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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Obsolete
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I <sup>2</sup> C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	34
Program Memory Size	96KB (96K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 10x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LFQFP (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f101gfafb-x0">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f101gfafb-x0</a>

Table 1-1. List of Ordering Part Numbers

(10/12)

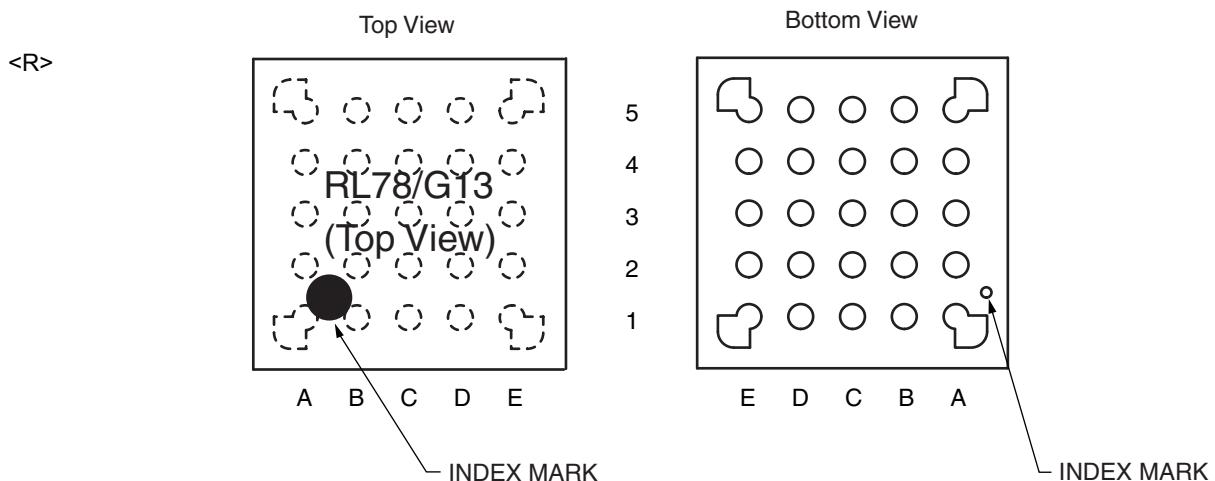
Pin count	Package	Data flash	Fields of Application <small>Note</small>	Ordering Part Number
80 pins	80-pin plastic LQFP (14 × 14 mm, 0.65 mm pitch)	Mounted	A	R5F100MFAFA#V0, R5F100MGAFA#V0, R5F100MHAFA#V0, R5F100MJAFA#V0, R5F100MKAFA#V0, R5F100MLAFA#V0 R5F100MFAFA#X0, R5F100MGAFA#X0, R5F100MHAFA#X0, R5F100MJAFA#X0, R5F100MKAFA#X0, R5F100MLAFA#X0 R5F100MF DFA#V0, R5F100MG DFA#V0, R5F100MH DFA#V0, R5F100MJD FA#V0, R5F100MK DFA#V0, R5F100MLD FA#V0 R5F100MF DFA#X0, R5F100MG DFA#X0, R5F100MH DFA#X0, R5F100MJD FA#X0, R5F100MK DFA#X0, R5F100MLD FA#X0 R5F100MFG FA#V0, R5F100MGG FA#V0, R5F100MHG FA#V0, R5F100MJG FA#V0 R5F100MFG FA#X0, R5F100MGG FA#X0, R5F100MHG FA#X0, R5F100MJG FA#X0
			D	R5F100MF DFA#V0, R5F100MG DFA#V0, R5F100MH DFA#V0, R5F100MJD FA#V0, R5F100MK DFA#V0, R5F100MLD FA#V0 R5F100MF DFA#X0, R5F100MG DFA#X0, R5F100MH DFA#X0, R5F100MJD FA#X0, R5F100MK DFA#X0, R5F100MLD FA#X0 R5F100MFG FA#V0, R5F100MGG FA#V0, R5F100MHG FA#V0, R5F100MJG FA#V0 R5F100MFG FA#X0, R5F100MGG FA#X0, R5F100MHG FA#X0, R5F100MJG FA#X0
			G	R5F101MFAFA#V0, R5F101MGAFA#V0, R5F101MHAFA#V0, R5F101MJAFA#V0, R5F101MKAFA#V0, R5F101MLAFA#V0 R5F101MFAFA#X0, R5F101MGAFA#X0, R5F101MHAFA#X0, R5F101MJAFA#X0, R5F101MKAFA#X0, R5F101MLAFA#X0 R5F101MF DFA#V0, R5F101MG DFA#V0, R5F101MH DFA#V0, R5F101MJD FA#V0, R5F101MK DFA#V0, R5F101MLD FA#V0 R5F101MF DFA#X0, R5F101MG DFA#X0, R5F101MH DFA#X0, R5F101MJD FA#X0, R5F101MK DFA#X0, R5F101MLD FA#X0 R5F101MFG FA#V0, R5F101MGG FA#V0, R5F101MHG FA#V0, R5F101MJG FA#V0 R5F101MFG FA#X0, R5F101MGG FA#X0, R5F101MHG FA#X0, R5F101MJG FA#X0
		Not mounted	A	R5F101MFAFB#V0, R5F100MGAFB#V0, R5F100MHAFB#V0, R5F100MJAFB#V0, R5F100MKAFB#V0, R5F100MLAFB#V0 R5F100MFAFB#X0, R5F100MGAFB#X0, R5F100MHAFB#X0, R5F100MJAFB#X0, R5F100MKAFB#X0, R5F100MLAFB#X0 R5F100MF DFB#V0, R5F100MG DFB#V0, R5F100MH DFB#V0, R5F100MJD FB#V0, R5F100MK DFB#V0, R5F100MLD FB#V0 R5F100MF DFB#X0, R5F100MG DFB#X0, R5F100MH DFB#X0, R5F100MJD FB#X0, R5F100MK DFB#X0, R5F100MLD FB#X0 R5F100MFG FB#V0, R5F100MGG FB#V0, R5F100MHG FB#V0, R5F100MJG FB#V0 R5F100MFG FB#X0, R5F100MGG FB#X0, R5F100MHG FB#X0, R5F100MJG FB#X0
	80-pin plastic LFQFP (12 × 12 mm, 0.5 mm pitch)	Mounted	A	R5F100MFAFB#V0, R5F100MGAFB#V0, R5F100MHAFB#V0, R5F100MJAFB#V0, R5F100MKAFB#V0, R5F100MLAFB#V0 R5F100MFAFB#X0, R5F100MGAFB#X0, R5F100MHAFB#X0, R5F100MJAFB#X0, R5F100MKAFB#X0, R5F100MLAFB#X0 R5F100MF DFB#V0, R5F100MG DFB#V0, R5F100MH DFB#V0, R5F100MJD FB#V0, R5F100MK DFB#V0, R5F100MLD FB#V0 R5F100MF DFB#X0, R5F100MG DFB#X0, R5F100MH DFB#X0, R5F100MJD FB#X0, R5F100MK DFB#X0, R5F100MLD FB#X0 R5F100MFG FB#V0, R5F100MGG FB#V0, R5F100MHG FB#V0, R5F100MJG FB#V0 R5F100MFG FB#X0, R5F100MGG FB#X0, R5F100MHG FB#X0, R5F100MJG FB#X0
			D	R5F100MFAFB#V0, R5F100MGAFB#V0, R5F100MHAFB#V0, R5F100MJAFB#V0, R5F100MKAFB#V0, R5F100MLAFB#V0 R5F100MFAFB#X0, R5F100MGAFB#X0, R5F100MHAFB#X0, R5F100MJAFB#X0, R5F100MKAFB#X0, R5F100MLAFB#X0 R5F100MF DFB#V0, R5F100MG DFB#V0, R5F100MH DFB#V0, R5F100MJD FB#V0, R5F100MK DFB#V0, R5F100MLD FB#V0 R5F100MF DFB#X0, R5F100MG DFB#X0, R5F100MH DFB#X0, R5F100MJD FB#X0, R5F100MK DFB#X0, R5F100MLD FB#X0 R5F100MFG FB#V0, R5F100MGG FB#V0, R5F100MHG FB#V0, R5F100MJG FB#V0 R5F100MFG FB#X0, R5F100MGG FB#X0, R5F100MHG FB#X0, R5F100MJG FB#X0
			G	R5F101MFAFB#V0, R5F101MGAFB#V0, R5F101MHAFB#V0, R5F101MJAFB#V0, R5F101MKAFB#V0, R5F101MLAFB#V0 R5F101MFAFB#X0, R5F101MGAFB#X0, R5F101MHAFB#X0, R5F101MJAFB#X0, R5F101MKAFB#X0, R5F101MLAFB#X0 R5F101MF DFB#V0, R5F101MG DFB#V0, R5F101MH DFB#V0, R5F101MJD FB#V0, R5F101MK DFB#V0, R5F101MLD FB#V0 R5F101MF DFB#X0, R5F101MG DFB#X0, R5F101MH DFB#X0, R5F101MJD FB#X0, R5F101MK DFB#X0, R5F101MLD FB#X0 R5F101MFG FB#V0, R5F101MGG FB#V0, R5F101MHG FB#V0, R5F101MJG FB#V0 R5F101MFG FB#X0, R5F101MGG FB#X0, R5F101MHG FB#X0, R5F101MJG FB#X0
		Not mounted	A	R5F101MFAFB#V0, R5F101MGAFB#V0, R5F101MHAFB#V0, R5F101MJAFB#V0, R5F101MKAFB#V0, R5F101MLAFB#V0 R5F101MFAFB#X0, R5F101MGAFB#X0, R5F101MHAFB#X0, R5F101MJAFB#X0, R5F101MKAFB#X0, R5F101MLAFB#X0 R5F101MF DFB#V0, R5F101MG DFB#V0, R5F101MH DFB#V0, R5F101MJD FB#V0, R5F101MK DFB#V0, R5F101MLD FB#V0 R5F101MF DFB#X0, R5F101MG DFB#X0, R5F101MH DFB#X0, R5F101MJD FB#X0, R5F101MK DFB#X0, R5F101MLD FB#X0 R5F101MFG FB#V0, R5F101MGG FB#V0, R5F101MHG FB#V0, R5F101MJG FB#V0 R5F101MFG FB#X0, R5F101MGG FB#X0, R5F101MHG FB#X0, R5F101MJG FB#X0

