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Details

Product Status	Obsolete
Core Processor	eZ8
Core Size	8-Bit
Speed	5MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, POR, PWM, WDT
Number of I/O	16
Program Memory Size	2KB (2K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	20-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f0213ph005sc

Table 6. Z8 Encore! XP F0823 Series Program Memory Maps (Continued)

Program Memory Address (Hex)	Function
0002–0003	Reset Vector
0004–0005	WDT Interrupt Vector
0006–0007	Illegal Instruction Trap
0008–0037	Interrupt Vectors*
0038–003D	Oscillator Fail Traps*
003E–03FF	Program Memory

*See Table 33 on page 54 for a list of the interrupt vectors and traps.

Data Memory

Z8 Encore! XP[®] F0823 Series does not use the eZ8 CPU's 64 KB Data Memory address space.

Flash Information Area

Table 7 lists the Z8 Encore! XP F0823 Series Flash Information Area. This 128 B Information Area is accessed by setting bit 7 of the Flash Page Select Register to 1. When access is enabled, the Flash Information Area is mapped into the Program Memory and overlays the 128 bytes at addresses FE00H to FF7FH. When the Information Area access is enabled, all reads from these Program Memory addresses return the Information Area data rather than the Program Memory data. Access to the Flash Information Area is read-only.

Table 7. Z8 Encore! XP F0823 Series Flash Memory Information Area Map

Program Memory Address (Hex)	Function
FE00–FE3F	Zilog Option Bits.
FE40–FE53	Part Number. 20-character ASCII alphanumeric code Left justified and filled with FH.
FE54–FE5F	Reserved.
FE60–FE7F	Zilog Calibration Data.
FE80–FFFF	Reserved.

GPIO Interrupts

Many of the GPIO port pins are used as interrupt sources. Some port pins are configured to generate an interrupt request on either the rising edge or falling edge of the pin input signal. Other port pin interrupt sources generate an interrupt when any edge occurs (both rising and falling). For more information about interrupts using the GPIO pins, see Interrupt Controller on page 53.

GPIO Control Register Definitions

Four registers for each Port provide access to GPIO control, input data, and output data. Table 17 lists these Port registers. Use the Port A–D Address and Control registers together to provide access to sub-registers for Port configuration and control.

Table 17. GPIO Port Registers and Sub-Registers

Port Register Mnemonic	Port Register Name
PxADDR	Port A–C Address Register (Selects sub-registers)
PxCTL	Port A–C Control Register (Provides access to sub-registers)
PxIN	Port A–C Input Data Register
PxOUT	Port A–C Output Data Register
Port Sub-Register Mnemonic	Port Register Name
PxDD	Data Direction
PxAF	Alternate Function
PxOC	Output Control (Open-Drain)
PxHDE	High Drive Enable
PxSMRE	Stop Mode Recovery Source Enable
PxPUE	Pull-up Enable
PxAFS1	Alternate Function Set 1
PxAFS2	Alternate Function Set 2

Operation

The timers are 16-bit up-counters. Minimum time-out delay is set by loading the value 0001H into the Timer Reload High and Low Byte registers and setting the prescale value to 1. Maximum time-out delay is set by loading the value 0000H into the Timer Reload High and Low Byte registers and setting the prescale value to 128. If the Timer reaches FFFFH, the timer rolls over to 0000H and continues counting.

Timer Operating Modes

The timers can be configured to operate in the following modes:

ONE-SHOT Mode

In ONE-SHOT mode, the timer counts up to the 16-bit Reload value stored in the Timer Reload High and Low Byte registers. The timer input is the system clock. Upon reaching the Reload value, the timer generates an interrupt and the count value in the Timer High and Low Byte registers is reset to 0001H. The timer is automatically disabled and stops counting.

Also, if the Timer Output alternate function is enabled, the Timer Output pin changes state for one system clock cycle (from Low to High or from High to Low) upon timer Reload. If it is appropriate to have the Timer Output make a state change at a One-Shot time-out (rather than a single cycle pulse), first set the TPOL bit in the Timer Control register to the start value before enabling ONE-SHOT mode. After starting the timer, set TPOL to the opposite bit value.

