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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I ² C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	21
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	30-LSSOP (0.240", 6.10mm Width)
Supplier Device Package	30-LSSOP
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f101acasp-x0

Table 1-1. List of Ordering Part Numbers

(1/12)

Pin count	Package	Data flash	Fields of Application ^{Note}	Ordering Part Number
20 pins	20-pin plastic LSSOP (7.62 mm (300), 0.65 mm pitch)	Mounted	A	R5F1006AASP#V0, R5F1006CASP#V0, R5F1006DASP#V0, R5F1006EASP#V0 R5F1006AASP#X0, R5F1006CASP#X0, R5F1006DASP#X0, R5F1006EASP#X0 R5F1006ADSP#V0, R5F1006CDSP#V0, R5F1006DDSP#V0, R5F1006EDSP#V0 R5F1006ADSP#X0, R5F1006CDSP#X0, R5F1006DDSP#X0, R5F1006EDSP#X0 R5F1006AGSP#V0, R5F1006CGSP#V0, R5F1006DGSP#V0, R5F1006EGSP#V0 R5F1006AGSP#X0, R5F1006CGSP#X0, R5F1006DGSP#X0, R5F1006EGSP#X0
			D	R5F1006ADSP#V0, R5F1006CDSP#V0, R5F1006DDSP#V0, R5F1006EDSP#V0 R5F1006ADSP#X0, R5F1006CDSP#X0, R5F1006DDSP#X0, R5F1006EDSP#X0 R5F1006AGSP#V0, R5F1006CGSP#V0, R5F1006DGSP#V0, R5F1006EGSP#V0 R5F1006AGSP#X0, R5F1006CGSP#X0, R5F1006DGSP#X0, R5F1006EGSP#X0
			G	R5F1016AASP#V0, R5F1016CASP#V0, R5F1016DASP#V0, R5F1016EASP#V0 R5F1016AASP#X0, R5F1016CASP#X0, R5F1016DASP#X0, R5F1016EASP#X0 R5F1016ADSP#V0, R5F1016CDSP#V0, R5F1016DDSP#V0, R5F1016EDSP#V0 R5F1016ADSP#X0, R5F1016CDSP#X0, R5F1016DDSP#X0, R5F1016EDSP#X0
		Not mounted	A	R5F1016AASP#V0, R5F1016CASP#V0, R5F1016DASP#V0, R5F1016EASP#V0 R5F1016AASP#X0, R5F1016CASP#X0, R5F1016DASP#X0, R5F1016EASP#X0 R5F1016ADSP#V0, R5F1016CDSP#V0, R5F1016DDSP#V0, R5F1016EDSP#V0 R5F1016ADSP#X0, R5F1016CDSP#X0, R5F1016DDSP#X0, R5F1016EDSP#X0
			D	R5F1016ADSP#V0, R5F1016CDSP#V0, R5F1016DDSP#V0, R5F1016EDSP#V0 R5F1016ADSP#X0, R5F1016CDSP#X0, R5F1016DDSP#X0, R5F1016EDSP#X0
			G	R5F1007AANA#U0, R5F1007CANA#U0, R5F1007DANA#U0, R5F1007EANA#U0 R5F1007AANA#W0, R5F1007CANA#W0, R5F1007DANA#W0, R5F1007EANA#W0 R5F1007ADNA#U0, R5F1007CDNA#U0, R5F1007DDNA#U0, R5F1007EDNA#U0 R5F1007ADNA#W0, R5F1007CDNA#W0, R5F1007DDNA#W0, R5F1007EDNA#W0 R5F1007AGNA#U0, R5F1007CGNA#U0, R5F1007DGNA#U0, R5F1007EGNA#U0 R5F1007AGNA#W0, R5F1007CGNA#W0, R5F1007DGNA#W0, R5F1007EGNA#W0
		Not mounted	A	R5F1017AANA#U0, R5F1017CANA#U0, R5F1017DANA#U0, R5F1017EANA#U0 R5F1017AANA#W0, R5F1017CANA#W0, R5F1017DANA#W0, R5F1017EANA#W0 R5F1017ADNA#U0, R5F1017CDNA#U0, R5F1017DDNA#U0, R5F1017EDNA#U0 R5F1017ADNA#W0, R5F1017CDNA#W0, R5F1017DDNA#W0, R5F1017EDNA#W0
			D	R5F1017ADNA#U0, R5F1017CDNA#U0, R5F1017DDNA#U0, R5F1017EDNA#U0 R5F1017ADNA#W0, R5F1017CDNA#W0, R5F1017DDNA#W0, R5F1017EDNA#W0

Note For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

Caution The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.

Table 1-1. List of Ordering Part Numbers

(4/12)

Pin count	Package	Data flash	Fields of Application <small>Note</small>	Ordering Part Number
44 pins	44-pin plastic LQFP (10 × 10 mm, 0.8 mm pitch)	Mounted	A D G	R5F100FAAFP#V0, R5F100FC AFP#V0, R5F100FDAFP#V0, R5F100FEA FP#V0, R5F100FFA FP#V0, R5F100FGA FP#V0, R5F100FH A FP#V0, R5F100FJA FP#V0, R5F100FKA FP#V0, R5F100FLA FP#V0 R5F100FAAFP#X0, R5F100FC AFP#X0, R5F100FDAFP#X0, R5F100FEA FP#X0, R5F100FFA FP#X0, R5F100FGA FP#X0, R5F100FH A FP#X0, R5F100FJA FP#X0, R5F100FKA FP#X0, R5F100FLA FP#X0 R5F100FADFP#V0, R5F100FCDFP#V0, R5F100FDDFP#V0, R5F100FEDFP#V0, R5F100FFDFP#V0, R5F100FGDFP#V0, R5F100FHDFP#V0, R5F100FJDFP#V0, R5F100FKDFP#V0, R5F100FLDFP#V0 R5F100FADFP#X0, R5F100FCDFP#X0, R5F100FDDFP#X0, R5F100FEDFP#X0, R5F100FFDFP#X0, R5F100FGDFP#X0, R5F100FHDFP#X0, R5F100FJDFP#X0, R5F100FKDFP#X0, R5F100FLDFP#X0 R5F100FAGFP#V0, R5F100FC GFP#V0, R5F100FD GFP#V0, R5F100FEGFP#V0, R5F100FF GFP#V0, R5F100FG GFP#V0, R5F100FH GFP#V0, R5F100FJ GFP#V0 R5F100FAGFP#X0, R5F100FC GFP#X0, R5F100FD GFP#X0, R5F100FEGFP#X0, R5F100FF GFP#X0, R5F100FG GFP#X0, R5F100FH GFP#X0, R5F100FJ GFP#X0
	Not mounted	A D		R5F101FAAFP#V0, R5F101FC AFP#V0, R5F101FDAFP#V0, R5F101FEA FP#V0, R5F101FFA FP#V0, R5F101FGA FP#V0, R5F101FH A FP#V0, R5F101FJA FP#V0, R5F101FKA FP#V0, R5F101FLA FP#V0 R5F101FAAFP#X0, R5F101FC AFP#X0, R5F101FDAFP#X0, R5F101FEA FP#X0, R5F101FFA FP#X0, R5F101FGA FP#X0, R5F101FH A FP#X0, R5F101FJA FP#X0, R5F101FKA FP#X0, R5F101FLA FP#X0 R5F101FADFP#V0, R5F101FCDFP#V0, R5F101FDDFP#V0, R5F101FEDFP#V0, R5F101FFDFP#V0, R5F101FGDFP#V0, R5F101FHDFP#V0, R5F101FJDFP#V0, R5F101FKDFP#V0, R5F101FLDFP#V0 R5F101FADFP#X0, R5F101FCDFP#X0, R5F101FDDFP#X0, R5F101FEDFP#X0, R5F101FFDFP#X0, R5F101FGDFP#X0, R5F101FHDFP#X0, R5F101FJDFP#X0, R5F101FKDFP#X0, R5F101FLDFP#X0

Note For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

Caution The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.

