



Welcome to [E-XFL.COM](#)

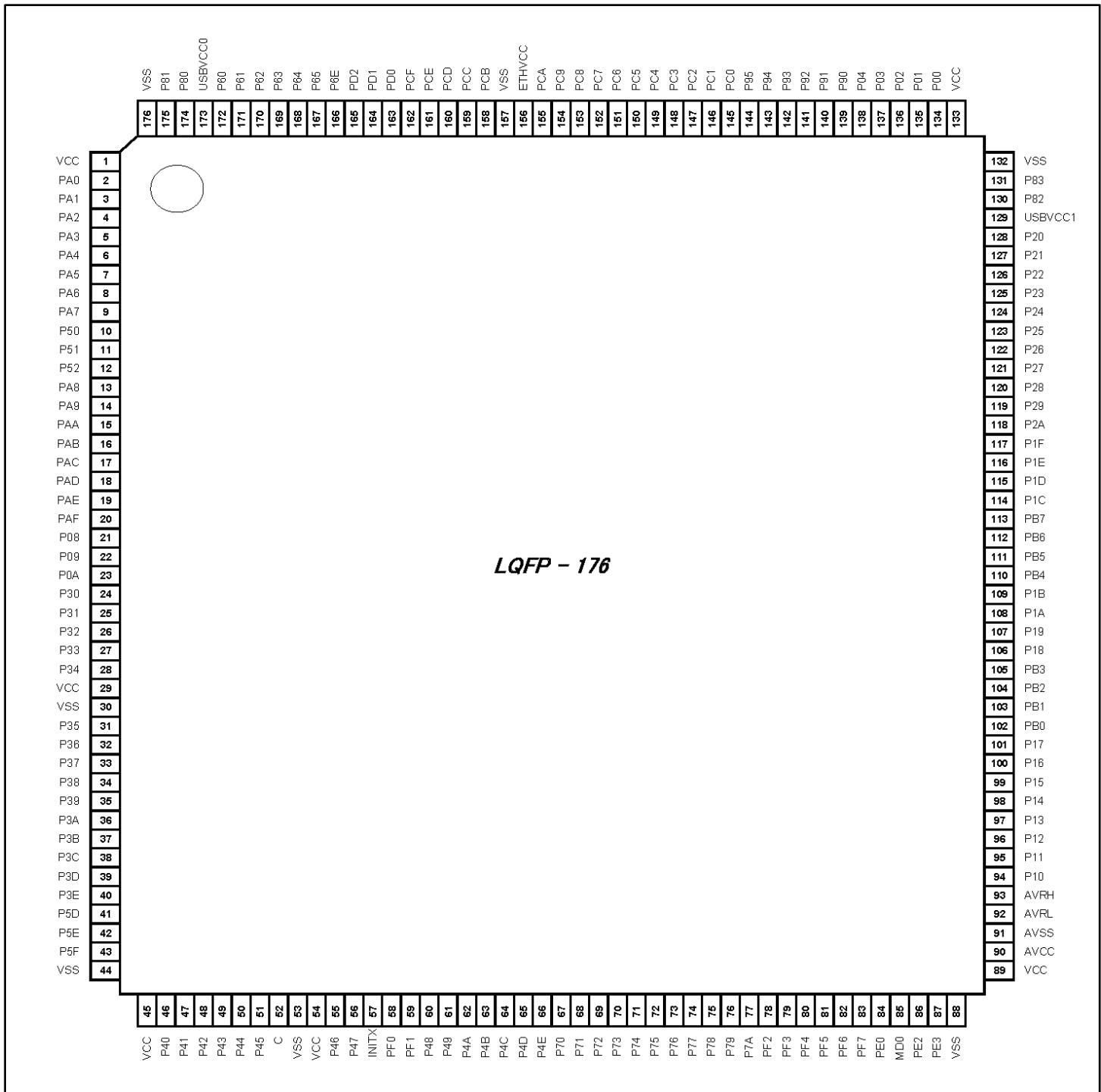
#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4F
Core Size	32-Bit Single-Core
Speed	180MHz
Connectivity	CSI0, EBI/EMI, I²C, LINbus, SmartCard, SPI, UART/USART, USB
Peripherals	DMA, I²S, LVD, POR, PWM, WDT
Number of I/O	121
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 24x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	176-LQFP
Supplier Device Package	176-LQFP (24x24)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/s6e2g36j0agv2000a">https://www.e-xfl.com/product-detail/infineon-technologies/s6e2g36j0agv2000a</a>

**LQP176**

**Note:**

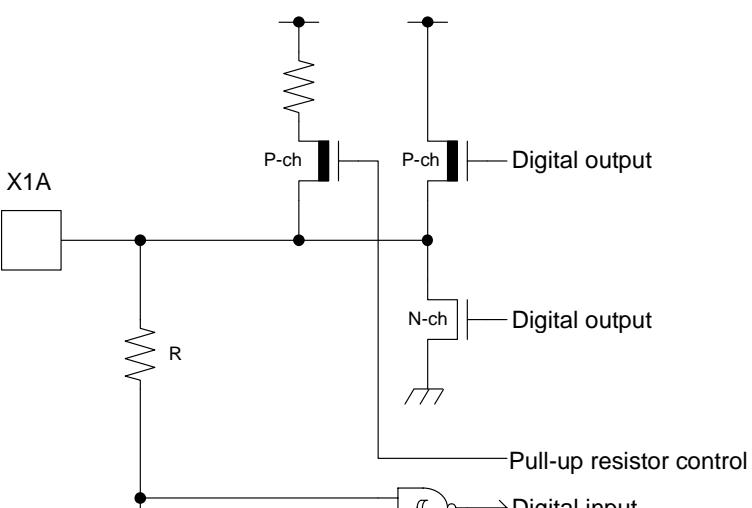
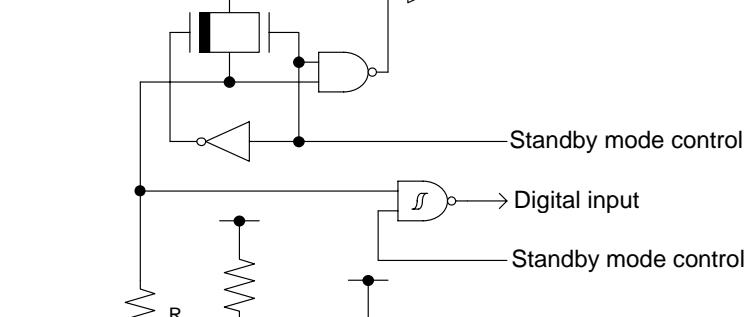
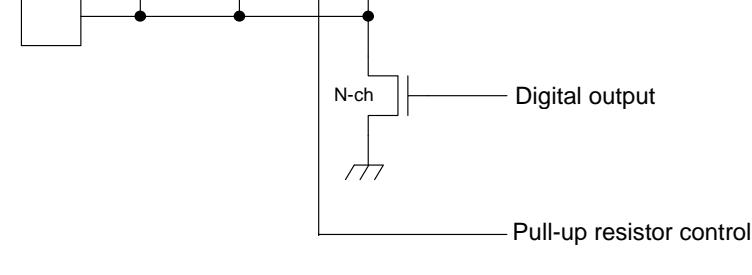
- Only the GPIO function is shown on GPIO pins. See the table in [Pin Descriptions](#) for the full, multiplexed signal name.