Follow the steps below for configuring a timer for ONE-SHOT mode and initiating the count:

1. Write to the Timer Control register to:
 - Disable the timer
 - Configure the timer for ONE-SHOT mode
 - Set the prescale value
 - Set the initial output level (High or Low) if using the Timer Output alternate function
2. Write to the Timer High and Low Byte registers to set the starting count value.
3. Write to the Timer Reload High and Low Byte registers to set the Reload value.
4. If appropriate, enable the timer interrupt and set the timer interrupt priority by writing to the relevant interrupt registers.
5. If using the Timer Output function, configure the associated GPIO port pin for the Timer Output alternate function.

CAPTURE/COMPARE Mode

0 = Counting is started on the first rising edge of the Timer Input signal. The current count is captured on subsequent rising edges of the Timer Input signal.

1 = Counting is started on the first falling edge of the Timer Input signal. The current count is captured on subsequent falling edges of the Timer Input signal.

PWM DUAL OUTPUT Mode

0 = Timer Output is forced Low (0) and Timer Output Complement is forced High (1) when the timer is disabled. When enabled, the Timer Output is forced High (1) upon PWM count match and forced Low (0) upon Reload. When enabled, the Timer Output Complement is forced Low (0) upon PWM count match and forced High (1) upon Reload. The PWMD field in TxCTL0 register is a programmable delay to control the number of cycles time delay before the Timer Output and the Timer Output Complement is forced to High (1).

1 = Timer Output is forced High (1) and Timer Output Complement is forced Low (0) when the timer is disabled. When enabled, the Timer Output is forced Low (0) upon PWM count match and forced High (1) upon Reload. When enabled, the Timer Output Complement is forced High (1) upon PWM count match and forced Low (0) upon Reload. The PWMD field in TxCTL0 register is a programmable delay to control the number of cycles time delay before the Timer Output and the Timer Output Complement is forced to Low (0).

CAPTURE RESTART Mode

0 = Count is captured on the rising edge of the Timer Input signal

1 = Count is captured on the falling edge of the Timer Input signal

COMPARATOR COUNTER Mode

When the timer is disabled, the Timer Output signal is set to the value of this bit.

When the timer is enabled, the Timer Output signal is complemented upon timer Reload.

! Caution: *When the Timer Output alternate function TxOUT on a GPIO port pin is enabled, TxOUT changes to whatever state the TPOL bit is in. The timer does not need to be enabled for that to happen. Also, the port data direction sub register is not needed to be set to output on TxOUT. Changing the TPOL bit with the timer enabled and running does not immediately change the TxOUT.*

PRES—Prescale value.

The timer input clock is divided by 2^{PRES} , where PRES can be set from 0 to 7. The prescaler is reset each time the Timer is disabled. This reset ensures proper clock division each time the Timer is restarted.

000 = Divide by 1

001 = Divide by 2

Watchdog Timer

The Watchdog Timer (WDT) protects against corrupt or unreliable software, power faults, and other system-level problems which can place Z8 Encore! XP[®] F0823 Series devices into unsuitable operating states. The features of Watchdog Timer include:

- On-chip RC oscillator
- A selectable time-out response: reset or interrupt
- 24-bit programmable time-out value

Operation

The WDT is a retriggerable one-shot timer that resets or interrupts Z8 Encore! XP F0823 Series devices when the WDT reaches its terminal count. The Watchdog Timer uses a dedicated on-chip RC oscillator as its clock source. The Watchdog Timer operates in only two modes: ON and OFF. Once enabled, it always counts and must be refreshed to prevent a time-out. Perform an enable by executing the WDT instruction or by setting the WDT_AO Flash Option Bit. The WDT_AO bit forces the Watchdog Timer to operate immediately upon reset, even if a WDT instruction has not been executed.