Table 1-1. List of Ordering Part Numbers

(8/12)

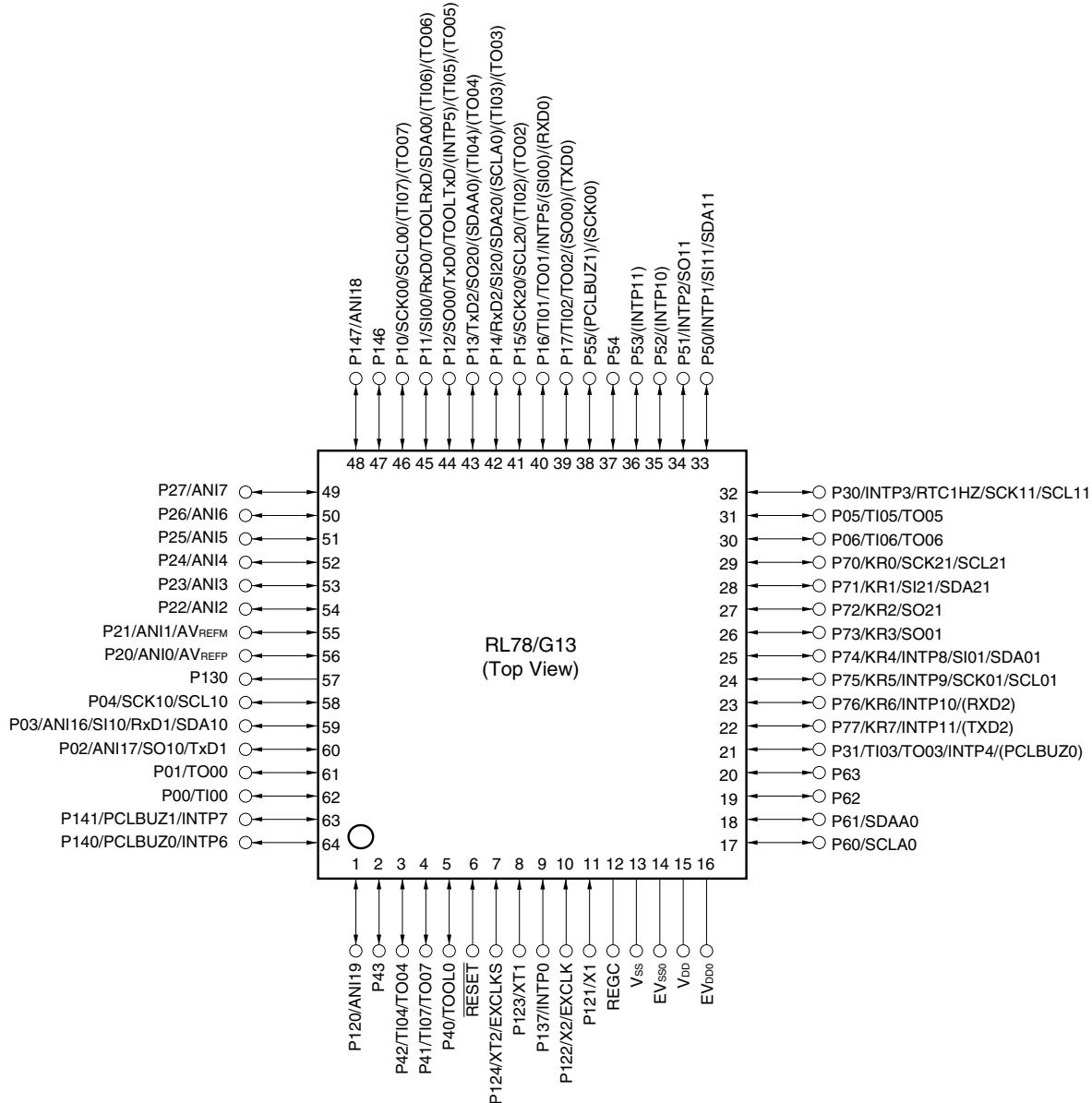
Pin count	Package	Data flash	Fields of Application ^{Note}	Ordering Part Number
64 pins	64-pin plastic LQFP (12 × 12 mm, 0.65 mm pitch)	Mounted	A D G	R5F100LCAFA#V0, R5F100LDAFA#V0, R5F100LEAFA#V0, R5F100LFAFA#V0, R5F100LGAFA#V0, R5F100LHAFA#V0, R5F100LJAFA#V0, R5F100LKAFA#V0, R5F100LLAFA#V0 R5F100LCAFA#X0, R5F100LDAFA#X0, R5F100LEAFA#X0, R5F100LFAFA#X0, R5F100LGAFA#X0, R5F100LHAFA#X0, R5F100LJAFA#X0, R5F100LKAFA#X0, R5F100LLAFA#X0 R5F100LCDFA#V0, R5F100LDDFA#V0, R5F100LEDFA#V0, R5F100LF DFA#V0, R5F100LGDFA#V0, R5F100LHDFA#V0, R5F100LJDFA#V0, R5F100LK DFA#V0, R5F100LLDFA#V0 R5F100LCDFA#X0, R5F100LDDFA#X0, R5F100LEDFA#X0, R5F100LF DFA#X0, R5F100LGDFA#X0, R5F100LHDFA#X0, R5F100LJDFA#X0, R5F100LK DFA#X0, R5F100LLDFA#X0 R5F100LCGFA#V0, R5F100LDGFA#V0, R5F100LEGFA#V0, R5F100LFGFA#V0 R5F100LCGFA#X0, R5F100LDGFA#X0, R5F100LEGFA#X0, R5F100LFGFA#X0 R5F100LGGFA#V0, R5F100LHGFA#V0, R5F100LJGFA#V0 R5F100LGGFA#X0, R5F100LHGFA#X0, R5F100LJGFA#X0
		Not mounted	A D	R5F101LCAFA#V0, R5F101LDAFA#V0, R5F101LEAFA#V0, R5F101LFAFA#V0, R5F101LGAFA#V0, R5F101LHAFA#V0, R5F101LJAFA#V0, R5F101LKAFA#V0, R5F101LLAFA#V0 R5F101LCAFA#X0, R5F101LDAFA#X0, R5F101LEAFA#X0, R5F101LFAFA#X0, R5F101LGAFA#X0, R5F101LHAFA#X0, R5F101LJAFA#X0, R5F101LKAFA#X0, R5F101LLAFA#X0 R5F101LCDFA#V0, R5F101LDDFA#V0, R5F101LEDFA#V0, R5F101LF DFA#V0, R5F101LGDFA#V0, R5F101LHDFA#V0, R5F101LJDFA#V0, R5F101LK DFA#V0, R5F101LLDFA#V0 R5F101LCDFA#X0, R5F101LDDFA#X0, R5F101LEDFA#X0, R5F101LF DFA#X0, R5F101LGDFA#X0, R5F101LHDFA#X0, R5F101LJDFA#X0, R5F101LK DFA#X0, R5F101LLDFA#X0

Note For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

Caution The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.

