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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I <sup>2</sup> C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	48
Program Memory Size	192KB (192K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 12x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFBGA
Supplier Device Package	64-VFBGA (4x4)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f101lhabg-u0">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f101lhabg-u0</a>

Table 1-1. List of Ordering Part Numbers

(6/12)

Pin count	Package	Data flash	Fields of Application <small>Note</small>	Ordering Part Number
48 pins	48-pin plastic HWQFN (7 × 7 mm, 0.5 mm pitch)	Mounted	A D G	R5F100GAANA#U0, R5F100GCANA#U0, R5F100GDANA#U0, R5F100GEANA#U0, R5F100GFANA#U0, R5F100GGANA#U0, R5F100GHANA#U0, R5F100GJANA#U0, R5F100GKANA#U0, R5F100GLANA#U0 R5F100GAANA#W0, R5F100GCANA#W0, R5F100GDANA#W0, R5F100GEANA#W0, R5F100GFANA#W0, R5F100GGANA#W0, R5F100GHANA#W0, R5F100GJANA#W0, R5F100GKANA#W0, R5F100GLANA#W0 R5F100GADNA#U0, R5F100GCDNA#U0, R5F100GDDNA#U0, R5F100GEDNA#U0, R5F100GFDNA#U0, R5F100GGDNA#U0, R5F100GHDNA#U0, R5F100GJDNA#U0, R5F100GKDNA#U0, R5F100GLDNA#U0 R5F100GADNA#W0, R5F100GCDNA#W0, R5F100GDDNA#W0, R5F100GEDNA#W0, R5F100GFDNA#W0, R5F100GGDNA#W0, R5F100GHDNA#W0, R5F100GJDNA#W0, R5F100GKDNA#W0, R5F100GLDNA#W0 R5F100GAGNA#U0, R5F100GCGNA#U0, R5F100GDGNA#U0, R5F100GEGNA#U0, R5F100GFGNA#U0, R5F100GGGNA#U0, R5F100GHGNA#U0, R5F100GJGNA#U0 R5F100GAGNA#W0, R5F100GCGNA#W0, R5F100GDGNA#W0, R5F100GEGNA#W0, R5F100GFGNA#W0, R5F100GGGNA#W0, R5F100GHGNA#W0, R5F100GJGNA#W0
	Not mounted	A D		R5F101GAANA#U0, R5F101GCANA#U0, R5F101GDANA#U0, R5F101GEANA#U0, R5F101GFANA#U0, R5F101GGANA#U0, R5F101GHANA#U0, R5F101GJANA#U0, R5F101GKANA#U0, R5F101GLANA#U0 R5F101GAANA#W0, R5F101GCANA#W0, R5F101GDANA#W0, R5F101GEANA#W0, R5F101GFANA#W0, R5F101GGANA#W0, R5F101GHANA#W0, R5F101GJANA#W0, R5F101GKANA#W0, R5F101GLANA#W0 R5F101GADNA#U0, R5F101GCDNA#U0, R5F101GDDNA#U0, R5F101GEDNA#U0, R5F101GFDNA#U0, R5F101GGDNA#U0, R5F101GHDNA#U0, R5F101GJDNA#U0, R5F101GKDNA#U0, R5F101GLDNA#U0 R5F101GADNA#W0, R5F101GCDNA#W0, R5F101GDDNA#W0, R5F101GEDNA#W0, R5F101GFDNA#W0, R5F101GGDNA#W0, R5F101GHDNA#W0, R5F101GJDNA#W0, R5F101GKDNA#W0, R5F101GLDNA#W0

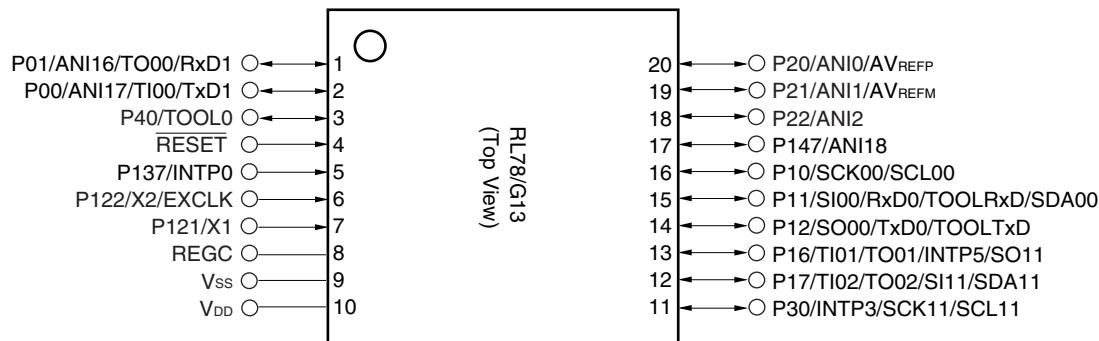
**Note** For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

**Caution** The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.

### 1.3 Pin Configuration (Top View)

#### 1.3.1 20-pin products

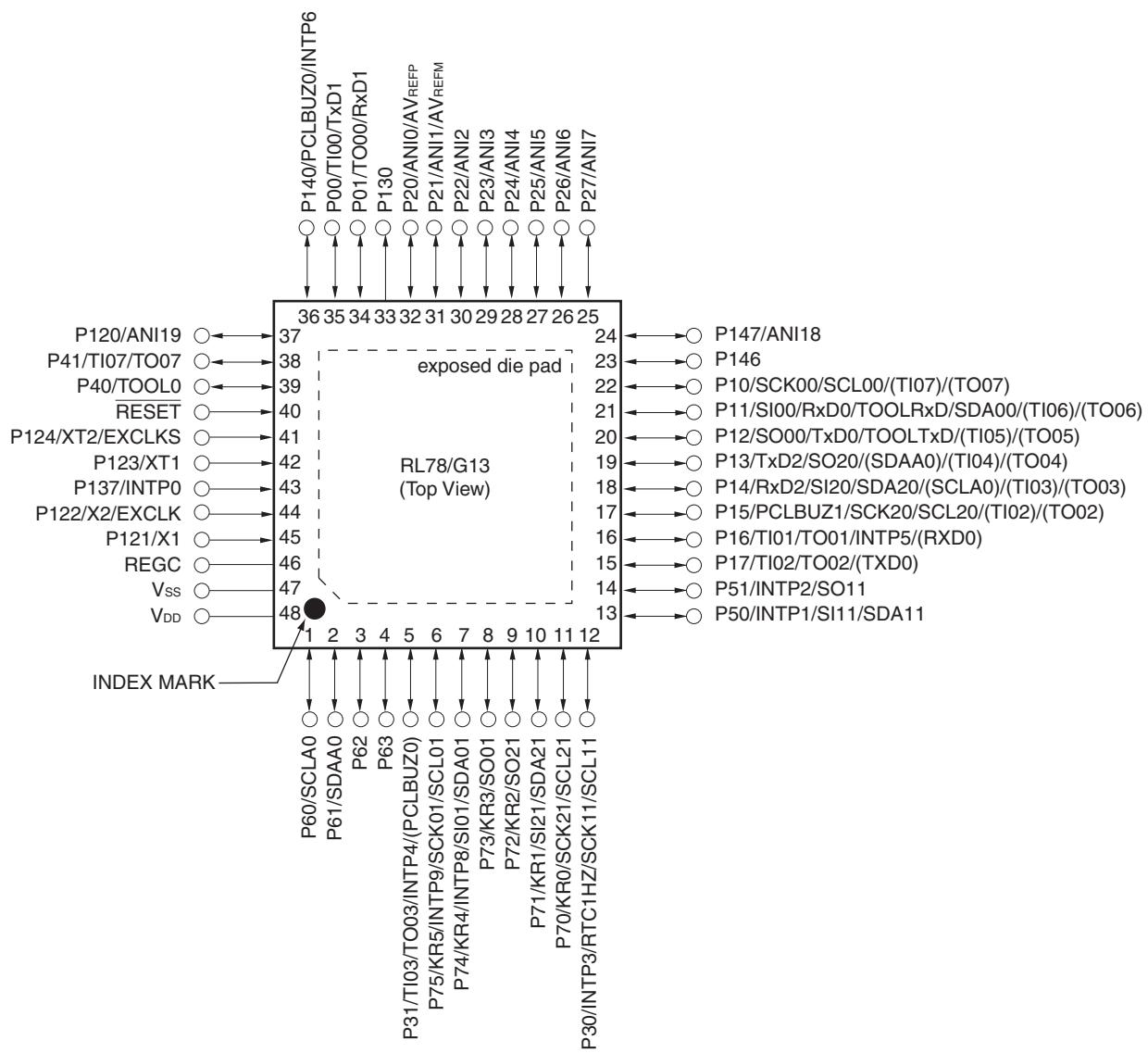
- 20-pin plastic LSSOP (7.62 mm (300), 0.65 mm pitch)



