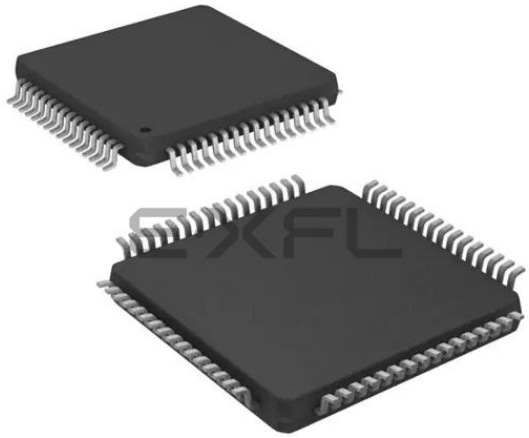

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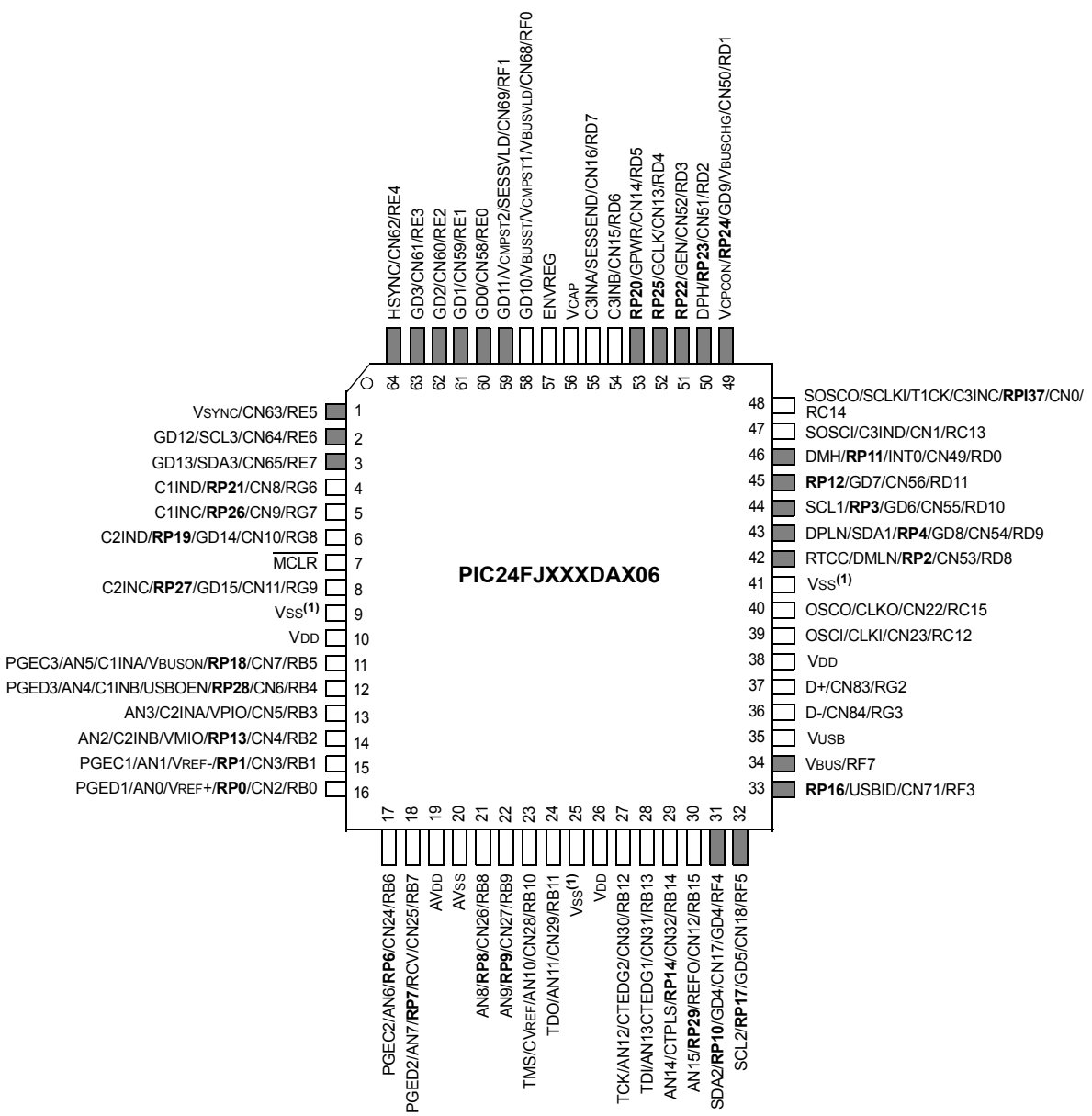
Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I²C, IrDA, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, GFX, LVD, POR, PWM, WDT
Number of I/O	52
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	96K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj128da206-i-pt

Pin Diagram (64-Pin TQFP/QFN)



Note 1: The back pad on QFN devices should be connected to VSS.

Legend: **RPn** and **RPIn** represents remappable peripheral pins.
Shaded pins indicate pins that are tolerant to up to +5.5V.

TABLE 3: COMPLETE PIN FUNCTION DESCRIPTIONS FOR 121-PIN (BGA) DEVICES

Pin	Function	Pin	Function
A1	PMD4/CN62/RE4	E5	VDD
A2	PMD3/CN61/RE3	E6	PMD9/CN78/RG1
A3	HSYNC/CN80/RG13	E7	N/C
A4	PMD0/CN58/RE0	E8	SDA1/**RPI35**/PMBE1/CN44/RA15
A5	PMD8/CN77/RG0	E9	DMLN/RTCC/**RP2**/CN53/RD8
A6	VCMPST2/SESSVLD/PMD10/CN69/RF1	E10	DPLN/**RP4**/GD10/PMACK2/CN54/RD9
A7	ENVREG	E11	SCL1/**RPI36**/PMA22/PMCS2(2)/CN43/RA14
A8	N/C	F1	$\overline{\text{MCLR}}$
A9	**RPI42**/PMD12/CN57/RD12	F2	AN19/C2IND/**RP19**/PMA3/PMA21(2)/CN10/RG8
A10	DPH/**RP23**/GD11/PMACK1/CN51/RD2	F3	AN20/C2INC/**RP27**/PMA2/CN11/RG9
A11	VCPCON/**RP24**/GD7/VBUSCHG/CN50/RD1	F4	AN18/C1INC/**RP26**/PMA4/PMA20(2)/CN9/RG7
B1	N/C	F5	VSS
B2	GCLK/CN82/RG15	F6	N/C
B3	PMD2/CN60/RE2	F7	N/C
B4	PMD1/CN59/RE1	F8	VDD
B5	AN22/PMA17/CN40/RA7	F9	OSCI/CLKI/CN23/RC12
B6	VBUSST/VCMPST1/VBUSVLD/PMD11/CN68/RF0	F10	VSS
B7	VCAP	F11	OSCO/CLKO/CN22/RC15
B8	**RP20**/PMRD/CN14/RD5	G1	**RPI33**/PMCS1/CN66/RE8
B9	**RP22**/PMBE0/CN52/RD3	G2	AN21/**RPI34**/PMA19/CN67/RE9
B10	VSS	G3	TMS/CN33/RA0
B11	SOSCO/SCLKI/T1CK/C3INC/**RPI37**/CN0/RC14	G4	N/C
C1	SCL3/PMD6/CN64/RE6	G5	VDD
C2	VDD	G6	VSS
C3	VSYNC/CN79/RG12	G7	VSS
C4	PMA16/CN81/RG14	G8	N/C
C5	AN23/GEN/CN39/RA6	G9	TDO/CN38/RA5
C6	N/C	G10	SDA2/PMA20/PMA4(2)/CN36/RA3
C7	C3INA/SESSEND/PMD15/CN16/RD7	G11	TDI/PMA21/PMA3(2)/CN37/RA4
C8	**RP25**/PMWR/CN13/RD4	H1	PGEC3/AN5/C1INA/VBUSON/**RP18**/CN7/RB5
C9	VDD	H2	PGED3/AN4/C1INB/USBOEN/**RP28**/GD4/CN6/RB4
C10	SOSCI/C3IND/CN1/RC13	H3	VSS
C11	**RP12**/PMA14/PMCS1(3)/CN56/RD11	H4	VDD
D1	**RPI38**/GD0/CN45/RC1	H5	N/C
D2	SDA3/PMD7/CN65/RE7	H6	VDD
D3	PMD5/CN63/RE5	H7	N/C
D4	VSS	H8	VBUS/CN73/RF7
D5	VSS	H9	VUSB
D6	N/C	H10	D+/CN83/RG2
D7	C3INB/PMD14/CN15/RD6	H11	SCL2/CN35/RA2
D8	PMD13/CN19/RD13	J1	AN3/C2INA/GD5/VPIO/CN5/RB3
D9	DMH/**RP11**/INT0/CN49/RD0	J2	AN2/C2INB/VMIO/**RP13**/GD6/CN4/RB2
D10	N/C	J3	PGED2/AN7/**RP7**/RCV/GPWR/CN25/RB7
D11	**RP3**/PMA15/PMCS2(3)/CN55/RD10	J4	AVDD
E1	AN16/**RPI41**/PMCS2/PMA22(2)/CN48/RC4	J5	AN11/PMA12/CN29/RB11
E2	**RPI40**/GD1/CN47/RC3	J6	TCK/CN34/RA1
E3	AN17/C1IND/**RP21**/PMA5/PMA18(2)/CN8/RG6	J7	AN12/PMA11/CTEDG2/CN30/RB12
E4	**RPI39**/GD8/CN46/RC2	J8	N/C

