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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

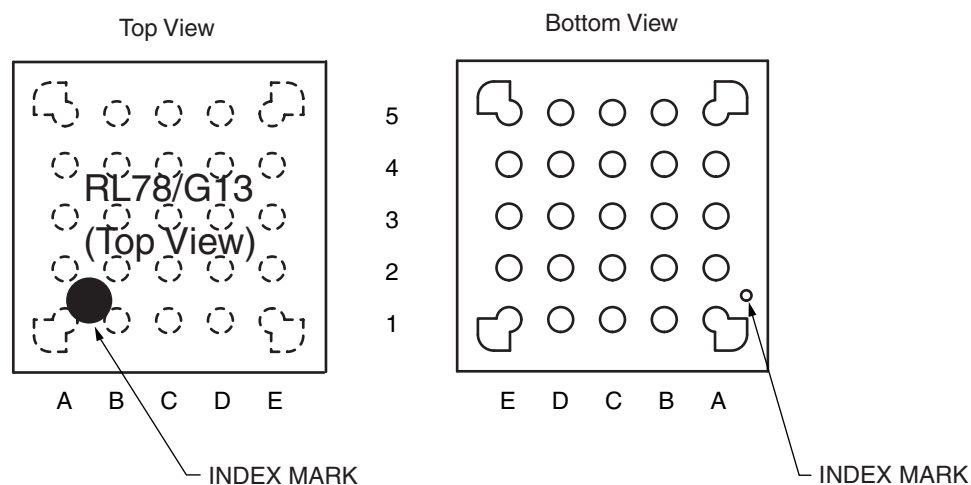
#### Details

Product Status	Discontinued at Digi-Key
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I <sup>2</sup> C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	34
Program Memory Size	192KB (192K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 5.5V
Data Converters	A/D 10x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LFQFP (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f100ghgfb-v0">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f100ghgfb-v0</a>

## 1.3.3 25-pin products

- 25-pin plastic WFLGA (3 × 3 mm, 0.50 mm pitch)

&lt;R&gt;



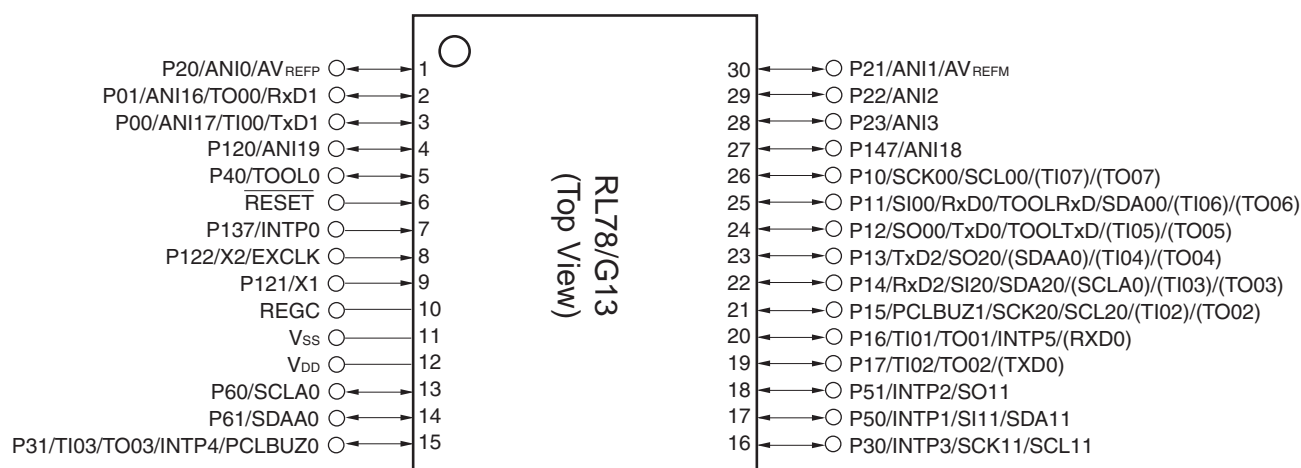
	A	B	C	D	E	
5	P40/TOOL0	RESET	P01/ANI16/ TO00/RxD1	P22/ANI2	P147/ANI18	5
4	P122/X2/ EXCLK	P137/INTP0	P00/ANI17/ TI00/TxD1	P21/ANI1/ AV <sub>REFM</sub>	P10/SCK00/ SCL00	4
3	P121/X1	V <sub>DD</sub>	P20/ANI0/ AV <sub>REFP</sub>	P12/SO00/ TxD0/ TOOLTxD	P11/SI00/ RxD0/ TOOLRxD/ SDA00	3
2	REGC	V <sub>SS</sub>	P30/INTP3/ SCK11/SCL11	P17/TI02/ TO02/SO11	P50/INTP1/ SI11/SDA11	2
1	P60/SCLA0	P61/SDAA0	P31/TI03/ TO03/INTP4/ PCLBUZ0	P16/TI01/ TO01/INTP5	P130	1
	A	B	C	D	E	

**Caution** Connect the REGC pin to V<sub>SS</sub> via a capacitor (0.47 to 1  $\mu$ F).

**Remark** For pin identification, see 1.4 Pin Identification.

## 1.3.4 30-pin products

- 30-pin plastic LSSOP (7.62 mm (300), 0.65 mm pitch)



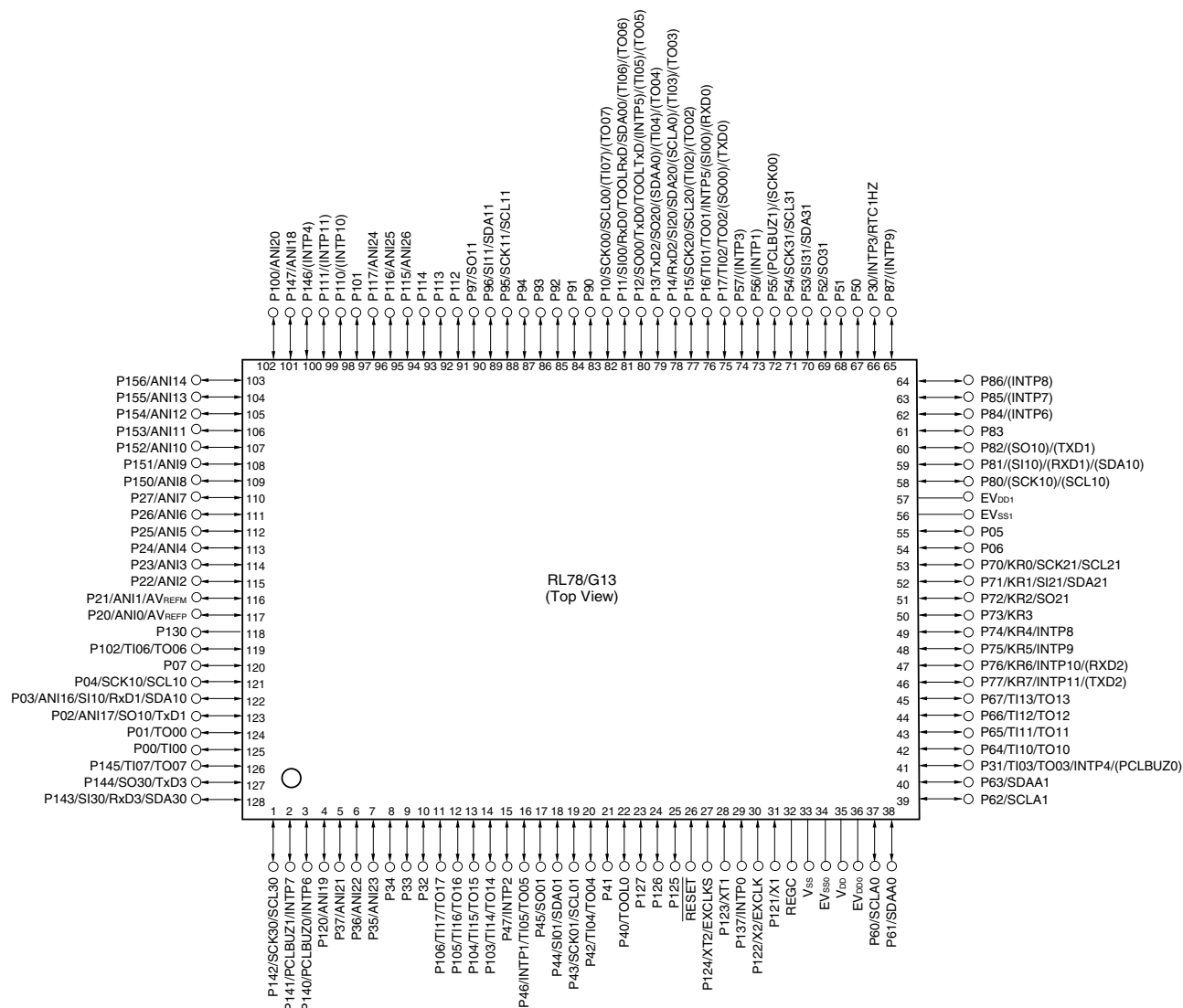
**Caution** Connect the REGC pin to V<sub>SS</sub> via a capacitor (0.47 to 1  $\mu$ F).

