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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Obsolete
Core Processor	eZ8
Core Size	8-Bit
Speed	5MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, POR, PWM, WDT
Number of I/O	6
Program Memory Size	4KB (4K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	8-SOIC (0.154", 3.90mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f0423sb005sc

Ordering Information **217**
 Part Number Suffix Designations 226
Index **227**
Customer Support **237**

Reset Controller

Z8 Encore! XP[®] F0823 Series products can be reset using the $\overline{\text{RESET}}$ pin, POR, WDT time-out, STOP mode exit, or Voltage Brownout warning signal. The $\overline{\text{RESET}}$ pin is bidirectional, that is, it functions as reset source as well as a reset indicator.

On-Chip Debugger

Z8 Encore! XP F0823 Series products feature an integrated On-Chip Debugger. The OCD provides a rich-set of debugging capabilities, such as reading and writing registers, programming Flash memory, setting breakpoints and executing code. A single-pin interface provides communication to the OCD.

Table 33. Trap and Interrupt Vectors in Order of Priority (Continued)

Priority	Program Memory Vector Address	Interrupt or Trap Source
Lowest	0036H	Port C Pin 0, both input edges
	0038H	Reserved

Architecture

Figure 8 displays the interrupt controller block diagram.

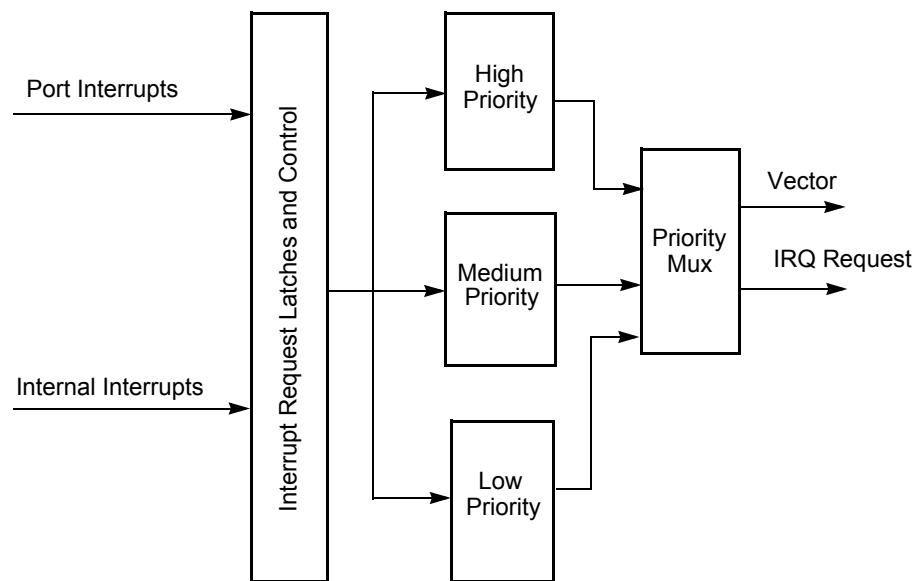


Figure 8. Interrupt Controller Block Diagram

Operation

Master Interrupt Enable

The master interrupt enable bit (IRQE) in the Interrupt Control register globally enables and disables interrupts.

Interrupts are globally enabled by any of the following actions:

- Execution of an Enable Interrupt (EI) instruction
- Execution of an Return from Interrupt (IRET) instruction

Table 36. Interrupt Request 2 Register (IRQ2)

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved				PC3I	PC2I	PC1I	PC0I
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FC6H							

Reserved—Must be 0

PCxI—Port C Pin *x* Interrupt Request

0 = No interrupt request is pending for GPIO Port C pin *x*

1 = An interrupt request from GPIO Port C pin *x* is awaiting service

where *x* indicates the specific GPIO Port C pin number (0–3)

IRQ0 Enable High and Low Bit Registers

Table 37 describes the priority control for IRQ0. The IRQ0 Enable High and Low Bit registers (Table 38 and Table 39) form a priority encoded enabling for interrupts in the Interrupt Request 0 register. Priority is generated by setting bits in each register.

Table 37. IRQ0 Enable and Priority Encoding

IRQ0ENH[x]	IRQ0ENL[x]	Priority	Description
0	0	Disabled	Disabled
0	1	Level 1	Low
1	0	Level 2	Nominal
1	1	Level 3	High

where *x* indicates the register bits from 0–7.