**Note** For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

**Caution** The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.

### 1.3.3 25-pin products

- 25-pin plastic WFLGA (3 × 3 mm, 0.50 mm pitch)



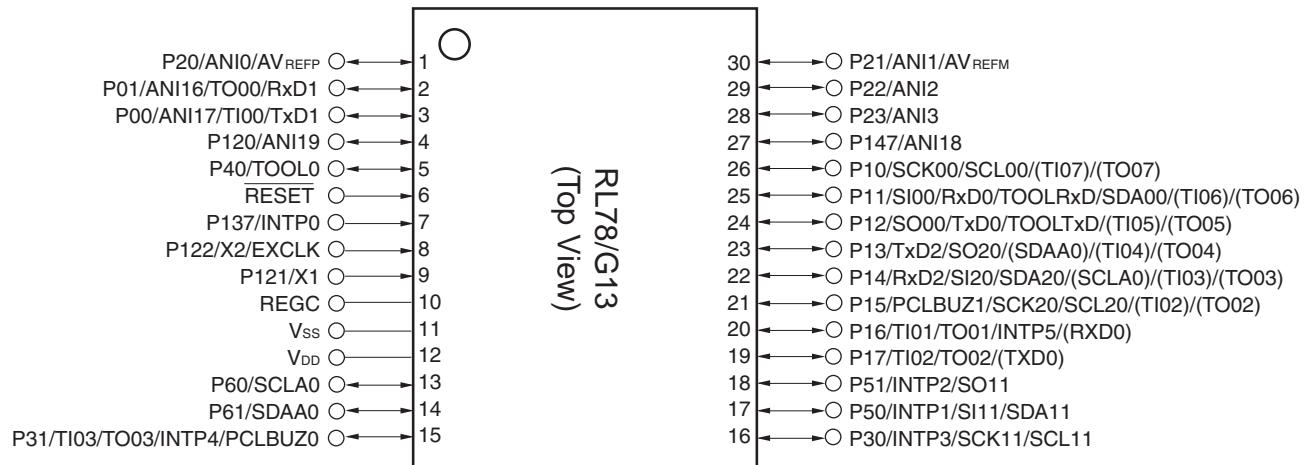
	A	B	C	D	E	
5	P40/TOOL0	RESET	P01/ANI16/ TO00/RxD1	P22/ANI2	P147/ANI18	5
4	P122/X2/ EXCLK	P137/INTP0	P00/ANI17/ TI00/TxD1	P21/ANI1/ AV <sub>REFM</sub>	P10/SCK00/ SCL00	4
3	P121/X1	V <sub>DD</sub>	P20/ANI0/ AV <sub>REFP</sub>	P12/SO00/ TxD0/ TOOLTxD	P11/SI00/ RxDo/ TOOLRxDo/ SDA00	3
2	REGC	V <sub>ss</sub>	P30/INTP3/ SCK11/SCL11	P17/TI02/ TO02/SO11	P50/INTP1/ SI11/SDA11	2
1	P60/SCLA0	P61/SDAA0	P31/TI03/ TO03/INTP4/ PCLBUZ0	P16/TI01/ TO01/INTP5	P130	1
	A	B	C	D	E	

**Caution** Connect the REGC pin to V<sub>ss</sub> via a capacitor (0.47 to 1  $\mu$ F).

**Remark** For pin identification, see **1.4 Pin Identification**.

### 1.3.4 30-pin products

- 30-pin plastic LSSOP (7.62 mm (300), 0.65 mm pitch)



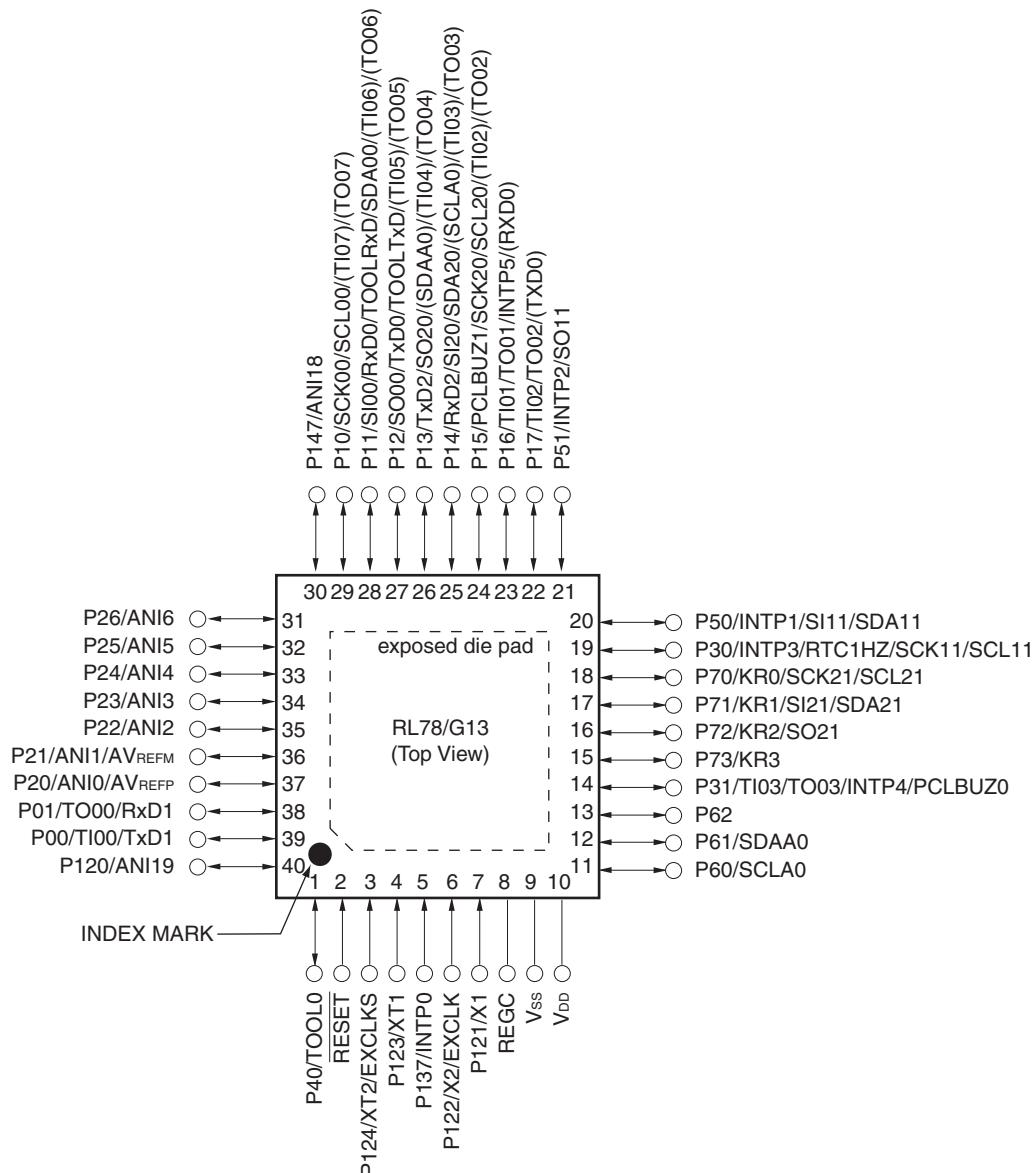
**Caution Connect the REGC pin to V<sub>ss</sub> via a capacitor (0.47 to 1  $\mu$ F).**

**Remarks 1.** For pin identification, see **1.4 Pin Identification**.

2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

### 1.3.7 40-pin products

- 40-pin plastic HWQFN (6 × 6 mm, 0.5 mm pitch)

