Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

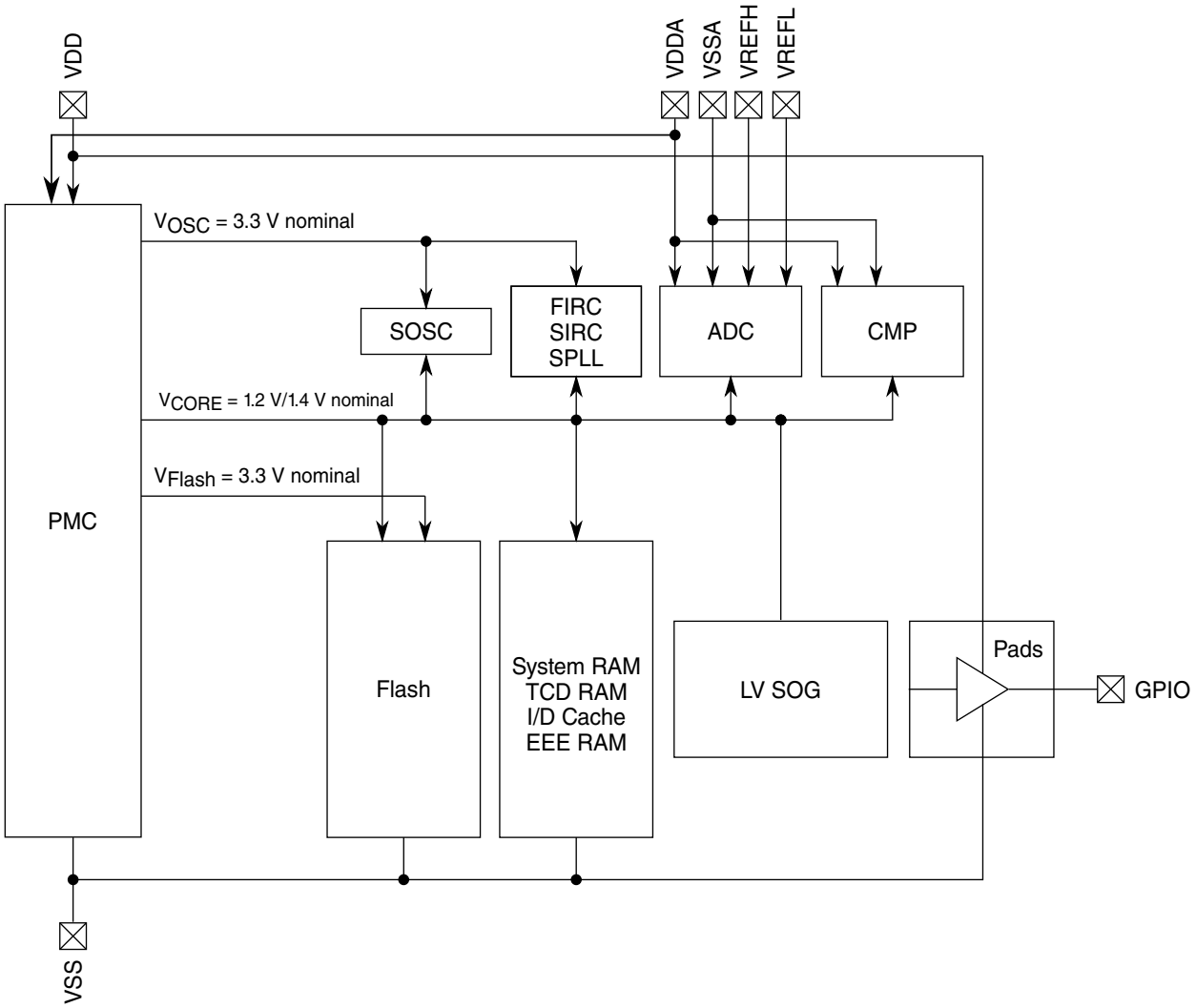
Details	
Product Status	Active
Core Processor	ARM® Cortex®-M4F
Core Size	32-Bit Single-Core
Speed	112MHz
Connectivity	CANbus, FlexIO, I²C, LINbus, SPI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	58
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x12b SAR; D/A1x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/fs32k144uft0vlht

- Communications interfaces
  - Up to three Low Power Universal Asynchronous Receiver/Transmitter (LPUART/LIN) modules with DMA support and low power availability
  - Up to three Low Power Serial Peripheral Interface (LPSPI) modules with DMA support and low power availability
  - Up to two Low Power Inter-Integrated Circuit (LPI2C) modules with DMA support and low power availability
  - Up to three FlexCAN modules (with optional CAN-FD support)
  - FlexIO module for emulation of communication protocols and peripherals (UART, I2C, SPI, I2S, LIN, PWM, etc).
  - Up to one 10/100Mbps Ethernet with IEEE1588 support and two Synchronous Audio Interface (SAI) modules.
- Safety and Security
  - Cryptographic Services Engine (CSEc) implements a comprehensive set of cryptographic functions as described in the SHE (Secure Hardware Extension) Functional Specification. Note: CSEc (Security) or EEPROM writes/erase will trigger error flags in HSRUN mode (112 MHz) because this use case is not allowed to execute simultaneously. The device will need to switch to RUN mode (80 MHz) to execute CSEc (Security) or EEPROM writes/erase.
  - 128-bit Unique Identification (ID) number
  - Error-Correcting Code (ECC) on flash and SRAM memories
  - System Memory Protection Unit (System MPU)
  - Cyclic Redundancy Check (CRC) module
  - Internal watchdog (WDOG)
  - External Watchdog monitor (EWM) module
- Timing and control
  - Up to eight independent 16-bit FlexTimers (FTM) modules, offering up to 64 standard channels (IC/OC/PWM)
  - One 16-bit Low Power Timer (LPTMR) with flexible wake up control
  - Two Programmable Delay Blocks (PDB) with flexible trigger system
  - One 32-bit Low Power Interrupt Timer (LPIT) with 4 channels
  - 32-bit Real Time Counter (RTC)
- Package
  - 32-pin QFN, 48-pin LQFP, 64-pin LQFP, 100-pin LQFP, 100-pin MAPBGA, 144-pin LQFP, 176-pin LQFP package options
- 16 channel DMA with up to 63 request sources using DMAMUX

3 Ordering information

3.1 Selecting orderable part number

Not all part number combinations are available. See the attachment *S32K1xx_Orderable_Part_Number_ List.xlsx* attached with the Datasheet for a list of standard orderable part numbers.



