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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M4F
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	CANbus, Ethernet, FlexIO, I²C, LINbus, SPI, UART/USART
Peripherals	I²S, POR, PWM, WDT
Number of I/O	128
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 32x12b SAR; D/A 1x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LQFP
Supplier Device Package	144-LQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/fs32k148hst0mlqt

- Communications interfaces
  - Up to three Low Power Universal Asynchronous Receiver/Transmitter (LPUART/LIN) modules with DMA support and low power availability
  - Up to three Low Power Serial Peripheral Interface (LPSPI) modules with DMA support and low power availability
  - Up to two Low Power Inter-Integrated Circuit (LPI2C) modules with DMA support and low power availability
  - Up to three FlexCAN modules (with optional CAN-FD support)
  - FlexIO module for emulation of communication protocols and peripherals (UART, I2C, SPI, I2S, LIN, PWM, etc).
  - Up to one 10/100Mbps Ethernet with IEEE1588 support and two Synchronous Audio Interface (SAI) modules.
- Safety and Security
  - Cryptographic Services Engine (CSEc) implements a comprehensive set of cryptographic functions as described in the SHE (Secure Hardware Extension) Functional Specification. Note: CSEc (Security) or EEPROM writes/erase will trigger error flags in HSRUN mode (112 MHz) because this use case is not allowed to execute simultaneously. The device will need to switch to RUN mode (80 MHz) to execute CSEc (Security) or EEPROM writes/erase.
  - 128-bit Unique Identification (ID) number
  - Error-Correcting Code (ECC) on flash and SRAM memories
  - System Memory Protection Unit (System MPU)
  - Cyclic Redundancy Check (CRC) module
  - Internal watchdog (WDOG)
  - External Watchdog monitor (EWM) module
- Timing and control
  - Up to eight independent 16-bit FlexTimers (FTM) modules, offering up to 64 standard channels (IC/OC/PWM)
  - One 16-bit Low Power Timer (LPTMR) with flexible wake up control
  - Two Programmable Delay Blocks (PDB) with flexible trigger system
  - One 32-bit Low Power Interrupt Timer (LPIT) with 4 channels
  - 32-bit Real Time Counter (RTC)
- Package
  - 32-pin QFN, 48-pin LQFP, 64-pin LQFP, 100-pin LQFP, 100-pin MAPBGA, 144-pin LQFP, 176-pin LQFP package options
- 16 channel DMA with up to 63 request sources using DMAMUX

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5. V_{REFH} should always be equal to or less than V_{DDA} + 0.1 V and V_{DD} + 0.1 V
6. Open drain outputs must be pulled to V_{DD}.
7. When input pad voltage levels are close to V_{DD} or V_{SS}, practically no current injection is possible.

