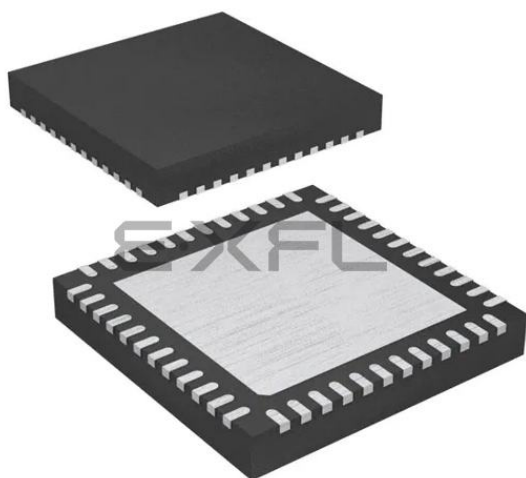




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Details

Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	40MHz
Connectivity	I ² C, SCI, SPI
Peripherals	LVD, POR, PWM, WDT
Number of I/O	38
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-VFQFN Exposed Pad
Supplier Device Package	48-QFN-EP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/s9s08aw16ae0cftr

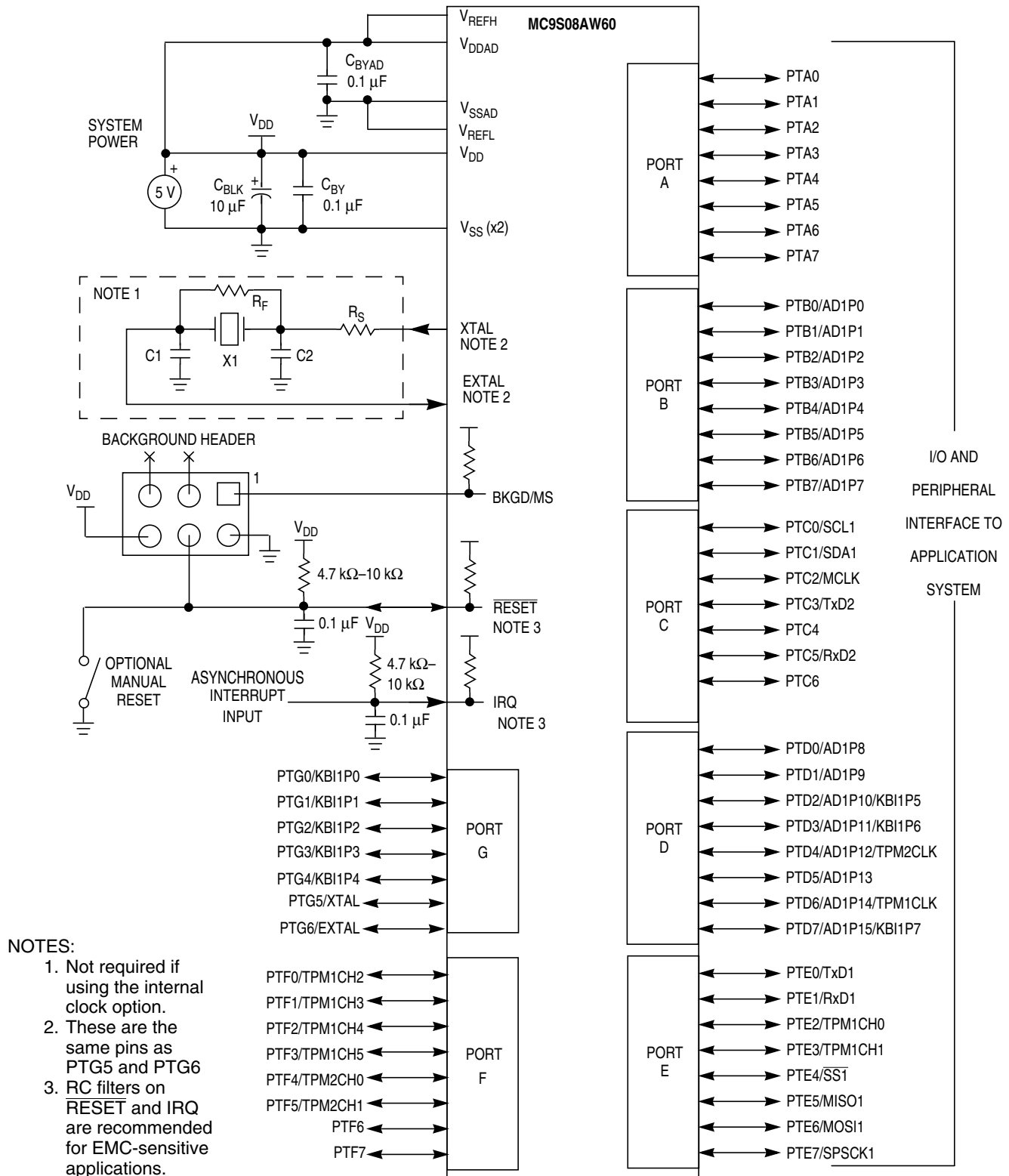


Figure 2-4. Basic System Connections



Table 4-3. High-Page Register Summary (Sheet 2 of 2)

