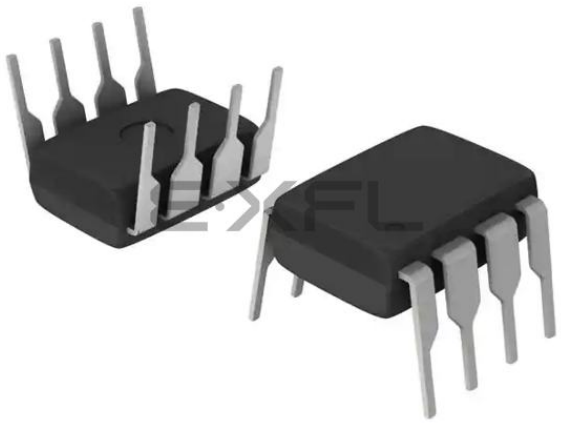

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	eZ8
Core Size	8-Bit
Speed	5MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, POR, PWM, WDT
Number of I/O	6
Program Memory Size	2KB (2K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Through Hole
Package / Case	8-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f0213pb005ec

Register Map

Table 8 lists the address map for the Register File of the Z8 Encore! XP® F0823 Series devices. Not all devices and package styles in the Z8 Encore! XP F0823 Series support the ADC, or all GPIO ports. Consider registers for unimplemented peripherals as reserved.

Table 8. Register File Address Map

Address (Hex)	Register Description	Mnemonic	Reset (Hex)	Page No
General-Purpose RAM				
Z8F0823/Z8F0813 Devices				
000–3FF	General-Purpose Register File RAM	—	XX	
400–EFF	Reserved	—	XX	
Z8F0423/Z8F0413 Devices				
000–3FF	General-Purpose Register File RAM	—	XX	
400–EFF	Reserved	—	XX	
Z8F0223/Z8F0213 Devices				
000–1FF	General-Purpose Register File RAM	—	XX	
200–EFF	Reserved	—	XX	
Z8F0123/Z8F0113 Devices				
000–0FF	General-Purpose Register File RAM	—	XX	
100–EFF	Reserved	—	XX	
Timer 0				
F00	Timer 0 High Byte	T0H	00	80
F01	Timer 0 Low Byte	T0L	01	80
F02	Timer 0 Reload High Byte	T0RH	FF	81
F03	Timer 0 Reload Low Byte	T0RL	FF	81
F04	Timer 0 PWM High Byte	T0PWMH	00	81
F05	Timer 0 PWM Low Byte	T0PWML	00	82
F06	Timer 0 Control 0	T0CTL0	00	82
F07	Timer 0 Control 1	T0CTL1	00	83
Timer 1				
F08	Timer 1 High Byte	T1H	00	80
F09	Timer 1 Low Byte	T1L	01	80
F0A	Timer 1 Reload High Byte	T1RH	FF	81
F0B	Timer 1 Reload Low Byte	T1RL	FF	81

Reset and Stop Mode Recovery

The Reset Controller within the Z8 Encore! XP® F0823 Series controls Reset and Stop Mode Recovery operation and provides indication of low supply voltage conditions. In typical operation, the following events cause a Reset:

- Power-On Reset (POR)
- Voltage Brownout (VBO)
- Watchdog Timer time-out (when configured by the WDT_RES Flash Option Bit to initiate a reset)
- External $\overline{\text{RESET}}$ pin assertion (when the alternate RESET function is enabled by the GPIO register)
- On-chip Debugger initiated Reset (OCDCTL[0] set to 1)

When the device is in STOP mode, a Stop Mode Recovery is initiated by either of the following:

- Watchdog Timer time-out
- GPIO port input pin transition on an enabled Stop Mode Recovery source

The VBO circuitry on the device performs the following function:

- Generates the VBO reset when the supply voltage drops below a minimum safe level

Reset Types

Z8 Encore! XP F0823 Series provides several different types of Reset operation. Stop Mode Recovery is considered a form of Reset. Table 9 lists the types of Reset and their operating characteristics. The System Reset is longer if the external crystal oscillator is enabled by the Flash option bits, allowing additional time for oscillator start-up.

