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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I <sup>2</sup> C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	34
Program Memory Size	48KB (48K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	3K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 10x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LFQFP (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f101gddfb-50">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f101gddfb-50</a>



Table 1-1. List of Ordering Part Numbers

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Pin count	Package	Data flash	Fields of Application Note	Ordering Part Number
25 pins	25-pin plastic WFLGA (3 × 3 mm, 0.5 mm pitch)	Mounted	A   G	R5F1008AALA#U0, R5F1008CALA#U0, R5F1008DALA#U0, R5F1008EALA#U0 R5F1008AALA#W0, R5F1008CALA#W0, R5F1008DALA#W0, R5F1008EALA#W0 R5F1008AGLA#U0, R5F1008CGLA#U0, R5F1008DGLA#U0, R5F1008EGLA#U0 R5F1008AGLA#W0, R5F1008CGLA#W0, R5F1008DGLA#W0, R5F1008EGLA#W0
		Not mounted	A	R5F1018AALA#U0, R5F1018CALA#U0, R5F1018DALA#U0, R5F1018EALA#U0 R5F1018AALA#W0, R5F1018CALA#W0, R5F1018DALA#W0, R5F1018EALA#W0
30 pins	30-pin plastic LSSOP (7.62 mm (300), 0.65 mm pitch)	Mounted	A  D  G	R5F100AAASP#V0, R5F100ACASP#V0, R5F100ADASP#V0, R5F100AEASP#V0, R5F100AFASP#V0, R5F100AGASP#V0 R5F100AAASP#X0, R5F100ACASP#X0, R5F100ADASP#X0, R5F100AEASP#X0, R5F100AFASP#X0, R5F100AGASP#X0 R5F100AADSP#V0, R5F100ACDSP#V0, R5F100ADDSP#V0, R5F100AEDSP#V0, R5F100AFDSP#V0, R5F100AGDSP#V0 R5F100AADSP#X0, R5F100ACDSP#X0, R5F100ADDSP#X0, R5F100AEDSP#X0, R5F100AFDSP#X0, R5F100AGDSP#X0 R5F100AAGSP#V0, R5F100ACGSP#V0, R5F100ADGSP#V0, R5F100AEGSP#V0, R5F100AFGSP#V0, R5F100AGGSP#V0 R5F100AAGSP#X0, R5F100ACGSP#X0, R5F100ADGSP#X0, R5F100AEGSP#X0, R5F100AFGSP#X0, R5F100AGGSP#X0
		Not mounted	A  D	R5F101AAASP#V0, R5F101ACASP#V0, R5F101ADASP#V0, R5F101AEASP#V0, R5F101AFASP#V0, R5F101AGASP#V0 R5F101AAASP#X0, R5F101ACASP#X0, R5F101ADASP#X0, R5F101AEASP#X0, R5F101AFASP#X0, R5F101AGASP#X0 R5F101AADSP#V0, R5F101ACDSP#V0, R5F101ADDSP#V0, R5F101AEDSP#V0, R5F101AFDSP#V0, R5F101AGDSP#V0 R5F101AADSP#X0, R5F101ACDSP#X0, R5F101ADDSP#X0, R5F101AEDSP#X0, R5F101AFDSP#X0, R5F101AGDSP#X0
32 pins	32-pin plastic HWQFN (5 × 5 mm, 0.5 mm pitch)	Mounted	A  D  G	R5F100BAANA#U0, R5F100BCANA#U0, R5F100BDANA#U0, R5F100BEANA#U0, R5F100BFANA#U0, R5F100BGANA#U0 R5F100BAANA#W0, R5F100BCANA#W0, R5F100BDANA#W0, R5F100BEANA#W0, R5F100BFANA#W0, R5F100BGANA#W0 R5F100BADNA#U0, R5F100BCDNA#U0, R5F100BDDNA#U0, R5F100BEDNA#U0, R5F100BFDNA#U0, R5F100BGDNA#U0 R5F100BADNA#W0, R5F100BCDNA#W0, R5F100BDDNA#W0, R5F100BEDNA#W0, R5F100BFDNA#W0, R5F100BGDNA#W0 R5F100BAGNA#U0, R5F100BCGNA#U0, R5F100BDGNA#U0, R5F100BEGNA#U0, R5F100BFGNA#U0, R5F100BGGNA#U0 R5F100BAGNA#W0, R5F100BCGNA#W0, R5F100BDGNA#W0, R5F100BEGNA#W0, R5F100BFGNA#W0, R5F100BGGNA#W0
		Not mounted	A  D	R5F101BAANA#U0, R5F101BCANA#U0, R5F101BDANA#U0, R5F101BEANA#U0, R5F101BFANA#U0, R5F101BGANA#U0 R5F101BAANA#W0, R5F101BCANA#W0, R5F101BDANA#W0, R5F101BEANA#W0, R5F101BFANA#W0, R5F101BGANA#W0 R5F101BADNA#U0, R5F101BCDNA#U0, R5F101BDDNA#U0, R5F101BEDNA#U0, R5F101BFDNA#U0, R5F101BGDNA#U0 R5F101BADNA#W0, R5F101BCDNA#W0, R5F101BDDNA#W0, R5F101BEDNA#W0, R5F101BFDNA#W0, R5F101BGDNA#W0

