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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I <sup>2</sup> C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	48
Program Memory Size	192KB (192K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 12x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LFQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f101lhafb-50">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f101lhafb-50</a>

**Table 1-1. List of Ordering Part Numbers**

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Pin count	Package	Data flash	Fields of Application <small>Note</small>	Ordering Part Number
44 pins	44-pin plastic LQFP (10 × 10 mm, 0.8 mm pitch)	Mounted	A D G	R5F100FAAFP#V0, R5F100FC AFP#V0, R5F100FDAFP#V0, R5F100FEA FP#V0, R5F100FFA FP#V0, R5F100FGA FP#V0, R5F100FH A FP#V0, R5F100FJA FP#V0, R5F100FKA FP#V0, R5F100FLA FP#V0 R5F100FAAFP#X0, R5F100FC AFP#X0, R5F100FDAFP#X0, R5F100FEA FP#X0, R5F100FFA FP#X0, R5F100FGA FP#X0, R5F100FH A FP#X0, R5F100FJA FP#X0, R5F100FKA FP#X0, R5F100FLA FP#X0 R5F100FADFP#V0, R5F100FCDFP#V0, R5F100FDDFP#V0, R5F100FEDFP#V0, R5F100FFDFP#V0, R5F100FGDFP#V0, R5F100FHDFP#V0, R5F100FJDFP#V0, R5F100FKDFP#V0, R5F100FLDFP#V0 R5F100FADFP#X0, R5F100FCDFP#X0, R5F100FDDFP#X0, R5F100FEDFP#X0, R5F100FFDFP#X0, R5F100FGDFP#X0, R5F100FHDFP#X0, R5F100FJDFP#X0, R5F100FKDFP#X0, R5F100FLDFP#X0 R5F100FAGFP#V0, R5F100FC GFP#V0, R5F100FDGFP#V0, R5F100FEGFP#V0, R5F100FF GFP#V0, R5F100FG GFP#V0, R5F100FH GFP#V0, R5F100FJ GFP#V0 R5F100FAGFP#X0, R5F100FC GFP#X0, R5F100FDGFP#X0, R5F100FEGFP#X0, R5F100FF GFP#X0, R5F100FG GFP#X0, R5F100FH GFP#X0, R5F100FJ GFP#X0
	Not mounted	A D		R5F101FAAFP#V0, R5F101FC AFP#V0, R5F101FDAFP#V0, R5F101FEA FP#V0, R5F101FFA FP#V0, R5F101FGA FP#V0, R5F101FH A FP#V0, R5F101FJA FP#V0, R5F101FKA FP#V0, R5F101FLA FP#V0 R5F101FAAFP#X0, R5F101FC AFP#X0, R5F101FDAFP#X0, R5F101FEA FP#X0, R5F101FFA FP#X0, R5F101FGA FP#X0, R5F101FH A FP#X0, R5F101FJA FP#X0, R5F101FKA FP#X0, R5F101FLA FP#X0 R5F101FADFP#V0, R5F101FCDFP#V0, R5F101FDDFP#V0, R5F101FEDFP#V0, R5F101FFDFP#V0, R5F101FGDFP#V0, R5F101FHDFP#V0, R5F101FJDFP#V0, R5F101FKDFP#V0, R5F101FLDFP#V0 R5F101FADFP#X0, R5F101FCDFP#X0, R5F101FDDFP#X0, R5F101FEDFP#X0, R5F101FFDFP#X0, R5F101FGDFP#X0, R5F101FHDFP#X0, R5F101FJDFP#X0, R5F101FKDFP#X0, R5F101FLDFP#X0

**Note** For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

**Caution** The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.

**Table 1-1. List of Ordering Part Numbers**

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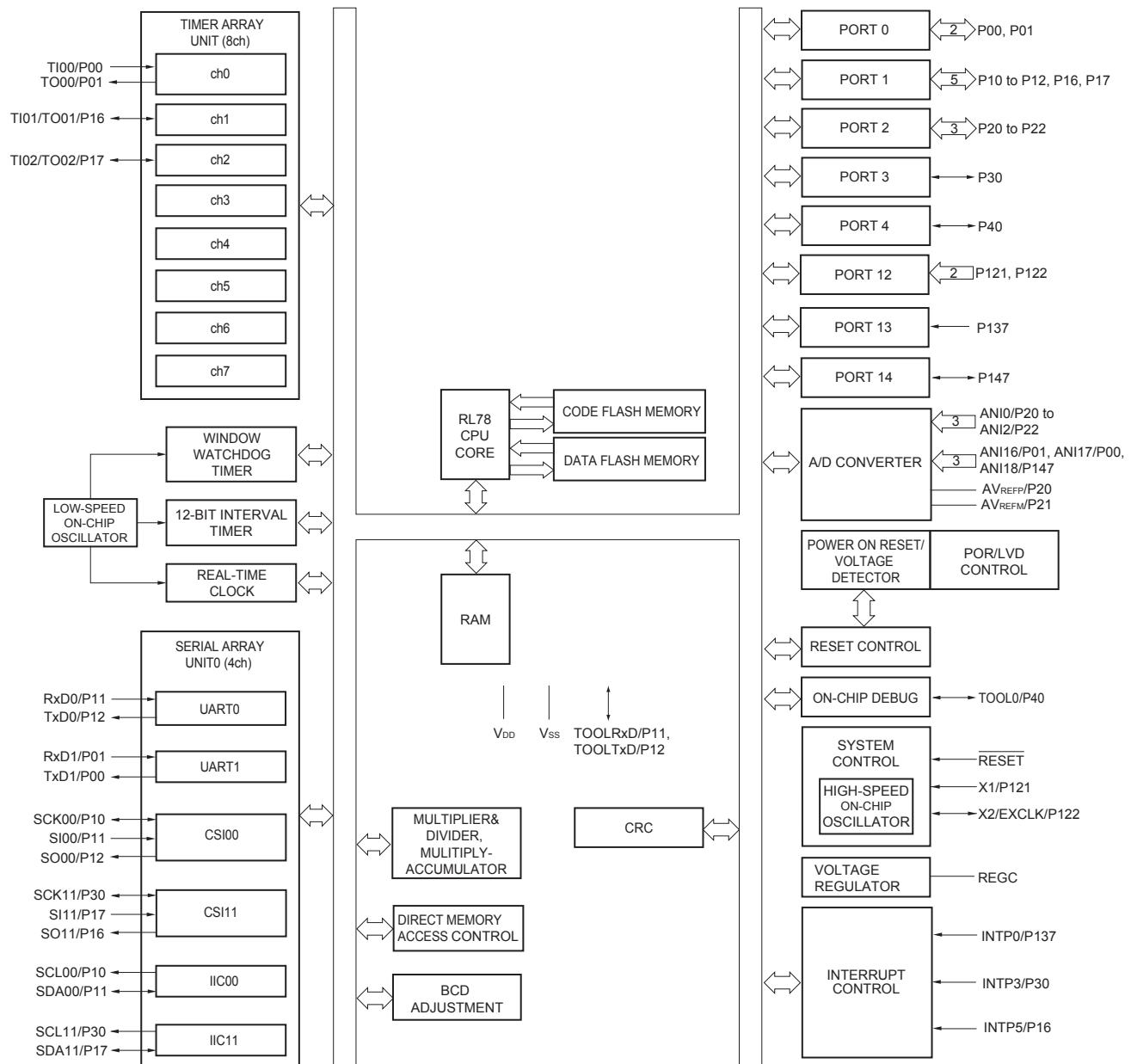
Pin count	Package	Data flash	Fields of Application <small>Note</small>	Ordering Part Number
48 pins	48-pin plastic LFQFP (7 × 7 mm, 0.5 mm pitch)	Mounted	A D G	R5F100GAAFB#V0, R5F100GCAFB#V0, R5F100GDAFB#V0, R5F100GEAFB#V0, R5F100GFAB#V0, R5F100GGAFB#V0, R5F100GHAFB#V0, R5F100GJAFB#V0, R5F100GKAFB#V0, R5F100GLAFB#V0 R5F100GAAFB#X0, R5F100GCAFB#X0, R5F100GDAFB#X0, R5F100GEAFB#X0, R5F100GFAB#X0, R5F100GGAFB#X0, R5F100GHAFB#X0, R5F100GJAFB#X0, R5F100GKAFB#X0, R5F100GLAFB#X0 R5F100GADFB#V0, R5F100GCDFB#V0, R5F100GDDFB#V0, R5F100GEDFB#V0, R5F100GFDFB#V0, R5F100GGDFB#V0, R5F100GHDFB#V0, R5F100GJDFB#V0, R5F100GKDFB#V0, R5F100GLDFB#V0 R5F100GADFB#X0, R5F100GCDFB#X0, R5F100GDDFB#X0, R5F100GEDFB#X0, R5F100GFDFB#X0, R5F100GGDFB#X0, R5F100GHDFB#X0, R5F100GJDFB#X0, R5F100GKDFB#X0, R5F100GLDFB#X0 R5F100GAGFB#V0, R5F100GCGFB#V0, R5F100GDGFB#V0, R5F100GEGFB#V0, R5F100GFGFB#V0, R5F100GGGFB#V0, R5F100GHGFB#V0, R5F100GJGFB#V0 R5F100GAGFB#X0, R5F100GCGFB#X0, R5F100GDGFB#X0, R5F100GEGFB#X0, R5F100GFGFB#X0, R5F100GGGFB#X0, R5F100GHGFB#X0, R5F100GJGFB#X0
		Not mounted	A D	R5F101GAAFB#V0, R5F101GCAFB#V0, R5F101GDAFB#V0, R5F101GEAFB#V0, R5F101GFAB#V0, R5F101GGAFB#V0, R5F101GHAFB#V0, R5F101GJAFB#V0, R5F101GKAFB#V0, R5F101GLAFB#V0 R5F101GAAFB#X0, R5F101GCAFB#X0, R5F101GDAFB#X0, R5F101GEAFB#X0, R5F101GFAB#X0, R5F101GGAFB#X0, R5F101GHAFB#X0, R5F101GJAFB#X0, R5F101GKAFB#X0, R5F101GLAFB#X0 R5F101GADFB#V0, R5F101GCDFB#V0, R5F101GDDFB#V0, R5F101GEDFB#V0, R5F101GFDFB#V0, R5F101GGDFB#V0, R5F101GHDFB#V0, R5F101GJDFB#V0, R5F101GKDFB#V0, R5F101GLDFB#V0 R5F101GADFB#X0, R5F101GCDFB#X0, R5F101GDDFB#X0, R5F101GEDFB#X0, R5F101GFDFB#X0, R5F101GGDFB#X0, R5F101GHDFB#X0, R5F101GJDFB#X0, R5F101GKDFB#X0, R5F101GLDFB#X0

