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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

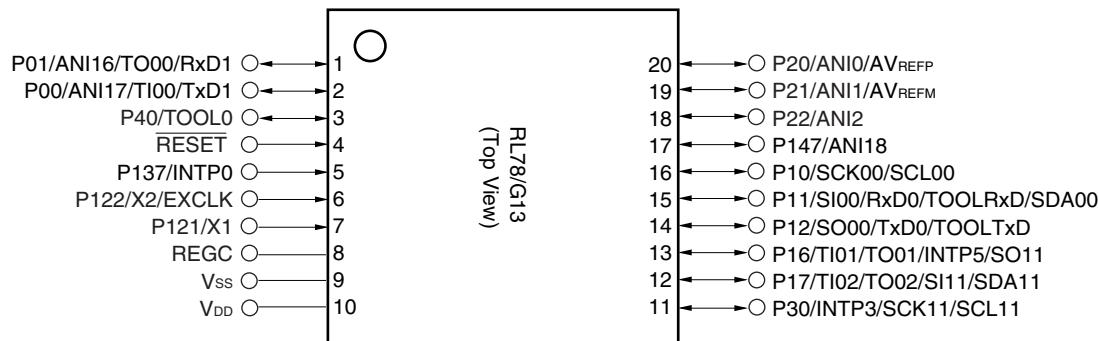
Details

Product Status	Obsolete
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I ² C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	31
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	12K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 10x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LQFP
Supplier Device Package	44-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f100fgdfp-v0

1.3 Pin Configuration (Top View)

1.3.1 20-pin products

- 20-pin plastic LSSOP (7.62 mm (300), 0.65 mm pitch)

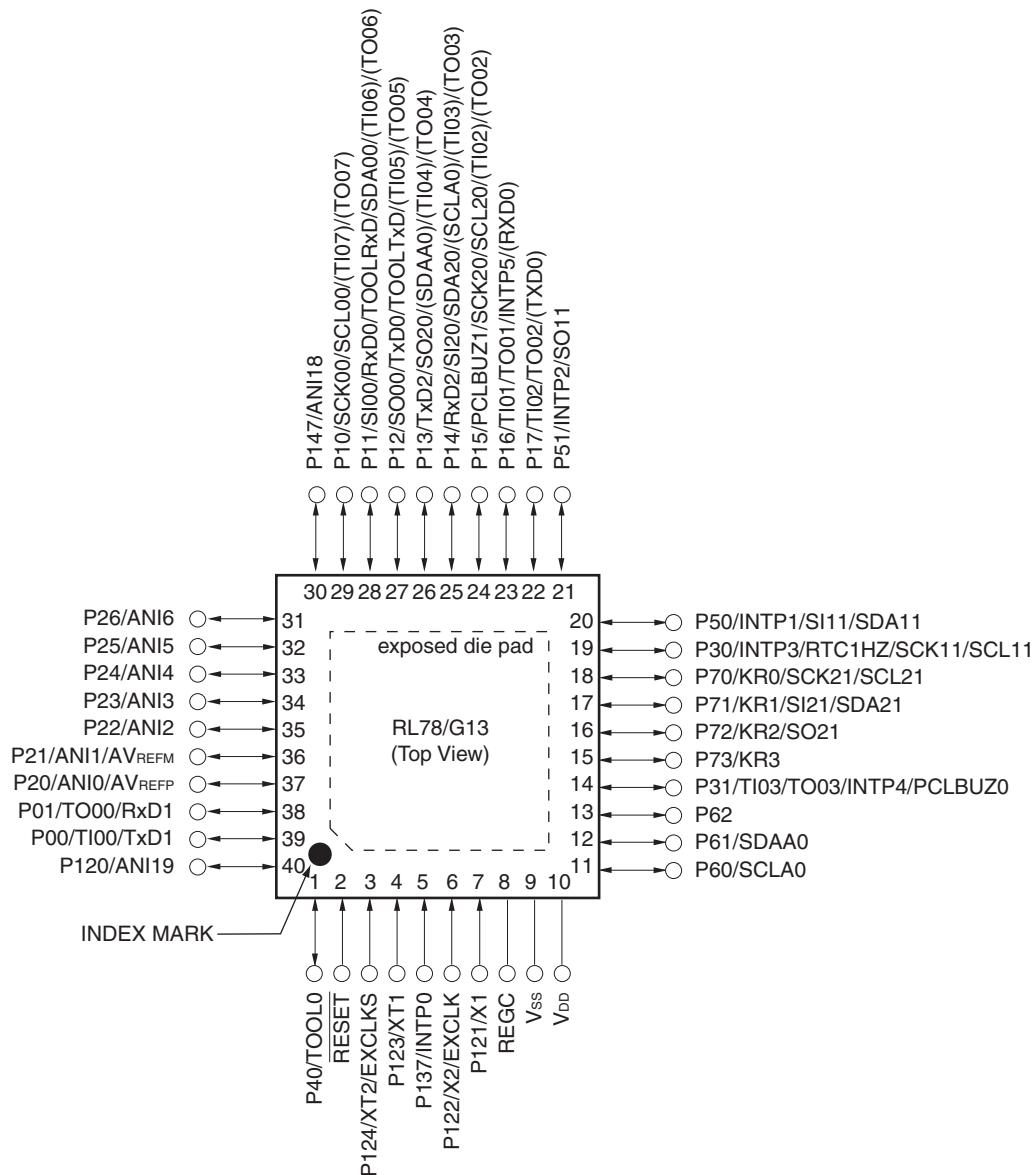


Caution Connect the REGC pin to V_{SS} via a capacitor (0.47 to 1 μ F).

Remark For pin identification, see **1.4 Pin Identification**.

1.3.7 40-pin products

- 40-pin plastic HWQFN (6 × 6 mm, 0.5 mm pitch)



Caution Connect the REGC pin to V_{ss} via a capacitor (0.47 to 1 μ F).

Remarks 1. For pin identification, see **1.4 Pin Identification**.

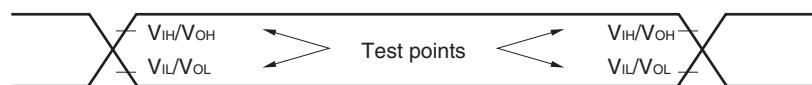
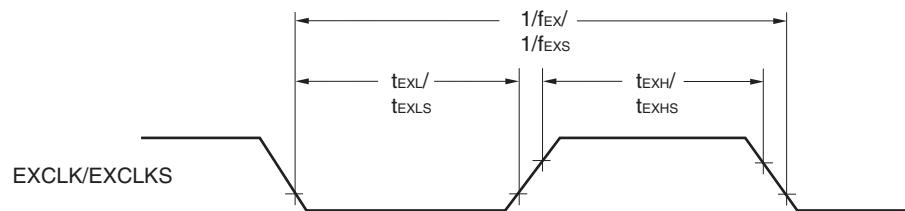
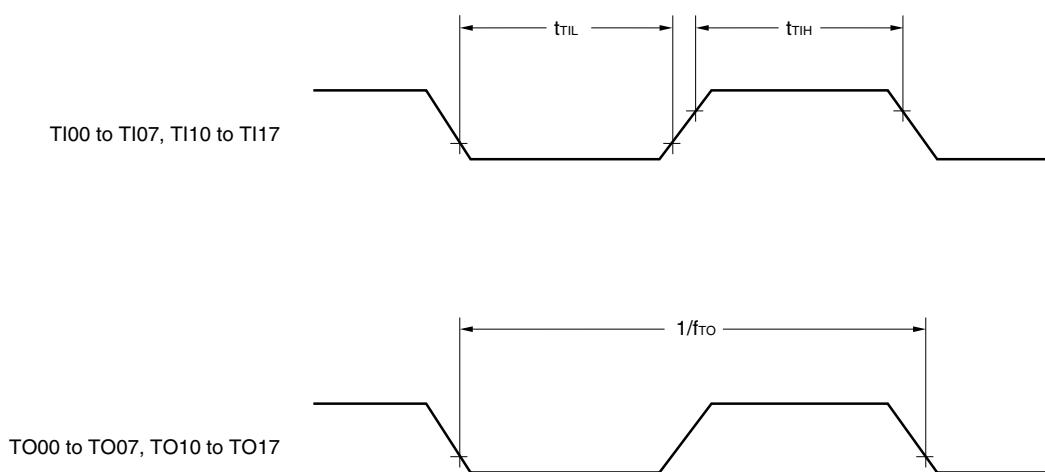
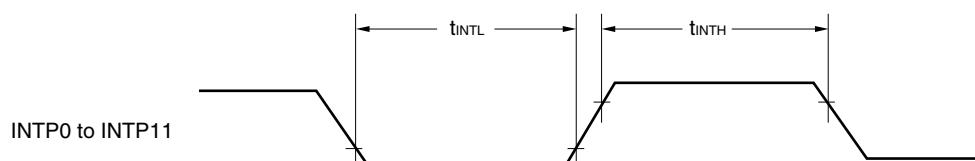
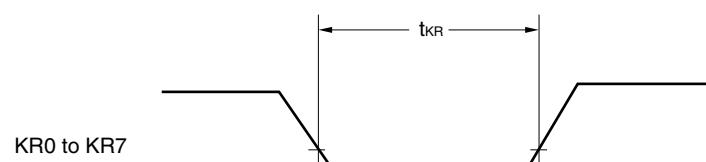
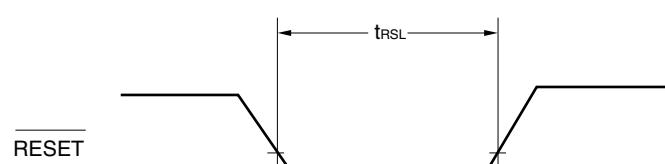
2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.
3. It is recommended to connect an exposed die pad to V_{ss}.