Legend: **RPn** and **RPIn** represent remappable pins for Peripheral Pin Select functions.

Note 1: Alternate pin assignments for VREF+ and VREF- when the $\overline{\text{ALTVREF}}$ Configuration bit is programmed.

2: Alternate pin assignments for EPMP when the $\overline{\text{ALTPMP}}$ Configuration bit is programmed.

3: Pin assignment for PMCSx when CSF<1:0> is not equal to '00'.

2.7 Configuration of Analog and Digital Pins During ICSP Operations

If an ICSP compliant emulator is selected as a debugger, it automatically initializes all of the A/D input pins (ANx) as “digital” pins. Depending on the particular device, this is done by setting all bits in the ADnPCFG register(s), or clearing all bit in the ANSx registers.

All PIC24F devices will have either one or more ADnPCFG registers or several ANSx registers (one for each port); no device will have both. Refer to (**Section 23.0 “10-Bit High-Speed A/D Converter”**) for more specific information.

The bits in these registers that correspond to the A/D pins that initialized the emulator must not be changed by the user application firmware; otherwise, communication errors will result between the debugger and the device.

If your application needs to use certain A/D pins as analog input pins during the debug session, the user application must modify the appropriate bits during initialization of the ADC module, as follows:

- For devices with an ADnPCFG register, clear the bits corresponding to the pin(s) to be configured as analog. Do not change any other bits, particularly those corresponding to the PGECx/PGEDx pair, at any time.
- For devices with ANSx registers, set the bits corresponding to the pin(s) to be configured as analog. Do not change any other bits, particularly those corresponding to the PGECx/PGEDx pair, at any time.

When a Microchip debugger/emulator is used as a programmer, the user application firmware must correctly configure the ADnPCFG or ANSx registers. Automatic initialization of this register is only done during debugger operation. Failure to correctly configure the register(s) will result in all A/D pins being recognized as analog input pins, resulting in the port value being read as a logic '0', which may affect user application functionality.

2.8 Unused I/Os

Unused I/O pins should be configured as outputs and driven to a logic low state. Alternatively, connect a 1 kΩ to 10 kΩ resistor to V_{SS} on unused pins and drive the output to logic low.

FIGURE 3-1: PIC24F CPU CORE BLOCK DIAGRAM

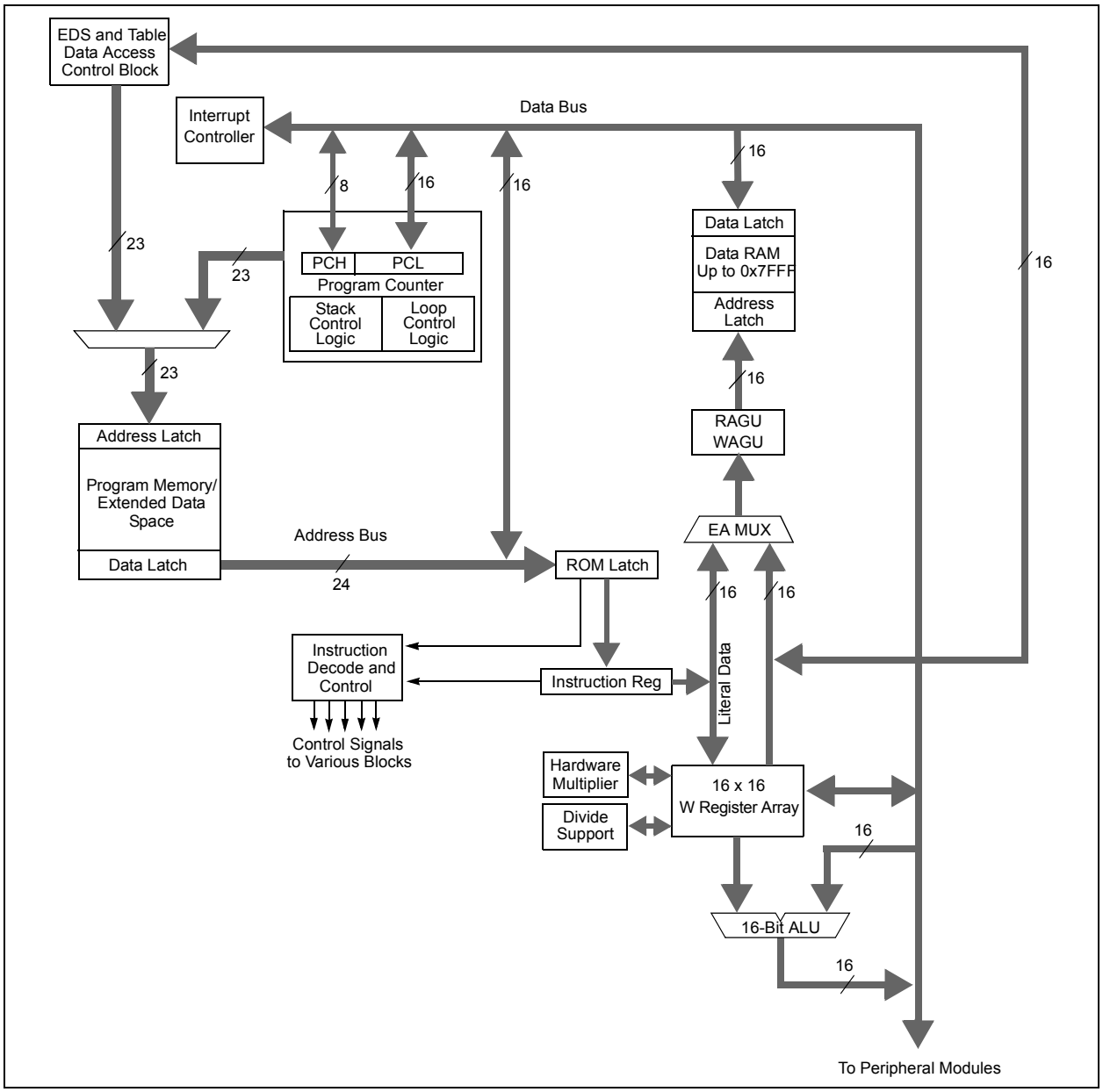


TABLE 3-1: CPU CORE REGISTERS

Register(s) Name	Description
W0 through W15	Working Register Array
PC	23-Bit Program Counter
SR	ALU STATUS Register
SPLIM	Stack Pointer Limit Value Register
TBLPAG	Table Memory Page Address Register
RCOUNT	Repeat Loop Counter Register
CORCON	CPU Control Register
DISICNT	Disable Interrupt Count Register
DSRPAG	Data Space Read Page Register
DSWPAG	Data Space Write Page Register