**Note** For the fields of application, refer to **Figure 1-1 Part Number, Memory Size, and Package of RL78/G13**.

**Caution** The ordering part numbers represent the numbers at the time of publication. For the latest ordering part numbers, refer to the target product page of the Renesas Electronics website.

## 1.5 Block Diagram

### 1.5.1 20-pin products



2. The number of PWM outputs varies depending on the setting of channels in use (the number of masters and slaves) (see **6.9.3 Operation as multiple PWM output function** in the RL78/G13 User's Manual).
3. When setting to PIOR = 1

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Item	40-pin		44-pin		48-pin		52-pin		64-pin	
	R5F100EX	R5F101EX	R5F100FX	R5F101FX	R5F100GX	R5F101GX	R5F100JX	R5F101JX	R5F100LX	R5F101LX
Clock output/buzzer output	2		2		2		2		2	
<ul style="list-style-type: none"> <li>• 2.44 kHz, 4.88 kHz, 9.76 kHz, 1.25 MHz, 2.5 MHz, 5 MHz, 10 MHz (Main system clock: <math>f_{MAIN} = 20</math> MHz operation)</li> <li>• 256 Hz, 512 Hz, 1.024 kHz, 2.048 kHz, 4.096 kHz, 8.192 kHz, 16.384 kHz, 32.768 kHz (Subsystem clock: <math>f_{SUB} = 32.768</math> kHz operation)</li> </ul>										
8/10-bit resolution A/D converter	9 channels		10 channels		10 channels		12 channels		12 channels	
Serial interface	<p>[40-pin, 44-pin products]</p> <ul style="list-style-type: none"> <li>• CSI: 1 channel/simplified I<sup>2</sup>C: 1 channel/UART: 1 channel</li> <li>• CSI: 1 channel/simplified I<sup>2</sup>C: 1 channel/UART: 1 channel</li> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART (UART supporting LIN-bus): 1 channel</li> </ul> <p>[48-pin, 52-pin products]</p> <ul style="list-style-type: none"> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART: 1 channel</li> <li>• CSI: 1 channel/simplified I<sup>2</sup>C: 1 channel/UART: 1 channel</li> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART (UART supporting LIN-bus): 1 channel</li> </ul> <p>[64-pin products]</p> <ul style="list-style-type: none"> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART: 1 channel</li> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART: 1 channel</li> <li>• CSI: 2 channels/simplified I<sup>2</sup>C: 2 channels/UART (UART supporting LIN-bus): 1 channel</li> </ul>									
I <sup>2</sup> C bus	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel	1 channel
Multiplier and divider/multiply-accumulator	<ul style="list-style-type: none"> <li>• 16 bits × 16 bits = 32 bits (Unsigned or signed)</li> <li>• 32 bits ÷ 32 bits = 32 bits (Unsigned)</li> <li>• 16 bits × 16 bits + 32 bits = 32 bits (Unsigned or signed)</li> </ul>									
DMA controller	2 channels									
Vectored interrupt sources	Internal	27	27	27	27	27	27	27	27	27
	External	7	7	10	12	12	13	13	13	13
Key interrupt	4									
Reset	<ul style="list-style-type: none"> <li>• Reset by <u>RESET</u> pin</li> <li>• Internal reset by watchdog timer</li> <li>• Internal reset by power-on-reset</li> <li>• Internal reset by voltage detector</li> <li>• Internal reset by illegal instruction execution <sup>Note</sup></li> <li>• Internal reset by RAM parity error</li> <li>• Internal reset by illegal-memory access</li> </ul>									
Power-on-reset circuit	<ul style="list-style-type: none"> <li>• Power-on-reset: 1.51 V (TYP.)</li> <li>• Power-down-reset: 1.50 V (TYP.)</li> </ul>									
Voltage detector	<ul style="list-style-type: none"> <li>• Rising edge : 1.67 V to 4.06 V (14 stages)</li> <li>• Falling edge : 1.63 V to 3.98 V (14 stages)</li> </ul>									
On-chip debug function	Provided									
Power supply voltage	$V_{DD} = 1.6$ to $5.5$ V ( $T_A = -40$ to $+85^\circ\text{C}$ ) $V_{DD} = 2.4$ to $5.5$ V ( $T_A = -40$ to $+105^\circ\text{C}$ )									
<R>	Operating ambient temperature									
	$T_A = 40$ to $+85^\circ\text{C}$ (A: Consumer applications, D: Industrial applications) $T_A = 40$ to $+105^\circ\text{C}$ (G: Industrial applications)									

**Note** The illegal instruction is generated when instruction code FFH is executed.

Reset by the illegal instruction execution not issued by emulation with the in-circuit emulator or on-chip debug emulator.

**( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$ ) (2/5)**

Items	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Output current, low <sup>Note 1</sup>	I <sub>OL1</sub>	Per pin for P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147			20.0 <sup>Note 2</sup>	mA
		Per pin for P60 to P63			15.0 <sup>Note 2</sup>	mA
		Total of P00 to P04, P07, P32 to P37, P40 to P47, P102 to P106, P120, P125 to P127, P130, P140 to P145 (When duty $\leq 70\%$ <sup>Note 3</sup> )	4.0 V $\leq$ EV <sub>DD0</sub> $\leq$ 5.5 V		70.0	mA
			2.7 V $\leq$ EV <sub>DD0</sub> $<$ 4.0 V		15.0	mA
			1.8 V $\leq$ EV <sub>DD0</sub> $<$ 2.7 V		9.0	mA
			1.6 V $\leq$ EV <sub>DD0</sub> $<$ 1.8 V		4.5	mA
		Total of P05, P06, P10 to P17, P30, P31, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100, P101, P110 to P117, P146, P147 (When duty $\leq 70\%$ <sup>Note 3</sup> )	4.0 V $\leq$ EV <sub>DD0</sub> $\leq$ 5.5 V		80.0	mA
			2.7 V $\leq$ EV <sub>DD0</sub> $<$ 4.0 V		35.0	mA
			1.8 V $\leq$ EV <sub>DD0</sub> $<$ 2.7 V		20.0	mA
			1.6 V $\leq$ EV <sub>DD0</sub> $<$ 1.8 V		10.0	mA
		Total of all pins (When duty $\leq 70\%$ <sup>Note 3</sup> )			150.0	mA
	I <sub>OL2</sub>	Per pin for P20 to P27, P150 to P156			0.4 <sup>Note 2</sup>	mA
		Total of all pins (When duty $\leq 70\%$ <sup>Note 3</sup> )	1.6 V $\leq$ V <sub>DD</sub> $\leq$ 5.5 V		5.0	mA

- Notes**
- Value of current at which the device operation is guaranteed even if the current flows from an output pin to the EV<sub>SS0</sub>, EV<sub>SS1</sub> and V<sub>SS</sub> pin.
  - However, do not exceed the total current value.
  - Specification under conditions where the duty factor  $\leq 70\%$ .

The output current value that has changed to the duty factor  $> 70\%$  the duty ratio can be calculated with the following expression (when changing the duty factor from 70% to n%).

- Total output current of pins =  $(I_{OL} \times 0.7)/(n \times 0.01)$

<Example> Where n = 80% and I<sub>OL</sub> = 10.0 mA

$$\text{Total output current of pins} = (10.0 \times 0.7)/(80 \times 0.01) \cong 8.7 \text{ mA}$$

However, the current that is allowed to flow into one pin does not vary depending on the duty factor. A current higher than the absolute maximum rating must not flow into one pin.

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

## (2) Flash ROM: 96 to 256 KB of 30- to 100-pin products

 $(T_A = -40$  to  $+85^\circ\text{C}$ ,  $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$ ) (1/2)

Parameter	Symbol	Conditions				MIN.	TYP.	MAX.	Unit
Supply current <small>Note 1</small>	$I_{DD1}$	Operating mode HS (high-speed main) mode <small>Note 5</small>	$f_{IH} = 32 \text{ MHz}^{\text{Note 3}}$	Basic operation	$V_{DD} = 5.0 \text{ V}$		2.3		mA
					$V_{DD} = 3.0 \text{ V}$		2.3		mA
				Normal operation	$V_{DD} = 5.0 \text{ V}$		5.2	8.5	mA
					$V_{DD} = 3.0 \text{ V}$		5.2	8.5	mA
			$f_{IH} = 24 \text{ MHz}^{\text{Note 3}}$	Normal operation	$V_{DD} = 5.0 \text{ V}$		4.1	6.6	mA
					$V_{DD} = 3.0 \text{ V}$		4.1	6.6	mA
			$f_{IH} = 16 \text{ MHz}^{\text{Note 3}}$	Normal operation	$V_{DD} = 5.0 \text{ V}$		3.0	4.7	mA
					$V_{DD} = 3.0 \text{ V}$		3.0	4.7	mA
		LS (low-speed main) mode <small>Note 5</small>	$f_{IH} = 8 \text{ MHz}^{\text{Note 3}}$	Normal operation	$V_{DD} = 3.0 \text{ V}$		1.3	2.1	mA
					$V_{DD} = 2.0 \text{ V}$		1.3	2.1	mA
		LV (low-voltage main) mode <small>Note 5</small>	$f_{IH} = 4 \text{ MHz}^{\text{Note 3}}$	Normal operation	$V_{DD} = 3.0 \text{ V}$		1.3	1.8	mA
					$V_{DD} = 2.0 \text{ V}$		1.3	1.8	mA
		HS (high-speed main) mode <small>Note 5</small>	$f_{MX} = 20 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		3.4	5.5	mA
					Resonator connection		3.6	5.7	mA
			$f_{MX} = 20 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		3.4	5.5	mA
					Resonator connection		3.6	5.7	mA
			$f_{MX} = 10 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		2.1	3.2	mA
					Resonator connection		2.1	3.2	mA
		LS (low-speed main) mode <small>Note 5</small>	$f_{MX} = 10 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		2.1	3.2	mA
					Resonator connection		2.1	3.2	mA
			$f_{MX} = 8 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		1.2	2.0	mA
					Resonator connection		1.2	2.0	mA
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = -40^\circ\text{C}$	Normal operation	Square wave input		4.8	5.9	$\mu\text{A}$
					Resonator connection		4.9	6.0	$\mu\text{A}$
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = +25^\circ\text{C}$	Normal operation	Square wave input		4.9	5.9	$\mu\text{A}$
					Resonator connection		5.0	6.0	$\mu\text{A}$
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = +50^\circ\text{C}$	Normal operation	Square wave input		5.0	7.6	$\mu\text{A}$
					Resonator connection		5.1	7.7	$\mu\text{A}$
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = +70^\circ\text{C}$	Normal operation	Square wave input		5.2	9.3	$\mu\text{A}$
					Resonator connection		5.3	9.4	$\mu\text{A}$
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = +85^\circ\text{C}$	Normal operation	Square wave input		5.7	13.3	$\mu\text{A}$
					Resonator connection		5.8	13.4	$\mu\text{A}$

(Notes and Remarks are listed on the next page.)

## (3) 128-pin products, and flash ROM: 384 to 512 KB of 44- to 100-pin products

 $(T_A = -40$  to  $+85^\circ\text{C}$ ,  $1.6 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{ss} = EV_{ss0} = EV_{ss1} = 0 \text{ V}$ ) (1/2)

Parameter	Symbol	Conditions					MIN.	TYP.	MAX.	Unit
Supply current <small>Note 1</small>	$I_{DD1}$	Operating mode HS (high-speed main) mode <small>Note 5</small>	$f_{IH} = 32 \text{ MHz}^{\text{Note 3}}$	Basic operation	$V_{DD} = 5.0 \text{ V}$		2.6			mA
					$V_{DD} = 3.0 \text{ V}$		2.6			mA
			$f_{IH} = 24 \text{ MHz}^{\text{Note 3}}$	Normal operation	$V_{DD} = 5.0 \text{ V}$		6.1	9.5		mA
					$V_{DD} = 3.0 \text{ V}$		6.1	9.5		mA
		LS (low-speed main) mode <small>Note 5</small>	$f_{IH} = 16 \text{ MHz}^{\text{Note 3}}$	Normal operation	$V_{DD} = 5.0 \text{ V}$		3.5	5.3		mA
					$V_{DD} = 3.0 \text{ V}$		3.5	5.3		mA
		LV (low-voltage main) mode <small>Note 5</small>	$f_{IH} = 8 \text{ MHz}^{\text{Note 3}}$	Normal operation	$V_{DD} = 3.0 \text{ V}$		1.5	2.3		mA
					$V_{DD} = 2.0 \text{ V}$		1.5	2.3		mA
		HS (high-speed main) mode <small>Note 5</small>	$f_{MX} = 20 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		3.9	6.1		mA
					Resonator connection		4.1	6.3		mA
			$f_{MX} = 20 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		3.9	6.1		mA
					Resonator connection		4.1	6.3		mA
			$f_{MX} = 10 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		2.5	3.7		mA
					Resonator connection		2.5	3.7		mA
		LS (low-speed main) mode <small>Note 5</small>	$f_{MX} = 8 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		1.4	2.2		mA
					Resonator connection		1.4	2.2		mA
			$f_{MX} = 8 \text{ MHz}^{\text{Note 2}}$ , $V_{DD} = 2.0 \text{ V}$	Normal operation	Square wave input		1.4	2.2		mA
					Resonator connection		1.4	2.2		mA
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = -40^\circ\text{C}$	Normal operation	Square wave input		5.4	6.5		$\mu\text{A}$
					Resonator connection		5.5	6.6		$\mu\text{A}$
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = +25^\circ\text{C}$	Normal operation	Square wave input		5.5	6.5		$\mu\text{A}$
					Resonator connection		5.6	6.6		$\mu\text{A}$
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = +50^\circ\text{C}$	Normal operation	Square wave input		5.6	9.4		$\mu\text{A}$
					Resonator connection		5.7	9.5		$\mu\text{A}$
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = +70^\circ\text{C}$	Normal operation	Square wave input		5.9	12.0		$\mu\text{A}$
					Resonator connection		6.0	12.1		$\mu\text{A}$
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 4</small> $T_A = +85^\circ\text{C}$	Normal operation	Square wave input		6.6	16.3		$\mu\text{A}$
					Resonator connection		6.7	16.4		$\mu\text{A}$