Address	Register Name	Bit 7	6	5	4	3	2	1	Bit 0
\$1846	PTBDS	PTBDS7	PTBDS6	PTBDS5	PTBDS4	PTBDS3	PTBDS2	PTBDS1	PTBDS0
\$1847	Reserved	—	—	—	—	—	—	—	—
\$1848	PTCPE	0	PTCPE6	PTCPE5	PTCPE4	PTCPE3	PTCPE2	PTCPE1	PTCPE0
\$1849	PTCSE	0	PTCSE6	PTCSE5	PTCSE4	PTCSE3	PTCSE2	PTCSE1	PTCSE0
\$184A	PTCDS	0	PTCDS6	PTCDS5	PTCDS4	PTCDS3	PTCDS2	PTCDS1	PTCDS0
\$184B	Reserved	—	—	—	—	—	—	—	—
\$184C	PTDPE	PTDPE7	PTDPE6	PTDPE5	PTDPE4	PTDPE3	PTDPE2	PTDPE1	PTDPE0
\$184D	PTDSE	PTDSE7	PTDSE6	PTDSE5	PTDSE4	PTDSE3	PTDSE2	PTDSE1	PTDSE0
\$184E	PTDDS	PTDDS7	PTDDS6	PTDDS5	PTDDS4	PTDDS3	PTDDS2	PTDDS1	PTDDS0
\$184F	Reserved	—	—	—	—	—	—	—	—
\$1850	PTEPE	PTEPE7	PTEPE6	PTEPE5	PTEPE4	PTEPE3	PTEPE2	PTEPE1	PTEPE0
\$1851	PTESE	PTESE7	PTESE6	PTESE5	PTESE4	PTESE3	PTESE2	PTESE1	PTESE0
\$1852	PTEDS	PTEDS7	PTEDS6	PTEDS5	PTEDS4	PTEDS3	PTEDS2	PTEDS1	PTEDS0
\$1853	Reserved	—	—	—	—	—	—	—	—
\$1854	PTFPE	PTFPE7	PTFPE6	PTFPE5	PTFPE4	PTFPE3	PTFPE2	PTFPE1	PTFPE0
\$1855	PTFSE	PTFSE7	PTFSE6	PTFSE5	PTFSE4	PTFSE3	PTFSE2	PTFSE1	PTFSE0
\$1856	PTFDS	PTFDS7	PTFDS6	PTFDS5	PTFDS4	PTFDS3	PTFDS2	PTFDS1	PTFDS0
\$1857	Reserved	—	—	—	—	—	—	—	—
\$1858	PTGPE	0	PTGPE6	PTGPE5	PTGPE4	PTGPE3	PTGPE2	PTGPE1	PTGPE0
\$1859	PTGSE	0	PTGSE6	PTGSE5	PTGSE4	PTGSE3	PTGSE2	PTGSE1	PTGSE0
\$185A	PTGDS	0	PTGDS6	PTGDS5	PTGDS4	PTGDS3	PTGDS2	PTGDS1	PTGDS0
\$185B– \$185F	Reserved	—	—	—	—	—	—	—	—

¹ This reserved bit must always be written to 0.

Nonvolatile FLASH registers, shown in Table 4-4, are located in the FLASH memory. These registers include an 8-byte backdoor key which optionally can be used to gain access to secure memory resources. During reset events, the contents of NVPROT and NVOPT in the nonvolatile register area of the FLASH memory are transferred into corresponding FPROT and FOPT working registers in the high-page registers to control security and block protection options.

be programmed to logic 0 to enable block protection. Therefore the value \$DE must be programmed into NVPROT to protect addresses \$E000 through \$FFFF.

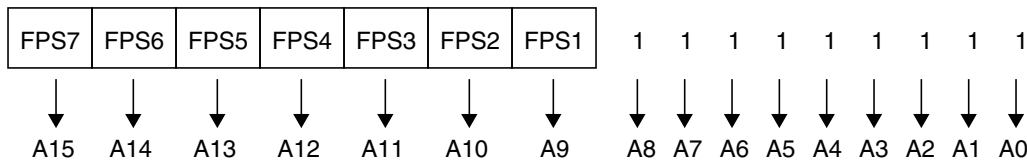


Figure 4-5. Block Protection Mechanism

One use for block protection is to block protect an area of FLASH memory for a bootloader program. This bootloader program then can be used to erase the rest of the FLASH memory and reprogram it. Because the bootloader is protected, it remains intact even if MCU power is lost in the middle of an erase and reprogram operation.

4.4.7 Vector Redirection

Whenever any block protection is enabled, the reset and interrupt vectors will be protected. Vector redirection allows users to modify interrupt vector information without unprotecting bootloader and reset vector space. Vector redirection is enabled by programming the FNORED bit in the NVOPT register located at address \$FFBF to zero. For redirection to occur, at least some portion but not all of the FLASH memory must be block protected by programming the NVPROT register located at address \$FFBD. All of the interrupt vectors (memory locations \$FFC0–\$FFFD) are redirected, though the reset vector (\$FFE:FFFF) is not.

For example, if 512 bytes of FLASH are protected, the protected address region is from \$FE00 through \$FFFF. The interrupt vectors (\$FFC0–\$FFFD) are redirected to the locations \$FDC0–\$FDFD. Now, if an SPI interrupt is taken for instance, the values in the locations \$FDE0:FDE1 are used for the vector instead of the values in the locations \$FFE0:FFE1. This allows the user to reprogram the unprotected portion of the FLASH with new program code including new interrupt vector values while leaving the protected area, which includes the default vector locations, unchanged.

4.5 Security

The MC9S08AW60 Series includes circuitry to prevent unauthorized access to the contents of FLASH and RAM memory. When security is engaged, FLASH and RAM are considered secure resources. Direct-page registers, high-page registers, and the background debug controller are considered unsecured resources. Programs executing within secure memory have normal access to any MCU memory locations and resources. Attempts to access a secure memory location with a program executing from an unsecured memory space or through the background debug interface are blocked (writes are ignored and reads return all 0s).

Security is engaged or disengaged based on the state of two nonvolatile register bits (SEC01:SEC00) in the FOPT register. During reset, the contents of the nonvolatile location NVOPT are copied from FLASH into the working FOPT register in high-page register space. A user engages security by programming the NVOPT location which can be done at the same time the FLASH memory is programmed. The 1:0 state disengages security and the other three combinations engage security. Notice the erased state (1:1) makes



Either RTI clock source can be used when the MCU is in run, wait or stop3 mode. When using the external oscillator in stop3, it must be enabled in stop (OSCSTEN = 1) and configured for low bandwidth operation (RANGE = 0). Only the internal 1-kHz clock source can be selected to wake the MCU from stop2 mode.

The SRTISC register includes a read-only status flag, a write-only acknowledge bit, and a 3-bit control value (RTIS2:RTIS1:RTIS0) used to disable the clock source to the real-time interrupt or select one of seven wakeup periods. The RTI has a local interrupt enable, RTIE, to allow masking of the real-time interrupt. The RTI can be disabled by writing each bit of RTIS to zeroes, and no interrupts will be generated. See Section 5.9.7, “System Real-Time Interrupt Status and Control Register (SRTISC),” for detailed information about this register.

