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Understanding <u>Embedded - CPLDs (Complex</u> <u>Programmable Logic Devices)</u>

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixedfunction ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

Applications of Embedded - CPLDs

Details

Product Status	Obsolete
Programmable Type	EE PLD
Delay Time tpd(1) Max	7.5 ns
Voltage Supply - Internal	4.75V ~ 5.25V
Number of Logic Elements/Blocks	-
Number of Macrocells	8
Number of Gates	-
Number of I/O	-
Operating Temperature	0°C ~ 75°C (TA)
Mounting Type	Surface Mount
Package / Case	20-LCC (J-Lead)
Supplier Device Package	20-PLCC (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/lattice-semiconductor/gal16v8d-7lj

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



Product Line	Ordering Part Number	Product Status	Reference PCN
	GAL16V8D-7LJ		
	GAL16V8D-7LJN		
	GAL16V8D-10LJ		
	GAL16V8D-10LJN		PCN#13-10
	GAL16V8D-15LJ		<u>1 010#10 10</u>
	GAL16V8D-15LJN		
	GAL16V8D-25LJ		
	GAL16V8D-25LJN		
	GAL16V8D-7LJI		PCN#09-10
	GAL16V8D-7LJNI		<u>1 011#00 10</u>
	GAL16V8D-10LJI		
	GAL16V8D-10LJNI		
	GAL16V8D-15LJI		
	GAL16V8D-15LJNI	Discontinued	
GAL16V8D	GAL16V8D-25LJI		
(Cont'd)	GAL16V8D-25LJNI		
	GAL16V8D-10QJ		
	GAL16V8D-10QJN		PCN#13-10
	GAL16V8D-15QJ		<u> </u>
	GAL16V8D-15QJN	_	
	GAL16V8D-25QJ	_	
	GAL16V8D-25QJN	_	
	GAL16V8D-20QJI	_	
	GAL16V8D-20QJNI	_	
	GAL16V8D-25QJI	_	
	GAL16V8D-25QJNI		
	GAL16V8D-7LS		
	GAL16V8D-10LS		PCN#06-07
	GAL16V8D-15LS		
	GAL16V8D-25LS		



GAL16V8 Ordering Information

Conventional Packaging Commercial Grade Specifications

Tpd (ns)	Tsu (ns)	Tco (ns)	lcc (mA)	Ordering #	Package
3.5	2.5	3.0	115	GAL16V8D-3LJ ¹	20-Lead PLCC
5	3	4	115	GAL16V8C-5LP1	20-Pin Plastic DIP
			115	GAL16V8D-5LJ	20-Lead PLCC
7.5	7	5	115	GAL16V8D-7LP	20-Pin Plastic DIP
			115	GAL16V8C-7LP1	20-Pin Plastic DIP
			115	GAL16V8D-7LJ	20-Lead PLCC
			115	GAL16V8D-7LS1	20-Pin SOIC
10	10	7	55	GAL16V8D-10QP	20-Pin Plastic DIP
			55	GAL16V8D-10QJ	20-Lead PLCC
			115	GAL16V8D-10LP	20-Pin Plastic DIP
			115	GAL16V8D-10LJ	20-Lead PLCC
			115	GAL16V8D-10LS1	20-Pin SOIC
15	12	10	55	GAL16V8D-15QP	20-Pin Plastic DIP
			55	GAL16V8D-15QJ	20-Lead PLCC
			90	GAL16V8D-15LP	20-Pin Plastic DIP
			90	GAL16V8D-15LJ	20-Lead PLCC
			90	GAL16V8D-15LS1	20-Pin SOIC
25	15	12	55	GAL16V8D-25QP	20-Pin Plastic DIP
			55	GAL16V8D-25QJ	20-Lead PLCC
			90	GAL16V8D-25LP	20-Pin Plastic DIP
			90	GAL16V8D-25LJ	20-Lead PLCC
			90	GAL16V8D-25LS1	20-Pin SOIC

1. Discontinued per PCN #06-07, Contact Rochester Electronics for available inventory.

Industrial Grade Specifications

Tpd (ns)	Tsu (ns)	Tco (ns)	lcc (mA)	Ordering #	Package
7.5	7	5	130	GAL16V8D-7LPI	20-Pin Plastic DIP
			130	GAL16V8D-7LJI	20-Lead PLCC
10	10	7	130	GAL16V8D-10LPI	20-Pin Plastic DIP
			130	GAL16V8D-10LJI	20-Lead PLCC
15	12	10	130	GAL16V8D-15LPI	20-Pin Plastic DIP
			130	GAL16V8D-15LJI	20-Lead PLCC
20	13	11	65	GAL16V8D-20QPI	20-Pin Plastic DIP
		•	65	GAL16V8D-20QJI	20-Lead PLCC
25	15	12	65	GAL16V8D-25QPI	20-Pin Plastic DIP
			65	GAL16V8D-25QJI	20-Lead PLCC
			130	GAL16V8D-25LPI	20-Pin Plastic DIP
			130	GAL16V8D-25LJI	20-Lead PLCC



Output Logic Macrocell (OLMC)

The following discussion pertains to configuring the output logic macrocell. It should be noted that actual implementation is accomplished by development software/hardware and is completely transparent to the user.