(Notes and Remarks are listed on the next page.)

6. Current flowing only to the A/D converter. The supply current of the RL78 microcontrollers is the sum of  $I_{DD1}$  or  $I_{DD2}$  and  $I_{ADC}$  when the A/D converter operates in an operation mode or the HALT mode.
7. Current flowing only to the LVD circuit. The supply current of the RL78 microcontrollers is the sum of  $I_{DD1}$ ,  $I_{DD2}$  or  $I_{DD3}$  and  $I_{LVD}$  when the LVD circuit is in operation.
8. Current flowing only during data flash rewrite.
9. Current flowing only during self programming.
10. For shift time to the SNOOZE mode, see **18.3.3 SNOOZE mode**.

**Remarks**

- 1.  $f_{IL}$ : Low-speed on-chip oscillator clock frequency
- 2.  $f_{SUB}$ : Subsystem clock frequency (XT1 clock oscillation frequency)
- 3.  $f_{CLK}$ : CPU/peripheral hardware clock frequency
- 4. Temperature condition of the TYP. value is  $T_A = 25^\circ\text{C}$

(7) Communication at different potential (2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock output, corresponding CSI00 only) (1/2)

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $2.7 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$ )

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCKp cycle time	t <sub>KCY1</sub>	t <sub>KCY1</sub> ≥ 2/f <sub>CLK</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	200		1150		1150		ns
			2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	300		1150		1150		ns
SCKp high-level width	t <sub>KH1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50			ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	t <sub>KCY1</sub> /2 – 120		t <sub>KCY1</sub> /2 – 120		t <sub>KCY1</sub> /2 – 120			ns
SCKp low-level width	t <sub>KL1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	t <sub>KCY1</sub> /2 – 7		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50			ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	t <sub>KCY1</sub> /2 – 10		t <sub>KCY1</sub> /2 – 50		t <sub>KCY1</sub> /2 – 50			ns
Slp setup time (to SCKp↑) <sup>Note 1</sup>	t <sub>SIK1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	58		479		479			ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	121		479		479			ns
Slp hold time (from SCKp↑) <sup>Note 1</sup>	t <sub>KS1</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ	10		10		10			ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ	10		10		10			ns
Delay time from SCKp↓ to SO <sub>p</sub> output <sup>Note 1</sup>	t <sub>KS01</sub>	4.0 V ≤ EV <sub>DD0</sub> ≤ 5.5 V, 2.7 V ≤ V <sub>b</sub> ≤ 4.0 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 1.4 kΩ		60		60		60		ns
		2.7 V ≤ EV <sub>DD0</sub> < 4.0 V, 2.3 V ≤ V <sub>b</sub> ≤ 2.7 V, C <sub>b</sub> = 20 pF, R <sub>b</sub> = 2.7 kΩ		130		130		130		ns

(Notes, Caution, and Remarks are listed on the next page.)

**(8) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock output)  
(3/3)**

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $1.8 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$ )

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		LV (low-voltage main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
Slp setup time (to SCKp $\downarrow$ ) <sup>Note 1</sup>	tsIK1	4.0 V $\leq$ EV <sub>DD0</sub> $\leq$ 5.5 V, 2.7 V $\leq$ V <sub>b</sub> $\leq$ 4.0 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 1.4 k $\Omega$	44		110		110		ns
		2.7 V $\leq$ EV <sub>DD0</sub> < 4.0 V, 2.3 V $\leq$ V <sub>b</sub> $\leq$ 2.7 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 2.7 k $\Omega$	44		110		110		ns
		1.8 V $\leq$ EV <sub>DD0</sub> < 3.3 V, 1.6 V $\leq$ V <sub>b</sub> $\leq$ 2.0 V <sup>Note 2</sup> , C <sub>b</sub> = 30 pF, R <sub>b</sub> = 5.5 k $\Omega$	110		110		110		ns
Slp hold time (from SCKp $\downarrow$ ) <sup>Note 1</sup>	tKS11	4.0 V $\leq$ EV <sub>DD0</sub> $\leq$ 5.5 V, 2.7 V $\leq$ V <sub>b</sub> $\leq$ 4.0 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 1.4 k $\Omega$	19		19		19		ns
		2.7 V $\leq$ EV <sub>DD0</sub> < 4.0 V, 2.3 V $\leq$ V <sub>b</sub> $\leq$ 2.7 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 2.7 k $\Omega$	19		19		19		ns
		1.8 V $\leq$ EV <sub>DD0</sub> < 3.3 V, 1.6 V $\leq$ V <sub>b</sub> $\leq$ 2.0 V <sup>Note 2</sup> , C <sub>b</sub> = 30 pF, R <sub>b</sub> = 5.5 k $\Omega$	19		19		19		ns
Delay time from SCKp $\uparrow$ to SO <sub>p</sub> output <sup>Note 1</sup>	tKS01	4.0 V $\leq$ EV <sub>DD0</sub> $\leq$ 5.5 V, 2.7 V $\leq$ V <sub>b</sub> $\leq$ 4.0 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 1.4 k $\Omega$		25		25		25	ns
		2.7 V $\leq$ EV <sub>DD0</sub> < 4.0 V, 2.3 V $\leq$ V <sub>b</sub> $\leq$ 2.7 V, C <sub>b</sub> = 30 pF, R <sub>b</sub> = 2.7 k $\Omega$		25		25		25	ns
		1.8 V $\leq$ EV <sub>DD0</sub> < 3.3 V, 1.6 V $\leq$ V <sub>b</sub> $\leq$ 2.0 V <sup>Note 2</sup> , C <sub>b</sub> = 30 pF, R <sub>b</sub> = 5.5 k $\Omega$		25		25		25	ns

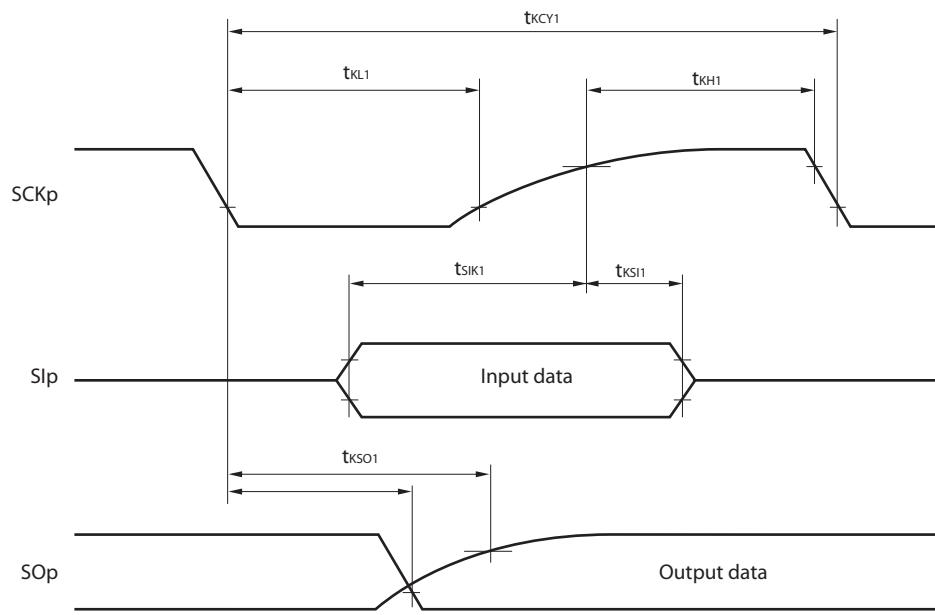
**Notes** 1. When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.

