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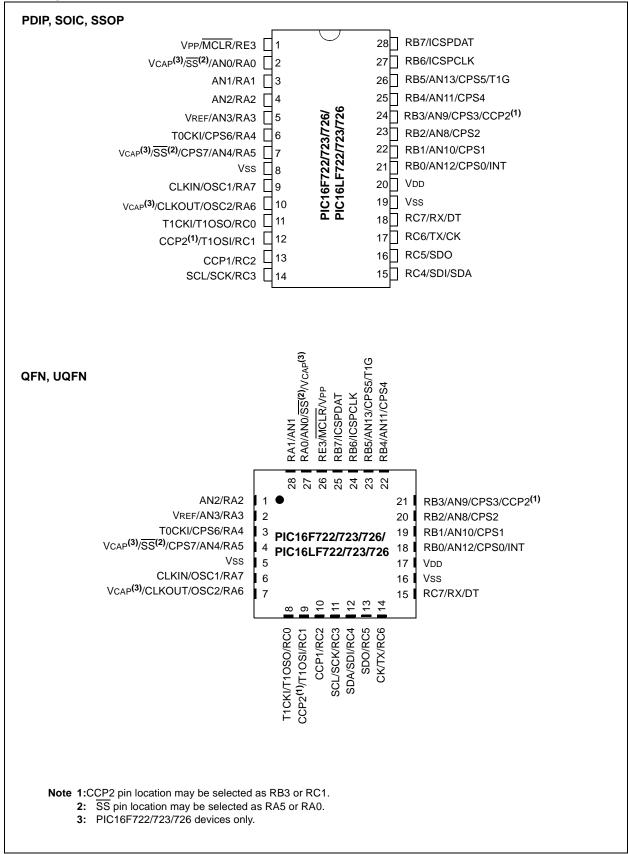
Details

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	25
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	192 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 11x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.300", 7.62mm)
Supplier Device Package	28-SPDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf723-e-sp

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Pin Diagrams - 28-PIN PDIP/SOIC/SSOP/QFN/UQFN (PIC16F722/723/726/PIC16LF722/723/726)



Name	Function	Input Type	Output Type	Description			
RD3/CPS11	RD3	ST	CMOS	General purpose I/O.			
	CPS11	AN	—	Capacitive sensing input 11.			
RD4/CPS12	RD4	ST	CMOS	General purpose I/O.			
	CPS12	AN	—	Capacitive sensing input 12.			
RD5/CPS13	RD5	ST	CMOS	General purpose I/O.			
	CPS13	AN	—	Capacitive sensing input 13.			
RD6/CPS14	RD6	ST	CMOS	General purpose I/O.			
	CPS14	AN	_	Capacitive sensing input 14.			
RD7/CPS15	RD7	ST	CMOS	General purpose I/O.			
	CPS15	AN	_	Capacitive sensing input 15.			
RE0/AN5	RE0	ST	CMOS	General purpose I/O.			
	AN5	AN	—	A/D Channel 5 input.			
RE1/AN6	RE1	ST	CMOS	General purpose I/O.			
	AN6	AN	—	A/D Channel 6 input.			
RE2/AN7	RE2	ST	CMOS	General purpose I/O.			
	AN7	AN	_	A/D Channel 7 input.			
RE3/MCLR/Vpp	RE3	TTL	—	General purpose input.			
	MCLR	ST	_	Master Clear with internal pull-up.			
	Vpp	ΗV	—	Programming voltage.			
VDD	Vdd	Power	—	Positive supply.			
Vss	Vss	Power	_	Ground reference.			
Legend: AN = Analog input or TTL = TTL compatible HV = High Voltage	input ST		nitt Trigger	ble input or output OD = Open Drain input with CMOS levels I^2C = Schmitt Trigger input with I^2C			

TABLE 1-1: PIC16(L)F722/3/4/6/7 PINOUT DESCRIPTION (CONTINUED)

Note: The PIC16F722/3/4/6/7 devices have an internal low dropout voltage regulator. An external capacitor must be connected to one of the available VCAP pins to stabilize the regulator. For more information, see **Section 5.0 "Low Dropout (LDO) Voltage Regulator**". The PIC16LF722/3/4/6/7 devices do not have the voltage regulator and therefore no external capacitor is required.