TABLE 4-8: INPUT CAPTURE REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IC1CON1	0140	—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC1CON2	0142	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC1BUF	0144	Input Capture 1 Buffer Register																0000
IC1TMR	0146	Input Capture 1 Timer Value Register																xxxx
IC2CON1	0148	—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC2CON2	014A	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC2BUF	014C	Input Capture 2 Buffer Register																0000
IC2TMR	014E	Input Capture 2 Timer Value Register																xxxx
IC3CON1	0150	—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC3CON2	0152	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC3BUF	0154	Input Capture 3 Buffer Register																0000
IC3TMR	0156	Input Capture 3 Timer Value Register																xxxx
IC4CON1	0158	—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC4CON2	015A	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC4BUF	015C	Input Capture 4 Buffer Register																0000
IC4TMR	015E	Input Capture 4 Timer Value Register																xxxx
IC5CON1	0160	—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC5CON2	0162	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC5BUF	0164	Input Capture 5 Buffer Register																0000
IC5TMR	0166	Input Capture 5 Timer Value Register																xxxx
IC6CON1	0168	—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC6CON2	016A	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC6BUF	016C	Input Capture 6 Buffer Register																0000
IC6TMR	016E	Input Capture 6 Timer Value Register																xxxx
IC7CON1	0170	—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC7CON2	0172	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC7BUF	0174	Input Capture 7 Buffer Register																0000
IC7TMR	0176	Input Capture 7 Timer Value Register																xxxx
IC8CON1	0178	—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC8CON2	017A	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC8BUF	017C	Input Capture 8 Buffer Register																0000
IC8TMR	017E	Input Capture 8 Timer Value Register																xxxx
IC9CON1	0180	—	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	—	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC9CON2	0182	—	—	—	—	—	—	—	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC9BUF	0184	Input Capture 9 Buffer Register																0000
IC9TMR	0186	Input Capture 9 Timer Value Register																xxxx

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-30: PERIPHERAL PIN SELECT REGISTER MAP (CONTINUED)

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPOR0	06C0	—	—	RP1R5	RP1R4	RP1R3	RP1R2	RP1R1	RP1R0	—	—	RP0R5	RP0R4	RP0R3	RP0R2	RP0R1	RP0R0	0000
RPOR1	06C2	—	—	RP3R5	RP3R4	RP3R3	RP3R2	RP3R1	RP3R0	—	—	RP2R5	RP2R4	RP2R3	RP2R2	RP2R1	RP2R0	0000
RPOR2	06C4	—	—	RP5R5(1)	RP5R4(1)	RP5R3(1)	RP5R2(1)	RP5R1(1)	RP5R0(1)	—	—	RP4R5	RP4R4	RP4R3	RP4R2	RP4R1	RP4R0	0000
RPOR3	06C6	—	—	RP7R5	RP7R4	RP7R3	RP7R2	RP7R1	RP7R0	—	—	RP6R5	RP6R4	RP6R3	RP6R2	RP6R1	RP6R0	0000
RPOR4	06C8	—	—	RP9R5	RP9R4	RP9R3	RP9R2	RP9R1	RP9R0	—	—	RP8R5	RP8R4	RP8R3	RP8R2	RP8R1	RP8R0	0000
RPOR5	06CA	—	—	RP11R5	RP11R4	RP11R3	RP11R2	RP11R1	RP11R0	—	—	RP10R5	RP10R4	RP10R3	RP10R2	RP10R1	RP10R0	0000
RPOR6	06CC	—	—	RP13R5	RP13R4	RP13R3	RP13R2	RP13R1	RP13R0	—	—	RP12R5	RP12R4	RP12R3	RP12R2	RP12R1	RP12R0	0000
RPOR7	06CE	—	—	RP15R5(1)	RP15R4(1)	RP15R3(1)	RP15R2(1)	RP15R1(1)	RP15R0(1)	—	—	RP14R5	RP14R4	RP14R3	RP14R2	RP14R1	RP14R0	0000
RPOR8	06D0	—	—	RP17R5	RP17R4	RP17R3	RP17R2	RP17R1	RP17R0	—	—	RP16R5	RP16R4	RP16R3	RP16R2	RP16R1	RP16R0	0000
RPOR9	06D2	—	—	RP19R5	RP19R4	RP19R3	RP19R2	RP19R1	RP19R0	—	—	RP18R5	RP18R4	RP18R3	RP18R2	RP18R1	RP18R0	0000
RPOR10	06D4	—	—	RP21R5	RP21R4	RP21R3	RP21R2	RP21R1	RP21R0	—	—	RP20R5	RP20R4	RP20R3	RP20R2	RP20R1	RP20R0	0000
RPOR11	06D6	—	—	RP23R5	RP23R4	RP23R3	RP23R2	RP23R1	RP23R0	—	—	RP22R5	RP22R4	RP22R3	RP22R2	RP22R1	RP22R0	0000
RPOR12	06D8	—	—	RP25R5	RP25R4	RP25R3	RP25R2	RP25R1	RP25R0	—	—	RP24R5	RP24R4	RP24R3	RP24R2	RP24R1	RP24R0	0000
RPOR13	06DA	—	—	RP27R5	RP27R4	RP27R3	RP27R2	RP27R1	RP27R0	—	—	RP26R5	RP26R4	RP26R3	RP26R2	RP26R1	RP26R0	0000
RPOR14	06DC	—	—	RP29R5	RP29R4	RP29R3	RP29R2	RP29R1	RP29R0	—	—	RP28R5	RP28R4	RP28R3	RP28R2	RP28R1	RP28R0	0000
RPOR15(1)	06DE	—	—	RP31R5(1)	RP31R4(1)	RP31R3(1)	RP31R2(1)	RP31R1(1)	RP31R0(1)	—	—	RP30R5(1)	RP30R4(1)	RP30R3(1)	RP30R2(1)	RP30R1(1)	RP30R0(1)	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.
Note 1: Bits are unimplemented in 64-pin devices; read as '0'.