2. Use it with EV<sub>DD0</sub>  $\geq$  V<sub>b</sub>.

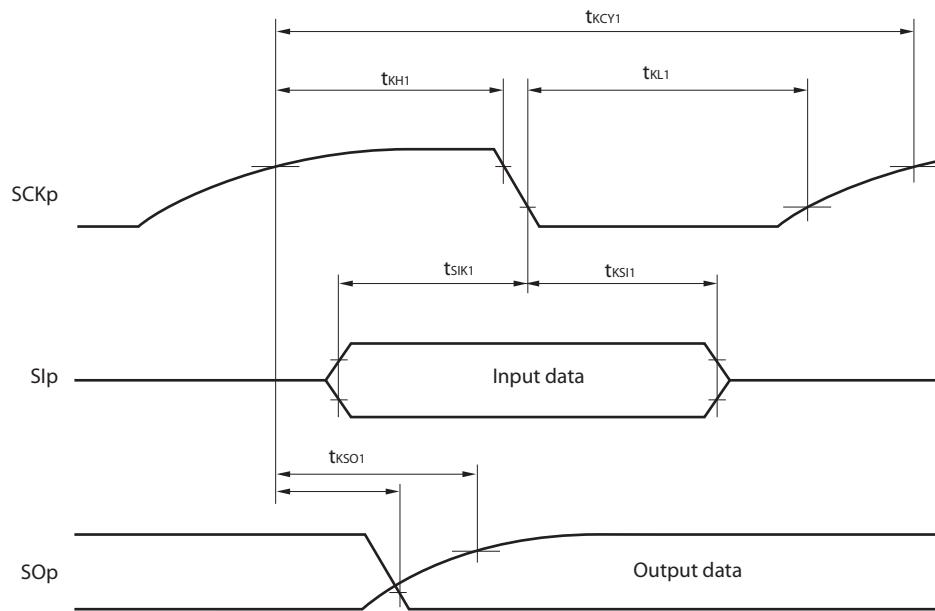
**Caution** Select the TTL input buffer for the Slp pin and the N-ch open drain output (V<sub>DD</sub> tolerance (When 20- to 52-pin products)/EV<sub>DD</sub> tolerance (When 64- to 128-pin products)) mode for the SO<sub>p</sub> pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg). For V<sub>IH</sub> and V<sub>IL</sub>, see the DC characteristics with TTL input buffer selected.

(Remarks are listed on the next page.)

**CSI mode serial transfer timing (master mode) (during communication at different potential)**  
**(When  $\text{DAP}_{mn} = 0$  and  $\text{CKP}_{mn} = 0$ , or  $\text{DAP}_{mn} = 1$  and  $\text{CKP}_{mn} = 1$ .)**



**CSI mode serial transfer timing (master mode) (during communication at different potential)**  
**(When  $\text{DAP}_{mn} = 0$  and  $\text{CKP}_{mn} = 1$ , or  $\text{DAP}_{mn} = 1$  and  $\text{CKP}_{mn} = 0$ .)**



- Remarks**
1. p: CSI number ( $p = 00, 01, 10, 20, 30, 31$ ), m: Unit number, n: Channel number ( $mn = 00, 01, 02, 10, 12, 13$ ), g: PIM and POM number ( $g = 0, 1, 4, 5, 8, 14$ )
  2. CSI01 of 48-, 52-, 64-pin products, and CSI11 and CSI21 cannot communicate at different potential.  
Use other CSI for communication at different potential.

- (4) When reference voltage (+) = Internal reference voltage ( $\text{ADREFP1} = 1$ ,  $\text{ADREFP0} = 0$ ), reference voltage (-) =  $\text{AV}_{\text{REFM}}/\text{ANI1}$  ( $\text{ADREFM} = 1$ ), target pin : ANI0, ANI2 to ANI14, ANI16 to ANI26

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $2.4 \text{ V} \leq V_{\text{DD}} \leq 5.5 \text{ V}$ ,  $1.6 \text{ V} \leq EV_{\text{DD0}} = EV_{\text{DD1}} \leq V_{\text{DD}}$ ,  $V_{\text{SS}} = EV_{\text{SS0}} = EV_{\text{SS1}} = 0 \text{ V}$ , Reference voltage (+) =  $\text{VBGR}^{\text{Note 3}}$ , Reference voltage (-) =  $\text{AV}_{\text{REFM}} = 0 \text{ V}^{\text{Note 4}}$ , HS (high-speed main) mode)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Resolution	RES			8		bit	
Conversion time	tconv	8-bit resolution	$2.4 \text{ V} \leq V_{\text{DD}} \leq 5.5 \text{ V}$	17		39	$\mu\text{s}$
Zero-scale error <sup>Notes 1, 2</sup>	Ezs	8-bit resolution	$2.4 \text{ V} \leq V_{\text{DD}} \leq 5.5 \text{ V}$			$\pm 0.60$	%FSR
Integral linearity error <sup>Note 1</sup>	ILE	8-bit resolution	$2.4 \text{ V} \leq V_{\text{DD}} \leq 5.5 \text{ V}$			$\pm 2.0$	LSB
Differential linearity error <sup>Note 1</sup>	DLE	8-bit resolution	$2.4 \text{ V} \leq V_{\text{DD}} \leq 5.5 \text{ V}$			$\pm 1.0$	LSB
Analog input voltage	V <sub>Ain</sub>			0		$\text{VBGR}^{\text{Note 3}}$	V

**Notes** 1. Excludes quantization error ( $\pm 1/2 \text{ LSB}$ ).

2. This value is indicated as a ratio (%FSR) to the full-scale value.

3. Refer to **2.6.2 Temperature sensor/internal reference voltage characteristics**.

4. When reference voltage (-) =  $V_{\text{SS}}$ , the MAX. values are as follows.

Zero-scale error: Add  $\pm 0.35\%$ FSR to the MAX. value when reference voltage (-) =  $\text{AV}_{\text{REFM}}$ .

Integral linearity error: Add  $\pm 0.5 \text{ LSB}$  to the MAX. value when reference voltage (-) =  $\text{AV}_{\text{REFM}}$ .

Differential linearity error: Add  $\pm 0.2 \text{ LSB}$  to the MAX. value when reference voltage (-) =  $\text{AV}_{\text{REFM}}$ .