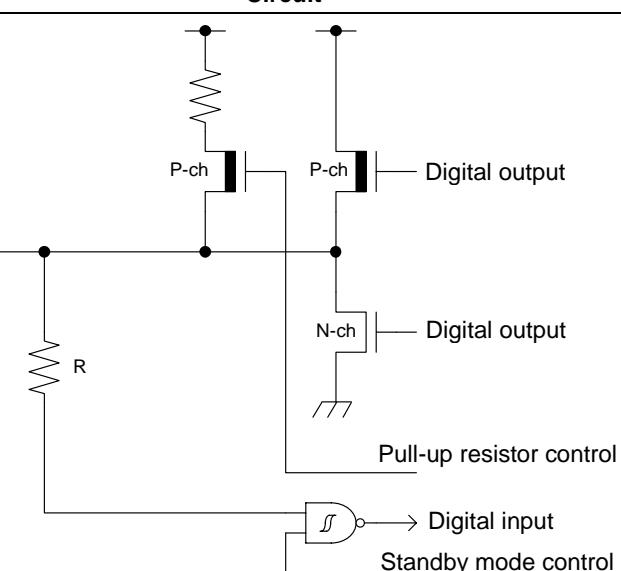
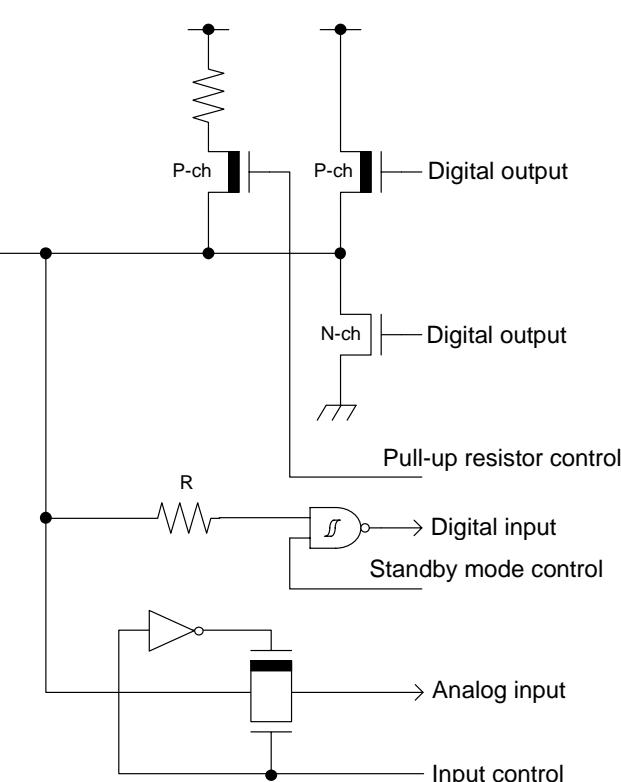
Pin Number		Pin Name	I/O Circuit Type	Pin State Type
LQFP-176	LQFP-144			
151	121	PC6	K	V
		TIOA14_0		
		E_MDIO		
152	122	PC7	E	W
		INT13_0		
		E_MDC		
		CROUT_1		
153	123	PC8	K	V
		E_RXCK_REFCK		
154	124	PC9	K	V
		TIOB15_0		
		E_COL		
155	125	PCA	K	V
		TIOA15_0		
		E_CRS		
156	126	ETHVCC	-	-
157	127	VSS	-	-
158	128	PCB	L	W
		INT28_0		
		E_COUT		
159	129	PCC	K	V
		E_TCK		
160	130	PCD	L	W
		SOT4_1 (SDA4_1)		
		INT14_0		
		E_TXER		
161	131	PCE	L	W
		SIN4_1		
		INT15_0		
		E_TX03		
162	132	PCF	L	W
		RTS4_1		
		INT12_0		
		E_TX02		
163	133	PD0	L	W
		INT30_1		
		E_TX01		
164	134	PD1	L	W
		INT31_1		
		E_TX00		
165	135	PD2	L	V
		CTS4_1		
		E_TXEN		

Module	Pin Name	Function	Pin Number	
			LQFP 176	LQFP 144
External interrupt	INT14_0	External interrupt request 14 input pin	160	130
	INT14_1		141	-
	INT15_0	External interrupt request 15 input pin	161	131
	INT15_1		142	-
	INT16_0	External interrupt request 16 input pin	20	17
	INT16_1		35	30
	INT17_0	External interrupt request 17 input pin	21	18
	INT17_1		36	31
	INT18_0	External interrupt request 18 input pin	22	19
	INT18_1		37	32
	INT19_0	External interrupt request 19 input pin	26	21
	INT19_1		38	33
	INT20_0	External interrupt request 20 input pin	70	60
	INT20_1		82	-
	INT21_0	External interrupt request 21 input pin	73	63
	INT21_1		83	-
	INT22_0	External interrupt request 22 input pin	76	66
	INT22_1		58	-
	INT23_0	External interrupt request 23 input pin	46	38
	INT23_1		59	-
	INT24_0	External interrupt request 24 input pin	121	97
	INT24_1		107	87
	INT25_0	External interrupt request 25 input pin	123	99
	INT25_1		97	81
	INT26_0	External interrupt request 26 input pin	126	102
	INT26_1		116	92
	INT27_0	External interrupt request 27 input pin	127	103
	INT27_1		117	93
	INT28_0	External interrupt request 28 input pin	158	128
	INT28_1		167	-
	INT29_0	External interrupt request 29 input pin	166	136
	INT29_1		168	-
	INT30_0	External interrupt request 30 input pin	169	137
	INT30_1		163	133
	INT31_0	External interrupt request 31 input pin	172	140
	INT31_1		164	134
	NMIX	Non-maskable interrupt input pin	128	104

Module	Pin Name	Function	Pin Number	
			LQFP 176	LQFP 144
GPIO	P30	General-purpose I/O port 3	24	-
	P31		25	-
	P32		26	21
	P33		27	22
	P34		28	23
	P35		31	26
	P36		32	27
	P37		33	28
	P38		34	29
	P39		35	30
	P3A		36	31
	P3B		37	32
	P3C		38	33
	P3D		39	34
	P3E		40	35
GPIO	P40	General-purpose I/O port 4	46	38
	P41		47	39
	P42		48	40
	P43		49	41
	P44		50	42
	P45		51	43
	P46		55	47
	P47		56	48
	P48		60	50
	P49		61	51
	P4A		62	52
	P4B		63	53
	P4C		64	54
	P4D		65	55
	P4E		66	56
GPIO	P50	General-purpose I/O port 5	10	-
	P51		11	-
	P52		12	-
	P5D		41	-
	P5E		42	-
	P5F		43	-
GPIO	P60	General-purpose I/O port 6	172	140
	P61		171	139
	P62		170	138
	P63		169	137
	P64		168	-
	P65		167	-
	P6E		166	136

