



Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

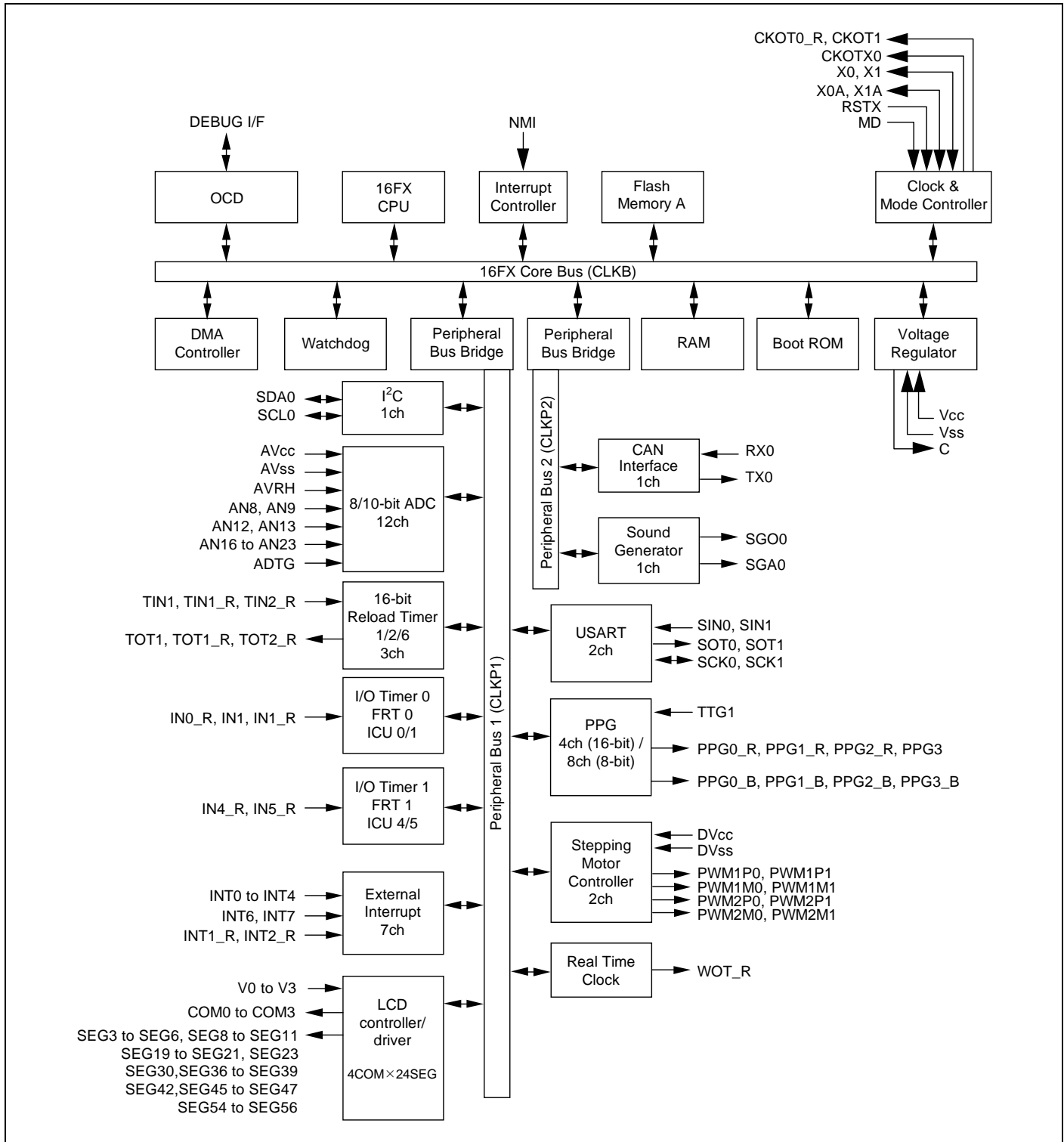
Details

Product Status	Obsolete
Core Processor	F ² MC-16FX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, I ² C, LINbus, SCI, UART/USART
Peripherals	DMA, LCD, LVD, POR, PWM, WDT
Number of I/O	50
Program Memory Size	96KB (96K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 12x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb96f673rbpmc1-gse1

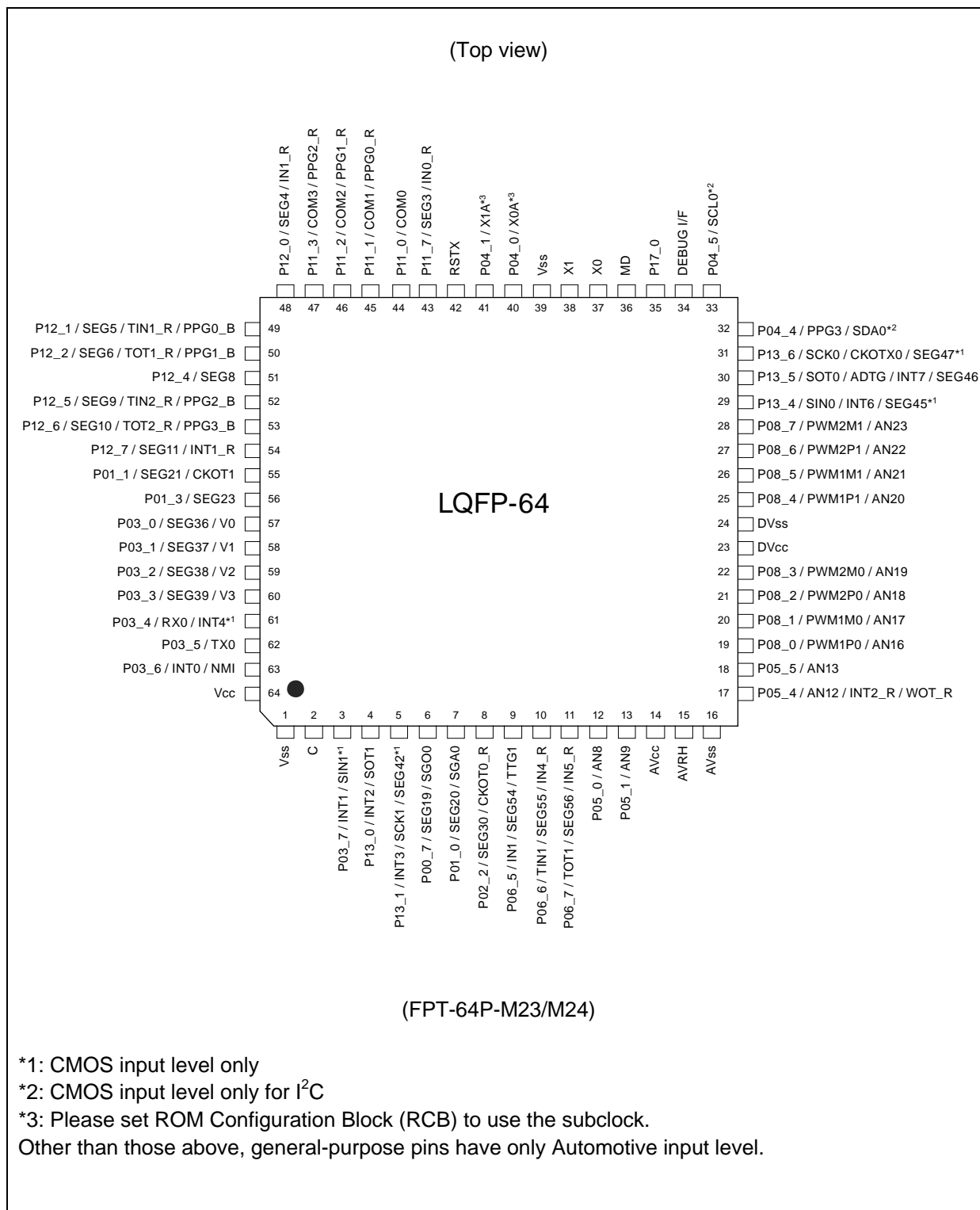
Contents

1. Product Lineup	6
2. Block Diagram	7
3. Pin Assignment	8
4. Pin Description	9
5. Pin Circuit Type	11
6. I/O Circuit Type	13
7. Memory Map	19
8. RAMSTART Addresses	20
9. User ROM Memory Map For Flash Devices	21
10. Serial Programming Communication Interface	22
11. Interrupt Vector Table	23
12. Handling Precautions	27
12.1 Precautions for Product Design	27
12.2 Precautions for Package Mounting	28
12.3 Precautions for Use Environment	29
13. Handling Devices	30
13.1 Latch-up prevention	30
13.2 Unused pins handling	30
13.3 External clock usage	31
13.3.1 Single phase external clock for Main oscillator	31
13.3.2 Single phase external clock for Sub oscillator	31
13.3.3 Opposite phase external clock	31
13.4 Notes on PLL clock mode operation	31
13.5 Power supply pins (Vcc/Vss)	31
13.6 Crystal oscillator and ceramic resonator circuit	32
13.7 Turn on sequence of power supply to A/D converter and analog inputs	32
13.8 Pin handling when not using the A/D converter	32
13.9 Notes on Power-on	32
13.10 Stabilization of power supply voltage	32
13.11 SMC power supply pins	32
13.12 Serial communication	32
13.13 Mode Pin (MD)	32
14. Electrical Characteristics	33
14.1 Absolute Maximum Ratings	33
14.2 Recommended Operating Conditions	35
14.3 DC Characteristics	36
14.3.1 Current Rating	36
14.3.2 Pin Characteristics	39
14.4 AC Characteristics	42
14.4.1 Main Clock Input Characteristics	42
14.4.2 Sub Clock Input Characteristics	43
14.4.3 Built-in RC Oscillation Characteristics	44
14.4.4 Internal Clock Timing	44
14.4.5 Operating Conditions of PLL	45
14.4.6 Reset Input	45
14.4.7 Power-on Reset Timing	46

2. Block Diagram

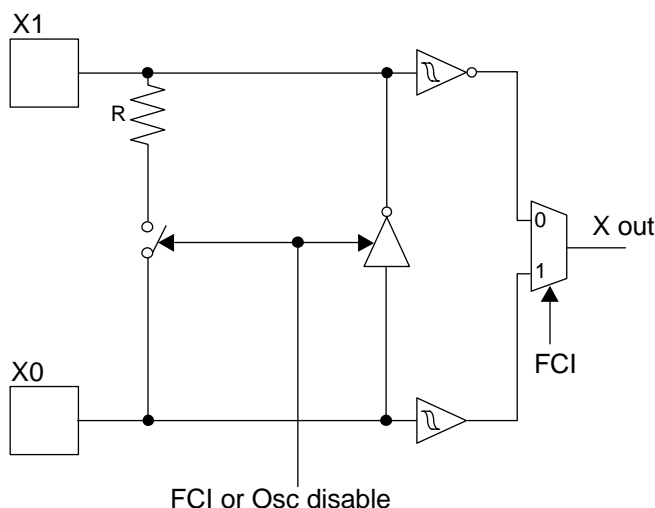


3. Pin Assignment



Pin name	Feature	Description
Vn	LCD	LCD voltage reference pin
Vcc	Supply	Power supply pin
Vss	Supply	Power supply pin
WOT_R	RTC	Relocated Real Time clock output pin
X0	Clock	Oscillator input pin
X0A	Clock	Subclock Oscillator input pin
X1	Clock	Oscillator output pin
X1A	Clock	Subclock Oscillator output pin

6. I/O Circuit Type

Type	Circuit	Remarks
A	 <p>FCI or Osc disable</p>	<p>High-speed oscillation circuit:</p> <ul style="list-style-type: none"> • Programmable between oscillation mode (external crystal or resonator connected to X0/X1 pins) and Fast external Clock Input (FCI) mode (external clock connected to X0 pin) • Feedback resistor = approx. 1.0MΩ • The amplitude: 1.8V±0.15V to operate by the internal supply voltage

8. RAMSTART Addresses

Devices	Bank 0 RAM size	RAMSTART0
MB96F673 MB96F675	4KB	00:7200 _H

11. Interrupt Vector Table

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
0	3FC _H	CALLV0	No	-	CALLV instruction
1	3F8 _H	CALLV1	No	-	CALLV instruction
2	3F4 _H	CALLV2	No	-	CALLV instruction
3	3F0 _H	CALLV3	No	-	CALLV instruction
4	3EC _H	CALLV4	No	-	CALLV instruction
5	3E8 _H	CALLV5	No	-	CALLV instruction
6	3E4 _H	CALLV6	No	-	CALLV instruction
7	3E0 _H	CALLV7	No	-	CALLV instruction
8	3DC _H	RESET	No	-	Reset vector
9	3D8 _H	INT9	No	-	INT9 instruction
10	3D4 _H	EXCEPTION	No	-	Undefined instruction execution
11	3D0 _H	NMI	No	-	Non-Maskable Interrupt
12	3CC _H	DLY	No	12	Delayed Interrupt
13	3C8 _H	RC_TIMER	No	13	RC Clock Timer
14	3C4 _H	MC_TIMER	No	14	Main Clock Timer
15	3C0 _H	SC_TIMER	No	15	Sub Clock Timer
16	3BC _H	LVDI	No	16	Low Voltage Detector
17	3B8 _H	EXTINT0	Yes	17	External Interrupt 0
18	3B4 _H	EXTINT1	Yes	18	External Interrupt 1
19	3B0 _H	EXTINT2	Yes	19	External Interrupt 2
20	3AC _H	EXTINT3	Yes	20	External Interrupt 3
21	3A8 _H	EXTINT4	Yes	21	External Interrupt 4
22	3A4 _H	-	-	22	Reserved
23	3A0 _H	EXTINT6	Yes	23	External Interrupt 6
24	39C _H	EXTINT7	Yes	24	External Interrupt 7
25	398 _H	-	-	25	Reserved
26	394 _H	-	-	26	Reserved
27	390 _H	-	-	27	Reserved
28	38C _H	-	-	28	Reserved
29	388 _H	-	-	29	Reserved
30	384 _H	-	-	30	Reserved
31	380 _H	-	-	31	Reserved
32	37C _H	-	-	32	Reserved
33	378 _H	CAN0	No	33	CAN Controller 0
34	374 _H	-	-	34	Reserved
35	370 _H	-	-	35	Reserved
36	36C _H	-	-	36	Reserved
37	368 _H	-	-	37	Reserved
38	364 _H	PPG0	Yes	38	Programmable Pulse Generator 0
39	360 _H	PPG1	Yes	39	Programmable Pulse Generator 1

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
81	2B8 _H	-	-	81	Reserved
82	2B4 _H	-	-	82	Reserved
83	2B0 _H	-	-	83	Reserved
84	2AC _H	-	-	84	Reserved
85	2A8 _H	-	-	85	Reserved
86	2A4 _H	-	-	86	Reserved
87	2A0 _H	-	-	87	Reserved
88	29C _H	-	-	88	Reserved
89	298 _H	FRT0	Yes	89	Free-Running Timer 0
90	294 _H	FRT1	Yes	90	Free-Running Timer 1
91	290 _H	-	-	91	Reserved
92	28C _H	-	-	92	Reserved
93	288 _H	RTC0	No	93	Real Time Clock
94	284 _H	CAL0	No	94	Clock Calibration Unit
95	280 _H	SG0	No	95	Sound Generator 0
96	27C _H	IIC0	Yes	96	I ² C interface 0
97	278 _H	-	-	97	Reserved
98	274 _H	ADC0	Yes	98	A/D Converter 0
99	270 _H	-	-	99	Reserved
100	26C _H	-	-	100	Reserved
101	268 _H	LINR0	Yes	101	LIN USART 0 RX
102	264 _H	LINT0	Yes	102	LIN USART 0 TX
103	260 _H	LINR1	Yes	103	LIN USART 1 RX
104	25C _H	LINT1	Yes	104	LIN USART 1 TX
105	258 _H	-	-	105	Reserved
106	254 _H	-	-	106	Reserved
107	250 _H	-	-	107	Reserved
108	24C _H	-	-	108	Reserved
109	248 _H	-	-	109	Reserved
110	244 _H	-	-	110	Reserved
111	240 _H	-	-	111	Reserved
112	23C _H	-	-	112	Reserved
113	238 _H	-	-	113	Reserved
114	234 _H	-	-	114	Reserved
115	230 _H	-	-	115	Reserved
116	22C _H	-	-	116	Reserved
117	228 _H	-	-	117	Reserved
118	224 _H	-	-	118	Reserved
119	220 _H	-	-	119	Reserved
120	21C _H	-	-	120	Reserved

12. Handling Precautions

Any semiconductor devices have inherently a certain rate of failure. The possibility of failure is greatly affected by the conditions in which they are used (circuit conditions, environmental conditions, etc.). This page describes precautions that must be observed to minimize the chance of failure and to obtain higher reliability from your Cypress semiconductor devices.

12.1 Precautions for Product Design

This section describes precautions when designing electronic equipment using semiconductor devices.

■ Absolute Maximum Ratings

Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of certain established limits, called absolute maximum ratings. Do not exceed these ratings.

■ Recommended Operating Conditions

Recommended operating conditions are normal operating ranges for the semiconductor device. All the device's electrical characteristics are warranted when operated within these ranges.

Always use semiconductor devices within the recommended operating conditions. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their sales representative beforehand.

■ Processing and Protection of Pins

These precautions must be followed when handling the pins which connect semiconductor devices to power supply and input/output functions.

1. Preventing Over-Voltage and Over-Current Conditions

Exposure to voltage or current levels in excess of maximum ratings at any pin is likely to cause deterioration within the device, and in extreme cases leads to permanent damage of the device. Try to prevent such overvoltage or over-current conditions at the design stage.

2. Protection of Output Pins

Shorting of output pins to supply pins or other output pins, or connection to large capacitance can cause large current flows. Such conditions if present for extended periods of time can damage the device. Therefore, avoid this type of connection.

3. Handling of Unused Input Pins

Unconnected input pins with very high impedance levels can adversely affect stability of operation. Such pins should be connected through an appropriate resistance to a power supply pin or ground pin.

■ Latch-up

Semiconductor devices are constructed by the formation of P-type and N-type areas on a substrate. When subjected to abnormally high voltages, internal parasitic PNP junctions (called thyristor structures) may be formed, causing large current levels in excess of several hundred mA to flow continuously at the power supply pin. This condition is called latch-up.

CAUTION: The occurrence of latch-up not only causes loss of reliability in the semiconductor device, but can cause injury or damage from high heat, smoke or flame. To prevent this from happening, do the following:

1. Be sure that voltages applied to pins do not exceed the absolute maximum ratings. This should include attention to abnormal noise, surge levels, etc.
2. Be sure that abnormal current flows do not occur during the power-on sequence.

■ Observance of Safety Regulations and Standards

Most countries in the world have established standards and regulations regarding safety, protection from electromagnetic interference, etc. Customers are requested to observe applicable regulations and standards in the design of products.

■ Fail-Safe Design

Any semiconductor devices have inherently a certain rate of failure. You must protect against injury, damage or loss from such failures by incorporating safety design measures into your facility and equipment such as redundancy, fire protection, and prevention of over-current levels and other abnormal operating conditions.

■ Static Electricity

Because semiconductor devices are particularly susceptible to damage by static electricity, you must take the following precautions:

1. Maintain relative humidity in the working environment between 40% and 70%. Use of an apparatus for ion generation may be needed to remove electricity.
2. Electrically ground all conveyors, solder vessels, soldering irons and peripheral equipment.
3. Eliminate static body electricity by the use of rings or bracelets connected to ground through high resistance (on the level of 1 MΩ).
Wearing of conductive clothing and shoes, use of conductive floor mats and other measures to minimize shock loads is recommended.
4. Ground all fixtures and instruments, or protect with anti-static measures.
5. Avoid the use of styrofoam or other highly static-prone materials for storage of completed board assemblies.

12.3 Precautions for Use Environment

Reliability of semiconductor devices depends on ambient temperature and other conditions as described above.

For reliable performance, do the following:

1. Humidity
Prolonged use in high humidity can lead to leakage in devices as well as printed circuit boards. If high humidity levels are anticipated, consider anti-humidity processing.
2. Discharge of Static Electricity
When high-voltage charges exist close to semiconductor devices, discharges can cause abnormal operation. In such cases, use anti-static measures or processing to prevent discharges.
3. Corrosive Gases, Dust, or Oil
Exposure to corrosive gases or contact with dust or oil may lead to chemical reactions that will adversely affect the device. If you use devices in such conditions, consider ways to prevent such exposure or to protect the devices.
4. Radiation, Including Cosmic Radiation
Most devices are not designed for environments involving exposure to radiation or cosmic radiation. Users should provide shielding as appropriate.
5. Smoke, Flame
CAUTION: Plastic molded devices are flammable, and therefore should not be used near combustible substances. If devices begin to smoke or burn, there is danger of the release of toxic gases.

Customers considering the use of Cypress products in other special environmental conditions should consult with sales representatives.

13. Handling Devices

Special care is required for the following when handling the device:

- Latch-up prevention
- Unused pins handling
- External clock usage
- Notes on PLL clock mode operation
- Power supply pins (V_{CC}/V_{SS})
- Crystal oscillator and ceramic resonator circuit
- Turn on sequence of power supply to A/D converter and analog inputs
- Pin handling when not using the A/D converter
- Notes on Power-on
- Stabilization of power supply voltage
- SMC power supply pins
- Serial communication
- Mode Pin (MD)

13.1 Latch-up prevention

CMOS IC chips may suffer latch-up under the following conditions:

- A voltage higher than V_{CC} or lower than V_{SS} is applied to an input or output pin.
- A voltage higher than the rated voltage is applied between V_{CC} pins and V_{SS} pins.
- The AV_{CC} power supply is applied before the V_{CC} voltage.

Latch-up may increase the power supply current dramatically, causing thermal damages to the device.

For the same reason, extra care is required to not let the analog power-supply voltage (AV_{CC} , AV_{RH}) exceed the digital power-supply voltage.

13.2 Unused pins handling

Unused input pins can be left open when the input is disabled (corresponding bit of Port Input Enable register $PIER = 0$).

Leaving unused input pins open when the input is enabled may result in misbehavior and possible permanent damage of the device. To prevent latch-up, they must therefore be pulled up or pulled down through resistors which should be more than $2k\Omega$.

Unused bidirectional pins can be set either to the output state and be then left open, or to the input state with either input disabled or external pull-up/pull-down resistor as described above.

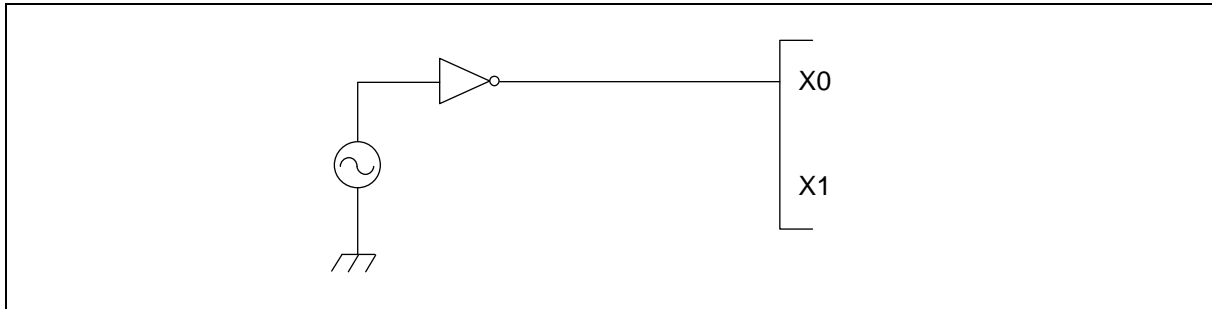
13.3 External clock usage

The permitted frequency range of an external clock depends on the oscillator type and configuration.

See AC Characteristics for detailed modes and frequency limits. Single and opposite phase external clocks must be connected as follows:

13.3.1 Single phase external clock for Main oscillator

When using a single phase external clock for the Main oscillator, X0 pin must be driven and X1 pin left open. And supply 1.8V power to the external clock.

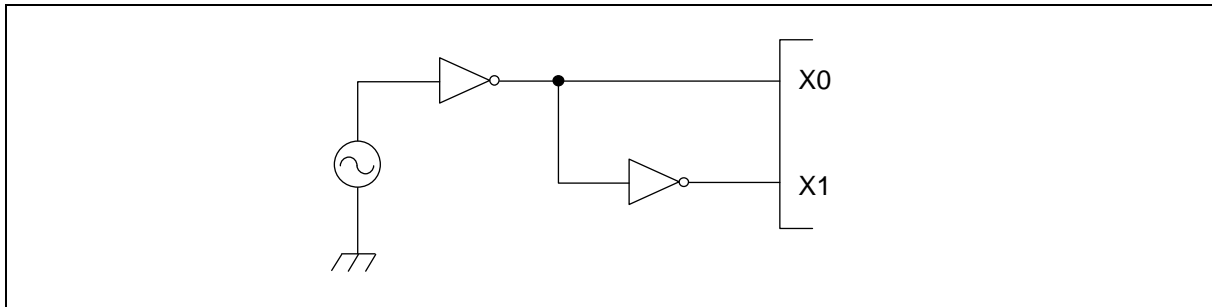


13.3.2 Single phase external clock for Sub oscillator

When using a single phase external clock for the Sub oscillator, "External clock mode" must be selected and X0A/P04_0 pin must be driven. X1A/P04_1 pin can be configured as GPIO.

13.3.3 Opposite phase external clock

When using an opposite phase external clock, X1 (X1A) pins must be supplied with a clock signal which has the opposite phase to the X0 (X0A) pins. Supply level on X0 and X1 pins must be 1.8V.



13.4 Notes on PLL clock mode operation

If the microcontroller is operated with PLL clock mode and no external oscillator is operating or no external clock is supplied, the microcontroller attempts to work with the free oscillating PLL. Performance of this operation, however, cannot be guaranteed.

13.5 Power supply pins (V_{CC}/V_{SS})

It is required that all V_{CC}-level as well as all V_{SS}-level power supply pins are at the same potential. If there is more than one V_{CC} or V_{SS} level, the device may operate incorrectly or be damaged even within the guaranteed operating range.

V_{CC} and V_{SS} pins must be connected to the device from the power supply with lowest possible impedance.

The smoothing capacitor at V_{CC} pin must use the one of a capacity value that is larger than C_s.

Besides this, as a measure against power supply noise, it is required to connect a bypass capacitor of about 0.1μF between V_{CC} and V_{SS} pins as close as possible to V_{CC} and V_{SS} pins.

14. Electrical Characteristics

14.1 Absolute Maximum Ratings

Parameter	Symbol	Condition	Rating		Unit	Remarks
			Min	Max		
Power supply voltage* ¹	V _{CC}	-	V _{SS} - 0.3	V _{SS} + 6.0	V	
Analog power supply voltage* ¹	AV _{CC}	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _{CC} = AV _{CC} * ²
Analog reference voltage* ¹	AVRH	-	V _{SS} - 0.3	V _{SS} + 6.0	V	AV _{CC} ≥ AVRH, AVRH ≥ AV _{SS}
SMC Power supply* ¹	DV _{CC}	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _{CC} = AV _{CC} = DV _{CC} * ²
LCD power supply voltage* ¹	V0 to V3	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V0 to V3 must not exceed V _{CC}
Input voltage* ¹	V _I	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _I ≤ (D)V _{CC} + 0.3V* ³
Output voltage* ¹	V _O	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _O ≤ (D)V _{CC} + 0.3V* ³
Maximum Clamp Current	I _{CLAMP}	-	-4.0	+4.0	mA	Applicable to general purpose I/O pins * ⁴
Total Maximum Clamp Current	Σ I _{CLAMP}	-	-	16	mA	Applicable to general purpose I/O pins * ⁴
"L" level maximum output current	I _{OL}	-	-	15	mA	Normal port
	I _{OLSMC}	T _A = -40°C	-	52	mA	High current port
		T _A = +25°C	-	39	mA	
		T _A = +85°C	-	32	mA	
		T _A = +105°C	-	30	mA	
"L" level average output current	I _{OLAV}	-	-	4	mA	Normal port
	I _{OLAVSMC}	T _A = -40°C	-	40	mA	High current port
		T _A = +25°C	-	30	mA	
		T _A = +85°C	-	25	mA	
		T _A = +105°C	-	23	mA	
"L" level maximum overall output current	ΣI _{OL}	-	-	34	mA	Normal port
	ΣI _{OLSMC}	-	-	180	mA	High current port
"L" level average overall output current	ΣI _{OLAV}	-	-	17	mA	Normal port
	ΣI _{OLAVSMC}	-	-	90	mA	High current port
"H" level maximum output current	I _{OH}	-	-	-15	mA	Normal port
	I _{OHSMC}	T _A = -40°C	-	-52	mA	High current port
		T _A = +25°C	-	-39	mA	
		T _A = +85°C	-	-32	mA	
		T _A = +105°C	-	-30	mA	
"H" level average output current	I _{OHAV}	-	-	-4	mA	Normal port
	I _{OHAVSMC}	T _A = -40°C	-	-40	mA	High current port
		T _A = +25°C	-	-30	mA	
		T _A = +85°C	-	-25	mA	
		T _A = +105°C	-	-23	mA	
"H" level maximum overall output current	ΣI _{OH}	-	-	-34	mA	Normal port
	ΣI _{OHSMC}	-	-	-180	mA	High current port
"H" level average overall output current	ΣI _{OHAV}	-	-	-17	mA	Normal port
	ΣI _{OHAVSMC}	-	-	-90	mA	High current port
Power consumption* ⁵	P _D	T _A = +105°C	-	281* ⁶	mW	
Operating ambient temperature	T _A	-	-40	+105	°C	
Storage temperature	T _{STG}	-	-55	+150	°C	

14.3 DC Characteristics

14.3.1 Current Rating

($V_{CC} = AV_{CC} = DV_{CC} = 2.7V$ to $5.5V$, $V_{SS} = AV_{SS} = DV_{SS} = 0V$, $T_A = -40^{\circ}C$ to $+105^{\circ}C$)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current in Run modes ^{*1}	I _{CCPLL}	V _{CC}	PLL Run mode with CLKS1/2 = CLKB = CLKP1/2 = 32MHz	-	25	-	mA	T _A = +25°C
			Flash 0 wait					
	(CLKRC and CLKSC stopped)		-	-	34	mA	T _A = +105°C	
	I _{CCMAIN}		Main Run mode with CLKS1/2 = CLKB = CLKP1/2 = 4MHz	-	3.5	-	mA	T _A = +25°C
			Flash 0 wait					
	(CLKPLL, CLKSC and CLKRC stopped)		-	-	7.5	mA	T _A = +105°C	
	I _{CCRCH}		RC Run mode with CLKS1/2 = CLKB = CLKP1/2 = CLKRC = 2MHz	-	1.7	-	mA	T _A = +25°C
			Flash 0 wait					
	(CLKMC, CLKPLL and CLKSC stopped)		-	-	5.5	mA	T _A = +105°C	
	I _{CCRCL}		RC Run mode with CLKS1/2 = CLKB = CLKP1/2 = CLKRC = 100kHz	-	0.15	-	mA	T _A = +25°C
Flash 0 wait								
(CLKMC, CLKPLL and CLKSC stopped)	-	-	3.2	mA	T _A = +105°C			
I _{CCSUB}	Sub Run mode with CLKS1/2 = CLKB = CLKP1/2 = 32kHz	-	0.1	-	mA	T _A = +25°C		
	Flash 0 wait							
(CLKMC, CLKPLL and CLKRC stopped)	-	-	3	mA	T _A = +105°C			

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks		
				Min	Typ	Max				
Power supply current in Sleep modes ^{*1}	I _{CCSPLL}	V _{CC}	PLL Sleep mode with CLK _S 1/2 = CLK _P 1/2 = 32MHz (CLK _R C and CLK _S C stopped)	-	6.5	-	mA	T _A = +25°C		
				-	-	13	mA	T _A = +105°C		
	I _{CCSMAIN}		Main Sleep mode with CLK _S 1/2 = CLK _P 1/2 = 4MHz, SMCR:LPMSS = 0 (CLK _P LL, CLK _R C and CLK _S C stopped)	-	0.9	-	mA	T _A = +25°C		
				-	-	4	mA	T _A = +105°C		
	I _{CCSRCH}		RC Sleep mode with CLK _S 1/2 = CLK _P 1/2 = CLK _R C = 2MHz, SMCR:LPMSS = 0 (CLK _M C, CLK _P LL and CLK _S C stopped)	-	0.5	-	mA	T _A = +25°C		
				-	-	3.5	mA	T _A = +105°C		
	I _{CCSRCL}		RC Sleep mode with CLK _S 1/2 = CLK _P 1/2 = CLK _R C = 100kHz (CLK _M C, CLK _P LL and CLK _S C stopped)	-	0.06	-	mA	T _A = +25°C		
				-	-	2.7	mA	T _A = +105°C		
	I _{CCSSUB}		Sub Sleep mode with CLK _S 1/2 = CLK _P 1/2 = 32kHz, (CLK _M C, CLK _P LL and CLK _R C stopped)	-	0.04	-	mA	T _A = +25°C		
				-	-	2.5	mA	T _A = +105°C		
	Power supply current in Timer modes ^{*2}		I _{CCTPLL}	V _{CC}	PLL Timer mode with CLK _P LL = 32MHz (CLK _R C and CLK _S C stopped)	-	1800	2245	μA	T _A = +25°C
						-	-	3140	μA	T _A = +105°C
I _{CCTMAIN}		Main Timer mode with CLK _M C = 4MHz, SMCR:LPMSS = 0 (CLK _P LL, CLK _R C and CLK _S C stopped)	-		285	325	μA	T _A = +25°C		
			-		-	1055	μA	T _A = +105°C		
I _{CCTRCH}		RC Timer mode with CLK _R C = 2MHz, SMCR:LPMSS = 0 (CLK _P LL, CLK _M C and CLK _S C stopped)	-		160	210	μA	T _A = +25°C		
			-		-	970	μA	T _A = +105°C		
I _{CCTRCL}		RC Timer mode with CLK _R C = 100kHz (CLK _P LL, CLK _M C and CLK _S C stopped)	-		30	70	μA	T _A = +25°C		
			-		-	820	μA	T _A = +105°C		
I _{CCTSUB}		Sub Timer mode with CLK _S C = 32kHz (CLK _M C, CLK _P LL and CLK _R C stopped)	-		25	55	μA	T _A = +25°C		
			-		-	800	μA	T _A = +105°C		

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Input leak current	I_{IL}	Pnn_m	$V_{SS} < V_I < V_{CC}$ $AV_{SS} < V_I < AV_{CC}, AVR_H$	- 1	-	+ 1	μA	Single port pin except high current output I/O for SMC
		P08_m	$DV_{SS} < V_I < DV_{CC}$ $AV_{SS} < V_I < AV_{CC}, AVR_H$	- 3	-	+ 3	μA	
Total LCD leak current	$\Sigma I_{LCD} $	All SEG/COM pin	$V_{CC} = 5.0V$	-	0.5	10	μA	Maximum leakage current of all LCD pins
Internal LCD divide resistance	R_{LCD}	Between V3 and V2, V2 and V1, V1 and V0	$V_{CC} = 5.0V$	6.25	12.5	25	$k\Omega$	
Pull-up resistance value	R_{PU}	Pnn_m	$V_{CC} = 5.0V \pm 10\%$	25	50	100	$k\Omega$	
Pull-down resistance value	R_{DOWN}	P08_m	$V_{CC} = 5.0V \pm 10\%$	25	50	100	$k\Omega$	
Input capacitance	C_{IN}	Other than C, Vcc, Vss, DVcc, DVss, AVcc, AVss, AVR_H, P08_m	-	-	5	15	pF	
		P08_m	-	-	15	30	pF	

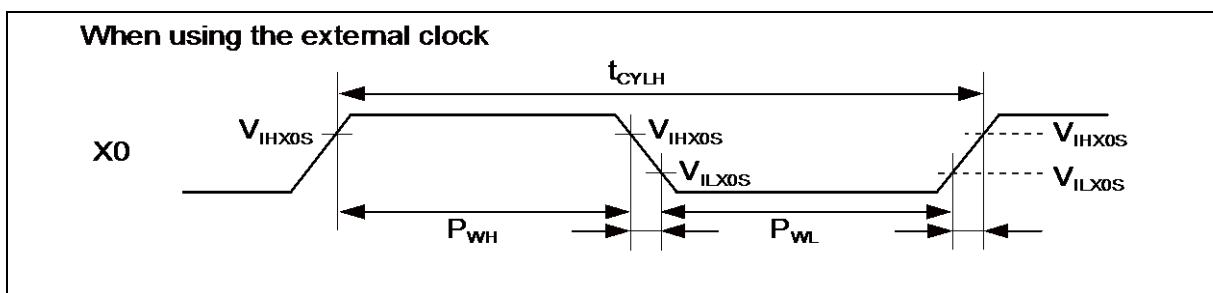
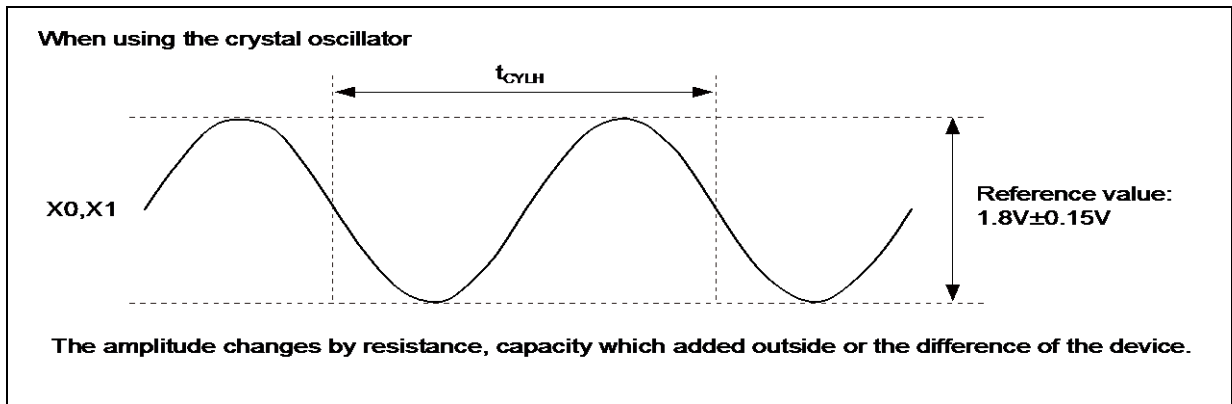
*: In the case of driving stepping motor directly or high current outputs, set "1" to the bit in the Port High Drive Register (PHDRnn:HDx="1").