Table 38. IRQ0 Enable High Bit Register (IRQ0ENH)

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved	T1ENH	T0ENH	U0RENH	U0TENH	Reserved	Reserved	ADCENH
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FC1H							

Reserved—Must be 0

T1ENH—Timer 1 Interrupt Request Enable High Bit

T0ENH—Timer 0 Interrupt Request Enable High Bit

U0RENH—UART 0 Receive Interrupt Request Enable High Bit

U0TENH—UART 0 Transmit Interrupt Request Enable High Bit

ADCENH—ADC Interrupt Request Enable High Bit

Table 39. IRQ0 Enable Low Bit Register (IRQ0ENL)

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved	T1ENL	T0ENL	U0RENL	U0TENL	Reserved	Reserved	ADCENL
RESET	0	0	0	0	0	0	0	0
R/W	R	R/W	R/W	R/W	R/W	R	R	R/W
ADDR	FC2H							

Reserved—0 when read

T1ENL—Timer 1 Interrupt Request Enable Low Bit

T0ENL—Timer 0 Interrupt Request Enable Low Bit

U0RENL—UART 0 Receive Interrupt Request Enable Low Bit

U0TENL—UART 0 Transmit Interrupt Request Enable Low Bit

ADCENL—ADC Interrupt Request Enable Low Bit

IRQ1 Enable High and Low Bit Registers

Table 40 describes the priority control for IRQ1. The IRQ1 Enable High and Low Bit registers (Table 41 and Table 42) form a priority encoded enabling for interrupts in the Interrupt Request 1 register. Priority is generated by setting bits in each register.

Table 40. IRQ1 Enable and Priority Encoding

IRQ1ENH[x]	IRQ1ENL[x]	Priority	Description
0	0	Disabled	Disabled
0	1	Level 1	Low
1	0	Level 2	Nominal
1	1	Level 3	High

where x indicates the register bits from 0–7.

Operation

The timers are 16-bit up-counters. Minimum time-out delay is set by loading the value 0001H into the Timer Reload High and Low Byte registers and setting the prescale value to 1. Maximum time-out delay is set by loading the value 0000H into the Timer Reload High and Low Byte registers and setting the prescale value to 128. If the Timer reaches FFFFH, the timer rolls over to 0000H and continues counting.

Timer Operating Modes

The timers can be configured to operate in the following modes:

ONE-SHOT Mode

In ONE-SHOT mode, the timer counts up to the 16-bit Reload value stored in the Timer Reload High and Low Byte registers. The timer input is the system clock. Upon reaching the Reload value, the timer generates an interrupt and the count value in the Timer High and Low Byte registers is reset to 0001H. The timer is automatically disabled and stops counting.

Also, if the Timer Output alternate function is enabled, the Timer Output pin changes state for one system clock cycle (from Low to High or from High to Low) upon timer Reload. If it is appropriate to have the Timer Output make a state change at a One-Shot time-out (rather than a single cycle pulse), first set the TPOL bit in the Timer Control register to the start value before enabling ONE-SHOT mode. After starting the timer, set TPOL to the opposite bit value.

Follow the steps below for configuring a timer for ONE-SHOT mode and initiating the count:

1. Write to the Timer Control register to:
 - Disable the timer
 - Configure the timer for ONE-SHOT mode
 - Set the prescale value
 - Set the initial output level (High or Low) if using the Timer Output alternate function
2. Write to the Timer High and Low Byte registers to set the starting count value.
3. Write to the Timer Reload High and Low Byte registers to set the Reload value.
4. If appropriate, enable the timer interrupt and set the timer interrupt priority by writing to the relevant interrupt registers.
5. If using the Timer Output function, configure the associated GPIO port pin for the Timer Output alternate function.

Timer Control Register Definitions

Timer 0–1 High and Low Byte Registers

The Timer 0–1 High and Low Byte (TxH and TxL) registers (Table 49 and Table 50) contain the current 16-bit timer count value. When the timer is enabled, a read from TxH causes the value in TxL to be stored in a temporary holding register. A read from TxL always returns this temporary register when the timers are enabled. When the timer is disabled, reads from the TxL reads the register directly.

Writing to the Timer High and Low Byte registers while the timer is enabled is not recommended. There are no temporary holding registers available for write operations, so simultaneous 16-bit writes are not possible. If either the Timer High or Low Byte registers are written during counting, the 8-bit written value is placed in the counter (High or Low Byte) at the next clock edge. The counter continues counting from the new value.