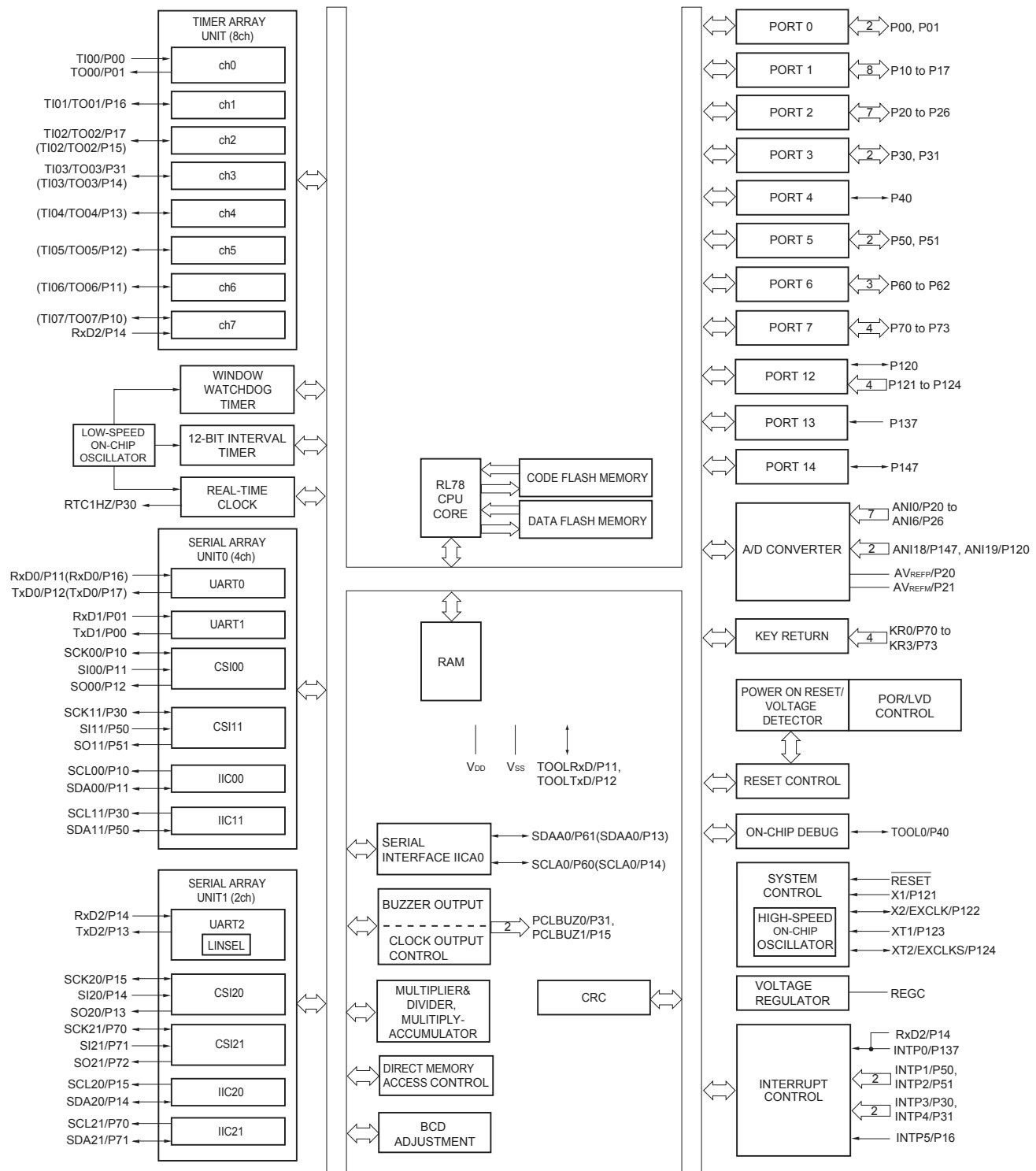


**Caution Connect the REGC pin to V<sub>ss</sub> via a capacitor (0.47 to 1  $\mu$ F).**

**Remarks 1.** For pin identification, see **1.4 Pin Identification**.

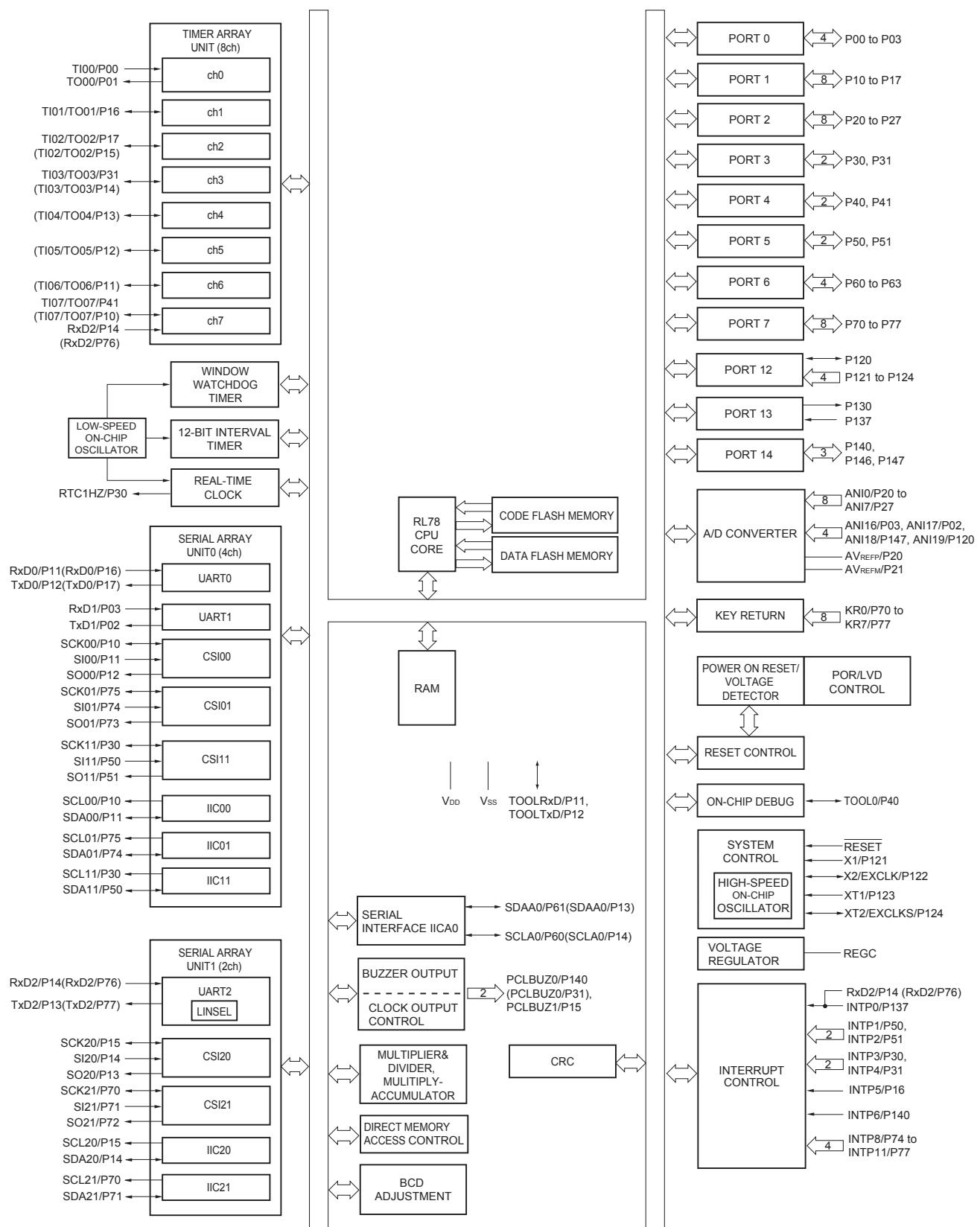
2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.
3. It is recommended to connect an exposed die pad to V<sub>ss</sub>.

## 1.5.7 40-pin products



**Remark** Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

## 1.5.10 52-pin products



**Remark** Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

[80-pin, 100-pin, 128-pin products]

**Caution This outline describes the functions at the time when Peripheral I/O redirection register (PIOR) is set to 00H.**

(1/2)

Item	80-pin		100-pin		128-pin										
	R5F100Mx	R5F101Mx	R5F100Px	R5F101Px	R5F100Sx	R5F101Sx									
Code flash memory (KB)	96 to 512		96 to 512		192 to 512										
Data flash memory (KB)	8	—	8	—	8	—									
RAM (KB)	8 to 32 <sup>Note 1</sup>		8 to 32 <sup>Note 1</sup>		16 to 32 <sup>Note 1</sup>										
Address space	1 MB														
Main system clock	High-speed system clock	X1 (crystal/ceramic) oscillation, external main system clock input (EXCLK) HS (High-speed main) mode: 1 to 20 MHz ( $V_{DD} = 2.7$ to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz ( $V_{DD} = 2.4$ to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz ( $V_{DD} = 1.8$ to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz ( $V_{DD} = 1.6$ to 5.5 V)													
	High-speed on-chip oscillator	HS (High-speed main) mode: 1 to 32 MHz ( $V_{DD} = 2.7$ to 5.5 V), HS (High-speed main) mode: 1 to 16 MHz ( $V_{DD} = 2.4$ to 5.5 V), LS (Low-speed main) mode: 1 to 8 MHz ( $V_{DD} = 1.8$ to 5.5 V), LV (Low-voltage main) mode: 1 to 4 MHz ( $V_{DD} = 1.6$ to 5.5 V)													
Subsystem clock	XT1 (crystal) oscillation, external subsystem clock input (EXCLKS) 32.768 kHz														
Low-speed on-chip oscillator	15 kHz (TYP.)														
General-purpose register	(8-bit register × 8) × 4 banks														
Minimum instruction execution time	0.03125 $\mu$ s (High-speed on-chip oscillator: $f_{IH} = 32$ MHz operation)														
	0.05 $\mu$ s (High-speed system clock: $f_{MX} = 20$ MHz operation)														
	30.5 $\mu$ s (Subsystem clock: $f_{SUB} = 32.768$ kHz operation)														
Instruction set	<ul style="list-style-type: none"> <li>• Data transfer (8/16 bits)</li> <li>• Adder and subtractor/logical operation (8/16 bits)</li> <li>• Multiplication (8 bits × 8 bits)</li> <li>• Rotate, barrel shift, and bit manipulation (Set, reset, test, and Boolean operation), etc.</li> </ul>														
I/O port	Total	74	92	120											
	CMOS I/O	64 (N-ch O.D. I/O [ $EV_{DD}$ withstand voltage]: 21)	82 (N-ch O.D. I/O [ $EV_{DD}$ withstand voltage]: 24)	110 (N-ch O.D. I/O [ $EV_{DD}$ withstand voltage]: 25)											
	CMOS input	5	5	5											
	CMOS output	1	1	1											
	N-ch O.D. I/O (withstand voltage: 6 V)	4	4	4											
Timer	16-bit timer	12 channels	12 channels	16 channels											
	Watchdog timer	1 channel	1 channel	1 channel											
	Real-time clock (RTC)	1 channel	1 channel	1 channel											
	12-bit interval timer (IT)	1 channel	1 channel	1 channel											
	Timer output	12 channels (PWM outputs: 10 <sup>Note 2</sup> )	12 channels (PWM outputs: 10 <sup>Note 2</sup> )	16 channels (PWM outputs: 14 <sup>Note 2</sup> )											
	RTC output	1 channel • 1 Hz (subsystem clock: $f_{SUB} = 32.768$ kHz)													

**Notes 1.** The flash library uses RAM in self-programming and rewriting of the data flash memory.

The target products and start address of the RAM areas used by the flash library are shown below.

