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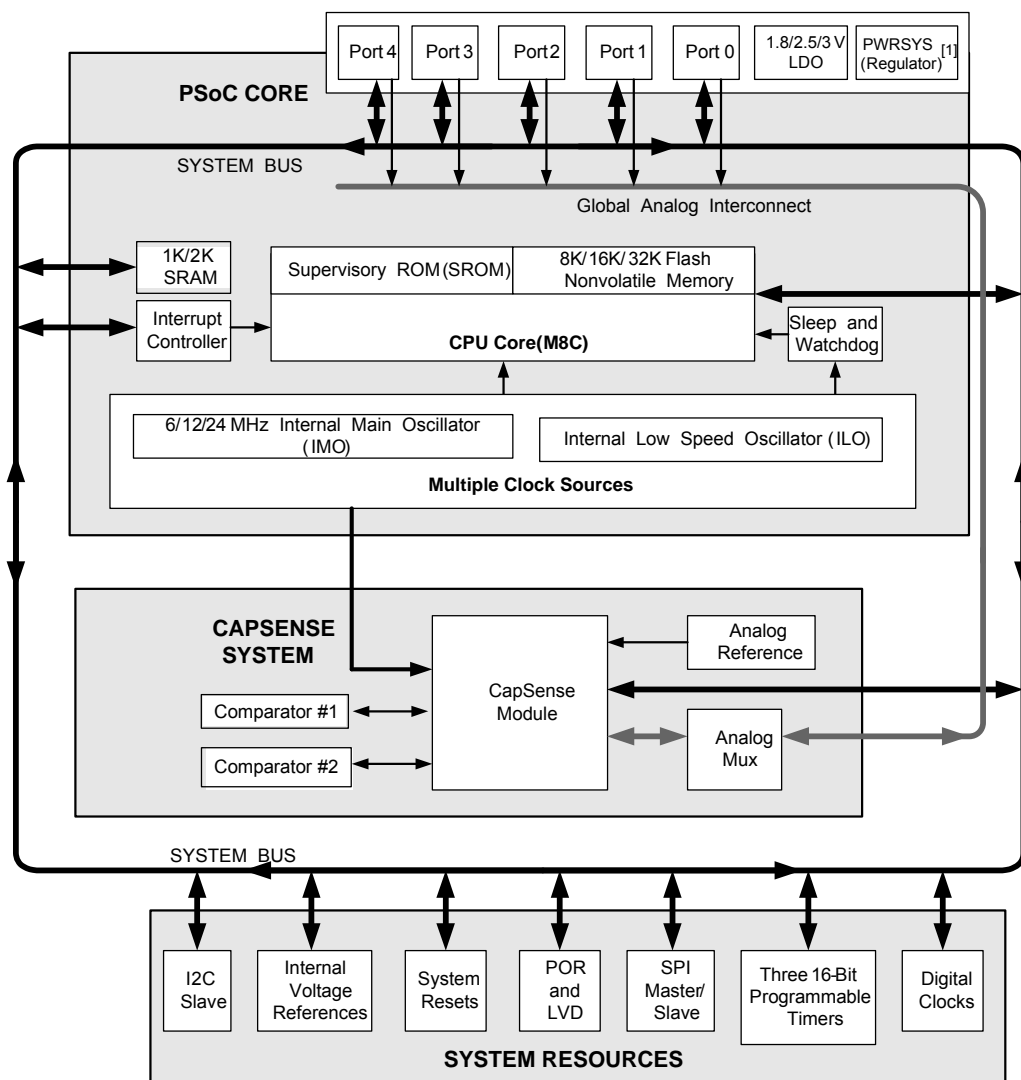
**What Are Embedded - Microcontrollers - Application Specific?**

Application specific microcontrollers are engineered to

#### Details

Product Status	Obsolete
Applications	Capacitive Sensing
Core Processor	M8C
Program Memory Type	FLASH (16kB)
Controller Series	CY8C20xx7/S
RAM Size	2K x 8
Interface	I <sup>2</sup> C, SPI
Number of I/O	33
Voltage - Supply	1.71V ~ 5.5V
Operating Temperature	-40°C ~ 85°C
Mounting Type	Surface Mount
Package / Case	48-UFQFN Exposed Pad
Supplier Device Package	48-QFN (6x6)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/cy8c20647-24lqxit">https://www.e-xfl.com/product-detail/infineon-technologies/cy8c20647-24lqxit</a>

## Logic Block Diagram



### Note

1. Internal voltage regulator for internal circuitry

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## PSoC® Functional Overview

The PSoC family consists of many devices with on-chip controllers. These devices are designed to replace multiple traditional MCU-based system components with one low-cost single-chip programmable component. A PSoC device includes configurable blocks of analog and digital logic, and programmable interconnect. This architecture makes it possible for you to create customized peripheral configurations, to match the requirements of each individual application. Additionally, a fast central processing unit (CPU), flash program memory, SRAM data memory, and configurable I/O are included in a range of convenient pinouts.

The architecture for this device family, as shown in the “Logic Block Diagram” on page 2, consists of three main areas:

- The core
- CapSense analog system
- System resources

A common, versatile bus allows connection between I/O and the analog system.

Each CY8C20x37/47/67/S PSoC device includes a dedicated CapSense block that provides sensing and scanning control circuitry for capacitive sensing applications. Depending on the PSoC package, up to 34 GPIOs are also included. The GPIOs provide access to the MCU and analog mux.

### PSoC Core

The PSoC core is a powerful engine that supports a rich instruction set. It encompasses SRAM for data storage, an interrupt controller, sleep and watchdog timers, and IMO and I/O. The CPU core, called the M8C, is a powerful processor with speeds up to 24 MHz. The M8C is a 4-million instructions per second (MIPS), 8-bit Harvard-architecture microprocessor.

### CapSense System

The analog system contains the capacitive sensing hardware. Several hardware algorithms are supported. This hardware performs capacitive sensing and scanning without requiring external components. The analog system is composed of the CapSense PSoC block and an internal 1 V or 1.2 V analog reference, which together support capacitive sensing of up to 31 inputs<sup>[2]</sup>. Capacitive sensing is configurable on each GPIO pin. Scanning of enabled CapSense pins is completed quickly and easily across multiple ports.

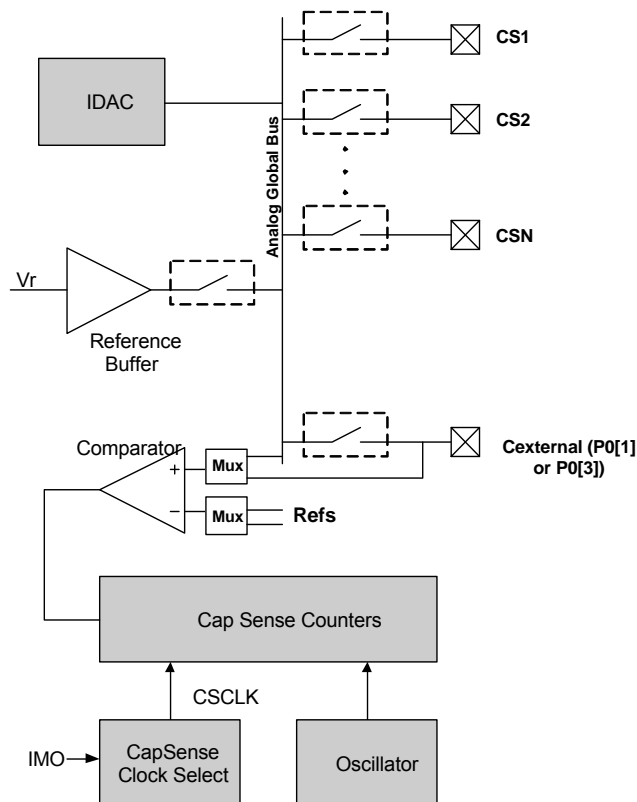
#### SmartSense™ Auto-tuning

SmartSense auto-tuning is an innovative solution from Cypress that removes manual tuning of CapSense applications. This solution is easy to use and provides robust noise immunity. It is the only auto-tuning solution that establishes, monitors, and maintains all required tuning parameters of each sensor during run time. SmartSense auto-tuning allows engineers to go from prototyping to mass production without retuning for manufacturing variations in PCB and/or overlay material properties.