**Note** For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

**Caution** The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.



Table 1-1. List of Ordering Part Numbers

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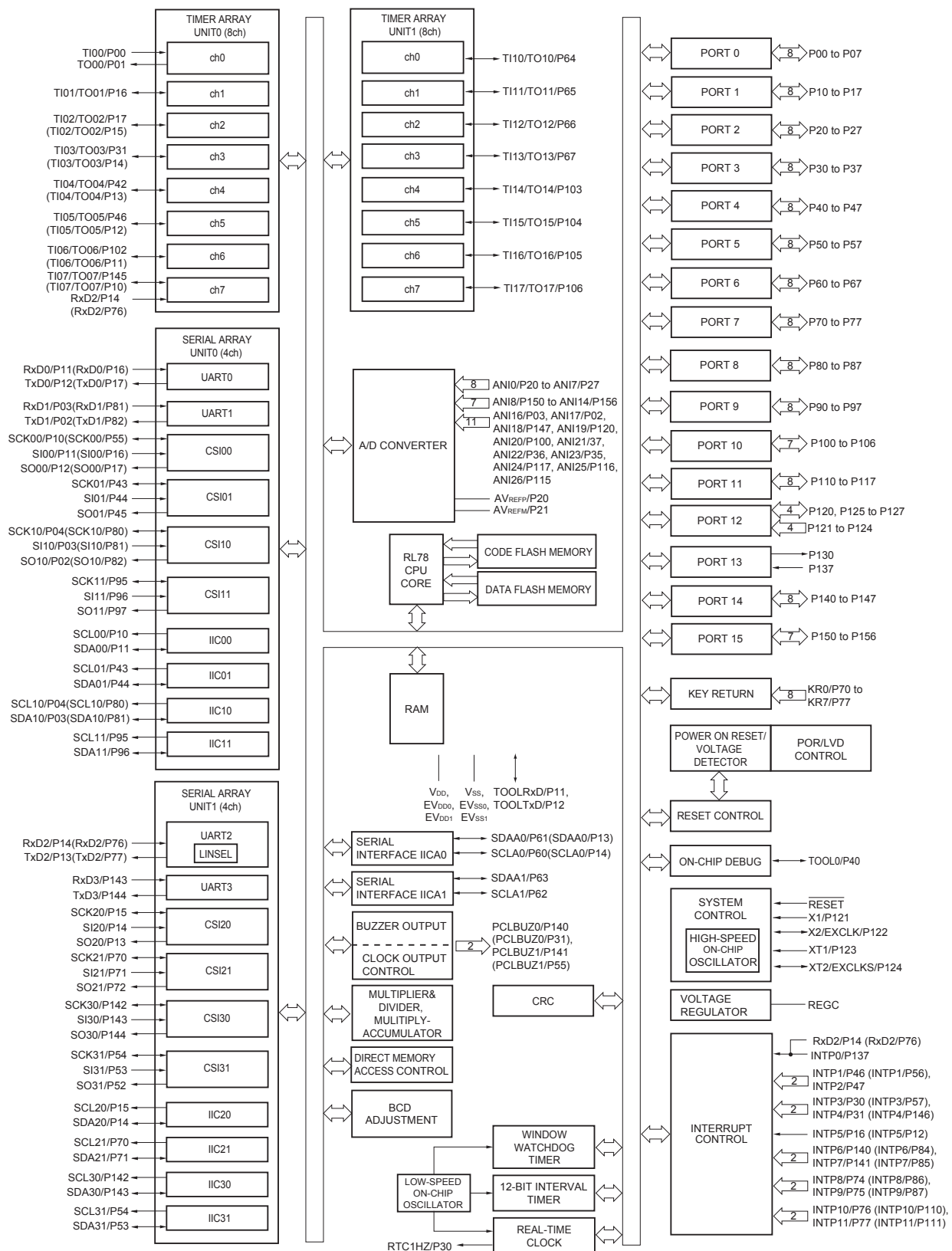
Pin count	Package	Data flash	Fields of Application Note	Ordering Part Number
48 pins	48-pin plastic LFQFP (7 × 7 mm, 0.5 mm pitch)	Mounted	A	R5F100GAAFB#V0, R5F100GCAFB#V0, R5F100GDAFB#V0, R5F100GEAFB#V0, R5F100GFAFB#V0, R5F100GGAFB#V0, R5F100GHAFB#V0, R5F100GJAFB#V0, R5F100GKAFB#V0, R5F100GLAFB#V0 R5F100GAAFB#X0, R5F100GCAFB#X0, R5F100GDAFB#X0, R5F100GEAFB#X0, R5F100GFAFB#X0, R5F100GGAFB#X0, R5F100GHAFB#X0, R5F100GJAFB#X0, R5F100GKAFB#X0, R5F100GLAFB#X0
			D	R5F100GADFB#V0, R5F100GCDFB#V0, R5F100GDDFB#V0, R5F100GEDFB#V0, R5F100GFDFB#V0, R5F100GGDFB#V0, R5F100GHDFB#V0, R5F100GJDFB#V0, R5F100GKDFB#V0, R5F100GLDFB#V0 R5F100GADFB#X0, R5F100GCDFB#X0, R5F100GDDFB#X0, R5F100GEDFB#X0, R5F100GFDFB#X0, R5F100GGDFB#X0, R5F100GHDFB#X0, R5F100GJDFB#X0, R5F100GKDFB#X0, R5F100GLDFB#X0
			G	R5F100GAGFB#V0, R5F100GCGFB#V0, R5F100GDGFB#V0, R5F100GEGFB#V0, R5F100GFGFB#V0, R5F100GGGFB#V0, R5F100GHGFB#V0, R5F100GJGFB#V0 R5F100GAGFB#X0, R5F100GCGFB#X0, R5F100GDGFB#X0, R5F100GEGFB#X0, R5F100GFGFB#X0, R5F100GGGFB#X0, R5F100GHGFB#X0, R5F100GJGFB#X0
		Not mounted	A	R5F101GAAFB#V0, R5F101GCAFB#V0, R5F101GDAFB#V0, R5F101GEAFB#V0, R5F101GFAFB#V0, R5F101GGAFB#V0, R5F101GHAFB#V0, R5F101GJAFB#V0, R5F101GKAFB#V0, R5F101GLAFB#V0 R5F101GAAFB#X0, R5F101GCAFB#X0, R5F101GDAFB#X0, R5F101GEAFB#X0, R5F101GFAFB#X0, R5F101GGAFB#X0, R5F101GHAFB#X0, R5F101GJAFB#X0, R5F101GKAFB#X0, R5F101GLAFB#X0
			D	R5F101GADFB#V0, R5F101GCDFB#V0, R5F101GDDFB#V0, R5F101GEDFB#V0, R5F101GFDFB#V0, R5F101GGDFB#V0, R5F101GHDFB#V0, R5F101GJDFB#V0, R5F101GKDFB#V0, R5F101GLDFB#V0 R5F101GADFB#X0, R5F101GCDFB#X0, R5F101GDDFB#X0, R5F101GEDFB#X0, R5F101GFDFB#X0, R5F101GGDFB#X0, R5F101GHDFB#X0, R5F101GJDFB#X0, R5F101GKDFB#X0, R5F101GLDFB#X0

**Note** For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

**Caution** The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.



## 1.5.14 128-pin products



**Remark** Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.



[80-pin, 100-pin, 128-pin products]

**Caution** This outline describes the functions at the time when Peripheral I/O redirection register (PIOR) is set to 00H.

(1/2)

Item		80-pin		100-pin		128-pin	
		R5F100Mx	R5F101Mx	R5F100Px	R5F101Px	R5F100Sx	R5F101Sx
Code flash memory (KB)		96 to 512		96 to 512		192 to 512	
Data flash memory (KB)		8	—	8	—	8	—
RAM (KB)		8 to 32 <sup>Note 1</sup>		8 to 32 <sup>Note 1</sup>		16 to 32 <sup>Note 1</sup>	
Address space		1 MB					
Main system clock	High-speed system clock	X1 (crystal/ceramic) oscillation, external main system clock input (EXCLK) HS (High-speed main) mode: 1 to 20 MHz (V <sub>DD</sub> = 2.7 to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz (V <sub>DD</sub> = 2.4 to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz (V <sub>DD</sub> = 1.8 to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz (V <sub>DD</sub> = 1.6 to 5.5 V)					
	High-speed on-chip oscillator	HS (High-speed main) mode: 1 to 32 MHz (V <sub>DD</sub> = 2.7 to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz (V <sub>DD</sub> = 2.4 to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz (V <sub>DD</sub> = 1.8 to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz (V <sub>DD</sub> = 1.6 to 5.5 V)					
Subsystem clock		XT1 (crystal) oscillation, external subsystem clock input (EXCLKS) 32.768 kHz					
Low-speed on-chip oscillator		15 kHz (TYP.)					
General-purpose register		(8-bit register × 8) × 4 banks					
Minimum instruction execution time		0.03125 μs (High-speed on-chip oscillator: f <sub>IH</sub> = 32 MHz operation)					
		0.05 μs (High-speed system clock: f <sub>MX</sub> = 20 MHz operation)					
		30.5 μs (Subsystem clock: f <sub>SUB</sub> = 32.768 kHz operation)					
Instruction set		<ul style="list-style-type: none"><li>• Data transfer (8/16 bits)</li><li>• Adder and subtractor/logical operation (8/16 bits)</li><li>• Multiplication (8 bits × 8 bits)</li><li>• Rotate, barrel shift, and bit manipulation (Set, reset, test, and Boolean operation), etc.</li></ul>					
I/O port	Total	74		92		120	
	CMOS I/O	64 (N-ch O.D. I/O [EVD <sub>D</sub> withstand voltage]: 21)		82 (N-ch O.D. I/O [EVD <sub>D</sub> withstand voltage]: 24)		110 (N-ch O.D. I/O [EVD <sub>D</sub> withstand voltage]: 25)	
	CMOS input	5		5		5	
	CMOS output	1		1		1	
	N-ch O.D. I/O (withstand voltage: 6 V)	4		4		4	
Timer	16-bit timer	12 channels		12 channels		16 channels	
	Watchdog timer	1 channel		1 channel		1 channel	
	Real-time clock (RTC)	1 channel		1 channel		1 channel	
	12-bit interval timer (IT)	1 channel		1 channel		1 channel	
	Timer output	12 channels (PWM outputs: 10 <sup>Note 2</sup> )		12 channels (PWM outputs: 10 <sup>Note 2</sup> )		16 channels (PWM outputs: 14 <sup>Note 2</sup> )	
	RTC output	1 channel • 1 Hz (subsystem clock: f <sub>SUB</sub> = 32.768 kHz)					

**Notes 1.** The flash library uses RAM in self-programming and rewriting of the data flash memory.

The target products and start address of the RAM areas used by the flash library are shown below.

