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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	40MHz
Connectivity	I²C, LINbus, SCI, SPI
Peripherals	LVD, POR, PWM, WDT
Number of I/O	38
Program Memory Size	96KB (96K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LQFP
Supplier Device Package	44-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=mc9s08ac96mfge

Chapter 1
Device Overview

The MC9S08AC128 is a member of the low-cost, high-performance HCS08 Family of 8-bit microcontroller units (MCUs). The MC9S08AC128 uses the enhanced HCS08 core.

1.1 MCU Block Diagram

The block diagram in Figure 1-1 shows the structure of the MC9S08AC128 Series MCU.

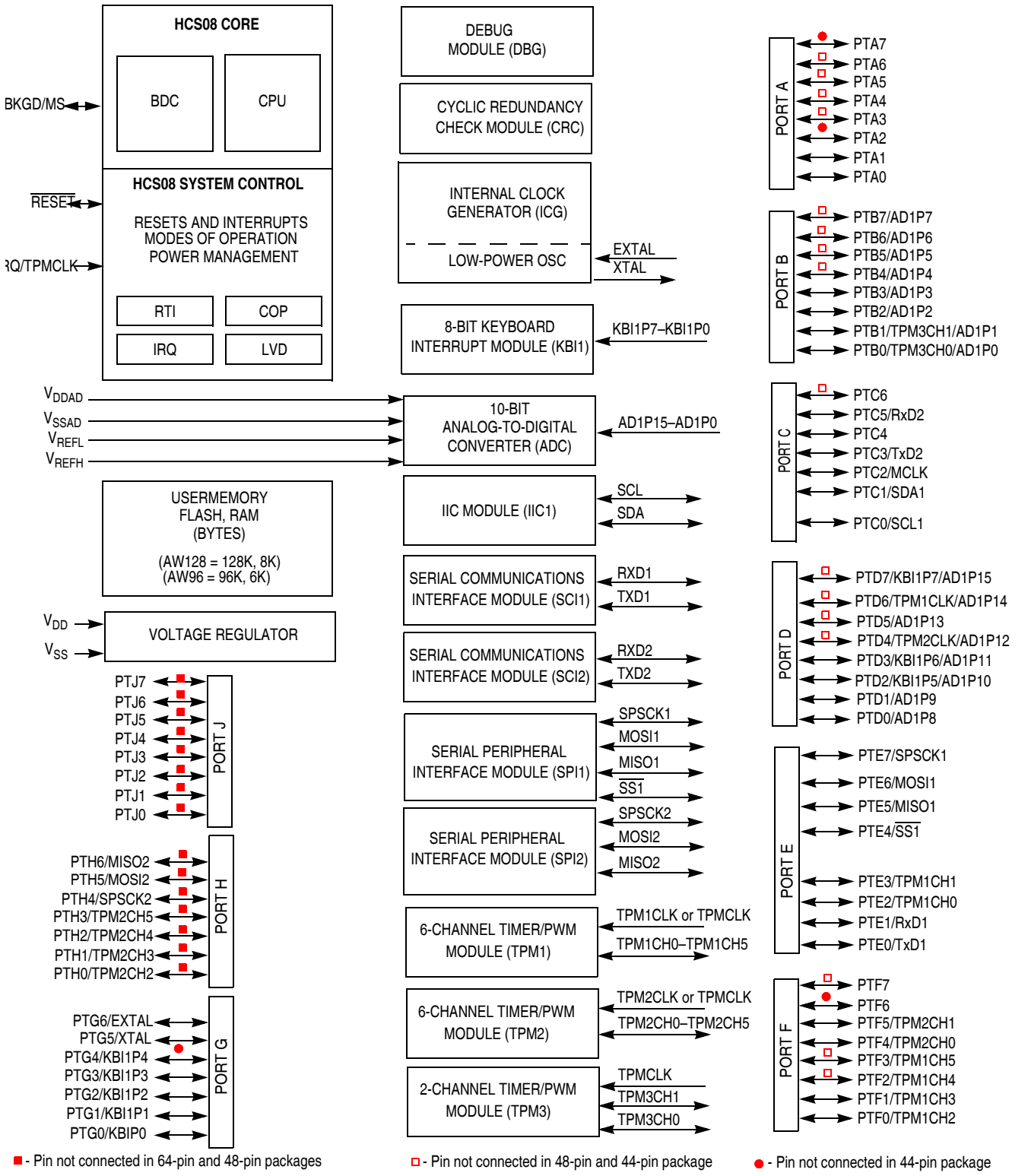


Figure 1-1. MC9S08AC128 Series Block Diagram

Chapter 2
Pins and Connections

This section describes signals that connect to package pins. It includes pinout diagrams, recommended system connections, and detailed discussions of signals.

2.1 Device Pin Assignment

Figure 2-1 shows the 80-pin LQFP package pin assignments for the MC9S08AC128 Series device.

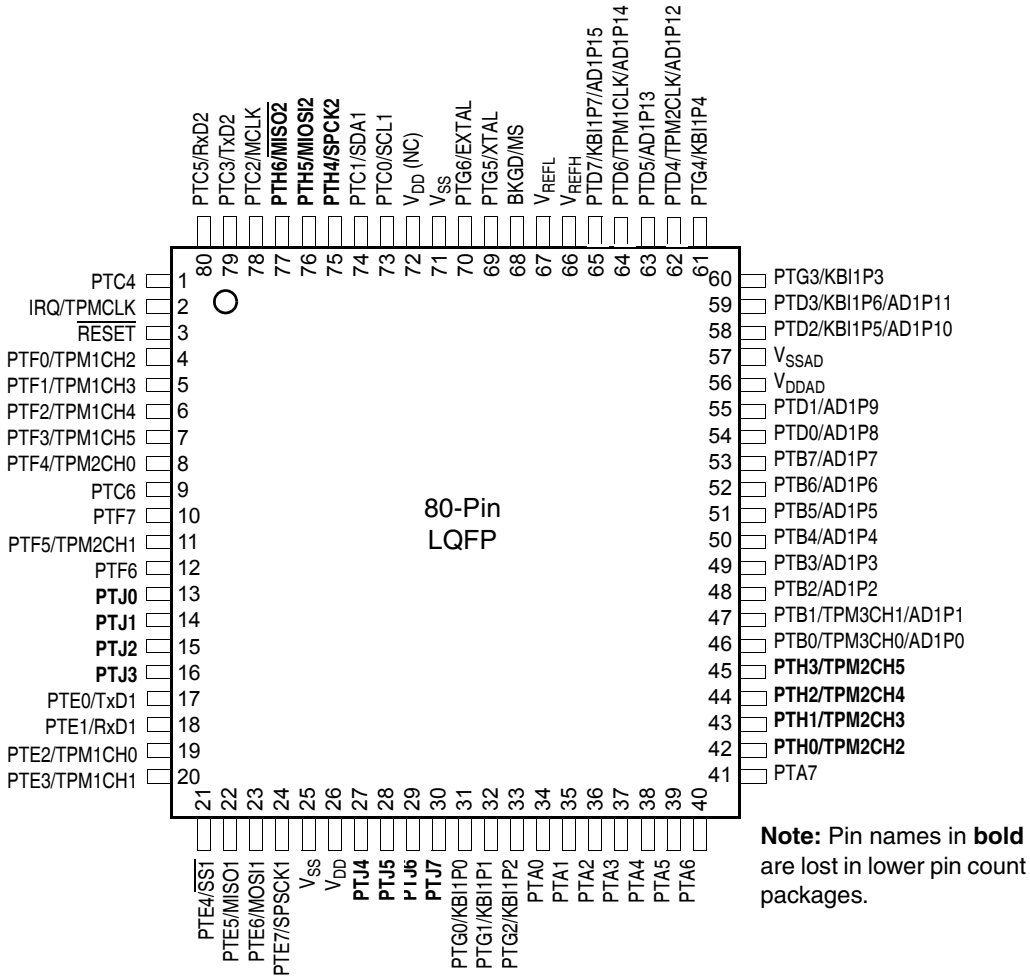
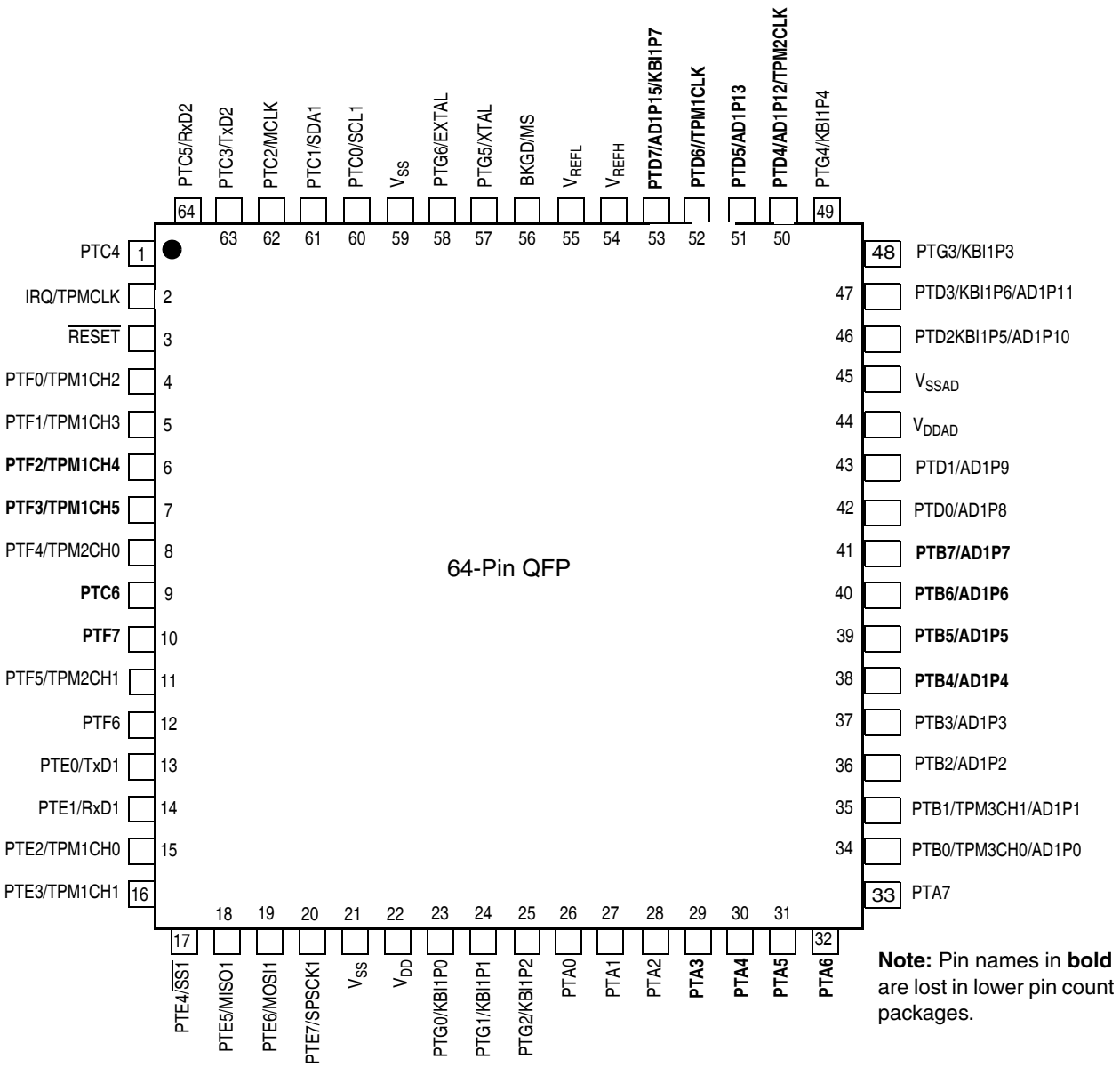


Figure 2-1. MC9S08AC128 Series in 80-Pin LQFP Package

Figure 2-2 shows the 64-pin package assignments for the MC9S08AC128 Series devices.



Note: Pin names in **bold** are lost in lower pin count packages.

Figure 2-2. MC9S08AC128 Series in 64-Pin QFP Package

Table 2-4. Pin Availability by Package Pin-Count (continued)

Pin Number				Lowest <-- Priority --> Highest		
80	**64**	**48**	**44**	**Port Pin**	**Alt 1**	**Alt 2**
54	42	30	27	PTD0	AD1P8	
55	43	31	28	PTD1	AD1P9	
56	44	32	29	V_{DDAD}		
57	45	33	30	V_{SSAD}		
58	46	34	31	PTD2	KBI1P5	AD1P10
59	47	35	32	PTD3	KBI1P6	AD1P11
60	48	36	33	PTG3	KBI1P3	
61	49	37	—	PTG4	KBI1P4	
62	50	—	—	PTD4	TPM2CLK	AD1P12
63	51	—	—	PTD5	AD1P13	
64	52	—	—	PTD6	TPM1CLK	AD1P14
65	53	—	—	PTD7	KBI1P7	AD1P15
66	54	38	34	V_{REFH}		
67	55	39	35	V_{REFL}		
68	56	40	36	BKGD	MS	
69	57	41	37	PTG5	XTAL	
70	58	42	38	PTG6	EXTAL	
71	59	43	39	V_{SS}		
72	—	—	—	V_{DD}(NC)		
73	60	44	40	PTC0	SCL1	
74	61	45	41	PTC1	SDA1	
75	—	—	—	PTH4	SPSCK2	
76	—	—	—	PTH5	MOSI2	
77	—	—	—	PTH6	MISO2	
78	62	46	42	PTC2	MCLK	
79	63	47	43	PTC3	TxD2	
80	64	48	44	PTC5	RxD2	

[1] TPMCLK, TPM1CLK, and TPM2CLK options are configured via software; out of reset, TPM1CLK, TPM2CLK, and TPMCLK are available to TPM1, TPM2, and TPM3 respectively.

Table 3-2. Absolute Maximum Ratings

Rating	Symbol	Value	Unit
Supply voltage	V_{DD}	−0.3 to + 5.8	V
Input voltage	V_{In}	− 0.3 to V_{DD} + 0.3	V
Instantaneous maximum current Single pin limit (applies to all port pins)[1], [2], [3]	I_D	± 25	mA
Maximum current into V_{DD}	I_{DD}	120	mA
Storage temperature	T_{stg}	−55 to +150	°C

1 Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive (V_{DD}) and negative (V_{SS}) clamp voltages, then use the larger of the two resistance values.

2 All functional non-supply pins are internally clamped to V_{SS} and V_{DD}.

3 Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If positive injection current ($V_{In} > V_{DD}$) is greater than I_{DD}, the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low which would reduce overall power consumption.

Table 3-6. DC Characteristics

Num	C	Parameter	Symbol	Min	Typ[1]	Max	Unit
1	—	Operating Voltage	V_{DD}	2.7	—	5.5	V
2	P	Output high voltage — Low Drive (PTxDSn = 0) 5 V, I_{Load} = –2 mA 3 V, I_{Load} = –0.6 mA 5 V, I_{Load} = –0.4 mA 3 V, I_{Load} = –0.24 mA	V_{OH}	 V_{DD} – 1.5 V_{DD} – 1.5 V_{DD} – 0.8 V_{DD} – 0.8	 — — — —	 — — — —	V
	P	Output high voltage — High Drive (PTxDSn = 1) 5 V, I_{Load} = –10 mA 3 V, I_{Load} = –3 mA 5 V, I_{Load} = –2 mA 3 V, I_{Load} = –0.4 mA		 V_{DD} – 1.5 V_{DD} – 1.5 V_{DD} – 0.8 V_{DD} – 0.8	 — — — —	 — — — —	
3	P	Output low voltage — Low Drive (PTxDSn = 0) 5 V, I_{Load} = 2 mA 3 V, I_{Load} = 0.6 mA 5 V, I_{Load} = 0.4 mA 3 V, I_{Load} = 0.24 mA	V_{OL}	 — — — —	 — — — —	 1.5 1.5 0.8 0.8	V
	P	Output low voltage — High Drive (PTxDSn = 1) 5 V, I_{Load} = 10 mA 3 V, I_{Load} = 3 mA 5 V, I_{Load} = 2 mA 3 V, I_{Load} = 0.4 mA		 — — — —	 — — — —	 1.5 1.5 0.8 0.8	
4	P	Output high current — Max total I_{OH} for all ports 5V 3V	I_{OHT}	 — —	 — —	 100 60	mA
5	P	Output low current — Max total I_{OL} for all ports 5V 3V	I_{OLT}	 — —	 — —	 100 60	mA
6	P	Input high voltage; all digital inputs 2.7v ≤ V_{DD} 4.5v	V_{IH}	0.70xV_{DD}	—	—	V
		4.5v ≤ V_{DD} ≤ 5.5v	V_{IH}	0.65xV_{DD}	—	—	
7	P	Input low voltage; all digital inputs	V_{IL}	—	—	0.35 x V_{DD}	
8	P	Input hysteresis; all digital inputs	V_{hys}	0.06 x V_{DD}			mV
9	P	Input leakage current; input only pins[2]	$\|I_{In}\|$	—	0.1	1	µA
10	P	High Impedance (off-state) leakage current[2]	$\|I_{OZ}\|$	—	0.1	1	µA
11	P	Internal pullup resistors[3]	R_{PU}	20	45	65	kΩ
12	P	Internal pulldown resistors[4]	R_{PD}	20	45	65	kΩ
13	C	Input Capacitance; all non-supply pins	C_{In}	—	—	8	pF
14	D	RAM retention voltage	V_{RAM}	—	0.6	1.0	V
15	P	POR rearm voltage	V_{POR}	0.9	1.4	2.0	V
16	D	POR rearm time	t_{POR}	10	—	—	µs
17	P	Low-voltage detection threshold — high range V_{DD} falling V_{DD} rising	V_{LVDH}	 4.2 4.3	 4.3 4.4	 4.4 4.5	V
18	P	Low-voltage detection threshold — low range V_{DD} falling V_{DD} rising	V_{LVDL}	 2.48 2.54	 2.56 2.62	 2.64 2.7	V

Table 3-6. DC Characteristics (continued)

Num	C	Parameter	Symbol	Min	Typ[1]	Max	Unit
19	P	Low-voltage warning threshold — high range V_{DD} falling V_{DD} rising	V_{LVWH}	4.2 4.3	4.3 4.4	4.4 4.5	V
20	P	Low-voltage warning threshold — low range V_{DD} falling V_{DD} rising	V_{LVWL}	2.48 2.54	2.56 2.62	2.64 2.7	V
21	P	Low-voltage inhibit reset/recover hysteresis 5V 3V	V_{hys}	— —	100 60	— —	mV
22	P	Bandgap Voltage Reference[5]	V_{BG}	1.170	1.200	1.230	V

1 Typical values are based on characterization data at 25°C unless otherwise stated.

2 Measured with $V_{In} = V_{DD}$ or V_{SS}.

3 Measured with $V_{In} = V_{SS}$.

4 Measured with $V_{In} = V_{DD}$.

5 Factory trimmed at V_{DD} = 3.0 V, Temperature = 25 °C.

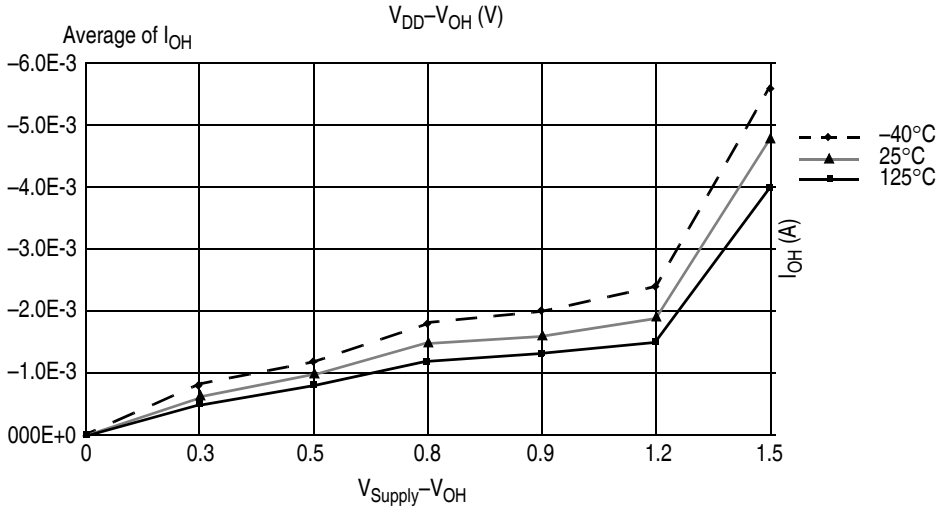


Figure 3-1. Typical I_{OH} (Low Drive) vs V_{DD}–V_{OH} at V_{DD} = 3 V

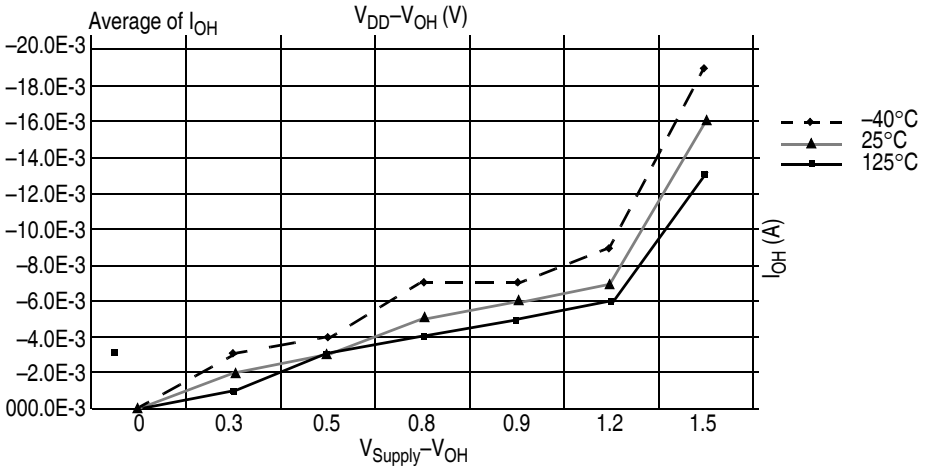


Figure 3-2. Typical I_{OH} (High Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 3 V

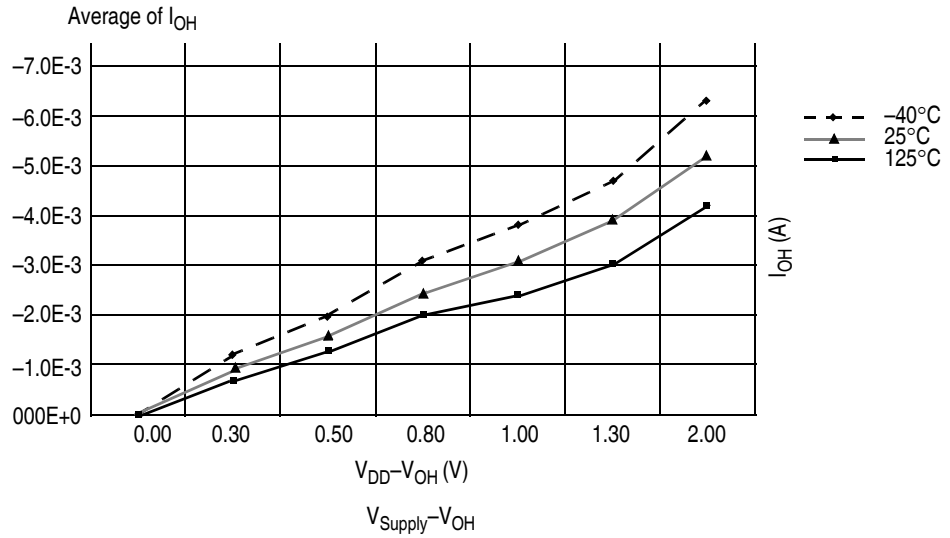


Figure 3-3. Typical I_{OH} (Low Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 5 V

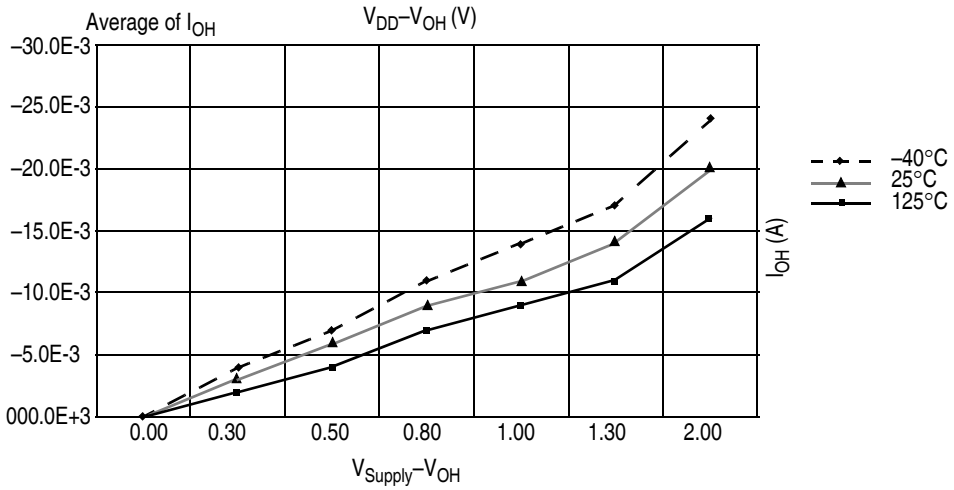
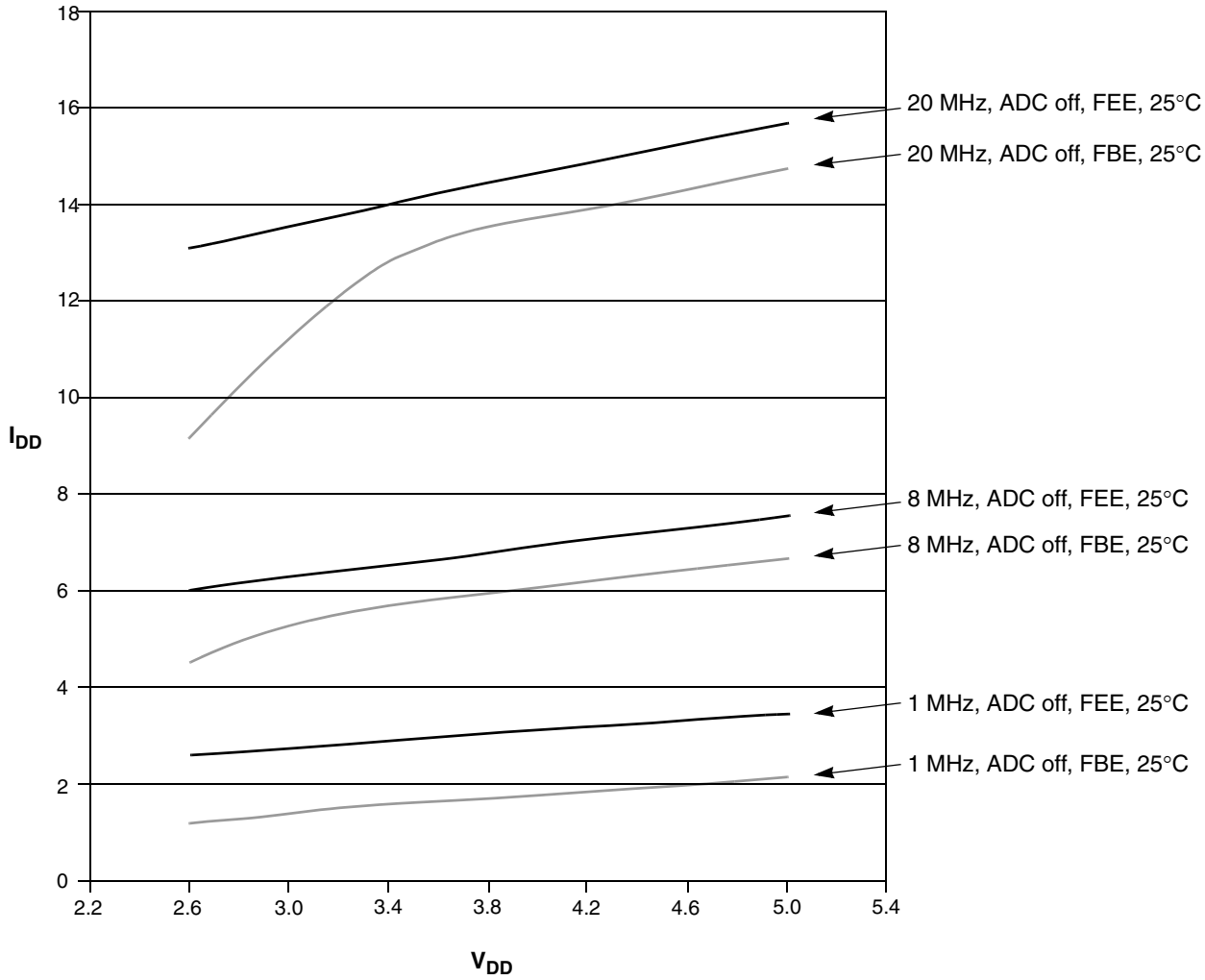


Figure 3-4. Typical I_{OH} (High Drive) vs $V_{DD}–V_{OH}$ at V_{DD} = 5 V



Note: External clock is square wave supplied by function generator. For FEE mode, external reference frequency is 4 MHz

Figure 3-5. Typical Run I_{DD} for FBE and FEE Modes, I_{DD} vs. V_{DD}

3.8 ADC Characteristics

Table 3-8. 5 Volt 10-bit ADC Operating Conditions

Characteristic	Conditions	Symb	Min	Typ[1]	Max	Unit
Supply voltage	Absolute	V_{DDAD}	2.7	—	5.5	V
	Delta to V_{DD} (V_{DD}–V_{DDAD})[2]	ΔV_{DDAD}	–100	0	+100	mV
Ground voltage	Delta to V_{SS} (V_{SS}–V_{SSAD})[2]	ΔV_{SSAD}	–100	0	+100	mV
Ref voltage high		V_{REFH}	2.7	V_{DDAD}	V_{DDAD}	V
Ref voltage low		V_{REFL}	V_{SSAD}	V_{SSAD}	V_{SSAD}	V
Supply current	Stop, reset, module off	I_{DDAD}	—	0.011	1	μA
Input voltage		V_{ADIN}	V_{REFL}	—	V_{REFH}	V
Input capacitance		C_{ADIN}	—	4.5	5.5	pF
Input resistance		R_{ADIN}	—	3	5	kΩ
Analog source resistance External to MCU	10-bit mode f_{ADCK} > 4MHz f_{ADCK} < 4MHz	R_{AS}	 — —	 — —	 5 10	kΩ
	8-bit mode (all valid f_{ADCK})		—	—	10	
ADC conversion clock frequency	High speed (ADLPC = 0)	f_{ADCK}	0.4	—	8.0	MHz
	Low power (ADLPC = 1)		0.4	—	4.0	
Temp Sensor Slope	–40°C to 25°C	m	—	3.266	—	mV/°C
	25°C to 125°C			3.638	—	
Temp Sensor Voltage	25°C	V_{TEMP25}	—	1.396	—	V

1 Typical values assume V_{DDAD} = 5.0 V, Temp = 25°C, f_{ADCK} = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2 dc potential difference.

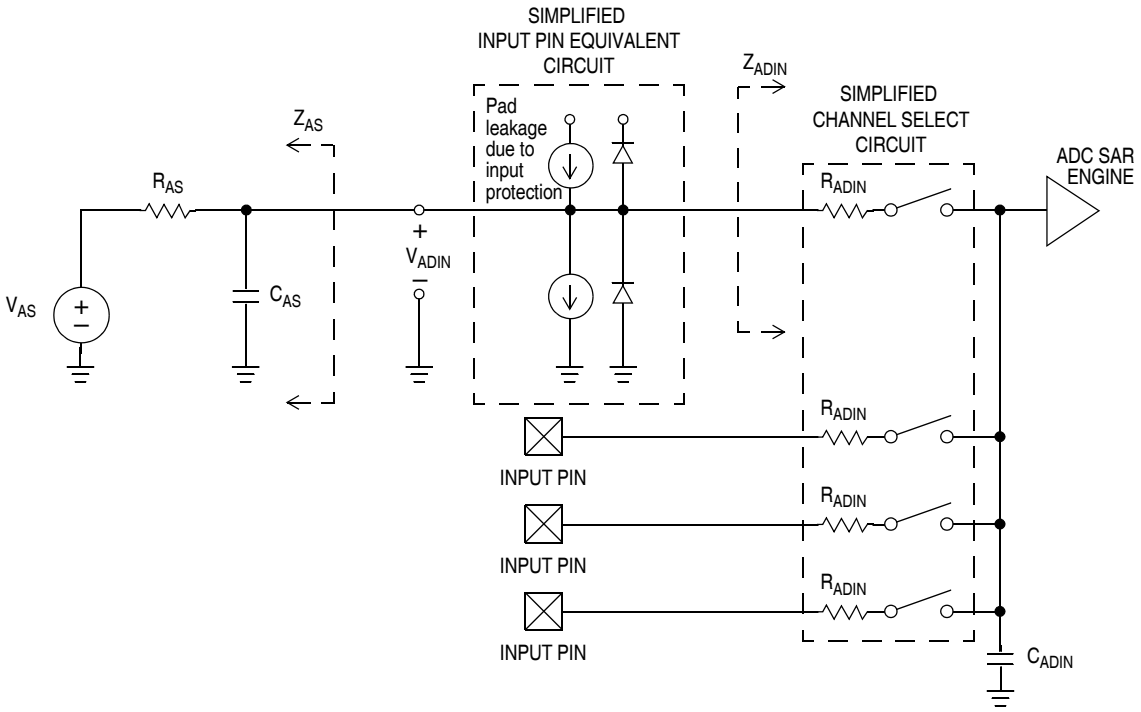


Figure 3-8. ADC Input Impedance Equivalency Diagram

Table 3-9. 5 Volt 10-bit ADC Characteristics ($V_{REFH} = V_{DDAD}$, $V_{REFL} = V_{SSAD}$)

Characteristic	Conditions	C	Symb	Min	Typ[1]	Max	Unit
Supply current ADLPC = 1 ADLSMP = 1 ADCO = 1		T	I_{DDAD}	—	133	—	μA
Supply current ADLPC = 1 ADLSMP = 0 ADCO = 1		T	I_{DDAD}	—	218	—	μA
Supply current ADLPC = 0 ADLSMP = 1 ADCO = 1		T	I_{DDAD}	—	327	—	μA
Supply current ADLPC = 0 ADLSMP = 0 ADCO = 1		T	I_{DDAD}	—	582	—	μA
	$V_{DDAD} \leq 5.5$ V	P		—	—	1	mA
ADC asynchronous clock source $t_{ADACK} = 1/f_{ADACK}$	High speed (ADLPC = 0)	P	f_{ADACK}	2	3.3	5	MHz
	Low power (ADLPC = 1)			1.25	2	3.3	
Conversion time (Including sample time)	Short sample (ADLSMP = 0)	P	t_{ADC}	—	20	—	ADCK cycles
	Long sample (ADLSMP = 1)			—	40	—	
Sample time	Short sample (ADLSMP = 0)	P	t_{ADS}	—	3.5	—	ADCK cycles
	Long sample (ADLSMP = 1)			—	23.5	—	
Total unadjusted error Includes quantization	10-bit mode	P	E_{TUE}	—	±1	±2.5	LSB[2]
	8-bit mode			—	±0.5	±1.0	
Differential non-linearity	10-bit mode	P	DNL	—	±0.5	±1.0	LSB[2]
	8-bit mode			—	±0.3	±0.5	
	Monotonicity and no-missing-codes guaranteed						
Integral non-linearity	10-bit mode	C	INL	—	±0.5	±1.0	LSB[2]
	8-bit mode			—	±0.3	±0.5	
Zero-scale error $V_{ADIN} = V_{SSA}$	10-bit mode	P	E_{ZS}	—	±0.5	±1.5	LSB[2]
	8-bit mode			—	±0.5	±0.5	
Full-scale error $V_{ADIN} = V_{DDA}$	10-bit mode	P	E_{FS}	—	±0.5	±1.5	LSB[2]
	8-bit mode			—	±0.5	±0.5	
Quantization error	10-bit mode	D	E_Q	—	—	±0.5	LSB[2]
	8-bit mode			—	—	±0.5	

3 Loss of reference frequency is the reference frequency detected internally, which transitions the ICG into self-clocked mode if it is not in the desired range.

4 Loss of DCO frequency is the DCO frequency detected internally, which transitions the ICG into FLL bypassed external mode (if an external reference exists) if it is not in the desired range.

5 This parameter is characterized before qualification rather than 100% tested.

6 Proper PC board layout procedures must be followed to achieve specifications.

7 This specification applies to the period of time required for the FLL to lock after entering FLL engaged internal or external modes. If a crystal/resonator is being used as the reference, this specification assumes it is already running.

8 Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f_{ICGOUT}. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V_{DDA} and V_{SSA} and variation in crystal oscillator frequency increase the C_{Jitter} percentage for a given interval.

9 See Figure 3-9

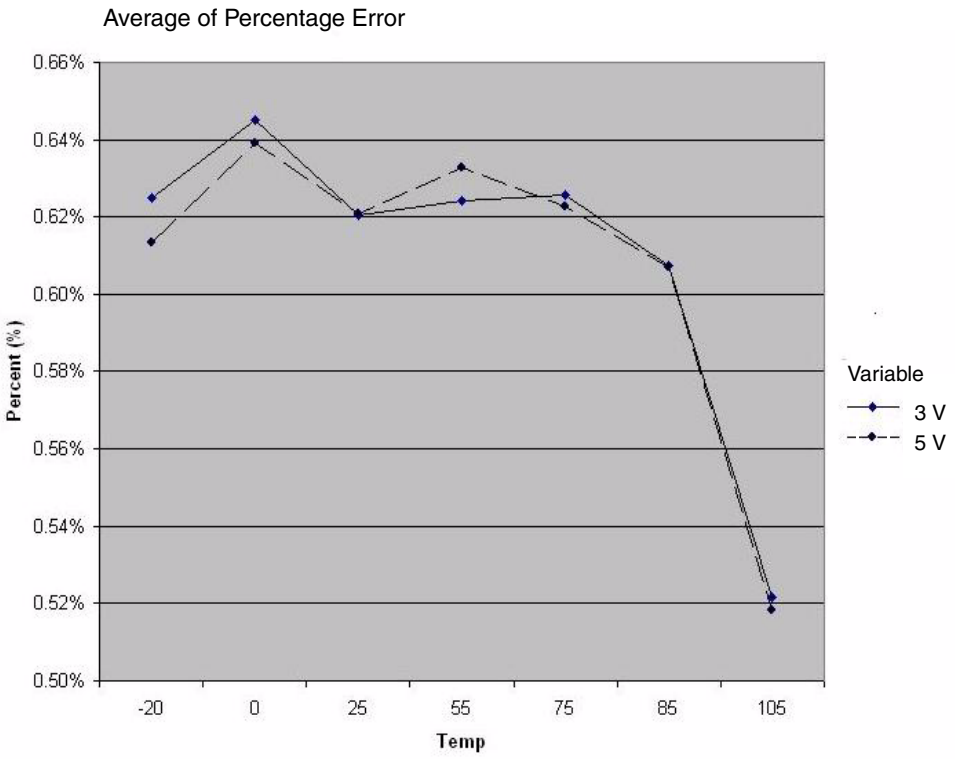


Figure 3-9. Internal Oscillator Deviation from Trimmed Frequency

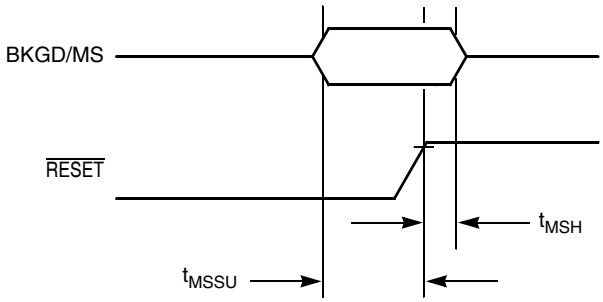


Figure 3-11. Active Background Debug Mode Latch Timing

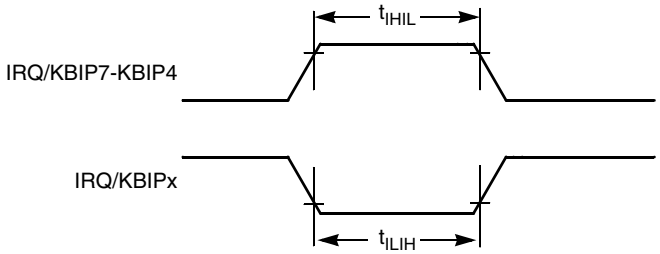


Figure 3-12. IRQ/KBIPx Timing

3.10.2 Timer/PWM (TPM) Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 3-13. TPM Input Timing

Function	Symbol	Min	Max	Unit
External clock frequency	f_{TPMext}	dc	$f_{Bus}/4$	MHz
External clock period	t_{TPMext}	4	—	t_{cyc}
External clock high time	t_{clkh}	1.5	—	t_{cyc}
External clock low time	t_{clkl}	1.5	—	t_{cyc}
Input capture pulse width	t_{ICPW}	1.5	—	t_{cyc}

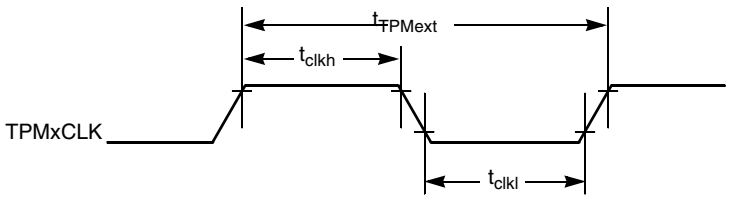


Figure 3-13. Timer External Clock

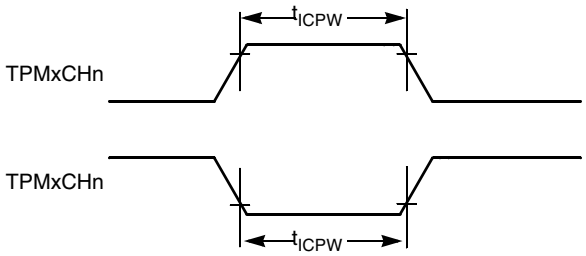


Figure 3-14. Timer Input Capture Pulse

3.11 SPI Characteristics

Table 3-14 and Figure 3-15 through Figure 3-18 describe the timing requirements for the SPI system.

Table 3-14. SPI Electrical Characteristic

Num[1]	C	Characteristic[2]	Symbol	Min	Max	Unit
		Operating frequency[3] Master Slave	 f_{op} f_{op}	 $f_{Bus}/2048$ dc	 $f_{Bus}/2$ $f_{Bus}/4$	Hz
1		Cycle time Master Slave	 t_{SCK} t_{SCK}	 2 4	 2048 —	 t_{cyc} t_{cyc}
2		Enable lead time Master Slave	 t_{Lead} t_{Lead}	 — 1/2	 1/2 —	 t_{SCK} t_{SCK}
3		Enable lag time Master Slave	 t_{Lag} t_{Lag}	 — 1/2	 1/2 —	 t_{SCK} t_{SCK}
4		Clock (SPSCK) high time Master and Slave	t_{SCKH}	1/2 t_{SCK} – 25	—	ns
5		Clock (SPSCK) low time Master and Slave	t_{SCKL}	1/2 t_{SCK} – 25	—	ns
6		Data setup time (inputs) Master Slave	 $t_{SI(M)}$ $t_{SI(S)}$	 30 30	 — —	 ns ns
7		Data hold time (inputs) Master Slave	 $t_{HI(M)}$ $t_{HI(S)}$	 30 30	 — —	 ns ns
8		Access time, slave[4]	t_A	0	40	ns
9		Disable time, slave[5]	t_{dis}	—	40	ns
10		Data setup time (outputs) Master Slave	 t_{SO} t_{SO}	 25 25	 — —	 ns ns
11		Data hold time (outputs) Master Slave	 t_{HO} t_{HO}	 –10 –10	 — —	 ns ns