5.8 MCLK Output

The PTC2 pin is shared with the MCLK clock output. Setting the pin enable bit, MPE, causes the PTC2 pin to output a divided version of the internal MCU bus clock. The divide ratio is determined by the MCSEL bits. When MPE is set, the PTC2 pin is forced to operate as an output pin regardless of the state of the port data direction control bit for the pin. If the MCSEL bits are all 0s, the pin is driven low. The slew rate and drive strength for the pin are controlled by PTCSE2 and PTCDS2, respectively. The maximum clock output frequency is limited if slew rate control is enabled, see Appendix A, “Electrical Characteristics and Timing Specifications,” for pin rise and fall times with slew rate enabled.

5.9 Reset, Interrupt, and System Control Registers and Control Bits

One 8-bit register in the direct page register space and eight 8-bit registers in the high-page register space are related to reset and interrupt systems.

Refer to the direct-page register summary in Chapter 4, “Memory,” of this data sheet for the absolute address assignments for all registers. This section refers to registers and control bits only by their names. A Freescale-provided equate or header file is used to translate these names into the appropriate absolute addresses.

Some control bits in the SOPT and SPMSC2 registers are related to modes of operation. Although brief descriptions of these bits are provided here, the related functions are discussed in greater detail in Chapter 3, “Modes of Operation.”

Chapter 6

Parallel Input/Output

6.1 Introduction

This chapter explains software controls related to parallel input/output (I/O). The MC9S08AW60 has seven I/O ports which include a total of 54 general-purpose I/O pins. See Chapter 2, “Pins and Connections” for more information about the logic and hardware aspects of these pins.

Many of these pins are shared with on-chip peripherals such as timer systems, communication systems, or keyboard interrupts. When these other modules are not controlling the port pins, they revert to general-purpose I/O control.

Pins that are not used in the application must be terminated. This prevents excess current caused by floating inputs and enhances immunity during noise or transient events. Termination methods include:

- Configuring unused pins as outputs driving high or low
- Configuring unused pins as inputs and using internal or external pullups

Never connect unused pins to V_{DD} or V_{SS} .

Table 6-1. KBI and Parallel I/O Interaction

PTxPE _n (Pull Enable)	PTxDD _n (Data Direction)	KBIPE _n (KBI Pin Enable)	KBEDG _n (KBI Edge Select)	Pullup	Pulldown
0	0	0	x ¹	disabled	disabled
1	0	0	x	enabled	disabled
x	1	0	x	disabled	disabled
1	x	1	0	enabled	disabled
1	x	1	1	disabled	enabled
0	x	1	x	disabled	disabled

¹ x = Don't care

6.2 Features

Parallel I/O and Pin Control features, depending on package choice, include:

- A total of 54 general-purpose I/O pins in seven ports
- Hysteresis input buffers
- Software-controlled pullups on each input pin

6.7.14 Port G Pin Control Registers (PTGPE, PTGSE, PTGDS)

In addition to the I/O control, port G pins are controlled by the registers listed below.

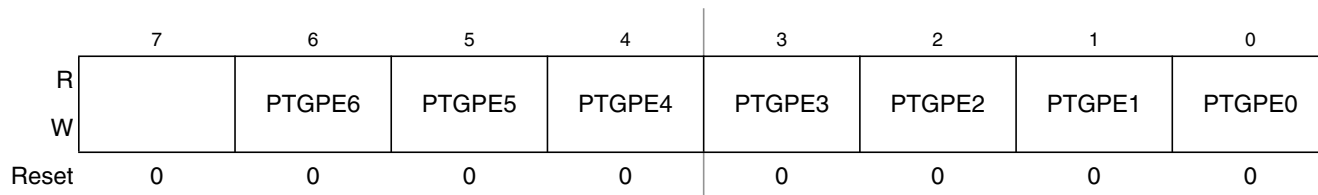


Figure 6-41. Internal Pullup Enable for Port G Bits (PTGPE)

Table 6-34. PTGPE Register Field Descriptions

Field	Description
6:0 PTGPE[6:0]	Internal Pullup Enable for Port G Bits — Each of these control bits determines if the internal pullup device is enabled for the associated PTG pin. For port G pins that are configured as outputs, these bits have no effect and the internal pullup devices are disabled. 0 Internal pullup device disabled for port G bit n. 1 Internal pullup device enabled for port G bit n.

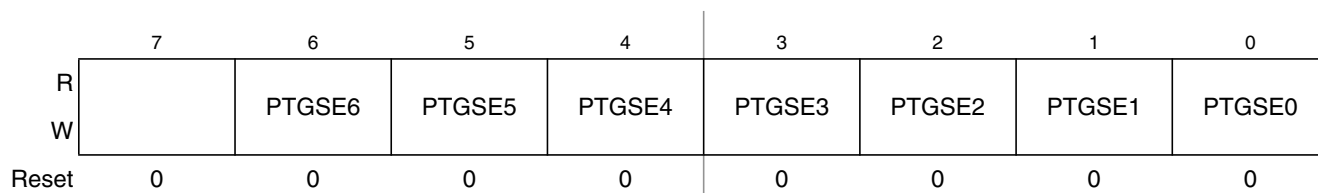


Figure 6-42. Output Slew Rate Control Enable for Port G Bits (PTGSE)

Table 6-35. PTGSE Register Field Descriptions

Field	Description
6:0 PTGSE[6:0]	Output Slew Rate Control Enable for Port G Bits — Each of these control bits determine whether output slew rate control is enabled for the associated PTG pin. For port G pins that are configured as inputs, these bits have no effect. 0 Output slew rate control disabled for port G bit n. 1 Output slew rate control enabled for port G bit n.

8.4.4 FLL Engaged Internal Unlocked

FEI unlocked is a temporary state that is entered when FEI is entered and the count error (Δn) output from the subtractor is greater than the maximum n_{unlock} or less than the minimum n_{unlock} , as required by the lock detector to detect the unlock condition.

The ICG will remain in this state while the count error (Δn) is greater than the maximum n_{lock} or less than the minimum n_{lock} , as required by the lock detector to detect the lock condition.

In this state the output clock signal ICGOUT frequency is given by f_{ICGDCLK} / R .

8.4.5 FLL Engaged Internal Locked

FLL engaged internal locked is entered from FEI unlocked when the count error (Δn), which comes from the subtractor, is less than n_{lock} (max) and greater than n_{lock} (min) for a given number of samples, as required by the lock detector to detect the lock condition. The output clock signal ICGOUT frequency is given by f_{ICGDCLK} / R . In FEI locked, the filter value is updated only once every four comparison cycles. The update made is an average of the error measurements taken in the four previous comparisons.

8.4.6 FLL Bypassed, External Clock (FBE) Mode

FLL bypassed external (FBE) is entered when any of the following conditions occur:

- From SCM when $\text{CLKS} = 10$ and ERCS is high
- When $\text{CLKS} = 10$, $\text{ERCS} = 1$ upon entering off mode, and off is then exited
- From FLL engaged external mode if a loss of DCO clock occurs and the external reference remains valid (both $\text{LOCS} = 1$ and $\text{ERCS} = 1$)

In this state, the DCO and IRG are off and the reference clock is derived from the external reference clock, ICGERCLK . The output clock signal ICGOUT frequency is given by f_{ICGERCLK} / R . If an external clock source is used ($\text{REFS} = 0$), then the input frequency on the EXTAL pin can be anywhere in the range 0 MHz to 40 MHz. If a crystal or resonator is used ($\text{REFS} = 1$), then frequency range is either low for $\text{RANGE} = 0$ or high for $\text{RANGE} = 1$.

8.4.7 FLL Engaged, External Clock (FEE) Mode

The FLL engaged external (FEE) mode is entered when any of the following conditions occur:

- $\text{CLKS} = 11$ and ERCS and DCOS are both high.
- The DCO stabilizes ($\text{DCOS} = 1$) while in SCM upon exiting the off state with $\text{CLKS} = 11$.

In FEE mode, the reference clock is derived from the external reference clock ICGERCLK , and the FLL loop will attempt to lock the ICGDCLK frequency to the desired value, as selected by the MFD bits. To run in FEE mode, there must be a working 32 kHz–100 kHz or 2 MHz–10 MHz external clock source. The maximum external clock frequency is limited to 10 MHz in FEE mode to prevent over-clocking the DCO. The minimum multiplier for the FLL, from Table 8-12 is 4. Because $4 \times 10 \text{ MHz}$ is 40MHz, which is the operational limit of the DCO, the reference clock cannot be any faster than 10 MHz.

8.4.10 Clock Mode Requirements

A clock mode is requested by writing to CLKS1:CLKS0 and the actual clock mode is indicated by CLKST1:CLKST0. Provided minimum conditions are met, the status shown in CLKST1:CLKST0 should be the same as the requested mode in CLKS1:CLKS0. Table 8-9 shows the relationship between CLKS, CLKST, and ICGOUT. It also shows the conditions for CLKS = CLKST or the reason CLKS ≠ CLKST.

NOTE

If a crystal will be used before the next reset, then be sure to set REFS = 1 and CLKS = 1x on the first write to the ICGC1 register. Failure to do so will result in “locking” REFS = 0 which will prevent the oscillator amplifier from being enabled until the next reset occurs.

Table 8-9. ICG State Table

Actual Mode (CLKST)	Desired Mode (CLKS)	Range	Reference Frequency ($f_{\text{REFERENCE}}$)	Comparison Cycle Time	ICGOUT	Conditions ¹ for CLKS = CLKST	Reason CLKS1 ≠ CLKST
Off (XX)	Off (XX)	X	0	—	0	—	—
	FBE (10)	X	0	—	0	—	ERCS = 0
SCM (00)	SCM (00)	X	$f_{\text{ICGIRCLK}}/7^2$	$8/f_{\text{ICGIRCLK}}$	ICGDCLK/R	Not switching from FBE to SCM	—
	FEI (01)	0	$f_{\text{ICGIRCLK}}/7^{(1)}$	$8/f_{\text{ICGIRCLK}}$	ICGDCLK/R	—	DCOS = 0
	FBE (10)	X	$f_{\text{ICGIRCLK}}/7^{(1)}$	$8/f_{\text{ICGIRCLK}}$	ICGDCLK/R	—	ERCS = 0
	FEE (11)	X	$f_{\text{ICGIRCLK}}/7^{(1)}$	$8/f_{\text{ICGIRCLK}}$	ICGDCLK/R	—	DCOS = 0 or ERCS = 0
FEI (01)	FEI (01)	0	$f_{\text{ICGIRCLK}}/7$	$8/f_{\text{ICGIRCLK}}$	ICGDCLK/R	DCOS = 1	—
	FEE (11)	X	$f_{\text{ICGIRCLK}}/7$	$8/f_{\text{ICGIRCLK}}$	ICGDCLK/R	—	ERCS = 0
FBE (10)	FBE (10)	X	0	—	ICGERCLK/R	ERCS = 1	—
	FEE (11)	X	0	—	ICGERCLK/R	—	LOCS = 1 & ERCS = 1
FEE (11)	FEE (11)	0	f_{ICGERCLK}	$2/f_{\text{ICGERCLK}}$	ICGDCLK/R ³	ERCS = 1 and DCOS = 1	—
		1	f_{ICGERCLK}	$128/f_{\text{ICGERCLK}}$	ICGDCLK/R ⁽²⁾	ERCS = 1 and DCOS = 1	—

¹ CLKST will not update immediately after a write to CLKS. Several bus cycles are required before CLKST updates to the new value.

² The reference frequency has no effect on ICGOUT in SCM, but the reference frequency is still used in making the comparisons that determine the DCOS bit

³ After initial LOCK; will be ICGDCLK/2R during initial locking process and while FLL is re-locking after the MFD bits are changed.

Chapter 12

Serial Peripheral Interface (S08SPIV3)

The MC9S08AW60 Series has one serial peripheral interface (SPI) module. The four pins associated with SPI functionality are shared with port E pins 4–7. See Appendix A, “Electrical Characteristics and Timing Specifications,” for SPI electrical parametric information.

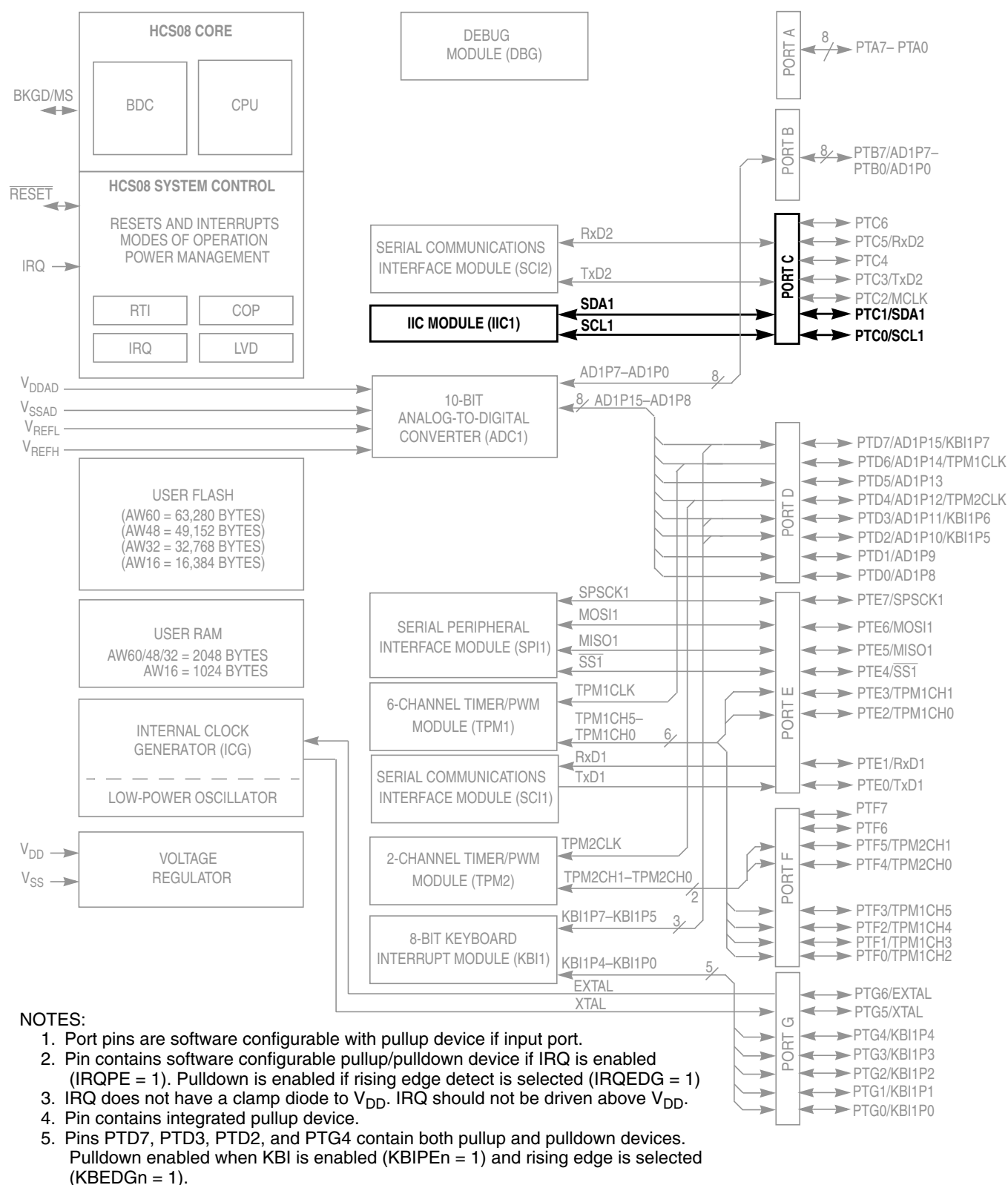


Figure 13-1. Block Diagram Highlighting the IIC Module

14.2.4 Features

Features of the ADC module include:

- Linear successive approximation algorithm with 10 bits resolution.
- Up to 28 analog inputs.
- Output formatted in 10- or 8-bit right-justified format.
- Single or continuous conversion (automatic return to idle after single conversion).
- Configurable sample time and conversion speed/power.
- Conversion complete flag and interrupt.
- Input clock selectable from up to four sources.
- Operation in wait or stop3 modes for lower noise operation.
- Asynchronous clock source for lower noise operation.
- Selectable asynchronous hardware conversion trigger.
- Automatic compare with interrupt for less-than, or greater-than or equal-to, programmable value.

14.2.5 Block Diagram

Figure 14-2 provides a block diagram of the ADC module

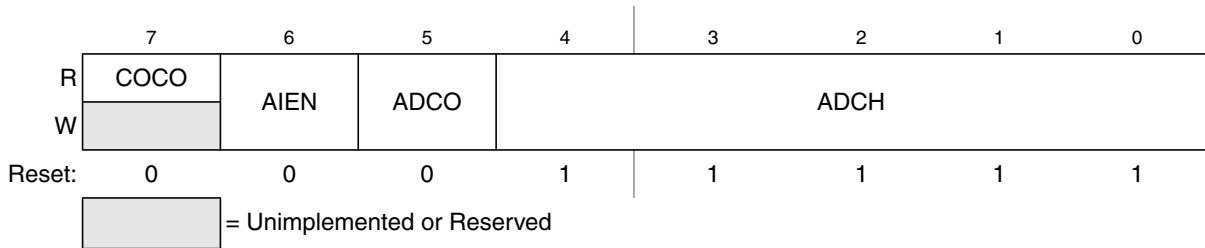


Figure 14-3. Status and Control Register (ADC1SC1)

Table 14-3. ADC1SC1 Register Field Descriptions

Field	Description
7 COCO	Conversion Complete Flag — The COCO flag is a read-only bit which is set each time a conversion is completed when the compare function is disabled (ACFE = 0). When the compare function is enabled (ACFE = 1) the COCO flag is set upon completion of a conversion only if the compare result is true. This bit is cleared whenever ADC1SC1 is written or whenever ADC1RL is read. 0 Conversion not completed 1 Conversion completed
6 AIEN	Interrupt Enable — AIEN is used to enable conversion complete interrupts. When COCO becomes set while AIEN is high, an interrupt is asserted. 0 Conversion complete interrupt disabled 1 Conversion complete interrupt enabled
5 ADCO	Continuous Conversion Enable — ADCO is used to enable continuous conversions. 0 One conversion following a write to the ADC1SC1 when software triggered operation is selected, or one conversion following assertion of ADHWT when hardware triggered operation is selected. 1 Continuous conversions initiated following a write to ADC1SC1 when software triggered operation is selected. Continuous conversions are initiated by an ADHWT event when hardware triggered operation is selected.
4:0 ADCH	Input Channel Select — The ADCH bits form a 5-bit field which is used to select one of the input channels. The input channels are detailed in Figure 14-4. The successive approximation converter subsystem is turned off when the channel select bits are all set to 1. This feature allows for explicit disabling of the ADC and isolation of the input channel from all sources. Terminating continuous conversions this way will prevent an additional, single conversion from being performed. It is not necessary to set the channel select bits to all 1s to place the ADC in a low-power state when continuous conversions are not enabled because the module automatically enters a low-power state when a conversion completes.

Figure 14-4. Input Channel Select

ADCH	Input Select	ADCH	Input Select
00000	AD0	10000	AD16
00001	AD1	10001	AD17
00010	AD2	10010	AD18
00011	AD3	10011	AD19
00100	AD4	10100	AD20
00101	AD5	10101	AD21
00110	AD6	10110	AD22
00111	AD7	10111	AD23

Table 14-4. ADC1SC2 Register Field Descriptions (continued)

Field	Description
5 ACFE	Compare Function Enable — ACFE is used to enable the compare function. 0 Compare function disabled 1 Compare function enabled
4 ACFGT	Compare Function Greater Than Enable — ACFGT is used to configure the compare function to trigger when the result of the conversion of the input being monitored is greater than or equal to the compare value. The compare function defaults to triggering when the result of the compare of the input being monitored is less than the compare value. 0 Compare triggers when input is less than compare level 1 Compare triggers when input is greater than or equal to compare level

14.4.3 Data Result High Register (ADC1RH)

ADC1RH contains the upper two bits of the result of a 10-bit conversion. When configured for 8-bit conversions both ADR8 and ADR9 are equal to zero. ADC1RH is updated each time a conversion completes except when automatic compare is enabled and the compare condition is not met. In 10-bit MODE, reading ADC1RH prevents the ADC from transferring subsequent conversion results into the result registers until ADC1RL is read. If ADC1RL is not read until after the next conversion is completed, then the intermediate conversion result will be lost. In 8-bit mode there is no interlocking with ADC1RL. In the case that the MODE bits are changed, any data in ADC1RH becomes invalid.

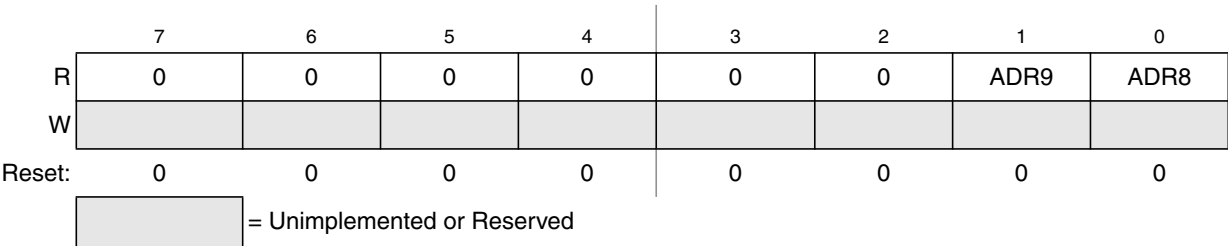


Figure 14-6. Data Result High Register (ADC1RH)

14.4.4 Data Result Low Register (ADC1RL)

ADC1RL contains the lower eight bits of the result of a 10-bit conversion, and all eight bits of an 8-bit conversion. This register is updated each time a conversion completes except when automatic compare is enabled and the compare condition is not met. In 10-bit mode, reading ADC1RH prevents the ADC from transferring subsequent conversion results into the result registers until ADC1RL is read. If ADC1RL is not read until the after next conversion is completed, then the intermediate conversion results will be lost. In 8-bit mode, there is no interlocking with ADC1RH. In the case that the MODE bits are changed, any data in ADC1RL becomes invalid.

15.4.1.1 BDC Status and Control Register (BDCSCR)

This register can be read or written by serial BDC commands (READ_STATUS and WRITE_CONTROL) but is not accessible to user programs because it is not located in the normal memory map of the MCU.

	7	6	5	4	3	2	1	0
R	ENBDM	BDMACT	BKPTEN	FTS	CLKSW	WS	WSF	DVF
W								
Normal Reset	0	0	0	0	0	0	0	0
Reset in Active BDM:	1	1	0	0	1	0	0	0

 = Unimplemented or Reserved

Figure 15-5. BDC Status and Control Register (BDCSCR)

Table 15-2. BDCSCR Register Field Descriptions

Field	Description
7 ENBDM	Enable BDM (Permit Active Background Mode) — Typically, this bit is written to 1 by the debug host shortly after the beginning of a debug session or whenever the debug host resets the target and remains 1 until a normal reset clears it. 0 BDM cannot be made active (non-intrusive commands still allowed) 1 BDM can be made active to allow active background mode commands
6 BDMACT	Background Mode Active Status — This is a read-only status bit. 0 BDM not active (user application program running) 1 BDM active and waiting for serial commands
5 BKPTEN	BDC Breakpoint Enable — If this bit is clear, the BDC breakpoint is disabled and the FTS (force tag select) control bit and BDCBKPT match register are ignored. 0 BDC breakpoint disabled 1 BDC breakpoint enabled
4 FTS	Force/Tag Select — When FTS = 1, a breakpoint is requested whenever the CPU address bus matches the BDCBKPT match register. When FTS = 0, a match between the CPU address bus and the BDCBKPT register causes the fetched opcode to be tagged. If this tagged opcode ever reaches the end of the instruction queue, the CPU enters active background mode rather than executing the tagged opcode. 0 Tag opcode at breakpoint address and enter active background mode if CPU attempts to execute that instruction 1 Breakpoint match forces active background mode at next instruction boundary (address need not be an opcode)
3 CLKSW	Select Source for BDC Communications Clock — CLKSW defaults to 0, which selects the alternate BDC clock source. 0 Alternate BDC clock source 1 MCU bus clock

15.4.3.9 Debug Status Register (DBGS)

This is a read-only status register.

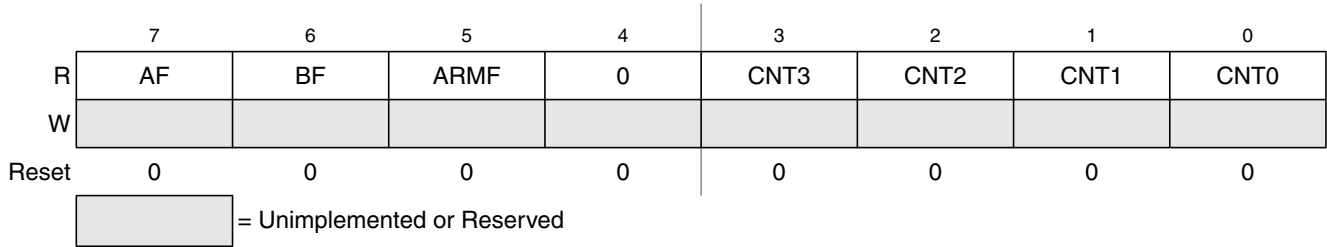
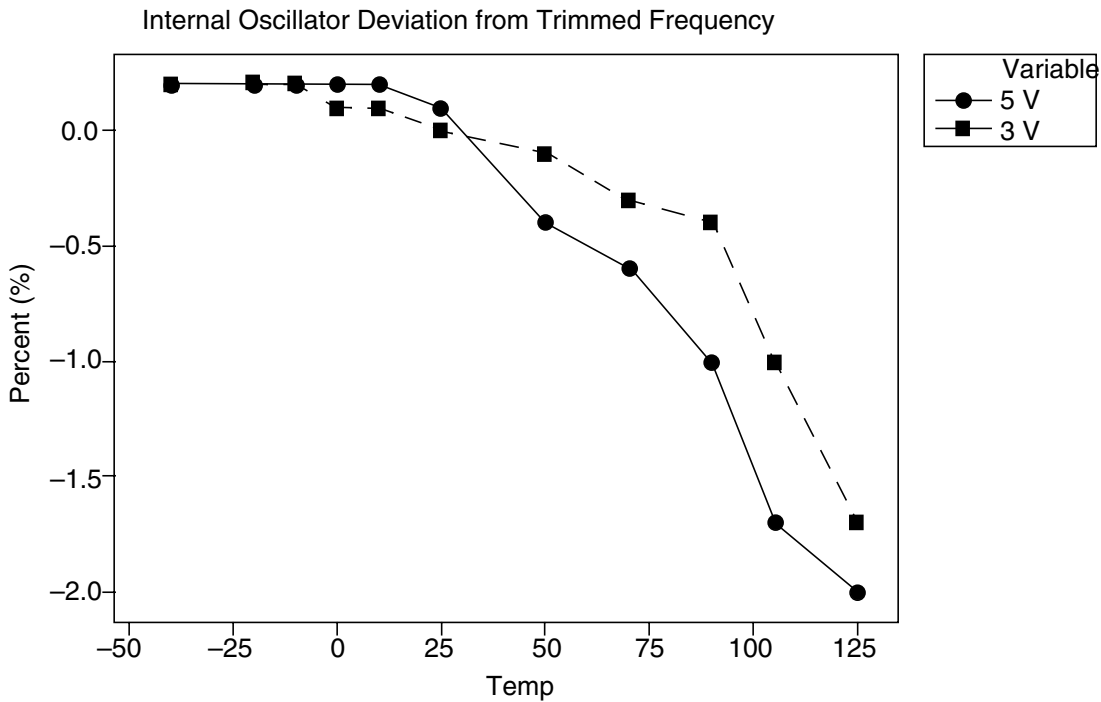


Figure 15-9. Debug Status Register (DBGS)

Table 15-6. DBGS Register Field Descriptions

Field	Description
7 AF	Trigger Match A Flag — AF is cleared at the start of a debug run and indicates whether a trigger match A condition was met since arming. 0 Comparator A has not matched 1 Comparator A match
6 BF	Trigger Match B Flag — BF is cleared at the start of a debug run and indicates whether a trigger match B condition was met since arming. 0 Comparator B has not matched 1 Comparator B match
5 ARMF	Arm Flag — While DBGEN = 1, this status bit is a read-only image of ARM in DBGIC. This bit is set by writing 1 to the ARM control bit in DBGIC (while DBGEN = 1) and is automatically cleared at the end of a debug run. A debug run is completed when the FIFO is full (begin trace) or when a trigger event is detected (end trace). A debug run can also be ended manually by writing 0 to ARM or DBGEN in DBGIC. 0 Debugger not armed 1 Debugger armed
3:0 CNT[3:0]	FIFO Valid Count — These bits are cleared at the start of a debug run and indicate the number of words of valid data in the FIFO at the end of a debug run. The value in CNT does not decrement as data is read out of the FIFO. The external debug host is responsible for keeping track of the count as information is read out of the FIFO. 0000 Number of valid words in FIFO = No valid data 0001 Number of valid words in FIFO = 1 0010 Number of valid words in FIFO = 2 0011 Number of valid words in FIFO = 3 0100 Number of valid words in FIFO = 4 0101 Number of valid words in FIFO = 5 0110 Number of valid words in FIFO = 6 0111 Number of valid words in FIFO = 7 1000 Number of valid words in FIFO = 8

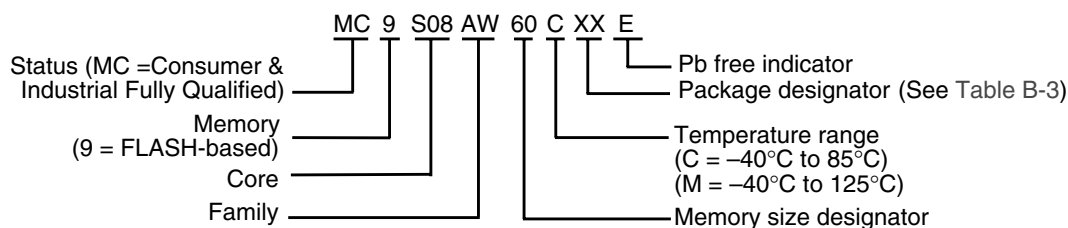


Device trimmed at 25°C at 3.0 V.

