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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

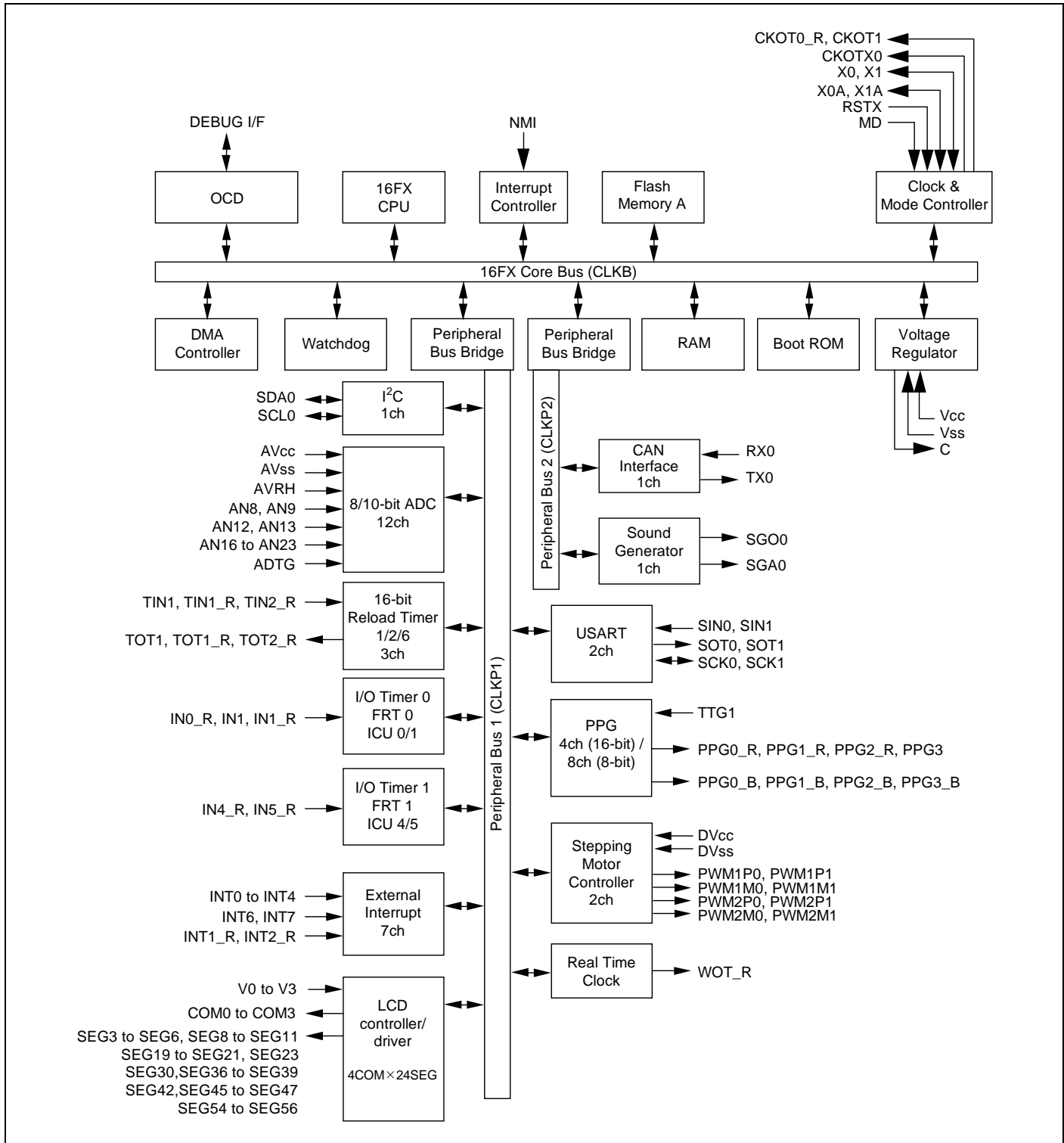
Details

Product Status	Obsolete
Core Processor	F ² MC-16FX
Core Size	16-Bit
Speed	32MHz
Connectivity	I ² C, LINbus, SCI, UART/USART
Peripherals	DMA, LCD, LVD, POR, PWM, WDT
Number of I/O	50
Program Memory Size	96KB (96K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 12x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb96f673abpmc-gse1

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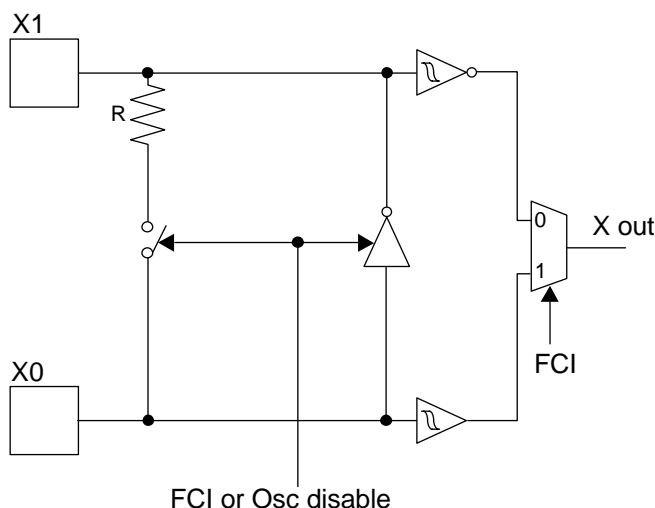
2. Block Diagram



Pin no.	I/O circuit type*	Pin name
33	N	P04_5 / SCL0
34	O	DEBUG I/F
35	H	P17_0
36	C	MD
37	A	X0
38	A	X1
39	Supply	Vss
40	B	P04_0 / X0A
41	B	P04_1 / X1A
42	C	RSTX
43	J	P11_7 / SEG3 / IN0_R
44	J	P11_0 / COM0
45	J	P11_1 / COM1 / PPG0_R
46	J	P11_2 / COM2 / PPG1_R
47	J	P11_3 / COM3 / PPG2_R
48	J	P12_0 / SEG4 / IN1_R
49	J	P12_1 / SEG5 / TIN1_R / PPG0_B
50	J	P12_2 / SEG6 / TOT1_R / PPG1_B
51	J	P12_4 / SEG8
52	J	P12_5 / SEG9 / TIN2_R / PPG2_B
53	J	P12_6 / SEG10 / TOT2_R / PPG3_B
54	J	P12_7 / SEG11 / INT1_R
55	J	P01_1 / SEG21 / CKOT1
56	J	P01_3 / SEG23
57	L	P03_0 / SEG36 / V0
58	L	P03_1 / SEG37 / V1
59	L	P03_2 / SEG38 / V2
60	L	P03_3 / SEG39 / V3
61	M	P03_4 / RX0 / INT4
62	H	P03_5 / TX0
63	H	P03_6 / INT0 / NMI
64	Supply	Vcc

*: See "I/O CIRCUIT TYPE" for details on the I/O circuit types.