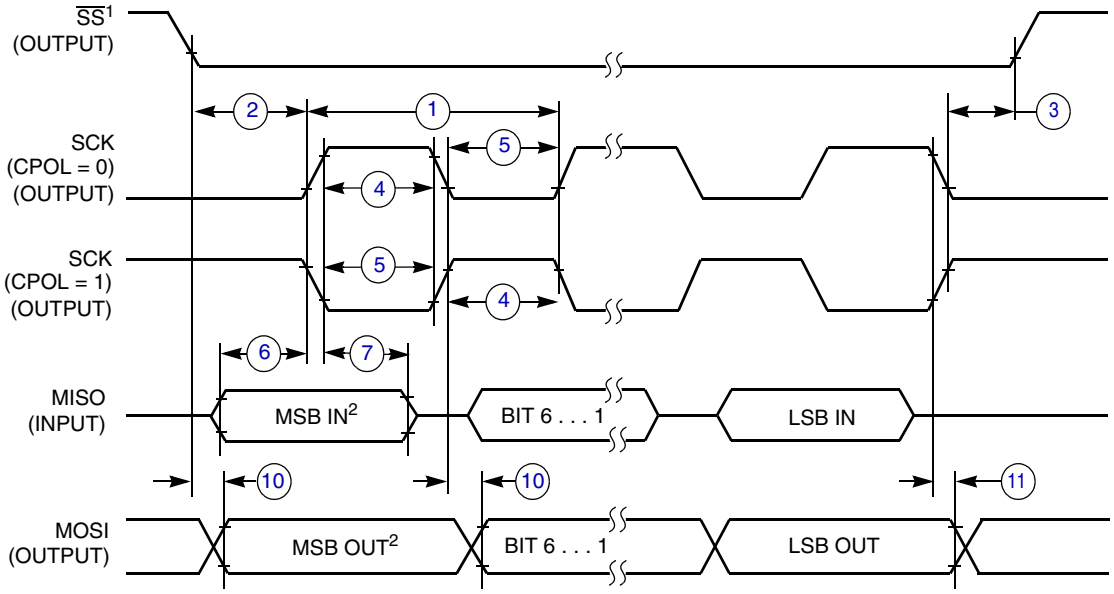
1 Refer to Figure 3-15 through Figure 3-18.

2 All timing is shown with respect to 20% V_{DD} and 70% V_{DD}, unless noted; 100 pF load on all SPI pins. All timing assumes slew rate control disabled and high drive strength enabled for SPI output pins.

3 Maximum baud rate must be limited to 5 MHz due to pad input characteristics.

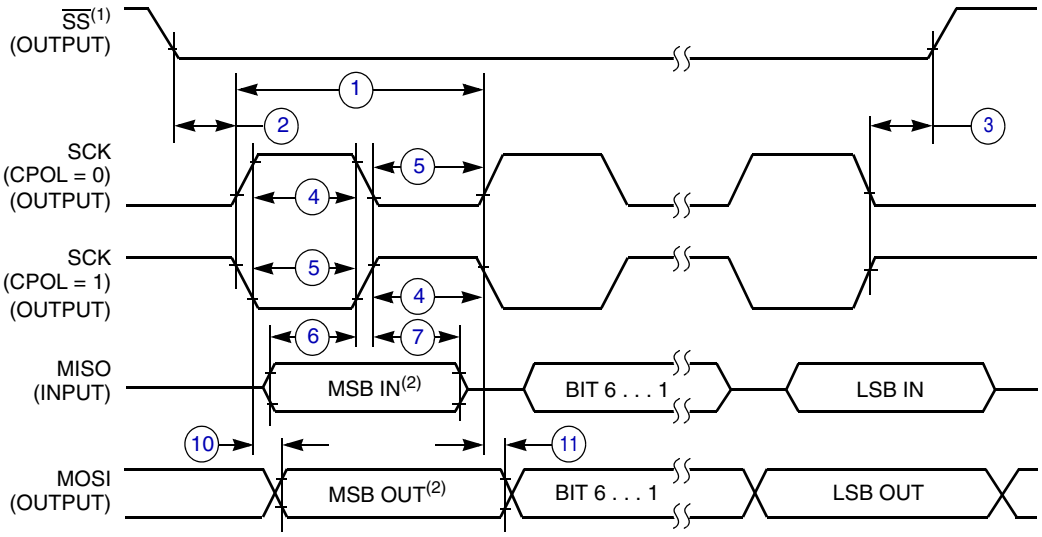
4 Time to data active from high-impedance state.

5 Hold time to high-impedance state.



NOTES:
1. $\overline{SS}$ output mode (MODFEN = 1, SSOE = 1).
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 3-15. SPI Master Timing (CPHA = 0)



NOTES:
1. $\overline{SS}$ output mode (MODFEN = 1, SSOE = 1).
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 3-16. SPI Master Timing (CPHA = 1)

3.13 EMC Performance

Electromagnetic compatibility (EMC) performance is highly dependant on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation all play a significant role in EMC performance. The system designer should consult Freescale applications notes such as AN2321, AN1050, AN1263, AN2764, and AN1259 for advice and guidance specifically targeted at optimizing EMC performance.

3.13.1 Radiated Emissions

Microcontroller radiated RF emissions are measured from 150 kHz to 1 GHz using the TEM/GTEM Cell method in accordance with the IEC 61967-2 and SAE J1752/3 standards. The measurement is performed with the microcontroller installed on a custom EMC evaluation board while running specialized EMC test software. The radiated emissions from the microcontroller are measured in a TEM cell in two package orientations (North and East). For more detailed information concerning the evaluation results, conditions and setup, please refer to the EMC Evaluation Report for this device.

The maximum radiated RF emissions of the tested configuration in all orientations are less than or equal to the reported emissions levels.

Table 3-16. Radiated Emissions

Parameter	Symbol	Conditions	Frequency	f_{OSC}/f_{BUS}	Level[1] (Max)	Unit
Radiated emissions, electric field and magnetic field	V_{RE_TEM}	V_{DD} = 5.0 V T_A = +25°C package type 80 LQFP	0.15 – 50 MHz	32kHz crystal 20MHz Bus	30	dBμV
			50 – 150 MHz		32	
			150 – 500 MHz		19	
			500 – 1000 MHz		7	
			IEC Level		I^2	—
			SAE Level		I^2	—

1 Data based on laboratory test results.

2 IEC and SAE Level Maximums: I=36 dBuV.

Chapter 5
Revision History

To provide the most up-to-date information, the version of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

http://freescale.com/

The following revision history table summarizes changes contained in this document.

Revision Number	Revision Date	Description of Changes
1	9/2008	Initial release of a separate data sheet and reference manual. Removed PTH7, clarified SPI as one full and one master-only, added missing RoHS logo, updated back cover addresses, and incorporated general release edits and updates. Added some finalized electrical characteristics.
2	6/2009	Added the parameter “Bandgap Voltage Reference” in Table 3-6 Updated Section 3.13, “EMC Performance” and corrected Table 3-16. Updated disclaimer page.
3	9/2010	Added 48-pin QFN package information.
4	8/2011	Updated the t_{RTI} in the Table 3-12. Updated the RI_{DD} in the Table 3-7.