**Remarks 1.** For pin identification, see 1.4 Pin Identification.

- Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

## 1.3.14 128-pin products

- 128-pin plastic LQFP (14 × 20 mm, 0.5 mm pitch)



**Cautions** 1. Make EV<sub>SS0</sub>, EV<sub>SS1</sub> pins the same potential as V<sub>SS</sub> pin.

2. Make V<sub>DD</sub> pin the potential that is higher than EV<sub>DD0</sub>, EV<sub>DD1</sub> pins (EV<sub>DD0</sub> = EV<sub>DD1</sub>).

3. Connect the REGC pin to V<sub>SS</sub> via a capacitor (0.47 to 1 μF).

**Remarks** 1. For pin identification, see 1.4 Pin Identification.

2. When using the microcontroller for an application where the noise generated inside the microcontroller must be reduced, it is recommended to supply separate powers to the V<sub>DD</sub>, EV<sub>DD0</sub> and EV<sub>DD1</sub> pins and connect the V<sub>SS</sub>, EV<sub>SS0</sub> and EV<sub>SS1</sub> pins to separate ground lines.

3. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

## 1.6 Outline of Functions

[20-pin, 24-pin, 25-pin, 30-pin, 32-pin, 36-pin products]

**Caution** This outline describes the functions at the time when Peripheral I/O redirection register (PIOR) is set to 00H.

(1/2)

Item		20-pin		24-pin		25-pin		30-pin		32-pin		36-pin	
		R5F1006x	R5F1016x	R5F1007x	R5F1017x	R5F1008x	R5F1018x	R5F100Ax	R5F101Ax	R5F100Bx	R5F101Bx	R5F100Cx	R5F101Cx
Code flash memory (KB)		16 to 64		16 to 64		16 to 64		16 to 128		16 to 128		16 to 128	
Data flash memory (KB)		4	–	4	–	4	–	4 to 8	–	4 to 8	–	4 to 8	–
RAM (KB)		2 to 4 <sup>Note1</sup>		2 to 4 <sup>Note1</sup>		2 to 4 <sup>Note1</sup>		2 to 12 <sup>Note1</sup>		2 to 12 <sup>Note1</sup>		2 to 12 <sup>Note1</sup>	
Address space		1 MB											
Main system clock	High-speed system clock	X1 (crystal/ceramic) oscillation, external main system clock input (EXCLK) HS (High-speed main) mode: 1 to 20 MHz (V <sub>DD</sub> = 2.7 to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz (V <sub>DD</sub> = 2.4 to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz (V <sub>DD</sub> = 1.8 to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz (V <sub>DD</sub> = 1.6 to 5.5 V)											
	High-speed on-chip oscillator	HS (High-speed main) mode: 1 to 32 MHz (V <sub>DD</sub> = 2.7 to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz (V <sub>DD</sub> = 2.4 to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz (V <sub>DD</sub> = 1.8 to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz (V <sub>DD</sub> = 1.6 to 5.5 V)											
Subsystem clock		–											
Low-speed on-chip oscillator		15 kHz (TYP.)											
General-purpose registers		(8-bit register × 8) × 4 banks											
Minimum instruction execution time		0.03125 μs (High-speed on-chip oscillator: f <sub>IH</sub> = 32 MHz operation)											
		0.05 μs (High-speed system clock: f <sub>MX</sub> = 20 MHz operation)											
Instruction set		<ul style="list-style-type: none"><li>• Data transfer (8/16 bits)</li><li>• Adder and subtractor/logical operation (8/16 bits)</li><li>• Multiplication (8 bits × 8 bits)</li><li>• Rotate, barrel shift, and bit manipulation (Set, reset, test, and Boolean operation), etc.</li></ul>											
I/O port	Total	16	20	21	26	28	32						
	CMOS I/O	13 (N-ch O.D. I/O [V <sub>DD</sub> withstand voltage]: 5)	15 (N-ch O.D. I/O [V <sub>DD</sub> withstand voltage]: 6)	15 (N-ch O.D. I/O [V <sub>DD</sub> withstand voltage]: 6)	21 (N-ch O.D. I/O [V <sub>DD</sub> withstand voltage]: 9)	22 (N-ch O.D. I/O [V <sub>DD</sub> withstand voltage]: 9)	26 (N-ch O.D. I/O [V <sub>DD</sub> withstand voltage]: 10)						
	CMOS input	3	3	3	3	3	3						
	CMOS output	–	–	1	–	–	–						
	N-ch O.D. I/O (withstand voltage: 6 V)	–	2	2	2	3	3						
Timer	16-bit timer	8 channels											
	Watchdog timer	1 channel											
	Real-time clock (RTC)	1 channel <sup>Note 2</sup>											
	12-bit interval timer (IT)	1 channel											
	Timer output	3 channels (PWM outputs: 2 <sup>Note 3</sup> )	4 channels (PWM outputs: 3 <sup>Note 3</sup> )				4 channels (PWM outputs: 3 <sup>Note 3</sup> ), 8 channels (PWM outputs: 7 <sup>Note 3</sup> ) <sup>Note 4</sup>						
	RTC output	–											

- Notes**
- The flash library uses RAM in self-programming and rewriting of the data flash memory. The target products and start address of the RAM areas used by the flash library are shown below.  
R5F100xD, R5F101xD (x = 6 to 8, A to C): Start address FF300H  
R5F100xE, R5F101xE (x = 6 to 8, A to C): Start address FEF00H  
For the RAM areas used by the flash library, see **Self RAM list of Flash Self-Programming Library for RL78 Family (R20UT2944)**.
  - Only the constant-period interrupt function when the low-speed on-chip oscillator clock (f<sub>IL</sub>) is selected

3. The number of PWM outputs varies depending on the setting of channels in use (the number of masters and slaves) (see **6.9.3 Operation as multiple PWM output function** in the RL78/G13 User's Manual).
4. When setting to PIOR = 1

(2/2)