R5F100xJ, R5F101xJ (x = M, P): Start address FAF00H

R5F100xL, R5F101xL (x = M, P, S): Start address F7F00H

For the RAM areas used by the flash library, see **Self RAM list of Flash Self-Programming Library for RL78 Family (R20UT2944)**.



## 2.2 Oscillator Characteristics

### 2.2.1 X1, XT1 oscillator characteristics

(T<sub>A</sub> = -40 to +85°C, 1.6 V ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = 0 V)

Parameter	Resonator	Conditions	MIN.	TYP.	MAX.	Unit
X1 clock oscillation frequency (f <sub>x</sub> ) <sup>Note</sup>	Ceramic resonator/ crystal resonator	2.7 V ≤ V <sub>DD</sub> ≤ 5.5 V	1.0		20.0	MHz
		2.4 V ≤ V <sub>DD</sub> < 2.7 V	1.0		16.0	MHz
		1.8 V ≤ V <sub>DD</sub> < 2.4 V	1.0		8.0	MHz
		1.6 V ≤ V <sub>DD</sub> < 1.8 V	1.0		4.0	MHz
XT1 clock oscillation frequency (f <sub>x</sub> ) <sup>Note</sup>	Crystal resonator		32	32.768	35	kHz

**Note** Indicates only permissible oscillator frequency ranges. Refer to AC Characteristics for instruction execution time. Request evaluation by the manufacturer of the oscillator circuit mounted on a board to check the oscillator characteristics.

**Caution** Since the CPU is started by the high-speed on-chip oscillator clock after a reset release, check the X1 clock oscillation stabilization time using the oscillation stabilization time counter status register (OSTC) by the user. Determine the oscillation stabilization time of the OSTC register and the oscillation stabilization time select register (OSTS) after sufficiently evaluating the oscillation stabilization time with the resonator to be used.

**Remark** When using the X1 oscillator and XT1 oscillator, refer to 5.4 System Clock Oscillator.

### 2.2.2 On-chip oscillator characteristics

(T<sub>A</sub> = -40 to +85°C, 1.6 V ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = 0 V)

Oscillators	Parameters	Conditions		MIN.	TYP.	MAX.	Unit
High-speed on-chip oscillator clock frequency <sup>Notes 1, 2</sup>	f <sub>IH</sub>			1		32	MHz
High-speed on-chip oscillator clock frequency accuracy		-20 to +85 °C	1.8 V ≤ V <sub>DD</sub> ≤ 5.5 V	-1.0		+1.0	%
			1.6 V ≤ V <sub>DD</sub> < 1.8 V	-5.0		+5.0	%
		-40 to -20 °C	1.8 V ≤ V <sub>DD</sub> ≤ 5.5 V	-1.5		+1.5	%
			1.6 V ≤ V <sub>DD</sub> < 1.8 V	-5.5		+5.5	%
Low-speed on-chip oscillator clock frequency	f <sub>IL</sub>				15		kHz
Low-speed on-chip oscillator clock frequency accuracy				-15		+15	%

**Notes 1.** High-speed on-chip oscillator frequency is selected by bits 0 to 3 of option byte (000C2H/010C2H) and bits 0 to 2 of HOCODIV register.

**2.** This indicates the oscillator characteristics only. Refer to AC Characteristics for instruction execution time.



**(3) 128-pin products, and flash ROM: 384 to 512 KB of 44- to 100-pin products****(T<sub>A</sub> = -40 to +85°C, 1.6 V ≤ E<sub>VDD0</sub> = E<sub>VDD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = E<sub>VSS0</sub> = E<sub>VSS1</sub> = 0 V) (1/2)**

Parameter	Symbol	Conditions				MIN.	TYP.	MAX.	Unit
Supply current <sup>Note 1</sup>	I <sub>DD1</sub>	Operating mode	HS (high-speed main) mode <sup>Note 5</sup>	f <sub>IH</sub> = 32 MHz <sup>Note 3</sup>	Basic operation	V <sub>DD</sub> = 5.0 V		2.6	mA
						V <sub>DD</sub> = 3.0 V		2.6	mA
					Normal operation	V <sub>DD</sub> = 5.0 V		6.1	mA
						V <sub>DD</sub> = 3.0 V		6.1	mA
				f <sub>IH</sub> = 24 MHz <sup>Note 3</sup>	Normal operation	V <sub>DD</sub> = 5.0 V		4.8	mA
						V <sub>DD</sub> = 3.0 V		4.8	mA
				f <sub>IH</sub> = 16 MHz <sup>Note 3</sup>	Normal operation	V <sub>DD</sub> = 5.0 V		3.5	mA
						V <sub>DD</sub> = 3.0 V		3.5	mA
			LS (low-speed main) mode <sup>Note 5</sup>	f <sub>IH</sub> = 8 MHz <sup>Note 3</sup>	Normal operation	V <sub>DD</sub> = 3.0 V		1.5	mA
						V <sub>DD</sub> = 2.0 V		1.5	mA
			LV (low-voltage main) mode <sup>Note 5</sup>	f <sub>IH</sub> = 4 MHz <sup>Note 3</sup>	Normal operation	V <sub>DD</sub> = 3.0 V		1.5	mA
						V <sub>DD</sub> = 2.0 V		1.5	mA
			HS (high-speed main) mode <sup>Note 5</sup>	f <sub>MX</sub> = 20 MHz <sup>Note 2</sup> , V <sub>DD</sub> = 5.0 V	Normal operation	Square wave input		3.9	mA
						Resonator connection		4.1	mA
				f <sub>MX</sub> = 20 MHz <sup>Note 2</sup> , V <sub>DD</sub> = 3.0 V	Normal operation	Square wave input		3.9	mA
						Resonator connection		4.1	mA
				f <sub>MX</sub> = 10 MHz <sup>Note 2</sup> , V <sub>DD</sub> = 5.0 V	Normal operation	Square wave input		2.5	mA
						Resonator connection		2.5	mA
				f <sub>MX</sub> = 10 MHz <sup>Note 2</sup> , V <sub>DD</sub> = 3.0 V	Normal operation	Square wave input		2.5	mA
						Resonator connection		2.5	mA
			LS (low-speed main) mode <sup>Note 5</sup>	f <sub>MX</sub> = 8 MHz <sup>Note 2</sup> , V <sub>DD</sub> = 3.0 V	Normal operation	Square wave input		1.4	mA
						Resonator connection		1.4	mA
				f <sub>MX</sub> = 8 MHz <sup>Note 2</sup> , V <sub>DD</sub> = 2.0 V	Normal operation	Square wave input		1.4	mA
						Resonator connection		1.4	mA
			Subsystem clock operation	f <sub>SUB</sub> = 32.768 kHz <sup>Note 4</sup> T <sub>A</sub> = -40°C	Normal operation	Square wave input		5.4	μA
						Resonator connection		5.5	μA
				f <sub>SUB</sub> = 32.768 kHz <sup>Note 4</sup> T <sub>A</sub> = +25°C	Normal operation	Square wave input		5.5	μA
						Resonator connection		5.6	μA
				f <sub>SUB</sub> = 32.768 kHz <sup>Note 4</sup> T <sub>A</sub> = +50°C	Normal operation	Square wave input		5.6	μA
						Resonator connection		5.7	μA
				f <sub>SUB</sub> = 32.768 kHz <sup>Note 4</sup> T <sub>A</sub> = +70°C	Normal operation	Square wave input		5.9	μA
						Resonator connection		6.0	μA
				f <sub>SUB</sub> = 32.768 kHz <sup>Note 4</sup> T <sub>A</sub> = +85°C	Normal operation	Square wave input		6.6	μA
						Resonator connection		6.7	μA

(Notes and Remarks are listed on the next page.)