#### Note

2. 34 GPIOs = 31 pins for capacitive sensing + 2 pins for I<sup>2</sup>C + 1 pin for modulator capacitor.

**Figure 1. CapSense System Block Diagram**



#### Analog Multiplexer System

The analog mux bus can connect to every GPIO pin. Pins are connected to the bus individually or in any combination. The bus also connects to the analog system for analysis with the CapSense block comparator.

Switch-control logic enables selected pins to precharge continuously under hardware control. This enables capacitive measurement for applications such as touch sensing. Other multiplexer applications include:

- Complex capacitive sensing interfaces, such as sliders and touchpads.
- Chip-wide mux that allows analog input from any I/O pin.
- Crosspoint connection between any I/O pin combinations.

## Designing with PSoC Designer

The PSoC development process can be summarized in the following four steps:

1. Select [User Modules](#)
2. Configure User Modules
3. Organize and Connect
4. Generate and Verify

### Select Components

PSoC Designer provides a library of pre-built, pre-tested hardware peripheral components called “user modules”. User modules make selecting and implementing peripheral devices, both analog and digital, simple.

### Configure Components

Each of the User Modules you select establishes the basic register settings that implement the selected function. They also provide parameters and properties that allow you to tailor their precise configuration to your particular application. The user module parameters permit you to establish the pulse width and duty cycle. Configure the parameters and properties to correspond to your chosen application. Enter values directly or by selecting values from drop-down menus. All the user modules are documented in datasheets that may be viewed directly in PSoC Designer or on the Cypress website. These [user module datasheets](#) explain the internal operation of the User Module and provide performance specifications. Each datasheet describes the use of each user module parameter, and other information you may need to successfully implement your design.

## Organize and Connect

You build signal chains at the chip level by interconnecting user modules to each other and the I/O pins. You perform the selection, configuration, and routing so that you have complete control over all on-chip resources.

## Generate, Verify, and Debug

When you are ready to test the hardware configuration or move on to developing code for the project, you perform the “Generate Configuration Files” step. This causes PSoC Designer to generate source code that automatically configures the device to your specification and provides the software for the system. The generated code provides application programming interfaces (APIs) with high-level functions to control and respond to hardware events at run time and interrupt service routines that you can adapt as needed.

A complete code development environment allows you to develop and customize your applications in C, assembly language, or both.

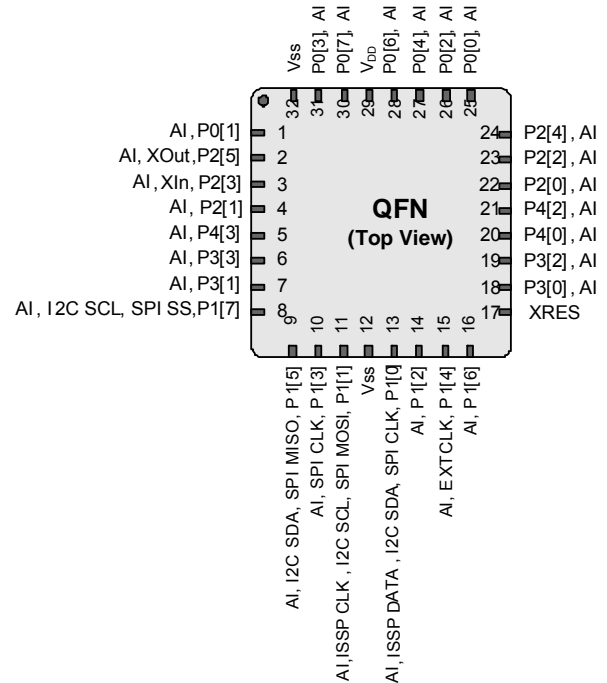
**32-pin QFN (25 Sensing Inputs)<sup>[25]</sup>**
**Table 5. Pin Definitions – CY8C20437, CY8C20447/S, CY8C20467/S<sup>[26]</sup>**

Pin No.	Type		Name	Description
	Digital	Analog		
1	IOH	I	P0[1]	Integrating input
2	I/O	I	P2[5]	Crystal output (XOut)
3	I/O	I	P2[3]	Crystal input (XIn)
4	I/O	I	P2[1]	
5	I/O	I	P4[3]	
6	I/O	I	P3[3]	
7	I/O	I	P3[1]	
8	IOHR	I	P1[7]	I <sup>2</sup> C SCL, SPI SS
9	IOHR	I	P1[5]	I <sup>2</sup> C SDA, SPI MISO
10	IOHR	I	P1[3]	SPI CLK.
11	IOHR	I	P1[1]	ISSP CLK <sup>[27]</sup> , I <sup>2</sup> C SCL, SPI MOSI.
12	Power		V <sub>SS</sub>	Ground connection <sup>[30]</sup>
13	IOHR	I	P1[0]	ISSP DATA <sup>[27]</sup> , I <sup>2</sup> C SDA, SPI CLK <sup>[28]</sup>
14	IOHR	I	P1[2]	Driven Shield Output (optional)
15	IOHR	I	P1[4]	Optional external clock input (EXTCLK)
16	IOHR	I	P1[6]	
17	Input		XRES	Active high external reset with internal pull-down <sup>[29]</sup>
18	I/O	I	P3[0]	
19	I/O	I	P3[2]	
20	I/O	I	P4[0]	
21	I/O	I	P4[2]	
22	I/O	I	P2[0]	
23	I/O	I	P2[2]	Driven Shield Output (optional)
24	I/O	I	P2[4]	Driven Shield Output (optional)
25	IOH	I	P0[0]	Driven Shield Output (optional)
26	IOH	I	P0[2]	Driven Shield Output (optional)
27	IOH	I	P0[4]	
28	IOH	I	P0[6]	
29	Power		V <sub>DD</sub>	
30	IOH	I	P0[7]	
31	IOH	I	P0[3]	Integrating input
32	Power		V <sub>SS</sub>	Ground connection <sup>[30]</sup>
CP	Power		V <sub>SS</sub>	Center pad must be connected to ground

**LEGEND** A = Analog, I = Input, O = Output, OH = 5 mA High Output Drive, R = Regulated Output.

**Notes**

25. The center pad (CP) on the QFN package must be connected to ground (V<sub>SS</sub>) for best mechanical, thermal, and electrical performance. If not connected to ground, it must be electrically floated and not connected to any other signal.
26. 28 GPIOs = 25 pins for capacitive sensing+2 pins for I<sup>2</sup>C + 1 pin for modulator capacitor.
27. On power-up, the SDA(P1[0]) drives a strong high for 256 sleep clock cycles and drives resistive low for the next 256 sleep clock cycles. The SCL(P1[1]) line drives resistive low for 512 sleep clock cycles and both the pins transition to high impedance state. On reset, after XRES de-asserts, the SDA and the SCL lines drive resistive low for 8 sleep clock cycles and transition to high impedance state. Hence, during power-up or reset event, P1[1] and P1[0] may disturb the I<sup>2</sup>C bus. Use alternate pins if you encounter issues.
28. Alternate SPI clock.
29. The internal pull down is 5KOhm.
30. All VSS pins should be brought out to one common GND plane.