(3) 128-pin products, and flash ROM: 384 to 512 KB of 44- to 100-pin products

 $(T_A = -40$ to $+85^\circ\text{C}$, $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{ss} = EV_{ss0} = EV_{ss1} = 0 \text{ V}$) (1/2)

Parameter	Symbol	Conditions					MIN.	TYP.	MAX.	Unit
Supply current ^{Note 1}	I_{DD1}	Operating mode HS (high-speed main) mode ^{Note 5}	$f_{IH} = 32 \text{ MHz}$ ^{Note 3}	Basic operation	$V_{DD} = 5.0 \text{ V}$		2.6			mA
					$V_{DD} = 3.0 \text{ V}$		2.6			mA
			$f_{IH} = 24 \text{ MHz}$ ^{Note 3}	Normal operation	$V_{DD} = 5.0 \text{ V}$		6.1	9.5		mA
					$V_{DD} = 3.0 \text{ V}$		6.1	9.5		mA
		LS (low-speed main) mode ^{Note 5}	$f_{IH} = 16 \text{ MHz}$ ^{Note 3}	Normal operation	$V_{DD} = 5.0 \text{ V}$		3.5	5.3		mA
					$V_{DD} = 3.0 \text{ V}$		3.5	5.3		mA
		LV (low-voltage main) mode ^{Note 5}	$f_{IH} = 8 \text{ MHz}$ ^{Note 3}	Normal operation	$V_{DD} = 3.0 \text{ V}$		1.5	2.3		mA
					$V_{DD} = 2.0 \text{ V}$		1.5	2.3		mA
		HS (high-speed main) mode ^{Note 5}	$f_{MX} = 20 \text{ MHz}$ ^{Note 2} , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		3.9	6.1		mA
					Resonator connection		4.1	6.3		mA
			$f_{MX} = 20 \text{ MHz}$ ^{Note 2} , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		3.9	6.1		mA
					Resonator connection		4.1	6.3		mA
			$f_{MX} = 10 \text{ MHz}$ ^{Note 2} , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		2.5	3.7		mA
					Resonator connection		2.5	3.7		mA
		LS (low-speed main) mode ^{Note 5}	$f_{MX} = 8 \text{ MHz}$ ^{Note 2} , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		1.4	2.2		mA
					Resonator connection		1.4	2.2		mA
			$f_{MX} = 8 \text{ MHz}$ ^{Note 2} , $V_{DD} = 2.0 \text{ V}$	Normal operation	Square wave input		1.4	2.2		mA
					Resonator connection		1.4	2.2		mA
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = -40^\circ\text{C}$	Normal operation	Square wave input		5.4	6.5		μA
					Resonator connection		5.5	6.6		μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +25^\circ\text{C}$	Normal operation	Square wave input		5.5	6.5		μA
					Resonator connection		5.6	6.6		μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +50^\circ\text{C}$	Normal operation	Square wave input		5.6	9.4		μA
					Resonator connection		5.7	9.5		μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +70^\circ\text{C}$	Normal operation	Square wave input		5.9	12.0		μA
					Resonator connection		6.0	12.1		μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +85^\circ\text{C}$	Normal operation	Square wave input		6.6	16.3		μA
					Resonator connection		6.7	16.4		μA

(Notes and Remarks are listed on the next page.)

AC Timing Test Points**External System Clock Timing****TI/TO Timing****Interrupt Request Input Timing****Key Interrupt Input Timing****RESET Input Timing**

(3) During communication at same potential (CSI mode) (master mode, SCKp... internal clock output)

 $(T_A = -40$ to $+85^\circ\text{C}$, $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$)

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit	
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
SCKp cycle time	t _{KCY1}	$t_{KCY1} \geq 4/f_{CLK}$	2.7 V $\leq EV_{DD0} \leq 5.5$ V	125		500		1000		ns
			2.4 V $\leq EV_{DD0} \leq 5.5$ V	250		500		1000		ns
			1.8 V $\leq EV_{DD0} \leq 5.5$ V	500		500		1000		ns
			1.7 V $\leq EV_{DD0} \leq 5.5$ V	1000		1000		1000		ns
			1.6 V $\leq EV_{DD0} \leq 5.5$ V	—		1000		1000		ns
SCKp high-/low-level width	t _{Kh1} , t _{kl1}	4.0 V $\leq EV_{DD0} \leq 5.5$ V	t _{KCY1} /2 – 12		t _{KCY1} /2 – 50		t _{KCY1} /2 – 50		ns	
		2.7 V $\leq EV_{DD0} \leq 5.5$ V	t _{KCY1} /2 – 18		t _{KCY1} /2 – 50		t _{KCY1} /2 – 50		ns	
		2.4 V $\leq EV_{DD0} \leq 5.5$ V	t _{KCY1} /2 – 38		t _{KCY1} /2 – 50		t _{KCY1} /2 – 50		ns	
		1.8 V $\leq EV_{DD0} \leq 5.5$ V	t _{KCY1} /2 – 50		t _{KCY1} /2 – 50		t _{KCY1} /2 – 50		ns	
		1.7 V $\leq EV_{DD0} \leq 5.5$ V	t _{KCY1} /2 – 100		t _{KCY1} /2 – 100		t _{KCY1} /2 – 100		ns	
		1.6 V $\leq EV_{DD0} \leq 5.5$ V	—		t _{KCY1} /2 – 100		t _{KCY1} /2 – 100		ns	
Slp setup time (to SCKp↑) <small>Note 1</small>	t _{SIK1}	4.0 V $\leq EV_{DD0} \leq 5.5$ V	44		110		110		ns	
		2.7 V $\leq EV_{DD0} \leq 5.5$ V	44		110		110		ns	
		2.4 V $\leq EV_{DD0} \leq 5.5$ V	75		110		110		ns	
		1.8 V $\leq EV_{DD0} \leq 5.5$ V	110		110		110		ns	
		1.7 V $\leq EV_{DD0} \leq 5.5$ V	220		220		220		ns	
		1.6 V $\leq EV_{DD0} \leq 5.5$ V	—		220		220		ns	
Slp hold time (from SCKp↑) <small>Note 2</small>	t _{ksi1}	1.7 V $\leq EV_{DD0} \leq 5.5$ V	19		19		19		ns	
		1.6 V $\leq EV_{DD0} \leq 5.5$ V	—		19		19		ns	
Delay time from SCKp↓ to SOp output <small>Note 3</small>	t _{ks01}	1.7 V $\leq EV_{DD0} \leq 5.5$ V C = 30 pF ^{Note 4}		25		25		25	ns	
		1.6 V $\leq EV_{DD0} \leq 5.5$ V C = 30 pF ^{Note 4}		—		25		25	ns	

- Notes**
- When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp setup time becomes “to SCKp↓” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
 - When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp hold time becomes “from SCKp↓” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
 - When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The delay time to SOp output becomes “from SCKp↑” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
 - C is the load capacitance of the SCKp and SOp output lines.

