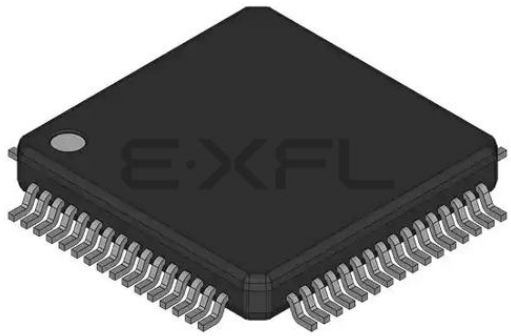

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	40MHz
Connectivity	I²C, LINbus, SCI, SPI
Peripherals	LVD, POR, PWM, WDT
Number of I/O	54
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-QFP
Supplier Device Package	64-QFP (14x14)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=mc9s08ac128cfue

Table of Contents

Related Documentation

MC9S08AC128 Series Reference Manual (MC9S08AC128RM)
contains extensive product information including modes of operartion, memory, resets and interrupts, register definitions, port pins, CPU, and all peripheral module information.

For the latest version of the documentation, check our website at:
http://www.freescale.com

Chapter 1
Device Overview

The MC9S08AC128 is a member of the low-cost, high-performance HCS08 Family of 8-bit microcontroller units (MCUs). The MC9S08AC128 uses the enhanced HCS08 core.

1.1 MCU Block Diagram

The block diagram in Figure 1-1 shows the structure of the MC9S08AC128 Series MCU.

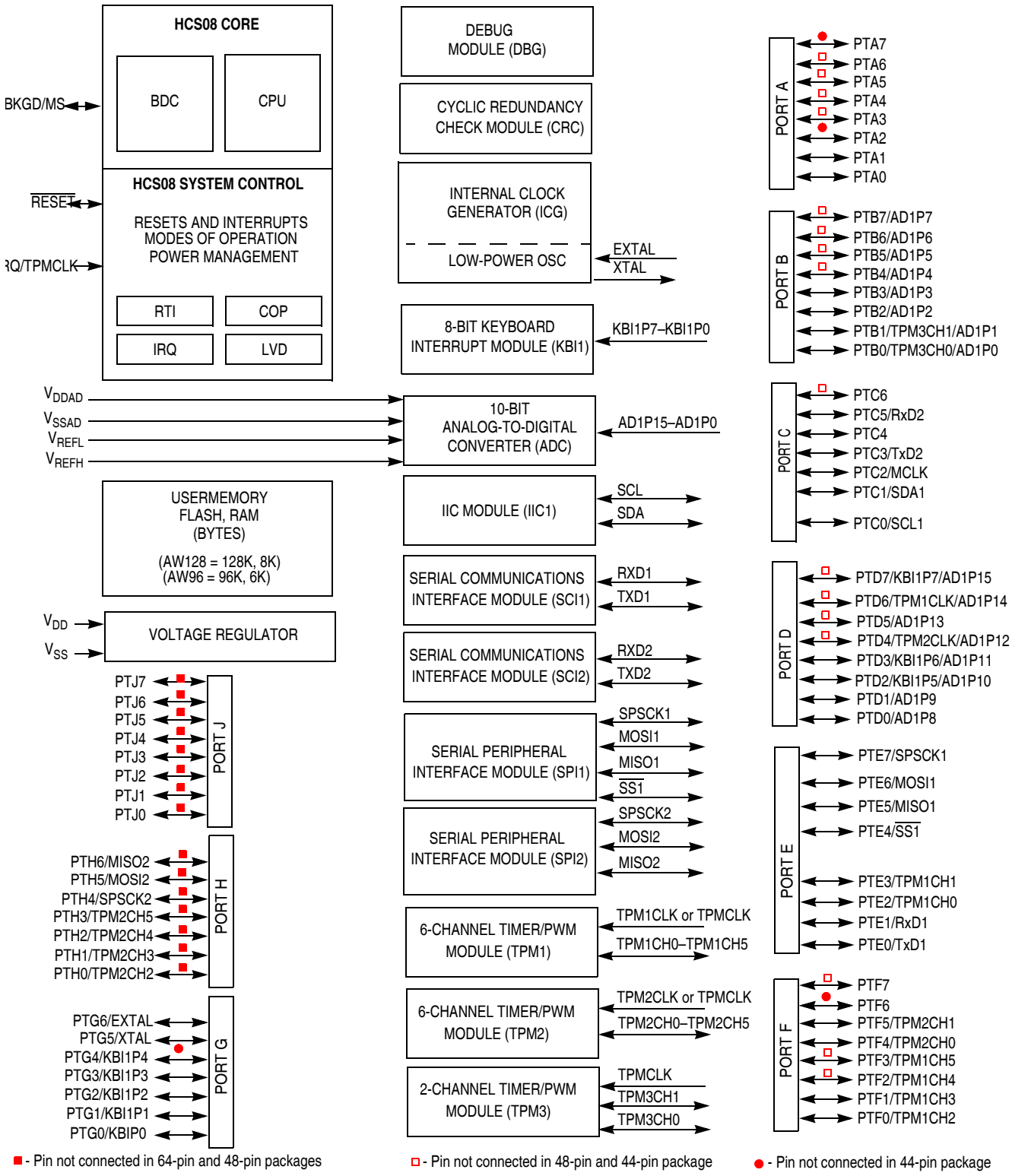
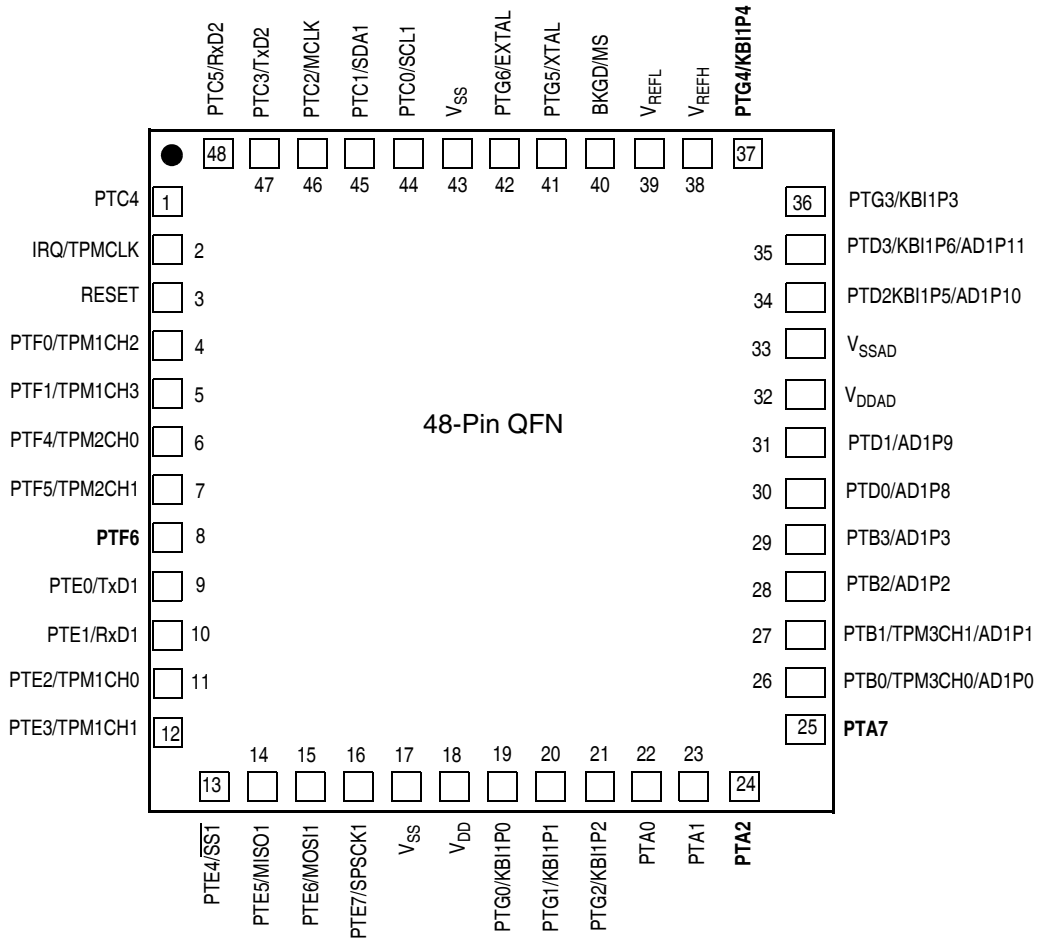