**Figure 6. CY8C20437, CY8C20447/S, CY8C20467/S Device**


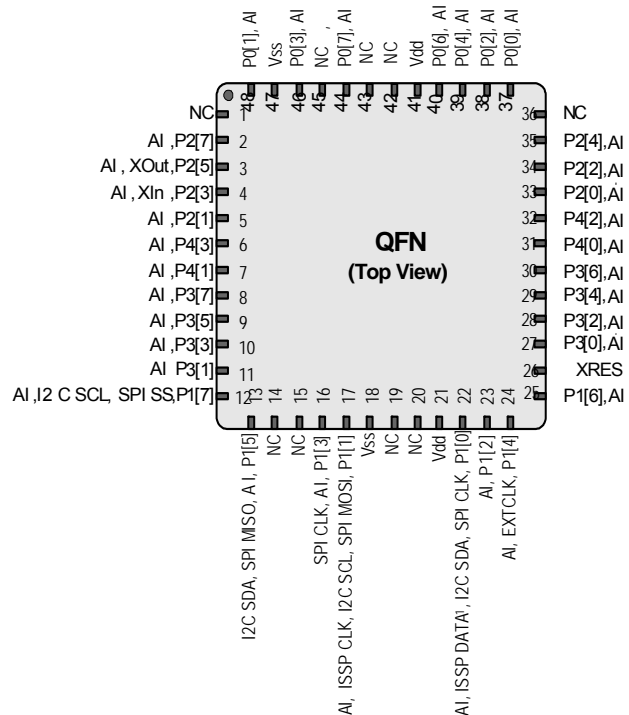
**48-pin QFN (31 Sensing Inputs)<sup>[31]</sup>**
**Table 6. Pin Definitions – CY8C20637, CY8C20647/S, CY8C20667/S <sup>[32]</sup>**

Pin No.	Digital	Analog	Name	Description	Pin No.	Digital	Analog	Name	Description
1			NC	No connection	40	IOH	I	P0[6]	
2	I/O	I	P2[7]		41	Power		V <sub>DD</sub>	Supply voltage
3	I/O	I	P2[5]	Crystal output (XOut)	42			NC	No connection
4	I/O	I	P2[3]	Crystal input (XIn)	43			NC	No connection
5	I/O	I	P2[1]		44	IOH	I	P0[7]	
6	I/O	I	P4[3]		45			NC	No connection
7	I/O	I	P4[1]		46	IOH	I	P0[3]	Integrating input
8	I/O	I	P3[7]		47	Power		V <sub>SS</sub>	Ground connection <sup>[36]</sup>
9	I/O	I	P3[5]		48	IOH	I	P0[1]	Integrating input
10	I/O	I	P3[3]			CP	Power	V <sub>SS</sub>	Center pad must be connected to ground
11	I/O	I	P3[1]						
12	IOHR	I	P1[7]	I <sup>2</sup> C SCL, SPI SS					
13	IOHR	I	P1[5]	I <sup>2</sup> C SDA, SPI MISO					
14			NC	No connection					
15			NC	No connection					
16	IOHR	I	P1[3]	SPI CLK					
17	IOHR	I	P1[1]	ISSP CLK <sup>[33]</sup> , I <sup>2</sup> C SCL, SPI MOSI					
18	Power		V <sub>SS</sub>	Ground connection <sup>[36]</sup>					
19			NC	No connection					
20			NC	No connection					
21	Power		V <sub>DD</sub>	Supply voltage					
22	IOHR	I	P1[0]	ISSP DATA <sup>[33]</sup> , I <sup>2</sup> C SDA, SPI CLK <sup>[34]</sup>					
23	IOHR	I	P1[2]	Driven Shield Output (optional)					
24	IOHR	I	P1[4]	Optional external clock input (EXTCLK)					
25	IOHR	I	P1[6]						
26	Input		XRES	Active high external reset with internal pull-down <sup>[35]</sup>					
27	I/O	I	P3[0]						
28	I/O	I	P3[2]						
29	I/O	I	P3[4]						
30	I/O	I	P3[6]						
31	I/O	I	P4[0]						
32	I/O	I	P4[2]						
33	I/O	I	P2[0]						
34	I/O	I	P2[2]	Driven Shield Output (optional)					
35	I/O	I	P2[4]	Driven Shield Output (optional)					
36			NC	No connection					
37	IOH	I	P0[0]	Driven Shield Output (optional)					
38	IOH	I	P0[2]	Driven Shield Output (optional)					
39	IOH	I	P0[4]						

**LEGEND** A = Analog, I = Input, O = Output, NC = No Connection H = 5 mA High Output Drive, R = Regulated Output.

**Notes**

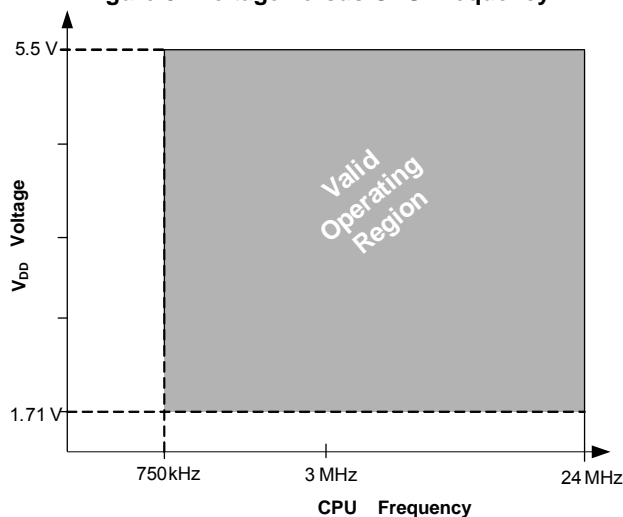
- The center pad (CP) on the QFN package must be connected to ground (V<sub>SS</sub>) for best mechanical, thermal, and electrical performance. If not connected to ground, it must be electrically floated and not connected to any other signal.
- 34 GPIOs = 31 pins for capacitive sensing+2 pins for I<sup>2</sup>C + 1 pin for modulator capacitor.
- On power-up, the SDA(P1[0]) drives a strong high for 256 sleep clock cycles and drives resistive low for the next 256 sleep clock cycles. The SCL(P1[1]) line drives resistive low for 512 sleep clock cycles and both the pins transition to high impedance state. On reset, after XRES de-asserts, the SDA and the SCL lines drive resistive low for 8 sleep clock cycles and transition to high impedance state. Hence, during power-up or reset event, P1[1] and P1[0] may disturb the I<sup>2</sup>C bus. Use alternate pins if you encounter issues.
- Alternate SPI clock.
- The internal pull down is 5KOhm.
- All VSS pins should be brought out to one common GND plane.

**Figure 7. CY8C20637, CY8C20647/S, CY8C20667/S Device**


## Electrical Specifications

This section presents the DC and AC electrical specifications of the CY8C20x37/47/67/S PSoC devices. For the latest electrical specifications, confirm that you have the most recent datasheet by visiting the web at <http://www.cypress.com/psoc>.

**Figure 8. Voltage versus CPU Frequency**



## Absolute Maximum Ratings

Exceeding maximum ratings may shorten the useful life of the device. User guidelines are not tested.

**Table 7. Absolute Maximum Ratings**

Symbol	Description	Conditions	Min	Typ	Max	Units
T <sub>STG</sub>	Storage temperature	Higher storage temperatures reduce data retention time. Recommended Storage Temperature is +25 °C ± 25 °C. Extended duration storage temperatures above 85 °C degrades reliability.	-55	+25	+125	°C
V <sub>DD</sub>	Supply voltage relative to V <sub>SS</sub>	—	-0.5	—	+6.0	V
V <sub>IO</sub>	DC input voltage	—	V <sub>SS</sub> - 0.5	—	V <sub>DD</sub> + 0.5	V
V <sub>IOZ</sub>	DC voltage applied to tristate	—	V <sub>SS</sub> - 0.5	—	V <sub>DD</sub> + 0.5	V
I <sub>MIO</sub>	Maximum current into any port pin	—	-25	—	+50	mA
ESD	Electro static discharge voltage	Human body model ESD	2000	—	—	V
LU	Latch up current	In accordance with JESD78 standard	—	—	200	mA

## Operating Temperature

**Table 8. Operating Temperature**

Symbol	Description	Conditions	Min	Typ	Max	Units
T <sub>A</sub>	Ambient temperature	—	-40	—	+85	°C
T <sub>C</sub>	Commercial temperature range	—	0	—	70	°C
T <sub>J</sub>	Operational die temperature	The temperature rise from ambient to junction is package specific. See the <a href="#">Thermal Impedances on page 30</a> . The user must limit the power consumption to comply with this requirement.	-40	—	+100	°C



## DC GPIO Specifications

The following tables list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 3.0 V to 5.5 V and  $-40\text{ }^{\circ}\text{C} \leq T_A \leq 85\text{ }^{\circ}\text{C}$ , 2.4 V to 3.0 V and  $-40\text{ }^{\circ}\text{C} \leq T_A \leq 85\text{ }^{\circ}\text{C}$ , or 1.71 V to 2.4 V and  $-40\text{ }^{\circ}\text{C} \leq T_A \leq 85\text{ }^{\circ}\text{C}$ , respectively. Typical parameters apply to 5 V and 3.3 V at 25 °C and are for design guidance only.

**Table 10. 3.0 V to 5.5 V DC GPIO Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
R <sub>PU</sub>	Pull-up resistor	–	4	5.60	8	k $\Omega$
V <sub>OH1</sub>	High output voltage Port 2 or 3 pins	I <sub>OH</sub> ≤ 10 $\mu$ A, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> – 0.20	–	–	V
V <sub>OH2</sub>	High output voltage Port 2 or 3 Pins	I <sub>OH</sub> = 1 mA, maximum of 20 mA source current in all I/Os	V <sub>DD</sub> – 0.90	–	–	V
V <sub>OH3</sub>	High output voltage Port 0 or 1 pins with LDO regulator Disabled for port 1	I <sub>OH</sub> < 10 $\mu$ A, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> – 0.20	–	–	V
V <sub>OH4</sub>	High output voltage Port 0 or 1 pins with LDO regulator Disabled for port 1	I <sub>OH</sub> = 5 mA, maximum of 20 mA source current in all I/Os	V <sub>DD</sub> – 0.90	–	–	V
V <sub>OH5</sub>	High output voltage Port 1 Pins with LDO Regulator Enabled for 3 V out	I <sub>OH</sub> < 10 $\mu$ A, V <sub>DD</sub> > 3.1 V, maximum of 4 I/Os all sourcing 5 mA	2.85	3.00	3.30	V
V <sub>OH6</sub>	High output voltage Port 1 pins with LDO regulator enabled for 3 V out	I <sub>OH</sub> = 5 mA, V <sub>DD</sub> > 3.1 V, maximum of 20 mA source current in all I/Os	2.20	–	–	V
V <sub>OH7</sub>	High output voltage Port 1 pins with LDO enabled for 2.5 V out	I <sub>OH</sub> < 10 $\mu$ A, V <sub>DD</sub> > 2.7 V, maximum of 20 mA source current in all I/Os	2.35	2.50	2.75	V
V <sub>OH8</sub>	High output voltage Port 1 pins with LDO enabled for 2.5 V out	I <sub>OH</sub> = 2 mA, V <sub>DD</sub> > 2.7 V, maximum of 20 mA source current in all I/Os	1.90	–	–	V
V <sub>OH9</sub>	High output voltage Port 1 pins with LDO enabled for 1.8 V out	I <sub>OH</sub> < 10 $\mu$ A, V <sub>DD</sub> > 2.7 V, maximum of 20 mA source current in all I/Os	1.60	1.80	2.10	V
V <sub>OH10</sub>	High output voltage Port 1 pins with LDO enabled for 1.8 V out	I <sub>OH</sub> = 1 mA, V <sub>DD</sub> > 2.7 V, maximum of 20 mA source current in all I/Os	1.20	–	–	V
V <sub>OL</sub>	Low output voltage	I <sub>OL</sub> = 25 mA, V <sub>DD</sub> > 3.3 V, maximum of 60 mA sink current on even port pins (for example, P0[2] and P1[4]) and 60 mA sink current on odd port pins (for example, P0[3] and P1[5])	–	–	0.75	V
V <sub>IL</sub>	Input low voltage	–	–	–	0.80	V
V <sub>IH</sub>	Input high voltage	–	V <sub>DD</sub> × 0.65	–	V <sub>DD</sub> + 0.7	V
V <sub>H</sub>	Input hysteresis voltage	–	–	80	–	mV
I <sub>IL</sub>	Input leakage (Absolute Value)	–	–	0.001	1	$\mu$ A
C <sub>PIN</sub>	Pin capacitance	Package and pin dependent Temp = 25 °C	0.50	1.70	7	pF
V <sub>ILLVT3.3</sub>	Input Low Voltage with low threshold enable set, Enable for Port1 <sup>[44]</sup>	Bit3 of IO_CFG1 set to enable low threshold voltage of Port1 input	0.8	V	–	–
V <sub>IHLVT3.3</sub>	Input High Voltage with low threshold enable set, Enable for Port1	Bit3 of IO_CFG1 set to enable low threshold voltage of Port1 input	1.4	–	–	V
V <sub>ILLVT5.5</sub>	Input Low Voltage with low threshold enable set, Enable for Port1	Bit3 of IO_CFG1 set to enable low threshold voltage of Port1 input	0.8	V	–	–
V <sub>IHLVT5.5</sub>	Input High Voltage with low threshold enable set, Enable for Port1	Bit3 of IO_CFG1 set to enable low threshold voltage of Port1 input	1.7	–	–	V

### Note

**44. Errata:** Pull-up resistor on port1 pins cannot be connected to a voltage that is greater than 0.7 V higher than CY8C20xx7/S VDD. For more information see item #7 in “Errata” on page 37.

**Table 11. 2.4 V to 3.0 V DC GPIO Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
R <sub>PU</sub>	Pull-up resistor	–	4	5.60	8	kΩ
V <sub>OH1</sub>	High output voltage Port 2 or 3 pins	I <sub>OH</sub> < 10 μA, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> - 0.20	–	–	V
V <sub>OH2</sub>	High output voltage Port 2 or 3 Pins	I <sub>OH</sub> = 0.2 mA, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> - 0.40	–	–	V
V <sub>OH3</sub>	High output voltage Port 0 or 1 pins with LDO regulator Disabled for port 1	I <sub>OH</sub> < 10 μA, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> - 0.20	–	–	V
V <sub>OH4</sub>	High output voltage Port 0 or 1 pins with LDO regulator Disabled for Port 1	I <sub>OH</sub> = 2 mA, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> - 0.50	–	–	V
V <sub>OH5A</sub>	High output voltage Port 1 pins with LDO enabled for 1.8 V out	I <sub>OH</sub> < 10 μA, V <sub>DD</sub> > 2.4 V, maximum of 20 mA source current in all I/Os	1.50	1.80	2.10	V
V <sub>OH6A</sub>	High output voltage Port 1 pins with LDO enabled for 1.8 V out	I <sub>OH</sub> = 1 mA, V <sub>DD</sub> > 2.4 V, maximum of 20 mA source current in all I/Os	1.20	–	–	V
V <sub>OL</sub>	Low output voltage	I <sub>OL</sub> = 10 mA, maximum of 30 mA sink current on even port pins (for example, P0[2] and P1[4]) and 30 mA sink current on odd port pins (for example, P0[3] and P1[5])	–	–	0.75	V
V <sub>IL</sub>	Input low voltage	–	–	–	0.72	V
V <sub>IH</sub>	Input high voltage	–	V <sub>DD</sub> × 0.65	–	V <sub>DD</sub> + 0.7	V
V <sub>H</sub>	Input hysteresis voltage	–	–	80	–	mV
I <sub>IL</sub>	Input leakage (absolute value)	–	–	1	1000	nA
C <sub>PIN</sub>	Capacitive load on pins	Package and pin dependent Temp = 25 °C	0.50	1.70	7	pF
V <sub>ILLVT2.5</sub>	Input Low Voltage with low threshold enable set, Enable for Port1	Bit3 of IO_CFG1 set to enable low threshold voltage of Port1 input	0.7	V	–	
V <sub>IHLVT2.5</sub>	Input High Voltage with low threshold enable set, Enable for Port1	Bit3 of IO_CFG1 set to enable low threshold voltage of Port1 input	1.2		–	V

**Table 12. 1.71 V to 2.4 V DC GPIO Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
R <sub>PU</sub>	Pull-up resistor	–	4	5.60	8	kΩ
V <sub>OH1</sub>	High output voltage Port 2 or 3 pins	I <sub>OH</sub> = 10 μA, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> - 0.20	–	–	V
V <sub>OH2</sub>	High output voltage Port 2 or 3 pins	I <sub>OH</sub> = 0.5 mA, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> - 0.50	–	–	V
V <sub>OH3</sub>	High output voltage Port 0 or 1 pins with LDO regulator Disabled for Port 1	I <sub>OH</sub> = 100 μA, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> - 0.20	–	–	V
V <sub>OH4</sub>	High output voltage Port 0 or 1 Pins with LDO Regulator Disabled for Port 1	I <sub>OH</sub> = 2 mA, maximum of 10 mA source current in all I/Os	V <sub>DD</sub> - 0.50	–	–	V

**Table 12. 1.71 V to 2.4 V DC GPIO Specifications (continued)**

Symbol	Description	Conditions	Min	Typ	Max	Units
$V_{OL}$	Low output voltage	$I_{OL} = 5$ mA, maximum of 20 mA sink current on even port pins (for example, P0[2] and P1[4]) and 30 mA sink current on odd port pins (for example, P0[3] and P1[5])	–	–	0.40	V
$V_{IL}$	Input low voltage	–	–	–	$0.30 \times V_{DD}$	V
$V_{IH}$	Input high voltage	–	$0.65 \times V_{DD}$	–	–	V
$V_H$	Input hysteresis voltage	–	–	80	–	mV
$I_{IL}$	Input leakage (absolute value)	–	–	1	1000	nA
$C_{PIN}$	Capacitive load on pins	Package and pin dependent temp = 25 °C	0.50	1.70	7	pF

**Table 13. GPIO Current Sink and Source Specifications**

Supply Voltage	Mode	Port 0/1 per I/O (max)	Port 2/3/4 per I/O (max)	Total Current Even Pins (max)	Total Current Odd Pins (max)	Units
1.71–2.4	Sink	5	5	20	30	mA
	Source	2	0.5	$10^{[45]}$		mA
2.4–3.0	Sink	10	10	30	30	mA
	Source	2	0.2	$10^{[45]}$		mA
3.0–5.0	Sink	25	25	60	60	mA
	Source	5	1	$20^{[45]}$		mA

### DC Analog Mux Bus Specifications

Table 14 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 14. DC Analog Mux Bus Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
$R_{SW}$	Switch resistance to common analog bus	–	–	–	800	$\Omega$
$R_{GND}$	Resistance of initialization switch to $V_{SS}$	–	–	–	800	$\Omega$

The maximum pin voltage for measuring  $R_{SW}$  and  $R_{GND}$  is 1.8 V

### DC Low Power Comparator Specifications

Table 15 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 15. DC Comparator Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
$V_{LPC}$	Low power comparator (LPC) common mode	Maximum voltage limited to $V_{DD}$	0.2	–	1.8	V
$I_{LPC}$	LPC supply current	–	–	10	80	$\mu$ A
$V_{OSLPC}$	LPC voltage offset	–	–	2.5	30	mV

#### Note

45. Total current (odd + even ports)

## AC Chip-Level Specifications

Table 24 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 24. AC Chip-Level Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
F <sub>IMO24</sub>	IMO frequency at 24 MHz Setting	—	22.8	24	25.2	MHz
F <sub>IMO12</sub>	IMO frequency at 12 MHz setting	—	11.4	12	12.6	MHz
F <sub>IMO6</sub>	IMO frequency at 6 MHz setting	—	5.7	6.0	6.3	MHz
F <sub>CPU</sub>	CPU frequency	—	0.75	—	25.20	MHz
F <sub>32K1</sub>	ILO frequency	—	15	32	50	kHz
F <sub>32K_U</sub>	ILO untrimmed frequency	—	—	32	—	kHz
DC <sub>IMO</sub>	Duty cycle of IMO	—	40	50	60	%
DC <sub>ILO</sub>	ILO duty cycle	—	40	50	60	%
SR <sub>POWER_UP</sub>	Power supply slew rate	V <sub>DD</sub> slew rate during power-up	—	—	250	V/ms
t <sub>XRST</sub>	External reset pulse width at power-up	After supply voltage is valid	1	—	—	ms
t <sub>XRST2</sub>	External reset pulse width after power-up <sup>[52]</sup>	Applies after part has booted	10	—	—	μs
t <sub>JIT_IMO</sub> <sup>[53]</sup>	6 MHz IMO cycle-to-cycle jitter (RMS)	—	—	0.7	6.7	ns
	6 MHz IMO long term N cycle-to-cycle jitter (RMS); N = 32	—	—	4.3	29.3	ns
	6 MHz IMO period jitter (RMS)	—	—	0.7	3.3	ns
	12 MHz IMO cycle-to-cycle jitter (RMS)	—	—	0.5	5.2	ns
	12 MHz IMO long term N cycle-to-cycle jitter (RMS); N = 32	—	—	2.3	5.6	ns
	12 MHz IMO period jitter (RMS)	—	—	0.4	2.6	ns
	24 MHz IMO cycle-to-cycle jitter (RMS)	—	—	1.0	8.7	ns
	24 MHz IMO long term N cycle-to-cycle jitter (RMS); N = 32	—	—	1.4	6.0	ns
	24 MHz IMO period jitter (RMS)	—	—	0.6	4.0	ns

### Note

52. The minimum required XRES pulse length is longer when programming the device (see Table 28 on page 23).

53. See the Cypress Jitter Specifications application note, [Understanding Datasheet Jitter Specifications for Cypress Timing Products – AN5054](#) for more information.

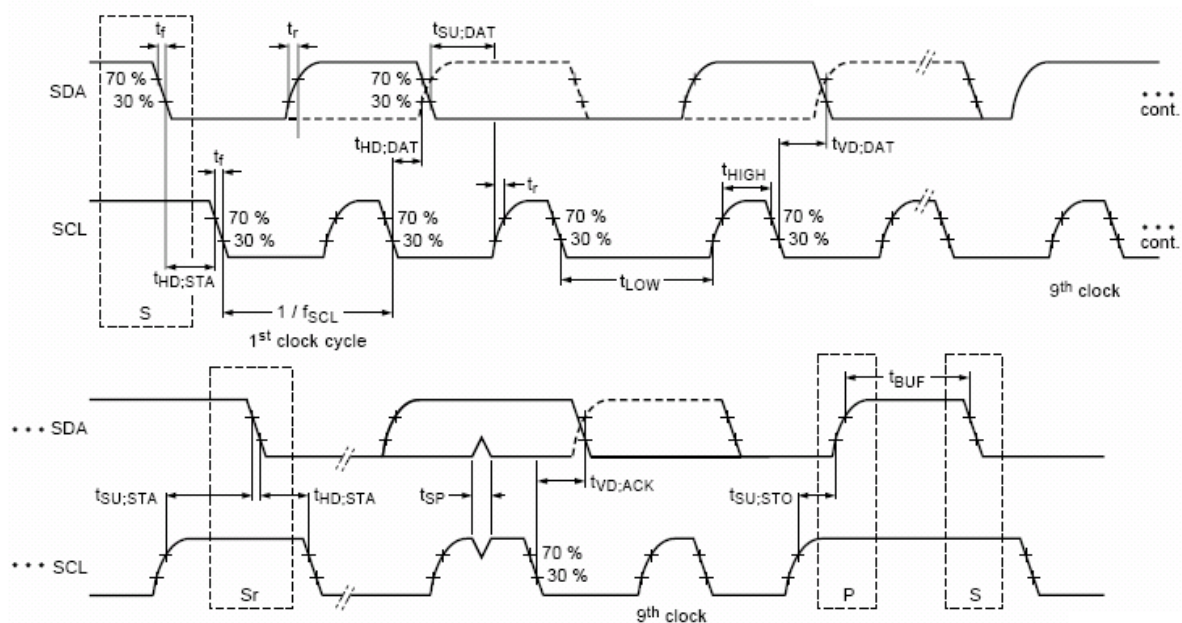
## AC I<sup>2</sup>C Specifications

Table 29 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 29. AC Characteristics of the I<sup>2</sup>C SDA and SCL Pins**