6. I/O Circuit Type

Type	Circuit	Remarks
A	 <p>FCI or Osc disable</p>	<p>High-speed oscillation circuit:</p> <ul style="list-style-type: none"> • Programmable between oscillation mode (external crystal or resonator connected to X0/X1 pins) and Fast external Clock Input (FCI) mode (external clock connected to X0 pin) • Feedback resistor = approx. 1.0MΩ • The amplitude: 1.8V±0.15V to operate by the internal supply voltage

7. Memory Map

FF:FFFF _H	USER ROM*1
DE:0000 _H DD:FFFF _H	Reserved
10:0000 _H	Boot-ROM
0F:C000 _H	Peripheral
0E:9000 _H	Reserved
01:0000 _H	ROM/RAM MIRROR
00:8000 _H	Internal RAM bank0
RAMSTART0*2	Reserved
00:0C00 _H	Peripheral
00:0380 _H	GPR*3
00:0180 _H	DMA
00:0100 _H	Reserved
00:00F0 _H	Peripheral
00:0000 _H	

*1: For details about USER ROM area, see “User ROM Memory Map For Flash Devices” on the following pages.

*2: For RAMSTART addresses, see the table on the next page.

*3: Unused GPR banks can be used as RAM area.

GPR: General-Purpose Register

The DMA area is only available if the device contains the corresponding resource.

The available RAM and ROM area depends on the device.

9. User ROM Memory Map For Flash Devices

		MB96F673	MB96F675	
CPU mode address	Flash memory mode address	Flash size 64.5KB + 32KB	Flash size 128.5KB + 32KB	
FF:FFFFH FF:0000H	3F:FFFFH 3F:0000H	SA39 - 64KB	SA39 - 64KB	Bank A of Flash A
FE:FFFFH FE:0000H	3E:FFFFH 3E:0000H	Reserved	SA38 - 64KB	
FD:FFFFH			Reserved	
DF:A000H				
DF:9FFFH DF:8000H	1F:9FFFH 1F:8000H	SA4 - 8KB	SA4 - 8KB	Bank B of Flash A
DF:7FFFH DF:6000H	1F:7FFFH 1F:6000H	SA3 - 8KB	SA3 - 8KB	
DF:5FFFH DF:4000H	1F:5FFFH 1F:4000H	SA2 - 8KB	SA2 - 8KB	
DF:3FFFH DF:2000H	1F:3FFFH 1F:2000H	SA1 - 8KB	SA1 - 8KB	
DF:1FFFH DF:0000H	1F:1FFFH 1F:0000H	SAS - 512B*	SAS - 512B*	
DE:FFFFH DE:0000H		Reserved	Reserved	Bank A of Flash A

*: Physical address area of SAS-512B is from DF:0000H to DF:01FFH.

Others (from DF:0200H to DF:1FFFH) is mirror area of SAS-512B.

Sector SAS contains the ROM configuration block RCBA at CPU address DF:0000H -DF:01FFH.

SAS can not be used for E²PROM emulation.

10. Serial Programming Communication Interface

USART pins for Flash serial programming (MD = 0, DEBUG I/F = 0, Serial Communication mode)

MB96670		
Pin Number	USART Number	Normal Function
29	USART0	SIN0
30		SOT0
31		SCK0
3	USART1	SIN1
4		SOT1
5		SCK1

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
81	2B8 _H	-	-	81	Reserved
82	2B4 _H	-	-	82	Reserved
83	2B0 _H	-	-	83	Reserved
84	2AC _H	-	-	84	Reserved
85	2A8 _H	-	-	85	Reserved
86	2A4 _H	-	-	86	Reserved
87	2A0 _H	-	-	87	Reserved
88	29C _H	-	-	88	Reserved
89	298 _H	FRT0	Yes	89	Free-Running Timer 0
90	294 _H	FRT1	Yes	90	Free-Running Timer 1
91	290 _H	-	-	91	Reserved
92	28C _H	-	-	92	Reserved
93	288 _H	RTC0	No	93	Real Time Clock
94	284 _H	CAL0	No	94	Clock Calibration Unit
95	280 _H	SG0	No	95	Sound Generator 0
96	27C _H	IIC0	Yes	96	I ² C interface 0
97	278 _H	-	-	97	Reserved
98	274 _H	ADC0	Yes	98	A/D Converter 0
99	270 _H	-	-	99	Reserved
100	26C _H	-	-	100	Reserved
101	268 _H	LINR0	Yes	101	LIN USART 0 RX
102	264 _H	LINT0	Yes	102	LIN USART 0 TX
103	260 _H	LINR1	Yes	103	LIN USART 1 RX
104	25C _H	LINT1	Yes	104	LIN USART 1 TX
105	258 _H	-	-	105	Reserved
106	254 _H	-	-	106	Reserved
107	250 _H	-	-	107	Reserved
108	24C _H	-	-	108	Reserved
109	248 _H	-	-	109	Reserved
110	244 _H	-	-	110	Reserved
111	240 _H	-	-	111	Reserved
112	23C _H	-	-	112	Reserved
113	238 _H	-	-	113	Reserved
114	234 _H	-	-	114	Reserved
115	230 _H	-	-	115	Reserved
116	22C _H	-	-	116	Reserved
117	228 _H	-	-	117	Reserved
118	224 _H	-	-	118	Reserved
119	220 _H	-	-	119	Reserved
120	21C _H	-	-	120	Reserved

■ Precautions Related to Usage of Devices

Cypress semiconductor devices are intended for use in standard applications (computers, office automation and other office equipment, industrial, communications, and measurement equipment, personal or household devices, etc.).

CAUTION: Customers considering the use of our products in special applications where failure or abnormal operation may directly affect human lives or cause physical injury or property damage, or where extremely high levels of reliability are demanded (such as aerospace systems, atomic energy controls, sea floor repeaters, vehicle operating controls, medical devices for life support, etc.) are requested to consult with sales representatives before such use. The company will not be responsible for damages arising from such use without prior approval.

12.2 Precautions for Package Mounting

Package mounting may be either lead insertion type or surface mount type. In either case, for heat resistance during soldering, you should only mount under Cypress's recommended conditions. For detailed information about mount conditions, contact your sales representative.

■ Lead Insertion Type

Mounting of lead insertion type packages onto printed circuit boards may be done by two methods: direct soldering on the board, or mounting by using a socket.

Direct mounting onto boards normally involves processes for inserting leads into through-holes on the board and using the flow soldering (wave soldering) method of applying liquid solder. In this case, the soldering process usually causes leads to be subjected to thermal stress in excess of the absolute ratings for storage temperature. Mounting processes should conform to Cypress recommended mounting conditions.

If socket mounting is used, differences in surface treatment of the socket contacts and IC lead surfaces can lead to contact deterioration after long periods. For this reason it is recommended that the surface treatment of socket contacts and IC leads be verified before mounting.

■ Surface Mount Type

Surface mount packaging has longer and thinner leads than lead-insertion packaging, and therefore leads are more easily deformed or bent. The use of packages with higher pin counts and narrower pin pitch results in increased susceptibility to open connections caused by deformed pins, or shorting due to solder bridges.

You must use appropriate mounting techniques. Cypress recommends the solder reflow method, and has established a ranking of mounting conditions for each product. Users are advised to mount packages in accordance with Cypress ranking of recommended conditions.

■ Lead-Free Packaging

CAUTION: When ball grid array (BGA) packages with Sn-Ag-Cu balls are mounted using Sn-Pb eutectic soldering, junction strength may be reduced under some conditions of use.

■ Storage of Semiconductor Devices

Because plastic chip packages are formed from plastic resins, exposure to natural environmental conditions will cause absorption of moisture. During mounting, the application of heat to a package that has absorbed moisture can cause surfaces to peel, reducing moisture resistance and causing packages to crack. To prevent, do the following:

1. Avoid exposure to rapid temperature changes, which cause moisture to condense inside the product. Store products in locations where temperature changes are slight.
2. Use dry boxes for product storage. Products should be stored below 70% relative humidity, and at temperatures between 5°C and 30°C.
When you open Dry Package that recommends humidity 40% to 70% relative humidity.
3. When necessary, Cypress packages semiconductor devices in highly moisture-resistant aluminum laminate bags, with a silica gel desiccant. Devices should be sealed in their aluminum laminate bags for storage.
4. Avoid storing packages where they are exposed to corrosive gases or high levels of dust.

■ Baking

Packages that have absorbed moisture may be de-moisturized by baking (heat drying). Follow the Cypress recommended conditions for baking.

Condition: 125°C/24 h

■ Static Electricity

Because semiconductor devices are particularly susceptible to damage by static electricity, you must take the following precautions:

1. Maintain relative humidity in the working environment between 40% and 70%. Use of an apparatus for ion generation may be needed to remove electricity.
2. Electrically ground all conveyors, solder vessels, soldering irons and peripheral equipment.
3. Eliminate static body electricity by the use of rings or bracelets connected to ground through high resistance (on the level of 1 MΩ).
Wearing of conductive clothing and shoes, use of conductive floor mats and other measures to minimize shock loads is recommended.
4. Ground all fixtures and instruments, or protect with anti-static measures.
5. Avoid the use of styrofoam or other highly static-prone materials for storage of completed board assemblies.

12.3 Precautions for Use Environment

Reliability of semiconductor devices depends on ambient temperature and other conditions as described above.

For reliable performance, do the following:

1. Humidity
Prolonged use in high humidity can lead to leakage in devices as well as printed circuit boards. If high humidity levels are anticipated, consider anti-humidity processing.
2. Discharge of Static Electricity
When high-voltage charges exist close to semiconductor devices, discharges can cause abnormal operation. In such cases, use anti-static measures or processing to prevent discharges.
3. Corrosive Gases, Dust, or Oil
Exposure to corrosive gases or contact with dust or oil may lead to chemical reactions that will adversely affect the device. If you use devices in such conditions, consider ways to prevent such exposure or to protect the devices.
4. Radiation, Including Cosmic Radiation
Most devices are not designed for environments involving exposure to radiation or cosmic radiation. Users should provide shielding as appropriate.
5. Smoke, Flame
CAUTION: Plastic molded devices are flammable, and therefore should not be used near combustible substances. If devices begin to smoke or burn, there is danger of the release of toxic gases.

Customers considering the use of Cypress products in other special environmental conditions should consult with sales representatives.

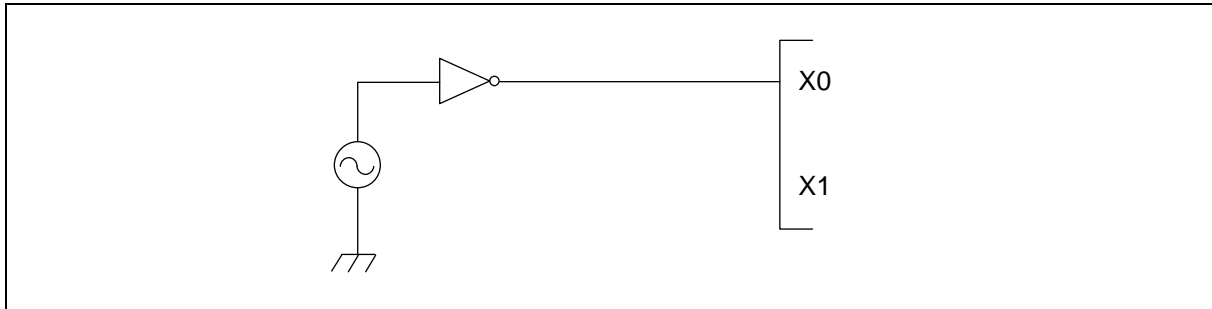
13.3 External clock usage

The permitted frequency range of an external clock depends on the oscillator type and configuration.

See AC Characteristics for detailed modes and frequency limits. Single and opposite phase external clocks must be connected as follows:

13.3.1 Single phase external clock for Main oscillator

When using a single phase external clock for the Main oscillator, X0 pin must be driven and X1 pin left open. And supply 1.8V power to the external clock.

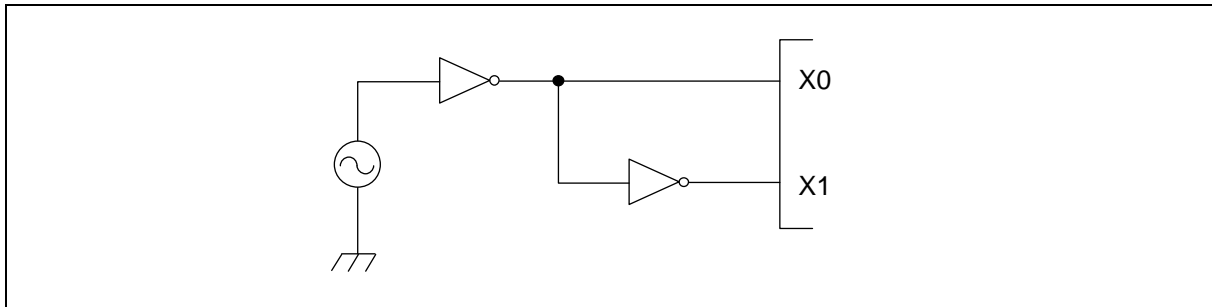


13.3.2 Single phase external clock for Sub oscillator

When using a single phase external clock for the Sub oscillator, "External clock mode" must be selected and X0A/P04_0 pin must be driven. X1A/P04_1 pin can be configured as GPIO.

13.3.3 Opposite phase external clock

When using an opposite phase external clock, X1 (X1A) pins must be supplied with a clock signal which has the opposite phase to the X0 (X0A) pins. Supply level on X0 and X1 pins must be 1.8V.



13.4 Notes on PLL clock mode operation

If the microcontroller is operated with PLL clock mode and no external oscillator is operating or no external clock is supplied, the microcontroller attempts to work with the free oscillating PLL. Performance of this operation, however, cannot be guaranteed.

13.5 Power supply pins (V_{CC}/V_{SS})

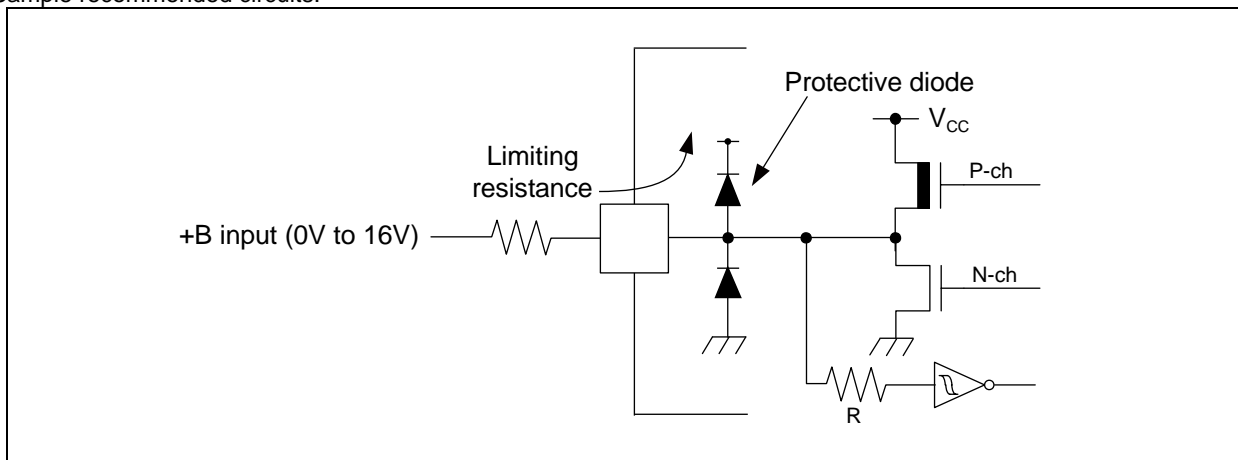
It is required that all V_{CC}-level as well as all V_{SS}-level power supply pins are at the same potential. If there is more than one V_{CC} or V_{SS} level, the device may operate incorrectly or be damaged even within the guaranteed operating range.

V_{CC} and V_{SS} pins must be connected to the device from the power supply with lowest possible impedance.

The smoothing capacitor at V_{CC} pin must use the one of a capacity value that is larger than C_s.

Besides this, as a measure against power supply noise, it is required to connect a bypass capacitor of about 0.1μF between V_{CC} and V_{SS} pins as close as possible to V_{CC} and V_{SS} pins.

- ^{*1}: This parameter is based on $V_{SS} = AV_{SS} = DV_{SS} = 0V$.
- ^{*2}: AV_{CC} and V_{CC} and DV_{CC} must be set to the same voltage. It is required that AV_{CC} does not exceed V_{CC} , DV_{CC} and that the voltage at the analog inputs does not exceed AV_{CC} when the power is switched on.
- ^{*3}: V_I and V_O should not exceed $V_{CC} + 0.3V$. V_I should also not exceed the specified ratings. However if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supersedes the V_I rating. Input/Output voltages of high current ports depend on DV_{CC} . Input/Output voltages of standard ports depend on V_{CC} .
- ^{*4}: Applicable to all general purpose I/O pins (Pnn_m).
- Use within recommended operating conditions.
 - Use at DC voltage (current).
 - The +B signal should always be applied a limiting resistance placed between the +B signal and the microcontroller.
 - The value of the limiting resistance should be set so that when the +B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
 - Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.
 - Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0V), the power supply is provided from the pins, so that incomplete operation may result.
 - Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the Power reset.
 - The DEBUG I/F pin has only a protective diode against V_{SS} . Hence it is only permitted to input a negative clamping current (4mA). For protection against positive input voltages, use an external clamping diode which limits the input voltage to maximum 6.0V.
 - Sample recommended circuits:



- ^{*5}: The maximum permitted power dissipation depends on the ambient temperature, the air flow velocity and the thermal conductance of the package on the PCB.
The actual power dissipation depends on the customer application and can be calculated as follows:

$$P_D = P_{IO} + P_{INT}$$

$$P_{IO} = \sum (V_{OL} \times I_{OL} + V_{OH} \times I_{OH})$$
 (I/O load power dissipation, sum is performed on all I/O ports)

$$P_{INT} = V_{CC} \times (I_{CC} + I_A)$$
 (internal power dissipation)
 I_{CC} is the total core current consumption into V_{CC} as described in the "DC characteristics" and depends on the selected operation mode and clock frequency and the usage of functions like Flash programming.
 I_A is the analog current consumption into AV_{CC} .
- ^{*6}: Worst case value for a package mounted on single layer PCB at specified T_A without air flow.

WARNING

Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

14.4.3 Built-in RC Oscillation Characteristics
 $(V_{CC} = AV_{CC} = DV_{CC} = 2.7V \text{ to } 5.5V, V_{SS} = AV_{SS} = DV_{SS} = 0V, T_A = -40^{\circ}C \text{ to } +105^{\circ}C)$

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Clock frequency	f_{RC}	50	100	200	kHz	When using slow frequency of RC oscillator
		1	2	4	MHz	When using fast frequency of RC oscillator
RC clock stabilization time	t_{RCSTAB}	80	160	320	μs	When using slow frequency of RC oscillator (16 RC clock cycles)
		64	128	256	μs	When using fast frequency of RC oscillator (256 RC clock cycles)

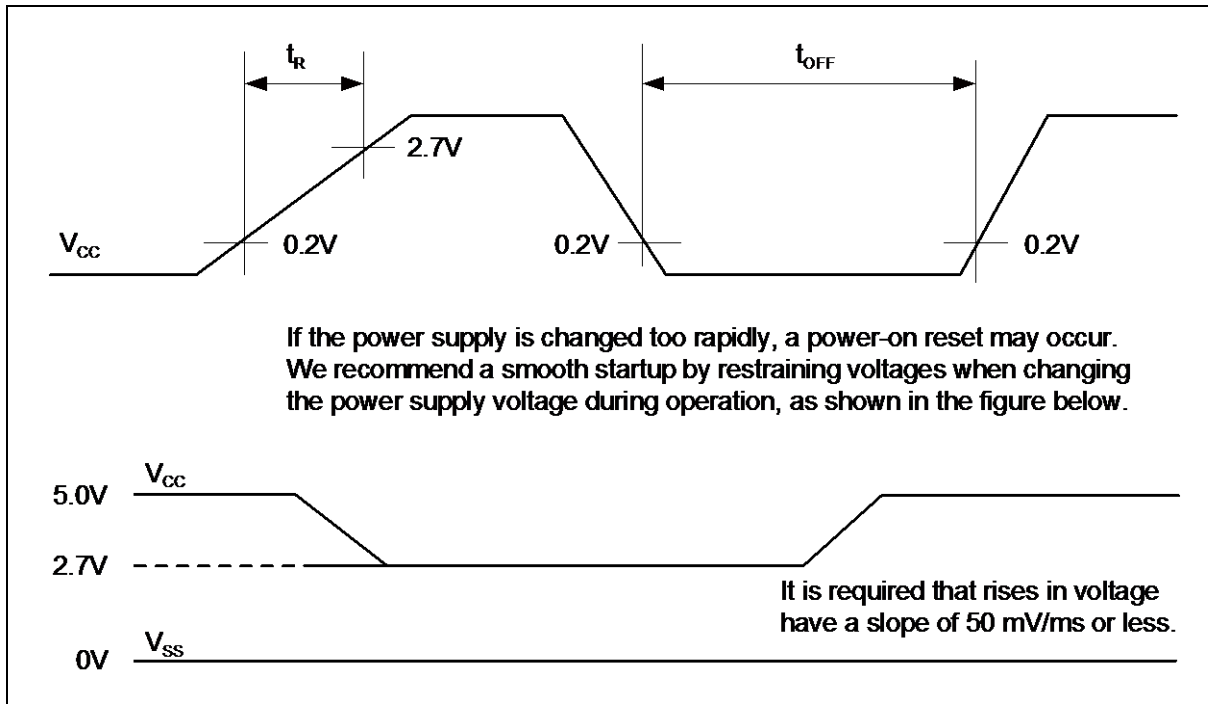
14.4.4 Internal Clock Timing
 $(V_{CC} = AV_{CC} = DV_{CC} = 2.7V \text{ to } 5.5V, V_{SS} = AV_{SS} = DV_{SS} = 0V, T_A = -40^{\circ}C \text{ to } +105^{\circ}C)$

Parameter	Symbol	Value		Unit
		Min	Max	
Internal System clock frequency (CLKS1 and CLKS2)	f_{CLKS1}, f_{CLKS2}	-	54	MHz
Internal CPU clock frequency (CLKB), Internal peripheral clock frequency (CLKP1)	f_{CLKB}, f_{CLKP1}	-	32	MHz
Internal peripheral clock frequency (CLKP2)	f_{CLKP2}	-	32	MHz

14.4.7 Power-on Reset Timing

($V_{CC} = AV_{CC} = DV_{CC} = 2.7V$ to $5.5V$, $V_{SS} = AV_{SS} = DV_{SS} = 0V$, $T_A = -40^{\circ}C$ to $+105^{\circ}C$)

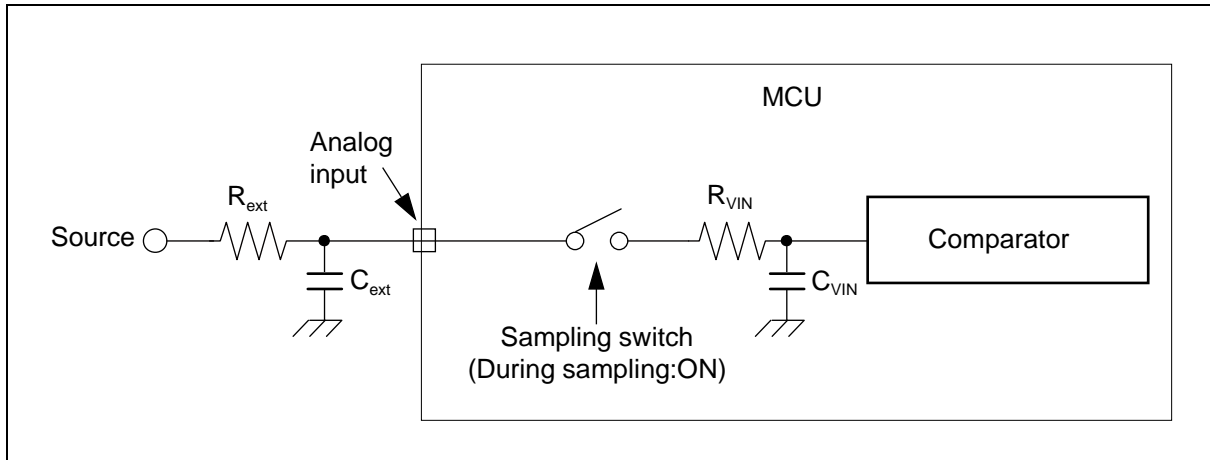
Parameter	Symbol	Pin name	Value			Unit
			Min	Typ	Max	
Power on rise time	t_R	Vcc	0.05	-	30	ms
Power off time	t_{OFF}	Vcc	1	-	-	ms



14.5.2 Accuracy and Setting of the A/D Converter Sampling Time

If the external impedance is too high or the sampling time too short, the analog voltage charged to the internal sample and hold capacitor is insufficient, adversely affecting the A/D conversion precision.