Figure 1-1. MC9S08AC128 Series Block Diagram

Figure 2-1 shows the 48-pin package assignments for the MC9S08AC128 Series devices.



Note: Pin names in **bold** are lost in lower pin count packages.

Figure 2-1. MC9S08AC128 Series in 48-Pin QFN Package

Table 2-4. Pin Availability by Package Pin-Count (continued)

Pin Number				Lowest <-- Priority --> Highest		
80	**64**	**48**	**44**	**Port Pin**	**Alt 1**	**Alt 2**
54	42	30	27	PTD0	AD1P8	
55	43	31	28	PTD1	AD1P9	
56	44	32	29	V_{DDAD}		
57	45	33	30	V_{SSAD}		
58	46	34	31	PTD2	KBI1P5	AD1P10
59	47	35	32	PTD3	KBI1P6	AD1P11
60	48	36	33	PTG3	KBI1P3	
61	49	37	—	PTG4	KBI1P4	
62	50	—	—	PTD4	TPM2CLK	AD1P12
63	51	—	—	PTD5	AD1P13	
64	52	—	—	PTD6	TPM1CLK	AD1P14
65	53	—	—	PTD7	KBI1P7	AD1P15
66	54	38	34	V_{REFH}		
67	55	39	35	V_{REFL}		
68	56	40	36	BKGD	MS	
69	57	41	37	PTG5	XTAL	
70	58	42	38	PTG6	EXTAL	
71	59	43	39	V_{SS}		
72	—	—	—	V_{DD}(NC)		
73	60	44	40	PTC0	SCL1	
74	61	45	41	PTC1	SDA1	
75	—	—	—	PTH4	SPSCK2	
76	—	—	—	PTH5	MOSI2	
77	—	—	—	PTH6	MISO2	
78	62	46	42	PTC2	MCLK	
79	63	47	43	PTC3	TxD2	
80	64	48	44	PTC5	RxD2	

[1] TPMCLK, TPM1CLK, and TPM2CLK options are configured via software; out of reset, TPM1CLK, TPM2CLK, and TPMCLK are available to TPM1, TPM2, and TPM3 respectively.

Solving equations 1 and 2 for K gives:

$$K = P_D \times (T_A + 273°C) + \theta_{JA} \times (P_D)^2 \qquad \textit{Eqn. 3-3}$$

where K is a constant pertaining to the particular part. K can be determined from equation 3 by measuring P_D (at equilibrium) for a known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving equations 1 and 2 iteratively for any value of T_A.

3.5 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions should be used to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

All ESD testing is in conformity with AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits and JEDEC Standard for Non-Automotive Grade Integrated Circuits. During the device qualification ESD stresses were performed for the Human Body Model (HBM), the Machine Model (MM) and the Charge Device Model (CDM).

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification. Complete DC parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.

Table 3-4. ESD and Latch-up Test Conditions

Model	Description	Symbol	Value	Unit
Human Body	Series Resistance	R1	1500	Ω
	Storage Capacitance	C	100	pF
	Number of Pulse per pin	–	3	
Machine	Series Resistance	R1	0	Ω
	Storage Capacitance	C	200	pF
	Number of Pulse per pin	–	3	
Latch-up	Minimum input voltage limit		– 2.5	V
	Maximum input voltage limit		7.5	V

Table 3-5. ESD and Latch-Up Protection Characteristics

Num	C	Rating	Symbol	Min	Max	Unit
1	C	Human Body Model (HBM)	V_{HBM}	± 2000	–	V
2	C	Machine Model (MM)	V_{MM}	± 200	–	V
3	C	Charge Device Model (CDM)	V_{CDM}	± 500	–	V
4	C	Latch-up Current at T_A = 125°C	I_{LAT}	± 100	–	mA

3.6 DC Characteristics

This section includes information about power supply requirements, I/O pin characteristics, and power supply current in various operating modes.

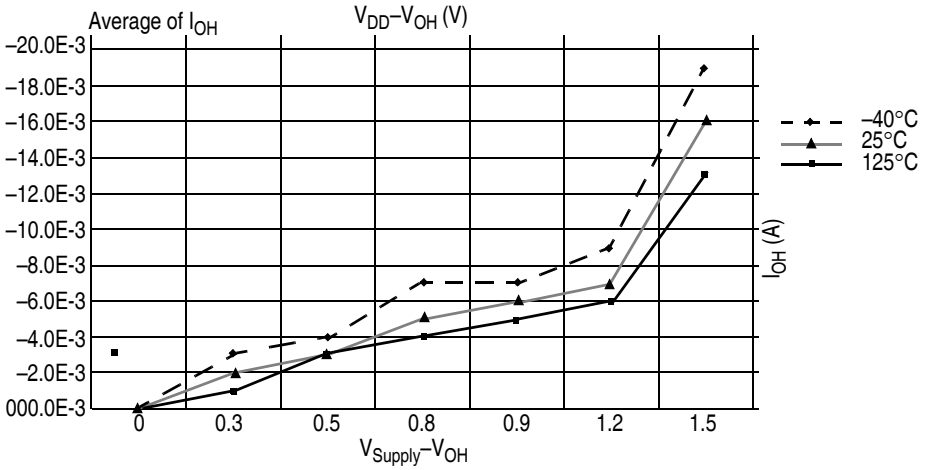


Figure 3-2. Typical I_{OH} (High Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 3 V

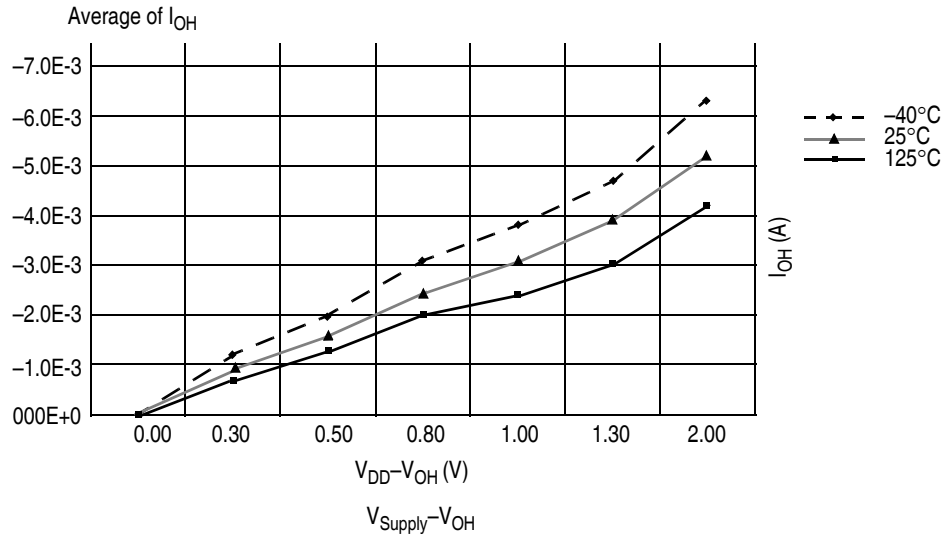


Figure 3-3. Typical I_{OH} (Low Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 5 V

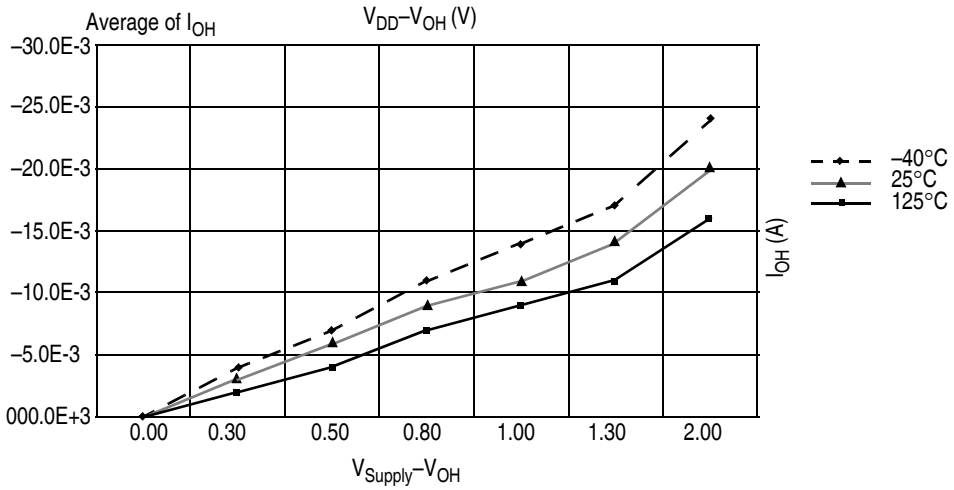


Figure 3-4. Typical I_{OH} (High Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 5 V

3.7 Supply Current Characteristics

Table 3-7. Supply Current Characteristics

Num	C	Parameter	Symbol	V_{DD} (V)	Typ[1]	Max	Unit	Temp (°C)
1	C	Run supply current[2] measured at (CPU clock = 2 MHz, f_{Bus} = 1 MHz)	RI_{DD}	5	1.1	1.4[3]	mA	–40 to 125°C
				3	1.0	1.2		
2	C	Run supply current[4] measured at (CPU clock = 16 MHz, f_{Bus} = 8 MHz)	RI_{DD}	5	6.7	8.0[5]	mA	–40 to 125°C
				3	6	7.5		
3	C	Stop2 mode supply current	$S2I_{DD}$	5	1.0	25 160	µA	–40 to 85°C –40 to 125°C
				3	0.8	23 150	µA	–40 to 85°C –40 to 125°C
4	C	Stop3 mode supply current	$S3I_{DD}$	5	1.2	27 180[3]	µA	–40 to 85°C –40 to 125°C
				3	1.0	25 170	µA	–40 to 85°C –40 to 125°C
5	C	RTI adder to stop2 or stop3[6]	$S23I_{DDRTI}$	5	300	500 500	nA	–40 to 85°C –40 to 125°C
				3	300	500 500	nA	–40 to 85°C –40 to 125°C
6	C	LVD adder to stop3 (LVDE = LVDSE = 1)	$S3I_{DDLVD}$	5	110	180 180	µA	–40 to 85°C –40 to 125°C
				3	90	160 160	µA	–40 to 85°C –40 to 125°C
7	C	Adder to stop3 for oscillator enabled[7] (OSCSTEN =1)	$S3I_{DDOSC}$	5,3	5	8 8	µA µA	–40 to 85°C –40 to 125°C

1 Typical values are based on characterization data at 25°C unless otherwise stated. See Figure 3-5 through Figure 3-7 for typical curves across voltage/temperature.

2 All modules except ADC active, ICG configured for FBE, and does not include any dc loads on port pins

3 Every unit tested to this parameter. All other values in the Max column are guaranteed by characterization.

4 All modules except ADC active, ICG configured for FBE, and does not include any dc loads on port pins

5 Every unit tested to this parameter. All other values in the Max column are guaranteed by characterization.

6 Most customers are expected to find that auto-wakeup from stop2 or stop3 can be used instead of the higher current wait mode. Wait mode typical is 560 µA at 3 V with f_{Bus} = 1 MHz.

7 Values given under the following conditions: low range operation (RANGE = 0) with a 32.768kHz crystal, low power mode (HGO = 0), clock monitor disabled (LOCD = 1).

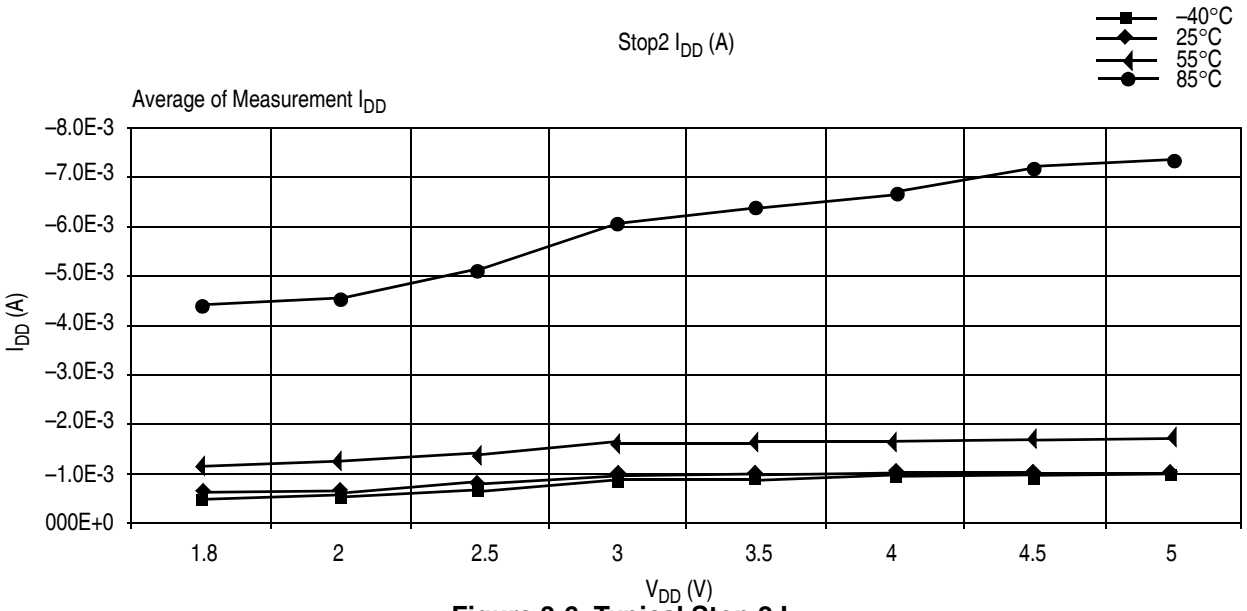


Figure 3-6. Typical Stop 2 I_{DD}

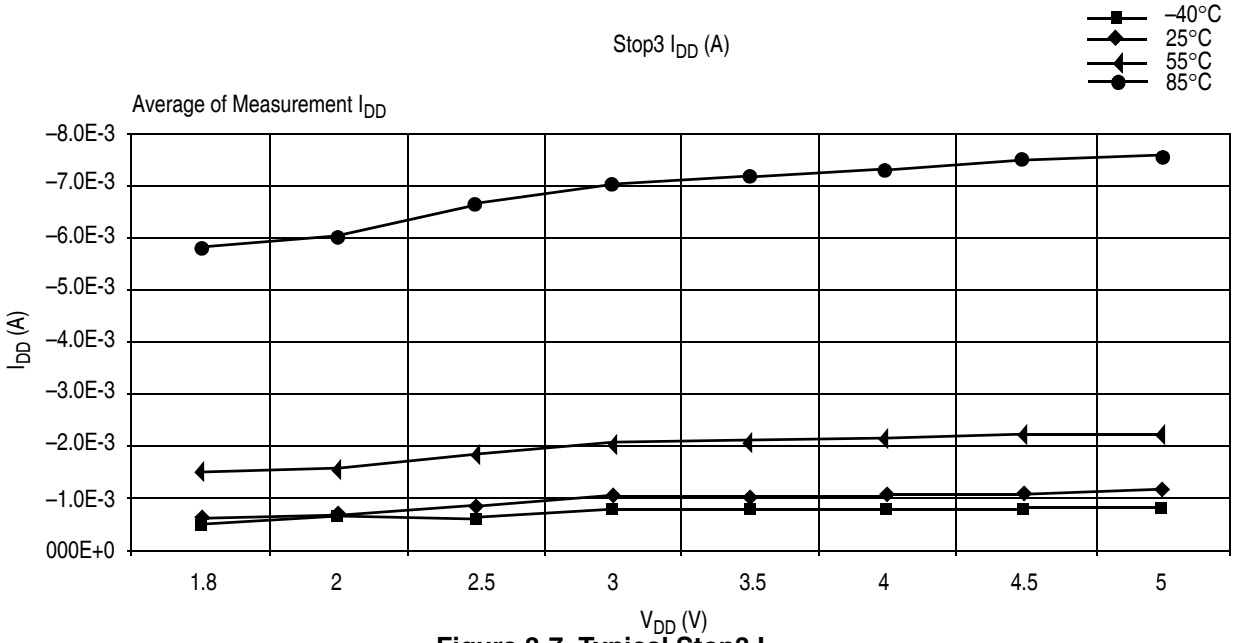


Figure 3-7. Typical Stop3 I_{DD}

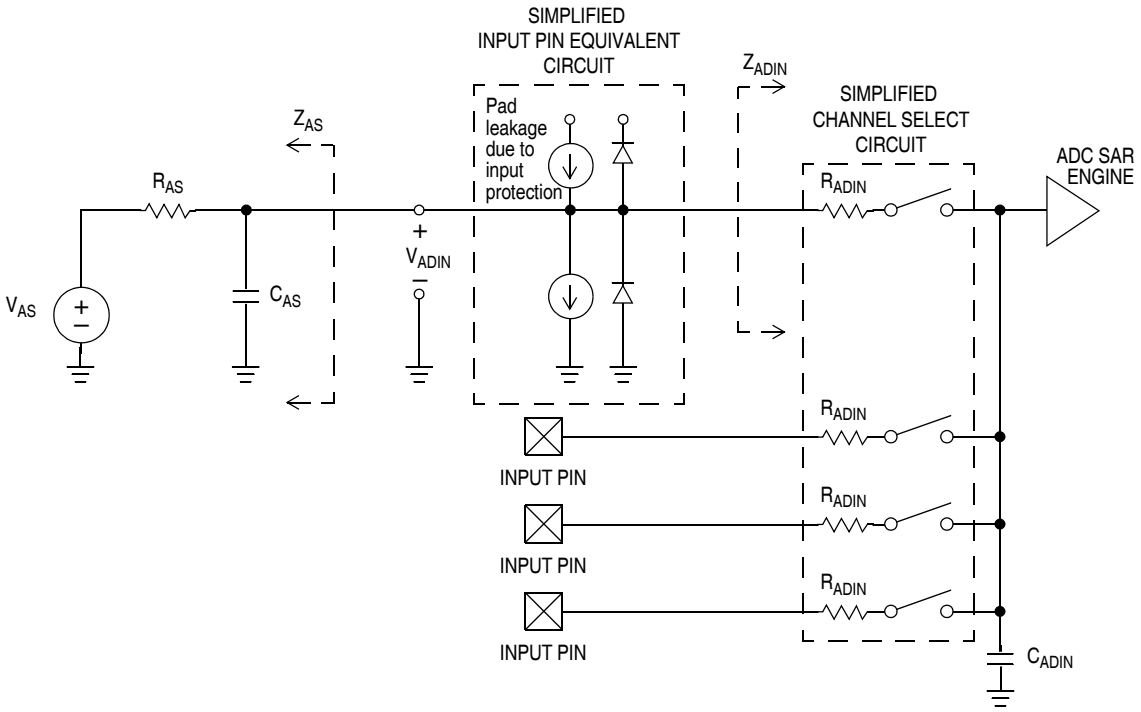


Figure 3-8. ADC Input Impedance Equivalency Diagram

Table 3-9. 5 Volt 10-bit ADC Characteristics ($V_{REFH} = V_{DDAD}$, $V_{REFL} = V_{SSAD}$)

Characteristic	Conditions	C	Symb	Min	Typ[1]	Max	Unit
Supply current ADLPC = 1 ADLSMP = 1 ADCO = 1		T	I_{DDAD}	—	133	—	μA
Supply current ADLPC = 1 ADLSMP = 0 ADCO = 1		T	I_{DDAD}	—	218	—	μA
Supply current ADLPC = 0 ADLSMP = 1 ADCO = 1		T	I_{DDAD}	—	327	—	μA
Supply current ADLPC = 0 ADLSMP = 0 ADCO = 1		T	I_{DDAD}	—	582	—	μA
	$V_{DDAD} \leq 5.5$ V	P		—	—	1	mA
ADC asynchronous clock source $t_{ADACK} = 1/f_{ADACK}$	High speed (ADLPC = 0)	P	f_{ADACK}	2	3.3	5	MHz
	Low power (ADLPC = 1)			1.25	2	3.3	
Conversion time (Including sample time)	Short sample (ADLSMP = 0)	P	t_{ADC}	—	20	—	ADCK cycles
	Long sample (ADLSMP = 1)			—	40	—	
Sample time	Short sample (ADLSMP = 0)	P	t_{ADS}	—	3.5	—	ADCK cycles
	Long sample (ADLSMP = 1)			—	23.5	—	
Total unadjusted error Includes quantization	10-bit mode	P	E_{TUE}	—	±1	±2.5	LSB[2]
	8-bit mode			—	±0.5	±1.0	
Differential non-linearity	10-bit mode	P	DNL	—	±0.5	±1.0	LSB[2]
	8-bit mode			—	±0.3	±0.5	
	Monotonicity and no-missing-codes guaranteed						
Integral non-linearity	10-bit mode	C	INL	—	±0.5	±1.0	LSB[2]
	8-bit mode			—	±0.3	±0.5	
Zero-scale error $V_{ADIN} = V_{SSA}$	10-bit mode	P	E_{ZS}	—	±0.5	±1.5	LSB[2]
	8-bit mode			—	±0.5	±0.5	
Full-scale error $V_{ADIN} = V_{DDA}$	10-bit mode	P	E_{FS}	—	±0.5	±1.5	LSB[2]
	8-bit mode			—	±0.5	±0.5	
Quantization error	10-bit mode	D	E_Q	—	—	±0.5	LSB[2]
	8-bit mode			—	—	±0.5	

3.9.1 ICG Frequency Specifications

Table 3-11. ICG Frequency Specifications

(V_{DDA} = V_{DDA} (min) to V_{DDA} (max), Temperature Range = –40 to 125°C Ambient)

Num	C	Characteristic	Symbol	Min	Typ[1]	Max	Unit
1		Oscillator crystal or resonator (REFS = 1) (Fundamental mode crystal or ceramic resonator) Low range High range High Gain, FBE (HGO = 1,CLKS = 10) High Gain, FEE (HGO = 1,CLKS = 11) Low Power, FBE (HGO = 0, CLKS = 10) Low Power, FEE (HGO = 0, CLKS = 11)	 flo fhi_byp fhi_eng flp_byp flp_eng	 32 1 2 1 2	 — — — 	 100 16 10 8 8	 kHz MHz MHz MHz MHz
2		Input clock frequency (CLKS = 11, REFS = 0) Low range High range	 f_{lo} f_{hi_eng}	 32 2	 — —	 100 10	 kHz MHz
3		Input clock frequency (CLKS = 10, REFS = 0)	f_{Extal}	0	—	40	MHz
4		Internal reference frequency (untrimmed)	$f_{ICGIRCLK}$	182.25	243	303.75	kHz
5		Duty cycle of input clock (REFS = 0)	t_{dc}	40	—	60	%
6		Output clock ICGOUT frequency CLKS = 10, REFS = 0 All other cases	f_{ICGOUT}	f_{Extal} (min) f_{lo} (min)	— —	f_{Extal} (max) $f_{ICGDCLKmax}$(max)	MHz
7		Minimum DCO clock (ICGDCLK) frequency	$f_{ICGDCLKmin}$	3	—		MHz
8		Maximum DCO clock (ICGDCLK) frequency	$f_{ICGDCLKmax}$		—	40	MHz
9		Self-clock mode (ICGOUT) frequency [2]	f_{Self}	$f_{ICGDCLKmin}$		$f_{ICGDCLKmax}$	MHz
10		Self-clock mode reset (ICGOUT) frequency	f_{Self_reset}	5.5	8	10.5	MHz
11		Loss of reference frequency [3] Low range High range	f_{LOR}	5 50		25 500	kHz
12		Loss of DCO frequency [4]	f_{LOD}	0.5		1.5	MHz
13		Crystal start-up time [5, 6] Low range High range	t_{CSTL} t_{CSTH}	— —	430 4	— —	ms
14		FLL lock time [, 7] Low range High range	t_{Lockl} t_{Lockh}	— —		2 2	ms
15		FLL frequency unlock range	n_{Unlock}	–4*N		4*N	counts
16		FLL frequency lock range	n_{Lock}	–2*N		2*N	counts
17		ICGOUT period jitter, [8] measured at f_{ICGOUT} Max Long term jitter (averaged over 2 ms interval)	C_{Jitter}	—		0.2	% f_{ICG}
18		Internal oscillator deviation from trimmed frequency[9] V_{DD} = 2.7 – 5.5 V, (constant temperature) V_{DD} = 5.0 V ±10%, –40° C to 125°C	ACC_{int}	— —	±0.5 ±0.5	±2 ±2	%

1 Typical values are based on characterization data at V_{DD} = 5.0V, 25°C unless otherwise stated.

2 Self-clocked mode frequency is the frequency that the DCO generates when the FLL is open-loop.

3.10 AC Characteristics

This section describes ac timing characteristics for each peripheral system.

3.10.1 Control Timing

Table 3-12. Control Timing

Num	C	Parameter	Symbol	Min	Typ[1]	Max	Unit
1		Bus frequency (t_{cyc} = 1/f_{Bus})	f_{Bus}	dc	—	20	MHz
2		Real-time interrupt internal oscillator period	t_{RTI}	600		1500	µs
3		External reset pulse width[2] (t_{cyc} = 1/f_{Self_reset})	t_{extrst}	1.5 x t_{Self_reset}		—	ns
4		Reset low drive[3]	t_{rstdrv}	34 x t_{cyc}		—	ns
5		Active background debug mode latch setup time	t_{MSSU}	25		—	ns
6		Active background debug mode latch hold time	t_{MSH}	25		—	ns
7		IRQ pulse width Asynchronous path[2] Synchronous path[4]	t_{ILIH}, t_{IHIL}	 100 1.5 x t_{cyc}	 — —	 — —	ns
8		KBIPx pulse width Asynchronous path[2] Synchronous path[3]	t_{ILIH}, t_{IHIL}	 100 1.5 x t_{cyc}	 — —	 — —	ns
9		Port rise and fall time (load = 50 pF)[5] Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	t_{Rise}, t_{Fall}	 — —	 3 30	 	ns

1 Typical values are based on characterization data at V_{DD} = 5.0V, 25°C unless otherwise stated.

2 This is the shortest pulse that is guaranteed to be recognized as a reset pin request. Shorter pulses are not guaranteed to override reset requests from internal sources.

3 When any reset is initiated, internal circuitry drives the reset pin low for about 34 bus cycles and then samples the level on the reset pin about 38 bus cycles later to distinguish external reset requests from internal requests.

4 This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized in that case.

5 Timing is shown with respect to 20% V_{DD} and 80% V_{DD} levels. Temperature range –40°C to 125°C.

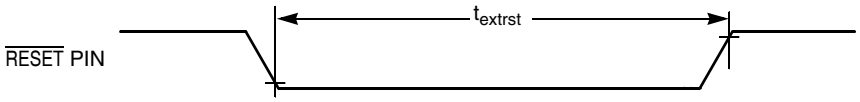


Figure 3-10. Reset Timing

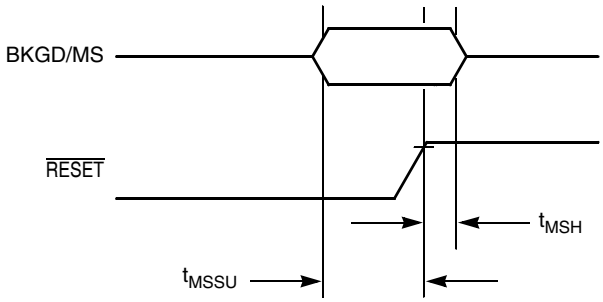


Figure 3-11. Active Background Debug Mode Latch Timing

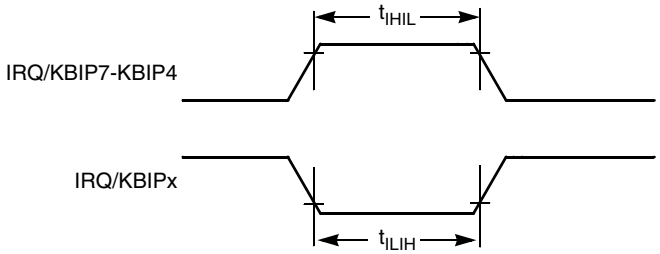


Figure 3-12. IRQ/KBIPx Timing

3.10.2 Timer/PWM (TPM) Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 3-13. TPM Input Timing

Function	Symbol	Min	Max	Unit
External clock frequency	f_{TPMext}	dc	$f_{Bus}/4$	MHz
External clock period	t_{TPMext}	4	—	t_{cyc}
External clock high time	t_{clkh}	1.5	—	t_{cyc}
External clock low time	t_{clkl}	1.5	—	t_{cyc}
Input capture pulse width	t_{ICPW}	1.5	—	t_{cyc}

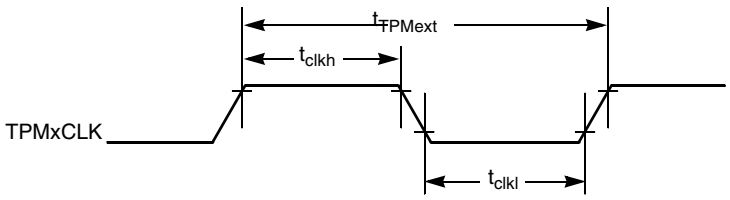


Figure 3-13. Timer External Clock

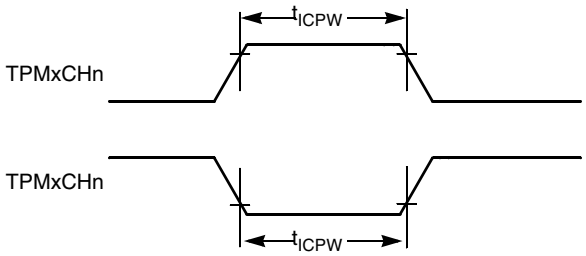


Figure 3-14. Timer Input Capture Pulse

3.11 SPI Characteristics

Table 3-14 and Figure 3-15 through Figure 3-18 describe the timing requirements for the SPI system.

Table 3-14. SPI Electrical Characteristic

Num[1]	C	Characteristic[2]	Symbol	Min	Max	Unit
		Operating frequency[3] Master Slave	 f_{op} f_{op}	 $f_{Bus}/2048$ dc	 $f_{Bus}/2$ $f_{Bus}/4$	Hz
1		Cycle time Master Slave	 t_{SCK} t_{SCK}	 2 4	 2048 —	 t_{cyc} t_{cyc}
2		Enable lead time Master Slave	 t_{Lead} t_{Lead}	 — 1/2	 1/2 —	 t_{SCK} t_{SCK}
3		Enable lag time Master Slave	 t_{Lag} t_{Lag}	 — 1/2	 1/2 —	 t_{SCK} t_{SCK}
4		Clock (SPSCK) high time Master and Slave	t_{SCKH}	1/2 t_{SCK} – 25	—	ns
5		Clock (SPSCK) low time Master and Slave	t_{SCKL}	1/2 t_{SCK} – 25	—	ns
6		Data setup time (inputs) Master Slave	 $t_{SI(M)}$ $t_{SI(S)}$	 30 30	 — —	 ns ns
7		Data hold time (inputs) Master Slave	 $t_{HI(M)}$ $t_{HI(S)}$	 30 30	 — —	 ns ns
8		Access time, slave[4]	t_A	0	40	ns
9		Disable time, slave[5]	t_{dis}	—	40	ns
10		Data setup time (outputs) Master Slave	 t_{SO} t_{SO}	 25 25	 — —	 ns ns
11		Data hold time (outputs) Master Slave	 t_{HO} t_{HO}	 –10 –10	 — —	 ns ns

1 Refer to Figure 3-15 through Figure 3-18.

2 All timing is shown with respect to 20% V_{DD} and 70% V_{DD}, unless noted; 100 pF load on all SPI pins. All timing assumes slew rate control disabled and high drive strength enabled for SPI output pins.

3 Maximum baud rate must be limited to 5 MHz due to pad input characteristics.

4 Time to data active from high-impedance state.

5 Hold time to high-impedance state.

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