Table 49. Timer 0–1 High Byte Register (TxH)

BITS	7	6	5	4	3	2	1	0
FIELD	TH							
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F00H, F08H							

Table 50. Timer 0–1 Low Byte Register (TxL)

BITS	7	6	5	4	3	2	1	0
FIELD	TL							
RESET	0	0	0	0	0	0	0	1
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F01H, F09H							

TH and TL—Timer High and Low Bytes

These 2 bytes, {TH[7:0], TL[7:0]}, contain the current 16-bit timer count value

Timer Reload High and Low Byte Registers

The Timer 0–1 Reload High and Low Byte (TxRH and TxRL) registers (Table 51 and Table 52) store a 16-bit Reload value, {TRH[7:0], TRL[7:0]}. Values written to the Timer Reload High Byte register are stored in a temporary holding register. When a write to the Timer Reload Low Byte register occurs, the temporary holding register value is written to the Timer High Byte register. This operation allows simultaneous updates of the 16-bit Timer Reload value.

Transmitter Interrupts

The transmitter generates a single interrupt when the Transmit Data Register Empty bit (TDRE) is set to 1. This indicates that the transmitter is ready to accept new data for transmission. The TDRE interrupt occurs after the Transmit shift register has shifted the first bit of data out. The Transmit Data register can now be written with the next character to send. This action provides 7 bit periods of latency to load the Transmit Data register before the Transmit shift register completes shifting the current character. Writing to the UART Transmit Data register clears the TDRE bit to 0.

Receiver Interrupts

The receiver generates an interrupt when any of the following occurs:

- A data byte is received and is available in the UART Receive Data register. This interrupt can be disabled independently of the other receiver interrupt sources. The received data interrupt occurs after the receive character has been received and placed in the Receive Data register. To avoid an overrun error, software must respond to this received data available condition before the next character is completely received.

► **Note:** *In MULTIPROCESSOR mode (MPEN = 1), the receive data interrupts are dependent on the multiprocessor configuration and the most recent address byte.*

- A break is received
- An overrun is detected
- A data framing error is detected

UART Overrun Errors

When an overrun error condition occurs the UART prevents overwriting of the valid data currently in the Receive Data register. The Break Detect and Overrun status bits are not displayed until after the valid data has been read.

After the valid data has been read, the UART Status 0 register is updated to indicate the overrun condition (and Break Detect, if applicable). The RDA bit is set to 1 to indicate that the Receive Data register contains a data byte. However, because the overrun error occurred, this byte cannot contain valid data and must be ignored. The BRKD bit indicates if the overrun was caused by a break condition on the line. After reading the status byte indicating an overrun error, the Receive Data register must be read again to clear the error bits in the UART Status 0 register. Updates to the Receive Data register occur only when the next data word is received.

UART Data and Error Handling Procedure

Figure 15 displays the recommended procedure for use in UART receiver interrupt service routines.

