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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	eZ8
Core Size	8-Bit
Speed	5MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, POR, PWM, WDT
Number of I/O	22
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f0823sj005ec

Table 8. Register File Address Map (Continued)

Address (Hex)	Register Description	Mnemonic	Reset (Hex)	Page No
F0C	Timer 1 PWM High Byte	T1PWMH	00	81
F0D	Timer 1 PWM Low Byte	T1PWML	00	82
F0E	Timer 1 Control 0	T1CTL0	00	82
F0F	Timer 1 Control 1	T1CTL1	00	80
F10–F3F	Reserved	—	XX	
UART				
F40	UART0 Transmit Data	U0TXD	XX	104
	UART0 Receive Data	U0RXD	XX	105
F41	UART0 Status 0	U0STAT0	0000011Xb	105
F42	UART0 Control 0	U0CTL0	00	107
F43	UART0 Control 1	U0CTL1	00	107
F44	UART0 Status 1	U0STAT1	00	106
F45	UART0 Address Compare	U0ADDR	00	109
F46	UART0 Baud Rate High Byte	U0BRH	FF	110
F47	UART0 Baud Rate Low Byte	U0BRL	FF	110
F48–F6F	Reserved	—	XX	
Analog-to-Digital Converter (ADC)				
F70	ADC Control 0	ADCCTL0	00	122
F71	ADC Control 1	ADCCTL1	80	122
F72	ADC Data High Byte	ADCD_H	XX	124
F73	ADC Data Low Bits	ADCD_L	XX	124
F74–F7F	Reserved	—	XX	
Low Power Control				
F80	Power Control 0	PWRCTL0	80	33
F81	Reserved	—	XX	
LED Controller				
F82	LED Drive Enable	LEDEN	00	51
F83	LED Drive Level High Byte	LEDLVLH	00	51
F84	LED Drive Level Low Byte	LEDLVLL	00	52
F85	Reserved	—	XX	
Oscillator Control				
F86	Oscillator Control	OSCCTL	A0	167
F87–F8F	Reserved	—	XX	
Comparator 0				
F90	Comparator 0 Control	CMP0	14	128

Table 8. Register File Address Map (Continued)

Address (Hex)	Register Description	Mnemonic	Reset (Hex)	Page No
F91–FBF	Reserved	—	XX	
Interrupt Controller				
FC0	Interrupt Request 0	IRQ0	00	58
FC1	IRQ0 Enable High Bit	IRQ0ENH	00	60
FC2	IRQ0 Enable Low Bit	IRQ0ENL	00	61
FC3	Interrupt Request 1	IRQ1	00	59
FC4	IRQ1 Enable High Bit	IRQ1ENH	00	62
FC5	IRQ1 Enable Low Bit	IRQ1ENL	00	62
FC6	Interrupt Request 2	IRQ2	00	60
FC7	IRQ2 Enable High Bit	IRQ2ENH	00	63
FC8	IRQ2 Enable Low Bit	IRQ2ENL	00	63
FC9–FCC	Reserved	—	XX	
FCD	Interrupt Edge Select	IRQES	00	64
FCE	Shared Interrupt Select	IRQSS	00	64
FCF	Interrupt Control	IRQCTL	00	65
GPIO Port A				
FD0	Port A Address	PAADDR	00	43
FD1	Port A Control	PACTL	00	45
FD2	Port A Input Data	PAIN	XX	45
FD3	Port A Output Data	PAOUT	00	45
GPIO Port B				
FD4	Port B Address	PBADDR	00	43
FD5	Port B Control	PBCTL	00	45
FD6	Port B Input Data	PBIN	XX	45
FD7	Port B Output Data	PBOUT	00	45
GPIO Port C				
FD8	Port C Address	PCADDR	00	43
FD9	Port C Control	PCCTL	00	45
FDA	Port C Input Data	PCIN	XX	45
FDB	Port C Output Data	PCOUT	00	45
FDC–FEF	Reserved	—	XX	
Watchdog Timer (WDT)				
FF0	Reset Status	RSTSTAT	XX	90
	Watchdog Timer Control	WDTCTL	XX	90
FF1	Watchdog Timer Reload Upper Byte	WDTU	FF	91

Table 19. Port A–C Control Registers (P*x*CTL)

BITS	7	6	5	4	3	2	1	0
FIELD	PCTL							
RESET	00H							
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FD1H, FD5H, FD9H							

PCTL[7:0]—Port Control
The Port Control register provides access to all sub-registers that configure the GPIO Port operation.