The Watchdog Timer is a 24-bit reloadable down counter that uses three 8-bit registers in the eZ8 CPU register space to set the reload value. The nominal WDT time-out period is described by the following equation:

$$\text{WDT Time-out Period (ms)} = \frac{\text{WDT Reload Value}}{10}$$

where the WDT reload value is the decimal value of the 24-bit value given by {WDTU[7:0], WDTM[7:0], WDTL[7:0]} and the typical Watchdog Timer RC oscillator frequency is 10 kHz. The Watchdog Timer cannot be refreshed after it reaches 000002H. The WDT Reload Value must not be set to values below 000004H. Table 57 provides information about approximate time-out delays for the minimum and maximum WDT reload values.

Table 57. Watchdog Timer Approximate Time-Out Delays

WDT Reload Value (Hex)	WDT Reload Value (Decimal)	Approximate Time-Out Delay (with 10 kHz typical WDT oscillator frequency)	
		Typical	Description
000004	4	400 μ s	Minimum time-out delay
FFFFFF	16,777,215	28 minutes	Maximum time-out delay

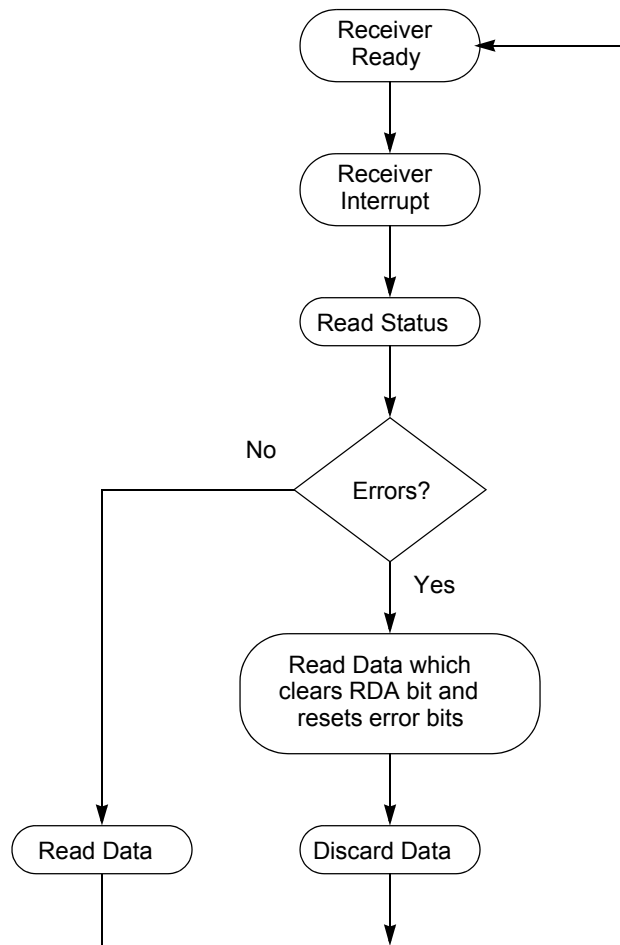


Figure 15. UART Receiver Interrupt Service Routine Flow

Baud Rate Generator Interrupts

If the Baud Rate Generator (BRG) interrupt enable is set, the UART Receiver interrupt asserts when the UART Baud Rate Generator reloads. This condition allows the Baud Rate Generator to function as an additional counter if the UART functionality is not employed.

UART Baud Rate Generator

The UART Baud Rate Generator creates a lower frequency baud rate clock for data transmission. The input to the Baud Rate Generator is the system clock. The UART Baud Rate High and Low Byte registers combine to create a 16-bit baud rate divisor value

Endec, and passed to the UART. Communication is half-duplex, which means simultaneous data transmission and reception is not allowed.