- Notes**
1. Total current flowing into  $V_{DD}$ ,  $EV_{DD0}$ , and  $EV_{DD1}$ , including the input leakage current flowing when the level of the input pin is fixed to  $V_{DD}$ ,  $EV_{DD0}$ , and  $EV_{DD1}$ , or  $V_{SS}$ ,  $EV_{SS0}$ , and  $EV_{SS1}$ . The values below the MAX. column include the peripheral operation current. However, not including the current flowing into the A/D converter, LVD circuit, I/O port, and on-chip pull-up/pull-down resistors and the current flowing during data flash rewrite.
  2. During HALT instruction execution by flash memory.
  3. When high-speed on-chip oscillator and subsystem clock are stopped.
  4. When high-speed system clock and subsystem clock are stopped.
  5. When high-speed on-chip oscillator and high-speed system clock are stopped. When  $RTCLPC = 1$  and setting ultra-low current consumption ( $AMPHS1 = 1$ ). The current flowing into the RTC is included. However, not including the current flowing into the 12-bit interval timer and watchdog timer.
  6. Not including the current flowing into the RTC, 12-bit interval timer, and watchdog timer.
  7. Relationship between operation voltage width, operation frequency of CPU and operation mode is as below.
    - HS (high-speed main) mode:  $2.7\text{ V} \leq V_{DD} \leq 5.5\text{ V}$  @ 1 MHz to 32 MHz  
 $2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}$  @ 1 MHz to 16 MHz
    - LS (low-speed main) mode:  $1.8\text{ V} \leq V_{DD} \leq 5.5\text{ V}$  @ 1 MHz to 8 MHz
    - LV (low-voltage main) mode:  $1.6\text{ V} \leq V_{DD} \leq 5.5\text{ V}$  @ 1 MHz to 4 MHz
  8. Regarding the value for current to operate the subsystem clock in STOP mode, refer to that in HALT mode.

- Remarks 1.** f<sub>MX</sub>: High-speed system clock frequency (X1 clock oscillation frequency or external main system clock frequency)
2. f<sub>IH</sub>: High-speed on-chip oscillator clock frequency
3. f<sub>SUB</sub>: Subsystem clock frequency (XT1 clock oscillation frequency)
4. Except subsystem clock operation and STOP mode, temperature condition of the TYP. value is T<sub>A</sub> = 25°C



## (3) During communication at same potential (CSI mode) (master mode, SCKp... internal clock output)

(T<sub>A</sub> = -40 to +85°C, 1.6 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCKp cycle time	t <sub>KCY1</sub>	t <sub>KCY1</sub> ≥ 4/f <sub>CLK</sub>	2.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	125		500		1000		ns
			2.4 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	250		500		1000		ns
			1.8 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	500		500		1000		ns
			1.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	1000		1000		1000		ns
			1.6 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	—		1000		1000		ns
SCKp high-/low-level width	t <sub>KH1</sub> , t <sub>KL1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		t <sub>KCY1</sub> /2 – 12		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		ns
		2.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		t <sub>KCY1</sub> /2 – 18		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		ns
		2.4 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		t <sub>KCY1</sub> /2 – 38		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		ns
		1.8 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		ns
		1.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		t <sub>KCY1</sub> /2 – 100		t <sub>KCY1</sub> /2 – 100		t <sub>KCY1</sub> /2 – 100		ns
		1.6 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		—		t <sub>KCY1</sub> /2 – 100		t <sub>KCY1</sub> /2 – 100		ns
Slp setup time (to SCKp↑) <small>Note 1</small>	t <sub>SIK1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		44		110		110		ns
		2.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		44		110		110		ns
		2.4 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		75		110		110		ns
		1.8 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		110		110		110		ns
		1.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		220		220		220		ns
		1.6 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		—		220		220		ns
Slp hold time (from SCKp↑) <small>Note 2</small>	t <sub>KSI1</sub>	1.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		19		19		19		ns
		1.6 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		—		19		19		ns
Delay time from SCKp↓ to SOp output <small>Note 3</small>	t <sub>KSO1</sub>	1.7 V ≤ EV <sub>DD0</sub> ≤ 5.5 V C = 30 pF <small>Note 4</small>			25		25		25	ns
		1.6 V ≤ EV <sub>DD0</sub> ≤ 5.5 V C = 30 pF <small>Note 4</small>			—		25		25	ns

- Notes**
1. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp setup time becomes “to SCKp↓” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
  2. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp hold time becomes “from SCKp↓” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
  3. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The delay time to SOp output becomes “from SCKp↑” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
  4. C is the load capacitance of the SCKp and SOp output lines.

**Caution** Select the normal input buffer for the Slp pin and the normal output mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg).



**(6) Communication at different potential (1.8 V, 2.5 V, 3 V) (UART mode) (2/2)****(T<sub>A</sub> = -40 to +85°C, 1.8 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V)**

Parameter	Symbol	Conditions		HS (high-speed main)		LS (low-speed main)		LV (low-voltage main)		Unit	
				Mode		Mode		Mode			
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Transfer rate		Transmission	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V			Note 1		Note 1		Note 1	bps
						2.8 Note 2		2.8 Note 2		2.8 Note 2	Mbps
			2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V			Note 3		Note 3		Note 3	bps
						1.2 Note 4		1.2 Note 4		1.2 Note 4	Mbps
			1.8 V ≤ EV <sub>DD0</sub> < 3.3 V, 1.6 V ≤ V <sub>b</sub> ≤ 2.0 V			Notes 5, 6		Notes 5, 6		Notes 5, 6	bps
						0.43 Note 7		0.43 Note 7		0.43 Note 7	Mbps



3. The smaller maximum transfer rate derived by using f<sub>MCK</sub>/6 or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when 2.7 V ≤ EV<sub>DD0</sub> < 4.0 V and 2.3 V ≤ V<sub>b</sub> ≤ 2.7 V

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{2.0}{V_b})\} \times 3} \text{ [bps]}$$

$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{2.0}{V_b})\}}{(\frac{1}{\text{Transfer rate}}) \times \text{Number of transferred bits}} \times 100 \text{ [%]}$$

\* This value is the theoretical value of the relative difference between the transmission and reception sides.