**Caution** Connect the REGC pin to V<sub>SS</sub> via a capacitor (0.47 to 1  $\mu$ F).

**Remark** For pin identification, see **1.4 Pin Identification**.

- 48-pin plastic HWQFN ( $7 \times 7$  mm, 0.5 mm pitch)



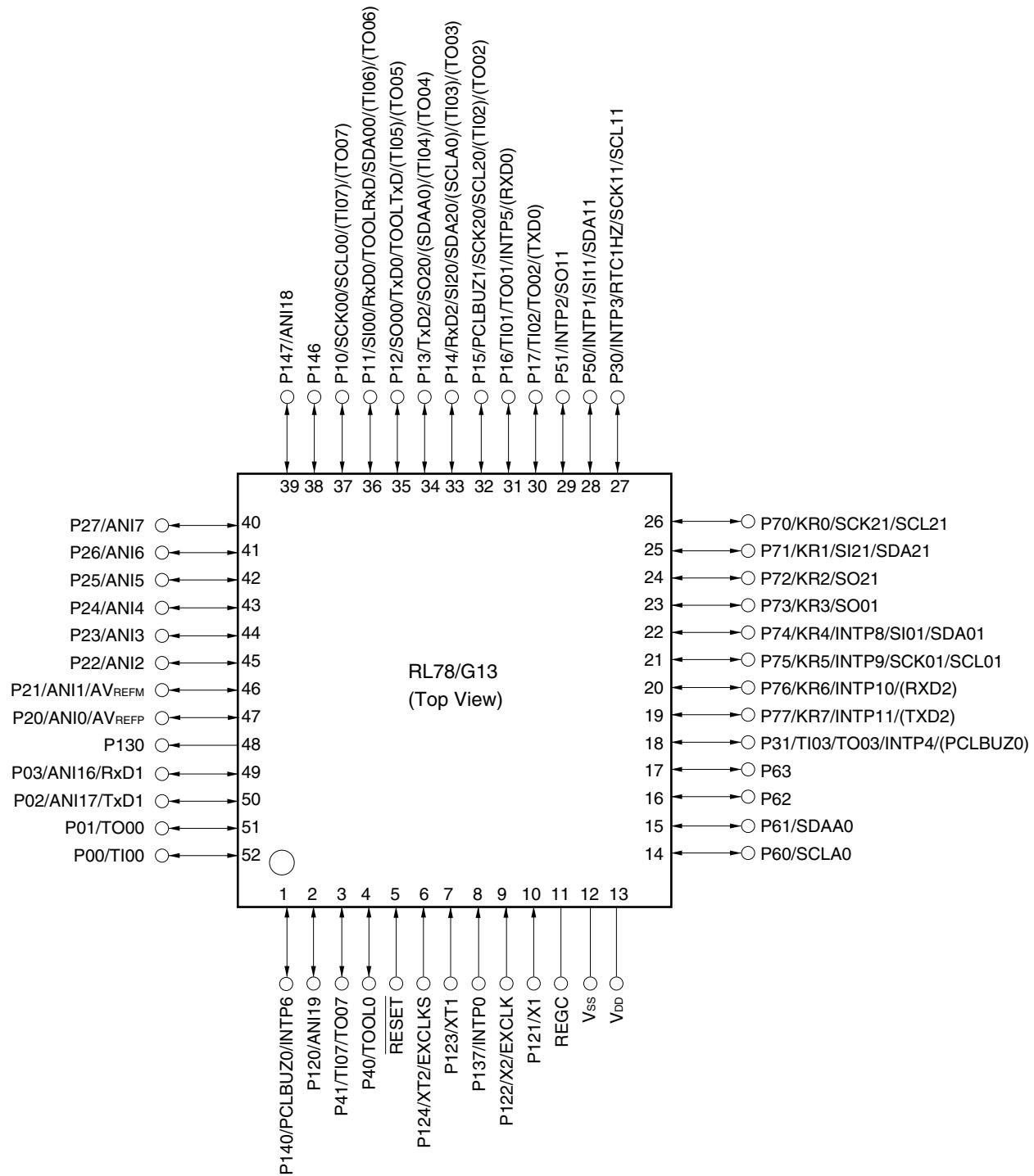
**Caution Connect the REGC pin to V<sub>ss</sub> via a capacitor (0.47 to 1  $\mu$ F).**

**Remarks 1.** For pin identification, see **1.4 Pin Identification**.

2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.
3. It is recommended to connect an exposed die pad to V<sub>ss</sub>.

### 1.3.10 52-pin products

- 52-pin plastic LQFP (10 × 10 mm, 0.65 mm pitch)

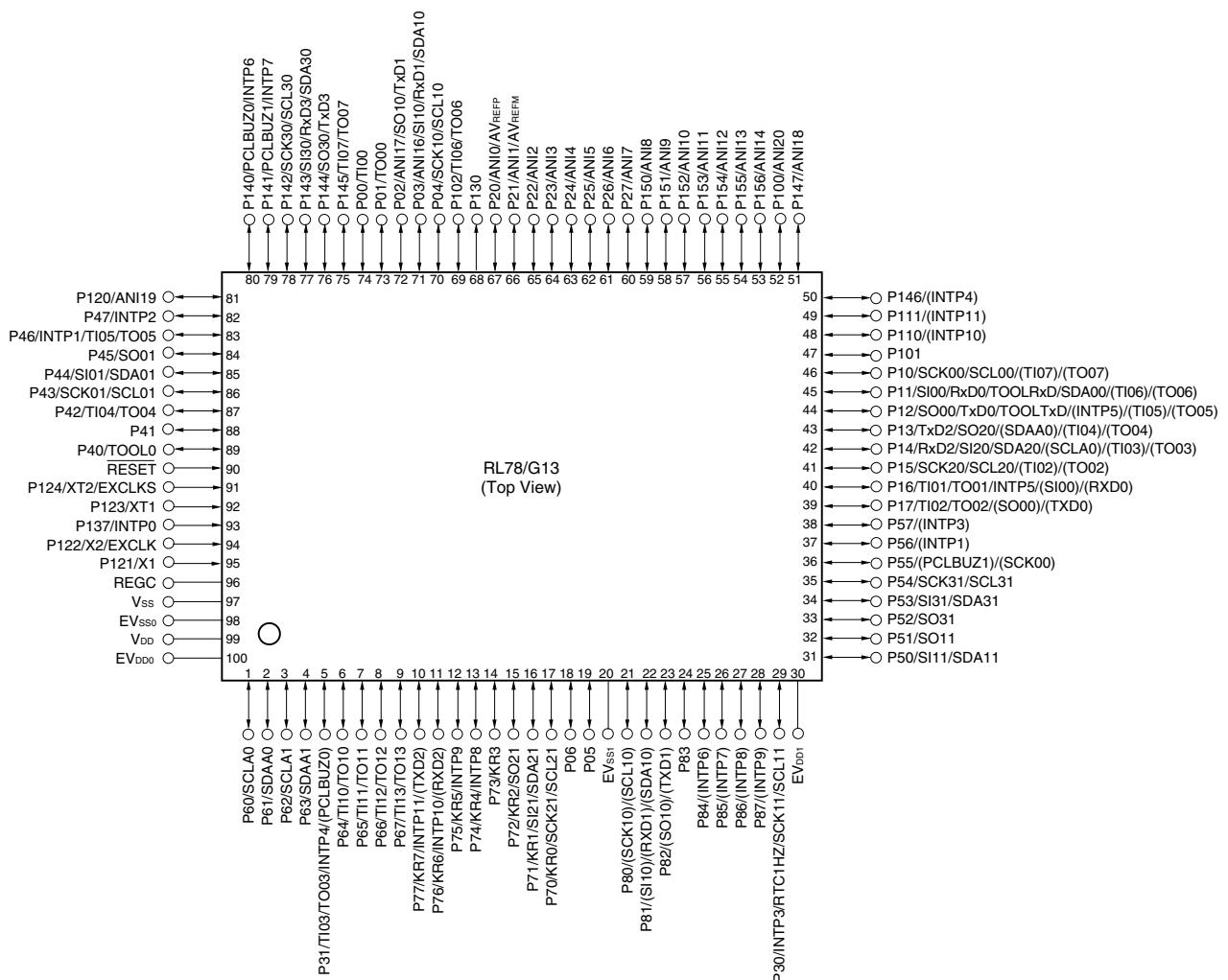


**Caution Connect the REGC pin to V<sub>ss</sub> via a capacitor (0.47 to 1  $\mu$ F).**

**Remarks 1.** For pin identification, see **1.4 Pin Identification**.

2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

- 100-pin plastic LQFP (14 × 20 mm, 0.65 mm pitch)