R5F100xJ, R5F101xJ (x = M, P): Start address FAF00H

R5F100xL, R5F101xL (x = M, P, S): Start address F7F00H

For the RAM areas used by the flash library, see **Self RAM list of Flash Self-Programming Library for RL78 Family (R20UT2944)**.

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$ ) (5/5)

Items	Symbol	Conditions		MIN.	TYP.	MAX.	Unit		
Input leakage current, high	$I_{LIH1}$	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147		$V_I = EV_{DD0}$		1	$\mu\text{A}$		
	$I_{LIH2}$	P20 to P27, P137, P150 to P156, RESET		$V_I = V_{DD}$		1	$\mu\text{A}$		
	$I_{LIH3}$	P121 to P124 (X1, X2, XT1, XT2, EXCLK, EXCLKS)		$V_I = V_{DD}$	In input port or external clock input	1	$\mu\text{A}$		
						10	$\mu\text{A}$		
Input leakage current, low	$I_{LIL1}$	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147		$V_I = EV_{SS0}$		-1	$\mu\text{A}$		
	$I_{LIL2}$	P20 to P27, P137, P150 to P156, RESET		$V_I = V_{SS}$		-1	$\mu\text{A}$		
	$I_{LIL3}$	P121 to P124 (X1, X2, XT1, XT2, EXCLK, EXCLKS)		$V_I = V_{SS}$	In input port or external clock input	-1	$\mu\text{A}$		
						-10	$\mu\text{A}$		
On-chip pll-up resistance	$R_u$	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147		$V_I = EV_{SS0}$ , In input port		10	20	100	$k\Omega$

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

## (1) Flash ROM: 16 to 64 KB of 20- to 64-pin products

 $(T_A = -40$  to  $+85^\circ\text{C}$ ,  $1.6 \text{ V} \leq EV_{DD0} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{ss} = EV_{ss0} = 0 \text{ V}$ ) (2/2)

Parameter	Symbol	Conditions			MIN.	TYP.	MAX.	Unit
Supply current <small>Note 1</small>	$I_{DD2}$ <small>Note 2</small>	HALT mode	HS (high-speed main) mode <small>Note 7</small>	$f_{IH} = 32 \text{ MHz}$ <small>Note 4</small>	$V_{DD} = 5.0 \text{ V}$	0.54	1.63	mA
					$V_{DD} = 3.0 \text{ V}$	0.54	1.63	mA
				$f_{IH} = 24 \text{ MHz}$ <small>Note 4</small>	$V_{DD} = 5.0 \text{ V}$	0.44	1.28	mA
					$V_{DD} = 3.0 \text{ V}$	0.44	1.28	mA
				$f_{IH} = 16 \text{ MHz}$ <small>Note 4</small>	$V_{DD} = 5.0 \text{ V}$	0.40	1.00	mA
					$V_{DD} = 3.0 \text{ V}$	0.40	1.00	mA
		LS (low-speed main) mode <small>Note 7</small>	$f_{IH} = 8 \text{ MHz}$ <small>Note 4</small>	$V_{DD} = 3.0 \text{ V}$	260	530	$\mu\text{A}$	
				$V_{DD} = 2.0 \text{ V}$	260	530	$\mu\text{A}$	
		LV (low-voltage main) mode <small>Note 7</small>	$f_{IH} = 4 \text{ MHz}$ <small>Note 4</small>	$V_{DD} = 3.0 \text{ V}$	420	640	$\mu\text{A}$	
				$V_{DD} = 2.0 \text{ V}$	420	640	$\mu\text{A}$	
		HS (high-speed main) mode <small>Note 7</small>	$f_{MX} = 20 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 5.0 \text{ V}$	Square wave input	0.28	1.00	mA	
				Resonator connection	0.45	1.17	mA	
			$f_{MX} = 20 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 3.0 \text{ V}$	Square wave input	0.28	1.00	mA	
				Resonator connection	0.45	1.17	mA	
			$f_{MX} = 10 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 5.0 \text{ V}$	Square wave input	0.19	0.60	mA	
				Resonator connection	0.26	0.67	mA	
			$f_{MX} = 10 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 3.0 \text{ V}$	Square wave input	0.19	0.60	mA	
				Resonator connection	0.26	0.67	mA	
		LS (low-speed main) mode <small>Note 7</small>	$f_{MX} = 8 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 3.0 \text{ V}$	Square wave input	95	330	$\mu\text{A}$	
				Resonator connection	145	380	$\mu\text{A}$	
			$f_{MX} = 8 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 2.0 \text{ V}$	Square wave input	95	330	$\mu\text{A}$	
				Resonator connection	145	380	$\mu\text{A}$	
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = -40^\circ\text{C}$	Square wave input	0.25	0.57	$\mu\text{A}$	
				Resonator connection	0.44	0.76	$\mu\text{A}$	
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = +25^\circ\text{C}$	Square wave input	0.30	0.57	$\mu\text{A}$	
				Resonator connection	0.49	0.76	$\mu\text{A}$	
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = +50^\circ\text{C}$	Square wave input	0.37	1.17	$\mu\text{A}$	
				Resonator connection	0.56	1.36	$\mu\text{A}$	
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = +70^\circ\text{C}$	Square wave input	0.53	1.97	$\mu\text{A}$	
				Resonator connection	0.72	2.16	$\mu\text{A}$	
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = +85^\circ\text{C}$	Square wave input	0.82	3.37	$\mu\text{A}$	
				Resonator connection	1.01	3.56	$\mu\text{A}$	
$I_{DD3}$ <small>Note 6</small>	STOP mode <small>Note 8</small>	$T_A = -40^\circ\text{C}$			0.18	0.50	$\mu\text{A}$	
		$T_A = +25^\circ\text{C}$			0.23	0.50	$\mu\text{A}$	
		$T_A = +50^\circ\text{C}$			0.30	1.10	$\mu\text{A}$	
		$T_A = +70^\circ\text{C}$			0.46	1.90	$\mu\text{A}$	
		$T_A = +85^\circ\text{C}$			0.75	3.30	$\mu\text{A}$	

(Notes and Remarks are listed on the next page.)