Item	20-pin		24-pin		25-pin		30-pin		32-pin		36-pin	
	R5F1006x	R5F1016x	R5F1007x	R5F1017x	R5F1008x	R5F1018x	R5F100Ax	R5F101Ax	R5F100Bx	R5F101Bx	R5F100Cx	R5F101Cx
Clock output/buzzer output	—		1		1		2		2		2	
	• 2.44 kHz, 4.88 kHz, 9.76 kHz, 1.25 MHz, 2.5 MHz, 5 MHz, 10 MHz (Main system clock: f <sub>MAIN</sub> = 20 MHz operation)											
8/10-bit resolution A/D converter	6 channels		6 channels		6 channels		8 channels		8 channels		8 channels	
Serial interface	[20-pin, 24-pin, 25-pin products] • CSI: 1 channel/simplified I <sup>2</sup> C: 1 channel/UART: 1 channel • CSI: 1 channel/simplified I <sup>2</sup> C: 1 channel/UART: 1 channel [30-pin, 32-pin products] • CSI: 1 channel/simplified I <sup>2</sup> C: 1 channel/UART: 1 channel • CSI: 1 channel/simplified I <sup>2</sup> C: 1 channel/UART: 1 channel • CSI: 1 channel/simplified I <sup>2</sup> C: 1 channel/UART (UART supporting LIN-bus): 1 channel [36-pin products] • CSI: 1 channel/simplified I <sup>2</sup> C: 1 channel/UART: 1 channel • CSI: 1 channel/simplified I <sup>2</sup> C: 1 channel/UART: 1 channel • CSI: 2 channels/simplified I <sup>2</sup> C: 2 channels/UART (UART supporting LIN-bus): 1 channel											
	I <sup>2</sup> C bus	—	1 channel		1 channel		1 channel		1 channel		1 channel	
Multiplier and divider/multiply-accumulator	• 16 bits × 16 bits = 32 bits (Unsigned or signed) • 32 bits ÷ 32 bits = 32 bits (Unsigned) • 16 bits × 16 bits + 32 bits = 32 bits (Unsigned or signed)											
DMA controller	2 channels											
Vectored interrupt sources	Internal	23	24		24		27		27		27	
	External	3	5		5		6		6		6	
Key interrupt	—											
Reset	• Reset by $\overline{\text{RESET}}$ pin • Internal reset by watchdog timer • Internal reset by power-on-reset • Internal reset by voltage detector • Internal reset by illegal instruction execution <sup>Note</sup> • Internal reset by RAM parity error • Internal reset by illegal-memory access											
Power-on-reset circuit	• Power-on-reset: 1.51 V (TYP.) • Power-down-reset: 1.50 V (TYP.)											
Voltage detector	• Rising edge : 1.67 V to 4.06 V (14 stages) • Falling edge : 1.63 V to 3.98 V (14 stages)											
On-chip debug function	Provided											
Power supply voltage	V <sub>DD</sub> = 1.6 to 5.5 V (T <sub>A</sub> = -40 to +85°C) V <sub>DD</sub> = 2.4 to 5.5 V (T <sub>A</sub> = -40 to +105°C)											
Operating ambient temperature	T <sub>A</sub> = 40 to +85°C (A: Consumer applications, D: Industrial applications ) T <sub>A</sub> = 40 to +105°C (G: Industrial applications)											

**Note** The illegal instruction is generated when instruction code FFH is executed.

Reset by the illegal instruction execution not issued by emulation with the in-circuit emulator or on-chip debug emulator.

(T<sub>A</sub> = -40 to +85°C, 1.6 V ≤ E<sub>VDD0</sub> = E<sub>VDD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = E<sub>VSS0</sub> = E<sub>VSS1</sub> = 0 V) (4/5)

Items	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Output voltage, high	V <sub>OH1</sub>	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	4.0 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OH1</sub> = -10.0 mA	E <sub>VDD0</sub> - 1.5		V
			4.0 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OH1</sub> = -3.0 mA	E <sub>VDD0</sub> - 0.7		V
			2.7 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OH1</sub> = -2.0 mA	E <sub>VDD0</sub> - 0.6		V
			1.8 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OH1</sub> = -1.5 mA	E <sub>VDD0</sub> - 0.5		V
			1.6 V ≤ E <sub>VDD0</sub> < 5.5 V, I <sub>OH1</sub> = -1.0 mA	E <sub>VDD0</sub> - 0.5		V
	V <sub>OH2</sub>	P20 to P27, P150 to P156	1.6 V ≤ V <sub>DD</sub> ≤ 5.5 V, I <sub>OH2</sub> = -100 μA	V <sub>DD</sub> - 0.5		V
Output voltage, low	V <sub>OL1</sub>	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	4.0 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OL1</sub> = 20 mA		1.3	V
			4.0 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OL1</sub> = 8.5 mA		0.7	V
			2.7 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OL1</sub> = 3.0 mA		0.6	V
			2.7 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OL1</sub> = 1.5 mA		0.4	V
			1.8 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OL1</sub> = 0.6 mA		0.4	V
			1.6 V ≤ E <sub>VDD0</sub> < 5.5 V, I <sub>OL1</sub> = 0.3 mA		0.4	V
	V <sub>OL2</sub>	P20 to P27, P150 to P156	1.6 V ≤ V <sub>DD</sub> ≤ 5.5 V, I <sub>OL2</sub> = 400 μA		0.4	V
	V <sub>OL3</sub>	P60 to P63	4.0 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OL3</sub> = 15.0 mA		2.0	V
			4.0 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OL3</sub> = 5.0 mA		0.4	V
			2.7 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OL3</sub> = 3.0 mA		0.4	V
			1.8 V ≤ E <sub>VDD0</sub> ≤ 5.5 V, I <sub>OL3</sub> = 2.0 mA		0.4	V
			1.6 V ≤ E <sub>VDD0</sub> < 5.5 V, I <sub>OL3</sub> = 1.0 mA		0.4	V

**Caution** P00, P02 to P04, P10 to P15, P17, P43 to P45, P50, P52 to P55, P71, P74, P80 to P82, P96, and P142 to P144 do not output high level in N-ch open-drain mode.

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

## (2) During communication at same potential (CSI mode) (master mode, SCKp... internal clock output, corresponding CSI00 only)

(T<sub>A</sub> = -40 to +85°C, 2.7 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V)

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCKp cycle time	t <sub>KCY1</sub>	t <sub>KCY1</sub> ≥ 2/f <sub>CLK</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	62.5		250		500	ns
			2.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	83.3		250		500	ns
SCKp high-/low-level width	t <sub>KH1</sub> , t <sub>KL1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	t <sub>KCY1</sub> /2 – 7		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		ns
		2.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	t <sub>KCY1</sub> /2 – 10		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		ns
Slp setup time (to SCKp↑) <small>Note 1</small>	t <sub>SIK1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	23		110		110		ns
		2.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	33		110		110		ns
Slp hold time (from SCKp↑) <small>Note 2</small>	t <sub>KSI1</sub>	2.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	10		10		10		ns
Delay time from SCKp↓ to SOp output <small>Note 3</small>	t <sub>KSO1</sub>	C = 20 pF <small>Note 4</small>		10		10		10	ns

- Notes**
1. When DAP<sub>mn</sub> = 0 and CKP<sub>mn</sub> = 0, or DAP<sub>mn</sub> = 1 and CKP<sub>mn</sub> = 1. The Slp setup time becomes “to SCKp↓” when DAP<sub>mn</sub> = 0 and CKP<sub>mn</sub> = 1, or DAP<sub>mn</sub> = 1 and CKP<sub>mn</sub> = 0.
  2. When DAP<sub>mn</sub> = 0 and CKP<sub>mn</sub> = 0, or DAP<sub>mn</sub> = 1 and CKP<sub>mn</sub> = 1. The Slp hold time becomes “from SCKp↓” when DAP<sub>mn</sub> = 0 and CKP<sub>mn</sub> = 1, or DAP<sub>mn</sub> = 1 and CKP<sub>mn</sub> = 0.
  3. When DAP<sub>mn</sub> = 0 and CKP<sub>mn</sub> = 0, or DAP<sub>mn</sub> = 1 and CKP<sub>mn</sub> = 1. The delay time to SOp output becomes “from SCKp↑” when DAP<sub>mn</sub> = 0 and CKP<sub>mn</sub> = 1, or DAP<sub>mn</sub> = 1 and CKP<sub>mn</sub> = 0.
  4. C is the load capacitance of the SCKp and SOp output lines.

**Caution** Select the normal input buffer for the Slp pin and the normal output mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg).