*Note: VSSA and VSS are shorted at package level

Figure 6. Power diagram

4.5 LVR, LVD and POR operating requirements

Table 5. V_{DD} supply LVR, LVD and POR operating requirements

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V_{POR}	Rising and falling V_{DD} POR detect voltage	1.1	1.6	2.0	V	
V_{LVR}	LVR falling threshold (RUN, HSRUN, and STOP modes)	2.50	2.58	2.7	V	
V_{LVR_HYST}	LVR hysteresis	—	45	—	mV	1
V_{LVR_LP}	LVR falling threshold (VLPS/VLPR modes)	1.97	2.22	2.44	V	
V_{LVD}	Falling low-voltage detect threshold	2.8	2.875	3	V	
V_{LVD_HYST}	LVD hysteresis	—	50	—	mV	1

Table continues on the next page...

Table 6. Power mode transition operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit
	VLPS → RUN	8	—	17	µs
	STOP1 → RUN	0.07	0.075	0.08	µs
	STOP2 → RUN	0.07	0.075	0.08	µs
	VLPR → RUN	19	—	26	µs
	VLPR → VLPS	5.1	5.7	6.5	µs
	VLPS → VLPR	18.8	23	27.75	µs
	RUN → Compute operation	0.72	0.75	0.77	µs
	HSRUN → Compute operation	0.3	0.31	0.35	µs
	RUN → STOP1	0.35	0.38	0.4	µs
	RUN → STOP2	0.2	0.23	0.25	µs
	RUN → VLPS	0.3	0.35	0.4	µs
	RUN → VLPR	3.5	3.8	5	µs
	VLPS → Asynchronous DMA Wakeup	105	110	125	µs
	STOP1 → Asynchronous DMA Wakeup	1	1.1	1.3	µs
	STOP2 → Asynchronous DMA Wakeup	1	1.1	1.3	µs
	Pin reset → Code execution	—	214	—	µs

NOTE

HSRUN should only be used when frequencies in excess of 80 MHz are required. When using 80 MHz and below, RUN mode is the recommended operating mode.

4.7 Power consumption

The following table shows the power consumption targets for the device in various mode of operations. Attached *S32K1xx_Power_Modes _Configuration.xlsx* details the modes used in gathering the power consumption data stated in the following table Table 7. For full functionality refer to table: Module operation in available power modes of the *Reference Manual*.

Table 7. Power consumption (Typicals unless stated otherwise) 1

Chip/Device	Ambient Temperature (°C)		VLPS (µA) 2		VLPR (mA)			STOP1 (mA)	STOP2 (mA)	RUN@48 MHz (mA)		RUN@64 MHz (mA)		RUN@80 MHz (mA)		HSRUN@112 MHz (mA) 3		IDD/MHz (µA/MHz) 4
			Peripherals disabled 5	Peripherals enabled	Peripherals disabled 6	Peripherals enabled use case 1 6	Peripherals enabled use case 2 7			Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	
S32K116	25	Typ	26	40	1.05	1.07	TBD	6.3	7.2	11.8	20.3	NA						245
	85	Typ	76	93	1.1	1.11	TBD	6.6	7.5	12	20.6							251
		Max	287	300	1.39	1.4	NA	8	8.9	13.4	22.1							279
	105	Typ	139	164	1.15	1.16	TBD	6.8	7.7	12.3	20.8							255
		Max	590	603	1.68	1.69	NA	9.2	10.1	14.5	23.1							302
	125	Typ	NA	NA	NA	NA	TBD	NA	NA	NA	NA							NA
		Max	891	904	2.02	2.04	NA	10.4	11.3	15.6	24.1							325
S32K118	25	Typ	26	38	1.9	2.5	TBD	7	12	TBD	TBD	NA						TBD
	105	Typ	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD							TBD
		Max	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD							TBD
	125	Max	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	42							TBD
S32K142	25	Typ	29	40	1.17	1.21	2.19	6.4	7.4	17.3	24.6	24.5	31.3	28.8	37.5	40.5	52.2	360
	85	Typ	128	137	1.48	1.51	2.31	7	8	17.6	24.9	25	31.6	29.1	37.7	41.1	52.5	364
		Max	335	360	1.87	1.89	NA	8.6	9.4	22	28.2	26.9	33.5	32	40	44	55.6	400
	105	Typ	240	257	1.58	1.61	2.44	7.6	8.3	18.3	25.7	25.5	31.9	29.8	38	41.5	53.1	373
		Max	740	791	2.32	2.34	NA	9.9	10.9	23.1	30.2	27.8	35.3	33.8	40.7	44.9	57.4	423
	125	Typ	NA	NA	NA	NA	2.84	NA	NA	NA	NA	NA	NA	NA	NA	NA		NA

Table continues on the next page...