REGISTER 6-5: PORTB: PORTB REGISTER

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	
bit 7							bit 0	
Legend:								
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'								
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x				x = Bit is unkr				

bit 7-0 **RB<7:0>**: PORTB I/O Pin bit 1 = Port pin is > VIH 0 = Port pin is < VIL

REGISTER 6-6: TRISB: PORTB TRI-STATE REGISTER

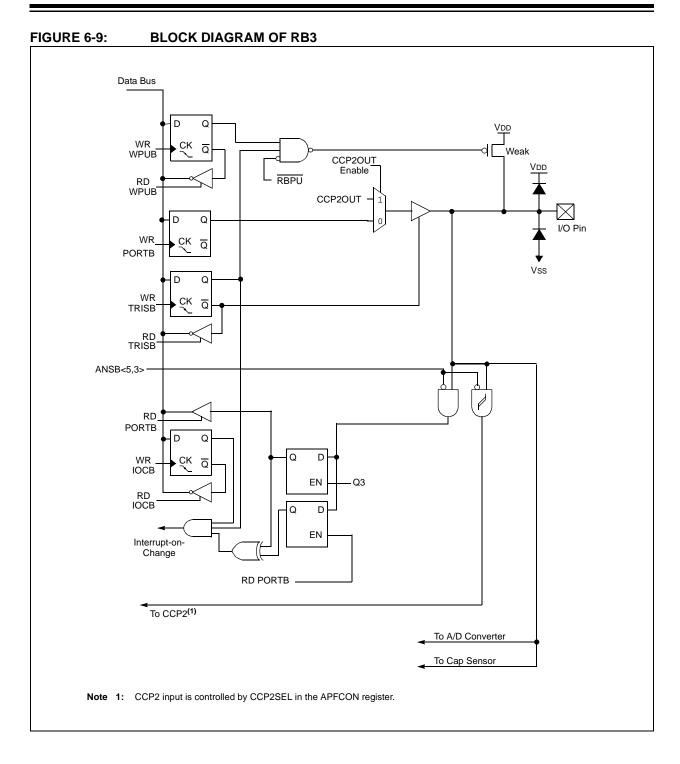
| R/W-1 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| TRISB7 | TRISB6 | TRISB5 | TRISB4 | TRISB3 | TRISB2 | TRISB1 | TRISB0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-0 TRISB<7:0>: PORTB Tri-State Control bit

1 = PORTB pin configured as an input (tri-stated)

0 = PORTB pin configured as an output



REGISTER	19-2. ADCO		ITROL REG				
U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0
_	ADCS2	ADCS1	ADCS0	_	_	ADREF1	ADREF0
bit 7							bit 0
Legend:							
R = Readabl	le bit	W = Writable bi	t	U = Unimpleme	ented bit, read as	s 'O'	
-n = Value at	t POR	'1' = Bit is set		'0' = Bit is clear	red	x = Bit is unkno	wn
bit 7	Unimplemente	ed: Read as '0'					
bit 6-4	ADCS<2:0>: A	/D Conversion C	lock Select bits				
	000 = Fosc/2						
	001 = Fosc/8						
	010 = Fosc/32	-					
	· · ·	ock supplied from	a dedicated RC	Coscillator)			
	100 = Fosc/4 101 = Fosc/16						
	101 = FOSC/10 110 = FOSC/64	-					
		, ock supplied from	a dedicated RC	coscillator)			
bit 3-2	Unimplemente	••		,			
bit 1-0	ADREF<1:0>:	Voltage Referend	e Configuration	bits			
		connected to VDD	0				
	10 = VREF is c	connected to exte	rnal VREF (RA3	/AN3)			
			nal Fixed Voltag				

REGISTER 9-2: ADCON1: A/D CONTROL REGISTER 1

REGISTER 9-3: ADRES: ADC RESULT REGISTER

| R/W-x |
|--------|--------|--------|--------|--------|--------|--------|--------|
| ADRES7 | ADRES6 | ADRES5 | ADRES4 | ADRES3 | ADRES2 | ADRES1 | ADRES0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-0 **ADRES<7:0>**: ADC Result Register bits 8-bit conversion result.

