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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

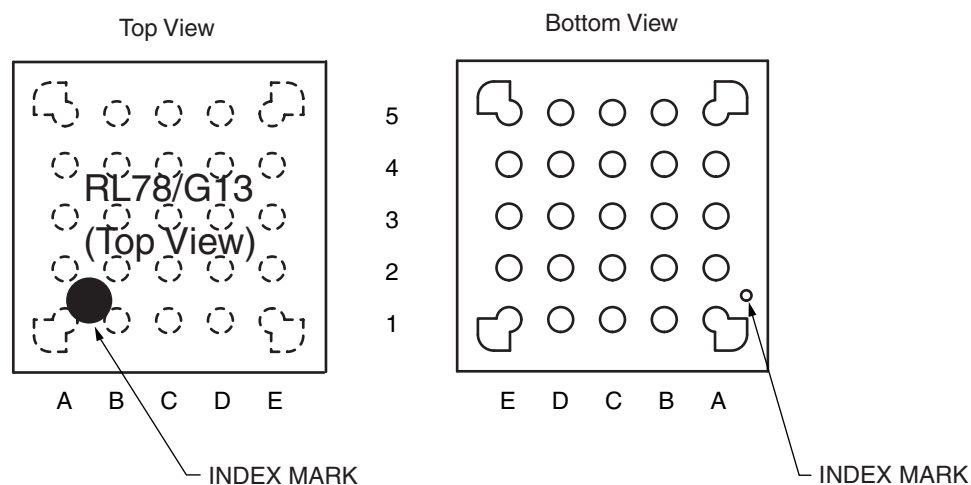
Details

| | |
|----------------------------|---|
| Product Status | Obsolete |
| Core Processor | RL78 |
| Core Size | 16-Bit |
| Speed | 32MHz |
| Connectivity | CSI, I ² C, LINbus, UART/USART |
| Peripherals | DMA, LVD, POR, PWM, WDT |
| Number of I/O | 31 |
| Program Memory Size | 16KB (16K x 8) |
| Program Memory Type | FLASH |
| EEPROM Size | 4K x 8 |
| RAM Size | 2K x 8 |
| Voltage - Supply (Vcc/Vdd) | 1.6V ~ 5.5V |
| Data Converters | A/D 10x8/10b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 105°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 44-LQFP |
| Supplier Device Package | 44-LQFP (10x10) |
| Purchase URL | https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f100fagfp-v0 |

1.3.3 25-pin products

- 25-pin plastic WFLGA (3 × 3 mm, 0.50 mm pitch)

<R>



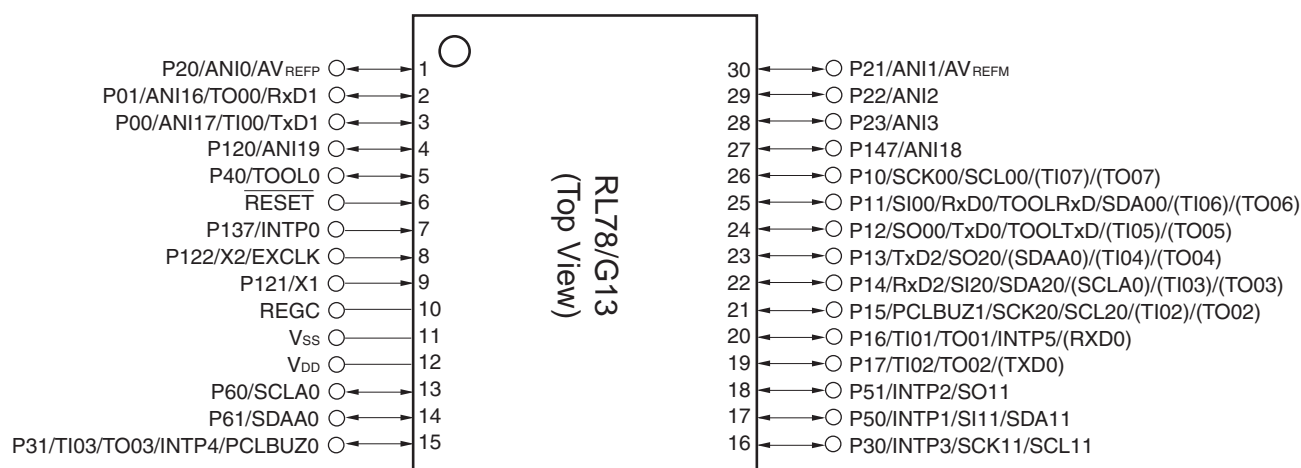
| | A | B | C | D | E | |
|---|-------------------|-----------------|-------------------------------------|---------------------------------|---|---|
| 5 | P40/TOOL0 | RESET | P01/ANI16/ TO00/RxD1 | P22/ANI2 | P147/ANI18 | 5 |
| 4 | P122/X2/ EXCLK | P137/INTP0 | P00/ANI17/ TI00/TxD1 | P21/ANI1/ AV _{REFM} | P10/SCK00/ SCL00 | 4 |
| 3 | P121/X1 | V _{DD} | P20/ANI0/ AV _{REFP} | P12/SO00/ TxD0/ TOOLTxD | P11/SI00/ RxD0/ TOOLRxD/ SDA00 | 3 |
| 2 | REGC | V _{SS} | P30/INTP3/ SCK11/SCL11 | P17/TI02/ TO02/SO11 | P50/INTP1/ SI11/SDA11 | 2 |
| 1 | P60/SCLA0 | P61/SDAA0 | P31/TI03/ TO03/INTP4/ PCLBUZ0 | P16/TI01/ TO01/INTP5 | P130 | 1 |
| | A | B | C | D | E | |

Caution Connect the REGC pin to V_{SS} via a capacitor (0.47 to 1 μ F).

Remark For pin identification, see 1.4 Pin Identification.

1.3.4 30-pin products

- 30-pin plastic LSSOP (7.62 mm (300), 0.65 mm pitch)



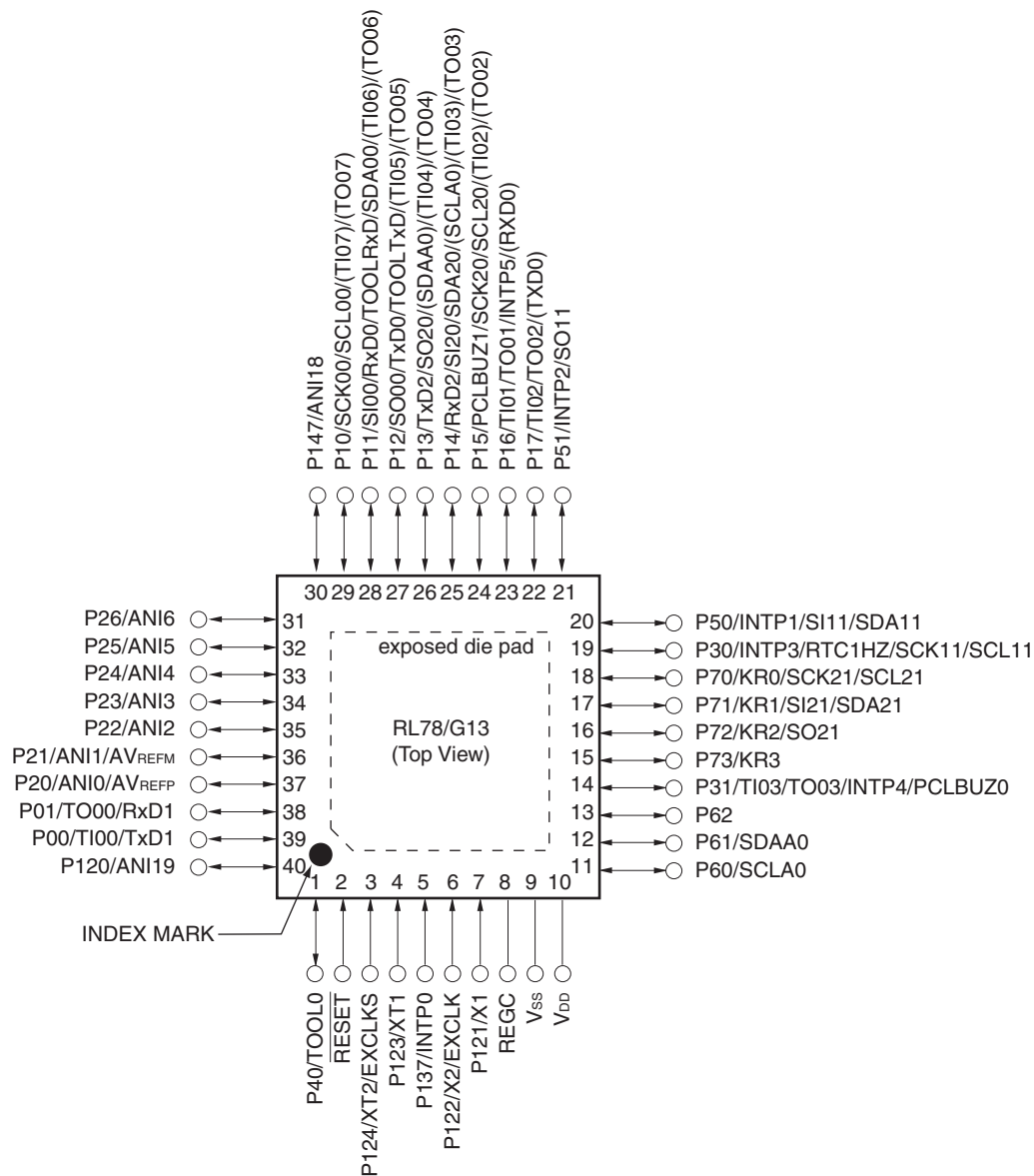
Caution Connect the REGC pin to V_{SS} via a capacitor (0.47 to 1 μ F).