Table 7. Power consumption (Typicals unless stated otherwise) 1 (continued)

Chip/Device	Ambient Temperature (°C)		VLPS (µA) [2]		VLPR (mA)			STOP1 (mA)	STOP2 (mA)	RUN@48 MHz (mA)		RUN@64 MHz (mA)		RUN@80 MHz (mA)		HSRUN@112 MHz (mA) [3]		IDD/MHz (µA/MHz) [4]
			Peripherals disabled [5]	Peripherals enabled	Peripherals disabled [6]	Peripherals enabled use case 1 [6]	Peripherals enabled use case 2 [7]			Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	
		Max	1637	1694	3.1	3.21	NA	12.7	13.7	25	32.9	30.7	38.8	36	43.8	NA		450
S32K144	25	Typ	29.8	42	1.48	1.50	2.91	7	7.7	19.7	26.9	25.1	33.3	30.2	39.6	43.3	55.6	378
	85	Typ	150	159	1.72	1.85	3.08	7.2	8.1	20.4	27.1	26.1	33.5	30.5	40	43.9	56.1	381
		Max	359	384	2.60	2.65	NA	9.2	9.9	23.2	29.6	29.3	36.2	34.8	42.1	46.3	59.7	435
	105	Typ	256	273	1.80	2.10	3.23	7.8	8.5	20.6	27.4	26.6	33.8	31.2	40.5	44.8	57.1	390
		Max	850	900	2.65	2.70	NA	10.3	11.1	23.9	30.6	30.3	37.3	35.6	43.5	47.9	61.3	445
	125	Typ	NA	NA	NA	NA	3.65	NA	NA	NA	NA	NA	NA	NA	NA	NA		NA
		Max	1960	1998	3.18	3.25	NA	12.9	13.8	26.9	33.6	35	40.3	38.7	46.8	NA		484
S32K146	25	Typ	37	47	1.57	1.61	3.3	8	9.2	23.4	31.4	30.5	40.2	36.2	47.6	52	68.3	452
	85	Typ	207	209	1.79	1.83	3.54	8.9	10.1	24.4	32.4	31.5	41.3	37.2	48.7	53.3	69.8	465
		Max	974	981	3.32	3.38	NA	12.7	13.9	29.3	37.9	36.7	47	42.4	54.4	60.3	78	530
	105	Typ	419	422	1.99	2.04	3.78	9.8	11	25.3	33.4	32.5	42.2	38.1	49.6	54.4	70.8	477
		Max	2004	2017	4.06	4.13	NA	17.1	18.3	34.1	42.6	41.3	51.4	46.9	58.8	65.7	82.8	587
	125	Typ	NA	NA	NA	NA	4.44	NA	NA	NA	NA	NA	NA	NA	NA	NA		NA
		Max	3358	3380	5.28	5.38	NA	22.6	23.7	40.2	48.8	47.3	57.4	52.8	64.8	NA		660
S32K148[8]	25	Typ	38	54	2.17	2.20	3.45	8.5	9.6	27.6	34.9	35.5	45.3	42.1	57.7	60.3	83.3	526
	85	Typ	336	357	2.30	2.35	3.74	10.1	11.1	29.1	37.0	36.8	46.6	43.4	59.9	62.9	88.7	543

Table continues on the next page...

5 I/O parameters

5.1 AC electrical characteristics

Unless otherwise specified, propagation delays are measured from the 50% to the 50% point, and rise and fall times are measured at the 20% and 80% points, as shown in the following figure.

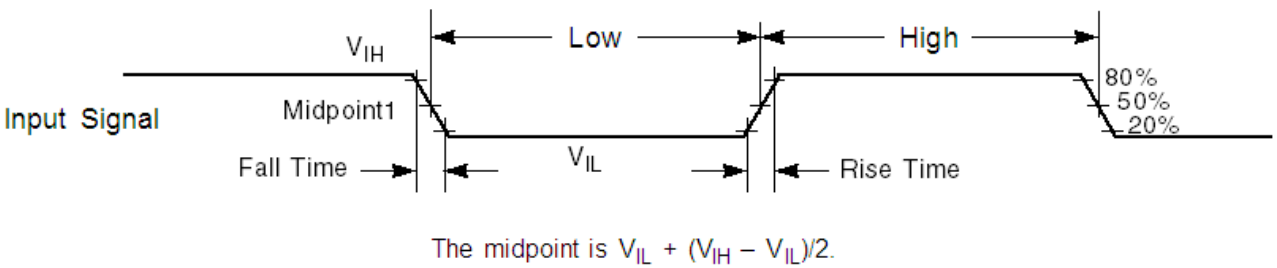


Figure 7. Input signal measurement reference

5.2 General AC specifications

These general purpose specifications apply to all signals configured for GPIO, UART, and timers.

Table 10. General switching specifications

Symbol	Description	Min.	Max.	Unit	Notes
	GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path	1.5	—	Bus clock cycles	1, 2
	GPIO pin interrupt pulse width (digital glitch filter disabled, passive filter disabled) — Asynchronous path	50	—	ns	3
WFRST	$\overline{\text{RESET}}$ input filtered pulse	—	10	ns	4
WNFRST	$\overline{\text{RESET}}$ input not filtered pulse	Maximum of (100 ns, bus clock period)	—	ns	5

1. This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In Stop and VLPS modes, the synchronizer is bypassed so shorter pulses can be recognized in that case.
2. The greater of synchronous and asynchronous timing must be met.
3. These pins do not have a passive filter on the inputs. This is the shortest pulse width that is guaranteed to be recognized.
4. Maximum length of $\overline{\text{RESET}}$ pulse which will be filtered by internal filter.
5. Minimum length of $\overline{\text{RESET}}$ pulse, guaranteed not to be filtered by the internal filter. This number depends on bus clock period also. For example, in VLPR mode bus clock is 4 MHz, which make clock period of 250 ns. In this case, minimum pulse width which will cause reset is 250 ns. For faster bus clock frequencies which have clock period less than 100 ns, the minimum pulse width not filtered will be 100 ns.