- Remarks**
1. This value is valid only when CSI00's peripheral I/O redirect function is not used.
  2. p: CSI number (p = 00), m: Unit number (m = 0), n: Channel number (n = 0),  
g: PIM and POM numbers (g = 1)
  3. f<sub>MCK</sub>: Serial array unit operation clock frequency  
(Operation clock to be set by the CKS<sub>mn</sub> bit of serial mode register mn (SMR<sub>mn</sub>). m: Unit number,  
n: Channel number (mn = 00))



**(6) Communication at different potential (1.8 V, 2.5 V, 3 V) (UART mode) (1/2)****(T<sub>A</sub> = -40 to +85°C, 1.8 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V)**

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit	
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Transfer rate		Reception	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V			f <sub>MCK</sub> /6 Note 1		f <sub>MCK</sub> /6 Note 1		f <sub>MCK</sub> /6 Note 1	bps
						5.3		1.3		0.6	Mbps
			Theoretical value of the maximum transfer rate f <sub>MCK</sub> = f <sub>CLK</sub> <sup>Note 4</sup>								
						5.3		1.3		0.6	Mbps
			2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V			f <sub>MCK</sub> /6 Note 1		f <sub>MCK</sub> /6 Note 1		f <sub>MCK</sub> /6 Note 1	bps
						5.3		1.3		0.6	Mbps
1.8 V ≤ EV <sub>DD0</sub> < 3.3 V, 1.6 V ≤ V <sub>b</sub> ≤ 2.0 V			f <sub>MCK</sub> /6 Notes 1 to 3		f <sub>MCK</sub> /6 Notes 1, 2		f <sub>MCK</sub> /6 Notes 1, 2	bps			
			5.3		1.3		0.6	Mbps			
Theoretical value of the maximum transfer rate f <sub>MCK</sub> = f <sub>CLK</sub> <sup>Note 4</sup>											

**Notes 1.** Transfer rate in the SNOOZE mode is 4800 bps only.**2.** Use it with EV<sub>DD0</sub> ≥ V<sub>b</sub>.**3.** The following conditions are required for low voltage interface when EV<sub>DD0</sub> < V<sub>DD</sub>.2.4 V ≤ EV<sub>DD0</sub> < 2.7 V : MAX. 2.6 Mbps1.8 V ≤ EV<sub>DD0</sub> < 2.4 V : MAX. 1.3 Mbps**4.** The maximum operating frequencies of the CPU/peripheral hardware clock (f<sub>CLK</sub>) are:HS (high-speed main) mode: 32 MHz (2.7 V ≤ V<sub>DD</sub> ≤ 5.5 V)16 MHz (2.4 V ≤ V<sub>DD</sub> ≤ 5.5 V)LS (low-speed main) mode: 8 MHz (1.8 V ≤ V<sub>DD</sub> ≤ 5.5 V)LV (low-voltage main) mode: 4 MHz (1.6 V ≤ V<sub>DD</sub> ≤ 5.5 V)

**Caution** Select the TTL input buffer for the RxDq pin and the N-ch open drain output (V<sub>DD</sub> tolerance (When 20- to 52-pin products)/EV<sub>DD</sub> tolerance (When 64- to 128-pin products)) mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg). For V<sub>IH</sub> and V<sub>IL</sub>, see the DC characteristics with TTL input buffer selected.

**Remarks 1.** V<sub>b</sub>[V]: Communication line voltage**2.** q: UART number (q = 0 to 3), g: PIM and POM number (g = 0, 1, 8, 14)**3.** f<sub>MCK</sub>: Serial array unit operation clock frequency

(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13))

**4.** UART2 cannot communicate at different potential when bit 1 (PIOR1) of peripheral I/O redirection register (PIOR) is 1.

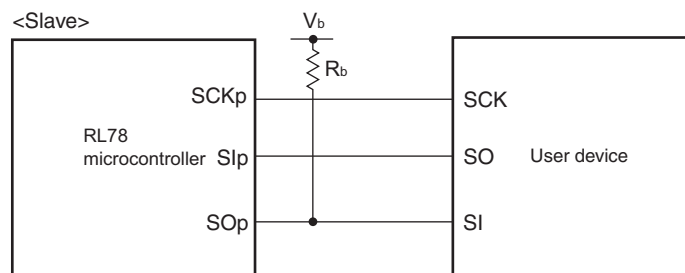
**(7) Communication at different potential (2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock output, corresponding CSI00 only) (2/2)****(T<sub>A</sub> = -40 to +85°C, 2.7 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V)**

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
Slp setup time (to SCKp↓) <sup>Note 2</sup>	t <sub>SIK1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	23		110		110		ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	33		110		110		ns
Slp hold time (from SCKp↓) <sup>Note 2</sup>	t <sub>KSI1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	10		10		10		ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	10		10		10		ns
Delay time from SCKp↑ to SOp output <sup>Note 2</sup>	t <sub>KSO1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ		10		10		10	ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ		10		10		10	ns

- Notes**
1. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.
  2. When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.

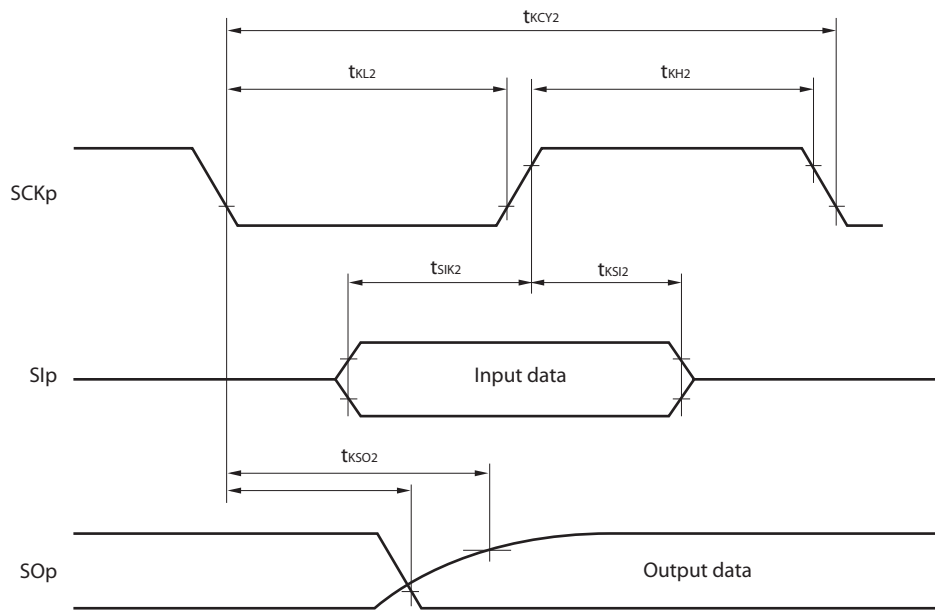
**Caution** Select the TTL input buffer for the Slp pin and the N-ch open drain output (V<sub>DD</sub> tolerance (When 20- to 52-pin products)/EV<sub>DD</sub> tolerance (When 64- to 128-pin products)) mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg). For V<sub>IH</sub> and V<sub>IL</sub>, see the DC characteristics with TTL input buffer selected.

- Remarks**
1. R<sub>b</sub>[Ω]: Communication line (SCKp, SOp) pull-up resistance, C<sub>b</sub>[F]: Communication line (SCKp, SOp) load capacitance, V<sub>b</sub>[V]: Communication line voltage
  2. p: CSI number (p = 00), m: Unit number (m = 0), n: Channel number (n = 0),  
g: PIM and POM number (g = 1)
  3. f<sub>MCK</sub>: Serial array unit operation clock frequency  
(Operation clock to be set by the CKS<sub>mn</sub> bit of serial mode register mn (SMR<sub>mn</sub>). m: Unit number, n: Channel number (mn = 00))
  4. This value is valid only when CSI00's peripheral I/O redirect function is not used.