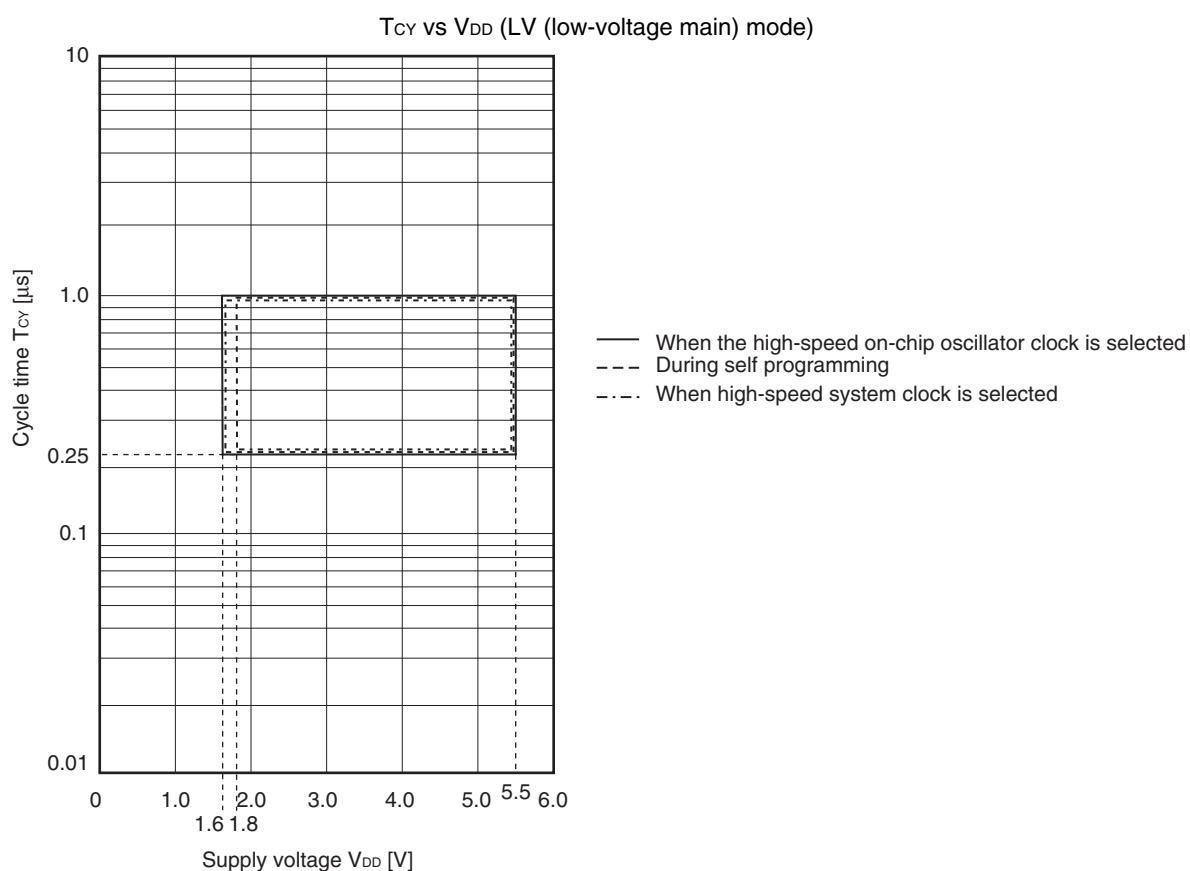
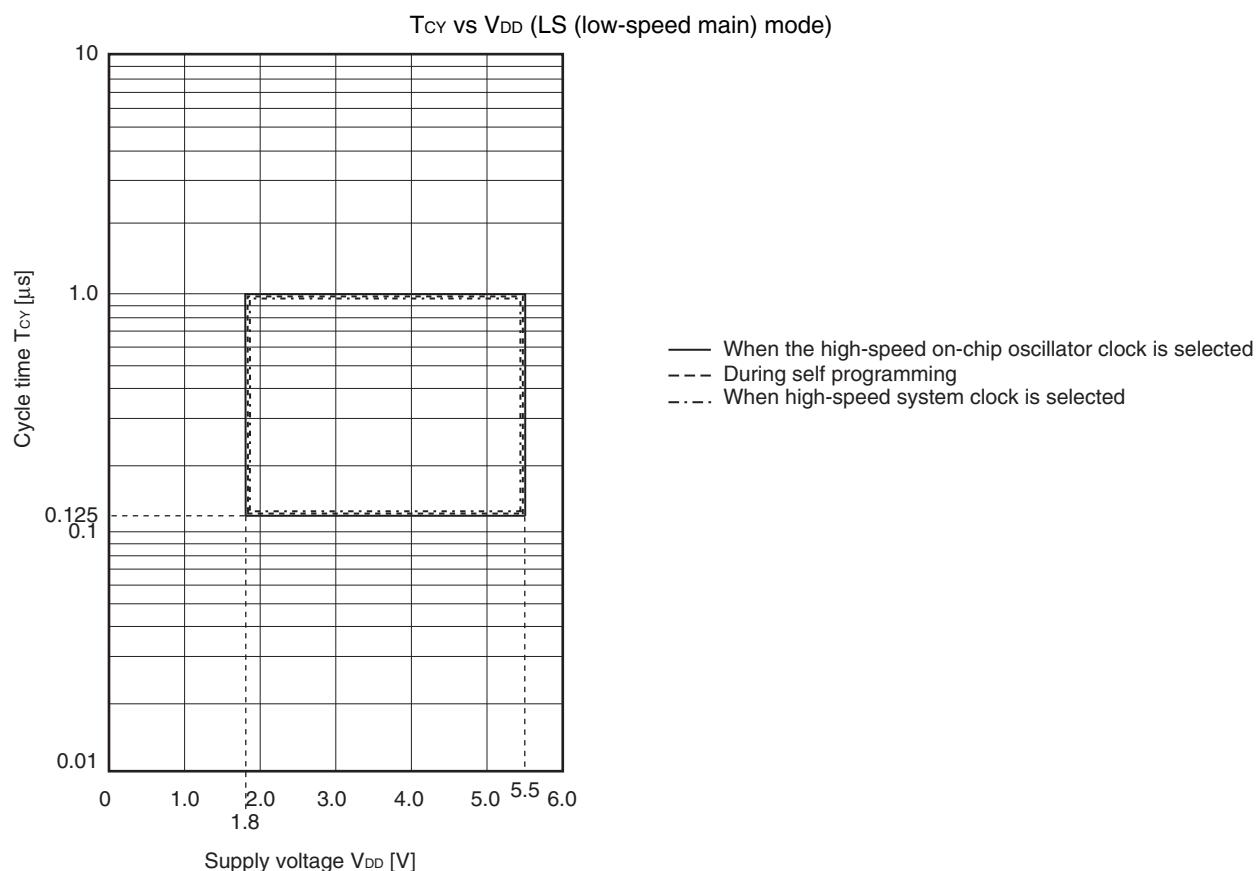
## (4) Peripheral Functions (Common to all products)

 $(T_A = -40$  to  $+85^\circ\text{C}$ ,  $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$ )

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Low-speed on-chip oscillator operating current	$I_{FIL}$ <sup>Note 1</sup>				0.20		$\mu\text{A}$
RTC operating current	$I_{RTC}$ Notes 1, 2, 3				0.02		$\mu\text{A}$
12-bit interval timer operating current	$I_{IT}$ <sup>Notes 1, 2, 4</sup>				0.02		$\mu\text{A}$
Watchdog timer operating current	$I_{WDT}$ Notes 1, 2, 5	$f_{IL} = 15 \text{ kHz}$			0.22		$\mu\text{A}$
A/D converter operating current	$I_{ADC}$ <sup>Notes 1, 6</sup>	When conversion at maximum speed	Normal mode, $AV_{REFP} = V_{DD} = 5.0 \text{ V}$		1.3	1.7	mA
			Low voltage mode, $AV_{REFP} = V_{DD} = 3.0 \text{ V}$		0.5	0.7	mA
A/D converter reference voltage current	$I_{ADREF}$ <sup>Note 1</sup>				75.0		$\mu\text{A}$
Temperature sensor operating current	$I_{TMPS}$ <sup>Note 1</sup>				75.0		$\mu\text{A}$
LVD operating current	$I_{LVI}$ <sup>Notes 1, 7</sup>				0.08		$\mu\text{A}$
Self-programming operating current	$I_{FSPI}$ <sup>Notes 1, 9</sup>				2.50	12.20	mA
BGO operating current	$I_{BGO}$ <sup>Notes 1, 8</sup>				2.50	12.20	mA
SNOOZE operating current	$I_{SNOZ}$ <sup>Note 1</sup>	ADC operation	The mode is performed <sup>Note 10</sup>		0.50	0.60	mA
			The A/D conversion operations are performed, Low voltage mode, $AV_{REFP} = V_{DD} = 3.0 \text{ V}$		1.20	1.44	mA
		CSI/UART operation			0.70	0.84	mA

Notes 1. Current flowing to  $V_{DD}$ .

2. When high speed on-chip oscillator and high-speed system clock are stopped.
3. Current flowing only to the real-time clock (RTC) (excluding the operating current of the low-speed on-chip oscillator and the XT1 oscillator). The supply current of the RL78 microcontrollers is the sum of the values of either  $I_{DD1}$  or  $I_{DD2}$ , and  $I_{RTC}$ , when the real-time clock operates in operation mode or HALT mode. When the low-speed on-chip oscillator is selected,  $I_{FIL}$  should be added.  $I_{DD2}$  subsystem clock operation includes the operational current of the real-time clock.
4. Current flowing only to the 12-bit interval timer (excluding the operating current of the low-speed on-chip oscillator and the XT1 oscillator). The supply current of the RL78 microcontrollers is the sum of the values of either  $I_{DD1}$  or  $I_{DD2}$ , and  $I_{IT}$ , when the 12-bit interval timer operates in operation mode or HALT mode. When the low-speed on-chip oscillator is selected,  $I_{FIL}$  should be added.
5. Current flowing only to the watchdog timer (including the operating current of the low-speed on-chip oscillator). The supply current of the RL78 microcontrollers is the sum of  $I_{DD1}$ ,  $I_{DD2}$  or  $I_{DD3}$  and  $I_{WDT}$  when the watchdog timer is in operation.



**(8) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock output)  
(3/3)**

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $1.8 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$ )

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
Slp setup time (to SCKp $\downarrow$ ) <sup>Note 1</sup>	tsIK1	4.0 V $\leq$ EV <sub>DD0</sub> $\leq$ 5.5 V, 2.7 V $\leq$ V <sub>b</sub> $\leq$ 4.0 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 1.4 k $\Omega$	44		110		110		ns
		2.7 V $\leq$ EV <sub>DD0</sub> < 4.0 V, 2.3 V $\leq$ V <sub>b</sub> $\leq$ 2.7 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 2.7 k $\Omega$	44		110		110		ns
		1.8 V $\leq$ EV <sub>DD0</sub> < 3.3 V, 1.6 V $\leq$ V <sub>b</sub> $\leq$ 2.0 V <sup>Note 2</sup> , C <sub>b</sub> = 30 pF, R <sub>b</sub> = 5.5 k $\Omega$	110		110		110		ns
Slp hold time (from SCKp $\downarrow$ ) <sup>Note 1</sup>	tKS11	4.0 V $\leq$ EV <sub>DD0</sub> $\leq$ 5.5 V, 2.7 V $\leq$ V <sub>b</sub> $\leq$ 4.0 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 1.4 k $\Omega$	19		19		19		ns
		2.7 V $\leq$ EV <sub>DD0</sub> < 4.0 V, 2.3 V $\leq$ V <sub>b</sub> $\leq$ 2.7 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 2.7 k $\Omega$	19		19		19		ns
		1.8 V $\leq$ EV <sub>DD0</sub> < 3.3 V, 1.6 V $\leq$ V <sub>b</sub> $\leq$ 2.0 V <sup>Note 2</sup> , C <sub>b</sub> = 30 pF, R <sub>b</sub> = 5.5 k $\Omega$	19		19		19		ns
Delay time from SCKp $\uparrow$ to SO <sub>p</sub> output <sup>Note 1</sup>	tKS01	4.0 V $\leq$ EV <sub>DD0</sub> $\leq$ 5.5 V, 2.7 V $\leq$ V <sub>b</sub> $\leq$ 4.0 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 1.4 k $\Omega$		25		25		25	ns
		2.7 V $\leq$ EV <sub>DD0</sub> < 4.0 V, 2.3 V $\leq$ V <sub>b</sub> $\leq$ 2.7 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 2.7 k $\Omega$		25		25		25	ns
		1.8 V $\leq$ EV <sub>DD0</sub> < 3.3 V, 1.6 V $\leq$ V <sub>b</sub> $\leq$ 2.0 V <sup>Note 2</sup> , C <sub>b</sub> = 30 pF, R <sub>b</sub> = 5.5 k $\Omega$		25		25		25	ns

**Notes** 1. When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.

2. Use it with EV<sub>DD0</sub>  $\geq$  V<sub>b</sub>.

**Caution** Select the TTL input buffer for the Slp pin and the N-ch open drain output (V<sub>DD</sub> tolerance (When 20- to 52-pin products)/EV<sub>DD</sub> tolerance (When 64- to 128-pin products)) mode for the SO<sub>p</sub> pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg). For V<sub>IH</sub> and V<sub>IL</sub>, see the DC characteristics with TTL input buffer selected.