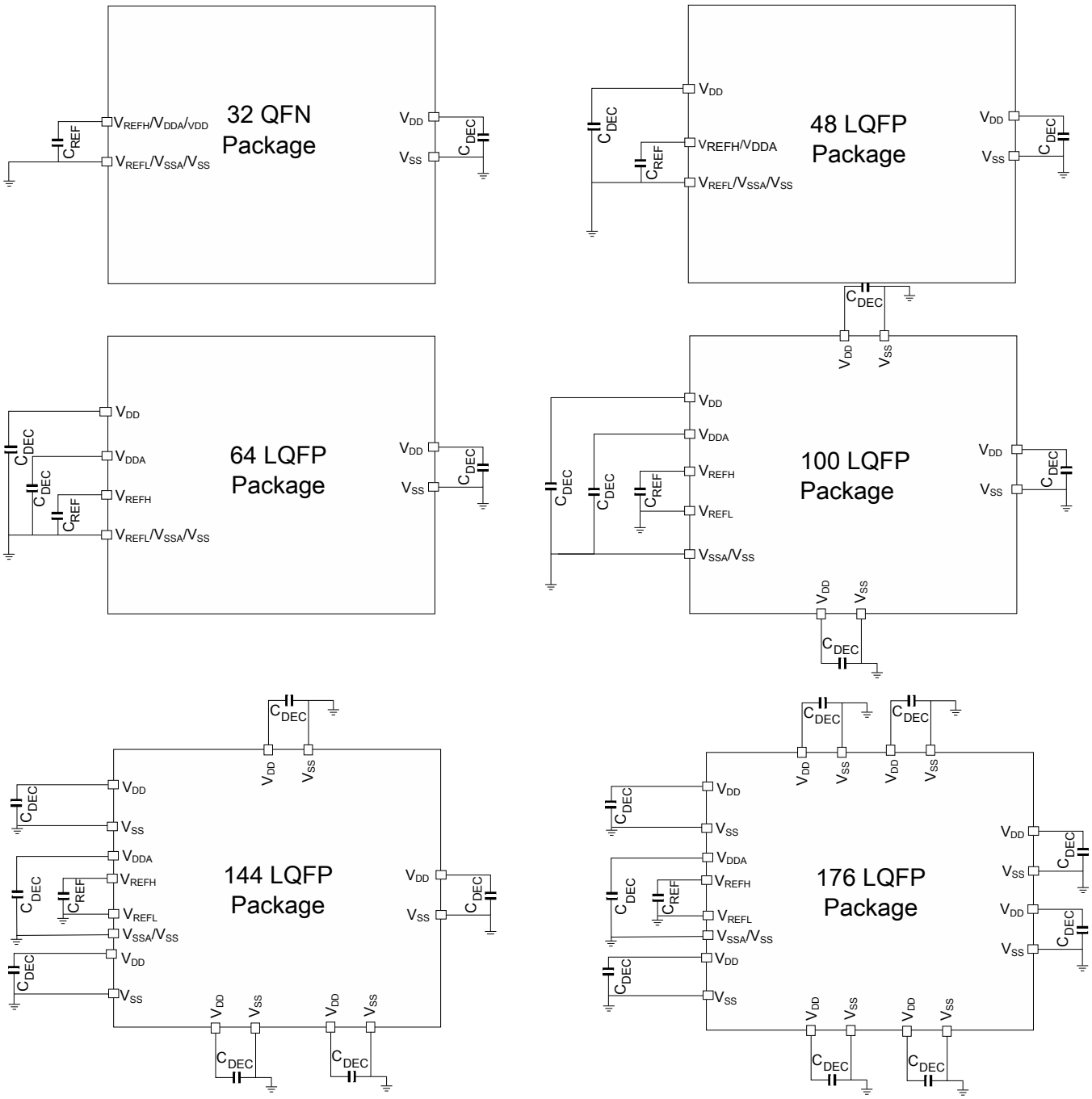
4.3 Thermal operating characteristics

Table 3. Thermal operating characteristics for 64 LQFP, 100 LQFP, and 100 MAP-BGA packages.

Symbol	Parameter	Value			Unit
		Min.	Typ.	Max.	
$T_{A\ C\text{-}Grade\ Part}$	Ambient temperature under bias	–40	—	85[1]	℃
$T_{J\ C\text{-}Grade\ Part}$	Junction temperature under bias	–40	—	105[1]	℃
$T_{A\ V\text{-}Grade\ Part}$	Ambient temperature under bias	–40	—	105[1]	℃
$T_{J\ V\text{-}Grade\ Part}$	Junction temperature under bias	–40	—	125[1]	℃
$T_{A\ M\text{-}Grade\ Part}$	Ambient temperature under bias	–40	—	125[2]	℃
$T_{J\ M\text{-}Grade\ Part}$	Junction temperature under bias	–40	—	135[2]	℃

1. Values mentioned are measured at ≤ 112 MHz in HSRUN mode.
2. Values mentioned are measured at ≤ 80 MHz in RUN mode.

4.4 Power and ground pins



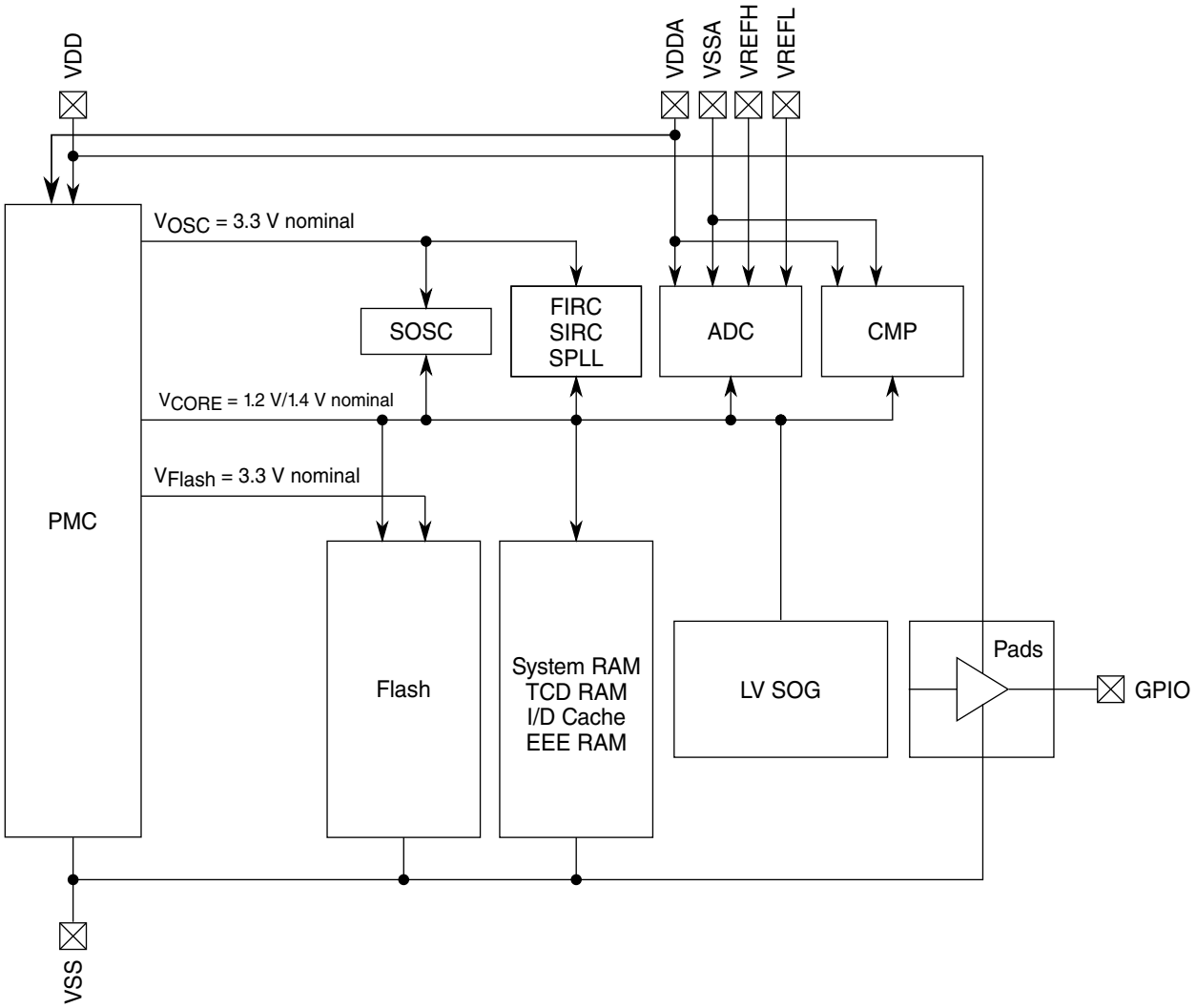
NOTE: V_{DD} and V_{DDA} must be shorted to a common source on PCB