Port A–C Data Direction Sub-Registers

The Port A–C Data Direction sub-register is accessed through the Port A–C Control register by writing 01H to the Port A–C Address register (Table 20).

Table 20. Port A–C Data Direction Sub-Registers (PxDD)

BITS	7	6	5	4	3	2	1	0
FIELD	DD7	DD6	DD5	DD4	DD3	DD2	DD1	DD0
RESET	1	1	1	1	1	1	1	1
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	If 01H in Port A–C Address Register, accessible through the Port A–C Control Register							

DD[7:0]—Data Direction
These bits control the direction of the associated port pin. Port Alternate Function operation overrides the Data Direction register setting.
0 = Output. Data in the Port A–C Output Data register is driven onto the port pin.
1 = Input. The port pin is sampled and the value written into the Port A–C Input Data Register. The output driver is tristated.

Port A–C Alternate Function Sub-Registers

The Port A–C Alternate Function sub-register (Table 21) is accessed through the Port A–C Control register by writing `02H` to the Port A–C Address register. The Port A–C Alternate Function sub-registers enable the alternate function selection on pins. If disabled, pins functions as GPIO. If enabled, select one of four alternate functions using alternate function set subregisters 1 and 2 as described in the Port A–C Alternate Function Set 1 Sub-Registers on page 48 and Port A–C Alternate Function Set 2 Sub-Registers on

Table 32. LED Drive Level Low Register (LEDLVLL)

BITS	7	6	5	4	3	2	1	0
FIELD	LEDLVLL[7:0]							
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F84H							

LEDLVLH[7:0]—LED Level High Bit
{LEDLVLH, LEDLVLL} select one of four programmable current drive levels for each Port C pin.
00 = 3 mA
01 = 7 mA
10 = 13 mA
11 = 20 mA

Table 33. Trap and Interrupt Vectors in Order of Priority

Priority	Program Memory Vector Address	Interrupt or Trap Source
Highest	0002H	Reset (not an interrupt)
	0004H	Watchdog Timer (see Watchdog Timer on page 87)
	003AH	Primary Oscillator Fail Trap (not an interrupt)
	003CH	Watchdog Timer Oscillator Fail Trap (not an interrupt)
	0006H	Illegal Instruction Trap (not an interrupt)
	0008H	Reserved
	000AH	Timer 1
	000CH	Timer 0
	000EH	UART 0 receiver
	0010H	UART 0 transmitter
	0012H	Reserved
	0014H	Reserved
	0016H	ADC
	0018H	Port A Pin 7, selectable rising or falling input edge
	001AH	Port A Pin 6, selectable rising or falling input edge or Comparator Output
	001CH	Port A Pin 5, selectable rising or falling input edge
	001EH	Port A Pin 4, selectable rising or falling input edge
	0020H	Port A Pin 3 or Port D Pin 3, selectable rising or falling input edge
	0022H	Port A Pin 2 or Port D Pin 2, selectable rising or falling input edge
	0024H	Port A Pin 1, selectable rising or falling input edge
	0026H	Port A Pin 0, selectable rising or falling input edge
	0028H	Reserved
	002AH	Reserved
	002CH	Reserved
	002EH	Reserved
	0030H	Port C Pin 3, both input edges
	0032H	Port C Pin 2, both input edges
	0034H	Port C Pin 1, both input edges

Reserved—Must be 0

T1ENH—Timer 1 Interrupt Request Enable High Bit
T0ENH—Timer 0 Interrupt Request Enable High Bit
U0RENH—UART 0 Receive Interrupt Request Enable High Bit
U0TENH—UART 0 Transmit Interrupt Request Enable High Bit
ADCENH—ADC Interrupt Request Enable High Bit