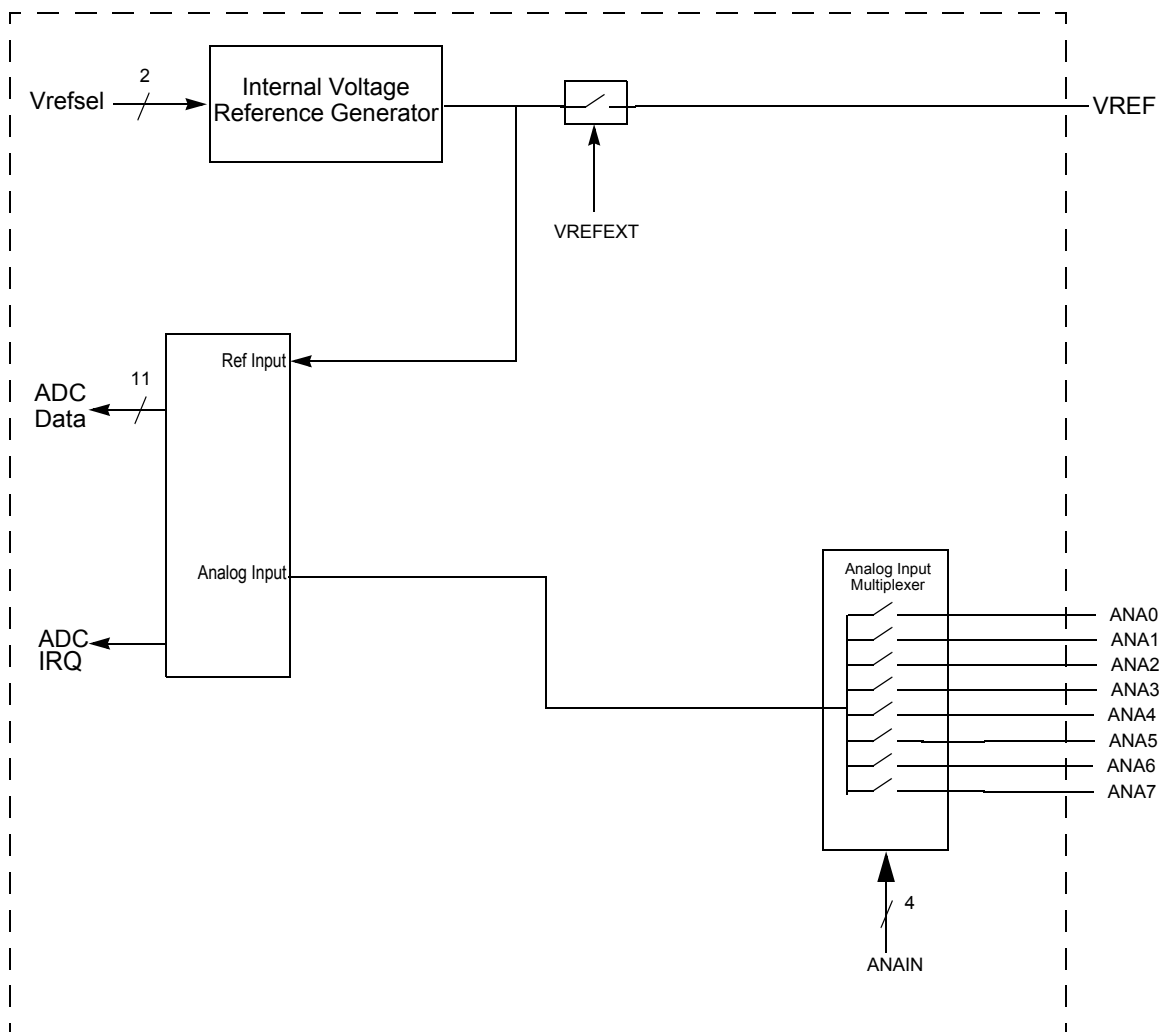


Figure 19. Analog-to-Digital Converter Block Diagram

Operation

Data Format

The output of the ADC is an 11-bit, signed, two's complement digital value. The output generally ranges from 0 to +1023, but offset errors can cause small negative values.

The ADC registers return 13 bits of data, but the two LSBs are intended for compensation use only. When the compensation routine is performed on the 13 bit raw ADC value, two

Figure 20. Flash Memory Arrangement

Flash Information Area

The Flash information area is separate from program memory and is mapped to the address range `FE00H` to `FFFFH`. Not all these addresses are accessible. Factory trim values for the analog peripherals are stored here. Factory calibration data for the ADC is also stored here.

Oscillator Control

Z8 Encore! XP[®] F0823 Series devices uses three possible clocking schemes, each user-selectable:

- On-chip precision trimmed RC oscillator
- External clock drive
- On-chip low power Watchdog Timer oscillator

In addition, Z8 Encore! XP F0823 Series devices contain clock failure detection and recovery circuitry, allowing continued operation despite a failure of the primary oscillator.

Operation

This chapter discusses the logic used to select the system clock and handle primary oscillator failures. A description of the specific operation of each oscillator is outlined elsewhere in this document.

System Clock Selection

The oscillator control block selects from the available clocks. Table 101 details each clock source and its usage.

Table 101. Oscillator Configuration and Selection

Clock Source	Characteristics	Required Setup
Internal Precision RC Oscillator	<ul style="list-style-type: none">• 32.8 kHz or 5.53 MHz• $\pm 4\%$ accuracy when trimmed• No external components required	<ul style="list-style-type: none">• Unlock and write Oscillator Control Register (OSCCTL) to enable and select oscillator at either 5.53 MHz or 32.8 kHz
External Clock Drive	<ul style="list-style-type: none">• 0 to 20 MHz• Accuracy dependent on external clock source	<ul style="list-style-type: none">• Write GPIO registers to configure PB3 pin for external clock function• Unlock and write OSCCTL to select external system clock• Apply external clock signal to GPIO
Internal Watchdog Timer Oscillator	<ul style="list-style-type: none">• 10 kHz nominal• $\pm 40\%$ accuracy; no external components required• Very Low power consumption	<ul style="list-style-type: none">• Enable WDT if not enabled and wait until WDT Oscillator is operating.• Unlock and write Oscillator Control Register (OSCCTL) to enable and select oscillator

Electrical Characteristics

The data in this chapter is pre-qualification and pre-characterization and is subject to change. Additional electrical characteristics may be found in the individual chapters.

Absolute Maximum Ratings

Stresses greater than those listed in Table 117 may cause permanent damage to the device. These ratings are stress ratings only. Operation of the device at any condition outside those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. For improved reliability, tie unused inputs to one of the supply voltages (V_{DD} or V_{SS}).