To satisfy the A/D conversion precision, a sufficient sampling time must be selected. The required sampling time (T_{samp}) depends on the external driving impedance R_{ext} , the board capacitance of the A/D converter input pin C_{ext} and the AV_{CC} voltage level. The following replacement model can be used for the calculation:



R_{ext} : External driving impedance

C_{ext} : Capacitance of PCB at A/D converter input

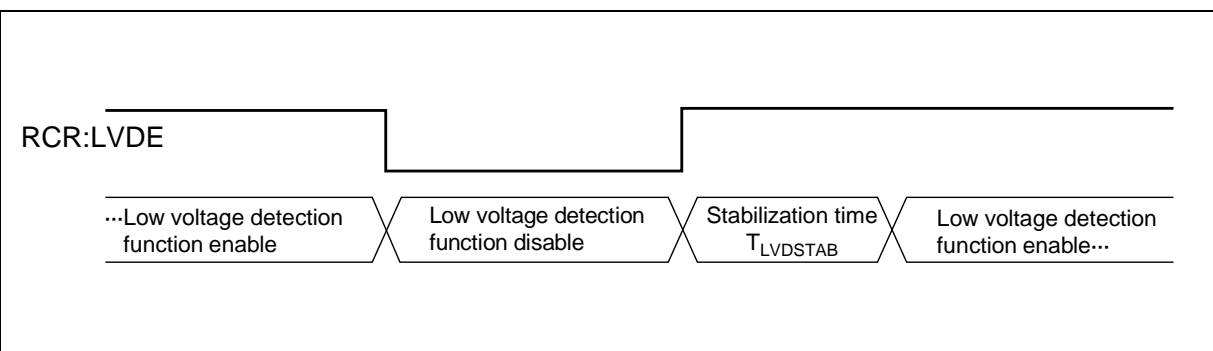
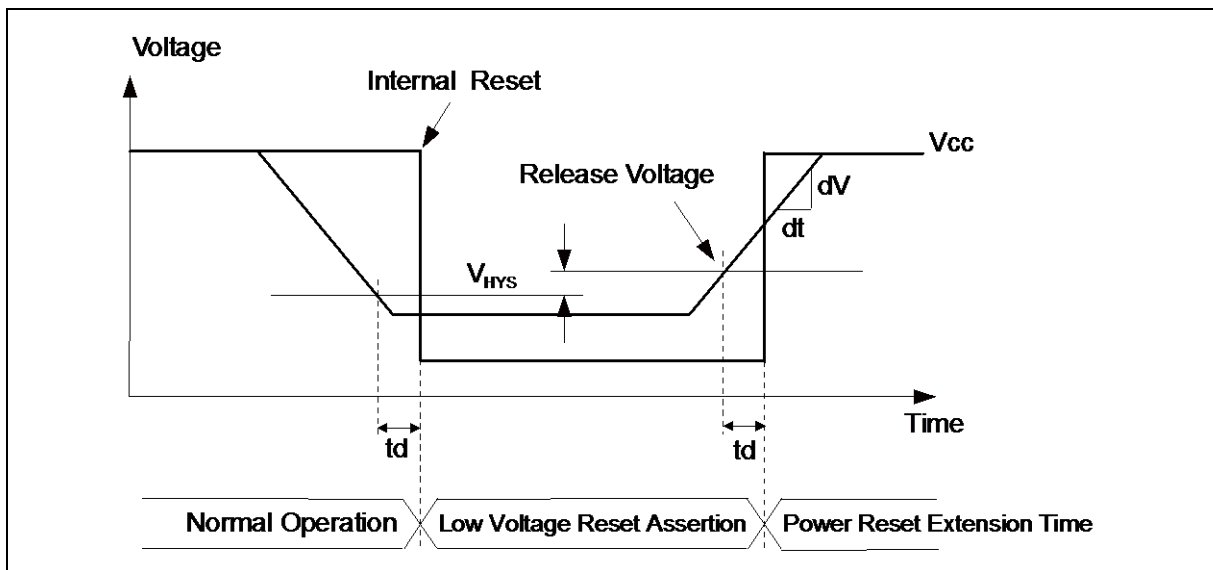
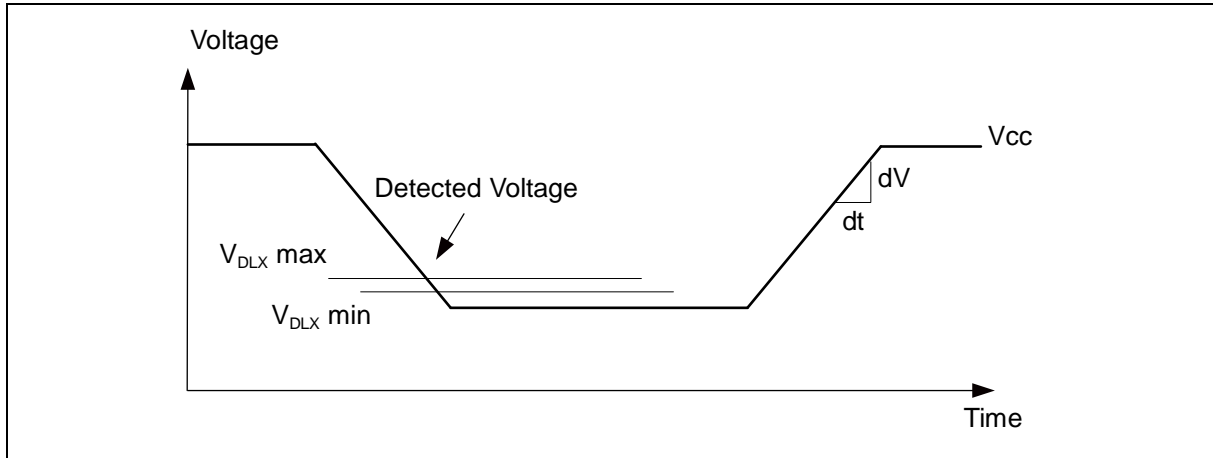
C_{VIN} : Analog input capacity (I/O, analog switch and ADC are contained)