TABLE 4-31: GRAPHICS REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
G1CMDL	0700	Graphics Command Register<15:0>																0000
G1CMDH	0702	Graphics Command Register<31:16>																0000
G1CON1	0704	G1EN	—	G1SIDL	GCMDWMK4	GCMDWMK3	GCMDWMK2	GCMDWMK1	GCMDWMK0	PUBPP2	PUBPP1	PUBPP0	GCMDCNT4	GCMDCNT3	GCMDCNT2	GCMDCNT1	GCMDCNT0	0000
G1STAT	0706	PUBUSY	—	—	—	—	—	—	—	IPUBUSY	RCCBUSY	CHRBUSY	VMRGN	HMRGN	CMDLV	CMDFUL	CMDMPT	0000
G1IE	0708	PUIE	—	—	—	—	—	—	—	IPUIE	RCCIE	CHRIE	VMRGNIE	HMRGNIE	CMDLVIE	CMDFULIE	CMDMPTIE	0000
G1IR	070A	PUIF	—	—	—	—	—	—	—	IPUIF	RCCIF	CHRIF	VMRGNIF	HMRGNIF	CMDLVIF	CMDFULIF	CMDMPTIF	0000
G1W1ADRL	070C	GPU Work Area 1 Start Address Register<15:0>																0000
G1W1ADRH	070E	—	—	—	—	—	—	—	—	GPU Work Area 1 Start Address Register<23:16>								0000
G1W2ADRL	0710	GPU Work Area 2 Start Address Register<15:0>																0000
G1W2ADRH	0712	—	—	—	—	—	—	—	—	GPU Work Area 2 Start Address Register<23:16>								0000
G1PUW	0714	—	—	—	—	—	GPU Work Area Width Register											0000
G1PUH	0716	—	—	—	—	—	GPU Work Area Height Register											0000
G1DPADRL	0718	Display Buffer Start Address Register<15:0>																0000
G1DPADRH	071A	—	—	—	—	—	—	—	—	Display Buffer Start Address Register<23:16>								0000
G1DPW	071C	—	—	—	—	—	Display Frame Width Register											0000
G1DPH	071E	—	—	—	—	—	Display Frame Height Register											0000
G1DPWT	0720	—	—	—	—	—	Display Total Width Register											0000
G1DPHT	0722	—	—	—	—	—	Display Total Height Register											0000
G1CON2	0724	DPGWDTH1	DPGWDTH0	DPSTGER1	DPSTGER0	—	—	DPTEST1	DPTEST0	DPBPP2	DPBPP1	DPBPP0	—	—	DPMODE2	DPMODE1	DPMODE0	0000
G1CON3	0726	—	—	—	—	—	—	DPPINOE	DPPOWER	DPCLKPOL	DPENPOL	DPVSPOL	DPHSPOL	DPPWROE	DPENOE	DPVSOE	DPHSOE	0000
G1ACTDA	0728	Number of Lines Before the First Active Line Register								Number of Pixels Before the First Active PIxel Register								0000
G1HSYNC	072A	HSYNC Pulse-Width Configuration Register								HSYNC Start Delay Configuration Register								0000
G1VSYNC	072C	VSYNC Pulse-Width Configuration Register								VSYNC Start Delay Configuration Register								0000
G1DBLCON	072E	Vertical Blanking Start to First Displayed Line Configuration Regsiter								Horizontal Blanking Start to First Displayed Line Configuration Regsiter								0000
G1CLUT	0730	CLUTEN	CLUTBUSY	—	—	—	—	CLUTTRD	CLUTRWEN	Color Look-Up Table Memory Address Register								0000
G1CLUTWR	0732	Color Look-up Table Memory Write Data Register																0000
G1CLUTRD	0734	Color Look-up Table Memory Read Data Register																0000
G1MRGN	0736	Vertical Blanking Advance Register								Horizontal Blanking Advance Register								0000
G1CHRX	0738	—	—	—	—	—	Current Character X-Coordinate Position Register											0000
G1CHRY	073A	—	—	—	—	—	Current Character Y-Coordinate Position Register											0000
G1IPU	073C	—	—	—	—	—	—	—	—	—	—	HUFFERR	BLCKERR	LENERR	WRAPERR	IPUDONE	BFINAL	0000
G1DBEN	073E	GDBEN15	GDBEN14	GDBEN13	GDBEN12	GDBEN11	GDBEN10	GDBEN9	GDBEN8	GDBEN7	GDBEN6	GDBEN5	GDBEN4	GDBEN3	GDBEN2	GDBEN1	GDBEN0	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-32: SYSTEM REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RCON	0740	TRAPR	IOPUWR	—	—	—	—	CM	VREGS	EXTR	SWR	SWDTEN	WDTO	SLEEP	IDLE	BOR	POR	**Note 1**
OSCCON	0742	—	COSC2	COSC1	COSC0	—	NOSC2	NOSC1	NOSC0	CLKLOCK	IOLOCK	LOCK	—	CF	POSCEN	SOSCEN	OSWEN	**Note 2**
CLKDIV	0744	ROI	DOZE2	DOZE1	DOZE0	DOZEN	RCDIV2	RCDIV1	RCDIV0	CPDIV1	CPDIV0	PLLEN	G1CLKSEL	—	—	—	—	0100
CLKDIV2	0746	GCLKDIV6	GCLKDIV5	GCLKDIV4	GCLKDIV3	GCLKDIV2	GCLKDIV1	GCLKDIV0	—	—	—	—	—	—	—	—	—	0000
OSCTUN	0748	—	—	—	—	—	—	—	—	—	—	TUN5	TUN4	TUN3	TUN2	TUN1	TUN0	0000
REFOCON	074E	ROEN	—	ROSSLP	ROSEL	RODIV3	RODIV2	RODIV1	RODIV0	—	—	—	—	—	—	—	—	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.
Note 1: The Reset value of the RCON register is dependent on the type of Reset event. See **Section 6.0 "Resets"** for more information.
2: The Reset value of the OSCCON register is dependent on both the type of Reset event and the device configuration. See **Section 8.0 "Oscillator Configuration"** for more information.

TABLE 4-33: NVM REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
NVMCON	0760	WR	WREN	WRERR	—	—	—	—	—	—	ERASE	—	—	NVMOP3	NVMOP2	NVMOP1	NVMOP0	0000(1)
NVMKEY	0766	—	—	—	—	—	—	—	—	NVMKEY Register<7:0>								0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.
Note 1: Reset value shown is for POR only. Value on other Reset states is dependent on the state of memory write or erase operations at the time of Reset.

TABLE 4-34: PMD REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0770	T5MD	T4MD	T3MD	T2MD	T1MD	—	—	—	I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	—	ADC1MD	0000
PMD2	0772	IC8MD	IC7MD	IC6MD	IC5MD	IC4MD	IC3MD	IC2MD	IC1MD	OC8MD	OC7MD	OC6MD	OC5MD	OC4MD	OC3MD	OC2MD	OC1MD	0000
PMD3	0774	—	—	—	—	—	CMPMD	RTCCMD	PMPMD(1)	CRCMD	—	—	—	U3MD	I2C3MD	I2C2MD	—	0000
PMD4	0776	—	—	—	—	—	—	—	—	—	UPWMMD	U4MD	—	REFOMD	CTMUMD	LVDMD	USB1MD	0000
PMD5	0778	—	—	—	—	—	—	—	IC9MD	—	—	—	—	—	—	—	OC9MD	0000
PMD6	077A	—	—	—	—	—	—	—	—	—	GFX1MD	—	—	—	—	—	SPI3MD	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.
Note 1: Unimplemented in 64-pin devices, read as '0'.

8.4 Clock Switching Operation

With few limitations, applications are free to switch between any of the four clock sources (POSC, SOSC, FRC and LPRC) under software control and at any time. To limit the possible side effects that could result from this flexibility, PIC24F devices have a safeguard lock built into the switching process.

Note:	The Primary Oscillator mode has three different submodes (XT, HS and EC) which are determined by the POSCMDx Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch between the different primary submodes without reprogramming the device.

8.4.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM1 Configuration bit in CW2 must be programmed to '0'. (Refer to **Section 27.1 "Configuration Bits"** for further details.) If the FCKSM1 Configuration bit is unprogrammed ('1'), the clock switching function and Fail-Safe Clock Monitor function are disabled. This is the default setting.

The NOSCx (OSCCON<10:8>) control bits do not control the clock selection when clock switching is disabled. However, the COSCx (OSCCON<14:12>) control bits will reflect the clock source selected by the FNOSCx Configuration bits.

The OSWEN (OSCCON<0>) control bit has no effect when clock switching is disabled; It is held at '0' at all times.

8.4.2 OSCILLATOR SWITCHING SEQUENCE

At a minimum, performing a clock switch requires this basic sequence:

1. If desired, read the COSCx (OSCCON<14:12>) control bits to determine the current oscillator source.
2. Perform the unlock sequence to allow a write to the OSCCON register high byte.
3. Write the appropriate value to the NOSCx (OSCCON<10:8>) control bits for the new oscillator source.
4. Perform the unlock sequence to allow a write to the OSCCON register low byte.
5. Set the OSWEN bit to initiate the oscillator switch.