Module	Pin Name	Function	Pin Number	
			LQFP 176	LQFP 144
Multi-Function Serial 2	SIN2_0	Multi-function serial interface ch 2 input pin	106	86
	SIN2_1		38	33
	SOT2_0 (SDA2_0)	Multi-function serial interface ch 2 output pin	107	87
	SOT2_1 (SDA2_1)	This pin operates as SOT2 when it is used in a UART/CSIO/LIN (operation modes 0 to 3) and as SDA2 when it is used in an I <sup>2</sup> C (operation mode 4).	39	34
	SCK2_0 (SCL2_0)	Multi-function serial interface ch 2 clock I/O pin	108	88
	SCK2_1 (SCL2_1)	This pin operates as SCK2 when it is used in a CSIO (operation mode 2) and as SCL2 when it is used in an I <sup>2</sup> C (operation mode 4).	40	35
Multi-Function Serial 3	SIN3_0	Multi-function serial interface ch 3 input pin	20	17
	SIN3_1		81	-
	SOT3_0 (SDA3_0)	Multi-function serial interface ch 3 output pin	19	16
	SOT3_1 (SDA3_1)	This pin operates as SOT3 when it is used in a UART/CSIO/LIN (operation modes 0 to 3) and as SDA3 when it is used in an I <sup>2</sup> C (operation mode 4).	82	-
	SCK3_0 (SCL3_0)	Multi-function serial interface ch 3 clock I/O pin	18	15
	SCK3_1 (SCL3_1)	This pin operates as SCK3 when it is used in a CSIO (operation modes 2) and as SCL3 when it is used in an I <sup>2</sup> C (operation mode 4).	83	-
Multi-Function Serial 4	SIN4_0	Multi-function serial interface ch 4 input pin	172	140
	SIN4_1		161	131
	SOT4_0 (SDA4_0)	Multi-function serial interface ch 4 output pin	171	139
	SOT4_1 (SDA4_1)	This pin operates as SOT4 when it is used in a UART/CSIO/LIN (operation modes 0 to 3) and as SDA4 when it is used in an I <sup>2</sup> C (operation mode 4).	160	130
	SCK4_0 (SCL4_0)	Multi-function serial interface ch 4 clock I/O pin	170	138
	SCK4_1 (SCL4_1)	This pin operates as SCK4 when it is used in a CSIO (operation mode 2) and as SCL4 when it is used in an I <sup>2</sup> C (operation mode 4).	166	136
	CTS4_0	Multi-function serial interface ch 4 CTS input pin	168	-
	CTS4_1		165	135
	RTS4_0	Multi-function serial interface ch 4 RTS output pin	169	137
	RTS4_1		162	132

Type	Circuit	Remarks
X1A	 <p>Digital output</p> <p>Pull-up resistor control</p> <p>Digital input</p> <p>Standby mode control</p>	<p>It is possible to select the sub oscillation/GPIO function.</p>
D	 <p>Standby mode control</p> <p>Digital input</p> <p>Standby mode control</p>	<p>When the main oscillation is selected:</p> <ul style="list-style-type: none"> <li>Oscillation feedback resistor: approximately 5 MΩ</li> <li>Standby mode control</li> </ul> <p>When the GPIO is selected:</p> <ul style="list-style-type: none"> <li>CMOS level output.</li> <li>CMOS level hysteresis input</li> <li>Pull-up resistor control</li> <li>Standby mode control</li> <li>Pull-up resistor: approximately 50 kΩ</li> <li><math>I_{OH} = -4 \text{ mA}</math>, <math>I_{OL} = 4 \text{ mA}</math></li> </ul>
X0A	 <p>Digital output</p> <p>N-ch</p> <p>Digital output</p> <p>Pull-up resistor control</p>	

Type	Circuit	Remarks
E	 <p>Pull-up resistor control</p> <p>Digital input</p> <p>Standby mode control</p>	<ul style="list-style-type: none"> <li>CMOS level output</li> <li>CMOS level hysteresis input</li> <li>Pull-up resistor control</li> <li>Standby mode control</li> <li>Pull-up resistor: approximately 50 kΩ</li> <li><math>I_{OH} = -4 \text{ mA}</math>, <math>I_{OL} = 4 \text{ mA}</math></li> <li>When this pin is used as an I<sup>2</sup>C pin, the digital output P-ch transistor is always off.</li> </ul>
F	 <p>Pull-up resistor control</p> <p>Digital input</p> <p>Standby mode control</p> <p>Analog input</p> <p>Input control</p>	<ul style="list-style-type: none"> <li>CMOS level output</li> <li>CMOS level hysteresis input</li> <li>Input control</li> <li>Analog input</li> <li>Pull-up resistor control</li> <li>Standby mode control</li> <li>Pull-up resistor: approximately 50 kΩ</li> <li><math>I_{OH} = -4 \text{ mA}</math>, <math>I_{OL} = 4 \text{ mA}</math></li> <li>When this pin is used as an I<sup>2</sup>C pin, the digital output P-ch transistor is always off.</li> </ul>

**Peripheral Address Map**

Start Address	End Address	Bus	Peripherals
0x4000_0000	0x4000_0FFF	AHB	MainFlash I/F register
0x4000_1000	0x4000_FFFF		Reserved
0x4001_0000	0x4001_0FFF	APB0	Clock/reset control
0x4001_1000	0x4001_1FFF		Hardware watchdog timer
0x4001_2000	0x4001_2FFF		Software watchdog timer
0x4001_3000	0x4001_4FFF		Reserved
0x4001_5000	0x4001_5FFF		Dual-timer
0x4001_6000	0x4001_FFFF		Reserved
0x4002_0000	0x4002_0FFF	APB1	Multi-Function Timer unit 0
0x4002_1000	0x4002_1FFF		Multi-Function Timer unit 1
0x4002_2000	0x4002_3FFF		Reserved
0x4002_4000	0x4002_4FFF		PPG
0x4002_5000	0x4002_5FFF		Base timer
0x4002_6000	0x4002_6FFF		Quadrature position/revolution counter
0x4002_7000	0x4002_7FFF		A/D converter
0x4002_8000	0x4002_DFFF		Reserved
0x4002_E000	0x4002_EFFF		Internal CR trimming
0x4002_F000	0x4002_FFFF		Reserved
0x4003_0000	0x4003_0FFF	APB2	External interrupt controller
0x4003_1000	0x4003_1FFF		Interrupt request batch-read function
0x4003_2000	0x4003_4FFF		Reserved
0x4003_5000	0x4003_57FF		Low voltage detector
0x4003_5800	0x4003_5FFF		Deep standby mode Controller
0x4003_6000	0x4003_6FFF		USB clock generator
0x4003_7000	0x4003_7FFF		CAN prescaler
0x4003_8000	0x4003_8FFF		Multi-function serial interface
0x4003_9000	0x4003_9FFF		CRC
0x4003_A000	0x4003_AFFF		Watch counter
0x4003_B000	0x4003_BFFF		RTC/port control
0x4003_C000	0x4003_C0FF		Low-speed CR prescaler
0x4003_C100	0x4003_C7FF		Peripheral clock gating
0x4003_C800	0x4003_C8FF		Reserved
0x4003_C900	0x4003_C9FF		I2S clock generator
0x4003_CA00	0x4003_CAFF		Smartcard Interface
0x4003_CB00	0x4003_EFFF		Reserved
0x4003_F000	0x4003_FFFF		External memory interface