Caution Select the normal input buffer for the Slp pin and the normal output mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg).

(6) Communication at different potential (1.8 V, 2.5 V, 3 V) (UART mode) (2/2)

 $(T_A = -40$ to $+85^\circ\text{C}$, $1.8 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
Transfer rate	Transmission	4.0 V $\leq EV_{DD0} \leq 5.5$ V, 2.7 V $\leq V_b \leq 4.0$ V	Theoretical value of the maximum transfer rate $C_b = 50 \text{ pF}$, $R_b = 1.4 \text{ k}\Omega$, $V_b = 2.7 \text{ V}$	Note 1		Note 1		Note 1		bps
				2.8 Note 2		2.8 Note 2		2.8 Note 2		Mbps
				Note 3		Note 3		Note 3		bps
		2.7 V $\leq EV_{DD0} < 4.0$ V, 2.3 V $\leq V_b \leq 2.7$ V	Theoretical value of the maximum transfer rate $C_b = 50 \text{ pF}$, $R_b = 2.7 \text{ k}\Omega$, $V_b = 2.3 \text{ V}$	1.2 Note 4		1.2 Note 4		1.2 Note 4		Mbps
		1.8 V $\leq EV_{DD0} < 3.3$ V, 1.6 V $\leq V_b \leq 2.0$ V	Theoretical value of the maximum transfer rate $C_b = 50 \text{ pF}$, $R_b = 5.5 \text{ k}\Omega$, $V_b = 1.6 \text{ V}$	Notes 5, 6		Notes 5, 6		Notes 5, 6		bps
				0.43 Note 7		0.43 Note 7		0.43 Note 7		Mbps

Notes 1. The smaller maximum transfer rate derived by using $f_{MCK}/6$ or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when $4.0 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$ and $2.7 \text{ V} \leq V_b \leq 4.0 \text{ V}$

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{2.2}{V_b})\} \times 3} \text{ [bps]}$$

$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{2.2}{V_b})\}}{\left(\frac{1}{\text{Transfer rate}}\right) \times \text{Number of transferred bits}} \times 100 \text{ [%]}$$

* This value is the theoretical value of the relative difference between the transmission and reception sides.

- 2.** This value as an example is calculated when the conditions described in the “Conditions” column are met. Refer to Note 1 above to calculate the maximum transfer rate under conditions of the customer.

(9) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (slave mode, SCKp... external clock input)

($T_A = -40$ to $+85^\circ\text{C}$, $1.8 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$) (2/2)

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCKp high-/low-level width	t_{KH2}, t_{KL2}	4.0 V $\leq EV_{DD0} \leq 5.5$ V, 2.7 V $\leq V_b \leq 4.0$ V	$t_{KCY2}/2$ – 12		$t_{KCY2}/2$ – 50		$t_{KCY2}/2$ – 50		ns
		2.7 V $\leq EV_{DD0} < 4.0$ V, 2.3 V $\leq V_b \leq 2.7$ V	$t_{KCY2}/2$ – 18		$t_{KCY2}/2$ – 50		$t_{KCY2}/2$ – 50		ns
		1.8 V $\leq EV_{DD0} < 3.3$ V, 1.6 V $\leq V_b \leq 2.0$ V ^{Note 2}	$t_{KCY2}/2$ – 50		$t_{KCY2}/2$ – 50		$t_{KCY2}/2$ – 50		ns
Slp setup time (to SCKp \uparrow) ^{Note 3}	t_{SIK2}	4.0 V $\leq EV_{DD0} \leq 5.5$ V, 2.7 V $\leq V_b \leq 4.0$ V	$1/f_{MCK}$ + 20		$1/f_{MCK}$ + 30		$1/f_{MCK}$ + 30		ns
		2.7 V $\leq EV_{DD0} < 4.0$ V, 2.3 V $\leq V_b \leq 2.7$ V	$1/f_{MCK}$ + 20		$1/f_{MCK}$ + 30		$1/f_{MCK}$ + 30		ns
		1.8 V $\leq EV_{DD0} < 3.3$ V, 1.6 V $\leq V_b \leq 2.0$ V ^{Note 2}	$1/f_{MCK}$ + 30		$1/f_{MCK}$ + 30		$1/f_{MCK}$ + 30		ns
Slp hold time (from SCKp \uparrow) ^{Note 4}	t_{SKI2}		$1/f_{MCK} + 31$		$1/f_{MCK} + 31$		$1/f_{MCK} + 31$		ns
Delay time from SCKp \downarrow to SOp output ^{Note 5}	t_{KS02}	4.0 V $\leq EV_{DD0} \leq 5.5$ V, 2.7 V $\leq V_b \leq 4.0$ V, $C_b = 30 \text{ pF}$, $R_b = 1.4 \text{ k}\Omega$		$2/f_{MCK}$ + 120		$2/f_{MCK}$ + 573		$2/f_{MCK}$ + 573	ns
		2.7 V $\leq EV_{DD0} < 4.0$ V, 2.3 V $\leq V_b \leq 2.7$ V, $C_b = 30 \text{ pF}$, $R_b = 2.7 \text{ k}\Omega$		$2/f_{MCK}$ + 214		$2/f_{MCK}$ + 573		$2/f_{MCK}$ + 573	ns
		1.8 V $\leq EV_{DD0} < 3.3$ V, 1.6 V $\leq V_b \leq 2.0$ V ^{Note 2} , $C_b = 30 \text{ pF}$, $R_b = 5.5 \text{ k}\Omega$		$2/f_{MCK}$ + 573		$2/f_{MCK}$ + 573		$2/f_{MCK}$ + 573	ns

Notes 1. Transfer rate in the SNOOZE mode : MAX. 1 Mbps

2. Use it with $EV_{DD0} \geq V_b$.
3. When $DAP_{mn} = 0$ and $CKP_{mn} = 0$, or $DAP_{mn} = 1$ and $CKP_{mn} = 1$. The Slp setup time becomes “to SCKp \uparrow ” when $DAP_{mn} = 0$ and $CKP_{mn} = 1$, or $DAP_{mn} = 1$ and $CKP_{mn} = 0$.
4. When $DAP_{mn} = 0$ and $CKP_{mn} = 0$, or $DAP_{mn} = 1$ and $CKP_{mn} = 1$. The Slp hold time becomes “from SCKp \downarrow ” when $DAP_{mn} = 0$ and $CKP_{mn} = 1$, or $DAP_{mn} = 1$ and $CKP_{mn} = 0$.
5. When $DAP_{mn} = 0$ and $CKP_{mn} = 0$, or $DAP_{mn} = 1$ and $CKP_{mn} = 1$. The delay time to SOp output becomes “from SCKp \uparrow ” when $DAP_{mn} = 0$ and $CKP_{mn} = 1$, or $DAP_{mn} = 1$ and $CKP_{mn} = 0$.

Caution Select the TTL input buffer for the Slp pin and the N-ch open drain output (V_{DD} tolerance (for the 20- to 52-pin products)/ EV_{DD} tolerance (for the 64- to 128-pin products)) mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg). For V_{IH} and V_{IL} , see the DC characteristics with TTL input buffer selected.

(Remarks are listed on the next page.)