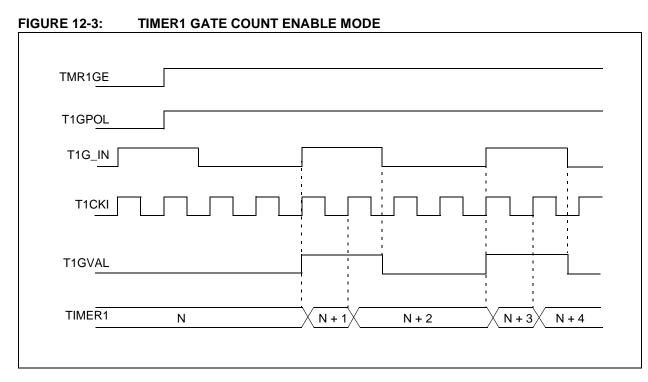


FIGURE 12-4: TIMER1 GATE TOGGLE MODE

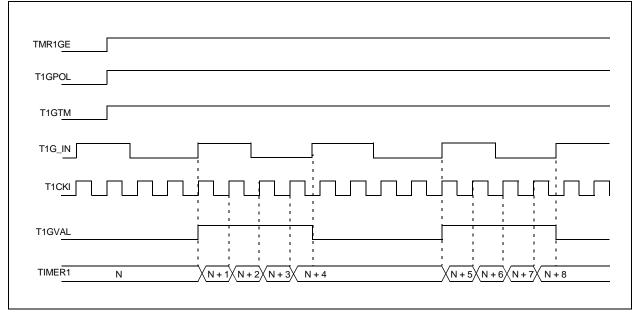


FIGURE 12-6:	TIMER1 GATE SINGLE	-PULSE AND TOGGLE COMBINED MODE
TMR1GE		
T1GPOL		
T1GSPM		
T1GTM		
T1GG <u>O/</u> DONE	← Set by software Counting enabled rising edge of T10	Cleared by hardware on falling edge of T1GVAL
T1G_IN		
тіскі		
T1GVAL		
TIMER1	Ν	N+1 $N+2$ $N+3$ $N+4$
TMR1GIF	- Cleared by software	Set by hardware on falling edge of T1GVAL —

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ANSELB	—	—	ANSB5	ANSB4	ANSB3	ANSB2	ANSB1	ANSB0	11 1111	11 1111
CCP1CON	_	_	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0	00 0000	00 0000
CCP2CON	_	_	DC2B1	DC2B0	CCP2M3	CCP2M2	CCP2M1	CCP2M0	00 0000	00 0000
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	0000 0000	0000 0000
PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	0000 0000	0000 0000
PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	XXXX XXXX	xxxx xxxx
TMR1H	Holding Reg	gister for the	Most Signific	ant Byte of th	he 16-bit TMI	R1 Register			XXXX XXXX	uuuu uuuu
TMR1L	Holding Reg	gister for the	Least Signifi	cant Byte of	the 16-bit TM	R1 Register			XXXX XXXX	uuuu uuuu
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	1111 1111	1111 1111
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
T1CON	TMR1CS1	TMR1CS0	T1CKPS1	T1CKPS0	T1OSCEN	T1SYNC	—	TMR1ON	0000 00-0	uuuu uu-u
T1GCON	TMR1GE	T1GPOL	T1GTM	T1GSPM	T <u>1GGO</u> / DONE	T1GVAL	T1GSS1	T1GSS0	00x0 0x00	uuuu uxuu

TABLE 12-6: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER1

Legend: x = unknown, u = unchanged, - = unimplemented, read as '0'. Shaded cells are not used by the Timer1 module.

17.1.2 SLAVE MODE

For any SPI device acting as a slave, the data is transmitted and received as external clock pulses appear on SCK pin. This external clock must meet the minimum high and low times as specified in the electrical specifications.

