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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	168MHz
Connectivity	CANbus, DCMI, EBI/EMI, Ethernet, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, LCD, POR, PWM, WDT
Number of I/O	82
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	192K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 16x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f417vet6tr">https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f417vet6tr</a>

## 2 Description

The STM32F415xx and STM32F417xx family is based on the high-performance ARM® Cortex®-M4 32-bit RISC core operating at a frequency of up to 168 MHz. The Cortex-M4 core features a Floating point unit (FPU) single precision which supports all ARM single-precision data-processing instructions and data types. It also implements a full set of DSP instructions and a memory protection unit (MPU) which enhances application security.

The STM32F415xx and STM32F417xx family incorporates high-speed embedded memories (Flash memory up to 1 Mbyte, up to 192 Kbytes of SRAM), up to 4 Kbytes of backup SRAM, and an extensive range of enhanced I/Os and peripherals connected to two APB buses, three AHB buses and a 32-bit multi-AHB bus matrix.

All devices offer three 12-bit ADCs, two DACs, a low-power RTC, twelve general-purpose 16-bit timers including two PWM timers for motor control, two general-purpose 32-bit timers, a true random number generator (RNG), and a cryptographic acceleration cell. They also feature standard and advanced communication interfaces.

- Up to three I<sup>2</sup>Cs
- Three SPIs, two I<sup>2</sup>Ss full duplex. To achieve audio class accuracy, the I2S peripherals can be clocked via a dedicated internal audio PLL or via an external clock to allow synchronization.
- Four USARTs plus two UARTs
- An USB OTG full-speed and a USB OTG high-speed with full-speed capability (with the ULPI),
- Two CANs
- An SDIO/MMC interface
- Ethernet and the camera interface available on STM32F417xx devices only.

New advanced peripherals include an SDIO, an enhanced flexible static memory control (FSMC) interface (for devices offered in packages of 100 pins and more), a camera interface for CMOS sensors and a cryptographic acceleration cell. Refer to [Table 2: STM32F415xx and STM32F417xx: features and peripheral counts](#) for the list of peripherals available on each part number.

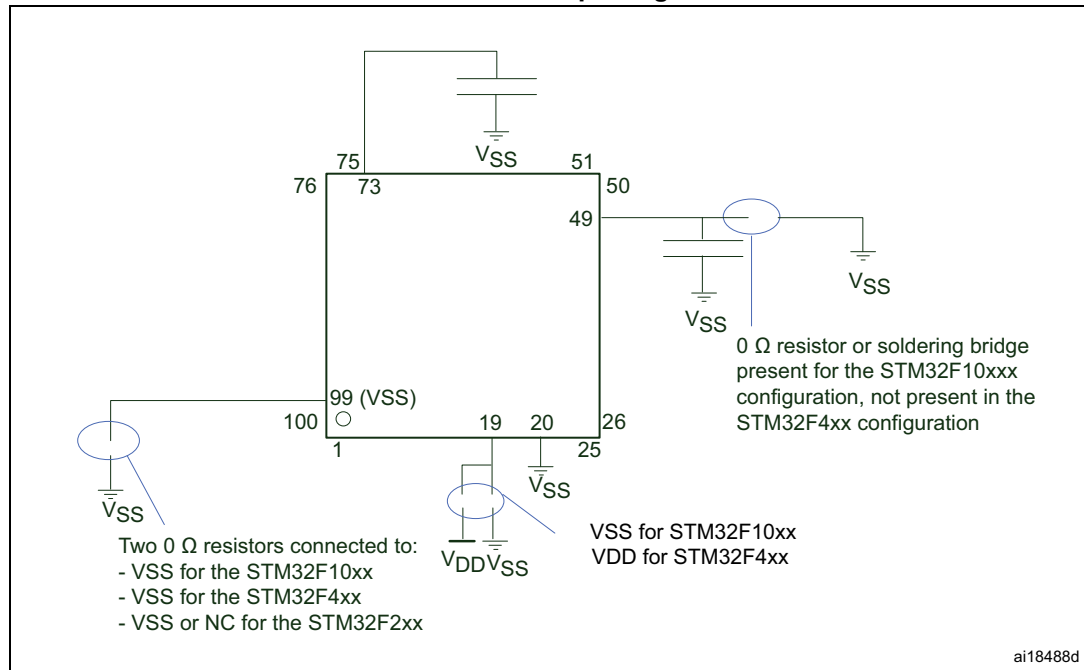
The STM32F415xx and STM32F417xx family operates in the –40 to +105 °C temperature range from a 1.8 to 3.6 V power supply. The supply voltage can drop to 1.7 V when the device operates in the 0 to 70 °C temperature range using an external power supply supervisor: refer to [Section : Internal reset OFF](#). A comprehensive set of power-saving mode allows the design of low-power applications.

The STM32F415xx and STM32F417xx family offers devices in various packages ranging from 64 pins to 176 pins. The set of included peripherals changes with the device chosen.

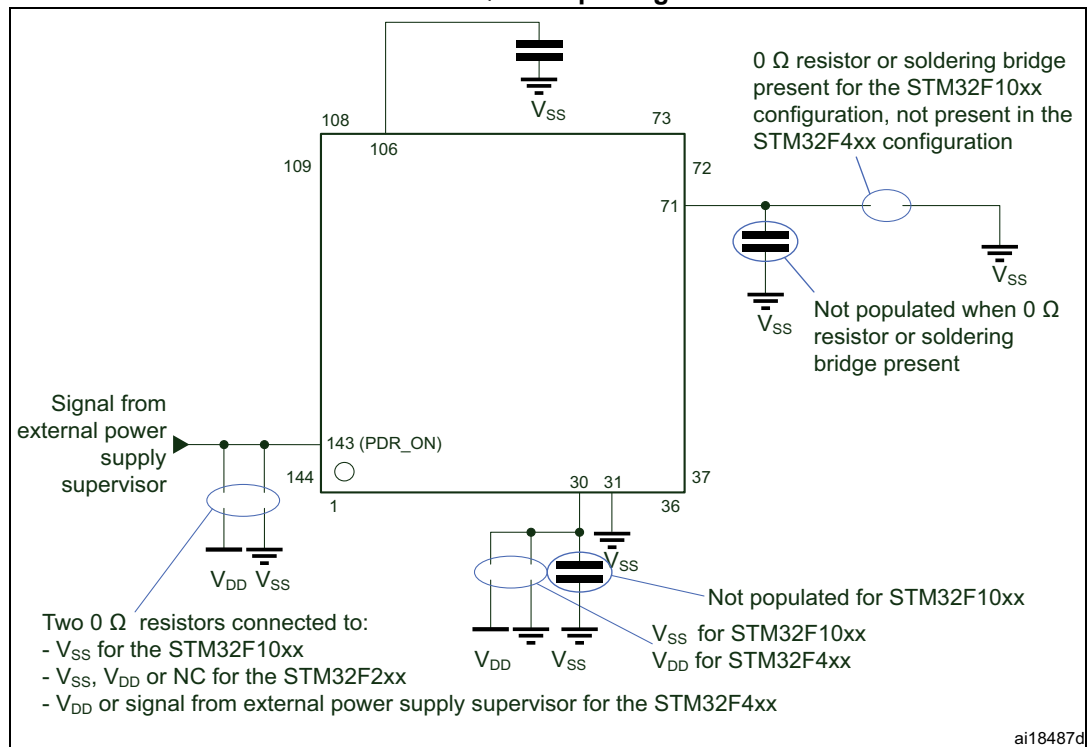
These features make the STM32F415xx and STM32F417xx microcontroller family suitable for a wide range of applications:

- Motor drive and application control
- Medical equipment
- Industrial applications: PLC, inverters, circuit breakers
- Printers, and scanners
- Alarm systems, video intercom, and HVAC
- Home audio appliances

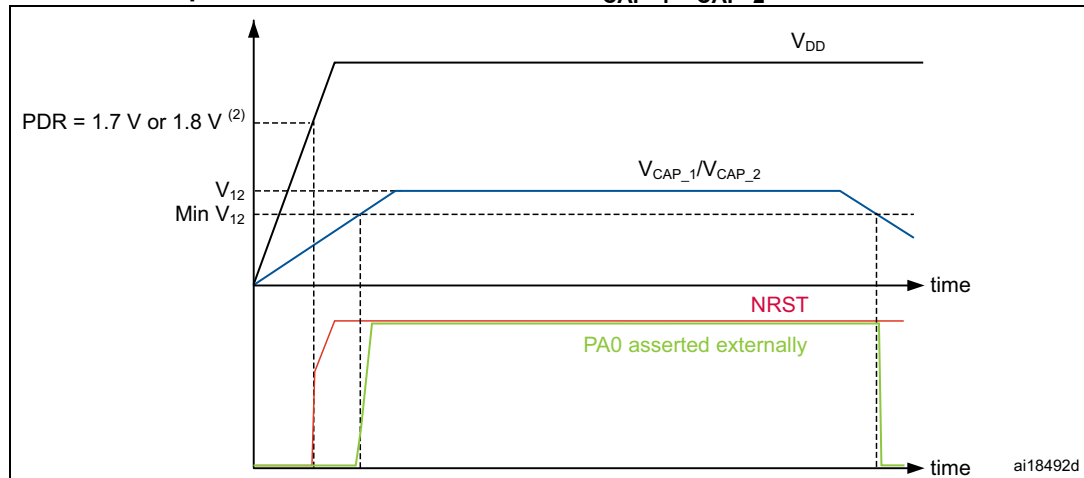
**Figure 2. Compatible board design STM32F10xx/STM32F2/STM32F41xxx for LQFP100 package**



**Figure 3. Compatible board design between STM32F10xx/STM32F2/STM32F41xxx for LQFP144 package**



**Figure 11. Startup in regulator OFF mode: fast  $V_{DD}$  slope  
- power-down reset risen before  $V_{CAP\_1}/V_{CAP\_2}$  stabilization**



1. This figure is valid both whatever the internal reset mode (ON or OFF).
2. PDR = 1.7 V for a reduced temperature range; PDR = 1.8 V for all temperature ranges.

### 2.2.17 Regulator ON/OFF and internal reset ON/OFF availability

**Table 3. Regulator ON/OFF and internal reset ON/OFF availability**

	Regulator ON	Regulator OFF	Internal reset ON	Internal reset OFF
LQFP64 LQFP100	Yes	No	Yes	No
LQFP144			Yes PDR_ON set to $V_{DD}$	Yes PDR_ON connected to an external power supply supervisor
WLCSP90 UFBGA176 LQFP176	Yes BYPASS_REG set to $V_{SS}$	Yes BYPASS_REG set to $V_{DD}$		

### 2.2.18 Real-time clock (RTC), backup SRAM and backup registers

The backup domain of the STM32F415xx and STM32F417xx includes:

- The real-time clock (RTC)
- 4 Kbytes of backup SRAM
- 20 backup registers

The real-time clock (RTC) is an independent BCD timer/counter. Dedicated registers contain the second, minute, hour (in 12/24 hour), week day, date, month, year, in BCD (binary-coded decimal) format. Correction for 28, 29 (leap year), 30, and 31 day of the month are performed automatically. The RTC provides a programmable alarm and programmable periodic interrupts with wakeup from Stop and Standby modes. The sub-seconds value is also available in binary format.

It is clocked by a 32.768 kHz external crystal, resonator or oscillator, the internal low-power RC oscillator or the high-speed external clock divided by 128. The internal low-speed RC

## General-purpose timers (TIMx)

There are ten synchronizable general-purpose timers embedded in the STM32F41xxx devices (see [Table 4](#) for differences).

- **TIM2, TIM3, TIM4, TIM5**

The STM32F41xxx include 4 full-featured general-purpose timers: TIM2, TIM5, TIM3, and TIM4. The TIM2 and TIM5 timers are based on a 32-bit auto-reload up/downcounter and a 16-bit prescaler. The TIM3 and TIM4 timers are based on a 16-bit auto-reload up/downcounter and a 16-bit prescaler. They all feature 4 independent channels for input capture/output compare, PWM or one-pulse mode output. This gives up to 16 input capture/output compare/PWMs on the largest packages.

The TIM2, TIM3, TIM4, TIM5 general-purpose timers can work together, or with the other general-purpose timers and the advanced-control timers TIM1 and TIM8 via the Timer Link feature for synchronization or event chaining.

Any of these general-purpose timers can be used to generate PWM outputs.

TIM2, TIM3, TIM4, TIM5 all have independent DMA request generation. They are capable of handling quadrature (incremental) encoder signals and the digital outputs from 1 to 4 hall-effect sensors.

- **TIM9, TIM10, TIM11, TIM12, TIM13, and TIM14**

These timers are based on a 16-bit auto-reload upcounter and a 16-bit prescaler. TIM10, TIM11, TIM13, and TIM14 feature one independent channel, whereas TIM9 and TIM12 have two independent channels for input capture/output compare, PWM or one-pulse mode output. They can be synchronized with the TIM2, TIM3, TIM4, TIM5 full-featured general-purpose timers. They can also be used as simple time bases.

## Basic timers TIM6 and TIM7

These timers are mainly used for DAC trigger and waveform generation. They can also be used as a generic 16-bit time base.

TIM6 and TIM7 support independent DMA request generation.

## Independent watchdog

The independent watchdog is based on a 12-bit downcounter and 8-bit prescaler. It is clocked from an independent 32 kHz internal RC and as it operates independently from the main clock, it can operate in Stop and Standby modes. It can be used either as a watchdog to reset the device when a problem occurs, or as a free-running timer for application timeout management. It is hardware- or software-configurable through the option bytes.

## Window watchdog

The window watchdog is based on a 7-bit downcounter that can be set as free-running. It can be used as a watchdog to reset the device when a problem occurs. It is clocked from the main clock. It has an early warning interrupt capability and the counter can be frozen in debug mode.

### 2.2.31 Universal serial bus on-the-go high-speed (OTG\_HS)

The STM32F415xx and STM32F417xx devices embed a USB OTG high-speed (up to 480 Mb/s) device/host/OTG peripheral. The USB OTG HS supports both full-speed and high-speed operations. It integrates the transceivers for full-speed operation (12 MB/s) and features a UTMI low-pin interface (ULPI) for high-speed operation (480 MB/s). When using the USB OTG HS in HS mode, an external PHY device connected to the ULPI is required.

The USB OTG HS peripheral is compliant with the USB 2.0 specification and with the OTG 1.0 specification. It has software-configurable endpoint setting and supports suspend/resume. The USB OTG full-speed controller requires a dedicated 48 MHz clock that is generated by a PLL connected to the HSE oscillator.

The major features are:

- Combined Rx and Tx FIFO size of 1 Kbit × 35 with dynamic FIFO sizing
- Supports the session request protocol (SRP) and host negotiation protocol (HNP)
- 6 bidirectional endpoints
- 12 host channels with periodic OUT support
- Internal FS OTG PHY support
- External HS or HS OTG operation supporting ULPI in SDR mode. The OTG PHY is connected to the microcontroller ULPI port through 12 signals. It can be clocked using the 60 MHz output.
- Internal USB DMA
- HNP/SNP/IP inside (no need for any external resistor)
- for OTG/Host modes, a power switch is needed in case bus-powered devices are connected

### 2.2.32 Digital camera interface (DCMI)

The camera interface is *not* available in STM32F415xx devices.

