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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I ² C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	31
Program Memory Size	96KB (96K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 10x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LQFP
Supplier Device Package	44-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f100ffdfp-x0

Table 1-1. List of Ordering Part Numbers

(8/12)

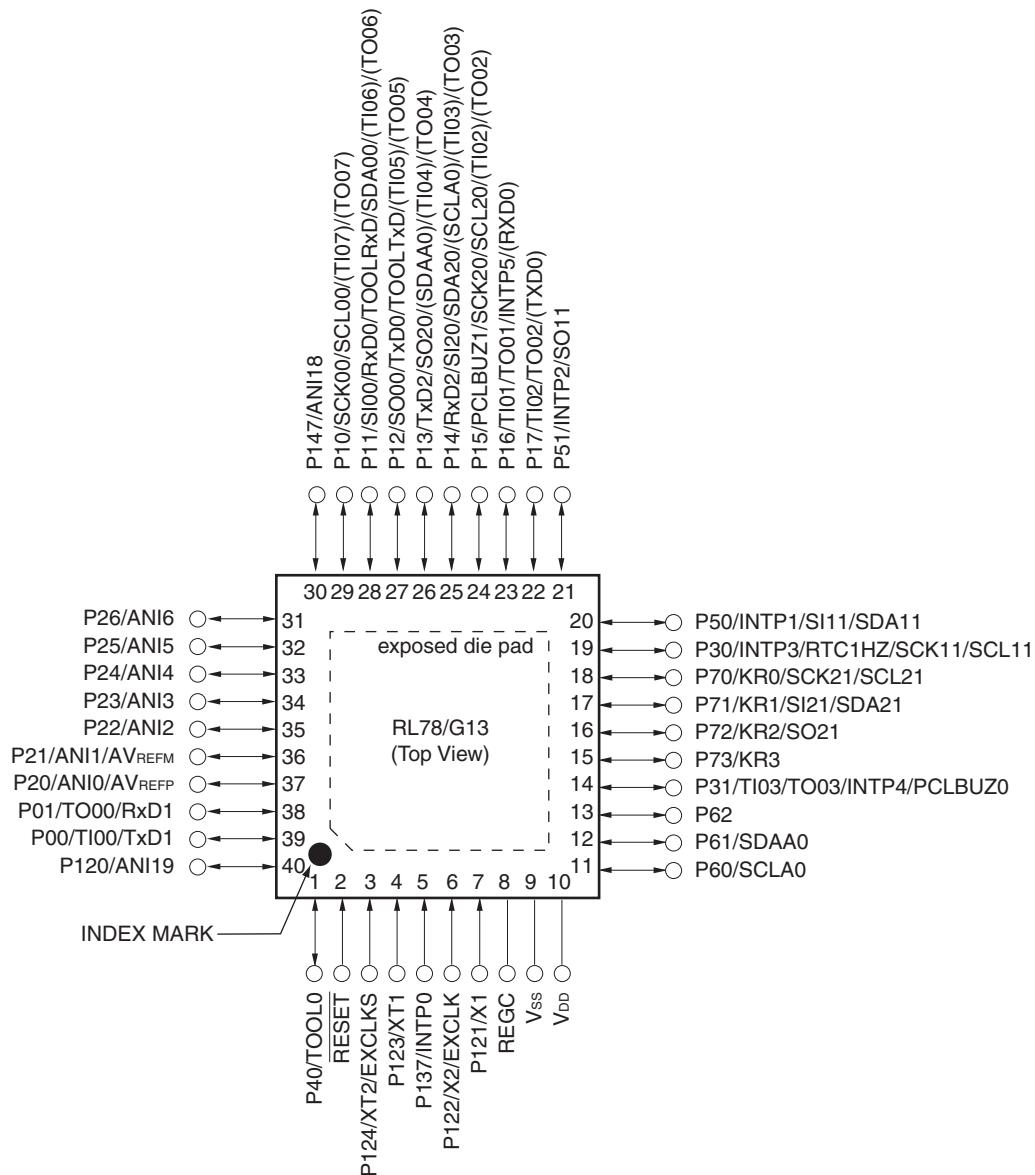
Pin count	Package	Data flash	Fields of Application ^{Note}	Ordering Part Number
64 pins	64-pin plastic LQFP (12 × 12 mm, 0.65 mm pitch)	Mounted	A D G	R5F100LCAFA#V0, R5F100LDAFA#V0, R5F100LEAFA#V0, R5F100LFAFA#V0, R5F100LGAFA#V0, R5F100LHAFA#V0, R5F100LJAFA#V0, R5F100LKAFA#V0, R5F100LLAFA#V0 R5F100LCAFA#X0, R5F100LDAFA#X0, R5F100LEAFA#X0, R5F100LFAFA#X0, R5F100LGAFA#X0, R5F100LHAFA#X0, R5F100LJAFA#X0, R5F100LKAFA#X0, R5F100LLAFA#X0 R5F100LCDFA#V0, R5F100LDDFA#V0, R5F100LEDFA#V0, R5F100LF DFA#V0, R5F100LGDFA#V0, R5F100LHDFA#V0, R5F100LJDFA#V0, R5F100LK DFA#V0, R5F100LLDFA#V0 R5F100LCDFA#X0, R5F100LDDFA#X0, R5F100LEDFA#X0, R5F100LF DFA#X0, R5F100LGDFA#X0, R5F100LHDFA#X0, R5F100LJDFA#X0, R5F100LK DFA#X0, R5F100LLDFA#X0 R5F100LCGFA#V0, R5F100LDGFA#V0, R5F100LEGFA#V0, R5F100LFGFA#V0 R5F100LCGFA#X0, R5F100LDGFA#X0, R5F100LEGFA#X0, R5F100LFGFA#X0 R5F100LGGFA#V0, R5F100LHGFA#V0, R5F100LJGFA#V0 R5F100LGGFA#X0, R5F100LHGFA#X0, R5F100LJGFA#X0
		Not mounted	A D	R5F101LCAFA#V0, R5F101LDAFA#V0, R5F101LEAFA#V0, R5F101LFAFA#V0, R5F101LGAFA#V0, R5F101LHAFA#V0, R5F101LJAFA#V0, R5F101LKAFA#V0, R5F101LLAFA#V0 R5F101LCAFA#X0, R5F101LDAFA#X0, R5F101LEAFA#X0, R5F101LFAFA#X0, R5F101LGAFA#X0, R5F101LHAFA#X0, R5F101LJAFA#X0, R5F101LKAFA#X0, R5F101LLAFA#X0 R5F101LCDFA#V0, R5F101LDDFA#V0, R5F101LEDFA#V0, R5F101LF DFA#V0, R5F101LGDFA#V0, R5F101LHDFA#V0, R5F101LJDFA#V0, R5F101LK DFA#V0, R5F101LLDFA#V0 R5F101LCDFA#X0, R5F101LDDFA#X0, R5F101LEDFA#X0, R5F101LF DFA#X0, R5F101LGDFA#X0, R5F101LHDFA#X0, R5F101LJDFA#X0, R5F101LK DFA#X0, R5F101LLDFA#X0

Note For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

Caution The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.