Remarks 1. For pin identification, see 1.4 Pin Identification.

- Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

1.3.7 40-pin products

- 40-pin plastic HWQFN (6 × 6 mm, 0.5 mm pitch)

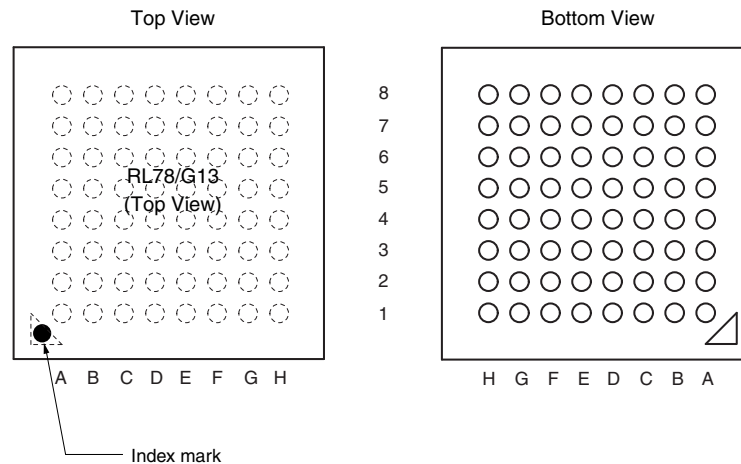


Caution Connect the REGC pin to Vss via a capacitor (0.47 to 1 μ F).

Remarks 1. For pin identification, see 1.4 Pin Identification.

- Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.
- It is recommended to connect an exposed die pad to Vss.

- 64-pin plastic VFBGA (4 × 4 mm, 0.4 mm pitch)



| Pin No. | Name | Pin No. | Name | Pin No. | Name | Pin No. | Name |
|---------|-------------------------------|---------|-----------------------------|---------|---|---------|-----------------------------|
| A1 | P05/TI05/TO05 | C1 | P51/INTP2/SO11 | E1 | P13/TxD2/SO20/(SDAA0)/(TI04)/(TO04) | G1 | P146 |
| A2 | P30/INTP3/RTC1HZ/SCK11/SCL11 | C2 | P71/KR1/SI21/SDA21 | E2 | P14/RxD2/SI20/SDA20/(SCLA0)/(TI03)/(TO03) | G2 | P25/ANI5 |
| A3 | P70/KR0/SCK21/SCL21 | C3 | P74/KR4/INTP8/SI01/SDA01 | E3 | P15/SCK20/SCL20/(TI02)/(TO02) | G3 | P24/ANI4 |
| A4 | P75/KR5/INTP9/SCK01/SCL01 | C4 | P52/(INTP10) | E4 | P16/TI01/TO01/INTP5/(SI00)/(RxD0) | G4 | P22/ANI2 |
| A5 | P77/KR7/INTP11/(TxD2) | C5 | P53/(INTP11) | E5 | P03/ANI16/SI10/RxD1/SDA10 | G5 | P130 |
| A6 | P61/SDAA0 | C6 | P63 | E6 | P41/TI07/TO07 | G6 | P02/ANI17/SO10/TxD1 |
| A7 | P60/SCLA0 | C7 | V _{SS} | E7 | RESET | G7 | P00/TI00 |
| A8 | EV _{DD0} | C8 | P121/X1 | E8 | P137/INTP0 | G8 | P124/XT2/EXCLKS |
| B1 | P50/INTP1/SI11/SDA11 | D1 | P55/(PCLBUZ1)/(SCK00) | F1 | P10/SCK00/SCL00/(TI07)/(TO07) | H1 | P147/ANI18 |
| B2 | P72/KR2/SO21 | D2 | P06/TI06/TO06 | F2 | P11/SI00/RxD0/TOOLRxD/SDA00/(TI06)/(TO06) | H2 | P27/ANI7 |
| B3 | P73/KR3/SO01 | D3 | P17/TI02/TO02/(SO00)/(TxD0) | F3 | P12/SO00/TxD0/TOOLTxD/(INTP5)/(TI05)/(TO05) | H3 | P26/ANI6 |
| B4 | P76/KR6/INTP10/(RxD2) | D4 | P54 | F4 | P21/ANI1/AV _{REFM} | H4 | P23/ANI3 |
| B5 | P31/TI03/TO03/INTP4/(PCLBUZ0) | D5 | P42/TI04/TO04 | F5 | P04/SCK10/SCL10 | H5 | P20/ANI0/AV _{REFP} |
| B6 | P62 | D6 | P40/TOOL0 | F6 | P43 | H6 | P141/PCLBUZ1/INTP7 |
| B7 | V _{DD} | D7 | REGC | F7 | P01/TO00 | H7 | P140/PCLBUZ0/INTP6 |
| B8 | EV _{SS0} | D8 | P122/X2/EXCLK | F8 | P123/XT1 | H8 | P120/ANI19 |

Cautions 1. Make EV_{SS0} pin the same potential as V_{SS} pin.

2. Make V_{DD} pin the potential that is higher than EV_{DD0} pin.

3. Connect the REGC pin to V_{SS} via a capacitor (0.47 to 1 μ F).

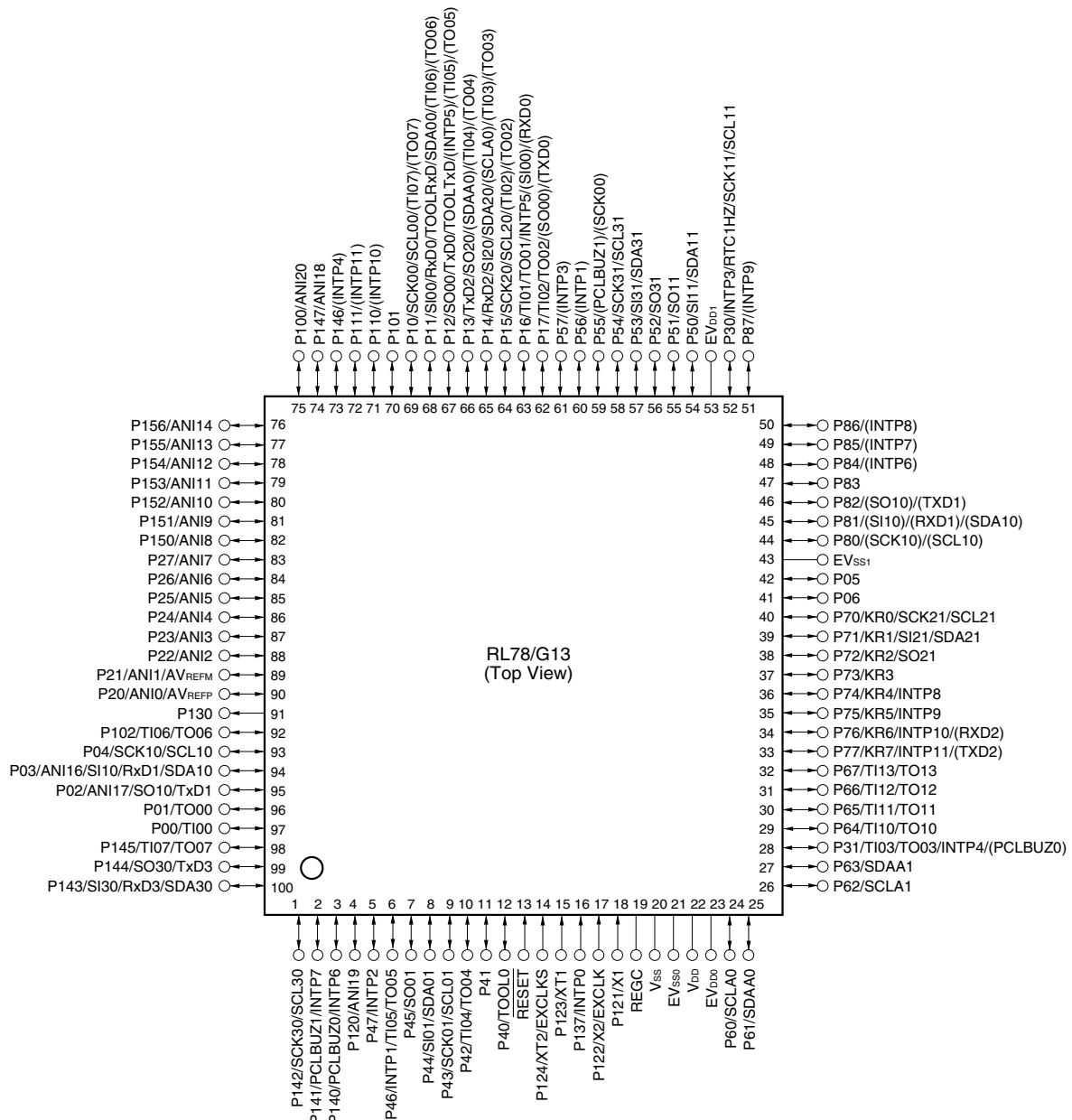
Remarks 1. For pin identification, see 1.4 Pin Identification.