4. This value as an example is calculated when the conditions described in the “Conditions” column are met. Refer to Note 3 above to calculate the maximum transfer rate under conditions of the customer.
5. Use it with EV<sub>DD0</sub> ≥ V<sub>b</sub>.
6. The smaller maximum transfer rate derived by using f<sub>MCK</sub>/6 or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when 1.8 V ≤ EV<sub>DD0</sub> < 3.3 V and 1.6 V ≤ V<sub>b</sub> ≤ 2.0 V

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{1.5}{V_b})\} \times 3} \text{ [bps]}$$

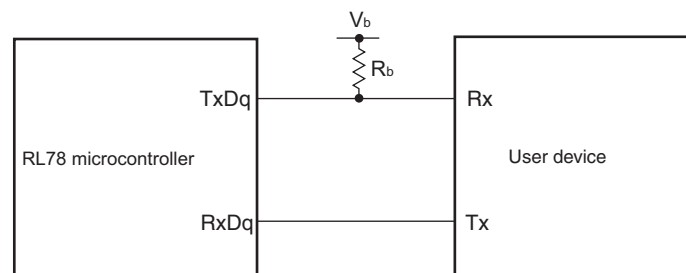
$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{1.5}{V_b})\}}{(\frac{1}{\text{Transfer rate}}) \times \text{Number of transferred bits}} \times 100 \text{ [%]}$$

\* This value is the theoretical value of the relative difference between the transmission and reception sides.

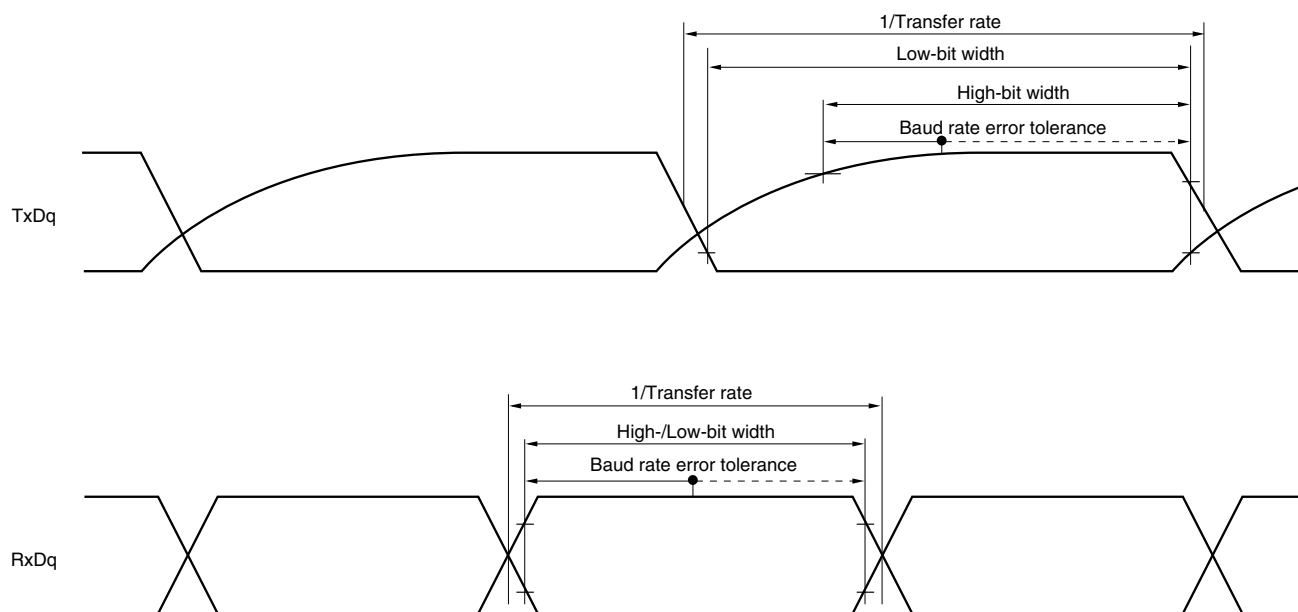
7. This value as an example is calculated when the conditions described in the “Conditions” column are met. Refer to Note 6 above to calculate the maximum transfer rate under conditions of the customer.

**Caution** Select the TTL input buffer for the Rx<sub>Dq</sub> pin and the N-ch open drain output (V<sub>DD</sub> tolerance (When 20- to 52-pin products)/EV<sub>DD</sub> tolerance (When 64- to 128-pin products)) mode for the Tx<sub>Dq</sub> pin by using port input mode register g (PIMg) and port output mode register g (POMg). For V<sub>IH</sub> and V<sub>IL</sub>, see the DC characteristics with TTL input buffer selected.

UART mode connection diagram (during communication at different potential)





**UART mode bit width (during communication at different potential) (reference)**

- Remarks**
1.  $R_b[\Omega]$ : Communication line (TxDq) pull-up resistance,  
 $C_b[\text{F}]$ : Communication line (TxDq) load capacitance,  $V_b[\text{V}]$ : Communication line voltage
  2. q: UART number (q = 0 to 3), g: PIM and POM number (g = 0, 1, 8, 14)
  3.  $f_{\text{MCK}}$ : Serial array unit operation clock frequency  
 (Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn).  
 m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13))
  4. UART2 cannot communicate at different potential when bit 1 (PIOR1) of peripheral I/O redirection register (PIOR) is 1.



## (7) Communication at different potential (2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock output, corresponding CSI00 only) (1/2)

(T<sub>A</sub> = -40 to +85°C, 2.7 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V)

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCKp cycle time	t <sub>KCY1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	200		1150		1150		ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	300		1150		1150		ns
SCKp high-level width	t <sub>KH1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	t <sub>KCY1</sub> /2 – 120		t <sub>KCY1</sub> /2 – 120		t <sub>KCY1</sub> /2 – 120		ns
SCKp low-level width	t <sub>KL1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	t <sub>KCY1</sub> /2 – 7		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	t <sub>KCY1</sub> /2 – 10		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		ns
Slp setup time (to SCKp↑) <sup>Note 1</sup>	t <sub>SIK1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	58		479		479		ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	121		479		479		ns
Slp hold time (from SCKp↑) <sup>Note 1</sup>	t <sub>SH1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	10		10		10		ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	10		10		10		ns
Delay time from SCKp↓ to SOp output <sup>Note 1</sup>	t <sub>KSO1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ		60		60		60	ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ		130		130		130	ns

(Notes, Caution, and Remarks are listed on the next page.)



(2) When reference voltage (+) = AV<sub>REFP</sub>/ANI0 (ADREFP1 = 0, ADREFP0 = 1), reference voltage (-) = AV<sub>REFM</sub>/ANI1 (ADREFM = 1), target pin : ANI16 to ANI26

(T<sub>A</sub> = -40 to +85°C, 1.6 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, 1.6 V ≤ AV<sub>REFP</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V, Reference voltage (+) = AV<sub>REFP</sub>, Reference voltage (-) = AV<sub>REFM</sub> = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Resolution	RES		8		10	bit
Overall error <sup>Note 1</sup>	AINL	10-bit resolution EV <sub>DD0</sub> = AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	1.8 V ≤ AV <sub>REFP</sub> ≤ 5.5 V		±5.0	LSB
			1.6 V ≤ AV <sub>REFP</sub> ≤ 5.5 V <sup>Note 5</sup>	1.2	±8.5	LSB
Conversion time	t <sub>CONV</sub>	10-bit resolution Target ANI pin : ANI16 to ANI26	3.6 V ≤ V <sub>DD</sub> ≤ 5.5 V	2.125	39	μs
			2.7 V ≤ V <sub>DD</sub> ≤ 5.5 V	3.1875	39	μs
			1.8 V ≤ V <sub>DD</sub> ≤ 5.5 V	17	39	μs
			1.6 V ≤ V <sub>DD</sub> ≤ 5.5 V	57	95	μs
Zero-scale error <sup>Notes 1, 2</sup>	E <sub>ZS</sub>	10-bit resolution EV <sub>DD0</sub> = AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	1.8 V ≤ AV <sub>REFP</sub> ≤ 5.5 V		±0.35	%FSR
			1.6 V ≤ AV <sub>REFP</sub> ≤ 5.5 V <sup>Note 5</sup>		±0.60	%FSR
Full-scale error <sup>Notes 1, 2</sup>	E <sub>FS</sub>	10-bit resolution EV <sub>DD0</sub> = AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	1.8 V ≤ AV <sub>REFP</sub> ≤ 5.5 V		±0.35	%FSR
			1.6 V ≤ AV <sub>REFP</sub> ≤ 5.5 V <sup>Note 5</sup>		±0.60	%FSR
Integral linearity error <sup>Note 1</sup>	ILE	10-bit resolution EV <sub>DD0</sub> = AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	1.8 V ≤ AV <sub>REFP</sub> ≤ 5.5 V		±3.5	LSB
			1.6 V ≤ AV <sub>REFP</sub> ≤ 5.5 V <sup>Note 5</sup>		±6.0	LSB
Differential linearity error <sup>Note 1</sup>	DLE	10-bit resolution EV <sub>DD0</sub> = AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	1.8 V ≤ AV <sub>REFP</sub> ≤ 5.5 V		±2.0	LSB
			1.6 V ≤ AV <sub>REFP</sub> ≤ 5.5 V <sup>Note 5</sup>		±2.5	LSB
Analog input voltage	V <sub>AIN</sub>	ANI16 to ANI26	0		AV <sub>REFP</sub> and EV <sub>DD0</sub>	V