Once the basic sequence is completed, the system clock hardware responds automatically as follows:

1. The clock switching hardware compares the COSCx bits with the new value of the NOSCx bits. If they are the same, then the clock switch is a redundant operation. In this case, the OSWEN bit is cleared automatically and the clock switch is aborted.
2. If a valid clock switch has been initiated, the LOCK (OSCCON<5>) and CF (OSCCON<3>) bits are cleared.
3. The new oscillator is turned on by the hardware if it is not currently running. If a crystal oscillator must be turned on, the hardware will wait until the OST expires. If the new source is using the PLL, then the hardware waits until a PLL lock is detected (LOCK = 1).
4. The hardware waits for 10 clock cycles from the new clock source and then performs the clock switch.
5. The hardware clears the OSWEN bit to indicate a successful clock transition. In addition, the NOSCx bit values are transferred to the COSCx bits.
6. The old clock source is turned off at this time, with the exception of LPRC (if WDT or FSCM are enabled) or SOSC (if SOSCEN remains set).

Note 1:	The processor will continue to execute code throughout the clock switching sequence. Timing-sensitive code should not be executed during this time.
2:	Direct clock switches between any Primary Oscillator mode with PLL and FRCPLL modes are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.

REGISTER 10-39: RPOR10: PERIPHERAL PIN SELECT OUTPUT REGISTER 10

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP21R5	RP21R4	RP21R3	RP21R2	RP21R1	RP21R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP20R5	RP20R4	RP20R3	RP20R2	RP20R1	RP20R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **RP21R<5:0>:** RP21 Output Pin Mapping bits
Peripheral output number n is assigned to pin, RP21 (see Table 10-4 for peripheral function numbers).

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **RP20R<5:0>:** RP20 Output Pin Mapping bits
Peripheral output number n is assigned to pin, RP20 (see Table 10-4 for peripheral function numbers).

REGISTER 10-40: RPOR11: PERIPHERAL PIN SELECT OUTPUT REGISTER 11

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP23R5	RP23R4	RP23R3	RP23R2	RP23R1	RP23R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP22R5	RP22R4	RP22R3	RP22R2	RP22R1	RP22R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

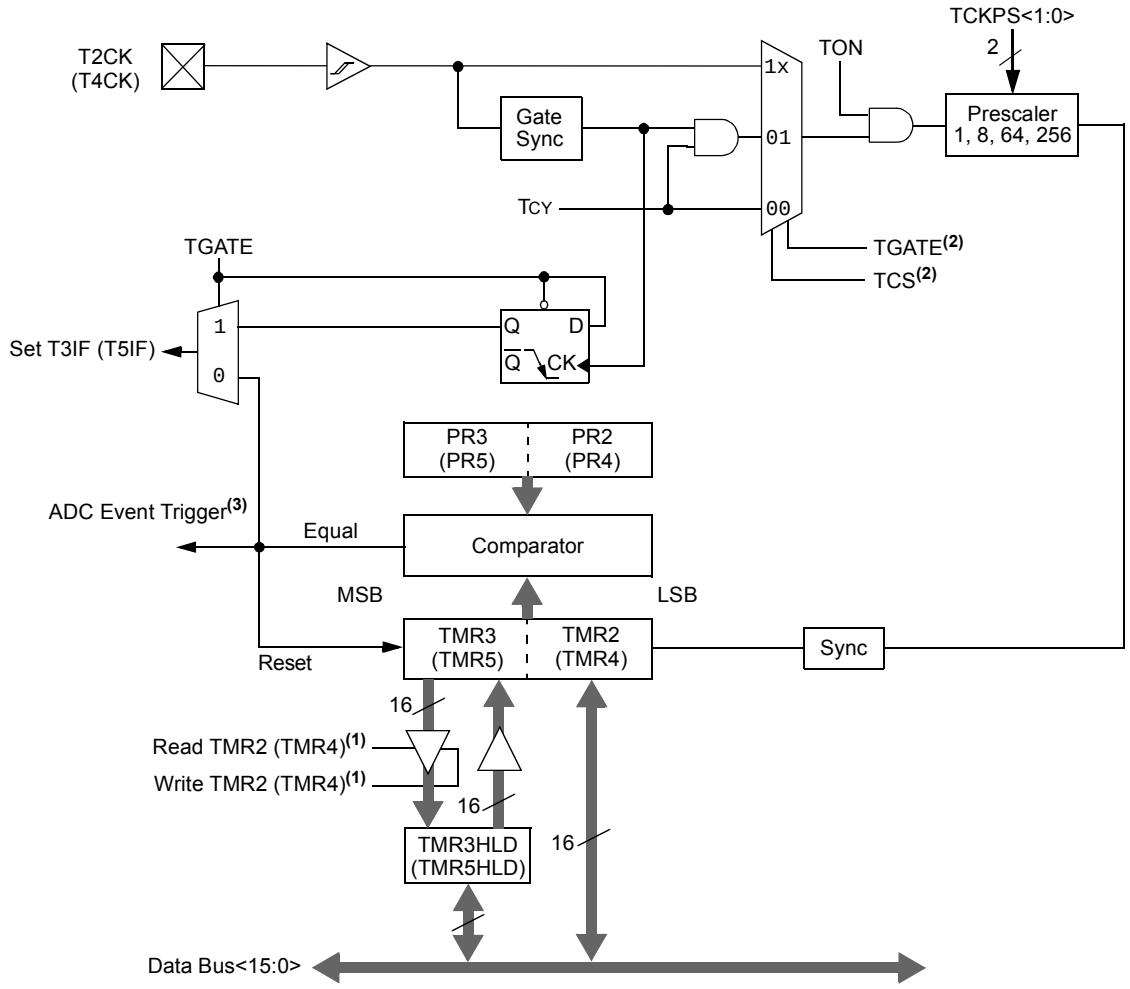
bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **RP23R<5:0>:** RP23 Output Pin Mapping bits
Peripheral output number n is assigned to pin, RP23 (see Table 10-4 for peripheral function numbers).

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **RP22R<5:0>:** RP22 Output Pin Mapping bits
Peripheral output number n is assigned to pin, RP22 (see Table 10-4 for peripheral function numbers).

FIGURE 12-1: TIMER2/3 AND TIMER4/5 (32-BIT) BLOCK DIAGRAM



Note 1: The 32-Bit Timer Configuration bit, T32, must be set for 32-bit timer/counter operation. All control bits are respective to the T2CON and T4CON registers.

2: The timer clock input must be assigned to an available RPn/RPIn pin before use. See **Section 10.4 "Peripheral Pin Select (PPS)"** for more information.

3: The ADC event trigger is available only on Timer 2/3 in 32-bit mode and Timer 3 in 16-bit mode.

15.0 SERIAL PERIPHERAL INTERFACE (SPI)

Note:	This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, **Section 23. "Serial Peripheral Interface (SPI)"** (DS39699). The information in this data sheet supersedes the information in the FRM.

The Serial Peripheral Interface (SPI) module is a synchronous serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices may be serial EEPROMs, shift registers, display drivers, A/D Converters, etc. The SPI module is compatible with the SPI and SIOP Motorola® interfaces. All devices of the PIC24FJ256DA210 family include three SPI modules.

The module supports operation in two buffer modes. In Standard mode, data is shifted through a single serial buffer. In Enhanced Buffer mode, data is shifted through an 8-level FIFO buffer.

Note:	Do not perform read-modify-write operations (such as bit-oriented instructions) on the SPIxBUF register in either Standard or Enhanced Buffer mode.