(3) I²C fast mode plus $(T_A = -40$ to $+85^\circ\text{C}$, $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCLA0 clock frequency	f _{SCL}	Fast mode plus: $f_{CLK} \geq 10 \text{ MHz}$	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$	0	1000	—	—	—	—	kHz
Setup time of restart condition	t _{SU:STA}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.26		—	—	—	—	μs
Hold time ^{Note 1}	t _{HD:STA}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.26		—	—	—	—	μs
Hold time when SCLA0 = "L"	t _{LOW}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.5		—	—	—	—	μs
Hold time when SCLA0 = "H"	t _{HIGH}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.26		—	—	—	—	μs
Data setup time (reception)	t _{SU:DAT}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		50		—	—	—	—	μs
Data hold time (transmission) ^{Note 2}	t _{HD:DAT}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0	0.45	—	—	—	—	μs
Setup time of stop condition	t _{SU:STO}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.26		—	—	—	—	μs
Bus-free time	t _{BUF}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.5		—	—	—	—	μs

Notes 1. The first clock pulse is generated after this period when the start/restart condition is detected.

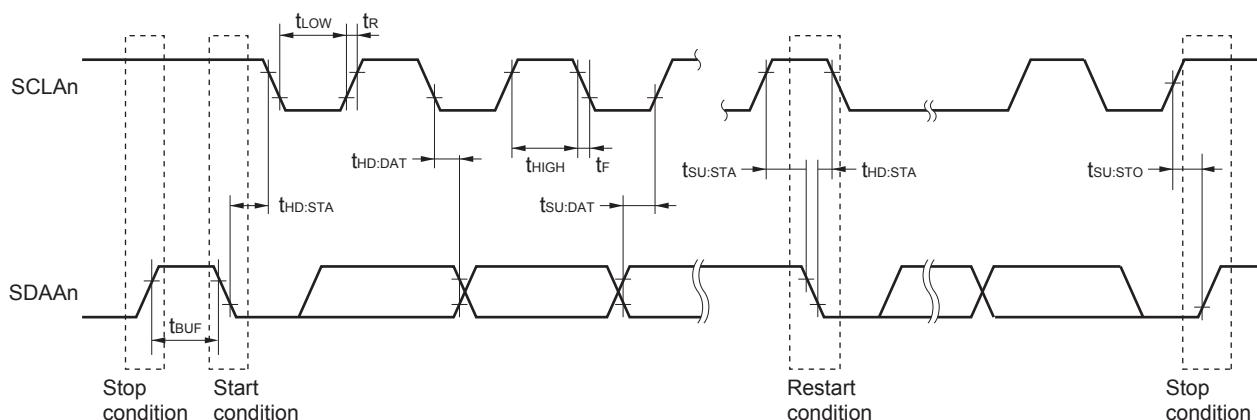
<R> 2. The maximum value (MAX.) of t_{HD:DAT} is during normal transfer and a wait state is inserted in the ACK (acknowledge) timing.

Caution The values in the above table are applied even when bit 2 (PIOR2) in the peripheral I/O redirection register (PIOR) is 1. At this time, the pin characteristics (I_{OH1}, I_{OL1}, V_{OH1}, V_{OL1}) must satisfy the values in the redirect destination.

Remark The maximum value of C_b (communication line capacitance) and the value of R_b (communication line pull-up resistor) at that time in each mode are as follows.

Fast mode plus: C_b = 120 pF, R_b = 1.1 k Ω

IICA serial transfer timing



Remark n = 0, 1

2.6.5 Power supply voltage rising slope characteristics

($T_A = -40$ to $+85^\circ\text{C}$, $V_{SS} = 0$ V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Power supply voltage rising slope	S_{VDD}				54	V/ms

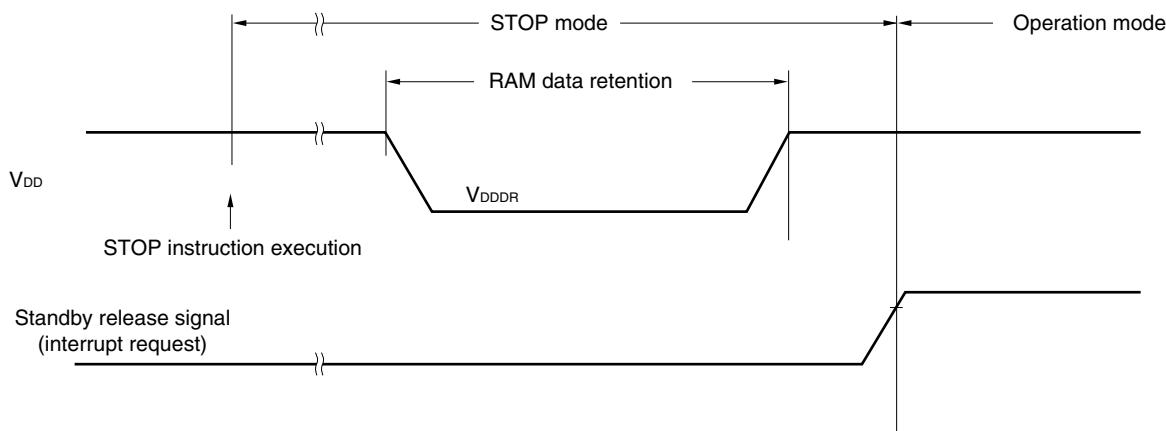
Caution Make sure to keep the internal reset state by the LVD circuit or an external reset until V_{DD} reaches the operating voltage range shown in 2.4 AC Characteristics.

2.7 RAM Data Retention Characteristics

($T_A = -40$ to $+85^\circ\text{C}$, $V_{SS} = 0$ V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Data retention supply voltage	V_{DDDR}		1.46 ^{Note}		5.5	V

Note This depends on the POR detection voltage. For a falling voltage, data in RAM are retained until the voltage reaches the level that triggers a POR reset but not once it reaches the level at which a POR reset is generated.



(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V) (3/5)

Items	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Input voltage, high	V _{IH1}	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147	Normal input buffer	0.8EV _{DD0}		EV _{DD0}	V
	V _{IH2}	P01, P03, P04, P10, P11, P13 to P17, P43, P44, P53 to P55, P80, P81, P142, P143	TTL input buffer 4.0 V ≤ EV _{DD0} ≤ 5.5 V	2.2		EV _{DD0}	V
			TTL input buffer 3.3 V ≤ EV _{DD0} < 4.0 V	2.0		EV _{DD0}	V
			TTL input buffer 2.4 V ≤ EV _{DD0} < 3.3 V	1.5		EV _{DD0}	V
	V _{IH3}	P20 to P27, P150 to P156		0.7V _{DD}		V _{DD}	V
	V _{IH4}	P60 to P63		0.7EV _{DD0}		6.0	V
	V _{IH5}	P121 to P124, P137, EXCLK, EXCLKS, RESET		0.8V _{DD}		V _{DD}	V
Input voltage, low	V _{IL1}	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147	Normal input buffer	0		0.2EV _{DD0}	V
	V _{IL2}	P01, P03, P04, P10, P11, P13 to P17, P43, P44, P53 to P55, P80, P81, P142, P143	TTL input buffer 4.0 V ≤ EV _{DD0} ≤ 5.5 V	0		0.8	V
			TTL input buffer 3.3 V ≤ EV _{DD0} < 4.0 V	0		0.5	V
			TTL input buffer 2.4 V ≤ EV _{DD0} < 3.3 V	0		0.32	V
	V _{IL3}	P20 to P27, P150 to P156		0		0.3V _{DD}	V
	V _{IL4}	P60 to P63		0		0.3EV _{DD0}	V
	V _{IL5}	P121 to P124, P137, EXCLK, EXCLKS, RESET		0		0.2V _{DD}	V

Caution The maximum value of V_{IH} of pins P00, P02 to P04, P10 to P15, P17, P43 to P45, P50, P52 to P55, P71, P74, P80 to P82, P96, and P142 to P144 is EV_{DD0}, even in the N-ch open-drain mode.