There are three global OLMC configuration modes possible: **simple**, **complex**, and **registered**. Details of each of these modes are illustrated in the following pages. Two global bits, SYN and ACO, control the mode configuration for all macrocells. The XOR bit of each macrocell controls the polarity of the output in any of the three modes, while the AC1 bit of each of the macrocells controls the input/output configuration. These two global and 16 individual architecture bits define all possible configurations in a GAL16V8. The information given on these architecture bits is only to give a better understanding of the device. Compiler software will transparently set these architecture bits from the pin definitions, so the user should not need to directly manipulate these architecture bits.

The following is a list of the PAL architectures that the GAL16V8 can emulate. It also shows the OLMC mode under which the GAL16V8 emulates the PAL architecture.



Compiler Support for OLMC

Software compilers support the three different global OLMC modes as different device types. These device types are listed in the table below. Most compilers have the ability to automatically select the device type, generally based on the register usage and output enable (OE) usage. Register usage on the device forces the software to choose the registered mode. All combinatorial outputs with OE controlled by the product term will force the software to choose the complex mode. The software will choose the simple mode only when all outputs are dedicated combinatorial without OE control. The different device types listed in the table can be used to override the automatic device selection by the software. For further details, refer to the compiler software manuals.

When using compiler software to configure the device, the user must pay special attention to the following restrictions in each mode. In **registered mode** pin 1 and pin 11 are permanently configured

as clock and output enable, respectively. These pins cannot be configured as dedicated inputs in the registered mode.

In **complex mode** pin 1 and pin 11 become dedicated inputs and use the feedback paths of pin 19 and pin 12 respectively. Because of this feedback path usage, pin 19 and pin 12 do not have the feedback option in this mode.

In **simple mode** all feedback paths of the output pins are routed via the adjacent pins. In doing so, the two inner most pins (pins 15 and 16) will not have the feedback option as these pins are always configured as dedicated combinatorial output.

	Registered	Complex	Simple	Auto Mode Select
ABEL	P16V8R	P16V8C	P16V8AS	P16V8
CUPL	G16V8MS	G16V8MA	G16V8AS	G16V8
LOG/iC	GAL16V8_R	GAL16V8_C7	GAL16V8_C8	GAL16V8
OrCAD-PLD	"Registered"1	"Complex" ¹	"Simple"1	GAL16V8A
PLDesigner	P16V8R ²	P16V8C ²	P16V8C ²	P16V8A
TANGO-PLD	G16V8R	G16V8C	G16V8AS ³	G16V8

1) Used with Configuration keyword.

2) Prior to Version 2.0 support.

3) Supported on Version 1.20 or later.



Registered Mode

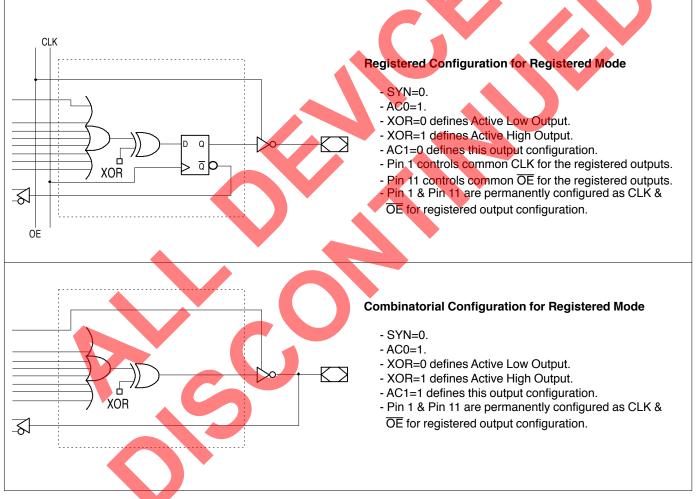
In the Registered mode, macrocells are configured as dedicated registered outputs or as I/O functions.

Architecture configurations available in this mode are similar to the common 16R8 and 16RP4 devices with various permutations of polarity, I/O and register placement.

All registered macrocells share common clock and output enable control pins. Any macrocell can be configured as registered or I/ O. Up to eight registers or up to eight I/O's are possible in this mode. Dedicated input or output functions can be implemented as subsets of the I/O function.

Registered outputs have eight product terms per output. I/O's have seven product terms per output.

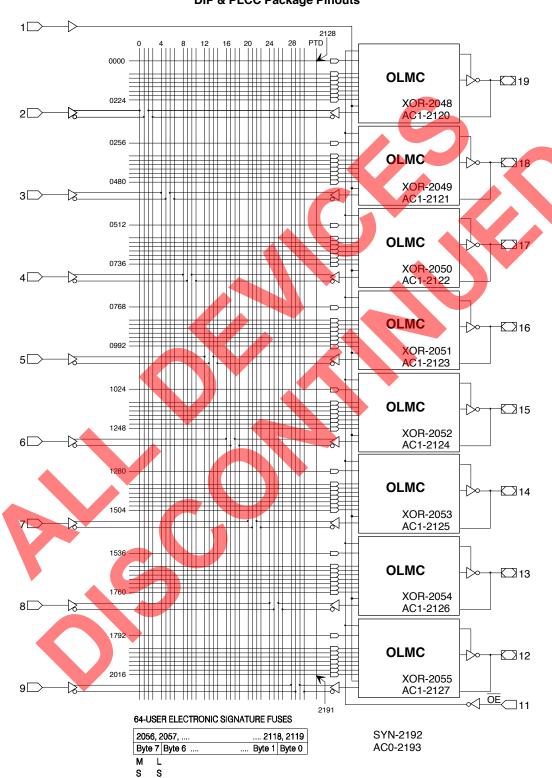
The JEDEC fuse numbers, including the User Electronic Signature (UES) fuses and the Product Term Disable (PTD) fuses, are shown on the logic diagram on the following page.



Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.



Registered Mode Logic Diagram



DIP & PLCC Package Pinouts

B B



Complex Mode

In the Complex mode, macrocells are configured as output only or $\ensuremath{\mathsf{I/O}}$ functions.

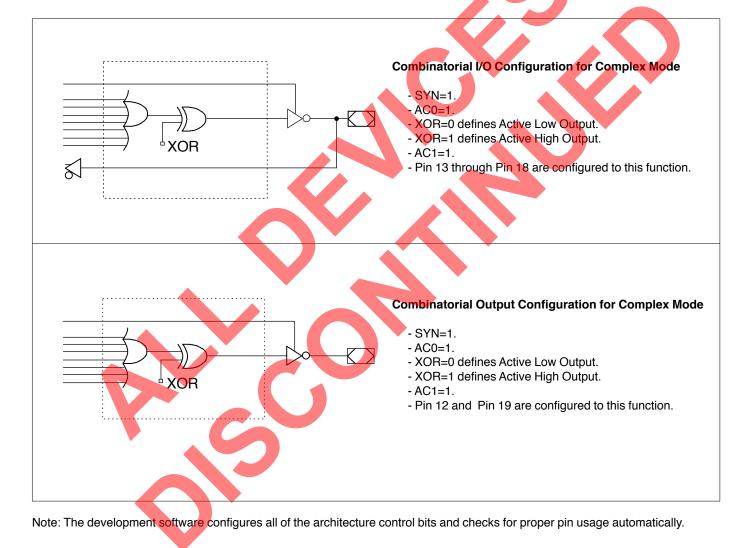
Architecture configurations available in this mode are similar to the common 16L8 and 16P8 devices with programmable polarity in each macrocell.

Up to six I/O's are possible in this mode. Dedicated inputs or outputs can be implemented as subsets of the I/O function. The two outer most macrocells (pins 12 & 19) do not have input capa-

bility. Designs requiring eight I/O's can be implemented in the Registered mode.

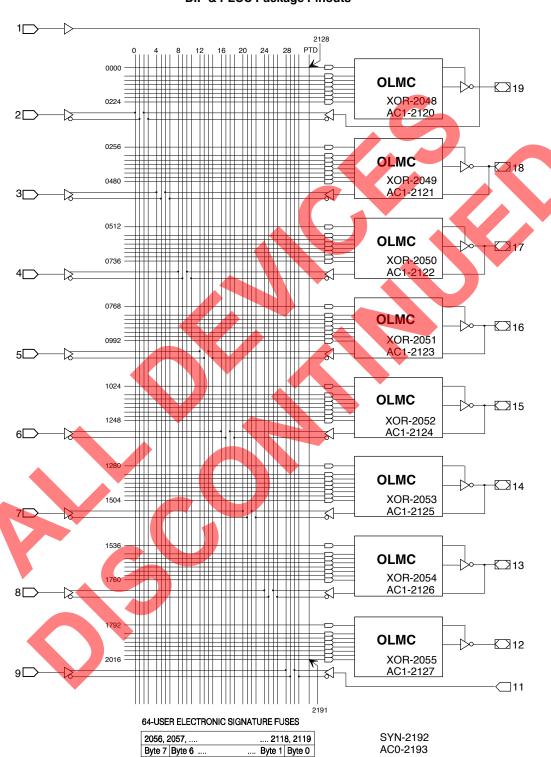
All macrocells have seven product terms per output. One product term is used for programmable output enable control. Pins 1 and 11 are always available as data inputs into the AND array.

The JEDEC fuse numbers including the UES fuses and PTD fuses are shown on the logic diagram on the following page.





