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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	64MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	128KB (64K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	3.6K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 35x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic18f47k40-i-pt">https://www.e-xfl.com/product-detail/microchip-technology/pic18f47k40-i-pt</a>

## Pin Allocation Tables

TABLE 1: 28-PIN ALLOCATION TABLE (PIC18(L)F27K40)

I/O <sup>(2)</sup>	28-Pin SPDIP, SOIC, SSOP	28-Pin QFN	A/D	Reference	Comparator	Timers	CCP	CWG	ZCD	Interrupt	EUSART	DSM	MSSP	Pull-up	Basic
RA0	2	27	ANA0	—	C1IN0- C2IN0-	—	—	—	—	IOCA0	—	—	—	Y	—
RA1	3	28	ANA1	—	C1IN1- C2IN1-	—	—	—	—	IOCA1	—	—	—	Y	—
RA2	4	1	ANA2	DAC1OUT1 VREF- (DAC) VREF- (ADC)	C1IN0+ C2IN0+	—	—	—	—	IOCA2	—	—	—	Y	—
RA3	5	2	ANA3	VREF+ (DAC) VREF+ (ADC)	C1IN1+	—	—	—	—	IOCA3	—	MDCIN1 <sup>(1)</sup>	—	Y	—
RA4	6	3	ANA4	—	—	T0CKI <sup>(1)</sup>	—	—	—	IOCA4	—	MDCIN2 <sup>(1)</sup>	—	Y	—
RA5	7	4	ANA5	—	—	—	—	—	—	IOCA5	—	MDMIN <sup>(1)</sup>	SS1 <sup>(1)</sup>	Y	—
RA6	10	7	ANA6	—	—	—	—	—	—	IOCA6	—	—	—	Y	CLKOUT OSC2
RA7	9	6	ANA7	—	—	—	—	—	—	IOCA7	—	—	—	Y	OSC1 CLKIN
RB0	21	18	ANB0	—	C2IN1+	—	—	CWG1 <sup>(1)</sup>	ZCDIN	IOCB0 INT0 <sup>(1)</sup>	—	—	SS2 <sup>(1)</sup>	Y	—
RB1	22	19	ANB1	—	C1IN3- C2IN3-	—	—	—	—	IOCB1 INT1 <sup>(1)</sup>	—	—	SCK2 <sup>(1)</sup> SCL2 <sup>(3,4)</sup>	Y	—
RB2	23	20	ANB2	—	—	—	—	—	—	IOCB2 INT2 <sup>(1)</sup>	—	—	SDI2 <sup>(1)</sup> SDA2 <sup>(3,4)</sup>	Y	—
RB3	24	21	ANB3	—	C1IN2- C2IN2-	—	—	—	—	IOCB3	—	—	—	Y	—
RB4	25	22	ANB4	—	—	T5G <sup>(1)</sup>	—	—	—	IOCB4	—	—	—	Y	—
RB5	26	23	ANB5	—	—	T1G <sup>(1)</sup>	—	—	—	IOCB5	—	—	—	Y	—
RB6	27	24	ANB6	—	—	—	—	—	—	IOCB6	CK2 <sup>(1)</sup>	—	—	Y	ICSPCLK
RB7	28	25	ANB7	DAC1OUT2	—	T6AIN <sup>(1)</sup>	—	—	—	IOCB7	RX2/DT2 <sup>(1)</sup>	—	—	Y	ICSPDAT

- Note**
- 1: Default peripheral input. Input can be moved to any other pin with the PPS input selection registers (Register 17-1).
  - 2: All pin outputs default to PORT latch data. Any pin can be selected as a peripheral digital output with the PPS output selection registers.
  - 3: These peripheral functions are bidirectional. The output pin selections must be the same as the input pin selections.
  - 4: These pins are configured for I<sup>2</sup>C logic levels; The SCLx/SDAx signals may be assigned to any of these pins. PPS assignments to the other pins (e.g., RB1) will operate, but input logic levels will be standard TTL/ST as selected by the INLVL register, instead of the I<sup>2</sup>C specific or SMBus input buffer thresholds.

# PIC18(L)F27/47K40

## Register 3-7: Configuration Word 4L (30 0006h): Memory Write Protection

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
WRT7	WRT6	WRT5	WRT4	WRT3	WRT2	WRT1	WRT0
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '1'  
 -n = Value for blank device        '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-0                      **WRT<7:0>**: User NVM Self-Write Protection bits<sup>(1)</sup>  
                                   1 = Corresponding Memory Block NOT write-protected  
                                   0 = Corresponding Memory Block write-protected

**Note 1:** Refer to Table 10-2 for details on implementation of the individual WRT bits.

## Register 3-8: Configuration Word 4H (30 0007h): Memory Write Protection

U-1	U-1	R/W-1	R/W-1	U-1	R/W-1	R/W-1	R/W-1
—	—	LVP	SCANE	—	WRTD	WRTB	WRTC
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '1'  
 -n = Value for blank device        '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-6                      **Unimplemented:** Read as '1'

bit 5                      **LVP:** Low-Voltage Programming Enable bit  
                                   1 = Low-voltage programming enabled.  $\overline{\text{MCLR}}/\text{VPP}$  pin function is  $\overline{\text{MCLR}}$ . MCLRE Configuration bit is ignored.  
                                   The LVP bit cannot be written (to zero) while operating from the LVP programming interface. The purpose of this rule is to prevent the user from dropping out of LVP mode while programming from LVP mode, or accidentally eliminating LVP mode from the Configuration state.  
                                   0 = HV on  $\overline{\text{MCLR}}/\text{VPP}$  must be used for programming

bit 4                      **SCANE:** Scanner Enable bit  
                                   1 = Scanner module is available for use, SCANMD bit enables the module  
                                   0 = Scanner module is NOT available for use, SCANMD bit is ignored

bit 3                      **Unimplemented:** Read as '1'

bit 2                      **WRTD:** Data EEPROM Write Protection bit  
                                   1 = Data EEPROM NOT write-protected  
                                   0 = Data EEPROM write-protected

bit 1                      **WRTB:** Boot Block Write Protection bit  
                                   1 = Boot Block NOT write-protected  
                                   0 = Boot Block write-protected

bit 0                      **WRTC:** Configuration Register Write Protection bit  
                                   1 = Configuration Register NOT write-protected  
                                   0 = Configuration Register write-protected

## 5.1 Clock Source

The input to the reference clock output can be selected using the CLKRCLK register.