Table 39. IRQ0 Enable Low Bit Register (IRQ0ENL)

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved	T1ENL	T0ENL	U0RENL	U0TENL	Reserved	Reserved	ADCENL
RESET	0	0	0	0	0	0	0	0
R/W	R	R/W	R/W	R/W	R/W	R	R	R/W
ADDR	FC2H							

Reserved—0 when read

T1ENL—Timer 1 Interrupt Request Enable Low Bit
T0ENL—Timer 0 Interrupt Request Enable Low Bit
U0RENL—UART 0 Receive Interrupt Request Enable Low Bit
U0TENL—UART 0 Transmit Interrupt Request Enable Low Bit
ADCENL—ADC Interrupt Request Enable Low Bit

IRQ1 Enable High and Low Bit Registers

Table 40 describes the priority control for IRQ1. The IRQ1 Enable High and Low Bit registers (Table 41 and Table 42) form a priority encoded enabling for interrupts in the Interrupt Request 1 register. Priority is generated by setting bits in each register.

Table 40. IRQ1 Enable and Priority Encoding

IRQ1ENH[*x*]	IRQ1ENL[*x*]	Priority	Description
0	0	Disabled	Disabled
0	1	Level 1	Low
1	0	Level 2	Nominal
1	1	Level 3	High

where *x* indicates the register bits from 0–7.

Table 43. IRQ2 Enable and Priority Encoding (Continued)

IRQ2ENH[*x*]	IRQ2ENL[*x*]	Priority	Description
1	1	Level 3	High

where *x* indicates the register bits from 0–7.

Table 44. IRQ2 Enable High Bit Register (IRQ2ENH)

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved				C3ENH	C2ENH	C1ENH	C0ENH
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FC7H							

Reserved—Must be 0

C3ENH—Port C3 Interrupt Request Enable High Bit
C2ENH—Port C2 Interrupt Request Enable High Bit
C1ENH—Port C1 Interrupt Request Enable High Bit
C0ENH—Port C0 Interrupt Request Enable High Bit

Table 45. IRQ2 Enable Low Bit Register (IRQ2ENL)

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved				C3ENL	C2ENL	C1ENL	C0ENL
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FC8H							

Reserved—Must be 0

C3ENL—Port C3 Interrupt Request Enable Low Bit
C2ENL—Port C2 Interrupt Request Enable Low Bit
C1ENL—Port C1 Interrupt Request Enable Low Bit
C0ENL—Port C0 Interrupt Request Enable Low Bit

Interrupt Edge Select Register

The Interrupt Edge Select (IRQES) register (Table 46) determines whether an interrupt is generated for the rising edge or falling edge on the selected GPIO Port A or Port D input pin.

- Configure the timer for CAPTURE/COMPARE mode
- Set the prescale value
- Set the Capture edge (rising or falling) for the Timer Input

2. Write to the Timer High and Low Byte registers to set the starting count value (typically 0001H).
3. Write to the Timer Reload High and Low Byte registers to set the Compare value.
4. Enable the timer interrupt, if appropriate, and set the timer interrupt priority by writing to the relevant interrupt registers.By default, the timer interrupt are generated for both input Capture and Reload events. If appropriate, configure the timer interrupt to be generated only at the input Capture event or the Reload event by setting TICONFIG field of the TxCTL1 register.
5. Configure the associated GPIO port pin for the Timer Input alternate function.
6. Write to the Timer Control register to enable the timer.
7. Counting begins on the first appropriate transition of the Timer Input signal. No interrupt is generated by this first edge.

In CAPTURE/COMPARE mode, the elapsed time from timer start to Capture event can be calculated using the following equation:

$$\text{Capture Elapsed Time (s)} = \frac{(\text{Capture Value} - \text{Start Value}) \times \text{Prescale}}{\text{System Clock Frequency (Hz)}}$$

Reading the Timer Count Values

The current count value in the timers can be read while counting (enabled). This capability has no effect on timer operation. When the timer is enabled and the Timer High Byte register is read, the contents of the Timer Low Byte register are placed in a holding register. A subsequent read from the Timer Low Byte register returns the value in the holding register. This operation allows accurate reads of the full 16-bit timer count value while enabled. When the timers are not enabled, a read from the Timer Low Byte register returns the actual value in the counter.

Timer Pin Signal Operation

Timer Output is a GPIO port pin alternate function. The Timer Output is toggled every time the counter is reloaded.

The timer input can be used as a selectable counting source. It shares the same pin as the complementary timer output. When selected by the GPIO Alternate Function Registers, this pin functions as a timer input in all modes except for the DUAL PWM OUTPUT mode. For this mode, there is no timer input available.

CAPTURE/COMPARE Mode

0 = Counting is started on the first rising edge of the Timer Input signal. The current count is captured on subsequent rising edges of the Timer Input signal.
1 = Counting is started on the first falling edge of the Timer Input signal. The current count is captured on subsequent falling edges of the Timer Input signal.

PWM DUAL OUTPUT Mode

0 = Timer Output is forced Low (0) and Timer Output Complement is forced High (1) when the timer is disabled. When enabled, the Timer Output is forced High (1) upon PWM count match and forced Low (0) upon Reload. When enabled, the Timer Output Complement is forced Low (0) upon PWM count match and forced High (1) upon Reload. The PWMD field in TxCTL0 register is a programmable delay to control the number of cycles time delay before the Timer Output and the Timer Output Complement is forced to High (1).
1 = Timer Output is forced High (1) and Timer Output Complement is forced Low (0) when the timer is disabled. When enabled, the Timer Output is forced Low (0) upon PWM count match and forced High (1) upon Reload.When enabled, the Timer Output Complement is forced High (1) upon PWM count match and forced Low (0) upon Reload. The PWMD field in TxCTL0 register is a programmable delay to control the number of cycles time delay before the Timer Output and the Timer Output Complement is forced to Low (0).

CAPTURE RESTART Mode

0 = Count is captured on the rising edge of the Timer Input signal
1 = Count is captured on the falling edge of the Timer Input signal

COMPARATOR COUNTER Mode

When the timer is disabled, the Timer Output signal is set to the value of this bit. When the timer is enabled, the Timer Output signal is complemented upon timer Reload.

Caution: *When the Timer Output alternate function TxOUT on a GPIO port pin is enabled, TxOUT changes to whatever state the* TPOL *bit is in. The timer does not need to be enabled for that to happen. Also, the port data direction sub register is not needed to be set to output on TxOUT. Changing the* TPOL *bit with the timer enabled and running does not immediately change the TxOUT.*

PRES—Prescale value.
The timer input clock is divided by 2^{PRES}, where PRES can be set from 0 to 7. The prescaler is reset each time the Timer is disabled. This reset ensures proper clock division each time the Timer is restarted.

000 = Divide by 1
001 = Divide by 2

received and the UART Receive Data register has not been read. If the RDA bit is reset to 0, reading the UART Receive Data register clears this bit.
0 = No overrun error occurred
1 = An overrun error occurred

FE—Framing Error
This bit indicates that a framing error (no Stop bit following data reception) was detected. Reading the UART Receive Data register clears this bit.
0 = No framing error occurred
1 = A framing error occurred

BRKD—Break Detect
This bit indicates that a break occurred. If the data bits, parity/multiprocessor bit, and Stop bit(s) are all 0s this bit is set to 1. Reading the UART Receive Data register clears this bit.
0 = No break occurred
1 = A break occurred

TDRE—Transmitter Data Register Empty
This bit indicates that the UART Transmit Data register is empty and ready for additional data. Writing to the UART Transmit Data register resets this bit.
0 = Do not write to the UART Transmit Data register
1 = The UART Transmit Data register is ready to receive an additional byte to be transmitted

TXE—Transmitter Empty
This bit indicates that the transmit shift register is empty and character transmission is finished.
0 = Data is currently transmitting
1 = Transmission is complete

CTS—$\overline{\text{CTS}}$ signal
When this bit is read it returns the level of the $\overline{\text{CTS}}$ signal. This signal is active Low.

UART Status 1 Register

This register contains multiprocessor control and status bits.

Table 65. UART Status 1 Register (U0STAT1)

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved						NEWFRM	MPRX
RESET	0	0	0	0	0	0	0	0
R/W	R	R	R	R	R/W	R/W	R	R
ADDR	F44H							

Reserved—R/W bits must be 0 during writes; 0 when read.

NEWFRM—Status bit denoting the start of a new frame. Reading the UART Receive Data register resets this bit to 0.
0 = The current byte is not the first data byte of a new frame
1 = The current byte is the first data byte of a new frame

MPRX—Multiprocessor Receive
Returns the value of the most recent multiprocessor bit received. Reading from the UART Receive Data register resets this bit to 0.

UART Control 0 and Control 1 Registers

The UART Control 0 and Control 1 registers (Table 66 and Table 67) configure the properties of the UART's transmit and receive operations. The UART Control registers must not be written while the UART is enabled.

Table 66. UART Control 0 Register (U0CTL0)

BITS	7	6	5	4	3	2	1	0
FIELD	TEN	REN	CTSE	PEN	PSEL	SBRK	STOP	LBEN
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F42H							

TEN—Transmit Enable
This bit enables or disables the transmitter. The enable is also controlled by the $\overline{CTS}$ signal and the CTSE bit. If the $\overline{CTS}$ signal is low and the CTSE bit is 1, the transmitter is enabled.
0 = Transmitter disabled
1 = Transmitter enabled

REN—Receive Enable
This bit enables or disables the receiver.
0 = Receiver disabled
1 = Receiver enabled

CTSE—CTS Enable
0 = The $\overline{CTS}$ signal has no effect on the transmitter
1 = The UART recognizes the $\overline{CTS}$ signal as an enable control from the transmitter

PEN—Parity Enable
This bit enables or disables parity. Even or odd is determined by the PSEL bit.
0 = Parity is disabled
1 = The transmitter sends data with an additional parity bit and the receiver receives an additional parity bit

A reset and stop function can be achieved by writing 81H to this register. A reset and go function can be achieved by writing 41H to this register. If the device is in DEBUG mode, a run function can be implemented by writing 40H to this register.

Table 99. OCD Control Register (OCDCTL)

BITS	7	6	5	4	3	2	1	0
FIELD	DBGMODE	BRKEN	DBGACK	Reserved				RST
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R	R	R	R	R/W

DBGMODE—DEBUG Mode
The device enters DEBUG mode when this bit is 1. When in DEBUG mode, the eZ8 CPU stops fetching new instructions. Clearing this bit causes the eZ8 CPU to restart. This bit is automatically set when a BRK instruction is decoded and breakpoints are enabled. If the Flash Read Protect Option Bit is enabled, this bit can only be cleared by resetting the device. It cannot be written to 0.
0 = Z8 Encore! XP F0823 Series device is operating in NORMAL mode
1 = Z8 Encore! XP F0823 Series device is in DEBUG mode

BRKEN—Breakpoint Enable
This bit controls the behavior of the BRK instruction (opcode 00H). By default, breakpoints are disabled and the BRK instruction behaves similar to an NOP instruction. If this bit is 1, when a BRK instruction is decoded, the DBGMODE bit of the OCDCTL register is automatically set to 1.
0 = Breakpoints are disabled
1 = Breakpoints are enabled

DBGACK—Debug Acknowledge
This bit enables the debug acknowledge feature. If this bit is set to 1, the OCD sends a Debug Acknowledge character (FFH) to the host when a Breakpoint occurs.
0 = Debug Acknowledge is disabled
1 = Debug Acknowledge is enabled

Reserved—0 when read

RST—Reset
Setting this bit to 1 resets the Z8F04xA family device. The device goes through a normal Power-On Reset sequence with the exception that the OCD is not reset. This bit is automatically cleared to 0 at the end of reset.
0 = No effect
1 = Reset the Flash Read Protect Option Bit device

Internal Precision Oscillator

The internal precision oscillator (IPO) is designed for use without external components. You can either manually trim the oscillator for a non-standard frequency or use the automatic factory-trimmed version to achieve a 5.53 MHz frequency. The features of IPO include:

- On-chip RC oscillator that does not require external components
- Output frequency of either 5.53 MHz or 32.8 kHz (contains both a fast and a slow mode)
- Trimming possible through Flash option bits with user override
- Elimination of crystals or ceramic resonators in applications where high timing accuracy is not required

Operation

An 8-bit trimming register, incorporated into the design, compensates for absolute variation of oscillator frequency. Once trimmed the oscillator frequency is stable and does not require subsequent calibration. Trimming is performed during manufacturing and is not necessary for you to repeat unless a frequency other than 5.53 MHz (fast mode) or 32.8 kHz (slow mode) is required. This trimming is done at +30 °C and a supply voltage of 3.3 V, so accuracy of this operating point is optimal.

Power down this block for minimum system power. By default, the oscillator is configured through the Flash Option bits. However, the user code can override these trim values as described in Trim Bit Address Space on page 146.

Select one of the two frequencies for the oscillator: 5.53 MHz and 32.8 kHz, using the OSCSEL bits in the Oscillator Control on page 165.

- Rotate and Shift

Tables 107 through Table 114 contain the instructions belonging to each group and the number of operands required for each instruction. Some instructions appear in more than one table as these instruction can be considered as a subset of more than one category. Within these tables, the source operand is identified as ‘src’, the destination operand is ‘dst’ and a condition code is ‘cc’.

Table 107. Arithmetic Instructions

Mnemonic	Operands	Instruction
ADC	dst, src	Add with Carry
ADCX	dst, src	Add with Carry using Extended Addressing
ADD	dst, src	Add
ADDX	dst, src	Add using Extended Addressing
CP	dst, src	Compare
CPC	dst, src	Compare with Carry
CPCX	dst, src	Compare with Carry using Extended Addressing
CPX	dst, src	Compare using Extended Addressing
DA	dst	Decimal Adjust
DEC	dst	Decrement
DECW	dst	Decrement Word
INC	dst	Increment
INCW	dst	Increment Word
MULT	dst	Multiply
SBC	dst, src	Subtract with Carry
SBCX	dst, src	Subtract with Carry using Extended Addressing
SUB	dst, src	Subtract
SUBX	dst, src	Subtract using Extended Addressing

Table 112. Logical Instructions (Continued)

Mnemonic	Operands	Instruction
ORX	dst, src	Logical OR using Extended Addressing
XOR	dst, src	Logical Exclusive OR
XORX	dst, src	Logical Exclusive OR using Extended Addressing

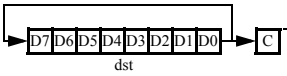
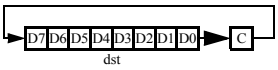
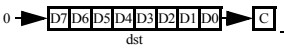
Table 113. Program Control Instructions

Mnemonic	Operands	Instruction
BRK	—	On-Chip Debugger Break
BTJ	p, bit, src, DA	Bit Test and Jump
BTJNZ	bit, src, DA	Bit Test and Jump if Non-Zero
BTJZ	bit, src, DA	Bit Test and Jump if Zero
CALL	dst	Call Procedure
DJNZ	dst, src, RA	Decrement and Jump Non-Zero
IRET	—	Interrupt Return
JP	dst	Jump
JP cc	dst	Jump Conditional
JR	DA	Jump Relative
JR cc	DA	Jump Relative Conditional
RET	—	Return
TRAP	vector	Software Trap

Table 114. Rotate and Shift Instructions

Mnemonic	Operands	Instruction
BSWAP	dst	Bit Swap
RL	dst	Rotate Left
RLC	dst	Rotate Left through Carry
RR	dst	Rotate Right
RRC	dst	Rotate Right through Carry

Table 115. eZ8 CPU Instruction Summary (Continued)