Complex Mode Logic Diagram



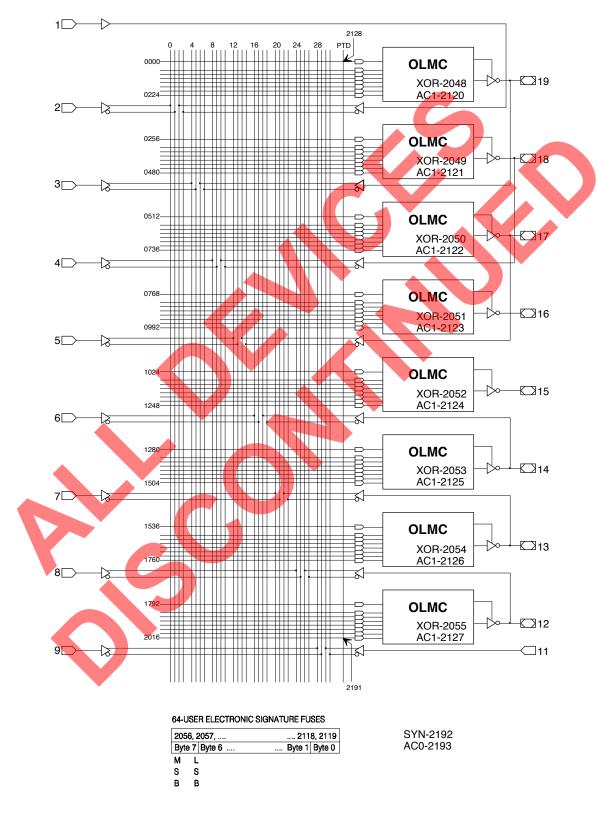
DIP & PLCC Package Pinouts

M L S S B B



Simple Mode Logic Diagram

DIP & PLCC Package Pinouts





Absolute Maximum Ratings(1)

Supply voltage V _{cc}	–0.5 to +7V
Input voltage applied	
Off-state output voltage applied	-2.5 to $V_{cc}^{\circ\circ}$ +1.0V
Storage Temperature	–65 to 150°C
Ambient Temperature with	

Power Applied--55 to 125°C 1.Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

Recommended Operating Conditions

Commercial Devices:

Ambient Temperature (T _A)	0 to 75°C
Supply voltage (V _{cc})	
with Respect to Ground	+4.75 to +5.25V

Industrial Devices:

Ambient Temperature (T _A)	–40 to 85°C
Supply voltage (V _{cc})	
with Respect to Ground	+4.50 to +5.50V

DC Electrical Characteristics

SYMBOL	PARAMETER	CONDITION	MIN.	TYP. ³	MAX.	UNITS
VIL	Input Low Voltage		Vss – 0.5	_	0.8	v
V ΙΗ	Input High Voltage		2.0	_	Vcc+1	V
IL ¹	Input or I/O Low Leakage Current	$0V \leq V_{IN} \leq V_{IL}$ (MAX.)	—	_	-100	μA
Ін	Input or I/O High Leakage Current	3.5V ≤ VIN ≤ Vcc	_	_	10	μA
VOL	Output Low Voltage	IOL = MAX. Vin = VIL or VIH	_	_	0.5	V
V он	Output High Voltage	Iон = MAX. Vin = Vil or Viн	2.4	_	_	V
IOL	Low Level Output Current	L-3/-5 & -7 (Ind. PLCC)	_	_	16	mA
		L-7 (Except Ind. PLCC)/-10/-15/-25 Q-10/-15/-20/-25	_	_	24	mA
Юн	High Level Output Current		_	_	-3.2	mA
OS ²	Output Short Circuit Current	V cc = 5V V out = $0.5V$ T _A = $25^{\circ}C$	-30	_	-150	mA
СОММЕ	RCIAL					

Over Recommended Operating Conditions (Unless Otherwise Specified)

COMM							
Icc	Operating Power	V IL = 0.5V V IH = 3.0V	L -3/-5/-7/-10	_	75	115	mA
	Supply Current	ftoggle = 15MHz Outputs Open	L-15/-25	—	75	90	mA
			Q-10/-15/-25	—	45	55	mA
INDUS							
Icc	Operating Power	$V_{IL} = 0.5V$ $V_{IH} = 3.0V$	L -7/-10/-15/-25	_	75	130	mA
	Supply Current	ftoggle = 15MHz Outputs Open	Q -20/-25	_	45	65	mA

1) The leakage current is due to the internal pull-up resistor on all pins. See Input Buffer section for more information.

2) One output at a time for a maximum duration of one second. Vout = 0.5V was selected to avoid test problems caused by tester ground degradation. Characterized but not 100% tested.

3) Typical values are at Vcc = 5V and T_A = 25 $^{\circ}$ C



AC Switching Characteristics

			СОМ	/IND	СОМ	/ IND	IN	ID	СОМ	/IND	
PARAM.	TEST	DESCRIPTION	-1	0	-15		-2	0	-2	25	UNITS
FANAM.	COND ¹ .		MIN.	MAX.	MIN.	MAX.	MIN.	МАХ.	MIN.	MAX.	01113
t pd	А	Input or I/O to Comb. Output	3	10	3	15	3	20	3	25	ns
t co	А	Clock to Output Delay	2	7	2	10	2	11	2	12	ns
tcf ²	_	Clock to Feedback Delay	_	6	-	8		9	-	10	ns
t su	_	Setup Time, Input or Fdbk before Clk↑	7.5		12	1	13	-	15	-	ns
t h	_	Hold Time, Input or Fdbk after Clk↑	0	/-	0		0		0	Į	ns
	A	Maximum Clock Frequency with External Feedback, 1/(tsu + tco)	66.7	5	45.5		41.6	-	37		MHz
f max ³	A	Maximum Clock Frequency with Internal Feedback, 1/(tsu + tcf)	71.4	_	50	1	45.4	-	40	_	MHz
	А	Maximum Clock Frequency with No Feedback	83.3	_	62.5	1	50	_	41.6		MHz
t wh	_	Clock Pulse Duration, High	6		8	Ì	10	_	12	_	ns
twl	_	Clock Pulse Duration, Low	6	_	8	-	10	_	12	_	ns
t en	В	Input or I/O to Output Enabled		10		15	_	18	_	20	ns
	В	OE to Output Enabled	1	10	_	15	_	18	_	20	ns
t dis	С	Input or I/O to Output Disabled	1	10	_	15	_	18	_	20	ns
	С	OE to Output Disabled	1	10	_	15	_	18	_	20	ns

Over Recommended Operating Conditions

1) Refer to Switching Test Conditions section.