1.3.11 64-pin products

- 64-pin plastic LQFP (12 × 12 mm, 0.65 mm pitch)
- 64-pin plastic LFQFP (10 × 10 mm, 0.5 mm pitch)



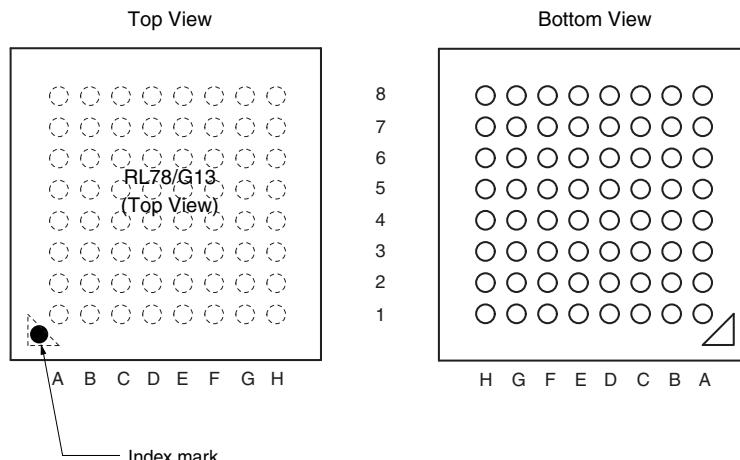
Cautions 1. Make EV_{SS0} pin the same potential as V_{ss} pin.

2. Make V_{DD} pin the potential that is higher than EV_{VDD0} pin.
3. Connect the REGC pin to V_{ss} via a capacitor (0.47 to 1 μ F).

Remarks 1. For pin identification, see **1.4 Pin Identification**.

2. When using the microcontroller for an application where the noise generated inside the microcontroller must be reduced, it is recommended to supply separate powers to the V_{DD} and EV_{VDD0} pins and connect the V_{ss} and EV_{SS0} pins to separate ground lines.
3. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

- 64-pin plastic VFBGA (4 × 4 mm, 0.4 mm pitch)



Pin No.	Name	Pin No.	Name	Pin No.	Name	Pin No.	Name
A1	P05/TI05/TO05	C1	P51/INTP2/SO11	E1	P13/TxD2/SO20/(SDAA0)/(TI04)/(TO04)	G1	P146
A2	P30/INTP3/RTC1HZ/SCK11/SCL11	C2	P71/KR1/SI21/SDA21	E2	P14/RxD2/SI20/SDA20/(SCLA0)/(TI03)/(TO03)	G2	P25/ANI5
A3	P70/KR0/SCK21/SCL21	C3	P74/KR4/INTP8/SI01/SDA01	E3	P15/SCK20/SCL20/(TI02)/(TO02)	G3	P24/ANI4
A4	P75/KR5/INTP9/SCK01/SCL01	C4	P52/(INTP10)	E4	P16/TI01/TO01/INTP5/(SI00)/(RxD0)	G4	P22/ANI2
A5	P77/KR7/INTP11/(TxD2)	C5	P53/(INTP11)	E5	P03/ANI16/SI10/RxD1/SDA10	G5	P130
A6	P61/SDAA0	C6	P63	E6	P41/TI07/TO07	G6	P02/ANI17/SO10/TxD1
A7	P60/SCLA0	C7	V _{ss}	E7	RESET	G7	P00/TI00
A8	EV _{DD0}	C8	P121/X1	E8	P137/INTP0	G8	P124/XT2/EXCLKS
B1	P50/INTP1/SI11/SDA11	D1	P55/(PCLBUZ1)/(SCK00)	F1	P10/SCK00/SCL00/(TI07)/(TO07)	H1	P147/ANI18
B2	P72/KR2/SO21	D2	P06/TI06/TO06	F2	P11/SI00/RxD0/TOOLRxDSDA00/(TI06)/(TO06)	H2	P27/ANI7
B3	P73/KR3/SO01	D3	P17/TI02/TO02/(SO00)/(TxD0)	F3	P12/SO00/TxD0/TOOLTxD/(INTP5)/(TI05)/(TO05)	H3	P26/ANI6
B4	P76/KR6/INTP10/(RxD2)	D4	P54	F4	P21/ANI1/AV _{REFM}	H4	P23/ANI3
B5	P31/TI03/TO03/INTP4/(PCLBUZ0)	D5	P42/TI04/TO04	F5	P04/SCK10/SCL10	H5	P20/ANI0/AV _{REFP}
B6	P62	D6	P40/TOOL0	F6	P43	H6	P141/PCLBUZ1/INTP7
B7	V _{DD}	D7	REGC	F7	P01/TO00	H7	P140/PCLBUZ0/INTP6
B8	EV _{SS0}	D8	P122/X2/EXCLK	F8	P123/XT1	H8	P120/ANI19

Cautions 1. Make EV_{SS0} pin the same potential as V_{ss} pin.

2. Make V_{DD} pin the potential that is higher than EV_{DD0} pin.
3. Connect the REGC pin to V_{ss} via a capacitor (0.47 to 1 μ F).

Remarks 1. For pin identification, see 1.4 Pin Identification.

2. When using the microcontroller for an application where the noise generated inside the microcontroller must be reduced, it is recommended to supply separate powers to the V_{DD} and EV_{DD0} pins and connect the V_{ss} and EV_{SS0} pins to separate ground lines.
3. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

2. The number of PWM outputs varies depending on the setting of channels in use (the number of masters and slaves) (see **6.9.3 Operation as multiple PWM output function** in the RL78/G13 User's Manual).
3. When setting to PIOR = 1

(2/2)

Item	40-pin		44-pin		48-pin		52-pin		64-pin	
	R5F100EX	R5F101EX	R5F100FX	R5F101FX	R5F100GX	R5F101GX	R5F100JX	R5F101JX	R5F100LX	R5F101LX
Clock output/buzzer output	2		2		2		2		2	
<ul style="list-style-type: none"> • 2.44 kHz, 4.88 kHz, 9.76 kHz, 1.25 MHz, 2.5 MHz, 5 MHz, 10 MHz (Main system clock: $f_{MAIN} = 20$ MHz operation) • 256 Hz, 512 Hz, 1.024 kHz, 2.048 kHz, 4.096 kHz, 8.192 kHz, 16.384 kHz, 32.768 kHz (Subsystem clock: $f_{SUB} = 32.768$ kHz operation) 										
8/10-bit resolution A/D converter	9 channels		10 channels		10 channels		12 channels		12 channels	
Serial interface	<p>[40-pin, 44-pin products]</p> <ul style="list-style-type: none"> • CSI: 1 channel/simplified I²C: 1 channel/UART: 1 channel • CSI: 1 channel/simplified I²C: 1 channel/UART: 1 channel • CSI: 2 channels/simplified I²C: 2 channels/UART (UART supporting LIN-bus): 1 channel <p>[48-pin, 52-pin products]</p> <ul style="list-style-type: none"> • CSI: 2 channels/simplified I²C: 2 channels/UART: 1 channel • CSI: 1 channel/simplified I²C: 1 channel/UART: 1 channel • CSI: 2 channels/simplified I²C: 2 channels/UART (UART supporting LIN-bus): 1 channel <p>[64-pin products]</p> <ul style="list-style-type: none"> • CSI: 2 channels/simplified I²C: 2 channels/UART: 1 channel • CSI: 2 channels/simplified I²C: 2 channels/UART: 1 channel • CSI: 2 channels/simplified I²C: 2 channels/UART (UART supporting LIN-bus): 1 channel 									
I ² C bus	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel
Multiplier and divider/multiply-accumulator	<ul style="list-style-type: none"> • 16 bits × 16 bits = 32 bits (Unsigned or signed) • 32 bits ÷ 32 bits = 32 bits (Unsigned) • 16 bits × 16 bits + 32 bits = 32 bits (Unsigned or signed) 									
DMA controller	2 channels									
Vectored interrupt sources	Internal	27	27	27	27	27	27	27	27	27
	External	7	7	10	12	12	13	13	13	13
Key interrupt	4									
Reset	<ul style="list-style-type: none"> • Reset by <u>RESET</u> pin • Internal reset by watchdog timer • Internal reset by power-on-reset • Internal reset by voltage detector • Internal reset by illegal instruction execution ^{Note} • Internal reset by RAM parity error • Internal reset by illegal-memory access 									
Power-on-reset circuit	<ul style="list-style-type: none"> • Power-on-reset: 1.51 V (TYP.) • Power-down-reset: 1.50 V (TYP.) 									
Voltage detector	<ul style="list-style-type: none"> • Rising edge : 1.67 V to 4.06 V (14 stages) • Falling edge : 1.63 V to 3.98 V (14 stages) 									
On-chip debug function	Provided									
Power supply voltage	$V_{DD} = 1.6$ to 5.5 V ($T_A = -40$ to $+85^\circ\text{C}$) $V_{DD} = 2.4$ to 5.5 V ($T_A = -40$ to $+105^\circ\text{C}$)									
<R>	Operating ambient temperature									
	$T_A = 40$ to $+85^\circ\text{C}$ (A: Consumer applications, D: Industrial applications) $T_A = 40$ to $+105^\circ\text{C}$ (G: Industrial applications)									