**Notes** 1. Excludes quantization error (±1/2 LSB).

2. This value is indicated as a ratio (%FSR) to the full-scale value.

3. When AV<sub>REFP</sub> < V<sub>DD</sub>, the MAX. values are as follows.

Overall error: Add ±1.0 LSB to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

Zero-scale error/Full-scale error: Add ±0.05%FSR to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

Integral linearity error/ Differential linearity error: Add ±0.5 LSB to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

4. When AV<sub>REFP</sub> < EV<sub>DD0</sub> ≤ V<sub>DD</sub>, the MAX. values are as follows.

Overall error: Add ±4.0 LSB to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

Zero-scale error/Full-scale error: Add ±0.20%FSR to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

Integral linearity error/ Differential linearity error: Add ±2.0 LSB to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

5. When the conversion time is set to 57 μs (min.) and 95 μs (max.).



## 2.6.5 Power supply voltage rising slope characteristics

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{SS} = 0\text{ V}$ )

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Power supply voltage rising slope	$S_{VDD}$				54	V/ms

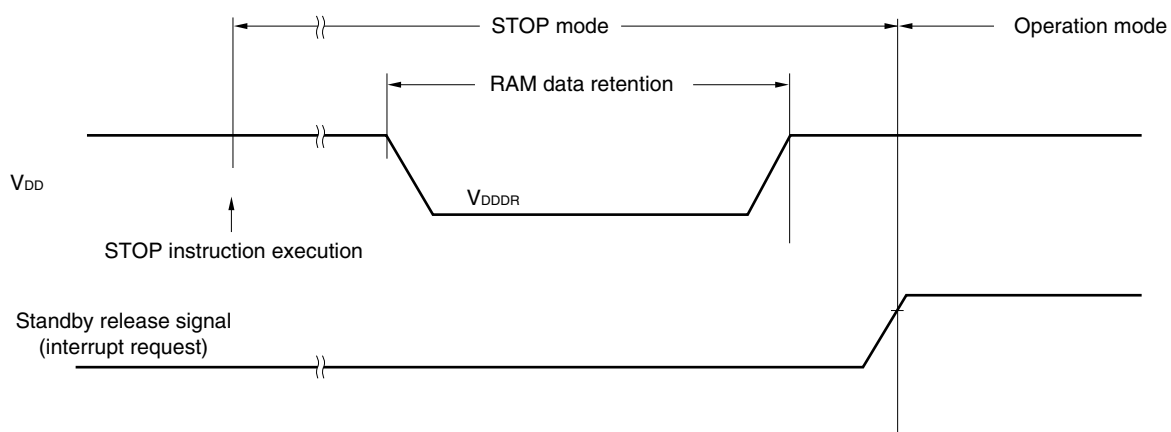
**Caution** Make sure to keep the internal reset state by the LVD circuit or an external reset until  $V_{DD}$  reaches the operating voltage range shown in 2.4 AC Characteristics.

## 2.7 RAM Data Retention Characteristics

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{SS} = 0\text{ V}$ )

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Data retention supply voltage	$V_{DDDR}$		1.46 <sup>Note</sup>		5.5	V

**Note** This depends on the POR detection voltage. For a falling voltage, data in RAM are retained until the voltage reaches the level that triggers a POR reset but not once it reaches the level at which a POR reset is generated.





**Remark** The electrical characteristics of the products G: Industrial applications ( $T_A = -40$  to  $+105^\circ\text{C}$ ) are different from those of the products “A: Consumer applications, and D: Industrial applications”. For details, refer to 3.1 to 3.10.

### 3.1 Absolute Maximum Ratings

#### Absolute Maximum Ratings ( $T_A = 25^\circ\text{C}$ ) (1/2)

Parameter	Symbols	Conditions	Ratings	Unit
Supply voltage	$V_{DD}$		$-0.5$ to $+6.5$	V
	$EV_{DD0}$ , $EV_{DD1}$	$EV_{DD0} = EV_{DD1}$	$-0.5$ to $+6.5$	V
	$EV_{SS0}$ , $EV_{SS1}$	$EV_{SS0} = EV_{SS1}$	$-0.5$ to $+0.3$	V
REGC pin input voltage	$V_{IREGC}$	REGC	$-0.3$ to $+2.8$ and $-0.3$ to $V_{DD} + 0.3$ <sup>Note 1</sup>	V
Input voltage	$V_{I1}$	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147	$-0.3$ to $EV_{DD0} + 0.3$ and $-0.3$ to $V_{DD} + 0.3$ <sup>Note 2</sup>	V
	$V_{I2}$	P60 to P63 (N-ch open-drain)	$-0.3$ to $+6.5$	V
	$V_{I3}$	P20 to P27, P121 to P124, P137, P150 to P156, EXCLK, EXCLKS, RESET	$-0.3$ to $V_{DD} + 0.3$ <sup>Note 2</sup>	V
Output voltage	$V_{O1}$	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	$-0.3$ to $EV_{DD0} + 0.3$ and $-0.3$ to $V_{DD} + 0.3$ <sup>Note 2</sup>	V
	$V_{O2}$	P20 to P27, P150 to P156	$-0.3$ to $V_{DD} + 0.3$ <sup>Note 2</sup>	V
Analog input voltage	$V_{AI1}$	ANI16 to ANI26	$-0.3$ to $EV_{DD0} + 0.3$ and $-0.3$ to $AV_{REF(+)} + 0.3$ <sup>Notes 2, 3</sup>	V
	$V_{AI2}$	ANI0 to ANI14	$-0.3$ to $V_{DD} + 0.3$ and $-0.3$ to $AV_{REF(+)} + 0.3$ <sup>Notes 2, 3</sup>	V

**Notes 1.** Connect the REGC pin to  $V_{SS}$  via a capacitor (0.47 to 1  $\mu\text{F}$ ). This value regulates the absolute maximum rating of the REGC pin. Do not use this pin with voltage applied to it.