2. When using the microcontroller for an application where the noise generated inside the microcontroller must be reduced, it is recommended to supply separate powers to the V_{DD} and EV_{DD0} pins and connect the V_{SS} and EV_{SS0} pins to separate ground lines.

3. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

1.3.13 100-pin products

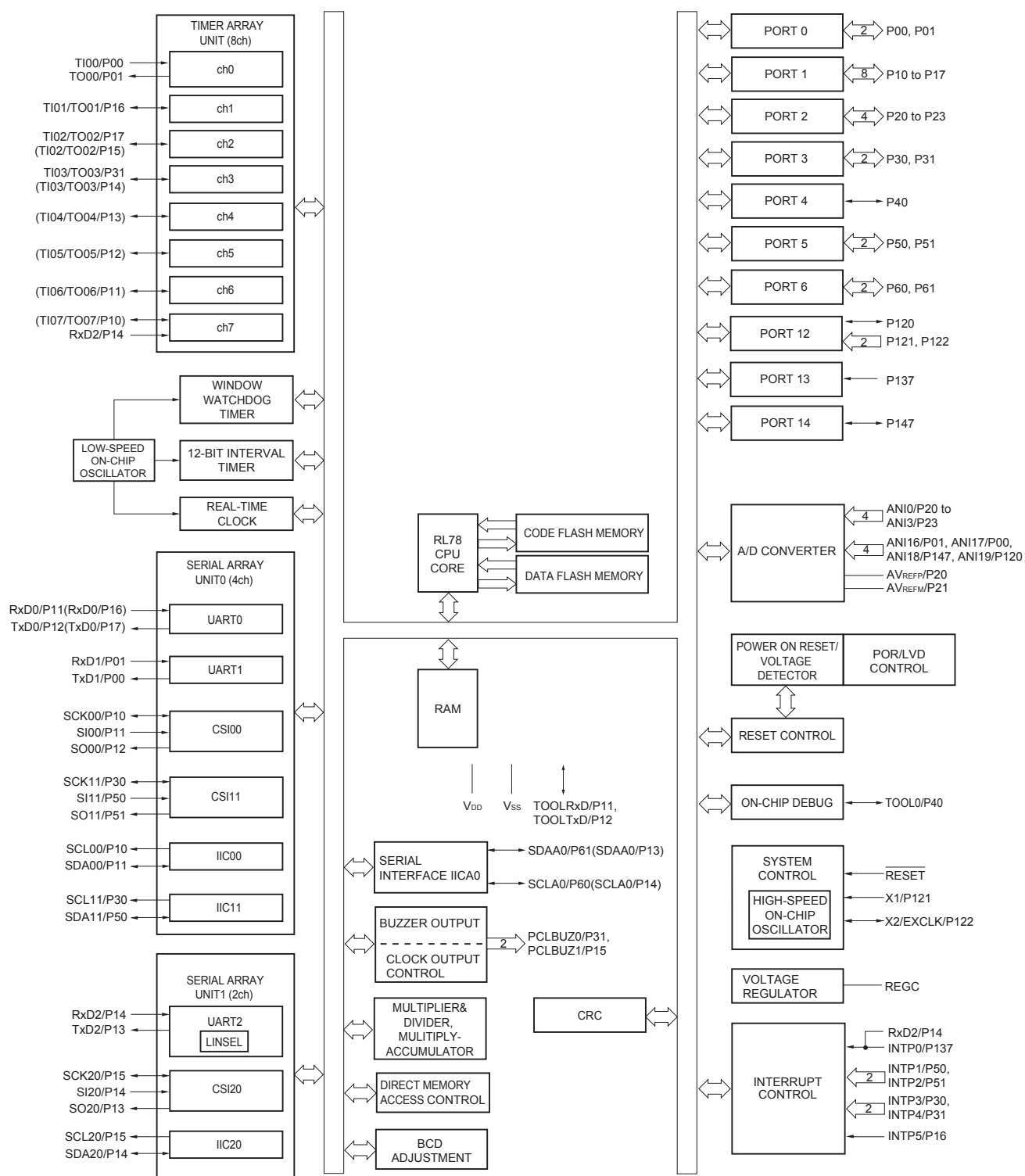
- 100-pin plastic LQFP (14 × 14 mm, 0.5 mm pitch)



- Cautions**
1. Make EV_{SS0}, EV_{SS1} pins the same potential as V_{SS} pin.
 2. Make V_{DD} pin the potential that is higher than EV_{DD0}, EV_{DD1} pins (EV_{DD0} = EV_{DD1}).
 3. Connect the REGC pin to V_{SS} via a capacitor (0.47 to 1 μ F).

- Remarks**
1. For pin identification, see 1.4 Pin Identification.
 2. When using the microcontroller for an application where the noise generated inside the microcontroller must be reduced, it is recommended to supply separate powers to the V_{DD}, EV_{DD0} and EV_{DD1} pins and connect the V_{SS}, EV_{SS0} and EV_{SS1} pins to separate ground lines.
 3. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

1.5.4 30-pin products



Remark Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

1.6 Outline of Functions

[20-pin, 24-pin, 25-pin, 30-pin, 32-pin, 36-pin products]

Caution This outline describes the functions at the time when Peripheral I/O redirection register (PIOR) is set to 00H.

(1/2)

| Item | | 20-pin | | 24-pin | | 25-pin | | 30-pin | | 32-pin | | 36-pin | |
|------------------------------------|---|---|--|--|--|--|---|--------------------------|----------|--------------------------|----------|--------------------------|----------|
| | | R5F1006x | R5F1016x | R5F1007x | R5F1017x | R5F1008x | R5F1018x | R5F100Ax | R5F101Ax | R5F100Bx | R5F101Bx | R5F100Cx | R5F101Cx |
| Code flash memory (KB) | | 16 to 64 | | 16 to 64 | | 16 to 64 | | 16 to 128 | | 16 to 128 | | 16 to 128 | |
| Data flash memory (KB) | | 4 | – | 4 | – | 4 | – | 4 to 8 | – | 4 to 8 | – | 4 to 8 | – |
| RAM (KB) | | 2 to 4 ^{Note1} | | 2 to 4 ^{Note1} | | 2 to 4 ^{Note1} | | 2 to 12 ^{Note1} | | 2 to 12 ^{Note1} | | 2 to 12 ^{Note1} | |
| Address space | | 1 MB | | | | | | | | | | | |
| Main system clock | High-speed system clock | X1 (crystal/ceramic) oscillation, external main system clock input (EXCLK) HS (High-speed main) mode: 1 to 20 MHz (V _{DD} = 2.7 to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz (V _{DD} = 2.4 to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz (V _{DD} = 1.8 to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz (V _{DD} = 1.6 to 5.5 V) | | | | | | | | | | | |
| | High-speed on-chip oscillator | HS (High-speed main) mode: 1 to 32 MHz (V _{DD} = 2.7 to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz (V _{DD} = 2.4 to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz (V _{DD} = 1.8 to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz (V _{DD} = 1.6 to 5.5 V) | | | | | | | | | | | |
| Subsystem clock | | – | | | | | | | | | | | |
| Low-speed on-chip oscillator | | 15 kHz (TYP.) | | | | | | | | | | | |
| General-purpose registers | | (8-bit register × 8) × 4 banks | | | | | | | | | | | |
| Minimum instruction execution time | | 0.03125 μs (High-speed on-chip oscillator: f _{IH} = 32 MHz operation) | | | | | | | | | | | |
| | | 0.05 μs (High-speed system clock: f _{MX} = 20 MHz operation) | | | | | | | | | | | |
| Instruction set | | <ul style="list-style-type: none">• Data transfer (8/16 bits)• Adder and subtractor/logical operation (8/16 bits)• Multiplication (8 bits × 8 bits)• Rotate, barrel shift, and bit manipulation (Set, reset, test, and Boolean operation), etc. | | | | | | | | | | | |
| I/O port | Total | 16 | 20 | 21 | 26 | 28 | 32 | | | | | | |
| | CMOS I/O | 13 (N-ch O.D. I/O [V _{DD} withstand voltage]: 5) | 15 (N-ch O.D. I/O [V _{DD} withstand voltage]: 6) | 15 (N-ch O.D. I/O [V _{DD} withstand voltage]: 6) | 21 (N-ch O.D. I/O [V _{DD} withstand voltage]: 9) | 22 (N-ch O.D. I/O [V _{DD} withstand voltage]: 9) | 26 (N-ch O.D. I/O [V _{DD} withstand voltage]: 10) | | | | | | |
| | CMOS input | 3 | 3 | 3 | 3 | 3 | 3 | | | | | | |
| | CMOS output | – | – | 1 | – | – | – | | | | | | |
| | N-ch O.D. I/O (withstand voltage: 6 V) | – | 2 | 2 | 2 | 3 | 3 | | | | | | |
| Timer | 16-bit timer | 8 channels | | | | | | | | | | | |
| | Watchdog timer | 1 channel | | | | | | | | | | | |
| | Real-time clock (RTC) | 1 channel ^{Note 2} | | | | | | | | | | | |
| | 12-bit interval timer (IT) | 1 channel | | | | | | | | | | | |
| | Timer output | 3 channels (PWM outputs: 2 ^{Note 3}) | 4 channels (PWM outputs: 3 ^{Note 3}) | | | | 4 channels (PWM outputs: 3 ^{Note 3}), 8 channels (PWM outputs: 7 ^{Note 3}) ^{Note 4} | | | | | | |
| | RTC output | – | | | | | | | | | | | |