**Cautions** 1. Make EV<sub>SS0</sub>, EV<sub>SS1</sub> pins the same potential as V<sub>SS</sub> pin.

2. Make V<sub>DD</sub> pin the potential that is higher than EV<sub>DD0</sub>, EV<sub>DD1</sub> pins (EV<sub>DD0</sub> = EV<sub>DD1</sub>).
3. Connect the REGC pin to V<sub>SS</sub> via a capacitor (0.47 to 1  $\mu$ F).

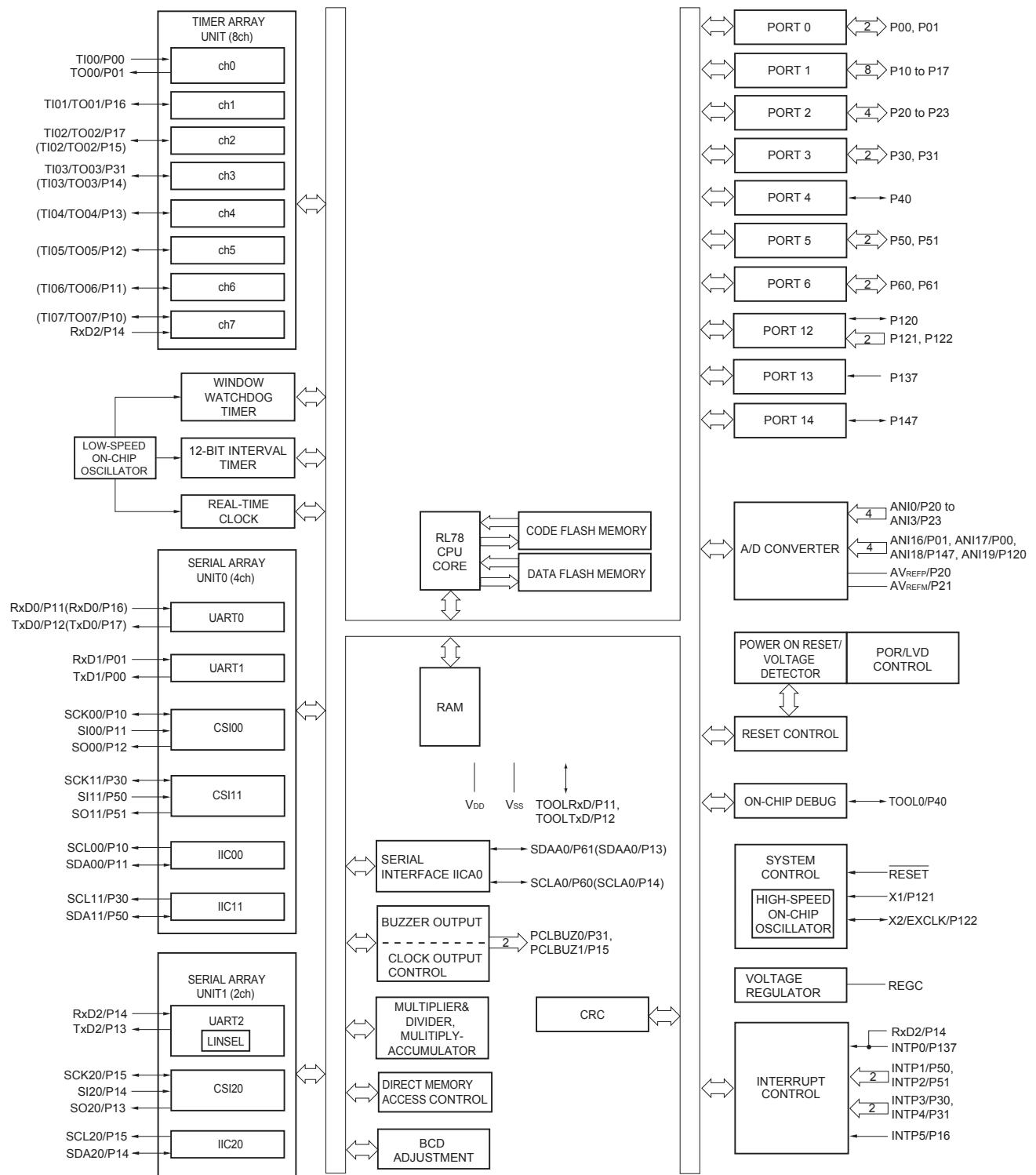
**Remarks** 1. For pin identification, see **1.4 Pin Identification**.

2. When using the microcontroller for an application where the noise generated inside the microcontroller must be reduced, it is recommended to supply separate powers to the V<sub>DD</sub>, EV<sub>DD0</sub> and EV<sub>DD1</sub> pins and connect the V<sub>SS</sub>, EV<sub>SS0</sub> and EV<sub>SS1</sub> pins to separate ground lines.
3. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