(Remarks are listed on the next page.)

(2) I<sup>2</sup>C fast mode $(T_A = -40$  to  $+85^\circ\text{C}$ ,  $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$ )

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCLA0 clock frequency	f <sub>SCL</sub>	Fast mode: $f_{CLK} \geq 3.5 \text{ MHz}$	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$	0	400	0	400	0	400	kHz
			1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$	0	400	0	400	0	400	kHz
Setup time of restart condition	t <sub>SU:STA</sub>	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		$\mu\text{s}$
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		$\mu\text{s}$
Hold time <sup>Note 1</sup>	t <sub>HD:STA</sub>	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		$\mu\text{s}$
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		$\mu\text{s}$
Hold time when SCLA0 = "L"	t <sub>LOW</sub>	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		1.3		1.3		1.3		$\mu\text{s}$
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		1.3		1.3		1.3		$\mu\text{s}$
Hold time when SCLA0 = "H"	t <sub>HIGH</sub>	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		$\mu\text{s}$
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		$\mu\text{s}$
Data setup time (reception)	t <sub>SU:DAT</sub>	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		100		100		100		$\mu\text{s}$
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		100		100		100		$\mu\text{s}$
Data hold time (transmission) <sup>Note 2</sup>	t <sub>HD:DAT</sub>	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0	0.9	0	0.9	0	0.9	$\mu\text{s}$
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0	0.9	0	0.9	0	0.9	$\mu\text{s}$
Setup time of stop condition	t <sub>SU:STO</sub>	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		$\mu\text{s}$
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		0.6		0.6		0.6		$\mu\text{s}$
Bus-free time	t <sub>BUF</sub>	2.7 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		1.3		1.3		1.3		$\mu\text{s}$
		1.8 V $\leq EV_{DD0} \leq 5.5 \text{ V}$		1.3		1.3		1.3		$\mu\text{s}$

**Notes** 1. The first clock pulse is generated after this period when the start/restart condition is detected.

<R> 2. The maximum value (MAX.) of t<sub>HD:DAT</sub> is during normal transfer and a wait state is inserted in the ACK (acknowledge) timing.

**Caution** The values in the above table are applied even when bit 2 (PIOR2) in the peripheral I/O redirection register (PIOR) is 1. At this time, the pin characteristics (I<sub>OH1</sub>, I<sub>OL1</sub>, V<sub>OH1</sub>, V<sub>OL1</sub>) must satisfy the values in the redirect destination.

**Remark** The maximum value of C<sub>b</sub> (communication line capacitance) and the value of R<sub>b</sub> (communication line pull-up resistor) at that time in each mode are as follows.

Fast mode: C<sub>b</sub> = 320 pF, R<sub>b</sub> = 1.1 k $\Omega$

### 2.6.2 Temperature sensor/internal reference voltage characteristics

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $2.4 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = 0 \text{ V}$ , HS (high-speed main) mode)

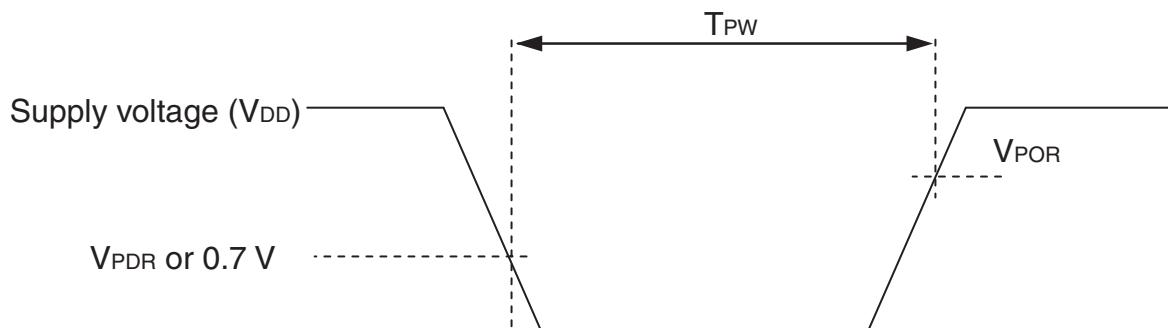
Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Temperature sensor output voltage	$V_{TMPS25}$	Setting ADS register = 80H, $T_A = +25^\circ\text{C}$		1.05		V
Internal reference voltage	$V_{BGR}$	Setting ADS register = 81H	1.38	1.45	1.5	V
Temperature coefficient	$F_{VTMPS}$	Temperature sensor that depends on the temperature		-3.6		mV/ $^\circ\text{C}$
Operation stabilization wait time	$t_{AMP}$		5			$\mu\text{s}$

### 2.6.3 POR circuit characteristics

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{SS} = 0 \text{ V}$ )

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Detection voltage	$V_{POR}$	Power supply rise time	1.47	1.51	1.55	V
	$V_{PDR}$	Power supply fall time	1.46	1.50	1.54	V
Minimum pulse width <sup>Note</sup>	$T_{PW}$		300			$\mu\text{s}$

**Note** Minimum time required for a POR reset when  $V_{DD}$  exceeds below  $V_{PDR}$ . This is also the minimum time required for a POR reset from when  $V_{DD}$  exceeds below 0.7 V to when  $V_{DD}$  exceeds  $V_{POR}$  while STOP mode is entered or the main system clock is stopped through setting bit 0 (HIOSTOP) and bit 7 (MSTOP) in the clock operation status control register (CSC).



### 3.3 DC Characteristics

#### 3.3.1 Pin characteristics

(TA = -40 to +105°C, 2.4 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V) (1/5)

Items	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Output current, high <sup>Note 1</sup>	I <sub>OH1</sub>	Per pin for P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	2.4 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		-3.0 <sup>Note 2</sup>	mA
		Total of P00 to P04, P07, P32 to P37, P40 to P47, P102 to P106, P120, P125 to P127, P130, P140 to P145 (When duty ≤ 70% <sup>Note 3</sup> )	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		-30.0	mA
			2.7 V ≤ EV <sub>DD0</sub> < 4.0 V		-10.0	mA
			2.4 V ≤ EV <sub>DD0</sub> < 2.7 V		-5.0	mA
		Total of P05, P06, P10 to P17, P30, P31, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100, P101, P110 to P117, P146, P147 (When duty ≤ 70% <sup>Note 3</sup> )	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		-30.0	mA
			2.7 V ≤ EV <sub>DD0</sub> < 4.0 V		-19.0	mA
			2.4 V ≤ EV <sub>DD0</sub> < 2.7 V		-10.0	mA
		Total of all pins (When duty ≤ 70% <sup>Note 3</sup> )	2.4 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		-60.0	mA
	I <sub>OH2</sub>	Per pin for P20 to P27, P150 to P156	2.4 V ≤ V <sub>DD</sub> ≤ 5.5 V		-0.1 <sup>Note 2</sup>	mA
		Total of all pins (When duty ≤ 70% <sup>Note 3</sup> )	2.4 V ≤ V <sub>DD</sub> ≤ 5.5 V		-1.5	mA

**Notes** 1. Value of current at which the device operation is guaranteed even if the current flows from the EV<sub>DD0</sub>, EV<sub>DD1</sub>, V<sub>DD</sub> pins to an output pin.

2. Do not exceed the total current value.

3. Specification under conditions where the duty factor ≤ 70%.

The output current value that has changed to the duty factor > 70% the duty ratio can be calculated with the following expression (when changing the duty factor from 70% to n%).

- Total output current of pins = (I<sub>OH</sub> × 0.7)/(n × 0.01)

<Example> Where n = 80% and I<sub>OH</sub> = -10.0 mA

$$\text{Total output current of pins} = (-10.0 \times 0.7)/(80 \times 0.01) \approx -8.7 \text{ mA}$$

However, the current that is allowed to flow into one pin does not vary depending on the duty factor.

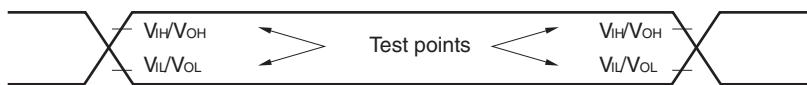
A current higher than the absolute maximum rating must not flow into one pin.

**Caution** P00, P02 to P04, P10 to P15, P17, P43 to P45, P50, P52 to P55, P71, P74, P80 to P82, P96, and P142 to P144 do not output high level in N-ch open-drain mode.