**2.** Must be 6.5 V or lower.

**3.** Do not exceed  $AV_{REF(+)} + 0.3$  V in case of A/D conversion target pin.

**Caution** Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

**Remarks 1.** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

**2.**  $AV_{REF(+)}$  : + side reference voltage of the A/D converter.

**3.**  $V_{SS}$  : Reference voltage



## (5) Communication at different potential (1.8 V, 2.5 V, 3 V) (UART mode) (2/2)

(T<sub>A</sub> = -40 to +105°C, 2.4 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V)

Parameter	Symbol	Conditions	HS (high-speed main) Mode		Unit
			MIN.	MAX.	
Transfer rate		Transmission	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, V <sub>b</sub> = 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V		
			Theoretical value of the maximum transfer rate C <sub>b</sub> = 50 pF, R <sub>b</sub> = 1.4 kΩ, V <sub>b</sub> = 2.7 V		
				<b>Note 1</b>	bps
				2.6 <sup>Note 2</sup>	Mbps
			2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, V <sub>b</sub> = 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V		
			Theoretical value of the maximum transfer rate C <sub>b</sub> = 50 pF, R <sub>b</sub> = 2.7 kΩ, V <sub>b</sub> = 2.3 V		
				<b>Note 3</b>	bps
				1.2 <sup>Note 4</sup>	Mbps
			2.4 V ≤ EV <sub>DD0</sub> < 3.3 V, V <sub>b</sub> = 1.6 V ≤ V <sub>b</sub> ≤ 2.0 V		
			Theoretical value of the maximum transfer rate C <sub>b</sub> = 50 pF, R <sub>b</sub> = 5.5 kΩ, V <sub>b</sub> = 1.6 V		
				<b>Note 5</b>	bps
				0.43 <sup>Note 6</sup>	Mbps

**Notes 1.** The smaller maximum transfer rate derived by using f<sub>MCK</sub>/12 or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when 4.0 V ≤ EV<sub>DD0</sub> ≤ 5.5 V and 2.7 V ≤ V<sub>b</sub> ≤ 4.0 V

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{2.2}{V_b})\} \times 3} \text{ [bps]}$$

$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{2.2}{V_b})\}}{(\frac{1}{\text{Transfer rate}}) \times \text{Number of transferred bits}} \times 100 \text{ [%]}$$

\* This value is the theoretical value of the relative difference between the transmission and reception sides.

- This value as an example is calculated when the conditions described in the “Conditions” column are met. Refer to Note 1 above to calculate the maximum transfer rate under conditions of the customer.
- The smaller maximum transfer rate derived by using f<sub>MCK</sub>/12 or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when 2.7 V ≤ EV<sub>DD0</sub> < 4.0 V and 2.4 V ≤ V<sub>b</sub> ≤ 2.7 V

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{2.0}{V_b})\} \times 3} \text{ [bps]}$$

$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{2.0}{V_b})\}}{(\frac{1}{\text{Transfer rate}}) \times \text{Number of transferred bits}} \times 100 \text{ [%]}$$

\* This value is the theoretical value of the relative difference between the transmission and reception sides.

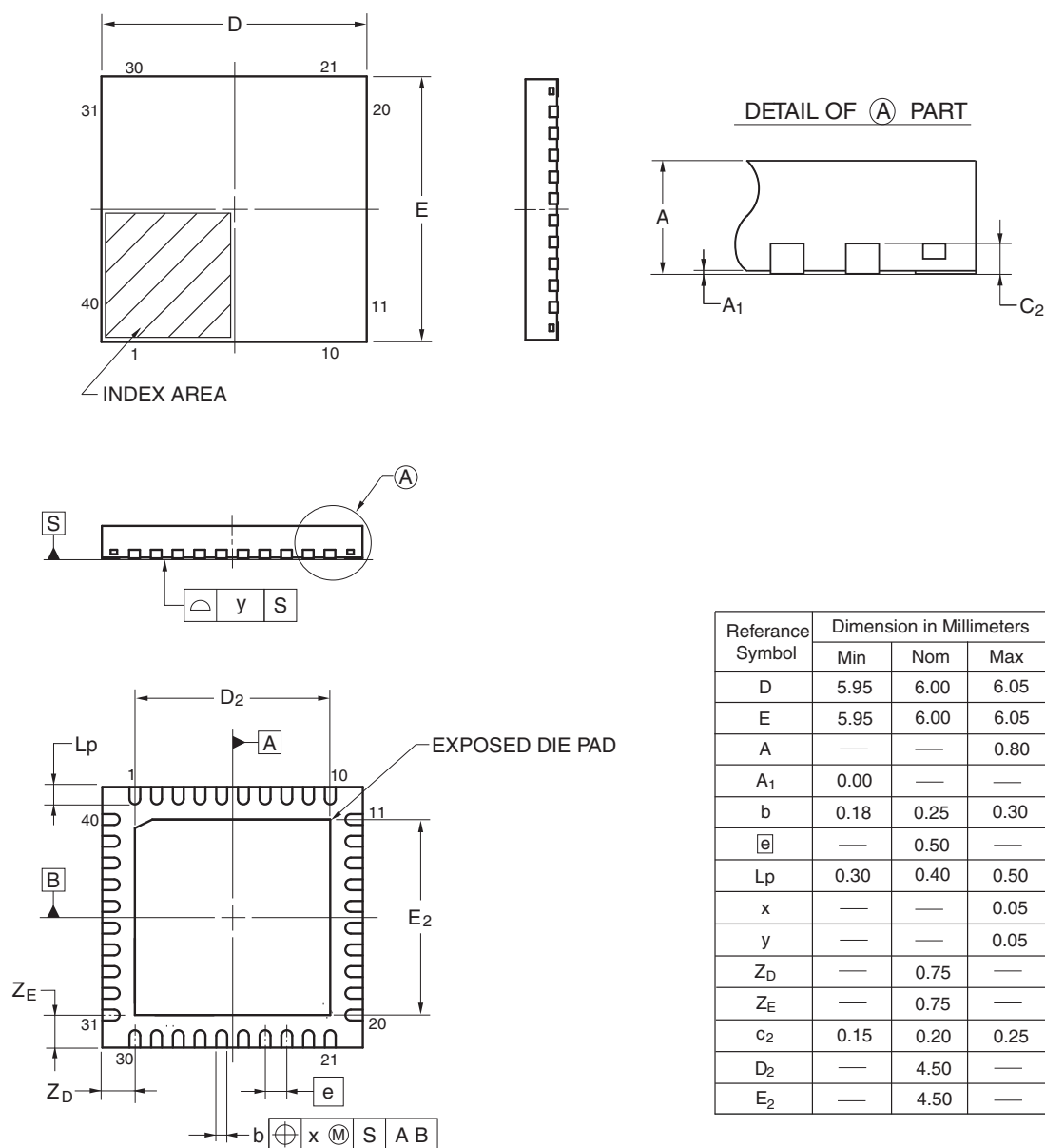
- This value as an example is calculated when the conditions described in the “Conditions” column are met. Refer to Note 3 above to calculate the maximum transfer rate under conditions of the customer.