Note The illegal instruction is generated when instruction code FFH is executed.

Reset by the illegal instruction execution not issued by emulation with the in-circuit emulator or on-chip debug emulator.

2.3.2 Supply current characteristics

(1) Flash ROM: 16 to 64 KB of 20- to 64-pin products

 $(T_A = -40$ to $+85^\circ\text{C}$, $1.6 \text{ V} \leq EV_{DD0} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{ss} = EV_{ss0} = 0 \text{ V}$) (1/2)

Parameter	Symbol	Conditions				MIN.	TYP.	MAX.	Unit
Supply current ^{Note 1}	I_{DD1}	Operating mode HS (high-speed main) mode ^{Note 5}	$f_{IH} = 32 \text{ MHz}$ ^{Note 3}	Basic operation	$V_{DD} = 5.0 \text{ V}$		2.1		mA
					$V_{DD} = 3.0 \text{ V}$		2.1		mA
			$f_{IH} = 24 \text{ MHz}$ ^{Note 3}	Normal operation	$V_{DD} = 5.0 \text{ V}$		4.6	7.0	mA
					$V_{DD} = 3.0 \text{ V}$		4.6	7.0	mA
			$f_{IH} = 16 \text{ MHz}$ ^{Note 3}	Normal operation	$V_{DD} = 5.0 \text{ V}$		2.7	4.0	mA
					$V_{DD} = 3.0 \text{ V}$		2.7	4.0	mA
		LS (low-speed main) mode ^{Note 5}	$f_{IH} = 8 \text{ MHz}$ ^{Note 3}	Normal operation	$V_{DD} = 3.0 \text{ V}$		1.2	1.8	mA
					$V_{DD} = 2.0 \text{ V}$		1.2	1.8	mA
		LV (low-voltage main) mode ^{Note 5}	$f_{IH} = 4 \text{ MHz}$ ^{Note 3}	Normal operation	$V_{DD} = 3.0 \text{ V}$		1.2	1.7	mA
					$V_{DD} = 2.0 \text{ V}$		1.2	1.7	mA
		HS (high-speed main) mode ^{Note 5}	$f_{MX} = 20 \text{ MHz}$ ^{Note 2} , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		3.0	4.6	mA
					Resonator connection		3.2	4.8	mA
			$f_{MX} = 20 \text{ MHz}$ ^{Note 2} , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		3.0	4.6	mA
					Resonator connection		3.2	4.8	mA
			$f_{MX} = 10 \text{ MHz}$ ^{Note 2} , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		1.9	2.7	mA
					Resonator connection		1.9	2.7	mA
			$f_{MX} = 10 \text{ MHz}$ ^{Note 2} , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		1.9	2.7	mA
					Resonator connection		1.9	2.7	mA
		LS (low-speed main) mode ^{Note 5}	$f_{MX} = 8 \text{ MHz}$ ^{Note 2} , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		1.1	1.7	mA
					Resonator connection		1.1	1.7	mA
			$f_{MX} = 8 \text{ MHz}$ ^{Note 2} , $V_{DD} = 2.0 \text{ V}$	Normal operation	Square wave input		1.1	1.7	mA
					Resonator connection		1.1	1.7	mA
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = -40^\circ\text{C}$	Normal operation	Square wave input		4.1	4.9	μA
					Resonator connection		4.2	5.0	μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +25^\circ\text{C}$	Normal operation	Square wave input		4.1	4.9	μA
					Resonator connection		4.2	5.0	μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +50^\circ\text{C}$	Normal operation	Square wave input		4.2	5.5	μA
					Resonator connection		4.3	5.6	μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +70^\circ\text{C}$	Normal operation	Square wave input		4.3	6.3	μA
					Resonator connection		4.4	6.4	μA
			$f_{SUB} = 32.768 \text{ kHz}$ ^{Note 4} $T_A = +85^\circ\text{C}$	Normal operation	Square wave input		4.6	7.7	μA
					Resonator connection		4.7	7.8	μA

(Notes and Remarks are listed on the next page.)

(2) Flash ROM: 96 to 256 KB of 30- to 100-pin products

 $(T_A = -40$ to $+85^\circ\text{C}$, $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$) (2/2)