2) Calculated from fmax with internal feedback. Refer to fmax Descriptions section.

3) Refer to fmax Descriptions section. Characterized but not 100% tested.

Capacitance ($T_A = 25^{\circ}C$, f = 1.0 MHz)

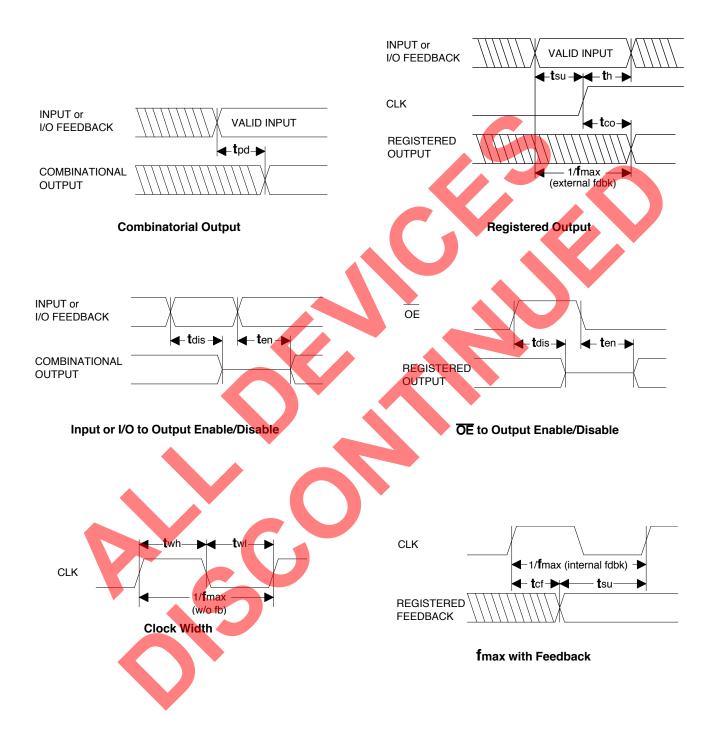
SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
C	Input Capacitance	8	pF	$V_{cc} = 5.0V, V_1 = 2.0V$
C _{I/O}	I/O Capacitance	8	pF	$V_{\rm CC} = 5.0$ V, $V_{\rm IVO} = 2.0$ V

*Characterized but not 100% tested.



Specifications GAL16V8

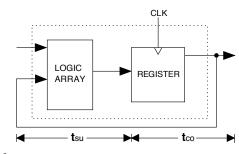
Switching Waveforms





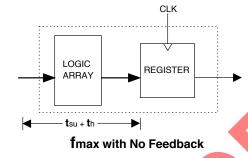
Specifications **GAL16V8**

fmax Descriptions

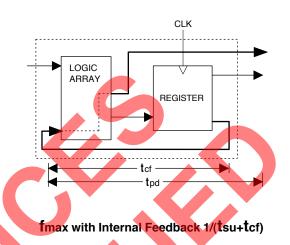


fmax with External Feedback 1/(tsu+tco)

Note: fmax with external feedback is calculated from measured tsu and tco.



Note: fmax with no feedback may be less than 1/(twh + twl). This is to allow for a clock duty cycle of other than 50%.



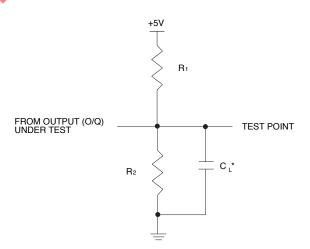
Note: tcf is a calculated value, derived by subtracting tsu from the period of fmax w/internal feedback (tcf = 1/fmax - tsu). The value of tcf is used primarily when calculating the delay from clocking a register to a combinatorial output (through registered feedback), as shown above. For example, the timing from clock to a combinatorial output is equal to tcf + tpd.

Switching Test Conditions

Input Pulse Levels		GND to 3.0V	
Input Rise and Fall Times	GAL16V8D-10 (and slower)	2 – 3ns 10% – 90%	
	GAL16V8D-3/-5/-7	1.5ns 10% – 90%	
Input Timing Re	1.5V		
Output Timing R	1.5V		
Output Load		See figure at right	
3-state levels are	Table 2-0003/16V8		
steady-state activ	e level.		