**Absolute Maximum Ratings (TA = 25°C) (2/2)**

Parameter	Symbols	Conditions	Ratings	Unit	
Output current, high	I <sub>OH1</sub>	Per pin	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	-40	mA
		Total of all pins -170 mA	P00 to P04, P07, P32 to P37, P40 to P47, P102 to P106, P120, P125 to P127, P130, P140 to P145	-70	mA
			P05, P06, P10 to P17, P30, P31, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P90 to P97, P100, P101, P110 to P117, P146, P147	-100	mA
	I <sub>OH2</sub>	Per pin	P20 to P27, P150 to P156	-0.5	mA
		Total of all pins		-2	mA
	I <sub>OL1</sub>	Per pin	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100 to P106, P110 to P117, P120, P125 to P127, P130, P140 to P147	40	mA
		Total of all pins 170 mA	P00 to P04, P07, P32 to P37, P40 to P47, P102 to P106, P120, P125 to P127, P130, P140 to P145	70	mA
			P05, P06, P10 to P17, P30, P31, P50 to P57, P60 to P67, P70 to P77, P80 to P87, P90 to P97, P100, P101, P110 to P117, P146, P147	100	mA
	I <sub>OL2</sub>	Per pin	P20 to P27, P150 to P156	1	mA
		Total of all pins		5	mA
Operating ambient temperature	T <sub>A</sub>	In normal operation mode	-40 to +105	°C	
		In flash memory programming mode			
Storage temperature	T <sub>stg</sub>		-65 to +150	°C	

**Caution** Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

## (1) Flash ROM: 16 to 64 KB of 20- to 64-pin products

 $(T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4 \text{ V} \leq EV_{DD0} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = 0 \text{ V}$ ) (2/2)

Parameter	Symbol	Conditions				MIN.	TYP.	MAX.	Unit	
Supply current <small>Note 1</small>	$I_{DD2}$ <small>Note 2</small>	HALT mode	HS (high-speed main) mode <small>Note 7</small>	$f_{IH} = 32 \text{ MHz}$ <small>Note 4</small>	$V_{DD} = 5.0 \text{ V}$		0.54	2.90	mA	
					$V_{DD} = 3.0 \text{ V}$		0.54	2.90	mA	
				$f_{IH} = 24 \text{ MHz}$ <small>Note 4</small>	$V_{DD} = 5.0 \text{ V}$		0.44	2.30	mA	
					$V_{DD} = 3.0 \text{ V}$		0.44	2.30	mA	
				$f_{IH} = 16 \text{ MHz}$ <small>Note 4</small>	$V_{DD} = 5.0 \text{ V}$		0.40	1.70	mA	
					$V_{DD} = 3.0 \text{ V}$		0.40	1.70	mA	
		HS (high-speed main) mode <small>Note 7</small>	$f_{MX} = 20 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 5.0 \text{ V}$	Square wave input		0.28	1.90	mA		
				Resonator connection		0.45	2.00	mA		
			$f_{MX} = 20 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 3.0 \text{ V}$	Square wave input		0.28	1.90	mA		
				Resonator connection		0.45	2.00	mA		
			$f_{MX} = 10 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 5.0 \text{ V}$	Square wave input		0.19	1.02	mA		
				Resonator connection		0.26	1.10	mA		
			$f_{MX} = 10 \text{ MHz}$ <small>Note 3</small> , $V_{DD} = 3.0 \text{ V}$	Square wave input		0.19	1.02	mA		
				Resonator connection		0.26	1.10	mA		
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = -40^\circ\text{C}$	Square wave input		0.25	0.57	$\mu\text{A}$		
				Resonator connection		0.44	0.76	$\mu\text{A}$		
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = +25^\circ\text{C}$	Square wave input		0.30	0.57	$\mu\text{A}$		
				Resonator connection		0.49	0.76	$\mu\text{A}$		
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = +50^\circ\text{C}$	Square wave input		0.37	1.17	$\mu\text{A}$		
				Resonator connection		0.56	1.36	$\mu\text{A}$		
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = +70^\circ\text{C}$	Square wave input		0.53	1.97	$\mu\text{A}$		
				Resonator connection		0.72	2.16	$\mu\text{A}$		
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = +85^\circ\text{C}$	Square wave input		0.82	3.37	$\mu\text{A}$		
				Resonator connection		1.01	3.56	$\mu\text{A}$		
			$f_{SUB} = 32.768 \text{ kHz}$ <small>Note 5</small> , $T_A = +105^\circ\text{C}$	Square wave input		3.01	15.37	$\mu\text{A}$		
				Resonator connection		3.20	15.56	$\mu\text{A}$		
$I_{DD3}$ <small>Note 6</small>	STOP mode <small>Note 8</small>	$T_A = -40^\circ\text{C}$					0.18	0.50	$\mu\text{A}$	
		$T_A = +25^\circ\text{C}$					0.23	0.50	$\mu\text{A}$	
		$T_A = +50^\circ\text{C}$					0.30	1.10	$\mu\text{A}$	
		$T_A = +70^\circ\text{C}$					0.46	1.90	$\mu\text{A}$	
		$T_A = +85^\circ\text{C}$					0.75	3.30	$\mu\text{A}$	
		$T_A = +105^\circ\text{C}$					2.94	15.30	$\mu\text{A}$	

(Notes and Remarks are listed on the next page.)

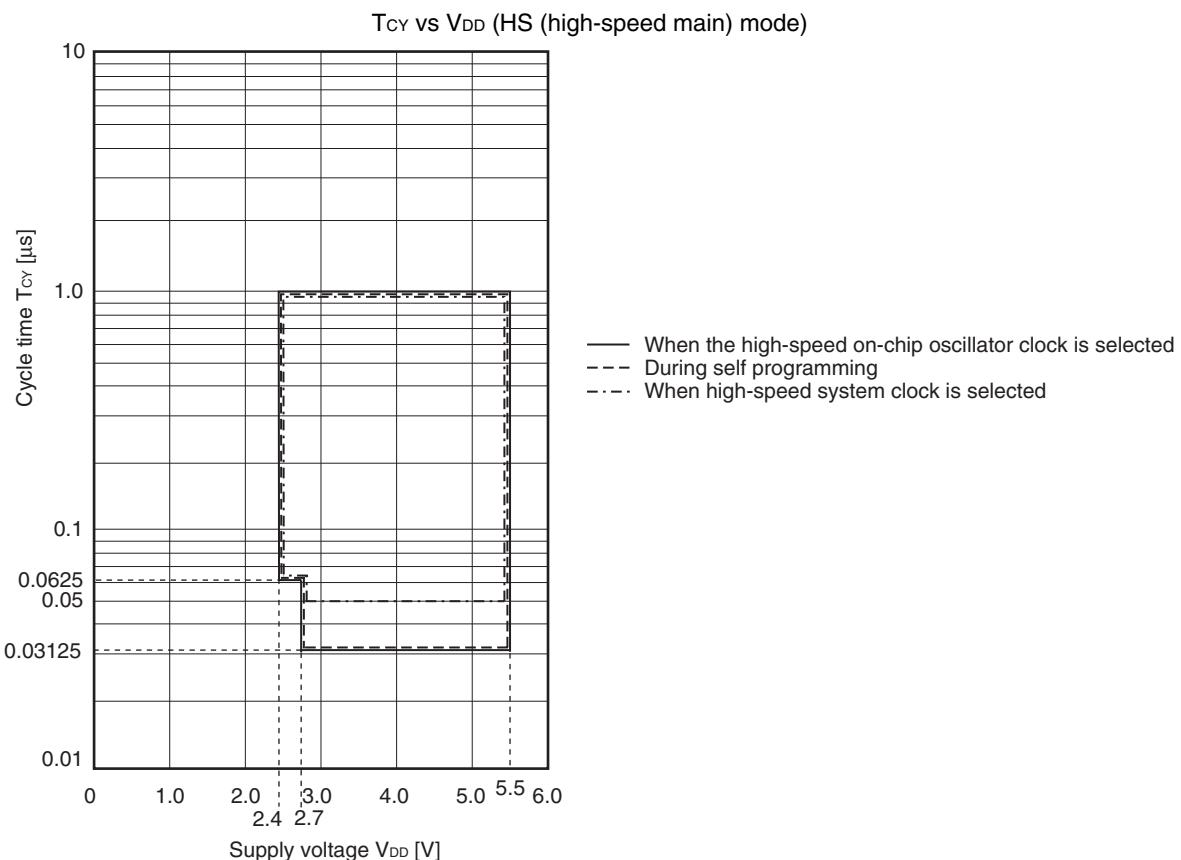
## (2) Flash ROM: 96 to 256 KB of 30- to 100-pin products