Remark Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

(2) Flash ROM: 96 to 256 KB of 30- to 100-pin products

 $(T_A = -40$ to $+105^\circ\text{C}$, $2.4 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$) (1/2)

Parameter	Symbol	Conditions				MIN.	TYP.	MAX.	Unit
Supply current Note 1	I_{DD1}	Operating mode	HS (high-speed main) mode Note 5	$f_{IH} = 32 \text{ MHz}$ ^{Note 3}	Basic operation	$V_{DD} = 5.0 \text{ V}$		2.3	mA
					Normal operation	$V_{DD} = 3.0 \text{ V}$		2.3	mA
				$f_{IH} = 24 \text{ MHz}$ ^{Note 3}	Normal operation	$V_{DD} = 5.0 \text{ V}$		5.2	mA
					Normal operation	$V_{DD} = 3.0 \text{ V}$		5.2	mA
			HS (high-speed main) mode Note 5	$f_{MX} = 20 \text{ MHz}$ ^{Note 2} , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		3.4	mA
					Normal operation	Resonator connection		3.6	mA
				$f_{MX} = 20 \text{ MHz}$ ^{Note 2} , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		3.4	mA
					Normal operation	Resonator connection		3.6	mA
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = -40^\circ\text{C}$	Normal operation	Square wave input		2.1	3.5	mA
					Normal operation	Resonator connection		2.1	3.5
				$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +25^\circ\text{C}$	Normal operation	Square wave input		4.8	μA
					Normal operation	Resonator connection		4.9	μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +50^\circ\text{C}$	Normal operation	Square wave input		4.9	5.9	μA
					Normal operation	Resonator connection		5.0	6.0 μA
				$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +70^\circ\text{C}$	Normal operation	Square wave input		5.0	7.6 μA
					Normal operation	Resonator connection		5.1	7.7 μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +85^\circ\text{C}$	Normal operation	Square wave input		5.2	9.3 μA	
					Normal operation	Resonator connection		5.3	9.4 μA
				$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +105^\circ\text{C}$	Normal operation	Square wave input		5.7	13.3 μA
					Normal operation	Resonator connection		5.8	13.4 μA
					Normal operation	Square wave input		10.0	46.0 μA
					Normal operation	Resonator connection		10.0	46.0 μA

(Notes and Remarks are listed on the next page.)

3.4 AC Characteristics

(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V)

Items	Symbol	Conditions			MIN.	TYP.	MAX.	Unit	
Instruction cycle (minimum instruction execution time)	T _{CY}	Main system clock (f _{MAIN}) operation	HS (high-speed main) mode	2.7 V ≤ V _{DD} ≤ 5.5 V	0.03125		1	μs	
				2.4 V ≤ V _{DD} < 2.7 V	0.0625		1	μs	
		Subsystem clock (f _{SUB}) operation		2.4 V ≤ V _{DD} ≤ 5.5 V	28.5	30.5	31.3	μs	
		In the self programming mode	HS (high-speed main) mode	2.7 V ≤ V _{DD} ≤ 5.5 V	0.03125		1	μs	
				2.4 V ≤ V _{DD} < 2.7 V	0.0625		1	μs	
External system clock frequency	f _{EX}	2.7 V ≤ V _{DD} ≤ 5.5 V			1.0		20.0	MHz	
		2.4 V ≤ V _{DD} < 2.7 V			1.0		16.0	MHz	
	f _{EXS}				32		35	kHz	
External system clock input high-level width, low-level width	t _{EXH} , t _{EXL}	2.7 V ≤ V _{DD} ≤ 5.5 V			24			ns	
		2.4 V ≤ V _{DD} < 2.7 V			30			ns	
	t _{EXHS} , t _{EXLS}				13.7			μs	
TI00 to TI07, TI10 to TI17 input high-level width, low-level width	t _{TIH} , t _{TIL}				1/f _{MCK} +10			ns ^{Note}	
TO00 to TO07, TO10 to TO17 output frequency	f _{TO}	HS (high-speed main) mode	4.0 V ≤ EV _{DD0} ≤ 5.5 V				16	MHz	
			2.7 V ≤ EV _{DD0} < 4.0 V				8	MHz	
			2.4 V ≤ EV _{DD0} < 2.7 V				4	MHz	
PCLBUZ0, PCLBUZ1 output frequency	f _{PCL}	HS (high-speed main) mode	4.0 V ≤ EV _{DD0} ≤ 5.5 V				16	MHz	
			2.7 V ≤ EV _{DD0} < 4.0 V				8	MHz	
			2.4 V ≤ EV _{DD0} < 2.7 V				4	MHz	
Interrupt input high-level width, low-level width	t _{INTH} , t _{INTL}	INTP0		2.4 V ≤ V _{DD} ≤ 5.5 V	1			μs	
		INTP1 to INTP11		2.4 V ≤ EV _{DD0} ≤ 5.5 V	1			μs	
Key interrupt input low-level width	t _{KR}	KR0 to KR7		2.4 V ≤ EV _{DD0} ≤ 5.5 V	250			ns	
RESET low-level width	t _{RS}				10			μs	

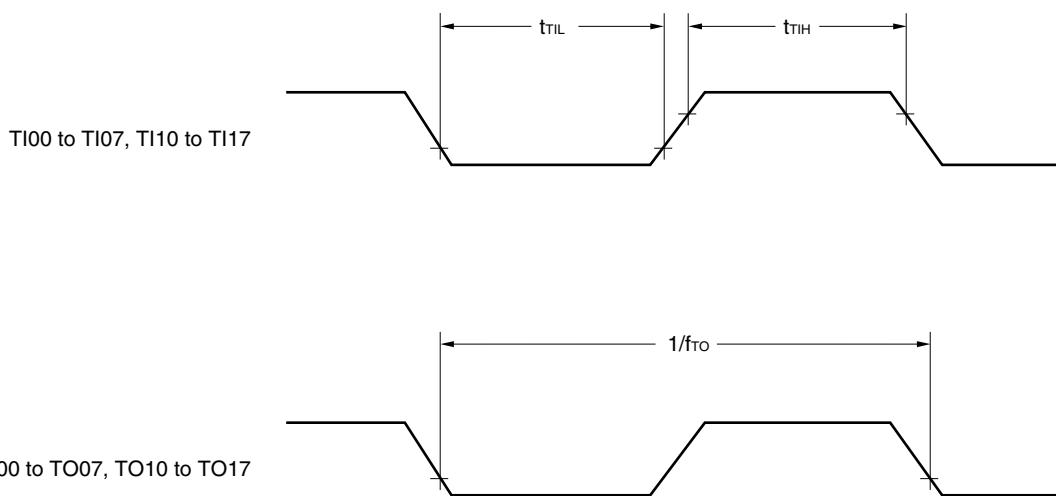
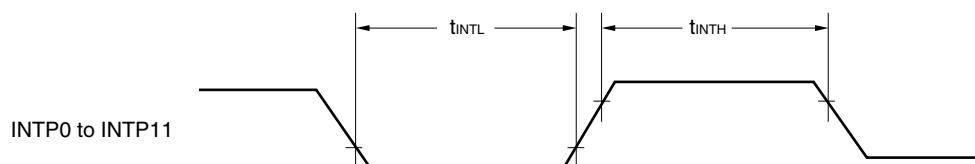
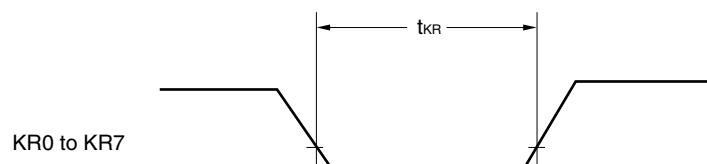
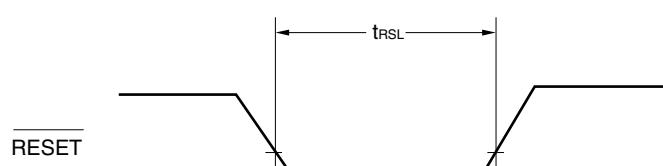
Note The following conditions are required for low voltage interface when EV_{DD0} < V_{DD}