5. Several I/O have both high drive and normal drive capability selected by the associated Portx_PCRn[DSE] control bit. All other GPIOs are normal drive only. For details refer to *SK3K144_IO_Signal_Description_Input_Multiplexing.xlsx* attached with the *Reference Manual*.
6. Measured at input V = V_{SS}
7. Measured at input V = V_{DD}

5.5 AC electrical specifications at 3.3 V range

Table 13. AC electrical specifications at 3.3 V Range

Symbol	DSE	Rise time (nS) [1]		Fall time (nS) [1]		Capacitance (pF) [2]
		Min.	Max.	Min.	Max.	
tRF_{GPIO}	NA	3.2	14.5	3.4	15.7	25
		5.7	23.7	6.0	26.2	50
		20.0	80.0	20.8	88.4	200
$tRF_{GPIO-HD}$	0	3.2	14.5	3.4	15.7	25
		5.7	23.7	6.0	26.2	50
		20.0	80.0	20.8	88.4	200
	1	1.5	5.8	1.7	6.1	25
		2.4	8.0	2.6	8.3	50
		6.3	22.0	6.0	23.8	200
$tRF_{GPIO-FAST}$	0	0.6	2.8	0.5	2.8	25
		3.0	7.1	2.6	7.5	50
		12.0	27.0	10.3	26.8	200
	1	0.4	1.3	0.38	1.3	25
		1.5	3.8	1.4	3.9	50
		7.4	14.9	7.0	15.3	200

1. For reference only. Run simulations with the IBIS model and your custom board for accurate results.
2. Maximum capacitances supported on Standard IOs. However interface or protocol specific specifications might be different, for example for ENET, QSPI etc. . For protocol specific AC specifications, see respective sections.

5.6 AC electrical specifications at 5 V range

Table 14. AC electrical specifications at 5 V Range

Symbol	DSE	Rise time (nS)[1]		Fall time (nS) [1]		Capacitance (pF) [2]
		Min.	Max .	Min.	Max.	
tRF_{GPIO}	NA	2.8	9.4	2.9	10.7	25
		5.0	15.7	5.1	17.4	50
		17.3	54.8	17.6	59.7	200
$tRF_{GPIO-HD}$	0	2.8	9.4	2.9	10.7	25
		5.0	15.7	5.1	17.4	50

Table continues on the next page...

6.2.3 System Clock Generation (SCG) specifications

6.2.3.1 Fast internal RC Oscillator (FIRC) electrical specifications

Table 19. Fast internal RC Oscillator electrical specifications

Symbol	Parameter[1]	Value			Unit
		Min.	Typ.	Max.	
F_{FIRC}	FIRC target frequency	—	48	—	MHz
ΔF	Frequency deviation across process, voltage, and temperature < 105°C	—	±0.5	±1	$\%F_{FIRC}$
ΔF125	Frequency deviation across process, voltage, and temperature < 125°C	—	±0.5	±1.1	$\%F_{FIRC}$
$T_{Startup}$	Startup time		3.4	5	µs[2]
T_{JIT}, [3]	Cycle-to-Cycle jitter	—	300	500	ps
T_{JIT}[3]	Long term jitter over 1000 cycles	—	0.04	0.1	$\%F_{FIRC}$

1. With FIRC regulator enable
2. Startup time is defined as the time between clock enablement and clock availability for system use.
3. FIRC as system clock

NOTE

Fast internal RC Oscillator is compliant with CAN and LIN standards.

6.2.3.2 Slow internal RC oscillator (SIRC) electrical specifications

Table 20. Slow internal RC oscillator (SIRC) electrical specifications

Symbol	Parameter	Value			Unit
		Min.	Typ.	Max.	
F_{SIRC}	SIRC target frequency	—	8	—	MHz
ΔF	Frequency deviation across process, voltage, and temperature < 105°C	—	—	±3	$\%F_{SIRC}$
ΔF125	Frequency deviation across process, voltage, and temperature < 125°C	—	—	±3.3	$\%F_{SIRC}$
$T_{Startup}$	Startup time	—	9	12.5	µs[1]

1. Startup time is defined as the time between clock enablement and clock availability for system use.

Table 23. Flash command timing specifications for S32K14x (continued)

Symbol	Description[1]		S32K142		S32K144		S32K146		S32K148			
			Typ	Max	Typ	Max	Typ	Max	Typ	Max	Unit	Notes
t_{setram}	Set FlexRAM Function execution time	Control Code 0xFF	0.08	—	0.08	—	0.08	—	0.08	—	ms	3
		32 KB EEPROM backup	0.8	1.2	0.8	1.2	0.8	1.2	—	—		
		48 KB EEPROM backup	1	1.5	1	1.5	1	1.5	—	—		
		64 KB EEPROM backup	1.3	1.9	1.3	1.9	1.3	1.9	1.3	1.9		
t_{eewr8b}	Byte write to FlexRAM execution time	32 KB EEPROM backup	385	1700	385	1700	385	1700	—	—	µs	3,4
		48 KB EEPROM backup	430	1850	430	1850	430	1850	—	—		
		64 KB EEPROM backup	475	2000	475	2000	475	2000	475	4000		
$t_{eewr16b}$	16-bit write to FlexRAM execution time	32 KB EEPROM backup	385	1700	385	1700	385	1700	—	—	µs	3,4
		48 KB EEPROM backup	430	1850	430	1850	430	1850	—	—		
		64 KB EEPROM backup	475	2000	475	2000	475	2000	475	4000		
$t_{eewr32bers}$	32-bit write to erased FlexRAM location execution time	—	360	2000	360	2000	360	2000	360	2000	µs	
$t_{eewr32b}$	32-bit write to FlexRAM execution time	32 KB EEPROM backup	630	2000	630	2000	630	2000	—	—	µs	3,4
		48 KB EEPROM backup	720	2125	720	2125	720	2125	—	—		
		64 KB EEPROM backup	810	2250	810	2250	810	2250	810	4500		
$t_{quickwr}$	32-bit Quick Write execution time: Time from CCIF clearing (start the write) until CCIF	1st 32-bit write	200	550	200	550	200	550	200	1100	µs	4,5,6
		2nd through Next to Last (Nth-1) 32-bit write	150	550	150	550	150	550	150	550		

Table continues on the next page...