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

### 3.5 Peripheral Functions Characteristics

#### AC Timing Test Points



#### 3.5.1 Serial array unit

##### (1) During communication at same potential (UART mode)

(TA = -40 to +105°C, 2.4 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V)

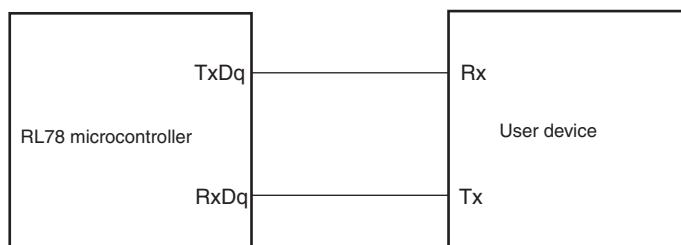
Parameter	Symbol	Conditions	HS (high-speed main) Mode		Unit
			MIN.	MAX.	
Transfer rate <sup>Note 1</sup>		Theoretical value of the maximum transfer rate f <sub>CLK</sub> = 32 MHz, f <sub>MCK</sub> = f <sub>CLK</sub>		f <sub>MCK</sub> /12 <sup>Note 2</sup>	bps
				2.6	Mbps

**Notes 1.** Transfer rate in the SNOOZE mode is 4800 bps only.

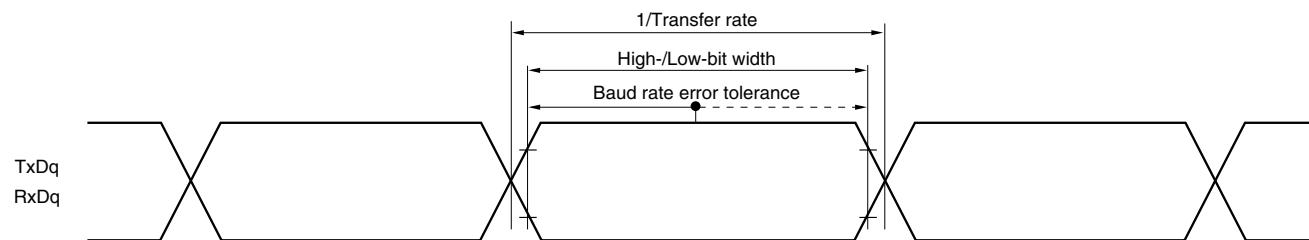
2. The following conditions are required for low voltage interface when EV<sub>DD0</sub> < V<sub>DD</sub>.
- 2.4 V ≤ EV<sub>DD0</sub> < 2.7 V : MAX. 1.3 Mbps

**Caution** Select the normal input buffer for the RxDq pin and the normal output mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg).

#### UART mode connection diagram (during communication at same potential)



#### UART mode bit width (during communication at same potential) (reference)



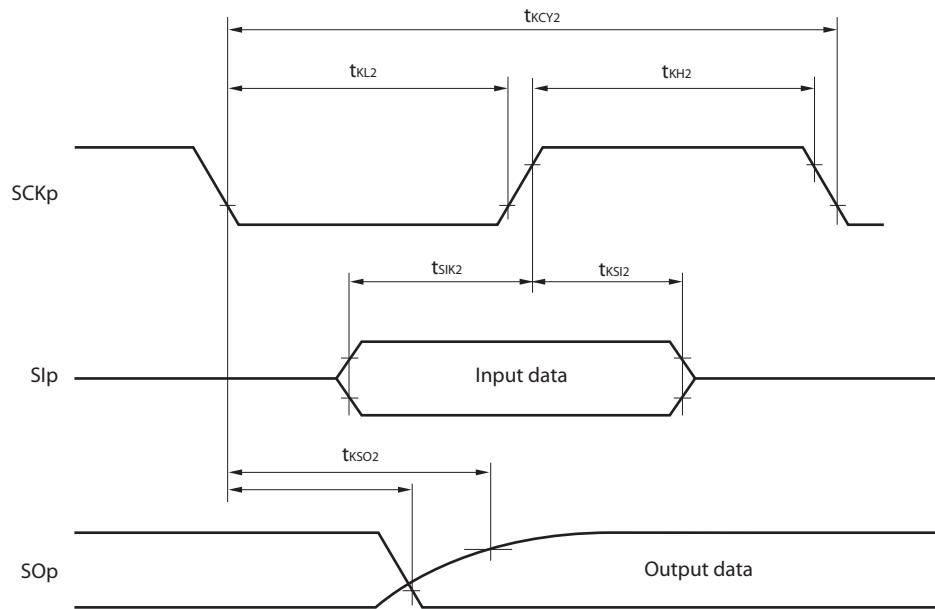
**Remarks 1.** q: UART number (q = 0 to 3), g: PIM and POM number (g = 0, 1, 8, 14)

2. f<sub>MCK</sub>: Serial array unit operation clock frequency

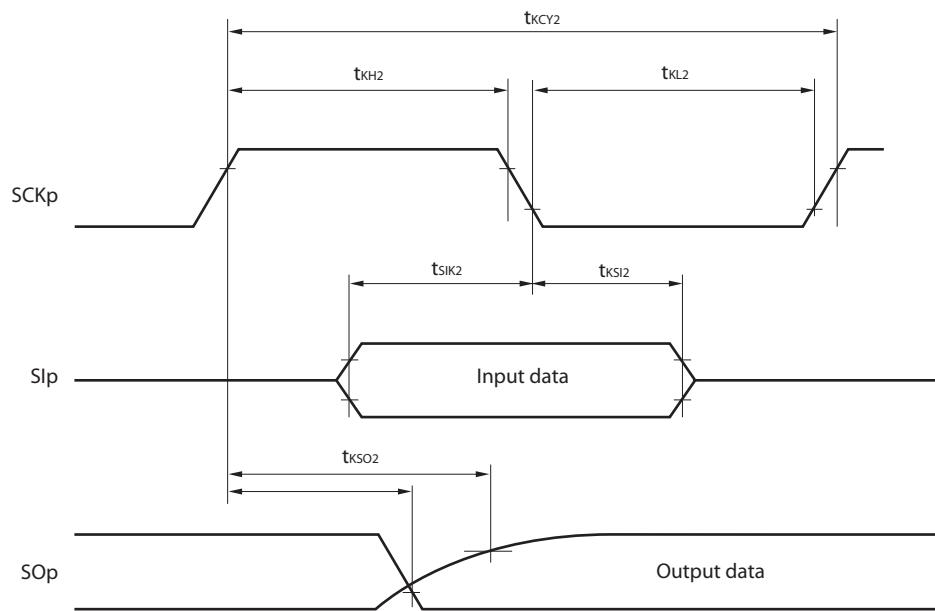
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13))

**CSI mode serial transfer timing (slave mode) (during communication at different potential)**

(When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.)

**CSI mode serial transfer timing (slave mode) (during communication at different potential)**

(When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.)

**Remarks** 1. p: CSI number (p = 00, 01, 10, 20, 30, 31), m: Unit number,

n: Channel number (mn = 00, 01, 02, 10, 12, 13), g: PIM and POM number (g = 0, 1, 4, 5, 8, 14)

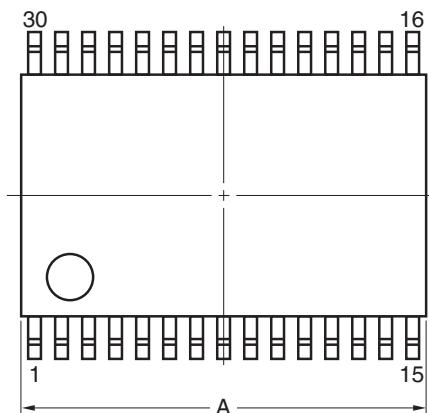
2. CSI01 of 48-, 52-, 64-pin products, and CSI11 and CSI21 cannot communicate at different potential.

Use other CSI for communication at different potential.

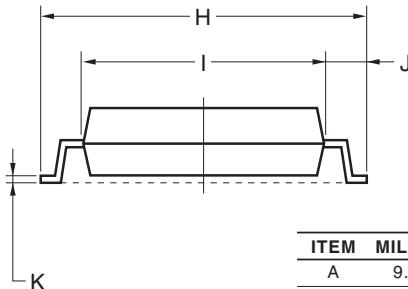
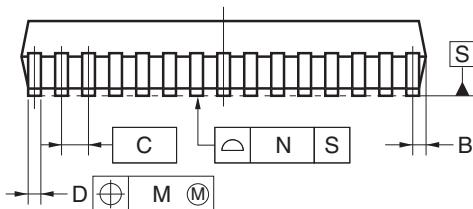
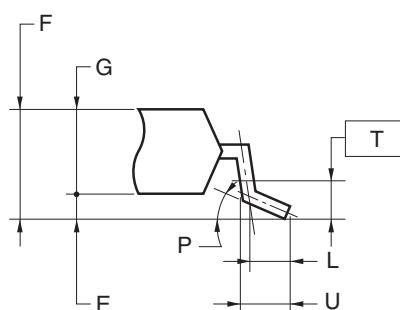
#### 4.4 30-pin Products

R5F100AAASP, R5F100ACASP, R5F100ADASP, R5F100AEASP, R5F100AFASP, R5F100AGASP  
 R5F101AAASP, R5F101ACASP, R5F101ADASP, R5F101AEASP, R5F101AFASP, R5F101AGASP  
 R5F100AADSP, R5F100ACDSP, R5F100ADDSP, R5F100AEDSP, R5F100AFDSP, R5F100AGDSP  
 R5F101AADSP, R5F101ACDSP, R5F101ADDSP, R5F101AEDSP, R5F101AFDSP, R5F101AGDSP  
 R5F100AAGSP, R5F100ACGSP, R5F100ADGSP, R5F100AEGSP, R5F100AFGSP, R5F100AGGSP