2.4V ≤ EV_{DD0} < 2.7 V : MIN. 125 ns

Remark f_{MCK}: Timer array unit operation clock frequency

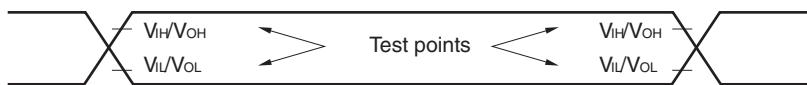
(Operation clock to be set by the CKSmn0, CKSmn1 bits of timer mode register mn (TMRmn).

m: Unit number (m = 0, 1), n: Channel number (n = 0 to 7))

TI/TO Timing**Interrupt Request Input Timing****Key Interrupt Input Timing****RESET Input Timing**

3.5 Peripheral Functions Characteristics

AC Timing Test Points



3.5.1 Serial array unit

(1) During communication at same potential (UART mode)

(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V)

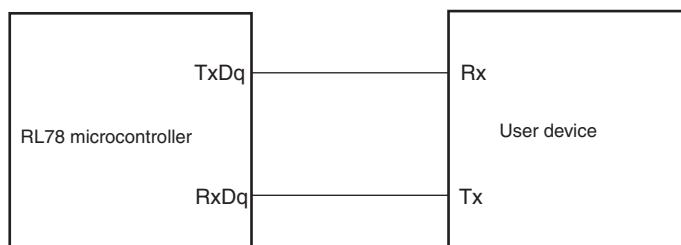
Parameter	Symbol	Conditions	HS (high-speed main) Mode		Unit
			MIN.	MAX.	
Transfer rate ^{Note 1}		Theoretical value of the maximum transfer rate f _{CLK} = 32 MHz, f _{MCK} = f _{CLK}		f _{MCK} /12 ^{Note 2}	bps
				2.6	Mbps

Notes 1. Transfer rate in the SNOOZE mode is 4800 bps only.

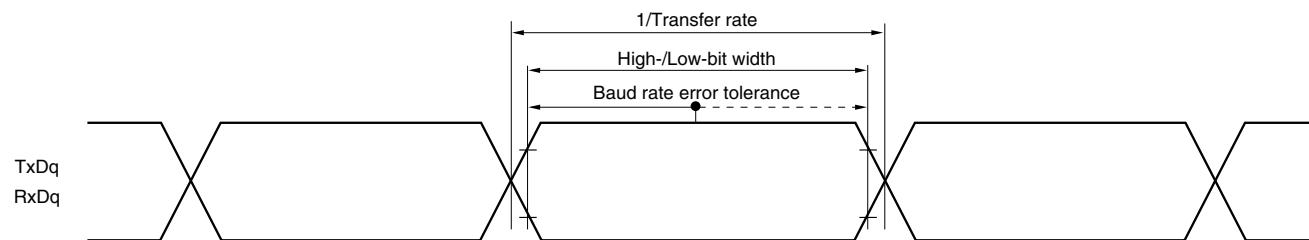
2. The following conditions are required for low voltage interface when EV_{DD0} < V_{DD}.
- 2.4 V ≤ EV_{DD0} < 2.7 V : MAX. 1.3 Mbps

Caution Select the normal input buffer for the RxDq pin and the normal output mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg).

UART mode connection diagram (during communication at same potential)



UART mode bit width (during communication at same potential) (reference)



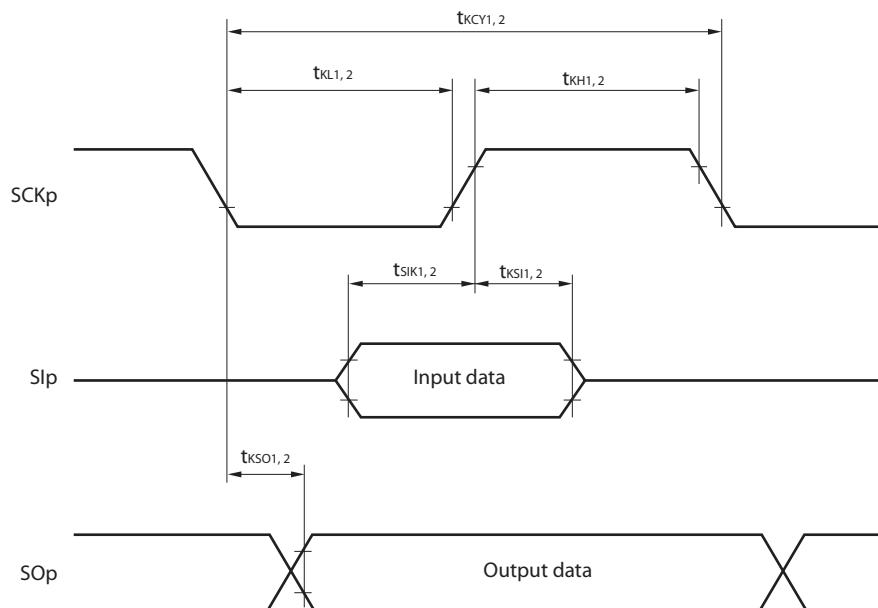
Remarks 1. q: UART number (q = 0 to 3), g: PIM and POM number (g = 0, 1, 8, 14)

2. f_{MCK}: Serial array unit operation clock frequency

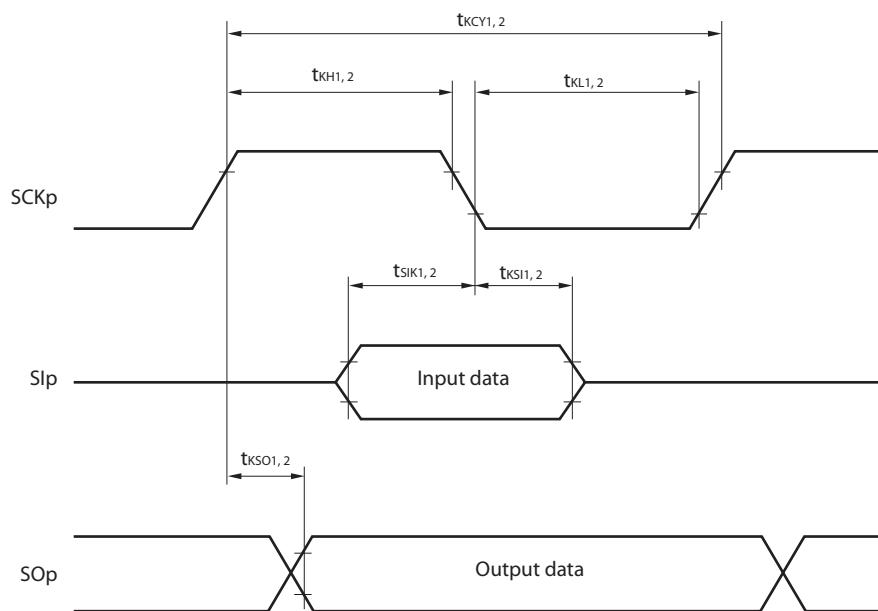
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13))

CSI mode serial transfer timing (during communication at same potential)

(When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.)

**CSI mode serial transfer timing (during communication at same potential)**

(When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.)

**Remarks 1.** p: CSI number (p = 00, 01, 10, 11, 20, 21, 30, 31)**2.** m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13)

(6) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock output) (2/3)

(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{ss} = EV_{SS0} = EV_{SS1} = 0 V)

Parameter	Symbol	Conditions	HS (high-speed main) Mode		Unit
			MIN.	MAX.	
Slp setup time (to SCKp↑) ^{Note}	t _{SIK1}	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V, C _b = 30 pF, R _b = 1.4 kΩ	162		ns
		2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V, C _b = 30 pF, R _b = 2.7 kΩ	354		ns
		2.4 V ≤ EV _{DD0} < 3.3 V, 1.6 V ≤ V _b ≤ 2.0 V, C _b = 30 pF, R _b = 5.5 kΩ	958		ns
Slp hold time (from SCKp↑) ^{Note}	t _{KSI1}	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V, C _b = 30 pF, R _b = 1.4 kΩ	38		ns
		2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V, C _b = 30 pF, R _b = 2.7 kΩ	38		ns
		2.4 V ≤ EV _{DD0} < 3.3 V, 1.6 V ≤ V _b ≤ 2.0 V, C _b = 30 pF, R _b = 2.7 kΩ	38		ns
Delay time from SCKp↓ to SO _p output ^{Note}	t _{KSO1}	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V, C _b = 30 pF, R _b = 1.4 kΩ		200	ns
		2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V, C _b = 30 pF, R _b = 2.7 kΩ		390	ns
		2.4 V ≤ EV _{DD0} < 3.3 V, 1.6 V ≤ V _b ≤ 2.0 V, C _b = 30 pF, R _b = 5.5 kΩ		966	ns

Note When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.