GPIO Interrupts

Many of the GPIO port pins are used as interrupt sources. Some port pins are configured to generate an interrupt request on either the rising edge or falling edge of the pin input signal. Other port pin interrupt sources generate an interrupt when any edge occurs (both rising and falling). For more information about interrupts using the GPIO pins, see Interrupt Controller on page 53.

GPIO Control Register Definitions

Four registers for each Port provide access to GPIO control, input data, and output data. Table 17 lists these Port registers. Use the Port A–D Address and Control registers together to provide access to sub-registers for Port configuration and control.

Table 17. GPIO Port Registers and Sub-Registers

Port Register Mnemonic	Port Register Name
P*x*ADDR	Port A–C Address Register (Selects sub-registers)
P*x*CTL	Port A–C Control Register (Provides access to sub-registers)
P*x*IN	Port A–C Input Data Register
P*x*OUT	Port A–C Output Data Register
Port Sub-Register Mnemonic	**Port Register Name**
P*x*DD	Data Direction
P*x*AF	Alternate Function
P*x*OC	Output Control (Open-Drain)
P*x*HDE	High Drive Enable
P*x*SMRE	Stop Mode Recovery Source Enable
P*x*PUE	Pull-up Enable
PxAFS1	Alternate Function Set 1
PxAFS2	Alternate Function Set 2

Interrupt Controller

The interrupt controller on the Z8 Encore! XP® F0823 Series products prioritizes the interrupt requests from the on-chip peripherals and the GPIO port pins. The features of interrupt controller include:

- 20 unique interrupt vectors
  - 12 GPIO port pin interrupt sources (two are shared)
  - 8 on-chip peripheral interrupt sources (two are shared)
- Flexible GPIO interrupts
  - Eight selectable rising and falling edge GPIO interrupts
  - Four dual-edge interrupts
- Three levels of individually programmable interrupt priority
- Watchdog Timer can be configured to generate an interrupt

Interrupt requests (IRQs) allow peripheral devices to suspend CPU operation in an orderly manner and force the CPU to start an interrupt service routine (ISR). Usually this interrupt service routine is involved with the exchange of data, status information, or control information between the CPU and the interrupting peripheral. When the service routine is completed, the CPU returns to the operation from which it was interrupted.

The eZ8 CPU supports both vectored and polled interrupt handling. For polled interrupts, the interrupt controller has no effect on operation. For more information on interrupt servicing by the eZ8 CPU, refer to *eZ8 CPU Core User Manual (UM0128)* available for download at www.zilog.com.

Interrupt Vector Listing

Table 33 lists all of the interrupts available in order of priority. The interrupt vector is stored with the most-significant byte (MSB) at the even Program Memory address and the least-significant byte (LSB) at the following odd Program Memory address.

Note: *Some port interrupts are not available on the 8- and 20-pin packages. The ADC interrupt is unavailable on devices not containing an ADC.*

Interrupt Request 1 Register

The Interrupt Request 1 (IRQ1) register (Table 35) stores interrupt requests for both vectored and polled interrupts. When a request is presented to the interrupt controller, the corresponding bit in the IRQ1 register becomes 1. If interrupts are globally enabled (vectored interrupts), the interrupt controller passes an interrupt request to the eZ8 CPU. If interrupts are globally disabled (polled interrupts), the eZ8 CPU reads the Interrupt Request 1 register to determine if any interrupt requests are pending.

Table 35. Interrupt Request 1 Register (IRQ1)

BITS	7	6	5	4	3	2	1	0
FIELD	PA7VI	PA6CI	PA5I	PA4I	PA3I	PA2I	PA1I	PA0I
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FC3H							

PA7VI—Port A7 Interrupt Request
0 = No interrupt request is pending for GPIO Port A
1 = An interrupt request from GPIO Port A

PA6CI—Port A6 or Comparator Interrupt Request
0 = No interrupt request is pending for GPIO Port A or Comparator
1 = An interrupt request from GPIO Port A or Comparator

PA*x*I—Port A Pin *x* Interrupt Request
0 = No interrupt request is pending for GPIO Port A pin *x*
1 = An interrupt request from GPIO Port A pin *x* is awaiting service

where *x* indicates the specific GPIO Port pin number (0–5)

Interrupt Request 2 Register

The Interrupt Request 2 (IRQ2) register (Table 36) stores interrupt requests for both vectored and polled interrupts. When a request is presented to the interrupt controller, the corresponding bit in the IRQ2 register becomes 1. If interrupts are globally enabled (vectored interrupts), the interrupt controller passes an interrupt request to the eZ8 CPU. If interrupts are globally disabled (polled interrupts), the eZ8 CPU can read the Interrupt Request 2 register to determine if any interrupt requests are pending.