The module also supports a basic framed SPI protocol while operating in either Master or Slave mode. A total of four framed SPI configurations are supported.

The SPI serial interface consists of four pins:

- SDIx: Serial Data Input
- SDOx: Serial Data Output
- SCKx: Shift Clock Input or Output
- $\overline{SS}$x: Active-Low Slave Select or Frame Synchronization I/O Pulse

The SPI module can be configured to operate using 2, 3 or 4 pins. In the 3-pin mode, $\overline{SS}$x is not used. In the 2-pin mode, both SDOx and $\overline{SS}$x are not used.

Block diagrams of the module in Standard and Enhanced modes are shown in Figure 15-1 and Figure 15-2.

Note:	In this section, the SPI modules are referred to together as SPIx or separately as SPI1, SPI2 or SPI3. Special Function Registers will follow a similar notation. For example, SPIxCON1 and SPIxCON2 refer to the control registers for any of the 3 SPI modules.

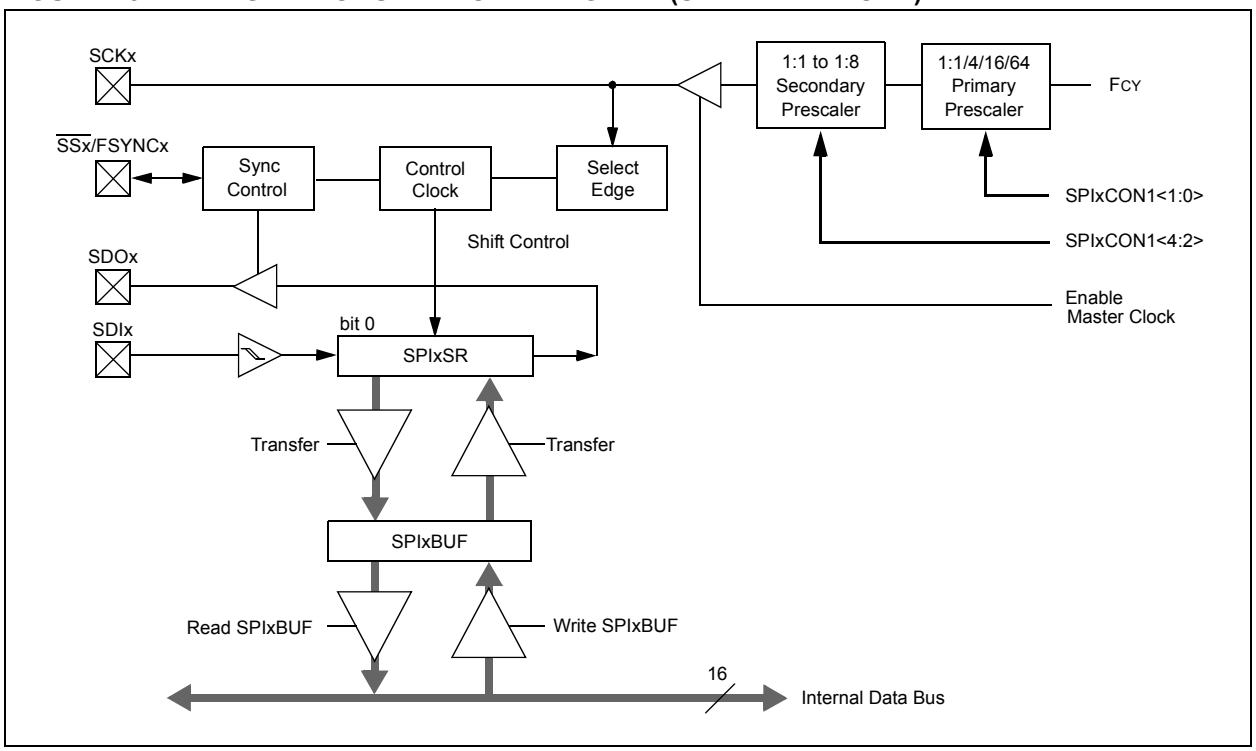
To set up the SPI module for the Standard Master mode of operation:

1. If using interrupts:
   a) Clear the SPIxIF bit in the respective IFS register.
   b) Set the SPIxIE bit in the respective IEC register.
   c) Write the SPIxIP bits in the respective IPC register to set the interrupt priority.
2. Write the desired settings to the SPIxCON1 and SPIxCON2 registers with MSTEN (SPIxCON1<5>) = 1.
3. Clear the SPIROV bit (SPIxSTAT<6>).
4. Enable SPI operation by setting the SPIEN bit (SPIxSTAT<15>).
5. Write the data to be transmitted to the SPIxBUF register. Transmission (and reception) will start as soon as data is written to the SPIxBUF register.

To set up the SPI module for the Standard Slave mode of operation:

1. Clear the SPIxBUF register.
2. If using interrupts:
   a) Clear the SPIxIF bit in the respective IFS register.
   b) Set the SPIxIE bit in the respective IEC register.
   c) Write the SPIxIP bits in the respective IPC register to set the interrupt priority.
3. Write the desired settings to the SPIxCON1 and SPIxCON2 registers with MSTEN (SPIxCON1<5>) = 0.
4. Clear the SMP bit.
5. If the CKE bit (SPIxCON1<8>) is set, then the SSEN bit (SPIxCON1<7>) must be set to enable the $\overline{SSx}$ pin.
6. Clear the SPIROV bit (SPIxSTAT<6>).
7. Enable SPI operation by setting the SPIEN bit (SPIxSTAT<15>).

FIGURE 15-1: SPIx MODULE BLOCK DIAGRAM (STANDARD MODE)



17.1 UART Baud Rate Generator (BRG)

The UART module includes a dedicated, 16-bit Baud Rate Generator. The UxBRG register controls the period of a free-running, 16-bit timer. Equation 17-1 shows the formula for computation of the baud rate with BRGH = 0.

EQUATION 17-1: UART BAUD RATE WITH BRGH = 0(1,2)

$$\text{Baud Rate} = \frac{FCY}{16 \bullet (UxBRG + 1)}$$

$$UxBRG = \frac{FCY}{16 \bullet \text{Baud Rate}} - 1$$

Note 1: FCY denotes the instruction cycle clock frequency (FOSC/2).

2: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

Example 17-1 shows the calculation of the baud rate error for the following conditions:

- FCY = 4 MHz
- Desired Baud Rate = 9600

The maximum baud rate (BRGH = 0) possible is FCY/16 (for UxBRG = 0) and the minimum baud rate possible is FCY/(16 * 65536).

Equation 17-2 shows the formula for computation of the baud rate with BRGH = 1.

EQUATION 17-2: UART BAUD RATE WITH BRGH = 1(1,2)

$$\text{Baud Rate} = \frac{FCY}{4 \bullet (UxBRG + 1)}$$

$$UxBRG = \frac{FCY}{4 \bullet \text{Baud Rate}} - 1$$

Note 1: FCY denotes the instruction cycle clock frequency.

2: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

The maximum baud rate (BRGH = 1) possible is FCY/4 (for UxBRG = 0) and the minimum baud rate possible is FCY/(4 * 65536).

Writing a new value to the UxBRG register causes the BRG timer to be reset (cleared). This ensures the BRG does not wait for a timer overflow before generating the new baud rate.