STM32F417xx products embed a camera interface that can connect with camera modules and CMOS sensors through an 8-bit to 14-bit parallel interface, to receive video data. The camera interface can sustain a data transfer rate up to 54 Mbyte/s at 54 MHz. It features:

- Programmable polarity for the input pixel clock and synchronization signals
- Parallel data communication can be 8-, 10-, 12- or 14-bit
- Supports 8-bit progressive video monochrome or raw bayer format, YCbCr 4:2:2 progressive video, RGB 565 progressive video or compressed data (like JPEG)
- Supports continuous mode or snapshot (a single frame) mode
- Capability to automatically crop the image

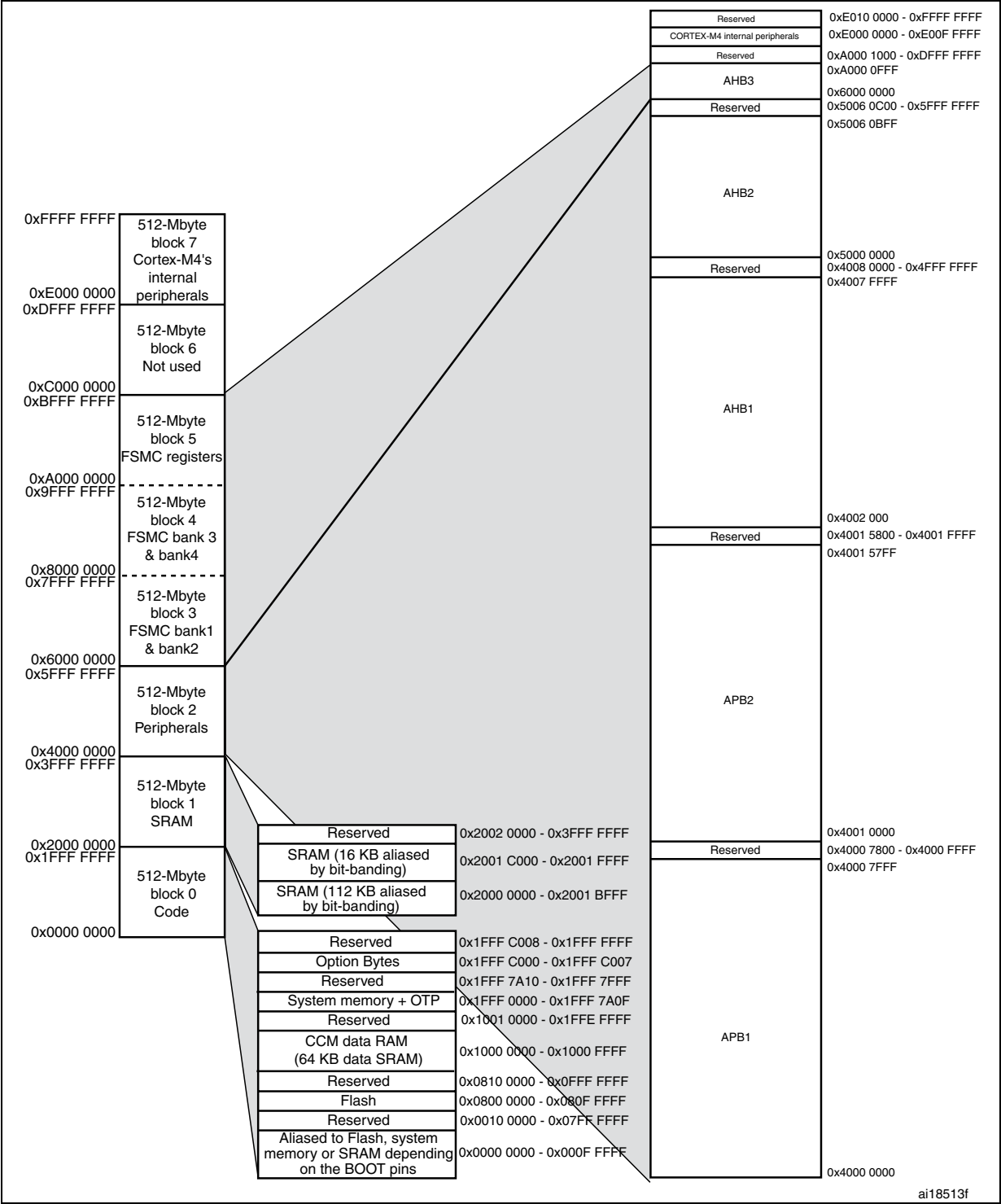
Table 8. FSMC pin definition (continued)

Pins <sup>(1)</sup>	FSMC				LQFP100 <sup>(2)</sup>	WLCSP90 <sup>(2)</sup>
	CF	NOR/PSRAM/ SRAM	NOR/PSRAM Mux	NAND 16 bit		
PF1	A1	A1	-	-	-	-
PF2	A2	A2	-	-	-	-
PF3	A3	A3	-	-	-	-
PF4	A4	A4	-	-	-	-
PF5	A5	A5	-	-	-	-
PF6	NIORD	-	-	-	-	-
PF7	NREG	-	-	-	-	-
PF8	NIOWR	-	-	-	-	-
PF9	CD	-	-	-	-	-
PF10	INTR	-	-	-	-	-
PF12	A6	A6	-	-	-	-
PF13	A7	A7	-	-	-	-
PF14	A8	A8	-	-	-	-
PF15	A9	A9	-	-	-	-
PG0	A10	A10	-	-	-	-
PG1		A11	-	-	-	-
PE7	D4	D4	DA4	D4	Yes	Yes
PE8	D5	D5	DA5	D5	Yes	Yes
PE9	D6	D6	DA6	D6	Yes	Yes
PE10	D7	D7	DA7	D7	Yes	Yes
PE11	D8	D8	DA8	D8	Yes	Yes
PE12	D9	D9	DA9	D9	Yes	Yes
PE13	D10	D10	DA10	D10	Yes	Yes
PE14	D11	D11	DA11	D11	Yes	Yes
PE15	D12	D12	DA12	D12	Yes	Yes
PD8	D13	D13	DA13	D13	Yes	Yes
PD9	D14	D14	DA14	D14	Yes	Yes
PD10	D15	D15	DA15	D15	Yes	Yes
PD11	-	A16	A16	CLE	Yes	Yes
PD12	-	A17	A17	ALE	Yes	Yes
PD13	-	A18	A18	-	Yes	-
PD14	D0	D0	DA0	D0	Yes	Yes
PD15	D1	D1	DA1	D1	Yes	Yes

4 Memory mapping

The memory map is shown in [Figure 18](#).

Figure 18. STM32F41xxx memory map



## 5 Electrical characteristics

### 5.1 Parameter conditions

Unless otherwise specified, all voltages are referenced to  $V_{SS}$ .

#### 5.1.1 Minimum and maximum values

Unless otherwise specified the minimum and maximum values are guaranteed in the worst conditions of ambient temperature, supply voltage and frequencies by tests in production on 100% of the devices with an ambient temperature at  $T_A = 25\text{ }^{\circ}\text{C}$  and  $T_A = T_{A\text{max}}$  (given by the selected temperature range).

Data based on characterization results, design simulation and/or technology characteristics are indicated in the table footnotes and are not tested in production. Based on characterization, the minimum and maximum values refer to sample tests and represent the mean value plus or minus three times the standard deviation ( $\text{mean} \pm 3\Sigma$ ).

#### 5.1.2 Typical values

Unless otherwise specified, typical data are based on  $T_A = 25\text{ }^{\circ}\text{C}$ ,  $V_{DD} = 3.3\text{ V}$  (for the  $1.8\text{ V} \leq V_{DD} \leq 3.6\text{ V}$  voltage range). They are given only as design guidelines and are not tested.