### 5.1.1 CLOCK SYNCHRONIZATION

Once the reference clock enable (EN) is set, the module is ensured to be glitch-free at start-up.

When the reference clock output is disabled, the output signal will be disabled immediately.

Clock dividers and clock duty cycles can be changed while the module is enabled, but glitches may occur on the output. To avoid possible glitches, clock dividers and clock duty cycles should be changed only when the CLKREN is clear.

## 5.2 Programmable Clock Divider

The module takes the clock input and divides it based on the value of the DIV<2:0> bits of the CLKRCON register (Register 5-1).

The following configurations can be made based on the DIV<2:0> bits:

- Base FOSC value
- FOSC divided by 2
- FOSC divided by 4
- FOSC divided by 8
- FOSC divided by 16
- FOSC divided by 32
- FOSC divided by 64
- FOSC divided by 128

The clock divider values can be changed while the module is enabled; however, in order to prevent glitches on the output, the DIV<2:0> bits should only be changed when the module is disabled (EN = 0).

## 5.3 Selectable Duty Cycle

The DC<1:0> bits of the CLKRCON register can be used to modify the duty cycle of the output clock. A duty cycle of 25%, 50%, or 75% can be selected for all clock rates, with the exception of the undivided base Fosc value.

The duty cycle can be changed while the module is enabled; however, in order to prevent glitches on the output, the DC<1:0> bits should only be changed when the module is disabled (EN = 0).

**Note:** The DC1 bit is reset to '1'. This makes the default duty cycle 50% and not 0%.

## 5.4 Operation in Sleep Mode

The reference clock output module clock is based on the system clock. When the device goes to Sleep, the module outputs will remain in their current state. This will have a direct effect on peripherals using the reference clock output as an input signal. No change should occur in the module from entering or exiting from Sleep.

## 5.5 Register Definitions: Reference Clock

Long bit name prefixes for the Reference Clock peripherals are shown in Table 5-1. Refer to **Section 1.4.2.2 “Long Bit Names”** for more information.

**TABLE 5-1:**

Peripheral	Bit Name Prefix
CLKR	CLKR

**REGISTER 5-1: CLKRCON: REFERENCE CLOCK CONTROL REGISTER**

R/W-0/0	U-0	U-0	R/W-1/1	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
EN	—	—	DC<1:0>	DIV<2:0>			
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

- bit 7      **EN:** Reference Clock Module Enable bit  
           1 = Reference clock module enabled  
           0 = Reference clock module is disabled
- bit 6-5    **Unimplemented:** Read as '0'
- bit 4-3    **DC<1:0>:** Reference Clock Duty Cycle bits<sup>(1)</sup>  
           11 = Clock outputs duty cycle of 75%  
           10 = Clock outputs duty cycle of 50%  
           01 = Clock outputs duty cycle of 25%  
           00 = Clock outputs duty cycle of 0%
- bit 2-0    **DIV<2:0>:** Reference Clock Divider bits  
           111 = Base clock value divided by 128  
           110 = Base clock value divided by 64  
           101 = Base clock value divided by 32  
           100 = Base clock value divided by 16  
           011 = Base clock value divided by 8  
           010 = Base clock value divided by 4  
           001 = Base clock value divided by 2  
           000 = Base clock value

**Note 1:** Bits are valid for reference clock divider values of two or larger, the base clock cannot be further divided.

# PIC18(L)F27/47K40

## REGISTER 7-3: PMD2: PMD CONTROL REGISTER 2

U-0	R/W-0/0	R/W-0/0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0
—	DACMD	ADCMD	—	—	CMP2MD	CMP1MD	ZCDMD <sup>(1)</sup>
bit 7							bit 0

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7	<b>Unimplemented:</b> Read as '0'
bit 6	<b>DACMD:</b> Disable DAC bit 1 = DAC module disabled 0 = DAC module enabled
bit 5	<b>ADCMD:</b> Disable ADC bit 1 = ADC module disabled 0 = ADC module enabled
bit 4-3	<b>Unimplemented:</b> Read as '0'
bit 2	<b>CMP2MD:</b> Disable Comparator CMP2 bit 1 = CMP2 module disabled 0 = CMP2 module enabled
bit 1	<b>CMP1MD:</b> Disable Comparator CMP1 bit 1 = CMP1 module disabled 0 = CMP1 module enabled
bit 0	<b>ZCDMD:</b> Disable Zero-Cross Detect module bit <sup>(1)</sup> 1 = ZCD module disabled 0 = ZCD module enabled

**Note 1:** Subject to  $\overline{\text{ZCD}}$  bit in CONFIG2H.

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## REGISTER 9-5: WDTTMR: WDT TIMER REGISTER (READ-ONLY)

R-0/0	R-0/0	R-0/0	R-0/0	R-0/0	R-0/0	R-0/0	R-0/0
WDTTMR<4:0>					STATE	PSCNT<17:16>	
bit 7					bit 0		

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-3 **WDTTMR<4:0>**: Watchdog Window Value bits

WINDOW	WDT Window State		Open Percent
	Closed	Open	
111	N/A	00000-11111	100
110	00000-00011	00100-11111	87.5
101	00000-00111	01000-11111	75
100	00000-01011	01100-11111	62.5
011	00000-01111	10000-11111	50
010	00000-10011	10100-11111	37.5
001	00000-10111	11000-11111	25
000	00000-11011	11100-11111	12.5

bit 2 **STATE**: WDT Armed Status bit

1 = WDT is armed

0 = WDT is not armed

bit 1-0 **PSCNT<17:16>**: Prescale Select Upper Byte bits<sup>(1)</sup>

**Note 1:** The 18-bit WDT prescale value, PSCNT<17:0> includes the WDTPSL, WDTPSH and the lower bits of the WDTTMR registers. PSCNT<17:0> is intended for debug operations and should be read during normal operation.