Table 117. Absolute Maximum Ratings

Parameter	Minimum	Maximum	Units	Notes
Ambient temperature under bias	-40	+105	°C	
Storage temperature	-65	+150	°C	
Voltage on any pin with respect to V_{SS}	-0.3	+5.5	V	1
	-0.3	+3.9	V	2
Voltage on V_{DD} pin with respect to V_{SS}	-0.3	+3.6	V	
Maximum current on input and/or inactive output pin	-5	+5	μA	
Maximum output current from active output pin	-25	+25	mA	
8-pin Packages Maximum Ratings at 0 °C to 70 °C				
Total power dissipation		220	mW	
Maximum current into V_{DD} or out of V_{SS}		60	mA	
20-pin Packages Maximum Ratings at 0 °C to 70 °C				
Total power dissipation		430	mW	
Maximum current into V_{DD} or out of V_{SS}		120	mA	
28-pin Packages Maximum Ratings at 0 °C to 70 °C				
Total power dissipation		450	mW	

Table 118. DC Characteristics (Continued)

Symbol	Parameter	T _A = -40 °C to +105 °C (unless otherwise specified)			Units	Conditions
		Minimum	Typical	Maximum		
V _{OH2}	High Level Output Voltage	2.4	–	–	V	I _{OH} = -20 mA; V _{DD} = 3.3 V High Output Drive enabled.
I _{IH}	Input Leakage Current	–	±0.002	±5	µA	V _{IN} = V _{DD} V _{DD} = 3.3 V;
I _{IL}	Input Leakage Current	–	±0.007	±5	µA	V _{IN} = V _{SS} V _{DD} = 3.3 V;
I _{TL}	Tristate Leakage Current	–	–	±5	µA	
I _{LED}	Controlled Current Drive	1.8	3	4.5	mA	{AFS2,AFS1} = {0,0}
		2.8	7	10.5	mA	{AFS2,AFS1} = {0,1}
		7.8	13	19.5	mA	{AFS2,AFS1} = {1,0}
		12	20	30	mA	{AFS2,AFS1} = {1,1}
C _{PAD}	GPIO Port Pad Capacitance	–	8.0 ²	–	pF	
C _{XIN}	XIN Pad Capacitance	–	8.0 ²	–	pF	
C _{XOUT}	XOUT Pad Capacitance	–	9.5 ²	–	pF	
I _{PU}	Weak Pull-up Current	30	100	350	µA	V _{DD} = 3.0 V–3.6 V
V _{RAM}	RAM Data Retention Voltage	TBD			V	Voltage at which RAM retains static values; no reading or writing is allowed.
Notes 1. This condition excludes all pins that have on-chip pull-ups, when driven Low. 2. These values are provided for design guidance only and are not tested in production.						

Table 123. Flash Memory Electrical Characteristics and Timing

Parameter	$V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ (unless otherwise stated)			Units	Notes
	Minimum	Typical	Maximum		
Flash Byte Read Time	100	–	–	ns	
Flash Byte Program Time	20	–	40	μs	
Flash Page Erase Time	10	–	–	ms	
Flash Mass Erase Time	200	–	–	ms	
Writes to Single Address Before Next Erase	–	–	2		
Flash Row Program Time	–	–	8	ms	Cumulative program time for single row cannot exceed limit before next erase. This parameter is only an issue when bypassing the Flash Controller.
Data Retention	100	–	–	years	25 $^{\circ}\text{C}$
Endurance	10,000	–	–	cycles	Program/erase cycles

Table 124. Watchdog Timer Electrical Characteristics and Timing

Symbol	Parameter	$V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ (unless otherwise stated)			Units	Conditions
		Minimum	Typical	Maximum		
F_{WDT}	WDT Oscillator Frequency		10		kHz	
F_{WDT}	WDT Oscillator Error			± 50	%	
$T_{WDT\text{CAL}}$	WDT Calibrated Timeout	0.98	1	1.02	s	$V_{DD} = 3.3 \text{ V};$ $T_A = 30 \text{ }^{\circ}\text{C}$
		0.70	1	1.30	s	$V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = 0 \text{ }^{\circ}\text{C to } 70 \text{ }^{\circ}\text{C}$
		0.50	1	1.50	s	$V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$

Figure 38 displays the 20-pin Small Outline Integrated Circuit Package (SOIC) available for Z8 Encore! XP F0823 Series devices.

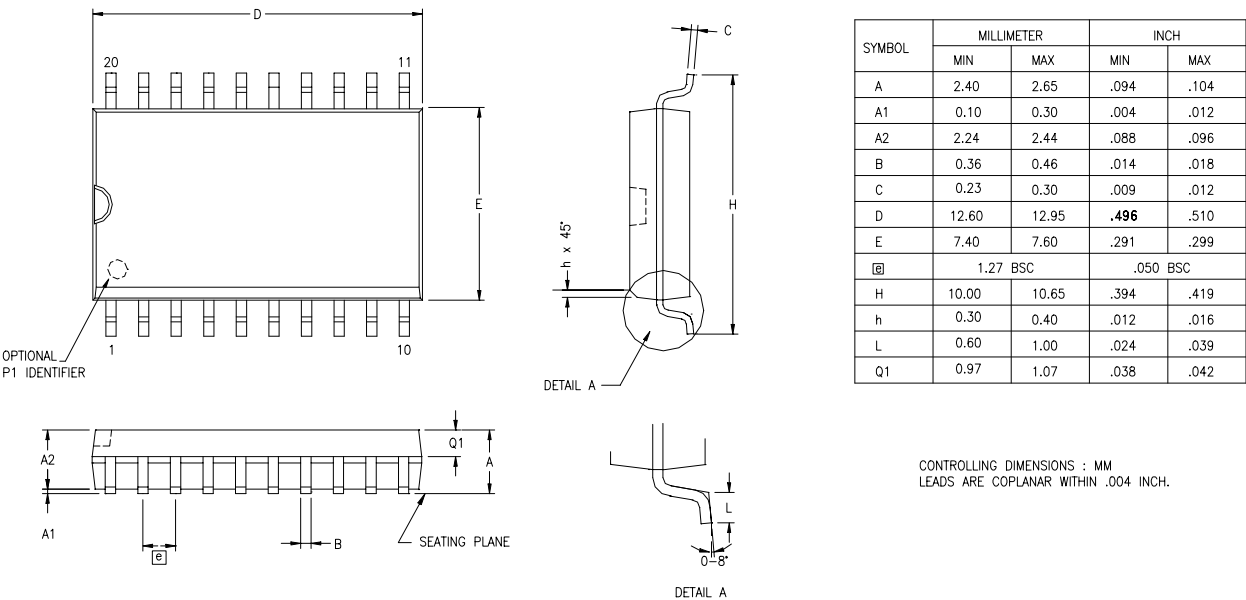


Figure 38. 20-Pin Small Outline Integrated Circuit Package (SOIC)

Figure 39 displays the 20-pin Small Shrink Outline Package (SSOP) available for Z8 Encore! XP F0823 Series devices.

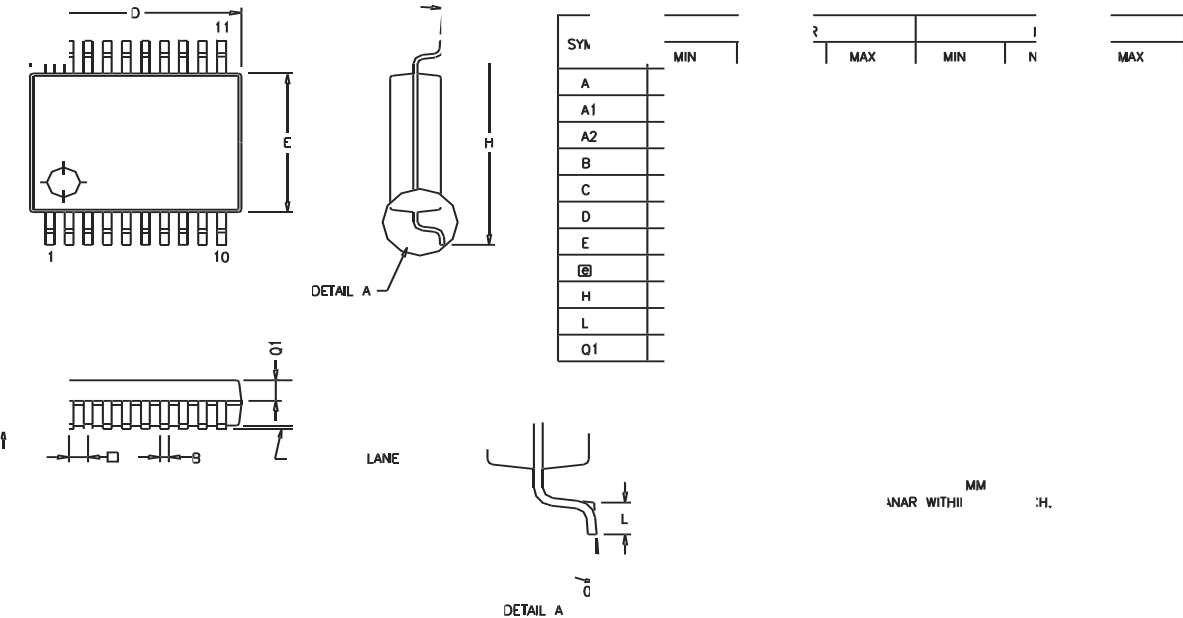


Figure 39. 20-Pin Small Shrink Outline Package (SSOP)

Figure 41 displays the 28-pin Small Outline Integrated Circuit package (SOIC) available in Z8 Encore! XP F0823 Series devices.