Figure 5. Pinout decoupling

Table 4. Supplies decoupling capacitors 1, 2

Symbol	Description	Min. 3	Typ.	Max.	Unit
C_{REF}, 4, 5	ADC reference high decoupling capacitance	70	100	—	nF
C_{DEC} 5, 6, 7	Recommended decoupling capacitance	70	100	—	nF

1. V_{DD} and V_{DDA} must be shorted to a common source on PCB. The differential voltage between V_{DD} and V_{DDA} is for RF-AC only. Appropriate decoupling capacitors to be used to filter noise on the supplies. See application note AN5032 for reference supply design for SAR ADC. All V_{SS} pins should be connected to common ground at the PCB level.
2. All decoupling capacitors must be low ESR ceramic capacitors (for example X7R type).
3. Minimum recommendation is after considering component aging and tolerance.
4. For improved performance, it is recommended to use 10 µF, 0.1 µF and 1 nF capacitors in parallel.
5. All decoupling capacitors should be placed as close as possible to the corresponding supply and ground pins.
6. Contact your local Field Applications Engineer for details on best analog routing practices.
7. The filtering used for decoupling the device supplies must comply with the following best practices rules:
   - The protection/decoupling capacitors must be on the path of the trace connected to that component.
   - No trace exceeding 1 mm from the protection to the trace or to the ground.
   - The protection/decoupling capacitors must be as close as possible to the input pin of the device (maximum 2 mm).
   - The ground of the protection is connected as short as possible to the ground plane under the integrated circuit.



*Note: VSSA and VSS are shorted at package level

Figure 6. Power diagram

4.5 LVR, LVD and POR operating requirements

Table 5. V_{DD} supply LVR, LVD and POR operating requirements

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V_{POR}	Rising and falling V_{DD} POR detect voltage	1.1	1.6	2.0	V	
V_{LVR}	LVR falling threshold (RUN, HSRUN, and STOP modes)	2.50	2.58	2.7	V	
V_{LVR_HYST}	LVR hysteresis	—	45	—	mV	1
V_{LVR_LP}	LVR falling threshold (VLPS/VLPR modes)	1.97	2.22	2.44	V	
V_{LVD}	Falling low-voltage detect threshold	2.8	2.875	3	V	
V_{LVD_HYST}	LVD hysteresis	—	50	—	mV	1

Table continues on the next page...

Table 7. Power consumption (Typicals unless stated otherwise) 1 (continued)

Chip/Device	Ambient Temperature (°C)		VLPS (µA) [2]		VLPR (mA)			STOP1 (mA)	STOP2 (mA)	RUN@48 MHz (mA)		RUN@64 MHz (mA)		RUN@80 MHz (mA)		HSRUN@112 MHz (mA) [3]		IDD/MHz (µA/MHz) [4]
			Peripherals disabled [5]	Peripherals enabled	Peripherals disabled [6]	Peripherals enabled use case 1[6]	Peripherals enabled use case 2[7]			Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	Peripherals disabled	Peripherals enabled	
		Max	1660	1736	3.48	3.55	NA	14.5	15.6	34.8	43.6	41.9	53.9	48.7	65.1	70.4	96.1	609
	105	Typ	560	577	2.49	2.54	4.03	10.9	11.9	29.8	37.8	37.6	47.5	45.2	61.5	63.8	89.1	565
		Max	2945	2970	4.40	4.47	NA	18.0	19.0	38.4	46.8	44.9	55.3	51.6	66.8	73.6	97.4	645
	125	Typ	NA	NA	NA	NA	4.85	NA	NA	NA	NA	NA	NA	NA	NA	NA		NA
		Max	3990	4166	6.00	6.08	NA	23.4	24.5	44.3	52.5	50.9	61.3	57.5	71.6	NA		719

1. Typical current numbers are indicative for typical silicon process and may vary based on the silicon distribution and user configuration. Typical conditions assumes $V_{DD} = V_{DDA} = V_{REFH} = 5$ V, temperature = 25 °C and typical silicon process unless otherwise stated. All output pins are floating and On-chip pulldown is enabled for all unused input pins.
2. Current numbers are for reduced configuration and may vary based on user configuration and silicon process variation.
3. HSRUN mode must not be used at 125°C. Max ambient temperature for HSRUN mode is 105°C.
4. Values mentioned for S32K14x devices are measured at RUN@80 MHz with peripherals disabled and values mentioned for S32K11x devices are measured at RUN@48 MHz with peripherals disabled.
5. With PMC_REGSC[CLKBIASDIS] set to 1. See Reference Manual for details.
6. Data collected using RAM
7. Numbers on limited samples size and data collected with Flash
8. The S32K148 data points assume that ENET/QuadSPI/SAI etc. are inactive.