# PIC18(L)F27/47K40

**TABLE 10-3: SPECIAL FUNCTION REGISTER MAP FOR PIC18(L)F27/47K40 DEVICES**

Address	Name	Address	Name	Address	Name	Address	Name
FFFh	TOSU	FD7h	PCON0	FAFh	T6TMR	F87h	LATE <sup>(2)</sup>
FFEh	TOSH	FD6h	T0CON1	FAEh	CCPTMRS	F86h	LATD <sup>(2)</sup>
FFDh	TOSL	FD5h	T0CON0	FADh	CCP1CAP	F85h	LATC
FFCh	STKPTR	FD4h	TMR0H	FACH	CCP1CON	F84h	LATB
FFBh	PCLATU	FD3h	TMR0L	FABh	CCP1H	F83h	LATA
FFAh	PCLATH	FD2h	T1CLK	FAAh	CCP1L	F82h	NVMCON2
FF9h	PCL	FD1h	T1GATE	FA9h	CCP2CAP	F81h	NVMCON1
FF8h	TBLPTRU	FD0h	T1GCON	FA8h	CCP2CON	F80h	NVMDAT
FF7h	TBLPTRH	FCFh	T1CON	FA7h	CCP2H	F7Fh	NVMADRH
FF6h	TBLPTRL	FCEh	TMR1H	FA6h	CCP2L	F7Eh	NVMADRL
FF5h	TABLAT	FCDh	TMR1L	FA5h	PWM3CON	F7Dh	CRCCON1
FF4h	PRODH	FCCh	T3CLK	FA4h	PWM3DCH	F7Ch	CRCCON0
FF3h	PRODL	FCBh	T3GATE	FA3h	PWM3DCL	F7Bh	CRCXORH
FF2h	INTCON	FCAh	T3GCON	FA2h	PWM4CON	F7Ah	CRCXORL
FF1h	—	FC9h	T3CON	FA1h	PWM4DCH	F79h	CRCSHIFTH
FF0h	—	FC8h	TMR3H	FA0h	PWM4DCL	F78h	CRCSHIFTL
FEFh	INDF0 <sup>(1)</sup>	FC7h	TMR3L	F9Fh	BAUD1CON	F77h	CRCACCH
FEEh	POSTINC0 <sup>(1)</sup>	FC6h	T5CLK	F9Eh	TX1STA	F76h	CRCACCL
FEDh	POSTDEC0 <sup>(1)</sup>	FC5h	T5GATE	F9Dh	RC1STA	F75h	CRCDATH
FECh	PREINC0 <sup>(1)</sup>	FC4h	T5GCON	F9Ch	SP1BRGH	F74h	CRCDATL
FEBh	PLUSW0 <sup>(1)</sup>	FC3h	T5CON	F9Bh	SP1BRGL	F73h	ADFLTRH
FEAh	FSR0H	FC2h	TMR5H	F9Ah	TX1REG	F72h	ADFLTRL
FE9h	FSR0L	FC1h	TMR5L	F99h	RC1REG	F71h	ADACCH
FE8h	WREG	FC0h	T2RST	F98h	SSP1CON3	F70h	ADACCL
FE7h	INDF1 <sup>(1)</sup>	FBFh	T2CLKCON	F97h	SSP1CON2	F6Fh	ADERRH
FE6h	POSTINC1 <sup>(1)</sup>	FBEh	T2HLT	F96h	SSP1CON1	F6Eh	ADERRL
FE5h	POSTDEC1 <sup>(1)</sup>	FBDh	T2CON	F95h	SSP1STAT	F6Dh	ADUTHH
FE4h	PREINC1 <sup>(1)</sup>	FBCh	T2PR	F94h	SSP1MSK	F6Ch	ADUTHL
FE3h	PLUSW1 <sup>(1)</sup>	FBBh	T2TMR	F93h	SSP1ADD	F6Bh	ADLTHH
FE2h	FSR1H	FBAh	T4RST	F92h	SSP1BUF	F6Ah	ADLTHL
FE1h	FSR1L	FB9h	T4CLKCON	F91h	PORTE	F69h	ADSTPTH
FE0h	BSR	FB8h	T4HLT	F90h	PORTD <sup>(2)</sup>	F68h	ADSTPTL
FDFh	INDF2 <sup>(1)</sup>	FB7h	T4CON	F8Fh	PORTC	F67h	ADCNT
FDEh	POSTINC2 <sup>(1)</sup>	FB6h	T4PR	F8Eh	PORTB	F66h	ADRPT
FDDh	POSTDEC2 <sup>(1)</sup>	FB5h	T4TMR	F8Dh	PORTA	F65h	ADSTAT
FDCh	PREINC2 <sup>(1)</sup>	FB4h	T6RST	F8Ch	TRISE <sup>(2)</sup>	F64h	ADRESH
FDBh	PLUSW2 <sup>(1)</sup>	FB3h	T6CLKCON	F8Bh	TRISD <sup>(2)</sup>	F63h	ADRESL
FDAh	FSR2H	FB2h	T6HLT	F8Ah	TRISC	F62h	ADPREVH
FD9h	FSR2L	FB1h	T6CON	F89h	TRISB	F61h	ADPREVL
FD8h	STATUS	FB0h	T6PR	F88h	TRISA	F60h	ADCON0

**Note 1:** This is not a physical register.

**Note 2:** Not available on PIC18(L)F27K40 (28-pin variants).



## 11.1.5 ERASING PROGRAM FLASH MEMORY

The minimum erase block is 32 or 64 words (refer to Table 11-3). Only through the use of an external programmer, or through ICSP™ control, can larger blocks of program memory be bulk erased. Word erase in the Flash array is not supported.

For example, when initiating an erase sequence from a microcontroller with erase row size of 32 words, a block of 32 words (64 bytes) of program memory is erased. The Most Significant 16 bits of the TBLPTR<21:6> point to the block being erased. The TBLPTR<5:0> bits are ignored.

The NVMCON1 register commands the erase operation. The NVMREG<1:0> bits must be set to point to the Program Flash Memory. The WREN bit must be set to enable write operations. The FREE bit is set to select an erase operation.

The NVM unlock sequence described in **Section 11.1.4 “NVM Unlock Sequence”** should be used to guard against accidental writes. This is sometimes referred to as a long write.

A long write is necessary for erasing the internal Flash. Instruction execution is halted during the long write cycle. The long write is terminated by the internal programming timer.

### 11.1.5.1 Program Flash Memory Erase Sequence

The sequence of events for erasing a block of internal program memory is:

1. NVMREG bits of the NVMCON1 register point to PFM
2. Set the FREE and WREN bits of the NVMCON1 register
3. Perform the unlock sequence as described in **Section 11.1.4 “NVM Unlock Sequence”**

If the PFM address is write-protected, the WR bit will be cleared and the erase operation will not take place, WRERR is signaled in this scenario.

The operation erases the memory row indicated by masking the LSBs of the current TBLPTR.

While erasing PFM, CPU operation is suspended and it resumes when the operation is complete. Upon completion the WR bit is cleared in hardware, the NVMIF is set and an interrupt will occur if the NVMIE bit is also set.

Write latch data is not affected by erase operations and WREN will remain unchanged.

- Note 1:** If a write or erase operation is terminated by an unexpected event, WRERR bit will be set which the user can check to decide whether a rewrite of the location(s) is needed.
- 2: WRERR is set if WR is written to '1' while TBLPTR points to a write-protected address.
  - 3: WRERR is set if WR is written to '1' while TBLPTR points to an invalid address location (Table 10-2 and Table 11-1).

## EXAMPLE 11-4: WRITING TO PROGRAM FLASH MEMORY

	MOVLW	D'64'	; number of bytes in erase block
	MOVWF	COUNTER	
	MOVLW	BUFFER_ADDR_HIGH	; point to buffer
	MOVWF	FSROH	
	MOVLW	BUFFER_ADDR_LOW	
	MOVWF	FSROL	
	MOVLW	CODE_ADDR_UPPER	; Load TBLPTR with the base
	MOVWF	TBLPTRU	; address of the memory block
	MOVLW	CODE_ADDR_HIGH	
	MOVWF	TBLPTRH	
	MOVLW	CODE_ADDR_LOW	
	MOVWF	TBLPTRL	
READ_BLOCK			
	TBLRD*+		; read into TABLAT, and inc
	MOVF	TABLAT, W	; get data
	MOVWF	POSTINC0	; store data
	DECFSZ	COUNTER	; done?
	BRA	READ_BLOCK	; repeat
MODIFY_WORD			
	MOVLW	BUFFER_ADDR_HIGH	; point to buffer
	MOVWF	FSROH	
	MOVLW	BUFFER_ADDR_LOW	
	MOVWF	FSROL	
	MOVLW	NEW_DATA_LOW	; update buffer word
	MOVWF	POSTINC0	
	MOVLW	NEW_DATA_HIGH	
	MOVWF	INDF0	
ERASE_BLOCK			
	MOVLW	CODE_ADDR_UPPER	; load TBLPTR with the base
	MOVWF	TBLPTRU	; address of the memory block
	MOVLW	CODE_ADDR_HIGH	
	MOVWF	TBLPTRH	
	MOVLW	CODE_ADDR_LOW	
	MOVWF	TBLPTRL	
	BCF	NVMCON1, NVMREG0	; point to Program Flash Memory
	BSF	NVMCON1, NVMREG1	; point to Program Flash Memory
	BSF	NVMCON1, WREN	; enable write to memory
	BSF	NVMCON1, FREE	; enable Erase operation
	BCF	INTCON, GIE	; disable interrupts
	MOVLW	55h	
<b>Required Sequence</b>	MOVWF	NVMCON2	; write 55h
	MOVLW	AAh	
	MOVWF	NVMCON2	; write 0AAh
	BSF	NVMCON1, WR	; start erase (CPU stall)
	BSF	INTCON, GIE	; re-enable interrupts
	TBLRD*-		; dummy read decrement
	MOVLW	BUFFER_ADDR_HIGH	; point to buffer
	MOVWF	FSROH	
	MOVLW	BUFFER_ADDR_LOW	
	MOVWF	FSROL	
WRITE_BUFFER_BACK			
	MOVLW	BlockSize	; number of bytes in holding register
	MOVWF	COUNTER	
	MOVLW	D'64'/BlockSize	; number of write blocks in 64 bytes
	MOVWF	COUNTER2	

# PIC18(L)F27/47K40

**REGISTER 15-6: ODCONx: OPEN-DRAIN CONTROL REGISTER**

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
ODCx7	ODCx6	ODCx5	ODCx4	ODCx3	ODCx2	ODCx1	ODCx0
bit 7							bit 0

**Legend:**

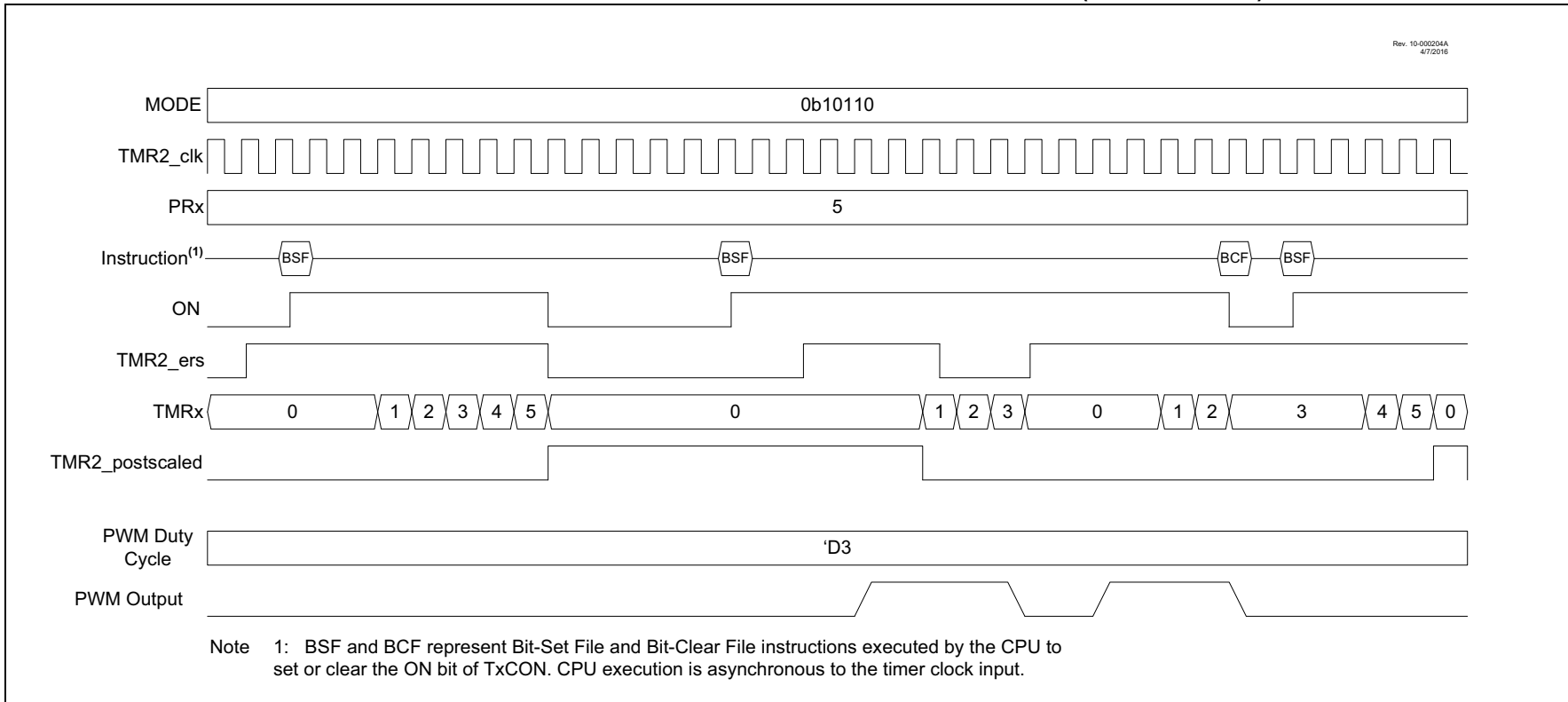
R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 '1' = Bit is set                          '0' = Bit is cleared                      x = Bit is unknown  
 -n/n = Value at POR and BOR/Value at all other Resets