COMPARATOR COUNTER Mode

In COMPARATOR COUNTER mode, the timer counts input transitions from the analog comparator output. The TPOL bit in the Timer Control Register selects whether the count occurs on the rising edge or the falling edge of the comparator output signal. In COMPARATOR COUNTER mode, the prescaler is disabled.

Caution: *The frequency of the comparator output signal must not exceed one-fourth the system clock frequency.*

After reaching the Reload value stored in the Timer Reload High and Low Byte registers, the timer generates an interrupt, the count value in the Timer High and Low Byte registers is reset to 0001H and counting resumes. Also, if the Timer Output alternate function is enabled, the Timer Output pin changes state (from Low to High or from High to Low) at timer Reload.

Follow the steps below for configuring a timer for COMPARATOR COUNTER mode and initiating the count:

1. Write to the Timer Control register to:
   - Disable the timer.
   - Configure the timer for COMPARATOR COUNTER mode.
   - Select either the rising edge or falling edge of the comparator output signal for the count. This also sets the initial logic level (High or Low) for the Timer Output alternate function. However, the Timer Output function is not required to be enabled.
2. Write to the Timer High and Low Byte registers to set the starting count value. This action only affects the first pass in COMPARATOR COUNTER mode. After the first timer Reload in COMPARATOR COUNTER mode, counting always begins at the reset value of 0001H. Generally, in COMPARATOR COUNTER mode the Timer High and Low Byte registers must be written with the value 0001H.
3. Write to the Timer Reload High and Low Byte registers to set the Reload value.
4. If appropriate, enable the timer interrupt and set the timer interrupt priority by writing to the relevant interrupt registers.
5. If using the Timer Output function, configure the associated GPIO port pin for the Timer Output alternate function.
6. Write to the Timer Control register to enable the timer.

In COMPARATOR COUNTER mode, the number of comparator output transitions since the timer start is given by the following equation:

Comparator Output Transitions = Current Count Value – Start Value

Timer Control Register Definitions

Timer 0–1 High and Low Byte Registers

The Timer 0–1 High and Low Byte (TxH and TxL) registers (Table 49 and Table 50) contain the current 16-bit timer count value. When the timer is enabled, a read from TxH causes the value in TxL to be stored in a temporary holding register. A read from TxL always returns this temporary register when the timers are enabled. When the timer is disabled, reads from the TxL reads the register directly.

Writing to the Timer High and Low Byte registers while the timer is enabled is not recommended. There are no temporary holding registers available for write operations, so simultaneous 16-bit writes are not possible. If either the Timer High or Low Byte registers are written during counting, the 8-bit written value is placed in the counter (High or Low Byte) at the next clock edge. The counter continues counting from the new value.

Table 49. Timer 0–1 High Byte Register (TxH)

BITS	7	6	5	4	3	2	1	0
FIELD	TH							
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F00H, F08H							

Table 50. Timer 0–1 Low Byte Register (TxL)

BITS	7	6	5	4	3	2	1	0
FIELD	TL							
RESET	0	0	0	0	0	0	0	1
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F01H, F09H							

TH and TL—Timer High and Low Bytes
These 2 bytes, {TH[7:0], TL[7:0]}, contain the current 16-bit timer count value

Timer Reload High and Low Byte Registers

The Timer 0–1 Reload High and Low Byte (TxRH and TxRL) registers (Table 51 and Table 52) store a 16-bit Reload value, {TRH[7:0], TRL[7:0]}. Values written to the Timer Reload High Byte register are stored in a temporary holding register. When a write to the Timer Reload Low Byte register occurs, the temporary holding register value is written to the Timer High Byte register. This operation allows simultaneous updates of the 16-bit Timer Reload value.