Parameter	Symbol	Conditions				MIN.	TYP.	MAX.	Unit	
Supply current <small>Note 1</small>	$I_{DD2}^{Note 2}$	HALT mode	HS (high-speed main) mode ^{Note 7}	$f_{IH} = 32 \text{ MHz}^{Note 4}$	$V_{DD} = 5.0 \text{ V}$		0.62	1.86	mA	
				$V_{DD} = 3.0 \text{ V}$			0.62	1.86	mA	
			$f_{IH} = 24 \text{ MHz}^{Note 4}$	$V_{DD} = 5.0 \text{ V}$			0.50	1.45	mA	
				$V_{DD} = 3.0 \text{ V}$			0.50	1.45	mA	
			$f_{IH} = 16 \text{ MHz}^{Note 4}$	$V_{DD} = 5.0 \text{ V}$			0.44	1.11	mA	
				$V_{DD} = 3.0 \text{ V}$			0.44	1.11	mA	
		LS (low-speed main) mode ^{Note 7}	$f_{IH} = 8 \text{ MHz}^{Note 4}$	$V_{DD} = 3.0 \text{ V}$			290	620	μA	
				$V_{DD} = 2.0 \text{ V}$			290	620	μA	
		LV (low-voltage main) mode ^{Note 7}	$f_{IH} = 4 \text{ MHz}^{Note 4}$	$V_{DD} = 3.0 \text{ V}$			440	680	μA	
				$V_{DD} = 2.0 \text{ V}$			440	680	μA	
		HS (high-speed main) mode ^{Note 7}	$f_{MX} = 20 \text{ MHz}^{Note 3}$, $V_{DD} = 5.0 \text{ V}$	Square wave input			0.31	1.08	mA	
				Resonator connection			0.48	1.28	mA	
			$f_{MX} = 20 \text{ MHz}^{Note 3}$, $V_{DD} = 3.0 \text{ V}$	Square wave input			0.31	1.08	mA	
				Resonator connection			0.48	1.28	mA	
			$f_{MX} = 10 \text{ MHz}^{Note 3}$, $V_{DD} = 5.0 \text{ V}$	Square wave input			0.21	0.63	mA	
				Resonator connection			0.28	0.71	mA	
			$f_{MX} = 10 \text{ MHz}^{Note 3}$, $V_{DD} = 3.0 \text{ V}$	Square wave input			0.21	0.63	mA	
				Resonator connection			0.28	0.71	mA	
		LS (low-speed main) mode ^{Note 7}	$f_{MX} = 8 \text{ MHz}^{Note 3}$, $V_{DD} = 3.0 \text{ V}$	Square wave input			110	360	μA	
				Resonator connection			160	420	μA	
			$f_{MX} = 8 \text{ MHz}^{Note 3}$, $V_{DD} = 2.0 \text{ V}$	Square wave input			110	360	μA	
				Resonator connection			160	420	μA	
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = -40^\circ\text{C}$	Square wave input			0.28	0.61	μA	
				Resonator connection			0.47	0.80	μA	
			$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = +25^\circ\text{C}$	Square wave input			0.34	0.61	μA	
				Resonator connection			0.53	0.80	μA	
			$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = +50^\circ\text{C}$	Square wave input			0.41	2.30	μA	
				Resonator connection			0.60	2.49	μA	
			$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = +70^\circ\text{C}$	Square wave input			0.64	4.03	μA	
				Resonator connection			0.83	4.22	μA	
			$f_{SUB} = 32.768 \text{ kHz}^{Note 5}$ $T_A = +85^\circ\text{C}$	Square wave input			1.09	8.04	μA	
				Resonator connection			1.28	8.23	μA	
$I_{DD3}^{Note 6}$	STOP mode ^{Note 8}	$T_A = -40^\circ\text{C}$					0.19	0.52	μA	
		$T_A = +25^\circ\text{C}$					0.25	0.52	μA	
		$T_A = +50^\circ\text{C}$					0.32	2.21	μA	
		$T_A = +70^\circ\text{C}$					0.55	3.94	μA	
		$T_A = +85^\circ\text{C}$					1.00	7.95	μA	

(Notes and Remarks are listed on the next page.)

Notes 1. Total current flowing into V_{DD} , EV_{DD0} , and EV_{DD1} , including the input leakage current flowing when the level of the input pin is fixed to V_{DD} , EV_{DD0} , and EV_{DD1} , or V_{SS} , EV_{SS0} , and EV_{SS1} . The values below the MAX. column include the peripheral operation current. However, not including the current flowing into the A/D converter, LVD circuit, I/O port, and on-chip pull-up/pull-down resistors and the current flowing during data flash rewrite.

2. When high-speed on-chip oscillator and subsystem clock are stopped.
3. When high-speed system clock and subsystem clock are stopped.
4. When high-speed on-chip oscillator and high-speed system clock are stopped. When $AMPHS1 = 1$ (Ultra-low power consumption oscillation). However, not including the current flowing into the RTC, 12-bit interval timer, and watchdog timer.
5. Relationship between operation voltage width, operation frequency of CPU and operation mode is as below.

HS (high-speed main) mode: $2.7 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$ @ 1 MHz to 32 MHz

$2.4 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$ @ 1 MHz to 16 MHz

LS (low-speed main) mode: $1.8 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$ @ 1 MHz to 8 MHz

LV (low-voltage main) mode: $1.6 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$ @ 1 MHz to 4 MHz

- Remarks**
1. f_{MX} : High-speed system clock frequency (X1 clock oscillation frequency or external main system clock frequency)
 2. f_{IH} : High-speed on-chip oscillator clock frequency
 3. f_{SUB} : Subsystem clock frequency (XT1 clock oscillation frequency)
 4. Except subsystem clock operation, temperature condition of the TYP. value is $T_A = 25^\circ\text{C}$

- (2) During communication at same potential (CSI mode) (master mode, SCKp... internal clock output, corresponding CSI00 only)

($T_A = -40$ to $+85^\circ\text{C}$, $2.7 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCKp cycle time	t_{KCY1}	$t_{KCY1} \geq 2/f_{CLK}$	$4.0 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$	62.5		250		500		ns
			$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$	83.3		250		500		ns
SCKp high-/low-level width	t_{KH1}, t_{KL1}	$4.0 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		$t_{KCY1}/2 - 7$		$t_{KCY1}/2 - 50$		$t_{KCY1}/2 - 50$		ns
		$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		$t_{KCY1}/2 - 10$		$t_{KCY1}/2 - 50$		$t_{KCY1}/2 - 50$		ns
Slp setup time (to SCKp \uparrow) <small>Note 1</small>	t_{SIK1}	$4.0 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		23		110		110		ns
		$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		33		110		110		ns
Slp hold time (from SCKp \uparrow) <small>Note 2</small>	t_{KSI1}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		10		10		10		ns
Delay time from SCKp \downarrow to SOp output <small>Note 3</small>	t_{KS01}	$C = 20 \text{ pF}$ <small>Note 4</small>			10		10		10	ns

- Notes**
- When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp setup time becomes “to SCKp \downarrow ” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
 - When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp hold time becomes “from SCKp \downarrow ” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
 - When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The delay time to SOp output becomes “from SCKp \uparrow ” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
 - C is the load capacitance of the SCKp and SOp output lines.

Caution Select the normal input buffer for the Slp pin and the normal output mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg).

Remarks 1. This value is valid only when CSI00’s peripheral I/O redirect function is not used.

- p: CSI number (p = 00), m: Unit number (m = 0), n: Channel number (n = 0),
g: PIM and POM numbers (g = 1)
3. f_{MCK}: Serial array unit operation clock frequency
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00))

(6) Communication at different potential (1.8 V, 2.5 V, 3 V) (UART mode) (2/2)

(TA = -40 to +85°C, 1.8 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
Transfer rate	Transmission	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V	Theoretical value of the maximum transfer rate C _b = 50 pF, R _b = 1.4 kΩ, V _b = 2.7 V	Note 1		Note 1		Note 1		bps
				2.8 Note 2		2.8 Note 2		2.8 Note 2		Mbps
				Note 3		Note 3		Note 3		bps
		2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V	Theoretical value of the maximum transfer rate C _b = 50 pF, R _b = 2.7 kΩ, V _b = 2.3 V	1.2 Note 4		1.2 Note 4		1.2 Note 4		Mbps
		1.8 V ≤ EV _{DD0} < 3.3 V, 1.6 V ≤ V _b ≤ 2.0 V	Theoretical value of the maximum transfer rate C _b = 50 pF, R _b = 5.5 kΩ, V _b = 1.6 V	Notes 5, 6		Notes 5, 6		Notes 5, 6		bps
				0.43 Note 7		0.43 Note 7		0.43 Note 7		Mbps

Notes 1. The smaller maximum transfer rate derived by using fmck/6 or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when 4.0 V ≤ EV_{DD0} ≤ 5.5 V and 2.7 V ≤ V_b ≤ 4.0 V

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{2.2}{V_b})\} \times 3} \text{ [bps]}$$

$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{2.2}{V_b})\}}{\left(\frac{1}{\text{Transfer rate}}\right) \times \text{Number of transferred bits}} \times 100 [\%]$$

* This value is the theoretical value of the relative difference between the transmission and reception sides.

- 2.** This value as an example is calculated when the conditions described in the “Conditions” column are met. Refer to Note 1 above to calculate the maximum transfer rate under conditions of the customer.