## 1.4 Pin Identification

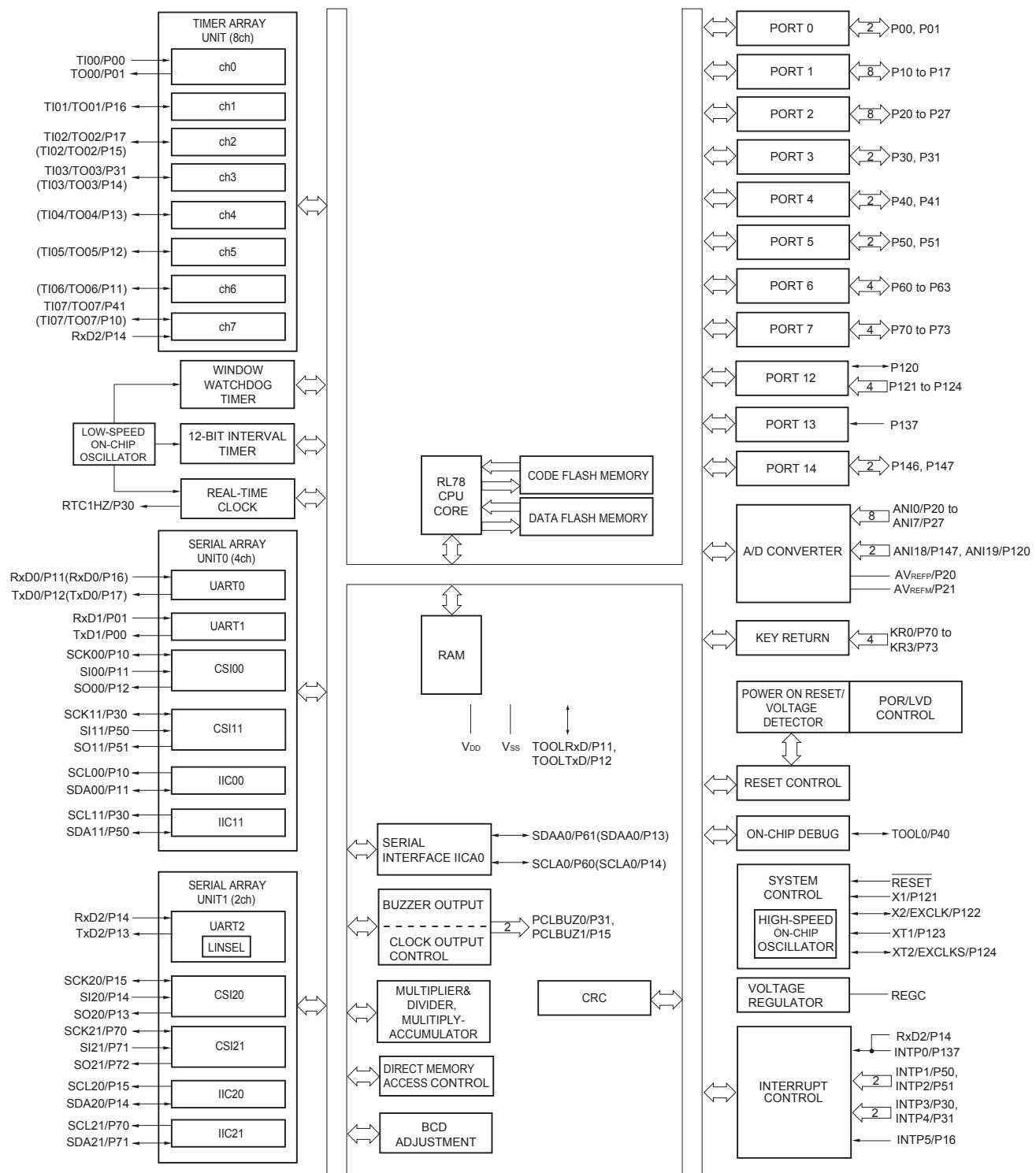
AN10 to AN14,		REGC:	Regulator capacitance
AN16 to ANI26:	Analog input	RESET:	Reset
AV <sub>REFM</sub> :	A/D converter reference potential (– side) input	RTC1HZ:	Real-time clock correction clock (1 Hz) output
AV <sub>REFP</sub> :	A/D converter reference potential (+ side) input	RxD0 to RxD3:	Receive data
EV <sub>VDD0</sub> , EV <sub>VDD1</sub> :	Power supply for port	SCK00, SCK01, SCK10, SCK11, SCK20, SCK21,	
EV <sub>SS0</sub> , EV <sub>SS1</sub> :	Ground for port	SCLA0, SCLA1:	Serial clock input/output
EXCLK:	External clock input (Main system clock)	SCLA0, SCLA1, SCL00, SCL01, SCL10, SCL11,	
EXCLKS:	External clock input (Subsystem clock)	SCL20, SCL21, SCL30, SCL31:	Serial clock output
INTP0 to INTP11:	Interrupt request from peripheral	SDAA0, SDAA1, SDA00, SDA01, SDA10, SDA11,	
KR0 to KR7:	Key return	SDA20, SDA21, SDA30, SDA31:	Serial data input/output
P00 to P07:	Port 0	SI00, SI01, SI10, SI11,	
P10 to P17:	Port 1	SI20, SI21, SI30, SI31:	Serial data input
P20 to P27:	Port 2	SO00, SO01, SO10,	
P30 to P37:	Port 3	SO11, SO20, SO21,	
P40 to P47:	Port 4	SO30, SO31:	Serial data output
P50 to P57:	Port 5	TI00 to TI07,	
P60 to P67:	Port 6	TI10 to TI17:	Timer input
P70 to P77:	Port 7	TO00 to TO07,	
P80 to P87:	Port 8	TO10 to TO17:	Timer output
P90 to P97:	Port 9	TOOL0:	Data input/output for tool
P100 to P106:	Port 10	TOOLRxD, TOOLTxD:	Data input/output for external device
P110 to P117:	Port 11	TxD0 to TxD3:	Transmit data
P120 to P127:	Port 12	V <sub>DD</sub> :	Power supply
P130, P137:	Port 13	V <sub>SS</sub> :	Ground
P140 to P147:	Port 14	X1, X2:	Crystal oscillator (main system clock)
P150 to P156:	Port 15	XT1, XT2:	Crystal oscillator (subsystem clock)
PCLBUZ0, PCLBUZ1:	Programmable clock output/buzzer output		

## 1.5.4 30-pin products



**Remark** Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

## 1.5.8 44-pin products



**Remark** Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR). Refer to **Figure 4-8 Format of Peripheral I/O Redirection Register (PIOR)** in the RL78/G13 User's Manual.

2. The number of PWM outputs varies depending on the setting of channels in use (the number of masters and slaves) (see **6.9.3 Operation as multiple PWM output function** in the RL78/G13 User's Manual).

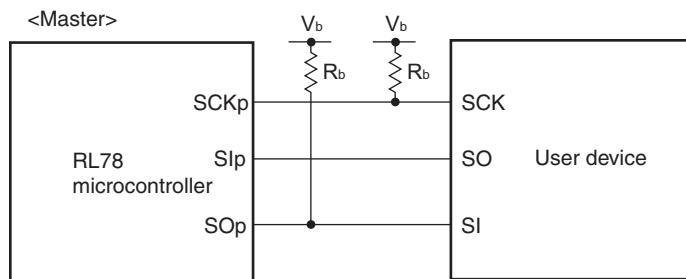
(2/2)

Item	80-pin		100-pin		128-pin	
	R5F100Mx	R5F101Mx	R5F100Px	R5F101Px	R5F100Sx	R5F101Sx
Clock output/buzzer output	2		2		2	
	<ul style="list-style-type: none"> <li>• 2.44 kHz, 4.88 kHz, 9.76 kHz, 1.25 MHz, 2.5 MHz, 5 MHz, 10 MHz (Main system clock: <math>f_{MAIN} = 20</math> MHz operation)</li> <li>• 256 Hz, 512 Hz, 1.024 kHz, 2.048 kHz, 4.096 kHz, 8.192 kHz, 16.384 kHz, 32.768 kHz (Subsystem clock: <math>f_{SUB} = 32.768</math> kHz operation)</li> </ul>					
8/10-bit resolution A/D converter	17 channels		20 channels		26 channels	
Serial interface	[80-pin, 100-pin, 128-pin products]		<ul style="list-style-type: none"> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART: 1 channel</li> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART: 1 channel</li> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART (UART supporting LIN-bus): 1 channel</li> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART: 1 channel</li> </ul>			
I <sup>2</sup> C bus	2 channels		2 channels		2 channels	
Multiplier and divider/multiply-accumulator	<ul style="list-style-type: none"> <li>• <math>16 \text{ bits} \times 16 \text{ bits} = 32 \text{ bits}</math> (Unsigned or signed)</li> <li>• <math>32 \text{ bits} \div 32 \text{ bits} = 32 \text{ bits}</math> (Unsigned)</li> <li>• <math>16 \text{ bits} \times 16 \text{ bits} + 32 \text{ bits} = 32 \text{ bits}</math> (Unsigned or signed)</li> </ul>					
DMA controller	4 channels					
Vectorized interrupt sources	Internal	37		37		41
	External	13		13		13
Key interrupt	8		8		8	
Reset	<ul style="list-style-type: none"> <li>• Reset by <math>\overline{\text{RESET}}</math> pin</li> <li>• Internal reset by watchdog timer</li> <li>• Internal reset by power-on-reset</li> <li>• Internal reset by voltage detector</li> <li>• Internal reset by illegal instruction execution <sup>Note</sup></li> <li>• Internal reset by RAM parity error</li> <li>• Internal reset by illegal-memory access</li> </ul>					
Power-on-reset circuit	<ul style="list-style-type: none"> <li>• Power-on-reset: 1.51 V (TYP.)</li> <li>• Power-down-reset: 1.50 V (TYP.)</li> </ul>					
Voltage detector	<ul style="list-style-type: none"> <li>• Rising edge : 1.67 V to 4.06 V (14 stages)</li> <li>• Falling edge : 1.63 V to 3.98 V (14 stages)</li> </ul>					
On-chip debug function	Provided					
Power supply voltage	$V_{DD} = 1.6$ to 5.5 V ( $T_A = -40$ to $+85^\circ\text{C}$ ) $V_{DD} = 2.4$ to 5.5 V ( $T_A = -40$ to $+105^\circ\text{C}$ )					
Operating ambient temperature	$T_A = 40$ to $+85^\circ\text{C}$ (A: Consumer applications, D: Industrial applications ) $T_A = 40$ to $+105^\circ\text{C}$ (G: Industrial applications)					

**Note** The illegal instruction is generated when instruction code FFH is executed.

Reset by the illegal instruction execution not issued by emulation with the in-circuit emulator or on-chip debug emulator.