17.1.2.1 Slave Mode Operation

The SSP consists of a transmit/receive shift register (SSPSR) and a buffer register (SSPBUF). The SSPSR shifts the data in and out of the device, MSb first. The SSPBUF holds the data that was written to the SSPSR until the received data is ready.

The slave has no control as to when data will be clocked in or out of the device. All data that is to be transmitted, to a master or another slave, must be loaded into the SSPBUF register before the first clock pulse is received.

Once eight bits of data have been received:

- · Received byte is moved to the SSPBUF register
- BF bit of the SSPSTAT register is set
- SSPIF bit of the PIR1 register is set

Any write to the SSPBUF register during transmission/reception of data will be ignored and the Write Collision Detect bit, WCOL of the SSPCON register, will be set. User software must clear the WCOL bit so that it can be determined if the following write(s) to the SSPBUF register completed successfully.

The user's firmware must read SSPBUF, clearing the BF flag, or the SSPOV bit of the SSPCON register will be set with the reception of the next byte and communication will be disabled.

A SPI module transmits and receives at the same time, occasionally causing dummy data to be transmitted/received. It is up to the user to determine which data is to be used and what can be discarded.

17.1.2.2 Enabling Slave I/O

To enable the serial port, the SSPEN bit of the SSPCON register must be set. If a Slave mode of operation is selected in the SSPM bits of the SSPCON register, the SDI, SDO, SCK pins will be assigned as serial port pins.

For these pins to function as serial port pins, they must have their corresponding data direction bits set or cleared in the associated TRIS register as follows:

- SDI configured as input
- SDO configured as output
- SCK configured as input

Optionally, a fourth pin, Slave Select (\overline{SS}) may be used in Slave mode. Slave Select may be configured to operate on one of the following pins via the SSSEL bit in the APFCON register.

- RA5/AN4/SS
- RA0/AN0/SS

Upon selection of a Slave Select pin, the appropriate bits must be set in the ANSELA and TRISA registers. Slave Select must be set as an input by setting the corresponding bit in TRISA, and digital I/O must be enabled on the SS pin by clearing the corresponding bit of the ANSELA register.

17.1.2.3 Slave Mode Setup

When initializing the SSP module to SPI Slave mode, compatibility must be ensured with the master device. This is done by programming the appropriate control bits of the SSPCON and SSPSTAT registers. These control bits allow the following to be specified:

- · SCK as clock input
- Idle state of SCK (CKP bit)
- Data input sample phase (SMP bit)
- Output data on rising/falling edge of SCK (CKE bit)

Figure 17-4 and Figure 17-5 show example waveforms of Slave mode operation.

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ANSELA	—	—	ANSA5	ANSA4	ANSA3	ANSA2	ANSA1	ANSA0	11 1111	11 1111
APFCON	—	—	_	—	_	_	SSSEL	CCP2SEL	00	00
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	0000 0000	0000 0000
PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	0000 0000	0000 0000
PR2	Timer2 Peri	iod Register	•	•				•	1111 1111	1111 1111
SSPBUF	Synchronou	us Serial Port	Receive But	fer/Transmit	Register				XXXX XXXX	uuuu uuuu
SSPCON	WCOL	SSPOV	SSPEN	CKP	SSPM3	SSPM2	SSPM1	SSPM0	0000 0000	0000 0000
SSPSTAT	SMP	CKE	D/A	Р	S	R/W	UA	BF	0000 0000	0000 0000
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	1111 1111	1111 1111
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
T2CON	_	TOUTPS3	TOUTPS2	TOUTPS1	TOUTPS0	TMR2ON	T2CKPS1	T2CKPS0	-000 0000	-000 0000

TABLE 17-1: SUMMARY OF REGISTERS ASSOCIATED WITH SPI OPERATION

Legend: x = unknown, u = unchanged, - = unimplemented, read as '0'. Shaded cells are not used by the SSP in SPI mode.