Table 54. Timer 0–1 PWM Low Byte Register (TxPWML)

BITS	7	6	5	4	3	2	1	0
FIELD	PWML							
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F05H, F0DH							

PWMH and PWML—Pulse-Width Modulator High and Low Bytes
These two bytes, {PWMH[7:0], PWML[7:0]}, form a 16-bit value that is compared to the current 16-bit timer count. When a match occurs, the PWM output changes state. The PWM output value is set by the TPOL bit in the Timer Control Register (TxCTL1) register.

The TxPWMH and TxPWML registers also store the 16-bit captured timer value when operating in CAPTURE or CAPTURE/COMPARE modes.

Timer 0–1 Control Registers

Time 0–1 Control Register 0

The Timer Control Register 0 (TxCTL0) and Timer Control Register 1 (TxCTL1) determine the timer operating mode. It also includes a programmable PWM deadband delay, two bits to configure timer interrupt definition, and a status bit to identify if the most recent timer interrupt is caused by an input Capture event.

Table 55. Timer 0–1 Control Register 0 (TxCTL0)

BITS	7	6	5	4	3	2	1	0
FIELD	TMODEHI	TICONFIG		Reserved	PWMD			INPCAP
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F06H, F0EH							

TMODEHI—Timer Mode High Bit
This bit along with the TMODE field in TxCTL1 register determines the operating mode of the timer. This is the most-significant bit of the Timer mode selection value. See the TxCTL1 register description for more details.

TICONFIG—Timer Interrupt Configuration
This field configures timer interrupt definition.

Receiving Data using the Interrupt-Driven Method

The UART Receiver interrupt indicates the availability of new data (as well as error conditions). Follow the steps below to configure the UART receiver for interrupt-driven operation:

1. Write to the UART Baud Rate High and Low Byte registers to set the acceptable baud rate.
2. Enable the UART pin functions by configuring the associated GPIO port pins for alternate function operation.
3. Execute a DI instruction to disable interrupts.
4. Write to the Interrupt control registers to enable the UART Receiver interrupt and set the acceptable priority.
5. Clear the UART Receiver interrupt in the applicable Interrupt Request register.
6. Write to the UART Control 1 Register to enable Multiprocessor (9-bit) mode functions, if appropriate.
   - Set the Multiprocessor Mode Select (MPEN) to Enable MULTIPROCESSOR mode
   - Set the Multiprocessor Mode Bits, MPMD[1:0], to select the acceptable address matching scheme
   - Configure the UART to interrupt on received data and errors or errors only (interrupt on errors only is unlikely to be useful for Z8 Encore! XP devices without a DMA block)
7. Write the device address to the Address Compare Register (automatic MULTIPROCESSOR modes only).
8. Write to the UART Control 0 register to:
   - Set the receive enable bit (REN) to enable the UART for data reception
   - Enable parity, if appropriate and if multiprocessor mode is not enabled, and select either even or odd parity
9. Execute an EI instruction to enable interrupts.

The UART is now configured for interrupt-driven data reception. When the UART Receiver interrupt is detected, the associated interrupt service routine (ISR) performs the following:

1. Checks the UART Status 0 register to determine the source of the interrupt - error, break, or received data.
2. Reads the data from the UART Receive Data register if the interrupt was because of data available. If operating in MULTIPROCESSOR (9-bit) mode, further actions may be required depending on the MULTIPROCESSOR mode bits MPMD[1:0].

3. Clears the UART Receiver interrupt in the applicable Interrupt Request register.
4. Executes the IRET instruction to return from the interrupt-service routine and await more data.

Clear To Send ($\overline{\text{CTS}}$) Operation

The CTS pin, if enabled by the CTSE bit of the UART Control 0 register, performs flow control on the outgoing transmit datastream. The Clear To Send ($\overline{\text{CTS}}$) input pin is sampled one system clock before beginning any new character transmission. To delay transmission of the next data character, an external receiver must deassert $\overline{\text{CTS}}$ at least one system clock cycle before a new data transmission begins. For multiple character transmissions, this action is typically performed during Stop Bit transmission. If $\overline{\text{CTS}}$ deasserts in the middle of a character transmission, the current character is sent completely.