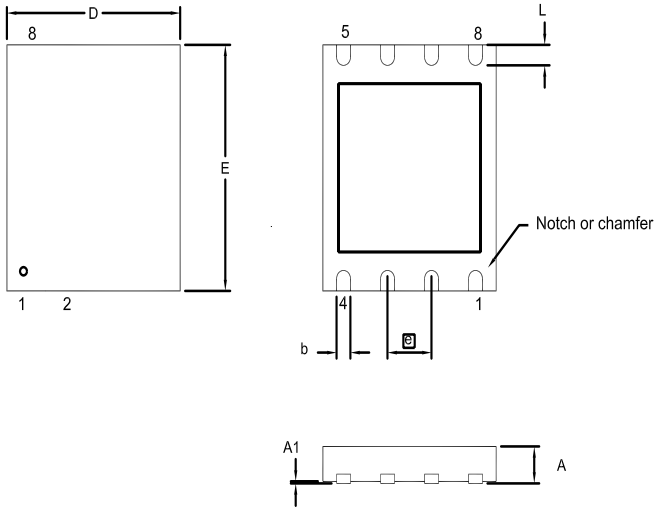
Assembly Mnemonic	Symbolic Operation	Address Mode dst	Address Mode src	Opcode(s) (Hex)	Flags C	Z	S	V	D	H	Fetch Cycles	Instr. Cycles
RR dst		R		E0	*	*	*	*	–	–	2	2
		IR		E1							2	3
RRC dst		R		C0	*	*	*	*	–	–	2	2
		IR		C1							2	3
SBC dst, src	dst ← dst – src - C	r	r	32	*	*	*	*	1	*	2	3
		r	Ir	33							2	4
		R	R	34							3	3
		R	IR	35							3	4
		R	IM	36							3	3
		IR	IM	37							3	4
SBCX dst, src	dst ← dst – src - C	ER	ER	38	*	*	*	*	1	*	4	3
		ER	IM	39							4	3
SCF	C ← 1			DF	1	–	–	–	–	–	1	2
SRA dst		R		D0	*	*	*	0	–	–	2	2
		IR		D1							2	3
SRL dst		R		1F C0	*	*	0	*	–	–	3	2
		IR		1F C1							3	3
SRP src	RP ← src		IM	01	–	–	–	–	–	–	2	2
STOP	STOP Mode			6F	–	–	–	–	–	–	1	2
SUB dst, src	dst ← dst – src	r	r	22	*	*	*	*	1	*	2	3
		r	Ir	23							2	4
		R	R	24							3	3
		R	IR	25							3	4
		R	IM	26							3	3
		IR	IM	27							3	4

Flags Notation:	* = Value is a function of the result of the operation. – = Unaffected X = Undefined	0 = Reset to 0 1 = Set to 1

Upper Nibble (Hex) \ Lower Nibble (Hex)	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0																
1																
2																
3																
4																
5																
6																
7	3, 2 **PUSH** IM															
8																
9																
A			3.3 **CPC** r1,r2	3.4 **CPC** r1,Ir2	4.3 **CPC** R2,R1	4.4 **CPC** IR2,R1	4.3 **CPC** R1,IM	4.4 **CPC** IR1,IM	5.3 **CPCX** ER2,ER1	5.3 **CPCX** IM,ER1						
B																
C	3.2 **SRL** R1	3.3 **SRL** IR1														
D																
E									5, 4 **LDWX** ER2,ER1							
F																

Figure 28. Second Opcode Map after 1FH

Figure 36 displays the 8-pin Quad Flat No-Lead package (QFN)/MLF-S available for the Z8 Encore! XP F0823 Series devices. This package has a footprint identical to that of the 8-pin SOIC, but with a lower profile.