1.3.7 40-pin products

- 40-pin plastic HWQFN (6 × 6 mm, 0.5 mm pitch)

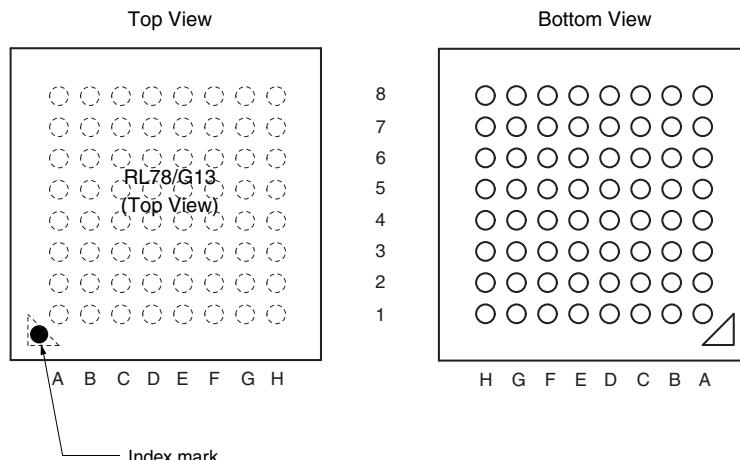


Caution Connect the REGC pin to V_{ss} via a capacitor (0.47 to 1 μ F).

Remarks 1. For pin identification, see **1.4 Pin Identification**.

2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.
3. It is recommended to connect an exposed die pad to V_{ss}.

- 64-pin plastic VFBGA (4 × 4 mm, 0.4 mm pitch)



Pin No.	Name	Pin No.	Name	Pin No.	Name	Pin No.	Name
A1	P05/TI05/TO05	C1	P51/INTP2/SO11	E1	P13/TxD2/SO20/(SDAA0)/(TI04)/(TO04)	G1	P146
A2	P30/INTP3/RTC1HZ/SCK11/SCL11	C2	P71/KR1/SI21/SDA21	E2	P14/RxD2/SI20/SDA20/(SCLA0)/(TI03)/(TO03)	G2	P25/ANI5
A3	P70/KR0/SCK21/SCL21	C3	P74/KR4/INTP8/SI01/SDA01	E3	P15/SCK20/SCL20/(TI02)/(TO02)	G3	P24/ANI4
A4	P75/KR5/INTP9/SCK01/SCL01	C4	P52/(INTP10)	E4	P16/TI01/TO01/INTP5/(SI00)/(RxD0)	G4	P22/ANI2
A5	P77/KR7/INTP11/(TxD2)	C5	P53/(INTP11)	E5	P03/ANI16/SI10/RxD1/SDA10	G5	P130
A6	P61/SDAA0	C6	P63	E6	P41/TI07/TO07	G6	P02/ANI17/SO10/TxD1
A7	P60/SCLA0	C7	Vss	E7	RESET	G7	P00/TI00
A8	EV _{DD0}	C8	P121/X1	E8	P137/INTP0	G8	P124/XT2/EXCLKS
B1	P50/INTP1/SI11/SDA11	D1	P55/(PCLBUZ1)/(SCK00)	F1	P10/SCK00/SCL00/(TI07)/(TO07)	H1	P147/ANI18
B2	P72/KR2/SO21	D2	P06/TI06/TO06	F2	P11/SI00/RxD0/TOOLRxDSDA00/(TI06)/(TO06)	H2	P27/ANI7
B3	P73/KR3/SO01	D3	P17/TI02/TO02/(SO00)/(TxD0)	F3	P12/SO00/TxD0/TOOLTxD/(INTP5)/(TI05)/(TO05)	H3	P26/ANI6
B4	P76/KR6/INTP10/(RxD2)	D4	P54	F4	P21/ANI1/AV _{REFM}	H4	P23/ANI3
B5	P31/TI03/TO03/INTP4/(PCLBUZ0)	D5	P42/TI04/TO04	F5	P04/SCK10/SCL10	H5	P20/ANI0/AV _{REFP}
B6	P62	D6	P40/TOOL0	F6	P43	H6	P141/PCLBUZ1/INTP7
B7	V _{DD}	D7	REGC	F7	P01/TO00	H7	P140/PCLBUZ0/INTP6
B8	EV _{SS0}	D8	P122/X2/EXCLK	F8	P123/XT1	H8	P120/ANI19

Cautions 1. Make EV_{SS0} pin the same potential as Vss pin.

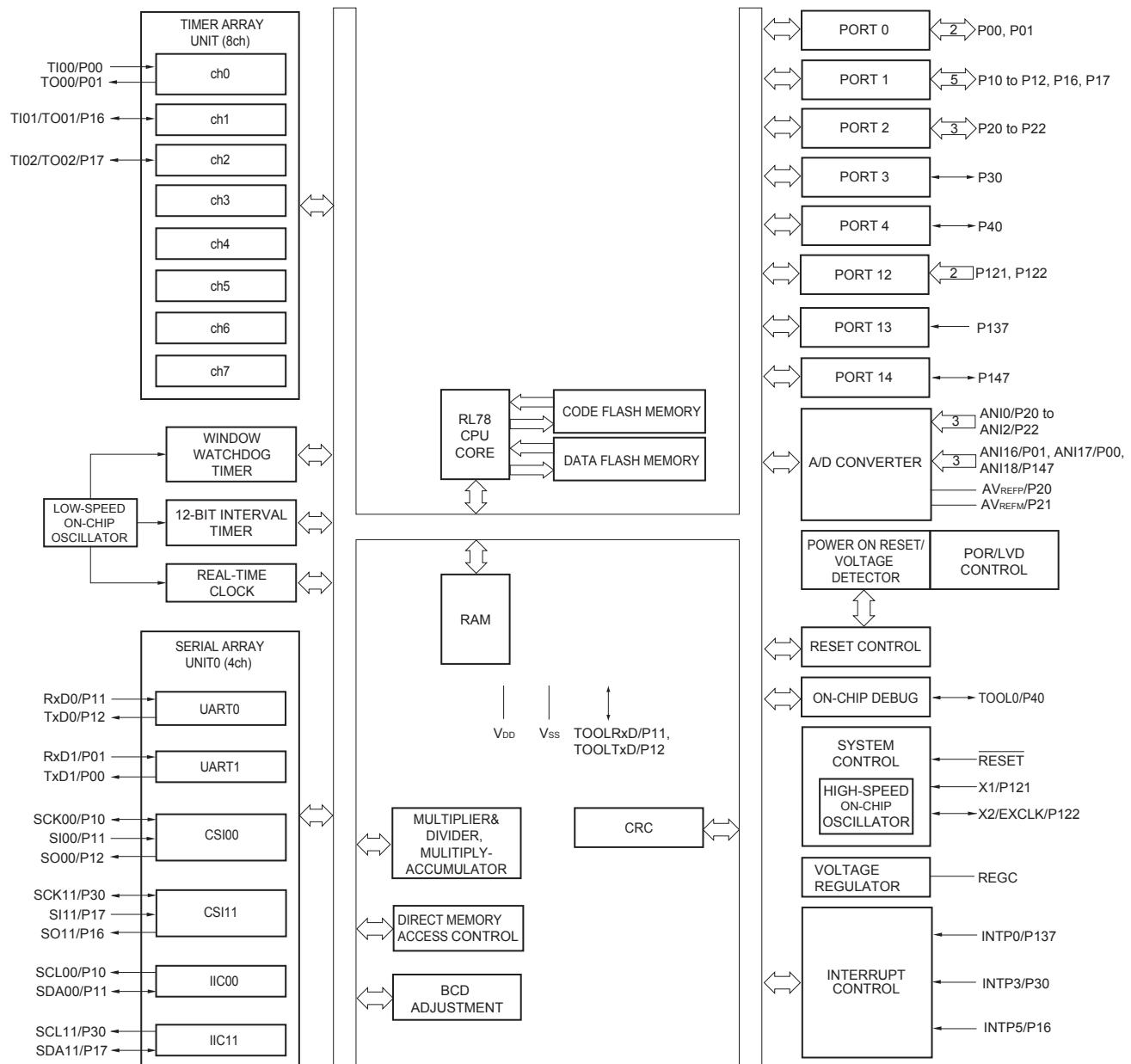
2. Make V_{DD} pin the potential that is higher than EV_{DD0} pin.
3. Connect the REGC pin to Vss via a capacitor (0.47 to 1 μ F).