- Notes**
- The flash library uses RAM in self-programming and rewriting of the data flash memory. The target products and start address of the RAM areas used by the flash library are shown below.
R5F100xD, R5F101xD (x = 6 to 8, A to C): Start address FF300H
R5F100xE, R5F101xE (x = 6 to 8, A to C): Start address FEF00H
For the RAM areas used by the flash library, see **Self RAM list of Flash Self-Programming Library for RL78 Family (R20UT2944)**.
 - Only the constant-period interrupt function when the low-speed on-chip oscillator clock (f_{IL}) is selected

- The number of PWM outputs varies depending on the setting of channels in use (the number of masters and slaves) (see **6.9.3 Operation as multiple PWM output function** in the RL78/G13 User's Manual).
- When setting to PIOR = 1

(2/2)

| Item | | 40-pin | | 44-pin | | 48-pin | | 52-pin | | 64-pin | |
|---|----------|---|-----------|-------------|-----------|-------------|-----------|-------------|-----------|-------------|-----------|
| | | R5F100Ex | R5F101Ex | R5F100Fx | R5F101Fx | R5F100Gx | R5F101Gx | R5F100Lx | R5F101Lx | R5F100Lx | R5F101Lx |
| Clock output/buzzer output | | 2 | | 2 | | 2 | | 2 | | 2 | |
| | | <ul style="list-style-type: none">2.44 kHz, 4.88 kHz, 9.76 kHz, 1.25 MHz, 2.5 MHz, 5 MHz, 10 MHz (Main system clock: f_{MAIN} = 20 MHz operation)256 Hz, 512 Hz, 1.024 kHz, 2.048 kHz, 4.096 kHz, 8.192 kHz, 16.384 kHz, 32.768 kHz (Subsystem clock: f_{SUB} = 32.768 kHz operation) | | | | | | | | | |
| 8/10-bit resolution A/D converter | | 9 channels | | 10 channels | | 10 channels | | 12 channels | | 12 channels | |
| Serial interface | | [40-pin, 44-pin products] <ul style="list-style-type: none">CSI: 1 channel/simplified I²C: 1 channel/UART: 1 channelCSI: 1 channel/simplified I²C: 1 channel/UART: 1 channelCSI: 2 channels/simplified I²C: 2 channels/UART (UART supporting LIN-bus): 1 channel [48-pin, 52-pin products] <ul style="list-style-type: none">CSI: 2 channels/simplified I²C: 2 channels/UART: 1 channelCSI: 1 channel/simplified I²C: 1 channel/UART: 1 channelCSI: 2 channels/simplified I²C: 2 channels/UART (UART supporting LIN-bus): 1 channel [64-pin products] <ul style="list-style-type: none">CSI: 2 channels/simplified I²C: 2 channels/UART: 1 channelCSI: 2 channels/simplified I²C: 2 channels/UART: 1 channelCSI: 2 channels/simplified I²C: 2 channels/UART (UART supporting LIN-bus): 1 channel | | | | | | | | | |
| | | I ² C bus | 1 channel | | 1 channel | | 1 channel | | 1 channel | | 1 channel |
| Multiplier and divider/multiply-accumulator | | <ul style="list-style-type: none">16 bits × 16 bits = 32 bits (Unsigned or signed)32 bits ÷ 32 bits = 32 bits (Unsigned)16 bits × 16 bits + 32 bits = 32 bits (Unsigned or signed) | | | | | | | | | |
| DMA controller | | 2 channels | | | | | | | | | |
| Vectored interrupt sources | Internal | 27 | | 27 | | 27 | | 27 | | 27 | |
| | External | 7 | | 7 | | 10 | | 12 | | 13 | |
| Key interrupt | | 4 | | 4 | | 6 | | 8 | | 8 | |
| Reset | | <ul style="list-style-type: none">Reset by RESET pinInternal reset by watchdog timerInternal reset by power-on-resetInternal reset by voltage detectorInternal reset by illegal instruction execution ^{Note}Internal reset by RAM parity errorInternal reset by illegal-memory access | | | | | | | | | |
| Power-on-reset circuit | | <ul style="list-style-type: none">Power-on-reset: 1.51 V (TYP.)Power-down-reset: 1.50 V (TYP.) | | | | | | | | | |
| Voltage detector | | <ul style="list-style-type: none">Rising edge : 1.67 V to 4.06 V (14 stages)Falling edge : 1.63 V to 3.98 V (14 stages) | | | | | | | | | |
| On-chip debug function | | Provided | | | | | | | | | |
| Power supply voltage | | V _{DD} = 1.6 to 5.5 V (T _A = -40 to +85°C) V _{DD} = 2.4 to 5.5 V (T _A = -40 to +105°C) | | | | | | | | | |
| Operating ambient temperature | | T _A = 40 to +85°C (A: Consumer applications, D: Industrial applications) T _A = 40 to +105°C (G: Industrial applications) | | | | | | | | | |

Note The illegal instruction is generated when instruction code FFH is executed.

Reset by the illegal instruction execution not issued by emulation with the in-circuit emulator or on-chip debug emulator.

<R>

[80-pin, 100-pin, 128-pin products]

Caution This outline describes the functions at the time when Peripheral I/O redirection register (PIOR) is set to 00H.

(1/2)

| Item | | 80-pin | | 100-pin | | 128-pin | |
|------------------------------------|--|---|----------|--|----------|---|----------|
| | | R5F100Mx | R5F101Mx | R5F100Px | R5F101Px | R5F100Sx | R5F101Sx |
| Code flash memory (KB) | | 96 to 512 | | 96 to 512 | | 192 to 512 | |
| Data flash memory (KB) | | 8 | — | 8 | — | 8 | — |
| RAM (KB) | | 8 to 32 ^{Note 1} | | 8 to 32 ^{Note 1} | | 16 to 32 ^{Note 1} | |
| Address space | | 1 MB | | | | | |
| Main system clock | High-speed system clock | X1 (crystal/ceramic) oscillation, external main system clock input (EXCLK) HS (High-speed main) mode: 1 to 20 MHz (V _{DD} = 2.7 to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz (V _{DD} = 2.4 to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz (V _{DD} = 1.8 to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz (V _{DD} = 1.6 to 5.5 V) | | | | | |
| | High-speed on-chip oscillator | HS (High-speed main) mode: 1 to 32 MHz (V _{DD} = 2.7 to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz (V _{DD} = 2.4 to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz (V _{DD} = 1.8 to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz (V _{DD} = 1.6 to 5.5 V) | | | | | |
| Subsystem clock | | XT1 (crystal) oscillation, external subsystem clock input (EXCLKS) 32.768 kHz | | | | | |
| Low-speed on-chip oscillator | | 15 kHz (TYP.) | | | | | |
| General-purpose register | | (8-bit register × 8) × 4 banks | | | | | |
| Minimum instruction execution time | | 0.03125 μs (High-speed on-chip oscillator: f _{IH} = 32 MHz operation) | | | | | |
| | | 0.05 μs (High-speed system clock: f _{MX} = 20 MHz operation) | | | | | |
| | | 30.5 μs (Subsystem clock: f _{SUB} = 32.768 kHz operation) | | | | | |
| Instruction set | | <ul style="list-style-type: none">• Data transfer (8/16 bits)• Adder and subtractor/logical operation (8/16 bits)• Multiplication (8 bits × 8 bits)• Rotate, barrel shift, and bit manipulation (Set, reset, test, and Boolean operation), etc. | | | | | |
| I/O port | Total | 74 | | 92 | | 120 | |
| | CMOS I/O | 64 (N-ch O.D. I/O [EVD _D withstand voltage]: 21) | | 82 (N-ch O.D. I/O [EVD _D withstand voltage]: 24) | | 110 (N-ch O.D. I/O [EVD _D withstand voltage]: 25) | |
| | CMOS input | 5 | | 5 | | 5 | |
| | CMOS output | 1 | | 1 | | 1 | |
| | N-ch O.D. I/O (withstand voltage: 6 V) | 4 | | 4 | | 4 | |
| Timer | 16-bit timer | 12 channels | | 12 channels | | 16 channels | |
| | Watchdog timer | 1 channel | | 1 channel | | 1 channel | |
| | Real-time clock (RTC) | 1 channel | | 1 channel | | 1 channel | |
| | 12-bit interval timer (IT) | 1 channel | | 1 channel | | 1 channel | |
| | Timer output | 12 channels (PWM outputs: 10 ^{Note 2}) | | 12 channels (PWM outputs: 10 ^{Note 2}) | | 16 channels (PWM outputs: 14 ^{Note 2}) | |
| | RTC output | 1 channel • 1 Hz (subsystem clock: f _{SUB} = 32.768 kHz) | | | | | |

Notes 1. The flash library uses RAM in self-programming and rewriting of the data flash memory.