EXAMPLE 17-1: BAUD RATE ERROR CALCULATION (BRGH = 0)(1)

Desired Baud Rate = FCY/(16 (BRGx + 1))

Solving for BRGx Value:

BRGx = ((FCY/Desired Baud Rate)/16) – 1
BRGx = ((4000000/9600)/16) – 1
BRGx = 25

Calculated Baud Rate = 4000000/(16 (25 + 1))
= 9615

Error = (Calculated Baud Rate – Desired Baud Rate) / Desired Baud Rate
= (9615 – 9600)/9600

Note: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

20.0 REAL-TIME CLOCK AND CALENDAR (RTCC)

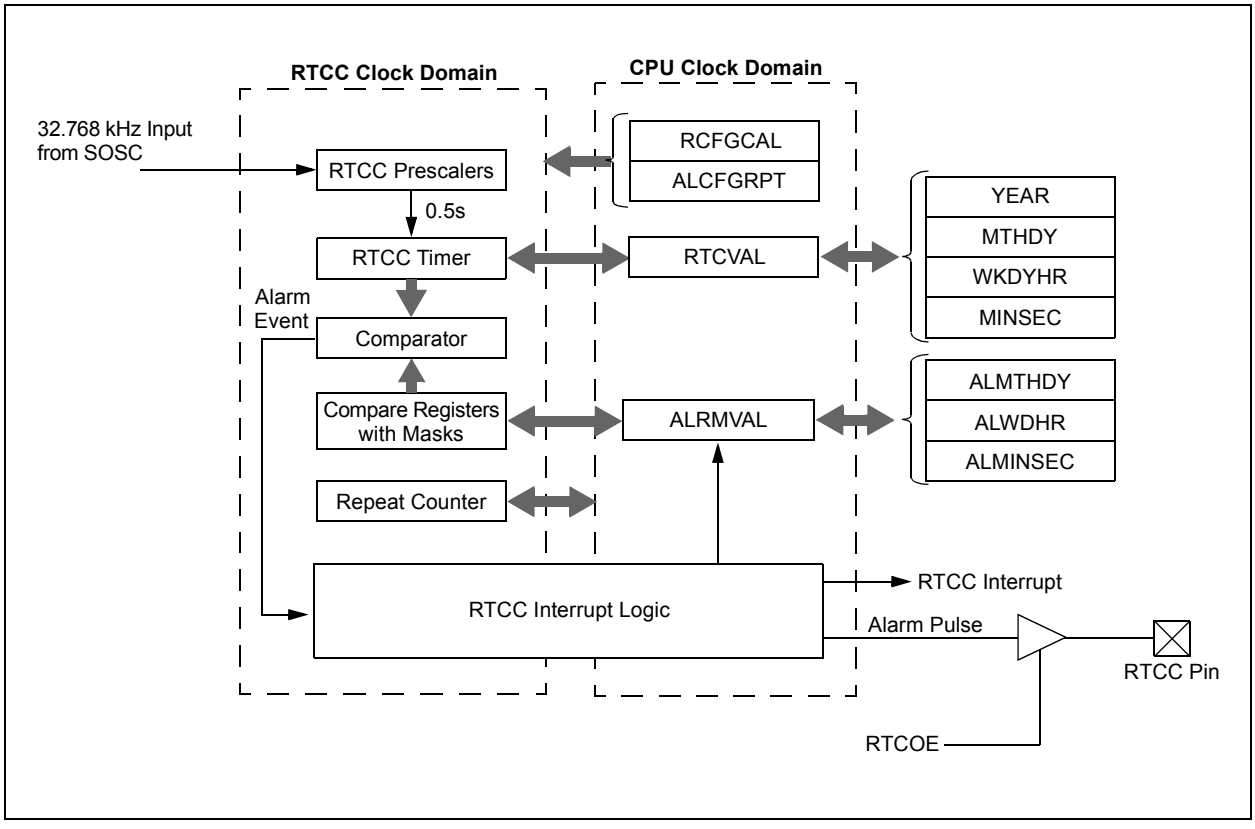
Note:	This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "*PIC24F Family Reference Manual*", **Section 29. "Real-Time Clock and Calendar (RTCC)"** (DS39696). The information in this data sheet supersedes the information in the FRM.

The Real-Time Clock and Calendar (RTCC) provides a function that can be calibrated.

Key features of the RTCC module are:

- Operates in Sleep mode
- Provides hours, minutes and seconds using 24-hour format
- Visibility of half of one second period
- Provides calendar – weekday, date, month and year
- Alarm configurable for half a second, one second,10 seconds, one minute, 10 minutes, one hour, one day, one week, one month or one year
- Alarm repeat with decrementing counter
- Alarm with indefinite repeat chime
- Year, 2000 to 2099, leap year correction
- BCD format for smaller software overhead
- Optimized for long-term battery operation
- User calibration of the 32.768 kHz clock crystal/32K INTRC frequency with periodic auto-adjust
  - Calibration to within ±2.64 seconds error per month
  - Calibrates up to 260 ppm of crystal error

FIGURE 20-1: RTCC BLOCK DIAGRAM



22.2 Display Resolution and Memory Requirements

The PIC24FJ256DA210 family of devices has two variants in terms of on-board RAM (24-Kbyte and 96-Kbyte variants). The 24-Kbyte variant supports monochrome displays while the 96-Kbyte variant supports Quarter VGA (QVGA) color displays, up to 256 colors. Support of higher resolution displays with higher color depth requirements are available by extending the data space through external memory. Table 22-1 provides the summary of image buffer memory requirements of different display resolutions and color depth requirements.

22.3 Display Clock (GCLK) Source

Frequency of the Graphics Controller Display Clock (GCLK) signal is determined by programming the GCLKDIV bits (CLKDIV2<15:9>). For more information, refer to the "*PIC24F Family Reference Manual*", **Section 6. "Oscillator" (**DS39700**)**.

22.4 Display Buffer and Work Areas Memory Locations

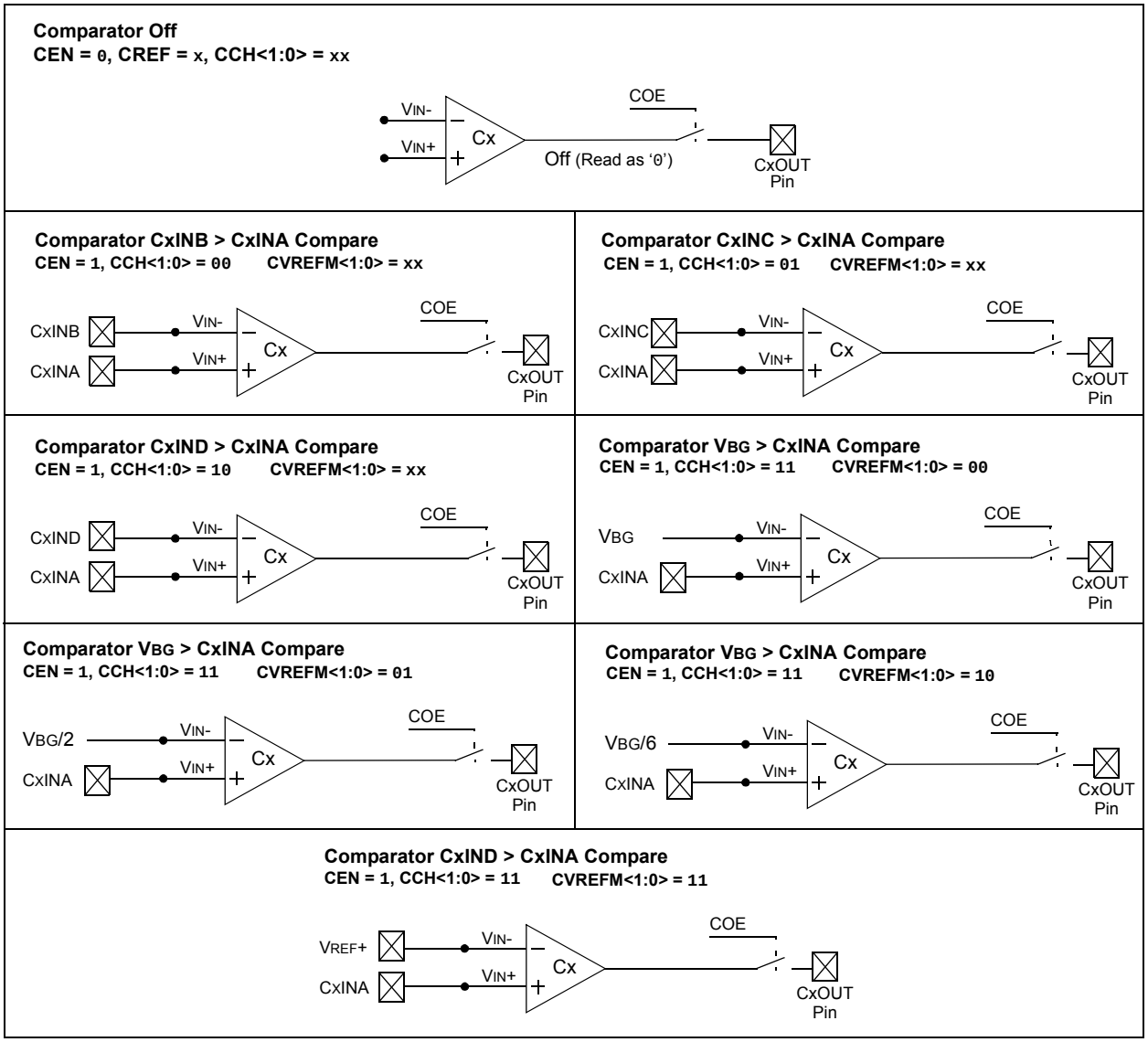
The PIC24FJ256DA210 family of devices has variants with two on-board RAM sizes. These are the 24-Kbyte and 96-Kbyte variants. These two RAM variants are further divided in terms of pin counts. The 100-pin count device will have the EPMP module available for extending RAM for applications. The 64-pin count device will not have the EPMP modules. Extending the RAM size is necessary for applications that require larger display buffers and work areas. It is recommended that the display buffers and work areas are **not** mapped into an area that overlaps the internal RAM and the external RAM. The external RAM can be interfaced using the EPMP module. For details, refer to the "*PIC24F Family Reference Manual*", **Section 42. "Enhanced Parallel Master Port (EPMP)"** (DS39730).