GAL16V8D (except -3) Output Load Conditions (see figure above)

Test Condition		R1	R2	C∟
Α		200Ω	390Ω	50pF
В	Active High	8	390 Ω	50pF
	Active Low	200Ω	390 Ω	50pF
С	Active High	x	390Ω	5pF
	Active Low	200Ω	390Ω	5pF



*C L INCLUDES TEST FIXTURE AND PROBE CAPACITANCE



Switching Test Conditions (Continued)

GAL16V8D-3 Output Load Conditions (see figure at right)

Test Condition		R1	C∟
Α		50Ω	35pF
В	High Z to Active High at 1.9V	50Ω	35pF
	High Z to Active Low at 1.0V	50Ω	35pF
С	Active High to High Z at 1.9V	50Ω	35pF
	Active Low to High Z at 1.0V	50Ω	35pF

Electronic Signature

An electronic signature is provided in every GAL16V8 device. It contains 64 bits of reprogrammable memory that can contain user defined data. Some uses include user ID codes, revision numbers, or inventory control. The signature data is always available to the user independent of the state of the security cell.

NOTE: The electronic signature is included in checksum calculations. Changing the electronic signature will alter the checksum.

Security Cell

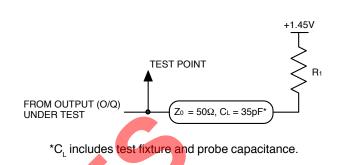
A security cell is provided in the GAL16V8 devices to prevent unauthorized copying of the array patterns. Once programmed, this cell prevents further read access to the functional bits in the device. This cell can only be erased by re-programming the device, so the original configuration can never be examined once this cell is programmed. The Electronic Signature is always available to the user, regardless of the state of this control cell.

Latch-Up Protection

GAL16V8 devices are designed with an on-board charge pump to negatively bias the substrate. The negative bias minimizes the potential of latch-up caused by negative input undershoots. Additionally, outputs are designed with n-channel pull-ups instead of the traditional p-channel pull-ups in order to eliminate latch-up due to output overshoots.

Device Programming

GAL devices are programmed using a Lattice Semiconductorapproved Logic Programmer, available from a number of manufacturers. Complete programming of the device takes only a few seconds. Erasing of the device is transparent to the user, and is done automatically as part of the programming cycle.



Output Register Preload

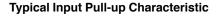
When testing state machine designs, all possible states and state transitions must be verified in the design, not just those required in the normal machine operations. This is because, in system operation, certain events occur that may throw the logic into an illegal state (power-up, line voltage glitches, brown-outs, etc.). To test a design for proper treatment of these conditions, a way must be provided to break the feedback paths, and force any desired (i.e., illegal) state into the registers. Then the machine can be sequenced and the outputs tested for correct next state conditions.

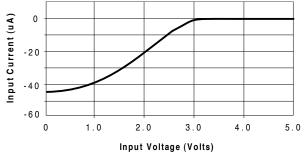
GAL16V8 devices include circuitry that allows each registered output to be synchronously set either high or low. Thus, any present state condition can be forced for test sequencing. If necessary, approved GAL programmers capable of executing text vectors perform output register preload automatically.

Input Buffers

GAL16V8 devices are designed with TTL level compatible input buffers. These buffers have a characteristically high impedance, and present a much lighter load to the driving logic than bipolar TTL devices.

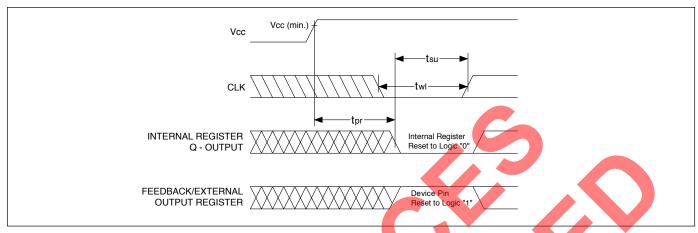
The GAL16V8 input and I/O pins have built-in active pull-ups. As a result, unused inputs and I/O's will float to a TTL "high" (logical "1"). Lattice Semiconductor recommends that all unused inputs and tri-stated I/O pins be connected to another active input, V_{CC} , or Ground. Doing this will tend to improve noise immunity and reduce I_{CC} for the device.



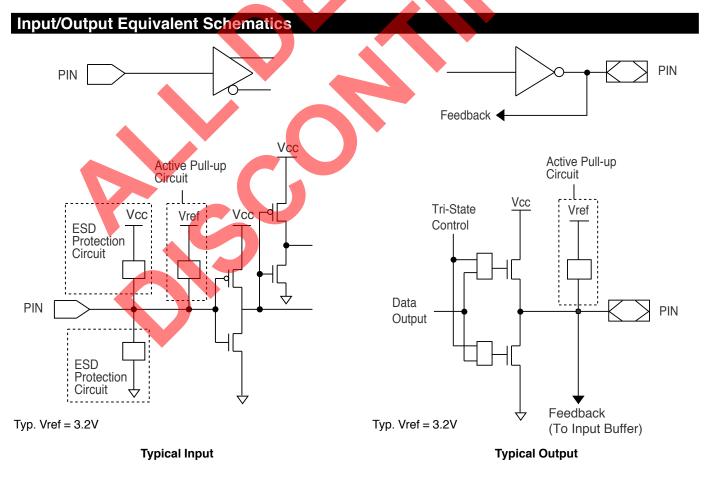




Power-Up Reset

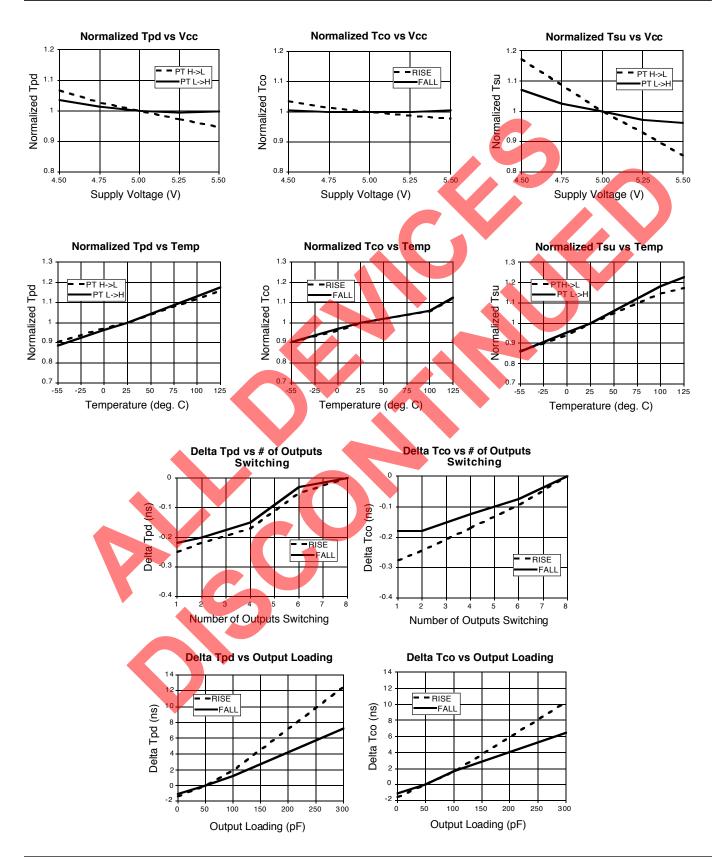


Circuitry within the GAL16V8 provides a reset signal to all registers during power-up. All internal registers will have their Q outputs set low after a specified time (tpr, 1 μ s MAX). As a result, the state on the registered output pins (if they are enabled) will always be high on power-up, regardless of the programmed polarity of the output pins. This feature can greatly simplify state machine design by providing a known state on power-up. Because of the asynchronous nature of system power-up, some conditions must be met to provide a valid power-up reset of the device. First, the Vcc rise must be monotonic. Second, the clock input must be at static TTL level as shown in the diagram during power up. The registers will reset within a maximum of tpr time. As in normal system operation, avoid clocking the device until all input and feedback path setup times have been met. The clock must also meet the minimum pulse width requirements.



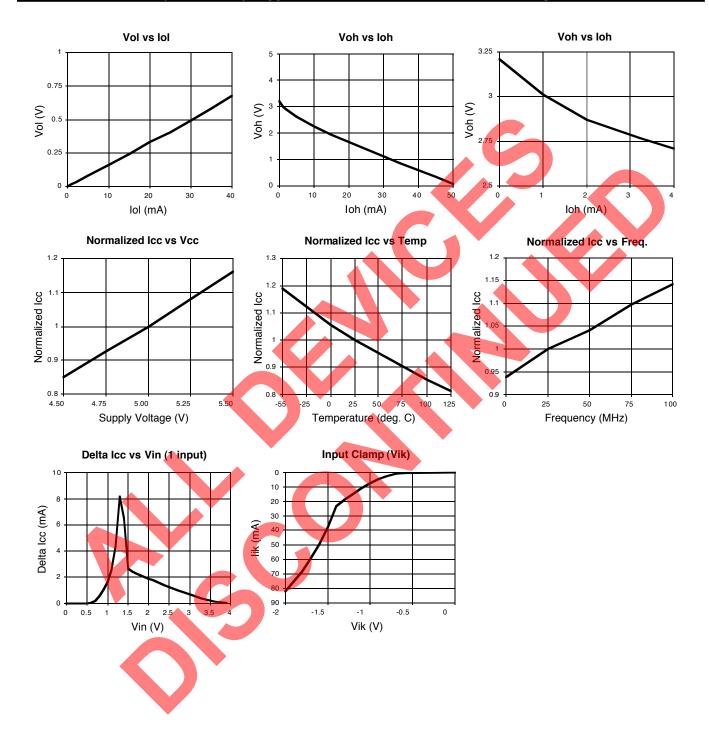


GAL16V8D-3/-5/-7 (IND PLCC): Typical AC and DC Characteristic Diagrams





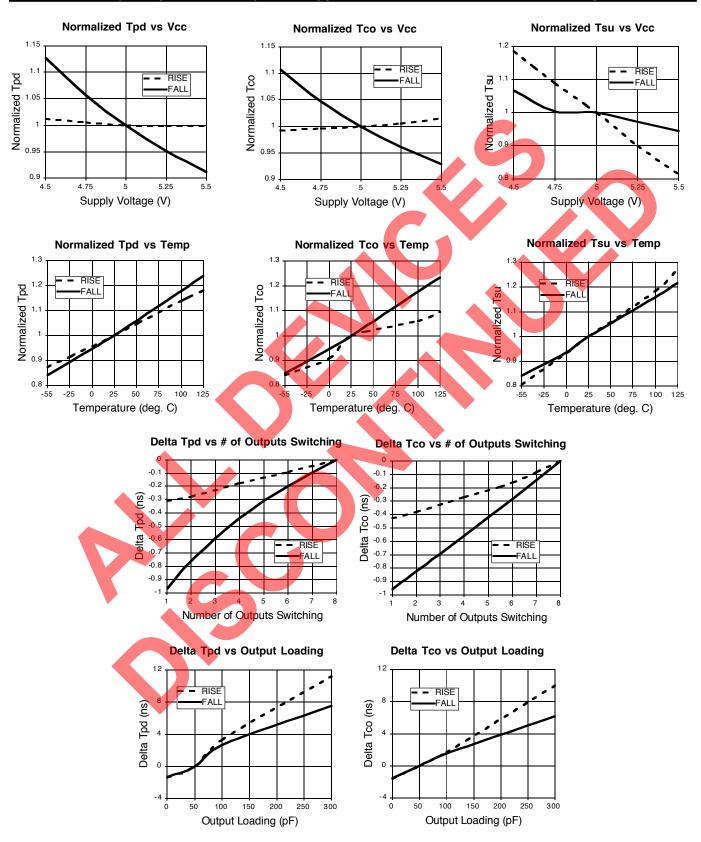
GAL16V8D-3/-5/-7 (IND PLCC): Typical AC and DC Characteristic Diagrams





Semiconductor Corporation

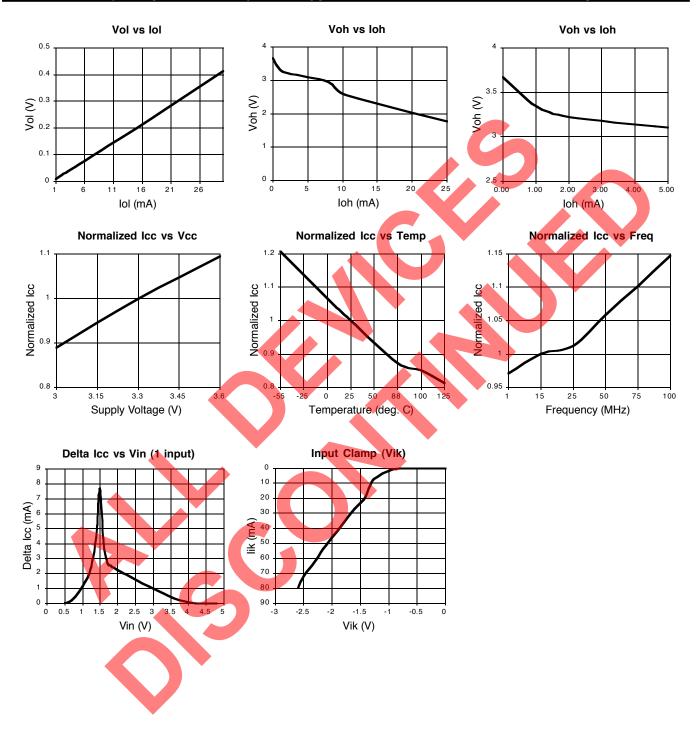
GAL16V8D-7 (Except IND PLCC)/-10L: Typical AC and DC Characteristic Diagrams





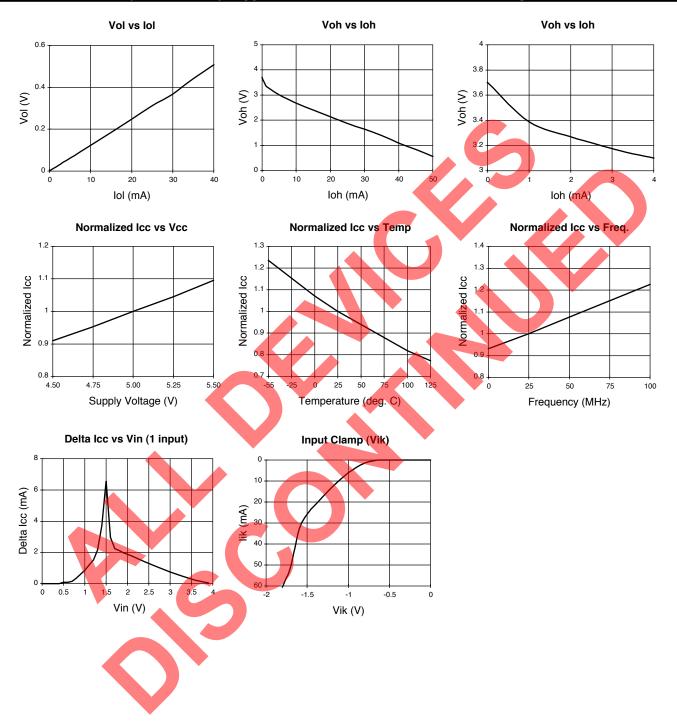
Semiconductor Corporation

GAL16V8D-7 (Except IND PLCC)/-10L: Typical AC and DC Characteristic Diagrams





GAL16V8D-10Q (and Slower): Typical AC and DC Characteristic Diagrams





Specifications **GAL16V8**

Revision History

Date	Version	Change Summary
-	16v8_10	Previous Lattice release.
August 2006	16v8_11	Updated for lead-free package options.