Table 25. NVM reliability specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
When using FlexMemory feature : FlexRAM as Emulated EEPROM						
$t_{nvmretee}$	Data retention	5	—	—	years	4
$n_{nvmwree16}$	Write endurance • EEPROM backup to FlexRAM ratio = 16	100 K	—	—	writes	5, 6, 7
$n_{nvmwree256}$	• EEPROM backup to FlexRAM ratio = 256	1.6 M	—	—	writes	

1. Data retention period per block begins upon initial user factory programming or after each subsequent erase.
2. Program and Erase for PFlash and DFlash are supported across product temperature specification in Normal Mode (not supported in HSRUN mode).
3. Cycling endurance is per DFlash or PFlash Sector.
4. Data retention period per block begins upon initial user factory programming or after each subsequent erase. Background maintenance operations during normal FlexRAM usage extend effective data retention life beyond 5 years.
5. FlexMemory write endurance specified for 16-bit and/or 32-bit writes to FlexRAM and is supported across product temperature specification in Normal Mode (not supported in HSRUN mode). Greater write endurance may be achieved with larger ratios of EEPROM backup to FlexRAM.
6. For usage of any EEE driver other than the FlexMemory feature, the endurance spec will fall back to the specified endurance value of the D-Flash specification (1K).
7. FlexMemory calculator tool is available at NXP web site for help in estimation of the maximum write endurance achievable at specific EEPROM/FlexRAM ratios. The “In Spec” portions of the online calculator refer to the NVM reliability specifications section of data sheet. This calculator is only applies to the FlexMemory feature.

6.3.2 QuadSPI AC specifications

The following table describes the QuadSPI electrical characteristics.

- Measurements are with maximum output load of 25 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.
- Add 50 ohm series termination on board in QuadSPI SCK for Flash A to avoid loop back reflection when using in Internal DQS (PAD Loopback) mode.
- QuadSPI trace length should be 3 inches.
- For non-Quad mode of operation if external device doesn’t have pull-up feature, external pull-up needs to be added at board level for non-used pads.
- With external pull-up, performance of the interface may degrade based on load associated with external pull-up.

Table 26. QuadSPI electrical specifications

FLASH PORT	Sym	Unit	FLASH A												FLASH B			
			RUN[1]						HSRUN[1]						RUN/HSRUN[2]			
QuadSPI Mode			SDR						SDR						SDR		DDR[3]	
			Internal Sampling		Internal DQS				Internal Sampling		Internal DQS				Internal Sampling		External DQS	
			N1		PAD Loopback		Internal Loopback		N1		PAD Loopback		Internal Loopback		N1		External DQS	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max
Register Settings																		
MCR[DDR_EN]		-	0		0		0		0		0		0		0		1	
MCR[DQS_EN]		-	0		1		1		0		1		1		0		1	
MCR[SCLKCFG[0]]		-	-		1		0		-		1		0		-		-	
MCR[SCLKCFG[1]]		-	-		1		0		-		1		0		-		-	
MCR[SCLKCFG[2]]		-	-		-		-		-		-		-		-		0	
MCR[SCLKCFG[3]]		-	-		-		-		-		-		-		-		0	
MCR[SCLKCFG[5]]		-	0		0		0		0		0		0		0		1	
SMPR[FSPHS]		-	0		1		0		0		1		0		0		0	
SMPR[FSDLY]		-	0		0		0		0		0		0		0		0	
SOCCR [SOCCFG[7:0]]			-		0		23		-		0		30		-		-	
SOCCR[SOCCFG[15:8]]		-	-		-		-		-		-		-		-		30	
FLSHCR[TDH]		-	0x00		0x00		0x00		0x00		0x00		0x00		0x00		0x01	
Timing Parameters																		
SCK Clock Frequency	f_{SCK}	MHz	-	38	-	64	-	48	-	40	-	80	-	50	-	20	-	20[4]
SCK Clock Period	t_{SCK}	ns	1/fSCK	-	1/fSCK	-	1/fSCK	-	1/fSCK	-	1/fSCK	-	1/fSCK	-	50.0	-	50.0[4]	-

Table continues on the next page...

Table 29. 12-bit ADC characteristics (3 V to 5.5 V)(V_{REFH} = V_{DDA}, V_{REFL} = V_{SS})

Symbol	Description	Conditions [1]	Min.	Typ.[2]	Max.	Unit	Notes
V_{DDA}	Supply voltage		3	—	5.5	V	
I_{DDA_ADC}	Supply current per ADC		—	1	—	mA	3
SMPLTS	Sample Time		275	—	Refer to the *Reference Manual*	ns	
TUE[4]	Total unadjusted error		—	±4	±8	LSB[5]	6, 7, 8, 9
DNL	Differential non-linearity		—	±0.7	—	LSB[5]	6, 7, 8, 9
INL	Integral non-linearity		—	±1.0	—	LSB[5]	6, 7, 8, 9

1. All accuracy numbers assume the ADC is calibrated with V_{REFH}=V_{DDA}=V_{DD}, with the calibration frequency set to less than or equal to half of the maximum specified ADC clock frequency.
2. Typical values assume V_{DDA} = 5.0 V, Temp = 25 °C, f_{ADCK} = 40 MHz, R_{AS}=20 Ω, and C_{AS}=10 nF unless otherwise stated.
3. The ADC supply current depends on the ADC conversion rate.
4. Represents total static error, which includes offset and full scale error.
5. 1 LSB = (V_{REFH} - V_{REFL})/2^N
6. The specifications are with averaging and in standalone mode only. Performance may degrade depending upon device use case scenario. When using ADC averaging, refer to the *Reference Manual* to determine the most appropriate settings for AVGS.
7. For ADC signals adjacent to V_{DD}/V_{SS} or XTAL/EXTAL or high frequency switching pins, some degradation in the ADC performance may be observed.
8. All values guarantee the performance of the ADC for multiple ADC input channel pins. When using ADC to monitor the internal analog parameters, assume minor degradation.
9. All the parameters in the table are given assuming system clock as the clocking source for ADC.