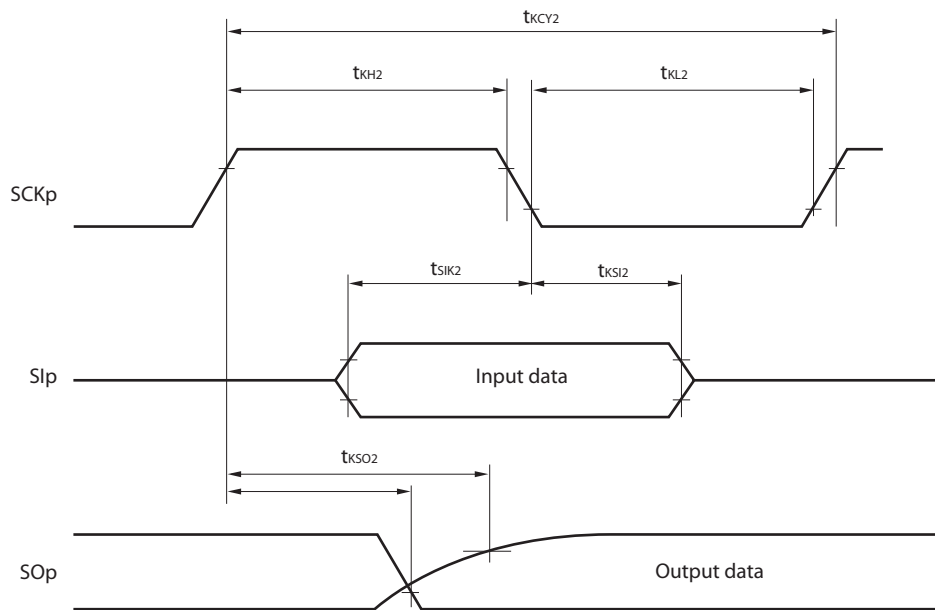
**CSI mode connection diagram (during communication at different potential)**

- Remarks**
1.  $R_b[\Omega]$ : Communication line (SO<sub>p</sub>) pull-up resistance,  $C_b[F]$ : Communication line (SO<sub>p</sub>) load capacitance,  $V_b[V]$ : Communication line voltage
  2. p: CSI number (p = 00, 01, 10, 20, 30, 31), m: Unit number, n: Channel number (mn = 00, 01, 02, 10, 12, 13), g: PIM and POM number (g = 0, 1, 4, 5, 8, 14)
  3.  $f_{MCK}$ : Serial array unit operation clock frequency  
(Operation clock to be set by the CKS<sub>mn</sub> bit of serial mode register mn (SMR<sub>mn</sub>).  
m: Unit number, n: Channel number (mn = 00, 01, 02, 10, 12, 13))
  4. CSI01 of 48-, 52-, 64-pin products, and CSI11 and CSI21 cannot communicate at different potential.  
Use other CSI for communication at different potential.

**CSI mode serial transfer timing (slave mode) (during communication at different potential)**  
**(When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.)**



**CSI mode serial transfer timing (slave mode) (during communication at different potential)**  
**(When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.)**



- Remarks 1.** p: CSI number (p = 00, 01, 10, 20, 30, 31), m: Unit number,  
 n: Channel number (mn = 00, 01, 02, 10, 12, 13), g: PIM and POM number (g = 0, 1, 4, 5, 8, 14)
- 2.** CSI01 of 48-, 52-, 64-pin products, and CSI11 and CSI21 cannot communicate at different potential.  
 Use other CSI for communication at different potential.

**( $T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4\text{ V} \leq \text{EV}_{\text{DD0}} = \text{EV}_{\text{DD1}} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}$ ,  $\text{V}_{\text{SS}} = \text{EV}_{\text{SS0}} = \text{EV}_{\text{SS1}} = 0\text{ V}$ ) (4/5)**

Items	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Output voltage, high	$\text{V}_{\text{OH1}}$	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	$4.0\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OH1}} = -3.0\text{ mA}$	$\text{EV}_{\text{DD0}} - 0.7$		V
			$2.7\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OH1}} = -2.0\text{ mA}$	$\text{EV}_{\text{DD0}} - 0.6$		V
			$2.4\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OH1}} = -1.5\text{ mA}$	$\text{EV}_{\text{DD0}} - 0.5$		V
	$\text{V}_{\text{OH2}}$	P20 to P27, P150 to P156	$2.4\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OH2}} = -100\text{ }\mu\text{A}$	$\text{V}_{\text{DD}} - 0.5$		V
Output voltage, low	$\text{V}_{\text{OL1}}$	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	$4.0\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OL1}} = 8.5\text{ mA}$		0.7	V
			$4.0\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OL1}} = 3.0\text{ mA}$		0.6	V
			$2.7\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OL1}} = 1.5\text{ mA}$		0.4	V
			$2.4\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OL1}} = 0.6\text{ mA}$		0.4	V
	$\text{V}_{\text{OL2}}$	P20 to P27, P150 to P156	$2.4\text{ V} \leq \text{V}_{\text{DD}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OL2}} = 400\text{ }\mu\text{A}$		0.4	V
	$\text{V}_{\text{OL3}}$	P60 to P63	$4.0\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OL3}} = 15.0\text{ mA}$		2.0	V
			$4.0\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OL3}} = 5.0\text{ mA}$		0.4	V
			$2.7\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OL3}} = 3.0\text{ mA}$		0.4	V
			$2.4\text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5\text{ V}$ , $\text{I}_{\text{OL3}} = 2.0\text{ mA}$		0.4	V

**Caution** P00, P02 to P04, P10 to P15, P17, P43 to P45, P50, P52 to P55, P71, P74, P80 to P82, P96, and P142 to P144 do not output high level in N-ch open-drain mode.

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

### 3.3.2 Supply current characteristics

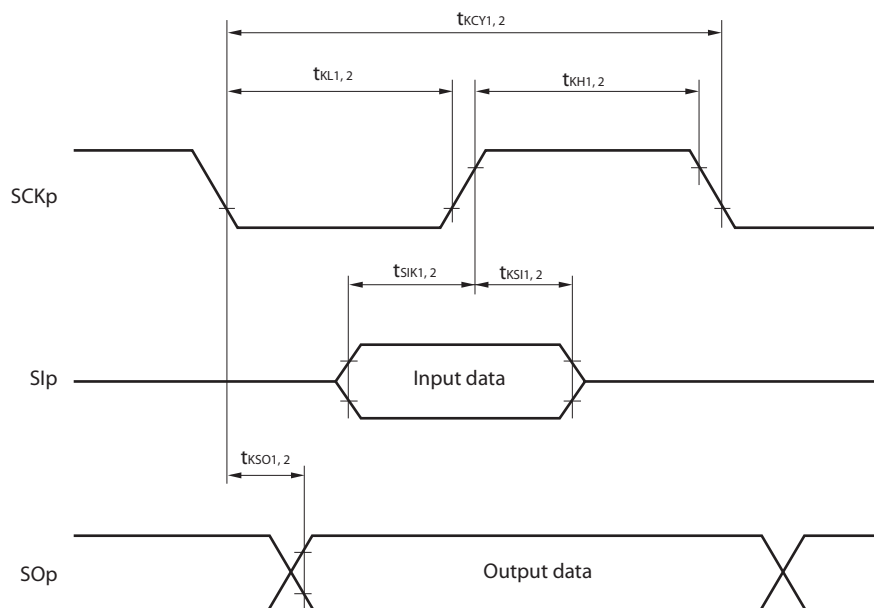
(1) Flash ROM: 16 to 64 KB of 20- to 64-pin products

( $T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4\text{ V} \leq V_{DD0} \leq V_{DD} \leq 5.5\text{ V}$ ,  $V_{SS} = V_{SS0} = 0\text{ V}$ ) (1/2)