bit 7-0                      **ODCx<7:0>**: Open-Drain Configuration on Pins Rx<7:0>  
 1 = Output drives only low-going signals (sink current only)  
 0 = Output drives both high-going and low-going signals (source and sink current)

**TABLE 15-7: OPEN-DRAIN CONTROL REGISTERS**

Name	Device		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
	28 Pins	40/44 Pins								
ODCONA	X	X	ODCA7	ODCA6	ODCA5	ODCA4	ODCA3	ODCA2	ODCA1	ODCA0
ODCONB	X	X	ODCB7	ODCB6	ODCB5	ODCB4	ODCB3	ODCB2	ODCB1	ODCB0
ODCONC	X	X	ODCC7	ODCC6	ODCC5	ODCC4	ODCC3	ODCC2	ODCC1	ODCC0
ODCOND	X		—	—	—	—	—	—	—	—
		X	ODCD7	ODCD6	ODCD5	ODCD4	ODCD3	ODCD2	ODCD1	ODCD0
ODCONE	X		—	—	—	—	—	—	—	—
		X	—	—	—	—	—	ODCE2	ODCE1	ODCE0

**FIGURE 20-13: LEVEL-TRIGGERED HARDWARE LIMIT ONE-SHOT MODE TIMING DIAGRAM (MODE = 10110)**



# PIC18(L)F27/47K40

## REGISTER 24-7: CWG1AS1: CWG AUTO-SHUTDOWN CONTROL REGISTER 1

U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	AS5E	AS4E	AS3E	AS2E	AS1E	AS0E
bit 7							bit 0

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

- bit 7-6      **Unimplemented** Read as '0'
- bit 5      **AS5E:** CWG Auto-shutdown Source 5 (CMP2 OUT) Enable bit  
 1 = Auto-shutdown for CMP2 OUT is enabled  
 0 = Auto-shutdown for CMP2 OUT is disabled
- bit 4      **AS4E:** CWG Auto-shutdown Source 4 (CMP1 OUT) Enable bit  
 1 = Auto-shutdown for CMP1 OUT is enabled  
 0 = Auto-shutdown for CMP1 OUT is disabled
- bit 3      **AS3E:** CWG Auto-shutdown Source 3 (TMR6\_Postscaled) Enable bit  
 1 = Auto-shutdown for TMR6\_Postscaled is enabled  
 0 = Auto-shutdown for TMR6\_Postscaled is disabled
- bit 2      **AS2E:** CWG Auto-shutdown Source 2 (TMR4\_Postscaled) Enable bit  
 1 = Auto-shutdown for TMR4\_Postscaled is enabled  
 0 = Auto-shutdown for TMR4\_Postscaled is disabled
- bit 1      **AS1E:** CWG Auto-shutdown Source 1 (TMR2\_Postscaled) Enable bit  
 1 = Auto-shutdown for TMR2\_Postscaled is enabled  
 0 = Auto-shutdown for TMR2\_Postscaled is disabled
- bit 0      **AS0E:** CWG Auto-shutdown Source 0 (Pin selected by CWG1PPS) Enable bit  
 1 = Auto-shutdown for CWG1PPS Pin is enabled  
 0 = Auto-shutdown for CWG1PPS Pin is disabled

## 30.6 Register Definitions: DAC Control

Long bit name prefixes for the DAC peripheral is shown in Table 30-1. Refer to **Section 1.4.2.2 “Long Bit Names”** for more information.

**TABLE 30-1:**

Peripheral	Bit Name Prefix
DAC	DAC

**REGISTER 30-1: DAC1CON0: DAC CONTROL REGISTER**

R/W-0/0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0
EN	—	OE1	OE2	PSS<1:0>		—	NSS
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7	<b>EN:</b> DAC Enable bit 1 = DAC is enabled 0 = DAC is disabled
bit 6	<b>Unimplemented:</b> Read as '0'
bit 5	<b>OE1:</b> DAC Voltage Output Enable bit 1 = DAC voltage level is output on the DAC1OUT1 pin 0 = DAC voltage level is disconnected from the DAC1OUT1 pin
bit 4	<b>OE2:</b> DAC Voltage Output Enable bit 1 = DAC voltage level is output on the DAC1OUT2 pin 0 = DAC voltage level is disconnected from the DAC1OUT2 pin
bit 3-2	<b>PSS&lt;1:0&gt;:</b> DAC Positive Source Select bit 11 = Reserved 10 = FVR buffer 01 = VREF+ 00 = AVDD
bit 1	<b>Unimplemented:</b> Read as '0'
bit 0	<b>NSS:</b> DAC Negative Source Select bit 1 = VREF- 0 = AVSS