&lt;R&gt;

**CSI mode connection diagram (during communication at different potential)**

- Remarks**
1.  $R_b[\Omega]$ : Communication line (SCKp, SOp) pull-up resistance,  $C_b[F]$ : Communication line (SCKp, SOp) load capacitance,  $V_b[V]$ : Communication line voltage
  2. p: CSI number (p = 00, 01, 10, 20, 30, 31), m: Unit number , n: Channel number (mn = 00, 01, 02, 10, 12, 13), g: PIM and POM number (g = 0, 1, 4, 5, 8, 14)
  3.  $f_{MCK}$ : Serial array unit operation clock frequency  
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn).  
m: Unit number, n: Channel number (mn = 00))
  4. CSI01 of 48-, 52-, 64-pin products, and CSI11 and CSI21 cannot communicate at different potential.  
Use other CSI for communication at different potential.

### 3.3 DC Characteristics

#### 3.3.1 Pin characteristics

(TA = -40 to +105°C, 2.4 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V) (1/5)

Items	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Output current, high <sup>Note 1</sup>	I <sub>OH1</sub>	Per pin for P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	2.4 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		-3.0 <sup>Note 2</sup>	mA
		Total of P00 to P04, P07, P32 to P37, P40 to P47, P102 to P106, P120, P125 to P127, P130, P140 to P145 (When duty ≤ 70% <sup>Note 3</sup> )	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		-30.0	mA
			2.7 V ≤ EV <sub>DD0</sub> < 4.0 V		-10.0	mA
			2.4 V ≤ EV <sub>DD0</sub> < 2.7 V		-5.0	mA
		Total of P05, P06, P10 to P17, P30, P31, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100, P101, P110 to P117, P146, P147 (When duty ≤ 70% <sup>Note 3</sup> )	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		-30.0	mA
			2.7 V ≤ EV <sub>DD0</sub> < 4.0 V		-19.0	mA
			2.4 V ≤ EV <sub>DD0</sub> < 2.7 V		-10.0	mA
		Total of all pins (When duty ≤ 70% <sup>Note 3</sup> )	2.4 V ≤ EV <sub>DD0</sub> ≤ 5.5 V		-60.0	mA
	I <sub>OH2</sub>	Per pin for P20 to P27, P150 to P156	2.4 V ≤ V <sub>DD</sub> ≤ 5.5 V		-0.1 <sup>Note 2</sup>	mA
		Total of all pins (When duty ≤ 70% <sup>Note 3</sup> )	2.4 V ≤ V <sub>DD</sub> ≤ 5.5 V		-1.5	mA

**Notes** 1. Value of current at which the device operation is guaranteed even if the current flows from the EV<sub>DD0</sub>, EV<sub>DD1</sub>, V<sub>DD</sub> pins to an output pin.

2. Do not exceed the total current value.

3. Specification under conditions where the duty factor ≤ 70%.

The output current value that has changed to the duty factor > 70% the duty ratio can be calculated with the following expression (when changing the duty factor from 70% to n%).

- Total output current of pins = (I<sub>OH</sub> × 0.7)/(n × 0.01)

<Example> Where n = 80% and I<sub>OH</sub> = -10.0 mA

$$\text{Total output current of pins} = (-10.0 \times 0.7)/(80 \times 0.01) \approx -8.7 \text{ mA}$$

However, the current that is allowed to flow into one pin does not vary depending on the duty factor.

A current higher than the absolute maximum rating must not flow into one pin.

**Caution** P00, P02 to P04, P10 to P15, P17, P43 to P45, P50, P52 to P55, P71, P74, P80 to P82, P96, and P142 to P144 do not output high level in N-ch open-drain mode.

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

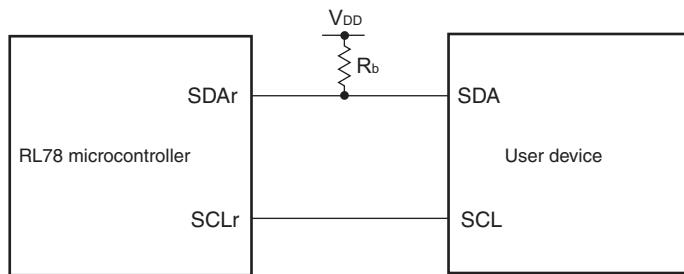
(TA = -40 to +105°C, 2.4 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V) (3/5)

Items	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Input voltage, high	V <sub>IH1</sub>	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147	Normal input buffer	0.8EV <sub>DD0</sub>		EV <sub>DD0</sub>	V
	V <sub>IH2</sub>	P01, P03, P04, P10, P11, P13 to P17, P43, P44, P53 to P55, P80, P81, P142, P143	TTL input buffer 4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	2.2		EV <sub>DD0</sub>	V
			TTL input buffer 3.3 V ≤ EV <sub>DD0</sub> < 4.0 V	2.0		EV <sub>DD0</sub>	V
			TTL input buffer 2.4 V ≤ EV <sub>DD0</sub> < 3.3 V	1.5		EV <sub>DD0</sub>	V
	V <sub>IH3</sub>	P20 to P27, P150 to P156		0.7V <sub>DD</sub>		V <sub>DD</sub>	V
	V <sub>IH4</sub>	P60 to P63		0.7EV <sub>DD0</sub>		6.0	V
	V <sub>IH5</sub>	P121 to P124, P137, EXCLK, EXCLKS, RESET		0.8V <sub>DD</sub>		V <sub>DD</sub>	V
Input voltage, low	V <sub>IL1</sub>	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P140 to P147	Normal input buffer	0		0.2EV <sub>DD0</sub>	V
	V <sub>IL2</sub>	P01, P03, P04, P10, P11, P13 to P17, P43, P44, P53 to P55, P80, P81, P142, P143	TTL input buffer 4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V	0		0.8	V
			TTL input buffer 3.3 V ≤ EV <sub>DD0</sub> < 4.0 V	0		0.5	V
			TTL input buffer 2.4 V ≤ EV <sub>DD0</sub> < 3.3 V	0		0.32	V
	V <sub>IL3</sub>	P20 to P27, P150 to P156		0		0.3V <sub>DD</sub>	V
	V <sub>IL4</sub>	P60 to P63		0		0.3EV <sub>DD0</sub>	V
	V <sub>IL5</sub>	P121 to P124, P137, EXCLK, EXCLKS, RESET		0		0.2V <sub>DD</sub>	V

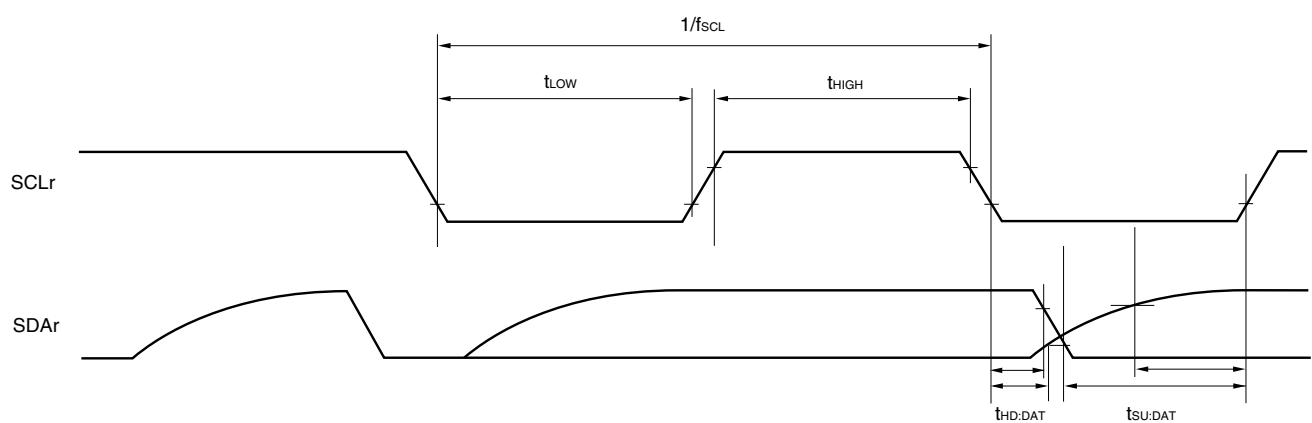
**Caution** The maximum value of V<sub>IH</sub> of pins P00, P02 to P04, P10 to P15, P17, P43 to P45, P50, P52 to P55, P71, P74, P80 to P82, P96, and P142 to P144 is EV<sub>DD0</sub>, even in the N-ch open-drain mode.

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

**Simplified I<sup>2</sup>C mode connection diagram (during communication at same potential)**



**Simplified I<sup>2</sup>C mode serial transfer timing (during communication at same potential)**



**Remarks** 1.  $R_b[\Omega]$ :Communication line (SDAr) pull-up resistance,  $C_b[F]$ : Communication line (SDAr, SCLr) load capacitance

2. r: IIC number ( $r = 00, 01, 10, 11, 20, 21, 30, 31$ ), g: PIM number ( $g = 0, 1, 4, 5, 8, 14$ ), h: POM number ( $g = 0, 1, 4, 5, 7 \text{ to } 9, 14$ )

3.  $f_{MCK}$ : Serial array unit operation clock frequency

(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number ( $m = 0, 1$ ), n: Channel number ( $n = 0 \text{ to } 3$ ), mn = 00 to 03, 10 to 13)

## (5) Communication at different potential (1.8 V, 2.5 V, 3 V) (UART mode) (2/2)

(TA = -40 to +105°C, 2.4 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>SS0</sub> = EV<sub>SS1</sub> = 0 V)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		Unit
				MIN.	MAX.	
Transfer rate	Transmission	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V	Theoretical value of the maximum transfer rate C <sub>b</sub> = 50 pF, R <sub>b</sub> = 1.4 kΩ, V <sub>b</sub> = 2.7 V		<b>Note 1</b>	bps
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V	Theoretical value of the maximum transfer rate C <sub>b</sub> = 50 pF, R <sub>b</sub> = 2.7 kΩ, V <sub>b</sub> = 2.3 V		<b>Note 3</b>	bps
		2.4 V ≤ EV <sub>DD0</sub> < 3.3 V, 1.6 V ≤ V <sub>b</sub> ≤ 2.0 V	Theoretical value of the maximum transfer rate C <sub>b</sub> = 50 pF, R <sub>b</sub> = 5.5 kΩ, V <sub>b</sub> = 1.6 V		<b>Note 5</b>	bps

**Notes 1.** The smaller maximum transfer rate derived by using f<sub>MCK</sub>/12 or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when 4.0 V ≤ EV<sub>DD0</sub> ≤ 5.5 V and 2.7 V ≤ V<sub>b</sub> ≤ 4.0 V

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{2.2}{V_b})\} \times 3} \text{ [bps]}$$

$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{2.2}{V_b})\}}{\frac{1}{(\text{Transfer rate})} \times \text{Number of transferred bits}} \times 100 [\%]$$

\* This value is the theoretical value of the relative difference between the transmission and reception sides.

2. This value as an example is calculated when the conditions described in the “Conditions” column are met. Refer to Note 1 above to calculate the maximum transfer rate under conditions of the customer.
3. The smaller maximum transfer rate derived by using f<sub>MCK</sub>/12 or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when 2.7 V ≤ EV<sub>DD0</sub> < 4.0 V and 2.4 V ≤ V<sub>b</sub> ≤ 2.7 V

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{2.0}{V_b})\} \times 3} \text{ [bps]}$$

$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{2.0}{V_b})\}}{\frac{1}{(\text{Transfer rate})} \times \text{Number of transferred bits}} \times 100 [\%]$$

\* This value is the theoretical value of the relative difference between the transmission and reception sides.

4. This value as an example is calculated when the conditions described in the “Conditions” column are met. Refer to Note 3 above to calculate the maximum transfer rate under conditions of the customer.

### 3.6 Analog Characteristics

#### 3.6.1 A/D converter characteristics

Classification of A/D converter characteristics

Input channel	Reference Voltage		
	Reference voltage (+) = AVREFP Reference voltage (-) = AVREFM	Reference voltage (+) = VDD Reference voltage (-) = Vss	Reference voltage (+) = VBGR Reference voltage (-) = AVREFM
ANI0 to ANI14	Refer to 3.6.1 (1).	Refer to 3.6.1 (3).	Refer to 3.6.1 (4).
ANI16 to ANI26	Refer to 3.6.1 (2).		
Internal reference voltage Temperature sensor output voltage	Refer to 3.6.1 (1).		—

- (1) When reference voltage (+) = AVREFP/ANI0 (ADREFP1 = 0, ADREFP0 = 1), reference voltage (-) = AVREFM/ANI1 (ADREFM = 1), target pin : ANI2 to ANI14, internal reference voltage, and temperature sensor output voltage

(TA = -40 to +105°C, 2.4 V ≤ AVREFP ≤ VDD ≤ 5.5 V, Vss = 0 V, Reference voltage (+) = AVREFP, Reference voltage (-) = AVREFM = 0 V)

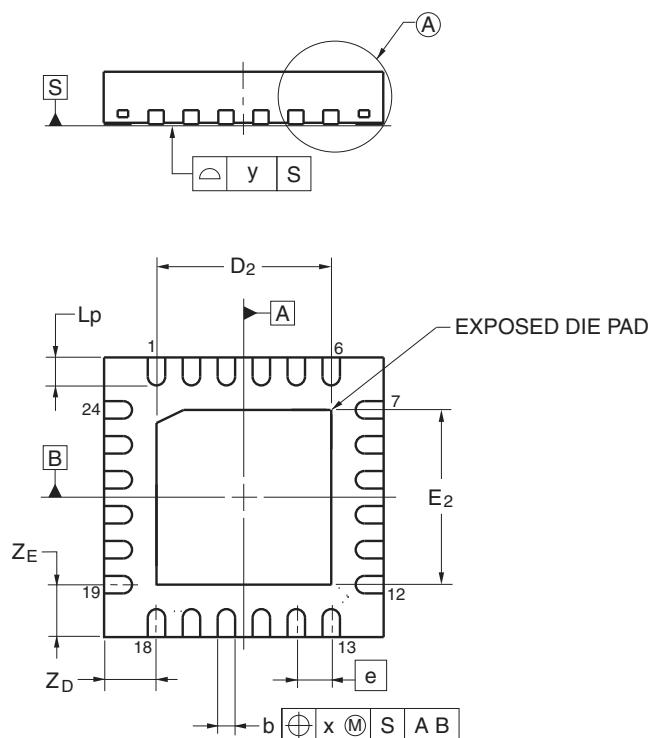
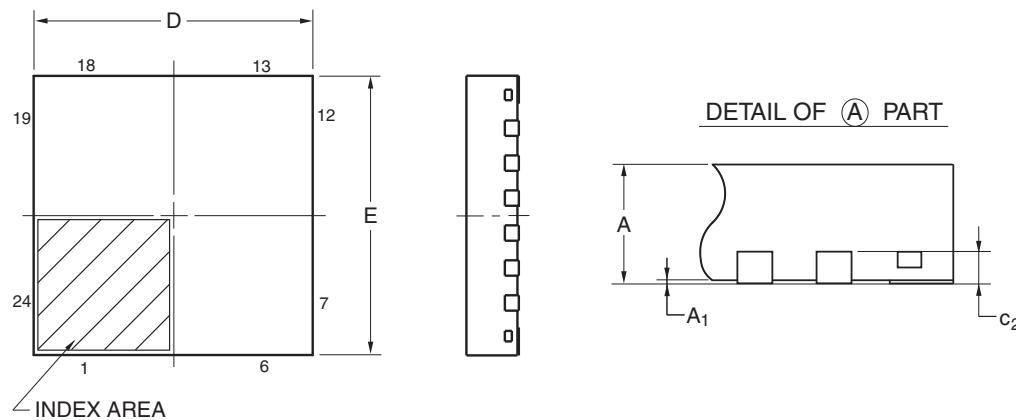
Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Resolution	RES			8		10	bit
Overall error <sup>Note 1</sup>	AINL	10-bit resolution AVREFP = VDD <sup>Note 3</sup>	2.4 V ≤ AVREFP ≤ 5.5 V		1.2	±3.5	LSB
Conversion time	tCONV	10-bit resolution Target pin: ANI2 to ANI14	3.6 V ≤ VDD ≤ 5.5 V	2.125		39	μs
			2.7 V ≤ VDD ≤ 5.5 V	3.1875		39	μs
			2.4 V ≤ VDD ≤ 5.5 V	17		39	μs
		10-bit resolution Target pin: Internal reference voltage, and temperature sensor output voltage (HS (high-speed main) mode)	3.6 V ≤ VDD ≤ 5.5 V	2.375		39	μs
			2.7 V ≤ VDD ≤ 5.5 V	3.5625		39	μs
			2.4 V ≤ VDD ≤ 5.5 V	17		39	μs
Zero-scale error <sup>Notes 1, 2</sup>	Ezs	10-bit resolution AVREFP = VDD <sup>Note 3</sup>	2.4 V ≤ AVREFP ≤ 5.5 V			±0.25	%FSR
Full-scale error <sup>Notes 1, 2</sup>	Efs	10-bit resolution AVREFP = VDD <sup>Note 3</sup>	2.4 V ≤ AVREFP ≤ 5.5 V			±0.25	%FSR
Integral linearity error <sup>Note 1</sup>	ILE	10-bit resolution AVREFP = VDD <sup>Note 3</sup>	2.4 V ≤ AVREFP ≤ 5.5 V			±2.5	LSB
Differential linearity error <sup>Note 1</sup>	DLE	10-bit resolution AVREFP = VDD <sup>Note 3</sup>	2.4 V ≤ AVREFP ≤ 5.5 V			±1.5	LSB
Analog input voltage	VAIN	ANI2 to ANI14		0		AVREFP	V
		Internal reference voltage output (2.4 V ≤ VDD ≤ 5.5 V, HS (high-speed main) mode)			VBGR <sup>Note 4</sup>		V
		Temperature sensor output voltage (2.4 V ≤ VDD ≤ 5.5 V, HS (high-speed main) mode)			VTMPS25 <sup>Note 4</sup>		V