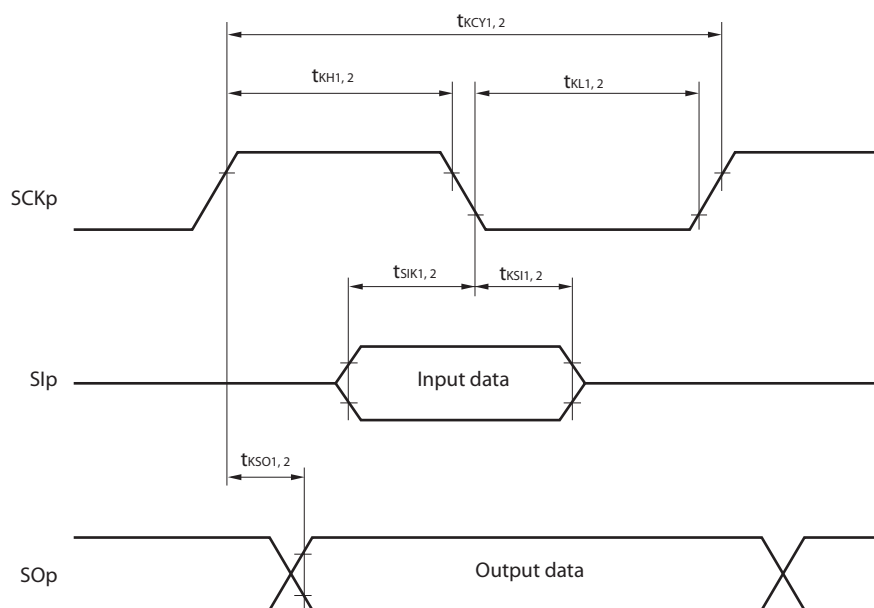
Parameter	Symbol	Conditions					MIN.	TYP.	MAX.	Unit
Supply current Note 1	I <sub>DD1</sub>	Operating mode	HS (high-speed main) mode Note 5	$f_{IH} = 32\text{ MHz}$ Note 3	Basic operation	$V_{DD} = 5.0\text{ V}$		2.1		mA
						$V_{DD} = 3.0\text{ V}$		2.1		mA
					Normal operation	$V_{DD} = 5.0\text{ V}$		4.6	7.5	mA
						$V_{DD} = 3.0\text{ V}$		4.6	7.5	mA
				$f_{IH} = 24\text{ MHz}$ Note 3	Normal operation	$V_{DD} = 5.0\text{ V}$		3.7	5.8	mA
						$V_{DD} = 3.0\text{ V}$		3.7	5.8	mA
				$f_{IH} = 16\text{ MHz}$ Note 3	Normal operation	$V_{DD} = 5.0\text{ V}$		2.7	4.2	mA
						$V_{DD} = 3.0\text{ V}$		2.7	4.2	mA
			HS (high-speed main) mode Note 5	$f_{MX} = 20\text{ MHz}$ Note 2, $V_{DD} = 5.0\text{ V}$	Normal operation	Square wave input		3.0	4.9	mA
						Resonator connection		3.2	5.0	mA
				$f_{MX} = 20\text{ MHz}$ Note 2, $V_{DD} = 3.0\text{ V}$	Normal operation	Square wave input		3.0	4.9	mA
						Resonator connection		3.2	5.0	mA
				$f_{MX} = 10\text{ MHz}$ Note 2, $V_{DD} = 5.0\text{ V}$	Normal operation	Square wave input		1.9	2.9	mA
						Resonator connection		1.9	2.9	mA
				$f_{MX} = 10\text{ MHz}$ Note 2, $V_{DD} = 3.0\text{ V}$	Normal operation	Square wave input		1.9	2.9	mA
						Resonator connection		1.9	2.9	mA
		Subsystem clock operation		$f_{SUB} = 32.768\text{ kHz}$ Note 4 $T_A = -40^\circ\text{C}$	Normal operation	Square wave input		4.1	4.9	$\mu\text{A}$
						Resonator connection		4.2	5.0	$\mu\text{A}$
				$f_{SUB} = 32.768\text{ kHz}$ Note 4 $T_A = +25^\circ\text{C}$	Normal operation	Square wave input		4.1	4.9	$\mu\text{A}$
						Resonator connection		4.2	5.0	$\mu\text{A}$
				$f_{SUB} = 32.768\text{ kHz}$ Note 4 $T_A = +50^\circ\text{C}$	Normal operation	Square wave input		4.2	5.5	$\mu\text{A}$
						Resonator connection		4.3	5.6	$\mu\text{A}$
				$f_{SUB} = 32.768\text{ kHz}$ Note 4 $T_A = +70^\circ\text{C}$	Normal operation	Square wave input		4.3	6.3	$\mu\text{A}$
						Resonator connection		4.4	6.4	$\mu\text{A}$
				$f_{SUB} = 32.768\text{ kHz}$ Note 4 $T_A = +85^\circ\text{C}$	Normal operation	Square wave input		4.6	7.7	$\mu\text{A}$
						Resonator connection		4.7	7.8	$\mu\text{A}$
				$f_{SUB} = 32.768\text{ kHz}$ Note 4 $T_A = +105^\circ\text{C}$	Normal operation	Square wave input		6.9	19.7	$\mu\text{A}$
						Resonator connection		7.0	19.8	$\mu\text{A}$

(Notes and Remarks are listed on the next page.)

**CSI mode serial transfer timing (during communication at same potential)**  
**(When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.)**



**CSI mode serial transfer timing (during communication at same potential)**  
**(When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.)**



- Remarks**
1. p: CSI number (p = 00, 01, 10, 11, 20, 21, 30, 31)
  2. m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13)

**(5) Communication at different potential (1.8 V, 2.5 V, 3 V) (UART mode) (1/2)****( $T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4\text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5\text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0\text{ V}$ )**

Parameter	Symbol	Conditions		HS (high-speed main) Mode		Unit	
				MIN.	MAX.		
Transfer rate		Reception	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V			f <sub>MCK</sub> /12 <sup>Note 1</sup>	bps
			Theoretical value of the maximum transfer rate f <sub>CLK</sub> = 32 MHz, f <sub>MCK</sub> = f <sub>CLK</sub>			2.6	Mbps
			2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V			f <sub>MCK</sub> /12 <sup>Note 1</sup>	bps
			Theoretical value of the maximum transfer rate f <sub>CLK</sub> = 32 MHz, f <sub>MCK</sub> = f <sub>CLK</sub>			2.6	Mbps
			2.4 V ≤ EV <sub>DD0</sub> < 3.3 V, 1.6 V ≤ V <sub>b</sub> ≤ 2.0 V			f <sub>MCK</sub> /12 <sup>Notes 1,2</sup>	bps
			Theoretical value of the maximum transfer rate f <sub>CLK</sub> = 32 MHz, f <sub>MCK</sub> = f <sub>CLK</sub>			2.6	Mbps

**Notes 1.** Transfer rate in the SNOOZE mode is 4800 bps only.

- 2.** The following conditions are required for low voltage interface when  $EV_{DD0} < V_{DD}$ .  
 $2.4\text{ V} \leq EV_{DD0} < 2.7\text{ V}$  : MAX. 1.3 Mbps

**Caution** Select the TTL input buffer for the RxDq pin and the N-ch open drain output ( $V_{DD}$  tolerance (for the 20- to 52-pin products)/ $EV_{DD}$  tolerance (for the 64- to 100-pin products)) mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg). For  $V_{IH}$  and  $V_{IL}$ , see the DC characteristics with TTL input buffer selected.

**Remarks 1.**  $V_b[V]$ : Communication line voltage**2.** q: UART number (q = 0 to 3), g: PIM and POM number (g = 0, 1, 8, 14)**3.**  $f_{MCK}$ : Serial array unit operation clock frequency

(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13))