MULTIPROCESSOR (9-Bit) Mode

The UART has a MULTIPROCESSOR (9-bit) mode that uses an extra (9th) bit for selective communication when a number of processors share a common UART bus. In MULTIPROCESSOR mode (also referred to as 9-bit mode), the multiprocessor bit (MP) is transmitted immediately following the 8-bits of data and immediately preceding the Stop bit(s) as displayed in Figure 13. The character format is given below:

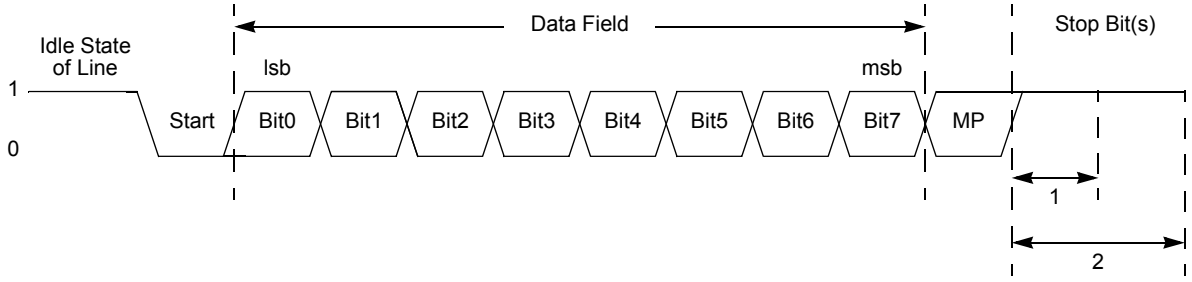


Figure 13. UART Asynchronous MULTIPROCESSOR Mode Data Format

In MULTIPROCESSOR (9-bit) mode, the Parity bit location (9th bit) becomes the Multiprocessor control bit. The UART Control 1 and Status 1 registers provide MULTIPROCESSOR (9-bit) mode control and status information. If an automatic address matching scheme is enabled, the UART Address Compare register holds the network address of the device.

MULTIPROCESSOR (9-bit) Mode Receive Interrupts

When MULTIPROCESSOR mode is enabled, the UART only processes frames addressed to it. The determination of whether a frame of data is addressed to the UART can be made

Infrared Encoder/Decoder

Z8 Encore! XP® F0823 Series products contain a fully-functional, high-performance UART with Infrared Encoder/Decoder (Endec). The Infrared Endec is integrated with an on-chip UART to allow easy communication between the Z8 Encore! XP and IrDA Physical Layer Specification, Version 1.3-compliant infrared transceivers. Infrared communication provides secure, reliable, low-cost, point-to-point communication between PCs, PDAs, cell phones, printers and other infrared enabled devices.

Architecture

Figure 16 displays the architecture of the Infrared Endec.