The baud rate is set by the UART's baud rate generator and supports IrDA standard baud rates from 9600 baud to 115.2 kbaud. Higher baud rates are possible, but do not meet IrDA specifications. The UART must be enabled to use the Infrared Endec. The Infrared Endec data rate is calculated using the following equation:

$$\text{Infrared Data Rate (bits/s)} = \frac{\text{System Clock Frequency (Hz)}}{16 \times \text{UART Baud Rate Divisor Value}}$$

Transmitting IrDA Data

The data to be transmitted using the infrared transceiver is first sent to the UART. The UART's transmit signal (TXD) and baud rate clock are used by the IrDA to generate the modulation signal (IR_TXD) that drives the infrared transceiver. Each UART/Infrared data bit is 16 clocks wide. If the data to be transmitted is 1, the IR_TXD signal remains low for the full 16 clock period. If the data to be transmitted is 0, the transmitter first outputs a 7 clock low period, followed by a 3 clock high pulse. Finally, a 6 clock low pulse is output to complete the full 16 clock data period. Figure 17 displays IrDA data transmission. When the Infrared Endec is enabled, the UART's TXD signal is internal to Z8 Encore! XP® F0823 Series products while the IR_TXD signal is output through the TXD pin.

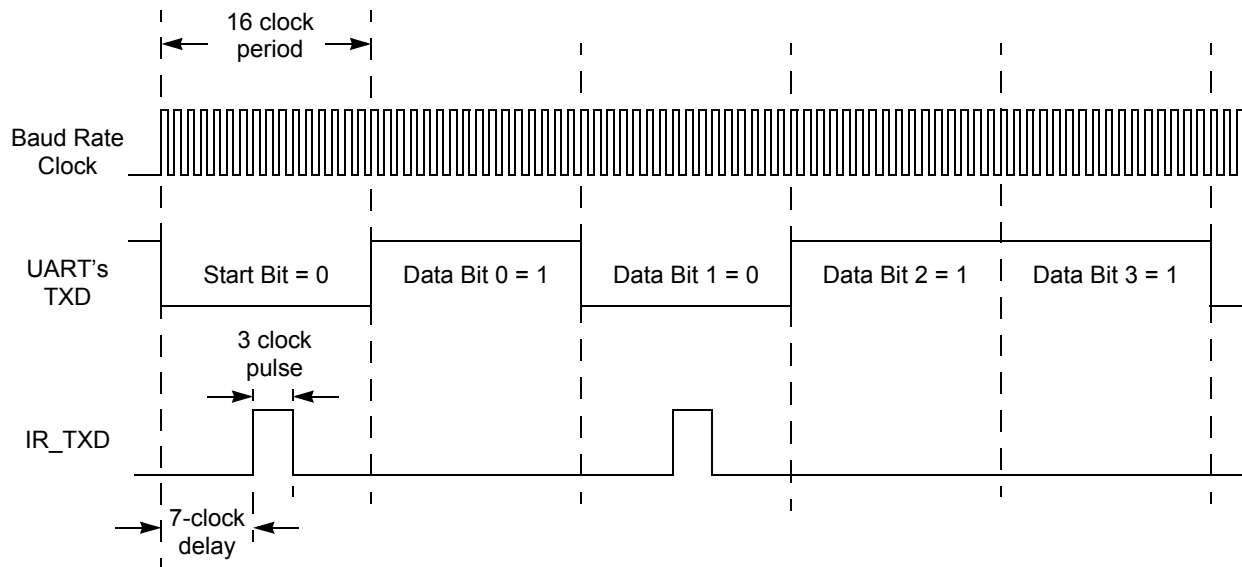


Figure 17. Infrared Data Transmission

Analog-to-Digital Converter

The Analog-to-Digital Converter (ADC) converts an analog input signal to its digital representation. The features of this sigma-delta ADC include:

- 10-bit resolution
- Eight single-ended analog input sources are multiplexed with general-purpose I/O ports
- Interrupt upon conversion complete
- Bandgap generated internal voltage reference generator with two selectable levels
- Factory offset and gain calibration

Architecture

Figure 19 displays the major functional blocks of the ADC. An analog multiplexer network selects the ADC input from the available analog pins, ANA0 through ANA7.