Caution Select the TTL input buffer for the Slp pin and the N-ch open drain output (V_{DD} tolerance (for the 20- to 52-pin products)/EV_{DD} tolerance (for the 64- to 100-pin products)) mode for the SO_p pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg). For V_{IH} and V_{IL}, see the DC characteristics with TTL input buffer selected.

(Remarks are listed on the page after the next page.)

(4) When reference voltage (+) = Internal reference voltage (ADREFP1 = 1, ADREFP0 = 0), reference voltage (-) = AV_{REFM}/ANI1 (ADREFM = 1), target pin : ANI0, ANI2 to ANI14, ANI16 to ANI26

(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V, Reference voltage (+) = V_{BGR}^{Note 3}, Reference voltage (-) = AV_{REFM}^{Note 4} = 0 V, HS (high-speed main) mode)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Resolution	RES			8		bit	
Conversion time	t _{CONV}	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V	17		39	μs
Zero-scale error ^{Notes 1, 2}	E _{Zs}	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V			±0.60	%FSR
Integral linearity error ^{Note 1}	ILE	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V			±2.0	LSB
Differential linearity error ^{Note 1}	DLE	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V			±1.0	LSB
Analog input voltage	V _{AIN}			0		V _{BGR} ^{Note 3}	V

Notes 1. Excludes quantization error (±1/2 LSB).

2. This value is indicated as a ratio (%FSR) to the full-scale value.

3. Refer to 3.6.2 Temperature sensor/internal reference voltage characteristics.

4. When reference voltage (-) = V_{SS}, the MAX. values are as follows.

Zero-scale error: Add ±0.35%FSR to the MAX. value when reference voltage (-) = AV_{REFM}.

Integral linearity error: Add ±0.5 LSB to the MAX. value when reference voltage (-) = AV_{REFM}.

Differential linearity error: Add ±0.2 LSB to the MAX. value when reference voltage (-) = AV_{REFM}.

3.6.2 Temperature sensor/internal reference voltage characteristics

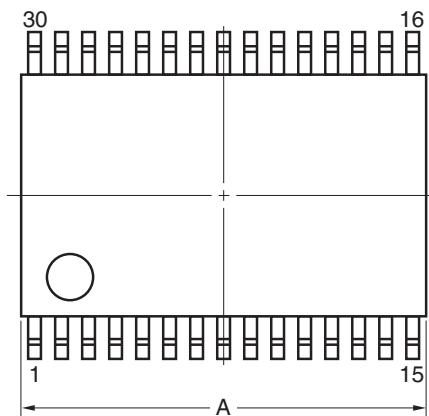
(TA = -40 to +105°C, 2.4 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V, HS (high-speed main) mode)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Temperature sensor output voltage	V _{TMP25}	Setting ADS register = 80H, TA = +25°C		1.05		V
Internal reference voltage	V _{BGR}	Setting ADS register = 81H	1.38	1.45	1.5	V
Temperature coefficient	F _{VTMP5}	Temperature sensor that depends on the temperature		-3.6		mV/°C
Operation stabilization wait time	t _{AMP}		5			μs

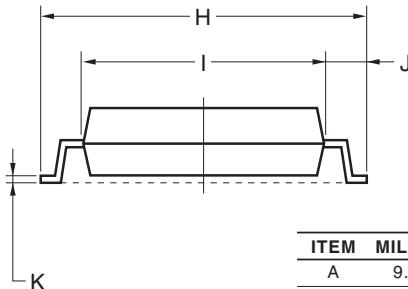
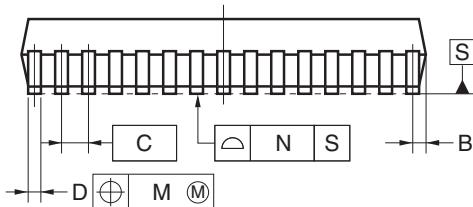
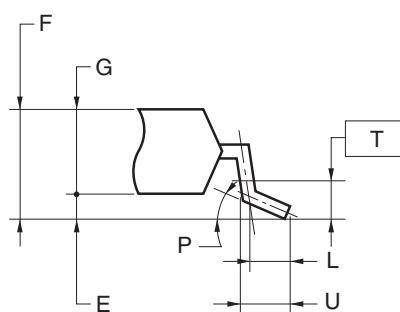
4.4 30-pin Products

R5F100AAASP, R5F100ACASP, R5F100ADASP, R5F100AEASP, R5F100AFASP, R5F100AGASP
 R5F101AAASP, R5F101ACASP, R5F101ADASP, R5F101AEASP, R5F101AFASP, R5F101AGASP
 R5F100AADSP, R5F100ACDSP, R5F100ADDSP, R5F100AEDSP, R5F100AFDSP, R5F100AGDSP
 R5F101AADSP, R5F101ACDSP, R5F101ADDSP, R5F101AEDSP, R5F101AFDSP, R5F101AGDSP
 R5F100AAGSP, R5F100ACGSP, R5F100ADGSP, R5F100AEGSP, R5F100AFGSP, R5F100AGGSP

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LSSOP30-0300-0.65	PLSP0030JB-B	S30MC-65-5A4-3	0.18



detail of lead end

**NOTE**

Each lead centerline is located within 0.13 mm of its true position (T.P.) at maximum material condition.

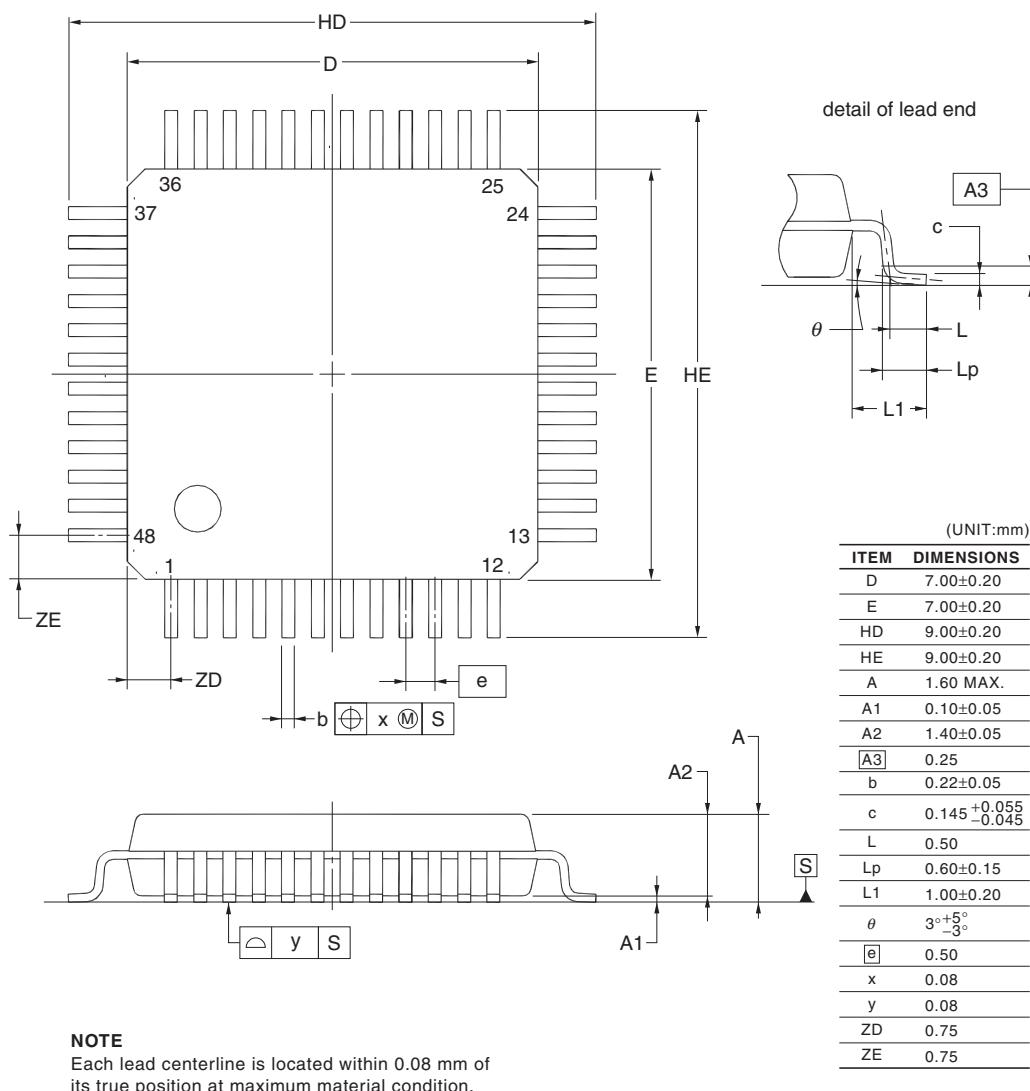
ITEM	MILLIMETERS
A	9.85±0.15
B	0.45 MAX.
C	0.65 (T.P.)
D	0.24 ^{+0.08} _{-0.07}
E	0.1±0.05
F	1.3±0.1
G	1.2
H	8.1±0.2
I	6.1±0.2
J	1.0±0.2
K	0.17±0.03
L	0.5
M	0.13
N	0.10
P	3° ^{+5°} _{-3°}
T	0.25
U	0.6±0.15