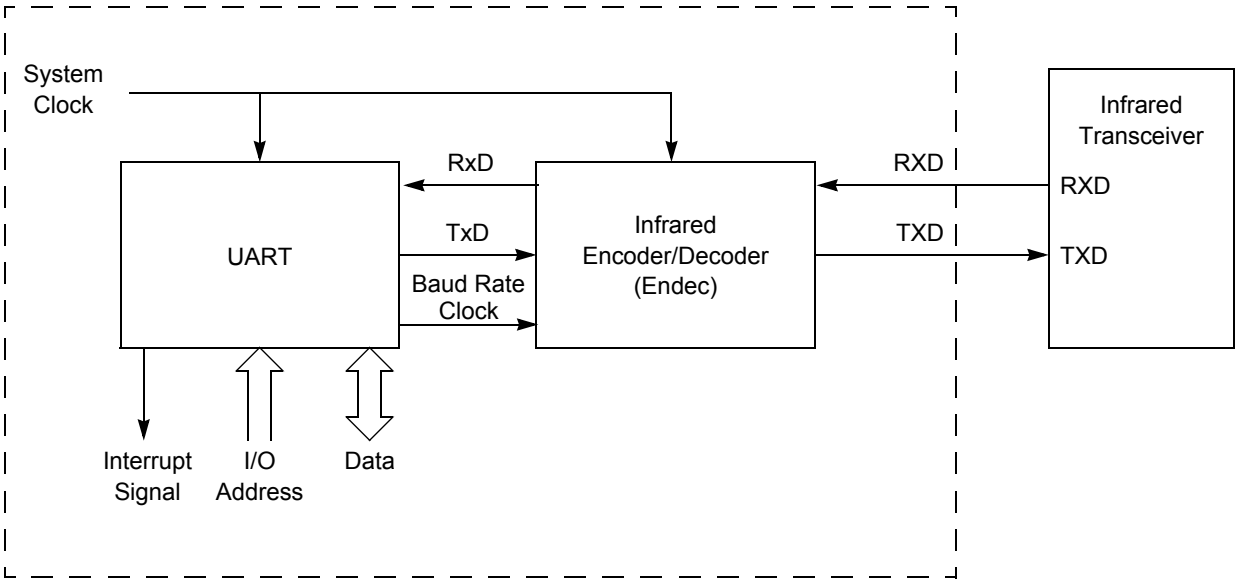


Figure 16. Infrared Data Communication System Block Diagram

Operation

When the Infrared Endec is enabled, the transmit data from the associated on-chip UART is encoded as digital signals in accordance with the IrDA standard and output to the infrared transceiver through the TXD pin. Similarly, data received from the infrared transceiver is passed to the Infrared Endec through the RXD pin, decoded by the Infrared

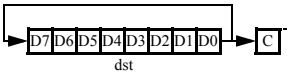
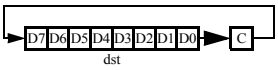
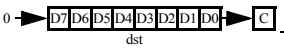
baud rate clocks to plus eight baud rate clocks around the expected time of an incoming pulse. If an incoming pulse is detected inside this window this process is repeated. If the incoming data is a logical 1 (no pulse), the Endec returns to the initial state and waits for the next falling edge. As each falling edge is detected, the Endec clock counter is reset, resynchronizing the Endec to the incoming signal, allowing the Endec to tolerate jitter and baud rate errors in the incoming datastream. Resynchronizing the Endec does not alter the operation of the UART, which ultimately receives the data. The UART is only synchronized to the incoming data stream when a Start bit is received.

Infrared Encoder/Decoder Control Register Definitions

All Infrared Endec configuration and status information is set by the UART control registers as defined in Universal Asynchronous Receiver/Transmitter on page 93.

Caution: *To prevent spurious signals during IrDA data transmission, set the IREN bit in the UART Control 1 register to 1 to enable the Infrared Encoder/Decoder before enabling the GPIO port alternate function for the corresponding pin.*

Table 115. eZ8 CPU Instruction Summary (Continued)

Assembly Mnemonic	Symbolic Operation	Address Mode dst	Address Mode src	Opcode(s) (Hex)	Flags C	Z	S	V	D	H	Fetch Cycles	Instr. Cycles
RR dst		R		E0	*	*	*	*	–	–	2	2
		IR		E1							2	3
RRC dst		R		C0	*	*	*	*	–	–	2	2
		IR		C1							2	3
SBC dst, src	dst ← dst – src - C	r	r	32	*	*	*	*	1	*	2	3
		r	Ir	33							2	4
		R	R	34							3	3
		R	IR	35							3	4
		R	IM	36							3	3
		IR	IM	37							3	4
SBCX dst, src	dst ← dst – src - C	ER	ER	38	*	*	*	*	1	*	4	3
		ER	IM	39							4	3
SCF	C ← 1			DF	1	–	–	–	–	–	1	2
SRA dst		R		D0	*	*	*	0	–	–	2	2
		IR		D1							2	3
SRL dst		R		1F C0	*	*	0	*	–	–	3	2
		IR		1F C1							3	3
SRP src	RP ← src		IM	01	–	–	–	–	–	–	2	2
STOP	STOP Mode			6F	–	–	–	–	–	–	1	2
SUB dst, src	dst ← dst – src	r	r	22	*	*	*	*	1	*	2	3
		r	Ir	23							2	4
		R	R	24							3	3
		R	IR	25							3	4
		R	IM	26							3	3
		IR	IM	27							3	4

Flags Notation:	* = Value is a function of the result of the operation. – = Unaffected X = Undefined	0 = Reset to 0 1 = Set to 1