(7) Communication at different potential (2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock output, corresponding CSI00 only) (1/2)

($T_A = -40$ to $+85^\circ\text{C}$, $2.7 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCKp cycle time	t _{KCY1}	t _{KCY1} ≥ 2/f _{CLK}	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V, C _b = 20 pF, R _b = 1.4 kΩ	200		1150		1150		ns
			2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V, C _b = 20 pF, R _b = 2.7 kΩ	300		1150		1150		ns
SCKp high-level width	t _{KH1}	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V, C _b = 20 pF, R _b = 1.4 kΩ	t _{KCY1} /2 – 50		t _{KCY1} /2 – 50		t _{KCY1} /2 – 50			ns
		2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V, C _b = 20 pF, R _b = 2.7 kΩ	t _{KCY1} /2 – 120		t _{KCY1} /2 – 120		t _{KCY1} /2 – 120			ns
SCKp low-level width	t _{KL1}	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V, C _b = 20 pF, R _b = 1.4 kΩ	t _{KCY1} /2 – 7		t _{KCY1} /2 – 50		t _{KCY1} /2 – 50			ns
		2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V, C _b = 20 pF, R _b = 2.7 kΩ	t _{KCY1} /2 – 10		t _{KCY1} /2 – 50		t _{KCY1} /2 – 50			ns
Slp setup time (to SCKp↑) ^{Note 1}	t _{SIK1}	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V, C _b = 20 pF, R _b = 1.4 kΩ	58		479		479			ns
		2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V, C _b = 20 pF, R _b = 2.7 kΩ	121		479		479			ns
Slp hold time (from SCKp↑) ^{Note 1}	t _{KS1}	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V, C _b = 20 pF, R _b = 1.4 kΩ	10		10		10			ns
		2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V, C _b = 20 pF, R _b = 2.7 kΩ	10		10		10			ns
Delay time from SCKp↓ to SO _p output ^{Note 1}	t _{KS01}	4.0 V ≤ EV _{DD0} ≤ 5.5 V, 2.7 V ≤ V _b ≤ 4.0 V, C _b = 20 pF, R _b = 1.4 kΩ		60		60		60		ns
		2.7 V ≤ EV _{DD0} < 4.0 V, 2.3 V ≤ V _b ≤ 2.7 V, C _b = 20 pF, R _b = 2.7 kΩ		130		130		130		ns

(Notes, Caution, and Remarks are listed on the next page.)

(9) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (slave mode, SCKp... external clock input)

($T_A = -40$ to $+85^\circ\text{C}$, $1.8 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$) (1/2)

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCKp cycle time ^{Note 1}	t _{KCY2}	4.0 V $\leq EV_{DD0} \leq 5.5$ V, 2.7 V $\leq V_b \leq 4.0$ V	24 MHz $< f_{MCK}$	14/ f_{MCK}	—	—	—	—	ns
			20 MHz $< f_{MCK} \leq 24$ MHz	12/ f_{MCK}	—	—	—	—	ns
			8 MHz $< f_{MCK} \leq 20$ MHz	10/ f_{MCK}	—	—	—	—	ns
			4 MHz $< f_{MCK} \leq 8$ MHz	8/ f_{MCK}	—	16/ f_{MCK}	—	—	ns
			$f_{MCK} \leq 4$ MHz	6/ f_{MCK}	—	10/ f_{MCK}	—	10/ f_{MCK}	ns
		2.7 V $\leq EV_{DD0} < 4.0$ V, 2.3 V $\leq V_b \leq 2.7$ V	24 MHz $< f_{MCK}$	20/ f_{MCK}	—	—	—	—	ns
			20 MHz $< f_{MCK} \leq 24$ MHz	16/ f_{MCK}	—	—	—	—	ns
			16 MHz $< f_{MCK} \leq 20$ MHz	14/ f_{MCK}	—	—	—	—	ns
			8 MHz $< f_{MCK} \leq 16$ MHz	12/ f_{MCK}	—	—	—	—	ns
			$f_{MCK} \leq 4$ MHz	8/ f_{MCK}	—	16/ f_{MCK}	—	—	ns
		1.8 V $\leq EV_{DD0} < 3.3$ V, 1.6 V $\leq V_b \leq 2.0$ V ^{Note 2}	24 MHz $< f_{MCK}$	48/ f_{MCK}	—	—	—	—	ns
			20 MHz $< f_{MCK} \leq 24$ MHz	36/ f_{MCK}	—	—	—	—	ns
			16 MHz $< f_{MCK} \leq 20$ MHz	32/ f_{MCK}	—	—	—	—	ns
			8 MHz $< f_{MCK} \leq 16$ MHz	26/ f_{MCK}	—	—	—	—	ns
			$f_{MCK} \leq 4$ MHz	16/ f_{MCK}	—	16/ f_{MCK}	—	—	ns

(Notes and Caution are listed on the next page, and Remarks are listed on the page after the next page.)

- Notes**
- 1. The first clock pulse is generated after this period when the start/restart condition is detected.
 - <R> 2. The maximum value (MAX.) of $t_{HD:DAT}$ is during normal transfer and a wait state is inserted in the ACK (acknowledge) timing.

Caution The values in the above table are applied even when bit 2 (PIOR2) in the peripheral I/O redirection register (PIOR) is 1. At this time, the pin characteristics (I_{OH1} , I_{OL1} , V_{OH1} , V_{OL1}) must satisfy the values in the redirect destination.

Remark The maximum value of C_b (communication line capacitance) and the value of R_b (communication line pull-up resistor) at that time in each mode are as follows.

Standard mode: $C_b = 400 \text{ pF}$, $R_b = 2.7 \text{ k}\Omega$

(2) I²C fast mode $(T_A = -40$ to $+85^\circ\text{C}$, $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCLA0 clock frequency	f _{SCL}	Fast mode: $f_{CLK} \geq 3.5 \text{ MHz}$	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$	0	400	0	400	0	400	kHz
			1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$	0	400	0	400	0	400	kHz
Setup time of restart condition	t _{SU:STA}	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		μs
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		μs
Hold time ^{Note 1}	t _{HD:STA}	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		μs
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		μs
Hold time when SCLA0 = "L"	t _{LOW}	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		1.3		1.3		1.3		μs
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		1.3		1.3		1.3		μs
Hold time when SCLA0 = "H"	t _{HIGH}	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		μs
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		μs
Data setup time (reception)	t _{SU:DAT}	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		100		100		100		μs
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		100		100		100		μs
Data hold time (transmission) ^{Note 2}	t _{HD:DAT}	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0	0.9	0	0.9	0	0.9	μs
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0	0.9	0	0.9	0	0.9	μs
Setup time of stop condition	t _{SU:STO}	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		μs
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		μs
Bus-free time	t _{BUF}	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		1.3		1.3		1.3		μs
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		1.3		1.3		1.3		μs

Notes 1. The first clock pulse is generated after this period when the start/restart condition is detected.

<R> 2. The maximum value (MAX.) of t_{HD:DAT} is during normal transfer and a wait state is inserted in the ACK (acknowledge) timing.

Caution The values in the above table are applied even when bit 2 (PIOR2) in the peripheral I/O redirection register (PIOR) is 1. At this time, the pin characteristics (I_{OH1}, I_{OL1}, V_{OH1}, V_{OL1}) must satisfy the values in the redirect destination.

Remark The maximum value of C_b (communication line capacitance) and the value of R_b (communication line pull-up resistor) at that time in each mode are as follows.

Fast mode: C_b = 320 pF, R_b = 1.1 k Ω

(3) I²C fast mode plus $(T_A = -40$ to $+85^\circ\text{C}$, $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$, $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCLA0 clock frequency	f _{SCL}	Fast mode plus: $f_{CLK} \geq 10 \text{ MHz}$	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$	0	1000	—	—	—	—	kHz
Setup time of restart condition	t _{SU:STA}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.26		—	—	—	—	μs
Hold time ^{Note 1}	t _{HD:STA}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.26		—	—	—	—	μs
Hold time when SCLA0 = "L"	t _{LOW}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.5		—	—	—	—	μs
Hold time when SCLA0 = "H"	t _{HIGH}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.26		—	—	—	—	μs
Data setup time (reception)	t _{SU:DAT}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		50		—	—	—	—	μs
Data hold time (transmission) ^{Note 2}	t _{HD:DAT}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0	0.45	—	—	—	—	μs
Setup time of stop condition	t _{SU:STO}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.26		—	—	—	—	μs
Bus-free time	t _{BUF}	$2.7 \text{ V} \leq EV_{DD0} \leq 5.5 \text{ V}$		0.5		—	—	—	—	μs

Notes 1. The first clock pulse is generated after this period when the start/restart condition is detected.

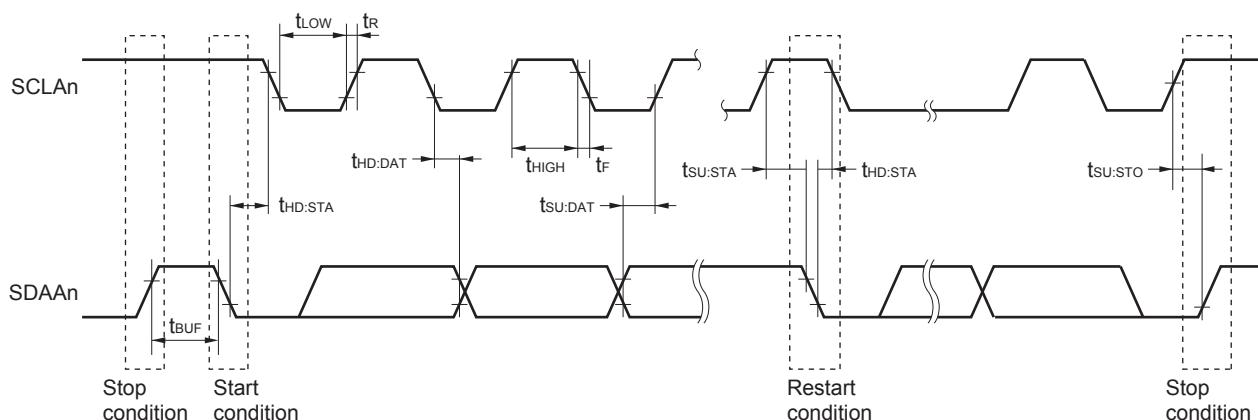
<R> 2. The maximum value (MAX.) of t_{HD:DAT} is during normal transfer and a wait state is inserted in the ACK (acknowledge) timing.

Caution The values in the above table are applied even when bit 2 (PIOR2) in the peripheral I/O redirection register (PIOR) is 1. At this time, the pin characteristics (I_{OH1}, I_{OL1}, V_{OH1}, V_{OL1}) must satisfy the values in the redirect destination.

Remark The maximum value of C_b (communication line capacitance) and the value of R_b (communication line pull-up resistor) at that time in each mode are as follows.

Fast mode plus: C_b = 120 pF, R_b = 1.1 k Ω

IICA serial transfer timing



Remark n = 0, 1

3.3 DC Characteristics

3.3.1 Pin characteristics

(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V) (1/5)

Items	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Output current, high ^{Note 1}	I _{OH1}	Per pin for P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	2.4 V ≤ EV _{DD0} ≤ 5.5 V		-3.0 ^{Note 2}	mA
		Total of P00 to P04, P07, P32 to P37, P40 to P47, P102 to P106, P120, P125 to P127, P130, P140 to P145 (When duty ≤ 70% ^{Note 3})	4.0 V ≤ EV _{DD0} ≤ 5.5 V		-30.0	mA
			2.7 V ≤ EV _{DD0} < 4.0 V		-10.0	mA
			2.4 V ≤ EV _{DD0} < 2.7 V		-5.0	mA
		Total of P05, P06, P10 to P17, P30, P31, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100, P101, P110 to P117, P146, P147 (When duty ≤ 70% ^{Note 3})	4.0 V ≤ EV _{DD0} ≤ 5.5 V		-30.0	mA
			2.7 V ≤ EV _{DD0} < 4.0 V		-19.0	mA
			2.4 V ≤ EV _{DD0} < 2.7 V		-10.0	mA
		Total of all pins (When duty ≤ 70% ^{Note 3})	2.4 V ≤ EV _{DD0} ≤ 5.5 V		-60.0	mA
	I _{OH2}	Per pin for P20 to P27, P150 to P156	2.4 V ≤ V _{DD} ≤ 5.5 V		-0.1 ^{Note 2}	mA
		Total of all pins (When duty ≤ 70% ^{Note 3})	2.4 V ≤ V _{DD} ≤ 5.5 V		-1.5	mA

Notes 1. Value of current at which the device operation is guaranteed even if the current flows from the EV_{DD0}, EV_{DD1}, V_{DD} pins to an output pin.

2. Do not exceed the total current value.

3. Specification under conditions where the duty factor ≤ 70%.

The output current value that has changed to the duty factor > 70% the duty ratio can be calculated with the following expression (when changing the duty factor from 70% to n%).

- Total output current of pins = (I_{OH} × 0.7)/(n × 0.01)

<Example> Where n = 80% and I_{OH} = -10.0 mA

$$\text{Total output current of pins} = (-10.0 \times 0.7)/(80 \times 0.01) \approx -8.7 \text{ mA}$$

However, the current that is allowed to flow into one pin does not vary depending on the duty factor.

A current higher than the absolute maximum rating must not flow into one pin.

Caution P00, P02 to P04, P10 to P15, P17, P43 to P45, P50, P52 to P55, P71, P74, P80 to P82, P96, and P142 to P144 do not output high level in N-ch open-drain mode.

Remark Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

5. The smaller maximum transfer rate derived by using $f_{MCK}/12$ or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when $2.4 \text{ V} \leq EV_{DD0} < 3.3 \text{ V}$ and $1.6 \text{ V} \leq V_b \leq 2.0 \text{ V}$

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{1.5}{V_b})\} \times 3} \text{ [bps]}$$

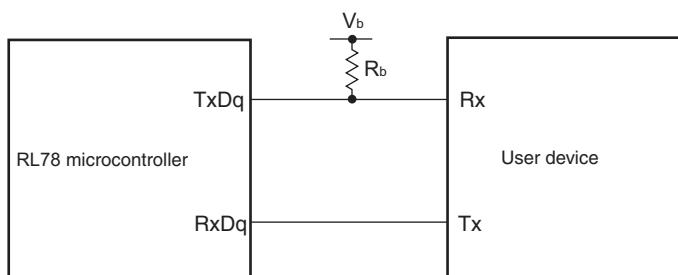
$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{1.5}{V_b})\}}{\left(\frac{1}{\text{Transfer rate}}\right) \times \text{Number of transferred bits}} \times 100 \text{ [%]}$$

* This value is the theoretical value of the relative difference between the transmission and reception sides.

6. This value as an example is calculated when the conditions described in the “Conditions” column are met. Refer to Note 5 above to calculate the maximum transfer rate under conditions of the customer.