Start Address	End Address	Bus	Peripherals
0x4004_0000	0x4004_FFFF	AHB	USB ch 0
0x4005_0000	0x4005_FFFF		USB ch 1
0x4006_0000	0x4006_0FFF		DMAC register
0x4006_1000	0x4006_1FFF		DSTC register
0x4006_2000	0x4006_2FFF		CAN ch 0
0x4006_3000	0x4006_3FFF		Reserved
0x4006_4000	0x4006_5FFF		Ethernet-MAC ch 0
0x4006_6000	0x4006_6FFF		Ethernet-MAC setting register
0x4006_7000	0x4006_DFFF		Reserved
0x4006_E000	0x4006_EFFF		SD card I/F
0x4006_F000	0x4006_FFFF		GPIO
0x4007_0000	0x41FF_FFFF		Reserved

Pin Status Type	Function Group	Power-On Reset or Low-Voltage Detection State	INITX Input State	Device Internal Reset State	Run mode or Sleep mode State	Timer mode, RTC mode, or Stop mode State	Deep Standby RTC mode or Deep Standby Stop mode State	Return from Deep Standby mode State	
		Power Supply Unstable	Power Supply Stable		Power Supply Stable	Power Supply Stable		Power Supply Stable	
		-	INITX=0	INITX=1	INITX=1	INITX=1		INITX=1	
		-	-	-	-	SPL=0	SPL=1	SPL=0	
M	Analog input selected	Hi-Z	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	
	External interrupt enable selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	GPIO selected, internal input fixed at 0	Hi-Z/internal input fixed at 0	
	Resource other than above selected					Hi-Z/internal input fixed at 0			
	GPIO selected					GPIO selected			
N	Analog input selected	Hi-Z	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	Hi-Z/internal input fixed at 0/ analog input enabled	
	Trace selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Trace output	GPIO selected, internal input fixed at 0	Hi-Z/internal input fixed at 0	
	Resource other than above selected					Hi-Z/internal input fixed at 0			
	GPIO selected					GPIO selected			

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
L level output voltage	V <sub>OL</sub>	4 mA type	V <sub>CC</sub> ≥ 4.5 V, I <sub>OL</sub> = 4 mA	V <sub>SS</sub>	-	0.4	V	
			V <sub>CC</sub> < 4.5 V, I <sub>OL</sub> = 2 mA					
			ETHV <sub>CC</sub> ≥ 4.5 V, I <sub>OL</sub> = 4 mA	V <sub>SS</sub>	-	0.4	V	
			RTHV <sub>CC</sub> < 4.5 V, I <sub>OL</sub> = 2 mA					
		8 mA type	V <sub>CC</sub> ≥ 4.5 V, I <sub>OL</sub> = 8 mA	V <sub>SS</sub>	-	0.4	V	
			V <sub>CC</sub> < 4.5 V, I <sub>OL</sub> = 4 mA					
			ETHV <sub>CC</sub> ≥ 4.5 V, I <sub>OL</sub> = 8 mA	V <sub>SS</sub>	-	0.4	V	
			RTHV <sub>CC</sub> < 4.5 V, I <sub>OL</sub> = 4 mA					
		12 mA type	V <sub>CC</sub> ≥ 4.5 V, I <sub>OL</sub> = 12 mA	V <sub>SS</sub>	-	0.4	V	
			V <sub>CC</sub> < 4.5 V, I <sub>OL</sub> = 8 mA					
		The pin doubled as USB I/O	USBV <sub>CC</sub> ≥ 4.5 V, I <sub>OL</sub> = 18.5 mA	V <sub>SS</sub>	-	0.4	V	*1
			USBV <sub>CC</sub> < 4.5 V, I <sub>OL</sub> = 10.5 mA					
		The pin doubled as I <sup>2</sup> C Fm+	V <sub>CC</sub> ≥ 4.5 V, I <sub>OL</sub> = 4 mA	V <sub>SS</sub>	-	0.4	V	At GPIO
			V <sub>CC</sub> < 4.5 V, I <sub>OL</sub> = 3 mA					At I <sup>2</sup> C Fm+
			V <sub>CC</sub> ≤ 4.5 V, I <sub>OL</sub> = 20 mA					
Input leak current	I <sub>IL</sub>	-	-	- 5	-	+ 5	µA	
Pull-up resistor value	R <sub>PU</sub>	Pull-up pin	V <sub>CC</sub> ≥ 4.5 V	25	50	100	kΩ	
			V <sub>CC</sub> < 4.5 V	30	80	200		
Input capacitance	C <sub>IN</sub>	Other than VCC, USBVCC0, USBVCC1, ETHVCC, VSS, AVCC, AVSS, AVRH	-	-	5	15	pF	

1: USBV<sub>CC0</sub> and USBV<sub>CC1</sub> are described as USBV<sub>CC</sub>.

## 12.4 AC Characteristics

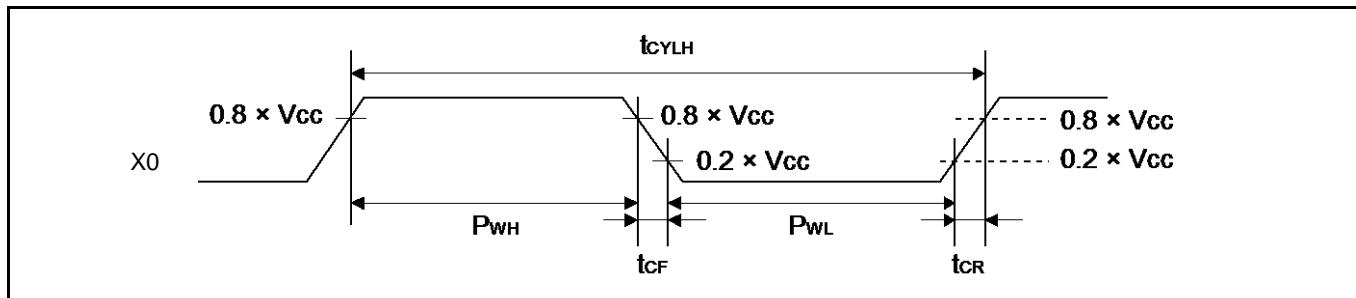
### 12.4.1 Main Clock Input Characteristics