Symbol	Description	Standard Mode		Fast Mode		Units
		Min	Max	Min	Max	
$f_{SCL}$	SCL clock frequency	0	100	0	400	kHz
$t_{HD;STA}$	Hold time (repeated) START condition. After this period, the first clock pulse is generated	4.0	–	0.6	–	$\mu$ s
$t_{LOW}$	LOW period of the SCL clock	4.7	–	1.3	–	$\mu$ s
$t_{HIGH}$	HIGH Period of the SCL clock	4.0	–	0.6	–	$\mu$ s
$t_{SU;STA}$	Setup time for a repeated START condition	4.7	–	0.6	–	$\mu$ s
$t_{HD;DAT}^{[55]}$	Data hold time	20	3.45	20	0.90	$\mu$ s
$t_{SU;DAT}$	Data setup time	250	–	100 <sup>[56]</sup>	–	ns
$t_{SU;STO}$	Setup time for STOP condition	4.0	–	0.6	–	$\mu$ s
$t_{BUF}$	Bus free time between a STOP and START condition	4.7	–	1.3	–	$\mu$ s
$t_{SP}$	Pulse width of spikes are suppressed by the input filter	–	–	0	50	ns

**Figure 11. Definition for Timing for Fast/Standard Mode on the I<sup>2</sup>C Bus**



### Notes

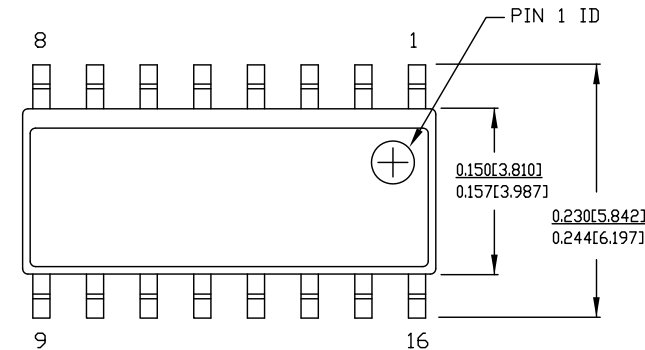
55. **Errata:** To wake up from sleep using I2C hardware address match event, I2C interface needs 20 ns hold time on SDA line with respect to falling edge of SCL. For more information see item #5 in the "Errata" on page 37.
56. A Fast-Mode I<sup>2</sup>C-bus device can be used in a standard mode I<sup>2</sup>C-bus system, but the requirement  $t_{SU;DAT} \geq 250$  ns must then be met. This automatically be the case if the device does not stretch the LOW period of the SCL signal. If such device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line  $t_{rmax} + t_{SU;DAT} = 1000 + 250 = 1250$  ns (according to the Standard-Mode I<sup>2</sup>C-bus specification) before the SCL line is released.

## Packaging Information

This section illustrates the packaging specifications for the CY8C20x37/47/67 PSoC device, along with the thermal impedances for each package.

**Important Note** Emulation tools may require a larger area on the target PCB than the chip's footprint. For a detailed description of the emulation tools' dimensions, refer to the document titled *PSoC Emulator Pod Dimensions* at <http://www.cypress.com/design/MR10161>.

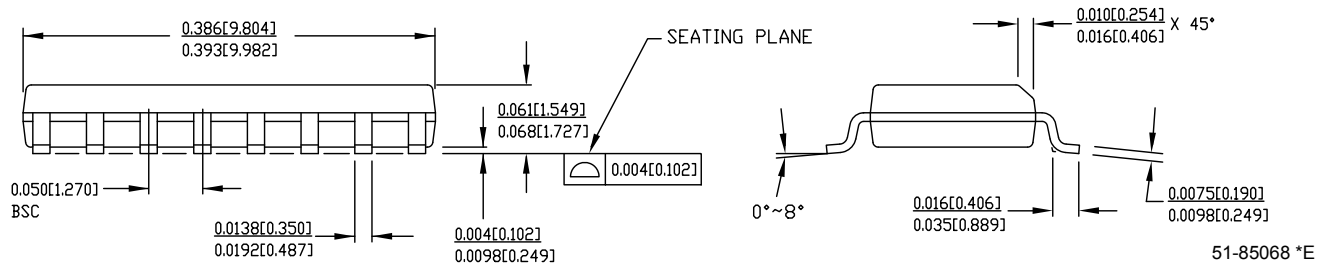
**Figure 16. 16-pin (150 Mil) SOIC**



NOTE:

1. DIMENSIONS IN INCHES[MM] **MAX.**
2. REFERENCE JEDEC MS-012
3. PACKAGE WEIGHT : refer to PMDD spec. 001-04308

PART #	
S16.15	STANDARD PKG.
SZ16.15	LEAD FREE PKG.

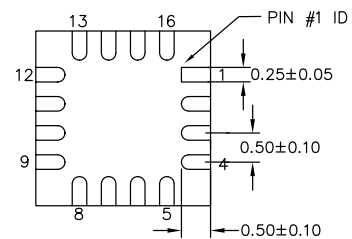
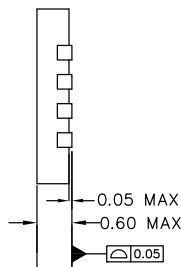
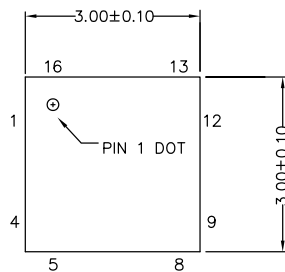


**Figure 17. 16-pin Chip-On-Lead (3 x 3 x 0.6 mm) (Sawn) Package Outline, 001-09116**

TOP VIEW

SIDE VIEW

BOTTOM VIEW



### NOTES

1. REFERENCE JEDEC # MO-220
2. ALL DIMENSIONS ARE IN MILLIMETERS

001-09116 \*J

## Thermal Impedances

**Table 32. Thermal Impedances per Package**

Package	Typical $\theta_{JA}$ <sup>[57]</sup>
16-pin SOIC	95 °C/W
16-pin QFN	33 °C/W
24-pin QFN <sup>[58]</sup>	21 °C/W
32-pin QFN <sup>[58]</sup>	20 °C/W
48-pin QFN <sup>[58]</sup>	18 °C/W
30-ball WLCSP	54 °C/W

## Capacitance on Crystal Pins

**Table 33. Typical Package Capacitance on Crystal Pins**

Package	Package Capacitance
32-Pin QFN	3.2 pF
48-Pin QFN	3.3 pF

## Solder Reflow Peak Temperature

Table 34 shows the solder reflow temperature limits that must not be exceeded.

**Table 34. Solder Reflow Peak Temperature**

Package	Maximum Peak Temperature ( $T_C$ )	Maximum Time above $T_C - 5$ °C
16-pin SOIC	260 °C	30 seconds
16-pin QFN	260 °C	30 seconds
24-pin QFN	260 °C	30 seconds
32-pin QFN	260 °C	30 seconds
48-pin QFN	260 °C	30 seconds
30-ball WLCSP	260 °C	30 seconds

### Notes

57.  $T_J = T_A + \text{Power} \times \theta_{JA}$ .

58. To achieve the thermal impedance specified for the QFN package, the center thermal pad must be soldered to the PCB ground plane.



## Development Tool Selection

### Software

#### *PSoC Designer™*

At the core of the PSoC development software suite is PSoC Designer, used to generate PSoC firmware applications. PSoC Designer is a Microsoft® Windows-based, integrated development environment for the Programmable System-on-Chip (PSoC) devices. The PSoC Designer IDE and application runs on Windows XP and Windows Vista.

This system provides design database management by project, in-system programming support, and built-in support for third-party assemblers and C compilers. PSoC Designer also supports C language compilers developed specifically for the devices in the PSoC family. PSoC Designer is available free of charge at <http://www.cypress.com/psocdesigner> and includes a free C compiler.

#### *PSoC Designer Software Subsystems*

You choose a base device to work with and then select different onboard analog and digital components called user modules that use the PSoC blocks. Examples of user modules are ADCs, DACs, Amplifiers, and Filters. You configure the user modules for your chosen application and connect them to each other and to the proper pins. Then you generate your project. This prepopulates your project with APIs and libraries that you can use to program your application.

The tool also supports easy development of multiple configurations and dynamic reconfiguration. Dynamic reconfiguration allows for changing configurations at run time. Code Generation Tools PSoC Designer supports multiple third-party C compilers and assemblers. The code generation tools work seamlessly within the PSoC Designer interface and have been tested with a full range of debugging tools. The choice is yours.