Figure 20. Flash Memory Arrangement

Flash Information Area

The Flash information area is separate from program memory and is mapped to the address range `FE00H` to `FFFFH`. Not all these addresses are accessible. Factory trim values for the analog peripherals are stored here. Factory calibration data for the ADC is also stored here.

Flash Control Register Definitions

Flash Control Register

The Flash Controller must be unlocked using the Flash Control (FCTL) register before programming or erasing the Flash memory. Writing the sequence 73H 8CH, sequentially, to the Flash Control register unlocks the Flash Controller. When the Flash Controller is unlocked, the Flash memory can be enabled for Mass Erase or Page Erase by writing the appropriate enable command to the FCTL. Page Erase applies only to the active page selected in Flash Page Select register. Mass Erase is enabled only through the On-Chip Debugger. Writing an invalid value or an invalid sequence returns the Flash Controller to its locked state. The Write-only Flash Control Register shares its Register File address with the read-only Flash Status Register.

Table 79. Flash Control Register (FCTL)

BITS	7	6	5	4	3	2	1	0
FIELD	FCMD							
RESET	0	0	0	0	0	0	0	0
R/W	W	W	W	W	W	W	W	W
ADDR	FF8H							

FCMD—Flash Command

73H = First unlock command

8CH = Second unlock command

95H = Page Erase command (must be third command in sequence to initiate Page Erase)

63H = Mass Erase command (must be third command in sequence to initiate Mass Erase)

5EH = Enable Flash Sector Protect Register Access

Flash Status Register

The Flash Status register indicates the current state of the Flash Controller. This register can be read at any time. The read-only Flash Status Register shares its Register File address with the write-only Flash Control Register.

Table 80. Flash Status Register (FSTAT)

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved		FSTAT					
RESET	0	0	0	0	0	0	0	0
R/W	R	R	R	R	R	R	R	R
ADDR	FF8H							

Trim Bit Data Register

The Trim Bid Data (TRMDR) register contains the read or write data for access to the trim option bits.

Table 86. Trim Bit Data Register (TRMDR)

BITS	7	6	5	4	3	2	1	0
FIELD	TRMDR - Trim Bit Data							
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FF7H							

Flash Option Bit Address Space

The first two bytes of Flash program memory at addresses 0000H and 0001H are reserved for the user-programmable Flash option bits.

Flash Program Memory Address 0000H

Table 87. Flash Option Bits at Program Memory Address 0000H

BITS	7	6	5	4	3	2	1	0
FIELD	WDT_RES	WDT_AO	Reserved		VBO_AO	FRP	Reserved	FWP
RESET	U	U	U	U	U	U	U	U
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	Program Memory 0000H							
Note: U = Unchanged by Reset. R/W = Read/Write.								

WDT_RES—Watchdog Timer Reset

0 = Watchdog Timer time-out generates an interrupt request. Interrupts must be globally enabled for the eZ8 CPU to acknowledge the interrupt request.

1 = Watchdog Timer time-out causes a system reset. This setting is the default for unprogrammed (erased) Flash.

WDT_AO—Watchdog Timer Always ON

0 = Watchdog Timer is automatically enabled upon application of system power. Watchdog Timer can not be disabled.

1 = Watchdog Timer is enabled upon execution of the WDT instruction. Once enabled, the

Assembly Language Syntax

For proper instruction execution, eZ8 CPU assembly language syntax requires that the operands be written as ‘destination, source’. After assembly, the object code usually has the operands in the order ‘source, destination’, but ordering is opcode-dependent. The following instruction examples illustrate the format of some basic assembly instructions and the resulting object code produced by the assembler. You must follow this binary format if you prefer manual program coding or intend to implement your own assembler.