The following table shows the power consumption targets for S32K148 in various mode of operations measure at 3.3 V.

Table 9. Power consumption at 3.3 V

Chip/Device	Ambient Temperature (°C)		RUN@80 MHz (mA)		HSRUN@112 MHz (mA)[1]	
			Peripherals enabled + QSPI	Peripherals enabled + ENET + SAI	Peripherals enabled + QSPI	Peripherals enabled + ENET + SAI
S32K148	25	Typ	67.3	79.1	89.8	105.5
	85	Typ	67.4	79.2	95.6	105.9
		Max	82.5	88.2	109.7	117.4
	105	Typ	68.0	79.8	96.6	106.7
		Max	80.3	89.1	109.0	119.0
	125	Max	83.5	94.7	NA	

1. HSRUN mode must not be used at 125°C. Max ambient temperature for HSRUN mode is 105°C.

4.8 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
V_{HBM}	Electrostatic discharge voltage, human body model	– 4000	4000	V	1
V_{CDM}	Electrostatic discharge voltage, charged-device model				2
	All pins except the corner pins	– 500	500	V	
	Corner pins only	– 750	750	V	
I_{LAT}	Latch-up current at ambient temperature of 125 °C	– 100	100	mA	3

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.
3. Determined according to JEDEC Standard JESD78, *IC Latch-Up Test*.

4.9 EMC radiated emissions operating behaviors

EMC measurements to IC-level IEC standards are available from NXP on request.

Table 16. Device clock specifications [1] (continued)

Symbol	Description	Min.	Max.	Unit
f_{FLASH}	Flash clock	—	24	MHz
Normal run mode (S32K14x series) [3]				
f_{SYS}	System and core clock	—	80	MHz
f_{BUS}	Bus clock	—	40[4]	MHz
f_{FLASH}	Flash clock	—	26.67	MHz
VLPR mode[5]				
f_{SYS}	System and core clock	—	4	MHz
f_{BUS}	Bus clock	—	4	MHz
f_{FLASH}	Flash clock	—	1	MHz
f_{ERCLK}	External reference clock	—	16	MHz

1. Refer to the section Feature comparison for the availability of modes and other specifications.
2. Only available on some devices. See section Feature comparison.
3. With SPLL as system clock source.
4. 48 MHz when f_{SYS} is 48 MHz
5. The frequency limitations in VLPR mode here override any frequency specification listed in the timing specification for any other module.

6 Peripheral operating requirements and behaviors

6.1 System modules

There are no electrical specifications necessary for the device's system modules.

6.2 Clock interface modules

6.2.1 External System Oscillator electrical specifications

6.2.4 Low Power Oscillator (LPO) electrical specifications

Table 21. Low Power Oscillator (LPO) electrical specifications

Symbol	Parameter	Min.	Typ.	Max.	Unit
F_{LPO}	Internal low power oscillator frequency	113	128	139	kHz
$T_{startup}$	Startup Time	—	—	20	µs

6.2.5 SPLL electrical specifications

Table 22. SPLL electrical specifications

Symbol	Parameter	Min.	Typ.	Max.	Unit
F_{SPLL_REF}[1]	PLL Reference Frequency Range	8	—	16	MHz
F_{SPLL_Input}[2]	PLL Input Frequency	8	—	40	MHz
F_{VCO_CLK}	VCO output frequency	180	—	320	MHz
F_{SPLL_CLK}	PLL output frequency	90	—	160	MHz
J_{CYC_SPLL}	PLL Period Jitter (RMS)[3]				
	at F_{VCO_CLK} 180 MHz	—	120	—	ps
	at F_{VCO_CLK} 320 MHz	—	75	—	ps
J_{ACC_SPLL}	PLL accumulated jitter over 1µs (RMS)[3]				
	at F_{VCO_CLK} 180 MHz	—	1350	—	ps
	at F_{VCO_CLK} 320 MHz	—	600	—	ps
D_{UNL}	Lock exit frequency tolerance	± 4.47	—	± 5.97	%
T_{SPLL_LOCK}	Lock detector detection time[4]	—	—	$150 \times 10^{-6} + 1075(1/F_{SPLL\_REF})$	s

1. F_{SPLL_REF} is PLL reference frequency range after the PREDIV. For PREDIV and MULT settings refer SCG_SPLLCFG register of Reference Manual.
2. F_{SPLL_Input} is PLL input frequency range before the PREDIV must be limited to the range 8 MHz to 40 MHz. This input source could be derived from a crystal oscillator or some other external square wave clock source using OSC bypass mode. For external clock source settings refer SCG_SOSCCFG register of Reference Manual.
3. This specification was obtained using a NXP developed PCB. PLL jitter is dependent on the noise characteristics of each PCB and results will vary
4. Lock detector detection time is defined as the time between PLL enablement and clock availability for system use.

6.3 Memory and memory interfaces

6.3.1 Flash memory module (FTFC) electrical specifications

This section describes the electrical characteristics of the flash memory module.