 $(T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4 \text{ V} \leq EV_{DD0} = EV_{DD1} \leq V_{DD} \leq 5.5 \text{ V}$ ,  $V_{SS} = EV_{SS0} = EV_{SS1} = 0 \text{ V}$ ) (1/2)

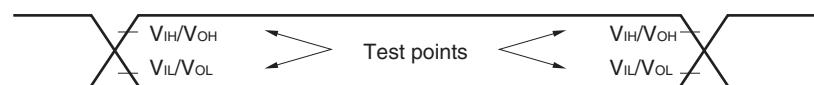
Parameter	Symbol	Conditions					MIN.	TYP.	MAX.	Unit
Supply current Note 1	$I_{DD1}$	Operating mode	HS (high-speed main) mode Note 5	$f_{IH} = 32 \text{ MHz}$ <sup>Note 3</sup>	Basic operation	$V_{DD} = 5.0 \text{ V}$		2.3		mA
						$V_{DD} = 3.0 \text{ V}$		2.3		mA
				$f_{IH} = 24 \text{ MHz}$ <sup>Note 3</sup>	Normal operation	$V_{DD} = 5.0 \text{ V}$		5.2	9.2	mA
						$V_{DD} = 3.0 \text{ V}$		5.2	9.2	mA
				$f_{IH} = 16 \text{ MHz}$ <sup>Note 3</sup>	Normal operation	$V_{DD} = 5.0 \text{ V}$		3.0	5.0	mA
						$V_{DD} = 3.0 \text{ V}$		3.0	5.0	mA
		HS (high-speed main) mode Note 5	$f_{MX} = 20 \text{ MHz}$ <sup>Note 2</sup> , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		3.4	5.9		mA
					Resonator connection		3.6	6.0	mA	
			$f_{MX} = 20 \text{ MHz}$ <sup>Note 2</sup> , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		3.4	5.9		mA
					Resonator connection		3.6	6.0	mA	
			$f_{MX} = 10 \text{ MHz}$ <sup>Note 2</sup> , $V_{DD} = 5.0 \text{ V}$	Normal operation	Square wave input		2.1	3.5		mA
					Resonator connection		2.1	3.5	mA	
			$f_{MX} = 10 \text{ MHz}$ <sup>Note 2</sup> , $V_{DD} = 3.0 \text{ V}$	Normal operation	Square wave input		2.1	3.5		mA
					Resonator connection		2.1	3.5	mA	
		Subsystem clock operation	$f_{SUB} = 32.768 \text{ kHz}$ <sup>Note 4</sup> $T_A = -40^\circ\text{C}$	Normal operation	Square wave input		4.8	5.9		$\mu\text{A}$
					Resonator connection		4.9	6.0	$\mu\text{A}$	
			$f_{SUB} = 32.768 \text{ kHz}$ <sup>Note 4</sup> $T_A = +25^\circ\text{C}$	Normal operation	Square wave input		4.9	5.9		$\mu\text{A}$
					Resonator connection		5.0	6.0	$\mu\text{A}$	
			$f_{SUB} = 32.768 \text{ kHz}$ <sup>Note 4</sup> $T_A = +50^\circ\text{C}$	Normal operation	Square wave input		5.0	7.6		$\mu\text{A}$
					Resonator connection		5.1	7.7	$\mu\text{A}$	
			$f_{SUB} = 32.768 \text{ kHz}$ <sup>Note 4</sup> $T_A = +70^\circ\text{C}$	Normal operation	Square wave input		5.2	9.3		$\mu\text{A}$
					Resonator connection		5.3	9.4	$\mu\text{A}$	
			$f_{SUB} = 32.768 \text{ kHz}$ <sup>Note 4</sup> $T_A = +85^\circ\text{C}$	Normal operation	Square wave input		5.7	13.3		$\mu\text{A}$
					Resonator connection		5.8	13.4	$\mu\text{A}$	
			$f_{SUB} = 32.768 \text{ kHz}$ <sup>Note 4</sup> $T_A = +105^\circ\text{C}$	Normal operation	Square wave input		10.0	46.0		$\mu\text{A}$
					Resonator connection		10.0	46.0	$\mu\text{A}$	

(Notes and Remarks are listed on the next page.)

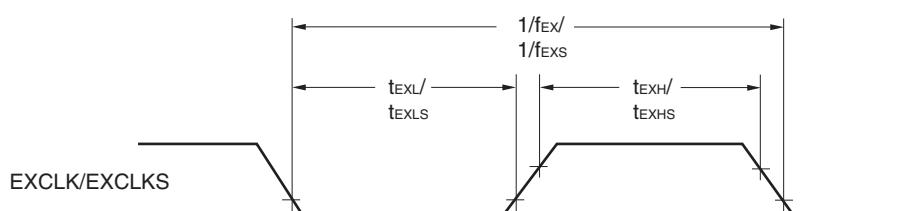
### Minimum Instruction Execution Time during Main System Clock Operation



### AC Timing Test Points

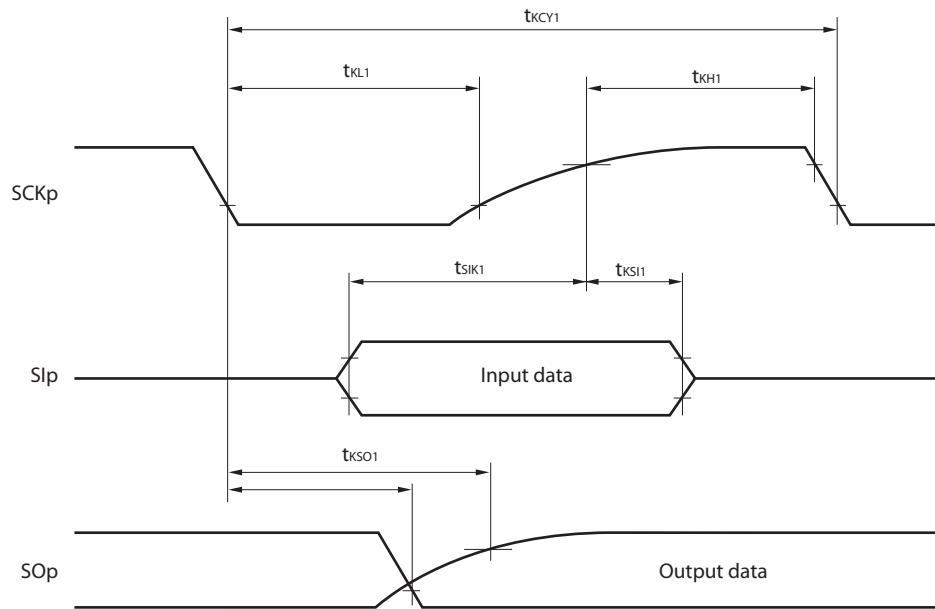


### External System Clock Timing

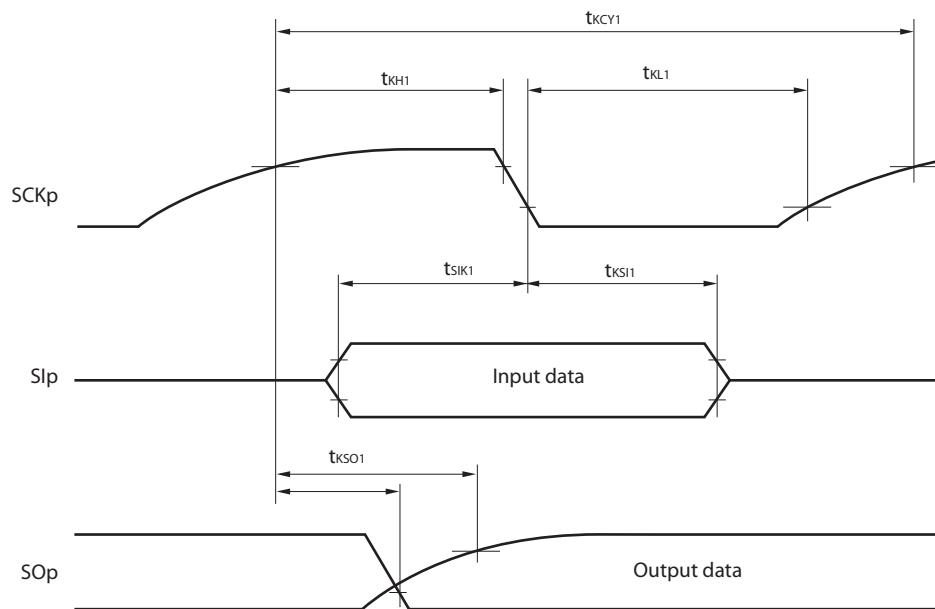


**CSI mode serial transfer timing (master mode) (during communication at different potential)**

(When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.)