Table 116. Opcode Map Abbreviations

Abbreviation	Description	Abbreviation	Description
b	Bit position	IRR	Indirect Register Pair
cc	Condition code	p	Polarity (0 or 1)
X	8-bit signed index or displacement	r	4-bit Working Register
DA	Destination address	R	8-bit register
ER	Extended Addressing register	r1, R1, Ir1, Irr1, IR1, rr1, RR1, IRR1, ER1	Destination address
IM	Immediate data value	r2, R2, Ir2, Irr2, IR2, rr2, RR2, IRR2, ER2	Source address
Ir	Indirect Working Register	RA	Relative
IR	Indirect register	rr	Working Register Pair
Irr	Indirect Working Register Pair	RR	Register Pair

Electrical Characteristics

The data in this chapter is pre-qualification and pre-characterization and is subject to change. Additional electrical characteristics may be found in the individual chapters.

Absolute Maximum Ratings

Stresses greater than those listed in Table 117 may cause permanent damage to the device. These ratings are stress ratings only. Operation of the device at any condition outside those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. For improved reliability, tie unused inputs to one of the supply voltages (V_{DD} or V_{SS}).

Table 117. Absolute Maximum Ratings

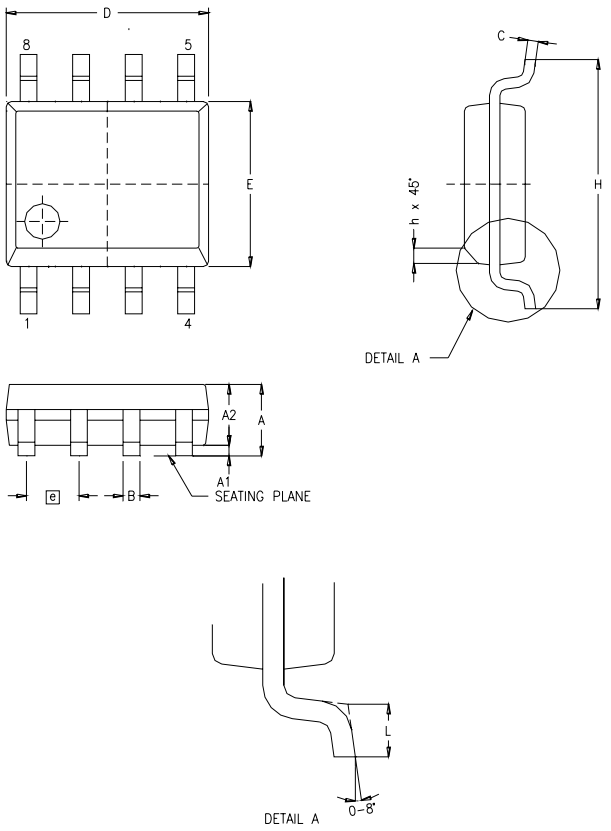
Parameter	Minimum	Maximum	Units	Notes
Ambient temperature under bias	-40	+105	°C	
Storage temperature	-65	+150	°C	
Voltage on any pin with respect to V_{SS}	-0.3	+5.5	V	1
	-0.3	+3.9	V	2
Voltage on V_{DD} pin with respect to V_{SS}	-0.3	+3.6	V	
Maximum current on input and/or inactive output pin	-5	+5	µA	
Maximum output current from active output pin	-25	+25	mA	
8-pin Packages Maximum Ratings at 0 °C to 70 °C				
Total power dissipation		220	mW	
Maximum current into V_{DD} or out of V_{SS}		60	mA	
20-pin Packages Maximum Ratings at 0 °C to 70 °C				
Total power dissipation		430	mW	
Maximum current into V_{DD} or out of V_{SS}		120	mA	
28-pin Packages Maximum Ratings at 0 °C to 70 °C				
Total power dissipation		450	mW	

Table 118. DC Characteristics (Continued)