Table 25. NVM reliability specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
When using FlexMemory feature : FlexRAM as Emulated EEPROM						
$t_{nvmretee}$	Data retention	5	—	—	years	4
$n_{nvmwree16}$	Write endurance • EEPROM backup to FlexRAM ratio = 16	100 K	—	—	writes	5, 6, 7
$n_{nvmwree256}$	• EEPROM backup to FlexRAM ratio = 256	1.6 M	—	—	writes	

1. Data retention period per block begins upon initial user factory programming or after each subsequent erase.
2. Program and Erase for PFlash and DFlash are supported across product temperature specification in Normal Mode (not supported in HSRUN mode).
3. Cycling endurance is per DFlash or PFlash Sector.
4. Data retention period per block begins upon initial user factory programming or after each subsequent erase. Background maintenance operations during normal FlexRAM usage extend effective data retention life beyond 5 years.
5. FlexMemory write endurance specified for 16-bit and/or 32-bit writes to FlexRAM and is supported across product temperature specification in Normal Mode (not supported in HSRUN mode). Greater write endurance may be achieved with larger ratios of EEPROM backup to FlexRAM.
6. For usage of any EEE driver other than the FlexMemory feature, the endurance spec will fall back to the specified endurance value of the D-Flash specification (1K).
7. FlexMemory calculator tool is available at NXP web site for help in estimation of the maximum write endurance achievable at specific EEPROM/FlexRAM ratios. The “In Spec” portions of the online calculator refer to the NVM reliability specifications section of data sheet. This calculator is only applies to the FlexMemory feature.

6.3.2 QuadSPI AC specifications

The following table describes the QuadSPI electrical characteristics.

- Measurements are with maximum output load of 25 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- I/O operating voltage ranges from 2.97 V to 3.6 V
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.
- Add 50 ohm series termination on board in QuadSPI SCK for Flash A to avoid loop back reflection when using in Internal DQS (PAD Loopback) mode.
- QuadSPI trace length should be 3 inches.
- For non-Quad mode of operation if external device doesn’t have pull-up feature, external pull-up needs to be added at board level for non-used pads.
- With external pull-up, performance of the interface may degrade based on load associated with external pull-up.

6.4.1.2 12-bit ADC electrical characteristics

NOTE

- ADC performance specifications are documented using a single ADC. For parallel/simultaneous operation of both ADCs, either for sampling the same channel by both ADCs or for sampling different channels by each ADC, some amount of decrease in performance can be expected. Care must be taken to stagger the two ADC conversions, in particular the sample phase, to minimize the impact of simultaneous conversions.
- On reduced pin packages where ADC reference pins are shared with supply pins, ADC analog performance characteristics may be impacted. The amount of variation will be directly impacted by the external PCB layout and hence care must be taken with PCB routing. See AN5426 for details

Table 28. 12-bit ADC characteristics (2.7 V to 3 V) (V_{REFH} = V_{DDA}, V_{REFL} = V_{SS})

Symbol	Description	Conditions [1]	Min.	Typ.[2]	Max.	Unit	Notes
V_{DDA}	Supply voltage		2.7	—	3	V	
I_{DDA_ADC}	Supply current per ADC		—	0.6	—	mA	3
SMPLTS	Sample Time		275	—	Refer to the *Reference Manual*	ns	
TUE[4]	Total unadjusted error		—	±4	±8	LSB[5]	6, 7, 8, 9
DNL	Differential non-linearity		—	±1.0	—	LSB[5]	6, 7, 8, 9
INL	Integral non-linearity		—	±2.0	—	LSB[5]	6, 7, 8, 9

1. All accuracy numbers assume the ADC is calibrated with V_{REFH}=V_{DDA}=V_{DD}, with the calibration frequency set to less than or equal to half of the maximum specified ADC clock frequency.
2. Typical values assume V_{DDA} = 3 V, Temp = 25 °C, f_{ADCK} = 40 MHz, R_{AS}=20 Ω, and C_{AS}=10 nF.
3. The ADC supply current depends on the ADC conversion rate.
4. Represents total static error, which includes offset and full scale error.
5. 1 LSB = $(V_{REFH} - V_{REFL})/2^N$
6. The specifications are with averaging and in standalone mode only. Performance may degrade depending upon device use case scenario. When using ADC averaging, refer to the *Reference Manual* to determine the most appropriate settings for AVGS.
7. For ADC signals adjacent to V_{DD}/V_{SS} or XTAL/EXTAL or high frequency switching pins, some degradation in the ADC performance may be observed.
8. All values guarantee the performance of the ADC for multiple ADC input channel pins. When using ADC to monitor the internal analog parameters, assume minor degradation.
9. All the parameters in the table are given assuming system clock as the clocking source for ADC.