Example 1

If the contents of Registers 43H and 08H are added and the result is stored in 43H, the assembly syntax and resulting object code is:

Table 103. Assembly Language Syntax Example 1

Assembly Language Code	ADD	43H,	08H	(ADD dst, src)
Object Code	04	08	43	(OPC src, dst)

Example 2

In general, when an instruction format requires an 8-bit register address, that address can specify any register location in the range 0–255 or, using Escaped Mode Addressing, a Working Register R0–R15. If the contents of Register 43H and Working Register R8 are added and the result is stored in 43H, the assembly syntax and resulting object code is:

Table 104. Assembly Language Syntax Example 2

Assembly Language Code	ADD	43H,	R8	(ADD dst, src)
Object Code	04	E8	43	(OPC src, dst)

See the device-specific Product Specification to determine the exact register file range available. The register file size varies, depending on the device type.

eZ8 CPU Instruction Notation

In the eZ8 CPU Instruction Summary and Description sections, the operands, condition codes, status flags, and address modes are represented by a notational shorthand that is described in Table 105.

- Rotate and Shift

Tables 107 through Table 114 contain the instructions belonging to each group and the number of operands required for each instruction. Some instructions appear in more than one table as these instruction can be considered as a subset of more than one category. Within these tables, the source operand is identified as ‘src’, the destination operand is ‘dst’ and a condition code is ‘cc’.

Table 107. Arithmetic Instructions

Mnemonic	Operands	Instruction
ADC	dst, src	Add with Carry
ADCX	dst, src	Add with Carry using Extended Addressing
ADD	dst, src	Add
ADDX	dst, src	Add using Extended Addressing
CP	dst, src	Compare
CPC	dst, src	Compare with Carry
CPCX	dst, src	Compare with Carry using Extended Addressing
CPX	dst, src	Compare using Extended Addressing
DA	dst	Decimal Adjust
DEC	dst	Decrement
DECW	dst	Decrement Word
INC	dst	Increment
INCW	dst	Increment Word
MULT	dst	Multiply
SBC	dst, src	Subtract with Carry
SBCX	dst, src	Subtract with Carry using Extended Addressing
SUB	dst, src	Subtract
SUBX	dst, src	Subtract using Extended Addressing

Table 112. Logical Instructions (Continued)

Mnemonic	Operands	Instruction
ORX	dst, src	Logical OR using Extended Addressing
XOR	dst, src	Logical Exclusive OR
XORX	dst, src	Logical Exclusive OR using Extended Addressing

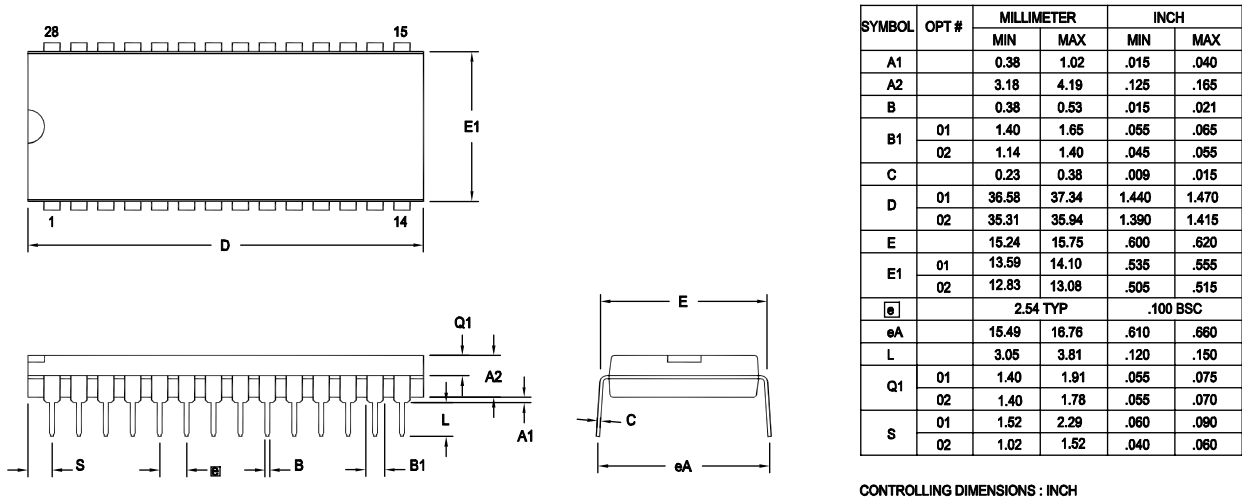
Table 113. Program Control Instructions

Mnemonic	Operands	Instruction
BRK	—	On-Chip Debugger Break
BTJ	p, bit, src, DA	Bit Test and Jump
BTJNZ	bit, src, DA	Bit Test and Jump if Non-Zero
BTJZ	bit, src, DA	Bit Test and Jump if Zero
CALL	dst	Call Procedure
DJNZ	dst, src, RA	Decrement and Jump Non-Zero
IRET	—	Interrupt Return
JP	dst	Jump
JP cc	dst	Jump Conditional
JR	DA	Jump Relative
JR cc	DA	Jump Relative Conditional
RET	—	Return
TRAP	vector	Software Trap

Table 114. Rotate and Shift Instructions

Mnemonic	Operands	Instruction
BSWAP	dst	Bit Swap
RL	dst	Rotate Left
RLC	dst	Rotate Left through Carry
RR	dst	Rotate Right
RRC	dst	Rotate Right through Carry

Figure 40 displays the 28-pin Plastic Dual Inline Package (PDIP) available for Z8 Encore! XP F0823 Series devices.



OPTION TABLE	
OPTION #	PACKAGE
01	STANDARD
02	IDF

Note: ZILOG supplies both options for production. Component layout
PCB design should cover bigger option 01.

Figure 40. 28-Pin Plastic Dual Inline Package (PDIP)

Part Number	Flash	RAM	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Description
Z8 Encore! XP with 4 KB Flash, 10-Bit Analog-to-Digital Converter								
Standard Temperature: 0 °C to 70 °C								
Z8F0423PB005SC	4 KB	1 KB	6	12	2	4	1	PDIP 8-pin package
Z8F0423QB005SC	4 KB	1 KB	6	12	2	4	1	QFN 8-pin package
Z8F0423SB005SC	4 KB	1 KB	6	12	2	4	1	SOIC 8-pin package
Z8F0423SH005SC	4 KB	1 KB	16	18	2	7	1	SOIC 20-pin package
Z8F0423HH005SC	4 KB	1 KB	16	18	2	7	1	SSOP 20-pin package
Z8F0423PH005SC	4 KB	1 KB	16	18	2	7	1	PDIP 20-pin package
Z8F0423SJ005SC	4 KB	1 KB	22	18	2	8	1	SOIC 28-pin package
Z8F0423HJ005SC	4 KB	1 KB	22	18	2	8	1	SSOP 28-pin package
Z8F0423PJ005SC	4 KB	1 KB	22	18	2	8	1	PDIP 28-pin package
Extended Temperature: -40 °C to 105 °C								
Z8F0423PB005EC	4 KB	1 KB	6	12	2	4	1	PDIP 8-pin package
Z8F0423QB005EC	4 KB	1 KB	6	12	2	4	1	QFN 8-pin package
Z8F0423SB005EC	4 KB	1 KB	6	12	2	4	1	SOIC 8-pin package
Z8F0423SH005EC	4 KB	1 KB	16	18	2	7	1	SOIC 20-pin package
Z8F0423HH005EC	4 KB	1 KB	16	18	2	7	1	SSOP 20-pin package
Z8F0423PH005EC	4 KB	1 KB	16	18	2	7	1	PDIP 20-pin package
Z8F0423SJ005EC	4 KB	1 KB	22	18	2	8	1	SOIC 28-pin package
Z8F0423HJ005EC	4 KB	1 KB	22	18	2	8	1	SSOP 28-pin package
Z8F0423PJ005EC	4 KB	1 KB	22	18	2	8	1	PDIP 28-pin package
Replace C with G for Lead-Free Packaging								