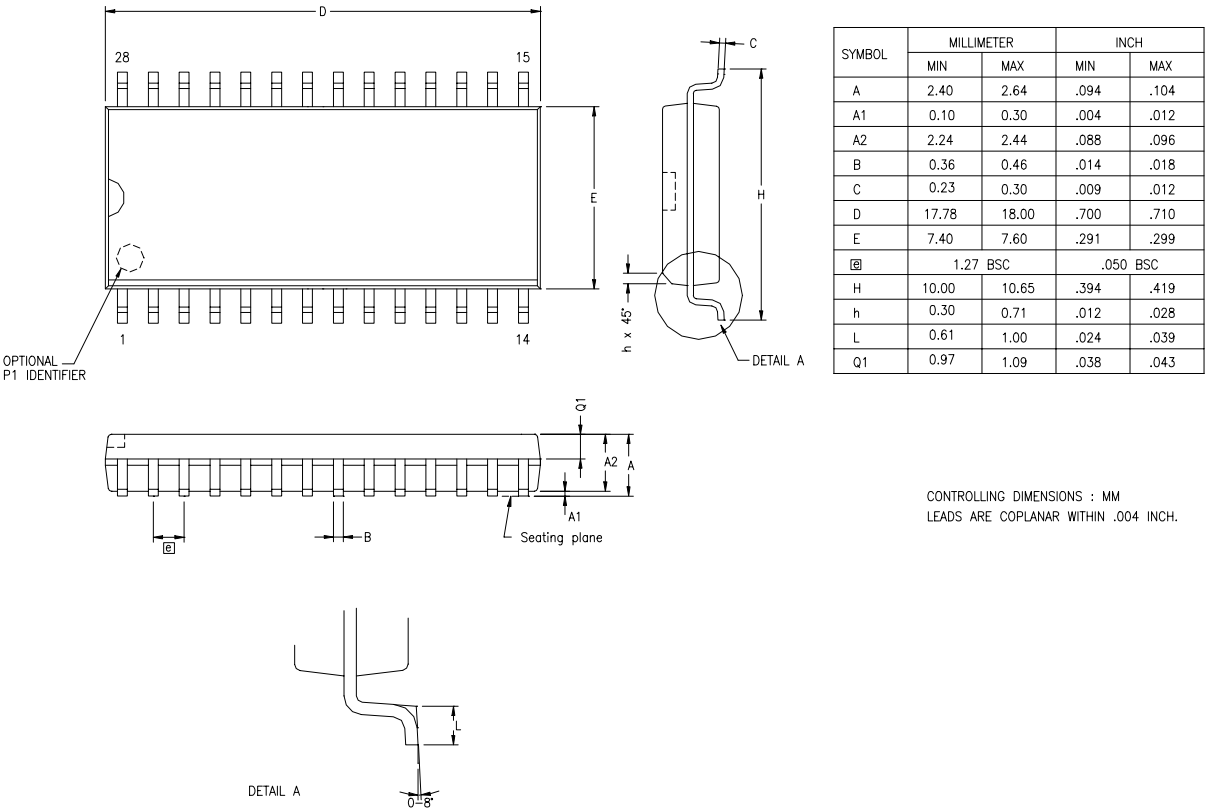


Figure 41. 28-Pin Small Outline Integrated Circuit Package (SOIC)

Figure 42 displays the 28-pin Small Shrink Outline Package (SSOP) available for Z8 Encore! XP F0823 Series devices.