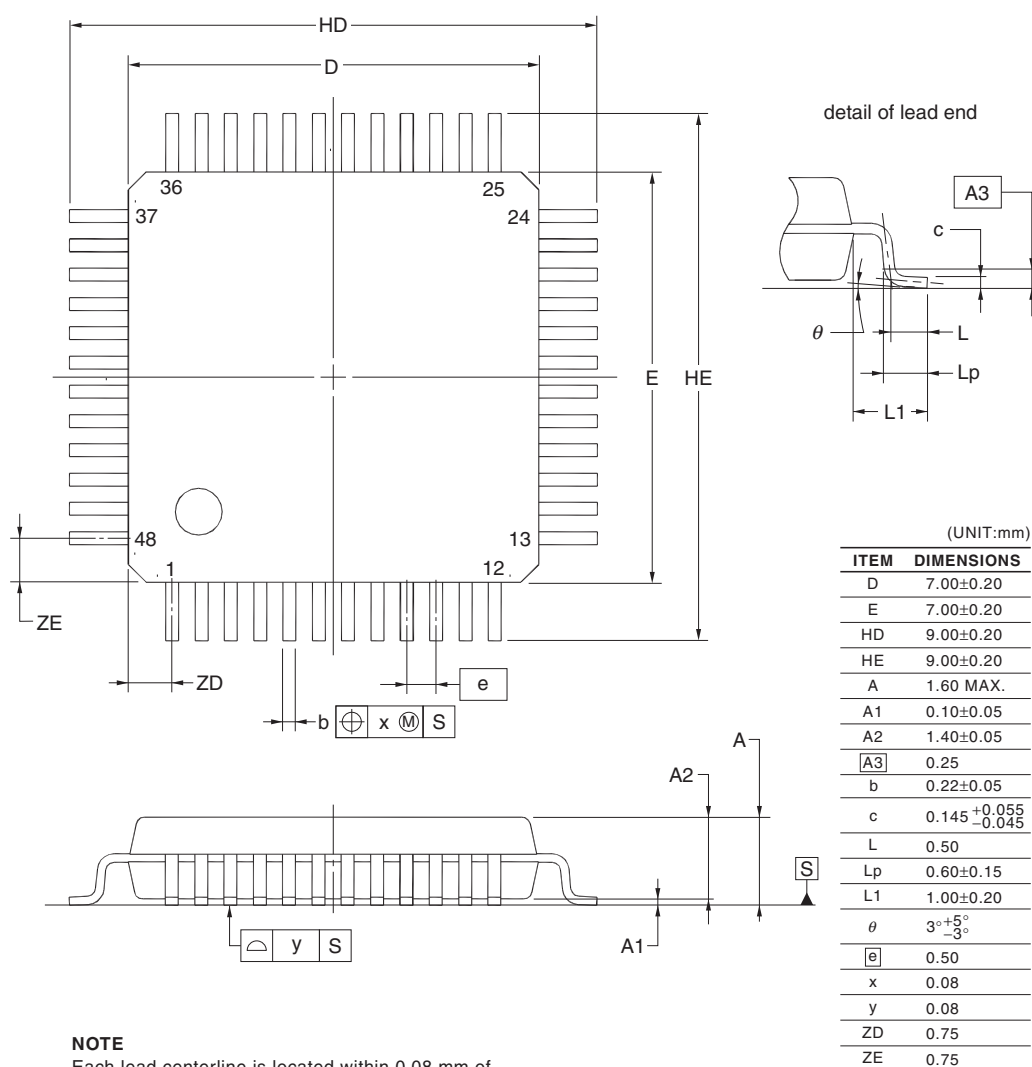
**4.** UART2 cannot communicate at different potential when bit 1 (PIOR1) of peripheral I/O redirection register (PIOR) is 1.



## 4.9 48-pin Products

R5F100GAAFB, R5F100GCAFB, R5F100GDAFB, R5F100GEAFB, R5F100GFAFB, R5F100GGAFB,  
 R5F100GHAFB, R5F100GJAFB, R5F100GKAFB, R5F100GLAFB  
 R5F101GAAFB, R5F101GCAFB, R5F101GDAFB, R5F101GEAFB, R5F101GFAFB, R5F101GGAFB,  
 R5F101GHAFB, R5F101GJAFB, R5F101GKAFB, R5F101GLAFB  
 R5F100GADFB, R5F100GCDFB, R5F100GDDFB, R5F100GEDFB, R5F100GFDFB, R5F100GGDFB,  
 R5F100GHDFB, R5F100GJDFB, R5F100GKDFB, R5F100GLDFB  
 R5F101GADFB, R5F101GCDFB, R5F101GDDFB, R5F101GEDFB, R5F101GFDFB, R5F101GGDFB,  
 R5F101GHDFB, R5F101GJDFB, R5F101GKDFB, R5F101GLDFB  
 R5F100GAGFB, R5F100GCGFB, R5F100GDGFB, R5F100GEGFB, R5F100GFGFB, R5F100GGGFB,  
 R5F100GHGFB, R5F100GJGFB

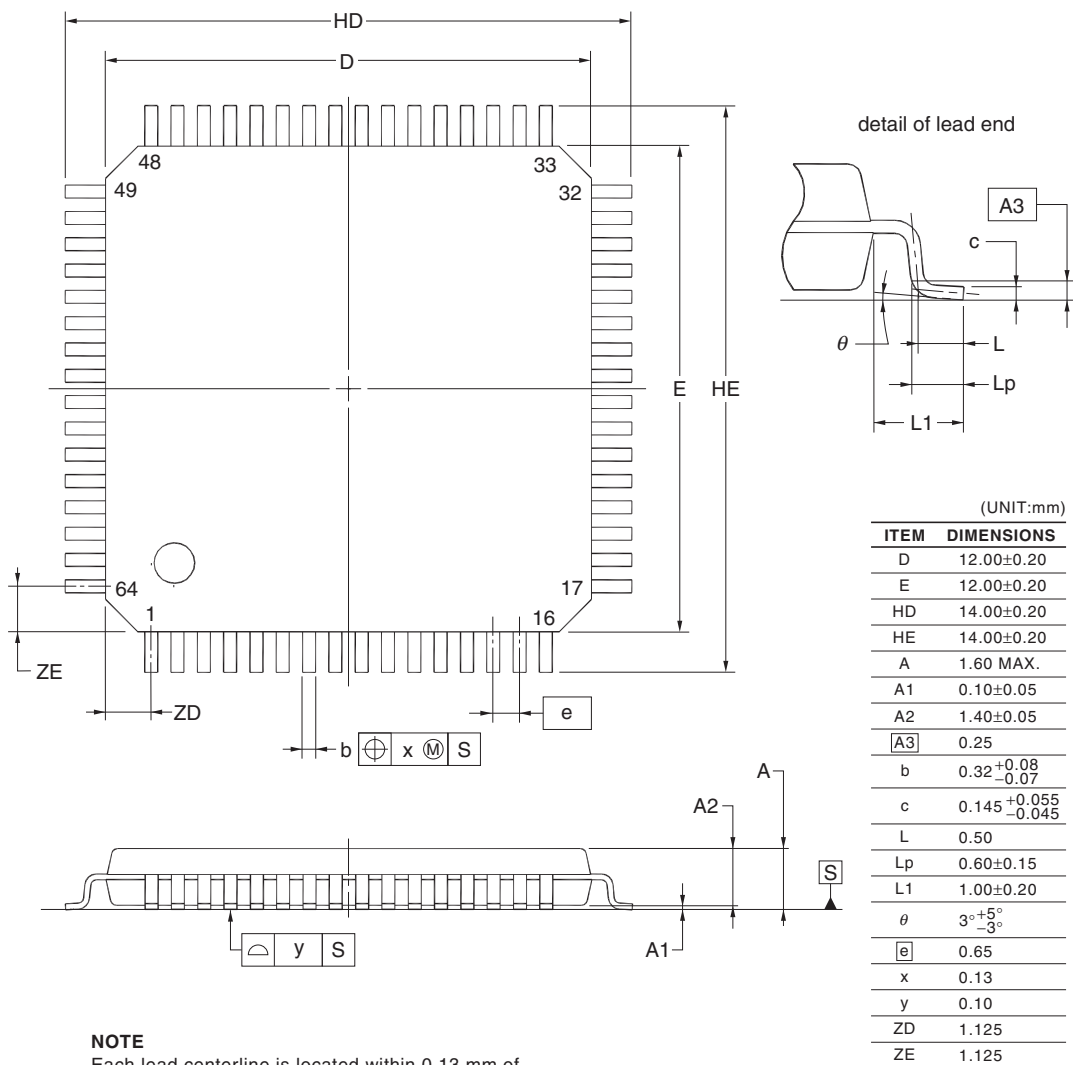
JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LFQFP48-7x7-0.50	PLQP0048KF-A	P48GA-50-8EU-1	0.16