Part Number	Flash	RAM	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Description
Z8 Encore! XP with 2 KB Flash, 10-Bit Analog-to-Digital Converter								
Standard Temperature: 0 °C to 70 °C								
Z8F0223PB005SC	2 KB	512 B	6	12	2	4	1	PDIP 8-pin package
Z8F0223QB005SC	2 KB	512 B	6	12	2	4	1	QFN 8-pin package
Z8F0223SB005SC	2 KB	512 B	6	12	2	4	1	SOIC 8-pin package
Z8F0223SH005SC	2 KB	512 B	16	18	2	7	1	SOIC 20-pin package
Z8F0223HH005SC	2 KB	512 B	16	18	2	7	1	SSOP 20-pin package
Z8F0223PH005SC	2 KB	512 B	16	18	2	7	1	PDIP 20-pin package
Z8F0223SJ005SC	2 KB	512 B	22	18	2	8	1	SOIC 28-pin package
Z8F0223HJ005SC	2 KB	512 B	22	18	2	8	1	SSOP 28-pin package
Z8F0223PJ005SC	2 KB	512 B	22	18	2	8	1	PDIP 28-pin package
Extended Temperature: -40 °C to 105 °C								
Z8F0223PB005EC	2 KB	512 B	6	12	2	4	1	PDIP 8-pin package
Z8F0223QB005EC	2 KB	512 B	6	12	2	4	1	QFN 8-pin package
Z8F0223SB005EC	2 KB	512 B	6	12	2	4	1	SOIC 8-pin package
Z8F0223SH005EC	2 KB	512 B	16	18	2	7	1	SOIC 20-pin package
Z8F0223HH005EC	2 KB	512 B	16	18	2	7	1	SSOP 20-pin package
Z8F0223PH005EC	2 KB	512 B	16	18	2	7	1	PDIP 20-pin package
Z8F0223SJ005EC	2 KB	512 B	22	18	2	8	1	SOIC 28-pin package
Z8F0223HJ005EC	2 KB	512 B	22	18	2	8	1	SSOP 28-pin package
Z8F0223PJ005EC	2 KB	512 B	22	18	2	8	1	PDIP 28-pin package
Replace C with G for Lead-Free Packaging								

L

LD 177
 LDC 177
 LDCI 176, 177
 LDE 177
 LDEI 176, 177
 LDX 177
 LEA 177
 load 177
 load constant 176
 load constant to/from program memory 177
 load constant with auto-increment addresses 177
 load effective address 177
 load external data 177
 load external data to/from data memory and auto-increment addresses 176
 load external to/from data memory and auto-increment addresses 177
 load instructions 177
 load using extended addressing 177
 logical AND 177
 logical AND/extended addressing 177
 logical exclusive OR 178
 logical exclusive OR/extended addressing 178
 logical instructions 177
 logical OR 177
 logical OR/extended addressing 178
 low power modes 31

M

master interrupt enable 55
 memory
 data 15
 program 13
 mode
 CAPTURE 84, 85
 CAPTURE/COMPARE 85
 CONTINUOUS 84
 COUNTER 84
 GATED 84
 ONE-SHOT 84
 PWM 84, 85

modes 84
 MULT 175
 multiply 175
 MULTIPROCESSOR mode, UART 99

N

NOP (no operation) 176
 notation
 b 173
 cc 173
 DA 173
 ER 173
 IM 173
 IR 173
 lr 173
 IRR 173
 lrr 173
 p 173
 R 173
 r 173
 RA 173
 RR 173
 rr 173
 vector 173
 X 173
 notational shorthand 173

O

OCD
 architecture 151
 auto-baud detector/generator 154
 baud rate limits 155
 block diagram 151
 breakpoints 156
 commands 157
 control register 161
 data format 154
 DBG pin to RS-232 Interface 152
 DEBUG mode 153
 debugger break 178
 interface 152
 serial errors 155