The target products and start address of the RAM areas used by the flash library are shown below.

R5F100xJ, R5F101xJ (x = M, P): Start address FAF00H

R5F100xL, R5F101xL (x = M, P, S): Start address F7F00H

For the RAM areas used by the flash library, see **Self RAM list of Flash Self-Programming Library for RL78 Family (R20UT2944)**.

2.1 Absolute Maximum Ratings

Absolute Maximum Ratings (T_A = 25°C) (1/2)

| Parameter | Symbols | Conditions | Ratings | Unit |
|------------------------|---------------------------------------|---|--|------|
| Supply voltage | V _{DD} | | -0.5 to +6.5 | V |
| | EV _{DD0} , EV _{DD1} | EV _{DD0} = EV _{DD1} | -0.5 to +6.5 | V |
| | EV _{SS0} , EV _{SS1} | EV _{SS0} = EV _{SS1} | -0.5 to +0.3 | V |
| REGC pin input voltage | V _{IREGC} | REGC | -0.3 to +2.8 and -0.3 to V _{DD} + 0.3 ^{Note 1} | V |
| Input voltage | V _{I1} | P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147 | -0.3 to EV _{DD0} + 0.3 and -0.3 to V _{DD} + 0.3 ^{Note 2} | V |
| | V _{I2} | P60 to P63 (N-ch open-drain) | -0.3 to +6.5 | V |
| | V _{I3} | P20 to P27, P121 to P124, P137, P150 to P156, EXCLK, EXCLKS, RESET | -0.3 to V _{DD} + 0.3 ^{Note 2} | V |
| Output voltage | V _{O1} | P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147 | -0.3 to EV _{DD0} + 0.3 and -0.3 to V _{DD} + 0.3 ^{Note 2} | V |
| | V _{O2} | P20 to P27, P150 to P156 | -0.3 to V _{DD} + 0.3 ^{Note 2} | V |
| Analog input voltage | V _{AI1} | ANI16 to ANI26 | -0.3 to EV _{DD0} + 0.3 and -0.3 to AV _{REF} (+) + 0.3 ^{Notes 2, 3} | V |
| | V _{AI2} | ANI0 to ANI14 | -0.3 to V _{DD} + 0.3 and -0.3 to AV _{REF} (+) + 0.3 ^{Notes 2, 3} | V |

Notes 1. Connect the REGC pin to V_{SS} via a capacitor (0.47 to 1 μF). This value regulates the absolute maximum rating of the REGC pin. Do not use this pin with voltage applied to it.

2. Must be 6.5 V or lower.

3. Do not exceed AV_{REF}(+) + 0.3 V in case of A/D conversion target pin.

Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

Remarks 1. Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

2. AV_{REF}(+) : + side reference voltage of the A/D converter.

3. V_{SS} : Reference voltage

2.3.2 Supply current characteristics

(1) Flash ROM: 16 to 64 KB of 20- to 64-pin products

(T_A = -40 to +85°C, 1.6 V ≤ E_{VDD0} ≤ V_{DD} ≤ 5.5 V, V_{SS} = E_{VSS0} = 0 V) (1/2)

| Parameter | Symbol | Conditions | | | | MIN. | TYP. | MAX. | Unit | | | |
|----------------------------------|------------------|----------------|---|---|---|--|-------------------------|----------------------|------|-----|-----|----|
| Supply current ^{Note 1} | I _{DD1} | Operating mode | HS (high-speed main) mode ^{Note 5} | f _{IH} = 32 MHz ^{Note 3} | Basic operation | V _{DD} = 5.0 V | | 2.1 | | mA | | |
| | | | | | | V _{DD} = 3.0 V | | 2.1 | | mA | | |
| | | | | | Normal operation | V _{DD} = 5.0 V | | 4.6 | 7.0 | mA | | |
| | | | | | | V _{DD} = 3.0 V | | 4.6 | 7.0 | mA | | |
| | | | | f _{IH} = 24 MHz ^{Note 3} | Normal operation | V _{DD} = 5.0 V | | 3.7 | 5.5 | mA | | |
| | | | | | | V _{DD} = 3.0 V | | 3.7 | 5.5 | mA | | |
| | | | | f _{IH} = 16 MHz ^{Note 3} | Normal operation | V _{DD} = 5.0 V | | 2.7 | 4.0 | mA | | |
| | | | | | | V _{DD} = 3.0 V | | 2.7 | 4.0 | mA | | |
| | | | | LS (low-speed main) mode ^{Note 5} | f _{IH} = 8 MHz ^{Note 3} | Normal operation | V _{DD} = 3.0 V | | 1.2 | 1.8 | mA | |
| | | | | | | | V _{DD} = 2.0 V | | 1.2 | 1.8 | mA | |
| | | | | LV (low-voltage main) mode ^{Note 5} | f _{IH} = 4 MHz ^{Note 3} | Normal operation | V _{DD} = 3.0 V | | 1.2 | 1.7 | mA | |
| | | | | | | | V _{DD} = 2.0 V | | 1.2 | 1.7 | mA | |
| | | | HS (high-speed main) mode ^{Note 5} | f _{MX} = 20 MHz ^{Note 2} , V _{DD} = 5.0 V | Normal operation | Square wave input | | 3.0 | 4.6 | mA | | |
| | | | | | | Resonator connection | | 3.2 | 4.8 | mA | | |
| | | | | | f _{MX} = 20 MHz ^{Note 2} , V _{DD} = 3.0 V | Normal operation | Square wave input | | 3.0 | 4.6 | mA | |
| | | | | | | | Resonator connection | | 3.2 | 4.8 | mA | |
| | | | | | f _{MX} = 10 MHz ^{Note 2} , V _{DD} = 5.0 V | Normal operation | Square wave input | | 1.9 | 2.7 | mA | |
| | | | | | | | Resonator connection | | 1.9 | 2.7 | mA | |
| | | | | f _{MX} = 10 MHz ^{Note 2} , V _{DD} = 3.0 V | Normal operation | Square wave input | | 1.9 | 2.7 | mA | | |
| | | | | | | Resonator connection | | 1.9 | 2.7 | mA | | |
| | | | | | LS (low-speed main) mode ^{Note 5} | f _{MX} = 8 MHz ^{Note 2} , V _{DD} = 3.0 V | Normal operation | Square wave input | | 1.1 | 1.7 | mA |
| | | | | | | | | Resonator connection | | 1.1 | 1.7 | mA |
| | | | | | | f _{MX} = 8 MHz ^{Note 2} , V _{DD} = 2.0 V | Normal operation | Square wave input | | 1.1 | 1.7 | mA |
| | | | | | | | | Resonator connection | | 1.1 | 1.7 | mA |
| | | | Subsystem clock operation | f _{SUB} = 32.768 kHz ^{Note 4} T _A = −40°C | Normal operation | Square wave input | | 4.1 | 4.9 | μA | | |
| | | | | | | Resonator connection | | 4.2 | 5.0 | μA | | |
| | | | | f _{SUB} = 32.768 kHz ^{Note 4} T _A = +25°C | Normal operation | Square wave input | | 4.1 | 4.9 | μA | | |
| | | | | | | Resonator connection | | 4.2 | 5.0 | μA | | |
| | | | | f _{SUB} = 32.768 kHz ^{Note 4} T _A = +50°C | Normal operation | Square wave input | | 4.2 | 5.5 | μA | | |
| | | | | | | Resonator connection | | 4.3 | 5.6 | μA | | |
| | | | | f _{SUB} = 32.768 kHz ^{Note 4} T _A = +70°C | Normal operation | Square wave input | | 4.3 | 6.3 | μA | | |
| | | | | | | Resonator connection | | 4.4 | 6.4 | μA | | |
| | | | | f _{SUB} = 32.768 kHz ^{Note 4} T _A = +85°C | Normal operation | Square wave input | | 4.6 | 7.7 | μA | | |
| | | | | | | Resonator connection | | 4.7 | 7.8 | μA | | |

(Notes and Remarks are listed on the next page.)