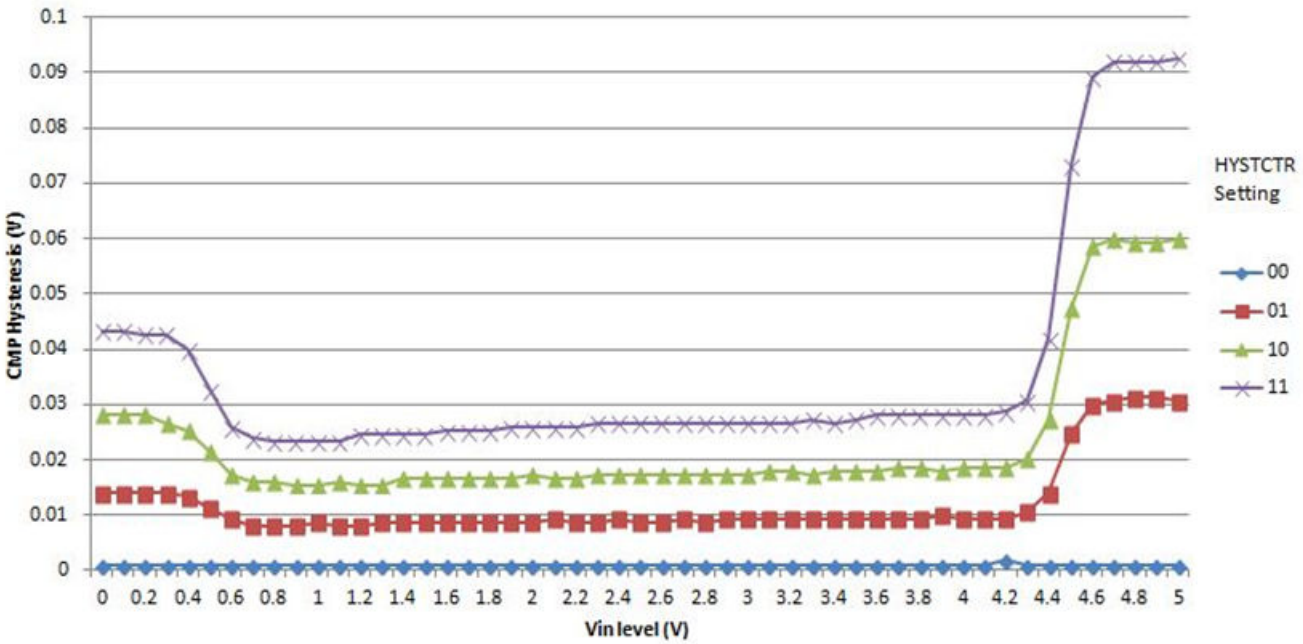


Figure 16. Typical hysteresis vs. Vin level (VDDA = 5 V, PMODE = 0)

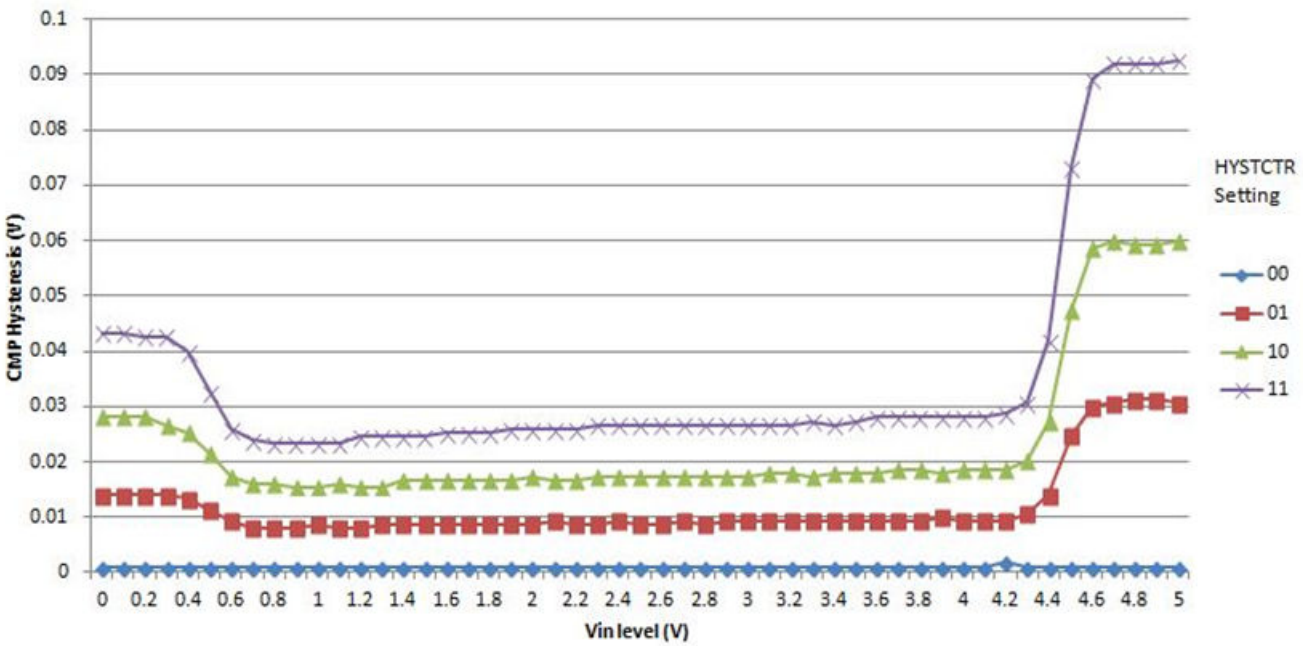


Figure 17. Typical hysteresis vs. Vin level (VDDA = 5 V, PMODE = 1)

6.5 Communication modules

6.5.1 LPUART electrical specifications

Refer to General AC specifications for LPUART specifications.

6.5.1.1 Supported baud rate

Baud rate = Baud clock / ((OSR+1) * SBR).

For details, see section: 'Baud rate generation' of the *Reference Manual*.

6.5.2 LPSPI electrical specifications

The Low Power Serial Peripheral Interface (LPSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The following tables provide timing characteristics for classic LPSPI timing modes.