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LSSOP30-0300-0.65	PLSP0030JB-B	S30MC-65-5A4-3	0.18



detail of lead end

**NOTE**

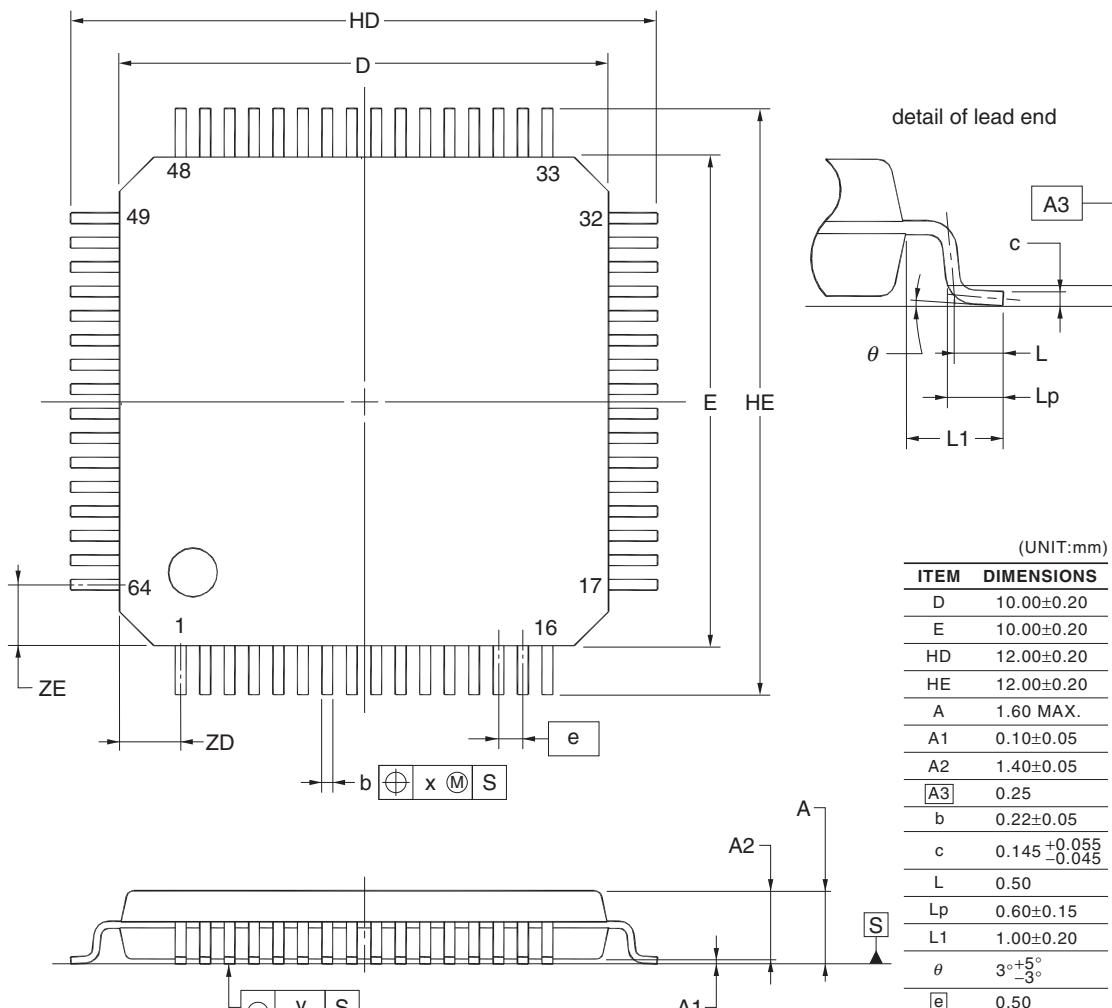
Each lead centerline is located within 0.13 mm of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS
A	9.85±0.15
B	0.45 MAX.
C	0.65 (T.P.)
D	0.24 <sup>+0.08</sup> <sub>-0.07</sub>
E	0.1±0.05
F	1.3±0.1
G	1.2
H	8.1±0.2
I	6.1±0.2
J	1.0±0.2
K	0.17±0.03
L	0.5
M	0.13
N	0.10
P	3° <sup>+5°</sup> <sub>-3°</sub>
T	0.25
U	0.6±0.15

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R5F100LCAF, R5F100LDAFB, R5F100LEAFB, R5F100LFAFB, R5F100LGAFB, R5F100LHAFB, R5F100LJAFB,  
 R5F100LKAFB, R5F100LLAFB  
 R5F101LCAF, R5F101LDAFB, R5F101LEAFB, R5F101LFAFB, R5F101LGAFB, R5F101LHAFB,  
 R5F101LJAFB, R5F101LKAFB, R5F101LLAFB  
 R5F100LCDFB, R5F100LDDFB, R5F100LEDFB, R5F100LFDFB, R5F100LGDFB, R5F100LHDFB, R5F100LJDFB,  
 R5F100LKDFB, R5F100LLDFB  
 R5F101LCDFB, R5F101LDDFB, R5F101LEDFB, R5F101LFDFB, R5F101LGDFB, R5F101LHDFB,  
 R5F101LJDFB, R5F101LKDFB, R5F101LLDFB  
 R5F100LCGFB, R5F100LDGFB, R5F100LEGFB, R5F100LFGFB, R5F100LGGFB, R5F100LHGFB,  
 R5F100LJGFB

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LFQFP64-10x10-0.50	PLQP0064KF-A	P64GB-50-UEU-2	0.35

**NOTE**

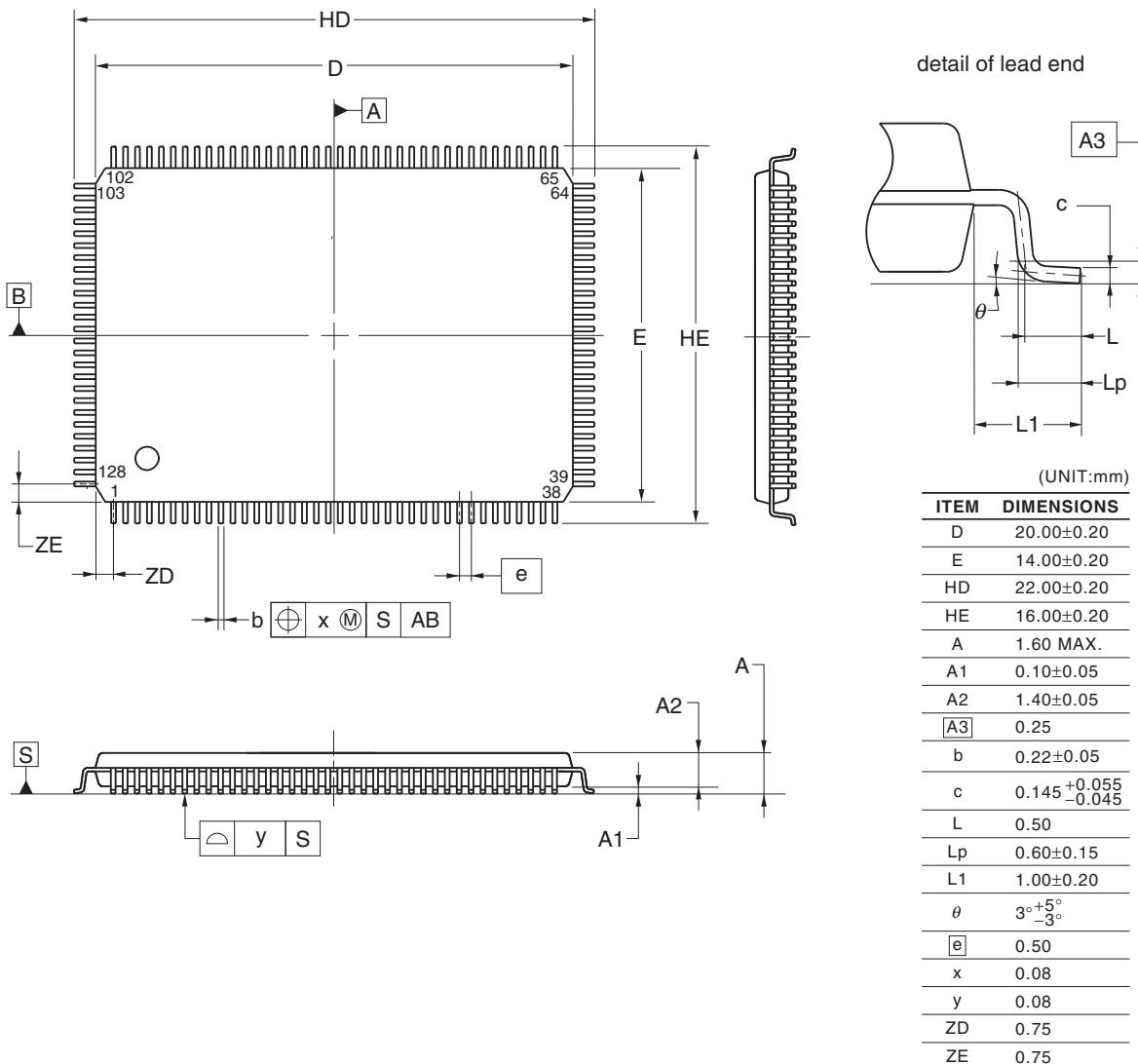
Each lead centerline is located within 0.08 mm of its true position at maximum material condition.

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## 4.14 128-pin Products

R5F100SHAFB, R5F100SJAFB, R5F100SKAFB, R5F100SLAFB  
 R5F101SHAFB, R5F101SJAFB, R5F101SKAFB, R5F101SLAFB  
 R5F100SHDFB, R5F100SJDFB, R5F100SKDFB, R5F100SLDFB  
 R5F101SHDFB, R5F101SJDFB, R5F101SKDFB, R5F101SLDFB

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LFQFP128-14x20-0.50	PLQP0128KD-A	P128GF-50-GBP-1	0.92



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