**Assemblers.** The assemblers allow assembly code to be merged seamlessly with C code. Link libraries automatically use absolute addressing or are compiled in relative mode, and linked with other software modules to get absolute addressing.

**C Language Compilers.** C language compilers are available that support the PSoC family of devices. The products allow you to create complete C programs for the PSoC family devices. The optimizing C compilers provide all the features of C tailored to the PSoC architecture. They come complete with embedded libraries providing port and bus operations, standard keypad and display support, and extended math functionality.

#### *PSoC Programmer*

PSoC Programmer is flexible enough and is used on the bench in development and is also suitable for factory programming. PSoC Programmer works either as a standalone programming application or operates directly from PSoC Designer. PSoC Programmer software is compatible with both PSoC ICE Cube in-circuit Emulator and PSoC MiniProg. PSoC programmer is available free of cost at <http://www.cypress.com/psocprogrammer>.

### Development Kits

All development kits are sold at the [Cypress Online Store](#).

### Evaluation Tools

All evaluation tools are sold at the [Cypress Online Store](#).

#### *CY3210-MiniProg1*

The **CY3210-MiniProg1 kit** allows you to program PSoC devices through the MiniProg1 programming unit. The MiniProg is a small, compact prototyping programmer that connects to the PC through a provided USB 2.0 cable. The kit includes:

- MiniProg programming unit
- MiniEval socket programming and evaluation board
- 28-pin CY8C29466-24PXI PDIP PSoC device sample
- 28-pin CY8C27443-24PXI PDIP PSoC device sample
- PSoC Designer software CD
- Getting Started guide
- USB 2.0 cable

#### *CY3210-PSoCEval1*

The **CY3210-PSoCEval1 kit** features an evaluation board and the MiniProg1 programming unit. The evaluation board includes an LCD module, potentiometer, LEDs, and plenty of bread-boarding space to meet all of your evaluation needs. The kit includes:

- Evaluation board with LCD module
- MiniProg programming unit
- Two 28-pin CY8C29466-24PXI PDIP PSoC device samples
- PSoC Designer software CD
- Getting Started guide
- USB 2.0 cable



## Device Programmers

All device programmers are purchased from the [Cypress Online Store](#).

### *CY3216 Modular Programmer*

The [CY3216 Modular Programmer kit](#) features a modular programmer and the MiniProg1 programming unit. The modular programmer includes three programming module cards and supports multiple Cypress products. The kit includes:

- Modular programmer base
- Three programming module cards
- MiniProg programming unit
- PSoC Designer software CD
- Getting Started guide
- USB 2.0 cable

## Third Party Tools

Several tools have been specially designed by the following third-party vendors to accompany PSoC devices during development and production. Specific details for each of these tools can be found at <http://www.cypress.com> under Documentation > Evaluation Boards.

### *CY3207ISSP In-System Serial Programmer (ISSP)*

The [CY3207ISSP](#) is a production programmer. It includes protection circuitry and an industrial case that is more robust than the MiniProg in a production-programming environment.

**Note** CY3207ISSP needs special software and is not compatible with PSoC Programmer. The kit includes:

- CY3207 programmer unit
- PSoC ISSP software CD
- 110 ~ 240 V power supply, Euro-Plug adapter
- USB 2.0 cable

## Ordering Information

Table 35 lists the CY8C20x37/47/67/S PSoC devices' key package features and ordering codes.

**Table 35. PSoC Device Key Features and Ordering Information**

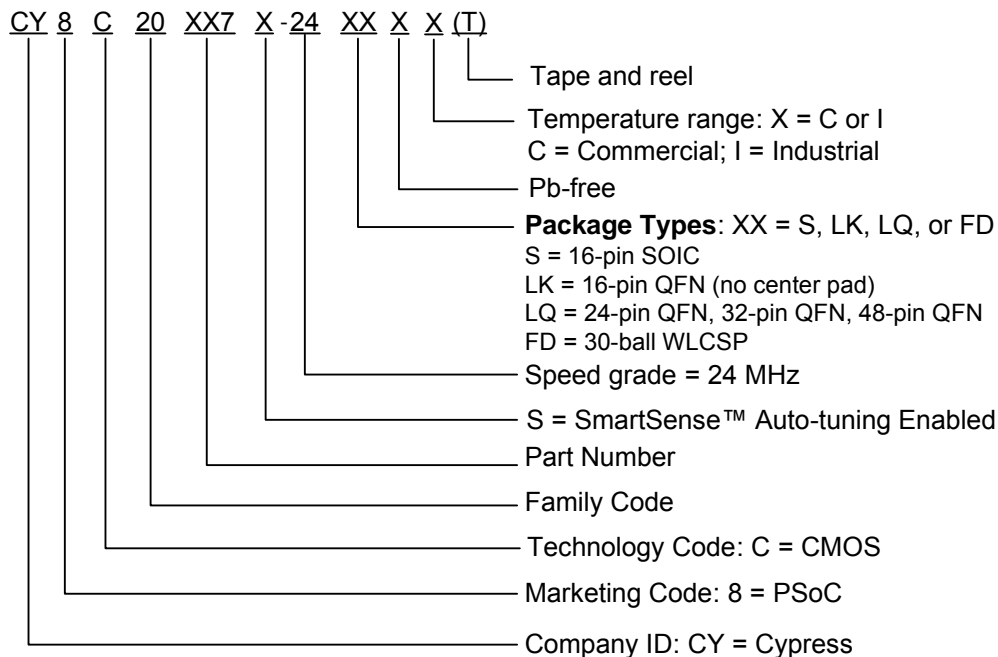
Ordering Code	Package	Flash (Bytes)	SRAM (Bytes)	CapSense Sensors	Digital I/O Pins	Analog Inputs <sup>[59]</sup>	XRES Pin	ADC
CY8C20237-24SXI	16-pin SOIC	8 K	1 K	10	13	13	Yes	Yes
CY8C20247S-24SXI	16-pin SOIC	16 K	2 K	10	13	13	Yes	Yes
CY8C20237-24LKXI	16-pin QFN	8 K	1 K	10	13	13	Yes	Yes
CY8C20237-24LKXIT	16-pin QFN (Tape and Reel)	8 K	1 K	10	13	13	Yes	Yes
CY8C20247S-24LKXI	16-pin QFN	16 K	2 K	10	13	13	Yes	Yes
CY8C20247S-24LKXIT	16-pin QFN (Tape and Reel)	16 K	2 K	10	13	13	Yes	Yes
CY8C20337-24LQXI	24-pin QFN	8 K	1 K	16	19	19	Yes	Yes
CY8C20337-24LQXIT	24-pin QFN (Tape and Reel)	8 K	1 K	16	19	19	Yes	Yes
CY8C20347-24LQXI	24-pin QFN	16 K	2 K	16	19	19	Yes	Yes
CY8C20347-24LQXIT	24-pin QFN (Tape and Reel)	16 K	2 K	16	19	19	Yes	Yes
CY8C20347S-24LQXI	24-pin QFN	16 K	2 K	16	19	19	Yes	Yes
CY8C20347S-24LQXIT	24-pin QFN (Tape and Reel)	16 K	2 K	16	19	19	Yes	Yes
CY8C20437-24LQXI	32-pin QFN	8 K	1 K	25	28	28	Yes	Yes
CY8C20437-24LQXIT	32-pin QFN (Tape and Reel)	8 K	1 K	25	28	28	Yes	Yes
CY8C20447-24LQXI	32-pin QFN	16 K	2 K	25	28	28	Yes	Yes
CY8C20447-24LQXIT	32-pin QFN (Tape and Reel)	16 K	2 K	25	28	28	Yes	Yes
CY8C20447S-24LQXI	32-pin QFN	16 K	2 K	25	28	28	Yes	Yes
CY8C20447S-24LQXIT	32-pin QFN (Tape and Reel)	16 K	2 K	25	28	28	Yes	Yes
CY8C20467-24LQXI	32-pin QFN	32 K	2 K	25	28	28	Yes	Yes
CY8C20467-24LQXIT	32-pin QFN (Tape and Reel)	32 K	2 K	25	28	28	Yes	Yes
CY8C20467S-24LQXI	32-pin QFN	32 K	2 K	25	28	28	Yes	Yes
CY8C20467S-24LQXIT	32-pin QFN (Tape and Reel)	32 K	2 K	25	28	28	Yes	Yes
CY8C20637-24LQXI	48-pin QFN	8 K	1 K	31	34	34	Yes	Yes
CY8C20637-24LQXIT	48-pin QFN (Tape and Reel)	8 K	1 K	31	34	34	Yes	Yes
CY8C20647-24LQXI	48-pin QFN	16 K	2 K	31	34	34	Yes	Yes
CY8C20647-24LQXIT	48-pin QFN (Tape and Reel)	16 K	2 K	31	34	34	Yes	Yes
CY8C20647S-24LQXI	48-pin QFN	16 K	2 K	31	34	34	Yes	Yes
CY8C20647S-24LQXIT	48-pin QFN (Tape and Reel)	16 K	2 K	31	34	34	Yes	Yes
CY8C20667-24LQXI	48-pin QFN	32 K	2 K	31	34	34	Yes	Yes
CY8C20667-24LQXIT	48-pin QFN (Tape and Reel)	32 K	2 K	31	34	34	Yes	Yes
CY8C20667S-24LQXI	48-pin QFN	32 K	2 K	31	34	34	Yes	Yes
CY8C20667S-24LQXIT	48-pin QFN (Tape and Reel)	32 K	2 K	31	34	34	Yes	Yes