(Notes are listed on the next page.)

## 4.2 24-pin Products

R5F1007AANA, R5F1007CANA, R5F1007DANA, R5F1007EANA  
 R5F1017AANA, R5F1017CANA, R5F1017DANA, R5F1017EANA  
 R5F1007ADNA, R5F1007CDNA, R5F1007DDNA, R5F1007EDNA  
 R5F1017ADNA, R5F1017CDNA, R5F1017DDNA, R5F1017EDNA  
 R5F1007AGNA, R5F1007CGNA, R5F1007DGNA, R5F1007EGNA

JEITA Package code	RENESAS code	Previous code	MASS(TYP.)[g]
P-HWQFN24-4x4-0.50	PWQN0024KE-A	P24K8-50-CAB-3	0.04

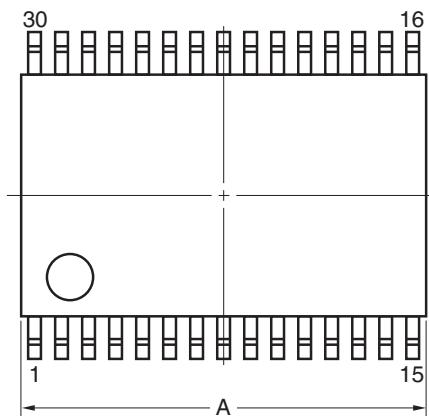


Reference Symbol	Dimension in Millimeters		
	Min	Nom	Max
D	3.95	4.00	4.05
E	3.95	4.00	4.05
A	—	—	0.80
A <sub>1</sub>	0.00	—	—
b	0.18	0.25	0.30
[e]	—	0.50	—
L <sub>p</sub>	0.30	0.40	0.50
x	—	—	0.05
y	—	—	0.05
Z <sub>D</sub>	—	0.75	—
Z <sub>E</sub>	—	0.75	—
c <sub>2</sub>	0.15	0.20	0.25
D <sub>2</sub>	—	2.50	—
E <sub>2</sub>	—	2.50	—

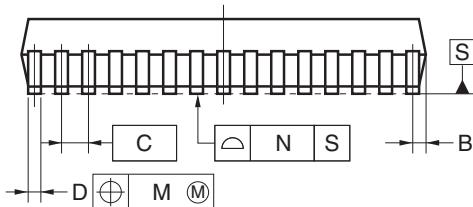
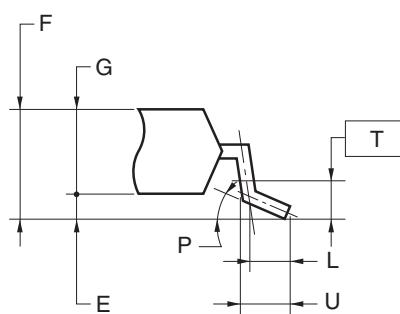
#### 4.4 30-pin Products

R5F100AAASP, R5F100ACASP, R5F100ADASP, R5F100AEASP, R5F100AFASP, R5F100AGASP  
 R5F101AAASP, R5F101ACASP, R5F101ADASP, R5F101AEASP, R5F101AFASP, R5F101AGASP  
 R5F100AADSP, R5F100ACDSP, R5F100ADDSP, R5F100AEDSP, R5F100AFDSP, R5F100AGDSP  
 R5F101AADSP, R5F101ACDSP, R5F101ADDSP, R5F101AEDSP, R5F101AFDSP, R5F101AGDSP  
 R5F100AAGSP, R5F100ACGSP, R5F100ADGSP, R5F100AEGSP, R5F100AFGSP, R5F100AGGSP

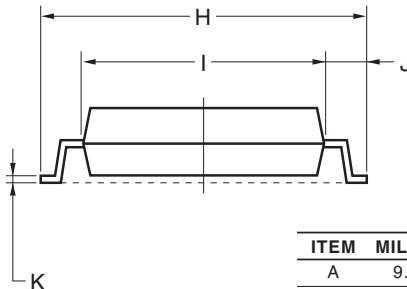
JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LSSOP30-0300-0.65	PLSP0030JB-B	S30MC-65-5A4-3	0.18



detail of lead end

**NOTE**

Each lead centerline is located within 0.13 mm of its true position (T.P.) at maximum material condition.