Caution Select the TTL input buffer for the RxDq pin and the N-ch open drain output (V_{DD} tolerance (for the 20- to 52-pin products)/ EV_{DD} tolerance (for the 64- to 100-pin products)) mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg). For V_{IH} and V_{IL} , see the DC characteristics with TTL input buffer selected.

UART mode connection diagram (during communication at different potential)



(4) When reference voltage (+) = Internal reference voltage (ADREFP1 = 1, ADREFP0 = 0), reference voltage (-) = AV_{REFM}/ANI1 (ADREFM = 1), target pin : ANI0, ANI2 to ANI14, ANI16 to ANI26

(TA = -40 to +105°C, 2.4 V ≤ EV_{DD0} = EV_{DD1} ≤ V_{DD} ≤ 5.5 V, V_{SS} = EV_{SS0} = EV_{SS1} = 0 V, Reference voltage (+) = V_{BGR}^{Note 3}, Reference voltage (-) = AV_{REFM}^{Note 4} = 0 V, HS (high-speed main) mode)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Resolution	RES			8		bit	
Conversion time	t _{CONV}	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V	17		39	μs
Zero-scale error ^{Notes 1, 2}	E _{Zs}	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V			±0.60	%FSR
Integral linearity error ^{Note 1}	ILE	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V			±2.0	LSB
Differential linearity error ^{Note 1}	DLE	8-bit resolution	2.4 V ≤ V _{DD} ≤ 5.5 V			±1.0	LSB
Analog input voltage	V _{AIN}			0		V _{BGR} ^{Note 3}	V

Notes 1. Excludes quantization error (±1/2 LSB).

2. This value is indicated as a ratio (%FSR) to the full-scale value.

3. Refer to 3.6.2 Temperature sensor/internal reference voltage characteristics.

4. When reference voltage (-) = V_{SS}, the MAX. values are as follows.

Zero-scale error: Add ±0.35%FSR to the MAX. value when reference voltage (-) = AV_{REFM}.

Integral linearity error: Add ±0.5 LSB to the MAX. value when reference voltage (-) = AV_{REFM}.

Differential linearity error: Add ±0.2 LSB to the MAX. value when reference voltage (-) = AV_{REFM}.

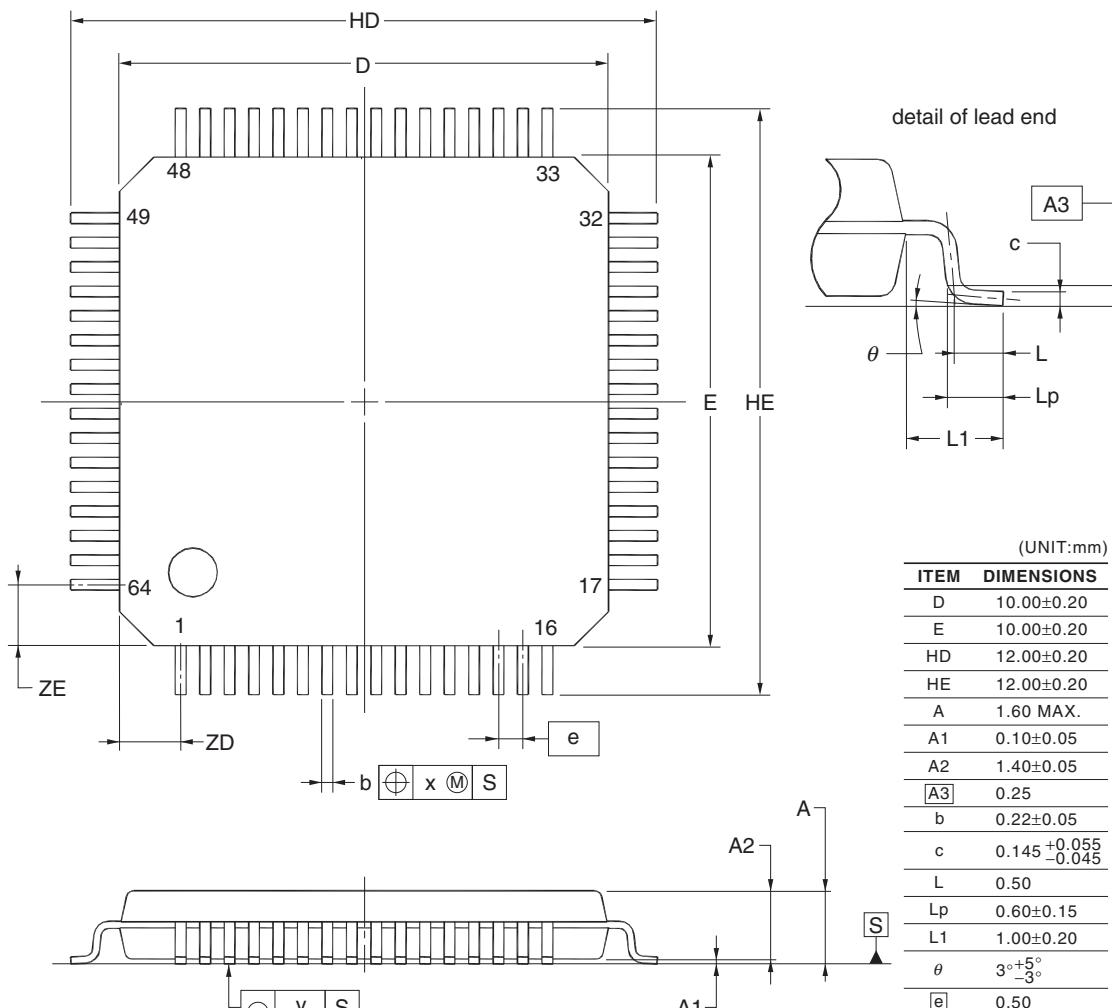
3.6.2 Temperature sensor/internal reference voltage characteristics

(TA = -40 to +105°C, 2.4 V ≤ V_{DD} ≤ 5.5 V, V_{SS} = 0 V, HS (high-speed main) mode)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Temperature sensor output voltage	V _{TMP25}	Setting ADS register = 80H, TA = +25°C		1.05		V
Internal reference voltage	V _{BGR}	Setting ADS register = 81H	1.38	1.45	1.5	V
Temperature coefficient	F _{VTMP5}	Temperature sensor that depends on the temperature		-3.6		mV/°C
Operation stabilization wait time	t _{AMP}		5			μs

R5F100LCAF, R5F100LDAFB, R5F100LEAFB, R5F100LFAFB, R5F100LGAFB, R5F100LHAFB, R5F100LJAFB,
 R5F100LKAFB, R5F100LLAFB
 R5F101LCAF, R5F101LDAFB, R5F101LEAFB, R5F101LFAFB, R5F101LGAFB, R5F101LHAFB,
 R5F101LJAFB, R5F101LKAFB, R5F101LLAFB
 R5F100LCDFB, R5F100LDDFB, R5F100LEDFB, R5F100LFDFB, R5F100LGDFB, R5F100LHDFB, R5F100LJDFB,
 R5F100LKDFB, R5F100LLDFB
 R5F101LCDFB, R5F101LDDFB, R5F101LEDFB, R5F101LFDFB, R5F101LGDFB, R5F101LHDFB,
 R5F101LJDFB, R5F101LKDFB, R5F101LLDFB
 R5F100LCGFB, R5F100LDGFB, R5F100LEGFB, R5F100LFGFB, R5F100LGGFB, R5F100LHGFB,
 R5F100LJGFB

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LFQFP64-10x10-0.50	PLQP0064KF-A	P64GB-50-UEU-2	0.35

**NOTE**

Each lead centerline is located within 0.08 mm of its true position at maximum material condition.

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