- Notes**
1. Total current flowing into V_{DD}, EV_{DD0}, and EV_{DD1}, including the input leakage current flowing when the level of the input pin is fixed to V_{DD}, EV_{DD0}, and EV_{DD1}, or V_{SS}, EV_{SS0}, and EV_{SS1}. The values below the MAX. column include the peripheral operation current. However, not including the current flowing into the A/D converter, LVD circuit, I/O port, and on-chip pull-up/pull-down resistors and the current flowing during data flash rewrite.
 2. When high-speed on-chip oscillator and subsystem clock are stopped.
 3. When high-speed system clock and subsystem clock are stopped.
 4. When high-speed on-chip oscillator and high-speed system clock are stopped. When AMPHS1 = 1 (Ultra-low power consumption oscillation). However, not including the current flowing into the 12-bit interval timer and watchdog timer.
 5. Relationship between operation voltage width, operation frequency of CPU and operation mode is as below.
 - HS (high-speed main) mode: $2.7\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ @ 1 MHz to 32 MHz
 - $2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ @ 1 MHz to 16 MHz
 - LS (low-speed main) mode: $1.8\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ @ 1 MHz to 8 MHz
 - LV (low-voltage main) mode: $1.6\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ @ 1 MHz to 4 MHz

- Remarks**
1. f_{MX}: High-speed system clock frequency (X1 clock oscillation frequency or external main system clock frequency)
 2. f_{IH}: High-speed on-chip oscillator clock frequency
 3. f_{SUB}: Subsystem clock frequency (XT1 clock oscillation frequency)
 4. Except subsystem clock operation, temperature condition of the TYP. value is T_A = 25°C

6. Current flowing only to the A/D converter. The supply current of the RL78 microcontrollers is the sum of I_{DD1} or I_{DD2} and I_{ADC} when the A/D converter operates in an operation mode or the HALT mode.
7. Current flowing only to the LVD circuit. The supply current of the RL78 microcontrollers is the sum of I_{DD1} , I_{DD2} or I_{DD3} and I_{LVD} when the LVD circuit is in operation.
8. Current flowing only during data flash rewrite.
9. Current flowing only during self programming.
10. For shift time to the SNOOZE mode, see **18.3.3 SNOOZE mode**.

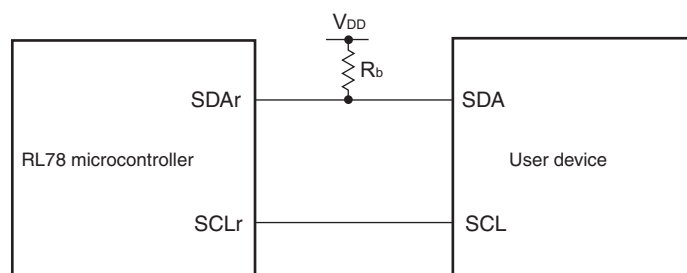
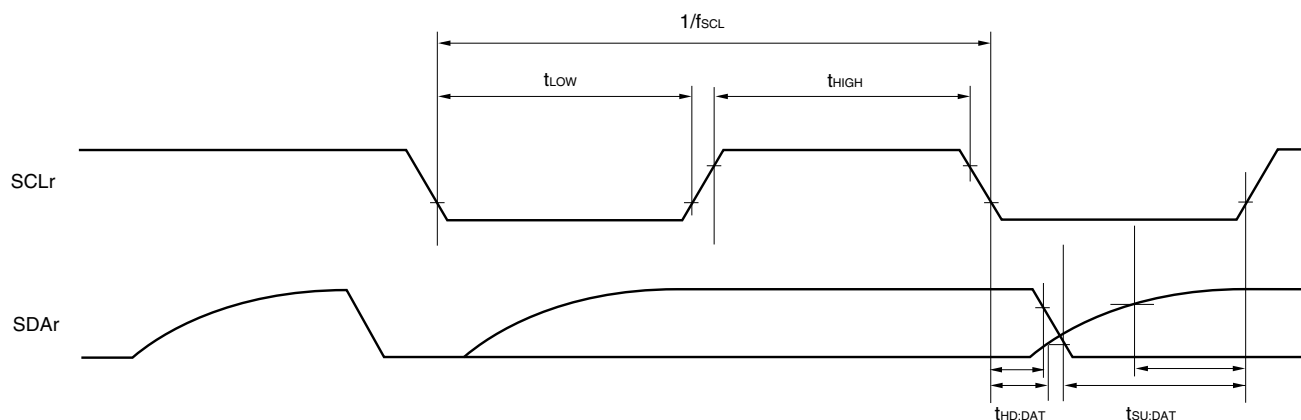
- Remarks**
1. f_{IL} : Low-speed on-chip oscillator clock frequency
 2. f_{SUB} : Subsystem clock frequency (XT1 clock oscillation frequency)
 3. f_{CLK} : CPU/peripheral hardware clock frequency
 4. Temperature condition of the TYP. value is $T_A = 25^{\circ}\text{C}$

- Remarks 1.** p: CSI number (p = 00, 01, 10, 11, 20, 21, 30, 31), m: Unit number (m = 0, 1), n: Channel number (n = 0 to 3),
g: PIM and POM numbers (g = 0, 1, 4, 5, 8, 14)
- 2.** f_{MCK}: Serial array unit operation clock frequency
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number,
n: Channel number (mn = 00 to 03, 10 to 13))

(4) During communication at same potential (CSI mode) (slave mode, SCKp... external clock input) (1/2)
(T_A = -40 to +85°C, 1.6 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V)

| Parameter | Symbol | Conditions | | HS (high-speed main) Mode | | LS (low-speed main) Mode | | LV (low-voltage main) Mode | | Unit |
|--|--|-----------------------------------|---------------------------|--------------------------------|------|--------------------------------|------|--------------------------------|------|------|
| | | | | MIN. | MAX. | MIN. | MAX. | MIN. | MAX. | |
| SCKp cycle time <small>Note 5</small> | t _{KCY2} | 4.0 V ≤ EV _{DD0} ≤ 5.5 V | 20 MHz < f _{MCK} | 8/f _{MCK} | | — | | — | | ns |
| | | | f _{MCK} ≤ 20 MHz | 6/f _{MCK} | | 6/f _{MCK} | | 6/f _{MCK} | | ns |
| | | 2.7 V ≤ EV _{DD0} ≤ 5.5 V | 16 MHz < f _{MCK} | 8/f _{MCK} | | — | | — | | ns |
| | | | f _{MCK} ≤ 16 MHz | 6/f _{MCK} | | 6/f _{MCK} | | 6/f _{MCK} | | ns |
| | | 2.4 V ≤ EV _{DD0} ≤ 5.5 V | | 6/f _{MCK} and 500 | | 6/f _{MCK} and 500 | | 6/f _{MCK} and 500 | | ns |
| | | 1.8 V ≤ EV _{DD0} ≤ 5.5 V | | 6/f _{MCK} and 750 | | 6/f _{MCK} and 750 | | 6/f _{MCK} and 750 | | ns |
| | | 1.7 V ≤ EV _{DD0} ≤ 5.5 V | | 6/f _{MCK} and 1500 | | 6/f _{MCK} and 1500 | | 6/f _{MCK} and 1500 | | ns |
| | | 1.6 V ≤ EV _{DD0} ≤ 5.5 V | | — | | 6/f _{MCK} and 1500 | | 6/f _{MCK} and 1500 | | ns |
| SCKp high-/low-level width | t _{KH2} , t _{KL2} | 4.0 V ≤ EV _{DD0} ≤ 5.5 V | | t _{KCY2} /2 – 7 | | t _{KCY2} /2 – 7 | | t _{KCY2} /2 – 7 | | ns |
| | | 2.7 V ≤ EV _{DD0} ≤ 5.5 V | | t _{KCY2} /2 – 8 | | t _{KCY2} /2 – 8 | | t _{KCY2} /2 – 8 | | ns |
| | | 1.8 V ≤ EV _{DD0} ≤ 5.5 V | | t _{KCY2} /2 – 18 | | t _{KCY2} /2 – 18 | | t _{KCY2} /2 – 18 | | ns |
| | | 1.7 V ≤ EV _{DD0} ≤ 5.5 V | | t _{KCY2} /2 – 66 | | t _{KCY2} /2 – 66 | | t _{KCY2} /2 – 66 | | ns |
| | | 1.6 V ≤ EV _{DD0} ≤ 5.5 V | | — | | t _{KCY2} /2 – 66 | | t _{KCY2} /2 – 66 | | ns |

(Notes, Caution, and Remarks are listed on the next page.)

Simplified I²C mode connection diagram (during communication at same potential)**Simplified I²C mode serial transfer timing (during communication at same potential)**

- Remarks**
1. $R_b[\Omega]$: Communication line (SDAr) pull-up resistance, $C_b[F]$: Communication line (SDAr, SCLr) load capacitance
 2. r: IIC number (r = 00, 01, 10, 11, 20, 21, 30, 31), g: PIM number (g = 0, 1, 4, 5, 8, 14),
h: POM number (g = 0, 1, 4, 5, 7 to 9, 14)
 3. f_{MCK} : Serial array unit operation clock frequency
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number (m = 0, 1),
n: Channel number (n = 0 to 3), mn = 00 to 03, 10 to 13)

(9) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (slave mode, SCKp... external clock input)

(T_A = -40 to +85°C, 1.8 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V) (1/2)

| Parameter | Symbol | Conditions | | HS (high-speed main) Mode | | LS (low-speed main) Mode | | LV (low-voltage main) Mode | | Unit |
|-----------------------------------|-------------------|--|------------------------------------|---------------------------|------|--------------------------|------|----------------------------|------|------|
| | | | | MIN. | MAX. | MIN. | MAX. | MIN. | MAX. | |
| SCKp cycle time ^{Note 1} | t _{KCY2} | 4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V | 24 MHz < f _{MCK} | 14/ f _{MCK} | | — | | — | | ns |
| | | | 20 MHz < f _{MCK} ≤ 24 MHz | 12/ f _{MCK} | | — | | — | | ns |
| | | | 8 MHz < f _{MCK} ≤ 20 MHz | 10/ f _{MCK} | | — | | — | | ns |
| | | | 4 MHz < f _{MCK} ≤ 8 MHz | 8/f _{MCK} | | 16/ f _{MCK} | | — | | ns |
| | | | f _{MCK} ≤ 4 MHz | 6/f _{MCK} | | 10/ f _{MCK} | | 10/ f _{MCK} | | ns |
| | | 2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V | 24 MHz < f _{MCK} | 20/ f _{MCK} | | — | | — | | ns |
| | | | 20 MHz < f _{MCK} ≤ 24 MHz | 16/ f _{MCK} | | — | | — | | ns |
| | | | 16 MHz < f _{MCK} ≤ 20 MHz | 14/ f _{MCK} | | — | | — | | ns |
| | | | 8 MHz < f _{MCK} ≤ 16 MHz | 12/ f _{MCK} | | — | | — | | ns |
| | | | 4 MHz < f _{MCK} ≤ 8 MHz | 8/f _{MCK} | | 16/ f _{MCK} | | — | | ns |
| | | | f _{MCK} ≤ 4 MHz | 6/f _{MCK} | | 10/ f _{MCK} | | 10/ f _{MCK} | | ns |
| | | 1.8 V ≤ EV _{DD0} < 3.3 V, 1.6 V ≤ V _b ≤ 2.0 V ^{Note 2} | 24 MHz < f _{MCK} | 48/ f _{MCK} | | — | | — | | ns |
| | | | 20 MHz < f _{MCK} ≤ 24 MHz | 36/ f _{MCK} | | — | | — | | ns |
| | | | 16 MHz < f _{MCK} ≤ 20 MHz | 32/ f _{MCK} | | — | | — | | ns |
| | | | 8 MHz < f _{MCK} ≤ 16 MHz | 26/ f _{MCK} | | — | | — | | ns |
| | | | 4 MHz < f _{MCK} ≤ 8 MHz | 16/ f _{MCK} | | 16/ f _{MCK} | | — | | ns |
| | | | f _{MCK} ≤ 4 MHz | 10/ f _{MCK} | | 10/ f _{MCK} | | 10/ f _{MCK} | | ns |

(Notes and Caution are listed on the next page, and Remarks are listed on the page after the next page.)

3. ELECTRICAL SPECIFICATIONS (G: INDUSTRIAL APPLICATIONS $T_A = -40$ to $+105^\circ\text{C}$)

This chapter describes the following electrical specifications.

Target products G: Industrial applications $T_A = -40$ to $+105^\circ\text{C}$
R5F100xxGxx

- Cautions**
1. The RL78 microcontrollers have an on-chip debug function, which is provided for development and evaluation. Do not use the on-chip debug function in products designated for mass production, because the guaranteed number of rewritable times of the flash memory may be exceeded when this function is used, and product reliability therefore cannot be guaranteed. Renesas Electronics is not liable for problems occurring when the on-chip debug function is used.
 2. With products not provided with an EV_{DD0} , EV_{DD1} , EV_{SS0} , or EV_{SS1} pin, replace EV_{DD0} and EV_{DD1} with V_{DD} , or replace EV_{SS0} and EV_{SS1} with V_{SS} .
 3. The pins mounted depend on the product. Refer to 2.1 Port Function to 2.2.1 Functions for each product.
 4. Please contact Renesas Electronics sales office for derating of operation under $T_A = +85^\circ\text{C}$ to $+105^\circ\text{C}$. Derating is the systematic reduction of load for the sake of improved reliability.

Remark When RL78/G13 is used in the range of $T_A = -40$ to $+85^\circ\text{C}$, see **CHAPTER 2 ELECTRICAL SPECIFICATIONS ($T_A = -40$ to $+85^\circ\text{C}$)**.

There are following differences between the products "G: Industrial applications ($T_A = -40$ to $+105^\circ\text{C}$)" and the products "A: Consumer applications, and D: Industrial applications".

| Parameter | Application | |
|--|--|---|
| | A: Consumer applications, D: Industrial applications | G: Industrial applications |
| Operating ambient temperature | $T_A = -40$ to $+85^\circ\text{C}$ | $T_A = -40$ to $+105^\circ\text{C}$ |
| Operating mode Operating voltage range | HS (high-speed main) mode: $2.7\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}@1\text{ MHz to }32\text{ MHz}$ $2.4\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}@1\text{ MHz to }16\text{ MHz}$ LS (low-speed main) mode: $1.8\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}@1\text{ MHz to }8\text{ MHz}$ LV (low-voltage main) mode: $1.6\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}@1\text{ MHz to }4\text{ MHz}$ | HS (high-speed main) mode only: $2.7\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}@1\text{ MHz to }32\text{ MHz}$ $2.4\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}@1\text{ MHz to }16\text{ MHz}$ |
| High-speed on-chip oscillator clock accuracy | $1.8\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}$ $\pm 1.0\% @ T_A = -20$ to $+85^\circ\text{C}$ $\pm 1.5\% @ T_A = -40$ to -20°C $1.6\text{ V} \leq \text{V}_{\text{DD}} < 1.8\text{ V}$ $\pm 5.0\% @ T_A = -20$ to $+85^\circ\text{C}$ $\pm 5.5\% @ T_A = -40$ to -20°C | $2.4\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}$ $\pm 2.0\% @ T_A = +85$ to $+105^\circ\text{C}$ $\pm 1.0\% @ T_A = -20$ to $+85^\circ\text{C}$ $\pm 1.5\% @ T_A = -40$ to -20°C |
| Serial array unit | UART CSI: $f_{\text{CLK}}/2$ (supporting 16 Mbps), $f_{\text{CLK}}/4$ Simplified I ² C communication | UART CSI: $f_{\text{CLK}}/4$ Simplified I ² C communication |
| IICA | Normal mode Fast mode Fast mode plus | Normal mode Fast mode |
| Voltage detector | Rise detection voltage: 1.67 V to 4.06 V (14 levels) Fall detection voltage: 1.63 V to 3.98 V (14 levels) | Rise detection voltage: 2.61 V to 4.06 V (8 levels) Fall detection voltage: 2.55 V to 3.98 V (8 levels) |

(Remark is listed on the next page.)

3.2 Oscillator Characteristics

3.2.1 X1, XT1 oscillator characteristics

($T_A = -40$ to $+105^\circ\text{C}$, $2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}$, $V_{SS} = 0\text{ V}$)

| Parameter | Resonator | Conditions | MIN. | TYP. | MAX. | Unit |
|---|---|--|------|--------|------|------|
| X1 clock oscillation frequency (f_x) ^{Note} | Ceramic resonator/ crystal resonator | $2.7\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ | 1.0 | | 20.0 | MHz |
| | | $2.4\text{ V} \leq V_{DD} < 2.7\text{ V}$ | 1.0 | | 16.0 | MHz |
| XT1 clock oscillation frequency (f_x) ^{Note} | Crystal resonator | | 32 | 32.768 | 35 | kHz |

Note Indicates only permissible oscillator frequency ranges. Refer to AC Characteristics for instruction execution time. Request evaluation by the manufacturer of the oscillator circuit mounted on a board to check the oscillator characteristics.

Caution Since the CPU is started by the high-speed on-chip oscillator clock after a reset release, check the X1 clock oscillation stabilization time using the oscillation stabilization time counter status register (OSTC) by the user. Determine the oscillation stabilization time of the OSTC register and the oscillation stabilization time select register (OSTS) after sufficiently evaluating the oscillation stabilization time with the resonator to be used.

Remark When using the X1 oscillator and XT1 oscillator, refer to 5.4 System Clock Oscillator.