Typical ADC accuracy values are determined by characterization of a batch of samples from a standard diffusion lot over the full temperature range, where 95% of the devices have an error less than or equal to the value indicated ( $\text{mean} \pm 2\Sigma$ ).

#### 5.1.3 Typical curves

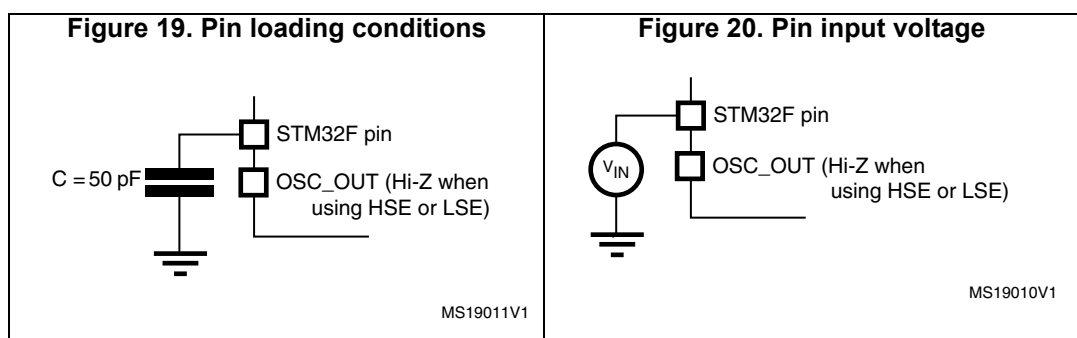
Unless otherwise specified, all typical curves are given only as design guidelines and are not tested.

#### 5.1.4 Loading capacitor

The loading conditions used for pin parameter measurement are shown in [Figure 19](#).

#### 5.1.5 Pin input voltage

The input voltage measurement on a pin of the device is described in [Figure 20](#).



### Low-speed external user clock generated from an external source

The characteristics given in [Table 31](#) result from tests performed using an low-speed external clock source, and under ambient temperature and supply voltage conditions summarized in [Table 14](#).

**Table 31. Low-speed external user clock characteristics**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{LSE\_ext}$	User External clock source frequency <sup>(1)</sup>	-	-	32.768	1000	kHz
$V_{LSEH}$	OSC32_IN input pin high level voltage		$0.7V_{DD}$	-	$V_{DD}$	V
$V_{LSEL}$	OSC32_IN input pin low level voltage		$V_{SS}$	-	$0.3V_{DD}$	
$t_{w(LSE)}$ $t_{f(LSE)}$	OSC32_IN high or low time <sup>(1)</sup>		450	-	-	ns
$t_{r(LSE)}$ $t_{f(LSE)}$	OSC32_IN rise or fall time <sup>(1)</sup>		-	-	50	
$C_{in(LSE)}$	OSC32_IN input capacitance <sup>(1)</sup>	-	-	5	-	pF
$DuCy_{(LSE)}$	Duty cycle	-	30	-	70	%
$I_L$	OSC32_IN Input leakage current	$V_{SS} \leq V_{IN} \leq V_{DD}$	-	-	$\pm 1$	$\mu A$

1. Guaranteed by design.

**Figure 30. High-speed external clock source AC timing diagram**

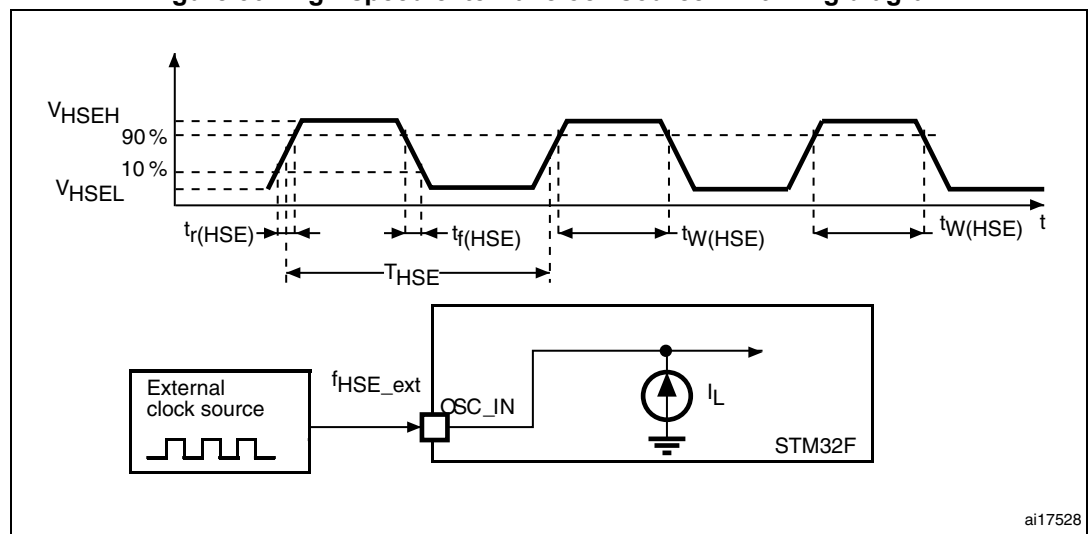


Table 37. PLLI2S (audio PLL) characteristics (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{DD(PLLI2S)}^{(4)}$	PLLI2S power consumption on $V_{DD}$	VCO freq = 100 MHz VCO freq = 432 MHz	0.15 0.45	-	0.40 0.75	mA
$I_{DDA(PLLI2S)}^{(4)}$	PLLI2S power consumption on $V_{DDA}$	VCO freq = 100 MHz VCO freq = 432 MHz	0.30 0.55	-	0.40 0.85	mA

1. Take care of using the appropriate division factor M to have the specified PLL input clock values.
2. Guaranteed by design.
3. Value given with main PLL running.
4. Guaranteed by characterization.

### 5.3.11 PLL spread spectrum clock generation (SSCG) characteristics

The spread spectrum clock generation (SSCG) feature allows to reduce electromagnetic interferences (see [Table 44: EMI characteristics](#)). It is available only on the main PLL.

Table 38. SSCG parameters constraint

Symbol	Parameter	Min	Typ	Max <sup>(1)</sup>	Unit
$f_{Mod}$	Modulation frequency	-	-	10	KHz
md	Peak modulation depth	0.25	-	2	%
MODEPER * INCSTEP		-	-	$2^{15}-1$	-

1. Guaranteed by design.

#### Equation 1

The frequency modulation period (MODEPER) is given by the equation below:

$$\text{MODEPER} = \text{round}[f_{\text{PLL\_IN}} / (4 \times f_{\text{Mod}})]$$

$f_{\text{PLL\_IN}}$  and  $f_{\text{Mod}}$  must be expressed in Hz.

