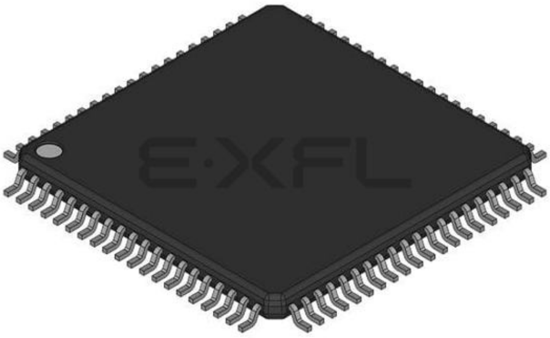
Freescale Semiconductor - MC9S08AC128MLKE Datasheet



What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	40MHz
Connectivity	I²C, LINbus, SCI, SPI
Peripherals	LVD, POR, PWM, WDT
Number of I/O	69
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	80-LQFP
Supplier Device Package	80-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=mc9s08ac128mlke

Part Number	Package Description	Original (gold wire) package document number	Current (copper wire) package document number
MC68HC908JW32	48 QFN	98ARH99048A	98ASA00466D
MC9S08AC16			
MC9S908AC60			
MC9S08AC128			
MC9S08AW60			
MC9S08GB60A			
MC9S08GT16A			
MC9S08JM16			
MC9S08JM60			
MC9S08LL16			
MC9S08QE128			
MC9S08QE32			
MC9S08RG60			
MCF51CN128			
MC9RS08LA8	48 QFN	98ARL10606D	98ASA00466D
MC9S08GT16A	32 QFN	98ARH99035A	98ASA00473D
MC9S908QE32	32 QFN	98ARE10566D	98ASA00473D
MC9S908QE8	32 QFN	98ASA00071D	98ASA00736D
MC9S08JS16	24 QFN	98ARL10608D	98ASA00734D
MC9S08QB8			
MC9S08QG8	24 QFN	98ARL10605D	98ASA00474D
MC9S08SH8	24 QFN	98ARE10714D	98ASA00474D
MC9RS08KB12	24 QFN	98ASA00087D	98ASA00602D
MC9S08QG8	16 QFN	98ARE10614D	98ASA00671D
MC9RS08KB12	8 DFN	98ARL10557D	98ASA00672D
MC9S08QG8			
MC9RS08KA2	6 DFN	98ARL10602D	98ASA00735D

Chapter 1
Device Overview

The MC9S08AC128 is a member of the low-cost, high-performance HCS08 Family of 8-bit microcontroller units (MCUs). The MC9S08AC128 uses the enhanced HCS08 core.

1.1 MCU Block Diagram

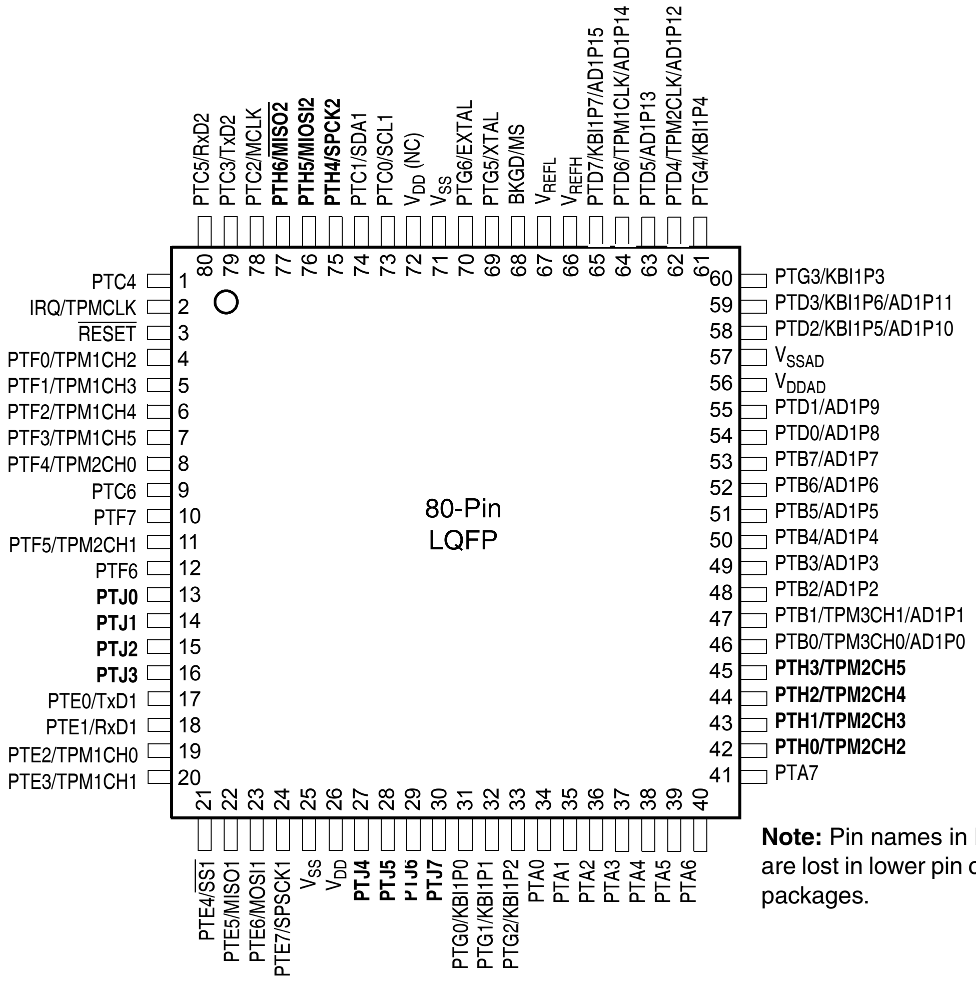
The block diagram in Figure 1-1 shows the structure of the MC9S08AC128 Series MCU.

Chapter 2
Pins and Connections

This section describes signals that connect to package pins. It includes pinout diagrams, recommended system connections, and detailed discussions of signals.