R_{VIN} : Analog input impedance (I/O, analog switch and ADC are contained)

The following approximation formula for the replacement model above can be used:

$$T_{\text{samp}} = 7.62 \times (R_{\text{ext}} \times C_{\text{ext}} + (R_{\text{ext}} + R_{\text{VIN}}) \times C_{\text{VIN}})$$

- Do not select a sampling time below the absolute minimum permitted value.
($0.5\mu\text{s}$ for $4.5\text{V} \leq AV_{\text{CC}} \leq 5.5\text{V}$, $1.2\mu\text{s}$ for $2.7\text{V} \leq AV_{\text{CC}} < 4.5\text{V}$)
- If the sampling time cannot be sufficient, connect a capacitor of about $0.1\mu\text{F}$ to the analog input pin.
- A big external driving impedance also adversely affects the A/D conversion precision due to the pin input leakage current I_{IL} (static current before the sampling switch) or the analog input leakage current I_{AIN} (total leakage current of pin input and comparator during sampling). The effect of the pin input leakage current I_{IL} cannot be compensated by an external capacitor.
- The accuracy gets worse as $|AV_{\text{RH}} - AV_{\text{SS}}|$ becomes smaller.



16. Ordering Information

MCU with CAN controller

Part number	Flash memory	Package*
MB96F673RBPMC-GSE1	Flash A (96.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F673RBPMC-GSE2		
MB96F673RBPMC1-GSE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F673RBPMC1-GSE2		
MB96F675RBPMC-GSE1	Flash A (160.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F675RBPMC-GSE2		
MB96F675RBPMC1-GSE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F675RBPMC1-GSE2		

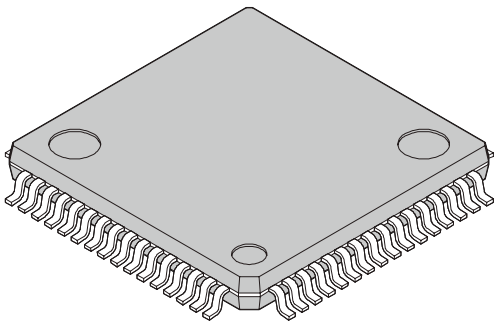
*: For details about package, see "■ PACKAGE DIMENSION".

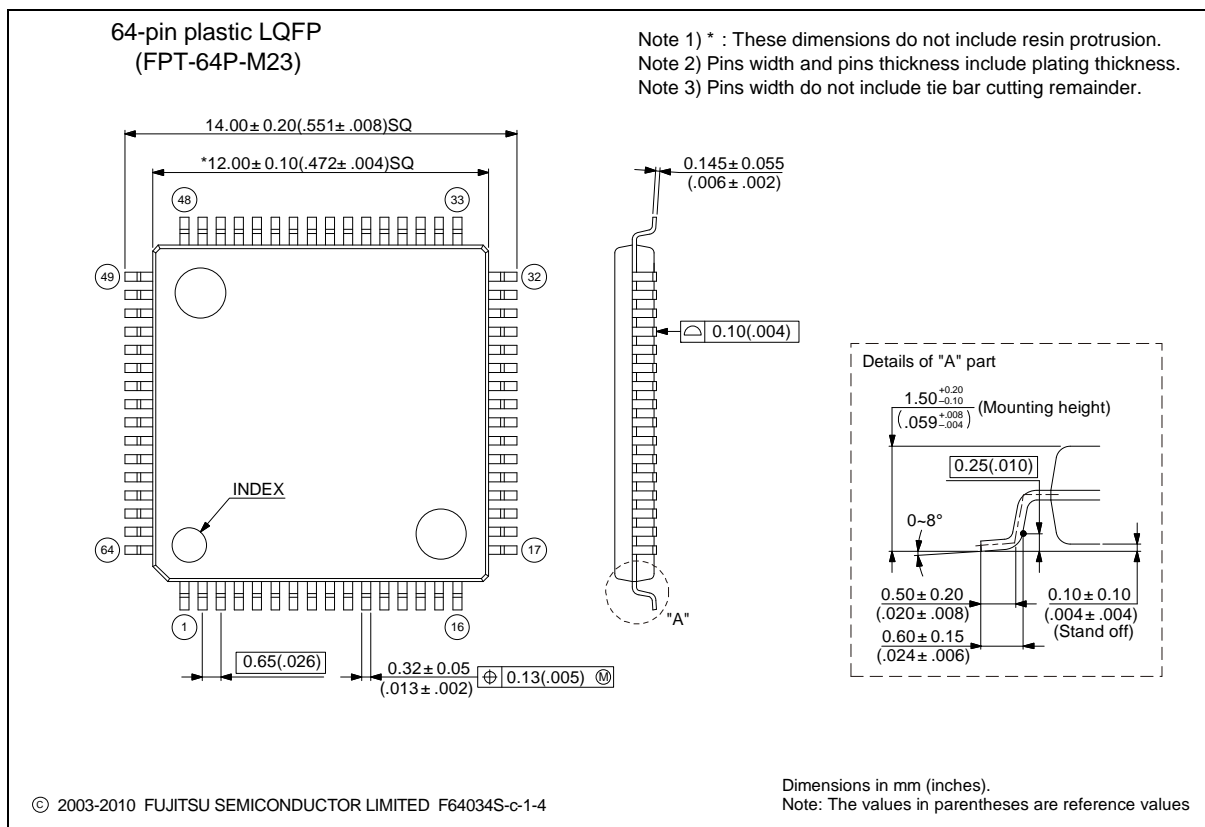
MCU without CAN controller

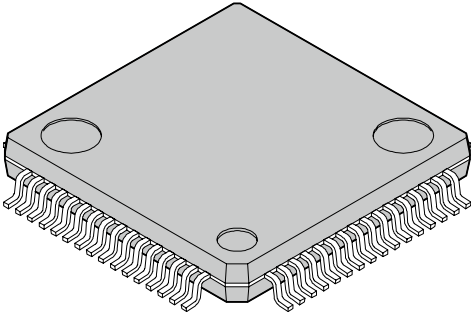
Part number	Flash memory	Package*
MB96F673ABPMC-GSE1	Flash A (96.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F673ABPMC-GSE2		
MB96F673ABPMC1-GSE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F673ABPMC1-GSE2		
MB96F675ABPMC-GSE1	Flash A (160.5KB)	64-pin plastic LQFP (FPT-64P-M23)
MB96F675ABPMC-GSE2		
MB96F675ABPMC1-GSE1		64-pin plastic LQFP (FPT-64P-M24)
MB96F675ABPMC1-GSE2		