As an example:

If  $f_{\text{PLL\_IN}} = 1 \text{ MHz}$ , and  $f_{\text{MOD}} = 1 \text{ kHz}$ , the modulation depth (MODEPER) is given by equation 1:

$$\text{MODEPER} = \text{round}[10^6 / (4 \times 10^3)] = 250$$

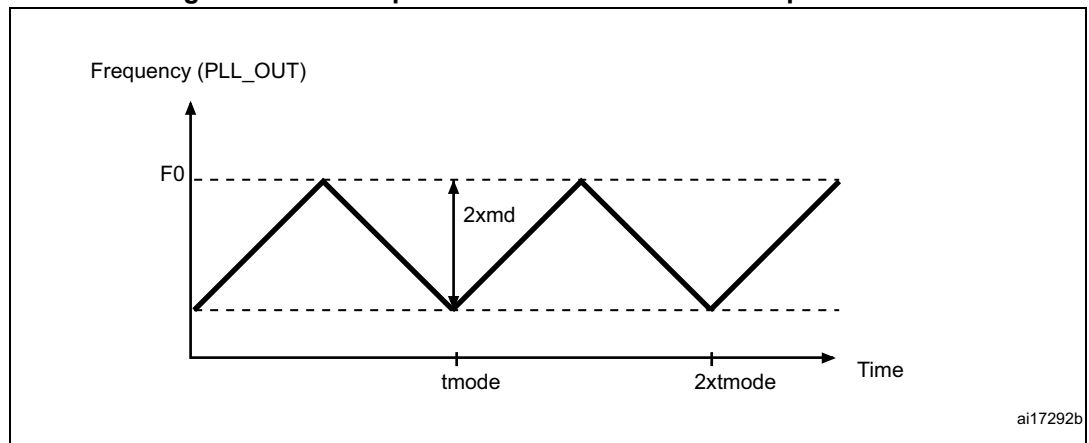
#### Equation 2

Equation 2 allows to calculate the increment step (INCSTEP):

$$\text{INCSTEP} = \text{round}[(2^{15} - 1) \times \text{md} \times \text{PLL_N}] / (100 \times 5 \times \text{MODEPER})]$$

$f_{\text{VCO\_OUT}}$  must be expressed in MHz.

Figure 36. PLL output clock waveforms in down spread mode



### 5.3.12 Memory characteristics

#### Flash memory

The characteristics are given at  $T_A = -40$  to  $105\text{ }^{\circ}\text{C}$  unless otherwise specified.

The devices are shipped to customers with the Flash memory erased.

Table 39. Flash memory characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{DD}$	Supply current	Write / Erase 8-bit mode, $V_{DD} = 1.8\text{ V}$	-	5	-	mA
		Write / Erase 16-bit mode, $V_{DD} = 2.1\text{ V}$	-	8	-	
		Write / Erase 32-bit mode, $V_{DD} = 3.3\text{ V}$	-	12	-	

Table 40. Flash memory programming

Symbol	Parameter	Conditions	Min <sup>(1)</sup>	Typ	Max <sup>(1)</sup>	Unit
$t_{prog}$	Word programming time	Program/erase parallelism (PSIZE) = x 8/16/32	-	16	100 <sup>(2)</sup>	$\mu\text{s}$
$t_{ERASE16KB}$	Sector (16 KB) erase time	Program/erase parallelism (PSIZE) = x 8	-	400	800	ms
		Program/erase parallelism (PSIZE) = x 16	-	300	600	
		Program/erase parallelism (PSIZE) = x 32	-	250	500	
$t_{ERASE64KB}$	Sector (64 KB) erase time	Program/erase parallelism (PSIZE) = x 8	-	1200	2400	ms
		Program/erase parallelism (PSIZE) = x 16	-	700	1400	
		Program/erase parallelism (PSIZE) = x 32	-	550	1100	

Table 47. I/O current injection susceptibility

Symbol	Description	Functional susceptibility		Unit
		Negative injection	Positive injection	
$I_{INJ}^{(1)}$	Injected current on BOOT0 pin	- 0	NA	mA
	Injected current on NRST pin	- 0	NA	
	Injected current on PE2, PE3, PE4, PE5, PE6, PI8, PC13, PC14, PC15, PI9, PI10, PI11, PF0, PF1, PF2, PF3, PF4, PF5, PF10, PH0/OSC_IN, PH1/OSC_OUT, PC0, PC1, PC2, PC3, PB6, PB7, PB8, PB9, PE0, PE1, PI4, PI5, PI6, PI7, PDR_ON, BYPASS_REG	- 0	NA	
	Injected current on all FT pins	- 5	NA	
	Injected current on any other pin	- 5	+5	

1. It is recommended to add a Schottky diode (pin to ground) to analog pins which may potentially inject negative currents.

### 5.3.16 I/O port characteristics

#### General input/output characteristics

Unless otherwise specified, the parameters given in [Table 48](#) are derived from tests performed under the conditions summarized in [Table 14](#). All I/Os are CMOS and TTL compliant.

Table 48. I/O static characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V <sub>IL</sub>	FT, TTa and NRST I/O input low level voltage	1.7 V ≤V <sub>DD</sub> ≤3.6 V	-	-	0.3V <sub>DD</sub> -0.04 <sup>(1)</sup>	V
			-	-	0.3V <sub>DD</sub> <sup>(2)</sup>	
	BOOT0 I/O input low level voltage	1.75 V ≤V <sub>DD</sub> ≤3.6 V -40 °C≤T <sub>A</sub> ≤105 °C	-	-	0.1V <sub>DD</sub> +0.1 <sup>(1)</sup>	
		1.7 V ≤V <sub>DD</sub> ≤3.6 V 0 °C≤T <sub>A</sub> ≤105 °C	-	-		
V <sub>IH</sub>	FT, TTa and NRST I/O input low level voltage	1.7 V ≤V <sub>DD</sub> ≤3.6 V	0.45V <sub>DD</sub> +0.3 <sup>(1)</sup>	-	-	
			0.7V <sub>DD</sub> <sup>(2)</sup>	-	-	
	BOOT0 I/O input low level voltage	1.75 V ≤V <sub>DD</sub> ≤3.6 V -40 °C≤T <sub>A</sub> ≤105 °C	0.17V <sub>DD</sub> +0.7 <sup>(1)</sup>	-	-	
		1.7 V ≤V <sub>DD</sub> ≤3.6 V 0 °C≤T <sub>A</sub> ≤105 °C		-	-	

**Input/output AC characteristics**

The definition and values of input/output AC characteristics are given in [Figure 37](#) and [Table 50](#), respectively.

Unless otherwise specified, the parameters given in [Table 50](#) are derived from tests performed under the ambient temperature and  $V_{DD}$  supply voltage conditions summarized in [Table 14](#).

**Table 50. I/O AC characteristics<sup>(1)(2)</sup>**

OSPEEDRy [1:0] bit value <sup>(1)</sup>	Symbol	Parameter	Conditions	Min	Typ	Max	Unit
00	$f_{\max(\text{IO})\text{out}}$	Maximum frequency <sup>(3)</sup>	$C_L = 50 \text{ pF}, V_{DD} > 2.70 \text{ V}$	-	-	4	MHz
			$C_L = 50 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	2	
			$C_L = 10 \text{ pF}, V_{DD} > 2.70 \text{ V}$	-	-	8	
			$C_L = 10 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	4	
	$t_{f(\text{IO})\text{out}}/$ $t_{r(\text{IO})\text{out}}$	Output high to low level fall time and output low to high level rise time	$C_L = 50 \text{ pF}, V_{DD} = 1.8 \text{ V to}$ $3.6 \text{ V}$	-	-	100	ns
01	$f_{\max(\text{IO})\text{out}}$	Maximum frequency <sup>(3)</sup>	$C_L = 50 \text{ pF}, V_{DD} > 2.70 \text{ V}$	-	-	25	MHz
			$C_L = 50 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	12.5	
			$C_L = 10 \text{ pF}, V_{DD} > 2.70 \text{ V}$	-	-	50 <sup>(4)</sup>	
			$C_L = 10 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	20	
	$t_{f(\text{IO})\text{out}}/$ $t_{r(\text{IO})\text{out}}$	Output high to low level fall time and output low to high level rise time	$C_L = 50 \text{ pF}, V_{DD} > 2.7 \text{ V}$	-	-	10	ns
			$C_L = 50 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	20	
			$C_L = 10 \text{ pF}, V_{DD} > 2.70 \text{ V}$	-	-	6	
			$C_L = 10 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	10	
10	$f_{\max(\text{IO})\text{out}}$	Maximum frequency <sup>(3)</sup>	$C_L = 40 \text{ pF}, V_{DD} > 2.70 \text{ V}$	-	-	50 <sup>(4)</sup>	MHz
			$C_L = 40 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	25	
			$C_L = 10 \text{ pF}, V_{DD} > 2.70 \text{ V}$	-	-	100 <sup>(4)</sup>	
			$C_L = 10 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	50 <sup>(4)</sup>	
	$t_{f(\text{IO})\text{out}}/$ $t_{r(\text{IO})\text{out}}$	Output high to low level fall time and output low to high level rise time	$C_L = 40 \text{ pF}, V_{DD} > 2.70 \text{ V}$	-	-	6	ns
			$C_L = 40 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	10	
			$C_L = 10 \text{ pF}, V_{DD} > 2.70 \text{ V}$	-	-	4	
			$C_L = 10 \text{ pF}, V_{DD} > 1.8 \text{ V}$	-	-	6	