NOTE

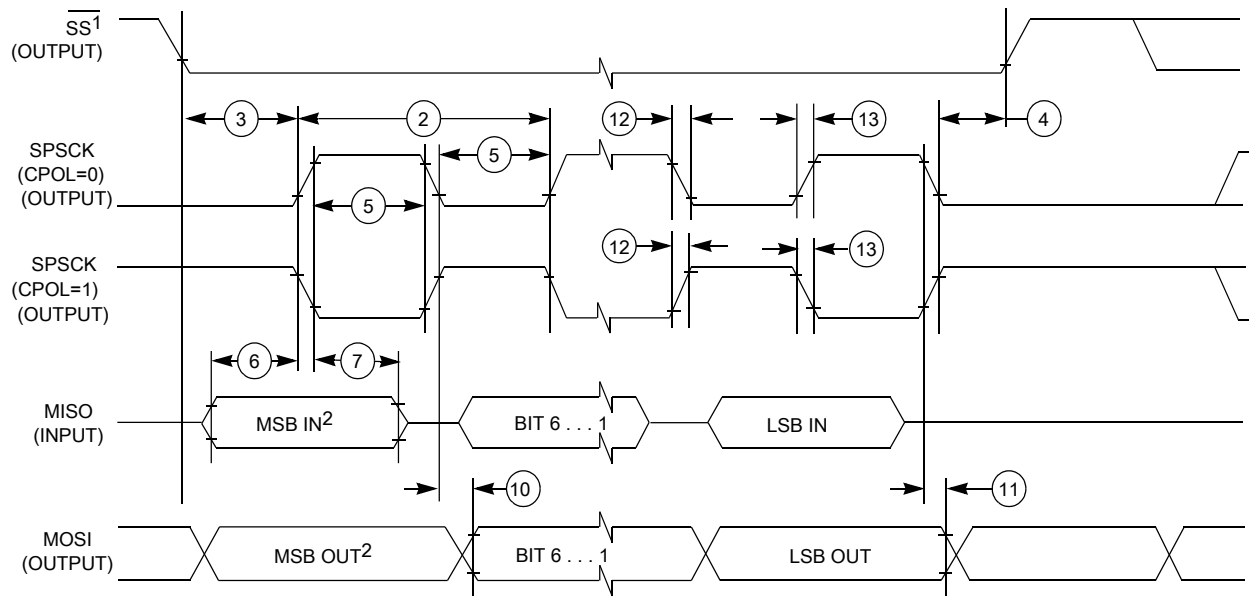
- Due to triple bonding in lower pin packages like 32-QFN, 48-LQFP, and 64-LQFP degradation might be seen in ADC parameters.
- When using high speed interfaces such as the QuadSPI, SAI0, SAI1 or ENET there may be some ADC degradation on the adjacent analog input paths. See following table for details.

Pin name	TGATE purpose
PTE8	CMP0_IN3
PTC3	ADC0_SE11/CMP0_IN4
PTC2	ADC0_SE10/CMP0_IN5
PTD7	CMP0_IN6
PTD6	CMP0_IN7
PTD28	ADC1_SE22
PTD27	ADC1_SE21

Table 32. LPSPI electrical specifications[1] (continued)

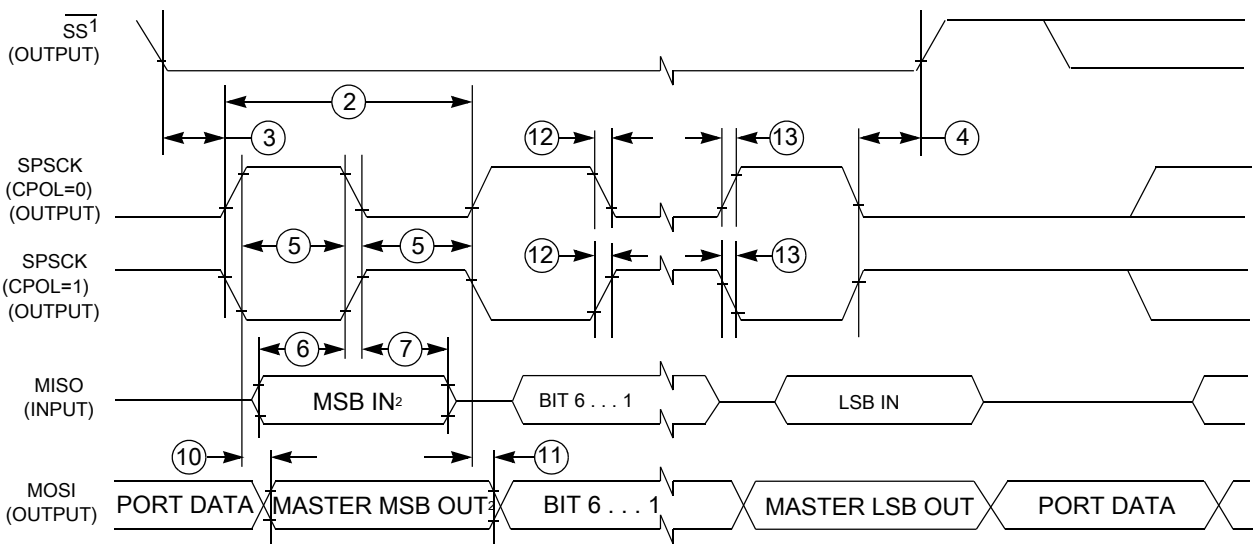
Num	Symbol	Description	Conditions	Run Mode[2]				HSRUN Mode[2]				VLPR Mode				Unit
				5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		
				Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
			Master Loopback(slow) [6]	-		-		-		-		-		-		

1. Trace length should not exceed 11 inches for SCK pad when used in Master loopback mode.
2. While transitioning from HSRUN mode to RUN mode, LPSPI output clock should not be more than 14 MHz.
3. f_{periph} = LPSPI peripheral clock
4. $t_{periph} = 1/f_{periph}$
5. Master Loopback mode - In this mode LPSPI_SCK clock is delayed for sampling the input data which is enabled by setting LPSPI_CFGR1[SAMPLE] bit as 1. Clock pads used are PTD15 and PTE0. Applicable only for LPSPI0.
6. Master Loopback (slow) - In this mode LPSPI_SCK clock is delayed for sampling the input data which is enabled by setting LPSPI_CFGR1[SAMPLE] bit as 1. Clock pad used is PTB2. Applicable only for LPSPI0.
7. This is the maximum operating frequency (f_{op}) for LPSPI0 with medium PAD type only. Otherwise, the maximum operating frequency (f_{op}) is 12 Mhz.
8. Set the PCSSCK configuration bit as 0, for a minimum of 1 delay cycle of LPSPI baud rate clock, where PCSSCK ranges from 0 to 255.
9. Set the SCKPCS configuration bit as 0, for a minimum of 1 delay cycle of LPSPI baud rate clock, where SCKPCS ranges from 0 to 255.
10. While selecting odd dividers, ensure Duty Cycle is meeting this parameter.
11. Maximum operating frequency (f_{op}) is 12 MHz irrespective of PAD type and LPSPI instance.
12. Applicable for LPSPI0 only with medium PAD type, with maximum operating frequency (f_{op}) as 14 MHz.



1. If configured as an output.
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 18. LPSPI master mode timing (CPHA = 0)



1.If configured as output
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 19. LPSPI master mode timing (CPHA = 1)

6.5.4 FlexCAN electical specifications

For supported baud rate, see section 'Protocol timing' of the *Reference Manual*.

6.5.5 SAI electrical specifications

The following table describes the SAI electrical characteristics.

- Measurements are with maximum output load of 50 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.

Table 33. Master mode timing specifications

Symbol	Description	Min.	Max.	Unit
—	Operating voltage	2.97	3.6	V
S1	SAI_MCLK cycle time	40	—	ns
S2	SAI_MCLK pulse width high/low	45%	55%	MCLK period
S3	SAI_BCLK cycle time	80	—	ns
S4	SAI_BCLK pulse width high/low	45%	55%	BCLK period
S5	SAI_RXD input setup before SAI_BCLK	28	—	ns
S6	SAI_RXD input hold after SAI_BCLK	0	—	ns
S7	SAI_BCLK to SAI_TXD output valid	—	8	ns
S8	SAI_BCLK to SAI_TXD output invalid	-2	—	ns
S9	SAI_FS input setup before SAI_BCLK	28	—	ns
S10	SAI_FS input hold after SAI_BCLK	0	—	ns
S11	SAI_BCLK to SAI_FS output valid	—	8	ns
S12	SAI_BCLK to SAI_FS output invalid	-2	—	ns

Table 37. MDIO timing specifications (continued)

Symbol	Description	Min.	Max.	Unit
MDC1	MDC pulse width high	40%	60%	MDC period
MDC2	MDC pulse width low	40%	60%	MDC period
MDC3	MDIO (input) to MDC rising edge setup	25	—	ns
MDC4	MDIO (input) to MDC rising edge hold	0	—	ns
MDC5	MDC falling edge to MDIO output valid (maximum propagation delay)	—	25	ns
MDC6	MDC falling edge to MDIO output invalid (minimum propagation delay)	-10	—	ns

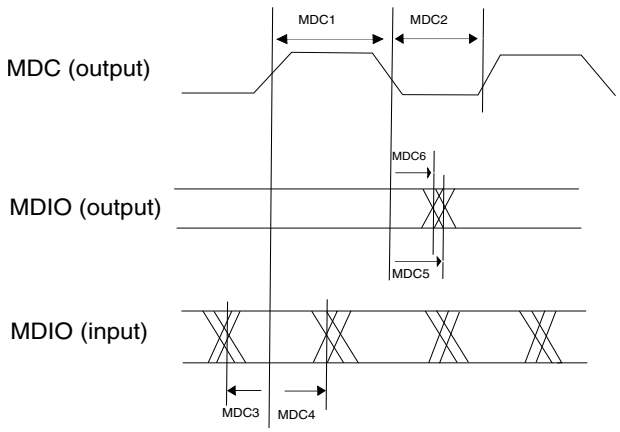


Figure 28. MII/RMII serial management channel timing diagram

6.5.7 Clockout frequency

Maximum supported clock out frequency for this device is 20 MHz

6.6 Debug modules

6.6.1 SWD electrical specofications

Table 40. JTAG electrical specifications

Symbol	Description	Run Mode				HSRUN Mode				VLPR Mode				Unit
		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
JI	TCLK frequency of operation													MHz
	Boundary Scan	-	20	-	20	-	20	-	20	-	10	-	10	
	JTAG	-	20	-	20	-	20	-	20	-	10	-	10	
J2	TCLK cycle period	1/JI	-	1/JI	-	1/JI	-	1/JI	-	1/JI	-	1/JI	-	ns
J3	TCLK clock pulse width													ns
	Boundary Scan	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	
	JTAG													
J4	TCLK rise and fall times	-	1	-	1	-	1	-	1	-	1	-	1	ns
J5	Boundary scan input data setup time to TCLK rise	5	-	5	-	5	-	5	-	15	-	15	-	ns
J6	Boundary scan input data hold time after TCLK rise	5	-	5	-	5	-	5	-	8	-	8	-	ns
J7	TCLK low to boundary scan output data valid	-	28	-	32	-	28	-	32	-	80	-	80	ns
J8	TCLK low to boundary scan output data invalid	0	-	0	-	0	-	0	-	0	-	0	-	
J9	TCLK low to boundary scan output high-Z	-	28	-	32	-	28	-	32	-	80	-	80	ns
J10	TMS, TDI input data setup time to TCLK rise	3	-	3	-	3	-	3	-	15	-	15	-	ns
J11	TMS, TDI input data hold time after TCLK rise	2	-	2	-	2	-	2	-	8	-	8	-	ns
J12	TCLK low to TDO data valid	-	28	-	32	-	28	-	32	-	80	-	80	ns
J13	TCLK low to TDO data invalid	0	-	0	-	0	-	0	-	0	-	0	-	ns
J14	TCLK low to TDO high-Z	-	28	-	32	-	28	-	32	-	80	-	80	ns