Remarks 1. For pin identification, see **1.4 Pin Identification**.

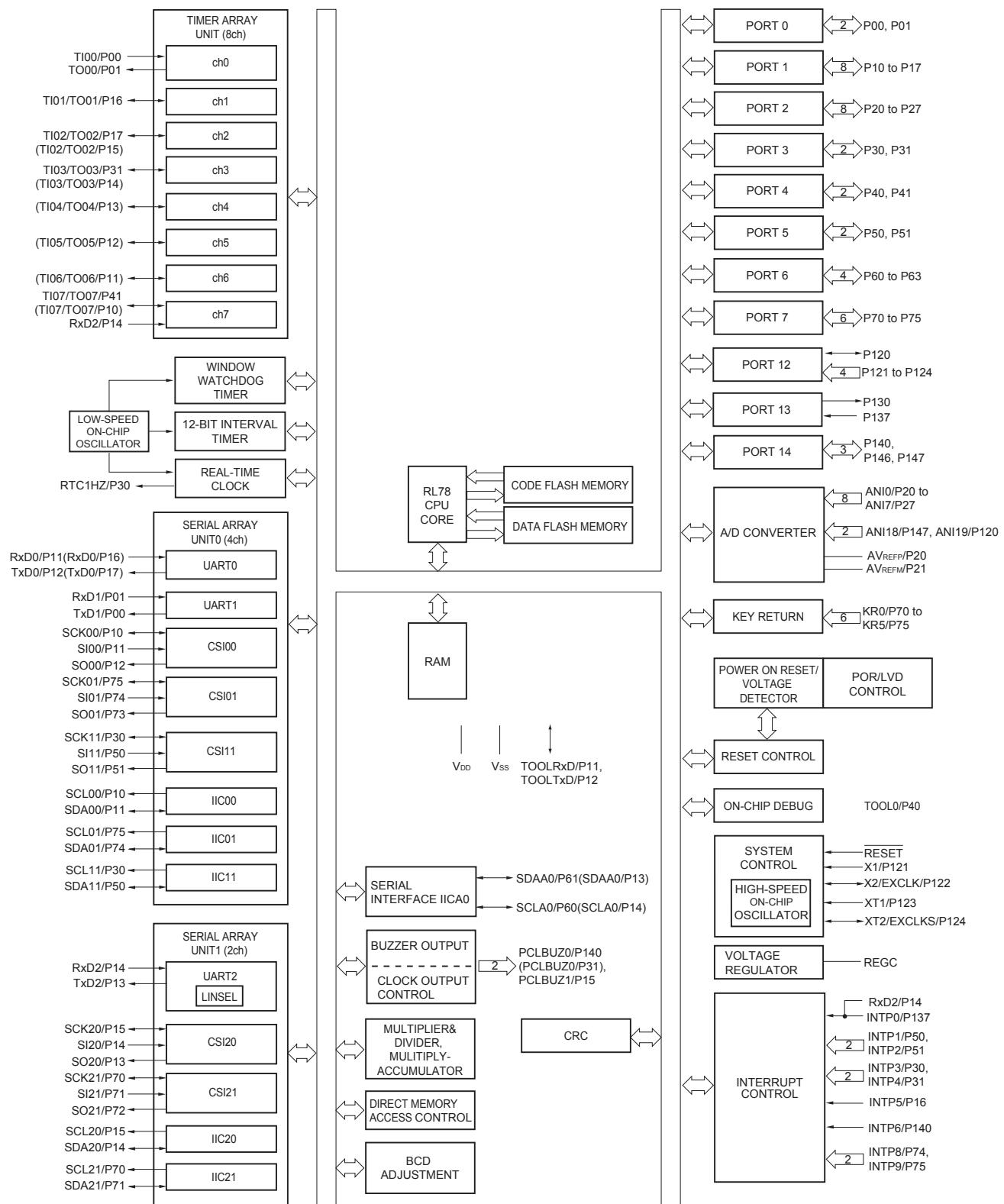
2. When using the microcontroller for an application where the noise generated inside the microcontroller must be reduced, it is recommended to supply separate powers to the V_{DD} and EV_{DD0} pins and connect the Vss and EV_{SS0} pins to separate ground lines.
3. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