Figure 41. SPI timing diagram - master mode

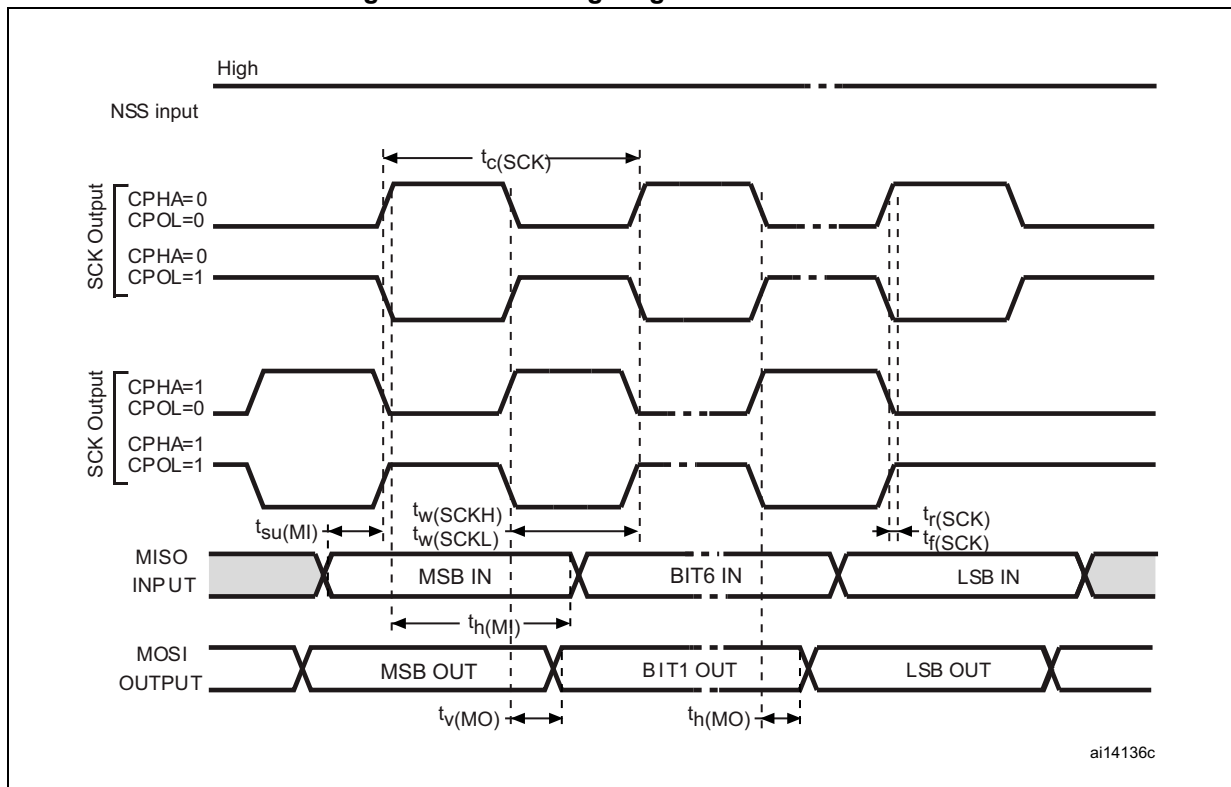
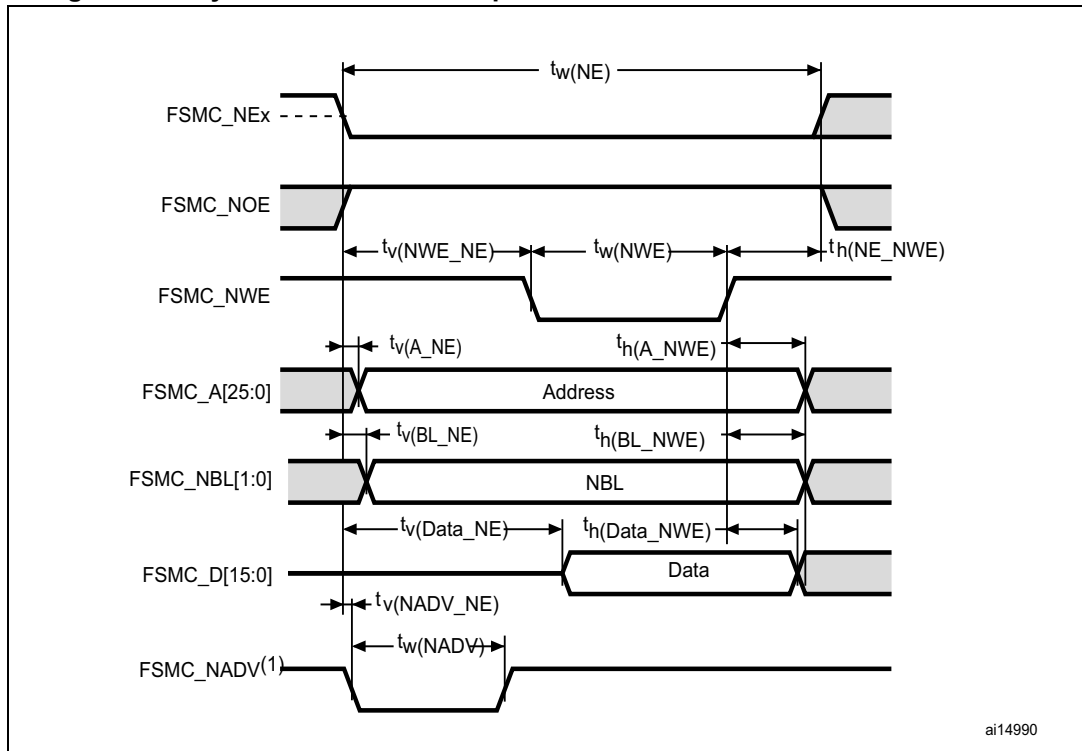


Table 67. ADC characteristics (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{lat}^{(4)}$	Injection trigger conversion latency	$f_{ADC} = 30\text{ MHz}$	-	-	0.100	$\mu\text{s}$
			-	-	$3^{(7)}$	$1/f_{ADC}$
$t_{latr}^{(4)}$	Regular trigger conversion latency	$f_{ADC} = 30\text{ MHz}$	-	-	0.067	$\mu\text{s}$
			-	-	$2^{(7)}$	$1/f_{ADC}$
$t_S^{(4)}$	Sampling time	$f_{ADC} = 30\text{ MHz}$	0.100	-	16	$\mu\text{s}$
		-	3	-	480	$1/f_{ADC}$
$t_{STAB}^{(4)}$	Power-up time	-	-	2	3	$\mu\text{s}$
$t_{CONV}^{(4)}$	Total conversion time (including sampling time)	$f_{ADC} = 30\text{ MHz}$ 12-bit resolution	0.50	-	16.40	$\mu\text{s}$
		$f_{ADC} = 30\text{ MHz}$ 10-bit resolution	0.43	-	16.34	$\mu\text{s}$
		$f_{ADC} = 30\text{ MHz}$ 8-bit resolution	0.37	-	16.27	$\mu\text{s}$
		$f_{ADC} = 30\text{ MHz}$ 6-bit resolution	0.30	-	16.20	$\mu\text{s}$
		9 to 492 ( $t_S$ for sampling + n-bit resolution for successive approximation)				$1/f_{ADC}$
$f_S^{(4)}$	Sampling rate ( $f_{ADC} = 30\text{ MHz}$ , and $t_S = 3\text{ ADC cycles}$ )	12-bit resolution Single ADC	-	-	2	Msp/s
		12-bit resolution Interleave Dual ADC mode	-	-	3.75	Msp/s
		12-bit resolution Interleave Triple ADC mode	-	-	6	Msp/s
$I_{VREF+}^{(4)}$	ADC $V_{REF}$ DC current consumption in conversion mode	-	-	300	500	$\mu\text{A}$
$I_{VDPA}^{(4)}$	ADC $V_{DDA}$ DC current consumption in conversion mode	-	-	1.6	1.8	mA

- $V_{DD}/V_{DDA}$  minimum value of 1.7 V is obtained when the device operates in reduced temperature range, and with the use of an external power supply supervisor (refer to [Section : Internal reset OFF](#)).
- It is recommended to maintain the voltage difference between  $V_{REF+}$  and  $V_{DDA}$  below 1.8 V.
- $V_{DDA} - V_{REF+} < 1.2\text{ V}$ .
- Guaranteed by characterization.
- $V_{REF+}$  is internally connected to  $V_{DDA}$  and  $V_{REF-}$  is internally connected to  $V_{SSA}$ .
- $R_{ADC}$  maximum value is given for  $V_{DD}=1.8\text{ V}$ , and minimum value for  $V_{DD}=3.3\text{ V}$ .
- For external triggers, a delay of  $1/f_{PCLK2}$  must be added to the latency specified in [Table 67](#).

**Figure 55. Asynchronous non-multiplexed SRAM/PSRAM/NOR write waveforms**

1. Mode 2/B, C and D only. In Mode 1, FSMC\_NADV is not used.

**Table 76. Asynchronous non-multiplexed SRAM/PSRAM/NOR write timings<sup>(1)(2)</sup>**

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FSMC_NE low time	$3T_{HCLK}$	$3T_{HCLK} + 4$	ns
$t_{v(NWE\_NE)}$	FSMC_NEx low to FSMC_NWE low	$T_{HCLK} - 0.5$	$T_{HCLK} + 0.5$	ns
$t_{w(NWE)}$	FSMC_NWE low time	$T_{HCLK} - 1$	$T_{HCLK} + 2$	ns
$t_{h(NE\_NWE)}$	FSMC_NWE high to FSMC_NE high hold time	$T_{HCLK} - 1$	-	ns
$t_{v(A\_NE)}$	FSMC_NEx low to FSMC_A valid	-	0	ns
$t_{h(A\_NWE)}$	Address hold time after FSMC_NWE high	$T_{HCLK} - 2$	-	ns
$t_{v(BL\_NE)}$	FSMC_NEx low to FSMC_NBL valid	-	1.5	ns
$t_{h(BL\_NWE)}$	FSMC_NBL hold time after FSMC_NWE high	$T_{HCLK} - 1$	-	ns
$t_{v(Data\_NE)}$	Data to FSMC_NEx low to Data valid	-	$T_{HCLK} + 3$	ns
$t_{h(Data\_NWE)}$	Data hold time after FSMC_NWE high	$T_{HCLK} - 1$	-	ns
$t_{v(NADV\_NE)}$	FSMC_NEx low to FSMC_NADV low	-	2	ns
$t_{w(NADV)}$	FSMC_NADV low time	-	$T_{HCLK} + 0.5$	ns

1.  $C_L = 30$  pF.

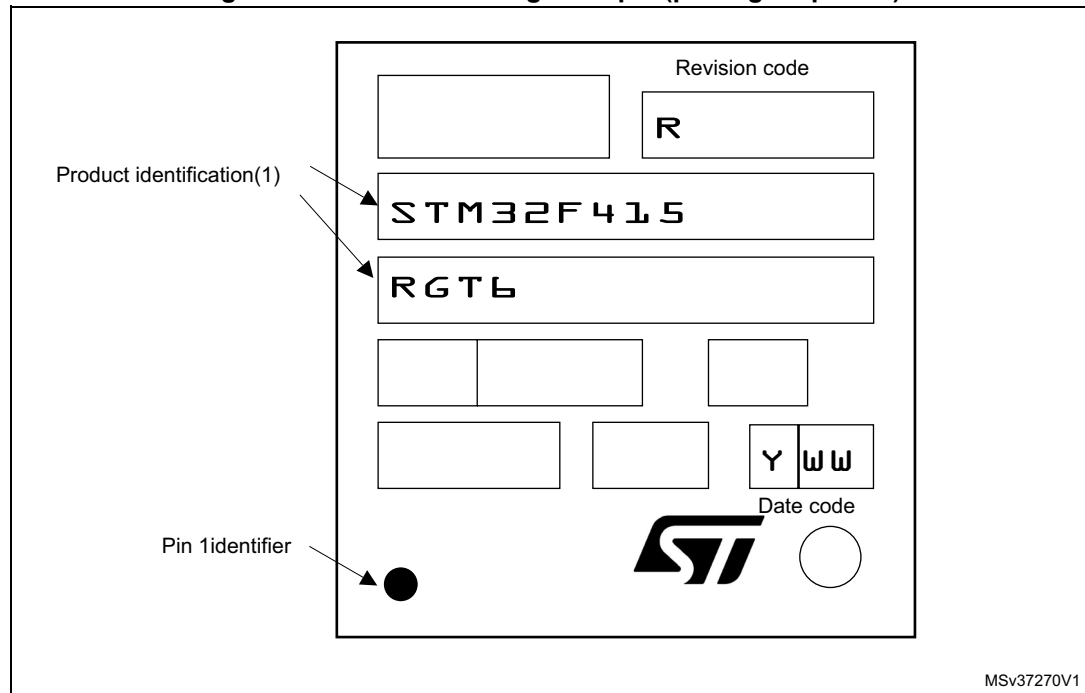
2. Guaranteed by characterization.

### Device marking for LQFP64

The following figure gives an example of topside marking and pin 1 position identifier location.

Other optional marking or inset/upset marks, which depend on supply chain operations, are not indicated below.