# PIC18(L)F27/47K40

## REGISTER 31-2: ADCON1: ADC CONTROL REGISTER 1

R/W-0/0	R/W-0/0	R/W-0/0	U-0	U-0	U-0	U-0	R/W-0/0
ADPPOL	ADIPEN	ADGPOL	–	–	–	–	ADDSEN
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                      x = Bit is unknown                      -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                              '0' = Bit is cleared

bit 7                      **ADPPOL:** Precharge Polarity bit  
If  $ADPRE > 0x00$ :

ADPPOL	Action During 1st Precharge Stage	
	External (selected analog I/O pin)	Internal (AD sampling capacitor)
1	Shorted to AVDD	$C_{HOLD}$ shorted to VSS
0	Shorted to VSS	$C_{HOLD}$ shorted to AVDD

### Otherwise:

The bit is ignored

bit 6                      **ADIPEN:** A/D Inverted Precharge Enable bit

If  $ADDSEN = 1$

1 = The precharge and guard signals in the second conversion cycle are the opposite polarity of the first cycle

0 = Both Conversion cycles use the precharge and guards specified by ADPPOL and ADGPOL

### Otherwise:

The bit is ignored

bit 5                      **ADGPOL:** Guard Ring Polarity Selection bit

1 = ADC guard Ring outputs start as digital high during Precharge stage

0 = ADC guard Ring outputs start as digital low during Precharge stage

bit 4-1                      **Unimplemented:** Read as '0'

bit 0                      **ADDSEN:** Double-sample enable bit

1 = Two conversions are performed on each trigger. Data from the first conversion appears in ADPREV

0 = One conversion is performed for each trigger

# PIC18(L)F27/47K40

## BRA Unconditional Branch

Syntax: BRA n

Operands:  $-1024 \leq n \leq 1023$

Operation:  $(PC) + 2 + 2n \rightarrow PC$

Status Affected: None

Encoding: 

1101	0nnn	nnnn	nnnn
------	------	------	------

Description: Add the 2's complement number '2n' to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be  $PC + 2 + 2n$ . This instruction is a 2-cycle instruction.

Words: 1

Cycles: 2

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read literal 'n'	Process Data	Write to PC
No operation	No operation	No operation	No operation

**Example:**           HERE       BRA   Jump

Before Instruction  
PC       =   address (HERE)

After Instruction  
PC       =   address (Jump)

## BSF Bit Set f

Syntax: BSF f, b {,a}

Operands:  $0 \leq f \leq 255$   
 $0 \leq b \leq 7$   
 $a \in [0,1]$

Operation:  $1 \rightarrow f < b >$

Status Affected: None

Encoding: 

1000	bbba	ffff	ffff
------	------	------	------

Description: Bit 'b' in register 'f' is set.  
If 'a' is '0', the Access Bank is selected.  
If 'a' is '1', the BSR is used to select the GPR bank.  
If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever  $f \leq 95$  (5Fh). See **Section 35.2.3 "Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode"** for details.

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	Write register 'f'

**Example:**           BSF       FLAG\_REG, 7, 1

Before Instruction  
FLAG\_REG = 0Ah

After Instruction  
FLAG\_REG = 8Ah



# PIC18(L)F27/47K40

## CPFSGT Compare f with W, skip if f > W

Syntax: CPFSGT f{,a}  
 Operands:  $0 \leq f \leq 255$   
 $a \in [0,1]$   
 Operation:  $(f) - (W)$ ,  
 skip if  $(f) > (W)$   
 (unsigned comparison)  
 Status Affected: None  
 Encoding: 

0110	010a	ffff	ffff
------	------	------	------

Description: Compares the contents of data memory location 'f' to the contents of the W by performing an unsigned subtraction. If the contents of 'f' are greater than the contents of WREG, then the fetched instruction is discarded and a NOP is executed instead, making this a 2-cycle instruction. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever  $f \leq 95$  (5Fh). See **Section 35.2.3 "Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode"** for details.

Words: 1  
 Cycles: 1(2)  
**Note:** 3 cycles if skip and followed by a 2-word instruction.

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	No operation

If skip:

Q1	Q2	Q3	Q4
No operation	No operation	No operation	No operation

If skip and followed by 2-word instruction:

Q1	Q2	Q3	Q4
No operation	No operation	No operation	No operation
No operation	No operation	No operation	No operation

**Example:** HERE CPFSGT REG, 0  
 NGREATER :  
 GREATER :

Before Instruction  
 PC = Address (HERE)  
 W = ?  
 After Instruction  
 If REG > W;  
 PC = Address (GREATER)  
 If REG ≤ W;  
 PC = Address (NGREATER)

## CPFSLT Compare f with W, skip if f < W

Syntax: CPFSLT f{,a}  
 Operands:  $0 \leq f \leq 255$   
 $a \in [0,1]$   
 Operation:  $(f) - (W)$ ,  
 skip if  $(f) < (W)$   
 (unsigned comparison)  
 Status Affected: None  
 Encoding: 

0110	000a	ffff	ffff
------	------	------	------

Description: Compares the contents of data memory location 'f' to the contents of W by performing an unsigned subtraction. If the contents of 'f' are less than the contents of W, then the fetched instruction is discarded and a NOP is executed instead, making this a 2-cycle instruction. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.

Words: 1  
 Cycles: 1(2)  
**Note:** 3 cycles if skip and followed by a 2-word instruction.