REGISTER 17-4: SSPSTAT: SYNCHRONOUS SERIAL PORT STATUS REGISTER (I²C MODE)

R/W-0	R/W-0	R-0	R-0	R-0	R-0	R-0	R-0
SMP	CKE	D/A	Р	S	R/W	UA	BF
bit 7							bit 0
Legend:						(0)	
R = Readable		W = Writable bi	t		ented bit, read		
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is clea	ired	x = Bit is unkno	own
bit 7	1 = Slew Rate	Input Sample Pl Control (limiting) Control (limiting)	disabled. Oper	ating in I ² C Star ating in I ² C Fast	dard Mode (100 Mode (400 kHz) kHz and 1 MHz).).	
bit 6		< Edge Select bit e maintained clea		mode only.			
bit 5	1 = Indicates th	DRESS bit (I ² C n lat the last byte r lat the last byte r	eceived or tran				
bit 4	1 = Indicates th	ed when the SSI hat a Stop bit has s not detected la	been detected	-		etected last.	
bit 3	1 = Indicates th	ed when the SSI at a Start bit has s not detected la	been detected	-	•	tected last.	
bit 2	This bit holds th	RITE bit Informat le R/W bit informat t bit, Stop bit or 7	ation following t	he last address i	natch. This bit is	s only valid from the	address match
bit 1	1 = Indicates th	dress bit (10-bit at the user need es not need to b	s to update the		SSPADD registe	er	
bit 0	0 = Receive no <u>Transmit:</u> 1 = Transmit in	Status bit mplete, SSPBUF t complete, SSP progress, SSPB mplete, SSPBU	BUF is empty UF is full				

Mnemonic, Operands		Description	Cycles		14-Bit	Opcode	Status	Neter	
		Description	Cycles	MSb			LSb	Affected	Notes
		BYTE-ORIENTED FILE	REGISTER OPE	RATIC	ONS				
ADDWF	f, d	Add W and f	1	00	0111	dfff	ffff	C, DC, Z	1, 2
ANDWF	f, d	AND W with f	1	00	0101	dfff	ffff	Z	1, 2
CLRF	f	Clear f	1	00	0001	lfff	ffff	Z	2
CLRW	-	Clear W	1	00	0001	0xxx	xxxx	Z	
COMF	f, d	Complement f	1	00	1001	dfff	ffff	Z	1, 2
DECF	f, d	Decrement f	1	00	0011	dfff	ffff	Z	1, 2
DECFSZ	f, d	Decrement f, Skip if 0	1 (2)	00	1011	dfff	ffff		1, 2, 3
INCF	f, d	Increment f	1	00	1010	dfff	ffff	Z	1, 2
INCFSZ	f, d	Increment f, Skip if 0	1 (2)	00	1111	dfff	ffff		1, 2, 3
IORWF	f, d	Inclusive OR W with f	1	00	0100	dfff	ffff	Z	1, 2
MOVF	f, d	Move f	1	00	1000	dfff	ffff	Z	1, 2
MOVWF	f	Move W to f	1	00	0000	lfff	ffff		-
NOP	-	No Operation	1	00	0000	0xx0	0000		
RLF	f, d	Rotate Left f through Carry	1	00	1101	dfff	ffff	С	1, 2
RRF	f, d	Rotate Right f through Carry	1	00	1100	dfff	ffff	С	1, 2
SUBWF	f, d	Subtract W from f	1	00	0010	dfff	ffff	C, DC, Z	1, 2
SWAPF	f, d	Swap nibbles in f	1	00	1110	dfff	ffff		1, 2
XORWF	f, d	Exclusive OR W with f	1	00	0110	dfff	ffff	Z	1, 2
		BIT-ORIENTED FILE R	EGISTER OPER	RATIO	NS				
BCF	f, b	Bit Clear f	1	01	00bb	bfff	ffff		1, 2
BSF	f, b	Bit Set f	1	01		bfff	ffff		1, 2
BTFSC	f, b	Bit Test f, Skip if Clear	1 (2)	01	10bb	bfff	ffff		3
BTFSS	f, b	Bit Test f, Skip if Set	1 (2)	01	11bb	bfff	ffff		3
		LITERAL AND CON	ITROL OPERAT	IONS					
ADDLW	k	Add literal and W	1	11	111x	kkkk	kkkk	C, DC, Z	
ANDLW	k	AND literal with W	1	11	1001	kkkk	kkkk	Z	
CALL	k	Call Subroutine	2	10	0kkk	kkkk	kkkk		
CLRWDT	-	Clear Watchdog Timer	1	00	0000	0110	0100	TO, PD	
GOTO	k	Go to address	2	10	1kkk	kkkk	kkkk		
IORLW	k	Inclusive OR literal with W	1	11	1000	kkkk	kkkk	Z	
MOVLW	k	Move literal to W	1	11	00xx	kkkk	kkkk		
RETFIE	-	Return from interrupt	2	00	0000	0000	1001		
RETLW	k	Return with literal in W	2	11	01xx	kkkk	kkkk		
RETURN	_	Return from Subroutine	2	00	0000	0000	1000		
SLEEP	_	Go into Standby mode	1	00	0000	0110	0011	TO, PD	
SUBLW	k	Subtract W from literal	1	11		kkkk		C, DC, Z	
XORLW	k	Exclusive OR literal with W	1	11		kkkk		Z	
Noto 1		1/O register is modified as a function of itself		I				I	l