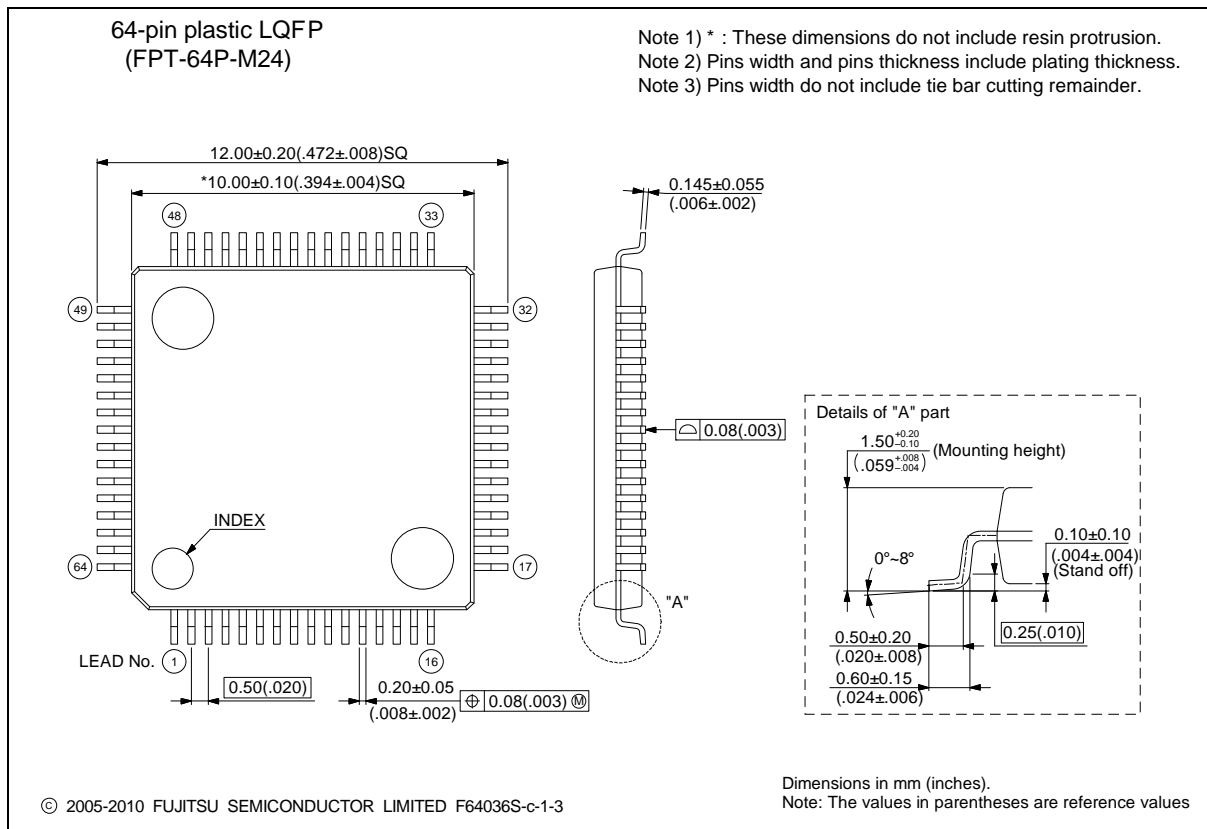
*: For details about package, see "■ PACKAGE DIMENSION".

17. Package Dimension

 <p>64-pin plastic LQFP</p> <p>(FPT-64P-M23)</p>	Lead pitch	0.65 mm
	Package width × package length	12.0 × 12.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Weight	0.47 g
	Code (Reference)	P-LQFP64-12 × 12-0.65



<p>64-pin plastic LQFP</p>  <p>(FPT-64P-M24)</p>	Lead pitch	0.50 mm
	Package width x package length	10.0 x 10.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Weight	0.32 g
	Code (Reference)	P-LFQFP64-10x10-0.50



18. Major Changes

Spanion Publication Number: MB96670_DS704-00001

Page	Section	Change Results
Revision 2.0		
4	FEATURES	<p>Changed the description of “LCD Controller” On-chip drivers for internal divider resistors or external divider resistors → Internal divider resistors or external divider resistors</p> <p>Changed the description of “External Interrupts” Interrupt mask and pending bit per channel → Interrupt mask bit per channel</p>
9	PIN DESCRIPTION	Deleted Pin name WOT
27 to 30	HANDLING PRECAUTIONS	Added a section
33	HANDLING DEVICES	<p>Changed the description in “11. SMC power supply pins” To avoid this, VCC must always be powered on before DVCC. → To avoid this, VCC must always be powered on before DVCC. DVcc/DVss must be applied when using SMC I/O pin as GPIO.</p>
35	ELECTRICAL CHARACTERISTICS 1. Absolute Maximum Ratings	<p>Changed the annotation *2 It is required that AVCC does not exceed VCC and that the voltage at the analog inputs does not exceed AVCC when the power is switched on. → It is required that AVCC does not exceed VCC, DVCC and that the voltage at the analog inputs does not exceed AVCC when the power is switched on.</p>
39	3. DC Characteristics (1) Current Rating	<p>Changed the Conditions for ICCSRCH CLKS1/2 = CLKB = CLKP1/2 = CLKRC = 2MHz, → CLKS1/2 = CLKP1/2 = CLKRC = 2MHz,</p> <p>Changed the Conditions for ICCSRCL CLKS1/2 = CLKB = CLKP1/2 = CLKRC = 100kHz → CLKS1/2 = CLKP1/2 = CLKRC = 100kHz</p> <p>Changed the Conditions for ICCTPLL PLL Timer mode with CLKP1 = 32MHz → PLL Timer mode with CLKPLL = 32MHz</p> <p>Changed the Value of “Power supply current in Timer modes” ICCTPLL Typ: 2480μA → 1800μA (TA = +25°C) Max: 2710μA → 2245μA (TA = +25°C) Max: 3955μA → 3140μA (TA = +105°C)</p> <p>Changed the Conditions for ICCTRCL RC Timer mode with CLKRC = 100kHz, SMCR:LPMSS = 0 (CLKPLL, CLKMC and CLKSC stopped) → RC Timer mode with CLKRC = 100kHz (CLKPLL, CLKMC and CLKSC stopped)</p>