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	No operation

If skip:

Q1	Q2	Q3	Q4
No operation	No operation	No operation	No operation

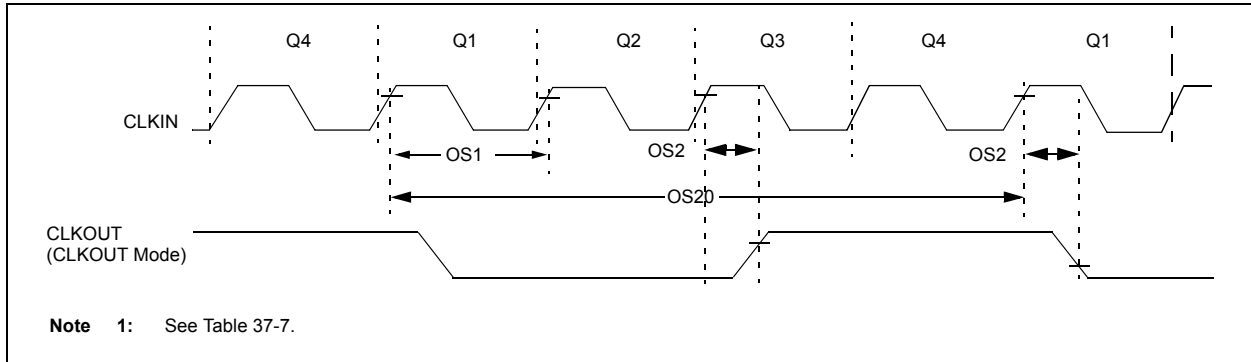
If skip and followed by 2-word instruction:

Q1	Q2	Q3	Q4
No operation	No operation	No operation	No operation
No operation	No operation	No operation	No operation

**Example:** HERE CPFSLT REG, 1  
 NLESS :  
 LESS :

Before Instruction  
 PC = Address (HERE)  
 W = ?  
 After Instruction  
 If REG < W;  
 PC = Address (LESS)  
 If REG ≥ W;  
 PC = Address (NLESS)

**FIGURE 37-5: CLOCK TIMING**



**TABLE 37-7: EXTERNAL CLOCK/OSCILLATOR TIMING REQUIREMENTS**

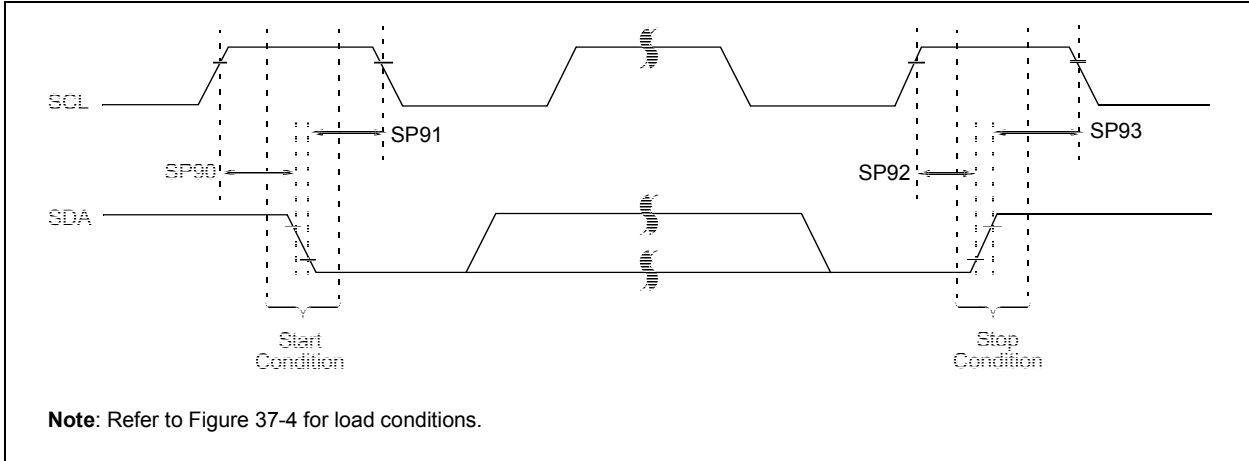
Standard Operating Conditions (unless otherwise stated)							
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
<b>ECL Oscillator</b>							
OS1	$F_{ECL}$	Clock Frequency	—	—	500	kHz	
OS2	$T_{ECL\_DC}$	Clock Duty Cycle	40	—	60	%	
<b>ECM Oscillator</b>							
OS3	$F_{ECM}$	Clock Frequency	—	—	8	MHz	
OS4	$T_{ECM\_DC}$	Clock Duty Cycle	40	—	60	%	
<b>ECH Oscillator</b>							
OS5	$F_{ECH}$	Clock Frequency	—	—	32	MHz	
OS6	$T_{ECH\_DC}$	Clock Duty Cycle	40	—	60	%	
<b>LP Oscillator</b>							
OS7	$F_{LP}$	Clock Frequency	—	—	100	kHz	<b>Note 4</b>
<b>XT Oscillator</b>							
OS8	$F_{XT}$	Clock Frequency	—	—	4	MHz	<b>Note 4</b>
<b>HS Oscillator</b>							
OS9	$F_{HS}$	Clock Frequency	—	—	20	MHz	<b>Note 4</b>
<b>Secondary Oscillator</b>							
OS10	$F_{SEC}$	Clock Frequency	32.4	32.768	33.1	kHz	
<b>System Oscillator</b>							
OS20	$F_{OSC}$	System Clock Frequency	—	—	64	MHz	<b>(Note 2, Note 3)</b>

\* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note 1:** Instruction cycle period (TCY) equals four times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "min" values with an external clock applied to OSC1 pin. When an external clock input is used, the "max" cycle time limit is "DC" (no clock) for all devices.
- 2:** The system clock frequency ( $F_{OSC}$ ) is selected by the "main clock switch controls" as described in **Section 6.0 "Power-Saving Operation Modes"**.
- 3:** The system clock frequency ( $F_{OSC}$ ) must meet the voltage requirements defined in the **Section 37.2 "Standard Operating Conditions"**.
- 4:** LP, XT and HS oscillator modes require an appropriate crystal or resonator to be connected to the device. For clocking the device with the external square wave, one of the EC mode selections must be used.