3.2.2 On-chip oscillator characteristics

($T_A = -40$ to $+105^\circ\text{C}$, $2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}$, $V_{SS} = 0\text{ V}$)

| Oscillators | Parameters | Conditions | | MIN. | TYP. | MAX. | Unit |
|---|------------|-------------------------------|--|--------|------|--------|------|
| High-speed on-chip oscillator clock frequency ^{Notes 1, 2} | f_{IH} | | | 1 | | 32 | MHz |
| High-speed on-chip oscillator clock frequency accuracy | | -20 to $+85^\circ\text{C}$ | $2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ | -1.0 | | $+1.0$ | % |
| | | -40 to -20°C | $2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ | -1.5 | | $+1.5$ | % |
| | | $+85$ to $+105^\circ\text{C}$ | $2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ | -2.0 | | $+2.0$ | % |
| Low-speed on-chip oscillator clock frequency | f_{IL} | | | | 15 | | kHz |
| Low-speed on-chip oscillator clock frequency accuracy | | | | -15 | | $+15$ | % |

Notes 1. High-speed on-chip oscillator frequency is selected by bits 0 to 3 of option byte (000C2H/010C2H) and bits 0 to 2 of HOCODIV register.

2. This indicates the oscillator characteristics only. Refer to AC Characteristics for instruction execution time.

(6) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock output) (2/3)**($T_A = -40$ to $+105^\circ\text{C}$, $2.4\text{ V} \leq \text{EV}_{\text{DD0}} = \text{EV}_{\text{DD1}} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}$, $\text{V}_{\text{SS}} = \text{EV}_{\text{SS0}} = \text{EV}_{\text{SS1}} = 0\text{ V}$)**

| Parameter | Symbol | Conditions | HS (high-speed main) Mode | | Unit |
|--|-------------------|--|---------------------------|------|------|
| | | | MIN. | MAX. | |
| Slp setup time (to SCKp \uparrow) ^{Note} | t_{SIK1} | $4.0\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$, $2.7\text{ V} \leq \text{V}_b \leq 4.0\text{ V}$, $\text{C}_b = 30\text{ pF}$, $\text{R}_b = 1.4\text{ k}\Omega$ | 162 | | ns |
| | | $2.7\text{ V} \leq \text{EV}_{\text{DD0}} < 4.0\text{ V}$, $2.3\text{ V} \leq \text{V}_b \leq 2.7\text{ V}$, $\text{C}_b = 30\text{ pF}$, $\text{R}_b = 2.7\text{ k}\Omega$ | 354 | | ns |
| | | $2.4\text{ V} \leq \text{EV}_{\text{DD0}} < 3.3\text{ V}$, $1.6\text{ V} \leq \text{V}_b \leq 2.0\text{ V}$, $\text{C}_b = 30\text{ pF}$, $\text{R}_b = 5.5\text{ k}\Omega$ | 958 | | ns |
| Slp hold time (from SCKp \uparrow) ^{Note} | t_{KSI1} | $4.0\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$, $2.7\text{ V} \leq \text{V}_b \leq 4.0\text{ V}$, $\text{C}_b = 30\text{ pF}$, $\text{R}_b = 1.4\text{ k}\Omega$ | 38 | | ns |
| | | $2.7\text{ V} \leq \text{EV}_{\text{DD0}} < 4.0\text{ V}$, $2.3\text{ V} \leq \text{V}_b \leq 2.7\text{ V}$, $\text{C}_b = 30\text{ pF}$, $\text{R}_b = 2.7\text{ k}\Omega$ | 38 | | ns |
| | | $2.4\text{ V} \leq \text{EV}_{\text{DD0}} < 3.3\text{ V}$, $1.6\text{ V} \leq \text{V}_b \leq 2.0\text{ V}$, $\text{C}_b = 30\text{ pF}$, $\text{R}_b = 2.7\text{ k}\Omega$ | 38 | | ns |
| Delay time from SCKp \downarrow to SOp output ^{Note} | t_{KSO1} | $4.0\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$, $2.7\text{ V} \leq \text{V}_b \leq 4.0\text{ V}$, $\text{C}_b = 30\text{ pF}$, $\text{R}_b = 1.4\text{ k}\Omega$ | | 200 | ns |
| | | $2.7\text{ V} \leq \text{EV}_{\text{DD0}} < 4.0\text{ V}$, $2.3\text{ V} \leq \text{V}_b \leq 2.7\text{ V}$, $\text{C}_b = 30\text{ pF}$, $\text{R}_b = 2.7\text{ k}\Omega$ | | 390 | ns |
| | | $2.4\text{ V} \leq \text{EV}_{\text{DD0}} < 3.3\text{ V}$, $1.6\text{ V} \leq \text{V}_b \leq 2.0\text{ V}$, $\text{C}_b = 30\text{ pF}$, $\text{R}_b = 5.5\text{ k}\Omega$ | | 966 | ns |

Note When $\text{DAPmn} = 0$ and $\text{CKPmn} = 0$, or $\text{DAPmn} = 1$ and $\text{CKPmn} = 1$.

Caution Select the TTL input buffer for the Slp pin and the N-ch open drain output (V_{DD} tolerance (for the 20- to 52-pin products)/ EV_{DD} tolerance (for the 64- to 100-pin products)) mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg). For V_{IH} and V_{IL} , see the DC characteristics with TTL input buffer selected.

(Remarks are listed on the page after the next page.)

3.5.2 Serial interface IICA

(TA = -40 to +105°C, 2.4 V ≤ EVDD0 = EVDD1 ≤ VDD ≤ 5.5 V, VSS = EVSS0 = EVSS1 = 0 V)

| Parameter | Symbol | Conditions | HS (high-speed main) Mode | | | | Unit |
|---|---------------------|---|---------------------------|------|-----------|------|------|
| | | | Standard Mode | | Fast Mode | | |
| | | | MIN. | MAX. | MIN. | MAX. | |
| SCLA0 clock frequency | f _{SCL} | Fast mode: f _{CLK} ≥ 3.5 MHz | – | – | 0 | 400 | kHz |
| | | Standard mode: f _{CLK} ≥ 1 MHz | 0 | 100 | – | – | kHz |
| Setup time of restart condition | t _{SU:STA} | | 4.7 | | 0.6 | | μs |
| Hold time ^{Note 1} | t _{HD:STA} | | 4.0 | | 0.6 | | μs |
| Hold time when SCLA0 = “L” | t _{LOW} | | 4.7 | | 1.3 | | μs |
| Hold time when SCLA0 = “H” | t _{HIGH} | | 4.0 | | 0.6 | | μs |
| Data setup time (reception) | t _{SU:DAT} | | 250 | | 100 | | ns |
| Data hold time (transmission) ^{Note 2} | t _{HD:DAT} | | 0 | 3.45 | 0 | 0.9 | μs |
| Setup time of stop condition | t _{SU:STO} | | 4.0 | | 0.6 | | μs |
| Bus-free time | t _{BUF} | | 4.7 | | 1.3 | | μs |

Notes 1. The first clock pulse is generated after this period when the start/restart condition is detected.

<R> 2. The maximum value (MAX.) of tHD:DAT is during normal transfer and a wait state is inserted in the ACK (acknowledge) timing.

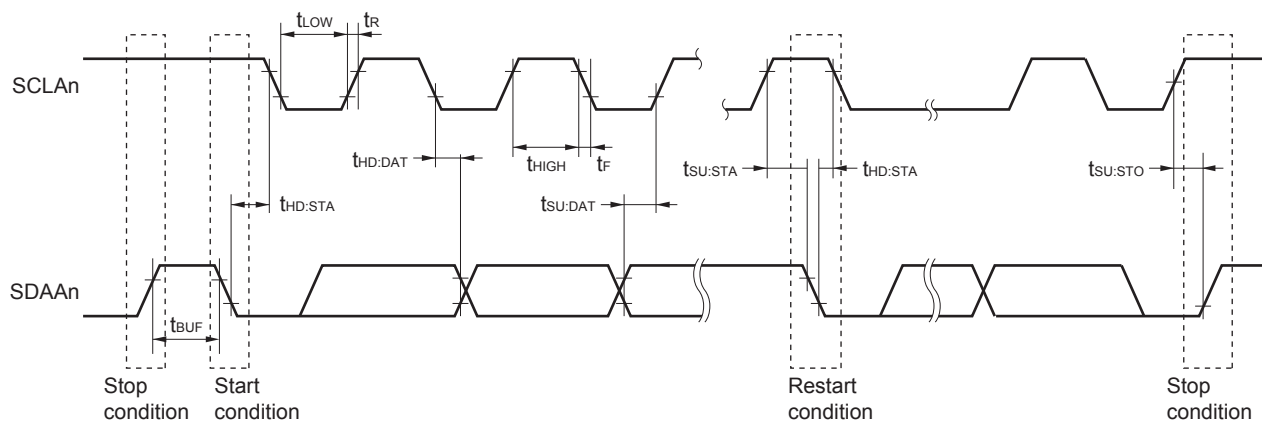
Caution The values in the above table are applied even when bit 2 (PIOR2) in the peripheral I/O redirection register (PIOR) is 1. At this time, the pin characteristics (IOH1, IOL1, VOH1, VOL1) must satisfy the values in the redirect destination.

Remark The maximum value of Cb (communication line capacitance) and the value of Rb (communication line pull-up resistor) at that time in each mode are as follows.

Standard mode: Cb = 400 pF, Rb = 2.7 kΩ

Fast mode: Cb = 320 pF, Rb = 1.1 kΩ

IICA serial transfer timing

**Remark** n = 0, 1