: Trace electrical specifications • Updated table: Table 41 : Updated numbers for S32K142 and S32K148 • Updated table: Table 42 : Updated numbers for S32K148 • Updated Document number for 32-pin QFN in topic Obtaining package dimensions
3	14 March 2017	• In Table 2 • Updated min. value of V_{DD_OFF} • Added parameter I_{INJSUM_AF} • Updated Power mode transition operating behaviors • Updated Power consumption • Updated footnote to T_{SPLL_LOCK} in SPLL electrical specifications • In 12-bit ADC electrical characteristics • Updated table: 12-bit ADC characteristics (2.7 V to 3 V) (VREFH = VDDA, VREFL = VSS) • Added typ. value to I_{DDA_ADC}, TUE, DNL, and INL • Added min. value to SMPLTS • Removed footnote 'All the parameters in this table ... ' • Updated table: 12-bit ADC characteristics (3 V to 5.5 V) (VREFH = VDDA, VREFL = VSS) • Added typ. value to I_{DDA_ADC} • Removed footnote 'All the parameters in this table ... ' • In Flash timing specifications — commands updated Max. value of t_{vfykey} to 33 µs
4	02 June 2017	• In section: Block diagram, added block diagram for S32K11x series. • Updated figure: S32K1xx product series comparison. • In section: Selecting orderable part number , added reference to attachement *S32K_Part_Numbers.xlsx*. • In section: Ordering information • Updated figure: Ordering information. • In Table 1,

Table continues on the next page...