1.5 Block Diagram

1.5.1 20-pin products

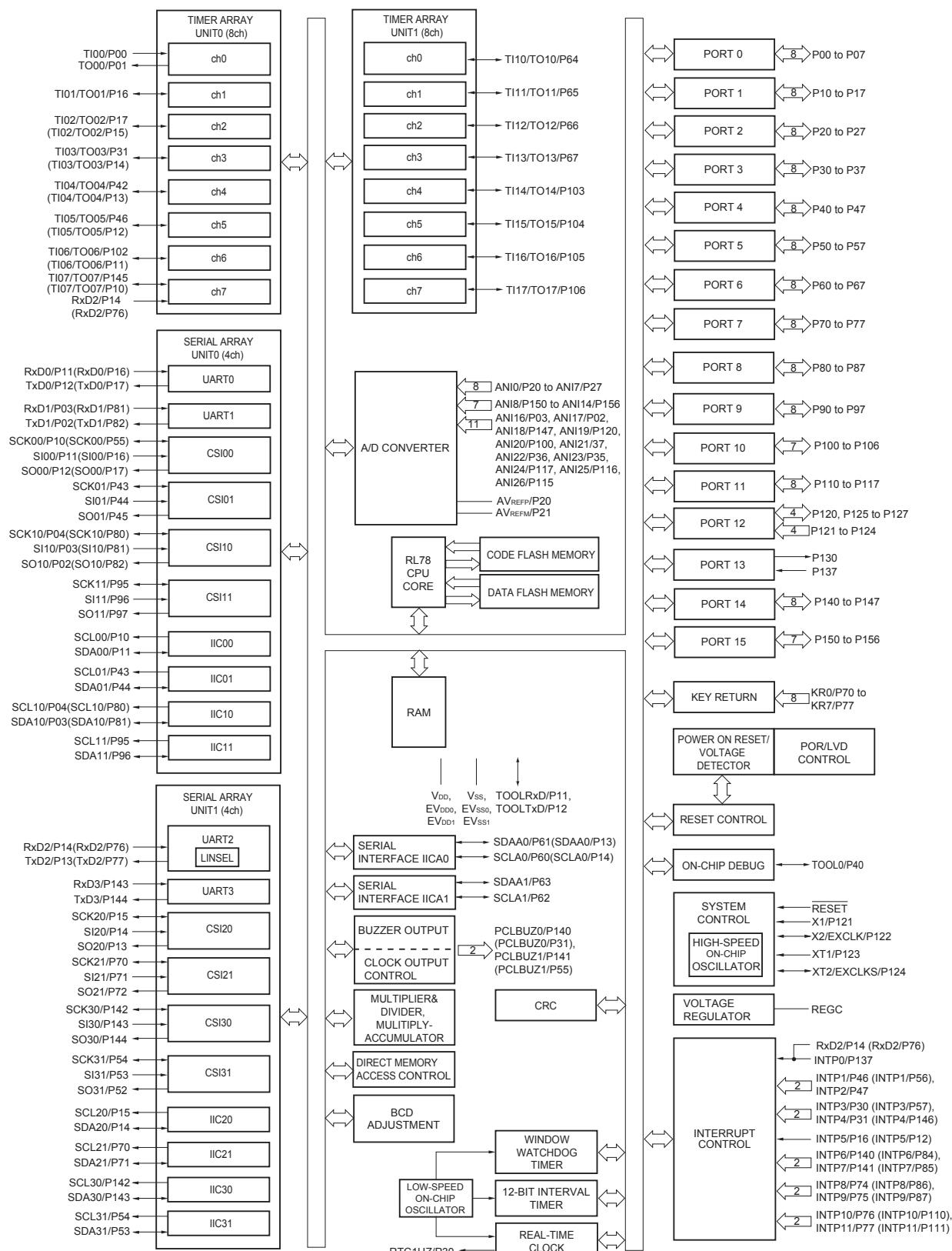


1.5.9 48-pin products



Remark Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

1.5.14 128-pin products



Remark Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

Absolute Maximum Ratings ($T_A = 25^\circ\text{C}$) (2/2)

Parameter	Symbols	Conditions		Ratings	Unit
Output current, high	I _{OH1}	Per pin	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	-40	mA
		Total of all pins -170 mA	P00 to P04, P07, P32 to P37, P40 to P47, P102 to P106, P120, P125 to P127, P130, P140 to P145	-70	mA
			P05, P06, P10 to P17, P30, P31, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100, P101, P110 to P117, P146, P147	-100	mA
	I _{OH2}	Per pin	P20 to P27, P150 to P156	-0.5	mA
		Total of all pins		-2	mA
	I _{OL1}	Per pin	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	40	mA
		Total of all pins 170 mA	P00 to P04, P07, P32 to P37, P40 to P47, P102 to P106, P120, P125 to P127, P130, P140 to P145	70	mA
			P05, P06, P10 to P17, P30, P31, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100, P101, P110 to P117, P146, P147	100	mA
	I _{OL2}	Per pin	P20 to P27, P150 to P156	1	mA
		Total of all pins		5	mA
Operating ambient temperature	T _A	In normal operation mode	-40 to +85	°C	
		In flash memory programming mode			
Storage temperature	T _{stg}			-65 to +150	°C

Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

Remark Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

2.3 DC Characteristics

2.3.1 Pin characteristics

($T_A = -40$ to $+85^\circ\text{C}$, $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$) (1/5)

Items	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Output current, high ^{Note 1}	I_{OH1}	Per pin for P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	$1.6 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		-10.0 ^{Note 2}	mA
		Total of P00 to P04, P07, P32 to P37, P40 to P47, P102 to P106, P120, P125 to P127, P130, P140 to P145 (When duty $\leq 70\%$ ^{Note 3})	$4.0 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		-55.0	mA
			$2.7 \text{ V} \leq EV_{DD0} < 4.0 \text{ V}$		-10.0	mA
			$1.8 \text{ V} \leq EV_{DD0} < 2.7 \text{ V}$		-5.0	mA
			$1.6 \text{ V} \leq EV_{DD0} < 1.8 \text{ V}$		-2.5	mA
		Total of P05, P06, P10 to P17, P30, P31, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100, P101, P110 to P117, P146, P147 (When duty $\leq 70\%$ ^{Note 3})	$4.0 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		-80.0	mA
			$2.7 \text{ V} \leq EV_{DD0} < 4.0 \text{ V}$		-19.0	mA
			$1.8 \text{ V} \leq EV_{DD0} < 2.7 \text{ V}$		-10.0	mA
			$1.6 \text{ V} \leq EV_{DD0} < 1.8 \text{ V}$		-5.0	mA
		Total of all pins (When duty $\leq 70\%$ ^{Note 3})	$1.6 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		-135.0 ^{Note 4}	mA
	I_{OH2}	Per pin for P20 to P27, P150 to P156	$1.6 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$		-0.1 ^{Note 2}	mA
		Total of all pins (When duty $\leq 70\%$ ^{Note 3})	$1.6 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$		-1.5	mA

Notes 1. Value of current at which the device operation is guaranteed even if the current flows from the EV_{DD0} , EV_{DD1} , V_{DD} pins to an output pin.

2. However, do not exceed the total current value.

3. Specification under conditions where the duty factor $\leq 70\%$.

The output current value that has changed to the duty factor $> 70\%$ the duty ratio can be calculated with the following expression (when changing the duty factor from 70% to n%).

- Total output current of pins = $(I_{OH} \times 0.7)/(n \times 0.01)$

<Example> Where n = 80% and $I_{OH} = -10.0 \text{ mA}$

$$\text{Total output current of pins} = (-10.0 \times 0.7)/(80 \times 0.01) \approx -8.7 \text{ mA}$$

However, the current that is allowed to flow into one pin does not vary depending on the duty factor.

A current higher than the absolute maximum rating must not flow into one pin.

4. The applied current for the products for industrial application (R5F100xxDxx, R5F101xxDxx, R5F100xxGxx) is -100 mA .

Caution P00, P02 to P04, P10 to P15, P17, P43 to P45, P50, P52 to P55, P71, P74, P80 to P82, P96, and P142 to P144 do not output high level in N-ch open-drain mode.

Remark Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

- Notes**
1. Total current flowing into V_{DD} , EV_{DD0} , and EV_{DD1} , including the input leakage current flowing when the level of the input pin is fixed to V_{DD} , EV_{DD0} , and EV_{DD1} , or V_{SS} , EV_{SS0} , and EV_{SS1} . The values below the MAX. column include the peripheral operation current . However, not including the current flowing into the A/D converter, LVD circuit, I/O port, and on-chip pull-up/pull-down resistors and the current flowing during data flash rewrite.
 2. During HALT instruction execution by flash memory.
 3. When high-speed on-chip oscillator and subsystem clock are stopped.
 4. When high-speed system clock and subsystem clock are stopped.
 5. When high-speed on-chip oscillator and high-speed system clock are stopped. When $RTCLPC = 1$ and setting ultra-low current consumption ($AMPHS1 = 1$). The current flowing into the RTC is included. However, not including the current flowing into the 12-bit interval timer and watchdog timer.
 6. Not including the current flowing into the RTC, 12-bit interval timer, and watchdog timer.
 7. Relationship between operation voltage width, operation frequency of CPU and operation mode is as below.