**Figure 80. LPQF64 marking example (package top view)**



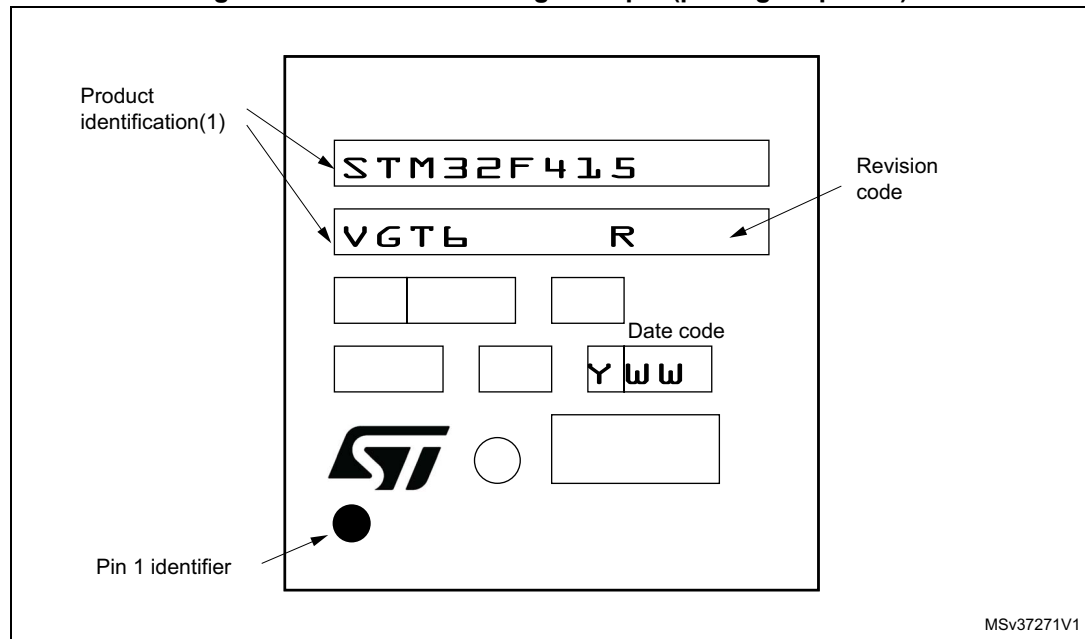
1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

### Device marking for LFP100

The following figure gives an example of topside marking and pin 1 position identifier location.

Other optional marking or inset/upset marks, which depend on supply chain operations, are not indicated below.

**Figure 83. LQFP100 marking example (package top view)**



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

Table 100. Document revision history (continued)

Date	Revision	Changes
31-May-2012	3 (continued)	<p>Removed <math>f_{HSE\_ext}</math> typical value in <a href="#">Table 30: High-speed external user clock characteristics</a>. Updated <a href="#">Table 32: HSE 4-26 MHz oscillator characteristics</a> and <a href="#">Table 33: LSE oscillator characteristics (fLSE = 32.768 kHz)</a>.</p> <p>Added <math>f_{PLL48\_OUT}</math> maximum value in <a href="#">Table 36: Main PLL characteristics</a>.</p> <p>Modified equation 1 and 2 in <a href="#">Section 5.3.11: PLL spread spectrum clock generation (SSCG) characteristics</a>.</p> <p>Updated <a href="#">Table 39: Flash memory characteristics</a>, <a href="#">Table 40: Flash memory programming</a>, and <a href="#">Table 41: Flash memory programming with VPP</a>.</p> <p>Updated <a href="#">Section : Output driving current</a>.</p> <p><a href="#">Table 56: I<sup>2</sup>C characteristics: Note 4</a> updated and applied to <math>t_{h(SDA)}</math> in Fast mode, and removed note 4 related to <math>t_{h(SDA)}</math> minimum value.</p> <p>Updated <a href="#">Table 67: ADC characteristics</a>. Updated note concerning ADC accuracy vs. negative injection current below <a href="#">Table 68: ADC accuracy at fADC = 30 MHz</a>.</p> <p>Added WLCSP90 thermal resistance in <a href="#">Table 98: Package thermal characteristics</a>.</p> <p>Updated <a href="#">Table 90: WLCSP90 - 4.223 x 3.969 mm, 0.400 mm pitch wafer level chip scale package mechanical data</a>.</p> <p>Updated <a href="#">Figure 87: UFBGA176+25 ball, 10 x 10 mm, 0.65 mm pitch, ultra fine pitch ball grid array package outline</a> and <a href="#">Table 95: UFBGA176+25 ball, 10 x 10 x 0.65 mm pitch, ultra thin fine pitch ball grid array mechanical data</a>.</p> <p>Added <a href="#">Figure 91: LQFP176 - 176-pin, 24 x 24 mm low profile quad flat recommended footprint</a>.</p> <p>Removed 256 and 768 Kbyte Flash memory density from <a href="#">Table 99: Ordering information scheme</a>.</p>

Table 100. Document revision history (continued)

Date	Revision	Changes
04-Jun-2013	4 (continued)	<p>Updated <a href="#">Figure 6: Multi-AHB matrix</a>.</p> <p>Updated <a href="#">Figure 7: Power supply supervisor interconnection with internal reset OFF</a></p> <p>Changed 1.2 V to <math>V_{12}</math> in <a href="#">Section : Regulator OFF</a></p> <p>Updated LQFP176 pin 48.</p> <p>Updated <a href="#">Section 1: Introduction</a>.</p> <p>Updated <a href="#">Section 2: Description</a>.</p> <p>Updated operating voltage in <a href="#">Table 2: STM32F415xx and STM32F417xx: features and peripheral counts</a>.</p> <p>Updated <a href="#">Note 1</a>.</p> <p>Updated <a href="#">Section 2.2.15: Power supply supervisor</a>.</p> <p>Updated <a href="#">Section 2.2.16: Voltage regulator</a>.</p> <p>Updated <a href="#">Figure 9: Regulator OFF</a>.</p> <p>Updated <a href="#">Table 3: Regulator ON/OFF and internal reset ON/OFF availability</a>.</p> <p>Updated <a href="#">Section 2.2.19: Low-power modes</a>.</p> <p>Updated <a href="#">Section 2.2.20: VBAT operation</a>.</p> <p>Updated <a href="#">Section 2.2.22: Inter-integrated circuit interface (I<sup>2</sup>C)</a> .</p> <p>Updated pin 48 in <a href="#">Figure 15: STM32F41xxx LQFP176 pinout</a>.</p> <p>Updated <a href="#">Table 6: Legend/abbreviations used in the pinout table</a>.</p> <p>Updated <a href="#">Table 7: STM32F41xxx pin and ball definitions</a>.</p> <p>Updated <a href="#">Table 14: General operating conditions</a>.</p> <p>Updated <a href="#">Table 15: Limitations depending on the operating power supply range</a>.</p> <p>Updated <a href="#">Section 5.3.7: Wakeup time from low-power mode</a>.</p> <p>Updated <a href="#">Table 34: HSI oscillator characteristics</a>.</p> <p>Updated <a href="#">Section 5.3.15: I/O current injection characteristics</a>.</p> <p>Updated <a href="#">Table 48: I/O static characteristics</a>.</p> <p>Updated <a href="#">Table 51: NRST pin characteristics</a>.</p> <p>Updated <a href="#">Table 56: I<sup>2</sup>C characteristics</a>.</p> <p>Updated <a href="#">Figure 39: I<sup>2</sup>C bus AC waveforms and measurement circuit</a>.</p> <p>Updated <a href="#">Section 5.3.19: Communications interfaces</a>.</p> <p>Updated <a href="#">Table 67: ADC characteristics</a>.</p> <p>Added <a href="#">Table 70: Temperature sensor calibration values</a>.</p> <p>Added <a href="#">Table 73: Internal reference voltage calibration values</a>.</p> <p>Updated <a href="#">Section 5.3.26: FSMC characteristics</a>.</p> <p>Updated <a href="#">Section 5.3.28: SD/SDIO MMC card host interface (SDIO) characteristics</a>.</p> <p>Updated <a href="#">Table 23: Typical and maximum current consumptions in Stop mode</a>.</p> <p>Updated <a href="#">Section : SPI interface characteristics</a> included <a href="#">Table 55</a>.</p> <p>Updated <a href="#">Section : I2S interface characteristics</a> included <a href="#">Table 56</a>.</p> <p>Updated <a href="#">Table 64: Dynamic characteristics: Eternity MAC signals for SMI</a>.</p> <p>Updated <a href="#">Table 66: Dynamic characteristics: Ethernet MAC signals for MII</a>.</p>