TABLE 21-2: PIC16(L)F722/3/4/6/7 INSTRUCTION SET

Note 1: When an I/O register is modified as a function of itself (e.g., MOVF PORTA, 1), the value used will be that value present on the pins themselves. For example, if the data latch is '1' for a pin configured as input and is driven low by an external device, the data will be written back with a '0'.

2: If this instruction is executed on the TMR0 register (and where applicable, d = 1), the prescaler will be cleared if assigned to the Timer0 module.

3: If the Program Counter (PC) is modified, or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a NOP.

22.2 MPLAB XC Compilers

The MPLAB XC Compilers are complete ANSI C compilers for all of Microchip's 8, 16, and 32-bit MCU and DSC devices. These compilers provide powerful integration capabilities, superior code optimization and ease of use. MPLAB XC Compilers run on Windows, Linux or MAC OS X.

For easy source level debugging, the compilers provide debug information that is optimized to the MPLAB X IDE.

The free MPLAB XC Compiler editions support all devices and commands, with no time or memory restrictions, and offer sufficient code optimization for most applications.

MPLAB XC Compilers include an assembler, linker and utilities. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. MPLAB XC Compiler uses the assembler to produce its object file. Notable features of the assembler include:

- · Support for the entire device instruction set
- · Support for fixed-point and floating-point data
- Command-line interface
- · Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

22.3 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel[®] standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code, and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB X IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multipurpose source files
- Directives that allow complete control over the assembly process

22.4 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

22.5 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC DSC devices. MPLAB XC Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire device instruction set
- · Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

23.4 DC Characteristics: PIC16(L)F722/3/4/6/7-I/E (Continued)

			Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for industrial $-40^{\circ}C \le TA \le +125^{\circ}C$ for extended						
Param No.	Sym.	Characteristic	Min.	Тур†	Max.	Units	Conditions		
D130	Eр	Cell Endurance	100	1k	—	E/W	Temperature during programming: $10^{\circ}C \le TA \le 40^{\circ}C$		
D131		VDD for Read	Vmin	—	_	V			
		Voltage on MCLR/VPP during Erase/Program	8.0	_	9.0	V	Temperature during programming: $10^{\circ}C \le TA \le 40^{\circ}C$		
		VDD for Bulk Erase	2.7	3	—	V	Temperature during programming: $10^{\circ}C \le TA \le 40^{\circ}C$		
D132	VPEW	VDD for Write or Row Erase	2.7	_	—	V	VMIN = Minimum operating voltage VMAX = Maximum operating voltage		
	IPPPGM	Current on MCLR/VPP during Erase/Write	—	-	5.0	mA	Temperature during programming: $10^{\circ}C \le TA \le 40^{\circ}C$		
	IDDPGM	Current on VDD during Erase/ Write	—		5.0	mA	Temperature during programming: $10^{\circ}C \le TA \le 40^{\circ}C$		
D133	TPEW	Erase/Write cycle time	-		2.8	ms	Temperature during programming: $10^{\circ}C \le TA \le 40^{\circ}C$		
D134	TRETD	Characteristic Retention	40	—	—	Year	Provided no other specifications are violated		
		VCAP Capacitor Charging							
D135		Charging current	—	200	_	μΑ			
D135A		Source/sink capability when charging complete	—	0.0	—	mA			

Legend: TBD = To Be Determined

* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: In RC oscillator configuration, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended to use an external clock in RC mode.