Symbol	Parameter	T_A = -40 °C to +105 °C (unless otherwise specified)			Units	Conditions
		Minimum	Typical	Maximum		
V_{OH2}	High Level Output Voltage	2.4	–	–	V	I_{OH} = -20 mA; V_{DD} = 3.3 V High Output Drive enabled.
I_{IH}	Input Leakage Current	–	±0.002	±5	µA	$V_{IN} = V_{DD}$ V_{DD} = 3.3 V;
I_{IL}	Input Leakage Current	–	±0.007	±5	µA	$V_{IN} = V_{SS}$ V_{DD} = 3.3 V;
I_{TL}	Tristate Leakage Current	–	–	±5	µA	
I_{LED}	Controlled Current Drive	1.8	3	4.5	mA	{AFS2,AFS1} = {0,0}
		2.8	7	10.5	mA	{AFS2,AFS1} = {0,1}
		7.8	13	19.5	mA	{AFS2,AFS1} = {1,0}
		12	20	30	mA	{AFS2,AFS1} = {1,1}
C_{PAD}	GPIO Port Pad Capacitance	–	8.0[2]	–	pF	
C_{XIN}	XIN Pad Capacitance	–	8.0[2]	–	pF	
C_{XOUT}	XOUT Pad Capacitance	–	9.5[2]	–	pF	
I_{PU}	Weak Pull-up Current	30	100	350	µA	V_{DD} = 3.0 V–3.6 V
V_{RAM}	RAM Data Retention Voltage	TBD			V	Voltage at which RAM retains static values; no reading or writing is allowed.

Notes
1. This condition excludes all pins that have on-chip pull-ups, when driven Low.
2. These values are provided for design guidance only and are not tested in production.

Figure 35 displays the 8-pin Small Outline Integrated Circuit package (SOIC) available for the Z8 Encore! XP F0823 Series devices.



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A	1.55	1.73	0.061	0.068
A1	0.10	0.25	0.004	0.010
A2	1.40	1.55	0.055	0.061
B	0.36	0.48	0.014	0.019
C	0.18	0.25	0.007	0.010
D	4.80	4.98	0.189	0.196
E	3.81	3.99	0.150	0.157
e	1.27 BSC		.050 BSC	
H	5.84	6.15	0.230	0.242
h	0.25	0.40	0.010	0.016
L	0.46	0.81	0.018	0.032

CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH.

Figure 35. 8-Pin Small Outline Integrated Circuit Package (SOIC)

Ordering Information

Part Number	Flash	RAM	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Description
Z8 Encore! XP with 8 KB Flash, 10-Bit Analog-to-Digital Converter								
Standard Temperature: 0 °C to 70 °C								
Z8F0823PB005SC	8 KB	1 KB	6	12	2	4	1	PDIP 8-pin package
Z8F0823QB005SC	8 KB	1 KB	6	12	2	4	1	QFN 8-pin package
Z8F0823SB005SC	8 KB	1 KB	6	12	2	4	1	SOIC 8-pin package
Z8F0823SH005SC	8 KB	1 KB	16	18	2	7	1	SOIC 20-pin package
Z8F0823HH005SC	8 KB	1 KB	16	18	2	7	1	SSOP 20-pin package
Z8F0823PH005SC	8 KB	1 KB	16	18	2	7	1	PDIP 20-pin package
Z8F0823SJ005SC	8 KB	1 KB	22	18	2	8	1	SOIC 28-pin package
Z8F0823HJ005SC	8 KB	1 KB	22	18	2	8	1	SSOP 28-pin package
Z8F0823PJ005SC	8 KB	1 KB	22	18	2	8	1	PDIP 28-pin package
Extended Temperature: -40 °C to 105 °C								
Z8F0823PB005EC	8 KB	1 KB	6	12	2	4	1	PDIP 8-pin package
Z8F0823QB005EC	8 KB	1 KB	6	12	2	4	1	QFN 8-pin package
Z8F0823SB005EC	8 KB	1 KB	6	12	2	4	1	SOIC 8-pin package
Z8F0823SH005EC	8 KB	1 KB	16	18	2	7	1	SOIC 20-pin package
Z8F0823HH005EC	8 KB	1 KB	16	18	2	7	1	SSOP 20-pin package
Z8F0823PH005EC	8 KB	1 KB	16	18	2	7	1	PDIP 20-pin package
Z8F0823SJ005EC	8 KB	1 KB	22	18	2	8	1	SOIC 28-pin package
Z8F0823HJ005EC	8 KB	1 KB	22	18	2	8	1	SSOP 28-pin package
Z8F0823PJ005EC	8 KB	1 KB	22	18	2	8	1	PDIP 28-pin package
Replace C with G for Lead-Free Packaging								