TABLE 22-1: BUFFER MEMORY REQUIREMENTS vs. DISPLAY CONFIGURATION

Display Resolution	Display Buffer Memory Requirements (Bytes)				
	1 Bpp	2 Bpp	4 Bpp	8 Bpp	16 Bpp
480x272 (WQVGA)	16320	32640	65280	130560	261120
320x240 (QVGA)	9600	19200	38400	76800	153600
240x160 (HQVGA)	4800	9600	19200	38400	76800
160x160	3200	6400	12800	25600	51200
160x120 (QQVGA)	2400	4800	9600	19200	38400
128x64	1024	2048	4096	8192	16384

Legend:
- Less than 24-Kbyte RAM variants (PIC24FJXXXDA106)
- Less than 96-Kbyte RAM variants (PIC24FJXXXDA2XX)
- External Memory with 96 Kbytes/24 Kbytes of RAM variants (PIC24FJXXXDAX10)

FIGURE 24-2: INDIVIDUAL COMPARATOR CONFIGURATIONS WHEN CREF = 0



26.0 CHARGE TIME MEASUREMENT UNIT (CTMU)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the associated "*PIC24F Family Reference Manual*", **Section 11. "Charge Time Measurement Unit (CTMU)"** (DS39724). The information in this data sheet supersedes the information in the FRM.

The Charge Time Measurement Unit (CTMU) is a flexible analog module that provides accurate differential time measurement between pulse sources, as well as asynchronous pulse generation. Its key features include:

- Four edge input trigger sources
- Polarity control for each edge source
- Control of edge sequence
- Control of response to edges
- Time measurement resolution of 1 nanosecond
- Accurate current source suitable for capacitive measurement

Together with other on-chip analog modules, the CTMU can be used to precisely measure time, measure capacitance, measure relative changes in capacitance or generate output pulses that are independent of the system clock. The CTMU module is ideal for interfacing with capacitive-based sensors.

The CTMU is controlled through two registers: CTMUCON and CTMUICON. CTMUCON enables the module, and controls edge source selection, edge source polarity selection, and edge sequencing. The CTMUICON register controls the selection and trim of the current source.

26.1 Measuring Capacitance

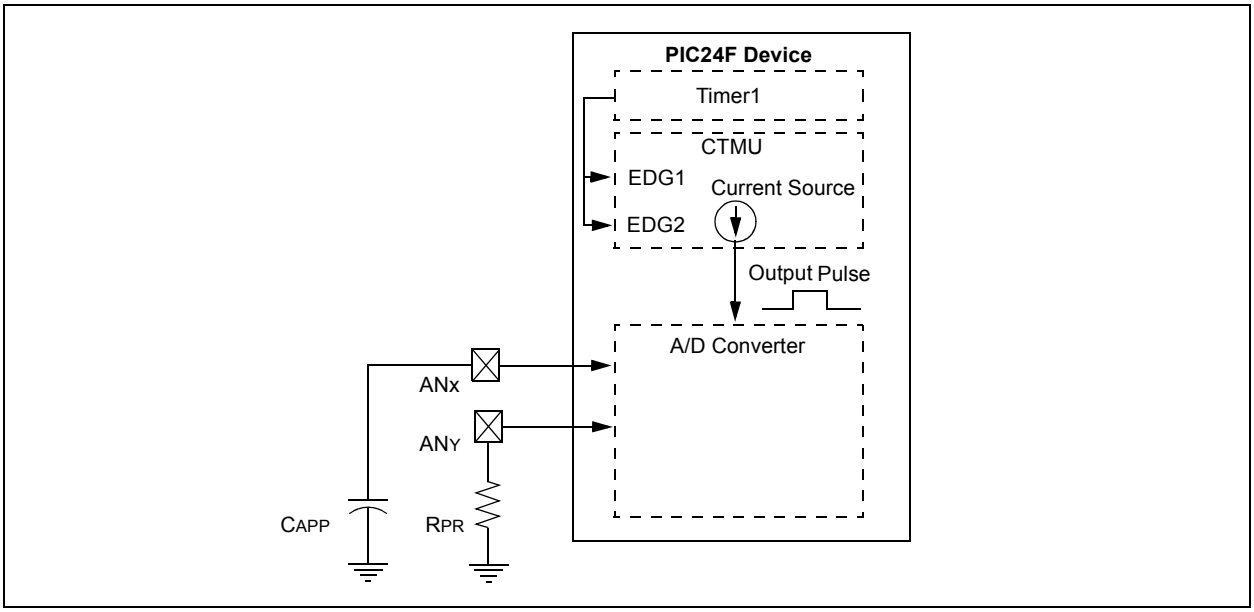
The CTMU module measures capacitance by generating an output pulse with a width equal to the time between edge events on two separate input channels. The pulse edge events to both input channels can be selected from four sources: two internal peripheral modules (OC1 and Timer1) and two external pins (CTEDG1 and CTEDG2). This pulse is used with the module's precision current source to calculate capacitance according to the relationship:

$$C = I \cdot \frac{dV}{dT}$$

For capacitance measurements, the A/D Converter samples an external capacitor (C_{APP}) on one of its input channels after the CTMU output's pulse. A precision resistor (R_{PR}) provides current source calibration on a second A/D channel. After the pulse ends, the converter determines the voltage on the capacitor. The actual calculation of capacitance is performed in software by the application.

Figure 26-1 shows the external connections used for capacitance measurements, and how the CTMU and A/D modules are related in this application. This example also shows the edge events coming from Timer1, but other configurations using external edge sources are possible. A detailed discussion on measuring capacitance and time with the CTMU module is provided in the "*PIC24F Family Reference Manual*".

FIGURE 26-1: TYPICAL CONNECTIONS AND INTERNAL CONFIGURATION FOR CAPACITANCE MEASUREMENT



NOTES: