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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I ² C, IrDA, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	37
Program Memory Size	192КВ (192К х 8)
Program Memory Type	FLASH
EEPROM Size	6K x 8
RAM Size	20К х 8
Voltage - Supply (Vcc/Vdd)	1.65V ~ 3.6V
Data Converters	A/D 10x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32l072czt6

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2 Description

The ultra-low-power STM32L072xx microcontrollers incorporate the connectivity power of the universal serial bus (USB 2.0 crystal-less) with the high-performance ARM[®] Cortex[®]-M0+ 32-bit RISC core operating at a 32 MHz frequency, a memory protection unit (MPU), high-speed embedded memories (up to 192 Kbytes of Flash program memory, 6 Kbytes of data EEPROM and 20 Kbytes of RAM) plus an extensive range of enhanced I/Os and peripherals.

The STM32L072xx devices provide high power efficiency for a wide range of performance. It is achieved with a large choice of internal and external clock sources, an internal voltage adaptation and several low-power modes.

The STM32L072xx devices offer several analog features, one 12-bit ADC with hardware oversampling, two DACs, two ultra-low-power comparators, several timers, one low-power timer (LPTIM), four general-purpose 16-bit timers and two basic timer, one RTC and one SysTick which can be used as timebases. They also feature two watchdogs, one watchdog with independent clock and window capability and one window watchdog based on bus clock.

Moreover, the STM32L072xx devices embed standard and advanced communication interfaces: up to three I2Cs, two SPIs, one I2S, four USARTs, a low-power UART (LPUART), and a crystal-less USB. The devices offer up to 24 capacitive sensing channels to simply add touch sensing functionality to any application.

The STM32L072xx also include a real-time clock and a set of backup registers that remain powered in Standby mode.

The ultra-low-power STM32L072xx devices operate from a 1.8 to 3.6 V power supply (down to 1.65 V at power down) with BOR and from a 1.65 to 3.6 V power supply without BOR option. They are available in the -40 to +125 °C temperature range. A comprehensive set of power-saving modes allows the design of low-power applications.









3.4.3 Voltage regulator

The regulator has three operation modes: main (MR), low power (LPR) and power down.

- MR is used in Run mode (nominal regulation)
- LPR is used in the Low-power run, Low-power sleep and Stop modes
- Power down is used in Standby mode. The regulator output is high impedance, the kernel circuitry is powered down, inducing zero consumption but the contents of the registers and RAM are lost except for the standby circuitry (wakeup logic, IWDG, RTC, LSI, LSE crystal 32 KHz oscillator, RCC_CSR).

3.5 Clock management

The clock controller distributes the clocks coming from different oscillators to the core and the peripherals. It also manages clock gating for low-power modes and ensures clock robustness. It features:

Clock prescaler

To get the best trade-off between speed and current consumption, the clock frequency to the CPU and peripherals can be adjusted by a programmable prescaler.

• Safe clock switching

Clock sources can be changed safely on the fly in Run mode through a configuration register.

• Clock management

To reduce power consumption, the clock controller can stop the clock to the core, individual peripherals or memory.

• System clock source

Three different clock sources can be used to drive the master clock SYSCLK:

- 1-25 MHz high-speed external crystal (HSE), that can supply a PLL
- 16 MHz high-speed internal RC oscillator (HSI), trimmable by software, that can supply a PLLMultispeed internal RC oscillator (MSI), trimmable by software, able to generate 7 frequencies (65 kHz, 131 kHz, 262 kHz, 524 kHz, 1.05 MHz, 2.1 MHz, 4.2 MHz). When a 32.768 kHz clock source is available in the system (LSE), the MSI frequency can be trimmed by software down to a ±0.5% accuracy.

• Auxiliary clock source

Two ultra-low-power clock sources that can be used to drive the real-time clock:

- 32.768 kHz low-speed external crystal (LSE)
- 37 kHz low-speed internal RC (LSI), also used to drive the independent watchdog. The LSI clock can be measured using the high-speed internal RC oscillator for greater precision.

• RTC clock source

The LSI, LSE or HSE sources can be chosen to clock the RTC, whatever the system clock.

USB clock source

A 48 MHz clock trimmed through the USB SOF or LSE supplies the USB interface.



independent from the CPU clock, allowing the I2C1/I2C3 to wake up the MCU from Stop mode on address match.

Each I2C interface can be served by the DMA controller.

Refer to *Table 12* for an overview of I2C interface features.

Table 12.	STM32L072xx	l ² C	implementation
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I2C features ⁽¹⁾	I2C1	I2C2	I2C3
7-bit addressing mode	Х	Х	Х
10-bit addressing mode	Х	Х	Х
Standard mode (up to 100 kbit/s)	Х	Х	Х
Fast mode (up to 400 kbit/s)	Х	Х	Х
Fast Mode Plus with 20 mA output drive I/Os (up to 1 Mbit/s)	х	X ⁽²⁾	х
Independent clock	Х	-	Х
SMBus	Х	-	Х
Wakeup from STOP	Х	-	Х

1. X = supported.

 See Table 16: STM32L072xxx pin definition on page 43 for the list of I/Os that feature Fast Mode Plus capability

3.17.2 Universal synchronous/asynchronous receiver transmitter (USART)

The four USART interfaces (USART1, USART2, USART4 and USART5) are able to communicate at speeds of up to 4 Mbit/s.

They provide hardware management of the CTS, RTS and RS485 driver enable (DE) signals, multiprocessor communication mode, master synchronous communication and single-wire half-duplex communication mode. USART1 and USART2 also support SmartCard communication (ISO 7816), IrDA SIR ENDEC, LIN Master/Slave capability, auto baud rate feature and has a clock domain independent from the CPU clock, allowing to wake up the MCU from Stop mode using baudrates up to 42 Kbaud.

All USART interfaces can be served by the DMA controller.

Table 13 for the supported modes and features of USART interfaces.

USART modes/features ⁽¹⁾	USART1 and USART2	USART4 and USART5
Hardware flow control for modem	Х	Х
Continuous communication using DMA	Х	Х
Multiprocessor communication	Х	Х
Synchronous mode ⁽²⁾	Х	Х
Smartcard mode	Х	-
Single-wire half-duplex communication	Х	Х
IrDA SIR ENDEC block	Х	-

Table 13	B. USART	implementation
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Figure 5. STM32L072xx LQFP64 pinout - 10 x 10 mm

1. The above figure shows the package top view.

2. I/O pin supplied by VDD_USB.



Symbol	Ratings	Max.	Unit
$\Sigma I_{VDD}^{(2)}$	Total current into sum of all V_{DD} power lines (source) ⁽¹⁾	105	
$\Sigma I_{VSS}^{(2)}$	Total current out of sum of all V_{SS} ground lines (sink) ⁽¹⁾	105	
ΣI _{VDD_USB}	Total current into V _{DD_USB} power lines (source)	25	
I _{VDD(PIN)}	Maximum current into each V _{DD} power pin (source) ⁽¹⁾	100	
I _{VSS(PIN)}	Maximum current out of each V_{SS} ground pin (sink) ⁽¹⁾	100	
I _{IO}	Output current sunk by any I/O and control pin except FTf pins	16	
	Output current sunk by FTf pins	22	
	Output current sourced by any I/O and control pin	-16	mA
	Total output current sunk by sum of all IOs and control pins except PA11 and PA12 $^{(2)}$	90	
$\Sigma I_{IO(PIN)}$	Total output current sunk by PA11 and PA12	25	
	Total output current sourced by sum of all IOs and control pins ⁽²⁾	-90	
1	Injected current on FT, FFf, RST and B pins	-5/+0 ⁽³⁾	
INJ(PIN)	Injected current on TC pin	± 5 ⁽⁴⁾	
ΣI _{INJ(PIN)}	Total injected current (sum of all I/O and control pins) ⁽⁵⁾	± 25	

Table 24. Current characteristics

1. All main power (V_{DD} , V_{DDA}) and ground (V_{SS} , V_{SSA}) pins must always be connected to the external power supply, in the permitted range.

 This current consumption must be correctly distributed over all I/Os and control pins. The total output current must not be sunk/sourced between two consecutive power supply pins referring to high pin count LQFP packages.

 Positive current injection is not possible on these I/Os. A negative injection is induced by V_{IN}<V_{SS}. I_{INJ(PIN)} must never be exceeded. Refer to *Table 23* for maximum allowed input voltage values.

A positive injection is induced by V_{IN} > V_{DD} while a negative injection is induced by V_{IN} < V_{SS}. I_{INJ(PIN)} must never be exceeded. Refer to *Table 23: Voltage characteristics* for the maximum allowed input voltage values.

5. When several inputs are submitted to a current injection, the maximum $\Sigma I_{INJ(PIN)}$ is the absolute sum of the positive and negative injected currents (instantaneous values).

Symbol	Ratings	Value	Unit
T _{STG}	Storage temperature range	–65 to +150	°C
TJ	Maximum junction temperature	150	°C

Table 25. Thermal characteristics



On-chip peripheral current consumption

The current consumption of the on-chip peripherals is given in the following tables. The MCU is placed under the following conditions:

- all I/O pins are in input mode with a static value at V_{DD} or V_{SS} (no load)
- all peripherals are disabled unless otherwise mentioned
- the given value is calculated by measuring the current consumption
 - with all peripherals clocked off
 - with only one peripheral clocked on

Table 40. Peripheral current consumption in Run or Sleep mode⁽¹⁾

Peripheral		Typical consumption, V _{DD} = 3.0 V, T _A = 25 °C				
		Range 1, V _{CORE} =1.8 V VOS[1:0] = 01	Range 2, V _{CORE} =1.5 V VOS[1:0] = 10	Range 3, V _{CORE} =1.2 V VOS[1:0] = 11	Low-power sleep and run	Unit
	CRS	2.5	2	2	2	
	DAC1/2	4	3.5	3	2.5	
	I2C1	11	9.5	7.5	9	
	I2C3	11	9	7	9	
	LPTIM1	10	8.5	6.5	8	
	LPUART1	8	6.5	5.5	6	μΔ/MH7
	SPI2	9	4.5	3.5	4	
	USB	8.5	4.5	4	4.5	
APB1	USART2	14.5	12	9.5	11	(f _{HCLK})
	USART4	5	4	3	5	
	USART5	5	4	3	5	
	TIM2	10.5	8.5	7	9	
	TIM3	12	10	8	11	
	TIM6	3.5	3	2.5	2	
	TIM7	3.5	3	2.5	2	
	WWDG	3	2	2	2	



Symbol	Poriphoral	Typical consum	Unit	
Symbol	Feripiteral	V _{DD} =1.8 V	V _{DD} =3.0 V	
I _{DD(PVD / BOR)}	-	0.7	1.2	
I _{REFINT}	-	-	1.7	
-	LSE Low drive ⁽²⁾	0.11	0,13	
-	LSI	0.27	0.31	
-	IWDG	0.2	0.3	
-	LPTIM1, Input 100 Hz	0.01	0,01	μΑ
-	LPTIM1, Input 1 MHz	11	12	
-	LPUART1	-	0,5	
-	RTC	0.16	0,3	

Table 41. Peripheral current consumption in §	Stop and Standby mode ⁽¹
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1. LPTIM, LPUART peripherals can operate in Stop mode but not in Standby mode.

2. LSE Low drive consumption is the difference between an external clock on OSC32_IN and a quartz between OSC32_IN and OSC32_OUT.-

6.3.5 Wakeup time from low-power mode

The wakeup times given in the following table are measured with the MSI or HSI16 RC oscillator. The clock source used to wake up the device depends on the current operating mode:

- Sleep mode: the clock source is the clock that was set before entering Sleep mode
- Stop mode: the clock source is either the MSI oscillator in the range configured before entering Stop mode, the HSI16 or HSI16/4.
- Standby mode: the clock source is the MSI oscillator running at 2.1 MHz

All timings are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 26*.

Symbol	Parameter	Conditions	Тур	Max	Unit
t _{WUSLEEP}	Wakeup from Sleep mode	f _{HCLK} = 32 MHz	7	8	
	Wakeup from Low-power sleep mode, f _{HCLK} = 262 kHz	f _{HCLK} = 262 kHz Flash memory enabled	7	8	Number of clock
LP		f _{HCLK} = 262 kHz Flash memory switched OFF	9	10	cycles

Table 42	I ow-nower	mode	wakeun	timinas
1 a Die 42.	LOW-DOWEI	moue	waneup	unnigs



Symbol	Parameter	Conditions	Тур	Мах	Unit
		f _{HCLK} = f _{MSI} = 4.2 MHz	5.0	8	
	Wakeup from Stop mode, regulator in Run mode	f _{HCLK} = f _{HSI} = 16 MHz	4.9	7	
		f _{HCLK} = f _{HSI} /4 = 4 MHz	8.0	11	
		f _{HCLK} = f _{MSI} = 4.2 MHz Voltage range 1	5.0	8	
		f _{HCLK} = f _{MSI} = 4.2 MHz Voltage range 2	5.0	8	
		f _{HCLK} = f _{MSI} = 4.2 MHz Voltage range 3	5.0	8	
t _{WUSTOP}	Wakeup from Stop mode, regulator in low- power mode	f _{HCLK} = f _{MSI} = 2.1 MHz	7.3	13	
		f _{HCLK} = f _{MSI} = 1.05 MHz	13	23	
		f _{HCLK} = f _{MSI} = 524 kHz	28	38	μs
		f _{HCLK} = f _{MSI} = 262 kHz	51	65	
		f _{HCLK} = f _{MSI} = 131 kHz	100	120	
		f _{HCLK} = MSI = 65 kHz	190	260	
		f _{HCLK} = f _{HSI} = 16 MHz	4.9	7	
		f _{HCLK} = f _{HSI} /4 = 4 MHz	8.0	11	
		f _{HCLK} = f _{HSI} = 16 MHz	4.9	7	
	power mode, code running from RAM	f _{HCLK} = f _{HSI} /4 = 4 MHz	7.9	10	
		f _{HCLK} = f _{MSI} = 4.2 MHz	4.7	8	
tuureener	Wakeup from Standby mode FWU bit = 1	f _{HCLK} = MSI = 2.1 MHz	65	130	
^t wustdby	Wakeup from Standby mode FWU bit = 0	f _{HCLK} = MSI = 2.1 MHz	2.2	3	ms

Table 42. Low-power mode wakeup timings (continued)



Output voltage levels

Unless otherwise specified, the parameters given in *Table 61* are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 26*. All I/Os are CMOS and TTL compliant.

Symbol	Parameter	Conditions	Min	Max	Unit
V _{OL} ⁽¹⁾	Output low level voltage for an I/O pin	CMOS port ⁽²⁾ ,	-	0.4	
V _{OH} ⁽³⁾	Output high level voltage for an I/O pin	$1_{O} = +0.01$ A 2.7 V $\leq V_{DD} \leq 3.6$ V	V _{DD} -0.4	-	
V _{OL} ⁽¹⁾	Output low level voltage for an I/O pin	$\begin{array}{c} {\sf TTL \ port}^{(2)}, \\ {\sf I}_{IO} \ \mbox{=+} \ \mbox{8 mA} \\ {\sf 2.7 \ V} \le {\sf V}_{DD} \le \ \mbox{3.6 V} \end{array}$	-	0.4	
V _{OH} ⁽³⁾⁽⁴⁾	Output high level voltage for an I/O pin	$\begin{array}{l} \text{TTL port}^{(2)},\\ \text{I}_{\text{IO}} \texttt{=} -\texttt{6} \text{ mA}\\ \textbf{2.7} \text{ V} \leq \text{V}_{\text{DD}} \leq \ \textbf{3.6} \text{ V} \end{array}$	2.4	-	
V _{OL} ⁽¹⁾⁽⁴⁾	Output low level voltage for an I/O pin	I_{IO} = +15 mA 2.7 V \leq V _{DD} \leq 3.6 V	-	1.3	V
V _{OH} ⁽³⁾⁽⁴⁾	Output high level voltage for an I/O pin	$\begin{array}{l} \text{I}_{\text{IO}} \text{ = -15 mA} \\ \text{2.7 V} \leq \text{V}_{DD} \leq \ \text{3.6 V} \end{array}$	V _{DD} -1.3	-	
V _{OL} ⁽¹⁾⁽⁴⁾	Output low level voltage for an I/O pin	I_{IO} = +4 mA 1.65 V \leq V _{DD} < 3.6 V	-	0.45	
V _{OH} ⁽³⁾⁽⁴⁾	Output high level voltage for an I/O pin	I_{IO} = -4 mA 1.65 V \leq V _{DD} \leq 3.6 V	V _{DD} -0.45	-	
Va	Output low level voltage for an FTf	$I_{IO} = 20 \text{ mA} \\ 2.7 \text{ V} \le V_{DD} \le 3.6 \text{ V}$	-	0.4	
V _{OLFM+} ⁽¹⁾⁽⁴⁾	I/O pin in Fm+ mode	$I_{IO} = 10 \text{ mA} \\ 1.65 \text{ V} \le \text{V}_{DD} \le 3.6 \text{ V}$	-	0.4	

Table 61. Output voltage	characteristics
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 The I_{IO} current sunk by the device must always respect the absolute maximum rating specified in *Table 24*. The sum of the currents sunk by all the I/Os (I/O ports and control pins) must always be respected and must not exceed ΣI_{IO(PIN)}.

2. TTL and CMOS outputs are compatible with JEDEC standards JESD36 and JESD52.

3. The I_{IO} current sourced by the device must always respect the absolute maximum rating specified in Table 24. The sum of the currents sourced by all the I/Os (I/O ports and control pins) must always be respected and must not exceed $\Sigma I_{IO(PIN)}$.

4. Guaranteed by characterization results.



The analog spike filter is compliant with I^2C timings requirements only for the following voltage ranges:

- Fast mode Plus: 2.7 V \leq V_DD \leq 3.6 V and voltage scaling Range 1
- Fast mode:
 - 2 V \leq V_{DD} \leq 3.6 V and voltage scaling Range 1 or Range 2.
 - V_{DD} < 2 V, voltage scaling Range 1 or Range 2, C_{load} < 200 pF.

In other ranges, the analog filter should be disabled. The digital filter can be used instead.

Note: In Standard mode, no spike filter is required.

Table 73.	12C	analog	filter	characteristics ⁽¹)
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Symbol	Parameter	Conditions	Min	Мах	Unit
	Maximum pulse width of spikes that are suppressed by the analog filter	Range 1		100 ⁽³⁾	ns
t _{AF}		Range 2	50 ⁽²⁾	-	
		Range 3		-	

- 1. Guaranteed by characterization results.
- 2. Spikes with widths below $t_{\mbox{AF}(\mbox{min})}$ are filtered.
- 3. Spikes with widths above $t_{AF(max)}$ are not filtered

USART/LPUART characteristics

The parameters given in the following table are guaranteed by design.

Symbol	Parameter	Conditions	Тур	Max	Unit
^t wuusart	Wakeup time needed to calculate the maximum USART/LPUART baudrate allowing to wake up from Stop mode	Stop mode with main regulator in Run mode, Range 2 or 3	-	8.7	
		Stop mode with main regulator in Run mode, Range 1	-	8.1	μs
		Stop mode with main regulator in low-power mode, Range 2 or 3	-	12	
		Stop mode with main regulator in low-power mode, Range 1		- 11.4	

Table 74. USART/LPUART characteristics



Symbol	Parameter	Conditions	Min	Тур	Max	Unit
f _{SCK}	SPI clock froquency	Master mode			2	
1/t _{c(SCK)}	SPI Clock liequency	Slave mode	-	-	2 ⁽²⁾	
Duty _(SCK)	Duty cycle of SPI clock frequency	Slave mode	30	50	70	%
t _{su(NSS)}	NSS setup time	Slave mode, SPI presc = 2	4*Tpclk	-	-	
t _{h(NSS)}	NSS hold time	Slave mode, SPI presc = 2	2*Tpclk	-	-	
t _{w(SCKH)} t _{w(SCKL)}	SCK high and low time	Master mode	Tpclk-2	Tpclk	Tpclk+2	
t _{su(MI)}	Data input satur timo	Master mode	1.5	-	-	
t _{su(SI)}		Slave mode	6	-	-	
t _{h(MI)}	Data input hold time	Master mode	13.5	-	-	
t _{h(SI)}		Slave mode	16	-	-	ns
t _{a(SO}	Data output access time	Slave mode	30	-	70	
t _{dis(SO)}	Data output disable time	Slave mode	40	-	80	
t _{v(SO)}	Data output valid time	Slave mode	-	30	70	
t _{v(MO)}		Master mode	-	7	9	
t _{h(SO)}	Data output hold time	Slave mode	25	-	-	
t _{h(MO)}		Master mode	8	-	-	

						(4)
Table 77.	SPI ch	aracteristics	in v	oltage	Range	3 (1)

1. Guaranteed by characterization results.

2. The maximum SPI clock frequency in slave transmitter mode is determined by the sum of $t_{v(SO)}$ and $t_{su(MI)}$ which has to fit into SCK low or high phase preceding the SCK sampling edge. This value can be achieved when the SPI communicates with a master having $t_{su(MI)} = 0$ while Duty_(SCK) = 50%.



Figure 35. SPI timing diagram - slave mode and CPHA = 0

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Figure 36. SPI timing diagram - slave mode and CPHA = $1^{(1)}$

1. Measurement points are done at CMOS levels: $0.3V_{DD}$ and $0.7V_{DD}$.



Figure 37. SPI timing diagram - master mode⁽¹⁾

1. Measurement points are done at CMOS levels: $0.3V_{DD}$ and $0.7V_{DD}$.



I2S characteristics

Symbol	Parameter	Conditions	Min	Мах	Unit	
f _{MCK}	I2S Main clock output	-	256 x 8K	256xFs ⁽²⁾	MHz	
f.	12S clock frequency	Master data: 32 bits	-	64xFs	MU-7	
'CK	125 Clock nequency	Slave data: 32 bits	-	64xFs	IVITIZ	
D _{CK}	I2S clock frequency duty cycle	Slave receiver	30	70	%	
t _{v(WS)}	WS valid time	Master mode	-	15		
t _{h(WS)}	WS hold time	Master mode	11	-		
t _{su(WS)}	WS setup time	Slave mode	6	-		
t _{h(WS)}	WS hold time	Slave mode	2	2 -		
$t_{su(SD_MR)}$	Data input setup time	Data input actua time		-		
t _{su(SD_SR)}		Slave receiver	6.5	-	ne	
t _{h(SD_MR)}	Data input hold time	Master receiver	18	-	115	
t _{h(SD_SR)}	Data input noid time	Slave receiver	15.5	-		
t _{v(SD_ST)}	Data output valid time	Slave transmitter (after enable edge)	-	77		
t _{v(SD_MT)}		Master transmitter (after enable edge)	-	8		
t _{h(SD_ST)}	Data output hold time	Slave transmitter (after enable edge)	18	-		
t _{h(SD_MT)}		Master transmitter (after enable edge)	1.5	-	1	

Table 78. I2S characteristics⁽¹⁾

1. Guaranteed by characterization results.

2. 256xFs maximum value is equal to the maximum clock frequency.

Note: Refer to the I2S section of the product reference manual for more details about the sampling frequency (Fs), f_{MCK} , f_{CK} and D_{CK} values. These values reflect only the digital peripheral behavior, source clock precision might slightly change them. DCK depends mainly on the ODD bit value, digital contribution leads to a min of (I2SDIV/(2*I2SDIV+ODD) and a max of (I2SDIV+ODD)/(2*I2SDIV+ODD). Fs max is supported for each mode/condition.



USB characteristics

The USB interface is USB-IF certified (full speed).

Table 79. USB startup time							
Symbol	Parameter	Max	Unit				
t _{STARTUP} ⁽¹⁾	USB transceiver startup time	1	μs				

1. Guaranteed by design.

Table 80. USB DC electrical characteristics

Symbol	Parameter	Conditions	Min. ⁽¹⁾	Max. ⁽¹⁾	Unit			
Input levels								
V _{DD}	USB operating voltage	-	3.0	3.6	V			
V _{DI} ⁽²⁾	Differential input sensitivity	I(USB_DP, USB_DM)	0.2	-				
V _{CM} ⁽²⁾	Differential common mode range Includes V _{DI} range		0.8	2.5	V			
V _{SE} ⁽²⁾	Single ended receiver threshold	-	1.3	2.0				
Output levels								
V _{OL} ⁽³⁾	Static output level low	${\sf R}_{\sf L}$ of 1.5 k Ω to 3.6 ${\sf V}^{(4)}$	-	0.3	V			
V _{OH} ⁽³⁾	Static output level high	${\sf R}_{\sf L}$ of 15 k Ω to ${\sf V}_{\sf SS}{}^{(4)}$	2.8	3.6	v			

1. All the voltages are measured from the local ground potential.

2. Guaranteed by characterization results.

3. Guaranteed by test in production.

4. $\ R_L$ is the load connected on the USB drivers.



7 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK[®] packages, depending on their level of environmental compliance. ECOPACK[®] specifications, grade definitions and product status *are available at www.st.com*. ECOPACK[®] is an ST trademark.

7.1 LQFP100 package information



Figure 41. LQFP100 - 100-pin, 14 x 14 mm low-profile quad flat package outline

1. Drawing is not to scale. Dimensions are in millimeters.



Device marking for UFBGA64

The following figure gives an example of topside marking versus ball A 1 position identifier location.



Figure 50. UFBGA64 marking example (package top view)

 Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.



	millimeters			inches ⁽¹⁾			
Symbol	Min	Тур	Мах	Min	Тур	Мах	
А	0.525	0.555	0.585	0.0207	0.0219	0.0230	
A1	-	0.175	-	-	0.0069	-	
A2	-	0.380	-	-	0.0150	-	
A3 ⁽²⁾	-	0.025	-	-	0.0010	-	
b ⁽³⁾	0.220	0.250	0.280	0.0087	0.0098	0.0110	
D	3.259	3.294	3.329	0.1283	0.1297	0.1311	
E	3.223	3.258	3.293	0.1269	0.1283	0.1296	
е	-	0.400	-	-	0.0157	-	
e1	-	2.400	-	-	0.0945	-	
e2	-	2.400	-	-	0.0945	-	
F	-	0.447	-	-	0.0176	-	
G	-	0.429	-	-	0.0169	-	
aaa	-	-	0.100	-	-	0.0039	
bbb	-	-	0.100	-	-	0.0039	
ССС	-	-	0.100	-	-	0.0039	
ddd	-	-	0.050	-	-	0.0020	
eee	-	-	0.050	-	-	0.0020	

Table 90. WLCSP49 - 49-pin, 3.294 x 3.258 mm, 0.4 mm pitch wafer level chip scalepackage mechanical data

1. Values in inches are converted from mm and rounded to 4 decimal digits.

2. Back side coating

3. Dimension is measured at the maximum bump diameter parallel to primary datum Z.

Figure 55. WLCSP49 - 49-pin, 3.294 x 3.258 mm, 0.4 mm pitch wafer level chip scale recommended footprint







Figure 58. LQFP48 - 48-pin, 7 x 7 mm low-profile quad flat recommended footprint

1. Dimensions are expressed in millimeters.



F													
Symbol	millimeters			inches ⁽¹⁾									
	Min	Тур	Max	Min	Тур	Max							
А	0.500	0.550	0.600	0.0197	0.0217	0.0236							
A1	0.000	0.020	0.050	0.0000	0.0008	0.0020							
A3	-	0.152	-	-	0.0060	-							
b	0.180	0.230	0.280	0.0071	0.0091	0.0110							
D	4.900	5.000	5.100	0.1929	0.1969	0.2008							
D1	3.400	3.500	3.600	0.1339	0.1378	0.1417							
D2	3.400	3.500	3.600	0.1339	0.1378	0.1417							
E	4.900	5.000	5.100	0.1929	0.1969	0.2008							
E1	3.400	3.500	3.600	0.1339	0.1378	0.1417							
E2	3.400	3.500	3.600	0.1339	0.1378	0.1417							
е	-	0.500	-	-	0.0197	-							
L	0.300	0.400	0.500	0.0118	0.0157	0.0197							
ddd	-	-	0.080	-	-	0.0031							

Table 94. UFQFPN32 - 32-pin, 5x5 mm, 0.5 mm pitch ultra thin fine pitch quad flatpackage mechanical data

1. Values in inches are converted from mm and rounded to 4 decimal digits.





1. Dimensions are expressed in millimeters.



8 Part numbering

Table 96. STM32L072xx ordering information scheme										
Example:	STM32	L (072	R	8	Т	6	D	TR	
Device family										
STM32 = ARM-based 32-bit microcontroller										
Product type										
L = Low power		-								
Device subfamily										
072 = USB			-							
Pin count										
K = 32 pins				-						
C = 48/49 pins										
R = 64 pins										
V = 100 pins										
Flash memory size										
8 = 64 Kbytes										
B = 128 Kbytes										
Z = 192 Kbytes										
Package										
T = LQFP										
H = TFBGA										
I = UFBGA										
U = UFQFPN										
Y = WLCSP pins										
Temperature range										
6 = Industrial temperature range, –40 to 85 °C										
7 = Industrial temperature range, –40 to 105 °C										
3 = Industrial temperature range, –40 to 125 °C										
Options										
No character = V_{DD} range: 1.8 to 3.6 V and BOR enabled										
D = V_{DD} range: 1.65 to 3.6 V and BOR disabled										
Packing										

TR = tape and reel

No character = tray or tube

For a list of available options (speed, package, etc.) or for further information on any aspect of this device, please contact your nearest ST sales office.