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4.9 48-pin Products

R5F100GAAFB, R5F100GCAFB, R5F100GDAFB, R5F100GEAFB, R5F100GFAFB, R5F100GGAFB,
 R5F100GHAFB, R5F100GJAFB, R5F100GKAFB, R5F100GLAFB
 R5F101GAAFB, R5F101GCAFB, R5F101GDAFB, R5F101GEAFB, R5F101GFAFB, R5F101GGAFB,
 R5F101GHAFB, R5F101GJAFB, R5F101GKAFB, R5F101GLAFB
 R5F100GADFB, R5F100GCDFB, R5F100GDDFB, R5F100GEDFB, R5F100GFDFB, R5F100GGDFB,
 R5F100GHDDB, R5F100GJDFB, R5F100GKDFB, R5F100GLDFB
 R5F101GADFB, R5F101GCDFB, R5F101GDDFB, R5F101GEDFB, R5F101GFDFB, R5F101GGDFB,
 R5F101GHDDB, R5F101GJDFB, R5F101GKDFB, R5F101GLDFB
 R5F100GAGFB, R5F100GCGFB, R5F100GDGFB, R5F100GEGFB, R5F100GFGFB, R5F100GGGFB,
 R5F100GHGFB, R5F100GJGFB

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LFQFP48-7x7-0.50	PLQP0048KF-A	P48GA-50-8EU-1	0.16



R5F100LCABG, R5F100LDABG, R5F100LEABG, R5F100LFABG, R5F100LGABG, R5F100LHABG,

R5F100LJABG

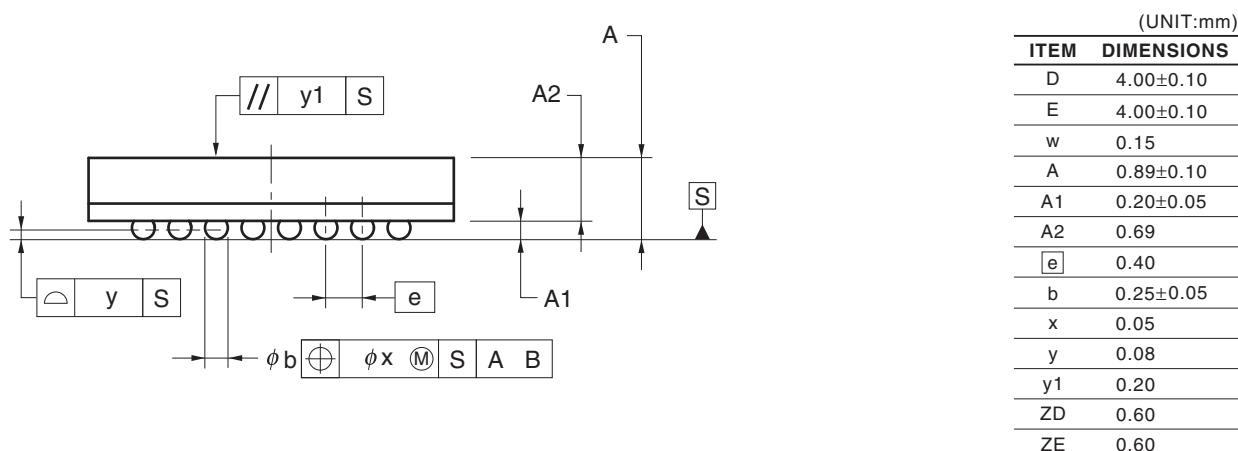
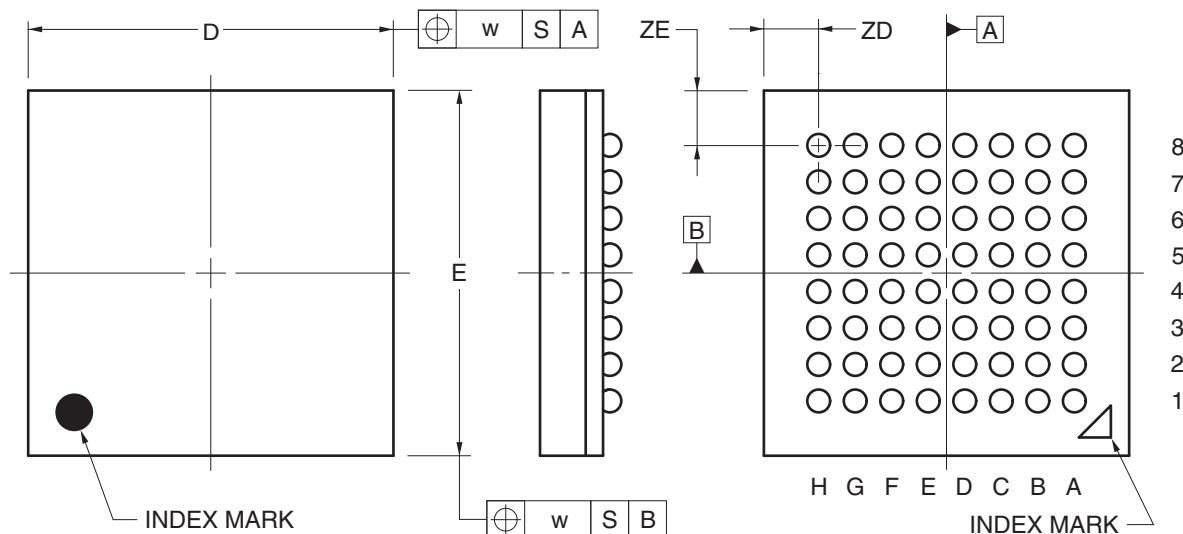
R5F101LCABG, R5F101LDABG, R5F101LEABG, R5F101LFABG, R5F101LGABG, R5F101LHABG,

R5F101LJABG

R5F100LCGBG, R5F100LDGBG, R5F100LEGBG, R5F100LFGBG, R5F100LGGBG, R5F100LHGBG,

R5F100LJGBG

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-VFBGA64-4x4-0.40	PVBG0064LA-A	P64F1-40-AA2-2	0.03



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