**FIGURE 37-20: I<sup>2</sup>C BUS START/STOP BITS TIMING**

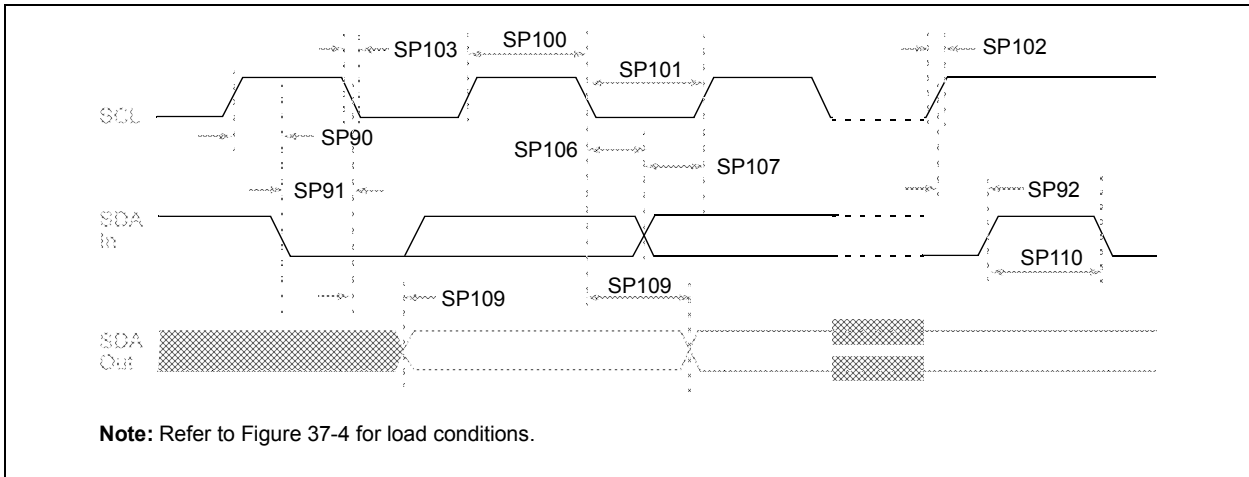


**TABLE 37-24: I<sup>2</sup>C BUS START/STOP BITS REQUIREMENTS**

Standard Operating Conditions (unless otherwise stated)								
Param No.	Symbol	Characteristic		Min.	Typ	Max.	Units	Conditions
SP90*	TSU:STA	Start condition	100 kHz mode	4700	—	—	ns	Only relevant for Repeated Start condition
		Setup time	400 kHz mode	600	—	—		
SP91*	THD:STA	Start condition	100 kHz mode	4000	—	—	ns	After this period, the first clock pulse is generated
		Hold time	400 kHz mode	600	—	—		
SP92*	TSU:STO	Stop condition	100 kHz mode	4700	—	—	ns	
		Setup time	400 kHz mode	600	—	—		
SP93	THD:STO	Stop condition	100 kHz mode	4000	—	—	ns	
		Hold time	400 kHz mode	600	—	—		

\* These parameters are characterized but not tested.

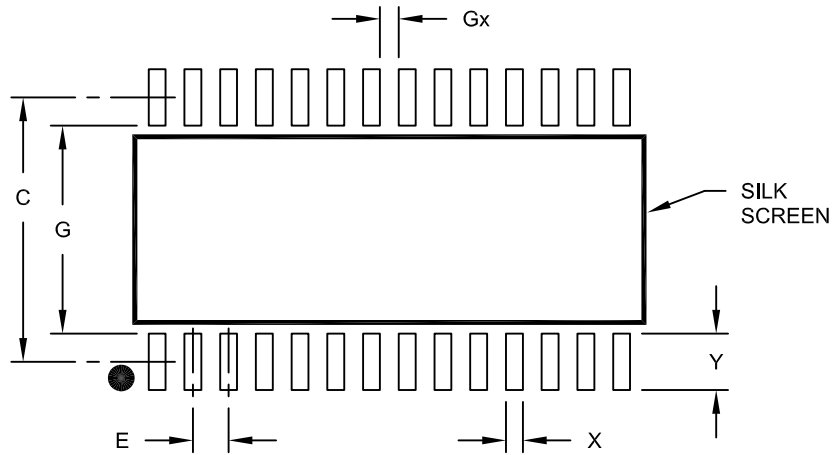
**FIGURE 37-21: I<sup>2</sup>C BUS DATA TIMING**



# PIC18(L)F27/47K40

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

		Units	MILLIMETERS		
Dimension Limits			MIN	NOM	MAX
Contact Pitch	E		1.27 BSC		
Contact Pad Spacing	C			9.40	
Contact Pad Width (X28)	X				0.60
Contact Pad Length (X28)	Y				2.00
Distance Between Pads	Gx		0.67		
Distance Between Pads	G		7.40		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

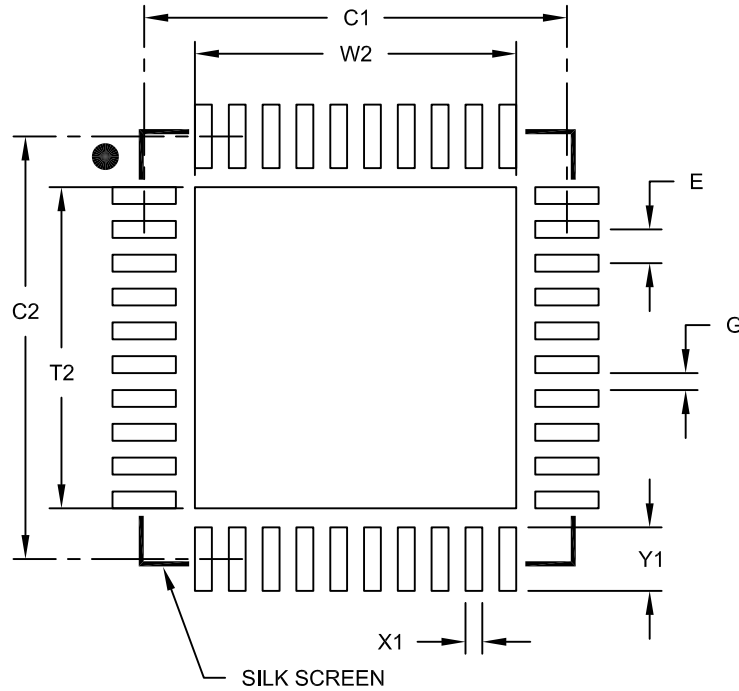
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2052A

# PIC18(L)F27/47K40

## 40-Lead Plastic Ultra Thin Quad Flat, No Lead Package (MV) - 5x5 mm Body [UQFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.40 BSC		
Optional Center Pad Width	W2			3.80
Optional Center Pad Length	T2			3.80
Contact Pad Spacing	C1		5.00	
Contact Pad Spacing	C2		5.00	
Contact Pad Width (X40)	X1			0.20
Contact Pad Length (X40)	Y1			0.75
Distance Between Pads	G	0.20		

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2156B