**Note**

<sup>59</sup>. Dual-function Digital I/O Pins also connect to the common analog mux.

**Table 35. PSoC Device Key Features and Ordering Information** *(continued)*

Ordering Code	Package	Flash (Bytes)	SRAM (Bytes)	CapSense Sensors	Digital I/O Pins	Analog Inputs <sup>[59]</sup>	XRES Pin	ADC
CY8C20767-24FDXC	30-pin WLCSP	32 K	2 K	24	27	27	Yes	Yes
CY8C20767-24FDXCT	30-pin WLCSP (Tape and Reel)	32 K	2 K	24	27	27	Yes	Yes

**Ordering Code Definitions**


## 5. Wake-up from Sleep with Hardware I2C Address match on Pins P1[0], P1[1]

### ■Problem Definition

I2C interface needs 20 ns hold time on SDA line with respect to falling edge of SCL, to wake-up from sleep using I2C hardware address match event.

### ■Parameters Affected

$t_{HD;DAT}$  increased to 20 ns from 0 ns

### ■Trigger Condition(S)

This is an issue only when all these three conditions are met:

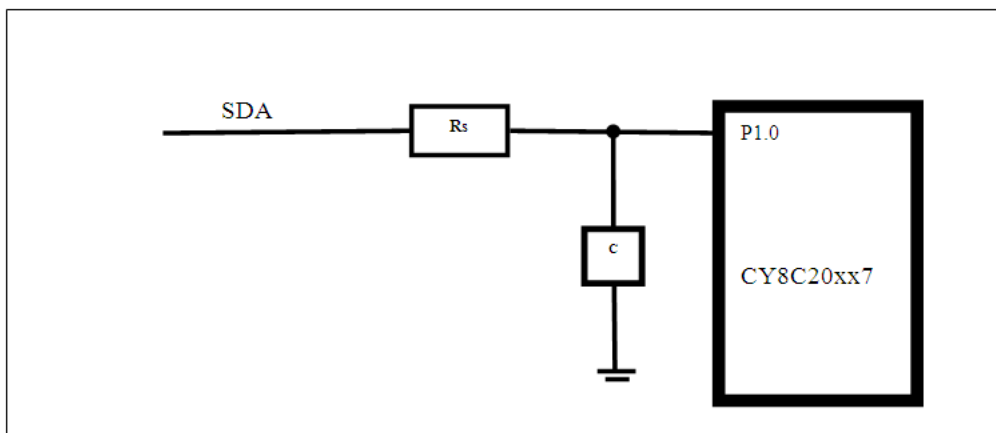
- 1) P1.0 and P1.1 are used as I2C pins,
- 2) Wakeup from sleep with hardware address match feature is enabled, and
- 3) I2C master does not provide 20 ns hold time on SDA with respect to falling edge of SCL.

### ■Scope of Impact

These trigger conditions cause the device to never wake-up from sleep based on I2C address match event.

### ■Workaround

For a design that meets all of the trigger conditions, the following suggested circuit has to be implemented as a work-around. The R and C values proposed are 100 ohm and 200 pF respectively.



### ■Fix Status

Will not be fixed

### ■Changes

None

**Document History Page** *(continued)*

<b>Document Title: CY8C20xx7/S, 1.8 V CapSense® Controller with SmartSense™ Auto-tuning 31 Buttons, 6 Sliders, Proximity Sensors</b> <b>Document Number: 001-69257</b>				
Revision	ECN	Orig. of Change	Submission Date	Description of Change
*F	3645807	DST/BVI	07/03/2012	<p>Updated F<sub>SCLK</sub> parameter in the <a href="#">Table 31, “SPI Slave AC Specifications,” on page 26</a></p> <p>Changed t<sub>OUT_HIGH</sub> to t<sub>OUT_H</sub> in <a href="#">Table 30, “SPI Master AC Specifications,” on page 25</a></p> <p>Updated Features section, “Programmable pin configurations” bullet:</p> <ul style="list-style-type: none"> <li>■ Included the following sub-bullet point - 5 mA source current on port 0 and 1 and 1 mA on port 2,3 and 4</li> <li>■ Changed the bullet point “High sink current of 25 mA for each GPIO” to “High sink current of 25 mA for each GPIO. Total 120 mA maximum sink current per chip”</li> <li>■ Added “QuietZone™ Controller” bullet and updated “Low power CapSense® block with SmartSense™ auto-tuning” bullet.</li> </ul> <p>Updated package diagrams 001-13937 to *D and 001-57280 to *C revisions.</p>
*G	3800055	DST	11/23/2012	<p>Changed document title.</p> <p>Part named changed from CY8C20xx7 to CY8C20xx7/S</p> <p>Table 20: Update to VIH2C to match Item #6 in K2 Si Errata document (001-75370)</p> <p>Updated package diagrams:</p> <p>51-85068 to *E 001-09116 to *G 001-13937 to *E 001-42168 to *E 001-57280 to *E</p>
*H	3881332	SRLI	02/04/2013	<p>Updated <a href="#">Features</a>:</p> <p>Added Note “Please contact your nearest sales office for additional details.” and referred the same note in “24 Sensing Inputs – 30-pin WLCSP”.</p>
*I	3993458	DST	05/07/2013	<p>Updated <a href="#">Electrical Specifications</a> (Updated <a href="#">DC GPIO Specifications</a> (Updated heading of third column as “Port 0/1 per I/O (max)” for <a href="#">Table 13</a>)).</p> <p>Updated <a href="#">Packaging Information</a>: spec 001-09116 – Changed revision from *G to *H (<a href="#">Figure 17</a>).</p> <p>Added <a href="#">Errata</a>.</p>
*J	4081796	DST	07/31/2013	<p>Added Errata footnotes (Note 40, 41, 42, 43, 44).</p> <p>Updated already existing footnotes (Note 50, 51, 55) as Errata footnotes.</p> <p>Updated <a href="#">Electrical Specifications</a>: Updated <a href="#">DC Chip-Level Specifications</a>: Added Note 40, 41, 42, 43 and referred the same notes in I<sub>SB0</sub>, I<sub>SB1</sub>, I<sub>SB12C</sub> parameters. Updated <a href="#">DC GPIO Specifications</a>: Added Note 44 and referred the same note in description of V<sub>ILLVT3.3</sub> parameter in <a href="#">Table 10</a>. Updated <a href="#">DC I2C Specifications</a>: Updated Note 50, 51 referred in <a href="#">Table 20</a>. Updated <a href="#">AC I2C Specifications</a>: Updated Note 55 referred in <a href="#">Table 29</a>.</p> <p>Updated to new template.</p>