**CSI mode serial transfer timing (master mode) (during communication at different potential)**

(When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.)



**Remarks** 1. p: CSI number (p = 00, 01, 10, 20, 30, 31), m: Unit number (m = 00, 01, 02, 10, 12, 13), n: Channel number (n = 0, 2), g: PIM and POM number (g = 0, 1, 4, 5, 8, 14)

2. CSI01 of 48-, 52-, 64-pin products, and CSI11 and CSI21 cannot communicate at different potential. Use other CSI for communication at different potential.

**Notes** 1. Excludes quantization error ( $\pm 1/2$  LSB).

2. This value is indicated as a ratio (%FSR) to the full-scale value.

3. When  $AV_{REFP} < V_{DD}$ , the MAX. values are as follows.

Overall error: Add  $\pm 1.0$  LSB to the MAX. value when  $AV_{REFP} = V_{DD}$ .

Zero-scale error/Full-scale error: Add  $\pm 0.05\%$ FSR to the MAX. value when  $AV_{REFP} = V_{DD}$ .

Integral linearity error/ Differential linearity error: Add  $\pm 0.5$  LSB to the MAX. value when  $AV_{REFP} = V_{DD}$ .

4. Refer to **3.6.2 Temperature sensor/internal reference voltage characteristics**.

- (2) When reference voltage (+) =  $AV_{REFP}/ANI0$  (ADREFP1 = 0, ADREFP0 = 1), reference voltage (-) =  $AV_{REFM}/ANI1$  (ADREFM = 1), target pin : ANI16 to ANI26

(TA = -40 to +105°C, 2.4 V ≤ EV<sub>DD0</sub> = EV<sub>DD1</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, 2.4 V ≤ AV<sub>REFP</sub> ≤ V<sub>DD</sub> ≤ 5.5 V, V<sub>SS</sub> = EV<sub>VSS0</sub> = EV<sub>VSS1</sub> = 0 V, Reference voltage (+) = AV<sub>REFP</sub>, Reference voltage (-) = AV<sub>REFM</sub> = 0 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Resolution	RES			8		10	bit
Overall error <sup>Note 1</sup>	AINL	10-bit resolution EV <sub>DD0</sub> ≤ AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	2.4 V ≤ AV <sub>REFP</sub> ≤ 5.5 V		1.2	±5.0	LSB
Conversion time	t <sub>CONV</sub>	10-bit resolution Target pin : ANI16 to ANI26	3.6 V ≤ V <sub>DD</sub> ≤ 5.5 V	2.125		39	μs
			2.7 V ≤ V <sub>DD</sub> ≤ 5.5 V	3.1875		39	μs
			2.4 V ≤ V <sub>DD</sub> ≤ 5.5 V	17		39	μs
Zero-scale error <sup>Notes 1, 2</sup>	E <sub>ZS</sub>	10-bit resolution EV <sub>DD0</sub> ≤ AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	2.4 V ≤ AV <sub>REFP</sub> ≤ 5.5 V			±0.35	%FSR
Full-scale error <sup>Notes 1, 2</sup>	E <sub>FS</sub>	10-bit resolution EV <sub>DD0</sub> ≤ AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	2.4 V ≤ AV <sub>REFP</sub> ≤ 5.5 V			±0.35	%FSR
Integral linearity error <sup>Note 1</sup>	ILE	10-bit resolution EV <sub>DD0</sub> ≤ AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	2.4 V ≤ AV <sub>REFP</sub> ≤ 5.5 V			±3.5	LSB
Differential linearity error <small>Note 1</small>	DLE	10-bit resolution EV <sub>DD0</sub> ≤ AV <sub>REFP</sub> = V <sub>DD</sub> <sup>Notes 3, 4</sup>	2.4 V ≤ AV <sub>REFP</sub> ≤ 5.5 V			±2.0	LSB
Analog input voltage	V <sub>AiN</sub>	ANI16 to ANI26		0		AV <sub>REFP</sub> and EV <sub>DD0</sub>	V

**Notes** 1. Excludes quantization error (±1/2 LSB).

2. This value is indicated as a ratio (%FSR) to the full-scale value.

3. When AV<sub>REFP</sub> < V<sub>DD</sub>, the MAX. values are as follows.

Overall error: Add ±1.0 LSB to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

Zero-scale error/Full-scale error: Add ±0.05%FSR to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

Integral linearity error/ Differential linearity error: Add ±0.5 LSB to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

4. When AV<sub>REFP</sub> < EV<sub>DD0</sub> ≤ V<sub>DD</sub>, the MAX. values are as follows.

Overall error: Add ±4.0 LSB to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

Zero-scale error/Full-scale error: Add ±0.20%FSR to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

Integral linearity error/ Differential linearity error: Add ±2.0 LSB to the MAX. value when AV<sub>REFP</sub> = V<sub>DD</sub>.

### 3.6.4 LVD circuit characteristics

#### LVD Detection Voltage of Reset Mode and Interrupt Mode

(TA = -40 to +105°C, VPDR ≤ VDD ≤ 5.5 V, Vss = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Detection voltage	V <sub>LVDO</sub>	Power supply rise time	3.90	4.06	4.22	V
		Power supply fall time	3.83	3.98	4.13	V
	V <sub>LVD1</sub>	Power supply rise time	3.60	3.75	3.90	V
		Power supply fall time	3.53	3.67	3.81	V
	V <sub>LVD2</sub>	Power supply rise time	3.01	3.13	3.25	V
		Power supply fall time	2.94	3.06	3.18	V
	V <sub>LVD3</sub>	Power supply rise time	2.90	3.02	3.14	V
		Power supply fall time	2.85	2.96	3.07	V
	V <sub>LVD4</sub>	Power supply rise time	2.81	2.92	3.03	V
		Power supply fall time	2.75	2.86	2.97	V
	V <sub>LVD5</sub>	Power supply rise time	2.70	2.81	2.92	V
		Power supply fall time	2.64	2.75	2.86	V
	V <sub>LVD6</sub>	Power supply rise time	2.61	2.71	2.81	V
		Power supply fall time	2.55	2.65	2.75	V
	V <sub>LVD7</sub>	Power supply rise time	2.51	2.61	2.71	V
		Power supply fall time	2.45	2.55	2.65	V
Minimum pulse width	t <sub>LW</sub>		300			μs
Detection delay time					300	μs

#### LVD Detection Voltage of Interrupt & Reset Mode

(TA = -40 to +105°C, VPDR ≤ VDD ≤ 5.5 V, Vss = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit		
Interrupt and reset mode	V <sub>LVDD0</sub>	V <sub>POC2</sub> , V <sub>POC1</sub> , V <sub>POC0</sub> = 0, 1, 1, falling reset voltage	2.64	2.75	2.86	V		
		LVIS1, LVIS0 = 1, 0	Rising release reset voltage	2.81	2.92	3.03		
	V <sub>LVDD1</sub>		Falling interrupt voltage	2.75	2.86	2.97		
			LVIS1, LVIS0 = 0, 1	Rising release reset voltage	2.90	3.02		
	V <sub>LVDD2</sub>			Falling interrupt voltage	2.85	2.96		
	V <sub>LVDD3</sub>			LVIS1, LVIS0 = 0, 0	Rising release reset voltage	3.90		
					Falling interrupt voltage	3.83		
					4.13			