2.1 Device Pin Assignment

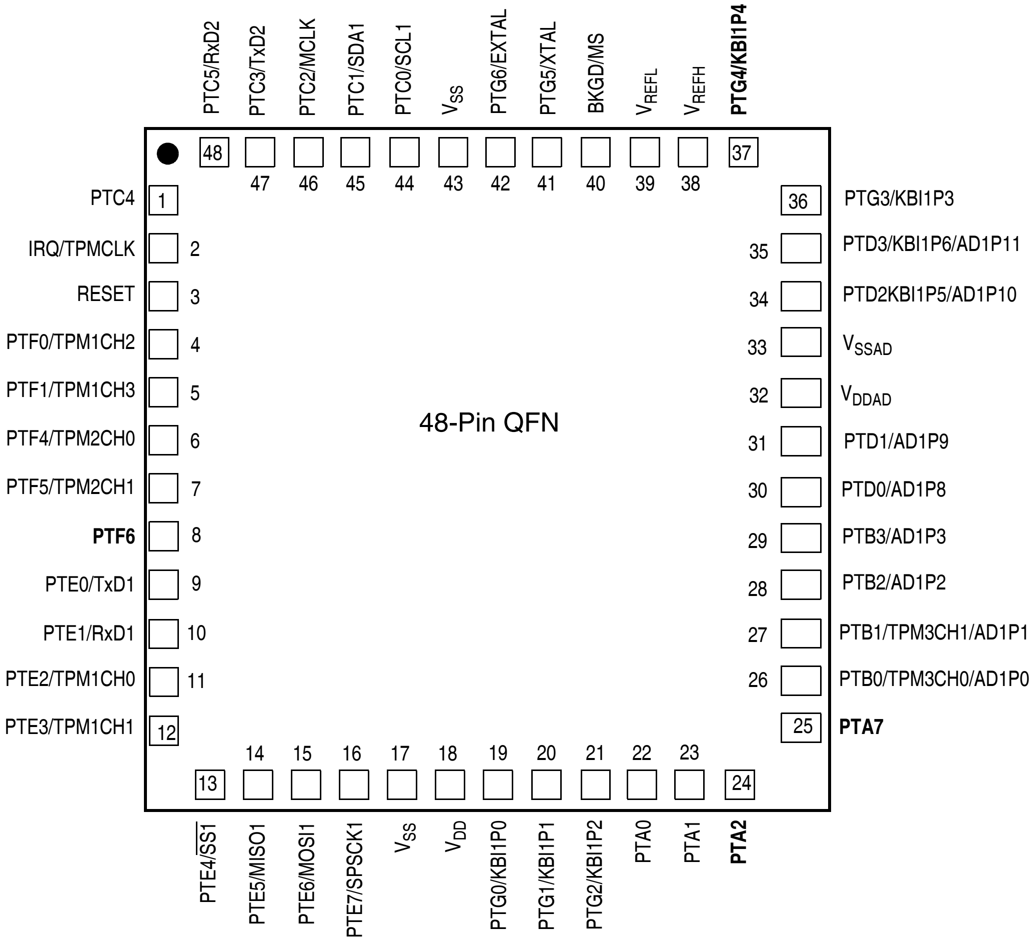
Figure 2-1 shows the 80-pin LQFP package pin assignments for the MC9S08AC128 Series device.



Note: Pin names in **bold** are lost in lower pin count packages.

Figure 2-1. MC9S08AC128 Series in 80-Pin LQFP Package

Figure 2-1 shows the 48-pin package assignments for the MC9S08AC128 Series devices.



Note: Pin names in **bold** are lost in lower pin count packages.

Figure 2-1. MC9S08AC128 Series in 48-Pin QFN Package

Figure 2-3 shows the 44-pin LQFP pin assignments for the MC9S08AC128 Series device.

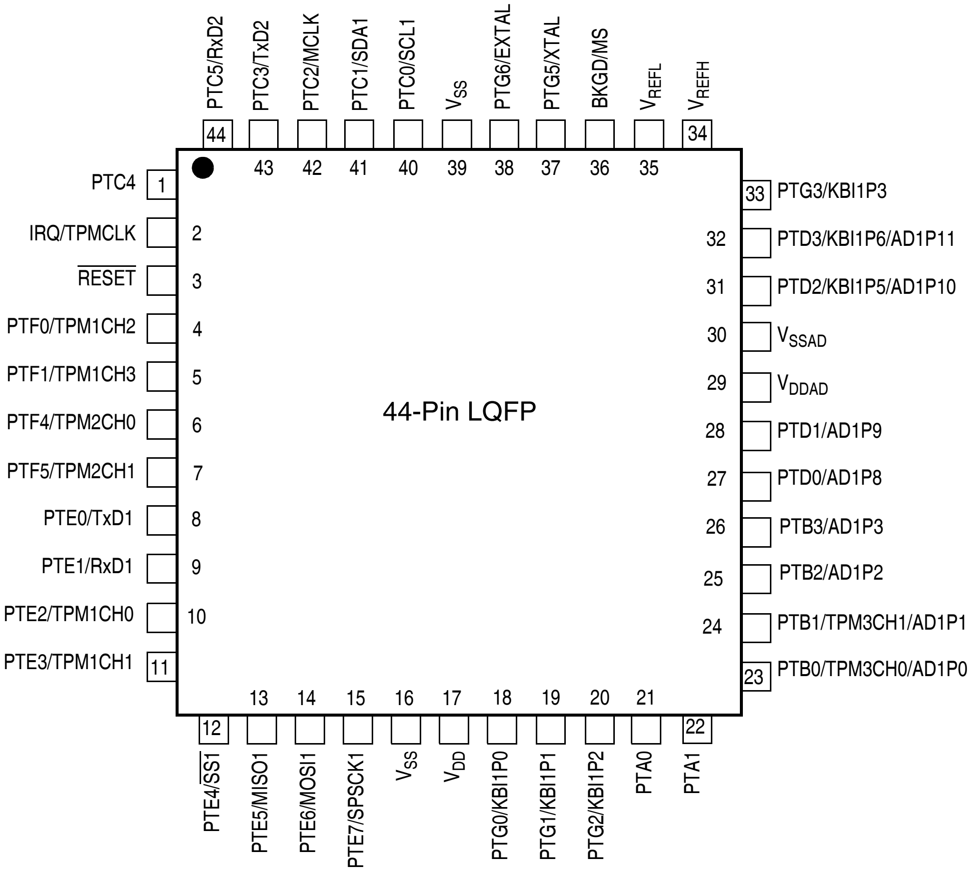


Figure 2-3. MC9S08AC128 Series in 44-Pin LQFP Package

Table 2-4. Pin Availability by Package Pin-Count

Pin Number				Lowest <--	Priority	--> Highest
80	64	48	44	Port Pin	Alt 1	Alt 2
1	1	1	1	PTC4		
2	2	2	2	IRQ	TPMCLK[1]	
3	3	3	3	RESET		
4	4	4	4	PTF0	TPM1CH2	
5	5	5	5	PTF1	TPM1CH3	
6	6	—	—	PTF2	TPM1CH4	
7	7	—	—	PTF3	TPM1CH5	
8	8	6	6	PTF4	TPM2CH0	
9	9	—	—	PTC6		
10	10	—	—	PTF7		
11	11	7	7	PTF5	TPM2CH1	
12	12	8	—	PTF6		

Table 2-4. Pin Availability by Package Pin-Count (continued)

Pin Number				Lowest <--	Priority	--> Highest
80	**64**	**48**	**44**	**Port Pin**	**Alt 1**	**Alt 2**
13	—	—	—	PTJ0		
14	—	—	—	PTJ1		
15	—	—	—	PTJ2		
16	—	—	—	PTJ3		
17	13	9	8	PTE0	TxD1	
18	14	10	9	PTE1	RxD1	
19	15	11	10	PTE2	TPM1CH0	
20	16	12	11	PTE3	TPM1CH1	
21	17	13	12	PTE4	$\overline{SS1}$	
22	18	14	13	PTE5	MISO1	
23	19	15	14	PTE6	MOSI1	
24	20	16	15	PTE7	SPSCK1	
25	21	17	16	V_{SS}		
26	22	18	17	V_{DD}		
27	—	—	—	PTJ4		
28	—	—	—	PTJ5		
29	—	—	—	PTJ6		
30	—	—	—	PTJ7		
31	23	19	18	PTG0	KBI1P0	
32	24	20	19	PTG1	KBI1P1	
33	25	21	20	PTG2	KBI1P2	
34	26	22	21	PTA0		
35	27	23	22	PTA1		
36	28	24	—	PTA2		
37	29	—	—	PTA3		
38	30	—	—	PTA4		
39	31	—	—	PTA5		
40	32	—	—	PTA6		
41	33	25	—	PTA7		
42	—	—	—	PTH0	TPM2CH2	
43	—	—	—	PTH1	TPM2CH3	
44	—	—	—	PTH2	TPM2CH4	
45	—	—	—	PTH3	TPM2CH5	
46	34	26	23	PTB0	TPM3CH0	AD1P0
47	35	27	24	PTB1	TPM3CH1	AD1P1
48	36	28	25	PTB2	AD1P2	
49	37	29	26	PTB3	AD1P3	
50	38	—	—	PTB4	AD1P4	
51	39	—	—	PTB5	AD1P5	
52	40	—	—	PTB6	AD1P6	
53	41	—	—	PTB7	AD1P7	

Chapter 3
Electrical Characteristics and Timing Specifications

3.1 Introduction

This section contains electrical and timing specifications.

3.2 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

Table 3-1. Parameter Classifications

P	Those parameters are guaranteed during production testing on each individual device.
C	Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.
T	Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category.
D	Those parameters are derived mainly from simulations.

NOTE

The classification is shown in the column labeled “C” in the parameter tables where appropriate.

3.3 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in Table 3-2 may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either V_{SS} or V_{DD}).

Solving equations 1 and 2 for K gives:

$$K = P_D \times (T_A + 273°C) + \theta_{JA} \times (P_D)^2 \qquad \textit{Eqn. 3-3}$$

where K is a constant pertaining to the particular part. K can be determined from equation 3 by measuring P_D (at equilibrium) for a known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving equations 1 and 2 iteratively for any value of T_A.

3.5 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions should be used to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

All ESD testing is in conformity with AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits and JEDEC Standard for Non-Automotive Grade Integrated Circuits. During the device qualification ESD stresses were performed for the Human Body Model (HBM), the Machine Model (MM) and the Charge Device Model (CDM).

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification. Complete DC parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.

Table 3-4. ESD and Latch-up Test Conditions

Model	Description	Symbol	Value	Unit
Human Body	Series Resistance	R1	1500	Ω
	Storage Capacitance	C	100	pF
	Number of Pulse per pin	–	3	
Machine	Series Resistance	R1	0	Ω
	Storage Capacitance	C	200	pF
	Number of Pulse per pin	–	3	
Latch-up	Minimum input voltage limit		– 2.5	V
	Maximum input voltage limit		7.5	V

Table 3-5. ESD and Latch-Up Protection Characteristics

Num	C	Rating	Symbol	Min	Max	Unit
1	C	Human Body Model (HBM)	V_{HBM}	± 2000	–	V
2	C	Machine Model (MM)	V_{MM}	± 200	–	V
3	C	Charge Device Model (CDM)	V_{CDM}	± 500	–	V
4	C	Latch-up Current at $T_A = 125°C$	I_{LAT}	± 100	–	mA

3.6 DC Characteristics

This section includes information about power supply requirements, I/O pin characteristics, and power supply current in various operating modes.

Table 3-6. DC Characteristics

Num	C	Parameter	Symbol	Min	Typ[1]	Max	Unit
1	—	Operating Voltage	V_{DD}	2.7	—	5.5	V
2	P	Output high voltage — Low Drive (PTxDSn = 0) 5 V, I_{Load} = –2 mA 3 V, I_{Load} = –0.6 mA 5 V, I_{Load} = –0.4 mA 3 V, I_{Load} = –0.24 mA	V_{OH}	 V_{DD} – 1.5 V_{DD} – 1.5 V_{DD} – 0.8 V_{DD} – 0.8	 — — — —	 — — — —	V
	P	Output high voltage — High Drive (PTxDSn = 1) 5 V, I_{Load} = –10 mA 3 V, I_{Load} = –3 mA 5 V, I_{Load} = –2 mA 3 V, I_{Load} = –0.4 mA		 V_{DD} – 1.5 V_{DD} – 1.5 V_{DD} – 0.8 V_{DD} – 0.8	 — — — —	 — — — —	
3	P	Output low voltage — Low Drive (PTxDSn = 0) 5 V, I_{Load} = 2 mA 3 V, I_{Load} = 0.6 mA 5 V, I_{Load} = 0.4 mA 3 V, I_{Load} = 0.24 mA	V_{OL}	 — — — —	 — — — —	 1.5 1.5 0.8 0.8	V
	P	Output low voltage — High Drive (PTxDSn = 1) 5 V, I_{Load} = 10 mA 3 V, I_{Load} = 3 mA 5 V, I_{Load} = 2 mA 3 V, I_{Load} = 0.4 mA		 — — — —	 — — — —	 1.5 1.5 0.8 0.8	
4	P	Output high current — Max total I_{OH} for all ports 5V 3V	I_{OHT}	 — —	 — —	 100 60	mA
5	P	Output low current — Max total I_{OL} for all ports 5V 3V	I_{OLT}	 — —	 — —	 100 60	mA
6	P	Input high voltage; all digital inputs — $2.7v \le V_{DD}$ 4.5v	V_{IH}	$0.70xV_{DD}$	—	—	V
		$4.5v \le V_{DD} \le 5.5v$	V_{IH}	$0.65xV_{DD}$	—	—	
7	P	Input low voltage; all digital inputs	V_{IL}	—	—	0.35 x V_{DD}	
8	P	Input hysteresis; all digital inputs	V_{hys}	0.06 x V_{DD}			mV
9	P	Input leakage current; input only pins[2]	$\|I_{In}\|$	—	0.1	1	µA
10	P	High Impedance (off-state) leakage current[2]	$\|I_{OZ}\|$	—	0.1	1	µA
11	P	Internal pullup resistors[3]	R_{PU}	20	45	65	kΩ
12	P	Internal pulldown resistors[4]	R_{PD}	20	45	65	kΩ
13	C	Input Capacitance; all non-supply pins	C_{In}	—	—	8	pF
14	D	RAM retention voltage	V_{RAM}	—	0.6	1.0	V
15	P	POR rearm voltage	V_{POR}	0.9	1.4	2.0	V
16	D	POR rearm time	t_{POR}	10	—	—	µs
17	P	Low-voltage detection threshold — high range V_{DD} falling V_{DD} rising	V_{LVDH}	 4.2 4.3	 4.3 4.4	 4.4 4.5	V
18	P	Low-voltage detection threshold — low range V_{DD} falling V_{DD} rising	V_{LVDL}	 2.48 2.54	 2.56 2.62	 2.64 2.7	V

Table 3-6. DC Characteristics (continued)

Num	C	Parameter	Symbol	Min	Typ[1]	Max	Unit
19	P	Low-voltage warning threshold — high range V_{DD} falling V_{DD} rising	V_{LVWH}	4.2 4.3	4.3 4.4	4.4 4.5	V
20	P	Low-voltage warning threshold — low range V_{DD} falling V_{DD} rising	V_{LVWL}	2.48 2.54	2.56 2.62	2.64 2.7	V
21	P	Low-voltage inhibit reset/recover hysteresis 5V 3V	V_{hys}	— —	100 60	— —	mV
22	P	Bandgap Voltage Reference[5]	V_{BG}	1.170	1.200	1.230	V

[1] Typical values are based on characterization data at 25°C unless otherwise stated.

[2] Measured with $V_{In} = V_{DD}$ or V_{SS}.

[3] Measured with $V_{In} = V_{SS}$.

[4] Measured with $V_{In} = V_{DD}$.

[5] Factory trimmed at $V_{DD} = 3.0$ V, Temperature = 25 °C.

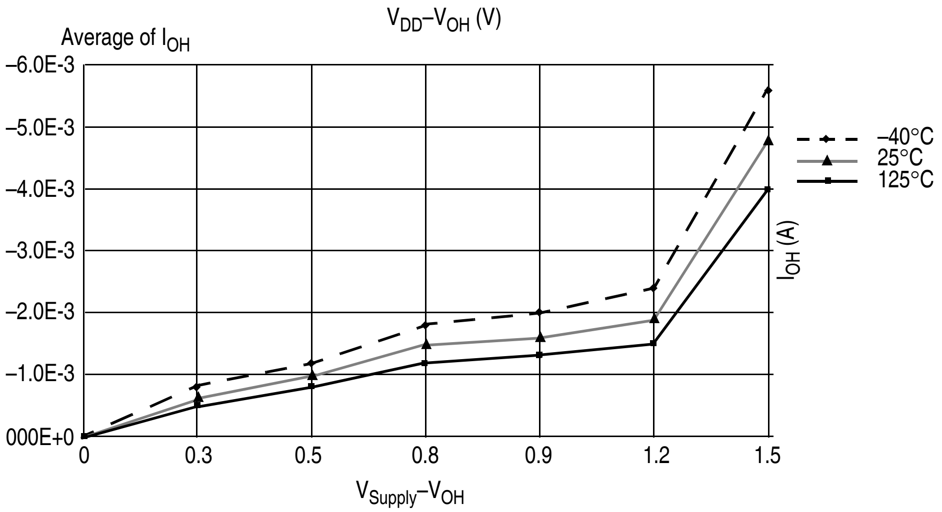


Figure 3-1. Typical I_{OH} (Low Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 3 V

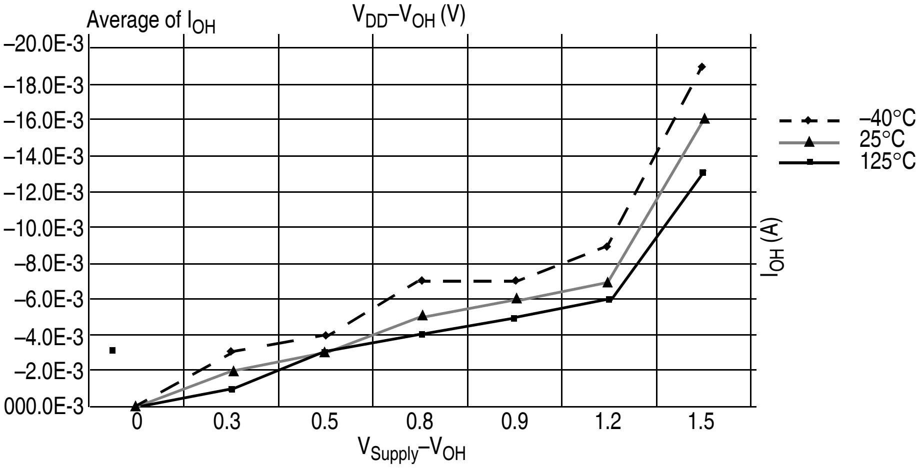


Figure 3-2. Typical I_{OH} (High Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 3 V

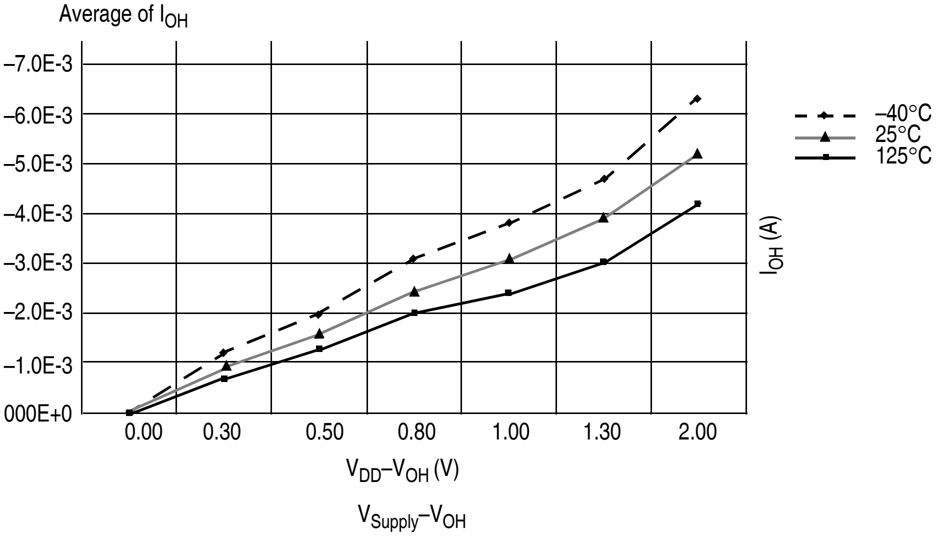


Figure 3-3. Typical I_{OH} (Low Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 5 V

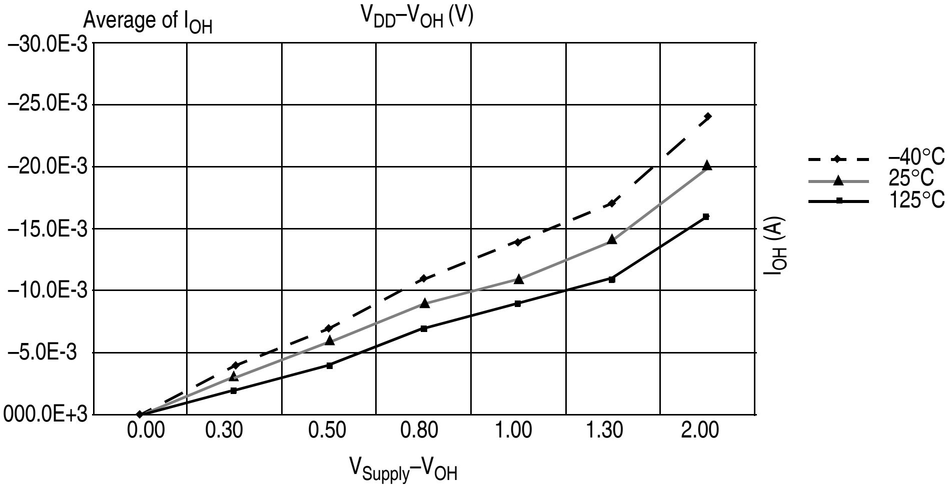
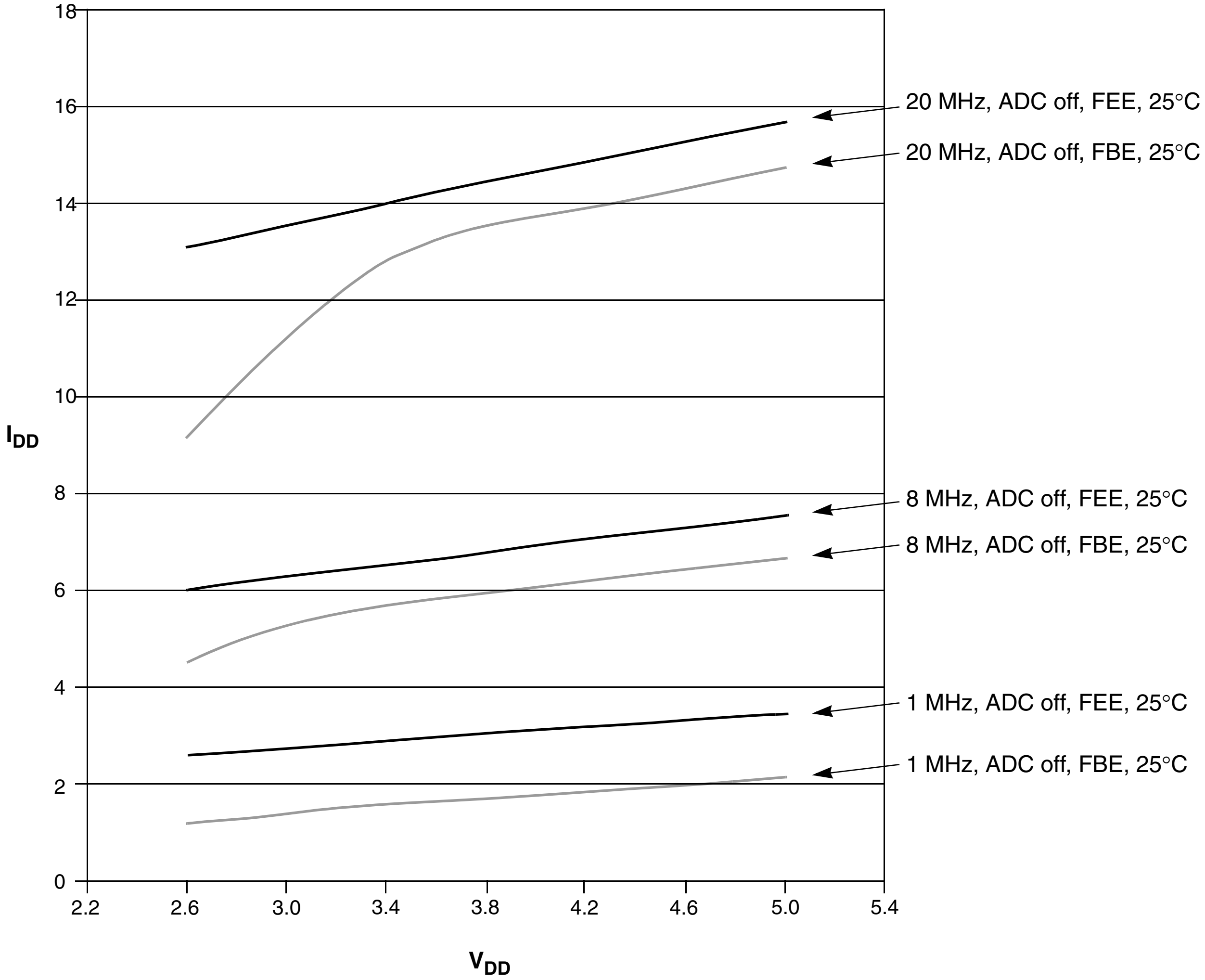


Figure 3-4. Typical I_{OH} (High Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 5 V



Note: External clock is square wave supplied by function generator. For FEE mode, external reference frequency is 4 MHz

Figure 3-5. Typical Run I_{DD} for FBE and FEE Modes, I_{DD} vs. V_{DD}

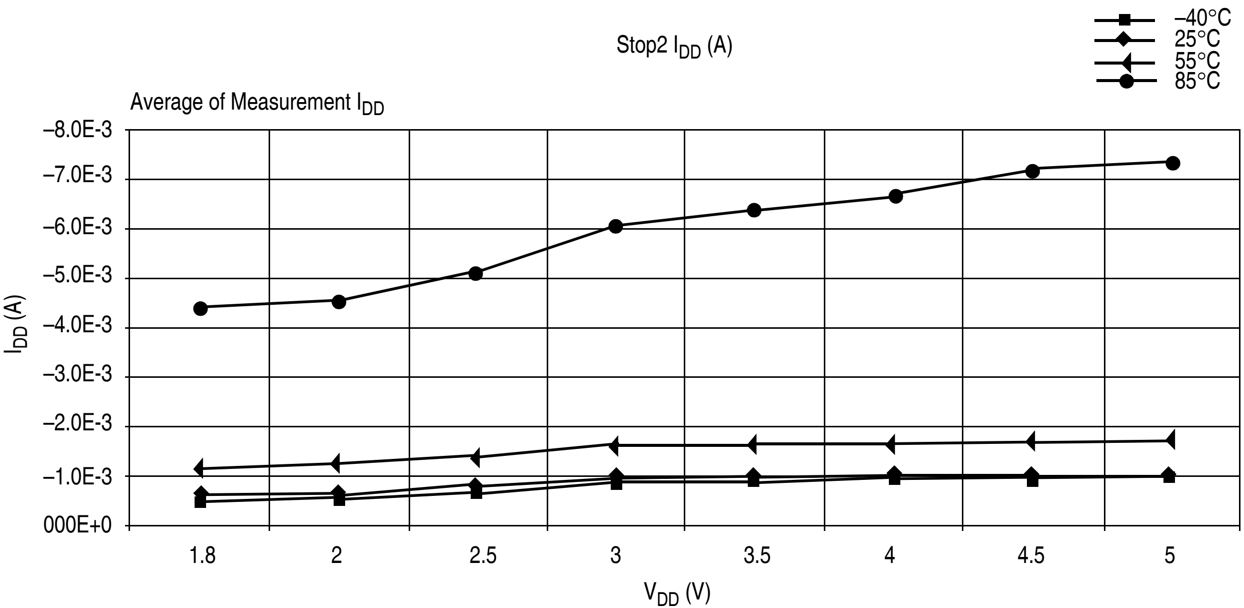


Figure 3-6. Typical Stop 2 I_{DD}

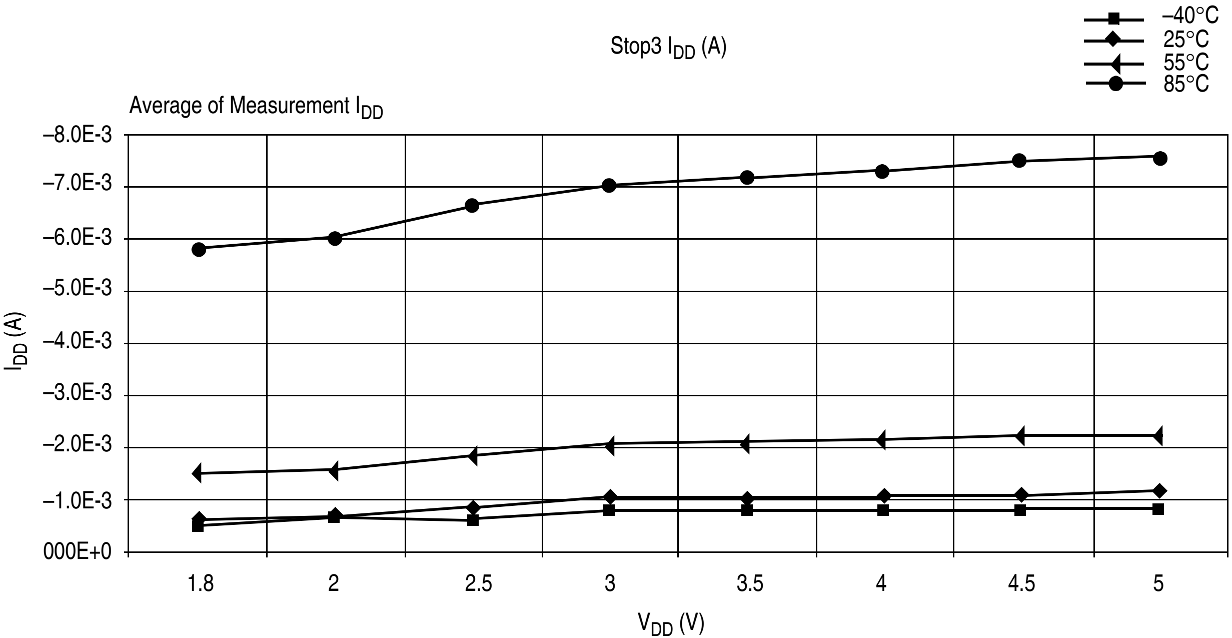


Figure 3-7. Typical Stop3 I_{DD}

3.9.1 ICG Frequency Specifications

Table 3-11. ICG Frequency Specifications

(V_{DDA} = V_{DDA} (min) to V_{DDA} (max), Temperature Range = –40 to 125°C Ambient)

Num	C	Characteristic	Symbol	Min	Typ[1]	Max	Unit
1		Oscillator crystal or resonator (REFS = 1) (Fundamental mode crystal or ceramic resonator) Low range High range High Gain, FBE (HGO = 1,CLKS = 10) High Gain, FEE (HGO = 1,CLKS = 11) Low Power, FBE (HGO = 0, CLKS = 10) Low Power, FEE (HGO = 0, CLKS = 11)	flo fhi_byp fhi_eng flp_byp flp_eng	32 1 2 1 2	— — —	100 16 10 8 8	kHz MHz MHz MHz MHz
2		Input clock frequency (CLKS = 11, REFS = 0) Low range High range	f_{lo} f_{hi_eng}	32 2	— —	100 10	kHz MHz
3		Input clock frequency (CLKS = 10, REFS = 0)	f_{Extal}	0	—	40	MHz
4		Internal reference frequency (untrimmed)	$f_{ICGIRCLK}$	182.25	243	303.75	kHz
5		Duty cycle of input clock (REFS = 0)	t_{dc}	40	—	60	%
6		Output clock ICGOUT frequency CLKS = 10, REFS = 0 All other cases	f_{ICGOUT}	f_{Extal} (min) f_{lo} (min)	— —	f_{Extal} (max) $f_{ICGDCLKmax}$(max)	MHz
7		Minimum DCO clock (ICGDCLK) frequency	$f_{ICGDCLKmin}$	3	—		MHz
8		Maximum DCO clock (ICGDCLK) frequency	$f_{ICGDCLKmax}$		—	40	MHz
9		Self-clock mode (ICGOUT) frequency [2]	f_{Self}	$f_{ICGDCLKmin}$		$f_{ICGDCLKmax}$	MHz
10		Self-clock mode reset (ICGOUT) frequency	f_{Self_reset}	5.5	8	10.5	MHz
11		Loss of reference frequency [3] Low range High range	f_{LOR}	5 50		25 500	kHz
12		Loss of DCO frequency [4]	f_{LOD}	0.5		1.5	MHz
13		Crystal start-up time [5, 6] Low range High range	t_{CSTL} t_{CSTH}	— —	430 4	— —	ms
14		FLL lock time ,[7] Low range High range	t_{Lockl} t_{Lockh}	— —		2 2	ms
15		FLL frequency unlock range	n_{Unlock}	–4*N		4*N	counts
16		FLL frequency lock range	n_{Lock}	–2*N		2*N	counts
17		ICGOUT period jitter, ,[8] measured at f_{ICGOUT} Max Long term jitter (averaged over 2 ms interval)	C_{Jitter}	—		0.2	% f_{ICG}
18		Internal oscillator deviation from trimmed frequency[9] V_{DD} = 2.7 – 5.5 V, (constant temperature) V_{DD} = 5.0 V ±10%, –40° C to 125°C	ACC_{int}	— —	±0.5 ±0.5	±2 ±2	%

[1] Typical values are based on characterization data at V_{DD} = 5.0V, 25°C unless otherwise stated.

[2] Self-clocked mode frequency is the frequency that the DCO generates when the FLL is open-loop.

[3] Loss of reference frequency is the reference frequency detected internally, which transitions the ICG into self-clocked mode if it is not in the desired range.

[4] Loss of DCO frequency is the DCO frequency detected internally, which transitions the ICG into FLL bypassed external mode (if an external reference exists) if it is not in the desired range.

[5] This parameter is characterized before qualification rather than 100% tested.

[6] Proper PC board layout procedures must be followed to achieve specifications.

[7] This specification applies to the period of time required for the FLL to lock after entering FLL engaged internal or external modes. If a crystal/resonator is being used as the reference, this specification assumes it is already running.

[8] Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f_{ICGOUT}. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V_{DDA} and V_{SSA} and variation in crystal oscillator frequency increase the C_{Jitter} percentage for a given interval.

[9] See Figure 3-9

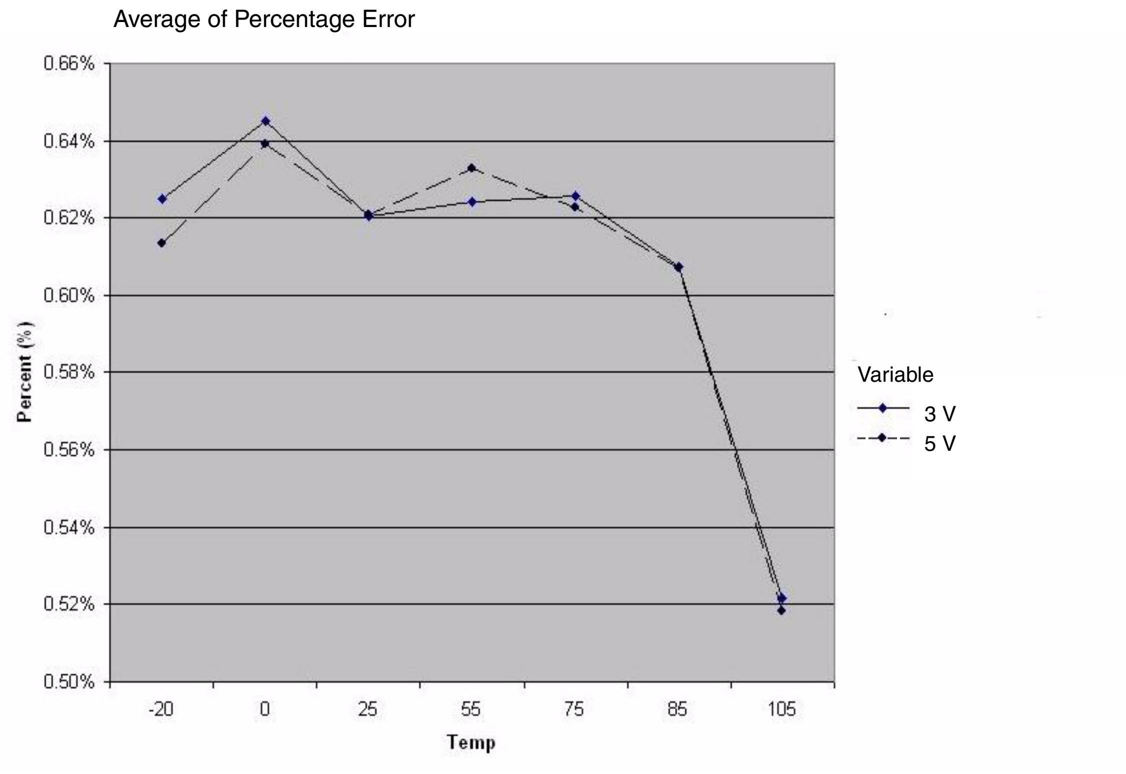


Figure 3-9. Internal Oscillator Deviation from Trimmed Frequency

3.10 AC Characteristics

This section describes ac timing characteristics for each peripheral system.

3.10.1 Control Timing

Table 3-12. Control Timing

Num	C	Parameter	Symbol	Min	Typ[1]	Max	Unit
1		Bus frequency ($t_{cyc} = 1/f_{Bus}$)	f_{Bus}	dc	—	20	MHz
2		Real-time interrupt internal oscillator period	t_{RTI}	600		1500	µs
3		External reset pulse width[2] ($t_{cyc} = 1/f_{Self\_reset}$)	t_{extrst}	1.5 x t_{Self_reset}		—	ns
4		Reset low drive[3]	t_{rstdrv}	34 x t_{cyc}		—	ns
5		Active background debug mode latch setup time	t_{MSSU}	25		—	ns
6		Active background debug mode latch hold time	t_{MSH}	25		—	ns
7		IRQ pulse width Asynchronous path[2] Synchronous path[4]	t_{ILIH}, t_{IHIL}	100 1.5 x t_{cyc}	—	—	ns
8		KBIPx pulse width Asynchronous path[2] Synchronous path[3]	t_{ILIH}, t_{IHIL}	100 1.5 x t_{cyc}	—	—	ns
9		Port rise and fall time (load = 50 pF)[5] Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	t_{Rise}, t_{Fall}	— —	3 30		ns

[1] Typical values are based on characterization data at V_{DD} = 5.0V, 25°C unless otherwise stated.

[2] This is the shortest pulse that is guaranteed to be recognized as a reset pin request. Shorter pulses are not guaranteed to override reset requests from internal sources.

[3] When any reset is initiated, internal circuitry drives the reset pin low for about 34 bus cycles and then samples the level on the reset pin about 38 bus cycles later to distinguish external reset requests from internal requests.

[4] This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized in that case.

[5] Timing is shown with respect to 20% V_{DD} and 80% V_{DD} levels. Temperature range –40°C to 125°C.

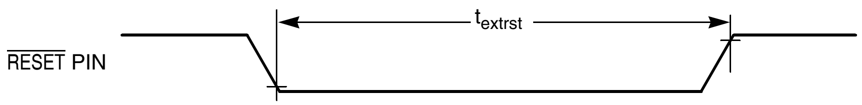


Figure 3-10. Reset Timing

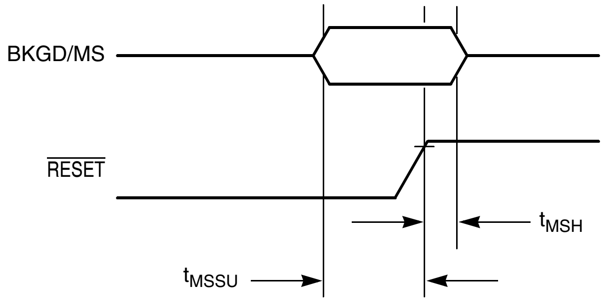


Figure 3-11. Active Background Debug Mode Latch Timing

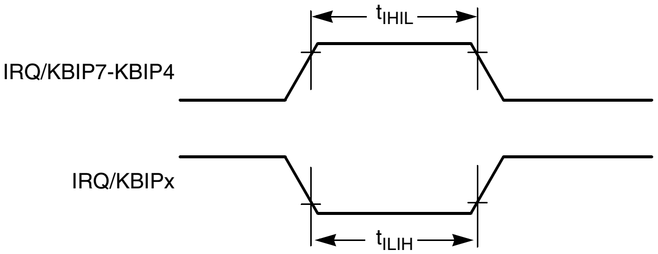


Figure 3-12. IRQ/KBIPx Timing

3.10.2 Timer/PWM (TPM) Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 3-13. TPM Input Timing

Function	Symbol	Min	Max	Unit
External clock frequency	f_{TPMext}	dc	$f_{Bus}/4$	MHz
External clock period	t_{TPMext}	4	—	t_{cyc}
External clock high time	t_{clkh}	1.5	—	t_{cyc}
External clock low time	t_{clkl}	1.5	—	t_{cyc}
Input capture pulse width	t_{ICPW}	1.5	—	t_{cyc}

3.13 EMC Performance

Electromagnetic compatibility (EMC) performance is highly dependant on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation all play a significant role in EMC performance. The system designer should consult Freescale applications notes such as AN2321, AN1050, AN1263, AN2764, and AN1259 for advice and guidance specifically targeted at optimizing EMC performance.

3.13.1 Radiated Emissions

Microcontroller radiated RF emissions are measured from 150 kHz to 1 GHz using the TEM/GTEM Cell method in accordance with the IEC 61967-2 and SAE J1752/3 standards. The measurement is performed with the microcontroller installed on a custom EMC evaluation board while running specialized EMC test software. The radiated emissions from the microcontroller are measured in a TEM cell in two package orientations (North and East). For more detailed information concerning the evaluation results, conditions and setup, please refer to the EMC Evaluation Report for this device.

The maximum radiated RF emissions of the tested configuration in all orientations are less than or equal to the reported emissions levels.

Table 3-16. Radiated Emissions

Parameter	Symbol	Conditions	Frequency	f_{OSC}/f_{BUS}	Level[1] (Max)	Unit
Radiated emissions, electric field and magnetic field	V_{RE_TEM}	$V_{DD} = 5.0$ V $T_A = +25^{o}C$ package type 80 LQFP	0.15 – 50 MHz	32kHz crystal 20MHz Bus	30	dBμV
			50 – 150 MHz		32	
			150 – 500 MHz		19	
			500 – 1000 MHz		7	
			IEC Level		I[2]	—
			SAE Level		I[2]	—

[1] Data based on laboratory test results.

[2] IEC and SAE Level Maximums: I=36 dBuV.

Chapter 5
Revision History

To provide the most up-to-date information, the version of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

http://freescale.com/

The following revision history table summarizes changes contained in this document.

Revision Number	Revision Date	Description of Changes
1	9/2008	Initial release of a separate data sheet and reference manual. Removed PTH7, clarified SPI as one full and one master-only, added missing RoHS logo, updated back cover addresses, and incorporated general release edits and updates. Added some finalized electrical characteristics.
2	6/2009	Added the parameter “Bandgap Voltage Reference” in Table 3-6 Updated Section 3.13, “EMC Performance” and corrected Table 3-16. Updated disclaimer page.
3	9/2010	Added 48-pin QFN package information.
4	8/2011	Updated the t_{RTI} in the Table 3-12. Updated the RI_{DD} in the Table 3-7.