HS (high-speed main) mode:	$2.7 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$ @ 1 MHz to 32 MHz
	$2.4 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$ @ 1 MHz to 16 MHz
LS (low-speed main) mode:	$1.8 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$ @ 1 MHz to 8 MHz
	LV (low-voltage main) mode: $1.6 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$ @ 1 MHz to 4 MHz
 8. Regarding the value for current to operate the subsystem clock in STOP mode, refer to that in HALT mode.

- Remarks**
1. f_{MX} : High-speed system clock frequency (X1 clock oscillation frequency or external main system clock frequency)
 2. f_{IH} : High-speed on-chip oscillator clock frequency
 3. f_{SUB} : Subsystem clock frequency (XT1 clock oscillation frequency)
 4. Except subsystem clock operation and STOP mode, temperature condition of the TYP. value is $T_A = 25^\circ\text{C}$

(3) 128-pin products, and flash ROM: 384 to 512 KB of 44- to 100-pin products

 $(T_A = -40$ to $+85^\circ\text{C}$, $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{ss} = EV_{ss0} = EV_{ss1} = 0 \text{ V}$) (2/2)

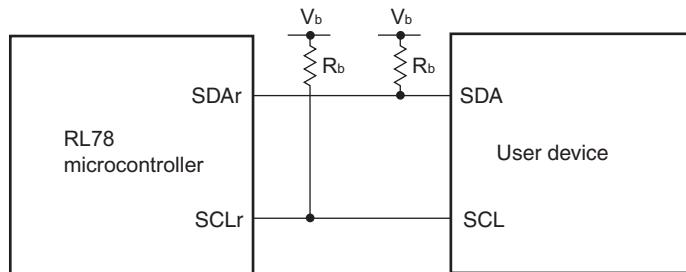
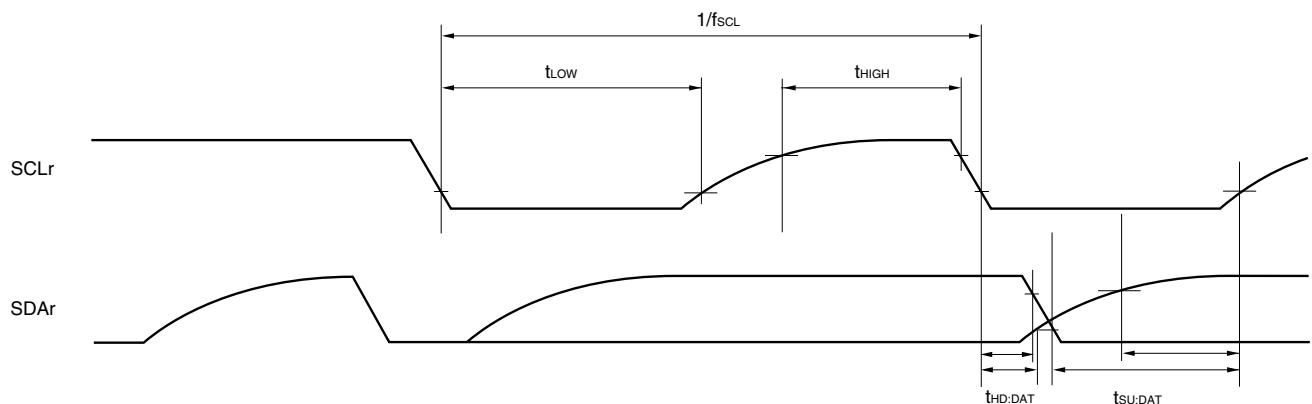
Parameter	Symbol	Conditions			MIN.	TYP.	MAX.	Unit
Supply current <small>Note 1</small>	$I_{DD2}^{Note 2}$	HALT mode	HS (high-speed main) mode ^{Note 7}	$f_{IH} = 32 \text{ MHz}^{Note 4}$	$V_{DD} = 5.0 \text{ V}$		0.62	1.89 mA
				$V_{DD} = 3.0 \text{ V}$			0.62	1.89 mA
			$f_{IH} = 24 \text{ MHz}^{Note 4}$	$V_{DD} = 5.0 \text{ V}$		0.50	1.48	mA
				$V_{DD} = 3.0 \text{ V}$		0.50	1.48	mA
			$f_{IH} = 16 \text{ MHz}^{Note 4}$	$V_{DD} = 5.0 \text{ V}$		0.44	1.12	mA
				$V_{DD} = 3.0 \text{ V}$		0.44	1.12	mA
		LS (low-speed main) mode ^{Note 7}	$f_{IH} = 8 \text{ MHz}^{Note 4}$	$V_{DD} = 3.0 \text{ V}$		290	620	μA
				$V_{DD} = 2.0 \text{ V}$		290	620	μA
		LV (low-voltage main) mode <small>Note 7</small>	$f_{IH} = 4 \text{ MHz}^{Note 4}$	$V_{DD} = 3.0 \text{ V}$		460	700	μA
				$V_{DD} = 2.0 \text{ V}$		460	700	μA
		HS (high-speed main) mode ^{Note 7}	$f_{MX} = 20 \text{ MHz}^{Note 3}$, $V_{DD} = 5.0 \text{ V}$	Square wave input		0.31	1.14	mA
				Resonator connection		0.48	1.34	mA
			$f_{MX} = 20 \text{ MHz}^{Note 3}$, $V_{DD} = 3.0 \text{ V}$	Square wave input		0.31	1.14	mA
				Resonator connection		0.48	1.34	mA
			$f_{MX} = 10 \text{ MHz}^{Note 3}$, $V_{DD} = 5.0 \text{ V}$	Square wave input		0.21	0.68	mA
				Resonator connection		0.28	0.76	mA
			$f_{MX} = 10 \text{ MHz}^{Note 3}$, $V_{DD} = 3.0 \text{ V}$	Square wave input		0.21	0.68	mA
				Resonator connection		0.28	0.76	mA
		LS (low-speed main) mode ^{Note 7}	$f_{MX} = 8 \text{ MHz}^{Note 3}$, $V_{DD} = 3.0 \text{ V}$	Square wave input		110	390	μA
				Resonator connection		160	450	μA
			$f_{MX} = 8 \text{ MHz}^{Note 3}$, $V_{DD} = 2.0 \text{ V}$	Square wave input		110	390	μA
				Resonator connection		160	450	μA
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = -40^\circ\text{C}$	Square wave input		0.31	0.66	μA
				Resonator connection		0.50	0.85	μA
			$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = +25^\circ\text{C}$	Square wave input		0.38	0.66	μA
				Resonator connection		0.57	0.85	μA
			$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = +50^\circ\text{C}$	Square wave input		0.47	3.49	μA
				Resonator connection		0.66	3.68	μA
			$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = +70^\circ\text{C}$	Square wave input		0.80	6.10	μA
				Resonator connection		0.99	6.29	μA
		$I_{DD3}^{Note 6}$	STOP mode ^{Note 8}	$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = +85^\circ\text{C}$	Square wave input	1.52	10.46	μA
					Resonator connection	1.71	10.65	μA
				$T_A = -40^\circ\text{C}$		0.19	0.54	μA
				$T_A = +25^\circ\text{C}$		0.26	0.54	μA
				$T_A = +50^\circ\text{C}$		0.35	3.37	μA
				$T_A = +70^\circ\text{C}$		0.68	5.98	μA
				$T_A = +85^\circ\text{C}$		1.40	10.34	μA

(Notes and Remarks are listed on the next page.)

6. Current flowing only to the A/D converter. The supply current of the RL78 microcontrollers is the sum of I_{DD1} or I_{DD2} and I_{ADC} when the A/D converter operates in an operation mode or the HALT mode.
7. Current flowing only to the LVD circuit. The supply current of the RL78 microcontrollers is the sum of I_{DD1} , I_{DD2} or I_{DD3} and I_{LVD} when the LVD circuit is in operation.
8. Current flowing only during data flash rewrite.
9. Current flowing only during self programming.
10. For shift time to the SNOOZE mode, see **18.3.3 SNOOZE mode**.

Remarks

- 1. f_{IL} : Low-speed on-chip oscillator clock frequency
- 2. f_{SUB} : Subsystem clock frequency (XT1 clock oscillation frequency)
- 3. f_{CLK} : CPU/peripheral hardware clock frequency
- 4. Temperature condition of the TYP. value is $T_A = 25^\circ\text{C}$

Simplified I²C mode connection diagram (during communication at different potential)**Simplified I²C mode serial transfer timing (during communication at different potential)**

Remarks

1. $R_b[\Omega]$: Communication line (SDAr, SCLr) pull-up resistance, $C_b[F]$: Communication line (SDAr, SCLr) load capacitance, $V_b[V]$: Communication line voltage
2. r: IIC number ($r = 00, 01, 10, 20, 30, 31$), g: PIM, POM number ($g = 0, 1, 4, 5, 8, 14$)
3. f_{MCK} : Serial array unit operation clock frequency
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number ($mn = 00, 01, 02, 10, 12, 13$)

Remark The electrical characteristics of the products G: Industrial applications ($T_A = -40$ to $+105^\circ\text{C}$) are different from those of the products "A: Consumer applications, and D: Industrial applications". For details, refer to **3.1 to 3.10**.

3.1 Absolute Maximum Ratings

Absolute Maximum Ratings ($T_A = 25^\circ\text{C}$) (1/2)

Parameter	Symbols	Conditions	Ratings	Unit
Supply voltage	V_{DD}		-0.5 to +6.5	V
	EV_{DD0}, EV_{DD1}	$EV_{DD0} = EV_{DD1}$	-0.5 to +6.5	V
	EV_{SS0}, EV_{SS1}	$EV_{SS0} = EV_{SS1}$	-0.5 to +0.3	V
REGC pin input voltage	V_{IREGC}	REGC	-0.3 to +2.8 and -0.3 to $V_{DD} + 0.3^{\text{Note 1}}$	V
Input voltage	V_{I1}	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147	-0.3 to $EV_{DD0} + 0.3$ and -0.3 to $V_{DD} + 0.3^{\text{Note 2}}$	V
	V_{I2}	P60 to P63 (N-ch open-drain)	-0.3 to +6.5	V
	V_{I3}	P20 to P27, P121 to P124, P137, P150 to P156, EXCLK, EXCLKS, RESET	-0.3 to $V_{DD} + 0.3^{\text{Note 2}}$	V
Output voltage	V_{O1}	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	-0.3 to $EV_{DD0} + 0.3$ and -0.3 to $V_{DD} + 0.3^{\text{Note 2}}$	V
	V_{O2}	P20 to P27, P150 to P156	-0.3 to $V_{DD} + 0.3^{\text{Note 2}}$	V
Analog input voltage	V_{AI1}	ANI16 to ANI26	-0.3 to $EV_{DD0} + 0.3$ and -0.3 to $AV_{REF}(+) + 0.3^{\text{Notes 2, 3}}$	V
	V_{AI2}	ANIO to ANI14	-0.3 to $V_{DD} + 0.3$ and -0.3 to $AV_{REF}(+) + 0.3^{\text{Notes 2, 3}}$	V

- Notes 1.** Connect the REGC pin to Vss via a capacitor (0.47 to 1 μF). This value regulates the absolute maximum rating of the REGC pin. Do not use this pin with voltage applied to it.
2. Must be 6.5 V or lower.
 3. Do not exceed $AV_{REF}(+) + 0.3$ V in case of A/D conversion target pin.

Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

- Remarks**
1. Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.
 2. $AV_{REF}(+)$: + side reference voltage of the A/D converter.
 3. V_{ss} : Reference voltage

(2) Flash ROM: 96 to 256 KB of 30- to 100-pin products

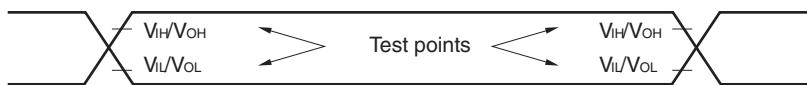
 $(T_A = -40$ to $+105^\circ\text{C}$, $2.4 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$) (1/2)

Parameter	Symbol	Conditions					MIN.	TYP.	MAX.	Unit
Supply current Note 1	I_{DD1}	Operating mode	HS (high-speed main) mode Note 5	$f_{IH} = 32 \text{ MHz}$ ^{Note 3}	Basic operation	$V_{DD} = 5.0 \text{ V}$		2.3		mA
					Normal operation	$V_{DD} = 3.0 \text{ V}$		2.3		mA
					Normal operation	$V_{DD} = 5.0 \text{ V}$		5.2	9.2	mA
					Normal operation	$V_{DD} = 3.0 \text{ V}$		5.2	9.2	mA
				$f_{IH} = 24 \text{ MHz}$ ^{Note 3}	Normal operation	$V_{DD} = 5.0 \text{ V}$		4.1	7.0	mA
					Normal operation	$V_{DD} = 3.0 \text{ V}$		4.1	7.0	mA
		HS (high-speed main) mode Note 5	$f_{MX} = 20 \text{ MHz}$ ^{Note 2} , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		3.4	5.9		mA
				Normal operation	Resonator connection		3.6	6.0		mA
				Normal operation	Square wave input		3.4	5.9		mA
				Normal operation	Resonator connection		3.6	6.0		mA
			$f_{MX} = 10 \text{ MHz}$ ^{Note 2} , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		2.1	3.5		mA
				Normal operation	Resonator connection		2.1	3.5		mA
			$f_{MX} = 10 \text{ MHz}$ ^{Note 2} , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		2.1	3.5		mA
				Normal operation	Resonator connection		2.1	3.5		mA
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = -40^\circ\text{C}$	Normal operation	Square wave input		4.8	5.9		μA
				Normal operation	Resonator connection		4.9	6.0		μA
				Normal operation	Square wave input		4.9	5.9		μA
				Normal operation	Resonator connection		5.0	6.0		μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +25^\circ\text{C}$	Normal operation	Square wave input		5.0	7.6		μA
				Normal operation	Resonator connection		5.1	7.7		μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +50^\circ\text{C}$	Normal operation	Square wave input		5.2	9.3		μA
				Normal operation	Resonator connection		5.3	9.4		μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +70^\circ\text{C}$	Normal operation	Square wave input		5.7	13.3		μA
				Normal operation	Resonator connection		5.8	13.4		μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +85^\circ\text{C}$	Normal operation	Square wave input		10.0	46.0		μA
				Normal operation	Resonator connection		10.0	46.0		μA

(Notes and Remarks are listed on the next page.)

3.5 Peripheral Functions Characteristics

AC Timing Test Points



3.5.1 Serial array unit

(1) During communication at same potential (UART mode)

(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V)

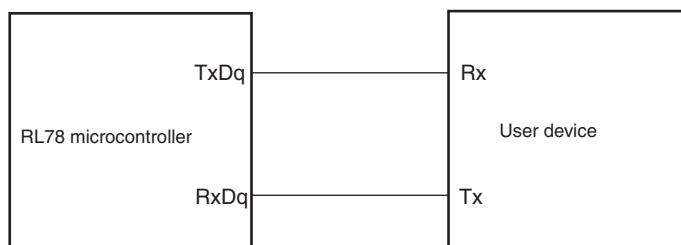
Parameter	Symbol	Conditions	HS (high-speed main) Mode		Unit
			MIN.	MAX.	
Transfer rate ^{Note 1}		Theoretical value of the maximum transfer rate f _{CLK} = 32 MHz, f _{MCK} = f _{CLK}		f _{MCK} /12 ^{Note 2}	bps
				2.6	Mbps

Notes 1. Transfer rate in the SNOOZE mode is 4800 bps only.

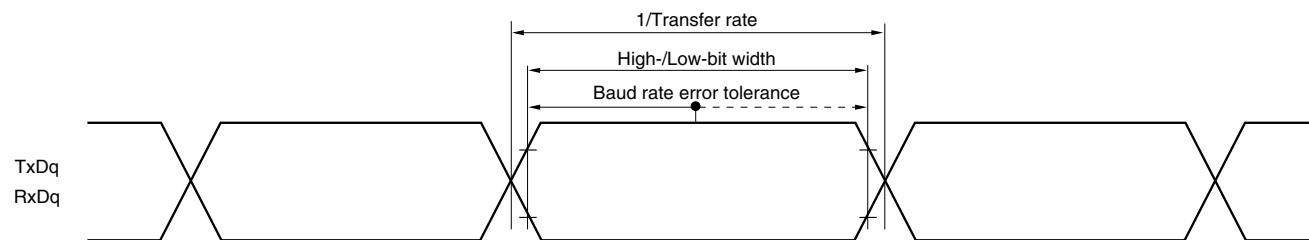
2. The following conditions are required for low voltage interface when EV_{DD0} < V_{DD}.
- 2.4 V ≤ EV_{DD0} < 2.7 V : MAX. 1.3 Mbps

Caution Select the normal input buffer for the RxDq pin and the normal output mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg).

UART mode connection diagram (during communication at same potential)



UART mode bit width (during communication at same potential) (reference)



Remarks 1. q: UART number (q = 0 to 3), g: PIM and POM number (g = 0, 1, 8, 14)

2. f_{MCK}: Serial array unit operation clock frequency

(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13))

(3) During communication at same potential (CSI mode) (slave mode, SCKp... external clock input)

(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		Unit
				MIN.	MAX.	
SCKp cycle time ^{Note 5}	t _{KCY2}	4.0 V ≤ EV _{DD0} ≤ 5.5 V	20 MHz < f _{MCK}	16/f _{MCK}		ns
			f _{MCK} ≤ 20 MHz	12/f _{MCK}		ns
		2.7 V ≤ EV _{DD0} ≤ 5.5 V	16 MHz < f _{MCK}	16/f _{MCK}		ns
			f _{MCK} ≤ 16 MHz	12/f _{MCK}		ns
		2.4 V ≤ EV _{DD0} ≤ 5.5 V		16/f _{MCK}		ns
				12/f _{MCK} and 1000		ns
SCKp high-/low-level width	t _{KH2} , t _{KL2}	4.0 V ≤ EV _{DD0} ≤ 5.5 V		t _{KCY2} /2 – 14		ns
		2.7 V ≤ EV _{DD0} ≤ 5.5 V		t _{KCY2} /2 – 16		ns
		2.4 V ≤ EV _{DD0} ≤ 5.5 V		t _{KCY2} /2 – 36		ns
Slp setup time (to SCKp↑) ^{Note 1}	t _{SIK2}	2.7 V ≤ EV _{DD0} ≤ 5.5 V		1/f _{MCK} +40		ns
		2.4 V ≤ EV _{DD0} ≤ 5.5 V		1/f _{MCK} +60		ns
Slp hold time (from SCKp↑) ^{Note 2}	t _{KSI2}	2.4 V ≤ EV _{DD0} ≤ 5.5 V		1/f _{MCK} +62		ns
Delay time from SCKp↓ to SOp output ^{Note 3}	t _{KSO2}	C = 30 pF ^{Note 4}	2.7 V ≤ EV _{DD0} ≤ 5.5 V		2/f _{MCK} +66	ns
			2.4 V ≤ EV _{DD0} ≤ 5.5 V		2/f _{MCK} +113	ns

- Notes**
- When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp setup time becomes “to SCKp↓” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
 - When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp hold time becomes “from SCKp↓” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
 - When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The delay time to SOp output becomes “from SCKp↑” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
 - C is the load capacitance of the SOp output lines.
 - Transfer rate in the SNOOZE mode : MAX. 1 Mbps

Caution Select the normal input buffer for the Slp pin and SCKp pin and the normal output mode for the SOp pin by using port input mode register g (PIMg) and port output mode register g (POMg).

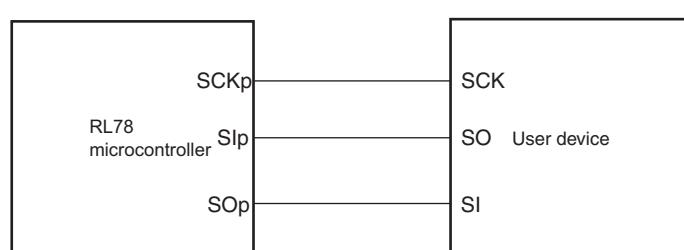
- Remarks** 1. p: CSI number (p = 00, 01, 10, 11, 20, 21, 30, 31), m: Unit number (m = 0, 1),

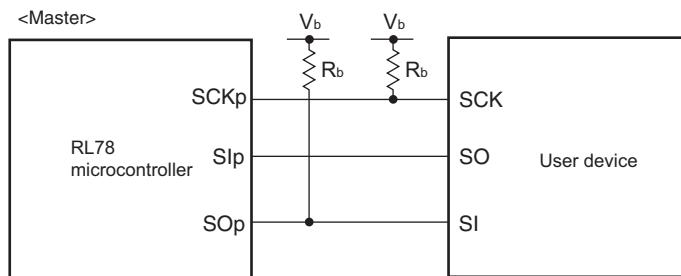
n: Channel number (n = 0 to 3), g: PIM number (g = 0, 1, 4, 5, 8, 14)

2. f_{MCK}: Serial array unit operation clock frequency

(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13))

CSI mode connection diagram (during communication at same potential)



CSI mode connection diagram (during communication at different potential)

- Remarks**
1. $R_b[\Omega]$: Communication line (SCKp, SOp) pull-up resistance, $C_b[F]$: Communication line (SCKp, SOp) load capacitance, $V_b[V]$: Communication line voltage
 2. p: CSI number ($p = 00, 01, 10, 20, 30, 31$), m: Unit number , n: Channel number ($mn = 00, 01, 02, 10, 12, 13$), g: PIM and POM number ($g = 0, 1, 4, 5, 8, 14$)
 3. fmck: Serial array unit operation clock frequency
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn).
m: Unit number, n: Channel number ($mn = 00$))
 4. CSI01 of 48-, 52-, 64-pin products, and CSI11 and CSI21 cannot communicate at different potential.
Use other CSI for communication at different potential.