2: Negative current is defined as current sourced by the pin.

3: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

4: Including OSC2 in CLKOUT mode.



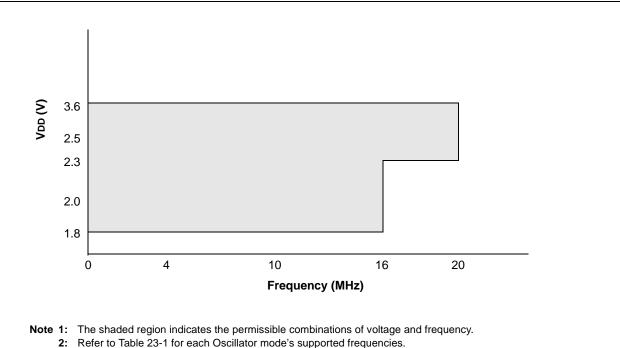
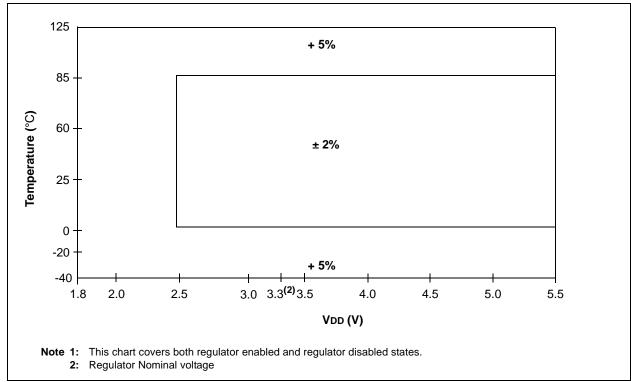
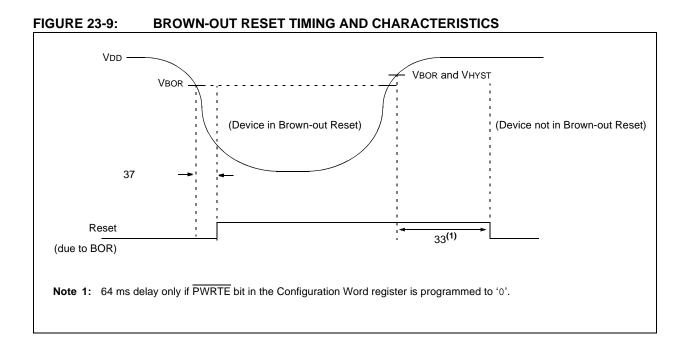


FIGURE 23-6: HFINTOSC FREQUENCY ACCURACY OVER DEVICE VDD AND TEMPERATURE





Param No.	Symbol	Characteristic		Min.	Тур	Max.	Units	Conditions	
SP90*	TSU:STA	Start condition	100 kHz mode	4700		_	ns	Only relevant for Repeated	
		Setup time	400 kHz mode	600	_	—		Start condition	
SP91*	THD:STA	Start condition	100 kHz mode	4000	_	—	ns	After this period, the first	
		Hold time	400 kHz mode	600	_	_		clock pulse is generated	
SP92*	Tsu:sto	Stop condition	100 kHz mode	4700	—	_	ns		
		Setup time	400 kHz mode	600	_	_			
SP93	THD:STO	Stop condition	100 kHz mode	4000	—	—	ns		
		Hold time	400 kHz mode	600	_				

TABLE 23-12: I²C BUS START/STOP BITS REQUIREMENTS

* These parameters are characterized but not tested.