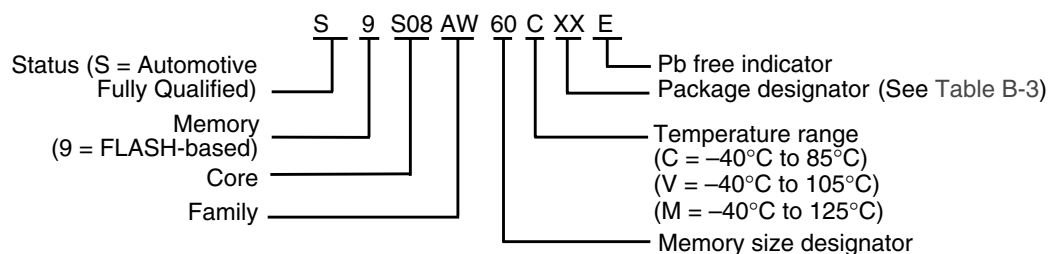
Figure A-9. Internal Oscillator Deviation from Trimmed Frequency

B.2 Orderable Part Numbering System

B.2.1 Consumer and Industrial Orderable Part Numbering System



B.2.2 Automotive Orderable Part Numbering System

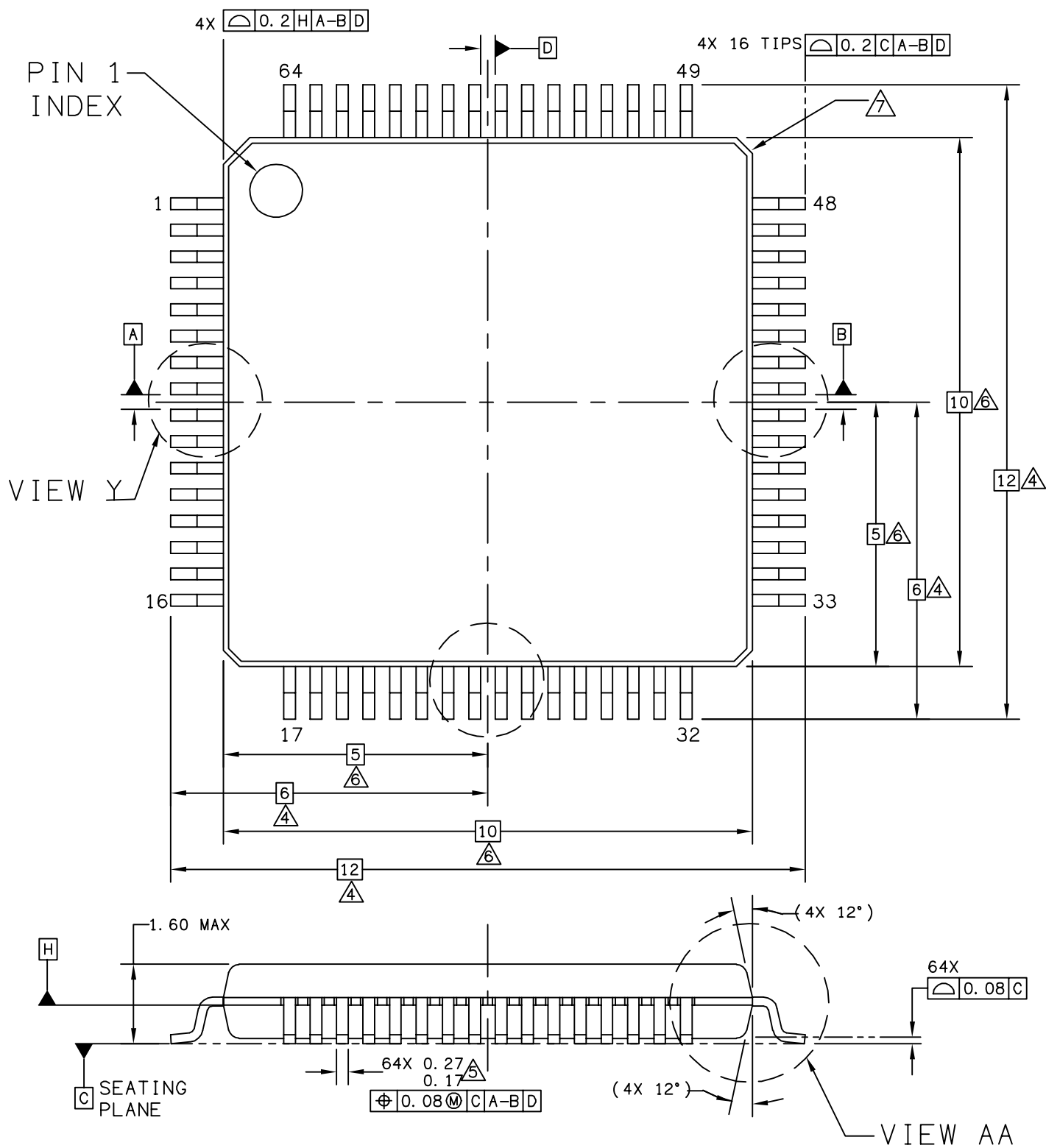


B.3 Mechanical Drawings

This following pages contain mechanical specifications for MC9S08AW60 Series package options. See Table B-3 for the document numbers that correspond to each package type.

Table B-3. Package Information

Pin Count	Type	Designator	Document No.
44	LQFP	FG	98ASS23225W
48	QFN	FD	98ARH99048A
64	LQFP	PU	98ASS23234W
64	QFP	FU	98ASB42844B



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TITLE: 64LD LQFP, 10 X 10 X 1.4 PKG, 0.5 PITCH, CASE OUTLINE			DOCUMENT NO: 98ASS23234W		REV: E
			CASE NUMBER: 840F-02		11 AUG 2006
			STANDARD: JEDEC MS-026 BCD		