## 4.11 64-pin Products

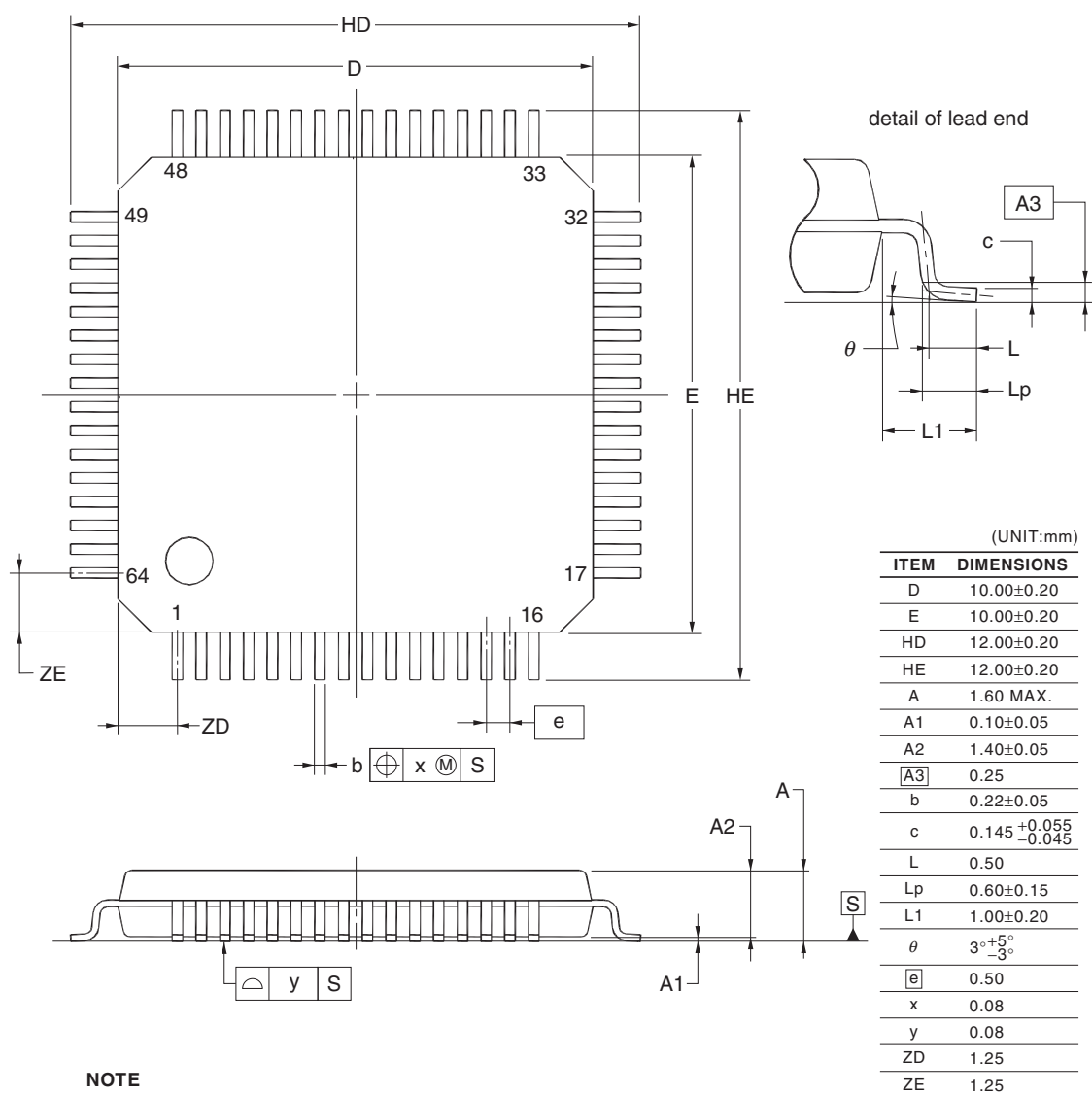
R5F100LCAFA, R5F100LDAFA, R5F100LEAFA, R5F100LFAFA, R5F100LGAFA, R5F100LHAFA, R5F100LJAF, A,  
R5F100LKAFA, R5F100LLAFA  
R5F101LCAFA, R5F101LDAFA, R5F101LEAFA, R5F101LFAFA, R5F101LGAFA, R5F101LHAFA, R5F101LJAF, A,  
R5F101LKAFA, R5F101LLAFA  
R5F100LCDFA, R5F100LDDFA, R5F100LEDFA, R5F100LFDFA, R5F100LG DFA, R5F100LH DFA, R5F100LJ DFA,  
R5F100LK DFA, R5F100LL DFA  
R5F101LCDFA, R5F101LDDFA, R5F101LEDFA, R5F101LFDFA, R5F101LG DFA, R5F101LH DFA, R5F101LJ DFA,  
R5F101LK DFA, R5F101LL DFA  
R5F100LCGFA, R5F100LDGFA, R5F100LEGFA, R5F100LFGFA, R5F100LGGFA, R5F100LHGFA,  
R5F100LJGFA

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LQFP64-12x12-0.65	PLQP0064JA-A	P64GK-65-UET-2	0.51



R5F100LCAFB, R5F100LDAFB, R5F100LEAFB, R5F100LFAFB, R5F100LGAFB, R5F100LHAFB, R5F100LJAFB,  
 R5F100LKAFB, R5F100LLAFB  
 R5F101LCAFB, R5F101LDAFB, R5F101LEAFB, R5F101LFAFB, R5F101LGAFB, R5F101LHAFB,  
 R5F101LJAFB, R5F101LKAFB, R5F101LLAFB  
 R5F100LCDFB, R5F100LDDFB, R5F100LEDDB, R5F100LFDDB, R5F100LGDFB, R5F100LHDFB, R5F100LJDFB,  
 R5F100LKDFB, R5F100LLDFB  
 R5F101LCDFB, R5F101LDDFB, R5F101LEDDB, R5F101LFDDB, R5F101LGDFB, R5F101LHDFB,  
 R5F101LJDFB, R5F101LKDFB, R5F101LLDFB  
 R5F100LCGFB, R5F100LDGFB, R5F100LEGFB, R5F100LFGFB, R5F100LGGFB, R5F100LHGFB,  
 R5F100LJGFB

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LFQFP64-10x10-0.50	PLQP0064KF-A	P64GB-50-UEU-2	0.35



#### NOTE

Each lead centerline is located within 0.08 mm of its true position at maximum material condition.

Rev.	Date	Description	
		Page	Summary
3.00	Aug 02, 2013	163	Modification of table in (8) Communication at different potential (1.8 V, 2.5 V, 3 V) (simplified I <sup>2</sup> C mode) (1/2)
		164, 165	Modification of table, note 1, and caution in (8) Communication at different potential (1.8 V, 2.5 V, 3 V) (simplified I <sup>2</sup> C mode) (2/2)
		166	Modification of table in 3.5.2 Serial interface IICA
		166	Modification of IICA serial transfer timing
		167	Addition of table in 3.6.1 A/D converter characteristics
		167, 168	Modification of table and notes 3 and 4 in 3.6.1 (1)
		169	Modification of description in 3.6.1 (2)
		170	Modification of description and note 3 in 3.6.1 (3)
		171	Modification of description and notes 3 and 4 in 3.6.1 (4)
		172	Modification of table and note in 3.6.3 POR circuit characteristics
		173	Modification of table of LVD Detection Voltage of Interrupt & Reset Mode
		173	Modification from Supply Voltage Rise Time to 3.6.5 Power supply voltage rising slope characteristics
		174	Modification of 3.9 Dedicated Flash Memory Programmer Communication (UART)
		175	Modification of table, figure, and remark in 3.10 Timing Specs for Switching Flash Memory Programming Modes
3.10	Nov 15, 2013	123	Caution 4 added.
		125	Note for operating ambient temperature in 3.1 Absolute Maximum Ratings deleted.
3.30	Mar 31, 2016		Modification of the position of the index mark in 25-pin plastic WFLGA (3 × 3 mm, 0.50 mm pitch) of 1.3.3 25-pin products
			Modification of power supply voltage in 1.6 Outline of Functions [20-pin, 24-pin, 25-pin, 30-pin, 32-pin, 36-pin products]
			Modification of power supply voltage in 1.6 Outline of Functions [40-pin, 44-pin, 48-pin, 52-pin, 64-pin products]
			Modification of power supply voltage in 1.6 Outline of Functions [80-pin, 100-pin, 128-pin products]
			<del>ACK</del> corrected to ACK
			<del>ACK</del> corrected to ACK

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## NOTES FOR CMOS DEVICES

- (1) **VOLTAGE APPLICATION WAVEFORM AT INPUT PIN:** Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN).
- (2) **HANDLING OF UNUSED INPUT PINS:** Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.
- (3) **PRECAUTION AGAINST ESD:** A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.
- (4) **STATUS BEFORE INITIALIZATION:** Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.
- (5) **POWER ON/OFF SEQUENCE:** In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current. The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.
- (6) **INPUT OF SIGNAL DURING POWER OFF STATE :** Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.