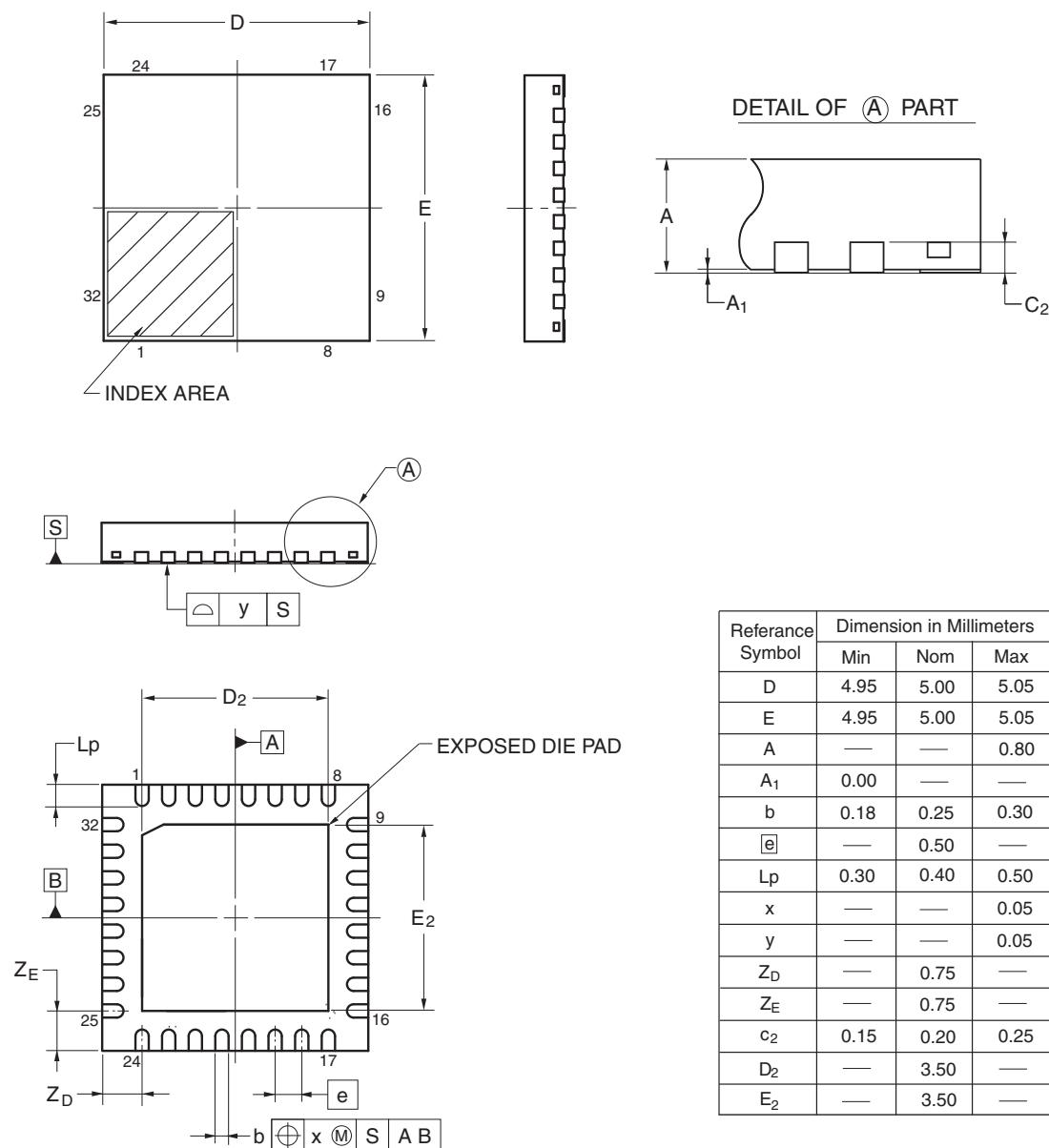
ITEM	MILLIMETERS
A	9.85±0.15
B	0.45 MAX.
C	0.65 (T.P.)
D	0.24 <sup>+0.08</sup> <sub>-0.07</sub>
E	0.1±0.05
F	1.3±0.1
G	1.2
H	8.1±0.2
I	6.1±0.2
J	1.0±0.2
K	0.17±0.03
L	0.5
M	0.13
N	0.10
P	3° <sup>+5°</sup> <sub>-3°</sub>
T	0.25
U	0.6±0.15

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## 4.5 32-pin Products

R5F100BAANA, R5F100BCANA, R5F100BDANA, R5F100BEANA, R5F100BFANA, R5F100BGANA  
 R5F101BAANA, R5F101BCANA, R5F101BDANA, R5F101BEANA, R5F101BFANA, R5F101BGANA  
 R5F100BADNA, R5F100BCDNA, R5F100BDDNA, R5F100BEDNA, R5F100BFDNA, R5F100BGDNA  
 R5F101BADNA, R5F101BCDNA, R5F101BDDNA, R5F101BEDNA, R5F101BFDNA, R5F101BGDNA  
 R5F100BAGNA, R5F100BCGNA, R5F100BDGNA, R5F100BEGNA, R5F100BFGNA, R5F100BGGNA

JEITA Package code	RENESAS code	Previous code	MASS (TYP.)[g]
P-HWQFN32-5x5-0.50	PWQN0032KB-A	P32K8-50-3B4-5	0.06



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R5F100LCABG, R5F100LDABG, R5F100LEABG, R5F100LFABG, R5F100LGABG, R5F100LHABG,

R5F100LJABG

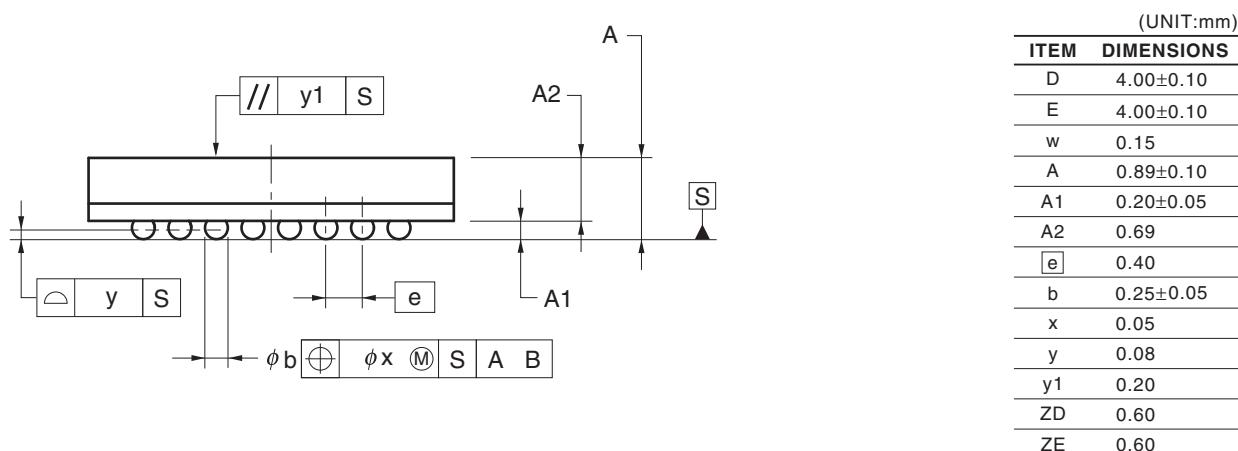
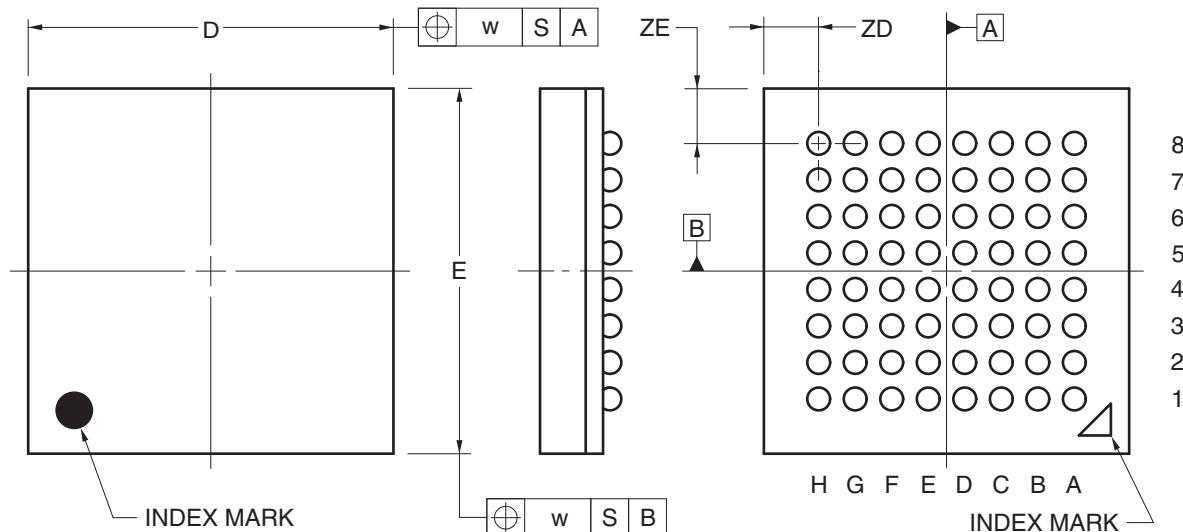
R5F101LCABG, R5F101LDABG, R5F101LEABG, R5F101LFABG, R5F101LGABG, R5F101LHABG,

R5F101LJABG

R5F100LCGBG, R5F100LDGBG, R5F100LEGBG, R5F100LFGBG, R5F100LGGBG, R5F100LHGBG,

R5F100LJGBG

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-VFBGA64-4x4-0.40	PVBG0064LA-A	P64F1-40-AA2-2	0.03



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## NOTES FOR CMOS DEVICES

- (1) VOLTAGE APPLICATION WAVEFORM AT INPUT PIN: Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between VIL (MAX) and VIH (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between VIL (MAX) and VIH (MIN).
- (2) HANDLING OF UNUSED INPUT PINS: Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.
- (3) PRECAUTION AGAINST ESD: A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.
- (4) STATUS BEFORE INITIALIZATION: Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.
- (5) POWER ON/OFF SEQUENCE: In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current. The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.
- (6) INPUT OF SIGNAL DURING POWER OFF STATE : Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.