- All timing is shown with respect to 20% V_{DD} and 80% V_{DD} thresholds.
- All measurements are with maximum output load of 50 pF, input transition of 1 ns and pad configured with fastest slew setting (DSE = 1).

Table 38. SWD electrical specifications

Symbol	Description	Run Mode				HSRUN Mode				VLPR Mode				Unit
		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
S1	SWD_CLK frequency of operation	-	25	-	25	-	25	-	25	-	10	-	10	MHz
S2	SWD_CLK cycle period	1/S1	-	1/S1	-	1/S1	-	1/S1	-	1/S1	-	1/S1	-	ns
S3	SWD_CLK clock pulse width	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	S2/2 - 5	S2/2 + 5	ns
S4	SWD_CLK rise and fall times	-	1	-	1	-	1	-	1	-	1	-	1	ns
S9	SWD_DIO input data setup time to SWD_CLK rise	4	-	4	-	4	-	4	-	16	-	16	-	ns
S10	SWD_DIO input data hold time after SWD_CLK rise	3	-	3	-	3	-	3	-	10	-	10	-	ns
S11	SWD_CLK high to SWD_DIO data valid	-	28	-	38	-	28	-	38	-	70	-	77	ns
S12	SWD_CLK high to SWD_DIO high-Z	-	28	-	38	-	28	-	38	-	70	-	77	ns
S13	SWD_CLK high to SWD_DIO data invalid	0	-	0	-	0	-	0	-	0	-	0	-	ns

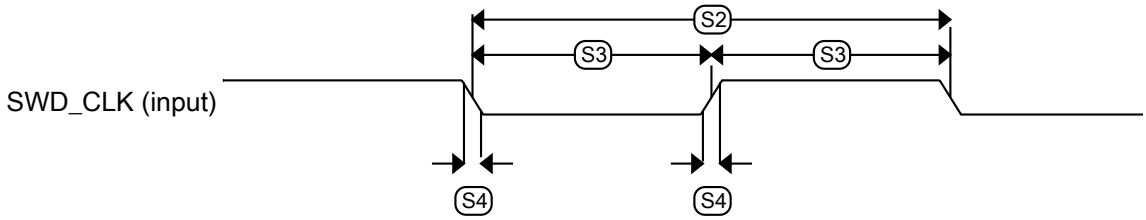


Figure 29. Serial wire clock input timing

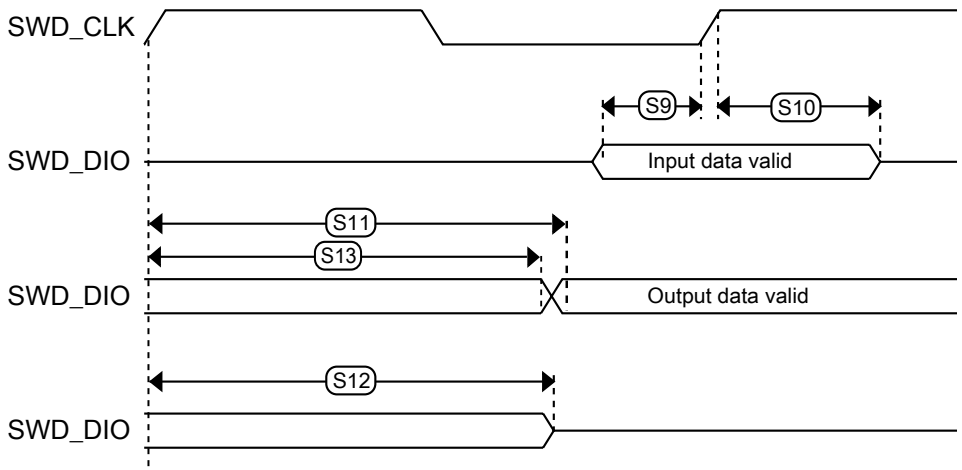


Figure 30. Serial wire data timing

6.6.2 Trace electrical specifications

The following table describes the Trace electrical characteristics.

- Measurements are with maximum output load of 50 pF, input transition of 1 ns and pad configured with fastest slew settings (DSE = 1'b1).
- While doing the mode transition (RUN -> HSRUN or HSRUN -> RUN), the interface should be OFF.

Table 39. Trace specifications

	Symbol	Description	RUN Mode			HSRUN Mode		VLPR Mode	Unit
—	Fsys	System frequency	80	48	40	112	80	4	MHz

Table continues on the next page...

Table 40. JTAG electrical specifications

Symbol	Description	Run Mode				HSRUN Mode				VLPR Mode				Unit
		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		5.0 V IO		3.3 V IO		
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
JI	TCLK frequency of operation													MHz
	Boundary Scan	-	20	-	20	-	20	-	20	-	10	-	10	
	JTAG	-	20	-	20	-	20	-	20	-	10	-	10	
J2	TCLK cycle period	1/JI	-	1/JI	-	1/JI	-	1/JI	-	1/JI	-	1/JI	-	ns
J3	TCLK clock pulse width													ns
	Boundary Scan	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	J2/2 - 5	J2/2 + 5	
	JTAG													
J4	TCLK rise and fall times	-	1	-	1	-	1	-	1	-	1	-	1	ns
J5	Boundary scan input data setup time to TCLK rise	5	-	5	-	5	-	5	-	15	-	15	-	ns
J6	Boundary scan input data hold time after TCLK rise	5	-	5	-	5	-	5	-	8	-	8	-	ns
J7	TCLK low to boundary scan output data valid	-	28	-	32	-	28	-	32	-	80	-	80	ns
J8	TCLK low to boundary scan output data invalid	0	-	0	-	0	-	0	-	0	-	0	-	
J9	TCLK low to boundary scan output high-Z	-	28	-	32	-	28	-	32	-	80	-	80	ns
J10	TMS, TDI input data setup time to TCLK rise	3	-	3	-	3	-	3	-	15	-	15	-	ns
J11	TMS, TDI input data hold time after TCLK rise	2	-	2	-	2	-	2	-	8	-	8	-	ns
J12	TCLK low to TDO data valid	-	28	-	32	-	28	-	32	-	80	-	80	ns
J13	TCLK low to TDO data invalid	0	-	0	-	0	-	0	-	0	-	0	-	ns
J14	TCLK low to TDO high-Z	-	28	-	32	-	28	-	32	-	80	-	80	ns