## 4.7 40-pin Products

R5F100EAANA, R5F100ECANA, R5F100EDANA, R5F100EEANA, R5F100EFANA, R5F100EGANA, R5F100EHANA  
 R5F101EAANA, R5F101ECANA, R5F101EDANA, R5F101EEANA, R5F101EFANA, R5F101EGANA, R5F101EHANA  
 R5F100EADNA, R5F100ECDNA, R5F100EDDNA, R5F100EEDNA, R5F100EFDNA, R5F100EGDNA,  
 R5F100EHDNA  
 R5F101EADNA, R5F101ECDNA, R5F101EDDNA, R5F101EEDNA, R5F101EFDNA, R5F101EGDNA,  
 R5F101EHDNA  
 R5F100EAGNA, R5F100ECGNA, R5F100EDGNA, R5F100EEGNA, R5F100EFGNA, R5F100EGGNA,  
 R5F100EHGNA

JEITA Package code	RENESAS code	Previous code	MASS (TYP.) [g]
P-HWQFN40-6x6-0.50	PWQN0040KC-A	P40K8-50-4B4-5	0.09



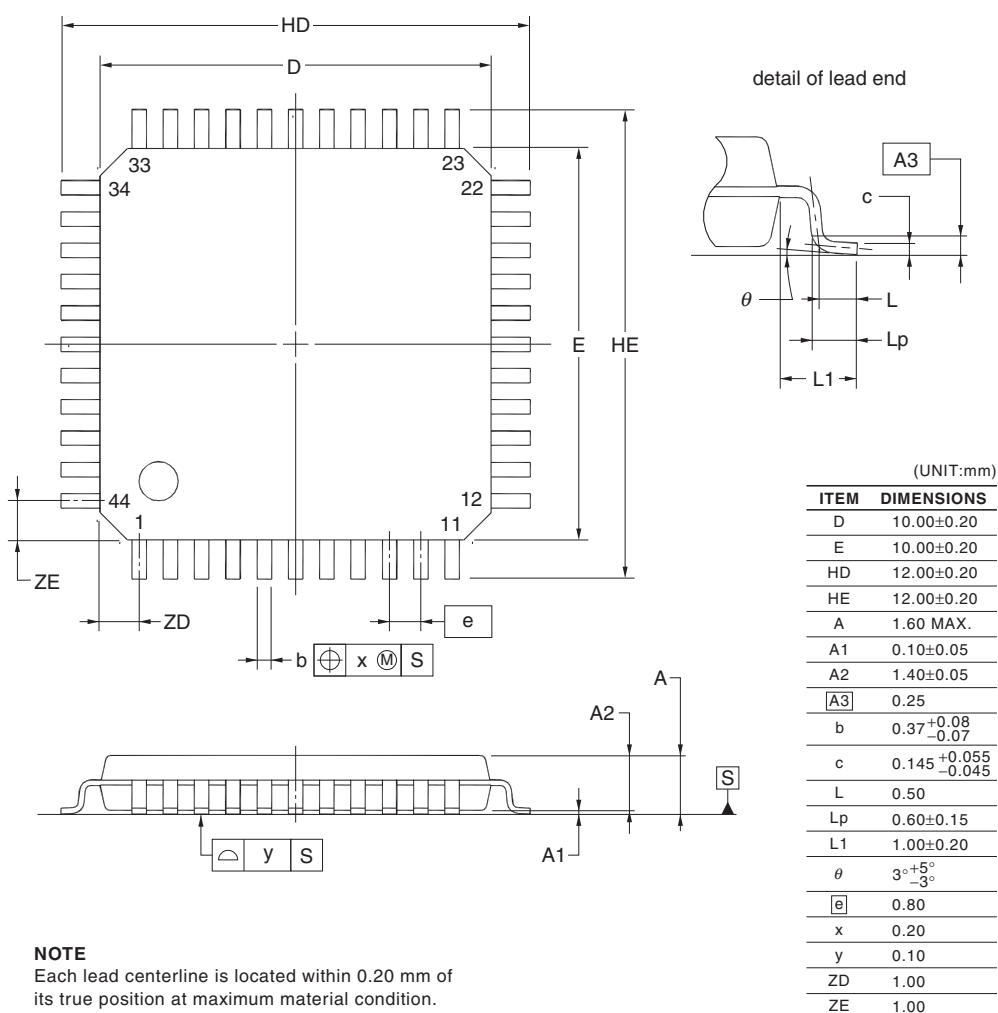
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## 4.8 44-pin Products

R5F100FAAFP, R5F100FCAFP, R5F100FDAFP, R5F100FEAFP, R5F100FFAFP, R5F100FGAFP,  
 R5F100FHAFP, R5F100FJAFP, R5F100FKAFP, R5F100FLAFP  
 R5F101FAAFP, R5F101FCAFP, R5F101FDAFP, R5F101FEAFP, R5F101FFAFP, R5F101FGAFP,  
 R5F101FHAFP, R5F101FJAFP, R5F101FKAFP, R5F101FLAFP  
 R5F100FADFP, R5F100FCDFP, R5F100FDDFP, R5F100FEDFP, R5F100FFDFP, R5F100FGDFP,  
 R5F100FHDFP, R5F100FJDFP, R5F100FKDFP, R5F100FLDFP  
 R5F101FADFP, R5F101FCDFP, R5F101FDDFP, R5F101FEDFP, R5F101FFDFP, R5F101FGDFP,  
 R5F101FHDFP, R5F101FJDFP, R5F101FKDFP, R5F101FLDFP  
 R5F100FAGFP, R5F100FCGFP, R5F100FDGFP, R5F100FEGFP, R5F100FFGFP, R5F100FGGFP,  
 R5F100FHGFP, R5F100FJGFP

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LQFP44-10x10-0.80	PLQP0044GC-A	P44GB-80-UES-2	0.36





Rev.	Date	Description	
		Page	Summary
3.00	Aug 02, 2013	118	Modification of table in 2.6.2 Temperature sensor/internal reference voltage characteristics
		118	Modification of table and note in 2.6.3 POR circuit characteristics
		119	Modification of table in 2.6.4 LVD circuit characteristics
		120	Modification of table of LVD Detection Voltage of Interrupt & Reset Mode
		120	Renamed to 2.6.5 Power supply voltage rising slope characteristics
		122	Modification of table, figure, and remark in 2.10 Timing Specs for Switching Flash Memory Programming Modes
		123	Modification of caution 1 and description
		124	Modification of table and remark 3 in Absolute Maximum Ratings ( $T_A = 25^\circ\text{C}$ )
		126	Modification of table, note, caution, and remark in 3.2.1 X1, XT1 oscillator characteristics
		126	Modification of table in 3.2.2 On-chip oscillator characteristics
		127	Modification of note 3 in 3.3.1 Pin characteristics (1/5)
		128	Modification of note 3 in 3.3.1 Pin characteristics (2/5)
		133	Modification of notes 1 and 4 in (1) Flash ROM: 16 to 64 KB of 20- to 64-pin products (1/2)
		135	Modification of notes 1, 5, and 6 in (1) Flash ROM: 16 to 64 KB of 20- to 64-pin products (2/2)
		137	Modification of notes 1 and 4 in (2) Flash ROM: 96 to 256 KB of 30- to 100-pin products (1/2)
		139	Modification of notes 1, 5, and 6 in (2) Flash ROM: 96 to 256 KB of 30- to 100-pin products (2/2)
		140	Modification of (3) Peripheral Functions (Common to all products)
		142	Modification of table in 3.4 AC Characteristics
		143	Addition of Minimum Instruction Execution Time during Main System Clock Operation
		143	Modification of figure of AC Timing Test Points
		143	Modification of figure of External System Clock Timing
		145	Modification of figure of AC Timing Test Points
		145	Modification of description, note 1, and caution in (1) During communication at same potential (UART mode)
		146	Modification of description in (2) During communication at same potential (CSI mode)
		147	Modification of description in (3) During communication at same potential (CSI mode)
		149	Modification of table, note 1, and caution in (4) During communication at same potential (simplified I <sup>2</sup> C mode)
		151	Modification of table, note 1, and caution in (5) Communication at different potential (1.8 V, 2.5 V, 3 V) (UART mode) (1/2)
		152 to 154	Modification of table, notes 2 to 6, caution, and remarks 1 to 4 in (5) Communication at different potential (1.8 V, 2.5 V, 3 V) (UART mode) (2/2)
		155	Modification of table in (6) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (1/3)
		156	Modification of table and caution in (6) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (2/3)
		157, 158	Modification of table, caution, and remarks 3 and 4 in (6) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (3/3)
		160, 161	Modification of table and caution in (7) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode)



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