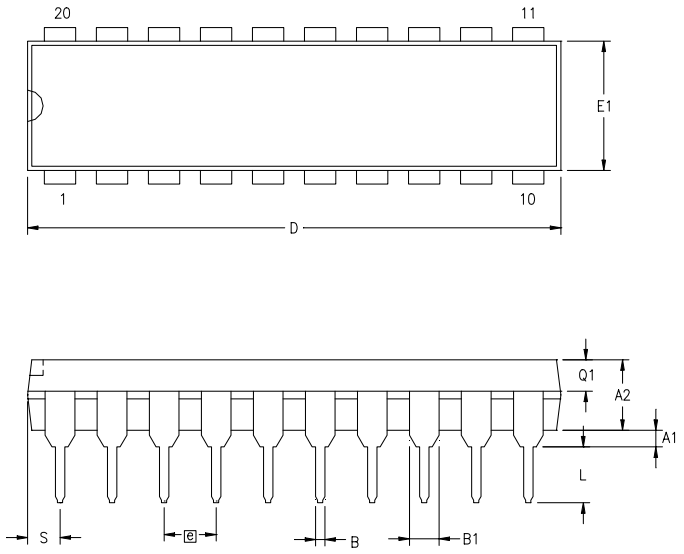


SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A	0.80	1.00	0.032	0.039
A1	0	0.05	0	0.002
b	0.35	0.45	0.014	0.018
D	4.95	5.05	0.195	0.199
E	5.95	6.05	0.234	0.238
e	1.27 BSC		0.050 BSC	
L	0.50	0.70	0.020	0.028

1. CONTROLLING DIMENSIONS : mm
2. MAX. COPLANARITY : 0.08 mm / 0.003"

Figure 36. 8-Pin Quad Flat No-Lead Package (QFN)/MLF-S

Figure 37 displays the 20-pin Plastic Dual Inline Package (PDIP) available for Z8 Encore! XP F0823 Series devices.



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A1	0.38	0.81	.015	.032
A2	3.25	3.68	.128	.145
B	0.41	0.51	.016	.020
B1	1.47	1.57	.058	.062
C	0.20	0.30	.008	.012
D	25.65	26.16	1.010	1.030
E	7.49	8.26	.295	.325
E1	6.10	6.65	.240	.262
e	2.54 BSC		.100 BSC	
eA	7.87	9.14	.310	.360
L	3.18	3.43	.125	.135
Q1	1.42	1.65	.056	.065
S	1.52	1.65	.060	.065

CONTROLLING DIMENSIONS : INCH

Figure 37. 20-Pin Plastic Dual Inline Package (PDIP)

Part Number	Flash	RAM	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Description
Z8 Encore! XP with 2 KB Flash, 10-Bit Analog-to-Digital Converter								
Standard Temperature: 0 °C to 70 °C								
Z8F0223PB005SC	2 KB	512 B	6	12	2	4	1	PDIP 8-pin package
Z8F0223QB005SC	2 KB	512 B	6	12	2	4	1	QFN 8-pin package
Z8F0223SB005SC	2 KB	512 B	6	12	2	4	1	SOIC 8-pin package
Z8F0223SH005SC	2 KB	512 B	16	18	2	7	1	SOIC 20-pin package
Z8F0223HH005SC	2 KB	512 B	16	18	2	7	1	SSOP 20-pin package
Z8F0223PH005SC	2 KB	512 B	16	18	2	7	1	PDIP 20-pin package
Z8F0223SJ005SC	2 KB	512 B	22	18	2	8	1	SOIC 28-pin package
Z8F0223HJ005SC	2 KB	512 B	22	18	2	8	1	SSOP 28-pin package
Z8F0223PJ005SC	2 KB	512 B	22	18	2	8	1	PDIP 28-pin package
Extended Temperature: -40 °C to 105 °C								
Z8F0223PB005EC	2 KB	512 B	6	12	2	4	1	PDIP 8-pin package
Z8F0223QB005EC	2 KB	512 B	6	12	2	4	1	QFN 8-pin package
Z8F0223SB005EC	2 KB	512 B	6	12	2	4	1	SOIC 8-pin package
Z8F0223SH005EC	2 KB	512 B	16	18	2	7	1	SOIC 20-pin package
Z8F0223HH005EC	2 KB	512 B	16	18	2	7	1	SSOP 20-pin package
Z8F0223PH005EC	2 KB	512 B	16	18	2	7	1	PDIP 20-pin package
Z8F0223SJ005EC	2 KB	512 B	22	18	2	8	1	SOIC 28-pin package
Z8F0223HJ005EC	2 KB	512 B	22	18	2	8	1	SSOP 28-pin package
Z8F0223PJ005EC	2 KB	512 B	22	18	2	8	1	PDIP 28-pin package
Replace C with G for Lead-Free Packaging								

D

E

F