7.3 General notes for specifications at maximum junction temperature

An estimation of the chip junction temperature, T_J, can be obtained from this equation:

$$T_J = T_A + (R_{\theta JA} \times P_D)$$

where:

- T_A = ambient temperature for the package (°C)
- $R_{\theta JA}$ = junction to ambient thermal resistance (°C/W)
- P_D = power dissipation in the package (W)

The junction to ambient thermal resistance is an industry standard value that provides a quick and easy estimation of thermal performance. Unfortunately, there are two values in common usage: the value determined on a single layer board and the value obtained on a board with two planes. For packages such as the PBGA, these values can be different by a factor of two. Which value is closer to the application depends on the power dissipated by other components on the board. The value obtained on a single layer board is appropriate for the tightly packed printed circuit board. The value obtained on the board with the internal planes is usually appropriate if the board has low power dissipation and the components are well separated.

When a heat sink is used, the thermal resistance is expressed in the following equation as the sum of a junction-to-case thermal resistance and a case-to-ambient thermal resistance:

$$R_{\theta JA} = R_{\theta JC} + R_{\theta CA}$$

where:

- $R_{\theta JA}$ = junction to ambient thermal resistance (°C/W)
- $R_{\theta JC}$ = junction to case thermal resistance (°C/W)
- $R_{\theta CA}$ = case to ambient thermal resistance (°C/W)

$R_{\theta JC}$ is device related and cannot be influenced by the user. The user controls the thermal environment to change the case to ambient thermal resistance, $R_{\theta CA}$. For instance, the user can change the size of the heat sink, the air flow around the device, the interface material, the mounting arrangement on printed circuit board, or change the thermal dissipation on the printed circuit board surrounding the device.

9 Pinouts

9.1 Package pinouts and signal descriptions

For package pinouts and signal descriptions, refer to the Reference Manual.

10 Revision History

The following table provides a revision history for this document.

Table 43. Revision History

Rev. No.	Date	Substantial Changes
1	12 Aug 2016	Initial release

2	03 March 2017	• Updated descpition of QSPI and Clock interfaces in Key Features section
		• Updated figure: High-level architecture diagram for the S32K1xx family
		• Updated figure: S32K1xx product series comparison
		• Added note in section Selecting orderable part number
		• Updated figure: Ordering information
		• In table: Absolute maximum ratings :
		  • Added footnote to I_{INJPAD_DC}
		  • Updated min and max value of I_{INJPAD_DC}
		  • Updated description, max and min values for I_{INJSUM}
		  • Updated $V_{IN\_TRANSIENT}$
		• In table: Voltage and current operating requirements :
		  • Renamed V_{SUP_OFF}
		  • Updated max value of V_{DD_OFF}
		  • Removed V_{INA} and V_{IN}
		  • Added V_{REFH} and V_{REFL}
		  • Updated footnote "Typical conditions assumes V_{DD} = V_{DDA} = V_{REFH} = 5 V ...
		  • Removed I_{NJSUM_AF}
		• Updated footnotes in table Table 4
		• Updated section Power mode transition operating behaviors
		• In table: Power consumption
		  • Added footnote "With PMC_REGSC[CLKBIASDIS] ... "
		  • Updated conditions for VLPR
		  • Removed Idd/MHz for S32K144
		  • Updated numbers for S32K142 and S32K148
		  • Removed use case footnotes
		• In section Modes configuration :
		  • Replaced table "Modes configuration" with spreadsheet attachment: 'S32K1xx_Power_Modes _Master_configuration_sheet'
		• In table: DC electrical specifications at 3.3 V Range :
		  • Added footnotes to V_{ih} Input Buffer High Voltage and V_{ih} Input Buffer Low Voltage
		  • Added footnote to High drive port pins
		• In table: DC electrical specifications at 5.0 V Range :

Table continues on the next page...

Table 43. Revision History

Rev. No.	Date	Substantial Changes
		• Updated specs for T_{JIT} Cycle-to-Cycle jitter to 300 ps • In QuadSPI AC specifications : • Updated specs for T_{iv} Data Output In-Valid Time • In figure 'QuadSPI output timing (SDR mode) diagram', marked Invalid area • In CMP with 8-bit DAC electrical specifications : • Removed '(VAIO)' from decription of V_{HYST0} • In LPSPI electrical specifications : • Added note 'Undefined' in figures 'LPSPI slave mode timing (CPHA = 0)' and 'LPSPI slave mode timing (CPHA = 1)'