Table 43. Revision History (continued)

Rev. No.	Date	Substantial Changes
		• Updated note 'All the limits defined ... ' • Updated parameter '$I_{INJPAD\_DC\_ABS}$', 'V_{IN_DC}', $I_{INJSUM\_DC\_ABS}$. • In Table 2, • Updated parameter $I_{INJPAD\_DC\_OP}$ and $I_{INJSUM\_DC\_OP}$. • In Table 5, updated TBDs for V_{LVR_HYST}, V_{LVD_HYST}, and $_{VLVW\_HYST}$ • In Power mode transition operating behaviors, • Added VLPR → VLPS • Added VLPS → VLPR • Updated TBDs for VLPS → Asynchronous DMA Wakeup, STOP1 → Asynchronous DMA Wakeup, and STOP2 → Asynchronous DMA Wakeup • In Table 7, updated the specifications for S32K144. • Updated the attachment *S32K1xx_Power_Modes _Configuration.xlsx*. • In Table 15, removed C_{IN_A}. • In Table 17, • Updated specificatins for g_{mXOSC}. • Removed I_{DDOSC} • In Table 19, • Added parameter ΔF125. • Removed I_{DDFIRC} • In Table 20, • Added parameter ΔF125. • Removed I_{DDSIRC} • In Table 21, removed I_{LPO} • Updated section: Flash memory module (FTFC) electrical specifications • In section: 12-bit ADC operating conditions, • Updated TBDs for I_{DDA_ADC} and TUE in Table 28 • Updated TBDs for I_{DDA_ADC} and TUE in Table 29 • In section: QuadSPI AC specifications, updated figure 'QuadSPI output timing (HyperRAM mode) diagram'. • In section: 12-bit ADC operating conditions, updated Table 27. • In section: CMP with 8-bit DAC electrical specifications, added note 'For comparator IN signals adjacent ... ' • In table: Table 32, minor update in footnote 6. • In table: Table 41, updated specifications for S32K146.
5	06 Dec 2017	• Removed S32K148 from 'Caution' • Updated figure: S32K1xx product series comparison for • 'EEPROM emulated by FlexRAM' of S32K148 (Added content to footnote) • Added support for LIN protocol version 2.2 A • In Absolute maximum ratings : • Added note 'Unless otherwise ... ' • Added parameter 'Added note 'T_{ramp_MCU}' • Updated footnote for 'T_{ramp}' • In Voltage and current operating requirements : • Added footnote 'V_{DD} and V_{DDA} must be shorted ... ' against parameter 'V_{DD}– V_{DDA}' • Updated footnote 'V_{DD} and V_{DDA} must be shorted ...' • In Power and ground pins • Added diagrams for 32-QFN and 48-LQFP and footnote below the diagrams. • Updated footnote 'V_{DD} and V_{DDA} must be shorted ...' • In Power mode transition operating behaviors :

Table continues on the next page...

Table 43. Revision History (continued)

Rev. No.	Date	Substantial Changes
		• Fixed the typo in R_{SW1} • In LPSPI electrical specifications : • Updated t_{Lead} and t_{Lag} • Added footnote in Figure: LPSPI slave mode timing (CPHA = 0) and Figure: LPSPI slave mode timing (CPHA = 1) • In Thermal characteristics : • Updated the name of table: Thermal characteristics for 32-pin QFN and 48/64/100/144/176-pin LQFP package • Deleted specs for $R_{\theta JC}$ for 32 QFN package • Added '$R_{\theta JCBottom}$'
8	18 June 2018	• In attachement '*S32K1xx_Power_Modes _Configuration*': • Updated VLPR peripherals disabled and Peripherals Enabled use case #1, using 4 Mhz for System clock, 2 Mhz for bus clock, and 1Mhz for flash. • Removed S32K116 from Notes • In figure: S32K1xx product series comparison : • Added note 'Availability of peripherals depends on the pin availability ...' • Updated 'Ambient Operation Temperature' row • Updated 'System RAM (including FlexRAM and MTB)' row for S32K144, S32K146, and S32K148 • In Ordering information : • Updated figure for 'Y: Optional feature' • Updated footnote 3 • In Power and ground pins : • In figure 'Power diagram', updtaed V_{Flash} frequency to 3.3 V • In Power mode transition operating behaviors : • Updated footnote for 'VLPS Mode: All clock sources disabled' • In Power consumption : • Added IDDs for S32K116 • Added VLPR Peripherals enabled use case 2 at 125 °C/Typicals • Renamed VLPR 'Peripherals enabled' to 'Peripherals enabled use case 1' • Added footnote 'Data collected using RAM' to VLPR 'Peripherals disabled' and VLPR 'Peripherals enabled use case 1' • Updated VLPS Peripherals enabled at 25 °C/Typicals for S32K142 and S32K144 to 40 µA and 42 µA respectively • Added table 'VLPS additional use-case power consumption at typical conditions' • In DC electrical specifications at 3.3 V Range : • Updated naming conventions • Added specs for GPIO-FAST pad • In DC electrical specifications at 5.0 V Range : • Updated naming conventions • Added specs for GPIO-FAST pad • In AC electrical specifications at 3.3 V range : • Updated naming conventions • Added specs for GPIO-FAST pad • In AC electrical specifications at 5 V range : • Updated naming conventions • Added specs for GPIO-FAST pad • In External System Oscillator electrical specifications : • Clarified description of g_{mXOSC} • Updated V_{IL} max. to 1.15 V • In Fast internal RC Oscillator (FIRC) electrical specifications :