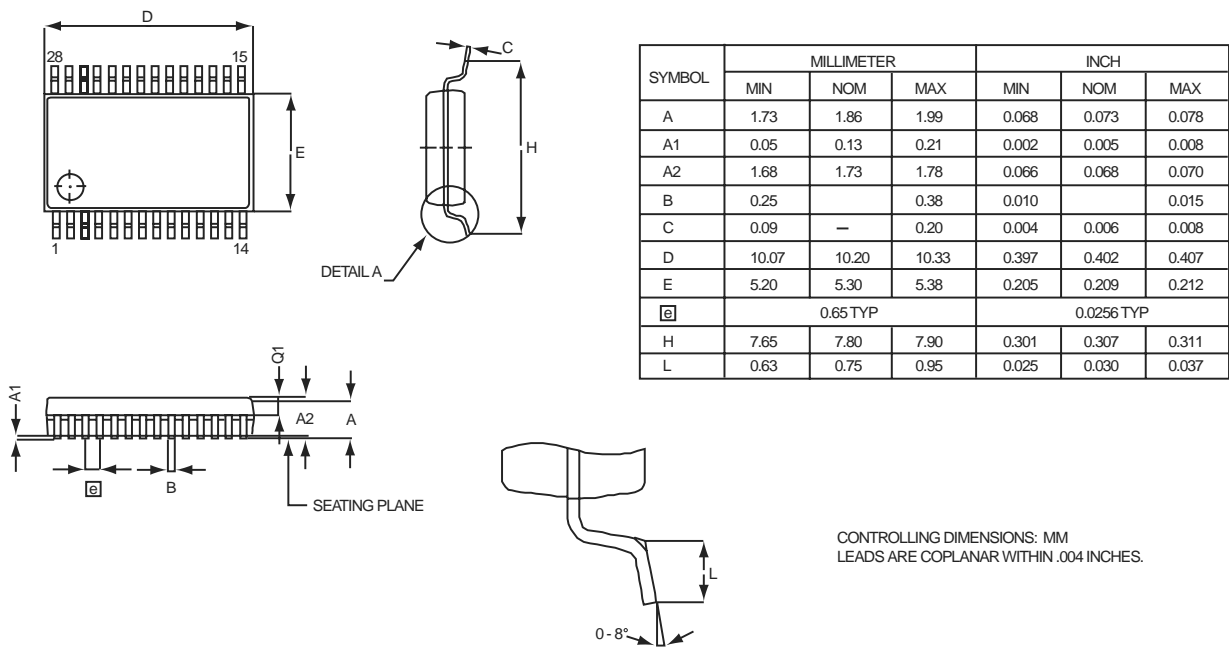


Figure 42. 28-Pin Small Shrink Outline Package (SSOP)

Part Number	Flash	RAM	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Description
Z8 Encore! XP with 8 KB Flash								
Standard Temperature: 0 °C to 70 °C								
Z8F0813PB005SC	8 KB	1 KB	6	12	2	0	1	PDIP 8-pin package
Z8F0813QB005SC	8 KB	1 KB	6	12	2	0	1	QFN 8-pin package
Z8F0813SB005SC	8 KB	1 KB	6	12	2	0	1	SOIC 8-pin package
Z8F0813SH005SC	8 KB	1 KB	16	18	2	0	1	SOIC 20-pin package
Z8F0813HH005SC	8 KB	1 KB	16	18	2	0	1	SSOP 20-pin package
Z8F0813PH005SC	8 KB	1 KB	16	18	2	0	1	PDIP 20-pin package
Z8F0813SJ005SC	8 KB	1 KB	24	18	2	0	1	SOIC 28-pin package
Z8F0813HJ005SC	8 KB	1 KB	24	18	2	0	1	SSOP 28-pin package
Z8F0813PJ005SC	8 KB	1 KB	24	18	2	0	1	PDIP 28-pin package
Extended Temperature: -40 °C to 105 °C								
Z8F0813PB005EC	8 KB	1 KB	6	12	2	0	1	PDIP 8-pin package
Z8F0813QB005EC	8 KB	1 KB	6	12	2	0	1	QFN 8-pin package
Z8F0813SB005EC	8 KB	1 KB	6	12	2	0	1	SOIC 8-pin package
Z8F0813SH005EC	8 KB	1 KB	16	18	2	0	1	SOIC 20-pin package
Z8F0813HH005EC	8 KB	1 KB	16	18	2	0	1	SSOP 20-pin package
Z8F0813PH005EC	8 KB	1 KB	16	18	2	0	1	PDIP 20-pin package
Z8F0813SJ005EC	8 KB	1 KB	24	18	2	0	1	SOIC 28-pin package
Z8F0813HJ005EC	8 KB	1 KB	24	18	2	0	1	SSOP 28-pin package
Z8F0813PJ005EC	8 KB	1 KB	24	18	2	0	1	PDIP 28-pin package
Replace C with G for Lead-Free Packaging								

Part Number	Flash	RAM	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Description
Z8 Encore! XP® F0823 Series Development Kit								
Z8F08A28100KITG								Z8 Encore! XP F082A Series Development Kit (20- and 28-Pin)
Z8F04A28100KITG								Z8 Encore! XP F042A Series Development Kit (20- and 28-Pin)
Z8F04A08100KITG								Z8 Encore! XP F042A Series Development Kit (8-Pin)
ZUSBSC00100ZACG								USB Smart Cable Accessory Kit
ZUSBOPTSC01ZACG								Opto-Isolated USB Smart Cable Accessory Kit
ZENETSC0100ZACG								Ethernet Smart Cable Accessory Kit

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