14.4 AC Characteristics

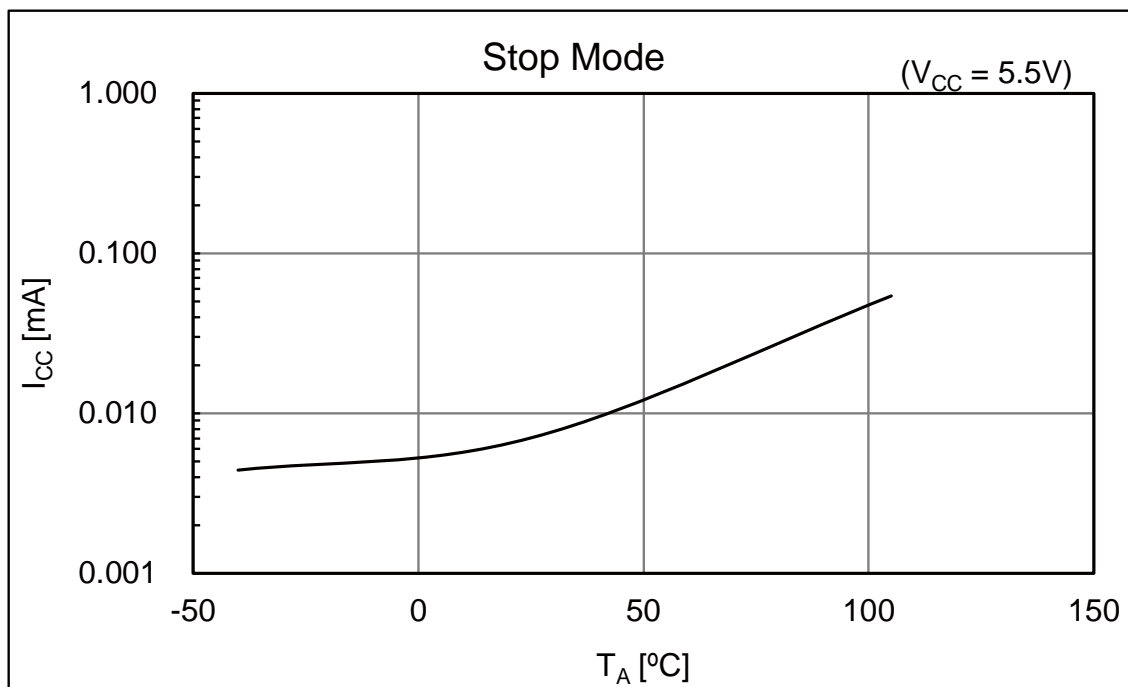
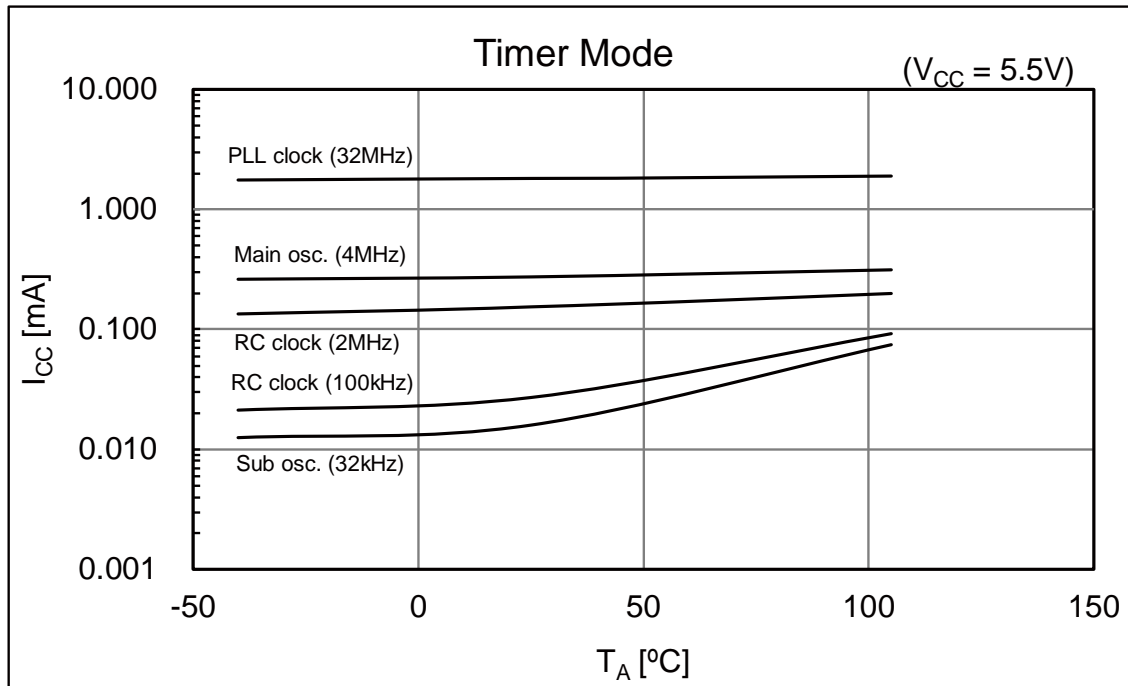
14.4.1 Main Clock Input Characteristics

($V_{CC} = AV_{CC} = DV_{CC} = 2.7V$ to $5.5V$, $V_D = 1.8V \pm 0.15V$, $V_{SS} = AV_{SS} = DV_{SS} = 0V$, $T_A = -40^\circ C$ to $+105^\circ C$)

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Input frequency	f_c	X0, X1	4	-	8	MHz	When using a crystal oscillator, PLL off
			-	-	8	MHz	When using an opposite phase external clock, PLL off
			4	-	8	MHz	When using a crystal oscillator or opposite phase external clock, PLL on
Input frequency	f_{FCI}	X0	-	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL off
			4	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL on
Input clock cycle	t_{CYLH}	-	125	-	-	ns	
Input clock pulse width	P_{WH}, P_{WL}	-	55	-	-	ns	

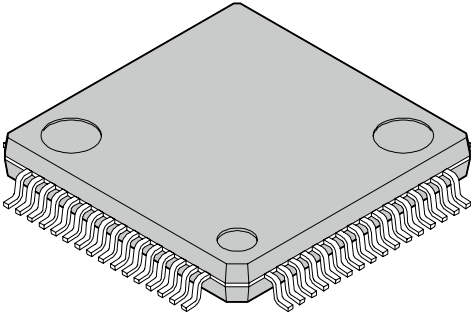


■ MB96F675



■ Used setting

Mode	Selected Source Clock	Clock/Regulator and FLASH Settings
Run mode	PLL	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 32MHz
	Main osc.	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 4MHz
	RC clock fast	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 2MHz
	RC clock slow	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 100kHz
	Sub osc.	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 32kHz
Sleep mode	PLL	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 32MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	Main osc.	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 4MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	RC clock fast	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 2MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	RC clock slow	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 100kHz Regulator in Low Power Mode, (CLKB is stopped in this mode)
	Sub osc.	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 32kHz Regulator in Low Power Mode, (CLKB is stopped in this mode)
Timer mode	PLL	CLKMC = 4MHz, CLKPLL = 32MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	Main osc.	CLKMC = 4MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	RC clock fast	CLKMC = 2MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	RC clock slow	CLKMC = 100kHz (System clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode
	Sub osc.	CLKMC = 32 kHz (System clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode
Stop mode	stopped	(All clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode

<p>64-pin plastic LQFP</p>  <p>(FPT-64P-M24)</p>	Lead pitch	0.50 mm
	Package width x package length	10.0 x 10.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Weight	0.32 g
	Code (Reference)	P-LFQFP64-10x10-0.50