3.5.2 Serial interface IICA

($T_A = -40$ to $+105^\circ\text{C}$, $2.4 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$)

Parameter	Symbol	Conditions	HS (high-speed main) Mode				Unit	
			Standard Mode		Fast Mode			
			MIN.	MAX.	MIN.	MAX.		
SCLA0 clock frequency	f_{SCL}	Fast mode: $f_{CLK} \geq 3.5 \text{ MHz}$	—	—	0	400	kHz	
		Standard mode: $f_{CLK} \geq 1 \text{ MHz}$	0	100	—	—	kHz	
Setup time of restart condition	$t_{SU:STA}$		4.7		0.6		μs	
Hold time ^{Note 1}	$t_{HD:STA}$		4.0		0.6		μs	
Hold time when SCLA0 = "L"	t_{LOW}		4.7		1.3		μs	
Hold time when SCLA0 = "H"	t_{HIGH}		4.0		0.6		μs	
Data setup time (reception)	$t_{SU:DAT}$		250		100		ns	
Data hold time (transmission) ^{Note 2}	$t_{HD:DAT}$		0	3.45	0	0.9	μs	
Setup time of stop condition	$t_{SU:STO}$		4.0		0.6		μs	
Bus-free time	t_{BUF}		4.7		1.3		μs	

Notes 1. The first clock pulse is generated after this period when the start/restart condition is detected.

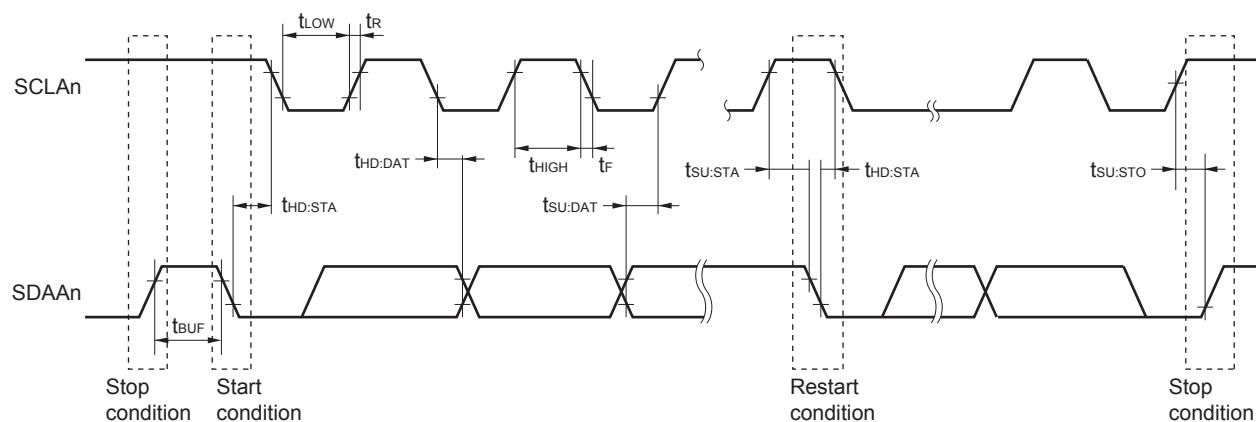
<R> 2. The maximum value (MAX.) of $t_{HD:DAT}$ is during normal transfer and a wait state is inserted in the ACK (acknowledge) timing.

Caution The values in the above table are applied even when bit 2 (PIOR2) in the peripheral I/O redirection register (PIOR) is 1. At this time, the pin characteristics (I_{OH1} , I_{OL1} , V_{OH1} , V_{OL1}) must satisfy the values in the redirect destination.

Remark The maximum value of C_b (communication line capacitance) and the value of R_b (communication line pull-up resistor) at that time in each mode are as follows.

Standard mode: $C_b = 400 \text{ pF}$, $R_b = 2.7 \text{ k}\Omega$
 Fast mode: $C_b = 320 \text{ pF}$, $R_b = 1.1 \text{ k}\Omega$

IICA serial transfer timing



Remark $n = 0, 1$

Notes 1. Excludes quantization error ($\pm 1/2$ LSB).

2. This value is indicated as a ratio (%FSR) to the full-scale value.

3. When $AV_{REFP} < V_{DD}$, the MAX. values are as follows.

Overall error: Add ± 1.0 LSB to the MAX. value when $AV_{REFP} = V_{DD}$.

Zero-scale error/Full-scale error: Add $\pm 0.05\%$ FSR to the MAX. value when $AV_{REFP} = V_{DD}$.

Integral linearity error/ Differential linearity error: Add ± 0.5 LSB to the MAX. value when $AV_{REFP} = V_{DD}$.

4. Refer to **3.6.2 Temperature sensor/internal reference voltage characteristics**.

(4) When reference voltage (+) = Internal reference voltage (ADREFP1 = 1, ADREFP0 = 0), reference voltage (-) = AV_{REFM}/ANI1 (ADREFM = 1), target pin : ANI0, ANI2 to ANI14, ANI16 to ANI26

(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V, Reference voltage (+) = V_{BGR}^{Note 3}, Reference voltage (-) = AV_{REFM}^{Note 4} = 0 V, HS (high-speed main) mode)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Resolution	RES			8		bit	
Conversion time	t _{CONV}	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V	17		39	μs
Zero-scale error ^{Notes 1, 2}	E _{Zs}	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V			±0.60	%FSR
Integral linearity error ^{Note 1}	ILE	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V			±2.0	LSB
Differential linearity error ^{Note 1}	DLE	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V			±1.0	LSB
Analog input voltage	V _{AIN}			0		V _{BGR} ^{Note 3}	V

Notes 1. Excludes quantization error (±1/2 LSB).

2. This value is indicated as a ratio (%FSR) to the full-scale value.

3. Refer to 3.6.2 Temperature sensor/internal reference voltage characteristics.

4. When reference voltage (-) = V_{SS}, the MAX. values are as follows.

Zero-scale error: Add ±0.35%FSR to the MAX. value when reference voltage (-) = AV_{REFM}.

Integral linearity error: Add ±0.5 LSB to the MAX. value when reference voltage (-) = AV_{REFM}.

Differential linearity error: Add ±0.2 LSB to the MAX. value when reference voltage (-) = AV_{REFM}.

3.6.2 Temperature sensor/internal reference voltage characteristics

(TA = -40 to +105°C, 2.4 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V, HS (high-speed main) mode)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Temperature sensor output voltage	V _{TMP25}	Setting ADS register = 80H, TA = +25°C		1.05		V
Internal reference voltage	V _{BGR}	Setting ADS register = 81H	1.38	1.45	1.5	V
Temperature coefficient	F _{VTMP5}	Temperature sensor that depends on the temperature		-3.6		mV/°C
Operation stabilization wait time	t _{AMP}		5			μs