( $V_{CC} = AV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ )

Parameter	Symbol	Pin Name	Conditions	Value		Unit	Remarks
				Min	Max		
Input frequency	$f_{CH}$	X0, X1	$V_{CC} \geq 4.5V$	4	48	MHz	When crystal oscillator is connected
			$V_{CC} < 4.5V$	4	20		
			$V_{CC} \geq 4.5V$	4	48	MHz	When using external clock
			$V_{CC} < 4.5V$	4	20		
Input clock cycle	$t_{CYLH}$		$V_{CC} \geq 4.5V$	20.83	250	ns	When using external clock
			$V_{CC} < 4.5V$	50	250		
Input clock pulse width	-		$P_{WH}/t_{CYLH}$ , $P_{WL}/t_{CYLH}$	45	55	%	When using external clock
Input clock rise time and fall time	$t_{CF}$ , $t_{CR}$		-	-	5	ns	When using external clock
Internal operating clock <sup>*1</sup> frequency	$f_{CC}$	-	-	-	180	MHz	Base clock (HCLK/FCLK)
	$f_{CP0}$	-	-	-	90	MHz	APB0bus clock <sup>*2</sup>
	$f_{CP1}$	-	-	-	180	MHz	APB1bus clock <sup>*2</sup>
	$f_{CP2}$	-	-	-	90	MHz	APB2bus clock <sup>*2</sup>
Internal operating clock <sup>*1</sup> cycle time	$t_{CYCC}$	-	-	5.56	-	ns	Base clock (HCLK/FCLK)
	$t_{CYCP0}$	-	-	11.1	-	ns	APB0bus clock <sup>*2</sup>
	$t_{CYCP1}$	-	-	5.56	-	ns	APB1bus clock <sup>*2</sup>
	$t_{CYCP2}$	-	-	11.1	-	ns	APB2bus clock <sup>*2</sup>

1: For more information about each internal operating clock, see Chapter 2-1: Clock in FM4 Family Peripheral Manual Main Part (002-04856).

2: For more about each APB bus to which each peripheral is connected, see 1. S6E2G Series Block Diagram in this data sheet.



#### 12.4.6 Operating Conditions of Main PLL (in the Case of Using Built-in High-Speed CR Clock for Input Clock of Main PLL)

(V<sub>CC</sub> = 2.7V to 5.5V, V<sub>SS</sub> = 0V)

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
PLL oscillation stabilization wait time <sup>*1</sup> (lock up time)	t <sub>LOCK</sub>	100	-	-	μs	
PLL input clock frequency	f <sub>PLL</sub>	3.8	4	4.2	MHz	
PLL multiplication rate	-	50	-	95	multiplier	
PLL macro oscillation clock frequency	f <sub>PLL</sub>	190	-	400	MHz	
Main PLL clock frequency <sup>*2</sup>	f <sub>CLKPLL</sub>	-	-	180	MHz	

1: Time from when the PLL starts operating until the oscillation stabilizes

2: For more information about Main PLL clock (CLKPLL), see Chapter 2-1: Clock in FM4 Family Peripheral Manual Main Part (002-04856).

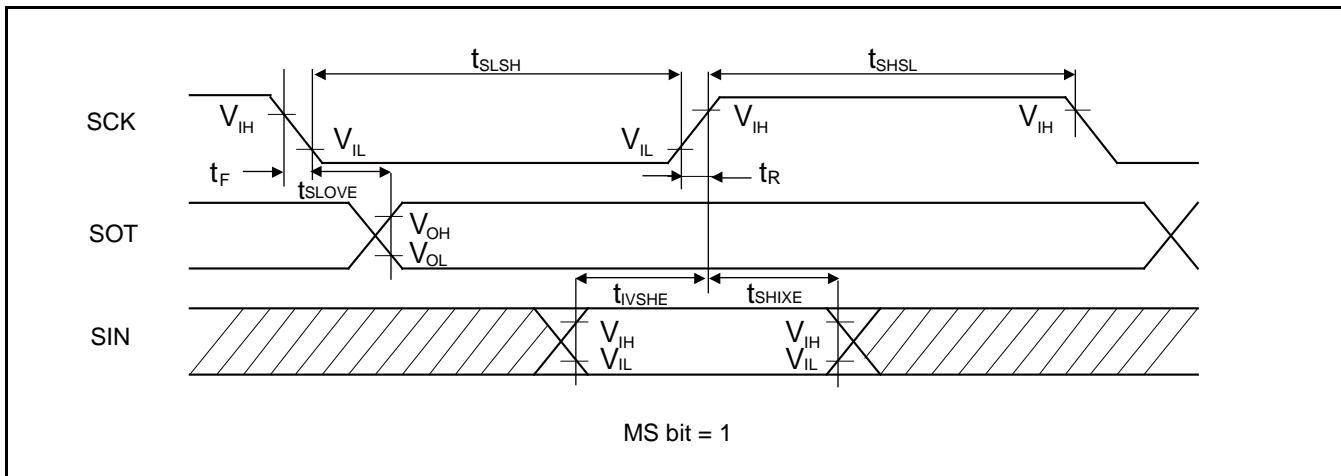
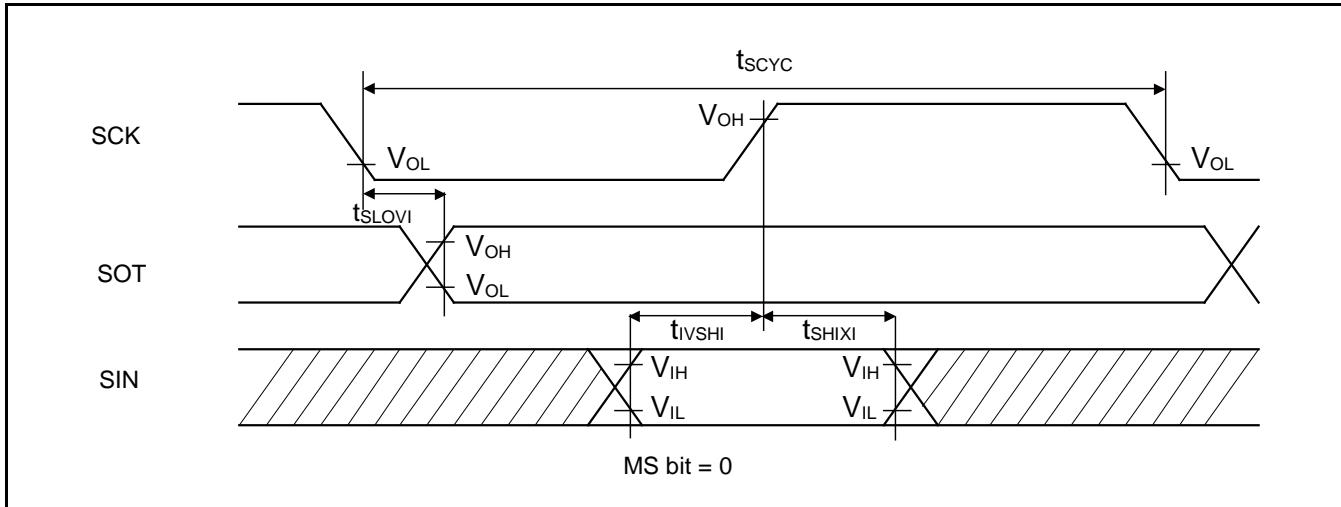
**Note:**

- The High-speed CR clock (CLKHC) should be set with frequency/temperature trimming to act as the source clock of the Main PLL.

#### 12.4.7 Reset Input Characteristics

(V<sub>CC</sub> = 2.7V to 5.5V, V<sub>SS</sub> = 0V)

Parameter	Symbol	Pin Name	Conditions	Value		Unit	Remarks
				Min	Max		
Reset input time	t <sub>INITX</sub>	INITX	-	500	-	ns	

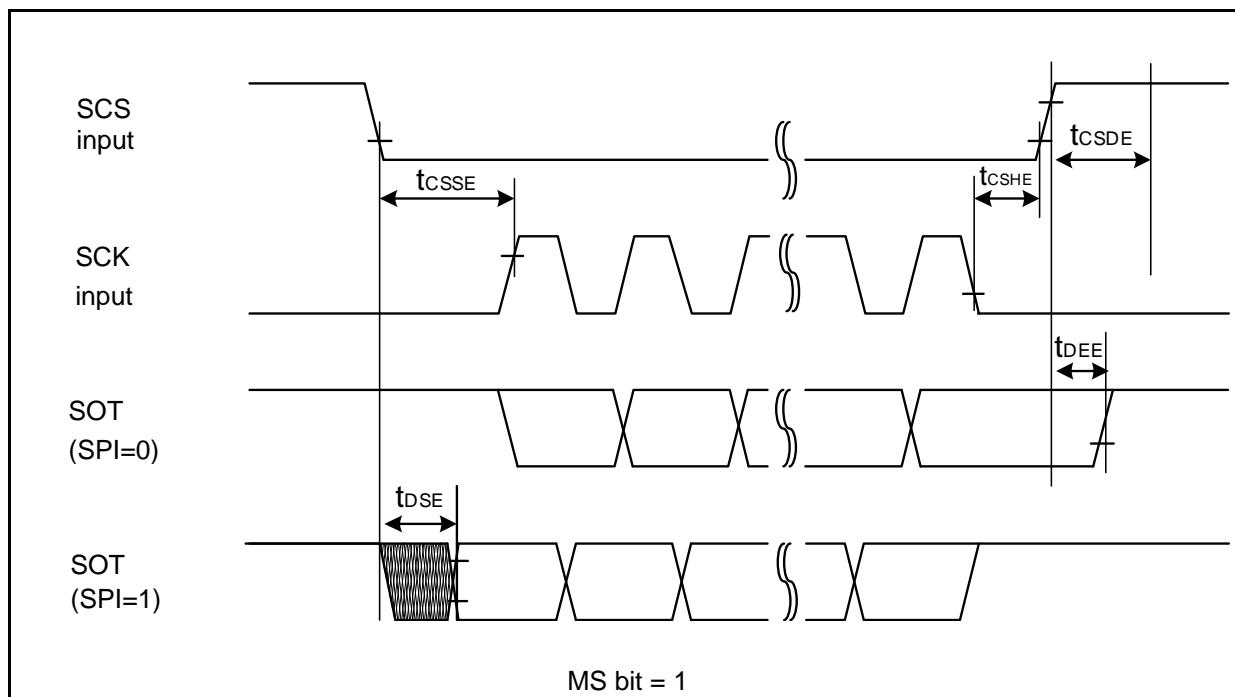
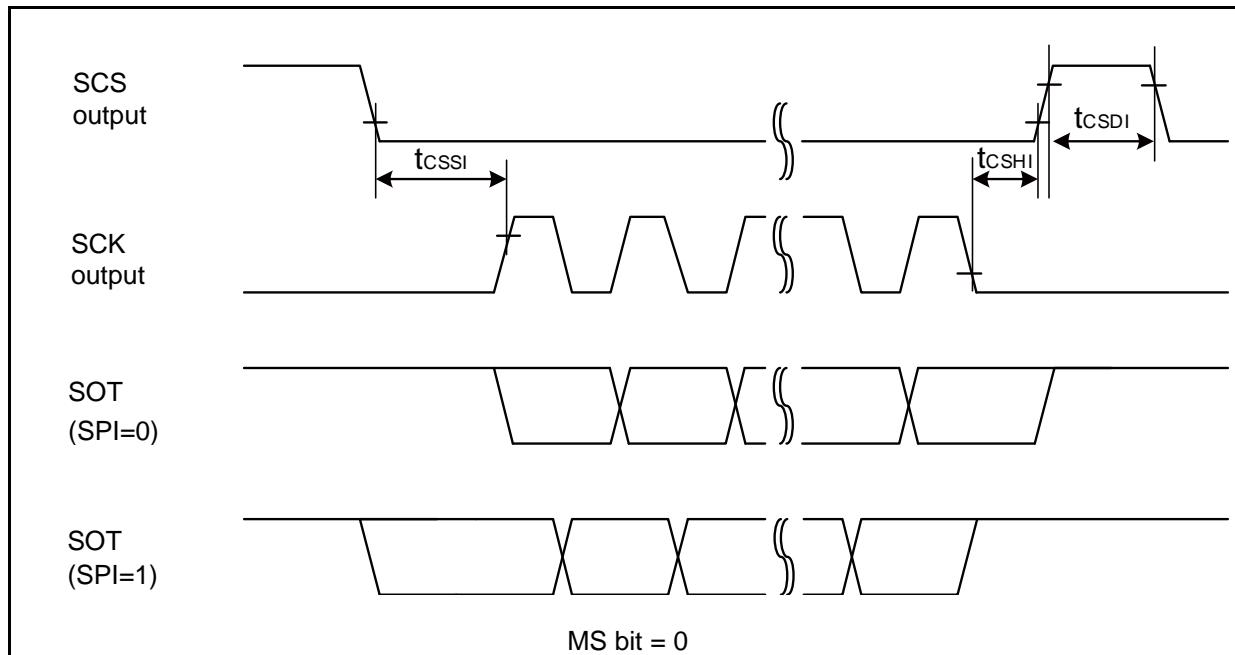


**Synchronous Serial (SPI = 1, SCINV = 1)**
 $(V_{CC} = 2.7V \text{ to } 5.5V, V_{SS} = 0V)$ 

Parameter	Symbol	Pin Name	Conditions	$V_{CC} < 4.5 \text{ V}$		$V_{CC} \geq 4.5 \text{ V}$		Unit
				Min	Max	Min	Max	
Baud rate	-	-	-	-	8	-	8	Mbps
Serial clock cycle time	t <sub>SCYC</sub>	SCKx	Internal shift clock operation	4t <sub>CYCP</sub>	-	4t <sub>CYCP</sub>	-	ns
SCK↓→SOT delay time	t <sub>SLOVI</sub>	SCKx, SOTx		- 30	+ 30	- 20	+ 20	ns
SIN→SCK↑ setup time	t <sub>IVSHI</sub>	SCKx, SINx		50	-	30	-	ns
SCK↑→SIN hold time	t <sub>SHIXI</sub>	SCKx, SINx		0	-	0	-	ns
SOT→SCK↑ delay time	t <sub>SOVHI</sub>	SCKx, SOTx		2t <sub>CYCP</sub> - 30	-	2t <sub>CYCP</sub> - 30	-	ns
Serial clock L pulse width	t <sub>SLSH</sub>	SCKx	External shift clock operation	2t <sub>CYCP</sub> - 10	-	2t <sub>CYCP</sub> - 10	-	ns
Serial clock H pulse width	t <sub>SHSL</sub>	SCKx		t <sub>CYCP</sub> + 10	-	t <sub>CYCP</sub> + 10	-	ns
SCK↓→SOT delay time	t <sub>SLOVE</sub>	SCKx, SOTx		-	50	-	30	ns
SIN→SCK↑ setup time	t <sub>IVSHE</sub>	SCKx, SINx		10	-	10	-	ns
SCK↑→SIN hold time	t <sub>SHIXE</sub>	SCKx, SINx		20	-	20	-	ns
SCK fall time	t <sub>F</sub>	SCKx		-	5	-	5	ns
SCK rise time	t <sub>R</sub>	SCKx		-	5	-	5	ns

**Notes:**

- The above characteristics apply to CLK synchronous mode.
- t<sub>CYCP</sub> indicates the APB bus clock cycle time. For more information about the APB bus number to which the multi-function serial is connected, see 1. S6E2G Series Block Diagram in this data sheet.
- These characteristics only guarantee the same relocate port number; for example, the combination of SCLKx\_0 and SOTx\_1 is not guaranteed.
- When the external load capacitance C<sub>L</sub> = 30 pF.

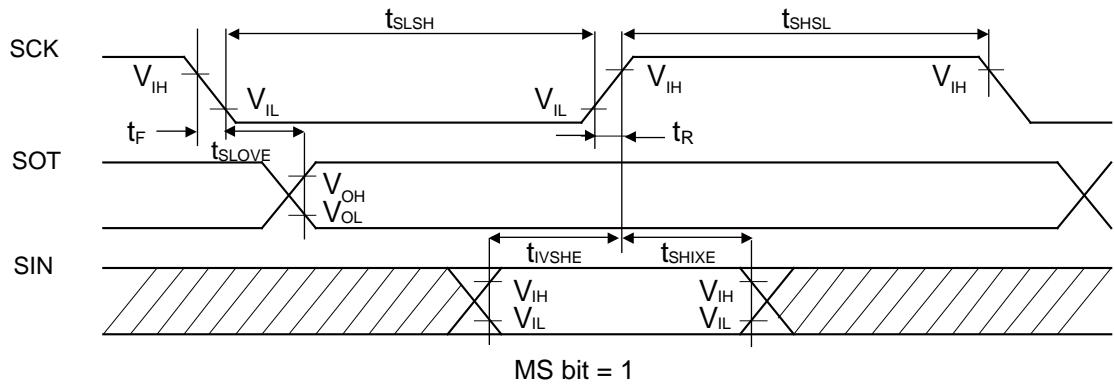
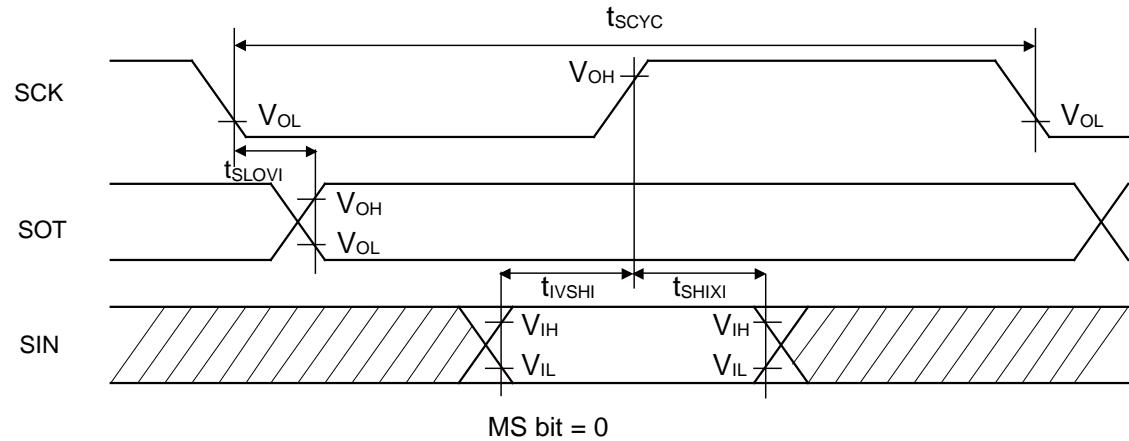


**High-Speed Synchronous Serial (SPI = 0, SCINV = 0)**
 $(V_{CC} = 2.7V \text{ to } 5.5V, V_{SS} = 0V)$ 

Parameter	Symbol	Pin Name	Conditions	$V_{CC} < 4.5 \text{ V}$		$V_{CC} \geq 4.5 \text{ V}$		Unit
				Min	Max	Min	Max	
Serial clock cycle time	t <sub>SCYC</sub>	SCKx	Internal shift clock operation	4t <sub>CYCP</sub>	-	4t <sub>CYCP</sub>	-	ns
SCK↓→SOT delay time	t <sub>SLOVI</sub>	SCKx, SOTx		- 10	+ 10	- 10	+ 10	ns
SIN→SCK↑ setup time	t <sub>IVSHI</sub>	SCKx, SINx		14	-	12.5	-	ns
SCK↑→SIN hold time	t <sub>SHIXI</sub>	SCKx, SINx		12.5*	-	-	-	ns
Serial clock L pulse width	t <sub>SLSH</sub>	SCKx		5	-	5	-	ns
Serial clock H pulse width	t <sub>SHSL</sub>	SCKx	External shift clock operation	2t <sub>CYCP</sub> - 5	-	2t <sub>CYCP</sub> - 5	-	ns
SCK↓→SOT delay time	t <sub>SLOVE</sub>	SCKx, SOTx		t <sub>CYCP</sub> + 10	-	t <sub>CYCP</sub> + 10	-	ns
SIN→SCK↑ setup time	t <sub>IVSHE</sub>	SCKx, SINx		-	15	-	15	ns
SCK↑→SIN hold time	t <sub>SHIXE</sub>	SCKx, SINx		5	-	5	-	ns
SCK fall time	t <sub>F</sub>	SCKx		5	-	5	-	ns
SCK rise time	t <sub>R</sub>	SCKx		-	5	-	5	ns

**Notes:**

- The above characteristics apply to CLK synchronous mode.
- t<sub>CYCP</sub> indicates the APB bus clock cycle time. For more information about the APB bus number to which the multi-function serial is connected, see 1. S6E2G Series Block Diagram in this data sheet.
- These characteristics only guarantee the following pins:  
 No chip select: SIN4\_0, SOT4\_0, SCK4\_0  
 Chip select: SIN6\_0, SOT6\_0, SCK6\_0, SCS60\_0, SCS61\_0, SCS62\_0, SCS63\_0
- When the external load capacitance C<sub>L</sub> = 30 pF. (For \*, when C<sub>L</sub> = 10 pF)



### 12.9.2 Recovery Cause: Reset

The time from reset release to the program operation start is shown.

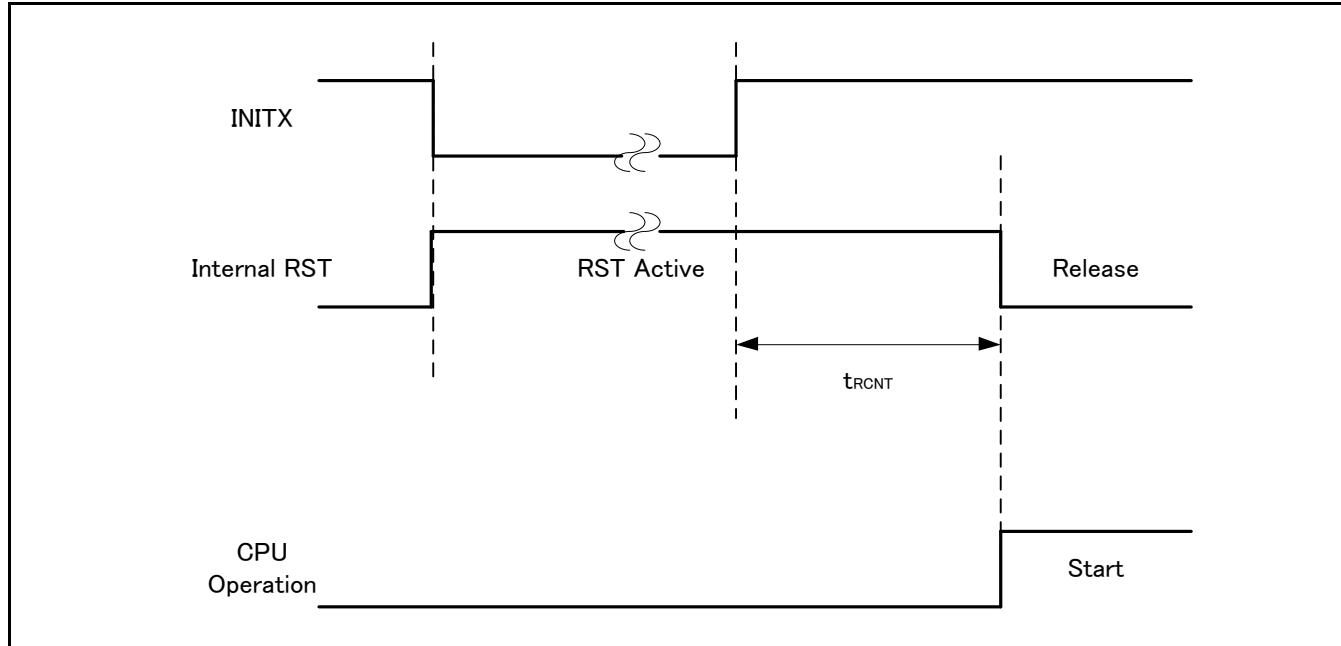
#### Recovery Count Time

(V<sub>CC</sub> = 2.7V to 5.5V, V<sub>SS</sub> = 0V)

Parameter	Symbol	Value		Unit	Remarks
		Typ	Max*		
Sleep mode	t <sub>RCNT</sub>	155	266	μs	
High-speed CR Timer mode		155	266	μs	
Main Timer mode		315	567	μs	
PLL Timer mode		315	567	μs	
Low-speed CR Timer mode		315	567	μs	
Sub Timer mode		315	567	μs	
RTC mode		315	567	μs	
Stop mode		336	667	μs	without RAM retention
Deep Standby RTC mode with RAM retention		336	667	μs	with RAM retention
Deep Standby Stop mode with RAM retention					

\*: The maximum value depends on the built-in CR accuracy.

#### Example of Standby Recovery Operation (when in INITX Recovery)



## Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at [Cypress Locations](#).

### Products

ARM® Cortex® Microcontrollers	<a href="http://cypress.com/arm">cypress.com/arm</a>
Automotive	<a href="http://cypress.com/automotive">cypress.com/automotive</a>
Clocks & Buffers	<a href="http://cypress.com/clocks">cypress.com/clocks</a>
Interface	<a href="http://cypress.com/interface">cypress.com/interface</a>
Internet of Things	<a href="http://cypress.com/iot">cypress.com/iot</a>
Memory	<a href="http://cypress.com/memory">cypress.com/memory</a>
Microcontrollers	<a href="http://cypress.com/mcu">cypress.com/mcu</a>
PSoC	<a href="http://cypress.com/psoc">cypress.com/psoc</a>
Power Management ICs	<a href="http://cypress.com/pmic">cypress.com/pmic</a>
Touch Sensing	<a href="http://cypress.com/touch">cypress.com/touch</a>
USB Controllers	<a href="http://cypress.com/usb">cypress.com/usb</a>
Wireless/RF	<a href="http://cypress.com/wireless">cypress.com/wireless</a>

### PSoC® Solutions

[PSoC 1](#) | [PSoC 3](#) | [PSoC 4](#) | [PSoC 5LP](#) | [PSoC 6](#)

### Cypress Developer Community

[Forums](#) | [WICED IOT Forums](#) | [Projects](#) | [Video](#) | [Blogs](#) | [Training](#) | [Components](#)

### Technical Support

[cypress.com/support](http://cypress.com/support)

ARM and Cortex are the registered trademarks of ARM Limited in the EU and other countries.

All other trademarks or registered trademarks referenced herein are the property of their respective owners.

© Cypress Semiconductor Corporation, 2015-2017. This document is the property of Cypress Semiconductor Corporation and its subsidiaries, including Spansion LLC ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Cypress products are not designed, intended, or authorized for use as critical components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or system could cause personal injury, death, or property damage ("Unintended Uses"). A critical component is any component of a device or system whose failure to perform can be reasonably expected to cause the failure of the device or system, or to affect its safety or effectiveness. Cypress is not liable, in whole or in part, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from or related to all Unintended Uses of Cypress products. You shall indemnify and hold Cypress harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of Cypress products.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit [cypress.com](http://cypress.com). Other names and brands may be claimed as property of their respective owners.